# **IMPACT OF TRUCK PLATOONING ON LOADING OF BRIDGES IN OREGON**

# **Final Report**

**SPR 848**



Oregon Department of Transportation

## **IMPACT OF TRUCK PLATOONING ON LOADING OF BRIDGES IN OREGON**

### **Final Report**

#### **PROJECT 848**

by

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## **1.0 INTRODUCTION AND BACKGROUND**

<span id="page-18-0"></span>Truck platooning is an emerging autonomous vehicle technology where two or more heavy trucks operate at close spacing to achieve fuel economies and perhaps, in the future, a reduction in labor by partial or full autonomous operations. Truck platoons are expected to be more widely and quickly adopted than autonomous vehicles (Banker, 2019; Bishop, 2019). Current versions of truck platooning technology available in the market use radar and vehicle-to-vehicle communications (V2V) to synchronize acceleration and braking of lead and rear truck, with both trucks operated by humans (Bishop, 2019). However, higher return of investment is expected when the follower truck is automated (Bishop, 2020a). Platooning technology is being viewed as a way to improve safety and throughput and is expected to have applications in other sectors such as forestry, mining, port drayage, and military logistics (Bishop, 2020a; Bishop 2020b). Sanctions in ORS 811.485 against a vehicle operator following another vehicle too closely have been excepted by House Bill 4059 Section 40 when a "connected automated braking system" is employed, without requiring permitting or notification to ODOT. The close spacing of platooned trucks allowed by this provision can impose loading on some bridges in excess of the load levels currently limited by weight regulations applicable to individual trucks. This potential overloading could reduce the lifespan of Oregon bridges and it is therefore important to understand the magnitude of truck platoon loading effects. To this end, this interim report contains a review and summary of the available literature on truck platooning technology, truck platoon studies, literature reporting structural analyses performed to quantify truck platoon loading effects, and a discussion of refined structural analysis methods which can capture those load effects and load distributions more accurately.

#### <span id="page-18-1"></span>**1.1 OBJECTIVE**

The objective of this research was to determine what combination of truck configurations (axle weights and axle spacings) and platoon vehicle spacings (headspace) may exceed acceptable load levels for Oregon bridges. To answer this question, bridge analyses were performed on representative bridges with truck platoon configurations consisting of trucks allowed under Oregon law and analysis results were compared with those based on truck loads currently used in Oregon. Analysis results are used for policy and regulatory recommendations and for recommendations to update load ratings on Oregon's bridges.

#### <span id="page-18-2"></span>**1.2 ORGANIZATION OF REPORT**

This report contains a literature review on existing truck platoon technologies and published truck platoon studies, structural analyses performed to quantify the load effects from truck platoons on bridge components, and refined structural analysis methodologies that can capture the distribution of vehicle loads in bridges. The Society of Automotive (SAE) International definitions of Level 0 to Level 5 are used to refer to the various levels of driving automation standards in this report (Shuttleworth, 2019). Moving load analyses performed as part of this research are discussed and ratios of internal forces from truck platoon configurations to legal and single-truck live loads analyzed in depth. A load rating example is discussed for reference. Finally, the results are summarized, and recommendations presented.

## **2.0 LITERATURE REVIEW**

### <span id="page-20-1"></span><span id="page-20-0"></span>**2.1 TRUCK PLATOONING**

This section reviews research projects and demonstration and evaluation studies on truck platooning conducted in the United States, Europe, and Asia over the last two decades.

Advantages of truck platooning are increased fuel efficiency and safety, as well as increased comfort and convenience for the driver (Tsugawa et al., 2016). This study reviews results from three continents describing configurations, technologies, and studies performed. Besides reporting fuel savings, one of the interesting findings is that autonomous driving for trucks may be implemented easier and faster than autonomous passenger cars because of the direct cost savings from reduced fuel consumption and, in the long run, reduced personnel costs.

The National Renewable Energy Laboratory (NREL) has conducted a series of research projects to determine the value of truck platooning in different aspects. The fuel savings varied with driving conditions, ambient temperature, load, and distance between platoons. In a three-truck platoon, fuel savings of up to 10%, 17%, and 13% were observed for the leading, follower, and trailer vehicles, respectively (Lammert et al., 2020, 2014; McAuliffe et al., 2018). The research also found that up to 63% of total miles driven by Class 8 trucks were at speeds for which platooning can occur and 65% of total miles driven by FHWA Class 7 and Class 8 trucks (see [Figure 2-1\)](#page-21-0) could be driven in platoon formation (Lammert et al., 2018; Muratori et al., 2017). Several other studies have also highlighted the fuel and environmental benefits of truck platooning (Zhang et al., 2020; Humphreys et al., 2016; Tsugawa et al., 2016). Given the cost benefits of truck platooning, Bhoopalam et al. (2018) provide a detailed survey of optimizing and planning the supply chain and logistics operations under platoons.



<span id="page-21-0"></span>**Figure 2.1: FHWA 13 Vehicle Classification (Source: Federal Highway Administration, 2016)**

Kuhn et al. (2017) recommended ideal roadway characteristics for truck platoons, e.g., interstate or multi-lane divided highways with two or more lanes in each direction, level terrain, low curvature, and sufficient lane and shoulder width as well as sufficient exit and on-ramp distances. With desirable roadway characteristics, the key question to consider for platoons is their effect on transportation structures, particularly bridges, many of which were built in the interstate expansion of the 1950s and are now reaching the end of their design lives.

Hartmann (2019) summarized many of the key issues to consider with truck platoons. Platoons of two to four trucks are expected in the near term, but it is possible that as platoon technology matures, larger platoons will emerge. One of the main interests in truck platoons is fuel savings (Roberts et al., 2016), which tends to increase as truck spacing decreases. Accordingly, truck spacing is an important consideration because spacing will have a significant impact on load effects in bridges. Similarly, individual axle weights are of concern in closely spaced platoons as well as bridge postings for weight and spacing limits of platoons. Consistent with structural engineering intuition, it is likely that long span bridges will be affected by truck platoons more so than short span bridges.

According to Bishop (2019), the first-generation truck platoons are expected to follow level one automated driving protocols where the driver is driving even when the automated driving support is engaged (Shuttleworth, 2019). The driver is expected to supervise and monitor the driving and accelerate, decelerate, brake, and steer to maintain safety. The lead driver may or may not use Adaptive Cruise Control. However, the Forward Collision Avoidance and Mitigation feature

must always be turned on for the leader and the follower trucks. The longitudinal control of the follower truck is automated and controlled by the leader. However, the driver of the follower truck is responsible for reacting to real-world traffic, weather conditions, and appropriately steering the truck. Both drivers will be communicating while driving.

Table 2.1 shows a number of truck platooning studies in the United States, Europe, and Asia which had extensive testing and validation (Bishop, 2019). All of the tests have leader trucks following level one automation. Most of the research efforts are focusing on platooning with two-trucks. By 2020 in the United States, full and commercial deployment was allowed in 27 states. Testing was allowed in five more states – California, Washington, Wyoming, Virginia, and New Jersey (see Figure 2.2). These 32 states account for 80% of US annual truck freight traffic (Bishop, 2020a).

Commercial	<b>Country</b>	Organizatio	<b>Automatio</b>	<b>Automatio</b>	<b>Numbe</b>	Year of
		n	n	$\mathbf n$	r	Operatio
Research			Level	Level	Of	n
			Leader	<b>Follower</b>	<b>Trucks</b>	
Commercial	<b>USA</b>	Peloton	L1	L1	$\overline{2}$	2018
Commercial	<b>USA</b>	Freightliner	L1	L1	$\overline{2}$	2018
Research	USA/	Auburn	L1	L2	$2 - 4$	2018
	Canada	University				
Commercial	Germany	<b>MAN</b>	L1	L2	$\overline{2}$	2018
<b>Research</b>	<b>UK</b>	Transp.	L1	L2	$\overline{3}$	2018
		Research Lab				
		(Helm-UK)				
<b>Research</b>	NL	Rijkswaterstaa	L1	L1	$\overline{2}$	2019
<b>Research</b>	Sweden	Volvo/Scania	L1	L2	$\overline{2}$	2019
Commercial	Finland	Scania	L1	L2	$\overline{3}$	2019
<b>Research</b>	Europe	ENSEMBLE,	L1	L2	$\overline{2}$	2019
		EC				
<b>Research</b>	Singapor	Port of	L1	L4 Driverless	$\overline{2}$	2019
	e	Singapore				
Research	Japan	<b>METI</b>	L1	L4 Driverless	$\overline{3}$	2019

<span id="page-22-0"></span>**Table 2.1: Truck Platooning Studies with Extensive Evaluation and Validation (Source: Bishop, 2019)**



**Figure 2.2: Truck Platooning Status in US (Source: Bishop, 2020a)**

<span id="page-23-0"></span>Truck platooning studies have been conducted in Europe since 2002. One of the earliest studies was the CHAUFFEUR project from 2000 to 2003, funded by the European Union (TRIMIS, 2021). The project focused on a detailed evaluation of the technology needed for the electronic coupling of two-trucks with only the leader truck driver being active. The project also conducted a feasibility study for truck platooning with more than two-trucks with only the leader truck driver being active as well as automated truck platooning. A system, CHAUFFEUR Assistant, which enables two-truck platooning, and five prototype vehicles, was developed.

Kunze et al. (2010) developed an electronic coupling system for trucks called KONVOI which enabled both longitudinal and lateral control. The system was tested on test tracks and trial runs conducted on motorways. The platoon had up to four trucks at a spacing of  $10 \text{ m } (33 \text{ ft})$ .

The Grand Cooperative Driving Challenge (GCDC) was an open competition on cooperative, autonomous driving in the Netherlands in the summer of 2011 (Lauer, 2011). The objective was to create a longitudinal control setup in a platoon with a human driver taking care of lateral control. Unlike previous demonstrations, The GCDC testing was done on a different vehicle of various sizes – small to large trucks with the lead vehicle chosen by the organizers. The competition was held on a highway; however, the highway was closed off to regular traffic during the competition. Processing and fusing data from multiple vehicles using different control and communication systems in regular traffic as well as data from on-board sensors, was identified as a key challenge.

Bergenheim et al. (2012) compared five platooning projects (see Table 2.2):

- SARTRE: European project to develop platooning systems for mixed traffic passenger car and trucks. The project focused on both longitudinal and lateral control. A fivevehicle platoon demonstration was conducted in Barcelona, Spain, in 2012.
- PATH research project is based in California. The experiments showed that two-truck platoons could be implemented at a gap of 3 m (10 ft), whereas three-truck platoons can be implemented at a gap of 4 m (13 ft). The research showed that truck platooning could lead to 10% to 15% fuel savings for the follower trucks. PATH focused on platooning of homogenous vehicles.
- GCDC, which was explained above, focused on integrating solutions from several vendors for platooning of heterogeneous vehicles in mixed traffic flow.
- Energy ITS is a platooning experiment and demonstration in Japan with three-truck platoons traveling at 80 km/h (50 mi/h) with a gap of 10 m (33 ft). The platoons are assumed to consist of homogenous trucks.
- SCANIA-platooning is a series of truck platooning experiments and research efforts in Sweden. The main goal of the research was fuel savings through platooning. The truck gaps considered in trials were 40 to 60 m (130 to 200 ft).

	Vehicle	Control	<b>Infrastructure</b>	<b>Traffic</b>	<b>Sensors</b>	Goals
	<b>Type</b>		<b>Requirements</b>	Integration		
<b>SARTRE</b>	Mixed	$Lat +$	None	Highway,	Production	Comfort,
		Long		mixed		safety,
						congestion,
						energy
<b>PATH</b>	Cars or	$Lat +$	Reference	Dedicated	Mixed	Increased
	Heavy	Long	markers in	lane		throughput
			road surface			per lane,
						energy
						saving
<b>GCDC</b>	Mixed	Long	Augmented	Mixed	State of Art	Accelerate
			<b>GPS</b>		$(SoA)[1]$ and	deployment
					production	of
						cooperative
						driving
						systems
Energy-	Heavy	Lat $+$	Lane	Dedicated	State of Art	Mitigate lack
<b>ITS</b>		Long	markings	lane	(SoA)	of skilled
						drivers
<b>SCANIA</b>	Heavy	Long	None	Highway,	No V2V	Commercial
				Mixed	communication	fleet, energy
					in first stage	

<span id="page-24-0"></span>**Table 2.2: Comparison of Truck Platooning Projects (Bergenheim et al., 2012)**

The COMPANION research project based in Sweden, with SCANIA as the lead partner, focuses on developing off-board and on-board platforms to promote cooperative mobility and evaluate legislative challenges (Eilers et al., 2015). The project's focus is to develop systems that aid in route optimization, including other vehicles to platoon with, speeds, merge and split points, etc. The project also evaluates systems for automated longitudinal control once the driver reaches the highway.

In the United States, Maxwell et al. (2013) highlights the need for developing standards for evaluating platooning technologies for military convoy applications. The authors describe features specific to military convoy applications such as obstacle avoidance and area mapping and stress the importance of developing clear benchmarks for evaluating technology solutions.

In collaboration with Peloton trucking, Auburn University evaluated the possibility of using truck platooning in reducing freight transport costs (Bevly et al., 2015). They tested a "Driver Assistive Truck Platooning" System, an SAE Level 1 Automated system (Shuttleworth, 2019) where the longitudinal control is automated, but the driver still controls the steering, acceleration, and braking. A computational fluid dynamics model was developed to evaluate drag reductions from two-truck platooning. Fuel economy testing was done on a test track with spacings of 9, 12, 15, 23, and 46 m (30, 40, 50, 75, and 150 ft) with total savings of around 7% observed for a 9 m (30 ft) gap. However, the gap for commercial operations was expected to be at least 15 to 23 m (50 to 75 ft) to account for driver comfort with greater distances under poor weather conditions. The research concluded that while further studies are needed, the initial results demonstrate the economic viability of truck platooning in reducing freight costs and improving efficiency.

Individual trucking companies have conducted truck platooning demonstrations in collaboration with other public and private sector enterprises. Daimler conducted two-truck platooning tests on select highways in Oregon and Nevada in 2017 (Daimler, 2017). Peloton technology demonstrated two Volvo Class 8 truck platoons on I-96 in Michigan and over 1000 miles in the Florida turnpike. The trucks were separated at 20 m (65 ft) and both trucks had drivers in control (CCJ, 2017a; CCJ, 2017b). North America conducted a demonstration of three-truck platoons on Triangle Expressway, NC 540 in collaboration with FedEx and North Carolina Turnpike Authority (Fleet Magazine, 2018). The platoons consisted of three Volvo NL trucks pulling two 28 ft trailers. The platoon traveled at 100 km/h (62 mi/h) with a gap of 1.5 seconds (around 41.5 m (136 ft)). All three-trucks had professional truck drivers. Dedicated short range communication based Cooperative Adaptive Cruise Control technology was used for the platoons.

Locomation, a startup specializing in autonomous and truck platooning technology have conducted demonstrations in multiple regions of the United States. Locomation in collaboration with Smart Belt Coalition, a consortium of 12 agencies and universities based in Pennsylvania, Michigan, and Ohio, demonstrated a L1 automated platoon of two tractor trailer platoons. The platoon made a trip of 450 km (280 mi) from Pennsylvania to Michigan through Ohio (Carey, 2020; The Trucker, 2020). Locomation in collaboration with Wilson logistics conducted deliveries of 14 loads from Portland, Oregon to Nampa, Idaho – a distance of 675 km (420 mi) along I-84. The platoon comprised of two-trucks with drivers equipped with the company's Autonomous Relay System (Fisher, 2020).

