



FAA TECHNICAL CENTER LETTER REPORT

PROGRAMS TO COMPUTE THE FIGURES
OF MERIT FOR THE GLOBAL POSITIONING SYSTEM (GPS)

by

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AVAILABLE IN
ELECTRONIC FORMAT

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ABSTRACT

The programs were written to compute, on a Hewlett Packard minicomputer, the dilution of precision parameters for the Global Positioning System (GPS) and to plot these data versus Greenwich Mean Time (GMT). The programs evaluate the influence of satellite geometry upon these parameters and subsequently upon the accuracy of the GPS. The flowcharts of the programs, a printout of the transfer files, program listings and examples of the program output are included in this report.

This work was accomplished when the author, Erhard Buchberger, was on an exchange program at the FAA Technical Center from the West German Aerospace Establishment. For further information contact Robert Esposito, phone number (609) 641-8200, extension 3961.

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Key Words

GPS

Dilution of Precision

Almanac

Flow Charts

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INTRODUCTION

BACKGROUND

The FAA Technical Center has made use of a GPS almanac program originally written at the Texas A&M University for execution on a Texas Instrument 990/4 minicomputer (Reference 1). This program computes satellite azimuth and elevation, satellite rise and fall time and the geometric dilution of precision. M. Magrogan (Reference 2) modified these routines to analyze FAA test results on a Digital Equipment Corporation PDP-11/34 minicomputer.

SCOPE

This report documents further modifications and additions which permit the GPS almanac program to run on a Hewlett Packard (HP) 1000 minicomputer with the main task of computing the dilution of precision factors for the case of four space-vehicles, and of three satellites plus altitude input.

DISCUSSION

The major changes made by the Technical Center include:

- An almanac unpacking subroutine developed by N. Watts for the HP.
- Revision of the computation of the GPS epoch time.
- A matrix inversion subroutine which detects singularities.
- Computation of the dilution of precision factors for three satellites plus altitude data.
- Use of double precision in all computations.

In addition, all main programs allow several different types of input data to be used. In doing so, the programs ask for the data with an explaining comment. The main programs also include Block Data, that is, parts in which the Common Blocks are initially defined. This was not necessary with the PDP-11.

Table 1 displays the time parameters which are needed in some of the programs as input parameters. Special attention must be given to the fact that different units (day and second) and different origins are used.

The order of Keplerian parameters, which are included in the almanac and used to compute the satellite trajectories, is listed in table 2. Note that parameters 9 through 14 are computed in the program HD00, with μ (used to calculate the mean motion) as the earth's universal gravitational constant. The algorithms and equations used in this program are given in references 5 through 9.

Three coordinate systems (reference 3) based on WGS-72 reference ellipsoid are utilized.

1. An earth-centered-earth-fixed (ECEF) system.
2. The east-north-up (ENU) system.
3. Geographic latitude, longitude and altitude.

USER MANUAL

Appendix A contains the transfer files for the main programs HD00, PLGH, EBGD1, and EBGH. Appendix B gives the flowcharts for these programs plus the subroutines HD01 and EB05. Appendix C provides listings of these programs and all subroutines. Each program is called on the HP computer with its name, and user prompting explicitly asks for the required inputs. Appendix D and E respectively give examples of the data files and program output.

Program: HD00 (Pages C-1 through C-8)

This program computes and prints out the position of up to 4 satellites in ECEF coordinates and in azimuth and elevation angle related to the user position and HDOP and GDOP. It also generates a plot file with the figures of merit.

The following input data must be prepared: User position in geographical coordinates (latitude (LAT), longitude, (LON), and altitude (ALT) in feet). If the location is the FAA Technical Center, this information is already stored in the program. After the program has received user position, the geographical coordinates are converted into ECEF and printed out. The next data requested are the user times. The routine needs the start (TSTART) and stop time (TFIN) of the time interval to be evaluated, the time increment (TDEL) - (i.e., the difference between the points in time, for which the calculations are made), the time of collection (TC) of the almanac, and the date of use (DTU)-(see also table 1).

Then, the choice must be made whether the computations should be made with 4 satellites or 3 satellites plus altitude information. When 3 satellites are selected, the fourth satellite is simulated in the center of the earth.

The next decision concerns the input of the almanac for the satellites:

(1) If the almanac is on a magnetic tape, it must be stated so and then the entire almanac file is read from the tape. After this is successfully completed, the input is requested of the PRN No. of the first space vehicle. The program checks whether the satellite data is on tape. If not, the request is repeated, otherwise, the next satellite is requested.

(2) The second choice is to provide the program with the names of data files containing an almanac for each space vehicle, or the data can be typed in over the keyboard.

After the steps are successfully completed, the routine computes the rest of the almanac parameters, and prints all inputs out together with a title. The calculation and the output of the results take place after a prompting of a user selected name (less than 6 characters) of a plot file for the GDOP.

Program: PLHG (Pages C-9 through C-11)

This program is a continuation of HD00. It was created because the plot software needs approximately 38,000 words of memory space since both routines together exceed the memory limits of the computer.

PLHG plots two data files generated by HD00 to compare HDOPs computed with three and with four satellites. After the input of the first file name, the user declares the logical unit of the plotting device and the ID of the device subroutine to initialize the plotter. Examples for this would be:

a) LU = 20
b) LU = 1

ID = 5
ID = 1

Device: Printer
Device: Monitor

Data is needed to enable the routine to draw a grid, select a time slot out of the complete files, and start and stop time. To ensure that data is available in the files for this period, because the records are formatted, the file can be looked up directly. Finally, the name of the second file must be entered, and the program then generates a plot as described under program HD00.

Program: EBGD1 (Pages C-12 through C-14)

This program also delivers as final results HDOP and GDOP, but it does not utilize the satellite almanac as input data. The operator selects whether the H-matrix is inserted directly or whether the azimuth and elevation angles of the satellites are inputted. This routine then calculates the figures of merit, and also prints out the intermediate steps of the matrix conversions. The program can be used to evaluate the influence of special space vehicle geometries on the HDOP and GDOP.

Program: EBGH (Pages C-15 through C-19)

The routine also computes the figures of merit from user and satellite positions. It is possible to input the needed data over the keyboard; that is, to type the user position in geographical coordinates, the number of satellites to be used (three or four), and the satellite position in ECEF coordinates. Also, the operator may read the data from a file by providing the file name. Depending on the number of space vehicles stored in the file (NSAT), the program will print out an error message (NSAT < 3), will ask whether the system is altimeter aided (NSAT = 3) or will just start computing (NSAT = 4). Due to restrictions in the subroutines, the system in this stage has to be altimeter aided, i.e., a fourth satellite is simulated in the earth center.

The H-matrix is computed in a different way from the other programs; the rotation of the matrix into the ENU system is a separate step. This was made to check whether the programs deliver the same results. The program EBGH delivers a printout similar to EBGD1. It prints all matrices, the figures of merit, and the satellite positions.

Subroutine Description

EB02: computes the rotation matrix, given on page C-20.
EB03: converts user geographical coordinates into the ECEF system, given on page C-21.
EB05: calls EB06 and EB07 and computes satellite azimuth and elevation, given on page C-22.
EB06: computes satellite position in ECEF, given on page C-23.
EB07: computes user to satellite distance, given on page C-24.
EB09: multiplies two matrices, given on page C-25.
EB12: converts seconds into hours, minutes and seconds, given on page C-26.
EB14: unpacks the almanac data (with assembly language subroutine DINTF), given on pages C-27 through C-29.
MINVD: inverts the matrices from the "Scientific Subroutine" package from DEC (Reference 4) given on pages C-32 through C-34.
DINTF: assembly language subroutine, unpacks the almanac data (with subroutine EB12), given on page C-35.
ENU: computes rotation matrix, given on page C-36.
HTRAN: converts H-matrix into its transpose, given on page C-37.
MLHHT: multiplies the transpose of H-matrix by H-matrix, given on page C-38.
INVHP: inverts the matrices, but does not check for singularities, given on pages C-39 and C-40.

The previously tested subroutines ENU, HTRAN, MLHHT, and INVHP (from references 1 and 2) were used in one program to check the computations made by the other subroutines for a non-singular matrix.

REFERENCES

1. A GPS Almanac, Wong, C.S., Texas A&M University.
2. Global Positioning System (GPS) Satellite Elevation and Azimuth Angles, Michael Magrogan, Letter Report, FAA, 1982.
3. Computer Program Development Specification for the Z-User-Set, Specification No. GP-US-305.
4. The Scientific Subroutine Package, Digital Equipment Corporation.
5. Handbook of Astronautical Engineering, Koelle, H.H., McGraw Hill, 1961.
6. Principle of Operation of NAVSTAR and System Characteristics, Milliken, R.J. and Zoller, C.J., Navigation, Vol. 25, pages 95-106, 1980.
7. Taschenbuch der Mathematik, Bronstein, I, and Semedjajew, K., Tuebner Verlagsgesellschaft Leipzig, 1960.
8. Using the Global Position Satellite System for Positioning and Navigation, Rhyne, T., Noe, P., and Painter, J., Altair Corporation.
9. Satellite Navigation, Klostermann, E., Lecture at the Carl-Cranz-Kurs, 1981.

<u>Parameter</u>	<u>Start of Count</u>	<u>Unit</u>
DTU - Date of use	Beginning of Year	Day
DTC - Date of collection of Almanac	Beginning of Year	Day
T - GPS - Time	Beginning of Day	Second
TC - Collection Time of Almanac	Beginning of week (0000 hours Sunday)	Second

The used time zone is Greenwich Mean Time (GMT)

TABLE 1. TIME PARAMETERS USED IN PROGRAMS

<u>No. in Almanac</u>	<u>Keplerian Parameter</u>	<u>Name in Program and (GPS) - Name</u>
1	Eccentricity of ellipsoid	E (e)
2	Reference time for almanac	TOA (toa)
3	Orbit inclination	Di (i)
4	Drift rate of right ascension	OMD ($\dot{\Omega}$)
5	Square root of semi-major axis	RA ($\sqrt{A}$)
6	Right ascension of the orbit	OMO (Ω_0)
7	Argument of perigee	W (ω)
8	Mean anomaly	MO (Mo)
9	Semi-major axis	A
10	Cosine of orbit inclination angle	cos(i)
11	Sine of orbit inclination angle	sin(i)
12	Cosine of argument of perigee	cos(ω)
13	Sine of argument of perigee	sin(ω)
14	Mean motion	$\sqrt{\mu/A^3}$

TABLE 2. ORDER OF KEPLERIAN PARAMETERS

APPENDIX A

Transfer Files - These files are used to load programs which consist of several subroutines.

TEBGH T=00004 IS ON CR00011 USING 00002 BLKS R=0000

0001	REL, %EBGH
0002	SEA, %ENU
0003	SEA, %EB12
0004	SEA, %EB03
0005	SEA, %HTRAN
0006	SEA, %NLHHT
0007	SEA, %INVHP

TEBGD1 T=00004 IS ON CR00002 USING 00002 BLKS R=0000

0001	REL, %EBGD1
0002	SEA, %EB09
0003	SEA, %MINVD

TPLHG T=00004 IS ON CR00002 USING 00002 BLKS R=0000

0001	RE, %PLHG
0002	RE, %DLTBL
0003	SEA, %GPS

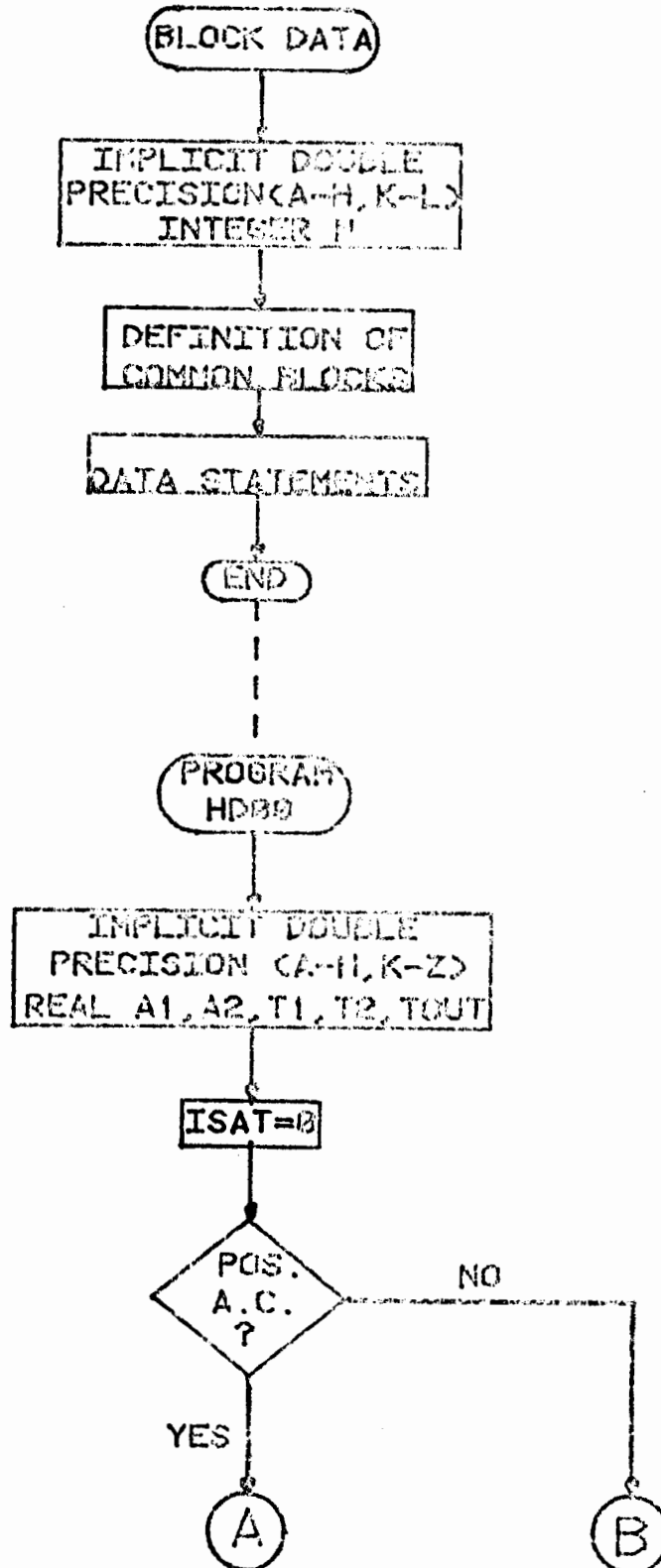
THD00 T=00004 IS ON CR00002 USING 00002 ELKS R=0000

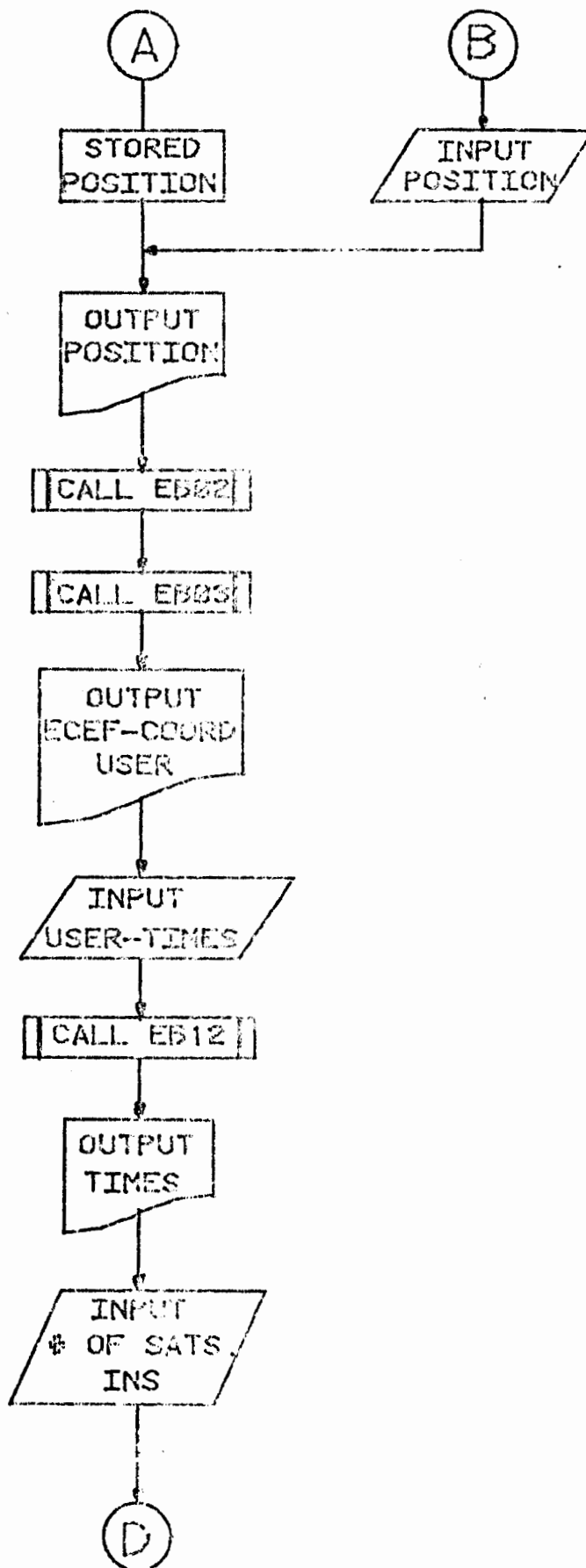
0001	REA, %HD00
0002	SEA, %EB02
0003	SEA, %EB03
0004	SEA, %EB05
0005	SEA, %EB06
0006	SEA, %EB07
0007	SEA, %HD01
0008	SEA, %EB09
0009	SEA, %MINVD
0010	SEA, %EB12
0011	SEA, %EB14
0012	SEA, %DINTF

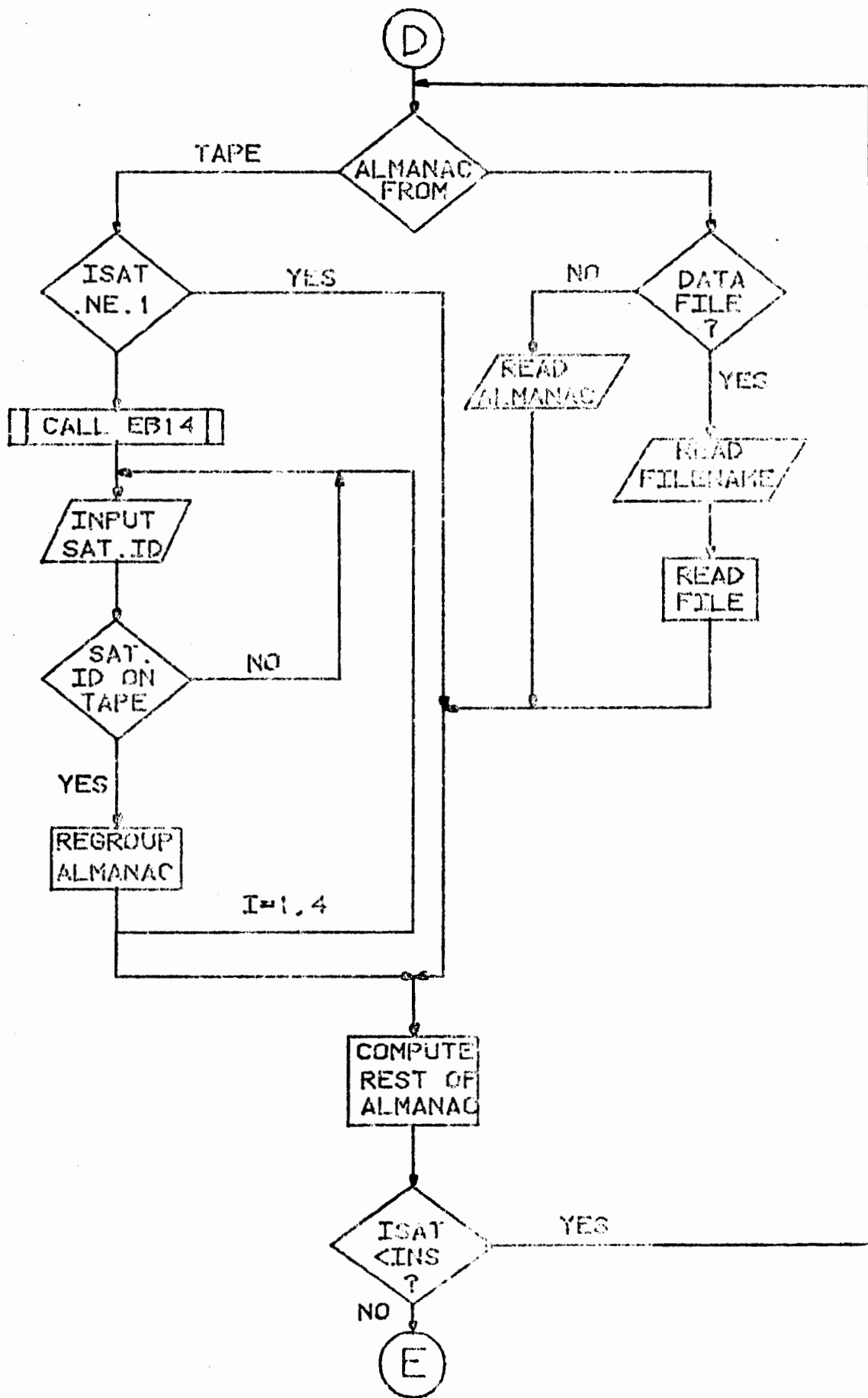
APPENDIX B

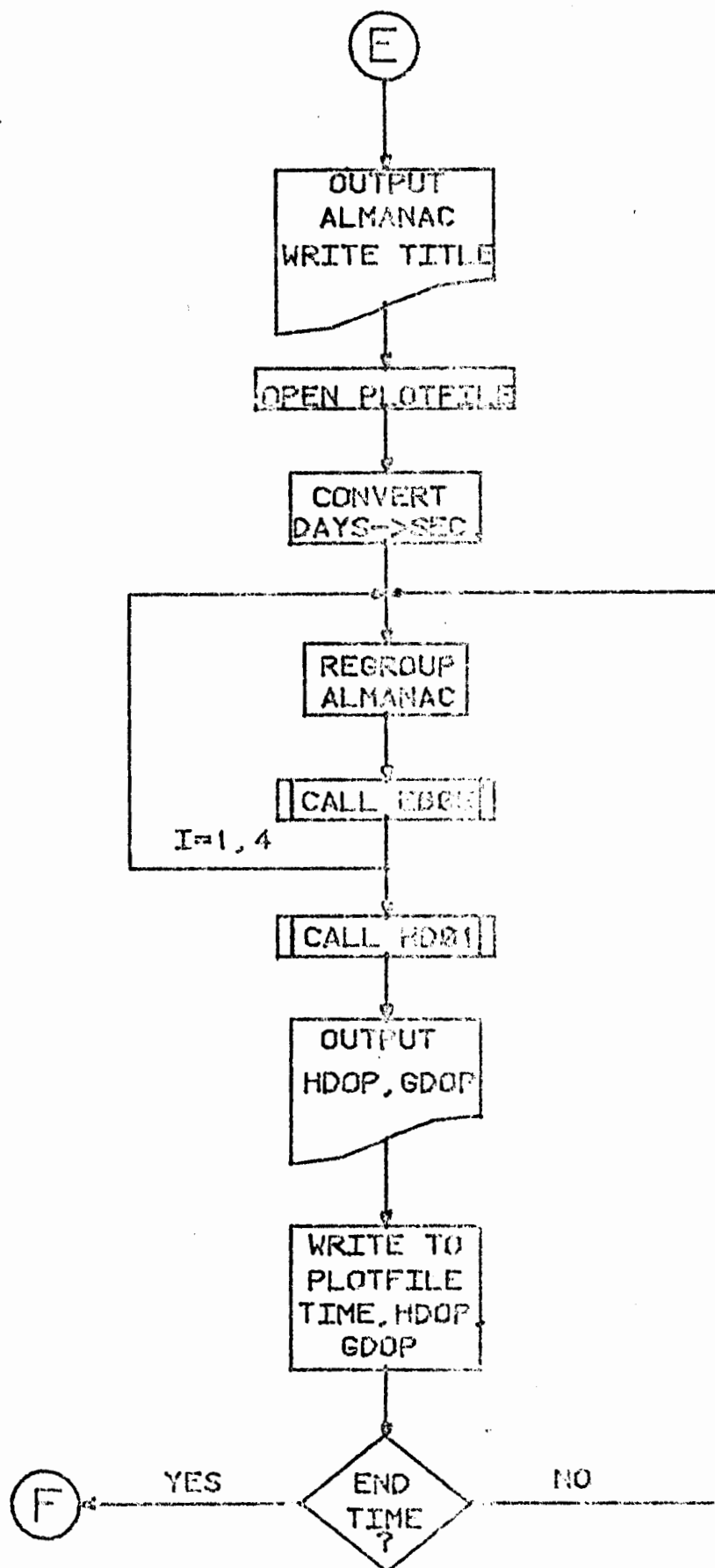
Flowcharts - These flowcharts were drawn on a Tektronix - minicomputer with a drafting software developed by a group of the Eglin AFB. Only new or significantly modified routines are included here.

