



Multiday User Equilibrium with Intelligent Travelers

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Background

- User Equilibrium (UE) typically is the equilibrium of one-shot games / each traveler makes one-shot decisions
- In this research, we propose a new framework -- Multiday User Equilibrium (MUE), where farsighted travelers make sequential decisions on their travel choices for multiple days
- Sequential decision-making: plan out a sequence of actions for a horizon considering long-term effects

Minghui Wu 2 / 28

In some scenarios, one can benefit from sequential decision-making

- Travel within a fixed budget[1]
- Parking search[2]
- Ride-hailing vehicles routing[3,4]

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^[1] Lin, X., Yin, Y., & He, F. (2021). Credit-based mobility management considering travelers' budgeting behaviors under uncertainty. Transportation Science, 55(2), 297–314.

^[2] Boyles, S. D., Tang, S., & Unnikrishnan, A. (2015). Parking search equilibrium on a network. Transportation Research Part B: Methodological, 81, 390-409.

^[3] Urata, J., Xu, Z., Ke, J., Yin, Y., Wu, G., Yang, H., & Ye, J. (2021). Learning ride-sourcing drivers' customer-searching behavior: A dynamic discrete choice approach. Transportation research part C: emerging technologies, 130, 103293.

^[4] Zhang, K., Mittal, A., Djavadian, S., Twumasi-Boakye, R., & Nie, M. (2021). RIde-hail VEhicle Routing (RIVER) as a congestion game. Available at SSRN 3974957.

Scenario: trip planning

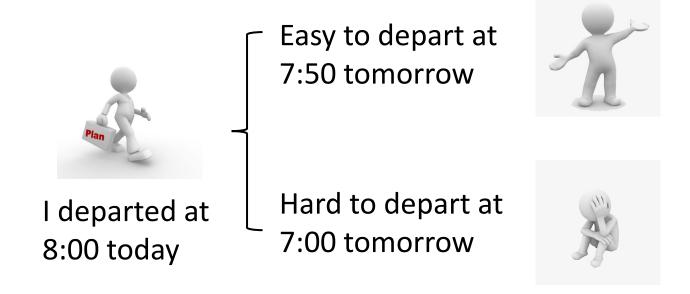
- Minimizing total travel cost considering user inertia over a planning horizon
- Empirical studies support the existence of user inertia in route choices^[1] and departure time choices
- Need to plan ahead to strike a balance between $\begin{cases} & \text{Avoiding congestion} \\ & \text{Avoiding adjustments} \end{cases}$

4 / 28 Minghui Wu

^[1] Srinivasan, K. K., & Mahmassani, H. S. (2000). Modeling inertia and compliance mechanisms in route choice behavior under real-time information. Transportation Research Record, 1725, 45–53.

Scenario: trip planning

• E.g. psychological burden when changing departure time choices



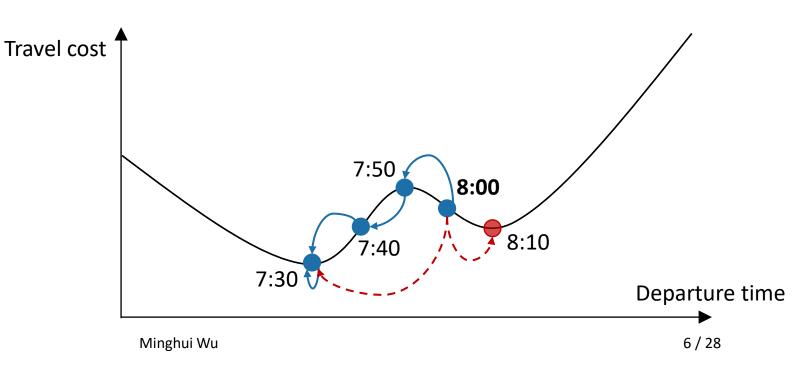
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Scenario: trip planning