### <span id="page-26-0"></span>**2.2 STRUCTURAL ANALYSES USING TRUCK PLATOONS**

Through structural analysis, bridge engineers can obtain an estimate of the effects of truck platoons on bridge condition. However, the literature on structural analyses for truck platoons is limited, presumably because platoons do not pose the types of additional analysis complexity or changes in analysis methodology that tend to invite academic research. This section summarizes literature documenting the structural analyses used to quantify the loading effects of hypothetical truck platoons.

Yarnold and Weidner (2019) present a parameter study to evaluate the live load effects of two to four platooning FDOT C5 trucks on hypothetical single and multi-span steel-girder composite bridges with different span lengths modeled with girder line analysis. Using a distribution factor of 1 for all cases, the shear force and bending moment demands were computed for a range of truck platoon configurations and compared to those generated from the AASHTO LRFD (2017) as well as the AASHTO Standard Specification (2002) design live load models. Multiple presence was not investigated, and the number of girders, deck thickness, and web depth were kept the same for all analyses.

The following variables were studied:

- Bridge span configuration  $(L = span length)$ :
	- o Simple span, span length, L
	- $\circ$  Two-span continuous, span lengths,  $L L$
	- o Three-span continuous, span lengths,  $0.8L L 0.8L$
	- o Three-span continuous, span lengths,  $0.4L L 0.4L$
- Span length, L ranging from 6.1 to 91 m (20 to 300 ft) in equal increments of 6.1 m (20) ft)
- Live load models considered:
	- o Two-, three-, and four-truck platoons consisting of FDOT C5 trucks, vehicle spacings, *Sa* ranging from 6.1 to 12.2 m (20 to 40 ft) in equal increments of 1.5 m (5 ft) (see Figure 2-3)
	- $\circ$  AASHTO LRFD design live load (HS20-44 + lane load or tandem axle + lane load)
	- o AASHTO Standard Specifications design live load (HS20-44 or lane load + concentrated loads)



<span id="page-27-0"></span>**Figure 2.3: Truck selected for parameter study. (Source: Yarnold and Weidner, 2019) Gross vehicle weight (GVW) = 356 kN (80 kip).** 

Three-dimensional envelopes were generated separately for positive and negative bending moments, and maximum shear forces, allowing for a comparison between truck platoons and the two LRFD design loads. The main findings of the study are that bridges designed with AASHTO LRFD will fare overall much better compared to bridges that were designed using the outdated AASHTO Standard Specifications. For multi-span bridges, the AASHTO LRFD live loads were found to produce larger negative bending moments compared to the moments found considering the truck platoons. Bridges with longer spans and closely spaced truck platoons are of concern no matter which design code was used. The authors recommend that the following factors are considered in future research: dynamic load allowance, multiple presence, fatigue, braking forces, load ratings, other truck platoon configurations, and other structure types.

In subsequent work, Tohme and Yarnold (2020) performed a parameter study based on the AASHTO Manual for Bridge Evaluation's load rating procedure (AASHTO 2018). Only the operating level was studied, but both the design and legal live loads were considered. The variables in this study included span length, number of spans (all having equal span length), number of trucks, and vehicle spacing. The benchmark bridge they used was the AASHTO MBE Example Bridge A1, which is a single-span steel girder composite bridge. The same girder line analysis was employed to compute ratios of load rating factors (LR) for truck platoon loadings and the AASHTO design live loads and legal loads. The study only considered bending moments. In addition to the most current load rating procedure, i.e. LRFR, the authors also computed LR ratios for the older LFR and ASR methodologies for comparison. Since the authors ultimately report load rating ratios, the live load factors cancel out. This implies that the authors assume that the live load factors for the design loads and the truck platoons are identical. In reality, live load factors for truck platoons would have to be calibrated based on actual data, which currently does not exist or is not publicly available. The study confirmed that the number of trucks in a platoon and their spacing plays an important role in the load effects on steel girder composite bridges.

Sayed et al. (2020) analyzed a typical single-span and a typical three-span continuous bridge for truck platoons consisting of 35-ton (315 kN = 70 kip) FDOT SU4 trucks. A comprehensive case study on an actual single-span bridge was also performed following the integrated bridge load rating (IBLR) methodology, which considers both super as well as substructure load ratings. The final load rating is based on the lower of the two rating factors. The authors found that platoons can lead to significant increases in live load reaction compared to single truck loadings. As vehicle spacing increases, the detrimental effect of truck platoons on flexural response tends to decrease; however, platooning causes significant increases in shear. The most significant increases in load effects due to truck platoons, which also translate to the substructure, were found for simple span bridges with span lengths over 15.2 m (50 ft). The authors emphasize the need to reassess the applicability of the federal bridge formula (FBF) for truck platoons. The assumption that as long as trucks adhere to the formula seems inadequate given that several states currently allow truck weights higher than those specified by the formula (NCHRP Report 575). Finally, bridge inspection and monitoring are discussed as an important tool to create data to identify critical loading conditions due to truck platoons and to improve maintenance and preservation.

Kamranian (2018) studied platoons of Canadian legal trucks (two, three, and four-truck platoons with as little as 1 m (3 ft) spacing) for a specific bridge in Alberta, Canada. The bridge was built in 1960 and is a three-span steel-concrete composite bridge with riveted steel girders. Span lengths are 45.1 - 49.4 - 45.1 m (148 - 162 - 148 ft). The Canadian load rating procedure was followed, which is similar to the MBE procedure. Using the computer program CSiBridge, a detailed finite element analysis was performed to compute live load rating factors (LLRF) for all girders. Additionally, to verify the output, a simple 2D model was set up in SAP2000. Both Alberta legal non-permit (NP) as well as permit trucks were considered. Specifically, CS1 (28 ton), CS2 (49 ton), and CS3 (63.5-ton) legal NP trucks were used. Note that target reliability indices in the Canadian code are a function of the permit type, structural system, element behavior, and inspection level. Kamranian found that the bridge could handle two-truck platoons consisting of Alberta NP trucks, but the weights of individual trucks would have to be restricted for three and four-truck platoons.

Devault (2017) performed an approximate analysis in which they first derived bridge capacities from recorded rating factors. These capacities where then used to infer TP rating factors for twotruck platoons consisting of C5 80-kip trucks for selected routes in Florida. Rating factors from the platoons were compared with the ones obtained using the AASHTO design live loads (HL-93 operating) as well as FL120 permit ratings. In addition, 88-kip trucks were used in two-truck platoon configuration. The load demands for these trucks were simply scaled based on the truck weight ratio. The analysis showed that for the 80 and 88-kip truck platoon configurations, 6 and 22, respectively, out of 2467 analyzed bridges would be insufficient. The analysis assumed a 40 ft spacing between vehicle axles. When spacing was increased to 60 feet, all analyzed bridges passed the load rating for the 80-kip truck platoon configuration and 10 remained unsuitable for the 88-kip truck platoon configurations.

Based on the Florida DOT report by Devault (2017), Crane et al. (2018) found that two-truck platoons with 30 ft spacing will not generate critical load effects in 99% of bridges on Florida interstates and turnpikes. The analysis methods were simplified in order to assess 2467 bridges, so Crane et al. recommended more detailed modeling of load effects in bridges in order to assess the effect of truck platoons. Additional modeling is also necessary for closer spacing and larger platoons.

### <span id="page-29-0"></span>**2.3 STRUCTURAL ANALYSIS METHODOLOGIES**

Load rating is an essential component of bridge preservation and in most cases a sufficient substitute for load testing or other on-site monitoring practices. In the process of load rating, structural analysis is performed to determine the load effects (or demands) on the structure due to both design live loads as well as certain legal trucks on an operational level. The capacity side of load rating should reflect actual system and material conditions of the structure (AASHTO 2018). The resulting bridge rating factor (RF) is the smallest of the rating factors obtained for all components and corresponds to the usable live load capacity of a bridge.

Since the early 1900s, bridges in the US have been designed considering multiple trucks in succession. For example, in 1923, "Shoemaker's Truck Train and Equivalent Load" was proposed and is based on five trucks spaced at 9 m (30 ft) with individual trucks weighing, 150 - 150 - 200 - 150 - 150 kN (34 - 34 - 45 - 34 - 34 kip) (Kulicki 2014). The individual trucks were assumed to have two axles. The notional design live loads proposed based on this truck train were a distributed and concentrated load of 8.75 kN/m (600 lb/ft) and 125 kN (28 kip), respectively. While debated and continually adjusted since then, some combination of two different live load models have prevailed in current standards. The design live load model used in the current AASHTO LRFD specifications is referred to as the HL-93 (AASHTO 2020). While this live load does prescribe a train of two design trucks, typically used to determine the maximum negative bending moment in a multi-span bridge, the truck spacing is fixed at 15 m (50 ft) and the truck weights are reduced by 10%. It has been recognized by many bridge engineers that the current design loads might not capture the demands exerted by truck platoons. The main reason is that even if the individual trucks in a platoon conform to the federal bridge formula (FHWA, 2019a), the potentially very small spacings between trucks will likely result in higher load demands in bridge components.

The challenge with truck platoons is that they do not currently exist, i.e. no actual data is available, e.g. from weigh-in-motion (WIM) stations, to estimate their occurrence in conjunction with regular traffic. Hence, live load factors, which are needed to determine factored demands in both structural analysis and load rating procedures, do not exist. A framework to include truck platoons in load rating procedures once data is available, and that can be readily adapted for truck platoons, is presented by HNTB and Ghosn (2019). In their methodology they determined live load factors for Fast Act Emergency Vehicles (EV) using statistical analysis of available WIM data in combination with Monte Carlo simulations, accounting for the probability of EV occurrences with legal trucks and random lane loads over multiple lanes.

With lane and axle loads and spacings established, numerical simulation of bridge response to vehicle loading covers a wide range of approaches, from girder line analysis to three-dimensional (3D) finite element analysis (FHWA 2019b). As structural analyses increase in complexity, the results generally become more accurate. While girder line analyses have low computational cost, i.e., they take seconds to run, these models are known for their inaccuracies in capturing actual live load distribution (see, e.g. Michaelson (2010)). Additionally, current AASHTO LRFD live load distribution factors might not be applicable for all truck platoon configurations. 2D grillage models lead to better estimates of load distribution between girders but are more computationally intensive. Analyses based on 3D solid finite element models can require hours to run, but can lead to accurate assessments of load effects in specific bridge components and can consider

nonlinear response due to overloading or deterioration. Furthermore, refined 3D modeling using the finite element method (FEM) can provide improved distribution factors for simplified girder line analyses (Song et al (2003), Hughs and Idriss (2006), Terzioglu et al (2017)). The tradeoff between accuracy and computational cost is illustrated in Figure 2.4.



<span id="page-30-0"></span>**Figure 2.4: Tradeoff between accuracy and computational cost for common bridge analysis approaches for vehicle loading.**

Analysis of bridges for moving vehicle loads is a semi-automated process that is already incorporated in many software packages such as CSiBridge. The typical approach for moving load analysis is to sweep a configuration of axles with known weights and relative spacings in small increments across a bridge model and perform a static structural analysis at each location. For girder line analysis, the bridge is modeled as a series of separate 1D beams and distribution factors (DF) approximate the effects of 2D load distribution. This type of analysis is still commonly employed for both design as well as load rating of slab and slab-girder bridges. Detailed 3D bridge models can be used to obtain a more accurate load distribution and to examine load effects on substructure components. 3D analysis is also necessary to analyze more complex bridge designs such as arch, suspension, or cable stayed bridges. However, 3D models can be computationally expensive and require special skill and expertise to develop, verify, and interpret correctly. Some software packages build FE models for specific bridge types automatically based on minimal user input via a so-called "Wizard" (e.g. CSI 2021). Dynamic vehicle effects are typically approximated with an impact factor applied to the static analysis results (AASTHO 2020).

The BRASS suite of computer programs is commonly used for moving load analysis as well as load rating. BRASS-Girder (WYDOT 2020) performs moving load analysis of simple span and continuous bridge girders as well as other span configurations. Other programs from the BRASS family can analyze other bridge components, e.g., BRASS-Pier and BRASS-Pad, and other

bridge types, e.g., BRASS-Truss. Other commercial software for load rating and analysis of bridges is available from Bentley Systems, CSiBridge (CSI 2020), and Midas-Civil.

The open-source software OpenSees is also capable of being augmented with programming for moving load analysis and probabilistic assessment of bridge models (Scott and Higgins 2006). With programming capabilities, originally via Tcl (a scripted programming language) and more recently with Python, OpenSees lets engineers customize analysis and load rating calculations (Scott et al. 2008). The software includes 3D formulations for solid elements as well as 2D line elements for grillage models. Rapid model building and moving load analysis can be achieved and visualized with Python commands through the use of Jupyter Notebooks to contain programming, documentation and results presentation. Moment and shear interactions from a girder line analysis obtained using OpenSees and Jupyter Notebooks are shown in Figure 2-5 for the bridge model considered in Scott et al (2008).



<span id="page-31-0"></span>**Figure 2.5: Girder moment-shear response history near an interior support of the McKenzie River Bridge on I-5 in Oregon. Loading scenario is two Legal 3-3 trucks with 20 ft head spacing.** 

In load rating, an important part of bridge preservation, the demands incurred by vehicle loads are compared with capacity estimates for bridge components. Reliability-based assessment and load rating are implemented in the AASHTOWare (2018) software. Reliability-based load rating of Oregon bridges using girder line analysis for reinforced concrete deck girder bridges has been performed in previous research projects (ODOT 2006). Additionally, live load factors have been calibrated based on WIM data (Pelphrey et al., 2008); however, there is a general lack of literature on load rating for connected autonomous vehicles because calibration of live load factors is currently not possible.

### <span id="page-32-0"></span>**2.4 SUMMARY**

Truck platooning is an emerging technology in the United States with various levels of State legislation and adoption. This literature review has identified the following key takeaways and knowledge gaps relative to preserving Oregon bridge infrastructure and mitigating the adverse loading effects of truck platoons:

- Truck platooning in the U.S. is not regulated top-down as it is done, for example in Europe. As a result, many different companies are developing their own autonomous driving technologies and are currently testing them on U.S. roads. Compared to autonomous passenger cars, truck platooning is expected to be adapted more quickly, due to the direct cost savings that it will provide trucking companies (Tsugawa et al., 2016).
- Reported truck spacings vary from study to study. While the largest fuel savings are reported for spacings as little as 6 m (20 ft), it is not expected that these will necessarily be adopted, due to safety concerns. Research indicates that the gap for commercial operations was expected to be at least 15 to 23 m (50 to 75 ft) with greater distances under poor weather conditions (Bevly et al., 2015).
- Very little literature is available on the impact of truck platoons on bridges as quantified by structural analyses. The lack of literature may be due to some rather intuitive results, e.g., that truck platoons increase shear at supports and can lead to increased flexural demands only on longer spans. A challenge is that truck platoon configurations, i.e. type of number of participating trucks and truck spacings, are currently unknown.
- Only one study (Kamranian 2018) to date has gone past the standard 1D girder line analysis. One question is what distribution factors should be used for girder line analysis and these factors could be computed from 2D grillage type models.
- All analyses, including the load rating study by Thome and Yarnold (2020), are based on comparisons between demands from hypothetical truck platoons and design live or legal loads. Actual load ratings involving truck platoons cannot be performed currently because they require live load factors. Since there are no actual data, e.g. from WIM stations, available, these factors are unknown.
- Comprehensive moving load analyses for the truck platoons expected in Oregon will lead to more detailed assessments of impacts on the state's bridge infrastructure and will provide the foundation to develop policies.