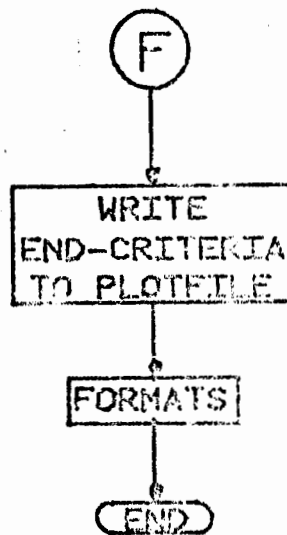
FLOWCHART HD00



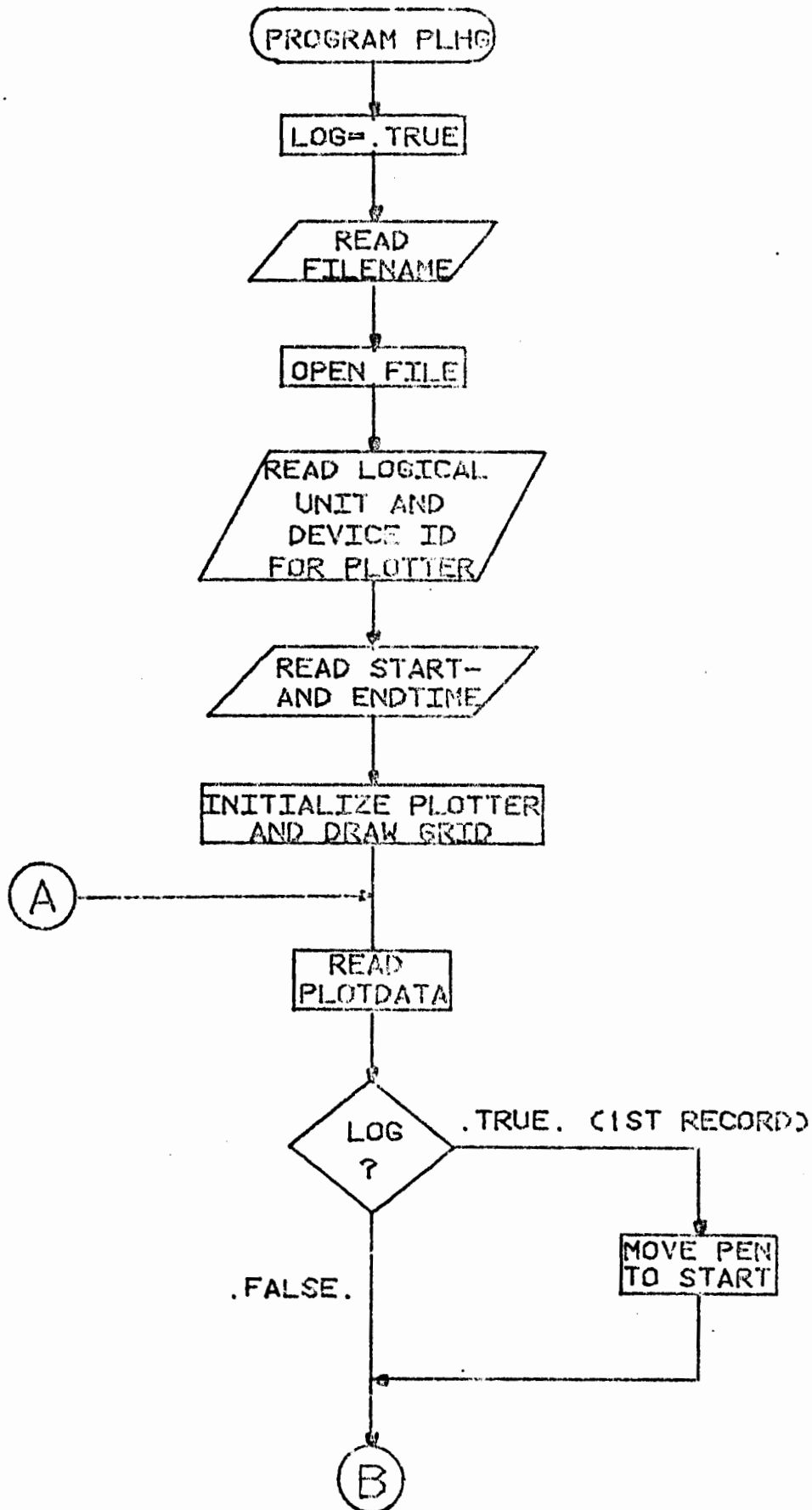


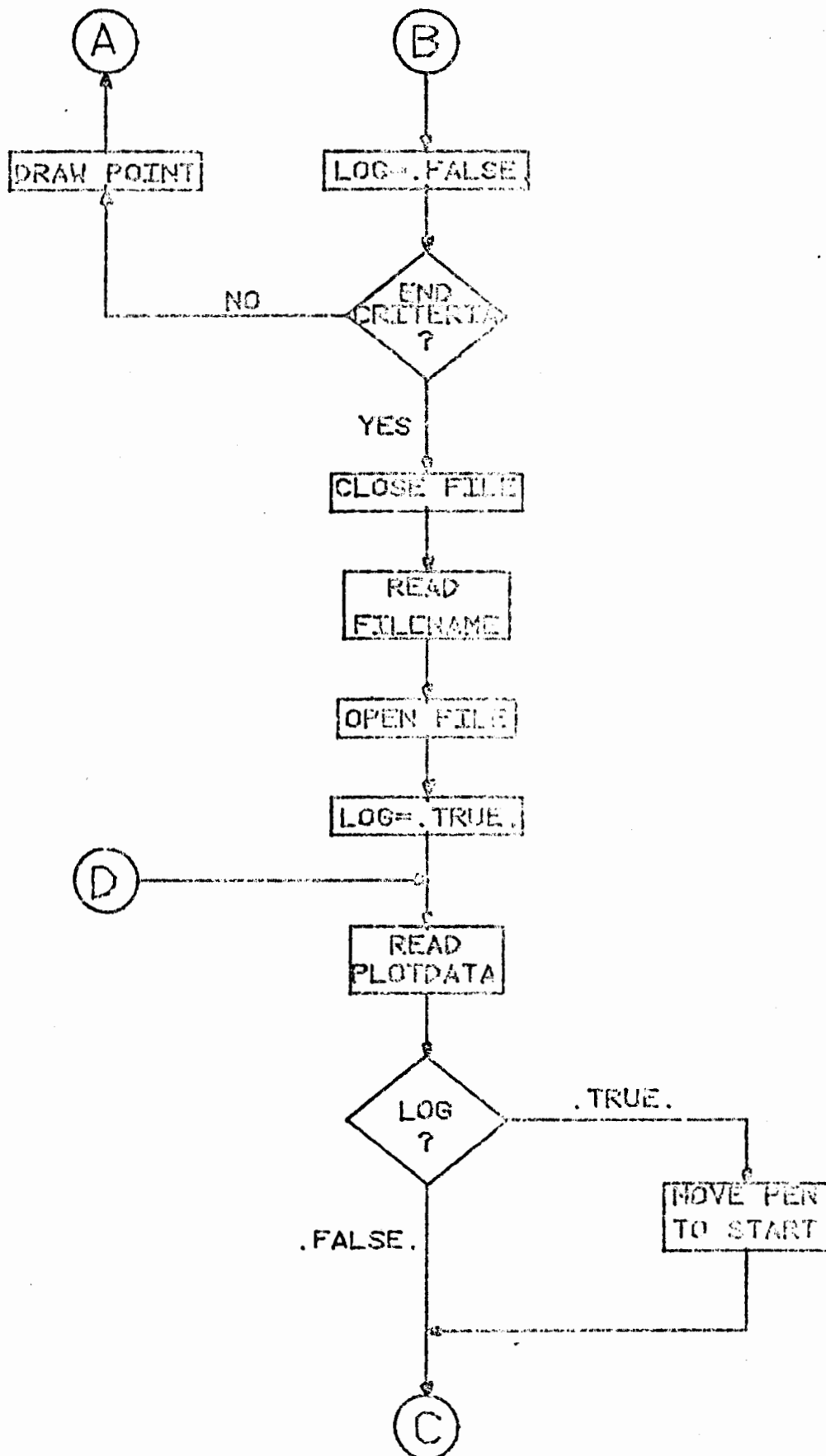


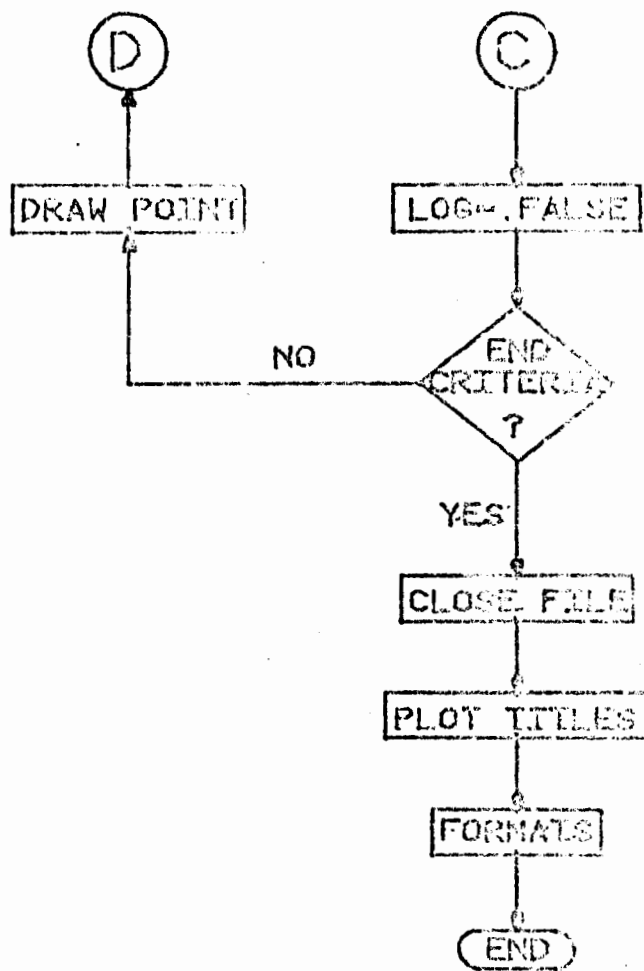




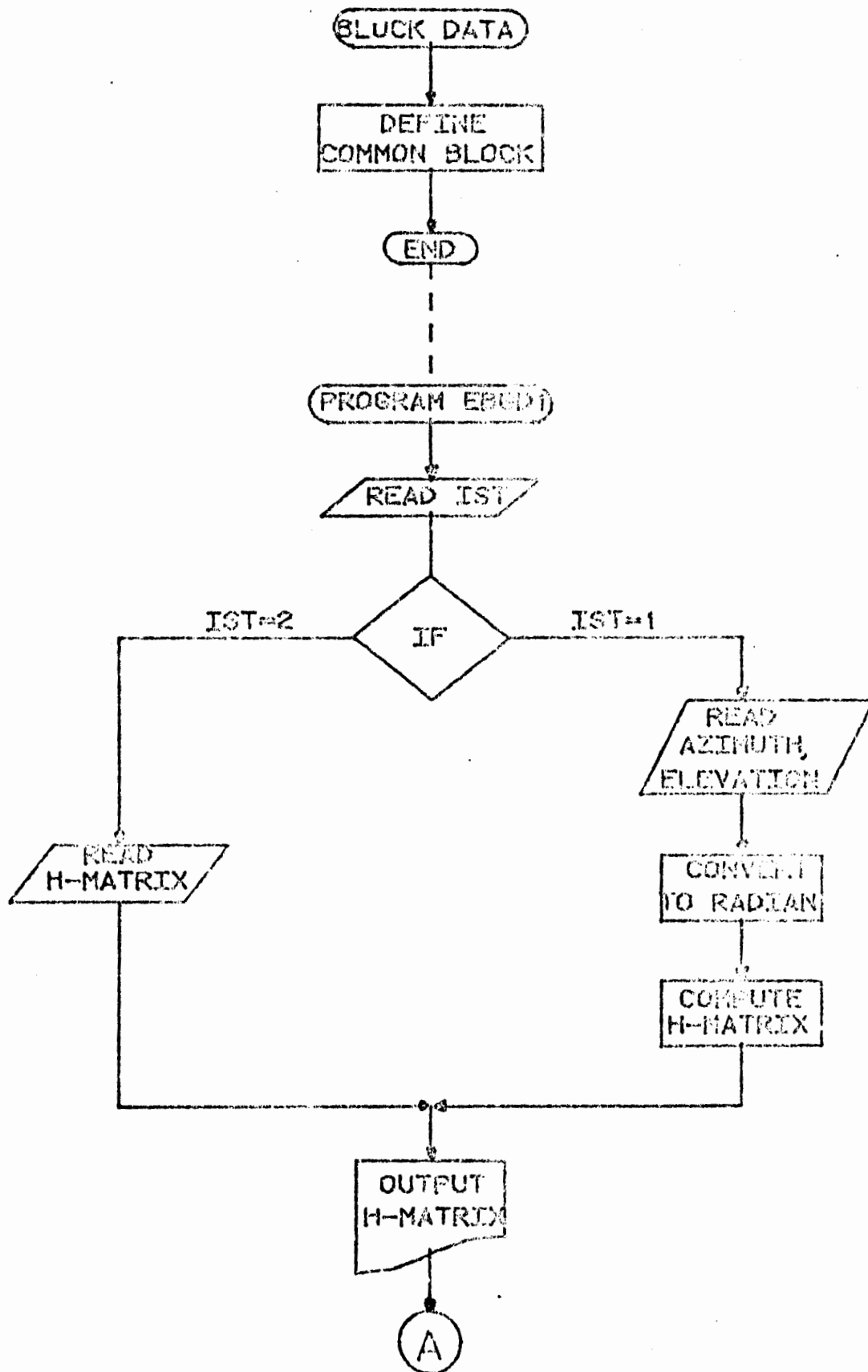
FLOWCHART PLHG

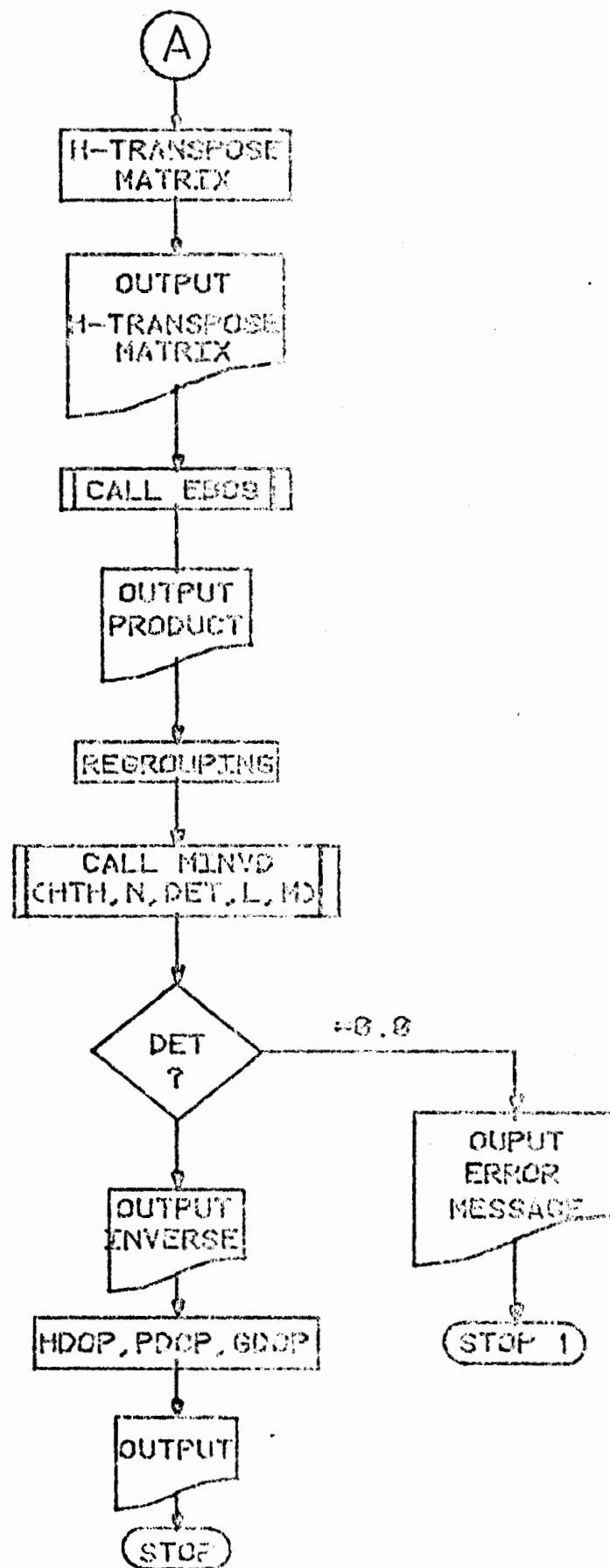




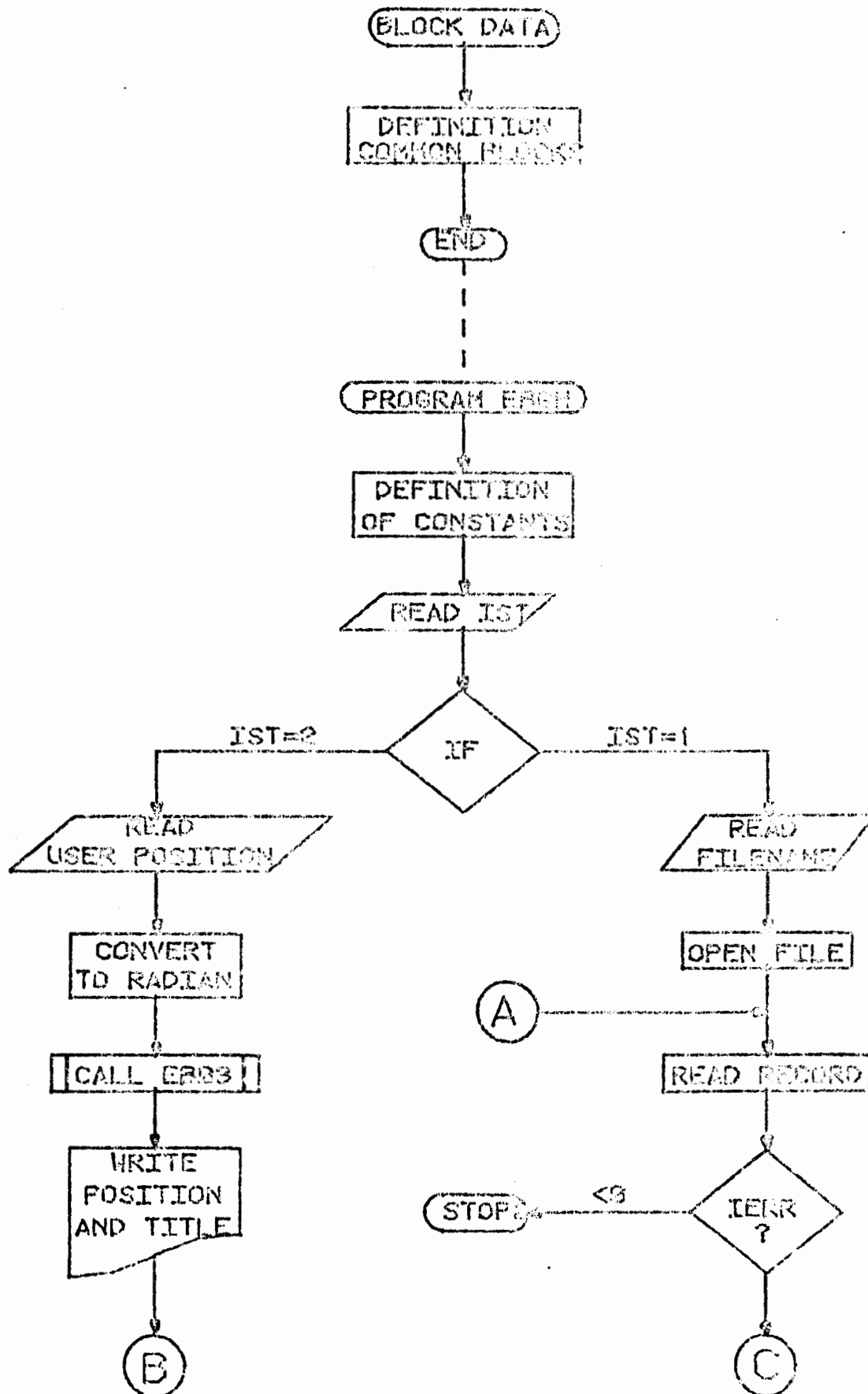


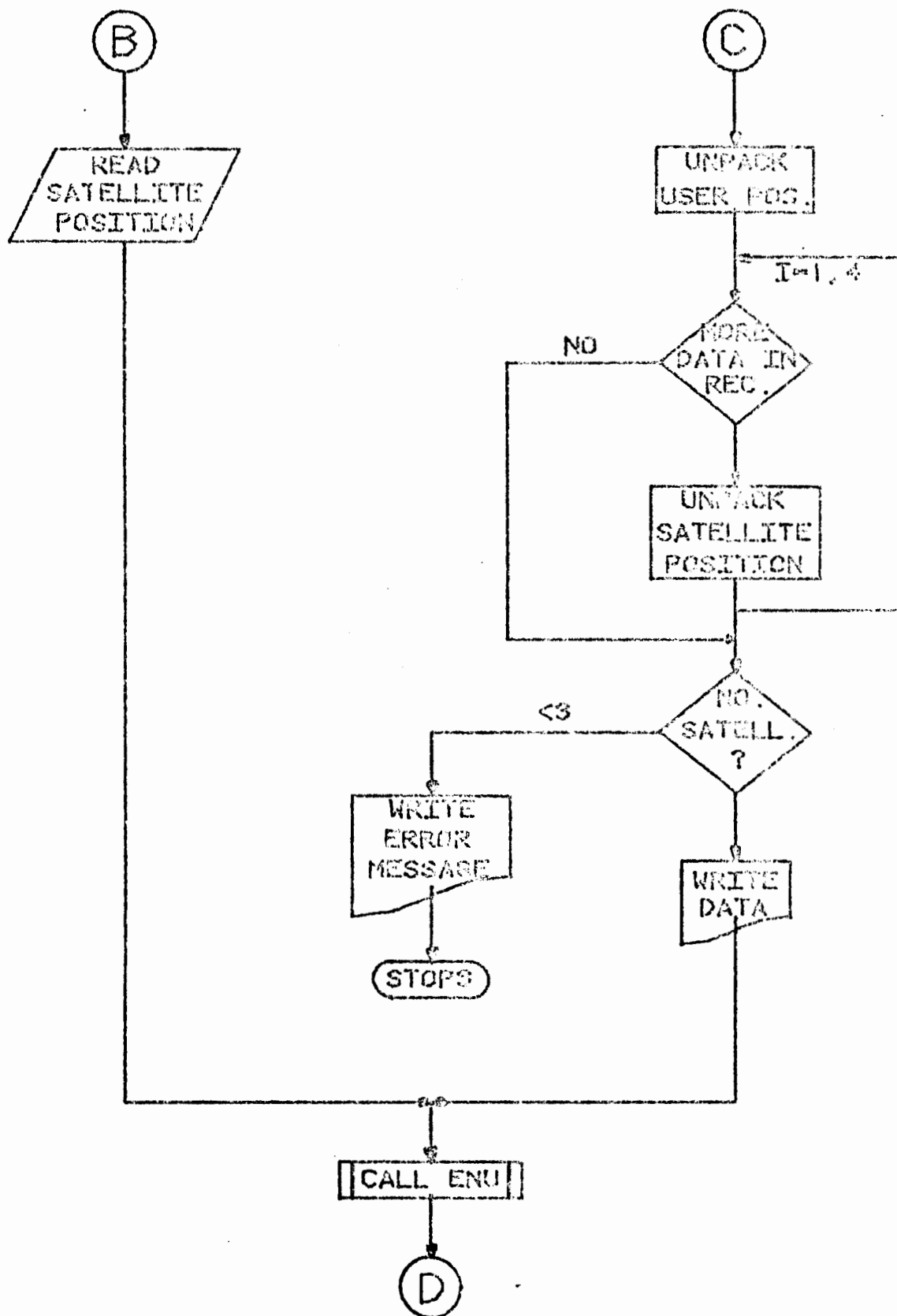
FLOWCHART EBGD1

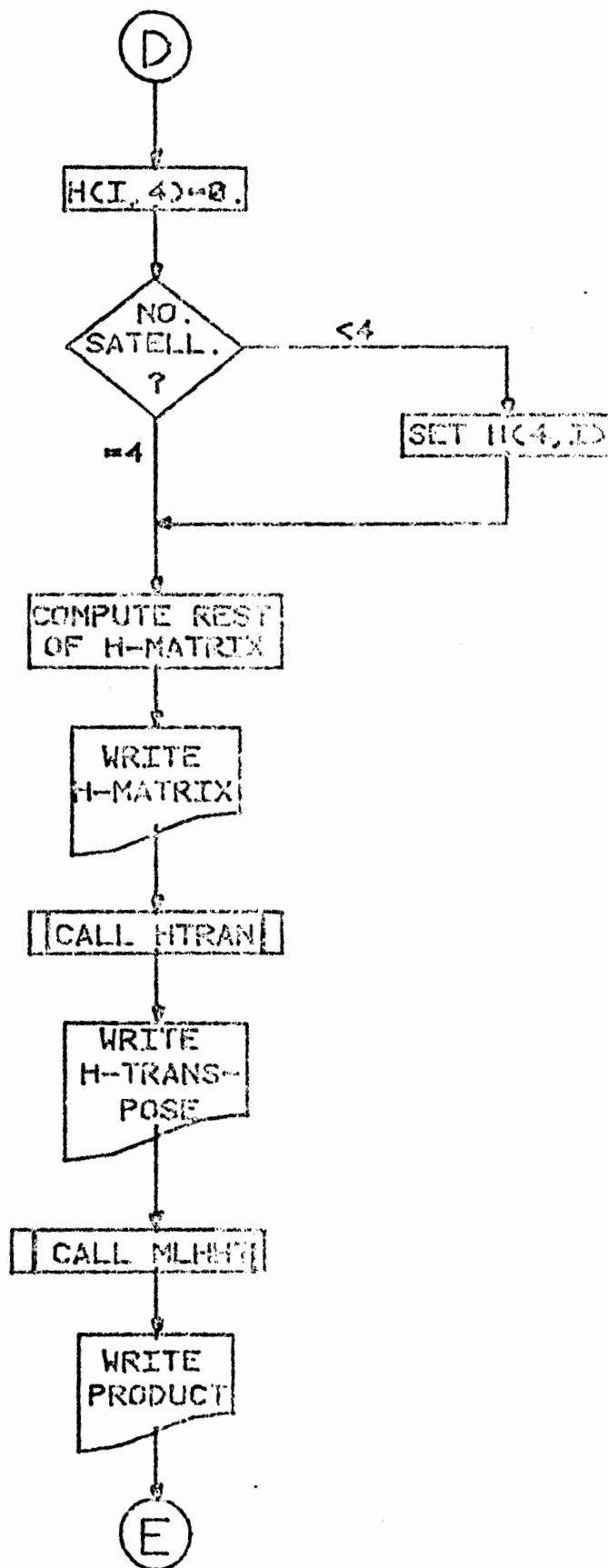


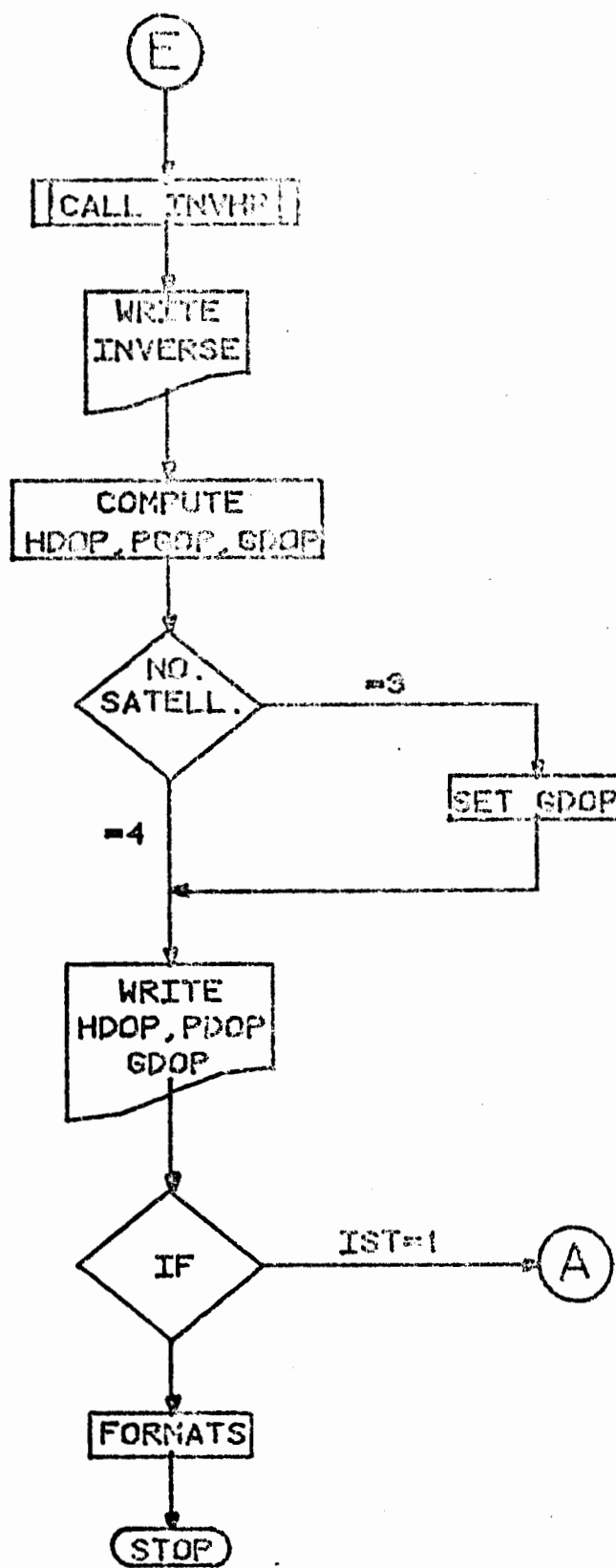


FLOWCHART EBGH

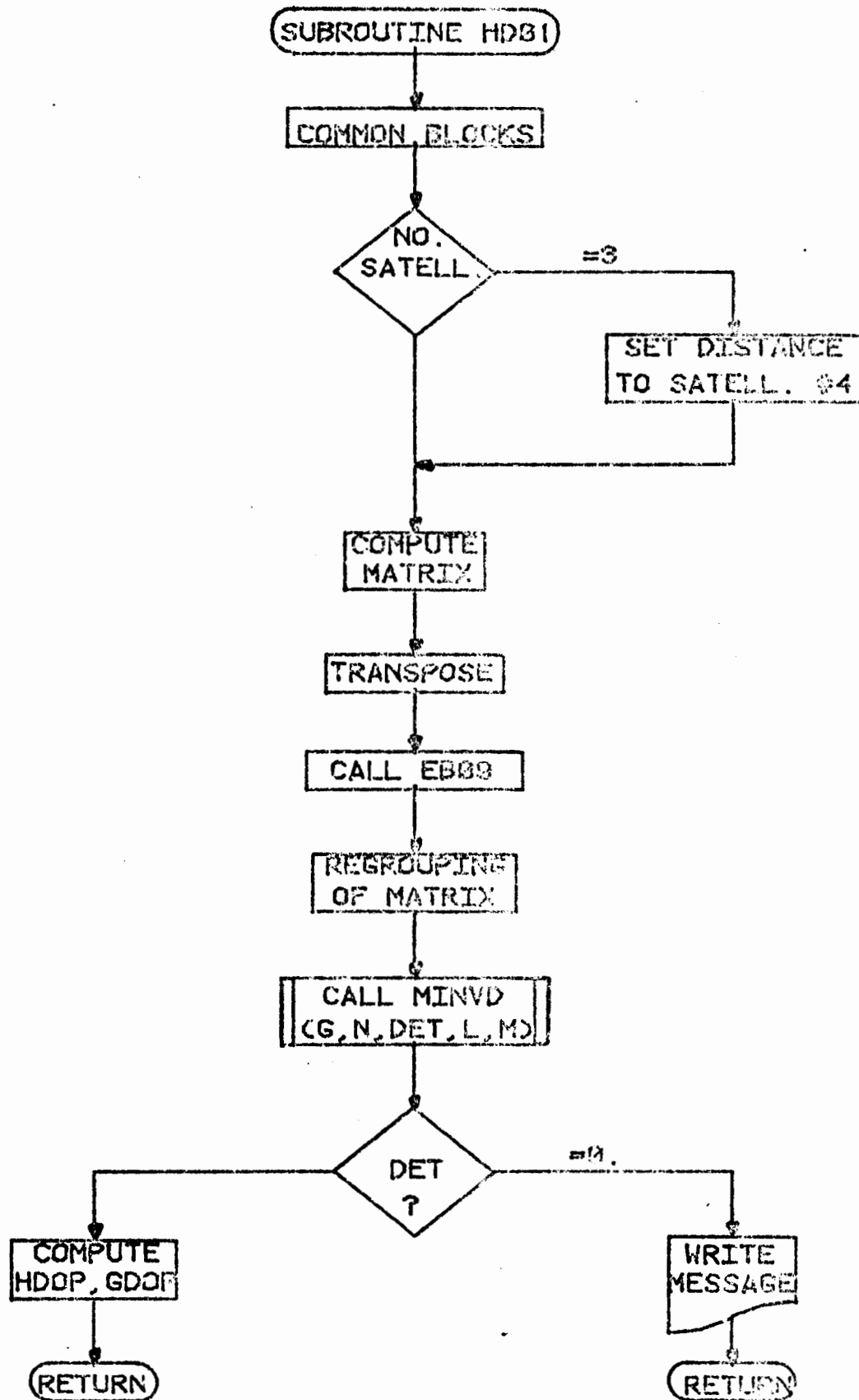




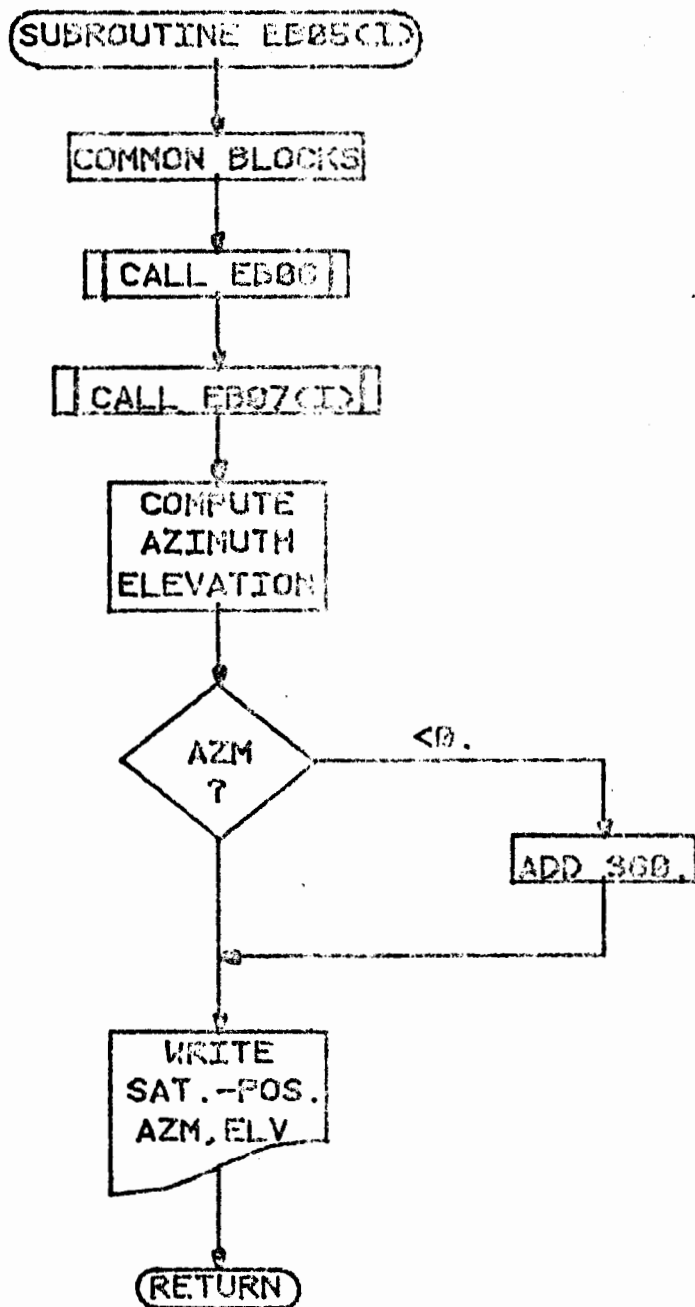




FLOWCHART HD01



FLOWCHART EB05



APPENDIX C
PROGRAM LISTINGS

```

0001  FTN4X,L,Y
0002  C *****
0003  C *   FILENAME : %HD00   *
0004  C *****
0005          BLOCK DATA
0006          IMPLICIT DOUBLE PRECISION (A-H,K-Z)
0007          INTEGER N
0008          COMMON /CNST/PI,RTD,OMF,AE,E2,OMF2,SGC,ERATE,PI2
0009          COMMON/TIME/TDEL,TFIN
0010          COMMON/AZM/ELV(4),AZM(4)
0011          COMMON/POS/LAT,LON,ALT,R
0012          COMMON/NAC/TUY,TCY,TKC,DTC(4),DTU,TC,T
0013          COMMON/DB2/AD1(14)
0014          COMMON/DTX/U(4),D(4,4),RBAR(4)
0015          COMMON/SAT/S(4)
0016          COMMON/HDOF/HDOF,INS,GDOF
0017          COMMON/ELEV/E(3,3)
0018          COMMON/MAT/A(4,4),AT(4,4),AAT(4,4)
0019          COMMON/BLG/G(4,4),N
0020          COMMON/ALM/AD2(14,24),ID1(24)
0021          COMMON/EPH/C(7),K,S1(7)
0022          DATA PI/3.14159265D0/,RTD/57.2957795D0/,PI2/6.2831853D0/
0023          DATA OMF/.99664722D00/,AE/6.378135D6/
0024          DATA E2/6.694317778D-3/,OMF2/.993305683D0/
0025          DATA SGC/1.996499D7/,ERATE/7.292115147D-5/
0026          END
0027  $FILES (1,1)
0028          PROGRAM HD00
0029  C *****
0030  C *   ROUTINE COMPUTES FOR A PROMPTED TIME (DAY AND TIME INTERVALL *
0031  C *   DURING THIS DAY) AND A PROMPTED USER POSITION THE POSITION OF *
0032  C *   4 GPS SATELLITES,THE AZIMUTH AND ELEVATION ANGLES, THE DISTANCE*
0033  C *   TO THE USER AND THE HDOP AND GDOP. *
0034  C *   THE SATELLITE POSITIONS ARE COMPUTED FROM THE ALMANAC DATA BY *
0035  C *   A MODIFIED PROGRAM OF THE TEXAS A&M-UNIVERSITY. *
0036  C *   A PLOTFILE WITH A TIME TAGGED HDOP IS CREATED. *
0037  C * *
0038  C * - - - - -
0039  C * *
0040  C *   USED SUBROUTINES:      EB02 *
0041  C *                        EB03 *
0042  C *                        EB05 *
0043  C *                        EB06 *
0044  C *                        EB07 *
0045  C *                        HD01 *
0046  C *                        EB09 *
0047  C *                        MINVD *
0048  C *                        EB12 *
0049  C *                        EB14 *
0050  C *                        DINTF *
0051  C * *
0052  C * - - - - -
0053  C * *
0054  C *   USED EARTH-REFERENCE-ELLIPSOID : WGS-72 *
0055  C * *
0056  C *   IMPORTANT VARIABLES AND CONSTANTS : *
0057  C *   INTEGER : IST,IST1,IST2      --> CONTROL-PARAMETERS *
0058  C *               I,II,J,I1,I2,I3  --> INDEX FOR DO-LOOPS *

```

0059	C *	N	--> SIZE OF MATRIX (USED IN	*
0060	C *		INVERSION SUBROUTINE)	*
0061	C *	INS	--> NUMBER OF SATELLITES FOR	*
0062	C *		HDOP COMPUTATION	*
0063	C *	ISAT	--> INDEX OF SATELLITES	*
0064	C *	ID (4)	--> PRN NO. OF USED SATELLITES	*
0065	C *	ID1 (24)	--> PRN NO. OF ALL SATELLITES	*
0066	C *	INAM (3)	--> NAME OF PLOTFILE	*
0067	C *			*
0068	C *	REAL : A1,A2,T1,T2,TOUT	--> ONLY FOR OUTPUT,ALL REAL-	*
0069	C *		VARIABLES ARE NOT INVOLVED	*
0070	C *		IN ANY SIGNIFICANT COMPUTAT.	*
0071	C *			*
0072	C *	DOUBLE PRECISION :		*
0073	C *	AD (14,4)	--> ALMANAC FOR 4 SATELLITES	*
0074	C *	AD1 (14)	--> ALMANAC JUST USED	*
0075	C *	AD2 (14,24)	--> ALMANAC FOR 24 SATELLITES	*
0076	C *	ALT	--> ALTITUDE	*
0077	C *	AE	--> RADIUS OF EARTH	*
0078	C *	AZM (4)	--> AZINUTH ANGLE OF SATELLITE	*
0079	C *	A(4,4),AT(4,4),	--> MATRIX,INVERTED MATRIX AND	*
0080	C *	AAT(4,4)	MULTIPLICATION MATRIX.	*
0081	C *		A CONTAINS THE DIRECTION-	*
0082	C *		COSINES IN ENU COORDINATES	*
0083	C *	D(4,4)	--> DISTANCES FROM USER TO 4	*
0084	C *		SATELLITES IN ECEF COORD.	*
0085	C *	DT(4)	--> DATE OF COLLECTION IN DAYS	*
0086	C *		FROM BEGINNING OF THE YEAR	*
0087	C *	DTU	--> DATE OF USE IN DAYS (CONVER-	*
0088	C *		TED INTO SECONDS) FROM	*
0089	C *		BEGINNING OF THE YEAR	*
0090	C *	E (3,3)	--> MATRIX CONTAINING SINES AND	*
0091	C *		COSINES OF USER POSITION	*
0092	C *	E2	--> SQUARE-ROOT OF THE EXCENTRI-	*
0093	C *		CITY OF THE EARTH ELLIPSOID	*
0094	C *	ELV (4)	--> ELEVATION ANGLE OF SATELLITES	*
0095	C *	ERATE	--> EARTH ROTATION RATE	*
0096	C *	G (4,4)	--> MATRIX FOR INVERSION-SUBROU.	*
0097	C *	GDOP	--> GEOMETRIC DILUTION OF PRECI-	*
0098	C *		SION	*
0099	C *	HDOP	--> HORIZONTAL DILUTION OF	*
0100	C *		PRECISION	*
0101	C *	LAT	--> LATITUDE	*
0102	C *	LON	--> LONGITUDE	*
0103	C *	PI,PI2	--> PI(3.1415,...) AND 2*PI	*
0104	C *	RTD	--> RADIAN TO DEGREE CONVERSION	*
0105	C *		FACTOR (180/PI)	*
0106	C *	RBAR	--> LENGTH OF VECTOR USER-SATEL.	*
0107	C *	S (4)	--> SATELLITE-POSITION IN ECEF	*
0108	C *	SGC	--> SQUARE ROOT OF GRAVITATIONAL	*
0109	C *		CONSTANT OF THE EARTH	*
0110	C *		ALL TIMES IN GMT AND IN SECONDS	*
0111	C *	T	--> GPS TIME	*
0112	C *	TC	--> COLLECTION TIME,START OF	*
0113	C *		COUNT AT BEGINNING OF EPOCH	*
0114	C *	TCY	--> TIME OF COLLECTION STARTING	*
0115	C *		AT BEGINNING OF YEAR	*
0116	C *	TDEL	--> TIME INCREMENT	*
0117	C *	TFIN	--> END TIME	*
0118	C *	TKC	--> DIFFERENCE BETWEEN COLLEC-	*

```

0119 C *                                TIONTIME AND REFERENCE TIME, *
0120 C *                                WRAPAROUNDS CONSIDERED *
0121 C *                                TUY --> TIME OF USE *
0122 C *                                U (4) --> USER POSITION IN ECEF-COORD, *
0123 C *
0124 C *****
0125 C
0126 C
0127     IMPLICIT DOUBLE PRECISION(A-H,K-Z)
0128     REAL A1,A2,T2,T1,TOUT
0129     DIMENSION AD(14,4),ID(4),INAM(3)
0130     COMMON/TIME/TDEL,TFIN
0131     COMMON/AZM/ELV(4),AZM(4)
0132     COMMON/POS/LAT,LON,ALT,R
0133     COMMON/NAC/TUY,TCY,TKC,DTC(4),DTU,TC,T
0134     COMMON/CNST/PI,RTD,OMF,AE,E2,OMF2,SGC,ERATE,PI2
0135     COMMON/DB2/AD1(14)
0136     COMMON/DTX/U(4),D(4,4)
0137     COMMON/SAT/S(4)
0138     COMMON/ALM/AD2(14,24),ID1(24)
0139     COMMON/HOOP/HOCP,INS,GDOP
0140     ISAT=0
0141 C .....
0142 C             INPUT
0143 C
0144 C ***** INPUT THE LATITUDE, LONGITUDE AND THE ALTITUDE *****
0145 C             LON WEST AND LAT SOUTH ARE DENOTED BY A NEGATIVE VALUE
0146 C
0147     WRITE (16,1)
0148 1     FORMAT (// " INPUT USER POSITION"
0149           1/ " ATLANTIC CITY (=1) OTHER POSITION (=2)"
0150           2/ " ANSWER :_" )
0151     READ (16,98) IST
0152     IF(IST.EQ.2) GOTO 1001
0153 C -----
0154     LAT=0.395D2
0155     LON=-0.745D2
0156     ALT=0.1D3
0157     GOTO 1002
0158 C -----
0159 1001 CONTINUE
0160     WRITE (16,2)
0161 2     FORMAT (// " USER POSITION IN DEGREES (FORMAT :G15.8)"
0162           1/ " LATITUDE :_" )
0163     READ (16,97) LAT
0164     WRITE (16,3)
0165 3     FORMAT (" LONGITUDE :_" )
0166     READ (16,97) LON
0167     WRITE (16,4)
0168 4     FORMAT (" ALTITUDE IN FEET :_" )
0169     READ (16,97) ALT
0170 1002 CONTINUE
0171 C -----
0172     WRITE (6,50) LAT,LON,ALT
0173 50     FORMAT (" PROGRAM * H D 0 0 *"
0174           1/ " -----"
0175           2// " USER-POSITION : "
0176           3/ " LATITUDE :",G15.8," DEGREE"
0177           4/ " LONGITUDE:",G15.8," DEGREE"
0178           5/ " ALTITUDE :",G15.8," FEET")