## **3.0 METHODOLOGY**

#### <span id="page-34-1"></span><span id="page-34-0"></span>**3.1 REPRESENTATIVE BRIDGE MODELS**

In this research, the National Bridge Inventory (NBI) dataset was utilized to compile a record of bridges located in the State of Oregon. The initial dataset for Oregon encompassed a total of 8,214 bridges. This baseline dataset was progressively refined by adding filters until a more manageable set, consisting of 832 bridges, was obtained. Table 3-1 summarizes the selected NBI items that were used as variables to characterize the final dataset and determine a set of representative bridge models. For each of these variables, histograms, frequency tables, and percentile tables (only for continuous variables) were created and are shown in Appendix A, Figures A1 to A40.

<b>NBI</b> Item	<b>Name</b>	<b>Type</b>	Unit	Filter?
27	Year built	Continuous	yr	N <sub>o</sub>
31	Design load	Categorical		N <sub>o</sub>
34	<b>Skew</b>	Continous	Degrees	Yes
41	Structure open, posted, or closed to traffic	Categorical		Yes
43A	Kind of material and/or design	Categorical		Yes
43B	Type of design and/or construction	Categorical		Yes
45	Number of spans in main unit	Discrete		N <sub>o</sub>
48	Length of maximum span	Continous	m	N <sub>o</sub>
58	Deck condition rating	Discrete		N <sub>o</sub>
59	Superstructure condition rating	Discrete		No
63	Method used to determine operating rating	Categorical		Yes
64	Operating rating	Continous	ton	No
65	Method used to determine inventory rating	Categorical		Yes
66	Inventory rating	Continous	ton	N <sub>o</sub>
104	Highway system of the inventory route	Categorical		Yes

<span id="page-34-2"></span>**Table 3.1: NBI Items Used As Variables In This Study. Terminology Follows (FHWA 1995).**

Figure 3.1 shows the total number of bridges that exist in each dataset after different combinations of filters were applied. The goal was to reduce the dataset to a manageable amount of bridges while maintaining a representative set of bridges for moving load analysis under truck platoons.



<span id="page-35-0"></span>**Figure 3.1: Size of datasets, Dataset 0 = unfiltered dataset, Dataset 6 = final dataset** 

The typical bridge in the final dataset  $(=$  Dataset 6) has the following characteristics (based on mode, i.e., highest frequency):

- was built in the early 1960s, i.e., is 55 to 60 years old
- was designed based on the HS 20 live load model (second most common: HS 25)
- $\bullet$  has no skew, i.e., skew angle = 0 Degrees
- is made of prestressed concrete (followed by reinforced concrete)
- consists of a stringer/multi-beam or girder structural system (followed by slab)
- has either one or three spans (followed distantly by two, four, five, six, etc. spans)
- has a length of the maximum span,  $L = 12$  to 16 m (for all bridges), and



• has a deck and superstructure condition rating of " $7$ " (= good condition) followed closely by "6" (= satisfactory condition), and
o a load rating of 25 to 30 tons and 20 to 25 tons, respectively

The pertinent variables describing a bridge model are the number of spans encoded in NBI Item 45 and the lengths of the individual spans. For the latter, only the length of the longest span is available in NBI Item 48. Figure 3.2 illustrates the terminology used in this research to describe representative bridge models with one to three spans, i.e.,  $n = 1$  to 3.



**Figure 3.2: Illustration and terminology used for one to three spans**

The following representative bridge model configurations were analyzed by means of moving load analysis for 749 cases:

- Single-span with  $L = 15$  to 65 m (in steps of 5 m) 11 cases
- Two-span with same  $L = 25$  to 75 m (in steps of 5 m) and  $\alpha = 1.0$  to 0.75 (in steps of  $(0.05) - 66$  cases
- Three-span with  $L = 15$  to 80 m (in steps of 5 m),  $\alpha = 1.0$  to 0.75 (in steps of 0.05), and  $\beta$  $= 1.0$  to 0.65 (in steps of 0.05) – 672 cases

Lower and upper bounds of span lengths correspond, approximately, to the 30 and 99 percentiles, respectively. The following assumptions were made:

• There is no distinction between non-continuous and continuous construction the way it is coded in NBI Item 43A. If a multi-span bridge consists of non-continuous spans, then the results from the corresponding single-span bridge models shall be used for each of the spans.

• More than three spans are not considered; three spans are deemed sufficient to cover bridges with more spans.

# **3.2 LOADING SCENARIOS**

With a suite of representative bridge models, baseline and systematic moving load analyses were performed for the following 20 vehicle live loads, for which axle weight and spacings are known:

- Design live loads (1) AASHTO LRFD HL-93
- Oregon legal trucks (3) Type 3, 3S2, and 3-3
- Oregon specialized hauling vehicles (SHVs) (4) SU4, 5, 6, and 7
- FAST Act emergency vehicles (EVs) (2) EV2 and EV3
- Oregon continuous trip permit (CTP) trucks  $(3)$  CTP-2A, 2B, and 3
- Oregon single trip permit (STP) trucks (7) STP-3, 4A, 4B, 4C, 4D, 4E, and 5BW

"Baseline" analyses were conducted for each (non-platooned) vehicle listed above, e.g., the OR 3 Legal truck (see Figure 3-3, left) and the OR 3S2 Legal truck (see Figure 3-3, right), and created output (Section 3.3) for comparison with platooned vehicles (or truck platoons).



#### **Figure 3.3: Axle weight and spacing for a OR 3 Legal truck (left) and OR 3S2 Legal truck (right) (1 kip = 4.45 kN, 1 ft = 0.305 m)**

"Systematic" analyses examined the effects of two and three-truck platoons for each of the live loads listed above. To prevent exponential loading scenarios, only platoons of the same vehicles were considered, e.g., a platoon of two OR 3-3 Legal trucks (see Figure 3.4) and not a platoon of a 3-3 with an STP-3A. Head spacings, *Sa* ranged from 10 ft to 60 ft in 10 ft increments (3 m to 18 m in 3 m increments) and were assumed the same for three-truck platoons. For each vehicle listed above, 13 configurations (single baseline, six head spacings on two-truck platoon, and six head spacings on three-truck platoon) were analyzed for each bridge model.



**Figure 3.4: Axle weights and spacings for a platoon of two OR 3-3 Legal trucks with a head space,** *Sa* **(1 kip = 4.45 kN, 1 ft = 0.305 m)**

### **3.3 MOVING LOAD ANALYSES**

For the 749 bridge models and 481 vehicle configurations, there were 360,269 moving load analysis cases to be run. For all analysis cases, the axles for each truck/platoon configuration were swept across the bridge model in both directions: "left to right" and "right to left". Load effects were determined by linear elastic, static analysis at each pseudo-time step as the trucks moved across the bridge models. To minimize computational time, the analyses were run on Amazon Web Services with a c6a.48xlarge EC2 (Elastic Compute Cloud) instance with 192 vCPUs (virtual CPUs) and 384 GB RAM (AWS (2022)).

The 360,269 moving load analyses were distributed to the 192 vCPUs using OpenSeesPy (McKenna et al (2010), Zhu et al (2018)). A single Python script was run on each vCPU and only executed the analyses that match the processor ID. These "embarrassingly parallel" analyses reduced what would have been over a week of serial computing down to about eight hours of computing. The short run times allowed for refinements and tweaking, making the task of rerunning analyses less onerous.

### **3.4 ANALYSIS OUTPUT**

For each analysis case, the bending moment and shear force were recorded at uniform locations at 0.1*L* intervals along each bridge span of length, *L* (Figure 3.5). These locations capture the worst effects of positive bending moment near midspans and negative bending moment and shear force near continuous supports.



**Figure 3.5: Monitoring locations (dashed lines) along each span of a two-span bridge model**

For all analysis cases (combinations of vehicle/platoon and bridge model), the following quantities were reported at each monitoring location along each span:

- Maximum positive bending moment
- Shear coincident with maximum positive bending moment
- Maximum negative bending moment
- Shear coincident with maximum negative bending moment
- Maximum shear force
- Bending moment coincident with maximum shear

The entire history of bending moment and shear force were recorded during each analysis case, but for the final analysis (Section 4.0 )only the maximum and coincident values listed above were extracted and saved in a summary database (Section 4.1).

# **4.0 RESULTS AND DISCUSSION**

### **4.1 SUMMARY DATASET**

A summary dataset was created using MATLAB coding to import data files for the structural analysis results from the 749 different bridge types and 481 truck type combinations. The information included in the file was comprised of various parameters, such as bridge number, number of spans, length of each span, truck number, truck type, number of trucks, head spacing, maximum positive moment, maximum negative moment, and maximum shear for the entire bridge. For each maximum loading value, corresponding shear force values and their respective locations on the bridge were recorded, except for shear, which had its maximum moment corresponding component and location. The information on the different bridge lengths, truck types, and spreadsheet data can be found in Appendix B, Figures B1 to B4.

To analyze a two or three span bridge, the MATLAB code treated each span individually. The maximum values of all span lengths, even though not representative of the maximum for the entire bridge, were recorded as well. Consequently, the exact same information that was gathered for the entire bridge was also collected separately for each span, including span one, span two, and span three.

Since each span could have positive and negative shear values, the decision was made to record the maximum shear closest to each support. For example, in the case of a single-span bridge, there would be the maximum positive bending moment and two maximum shear forces – one corresponding to the left support and the other corresponding to the right support.

Figure 4.1 is a plot of the data from a sample structural analysis run for one row in the full dataset. It depicts a sample two-span bridge with the first span length of 131 feet and the second span length of 98.4 feet. The live load was modeled after the Type OR CTP-3 truck with a head spacing of 10-feet and platooned to three-trucks. Labeled numerical values are the maximum internal forces stored in the corresponding analysis output file.



**Figure 4.1: Example of the structural analysis results for a two-span bridge under a sample truck type combination pulled from one row of the full database** 

### **4.2 ANALYSIS OF SUMMARY DATASET**

This section presents an in-depth analysis of the summary dataset, focusing on an overall worstcase analysis, as well as the effects of head spacing and span length on the internal forces. Two distinct approaches were employed to evaluate the overall impacts: Normalizing data using OR Type 3 Legal and OR Type 3S2 Legal truck types and calculating internal force ratios that can be interpreted as amplification factors of individual loading scenarios. Lastly, a case study that uses the platooned live load ratios to calculate rating factors for a select bridge is presented.

### **4.2.1 Overall Worst-Case Analysis**

In the analysis, two distinct approaches were employed to evaluate the effect of different truck types on the internal force response of the analyzed bridges.

The first approach (Equation 1) involved calculating ratios based on one specific truck type, provided by the 2018 ODOT LRFR Manual, with zero head spacing for the OR Type 3 Legal truck type. The internal forces due to all trucks and truck types considering all head spacings were divided by the internal forces for single truck OR Type 3 Legal. This process was also repeated using the OR Type 3S2 Legal truck type. Note that all EV (Emergency Vehicle), HL-93 Tandem, and HS-20 truck types, were excluded from the analysis as it is highly unlikely or impossible that they would participate in platooning in the real-world. The remaining truck types were examined for their worst-case load effects on bridges. Using histograms, Figure 4.2, the normalization of load effects (or internal forces) across all truck types allowed for a comprehensive evaluation of the maximum positive bending moment, maximum negative bending moment, and maximum shear of the entire bridge. To gain a deeper understanding, separate breakdowns were created for each maximum loading value, and histograms were generated to visualize the distribution of ratios greater than or equal to two and by truck type, as seen in Figure 4.3 and Figure 4.4, respectively. In all histograms, the frequency of internal force ratios exceeding 2.0 is substantial. Subsequently, the data were divided into smaller bins, indicated by Roman numerals. The same breakdown was repeated, considering only values at or above the 95th percentile, Figure 4.5 and Figure 4.6. Based on the histogram analysis, further categorizations were derived by examining truck frequency, which indicated the number of instances where a truck exceeded a certain threshold. Additionally, the breakdown was explored in terms of bridge types, leading to a noteworthy observation: bridges with longer spans demonstrated the highest ratios. For figures of the overall max positive bending, max negative bending, and max shear histograms normalized by the OR Type Legal, and OR Type 3S2 Legal, ratio of final bin, 95<sup>th</sup> percentile, and truck frequencies for maximum live load please refer to Appendix B, Figures B5 to B64.

 $Ratio = \frac{Internal Force from a Specific Plational True K Type}{Internal Force from a Single Reference True K (OR Type 3 or 3S2 Legal)}$ 

**(4-1)**



**Figure 4.2. Histogram of maximum positive bending moment ratio (full database) normalized by OR Type 3 Legal Truck**



**Figure 4.3. Histogram of maximum positive bending moment ratio (2.0+ ratio) normalized by OR Type 3 Legal Truck**

Figure 4.3 shows the histogram with the maximum positive bending moment ratios of a total of 26,730 data points, for a ratio of two or greater. These specific data points were singled out for a more detailed examination concerning the types of trucks involved, as illustrated in Figure 4.4. The primary aim was to discern how frequently a particular truck type appeared within this higher ratio range, thereby identifying the most commonly occurring worst truck type. It can be observed that both Type OR CTP-3 and OR SU7 emerge as the predominant truck types with the highest frequency counts.

This same analytical approach was applied to the 95th percentile dataset, comprising 5,282 data points, as depicted in Figure 4.5 and Figure 4.6. In almost all instances, the findings revealed that trucks of Type OR CTP-3 and OR SU7 exhibited the highest frequencies. The sole exception was observed in the final bin pertaining to negative bending moments, where Type OR TP-2B outpaced Type OR CTP-3.



**Figure 4.4. Histogram of maximum positive bending moment by truck type (2.0+ ratio) normalized by OR Type 3 Legal Truck**



**Figure 4.5. Histogram of maximum positive bending moment ratio (the 95th percentile) normalized by OR Type 3 Legal Truck**



**Figure 4.6. Histogram of maximum positive bending by truck type (the 95th percentile) normalized by OR Type 3 Legal Truck**

Tables 4.1 and 4.2 show a summary of the internal force ratios for the OR Type 3 Legal and OR Type 3S2 Legal references for all three internal forces. The former produces the larger ratios overall with the highest value being associated with the negative bending moment ratio reaching a value of 5.10, which is for the case where three CPT3s platoon at a head spacing,  $S_a = 10$  ft. For both ratios, the negative bending moment generates the highest ratio, and the positive bending moment results in the lowest ratio. Another interesting note is that the largest negative bending moment ratios are driven by Type OR CTP trucks with three trucks in the platoon, the shear ratios have a mix of truck types with mostly three-truck platoons, and the positive bending moment ratios have a mix of both truck types and two- and three-truck platoons. This shows that the internal force effects are independent with the negative bending moment and shear force being sensitive to the number of trucks in a platoon.

<b>Maximum Positive Bending</b> <b>Moment</b>		<b>Maximum Negative</b> <b>Bending Moment</b>		<b>Maximum Shear</b>	
<b>Truck Type</b>	<b>Ratio</b>	<b>Truck Type</b>	Ratio	<b>Truck Type</b>	<b>Ratio</b>
CTP3 3 10	4.08	CTP3 3 10	5.10	CTP3 3 10	4.77
CTP3 3 20	3.75	CTP2B 3 10	5.07	CTP3 3 20	4.54
SU7 3 10	3.66	CTP2B 3 20	5.04	CTP3 3 30	4.30
CTP3 3 30	3.43	CTP2B 3 30	5.01	SU7 3 10	4.08
SU6 3 10	3.39	CTP2A 3 10	4.97	CTP3 3 40	4.05
SU7 3 20	3.39	CTP2B 3 40	4.97	CTP2B 3 10	3.98
CTP3 2 10	3.19	CTP2A 3 20	4.95	SU7 3 20	3.92
CTP2B 3 10	3.15	CTP2A 3 30	4.92	CTP3 3 50	3.79
SU6 3 20	3.14	CTP2B 3 50	4.89	CTP2A 3 10	3.79
SU7 3 30	3.12	CTP2A 3 40	4.86	SU6 3 10	3.75
SU5 3 10	3.12	CTP3 3 20	4.82	SU7 3 30	3.75
CTP3 3 40	3.12	CTP2B 3 60	4.75	CTP2B 3 20	3.72
Legal $3S2$ 3 10	3.08	CTP2A 3 50	4.74	Legal $3S2$ 3 10	3.65
CTP3 2 20	3.02	CTP3 3 60	4.62	Legal 3 3 10	3.61
Legal 3 3 10	2.99	CTP3 3 30	4.62	SU6 3 20	3.61
CTP2A 3 10	2.96	CTP3 3 50	4.60	SU7 3 40	3.56
SU6 3 30	2.9	CTP2A 3 60	4.57	CTP3 2 10	3.53
SU5 3 20	2.89	CTP3 3 40	4.56	CTP3 3 60	3.53
CTP3 2 30	2.86	SU7 3 10	4.32	CTP2A 3 20	3.51
SU7 3 40	2.86	SU7 3 20	4.15	CTP3 2 20	3.47

**Table 4.1: Summary Table of Largest Internal Force Ratios By Truck Type (Reference: OR Type 3 Legal Truck), Number Of Trucks Platooning And Head Spacing (All Bridges)** 

<b>Maximum Positive Bending</b> <b>Moment</b>		<b>Maximum Negative</b> <b>Bending Moment</b>		<b>Maximum Shear</b>	
<b>Truck Type</b>	Ratio	<b>Truck Type</b>	Ratio	<b>Truck Type</b>	<b>Ratio</b>
CTP3 3 10	2.85	CTP3 3 10	3.47	CTP3 3 10	3.11
CTP3 3 20	2.61	CTP2B 3 10	3.32	CTP3 3 20	2.96
SU7 3 10	2.55	CTP2B 3 20	3.27	CTP3 3 30	2.81
CTP3 3 30	2.39	CTP2A 3 10	3.24	SU7 3 10	2.66
SU6 3 10	2.37	CTP3 3 20	3.23	CTP3 3 40	2.64
SU7 3 20	2.36	CTP2B 3 30	3.22	CTP2B 3 10	2.60
CTP3 2 10	2.22	CTP <sub>2</sub> A 3 20	3.19	SU7 3 20	2.56
CTP2B 3 10	2.2	CTP2B 3 40	3.19	CTP3 3 50	2.47
SU6 3 20	2.19	CTP2A 3 30	3.15	CTP2A 3 10	2.47
SU7 3 30	2.17	CTP2B 3 50	3.13	SU6 3 10	2.45
SU5 3 10	2.18	CTP2A 3 40	3.11	SU7 3 30	2.45
CTP3 3 40	2.17	CTP3 3 30	3.10	CTP2B 3 20	2.43
Legal $3S2$ 3 10	2.15	CTP2B 3 60	3.05	Legal $3S2$ 3 10	2.38
CTP3 2 20	2.11	CTP2A 3 50	3.04	Legal 3 3 10	2.36
Legal 3 3 10	2.09	CTP3 3 40	3.00	SU6 3 20	2.35
CTP2A 3 10	2.06	CTP3 3 50	2.98	SU7 3 40	2.33
SU6 3 30	2.02	CTP3 3 60	2.97	CTP3 2 10	2.30
SU5 3 20	2.02	CTP2A 3 60	2.93	CTP3 3 60	2.30
CTP3 2 30	2.00	SU7 3 10	2.84	CTP2A 3 20	2.29
SU7 3 40	2.00	SU7 3 20	2.73	CTP3 2 20	2.26

**Table 4.2: Summary Table of Largest Internal Force Ratios by Truck Type (Reference: OR Type 3S2 Legal Truck), Number of Trucks Platooning and Head Spacing (All Bridges)**

The second approach (Equation 4-2) aimed to create ratios that show the amplification of each truck type by dividing the load effect of a platooned truck type (two or three-trucks and different head spacings) by the load effect of the single truck of the same truck type. These ratios allowed for assessing the amplification effect platooning has on different trucks. These ratios can be substituted in the load rating equation (see case study presented in Section 4.3).

**Ratio** = 
$$
\frac{Internal Force from a Specific Platoned Truck Type}{Internal Force from a Single Truck for the Same Specific Truck Type}
$$

**(4-2)** 

To identify the worst-case bridges, it was first determined which span the maximum loading, positive or negative bending moment or shear force, was acting upon. This defined the span length for comparison. Then, the normalized ratio data for OR Type 3 Legal and OR Type 3S2 Legal reference trucks were plotted for each bridge, truck and platoon combination based on the defined span length. The Type OR CTP-3 truck at a 10-foot head spacing was chosen as it was the worst overall truck type when looking at the histogram data presented earlier. Figures 4-7

through 4-9 show the results for the internal force ratios for the Type OR CTP-3 truck to the OR Type 3 Legal (L3) and the OR Type 3S2 Legal (L3S2) trucks comparing a single truck and a three-truck platoons at 10-foot head spacings.



**Figure 4.7: Maximum Positive Bending Moment vs. Span Length for the Type OR CTP-3 at 10-foot head spacing normalized by OR Type 3 Legal and OR Type 3S2 Legal trucks**



**Figure 4.8: Maximum Negative Bending Moment vs. Span Length for the Type OR CTP-3 at 10-foot head spacing normalized by OR Type 3 Legal and OR Type 3S2 Legal trucks**



#### **Figure 4.9: Maximum Shear vs. Span Length for the Type OR CTP-3 at 10-foot head spacing normalized by OR Type 3 Legal and OR Type 3S2 Legal trucks**

As is evident from the graphs, longer span lengths tend to exhibit higher internal force ratios. This is present in the OR Type 3 Legal data for all three load outputs as well as the OR Type 3S2 Legal positive bending moment and shear force ratios. However, as seen in the individual graph of the OR Type 3S2 Legal negative bending moment ratio in Figure 4.8, some shorter span bridges resulted in a higher ratio. This is likely caused by the longer platoon lengths of the OR Type 3S2 Legal configurations as compared to some of the higher load, shorter length trucks. It would allow for more concentrated loads around the supports on short spans as compared to a longer truck on the same shorter span. Overall, the trend is for longer spans to have higher ratios. Therefore, the longest span bridges, the single span of 213 feet and the three-span bridges with two spans of length 262 feet, are the bridges with the highest ratios and the longest bridges analyzed.

Bridge number 11 of the single-span bridge set (with a length of 213 feet) and bridge number 708 of the three-span set (with two spans having lengths of 262 feet) ended up being the worstcase bridges. However, in the multi-span analysis, the worst-case bridges were all of the same subset with the first two spans having a length 262 feet (bridge numbers 702-709) and were all within 0.1% of bridge number 708's total load effect.

In summary, the analysis highlights that the Type OR CTP-3 and OR SU7 truck types resulted in the highest load effect ratios. The overall highest internal force ratio is associated with the negative bending moment and three CPT3s platooning at 10 ft, which resulted in a ratio of 5.10. Additionally, when considering individual bridge spans, the longest bridge spans (262 feet), such as the 708 bridge exhibited the highest load effect ratios.

# **4.2.2 Effect of Specific Trucks**

For this analysis, single, single-truck types were left in to have available references for these truck types. The analysis was conducted considering the maximum internal force effects of the entire bridge.

Based on insights from the overall worst-case analysis, the specific truck configurations that received further examination were Type OR CTP-3 (Figure 4.10), the OR Type 3 Legal (Figure 4.11), and OR SU7 (Figure 4.12). When comparing the Type OR CTP-3 to the OR Type 3 Legal truck configurations, interesting patterns emerge. The graph for Type OR CTP-3 shows that at a 100-foot span length, the internal forces caused by the different truck platoons are still relatively similar. In contrast, OR Type 3 Legal at a 100-foot span length exhibited the three-truck platoon with 10-foot head spacing already reaching twice the baseline moment, accelerating more rapidly under load compared to Type OR CTP-3. Even at a 60-foot head spacing, Type OR CTP-3 remained close to the baseline up to 150 feet, while OR Type 3 Legal had already diverged from the baseline by the same point.

This observation emphasizes the significance of platooning depending on the truck type. Span length does play a role, but it may vary in impact for different truck types. There isn't a one-sizefits-all cutoff point where platooning becomes a concern. The truck type's ratio is closely tied to the load rating factor analysis, indicating that the worst case for a bridge at a specific loading may not necessarily apply to all platooning scenarios. The platooning ratio from a single-truck type may significantly differ from another, and the load effects may be influenced accordingly.



**Figure 4.10: Type OR CTP-3 vs. Span Length**



**Figure 4.11: Type OR Type 3 Legal vs. Span Length**



**Figure 4.12: Type OR SU7 vs. Span Length**

## **4.2.3 Effect of Head Spacing**

To maintain consistency, the analysis continues to focus on Type OR CTP-3, OR Type 3 Legal, OR Type 3S2 Legal, and OR SU7 trucks, exploring the impacts of two-truck and three-truck platooning scenarios based on head spacing. The average values of positive bending moment, negative bending moment, and shear force across all bridges were calculated to compare with the maximum values and identify any potential outliers.

The internal force ratio for a single truck to multiple truck platoons in the averages revealed interesting trends. OR Type 3 Legal exhibited the highest ratio, while Legal Type 3S2 had the lowest, except in the case of shear, where, surprisingly, Type OR CTP-3 at three-trucks showed the lowest ratio for truck platooning. This observation hinted at the normalization effect, highlighting the difference between the ratios that were normalized compared to the ratio of platooned truck types.

The analysis of average graphs revealed a difference between two-truck and three-truck platooning scenarios, Figure 4.13. Three-truck platoons demonstrated a more rapid decrease in average maximum moment compared to two-truck platoons, particularly evident in the positive moment graph, where the slopes of the two versions of the same truck type showed a distinct contrast.



**Figure 4.13: Effect of Head Spacing on Average Max Positive Bending Moment of Two and Three-Truck Platoons**

The examination of maximum loading figures further supported the significance of head spacing in three-truck platooning scenarios, Figure 4.14. As the space between the three-trucks increased, the difference in distance of the load from the front truck to the rear truck grew more quickly, leading to a more rapid decrease in the maximum values. In contrast, for two-truck platoons, the effect of head spacing on the overall load spacing was less pronounced.



**Figure 4.14: Effect of Head Spacing on Max Positive Bending Moment of Two and Three-Truck Platoons**

Additional figures looking at the effect of head spacing for averages, maximums, and truck platooning ratios for positive and negative moments and shear can be found in Appendix B, Figures  $B65 - B74$ .

Focusing on bridge 708, one of the worst case three span bridges with span lengths 262 - 262 - 184 feet, a targeted study was conducted looking at head spacing across truck types while excluding data from all other bridges. Analyzing this isolated case reaffirmed the trends observed in the average and maximum graphs, lending further support to the significance of head spacing in determining internal forces under platooning scenarios (Figures 4.15 to 4.17).



**Figure 4.15: Effect of Head Spacing on Bridge 708 for the Max Positive Bending Moment**



**Figure 4.16: Effect of Head on Bridge 708 for the Max Negative Bending Moment**



**Figure 4.17: Effect of Head on Bridge 708 for the Max Shear Force**

Removing data from all bridges to focus solely on this single bridge, we cleaned up the graphs to highlight Type OR CTP-3, OR Type 3 Legal, OR Type 3S2 Legal, and OR SU7. The patterns observed in the average and maximum graphs remained consistent, even in this isolated case (Figures 4.18 to 4.20).



**Figure 4.18: Effect of Head on Bridge 708 for the Max Positive Bending Moment - Isolating Specific Truck Types**



**Figure 4.19: Effect of Head on Bridge 708 for the Max Negative Bending Moment – Isolating Specific Truck Types**



**Figure 4.20: Effect of Head on Bridge 708 for the Max Shear Force - Isolating Specific Truck Types**

It is worth noting that the dip in the negative moment graphs, Figure 4.19, can likely be attributed to the size of the three-span bridge and the increasing head spacing. The distributed load of the three-trucks contributes to an increasing negative moment due to their specific locations on the bridge. This effect could be influenced by the length of the trucks, as evident in OR Type 3 Legal three-truck platoon, being one of the shortest trucks, which does not show the dip. Conversely, the OR Type 3S2 Legal trucks, being one of the longest, shows a dip starting at the 30-ft head spacing. These findings underscore the importance of head spacing and its interaction with truck types in understanding load effects under platooning scenarios.