```

```

0179      LAT=LAT/RTD
0180      LON=LON/RTD
0181      ALT=ALT/0.32809D1
0182 C
0183 C ***** EB02 COMPUTES E-MATRIX *****
0184 C
0185      CALL EB02
0186 C
0187 C ***** EB03 TAKES LAT, LON, AND ALT; *****
0188 C      IT RETURNS X,Y,Z IN U-VECTOR
0189 C
0190      CALL EB03
0191      WRITE (6,51) (U(I),I=1,3)
0192 51      FORMAT (/" ECEF-COORDINATES :",7X,"X",14X,"Y",14X,"Z"
0193      1/"
0194      U(4)=0.
0195 C
0196 C ***** READ USER TIME *****
0197 C
0198      WRITE (16,7)
0199 7      FORMAT (/" USER TIME (FORMAT : G15.8)"
0200      1/"
0201      2/" STARTTIME (T),ENDTIME (TFIN) TIME INCREMENT (TDEL)"
0202      3/" AND ALMANAC COLLECTION TIME (TC) IN SECONDS."
0203      4/"
0204      5/" START OF COUNT : T,TFIN,TDEL --> EVERY DAY AT 00:00"
0205      6/" TC --> BEGINNING OF EPOCH"
0206      7/" TSTART=_")
0207 8      READ (16,97) T
0208      WRITE (16,8)
0209      FORMAT (" TFIN =_")
0210      READ (16,97) TFIN
0211      WRITE (16,9)
0212      FORMAT (" TDEL =_")
0213      READ (16,97) TDEL
0214      WRITE (16,32)
0215      FORMAT (" TC =_")
0216      READ (16,97) TC
0217      WRITE (16,10)
0218      FORMAT (" DATE OF USE IN DAYS FROM JANUARY,FIRST :_")
0219      READ (16,97) DTU
0220      WRITE (16,31)
0221 31      FORMAT ( " 3 OR 4 SATELLITES FOR HDOP-COMPUTATION :_")
0222      READ (16,98) INS
0223 C -----
0224      CALL EB12(T,T1)
0225      CALL EB12(TFIN,T2)
0226      WRITE (6,52) T,T1,TFIN,T2,TDEL,DTU
0227 52      FORMAT (/" USERTIMES : "
0228      1/"
0229      2/" START (TSTART): ",G15.8," SEC. = ",F5.2," HOURS"
0230      3/" END (TFIN) : ",G15.8," SEC. = ",F5.2," HOURS"
0231      4/" INCR. (TDEL) : ",G15.8," SEC"
0232      5/" DATE (DTU) : ",G15.8," DAYS")
0233 C
0234 C ***** READ ALMANACS *****
0235 C
0236      WRITE (16,12)
0237 12      FORMAT ( " ALMANAC-DATA FROM TAPE (=1) ? _")
0238      READ (16,98) IST1
0239 1000      CONTINUE
0240      ISAT=ISAT+1
0241      IF(IST1.EQ.1) GOTO 1009

```

```

0239      WRITE (16,13) ISAT
0240 13      FORMAT (/" OWN ALMANAC =1 OR DATA FROM FILE =2 FOR SV NO.",I2,"?"
0241      1/" " ANSWER :_"")
0242      READ (16,98) IST
0243      IF(IST.EQ.1) GOTO 1005
0244 C -----
0245      WRITE (16,14)
0246 14      FORMAT (/" FILENAME :_"")
0247      READ(16,92) INAM
0248      OPEN (2,FILE=INAM,FORM='FORMATTED')
0249      READ (2,96) DTC(ISAT),ID(ISAT)
0250      READ (2,91) (AD(I,ISAT),I=1,4)
0251      READ (2,91) (AD(I,ISAT),I=5,8)
0252      CLOSE(2)
0253      WRITE (16,15) ID(ISAT)
0254 15      FORMAT ( " SATELLITE ID = ",I2)
0255      GOTO 1010
0256 C -----
0257 1005     CONTINUE
0258      WRITE (16,16) ISAT
0259 16      FORMAT ( " ##### ALMANAC-DATA FOR SATELLITE ",I2,"#####")
0260      1/" " FORMAT :D12.4"
0261      2/" " DATE OF COLLECTION :_"")
0262      READ (16,99) DTC(ISAT)
0263      WRITE (16,17)
0264 17      FORMAT ( " EXCENTRICITY :_"")
0265      READ (16,99) AD(1,ISAT)
0266      WRITE (16,18)
0267 18      FORMAT ( " REFERENCE TIME :_"")
0268      READ (16,99) AD(2,ISAT)
0269      WRITE (16,19)
0270 19      FORMAT ( " ORBIT INCLINATION (IO) :_"")
0271      READ (16,99) AD(3,ISAT)
0272      WRITE (16,20)
0273 20      FORMAT ( " DRIFT RATE OF (IO) :_"")
0274      READ (16,99) AD(4,ISAT)
0275      WRITE (16,21)
0276 21      FORMAT ( " SQUARE ROOT OF GREAT HALF-AXIS :_"")
0277      READ (16,99) AD(5,ISAT)
0278      WRITE (16,22)
0279 22      FORMAT ( " RIGHT ASCENSION OF ORBIT :_"")
0280      READ (16,99) AD(6,ISAT)
0281      WRITE (16,23)
0282 23      FORMAT ( " ARGUMENT OF PERIGEE :_"")
0283      READ (16,99) AD(7,ISAT)
0284      WRITE (16,24)
0285 24      FORMAT ( " MEAN ANOMALY :_"")
0286      READ (16,99) AD(8,ISAT)
0287      WRITE (16,25)
0288 25      FORMAT ( " SATELLITE ID :_"")
0289      READ (16,98) ID(ISAT)
0290      GOTO 1010
0291 C -----
0292 1009     CONTINUE
0293      IF(ISAT.NE.1) GOTO 1010
0294      CALL EB14
0295      DO 107 I1=1,4
0296 1011     CONTINUE
0297      WRITE (16,26) I1
0298 26      FORMAT ( " ID OF SATELLITE (",I2,") :_"")

```

```

0299      READ (16,98) ID(I1)
0300      DO 108 I2=1,24
0301      IF(ID(I1).NE.ID1(I2).AND.I2.LT.24) GOTO 108
0302      IF(ID(I1).EQ.ID1(I2)) GOTO 1012
0303      WRITE (16,27) ID(I1)
0304 27      FORMAT ( " =====> SATELLITE ALMANAC OF SAT,(",I2,") NOT ON"
0305          1" TAPE !! <=====")
0306      GOTO 1011
0307 108      CONTINUE
0308 1012      CONTINUE
0309      DO 107 I3=1,8
0310      AD(I3,I1)=AD2(I3,I2)
0311      ID(I1)=ID1(I2)
0312 107      CONTINUE
0313  C -----
0314 1010      CONTINUE
0315      AD(9,ISAT)=AD(5,ISAT)**2
0316      AD(10,ISAT)=COS(AD(3,ISAT))
0317      AD(11,ISAT)=SIN(AD(3,ISAT))
0318      AD(12,ISAT)=COS(AD(7,ISAT))
0319      AD(13,ISAT)=SIN(AD(7,ISAT))
0320      AD(14,ISAT)=SGC/(AD(5,ISAT)*AD(9,ISAT))
0321      IF(ISAT.LT.INS) GOTO 1000
0322  C .....
0323  C
0324  C ***** OUTPUT ALMANAC *****
0325  C
0326      A1=SNGL(DTC(1))
0327      A2=SNGL(TC)
0328      WRITE (6,53) A1,A2,(ID(I),I=1,4)
0329 53      FORMAT (/ "      USED ALMANACS          DTC= ",F5.0,"      TC= ",F7.0,
0330          1/      "      ----- "
0331          2/      " SAT. ID : ",I3,19X,I3,19X,I3,19X,I3)
0332      WRITE (6,54) ((AD(I,J),J=1,4),I=1,14)
0333 54      FORMAT (4(10X,D12.4,))
0334  C .....
0335  C          CALCULATIONS AND OUTPUT
0336  C
0337  C ***** WRITE TITLE *****
0338  C
0339      WRITE (6,61)
0340 61      FORMAT (/ " OUTPUT OF COMPUTATIONS "
0341          1/      " ----- "
0342          2//      " ===== "
0343          2/      " ! THE PRINTOUT IS ARRANGED AS FOLLOWING EXAMPLE : ! "
0344          3/      " ! ----- ! "
0345          4/      " ! TIME ! "
0346          5/      " ! POSITION OF SATELLITES IN ECEF-COORDINATES (X,Y,Z)! "
0347          6/      " ! AND ELEVATION AND AZIMUTH (3-4 LINES) ! "
0348          7/      " ! - - - - - ! "
0349          8/      " ! HDOP AND GDOP ! "
0350          9/      " ! ----- ! "
0351          A/      " ! ALL VALUES ARE IN METER ! "
0352          B/      " =====")
0353      WRITE (16,29)
0354 29      FORMAT ( " NAME OF PLOTFILE :_")
0355      READ (16,92) INAM
0356      OPEN(2,FILE=INAM,FORM='FORMATTED')
0357      WRITE (2,92) INAM
0358      WRITE (2,98) INS

```

```

0359 C
0360 C ----- BEGINNING OF COMPUTATION-LOOP ----->
0361 C
0362 DTU=(DTU-1.)*0.86405
0363 TCY=(DTC(1)-1.)*0.86405+DMOD(TC,0.86405)
0364 1004 CONTINUE
0365 CALL EB12 (T,TOUT)
0366 WRITE (6,70)
0367 WRITE (6,62) TOUT
0368 62 FORMAT ( " TIME : ",F7.4," HOURS ")
0369 DO 102 I=1,INS
0370 DO 101 J=1,14
0371 ADI(J)=AD(J,I)
0372 101 CONTINUE
0373 C
0374 C ***** COMPUTATION OF POSITION,DISTANCE TO USER *****
0375 C AND AZIMUTH AND ELEVATION OF SATELLITE(I)
0376 C
0377 II=I
0378 CALL EB05(II)
0379 102 CONTINUE
0380 C
0381 C ***** COMPUTATION OF INVERTED G-MATRIX,HDOP AND GDOP *****
0382 C
0383 CALL HD01
0384 WRITE (6,71)
0385 WRITE (6,63) HDOP,GDOP
0386 63 FORMAT (G15.8,5X,G15.8)
0387 A1=SNGL(HDOP)
0388 A2=SNGL(GDOP)
0389 TOUT=SNGL(T)/3600.
0390 WRITE (2,90) TOUT,A1,A2
0391 WRITE (6,70)
0392 T=T+TDEL
0393 IF (T.LE.TFIN) GOTO 1004
0394 C <----- END OF COMPUTATION-LOOP-----<--
0395 C
0396 C ***** WRITE END-CRITERIA TO PLOTFILE *****
0397 C
0398 TOUT=0.
0399 A1=0.
0400 A2=0.
0401 WRITE (2,90) TOUT,A1,A2
0402 CLOSE (2)
0403 STOP
0404 C
0405 C ***** FORMATS *****
0406 C
0407 70 FORMAT ( " ----- " )
0408 71 FORMAT ( " - - - - - " )
0409 90 FORMAT (1X,3F12.6)
0410 91 FORMAT (4D18.8)
0411 92 FORMAT (3A2)
0412 93 FORMAT (I4)
0413 94 FORMAT (4E12.4)
0414 95 FORMAT (A4)
0415 96 FORMAT (G15.8,I3)
0416 97 FORMAT(G15.8)
0417 98 FORMAT(I2)
0418 99 FORMAT(D12.4)

```

0419
0420

END

&PLHG T=00004 IS ON CR00011 USING 00018 BLKS R=0000

```
0001 FTH4X,L,Y
0002 $FILES (1,1)
0003 PROGRAM PLHG
0004 C *****
0005 C * FILENAME : &PLHG *
0006 C * ***** *
0007 C * PROGRAM PLOTS DATA FILES GENERATED BY THE PROGRAM "H000" *
0008 C * TO COMPARE THE HDOP'S COMPUTED FOR A SITUATION WITH FOUR *
0009 C * SATELLITES (PLOTFILE 1) AND WITH THREE SATELLITES (PLOT- *
0010 C * FILE 2), *
0011 C * *
0012 C * - - - - - *
0013 C * USED SUBROUTINES : DLTBL,GPS (PLOTLIBRARY) *
0014 C * *
0015 C *****
0016 C
0017 DIMENSION IGCB(192),INAM1(3),INAM2(3)
0018 LOGICAL LOG
0019 C
0020 C ***** READ NAME OF FILE,LOGICAL UNIT AND ID OF *****
0021 C DEVICE SUB *****
0022 C
0023 LOG=.TRUE.
0024 WRITE (16,1)
0025 1 FORMAT ( " NAME OF PLOTFILE 1 :_" )
0026 READ (16,92) INAM1
0027 OPEN (2,FILE=INAM1,FORM='FORMATTED')
0028 READ (2,92) INAM1
0029 READ (2,93) INS
0030 WRITE (16,3)
0031 3 FORMAT ( " LOGICAL UNIT (LU) AND ID OF DEVICE-SUBROUTINE"
0032 1/ " LU =_" )
0033 READ (16,93) LU
0034 WRITE (16,4)
0035 4 FORMAT ( " ID =_" )
0036 READ (16,93) ID
0037 C
0038 C ***** INITIALIZE PLOTTER AND DRAW GRID *****
0039 C
0040 WRITE (16,5)
0041 5 FORMAT ( " START-AND ENDTIME IN HOURS."
0042 1/ " TSTART :_" )
0043 READ (16,94) TSTART
0044 WRITE (16,6)
0045 6 FORMAT ( " TEND :_" )
0046 READ (16,94) TEND
0047 CALL PLOTR (IGCB,ID,1,LU)
0048 CALL SETAR (IGCB)
0049 CALL FRAME (IGCB)
0050 CALL VIEWP (IGCB,30.,90.,20.,60.)
0051 CALL WINDW (IGCB,TSTART,TEND,0.,20.)
0052 CALL FXD (IGCB,2)
0053 CALL LGRID (IGCB,-0.25,5.,0.,0.,1.,1.,1.)
0054 C
0055 C ***** DATA INPUT FROM FILES AND PLOT *****
0056 C
0057 CALL LINE (IGCB,0)
0058 1000 CONTINUE
```

```

0059      READ (2,95) TOUT,HDOP,GDOP
0060      IF<LOG> CALL MOVE (IGCB,TOUT,HDOP)
0061      LOG=.FALSE.
0062      IF<TOUT.LT.0.01.AND.HDOP.LT.0.01> GOTO 1001
0063      CALL DRAW<IGCB,TOUT,HDOP>
0064      GOTO 1000
0065 1001  CONTINUE
0066      CLOSE<2>
0067  C -----
0068      WRITE (16,2)
0069  2      FORMAT ( " NAME OF PLOTFILE 2 :_" )
0070      READ (16,92) INAM2
0071      OPEN (3,FILE=INAM2,FORM='FORMATTED')
0072      READ (3,92) INAM2
0073      READ (3,93) INS2
0074      CALL LINE<IGCB,1>
0075      LOG=.TRUE.
0076 1002  CONTINUE
0077      READ (3,95) TOUT,HDOP,GDOP
0078      IF<LOG> CALL MOVE (IGCB,TOUT,HDOP)
0079      LOG=.FALSE.
0080      IF<TOUT.LT.0.01.AND.HDOP.LT.0.01> GOTO 1003
0081      CALL DRAW (IGCB,TOUT,HDOP)
0082      GOTO 1002
0083 1003  CONTINUE
0084      CLOSE (3)
0085  C
0086  C ***** PLACE TITLES AND OTHER INFORMATION *****
0087  C
0088      CALL VIEWP (IGCB,10.,100.,10.,90.)
0089      CALL WINDW (IGCB,10.,100.,10.,90.)
0090      CALL MOVE (IGCB,55.,80.)
0091      CALL CPLOT (IGCB,-11.,0.,0)
0092      CALL LABEL (IGCB)
0093      WRITE (LU,7)
0094  7      FORMAT ("GRAPH OF HDOP VS. TIME")
0095      CALL MOVE (IGCB,55.,10.)
0096      CALL CPLOT (IGCB,-8.,0.,0)
0097      CALL LABEL (IGCB)
0098      WRITE (LU,8)
0099  8      FORMAT ("GNT-TIME IN HOURS")
0100      CALL MOVE (IGCB,1.,50.)
0101      CALL LABEL (IGCB)
0102      WRITE (LU,9)
0103  9      FORMAT ("HDOP")
0104      CALL LINE (IGCB,0)
0105      CALL MOVE (IGCB,30.,70.)
0106      CALL DRAWI (IGCB,15.,0.)
0107      CALL MOVEI (IGCB,2.,0.)
0108      CALL CPLOT (IGCB,0.,-0.25,0)
0109      CALL LABEL (IGCB)
0110      WRITE (LU,10)
0111 10      FORMAT ("4 SAT.")
0112      CALL LINE (IGCB,1)
0113      CALL MOVE (IGCB,65.,70.)
0114      CALL DRAWI (IGCB,15.,0.)
0115      CALL MOVEI (IGCB,2.,0.)
0116      CALL CPLOT (IGCB,0.,-0.25,0)
0117      CALL LABEL (IGCB)
0118      WRITE (LU,11)

```

```

0119 11    FORMAT ("3 SAT.")
0120      CALL PLOTR (IGCB,ID,0)
0121 C
0122 C ***** FORMATS *****
0123 C
0124 92    FORMAT (3A2)
0125 93    FORMAT (I2)
0126 94    FORMAT (F8.6)
0127 95    FORMAT (1X,3F12.6)
0128      CALL PLOTR (IGCB,ID,0)
0129      STOP
0130      END