## **4.3 CASE STUDY 1: EFFECT OF HEAD SPACING FOR TWO MOST COMMON BRIDGE CONFIGURATIONS**

In this case study, the effect of head spacing on internal force ratios for the two most common bridge configurations (per Appendix A) is studied:

- Single-span bridge with a span length of  $15 \text{ m}$  (49.2 ft)
- Three-span bridge with span lengths of  $15 \text{ m} 20 \text{ m} 15 \text{ m}$  (49.2 ft 65.6 ft 49.2 ft)

Two truck types that are most likely to be platooned in the near term are considered:

- OR legal truck Type 3S2
- OR continuous trip permit (CTP) truck CTP-3

Filters were applied to the summary dataset to only include the bridge configuration and truck types listed above. Using this reduced dataset, internal force ratios were extracted and are shown in Tables 4.3 through 4.6 seperately for each bridge and truck platoon configuration. Internal force ratios are based on Equation 1 with the OR legal truck Type 3S2 as reference. The following ranges were distinguished by color coding the tabulated ratios:



In Tables 4.3 and 4.4, the internal force ratios for the single-span bridge (Span length  $= 15$  m) are shown for the OR legal Type 3S2 and CPT3 truck platoon configurations, respectively. It can be observed that for the former, as long as the head spacing is kept to at least 30 ft, the increase in the internal forces are less than 5% compared to a single OR legal Type 3S2 truck. If the OR CPT-3 truck is platooned, the increase in the internal forces is at least 20%.





o <b>Positive bending moment</b>		o $\bullet$ <b>Shear force</b>		
<b>Truck platoon</b>	Ratio	<b>Truck platton</b>	Ratio	
configuration		configuration		
CTP3 2 10	1.416	CTP3 3 10	1.681	
CTP3 3 10	1.416	CTP3 2 10	1.678	
CTP3 2 30	1.203	CTP3 2 20	1.460	
CTP3 2 40	1.203	CTP3 3 20	1.458	
CTP3 2 60	1.203	CTP3 3 60	1.446	
CTP3 3 40	1.203	CTP3 3 40	1.446	
CTP3 2 50	1.203	CTP3 3 30	1.446	
CTP3 1 0	1.203	CTP3 2 60	1.445	
CTP3 2 20	1.203	CTP3 3 50	1.444	
CTP3 3 30	1.203	CTP3 1 0	1.443	
$CTP3$ 3 60	1.203	CTP3 2 40	1.441	
CTP3 3 50	1.203	CTP3 2 30	1.440	
CTP3 3 20	1.203	CTP3 2 50	1.440	

**Table 4.4: OR CPT-3 Truck Platoon Configurations On Single-Span Bridge (Reference: OR Legal Truck Type 3S2). Ratios < 1.10 Are Highlighted In Green**

In Tables 4.5 and 4.6, the internal force ratios for the three-span bridge (Span lengths =  $15$  m – 20 m – 15 m) are shown for the OR legal Type 3S2 and CPT3 truck platoon configurations, respectively. It can oberved that for the former, as long as the head spacing is at least 30 ft, the increase in the internal forces are less than 10% compared to a single OR legal Type 3S2 truck. If the OR CPT-3 truck is platooned, the increase in the internal forces is at least 12% (for negative bending moment).





ਤ ◡ၬ <b>Positive bending moment</b>		- 0 <b>Negative bending moment</b>		<b>Shear force</b>	
<b>Truck platoon</b> configuration	<b>Ratio</b>	<b>Truck platton</b> configuration	Ratio	<b>Truck platton</b> configuration	Ratio
CTP3 2 60	1.384	CTP3 3 10	1.961	CTP3 2 10	1.801
CTP3 10	1.384	CTP3 2 10	1.755	CTP3 3 10	1.799
CTP3 3 60	1.383	CTP3 2 2 0	1.622	CTP3 3 20	1.515
$CTP3$ 3 50	1.369	CTP3 3 20	1.622	CTP3 2 20	1.513
CTP3 2 50	1.369	CTP3 2 30	1.545	CTP3 2 30	1.475
CTP3 2 10	1.363	CTP3 3 30	1.545	CTP3 3 30	1.473
$CTP3$ 3 40	1.329	CTP3 2 40	1.412	CTP3 2 40	1.446
2 CTP3 40	1.329	$CTP3$ 3 40	1.412	CTP3 3 40	1.438
CTP3 3 <sup>10</sup>	1.296	CTP3 3 50	1.219	CTP3 1 0	1.433
CTP3 2 30	1.246	CTP3 2 50	1.219	CTP3 3 50	1.432
CTP3 3 30	1.246	CTP3 1 0	1.118	CTP3 2 60	1.432
CTP3 2 20	1.217	CTP3 2 60	1.118	CTP3 2 50	1.431
CTP3 3 20	1.216	CTP3 3 60	1.118	CTP3 3 -60	1.428

**Table 4.6: OR CPT-3 Truck Platoon Configurations On Three-Span Bridge (Reference: OR Legal Truck Type 3S2). Ratios < 1.10 Are Highlighted In Green**

Because of the complexity of the bridge and truck platoon configurations, and their combinations, these tables need to be created individually, as needed. Also, to capture the true effect of truck platooning on the bridge network, load ratings should be conducted on a network level. An example of how approximate rating factors for LRFR load rating can be computed is provided in Section 4.4.

### **4.4 CASE STUDY 2: LOAD RATING OF AN IN-SERVICE BRIDGE**

To understand how platooning could affect the rating factor (RF) of an in-service bridge, the live load ratios obtained from the summary dataset were applied to the LRFR strength equation for the rating factor (Figure 4.21), where Capacity, Dead Load Effect, and Live Load Effect are internal forces, i.e., bending moment or shear force, evaluated at a specific location along the length of the bridge (FHWA, 2018). Strength reduction factors,  $\varphi$  and load factors,  $\gamma$ , are shown for reference. Bridge 20026, an existing in-service bridge in Oregon, was selected for this case study. Bridge 20026 is a prestressed Bulb-T girder bridge comprising of two spans. The elevation view is depicted in Figure 4.22, where the first and second span measure 91 feet 10 inches and 142 feet 9 inches, respectively.







**Figure 4.22: Elevation View of Bridge 2026** 

By utilizing the "Bridge Section Tier 2 Load Rating Summary Report" from ODOT (Appendix B, Figure B75) to calculate capacity and employing the "Wyoming Department of Transportation System Rating and Analysis of Structural Systems" (BRASS) files for Bridge 20026 to calculate the dead and live loads, the current RF was determined using the LRFR Strength Equation, equation 1. This calculation was verified against the "Bridge Section Tier 2 Load Rating Summary Report". This bridge has a current inventory and operating RF of 1.52 and 2.51, respectively. Herein, only the operating RF was computed and is compared.

To calculate an updated RF, a bridge with similar span lengths needed to be selected from the established summary dataset. Upon comparing the span lengths of Bridge 20026 with the summary dataset, Bridge 35 was found to be the closest match. The first span of Bridge 35 measured 131 feet, while the second spanned a length of 98.2 feet.

Next, internal force ratios were derived from single-truck versus two and three-truck platoons, considering different head spacings ranging from 10 to 60 feet. These ratios were calculated for various truck types, including OR Type 3 Legal, OR Type 3S2 Legal, Type 3-3 Legal, OR SU4, OR SU5, OR SU6, OR SU7, Type OR CTP-2A, Type OR CTP-2B, and Type OR CTP-3. However, in this case, the ratios were not obtained from the maximum positive moment for the entire bridge. Instead, they were based on the maximum positive moment per span length that corresponded to the span length of Bridge 20026. This adjustment was necessary because the live load rating created moments that were controlled by different spans for Type OR CTP-2A and Type OR CTP-2B. The updated RF were then calculated by applying the above internal force ratios to the live load in Equation 3. The updated RF were then plotted vs. head spacing and can be seen in Figures 4.22 and 4.23.

Some of the built-in assumptions of this approach regarding platooned trucks vs. their single truck versions are that they have the same:

- live load factors, γ<sub>L</sub>,
- live load distribution factors, *DF*, and

• impact factors, *IM*.

These assumptions are necessary because no traffic data are currently available for platooned trucks; they are at this point entirely hypothetical.



**Figure 4.23: Rating Factor vs. Head Spacing for Two-Truck Platoons for Positive Bending Moment**



**Figure 4.24: Rating Factor vs. Head Spacing for Three-Truck Platoons for Positive Bending Moment**

To conclude, it can be observed that truck platooning consistently resulted in a decrease in the rating factor across all cases. While the reduction of the RF is significant for this bridge, the RF never dropped below 2.0, the reason being that this bridge is overdesigned. However, the updated RF using platooned trucks is still notably lower than the current operating RF of 2.51. By referring to Figures 4.22 and 4.23, it becomes evident that once the trucks are spaced at least 50 feet apart, the RF remains essentially flat and head spacing does not substantially influence the RF in most scenarios. This trend holds true for both two-truck and three-truck platoons. Individual truck types and their rating factors are available in Appendix B, Figures B76-B85.

# **5.0 SUMMARY AND CONCLUSIONS**

The emerging technology of truck platooning holds immense potential for revolutionizing the transportation industry by enhancing fuel efficiency, traffic safety, and traffic flow in long-haul trucking. The implementation of automated driving technologies to facilitate truck platooning brings forth the prospect of optimized traffic management and improved driver comfort during extended journeys.

In the context of Oregon's transportation network, recent legislative changes, such as House Bill 4059, Section 40, have effectively permitted truck platooning by waiving headspace requirements for vehicles equipped with "connected automated braking systems." While this presents new opportunities for efficient freight transportation, the distinct behaviors of different truck types within platoons can substantially impact internal forces.

The research findings underscore that specific conditions can lead to notably higher internal load effects from platooned trucks. This highlights potential concerns regarding the integrity and safety of bridges, particularly in cases involving the use of Type OR CTP-3 and OR SU7 truck platoons, which have emerged as the predominant truck types associated with the highest frequency of elevated internal force ratios. Additionally, bridges featuring certain configurations, such as longer spans, may encounter challenges when subjected to truck platooning. This trend is evident in the analysis, where bridges with longer spans consistently exhibit the highest ratios. This pattern is particularly evident in the multi-span analysis, where a subset of bridges with the first two spans measuring 262 feet in length (bridge numbers 702-709) represents the worst-case scenario overall. Interestingly, the individual graph depicting the OR Type 3S2 Legal negative bending moment ratio in Figure 4.8 reveals that some shorter span bridges also exhibit elevated ratios. This phenomenon can likely be attributed to the longer platoon lengths of the OR Type 3S2 Legal configurations when compared to certain higher load and shorter length trucks. It is worth noting that the introduction of truck platooning poses a potential risk of structural inadequacy for bridges with lower rating factors (RF). These factors are often influenced by economic considerations, including cost, materials, and maintenance.

Two case studies showcase how the products of SPR-848 can be implemented to provide policies. The first case study looked at the two most common bridge configurations and most likely platooned truck types and how minimum head spacings can be determined. To capture the true effect of truck platooning on a bridge, however, a load rating needs to be conducted, which is shown in the second case study. With a load rating, the capacity of the bridge is considered, allowing to determine which truck platoon configurations a bridge can handle.

As further exploration and analysis are essential for a comprehensive understanding of the intricate interactions between truck platooning and the effect on internal forces, future research should address scenarios involving truck platoons at tight spacings (less than 30 feet) of more than three trucks of Type OR CTP-3 and OR SU7 and analyze bridge spans exceeding lengths of 262 feet, if applicable. This endeavor will facilitate informed policy recommendations and load rating updates that ensure the safe and sustainable integration of truck platooning within Oregon's existing transportation infrastructure. In navigating the evolving landscape of transportation technologies, it is imperative to strike a balance between innovation and structural

safety to foster a resilient and efficient future for freight movement. Finally, the impacts of truck platooning on the design of new bridges should be explored, one example being the impact of truck platooning on the replacement of the I-5 Bridge crossing the Columbia River in Portland.

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**APPENDIX A**



**Figure A1. Histogram of NBI Item 27: Year built (yr).** 





Mean =  $1979.86$  Standard deviation =  $20.9768$ 



**Figure A2. Histogram of NBI Item 31: Design load (-).**





Mean =  $5.89515$  Standard deviation =  $1.92979$ 



**Figure A3. Histogram of NBI Item 34: Skew (Degrees).** 





Mean =  $15.9055$  Standard deviation =  $21.532$ 



**Figure A4. Histogram of NBI Item 41: Structure open, posted, or closed to traffic (-).**





Mean =  $1.01918$  Standard deviation =  $0.276518$ 



**Figure A5. Histogram of NBI Item 43A: Kind of material and/or design (-).**





Mean =  $4.23593$  Standard deviation =  $1.45949$ 



**Figure A6. Histogram of NBI Item 43B: Type of design and/or construction (-).**





Mean =  $4.16861$  Standard deviation =  $4.74825$ 



**Figure A7. Histogram of NBI Item 45: Number of spans in main unit (-).**





Mean =  $3.23197$  Standard deviation =  $5.50311$ 



**Figure A8. Histogram of NBI Item 48: Length of maximum span (all spans) (m).**



## **Table A8. Frequencies of NBI Item 48: Length of maximum span (all spans) (m).**

Mean =  $29.4139$  Standard deviation =  $30.4938$ 



**Figure A9. Histogram of NBI Item 48: Length of maximum span (# of spans = 1) (m).**

<b>Class</b>	Lower	<b>Upper</b>	<b>Midpoint</b>	Frequency	<b>Relative</b>	<b>Cumulative</b>	Cum. Rel.				
	Limit	Limit			<b>Frequency</b>	<b>Frequency</b>	<b>Frequency</b>				
	at or below	$\boldsymbol{0}$		$\mathbf{0}$	0.0000	$\boldsymbol{0}$	0.0000				
	$\boldsymbol{0}$	4.0	2.0	$\boldsymbol{0}$	0.0000	$\boldsymbol{0}$	0.0000				
$\overline{\mathbf{c}}$	$\overline{4}$	8.0	6.0	18	0.0600	0.0600					
$\overline{3}$	8	12.0	10.0	31	0.1033	0.1633					
$\overline{\mathbf{4}}$	12	16.0	14.0	49	0.1633	98	0.3267				
5	16	20.0	18.0	28	0.0933	126	0.4200				
6	20	24.0	22.0	34	0.1133	160	0.5333				
$\overline{7}$	24	28.0	26.0	25	0.0833	185	0.6167				
8	28	32.0	30.0	24	0.0800	209	0.6967				
9	32	36.0	34.0	25	0.0833	234	0.7800				
10	36	40.0	38.0	20	0.0667	254	0.8467				
11	40	44.0	42.0	16	0.0533	270	0.9000				
12	44	48.0 46.0		7	0.0233	277	0.9233				
13	48	52.0	50.0	$\overline{8}$	0.0267	0.9500					
14	$\overline{52}$	56.0	54.0	7	0.0233	292	0.9733				
15	56	60.0	58.0	3	0.0100	295	0.9833				
16	60	64.0	62.0	$\mathbf 1$	0.0033	296	0.9867				
17	64	68.0	66.0	$\overline{2}$	0.0067	298	0.9933				
18	68	72.0	70.0	$\mathbf{1}$	0.0033	299	0.9967				
19	72	76.0	74.0	$\overline{0}$	0.0000	299	0.9967				
20	76	80.0	78.0	$\boldsymbol{0}$	0.0000	299	0.9967				
21	80	84.0	82.0	$\boldsymbol{0}$	0.0000	299	0.9967				
22	84	88.0	86.0	$\boldsymbol{0}$	0.0000	299	0.9967				
23	88	92.0	90.0	$\mathbf{1}$	0.0033	300	1.0000				
24	92	96.0	94.0	$\overline{0}$	0.0000	300	1.0000				
25	96	100.0	98.0	$\overline{0}$	0.0000	300	1.0000				
	above	100		$\overline{0}$	0.0000	300	1.0000				