```

&EBGD1 T=00004 IS ON CR00011 USING 00018 BLKS R=0000

```
0001  FTN4X,L,Y
0002  C *****
0003  C *   FILENAME : &EBGD1   *
0004  C *****
0005      BLOCK DATA
0006      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
0007      COMMON/MAT/HT(4,4),H(4,4),HTH(4,4)
0008      END
0009      PROGRAM EBGD1
0010  C *****
0011  C *   ROUTINE TO CALCULATE GDOP WITH INSERTED H-MATRIX OR WITH   *
0012  C *   AZIMUTH- AND ELEVATIONANGLE.                               *
0013  C *                                                                *
0014  C *   - - - - -
0015  C *   USED SUBROUTINES : EB09                                     *
0016  C *                               MINVD                             *
0017  C *   - - - - -
0018  C *   MICHAEL J. MAGROGAN   CO-OP   ACT-100D   FEBRUARY 1981      *
0019  C *   ERHARD BUCHBERGER    ACT-100B   APRIL 1982                  *
0020  C *****
0021  C
0022      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
0023      DIMENSION AZ(4),EL(4),HPROD(4,4),L(4),M(4)
0024      COMMON/MAT/HT(4,4),H(4,4),HTH(4,4)
0025      N=4
0026      RTD=57.2957795
0027  C .....
0028  C                               INPUT
0029  C
0030  C ***** INPUT H-MATRIX OR ANGLES *****
0031  C
0032      WRITE (6,17)
0033  17  FORMAT ( " PROGRAM *EBGD1*"
0034      1/      " *****" )
0035      WRITE (16,9)
0036  9    FORMAT ( " SELECT INPUT : "
0037      1/      " H-MATRIX=1      ANGLES=2"
0038      2/      " ANSWER      :_" )
0039      READ (16,91) IST
0040      IF(IST.EQ.2) GOTO 1002
0041  C -----
0042      DO 100 I=1,4
0043      DO 100 J=1,4
0044      WRITE (16,10) I,J
0045  10  FORMAT ( " ELEMENT (",I2,",",I2,") :_" )
0046      READ (16,90) H(I,J)
0047  100 CONTINUE
0048      GOTO 1003
0049  C -----
0050  1002 CONTINUE
0051      WRITE (6,15)
0052  15  FORMAT (// " AZIMUTH      ELEVATION" )
0053      DO 103 I=1,4
0054      WRITE (16,13) I
0055  13  FORMAT ( " AZIMUTH(",I2,") :_" )
0056      READ (16,90) AZ(I)
0057      WRITE (16,14) I
0058  14  FORMAT ( " ELEVATION(",I2,") :_" )
```

```

0059      READ (16,90) EL(I)
0060      WRITE (6,16) AZ(I),EL(I)
0061  16      FORMAT (2D12.4)
0062      AZ(I)=AZ(I)/RTD
0063      EL(I)=EL(I)/RTD
0064      H(I,1)=COS(EL(I))*COS(AZ(I))
0065      H(I,2)=COS(EL(I))*SIN(AZ(I))
0066      H(I,3)=SIN(EL(I))
0067      H(I,4)=1.
0068  103     CONTINUE
0069  C -----
0070  1003     CONTINUE
0071      WRITE (6,4)
0072  4        FORMAT (// " H-MATRIX " )
0073      WRITE (6,5) ((H(I,J),J=1,4),I=1,4)
0074  5        FORMAT (4D16.8)
0075  C .....
0076  C                                COMPUTATIONS
0077  C
0078  C ***** COMPUTE THE TRANSPOSE OF THE H MATRIX *****
0079  C
0080      DO 101 I=1,4
0081      DO 101 J=1,4
0082      HT(I,J)=H(J,I)
0083  101      CONTINUE
0084      WRITE (6,6)
0085  6        FORMAT (/" H-TRANSPOSE-MATRIX " )
0086      WRITE (6,5) ((HT(I,J),J=1,4),I=1,4)
0087  C
0088  C ***** CALL EB09 TO MULTIPLY THE H AND H TRANSPOSE *****
0089  C                                MATRIX
0090  C
0091      CALL EB09
0092      WRITE (6,7)
0093  7        FORMAT (/" HT*H-MATRIX " )
0094      WRITE (6,5) ((HTH(I,J),J=1,4),I=1,4)
0095  C
0096  C ***** CALL MINVD TO COMPUTE THE INVERSE OF THE H AND *****
0097  C                                H TRANSPOSE PRODUCT MATRIX
0098  C
0099      DO 102 I=1,4
0100      DO 102 J=1,4
0101      HPROD(I,J)=HTH(I,J)
0102  102      CONTINUE
0103      CALL MINVD (HPROD,N,DET,L,M)
0104      IF (DET.LT.1.0D-5) GOTO 1000
0105      WRITE (6,8)
0106  8        FORMAT (/" INVERTED HT*H-MATRIX " )
0107      WRITE (6,5) ((HPROD(I,J),J=1,4),I=1,4)
0108  C
0109  C ***** THE TRACE OF THE MATRIX IS THE SUM OF ITS *****
0110  C                                ELEMENTS
0111  C
0112      TRACEZ=HPROD(1,1)+HPROD(2,2)
0113      HDOPV=DSQRT(TRACEZ)
0114      TRACEZ=TRACEZ+HPROD(3,3)+HPROD(4,4)
0115      GDOPV=DSQRT(TRACEZ)
0116      GOTO 1001
0117  C -----
0118  1000     CONTINUE

```

```

0119      WRITE (16,1) DET
0120 1      FORMAT ( " DETERMINANT OF MATRIX : ",D16.8)
0121      WRITE (6,12)
0122      WRITE (16,12)
0123 12      FORMAT ( " ***** "
0124      1/      " *HT*H-MATRIX IS SINGULAR (DETERMINANT=0.)* "
0125      2/      " ***** " )
0126      STOP1
0127 C -----
0128 1001 CONTINUE
0129      HDOP=SNGL(HDOPV)
0130      GDOP=SNGL(GDOPV)
0131      WRITE (16,11) HDOP,GDOP
0132      WRITE (6,11) HDOP,GDOP
0133 11      FORMAT ( " HDOP = ",F15.8," GDOP = ",F15.8)
0134 C
0135 C ***** FORMATS *****
0136 C
0137 90      FORMAT (D16.8)
0138 91      FORMAT (I2)
0139      STOP
0140      END

```

%EBGH T=00004 IS ON CR00011 USING 00024 BLKS R=0000

```
0001 FTN4X,L,Y
0002 C *****
0003 C *   FILENAME : %EBGH   *
0004 C *****
0005     BLOCK DATA
0006     DOUBLE PRECISION ENUP,XP,YP,ZP,H,HT,HPROD,HDOVP,GDOVP
0007     DOUBLE PRECISION PI,RTD,OMF,AE,E2,OMF2,U,LAT,LON,ALT
0008     DOUBLE PRECISION XS,YS,ZS,TRACEZ,X,Y,Z,NORM
0009     DOUBLE PRECISION SGC,ERATE,XY
0010     COMMON/COORD/ENUP(3,3),XP,YP,ZP,H(4,4),HT(4,4),HPROD(4,4),
0011     +LSAT(4),XS(4),YS(4),ZS(4),HDOVP,GDOVP
0012     COMMON/CNST/PI,RTD,OMF,AE,E2,OMF2,SGC,ERATE
0013     COMMON/DTX/U(4)
0014     COMMON/POS/LAT,LON,ALT,XY
0015     END
0016     PROGRAM EBGH
0017 C *****
0018 C *   ROUTINE TO CALCULATE HDOP,PDOP AND GDOP WITH PROMPTED   *
0019 C *   USER- AND SATELLITE-POSITIONS.                           *
0020 C *   INPUT IS POSSIBLE OVER THE KEYBOARD OR FROM A DATAFILE. *
0021 C *                                                             *
0022 C * - - - - - - - - - - - - - - - - - - - - - - - - - - - *
0023 C *   THE ORIGINAL PROGRAM WAS MADE BY MICHAEL J. MAGROGAN,CO-OP,*
0024 C *   ACT 100B, ALSO THE SUBROUTINES "ENU","HTRAN","MLHHT","INVHP",*
0025 C *                                                             *
0026 C *   FURTHER USED SUBROUTINES : EB03,EB12                       *
0027 C *                                                             *
0028 C * - - - - - - - - - - - - - - - - - - - - - - - - - - - *
0029 C *   THE COMMON-BLOCKS ARE DEFINED TO FIT THE PROGRAM "HD00".  *
0030 C *                                                             *
0031 C *****
0032 C
0033     DIMENSION IBUF(69),IDCB(144),NAME(3),ISATV(4)
0034     COMMON /COORD/ ENUP(3,3),XP,YP,ZP,H(4,4),HT(4,4),HPROD(4,4),
0035     +LSAT(4),XS(4),YS(4),ZS(4),HDOVP,GDOVP
0036     COMMON/CNST/PI,RTD,OMF,AE,E2,OMF2
0037     COMMON/DTX/U(4)
0038     COMMON/POS/LAT,LON,ALT
0039     DOUBLE PRECISION ENUP,XP,YP,ZP,H,HT,HPROD,HDOVP,GDOVP,PDOPV
0040     DOUBLE PRECISION PI,RTD,OMF,AE,E2,OMF2,U,LAT,LON,ALT
0041     DOUBLE PRECISION XS,YS,ZS,TRACEZ,X,Y,Z,NORM,TIME,BUF(15)
0042     EQUIVALENCE (IBUF,TIME),(IBUF(5),BUF),(IBUF(65),ISATV)
0043     REAL LAT1,LON1
0044 C
0045 C ***** DEFINITION OF CONSTANTS *****
0046 C
0047     RTD=57.2957795D0
0048     AE=6.378135D6
0049     E2=6.694317778D-3
0050     OMF2=0.993305683D0
0051 C
0052 C ***** THIS PROGRAM NEEDS AIRPLANE POSITION(XP,YP,ZP) *****
0053 C   AND FOUR SATELLITE POSITIONS (XS(1-4),YS(1-4),ZS(1-4)) AS INPUTS
0054 C
0055     WRITE (16,10)
0056 10    FORMAT ( " COORDINATES INPUT FROM FILE (=1) ?  _" )
0057     READ (16,92) IST
0058     IF(IST.EQ.1) GOTO 1000
```

```

0059 C .....
0060 C             INPUT OVER KEYBOARD
0061 C
0062 C ***** USER POSITION *****
0063 C
0064     WRITE (16,1)
0065 1     FORMAT ( " INPUT USER POSITION IN GEOGR. COORDINATES (ALTITUDE
0066     1 IN FEET)"
0067     2/         " LATITUDE :_" )
0068     READ (16,91) LAT1
0069     WRITE (16,2)
0070 2     FORMAT ( " LONGITUDE:_" )
0071     READ (16,91) LON1
0072     WRITE (16,3)
0073 3     FORMAT ( " ALTITUDE :_" )
0074     READ (16,91) ALT1
0075     LAT=DBLE(LAT1)/RTD
0076     LON=DBLE(LON1)/RTD
0077     ALT=DBLE(ALT1)/0.32809D1
0078 C
0079 C ***** COMPUTE ECEF-COORDINATES WITH SUBR. EB03 *****
0080 C
0081     CALL EB03
0082     XP=U(1)
0083     YP=U(2)
0084     ZP=U(3)
0085     WRITE (6,4) LAT1,LON1,ALT1,XP,YP,ZP
0086 4     FORMAT ( " PROGRAM *EBGH*          VERSION A"
0087     1/         " *****"
0088     2//         " USER-COORDINATES : "
0089     3/         " LAT =",G15.8," LON =",G15.8," ALT =",G15.8,
0090     4/         " XP =",G15.8," YP =",G15.8," ZP =",G15.8)
0091 C
0092 C ***** SATELLITE-POSITION *****
0093 C
0094     WRITE (16,15)
0095 15    FORMAT ( " HOW MANY SATELLITES ? :_" )
0096     READ (16,92) NSAT
0097     IST2=1
0098     WRITE (16,5)
0099 5     FORMAT ( " INPUT SATELLITE-POSITION IN ECEF." )
0100     DO 101 I=1,NSAT
0101     WRITE (16,6) I
0102 6     FORMAT ( " XS(",I2,") =_" )
0103     READ (16,90) XS(I)
0104     WRITE (16,7) I
0105 7     FORMAT ( " YS(",I2,") =_" )
0106     READ (16,90) YS(I)
0107     WRITE (16,8) I
0108 8     FORMAT ( " ZS(",I2,") =_" )
0109     READ (16,90) ZS(I)
0110     WRITE (6,9) I,XS(I),YS(I),ZS(I)
0111 9     FORMAT ( " SAT.NO :",I2," XS =",D16.8," YS =",D16.8," ZS ="
0112     1,D16.8)
0113 101   CONTINUE
0114     GOTO 1001
0115 C .....
0116 C
0117 C             INPUT FROM FILE
0118 C

```

```

0119 C   BECAUSE OF RESTRICTION IN THE SUBROUTINES THE SYSTEM HAS TO BE
0120 C   ALTIMETER AIDED.
0121 C
0122 1000 CONTINUE
0123     WRITE (16,11)
0124 11     FORMAT ( " FILENAME :_" )
0125     READ (16,93) NAME
0126     CALL OPEN (IDCB,IERR,NAME,0,0)
0127     IF(IERR.LT.0) STOP1
0128     WRITE (6,12) NAME
0129 12     FORMAT ( " PROGRAM *EBGH*          VERSION B"
0130             1/          " *****"
0131             2//          " FILENAME : ",3A2,/)
0132     NUM=1
0133     NSAT=4
0134     WRITE (16,16)
0135 16     FORMAT ( " SYSTEM ALTIMETER AIDED (=1) ? :_" )
0136     READ (16,92) IST2
0137 1002 CONTINUE
0138     CALL READF (IDCB,IERR,IBUF,068,LEN,NUM)
0139     IF(IERR.LT.0) STOP2
0140     XP=BUF(1)
0141     YP=BUF(2)
0142     ZP=BUF(3)
0143     I=0
0144     DO 102 K=1,4
0145     IF(ISATV(K).EQ.0) GOTO 102
0146     I=I+1
0147     ISATV(I)=ISATV(K)
0148     XS(I)=BUF(K+3)
0149     YS(I)=BUF(K+7)
0150     ZS(I)=BUF(K+11)
0151 102 CONTINUE
0152     IF(I-3) 1004,1005,1006
0153 C -----
0154 1004 WRITE (16,22)
0155 22     FORMAT ( " *****"
0156             1/          " *ONLY TWO SATELLITES IN FILE*"
0157             2/          " *****" )
0158     STOP3
0159 C -----
0160 1005 NSAT=3
0161 1006 CONTINUE
0162     CALL EB12(TIME,TOUT)
0163     WRITE (6,13) NUM,TIME,TOUT,XP,YP,ZP
0164 13     FORMAT ( " RECORD-NO. : ",I3,
0165             1/          " TIME : ",D14,6," SEC. ==> ",F8,4," HOURS GMT"
0166             2/          " USERPOSITION ---> ",3D16,8,
0167             3/          " SATELLITE-POSITIONS : "
0168             4/,10X,"XS",14X,"YS",14X,"ZS")
0169     WRITE (6,14) ((ISATV(I),XS(I),YS(I),ZS(I)),I=1,NSAT)
0170 14     FORMAT (I3,3D16,8)
0171 C .....
0172 C                               COMPUTATIONS
0173 C
0174 C ***** CALL ENU TO FILL ENUP MATRIX *****
0175 C
0176 1001 CONTINUE
0177     CALL ENU
0178 C

```

```

0179 C ***** FILL COLUMN 4 OF H MATRIX WITH 1'S. *****
0180 C
0181     DO 40 I=1,4
0182         H(I,4)=1.D0
0183     40 CONTINUE
0184     IF(NSAT.EQ.4) GOTO 1003
0185     IF(IST2.NE.1) GOTO 1003
0186     H(4,1)=0.
0187     H(4,2)=0.
0188     H(4,3)=-1.
0189     H(4,4)=0.
0190 1003 CONTINUE
0191     DO 50 I=1,NSAT
0192 C
0193 C ***** SATELLITE POSITION VECTOR MINUS AIRPLANE *****
0194 C             POSITION VECTOR
0195 C
0196         X=XS(I)-XP
0197         Y=YS(I)-YP
0198         Z=ZS(I)-ZP
0199 C
0200 C ***** MAGNITUDE OF THE VECTOR BETWEEN THE SATELLITE *****
0201 C             AND THE AIRPLANE
0202 C
0203         NORM=DSQRT(X**2+Y**2+Z**2)
0204 C
0205 C ***** UNIT VECTOR FROM THE VECTOR BETWEEN THE *****
0206 C             SATELLITE AND THE AIRPLANE
0207 C
0208         X=X/NORM
0209         Y=Y/NORM
0210         Z=Z/NORM
0211 C
0212 C ***** CONVERT FROM ECEF COORDINATES TO ENU COOR- *****
0213 C             DINATES USING ENUP-MATRIX AND FILL UP H-MATRIX
0214 C
0215         H(1,1)=ENUP(1,1)*X+ENUP(1,2)*Y+ENUP(1,3)*Z
0216         H(1,2)=ENUP(2,1)*X+ENUP(2,2)*Y+ENUP(2,3)*Z
0217         H(1,3)=ENUP(3,1)*X+ENUP(3,2)*Y+ENUP(3,3)*Z
0218     50 CONTINUE
0219     WRITE (6,17)
0220 17   FORMAT (/" H-MATRIX")
0221     WRITE (6,94) ((H(I,J),J=1,4),I=1,4)
0222 C
0223 C ***** CALL HTRAN TO COMPUTE THE TRANSPOSE OF *****
0224 C             THE H-MATRIX
0225 C
0226     CALL HTRAN
0227     WRITE (6,18)
0228 18   FORMAT (/" H-TRANSPOSE-MATRIX")
0229     WRITE (6,94) ((HT(1,J),J=1,4),I=1,4)
0230 C
0231 C ***** CALL MLHHT TO MULTIPLY THE H AND H *****
0232 C             TRANSPOSE MATRIX
0233     CALL MLHHT
0234     WRITE (6,19)
0235 19   FORMAT (/" HT*H-MATRIX")
0236     WRITE (6,94) ((HPROD(I,J),J=1,4),I=1,4)
0237 C
0238 C ***** CALL INVHP TO COMPUTE THE INVERSE OF THE H AND *****

```

```

0239 C                      HTRANSPOSE PRODUCT MATRIX
0240 C
0241      CALL INVHP
0242      WRITE (6,20)
0243 20      FORMAT (/" INVERTED H*HT-MATRIX")
0244      WRITE (6,94) ((HPROD(I,J),J=1,4),I=1,4)
0245 C
0246 C ***** THE TRACE OF THE MATRIX IS THE SUM OF ITS *****
0247 C                      DIAGONAL ELEMENTS
0248 C
0249      TRACEZ=HPROD(1,1)+HPROD(2,2)
0250      HDOPV=DSQRT(TRACEZ)
0251      PDOPV=DSQRT(TRACEZ+HPROD(3,3))
0252      TRACEZ=TRACEZ+HPROD(3,3)+HPROD(4,4)
0253      GDOPV=DSQRT(TRACEZ)
0254      HDOP=SNGL(HDOPV)
0255      PDOP=SNGL(PDOPV)
0256      GDOP=SNGL(GDOPV)
0257      IF(NSAT.EQ.3.AND.IST2.NE.1) GDOP=1.E20
0258      WRITE (6,21) HDOP,PDOP,GDOP
0259      WRITE (16,21) HDOP,PDOP,GDOP
0260 21      FORMAT ( " HDOP = ",F10.5," PDOP = ",F10.5," GDOP = ",F10.5,/)
0261      NUM=NUM+1
0262      IF(IST.EQ.1) GOTO 1002
0263 C
0264 C ***** FORMATS *****
0265 C
0266 90      FORMAT (D16.8)
0267 91      FORMAT (F15.8)
0268 92      FORMAT (I2)
0269 93      FORMAT (3A2)
0270 94      FORMAT (4D16.8)
0271      STOP
0272      END

```

&EB02 T=00004 IS ON CR00011 USING 00012 BLKS R=0000

```
0001 FTN4X,L,Y
0002 C *****
0003 C *          FILENAME : &EB02          *
0004 C *
0005 C *          PROGRAM COMPUTES THE E-MATRIX      *
0006 C *****
0007 C
0008         SUBROUTINE EB02
0009         IMPLICIT DOUBLE PRECISION (A-H,K-Z)
0010         COMMON/ELEV/E(3,3)
0011         COMMON/POS/LAT,LON,ALT,R
0012 C -----
0013         SN=DSIN(LON)
0014         CN=DCOS(LON)
0015         ST=DSIN(LAT)
0016         CT=DCOS(LAT)
0017         E(1,1)=-SN
0018         E(1,2)=CN
0019         E(1,3)=0.0
0020         E(2,1)=-CN*ST
0021         E(2,2)=-SN*ST
0022         E(2,3)=CT
0023         E(3,1)=CN*CT
0024         E(3,2)=SN*CT
0025         E(3,3)=ST
0026         RETURN
0027         END
```

&EB03 T=00004 IS ON CR00011 USING 00012 BLKS R=0000

```
0001 FTN4X,L,Y
0002 C *****
0003 C * FILENAME : &EB03 *
0004 C * *
0005 C * COMPUTES THE USER-POSITION IN ECEF-COORDINATES *
0006 C * (TU-VECTOR=U-VECTOR (IN MAINPROGRAM) ) *
0007 C * *
0008 C *****
0009 C
0010 SUBROUTINE EB03
0011 IMPLICIT DOUBLE PRECISION(A-Z)
0012 COMMON/CNST/PI,RTD,OMF,AE,E2,OMF2,SGC,ERATE
0013 COMMON/DTX/TU(4)
0014 COMMON/POS/LAT,LON,ALT,XY
0015 C -----
0016 SLAT=DSIN(LAT)
0017 XY=AE/DSQRT(1.E0-E2*SLAT*SLAT)
0018 TU(3)=(XY*OMF2+ALT)*SLAT
0019 XY=(XY+ALT)*DCOS(LAT)
0020 TU(1)=XY*DCOS(LON)
0021 TU(2)=XY*DSIN(LON)
0022 RETURN
0023 END
```

&EB05 T=00004 IS ON CR00011 USING 00012 BLKS R=0000

```
0001  FTN4X,L,Y
0002  C *****
0003  C *          FILENAME :  &EB05          *
0004  C *                                          *
0005  C *          COMPUTES ELEVATION AND AZIMUTH OF SATELLITES AND IN  *
0006  C *          SUB. "EB06" THE POSITION AND IN SUB. "EB07" THE DISTANCE *
0007  C *          USER-SATELLITE.          *
0008  C *                                          *
0009  C *****
0010  C
0011      SUBROUTINE EB05 (I)
0012      IMPLICIT DOUBLE PRECISION (A-H,K-Z)
0013      DIMENSION Y(4,3)
0014      COMMON/ELEV/E(3,3)
0015      COMMON/SAT/S(4)
0016      COMMON/AZM/ELV(4),AZM(4)
0017      COMMON/CNST/PI,RTD,DMF,AE,E2,DMF2,SGC,ERATE
0018      COMMON/DTX/U(4),D(4,4),RBAR(4)
0019  C -----
0020      CALL EB06
0021      CALL EB07(I)
0022      DO 100 II=1,3
0023      Y(I,II)=0.D0
0024      DO 100 III=1,3
0025      Y(I,II)=Y(I,II)+S(III)*E(II,III)
0026 100  CONTINUE
0027  C
0028  C ***** COMPUTATION OF ELEVATION AND AZIMUTH OF *****
0029  C          SATELLITES AND OUTPUT
0030  C
0031      Y(I,3)=Y(I,3)-AE
0032      SY=DSQRT(Y(I,1)*Y(I,1)+Y(I,2)*Y(I,2))
0033      ELV(I)=DATAN2(Y(I,3),SY)*RTD
0034      AZM(I)=DATAN2(Y(I,1),Y(I,2))*RTD
0035      IF(AZM(I).LT.0.) AZM(I)=AZM(I)+360.0
0036      WRITE (6,1) (S(J),J=1,3),ELV(I),AZM(I)
0037 1  FORMAT (5(2X,D12.4))
0038      RETURN
0039      END
```