**Table A9. Frequencies of NBI Item 48: Length of maximum span (# of spans = 1) (m).**

Mean =  $25.569$  Standard deviation =  $14.1211$ 



**Figure A10. Histogram of NBI Item 48: Length of maximum span (# of spans = 2) (m).**

<b>Class</b>	Lower	<b>Upper</b>	<b>Midpoint</b>	Frequency	<b>Relative</b>	<b>Cumulative</b>	Cum. Rel.				
	Limit	Limit			<b>Frequency</b>	<b>Frequency</b>	<b>Frequency</b>				
	at or below	$\boldsymbol{0}$		$\overline{0}$	0.0000	$\boldsymbol{0}$	0.0000				
	$\boldsymbol{0}$	4.0	2.0	$\overline{0}$	0.0000	$\boldsymbol{0}$	0.0000				
$\overline{\mathbf{c}}$	$\overline{4}$	8.0	6.0	3	0.0435	0.0435					
$\overline{\mathbf{3}}$	8	12.0	10.0	3	0.0435	6	0.0870				
$\overline{\mathbf{4}}$	12	16.0	14.0	6	0.0870	12	0.1739				
5	16	20.0	18.0	3	0.0435	15	0.2174				
6	20	24.0	22.0	5	0.0725	20	0.2899				
$\overline{7}$	24	28.0	26.0	4	0.0580	24	0.3478				
8	28	32.0	30.0	8	0.1159	32	0.4638				
9	32	36.0	34.0	4	0.0580	36	0.5217				
10	36	40.0	38.0	10	0.1449	46	0.6667				
11	40	44.0	42.0	5 7	0.0725	51	0.7391				
12	44	48.0	46.0		58 0.1014		0.8406				
13	48	52.0	50.0	5	0.0725	0.9130					
14	$\overline{52}$	56.0	54.0	$\mathbf{1}$	0.0145	64	0.9275				
15	56	60.0	58.0	$\mathbf{1}$	0.0145	65	0.9420				
16	60	64.0	62.0	$\overline{2}$	0.0290	67	0.9710				
17	64	68.0	66.0	$\overline{0}$	0.0000	67	0.9710				
18	68	72.0	70.0	$\overline{0}$	0.0000	67	0.9710				
19	72	76.0	74.0	$\overline{2}$	0.0290	69	1.0000				
20	76	80.0	78.0	$\overline{0}$	0.0000	69	1.0000				
21	80	84.0	82.0	$\boldsymbol{0}$	0.0000	69	1.0000				
22	84	88.0	86.0	$\boldsymbol{0}$	0.0000	69	1.0000				
23	88	92.0	90.0	$\boldsymbol{0}$	0.0000	69	1.0000				
24	92	96.0	94.0	$\boldsymbol{0}$	0.0000	69	1.0000				
25	96	100.0	98.0	$\overline{0}$	0.0000	69	1.0000				
	above	100		$\overline{0}$	0.0000	69	1.0000				

**Table A10. Frequencies of NBI Item 48: Length of maximum span (# of spans = 2) (m).**

Mean =  $33.8159$  Standard deviation =  $15.6458$ 



**Figure A11. Histogram of NBI Item 48: Length of maximum span (# of spans = 3) (m).**

<b>Class</b>	Lower	<b>Upper</b>	<b>Midpoint</b>	<b>Frequency</b>	$\ldots$ <b>Relative</b>	<b>Cumulative</b>	$\bullet$ , $\ldots$ , Cum. Rel.				
	Limit	Limit			<b>Frequency</b>	<b>Frequency</b>	<b>Frequency</b>				
	at or below	$\mathbf{0}$		$\mathbf 1$	0.0038		0.0038				
1	$\overline{0}$	4.0	2.0	$\overline{0}$	0.0000		0.0038				
$\overline{2}$	$\overline{4}$	8.0	6.0	11	0.0421	12	0.0460				
$\overline{\mathbf{3}}$	8	12.0	10.0	21	0.0805	0.1264					
$\overline{\mathbf{4}}$	12	16.0	14.0	59	0.2261	92	0.3525				
5	16	20.0	18.0	37	0.1418	129	0.4943				
6	20	24.0	22.0	28	0.1073	157	0.6015				
$\overline{7}$	24	28.0	26.0	20	0.0766	177	0.6782				
8	28	32.0	30.0	17	0.0651	194	0.7433				
9	32	36.0	34.0	11	0.0421	205	0.7854				
10	36	40.0	38.0	12	0.0460	217	0.8314				
11	40	44.0	42.0	$\overline{7}$	0.0268	224	0.8582				
12	44	48.0	46.0	10	0.0383	234	0.8966 0.9119				
13	48	52.0	50.0	$\overline{4}$	0.0153	238					
14	52	56.0	54.0	6	0.0230	244	0.9349				
15	$\overline{56}$	60.0	58.0	7	0.0268	251	0.9617				
16	60	64.0	62.0	1	0.0038	252	0.9655				
17	64	68.0	66.0	$\overline{2}$	0.0077	254	0.9732				
18	$\overline{68}$	72.0	70.0	$\overline{2}$	0.0077	256	0.9808				
19	72	76.0	74.0	$\overline{2}$	0.0077	258	0.9885				
20	76	80.0	78.0	$\mathbf{1}$	0.0038	259	0.9923				
21	80	84.0	82.0	$\overline{0}$	0.0000	259	0.9923				
22	84	88.0	86.0	$\overline{0}$	0.0000	259	0.9923				
23	88	92.0	90.0	$\boldsymbol{0}$	0.0000	259	0.9923				
24	92	96.0	94.0	$\mathbf{1}$	0.0038	260	0.9962				
25	96	100.0	98.0	$\overline{0}$	0.0000	260	0.9962				
	above	100			0.0038	261	1.0000				

**Table A11. Frequencies of NBI Item 48: Length of maximum span (# of spans = 3) (m).**

Mean =  $25.772$  Standard deviation =  $16.9927$ 



**Figure A12. Histogram of NBI Item 48: Length of maximum span (# of spans = 4) (m).**

<b>Class</b>	Lower	<b>Upper</b>	<b>Midpoint</b>	Frequency	<b>Relative</b>	<b>Cumulative</b>	Cum. Rel.				
	Limit	Limit			<b>Frequency</b>	<b>Frequency</b>	<b>Frequency</b>				
	at or below	$\overline{0}$		$\mathbf{0}$	0.0000	$\boldsymbol{0}$	0.0000				
	$\boldsymbol{0}$	4.0	2.0	$\boldsymbol{0}$	0.0000	$\boldsymbol{0}$	0.0000				
$\overline{\mathbf{c}}$	$\overline{4}$	8.0	6.0	$\boldsymbol{0}$	0.0000	$\boldsymbol{0}$					
$\overline{3}$	8	12.0	10.0	4	0.0667	$\overline{4}$					
$\overline{\mathbf{4}}$	12	16.0	14.0	9	0.1500	13	0.2167				
5	16	20.0	18.0	5	0.0833	18	0.3000				
6	20	24.0	22.0	$\overline{8}$	0.1333	26	0.4333				
$\overline{7}$	24	28.0	26.0	$\overline{2}$	0.0333	28	0.4667				
8	28	32.0	30.0	6	0.1000	34	0.5667				
9	32	36.0	34.0		0.0167	35	0.5833				
10	36	40.0	38.0	5	0.0833	40	0.6667				
11	40	44.0	42.0		0.0167	41	0.6833				
12	44	48.0 46.0		$\overline{2}$	0.0333	43	0.7167				
13	48	52.0	50.0	$\overline{4}$	0.0667	0.7833					
14	$\overline{52}$	56.0	54.0	4	0.0667	$\overline{51}$	0.8500				
15	56	60.0	58.0		0.0167	52	0.8667				
16	60	64.0	62.0		0.0167	53	0.8833				
17	64	68.0	66.0	$\overline{2}$	0.0333	55	0.9167				
18	68	72.0	70.0		0.0167	56	0.9333				
19	72	76.0	74.0		0.0167	57	0.9500				
20	76	80.0	78.0		0.0167	58	0.9667				
21	80	84.0	82.0	$\overline{2}$	0.0333	60	1.0000				
22	84	88.0	86.0	$\boldsymbol{0}$	0.0000	60	1.0000				
23	88	92.0	90.0	$\boldsymbol{0}$	0.0000	60	1.0000				
24	92	96.0	94.0	$\boldsymbol{0}$	0.0000	60	1.0000				
25	96	100.0	98.0	$\overline{0}$	0.0000	60	1.0000				
	above	100		$\boldsymbol{0}$	0.0000	60	1.0000				

**Table A12. Frequencies of NBI Item 48: Length of maximum span (# of spans = 4) (m).**

Mean =  $34.7667$  Standard deviation =  $20.2663$ 



**Figure A13. Histogram of NBI Item 48: Length of maximum span (# of spans = 5) (m).**

<b>Class</b>	<b>Lower Limit</b>	<b>Upper Limit</b>	<b>Midpoint</b>	<b>Frequency</b>	Relative	<b>Cumulative</b>	Cum. Rel.				
					<b>Frequency</b>	<b>Frequency</b>	<b>Frequency</b>				
	at or below	$\boldsymbol{0}$		$\boldsymbol{0}$	0.0000	$\boldsymbol{0}$	0.0000				
$\mathbf{1}$	$\overline{0}$	4.0	2.0	$\overline{0}$	0.0000	$\boldsymbol{0}$	0.0000 0.0476				
$\overline{2}$	4	8.0	6.0	$\overline{2}$	0.0476	$\overline{2}$					
$\overline{\mathbf{3}}$	8	12.0	10.0	$\overline{3}$	0.0714	$\overline{5}$	0.1190				
$\overline{\mathbf{4}}$	12	16.0	14.0	$\overline{4}$	0.0952	9	0.2143				
5	16	20.0	18.0	$\overline{3}$	0.0714	12	0.2857				
6	20	24.0	22.0	10	0.2381	22	0.5238				
$\overline{7}$	24	28.0	26.0	$\overline{2}$	0.0476	24	0.5714				
8	28	32.0	30.0	$\overline{4}$	0.0952	28	0.6667				
9	32	36.0	34.0		0.0238	29	0.6905				
10	36	40.0	38.0	3	0.0714	32	0.7619				
11	40	44.0	42.0	6	0.1429	38 0.9048					
12	44	48.0	46.0	$\boldsymbol{0}$	0.0000	38 38	0.9048				
13	48	52.0	50.0	$\boldsymbol{0}$	0.0000	0.9048					
14	52	56.0	54.0		0.0238	39	0.9286				
15	56	60.0	58.0	$\overline{2}$	0.0476	41	0.9762				
16	60	64.0	62.0	$\boldsymbol{0}$	0.0000	41	0.9762				
17	64	68.0	66.0	$\boldsymbol{0}$	0.0000	41	0.9762				
18	68	72.0	70.0	$\mathbf{1}$	0.0238	42	1.0000				
19	72	76.0	74.0	$\boldsymbol{0}$	0.0000	42	1.0000				
20	76	80.0	78.0	$\boldsymbol{0}$	0.0000	42	1.0000				
21	80	84.0	82.0	$\overline{0}$	0.0000	42	1.0000				
22	84	88.0	86.0	$\boldsymbol{0}$	0.0000	42	1.0000				
23	88	92.0	90.0	$\boldsymbol{0}$	0.0000	42	1.0000				
24	92	96.0	94.0	$\overline{0}$	0.0000	42	1.0000				
25	96	100.0	98.0	$\boldsymbol{0}$	0.0000	42	1.0000				
	above	100		$\boldsymbol{0}$	0.0000	42	1.0000				