&EB06 T=00004 IS ON CR00011 USING 00018 BLKS P=0000

```

0001 FTN4X,L,Y
0002 C *****
0003 C *                               FILENAME :  &EB06                               *
0004 C *                               *                               *
0005 C * COMPUTES THE ACTUAL POSITION OF THE SATELLITE *
0006 C * IN ECEF-COORDINATES ( S-VECTOR = X,Y,Z ) *
0007 C *                               *                               *
0008 C *****
0009 C
0010 SUBROUTINE EB06
0011 IMPLICIT DOUBLE PRECISION (A-Z)
0012 INTEGER I
0013 COMMON/NAC/TUY,TCY,TKC,DTU,TC,T
0014 COMMON/CNST/PI,RTD,OMF,AE,E2,OMF2,SGC,ERATE,PI2
0015 COMMON/SAT/X,Y,Z,MK
0016 COMMON/DB2/ECC,TOE,INOT,NRATE,SRAD,OMEO,OME,MNOT,R,CINO,
0017 *SINO,COME,SOME,C
0018 C -----
0019 A=TC-TOE
0020 TUY=DTU+T
0021 IF(A.GT.-0.302406.AND.A.LT.302406) TKC=A
0022 IF(A.LT.-0.302406) TKC=A+0.604806
0023 IF(A.GT.0.302406) TKC=A-0.604806
0024 TK=TUY-TCY+TKC
0025 OGA=OMEO+(NRATE-ERATE)*TK-ERATE*TOE
0026 MK=MNOT+C*TK
0027 6 IF(MK.GE.-PI2)GO TO 7
0028 MK=MK+PI2
0029 GO TO 6
0030 7 IF(MK.LE.PI2)GO TO 8
0031 MK=MK-PI2
0032 GO TO 7
0033 8 EK=MK+ECC*DSIN(MK)
0034 DO 100 I=1,4
0035 COSE=DCOS(EK)
0036 SINE=DSIN(EK)
0037 TK=1.-ECC*COSE
0038 100 EK=EK-(EK-MK-ECC*SINE)/TK
0039 COSE=(COSE-ECC)/TK
0040 SINE=DSQRT(1.-ECC*ECC)*SINE/TK
0041 EK=COSE*COME-SINE*SOME
0042 MK=SINE*COME+COSE*SOME
0043 SINE=2.*MK*EK
0044 COSE=2.*EK*EK-1.
0045 RK=TK*R
0046 X=RK*EK
0047 Y=RK*MK
0048 Z=Y*SINO
0049 EK=CINO*Y
0050 SINE=DSIN(OGA)
0051 COSE=DCOS(OGA)
0052 Y=X*SINE+EK*COSE
0053 X=X*COSE-EK*SINE
0054 RETURN
0055 END

```

&EB07 T=00004 IS ON CR00011 USING 00012 BLKS R=0000

```
0001 FTN4X,L,Y
0002 C *****
0003 C *          FILENAME : &EB07          *
0004 C *                                          *
0005 C *    COMPUTES DISTANCES TO SATTELLITE    *
0006 C *                                          *
0007 C *****
0008 C
0009     SUBROUTINE EB07(I)
0010     IMPLICIT DOUBLE PRECISION (A-H,K-Z)
0011     COMMON/SAT/S(4)
0012     COMMON/DTX/U(4),D(4,4),R(4)
0013 C -----
0014     R(I)=0.
0015     DO 100 J=1,3
0016     D(I,J)=S(J)-U(J)
0017     R(I)=D(I,J)*D(I,J)+R(I)
0018 100 CONTINUE
0019     R(I)=DSQRT(R(I))
0020     D(I,4)=1.0
0021     RETURN
0022     END
```

&EB09 T=00004 IS ON CR00011 USING 00012 BLKS R=0000

```
0001 FTN4X,L,Y
0002 C *****
0003 C *          FILENAME : &EB09          *
0004 C *                                          *
0005 C * MULTIPLICATES TWO MATRICES --> H*G=A *
0006 C *                                          *
0007 C *****
0008 C
0009     SUBROUTINE EB09
0010     IMPLICIT DOUBLE PRECISION (A-H,L-Z)
0011     COMMON/MAT/G(4,4),H(4,4),A(4,4)
0012 C -----
0013     DO 100 I=1,4
0014     DO 100 J=1,4
0015     TEMP=0.000
0016     DO 101 K=1,4
0017     TEMP=TEMP+H(I,K)*G(K,J)
0018 101 CONTINUE
0019     A(I,J)=TEMP
0020 100 CONTINUE
0021     RETURN
0022     END
```

&EB12 T=00004 IS ON CR00011 USING 00012 BLKS R=0000

```
0001 FTN4X,L,Y
0002 C *****
0003 C *          FILENAME : &EB12          *
0004 C *                                          *
0005 C * ROUTINE TO CONVERT SECONDS TO HOURS MIN SEC. *
0006 C *                                          *
0007 C *****
0008 C
0009     SUBROUTINE EB12 (TMIN,THR)
0010     IMPLICIT DOUBLE PRECISION (A-Z)
0011     REAL THR
0012     INTEGER*4 HR,MIN,SEC
0013 C -----
0014     THR=(SNGL(TMIN)/3600.0)+.00005
0015     HR=INT(THR)
0016     THR=(THR-HR)*60
0017     MIN=INT(THR)
0018     THR=(THR-MIN)*60
0019     SEC=INT(THR)
0020     THR=HR+(MIN*.01)+(SEC*.0001)+.00005
0021     RETURN
0022     END
```

%EB14 T=00004 IS ON CR00011 USING 00024 BLKS R=0000

```
0001  FTN4,L,Y
0002  C *****
0003  C *          FILENAME : %EB14          *
0004  C * READS ALMANAC-DATA FROM DATA-TAPE, CONVERTS IT *
0005  C * INTO DOUBLE PRECISION AND CREATES ARRAY WITH *
0006  C * DATA FOR MAINPROGRAM.          *
0007  C *          *
0008  C *****
0009  C
0010      SUBROUTINE EB14
0011      DOUBLE PRECISION AD,A,B,C,DTC
0012      COMMON/ALM/AD(14,24),ID1(24)
0013      COMMON/NAC/A,B,C,DTC
0014      DIMENSION IALMAC(12,24),ISVPRN(24),ID(24)
0015      INTEGER ALMAC(24,24),IAR(2),IBUF(310),IDARY(24)
0016      EQUIVALENCE(IBUF(16),IALMAC)
0017      REAL OMD,OMD,MO
0018      INTEGER H
0019      DATA PI/3.14159265/,ISVPRN/4,7,6,8,5,9,18*0/
0020  C
0021  C  ISTD IS THE STARTING ADDRESS OF ALMANAC DATA AND IWCNT IS THE NUMBER
0022  C  OF WORDS IN THE ALMANAC DATA.
0023  C
0024      DATA ISTD/172700B/,IWCNT/310/,LUS/8/
0025  C
0026  C  CALL EXEC TO READ IN ALMANAC DATA.
0027  C
0028  100  CALL EXEC(1,LUS,IBUF,IWCNT)
0029      CALL ABREG(IERR,NWRD)
0030      IF(NWRD.NE.288)GO TO 100
0031      DO 40 J=1,24
0032          DO 50 I=1,12
0033              I2=2*I
0034              I1=I2-1
0035              ITMP=IALMAC(I,J)
0036              ALMAC(I1,J)=IAND(ITMP,377B)
0037              ALMAC(I2,J)=ISHFT(ITMP,-8)
0038  50  CONTINUE
0039  40  CONTINUE
0040      WRITE(16,120)
0041      READ(16,*)DTC
0042  C
0043  C  GET SATELLITE ID(PRN NUMBER) FROM ALMANAC DATA.
0044  C
0045      DO 10 J=1,24
0046          DO 20 I=1,24
0047              ID(I)=ALMAC(1,I)
0048  C
0049  C  TEST TO SEE IF SATELLITE IS IN PRN NUMBER ORDER.
0050  C
0051          IF(ID(I).EQ. 0)GO TO 20
0052          IF(ID(I).EQ. ISVPRN(J))GO TO 30
0053  20  CONTINUE
0054      GO TO 10
0055  C
0056  C  GET ECENTRICITY OF SATELLITE ORBIT FROM ALMANAC DATA.
0057  C
0058  30  IAR(2)=IOR(ISHFT(ALMAC(2,I),8),ALMAC(3,I))
```

```

0059      IDARY(J)=ID
0060      IAR(1)=0
0061      ID1(J)=ID(I)
0062 C
0063 C   ECENTRICITY IS SCALED BY A FACTOR OF 2**-21.
0064 C
0065      E=DINTF(IAR)*4.7683716E-7
0066 C
0067 C   GET TIME OF APPLICABILITY OF THE ALMANAC PARAMETERS.
0068 C
0069      IAR(2)=ALMAC(4,I)
0070      IAR(1)=0
0071 C
0072 C   TOA(SECONDS) IS SCALED BY A FACTOR OF 2**12.
0073 C
0074      TOA=DINTF(IAR)*4096.0
0075 C
0076 C   GET SATELLITE ORBIT INCLINATION FROM ALMANAC DATA.
0077 C
0078      IAR(2)=IOR(ISHFT(ALMAC(5,I),8),ALMAC(6,I))
0079      IAR(1)=0
0080      IF(IAR(2) .LT. 0) IAR(1)=-1
0081 C
0082 C   DI(SEMICIRCLES) IS SCALED BY A FACTOR OF 2**-19 INCREMENTED
0083 C   BY 1/3 AND MULTIPLIED BY PI TO YIELD RADIANS.
0084 C
0085      DI=((DINTF(IAR)*1.9073486E-6)+(1.0/3.0))*PI
0086 C
0087 C   GET DRIFT RATE OF LONGITUDE OF ASCENDING NODE OF THE ORBIT
0088 C   FROM ALMANAC DATA.
0089 C
0090      IAR(1)=0
0091      IAR(2)=IOR(ISHFT(ALMAC(7,I),8),ALMAC(8,I))
0092      IF(IAR(2) .LT. 0) IAR(1)=-1
0093 C
0094 C   OMD (SEMICIRCLES/SEC) IS SCALED BY A FACTOR OF 2**-38 AND
0095 C   MULTIPLIED BY PI TO YIELD RADIANS/SEC.
0096 C
0097      OMD=DINTF(IAR)*PI*3.6379788E-12
0098 C
0099 C   GET HEALTH WORD FROM ALMANAC DATA.
0100 C
0101      H=ALMAC(9,I)
0102 C
0103 C   GET THE SQUARE ROOT OF THE SEMI-MAJOR AXIS OF THE ORBIT
0104 C   FROM ALMANAC DATA.
0105 C
0106      IAR(1)=ALMAC(10,I)
0107      IAR(2)=IOR(ISHFT(ALMAC(11,I),8),ALMAC(12,I))
0108 C
0109 C   RA(METERS) IS SCALED BY A FACTOR OF 2**-11.
0110 C
0111      RA=DINTF(IAR)*4.8828125E-4
0112 C
0113 C   GET THE RIGHT ASCENSION OF THE ORBIT FROM ALMANAC DATA.
0114 C
0115      IAR(2)=IOR(ISHFT(ALMAC(14,I),8),ALMAC(15,I))
0116      IAR(1)=ALMAC(13,I)
0117      IF(IAND(ALMAC(13,I),200B).NE.0) IAR(1)=IOR(IAR(1),177400B)
0118 C

```

```

0119 C OMO(SEMICIRCLES) IS SCALED BY A FACTOR OF 2**-23 AND
0120 C MULTIPLIED BY PI TO YIELD RADIANS.
0121 C
0122 C OMO=DINTF(IAR)*PI*1.1920929E-7
0123 C
0124 C GET THE ARGUMENT OF PERIGEE FROM ALMANAC DATA.
0125 C
0126 C IAR(1)=ALMAC(16,I)
0127 C IAR(2)=IOR(ISHFT(ALMAC(17,I),8),ALMAC(18,I))
0128 C IF(IAND(IAR(1),200B).NE.0)IAR(1)=IOR(IAR(1),177400B)
0129 C
0130 C W(SEMICIRCLES) IS SCALED BY A FACTOR OF 2**-23 AND
0131 C MULTIPLIED BY PI TO YIELD RADIANS.
0132 C
0133 C W=DINTF(IAR)*PI*1.1920929E-7
0134 C
0135 C GET MEAN ANOMALY AT TOA FROM ALMANAC DATA.
0136 C
0137 C IAR(1)=ALMAC(19,I)
0138 C IF(IAND(IAR(1),200B).NE.0)IAR(1)=IOR(IAR(1),177400B)
0139 C IAR(2)=IOR(ISHFT(ALMAC(20,I),8),ALMAC(21,I))
0140 C
0141 C MO(SEMICIRCLES) IS SCALED BY A FACTOR OF 2**-23 AND
0142 C MULTIPLIED BY PI TO YIELD RADIANS.
0143 C
0144 C MO=DINTF(IAR)*PI*1.1920929E-7
0145 C AD(1,J)=DBLE(E)
0146 C AD(2,J)=DBLE(TOA)
0147 C AD(3,J)=DBLE(DI)
0148 C AD(4,J)=DBLE(OMD)
0149 C AD(5,J)=DBLE(RA)
0150 C AD(6,J)=DBLE(OMO)
0151 C AD(7,J)=DBLE(W)
0152 C AD(8,J)=DBLE(MO)
0153 10 CONTINUE
0154 RETURN
0155 120 FORMAT(" ENTER COLLECTION DATE FOR ALMANAC DATA(NTH DAY)_" )
0156 END

```

&HD01 T=00004 IS ON CR00011 USING 00018 BLKS R=0000

```
0001 FTN4X,L,Y
0002 C *****
0003 C * FILENAME : &HD01 *
0004 C * *
0005 C * COMPUTES THE G-MATRIX,INVERTES AND TRANSPONES *
0006 C * IT AND COMPUTES THE HDOP AND GDOP. *
0007 C * FORMULAS FROM : MILLIKEN/ZOLLER *
0008 C * "NAVSTAR OPERATION" *
0009 C * *
0010 C *****
0011 C
0012 SUBROUTINE HD01
0013 IMPLICIT DOUBLE PRECISION (A-H,K-M,O-Z)
0014 DIMENSION IL(4),IM(4)
0015 COMMON/POS/LAT,LON,ALT
0016 COMMON/DTX/U(4),D(4,4)
0017 COMMON/CNST/PI,RTD
0018 COMMON/BLG/G(4,4),N ! FOR MATRIXINVERSION
0019 COMMON/MAT/A(4,4),AT(4,4),AAT(4,4)
0020 COMMON/HDOP/HDOP,INS,GDOP
0021 N=4
0022 C
0023 C ***** COMPUTATION OF A (=G) *****
0024 C
0025 A1=DSIN(LON)
0026 A2=DCOS(LON)
0027 A3=DSIN(LAT)
0028 A4=DCOS(LAT)
0029 IF(INS.EQ.4) GOTO 1000
0030 DO 102 I=1,4
0031 D(4,I)=U(I)
0032 102 CONTINUE
0033 1000 CONTINUE
0034 DO 100 I=1,4
0035 A5=1./DSQRT(D(I,1)*D(I,1)+D(I,2)*D(I,2)+D(I,3)*D(I,3))
0036 A(I,1)=(-D(I,1)*A1+D(I,2)*A2)*A5
0037 A(I,2)=(-D(I,1)*A3+A2*-D(I,2)*A3+A1+D(I,3)*A4)*A5
0038 A(I,3)=(D(I,1)*A4*A2+D(I,2)*A4*A1+D(I,3)*A3)*A5
0039 A(I,4)=1.
0040 100 CONTINUE
0041 C
0042 C ***** MATRIX-TRANSPONATION *****
0043 C
0044 DO 101 I=1,4
0045 DO 101 J=1,4
0046 AT(I,J)=A(J,I)
0047 101 CONTINUE
0048 C
0049 C ***** MULTIPLICATION OF MATRIZES (AT*A)=AAT *****
0050 C
0051 CALL EB09
0052 C
0053 C ***** INVERSION OF AAT AND COMPUTATION OF HDOP *****
0054 C
0055 DO 103 I=1,4
0056 DO 103 J=1,4
0057 G(I,J)=AAT(I,J)
0058 103 CONTINUE
```

```

0059      CALL MINVD(G,N,DET,IL,IM)
0060      IF(DET.EQ.0.0D0) GOTO 1001
0061      HDOP=DSQRT(G(1,1)+G(2,2))
0062      GDOP=DSQRT(G(1,1)+G(2,2)+G(3,3)+G(4,4))
0063      RETURN
0064 1001  CONTINUE
0065      WRITE (6,1)
0066      WRITE (16,1)
0067 1      FORMAT ( " ***** "
0068      1/      " +MATRIX SINGULAR* "
0069      2/      " ***** ")
0070      RETURN
0071      END

```

&MINVD T=00003 IS ON CR00011 USING 00024 BLKS R=0000

```
0001  FTN4X,L,Y
0002  C
0003  C .....
0004  C
0005  C      SUBROUTINE MINVD          HP-VERSION
0006  C
0007  C      PURPOSE
0008  C          INVERT A MATRIX
0009  C
0010  C      USAGE
0011  C          CALL MINVD(A,N,D,L,M)
0012  C
0013  C      DESCRIPTION OF PARAMETERS
0014  C          A - INPUT MATRIX, DESTROYED IN COMPUTATION AND REPLACED BY
0015  C              RESULTANT INVERSE.
0016  C          N - ORDER OF MATRIX A
0017  C          D - RESULTANT DETERMINANT
0018  C          L - WORK VECTOR OF LENGTH N
0019  C          M - WORK VECTOR OF LENGTH N
0020  C
0021  C      REMARKS
0022  C          MATRIX A MUST BE A GENERAL MATRIX
0023  C
0024  C      SUBROUTINES AND FUNCTION SUBPROGRAMS REQUIRED
0025  C          NONE
0026  C
0027  C      METHOD
0028  C          THE STANDARD GAUSS-JORDAN METHOD IS USED. THE DETERMINANT
0029  C          IS ALSO CALCULATED. A DETERMINANT OF ZERO INDICATES THAT
0030  C          THE MATRIX IS SINGULAR.
0031  C
0032  C .....
0033  C
0034  C      SUBROUTINE MINVD(A,N,D,L,M)
0035  C      IMPLICIT DOUBLE PRECISION (A-H,O-T,V-Z)
0036  C      IMPLICIT REAL*4 (U)
0037  C      DIMENSION A(1),L(1),M(1)
0038  C
0039  C          SEARCH FOR LARGEST ELEMENT
0040  C
0041  C          D=1.0D0
0042  C          NK=-N
0043  C          DO 80 K=1,N
0044  C              NK=NK+N
0045  C              L(K)=K
0046  C              M(K)=K
0047  C              KK=NK+K
0048  C              BIGA=A(KK)
0049  C              DO 20 J=K,N
0050  C                  IZ=N*(J-1)
0051  C                  DO 20 I=K,N
0052  C                      IJ=IZ+I
0053  C                      10 IF(DABS(BIGA)-DABS(A(IJ)))> 15,20,20
0054  C                      15 BIGA=A(IJ)
0055  C                      L(K)=I
0056  C                      M(K)=J
0057  C                      20 CONTINUE
0058  C
```

```

0059 C          INTERCHANGE ROWS
0060 C
0061         J=L(K)
0062         IF(J-K) 35,35,25
0063     25 KI=K-N
0064         DO 30 I=1,N
0065         KI=KI+N
0066         HOLD=-A(KI)
0067         JI=KI-K+J
0068         A(KI)=A(JI)
0069     30 A(JI) =HOLD
0070 C
0071 C          INTERCHANGE COLUMNS
0072 C
0073     35 I=M(K)
0074         IF(I-K) 45,45,38
0075     38 JP=N*(I-1)
0076         DO 40 J=1,N
0077         JK=NK+J
0078         JI=JP+J
0079         HOLD=-A(JK)
0080         A(JK)=A(JI)
0081     40 A(JI) =HOLD
0082 C
0083 C          DIVIDE COLUMN BY MINUS PIVOT (VALUE OF PIVOT ELEMENT IS
0084 C          CONTAINED IN BIGA)
0085 C
0086     45 IF(BIGA) 48,46,48
0087     46 D=0.0D0
0088         RETURN
0089     48 DO 55 I=1,N
0090         IF(I-K) 50,55,50
0091     50 IK=NK+I
0092         A(IK)=A(IK)/(-BIGA)
0093     55 CONTINUE
0094 C
0095 C          REDUCE MATRIX
0096 C
0097         DO 65 I=1,N
0098         IK=NK+I
0099         HOLD=A(IK)
0100         IJ=I-N
0101         DO 65 J=1,N
0102         IJ=IJ+N
0103         IF(I-K) 60,65,60
0104     60 IF(J-K) 62,65,62
0105     62 KJ=IJ-I+K
0106         A(IJ)=HOLD*A(KJ)+A(IJ)
0107     65 CONTINUE
0108 C
0109 C          DIVIDE ROW BY PIVOT
0110 C
0111         KJ=K-N
0112         DO 75 J=1,N
0113         KJ=KJ+N
0114         IF(J-K) 70,75,70
0115     70 A(KJ)=A(KJ)/BIGA
0116     75 CONTINUE
0117 C
0118 C          PRODUCT OF PIVOTS

```

```

0119  C
0120      D=D*BIGA
0121  C
0122  C      REPLACE PIVOT BY RECIPROCAL
0123  C
0124      A(KK)=1.0D0/BIGA
0125      80 CONTINUE
0126  C
0127  C      FINAL ROW AND COLUMN INTERCHANGE
0128  C
0129      K=N
0130      100 K=(K-1)
0131      IF(K) 150,150,105
0132      105 I=L(K)
0133      IF(I-K) 120,120,108
0134      108 JQ=N*(K-1)
0135      JR=N*(I-1)
0136      DO 110 J=1,N
0137      JK=JQ+J
0138      HOLD=A(JK)
0139      JI=JR+J
0140      A(JK)=-A(JI)
0141      110 A(JI) =HOLD
0142      120 J=M(K)
0143      IF(J-K) 100,100,125
0144      125 KI=K-N
0145      DO 130 I=1,N
0146      KI=KI+N
0147      HOLD=A(KI)
0148      JI=KI-K+J
0149      A(KI)=-A(JI)
0150      130 A(JI) =HOLD
0151      GO TO 100
0152      150 RETURN
0153      END

```

&DINTF T=00004 IS ON CR00013 USING 00003 BLKS R=0000

0001	ASMB,L		
0002		NAM	DINTF
0003		ENT	DINTF
0004		EXT	.FLTD
0005	DINTF	NOP	
0006		ISZ	DINTF
0007		LDA	DINTF,I
0008		STA	IBF
0009		ISZ	DINTF
0010		DLD	IBF,I
0011		AND	B377
0012		JSB	.FLTD
0013		JMF	DINTF,I
0014	IBF	BSS	1
0015	B377	OCT	377
0016		END	

%ENU T=00003 IS ON CR00002 USING 00023 BLKS R=0000

```
0001 FTN4,M,Y
0002 C*****
0003 C
0004 C      THIS SUBROUTINE FILLS THE ENUP MATRIX.
0005 C
0006 C      MICHAEL J. MAGROGAN CO-OP ACT-100D FEBRUARY 1981
0007 C
0008 C*****
0009 SUBROUTINE ENU
0010 C THIS SUBROUTINE IS PASSED AIRCRAFT POSITION(XP,YP,ZP) FROM THE MAIN
0011 C PROGRAM(GDOP) AND RETURNS THE FILLED ENUP MATRIX.
0012 COMMON /COORD/ ENUP(3,3),XP,YP,ZP,H(4,4),HT(4,4),HPROD(4,4),
0013 +LSAT(4),XS(4),YS(4),ZS(4),HDOPV,GDOPV
0014 DOUBLE PRECISION ENUP,XP,YP,ZP,H,HT,HPROD,XS,YS,ZS,HDOPV,GDOPV
0015 DOUBLE PRECISION WP,TANPHI,COSLAM,SINLAM,COSPHI,SINPHI,ESQU
0016 DATA ESQU/0.00669431778D0/
0017 C CALCULATE THE TERMS NEEDED TO FILL ENUP MATRIX.
0018 WP=DSQRT(XP**2+YP**2)
0019 TANPHI=ZP/WP
0020 COSLAM=XP/WP
0021 SINLAM=YP/WP
0022 TANPHI=TANPHI/(1.D0-ESQU)
0023 COSPHI=1.D0/DSQRT(1.D0+TANPHI**2)
0024 SINPHI=COSPHI*TANPHI
0025 C FILL ENUP MATRIX.
0026 ENUP(1,1)=-SINLAM
0027 ENUP(1,2)=COSLAM
0028 ENUP(1,3)=0.D0
0029 ENUP(2,1)=-SINPHI*COSLAM
0030 ENUP(2,2)=-SINPHI*SINLAM
0031 ENUP(2,3)=COSPHI
0032 ENUP(3,1)=COSPHI*COSLAM
0033 ENUP(3,2)=COSPHI*SINLAM
0034 ENUP(3,3)=SINPHI
0035 RETURN
0036 END
```

&HTRAN T=00003 IS ON CR00002 USING 00007 BLKS R=0000

```
0001 FTH4,L,Y
0002 C*****
0003 C
0004 C      THIS SUBROUTINE COMPUTES THE TRANSPOSE OF THE H MATRIX.
0005 C
0006 C      MICHAEL J. MAGROGAN  CO-OP  ACT-100D  FEBRUARY 1981
0007 C
0008 C*****
0009 SUBROUTINE HTRAN
0010 C  THIS SUBROUTINE IS PASSED THE H MATRIX FROM THE MAIN PROGRAM(GDOP)
0011 C  AND RETURNS THE TRANSPOSE OF THE H MATRIX(HT).
0012 COMMON /COORD/ ENUP(3,3),XP,YP,ZP,H(4,4),HT(4,4),HPROD(4,4),
0013 +LSAT(4),XS(4),YS(4),ZS(4),HDOPV,GDOPV
0014 DOUBLE PRECISION ENUP,XP,YP,ZP,H,HT,HPROD,XS,YS,ZS,HDOPV,GDOPV
0015 C  COMPUTE THE TRANSPOSE OF THE H MATRIX.
0016 DO 10 I=1,4
0017 DO 20 J=1,4
0018 HT(I,J)=H(J,I)
0019 20 CONTINUE
0020 10 CONTINUE
0021 RETURN
0022 END
```

&MLHHT T=00003 IS ON CR00002 USING 00024 BLKS R=0000

```
0001  FTN4,L,Y
0002  C*****
0003  C
0004  C      THIS SUBROUTINE MULTILLIES THE H AND H TRANSPOSE MATRICES
0005  C
0006  C      MICHAEL J. MAGROGAN CO-OP ACT-1000 FEB 1981
0007  C
0008  C*****
0009  SUBROUTINE MLHHT
0010  C THIS SUBROUTINE IS PASSED THE H AND H TRANSPOSE MATRICES FROM THE
0011  C NAIN PROGRAM (GDOP) AND RETURNS THE PRODUCT MATRIX (HPROD)
0012  COMMON/COORD/ENUP(3,3),XP,YP,ZP,H(4,4),HT(4,4),HPROD(4,4),
0013  +LSAT(4),XS(4),YS(4),ZS(4),HDOPV,GDOPV
0014  DOUBLE PRECISION ENUP,XP,YP,ZP,H,HT,HPROD,XS,YS,ZS,HDOPV,GDOPV
0015  C MULTIPLY THE H AND HT MATRICES
0016  DO 10 I=1,4
0017  DO 10 J=1,4
0018  HPROD(I,J)=0.D0
0019  DO 10 K=1,4
0020  HPROD(I,J)=HPROD(I,J)+HT(I,K)*H(K,J)
0021  10  CONTINUE
0022  RETURN
0023  END
```

&INVHP T=00003 IS ON CR00002 USING 00024 BLKS R=0000

```
0001  FTN4,L,Y
0002  C*****
0003  C
0004  C      THIS SUBROUTINE WAS WRITTEN BY CHE S. WONG IT IS IN HIS
0005  C      PAPER "A GPS ALMANAC", HE CALLS THIS SUBROUTINE "MATI".
0006  C
0007  C
0008  C      MICHAEL J. MAGROGAN  CO-OP  ACT-1000  FEBRUARY 1981
0009  C
0010  C*****
0011      SUBROUTINE INVHP
0012  C  'INVHPR' INVERTS THE H PRODUCT MATRIX AND SUBSTITUTES THE
0013  C  RESULTS BACK INTO THE H PRODUCT MATRIX.
0014  C
0015  C  THIS SUBROUTINE IS PASSED THE H PRODUCT MATRIX(HPROD) FROM THE
0016  C  MAIN PROGRAM(GDOP) AND RETURNS THE MATRIX INVERSE OF THE H
0017  C  PRODUCT MATRIX(HPROD).
0018      COMMON /COORD/ENUP(3,3),XP,YP,ZP,H(4,4),HT(4,4),HPROD(4,4),
0019      +LSAT(4),XS(4),YS(4),ZS(4),HDOPV,GDOPV,DET
0020      DOUBLE PRECISION ENUP,XP,YP,ZP,H,HT,HPROD,XS,YS,ZS,HDOPV,GDOPV
0021      DOUBLE PRECISION PIVOT,ONE,ZERO,T,DET
0022      DIMENSION INDEX(4,2),IPVOT(4),PIVOT(4)
0023      DATA ONE/1.00/,ZERO/0.00/
0024      DET=1.00
0025  C  CLEAR IPVOT VECTOR.
0026      DO 10 I=1,4
0027          IPVOT(I)=0
0028      10 CONTINUE
0029  C  FOLLOWING 12 STATEMENTS SEARCH FOR PIVOT ELEMENT.
0030      DO 20 I=1,4
0031          T=ZERO
0032          DO 30 J=1,4
0033              IF(IPVOT(J)-1) 31,30,31
0034          31      DO 40 K=1,4
0035                  IF(IPVOT(K)-1) 41,40,91
0036          41      IF(DABS(T)-DABS(HPROD(J,K))) 42,40,40
0037          42      IROW=J
0038                  ICOL=K
0039                  T=HPROD(J,K)
0040          40 CONTINUE
0041          30 CONTINUE
0042              IPVOT(ICOL)=IPVOT(ICOL)+1
0043  C  FOLLOWING 15 STATEMENTS PUT PIVOT ELEMENT ON DIAGONAL.
0044              IF(IROW-ICOL) 43,51,43
0045          43      DET=-DET
0046                  DO 50 L=1,4
0047                      T=HPROD(IROW,L)
0048                      HPROD(IROW,L)=HPROD(ICOL,L)
0049          50      HPROD(ICOL,L)=T
0050          51      INDEX(I,1)=IROW
0051                  INDEX(I,2)=ICOL
0052                  PIVOT(I)=HPROD(ICOL,ICOL)
0053                  DET=DET*PIVOT(I)
0054  C  THE FOLLOWING 6 STATEMENTS DIVIDE PIVOT ROW
0055  C  BY PIVOT ELEMENT.
0056                  HPROD(ICOL,ICOL)=ONE
0057                  DO 60 L=1,4
0058          60      HPROD(ICOL,L)=HPROD(ICOL,L)/PIVOT(I)
```

```

0059 C FOLLOWING 10 STATEMENTS TO REDUCE NON-PIVOT ROWS.
0060         DO 20 LI=1,4
0061             IF(LI-ICOL) 21,20,21
0062         21         T=HPROD(LI,ICOL)
0063             HPROD(LI,ICOL)=ZERO
0064             DO 70 L=1,4
0065         70         HPROD(LI,L)=HPROD(LI,L)-HPROD(ICOL,L)*T
0066         20 CONTINUE
0067 C FOLLOWING 11 STATEMENTS TO INTERCHANGE COLUMNS.
0068         DO 80 I=1,4
0069             L=4-I+1
0070             IF( INDEX(L,1)-INDEX(L,2))81,80,81
0071         81         JROW=INDEX(L,1)
0072             JCOL=INDEX(L,2)
0073             DO 90 K=1,4
0074                 T=HPROD(K,JROW)
0075                 HPROD(K,JROW)=HPROD(K,JCOL)
0076                 HPROD(K,JCOL)=T
0077         90 CONTINUE
0078         80 CONTINUE
0079         91 RETURN
0080         END

```

APPENDIX D EXAMPLES OF DATA FILES

Almanac Files

A557 T=00004 IS ON CR00002 USING 00002 BLKS R=0000

0001	57.000000	5			
0002	0.23045540D-02		0.33177600D+06	0.11124156D+01	-0.61945435D-08
0003	0.51536416D+04		0.56938994D+00	-0.20916948D+01	0.69497383D+00
0004					

A657 T=00004 IS ON CR00002 USING 00002 BLKS R=0000

0001	57.000000	6			
0002	0.15506744D-02		0.33177600D+06	0.11071186D+01	-0.64574115D-08
0003	0.51536494D+04		-0.15504746D+01	0.20494380D+01	-0.10743264D+01
0004					

A857 T=00004 IS ON CR00002 USING 00002 BLKS R=0000

0001	57.000000	8			
0002	0.22068024D-02		0.33177600D+06	0.11034214D+01	-0.63431207D-08
0003	0.51536484D+04		0.56528795D+00	-0.19833443D+00	0.35664302D+00
0004					

A957 T=00004 IS ON CR00002 USING 00002 BLKS R=0000

0001	57.000000	9			
0002	0.81076622D-02		0.33177600D+06	0.11036611D+01	-0.65031278D-08
0003	0.51536670D+04		-0.15456643D+01	0.13524077D+01	-0.11417092D+01
0004					

URE File

U557 T=00004 IS ON CR00002 USING 00024 BLKS R=0000

0001	11		
0002	.1050E+02	.1200E+01	
0003	.1075E+02	.1230E+01	
0004	.1100E+02	.2600E+00	
0005	.1125E+02	-.5000E+00	
0006	.1150E+02	-.6700E+00	
0007	.1175E+02	-.8400E+00	
0008	.1200E+02	-.1080E+01	
0009	.1225E+02	-.8000E+00	
0010	.1250E+02	-.2500E+00	
0011	.1275E+02	-.8700E+00	
0012	.1300E+02	-.9000E+00	

APPENDIX E

PROGRAM *EBGH*

VERSION A

EXAMPLES OF PROGRAM OUTPUT

USER-COORDINATES :

LAT = 39.500000 LON = -74.500000 ALT = 100.00000
 XP = 1317011.6 YP = -4748990.4 ZP = 4035321.8
 SAT.NO : 1 XS = -.18330000D+08 YS = -.19150000D+08 ZS = .21860000D+07
 SAT.NO : 2 XS = -.28430000D+07 YS = -.21740000D+08 ZS = .14930000D+08
 SAT.NO : 3 XS = .97110000D+07 YS = -.72340000D+07 ZS = .23660000D+08
 SAT.NO : 4 XS = -.10730000D+08 YS = -.59120000D+07 ZS = .23340000D+08

H-MATRIX

-.93250784D+00 -.28302801D+00 .22433071D+00 .10000000D+01
 -.41485437D+00 -.63121006D-01 .90769576D+00 .10000000D+01
 .34551315D+00 .56740932D+00 .74744052D+00 .10000000D+01
 -.52313791D+00 .71235238D+00 .46784699D+00 .10000000D+01

H-TRANSPOSE-MATRIX

-.93250784D+00 -.41485437D+00 .34551315D+00 -.52313791D+00
 -.28302801D+00 -.63121006D-01 .56740932D+00 .71235238D+00
 .22433071D+00 .90769576D+00 .74744052D+00 .46784699D+00
 .10000000D+01 .10000000D+01 .10000000D+01 .10000000D+01

HT*H-MATRIX

.14347276D+01 .11350071D+00 -.57224967D+00 -.15249870D+01
 .11350071D+00 .91348837D+00 .63659009D+00 .93361268D+00
 -.57224967D+00 .63659009D+00 .16517840D+01 .23473140D+01
 -.15249870D+01 .93361268D+00 .23473140D+01 .48000000D+01

INVERTED H*HT-MATRIX

.36502949D+01 -.19983312D+01 -.36472862D+01 .39984113D+01
 -.19983312D+01 .25934803D+01 .15117074D+01 -.22542968D+01
 -.36472862D+01 .15117074D+01 .74466003D+01 -.61132306D+01
 .39984113D+01 -.22542968D+01 -.61132306D+01 .58879592D+01

HDOP = 2.49875 PDOP = 3.70005 GDOP = 4.42474

PROGRAM *EBGH*

VERSION A

USER-COORDINATES :

LAT = 39.500000 LON = -74.500000 ALT = 100.00000
 XP = 1317011.6 YP = -4748990.4 ZP = 4035321.8
 SAT.NO : 1 XS = -.18330000D+08 YS = -.19150000D+08 ZS = .21860000D+07
 SAT.NO : 2 XS = -.28430000D+07 YS = -.21740000D+08 ZS = .14930000D+08
 SAT.NO : 3 XS = .97110000D+07 YS = -.72340000D+07 ZS = .23660000D+08

H-MATRIX

-.93250784D+00 -.28302801D+00 .22433071D+00 .10000000D+01
 -.41485437D+00 -.63121006D-01 .90769576D+00 .10000000D+01
 .34551315D+00 .56740932D+00 .74744052D+00 .10000000D+01
 .00000000D+00 .00000000D+00 -.10000000D+01 .00000000D+00

H-TRANSPOSE-MATRIX

-.93250784D+00 -.41485437D+00 .34551315D+00 .00000000D+00
 -.28302801D+00 -.63121006D-01 .56740932D+00 .00000000D+00
 .22433071D+00 .90769576D+00 .74744052D+00 -.10000000D+01
 .10000000D+01 .10000000D+01 .10000000D+01 .00000000D+00

HT*H-MATRIX

.11610544D+01	.48615925D+00	-.32750117D+00	-.10018491D+01
.48615925D+00	.40604245D+00	.30331817D+00	.22126030D+00
-.32750117D+00	.30331817D+00	.24329032D+01	.18794670D+01
-.10018491D+01	.22126030D+00	.18794670D+01	.30000000D+01

INVERTED H*HT-MATRIX

.54713155D+02	-.77387582D+02	-.29281686D+01	.25813506D+02
-.77387582D+02	.11217536D+03	.37852890D+01	-.36488319D+02
-.29281686D+01	.37852890D+01	.10000000D+01	-.18835280D+01
.25813506D+02	-.36488319D+02	-.18835280D+01	.12824894D+02

HDOP = 12.91853 PDOP = 12.95718 GDOP = 13.44297

FILENAME : 12/23/

RECORD-NO. : 1
 TIME : .240295D+05 SEC. ==> 6.4029 HOURS GMT
 USERPOSITION ---> .13124184D+07 -.47538986D+07 .40310172D+07
 SATELLITE-POSITIONS :

	XS	YS	ZS
6	-.27384016D+07	-.24919635D+08	.86777768D+07
9	-.99460549D+07	-.12005477D+08	.21292195D+08
8	.14541746D+08	-.34133485D+07	.22000845D+08

H-MATRIX

-.43966564D+00	-.38309360D+00	.81236286D+00	.10000000D+01
-.58508400D+00	.49393319D+00	-.64320037D+00	.10000000D+01
.58641386D+00	.55738190D+00	.58774502D+00	.10000000D+01
.00000000D+00	.00000000D+00	-.10000000D+01	.00000000D+00

H-TRANSPOSE-MATRIX

-.43966564D+00	-.58508400D+00	.58641386D+00	.00000000D+00
-.38309360D+00	.49393319D+00	.55738190D+00	.00000000D+00
.81236286D+00	.64320037D+00	.58774502D+00	-.10000000D+01
.10000000D+01	.10000000D+01	.10000000D+01	.00000000D+00

HT*H-MATRIX

.87951037D+00	.20629715D+00	-.38883246D+00	-.43833579D+00
.20629715D+00	.70140529D+00	.33408543D+00	.66822149D+00
-.38883246D+00	.33408543D+00	.24190843D+01	.20433082D+01
-.43833579D+00	.66822149D+00	.20433082D+01	.30000000D+01

INVERTED H*HT-MATRIX

.15438569D+01	-.84117185D+00	.36562251D-01	.38803629D+00
-.84117185D+00	.23159976D+01	.19894412D+00	-.77427307D+00
.36562251D-01	.19894412D+00	.10000000D+01	-.72007348D+00
.38803629D+00	-.77427307D+00	-.72007348D+00	.10529361D+01

HDOP = 1.96465 PDOP = 2.20451 GDOP = 2.43162

RECORD-NO. : 2
 TIME : .241645D+05 SEC. ==> 6.4244 HOURS GMT
 USERPOSITION ---> .13137653D+07 -.47567960D+07 .40272182D+07
 SATELLITE-POSITIONS :

	XS	YS	ZS
6	-.27577762D+07	-.25088535D+08	.81721616D+07
9	-.99341777D+07	-.12380684D+08	.21084965D+08
8	.14774962D+08	-.32576402D+07	.21870541D+08

H-MATRIX

-.44157237D+00	-.40434632D+00	.80094812D+00	.10000000D+01
-.59021561D+00	.47760913D+00	.65079571D+00	.10000000D+01
.59703183D+00	.55484459D+00	.57939665D+00	.10000000D+01
.00000000D+00	.00000000D+00	-.10000000D+01	.00000000D+00

H-TRANSPOSE-MATRIX

-.44157237D+00	-.59021561D+00	.59703183D+00	.00000000D+00
-.40434632D+00	.47760913D+00	.55484459D+00	.00000000D+00
.80094812D+00	.65079571D+00	.57939665D+00	-.10000000D+01
.10000000D+01	.10000000D+01	.10000000D+01	.00000000D+00

HT*H-MATRIX

.89978762D+00	.22791568D+00	-.39186811D+00	-.43475615D+00
.22791568D+00	.69945895D+00	.30844064D+00	.62810740D+00
-.39186811D+00	.30844064D+00	.24007534D+01	.20311405D+01
-.43475615D+00	.62810740D+00	.20311405D+01	.30000000D+01

INVERTED H*HT-MATRIX

.15228542D+01	-.84519400D+00	.48530776D-01	.36479000D+00
-.84519400D+00	.22720379D+01	.17842872D+00	-.71898363D+00
.48530776D-01	.17842872D+00	.10000000D+01	-.70737127D+00
.36479000D+00	-.71898363D+00	-.70737127D+00	.10156547D+01

HDOP = 1.94805 PDOP = 2.18972 GDOP = 2.41051

RECORD-NO. : 3

TIME : .242855D+05 SEC. ==> 6.4445 HOURS GMT

USERPOSITION ---> .13146833D+07 -.47595232D+07 .40237264D+07

SATELLITE-POSITIONS :

	XS	YS	ZS
6	-.27734586D+07	-.25213739D+08	.77753730D+07
9	-.99268982D+07	-.12705524D+08	.20897338D+08
8	.15109884D+08	-.30452386D+07	.21672668D+08

H-MATRIX

-.44289760D+00	-.42060457D+00	.79179133D+00	.10000000D+01
-.59473423D+00	.46314714D+00	.65710419D+00	.10000000D+01
.61219330D+00	.55030335D+00	.56779009D+00	.10000000D+01
.00000000D+00	.00000000D+00	-.10000000D+01	.00000000D+00

H-TRANSPOSE-MATRIX

-.44289760D+00	-.59473423D+00	.61219330D+00	.00000000D+00
-.42060457D+00	.46314714D+00	.55030335D+00	.00000000D+00
.79179133D+00	.65710419D+00	.56779009D+00	-.10000000D+01
.10000000D+01	.10000000D+01	.10000000D+01	.00000000D+00

HT*H-MATRIX

.92464773D+00	.24772732D+00	-.39388755D+00	-.42543853D+00
.24772732D+00	.69424725D+00	.28376167D+00	.59284592D+00
-.39388755D+00	.28376167D+00	.23811050D+01	.20166856D+01
-.42543853D+00	.59284592D+00	.20166856D+01	.30000000D+01

INVERTED H*HT-MATRIX

.14885525D+01	-.84347279D+00	.62223630D-01	.33595049D+00
-.84347279D+00	.22502180D+01	.16309441D+00	-.67392952D+00
.62223630D-01	.16309441D+00	.10000000D+01	-.69563438D+00
.33595049D+00	-.67392952D+00	-.69563438D+00	.98177950D+00

HDOP = 1.93359 PDOP = 2.17687 GDOP = 2.39177

RECORD-NO. : 4

TIME : .244363D+05 SEC. ==> 6.4717 HOURS GMT

USERPOSITION ---> .13116254D+07 -.47538321D+07 .40296685D+07

SATELLITE-POSITIONS :

	XS	YS	ZS
6	-.27913019D+07	-.25319994D+08	.74149243D+07
9	-.99219754D+07	-.13107162D+08	.20654291D+08
8	.15474265D+08	-.28247174D+07	.21444534D+08

H-MATRIX

-.44368457D+00	-.43720261D+00	.78230293D+00	.10000000D+01
-.60048559D+00	.44268187D+00	.66592028D+00	.10000000D+01
.62875741D+00	.54316541D+00	.55644898D+00	.10000000D+01
.00000000D+00	.00000000D+00	-.10000000D+01	.00000000D+00

H-TRANSPOSE-MATRIX

-.44368457D+00	-.60048559D+00	.62875741D+00	.00000000D+00
-.43720261D+00	.44268187D+00	.54316541D+00	.00000000D+00
.78230293D+00	.66592028D+00	.55644898D+00	-.10000000D+01
.10000000D+01	.10000000D+01	.10000000D+01	.00000000D+00

HT*H-MATRIX

.95277432D+00	.26967525D+00	-.39709986D+00	-.41541275D+00
.26967525D+00	.68214202D+00	.25500978D+00	.54864466D+00
-.39709986D+00	.25500978D+00	.23650832D+01	.20046722D+01
-.41541275D+00	.54864466D+00	.20046722D+01	.30000000D+01

INVERTED H*HT-MATRIX

.14554206D+01	-.84986195D+00	.77120096D-01	.30542400D+00
-.84986195D+00	.22516961D+01	.14601366D+00	-.62704469D+00
.77120096D-01	.14601366D+00	.10000000D+01	-.68424838D+00
.30542400D+00	-.62704469D+00	-.68424838D+00	.94753181D+00

HDOP = 1.92539 PDOP = 2.16959 GDOP = 2.37795

RECORD-NO. : 5

TIME : .245579D+05 SEC. ==> 6.4918 HOURS GMT

USERPOSITION ---> .13157679D+07 -.47542795D+07 .40295002D+07

SATELLITE-POSITIONS :

	XS	YS	ZS
6	-.28158738D+07	-.25466048D+08	.68916140D+07
9	-.99226391D+07	-.13435843D+08	.20444894D+08
8	.15755228D+08	-.26559606D+07	.21261766D+08