**Table A13. Frequencies of NBI Item 48: Length of maximum span (# of spans = 5) (m).**

Mean =  $28.5738$  Standard deviation =  $15.1319$ 



**Figure A14. Histogram of NBI Item 58: Deck condition rating (-).**





Mean =  $6.48736$  Standard deviation =  $0.724459$ 



**Figure A15. Histogram of NBI Item 59: Superstructure condition rating (-).**





Mean =  $6.64303$  Standard deviation =  $0.749633$ 



**Figure A16. Histogram of NBI Item 63: Method used to determine operating rating (-).**





Mean =  $6.06424$  Standard deviation =  $3.1282$ 



**Figure A17. Histogram of NBI Item 64: Operating rating (-).**





Mean =  $38.6221$  Standard deviation =  $18.11$ 



**Figure A18. Histogram of NBI Item 65: Method used to determine inventory rating (-).**





Mean =  $6.06424$  Standard deviation =  $3.1282$ 



**Figure A19. Histogram of NBI Item 66: Inventory rating (-).**





Mean =  $29.7944$  Standard deviation = 13.9606



**Figure A20. Histogram of NBI Item 104: Highway system of the inventory route (-).**





Mean =  $0.444207$  Standard deviation =  $0.49701$ 

**APPENDIX B**

	$\blacksquare$ A	B	$\mathbf{c}$	D	E	F.	G	$H = 1$	- 11	- 11	K	L.	M	N	$\circ$	P.	$\Omega$	R	-S.		$\cup$	V	<b>W</b>	$\mathbf{x}$	<b>Y</b>
																				V M M x M Ma			V M M x M Ma		
		Bridge Number of Span 1 Span 2 Span 3 Truck N												Number of Head Spaci M Max Po V M Max X M Max M Max Ne V M Max X M Max				M V Max x V Max E M Max ax Pos x Pos S M Max ax Neg x Neg S							
	1 Number	<b>Spans</b>					Length Length Length umber Truck Type	<b>Trucks</b>	nq	s EB	Pos EB	Pos EB	g EB	Neg EB	Neg EB	V Max EB	EB	R	Pos <sub>S1</sub>	<b>S1</b>		Neg S1	<b>S1</b>	$\mathbf{1}$	<b>VL 51</b>
$\overline{2}$	1		1 49.2126				0 No Trucks	$\mathbf{0}$	$\Omega$	302.284	$-0.40864$	25	$\Omega$	$\Omega$	$\Omega$		24.5914 1.0082F-12		0 302.284 -0.40864		25	$\Omega$	$\Omega$		0 24.5914
$\overline{\mathbf{3}}$	1		1 49.2126				1 HL93Tandem	$\mathbf{1}$	$\Omega$	543.369	$-1.34944$			24 -2.3199E-11 -2.1583E-13	24		$-46,0062 -2.1549E-13$		49.2126 543.369 -1.34944				24 -2.3E-11 -2.2E-13		24 46,0062
4	$\mathbf{1}$		1 49,2126				10 HL93Tandem	$\overline{2}$	50	543.365	$-1.34228$			24 -4.6045E-11 -4.5963E-13	23		$-46.0473 - 4.5825E - 13$		49.2126 543.365 -1.34228				24 -4.6E-11 -4.6E-13		23 46,0473
$\overline{\mathbf{S}}$	$\mathbf{1}$		1 49,2126				100 SU7	$\overline{\mathbf{3}}$	40	688,255	5.15302			24 -3.1967E-11 -8.793E-13	23		-57.0278 7.1879E-12		49.2126 688.255 5.15302				24 -3.2E-11 -8.8E-13		23 57.0278
6	$\mathbf{1}$		1 49.2126				101 SU7	$\overline{2}$	50	688.185	5.13021			24 -2.3289E-11 -2.558E-13	24	$-57,0534$	8.108E-12		49.2126 688.185 5.13021				24 -2.3E-11 -2.6E-13		24 57,0534
$\overline{7}$	$\mathbf{1}$		1 49,2126				102 SU7	$\overline{\mathbf{3}}$	50	688.32	$-11.8167$			24 -3.4769E-11 -2.6645E-13	24		$-57.0189$ 1.7871E-12		49.2126 688.32 -11.8167				24 -3.5E-11 -2.7E-13		24 57,0189
8	$\mathbf{1}$		1 49.2126				103 SU7	$\overline{2}$	60	688.166	$-11.7969$			24 -2.454E-11 4.7429E-13	24		56.8897 3.5506E-12		49.2126 688.166 -11.7969				24 -2.5E-11 4.7E-13		24 56.8897
9	$\mathbf{1}$		1 49.2126				104 SU7	3	60	688.247	$-11.8073$			24 -3.7602E-11 -6.2883E-13	23		$-57.0541 - 5.0442E - 12$		49.2126 688.247 -11.8073				24 -3.8E-11 -6.3E-13		23 57.0541
10 <sup>°</sup>	1		1 49.2126				105 EV2	1	$\theta$	538.718	$-25.3961$	28		$-3.9E - 11 - 2.8777E - 13$	24		$-50.1547 - 3.4617E - 13$		49.2126 538.718 -25.3961				28 -3.9E-11 -2.9E-13		24 50.1547
$\overline{11}$	$\mathbf{1}$		1 49,2126				106 EV2	$\overline{2}$	10	718.674	6.6481			28 -5.4619E-11 -1.3323E-12	23		$-71.0277$ 3.3373E-12		49.2126 718.674	6.6481			28 -5.5E-11 -1.3E-12		23 71.0277
12 <sup>2</sup>	1		1 49.2126				107 EV2	$\mathbf{a}$	10	736.255	9.13648			29 -6.9658E-11 -1.3749E-12	23		$-75.9777 - 1.9962E - 13$		49.2126 736.255 9.13648				29 - 7E-11 - 1.4E-12		23 75.9777
13	1		1 49.2126				108 EV2	$\overline{2}$	20	583.131	$-14.9349$			25 -6.0595E-11 -7.7272E-13	24		$-59.8538 - 5.2081E - 12$		49.2126 583.131 -14.9349			25 -6.1E-11 -7.7E-13			24 59,8538
14	п.		1 49.2126				109 EV2	R	20	583.335	$-14.9559$			25 -8.2054E-11 -1.9078E-12	23	$-59.7463$	$5E-12$		49.2126 583.335 -14.9559				25 -8.2E-11 -1.9E-12		23 59,7463
15	$\mathbf{1}$		1 49.2126				11 HL93Tandem	3	50	543.318	$-1.26399$			24 -7.0699E-11 -1.7373E-12	23		46.0197 3.0886E-13		49.2126 543.318 -1.26399				24 - 7.1E-11 - 1.7E-12		23 46.0197
16	$\mathbf{1}$		1 49.2126				110 EV2	$\overline{2}$	30	538.249	8.02612			28 -6.6613E-11 -4.4764E-13	24		$-52.9286 -1.4255E-12$		49.2126 538.249 8.02612				28 -6.7E-11 -4.5E-13		24 52.9286
17	1		1 49,2126				111 EV2	$\overline{3}$	30	538.542	$-7.84189$			21 -9.4282E-11 -2.3448E-12	23		$-53.0177$ 6.8621E-12		49.2126 538.542 -7.84189				21 -9.4E-11 -2.3E-12		23 53,0177
18	$\mathbf{1}$		1 49,2126				112 EV2	$\mathfrak{p}$	40	538.67	8.08252			28 -7.2333E-11 -1.0658E-13	24		$-50.1605 - 1.9144E - 12$	49,2126		538.67 8.08252			28 -7.2E-11 -1.1E-13		24 50,1605
19	1		1 49,2126				113 EV2	3	40	538,528	$-7,8401$			21 -1.0582E-10 -6.7146E-13	24		$-50.1457 - 8.904E - 14$		49.2126 538.528 -7.8401				$21 - 1.1E - 10 - 6.7E - 13$		24 50.1457
20	$\mathbf{1}$		1 49,2126				114 EV2	٠	50	538,512	8.06136			28 -7.8995E-11 -1.9504E-12	23		$-50.0542$ 1.0023E-12		49.2126 538.512 8.06136				28 - 7.9E-11 - 2E-12		23 50,0542
21	$\mathbf{1}$		1 49.2126				<b>115 EV2</b>	3	50	538,557	8.06748			28 -1.1822E-10 -2.2382E-12	23		$-50.1666 - 1.7064E - 13$		49.2126 538.557 8.06748				28 -1.2E-10 -2.2E-12		23 50.1666
22	$\mathbf{1}$		1 49.2126				116 EV2	$\overline{2}$	60	538.649	8.07976			28 -8.4803E-11 -1.4815E-12	23		$-50.144$ 2.0879E-12		49.2126 538.649 8.07976				28 -8.5E-11 -1.5E-12		23 50.144
23	$\mathbf{1}$		1 49.2126				117 EV2	3	60	538.707	8.08753			28 -1.3051E-10 -2.0037E-12	23		-50.0003 7.0699E-13		49.2126 538.707 8.08753				28 -1.3E-10 -2E-12		23 50,0003
24	1		1 49.2126				118 EV3	$\mathbf{1}$	$\bullet$	819.143	$-20.9787$			23 -3.8455E-11 -9.2193E-13	23		$-74.1597 - 1.2356E - 12$		49.2126 819.143 -20.9787				23 -3.8E-11 -9.2E-13		23 74.1597
25	1		1 49,2126				119 EV3	$\overline{2}$	10	948.662	$-3.30911$			23 -5.4815E-11 -1.0232E-12	23		$-99,4405 - 3,3416E - 12$		49.2126 948.662 -3.30911			$23 - 5.5E - 11$	$-1E-12$		23 99,4405
26	$\mathbf{1}$		1 49,2126				12 HL93Tandem	$\overline{ }$	60	543.349	0.572559			26 -5.134E-11 -1.215E-12	23		$-45.9512 - 1.0481E - 13$		49.2126 543.349 0.57256				26 -5.1E-11 -1.2E-12		23 45.9512
27	$\mathbf{1}$		1 49,2126				120 EV3	$\mathbf{3}$	10	953.456	9.22503			22 -7.1111E-11 -1.4389E-12	23		$-102.29$ 4.9711E-12		49.2126 953.456 9.22503				22 -7.1E-11 -1.4E-12		23 102.29
28	1		1 49.2126				121 EV3	$\overline{2}$	20	828,446	$-3.17478$			23 -6.0421E-11 -1.0232E-12	23		$-84.5549 - 2.4675E - 12$		49.2126 828.446 -3.17478				23 -6E-11 -1E-12		23 84.5549
29	$\mathbf{1}$		1 49.2126				122 EV3	$\overline{3}$	20	828,607	$-3.27514$			23 -8.2466E-11 -1.652E-12	23		$-84.4214 - 1.2772E - 12$		49.2126 828.607 -3.27514				23 -8.2E-11 -1.7E-12		23 84.4214
30	$\mathbf{1}$		1 49.2126				123 EV3	$\overline{2}$	30	819.332	21.3577			26 -6.6422E-11 -1.3216E-12	24		-74.1093 2.8737E-12		49.2126 819.332 21.3577				26 -6.6E-11 -1.3E-12		24 74.1093
31	$\mathbf{1}$		1 49.2126				124 EV3	3	30	819,204	$-9.61152$			26 -9.3529E-11 -3.4106E-13	24		$-74.3158 - 2.6656E - 12$		49.2126 819.204 -9.61152				26 -9.4E-11 -3.4E-13		24 74.3158
32 <sub>2</sub>	1		1 49,2126				125 EV3	$\mathbf{r}$	40	818,929	9.94762			23 -7.1658E-11 -3.7304E-13	24		$-74.0713$ 1.1116E-12		49.2126 818.929 9.94762				23 - 7.2E-11 - 3.7E-13		24 74,0713
33	$\mathbf{1}$		1 49.2126				126 EV3	$\overline{\mathbf{3}}$	40	819.171	$-9,60545$			26 -1.0463E-10 -1.5135E-12	23		$-74.1741$ 2.3506E-12		49.2126 819.171 -9.60545				26 -1E-10 -1.5E-12		23 74.1741
34	1		1 49,2126				<b>127 EV3</b>	$\overline{ }$	50	819.192	9.99773			23 -7.7648E-11 1.3856E-12	23		$-74.0876 - 2.7343E - 12$		49.2126 819.192 9.99773				23 - 7.8E-11 1.4E-12		23 74,0876
35	1		1 49.2126				128 EV3	$\overline{3}$	50	819.188	$-9.60863$			26 -1.1605E-10 -1.7053E-12	23		$-74.1222 - 6.406E - 13$		49.2126 819.188 -9.60863				26 -1.2E-10 -1.7E-12		23 74.1222
36	$\mathbf{1}$		1 49,2126				129 EV3	$\overline{ }$	60	818.952	9.95208			23 -8.3414E-11 -1.4389E-12	24		$-74.1382 - 6.4793E - 13$		49.2126 818.952 9.95208				23 -8.3E-11 -1.4E-12		24 74.1382

**Figure B1. Spreadsheet with maximum internal forces for the entire bridge and all span lengths**


t <b>h of</b>	<b>Bridge</b>	<b>Span Length 1</b>	<b>Span Length 2</b>	<b>Span Length 3</b>
	No.			
gth 3	27	114.8293963	97.60498688	$\overline{0}$
	28	114.8293963	91.86351706	$\mathbf{0}$
	29	114.8293963	86.12204724	$\boldsymbol{0}$
	30	131.2335958	131.2335958	$\overline{0}$
	31	131.2335958	124.671916	$\boldsymbol{0}$
	32	131.2335958	118.1102362	$\boldsymbol{0}$
	33	131.2335958	111.5485564	$\boldsymbol{0}$
	34	131.2335958	104.9868766	$\overline{0}$
	35	131.2335958	98.42519685	$\boldsymbol{0}$
	36	147.6377953	147.6377953	$\boldsymbol{0}$
	37	147.6377953	140.2559055	$\boldsymbol{0}$
	38	147.6377953	132.8740157	$\boldsymbol{0}$
	39	147.6377953	125.492126	$\overline{0}$
	40	147.6377953	118.1102362	$\boldsymbol{0}$
	41	147.6377953	110.7283465	$\boldsymbol{0}$
	42	164.0419948	164.0419948	$\overline{0}$
	43	164.0419948	155.839895	$\overline{0}$
	44	164.0419948	147.6377953	$\overline{0}$
	45	164.0419948	139.4356955	$\boldsymbol{0}$
	46	164.0419948	131.2335958	$\overline{0}$
	47	164.0419948	123.0314961	$\theta$
	48	180.4461942	180.4461942	$\overline{0}$
	49	180.4461942	171.4238845	$\boldsymbol{0}$
	50	180.4461942	162.4015748	$\overline{0}$
	51	180.4461942	153.3792651	$\boldsymbol{0}$
	52	180.4461942	144.3569554	$\boldsymbol{0}$
	53	180.4461942	135.3346457	$\boldsymbol{0}$
	54	196.8503937	196.8503937	$\boldsymbol{0}$

**Table B2. Bridge Number Reference Table – The length of each of the three spands in feet.**

























































































<b>Column Heading</b>	<b>Definition</b>	<b>Units</b>
<b>Bridge Number</b>	Corresponds to the Bridge Reference Number	$\blacksquare$
<b>Number of Spans</b>	Number of Spans Per Bridge (1, 2, or 3 Spans)	
Span 1 Length	Lengths of Span 1	feet
Span 2 Length	Lengths of Span 2	feet
Span 3 Length	Lengths of Span 3	feet
<b>Truck Number</b>	Corresponds to the Truck Reference Number	
<b>Truck Type</b>	Oregon Truck Type - From the LRFR Manual	
<b>Number of Trucks</b>	Number of Trucks in a Platoon	
<b>Head_Spacing</b>	Spacing Between Trucks in a Platoon	feet
<b>M_Max_Pos_EB</b>	Maximum Positive Bending Moment for the entire bridge (all spans)	kip-feet
V M Max Pos EB	Corresponding Shear at the Max Positive Bending Moment for the entire bridge	kips
x M Max Pos EB	Location of Maximum Positive Bending Moment for the entire bridge, from left side of bridge	feet
M_Max_Neg_EB	Maximum Negative Bending Moment for the entire bridge (all spans)	kip-feet
V M Max Neg EB	Corresponding Shear at the Max Negative Bending Moment for the entire bridge	kips
x M Max Neg EB	Location of Maximum Negative Bending Moment for the entire bridge, from left side of bridge	feet
V Max EB	Maximum Shear for the entire bridge (all spans)	kips
<b>M_V_Max_EB</b>	Corresponding Moment at Max Shear for the entire bridge	kip-feet
x_V_Max_EB	Location of Shear for the entire bridge, from left side of bridge	feet
<b>M Max Pos S1</b>	Maximum Positive Bending Moment for span 1	kip-feet

**Table B4. Column Heading Reference Table – for data tab in spreadsheet with maximum internal forces**







**Figure B5. Histogram of maximum positive bending moment ratio (full database) normalized by OR Type 3 Legal Truck**



3.30 275 3.40 186 3.50 160 3.60 106 3.70  $|47$ 3.80 44 3.90 33 4.00 13

1.60 7300 1.70 7744 1.80 5727 1.90 5085 2.00 4581

 $\begin{array}{|c|c|c|}\n 2.10 & 3876 \\
\hline\n 2.20 & 3529 \\
\end{array}$ 

2.30 2976

3529

**Table B5. Count of maximum positive bending moment ratio (full database) normalized by OR Typ** 



**Figure B6. Histogram of maximum positive bending moment ratio (full database) normalized by OR Type 3S2 Legal Truck**

	'N TYPU JOZ LUGAL TIUUN				
<b>Class</b>	Count	<b>Class</b>	<b>Count</b>	<b>Class</b>	Count
0.65	88	1.41	5501	2.18	557
0.71	654	1.47	4787	2.24	318
0.76	1441	1.53	3730	2.29	378
0.82	1549	1.59	3551	2.35	206
0.88	2388	1.65	2990	2.41	233
0.94	6933	1.71	2911	2.47	182
1.00	9507	1.76	2256	2.53	112
1.06	7912	1.82	1868	2.59	55
1.12	7758	1.88	1490	2.65	37
1.18	8841	1.94	1484	2.71	48
1.24	7287	2.00	1131	2.76	30
1.29	8524	2.06	883	2.82	13
1.35	7224	2.12	752		

**Table B6. Count of maximum positive bending moment ratio (full database) normalized by OR Type 3S2 Legal Truck**



**Figure B7. Histogram of maximum positive bending moment ratio (2.0+ ratio) normalized by OR Type 3 Legal Truck**

**Table B7. Count of maximum positive bending moment ratio (2.0+ ratio) normalized by OR Type 3 Legal Truck**

<b>Class</b>	Count
2.00	4582
2.10	3876
2.20	3529
2.30	2976
2.40	2476
2.50	1942
2.60	1754
2.70	1338
2.80	1160
2.90	772
3.00	685





**Figure B8. Histogram of maximum positive bending moment by truck type (2.0+ ratio) normalized by OR Type 3 Legal Truck**

<b>Truck</b>	
<b>Type</b>	Count
CTP3	4533
SU7	3953
SU <sub>6</sub>	3298
SU <sub>5</sub>	2501
CTP2B	2200
Legal3S2	1762
CTP2A	1622
Lega133	1503
SU <sub>4</sub>	1432
Legal3	1002
STP4D	632
STP4E	621
STP5BW	535
STP4C	517
STP4B	462
STP3	157