H-MATRIX

-.44603845D+00	-.45832357D+00	.76875823D+00	.10000000D+01
-.60568836D+00	.42700231D+00	.67142433D+00	.10000000D+01
.64110224D+00	.53800090D+00	.54730518D+00	.10000000D+01
.00000000D+00	.00000000D+00	-.10000000D+01	.00000000D+00

H-TRANSPOSE-MATRIX

-.44603845D+00	-.60568836D+00	.64110224D+00	.00000000D+00
-.45832357D+00	.42700231D+00	.53800090D+00	.00000000D+00
.76875823D+00	.67142433D+00	.54730518D+00	-.10000000D+01
.10000000D+01	.10000000D+01	.10000000D+01	.00000000D+00

HT*H-MATRIX

.97682077D+00	.29071318D+00	-.39869106D+00	-.41062457D+00
.29071318D+00	.68183643D+00	.22881041D+00	.50667964D+00
-.39869106D+00	.22881041D+00	.23413428D+01	.19874877D+01
-.41062457D+00	.50667964D+00	.19874877D+01	.30000000D+01

INVERTED H*HT-MATRIX

.14299077D+01	-.84764592D+00	.88344820D-01	.28035198D+00
-.84764592D+00	.22115435D+01	.12587245D+00	-.57292608D+00
.88344820D-01	.12587245D+00	.10000000D+01	-.67166273D+00
.28035198D+00	-.57292608D+00	-.67166273D+00	.91344361D+00

HDOP = 1.90826 PDOP = 2.15440 GDOP = 2.35688

```

PROGRAM *EBGD1*
*****

```

H-MATRIX

.100000000D+01	.000000000D+00	.000000000D+00	.100000000D+01
-.500000000D+00	.866025000D+00	.000000000D+00	.100000000D+01
-.500000000D+00	-.866025000D+00	.000000000D+00	.100000000D+01
.000000000D+00	.000000000D+00	.100000000D+01	.100000000D+01

H-TRANPOSE-MATRIX

.100000000D+01	-.500000000D+00	-.500000000D+00	.000000000D+00
.000000000D+00	.866025000D+00	-.866025000D+00	.000000000D+00
.000000000D+00	.000000000D+00	.000000000D+00	.100000000D+01
.100000000D+01	.100000000D+01	.100000000D+01	.100000000D+01

HT*H-MATRIX

.200000000D+01	.500000000D+00	.500000000D+00	.100000000D+01
.500000000D+00	.19999993D+01	.50000070D+00	.100000000D+01
.500000000D+00	.50000070D+00	.19999993D+01	.100000000D+01
.100000000D+01	.100000000D+01	.100000000D+01	.200000000D+01

INVERTED HT*H-MATRIX

.66666667D+00	-.34694470D-17	.000000000D+00	-.33333333D+00
-.34694470D-17	.66666698D+00	-.31083362D-06	-.33333333D+00
.000000000D+00	-.31083362D-06	.66666698D+00	-.33333333D+00
-.33333333D+00	-.33333333D+00	-.33333333D+00	.100000000D+01

HDQP = 1.15470076 GDQP = 1.73205090

```

PROGRAM *EBGD1*
*****

```

H-MATRIX

.100000000D+01	.000000000D+00	.000000000D+00	.100000000D+01
-.500000000D+00	.866000000D+00	.000000000D+00	.100000000D+01
-.500000000D+00	-.866000000D+00	.000000000D+00	.100000000D+01
.100000000D+01	.000000000D+00	.000000000D+00	.100000000D+01

H-TRANPOSE-MATRIX

.100000000D+01	-.500000000D+00	-.500000000D+00	.100000000D+01
.000000000D+00	.866000000D+00	-.866000000D+00	.000000000D+00
.000000000D+00	.000000000D+00	.000000000D+00	.000000000D+00
.100000000D+01	.100000000D+01	.100000000D+01	.100000000D+01

HT*H-MATRIX

.200000000D+01	.500000000D+00	.500000000D+00	.200000000D+01
.500000000D+00	.19999560D+01	.50004400D+00	.500000000D+00
.500000000D+00	.50004400D+00	.19999560D+01	.500000000D+00
.200000000D+01	.500000000D+00	.500000000D+00	.200000000D+01

*HT*H-MATRIX IS SINGULAR (DETERMINANT=0.)*

```

PROGRAM *EBGD1*
*****

```

AZIMUTH	ELEVATION
.0000D+00	.1000D+02
.2400D+03	.1000D+02
.1200D+03	.1000D+02

.00000D+00 .90000D+02

H-MATRIX

.98480775D+00	.00000000D+00	.17364819D+00	.10000000D+01
-.49240368D+00	-.85286864D+00	.17364819D+00	.10000000D+01
-.49240397D+00	.85286847D+00	.17364819D+00	.10000000D+01
-.86246497D-07	.00000000D+00	.10000000D+01	.10000000D+01

H-TRANSPPOSE-MATRIX

.98480775D+00	-.49240368D+00	-.49240397D+00	-.86246497D-07
.00000000D+00	-.85286864D+00	.85286847D+00	.00000000D+00
.17364819D+00	.17364819D+00	.17364819D+00	.10000000D+01
.10000000D+01	.10000000D+01	.10000000D+01	.10000000D+01

HT*H-MATRIX

.20000000D+01	.54523073D+00	.54523044D+00	.11736481D+01
.54523073D+00	.20000000D+01	.54523044D+00	.11736482D+01
.54523044D+00	.54523044D+00	.20000000D+01	.11736482D+01
.11736481D+01	.11736482D+01	.11736482D+01	.20000000D+01

INVERTED HT*H-MATRIX

.78369263D+00	.96298448D-01	.96298605D-01	-.57291028D+00
.96298448D-01	.78369273D+00	.96298655D-01	-.57291041D+00
.96298605D-01	.96298655D-01	.78369277D+00	-.57291052D+00
-.57291028D+00	-.57291041D+00	-.57291052D+00	.15085929D+01

HDOP = 1.25195265 GDOP = 1.96460462

PROGRAM * H D 0 0 *

USER-POSITION :

LATITUDE : 39.500000 DEGREE
LONGITUDE: -74.500000 DEGREE
ALTITUDE : 100.00000 FEET

ECEF-COORDINATES :

X Y Z
----- 1317011.6 -4748990.4 4035321.8

USERTIMES :

START (TSTART): 38700.000 SEC. = 10.45 HOURS
END (TFIN) : 46800.000 SEC. = 13.00 HOURS
INCR. (TDEL) : 600.00000 SEC
DATE (DTU) : 57.000000 DAYS

USED ALMANACS DTC= 57. TC= 20000.

SAT. ID :	5	6	8	9
	.2305D-02	.1551D-02	.2207D-02	.8108D-02
	.3318D+06	.3318D+06	.3318D+06	.3318D+06
	.1112D+01	.1107D+01	.1103D+01	.1104D+01
	-.6195D-08	-.6457D-08	-.6343D-08	-.6503D-08
	.5154D+04	.5154D+04	.5154D+04	.5154D+04
	.5694D+00	-.1550D+01	.5653D+00	-.1546D+01
	-.2092D+01	.2049D+01	-.1983D+00	.1352D+01
	.6950D+00	-.1074D+01	.3566D+00	-.1142D+01
	.2656D+08	.2656D+08	.2656D+08	.2656D+08
	.4425D+00	.4472D+00	.4505D+00	.4503D+00
	.8968D+00	.8944D+00	.8928D+00	.8929D+00
	-.4977D+00	-.4606D+00	.9804D+00	.2167D+00
	-.8674D+00	.8876D+00	-.1970D+00	.9762D+00
	.1459D-03	.1459D-03	.1459D-03	.1459D-03

OUTPUT OF COMPUTATIONS

=====

! THE PRINTOUT IS ARRANGED AS FOLLOWING EXAMPLE : !

! ----- !

! TIME !

! POSITION OF SATELLITES IN ECEF-COORDINATES (X,Y,Z) !

! AND ELEVATION AND AZIMUTH (3-4 LINES) !

! ----- !

! HDOP AND GDOP !

! ----- !

! ALL VALUES ARE IN METER !

=====

TIME : 10.4501 HOURS

-.1833D+08	-.1915D+08	.2186D+07	.1294D+02	.2531D+03
-.2843D+07	-.2174D+08	.1493D+08	.6517D+02	.2612D+03
.9711D+07	-.7234D+07	.2368D+08	.4839D+02	.3139D+02
-.1073D+08	-.5912D+07	.2334D+08	.2789D+02	.3237D+03

2.4984615 4.4243006

TIME : 10.5500 HOURS

-.1824D+08	-.1889D+08	.4249D+07	.1588D+02	.2571D+03
-.2728D+07	-.2281D+08	.1326D+08	.6319D+02	.2493D+03
.1104D+08	-.6041D+07	.2341D+08	.4477D+02	.3586D+02
-.1039D+08	-.7676D+07	.2298D+08	.3173D+02	.3208D+03

2.3736091 4.5147265

TIME : 11.0500 HOURS

-.1803D+08	-.1853D+08	.6279D+07	.1877D+02	.2612D+03
-.2686D+07	-.2376D+08	.1148D+08	.6012D+02	.2396D+03
.1241D+08	-.4931D+07	.2299D+08	.4126D+02	.4015D+02
-.1015D+08	-.9419D+07	.2245D+08	.3536D+02	.3172D+03

2.2600505 4.7088703

```

-----
TIME : 11.1500 HOURS
-.1767D+08  -.1809D+08  .8261D+07  .2161D+02  .2655D+03
-.2706D+07  -.2457D+08  .9620D+07  .5628D+02  .2320D+03
.1380D+08  -.3914D+07  .2239D+08  .3785D+02  .4434D+02
-.9994D+07  -.1112D+08  .2174D+08  .3851D+02  .3128D+03
-----
2.1423699      5.0271648
-----
TIME : 11.2500 HOURS
-.1718D+08  -.1759D+08  .1018D+08  .2439D+02  .2700D+03
-.2774D+07  -.2524D+08  .7684D+07  .5195D+02  .2261D+03
.1519D+08  -.2997D+07  .2162D+08  .3456D+02  .4844D+02
-.9927D+07  -.1277D+08  .2086D+08  .4124D+02  .3075D+03
-----
2.0113983      5.5042133
-----
TIME : 11.3500 HOURS
-.1654D+08  -.1704D+08  .1202D+08  .2712D+02  .2746D+03
-.2879D+07  -.2576D+08  .5688D+07  .4732D+02  .2215D+03
.1657D+08  -.2183D+07  .2069D+08  .3136D+02  .5249D+02
-.9944D+07  -.1435D+08  .1981D+08  .4337D+02  .3014D+03
-----
1.8709018      6.1925626
-----
TIME : 11.4501 HOURS
-.1575D+08  -.1645D+08  .1377D+08  .2981D+02  .2793D+03
-.3005D+07  -.2611D+08  .3649D+07  .4253D+02  .2179D+03
.1793D+08  -.1478D+07  .1960D+08  .2827D+02  .5651D+02
-.1004D+08  -.1584D+08  .1862D+08  .4478D+02  .2946D+03
-----
1.7567730      7.1692332
-----
TIME : 11.5500 HOURS
-.1483D+08  -.1584D+08  .1542D+08  .3245D+02  .2843D+03
-.3138D+07  -.2631D+08  .1582D+07  .3767D+02  .2150D+03
.1924D+08  -.3800D+06  .1836D+08  .2525D+02  .6050D+02
-.1019D+08  -.1722D+08  .1727D+08  .4538D+02  .2873D+03
-----
1.7786423      8.5484359
-----
TIME : 12.0500 HOURS
-.1376D+08  -.1523D+08  .1695D+08  .3506D+02  .2893D+03
-.3262D+07  -.2634D+08  -.4972D+06  .3282D+02  .2125D+03
.2049D+08  -.3895D+06  .1698D+08  .2232D+02  .6447D+02
-.1041D+08  -.1849D+08  .1580D+08  .4513D+02  .2800D+03
-----
2.1462068      10.507829
-----
TIME : 12.1500 HOURS
-.1257D+08  -.1463D+08  .1835D+08  .3763D+02  .2946D+03
-.3364D+07  -.2621D+08  -.2573D+07  .2801D+02  .2104D+03
.2166D+08  -.2539D+04  .1547D+08  .1946D+02  .6842D+02
-.1067D+08  -.1963D+08  .1420D+08  .4407D+02  .2727D+03
-----
3.0898991      13.345598
-----
TIME : 12.2500 HOURS
-.1125D+08  -.1406D+08  .1961D+08  .4018D+02  .3000D+03
-.3427D+07  -.2592D+08  -.4628D+07  .2329D+02  .2085D+03
.2273D+08  .2861D+06  .1384D+08  .1665D+02  .7236D+02
-.1096D+08  -.2063D+08  .1249D+08  .4226D+02  .2659D+03
-----
4.8538946      17.615520
-----
TIME : 12.3500 HOURS
-.9819D+07  -.1353D+08  .2072D+08  .4269D+02  .3056D+03
-.3439D+07  -.2548D+08  -.6649D+07  .1868D+02  .2067D+03
.2370D+08  .4837D+06  .1211D+08  .1390D+02  .7627D+02
-.1127D+08  -.2148D+08  .1069D+08  .3982D+02  .2597D+03
-----
7.9541551      24.494625
-----

```

PROGRAM * H D 0 0 *

USER-POSITION :

LATITUDE : 39.500000 DEGREE
LONGITUDE : -74.500000 DEGREE
ALTITUDE : 100.00000 FEET

ECEF-COORDINATES :

X Y Z
1317011.6 -4748990.4 4035321.8

USERTIMES :

START (TSTART) : 38700.000 SEC. = 10.45 HOURS
END (TFIN) : 46800.000 SEC. = 13.00 HOURS
INCR. (TDEL) : 600.00000 SEC
DATE (DTU) : 57.000000 DAYS

USED ALMANACS DTC= 57. TC= 20000.

SAT. ID :	5	6	9	0
	.2305D-02	.1551D-02	.8108D-02	.0000D+00
	.3318D+06	.3318D+06	.3318D+06	.0000D+00
	.1112D+01	.1107D+01	.1104D+01	.0000D+00
	-.6195D-08	-.6457D-08	-.6503D-08	.0000D+00
	.5154D+04	.5154D+04	.5154D+04	.0000D+00
	.5694D+00	-.1550D+01	-.1546D+01	.0000D+00
	-.2092D+01	.2049D+01	.1352D+01	.0000D+00
	.6950D+00	-.1074D+01	-.1142D+01	.0000D+00
	.2656D+08	.2656D+08	.2656D+08	.0000D+00
	.4425D+00	.4472D+00	.4503D+00	.0000D+00
	.8968D+00	.8944D+00	.8929D+00	.0000D+00
	-.4977D+00	-.4606D+00	.2167D+00	.0000D+00
	-.8674D+00	.8876D+00	.9762D+00	.0000D+00
	.1459D-03	.1459D-03	.1459D-03	.0000D+00

OUTPUT OF COMPUTATIONS

=====

THE PRINTOUT IS ARRANGED AS FOLLOWING EXAMPLE :

TIME

POSITION OF SATELLITES IN ECEF-COORDINATES (X,Y,Z)

AND ELEVATION AND AZIMUTH (3-4 LINES)

HDOP AND GDOP

ALL VALUES ARE IN METER

=====

TIME : 10.4501 HOURS

-.1833D+08	-.1915D+08	.2186D+07	.1294D+02	.2531D+03
-.2843D+07	-.2174D+08	.1493D+08	.6517D+02	.2612D+03
-.1073D+08	-.5912D+07	.2334D+08	.2789D+02	.3237D+03

4.7632762 8.3858993

TIME : 10.5500 HOURS

-.1824D+08	-.1889D+08	.4249D+07	.1588D+02	.2571D+03
-.2728D+07	-.2281D+08	.1326D+08	.6319D+02	.2493D+03
-.1039D+08	-.7676D+07	.2298D+08	.3173D+02	.3208D+03

5.3833744 10.201813

TIME : 11.0500 HOURS

-.1803D+08	-.1953D+08	.6279D+07	.1877D+02	.2612D+03
-.2686D+07	-.2376D+08	.1148D+08	.6012D+02	.2396D+03
-.1015D+08	-.9419D+07	.2245D+08	.3530D+02	.3172D+03

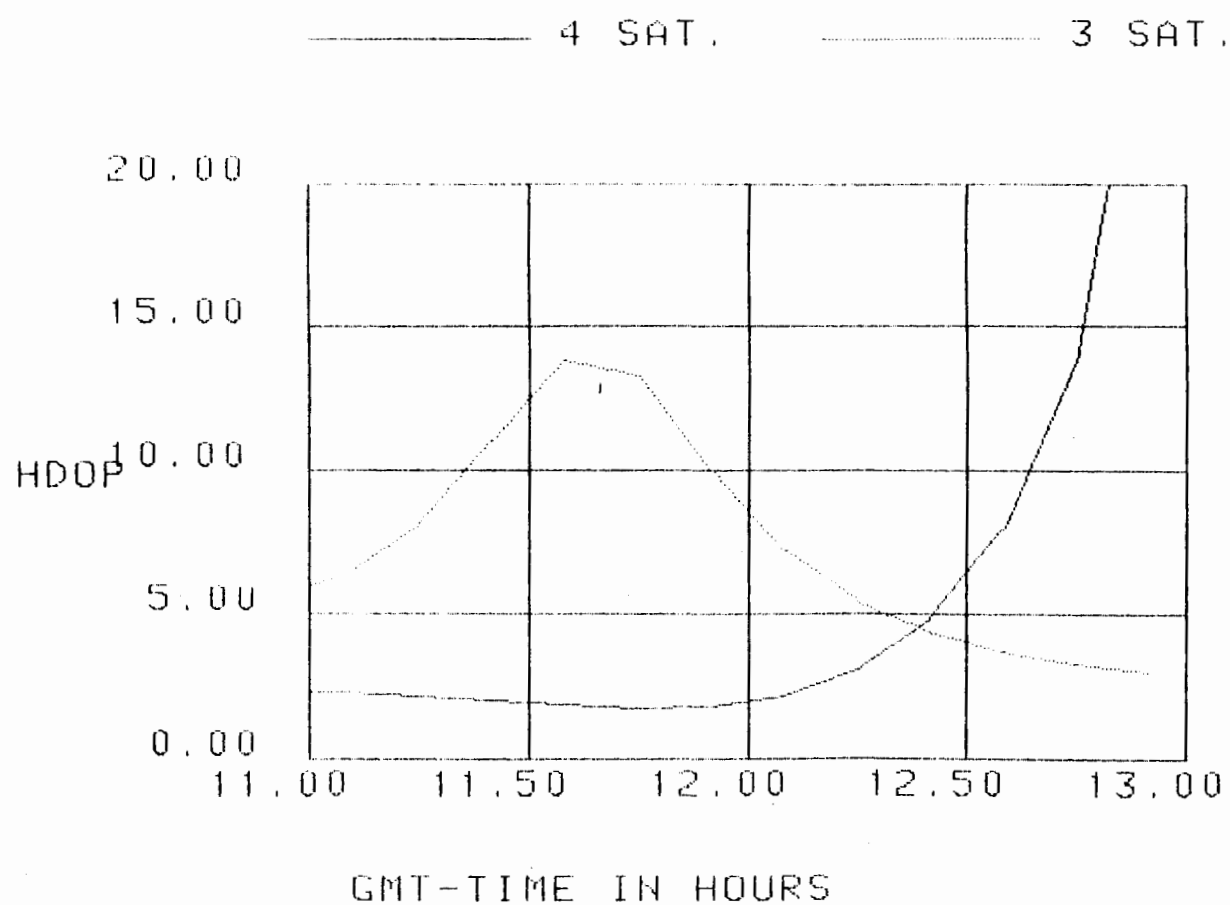
6.4216688 13.226424

```

-----
TIME : 11.1500 HOURS
-.17670+08  -.18090+08  .82610+07  .21610+02  .26550+03
-.27060+07  -.24570+08  .96200+07  .56280+02  .23200+03
-.99940+07  -.11120+08  .21740+08  .38510+02  .31280+03
-----
8.1927780      18.405895
-----
TIME : 11.2500 HOURS
-.17180+08  -.17590+08  .10180+08  .24390+02  .27000+03
-.27740+07  -.25240+08  .76840+07  .51950+02  .22610+03
-.99270+07  -.12770+08  .20860+08  .41240+02  .30750+03
-----
11.009826      26.657326
-----
TIME : 11.3500 HOURS
-.16540+08  -.17040+08  .12020+08  .27120+02  .27460+03
-.28790+07  -.25760+08  .56880+07  .47320+02  .22150+03
-.99440+07  -.14350+08  .19810+08  .43370+02  .30140+03
-----
13.818422      34.879208
-----
TIME : 11.4501 HOURS
-.15750+08  -.16450+08  .13770+08  .29810+02  .27930+03
-.30050+07  -.26110+08  .36490+07  .42530+02  .21790+03
-.10040+08  -.15840+08  .18620+08  .44780+02  .29460+03
-----
13.244735      33.416337
-----
TIME : 11.5500 HOURS
-.14830+08  -.15840+08  .15420+08  .32450+02  .28430+03
-.31380+07  -.26310+08  .15820+07  .37670+02  .21500+03
-.10190+08  -.17220+08  .17270+08  .45380+02  .28730+03
-----
9.9871434      24.453441
-----
TIME : 12.0500 HOURS
-.13760+08  -.15230+08  .16950+08  .35060+02  .28930+03
-.32620+07  -.26340+08  -.49720+06  .32820+02  .21250+03
-.10410+08  -.18490+08  .15800+08  .45130+02  .28000+03
-----
7.1913427      16.889341
-----
TIME : 12.1500 HOURS
-.12570+08  -.14630+08  .18350+08  .37630+02  .29460+03
-.33640+07  -.26210+08  -.25730+07  .28010+02  .21040+03
-.10670+08  -.19630+08  .14200+08  .44070+02  .27270+03
-----
5.4283696      12.201738
-----
TIME : 12.2500 HOURS
-.11250+08  -.14060+08  .19610+08  .40180+02  .30000+03
-.34270+07  -.25920+08  -.46280+07  .23290+02  .20850+03
-.10960+08  -.20630+08  .12490+08  .42260+02  .26590+03
-----
4.3584985      9.3746357
-----
TIME : 12.3500 HOURS
-.98190+07  -.13530+08  .20720+08  .42690+02  .30560+03
-.34390+07  -.15480+08  -.66490+07  .18680+02  .20670+03
-.11270+08  -.1480+08  .10690+08  .39820+02  .25970+03
-----
3.6957639      7.5990681
-----
TIME : 12.4501
-.82890+07  -.13050+08  .21670+08  .45180+02  .31140+03
-.33860+07  -.14890+08  -.86180+07  .14190+02  .20490+03
-.11580+08  -.22180+08  .88000+07  .36880+02  .25420+03
-----
3.2771483      6.4295319
-----

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GRAPH OF HDOP VS. TIME



GRAPH OF HDOP VS. TIME