**Table B8. Count of maximum positive bending moment by truck type (2.0+ ratio) normalized by OR Type 3 Legal Truck** 



**Figure B9. Histogram of maximum positive bending moment ratio (2.0+ ratio) normalized by OR Type 3S2 Legal Truck** 

<b>Class</b>	Count
2.00	1742
2.10	1245
2.20	708
2.30	514
2.40	359
2.50	185
2.60	91
2.70	67
2.80	24

**Table B9. Count of maximum positive bending moment ratio (2.0+ ratio) normalized by OR Type 3S2 Legal Truck** 



**Figure B10. Histogram of maximum positive bending moment by truck type (2.0+ ratio) normalized by OR Type 3S2 Legal Truck**

<b>Truck</b>	
<b>Type</b>	Count
CTP3	1531
SU <sub>7</sub>	917
SU <sub>6</sub>	720
SU <sub>5</sub>	437
STP4D	376
STP4E	362
STP5BW	353
Legal3S2	98
CTP2B	72
Lega133	43
CTP2A	13
STP4B	13

**Table B10. Count of maximum positive bending moment by truck type (2.0+ ratio) normalized by OR Type 3S2 Legal Truck** 



**Figure B11. Histogram of maximum positive bending moment (the 95th percentile) normalized by OR Type 3 Legal Truck** 

<b>Class</b>	Count		
2.70	1025		
2.80	1160		
2.90	772		
3.00	685		
3.10	465		
3.20	311		
3.30	275		
3.40	186		
3.50	160		
3.60	106		
3.70	47		
3.80	44		
3.90	33		
4.00	13		
	2000		
		Reference truck: OR Type 3 Legal	
		Total Number of Data Points: 5,282	
	1586		
	1500		
Count(-)			
	1000	912	
		711	
	500	446	
		335 327	
		264 177	
		152 118 105 102	
	$\pmb{0}$ ofectes of start of start		
		<b>USSL STPIP OR-SUA</b>	
		o or she speak or or or or or or DR.C.R2A	

**Table B11. Count of maximum positive bending moment (the 95th percentile) normalized by OR Type 3 Legal Truck** 

**Figure B12. Histogram of maximum positive bending by truck type (the 95th percentile) normalized by OR Type 3 Legal Truck** 

<b>Truck</b>	
<b>Type</b>	Count
CTP3	1586
SU <sub>7</sub>	912
SU <sub>6</sub>	711
SU <sub>5</sub>	446
STP4E	335
STP5BW	327
STP4D	264
CTP2B	177
Legal3S2	152
STP4B	118
SU <sub>4</sub>	105
Legal 33	102
CTP <sub>2</sub> A	47

**Table B12. Count of maximum positive bending by truck type (the 95th percentile) normalized by OR Type 3 Legal Truck** 



**Figure B13. Histogram of maximum positive bending moment (the 95th percentile) normalized by OR Type 3S2 Legal Truck** 







**Figure B14. Histogram of maximum positive bending by truck type (the 95th percentile) normalized by OR Type 3S2 Legal Truck**
Truck	
<b>Type</b>	Count
CTP3	1599
SU <sub>7</sub>	965
SU <sub>6</sub>	734
SU <sub>5</sub>	460
STP4D	456
STP4E	390
STP5BW	385
Legal3S2	113
CTP2B	76
Lega133	47
STP4B	43
CTP2A	13

**Table B14. Count of maximum positive bending by truck type (the 95th percentile) normalized by OR Type 3S2 Legal Truck** 



**Figure B15. Histogram of maximum negative bending moment ratio (full database) normalized by OR Type 3 Legal Truck**



**Table B15. Count of maximum negative bending moment ratio (full database) normalized by OR Type 3 Legal Truck**

**Figure B16. Histogram of maximum negative bending moment ratio (full database) normalized by OR Type 3S2 Legal Truck**

	$\sigma$ y ON Type JSZ Legal Truen				
<b>Class</b>	Count	<b>Class</b>	<b>Count</b>	<b>Class</b>	Count
0.50	18	1.60	7644	2.70	1788
0.60	1449	1.70	7655	2.80	1591
0.70	1732	7.80	7020	2.90	938
0.80	2125	1.90	6254	3.00	552
0.90	2148	2.00	6773	3.10	286
1.00	4404	2.10	6564	3.20	135
1.10	4682	2.20	6146	3.30	28
1.20	7121	2.30	3636	3.40	8
1.30	5733	2.40	2053	3.50	4
1.40	5567	2.50	1258		
1.50	7309	2.60	1437		

**Table B16. Count of maximum negative bending moment ratio (full database) normalized by OR Type 3S2 Legal Truck**



**Figure B17. Histogram of maximum negative bending moment ratio (4.5+ ratio) normalized by OR Type 3 Legal Truck**

**Table B17. Count of maximum negative bending moment ratio (4.5+ ratio) normalized by OR Type 3 Legal Truck**

<b>Class</b>	Count
4.50	550
4.60	351
4.70	204
4.80	153
4.90	93
5.00	18
5.10	13



**Figure B18. Histogram of maximum negative bending moment by truck type (4.5+ ratio) normalized by OR Type 3 Legal Truck**

**Table B18. Count of maximum negative bending moment by truck type (2.0+ ratio) normalized by OR Type 3 Legal Truck** 

Truck	
<b>Type</b>	Count
CTP2B	565
CTP3	431
CTP2A	346
STP4E	40



**Figure B19. Histogram of maximum negative bending moment ratio (3.0+ ratio) normalized by OR Type 3S2 Legal Truck**

**Table B19. Count of maximum negative bending moment ratio (3.0+ ratio) normalized by OR Type 3S2 Legal Truck** 

<b>Class</b>	Count
3.00	552
3.10	286
3.20	135
3.30	28
3.40	8
3.50	



**Figure B20. Histogram of maximum negative bending moment (the 95th percentile) normalized by OR Type 3 Legal Truck**

**Table B20. Count of maximum negative bending moment (the 95th percentile) normalized by OR Type 3 Legal Truck** 

<b>Truck</b>	
<b>Type</b>	Count
CTP3	397
CTP2B	321
CTP <sub>2</sub> A	153
STP4E	142



**Figure B21. Histogram of maximum negative bending moment (the 95th percentile) normalized by OR Type 3 Legal Truck**

**Table B21. Count of maximum negative bending moment (the 95th percentile) normalized by OR Type 3 Legal Truck** 

<b>Class</b>	Count
4.10	812
4.20	1106
4.30	1083
4.40	820
4.50	550
4.60	351
4.70	204
4.80	153
4.90	93
5.00	18
5.10	13



**Figure B22. Histogram of maximum negative bending by truck type (the 95th percentile) normalized by OR Type 3 Legal Truck**

**Table B22. Count of maximum negative bending by truck type (the 95th percentile) normalized by OR Type 3 Legal Truck** 

<b>Truck</b>	
<b>Type</b>	Count
CTP3	2009
CTP2B	1448
CTP <sub>2</sub> A	1161
STP4E	397
SU <sub>7</sub>	188



**Figure B23. Histogram of maximum negative bending moment (the 95th percentile) normalized by OR Type 3S2 Legal Truck** 

**Table B23. Count of maximum negative bending moment (the 95th percentile) normalized by OR Type 3S2 Legal Truck** 

<b>Class</b>	Count
2.70	1661
2.80	1591
2.90	938
3.00	552
3.10	286
3.20	135
3.30	28
3.40	8
3.50	4



**Figure B24. Histogram of maximum negative bending by truck type (the 95th percentile) normalized by OR Type 3S2 Legal Truck**

**Table B24. Count of maximum negative bending by truck type (the 95th percentile) normalized by OR Type 3S2 Legal Truck**

Truck	
<b>Type</b>	Count
CTP3	2113
CTP2B	1417
CTP2A	1087
STP4E	447
SU <sub>7</sub>	132
STP5BW	



**Figure B25. Histogram of maximum shear ratio (full database) normalized by OR Type 3 Legal Truck**

<b>Class</b>	Count	<b>Class</b>	Count	<b>Class</b>	Count
0.90	1900	2.20	5252	3.50	696
1.00	2906	2.30	5077	3.60	566
1.10	3645	2.40	5019	3.70	389
1.20	3826	2.50	4638	3.80	266
1.30	5590	2.60	3956	3.90	242
1.40	5744	2.70	3540	4.00	195
1.50	5147	2.80	2845	4.10	136
1.60	4794	2.90	2534	4.20	144
1.70	6257	3.00	2244	4.30	63
1.80	6830	3.10	1874	4.40	68
1.90	5725	3.20	1570	4.50	53
2.00	5052	3.30	1207	4.60	30
2.10	4633	3.40	943	4.70	13

**Table B25. Count of maximum shear ratio (full database) normalized by OR Type 3 Legal Truck**



**Figure B26. Histogram of maximum shear ratio (full database) normalized by OR Type 3S2 Legal Truck** 

**Table B26. Count of maximum shear ratio (full database) normalized by OR Type 3S2 Legal Truck Class Count**

	<b>Class</b>	Count			<b>Class</b>	Count
	0.60	892			1.90	4621
	0.70	1275			2.00	3377
	0.80	1360			2.10	2662
	0.90	3984			2.20	1699
	1.00	9266			2.30	1167
	1.10	9614			2.40	670
	1.20	12202			2.50	487
	1.30	10444			2.60	316
	1.40	9981			2.70	234
	1.50	9229			2.80	179
	1.60	8611			2.90	99
	1.70	7587			3.00	44
	1.80	5602			3.10	13
800						
						Reference truck: Type 3 Legal <b>Total Number of Data Points: 2</b>
600						Mean = $3.829$ Maximum $= 4$



**Figure B27. Histogram of maximum shear ratio (3.5+ ratio) normalized by OR Type 3 Legal Truck**

11 U.C.N	
Class	Count
3.50	697
3.60	566
3.70	389
3.80	266
3.90	242
4.00	195
4.10	136
4.20	144
4.30	63
4.40	68
4.50	53
4.60	30
4.70	13

**Table B27. Count of maximum shear ratio (3.5+ ratio) normalized by OR Type 3 Legal Truck**



**Figure B28. Histogram of maximum shear by truck type (3.5+ ratio) normalized by OR Type 3 Legal Truck**

**Table B28. Count of maximum shear by truck type (3.5+ ratio) normalized by OR Type 3 Legal Truck** 

<b>Truck</b>	
<b>Type</b>	Count
CTP3	1081
SU7	648
STP4E	351
SU <sub>6</sub>	279
CTP2B	194
STP5BW	176
CTP2A	62
Legal3S2	43
Legal33	28



**Figure B29. Histogram of maximum shear ratio (2.2+ ratio) normalized by OR Type 3S2 Legal Truck**

**Table B29. Count of maximum shear ratio (2.2+ ratio) normalized by OR Type 3S2 Legal Truck**

<b>Class</b>	Count
2.50	487
2.60	316
2.70	234
2.80	179
2.90	99
3.00	44
3.10	13



**Figure B30. Histogram of maximum shear by truck type (2.5+ ratio) normalized by OR Type 3S2 Legal Truck** 

**Table B30. Count of maximum shear by truck type (2.5+ ratio) normalized by OR Type 3S2 Legal Truck** 

<b>Truck</b>	
<b>Type</b>	Count
CTP3	772
STP4E	289
SU <sub>7</sub>	268
CTP2B	



**Figure B31. Histogram of maximum shear (the 95th percentile) normalized by OR Type 3 Legal Truck**

і гиск	
<b>Class</b>	Count
3.20	271
3.30	1207
3.40	943
3.50	696
3.60	566
3.70	389
3.80	266
3.90	242
4.00	195
4.10	136
4.20	144
4.30	63
4.40	68
4.50	53
4.60	30
4.70	13

**Table B31. Count of maximum shear (the 95th percentile) normalized by OR Type 3 Legal Truck** 



Figure B32. Histogram of maximum shear by truck type (the 95<sup>th</sup> percentile) normalized by **OR Type 3 Legal Truck**

**Table B32. Count of maximum shear by truck type (the 95th percentile) normalized by OR Type 3 Legal Truck**

0	
<b>Truck</b>	
<b>Type</b>	Count
CTP3	1821
SU7	1016
SU <sub>6</sub>	652
STP4E	395
CTP2B	372
STP5BW	326
SU <sub>5</sub>	183
Legal3S2	173
CTP2A	171
Lega133	131
STP4B	42



**Figure B33. Histogram of maximum shear (the 95th percentile) normalized by OR Type 3S2 Legal Truck** 

**Table B33. Count of maximum shear (the 95th percentile) normalized by OR Type 3S2 Legal Truck** 

<b>Class</b>	Count
2.10	373
2.20	1699
2.30	1167
2.40	670
2.50	487
2.60	316
2.70	234
2.80	179
2.90	99
3.00	44
3.10	13



Figure B34. Histogram of maximum shear by truck type (the 95<sup>th</sup> percentile) normalized by **OR Type 3S2 Legal Truck**

	ᇰ
Truck	
Type	Count
CTP3	1835
SU7	1079
SU <sub>6</sub>	689
STP4E	422
STP5BW	383
CTP2B	334
SU <sub>5</sub>	156
CTP2A	142
Legal3S2	131
Legal33	110

**Table B34. Count of maximum shear by truck type (the 95th percentile) normalized by OR Type 3S2 Legal Truck** 



**Figure B35: Effect of Head Spacing on Average Max Negative Moment of Two versus Three-Truck Platoons** 



**Figure B36: Effect of Head Spacing on Average Max Shear of Two versus Three-Truck Platoons** 



**Figure B37: Effect of Head Spacing on Max Negative Moment of Two versus Three-Truck Platoons** 



**Figure B38: Effect of Head Spacing on Max Shear Moment of Two versus Three-Truck Platoons** 



**Figure B39: Effect of Head Spacing on Average Max Positive Moment of Single Truck Platoon Ratios for Two versus Three-Truck Platoons**



**Figure B40: Effect of Head Spacing on Average Max Negative Moment of Single Truck Platoon Ratios for Two versus Three-Truck Platoons**



**Figure B41: Effect of Head Spacing on Average Max Shear of Single Truck Platoon Ratios for Two versus Three-Truck Platoons** 



**Figure B42: Effect of Head Spacing on Max Positive Moment of Single Truck Platoon Ratios for Two versus Three-Truck Platoons** 



**Figure B43: Effect of Head Spacing on Max Negative Moment of Single Truck Platoon Ratios for Two versus Three-Truck Platoons** 



**Figure B44: Effect of Head Spacing on Max Shear of Single Truck Platoon Ratios for Two versus Three-Truck Platoons**



**Figure B45: ODOT Bridge Section Tier 2 Load Rating Summary Report for Bridge 20026**



**Figure B46: Rating Factor versus Head Spacing for the OR Type 3 Legal Truck**







**Figure B48: Rating Factor versus Head Spacing for the Type 3-3 Legal Truck**



**Figure B49: Rating Factor versus Head Spacing for the OR SU4 Truck**



**Figure B50: Rating Factor versus Head Spacing for the OR SU5 Truck**



**Figure B51: Rating Factor versus Head Spacing for the OR SU6 Truck**



**Figure B52: Rating Factor versus Head Spacing for the OR SU7 Truck**



**Figure B53: Rating Factor versus Head Spacing for the Type OR CTP-2A Truck**



**Figure B54: Rating Factor versus Head Spacing for the Type OR CTP-2B Truck**



**Figure B55: Rating Factor versus Head Spacing for the Type OR CTP-3 Truck**