 E.g. a farsighted traveler should plan a trajectory in the future, resulting a lower total cost

 Suppose one can only change 10min per day

 Suppose others' departure profile is fixed



How to be farsighted

Connected and automated mobility provides

- Broader information source
- Stronger computation power



Picture source: MnDOT

- However, it still represents human interests
 - E.g. departure time still largely influences ones' daily routine
 - Intelligent commuters should still consider user inertia

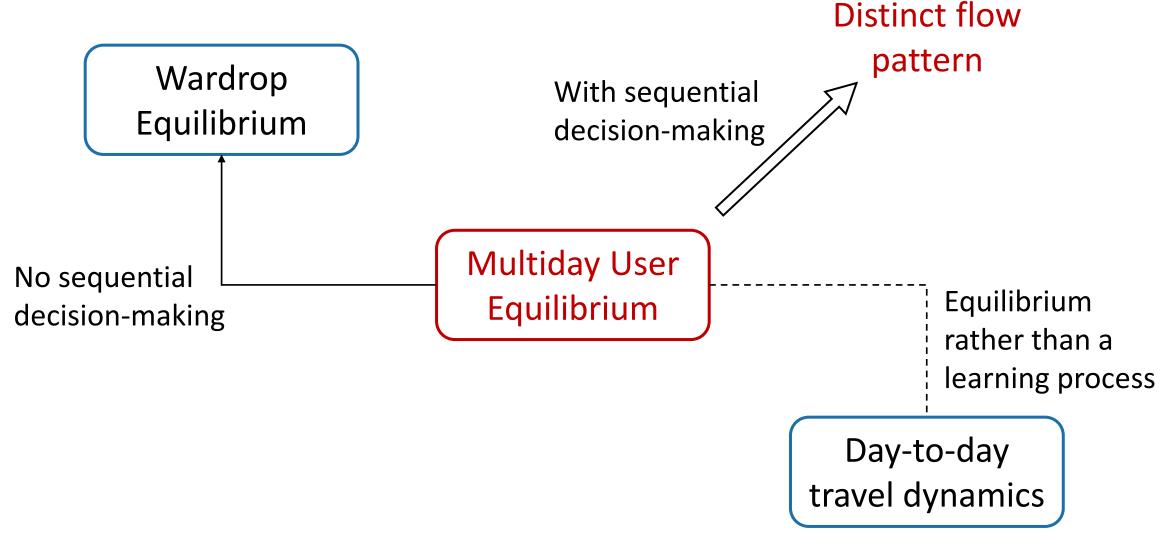
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Research overview

- When all travelers are doing sequential decision-making, it will dictate a new traffic flow pattern
- In this research, we propose a mathematical framework for modeling interactions of intelligent travelers who make sequential decisions on their travel choices over a planning horizon

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Research overview



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Choose Choose
Action Path 2 Path 2

State Path 1 Path 2 Path 2

- Planning horizon $\mathcal{N} = \{0,1,\dots,N-1\}$, with day $n \in \mathcal{N}$
- State space $S = \{s_1, \dots, s_M\}$, with state $s \in S$

Travel choices (routes, departure time, or both)

• Action space $\mathcal{A} = \mathcal{S}$, with action $a \in \mathcal{S}$

Choosing the option for the next day

- Mean field (MF) distribution $\mu_n \in \mathcal{P}(\mathcal{S})$
- MF sequence $\mu = \{\mu_n\}_{n \in \mathcal{N}}$





10 on path 1 10 on path 2

$$\longrightarrow$$
 MF = $\left[\frac{1}{2}, \frac{1}{2}\right]$

- Choose Choose
 Action Path 2 Path 2

 State Path 1 Path 2 Path 2
- Policy $\pi_n(a|s) = P(a_n = a|s_n = s)$
- Policy sequence $\pi = \{\pi_n\}_{n \in \mathcal{N}}$

- Transition $p(s'|s, a) = P(s_{n+1} = s'|s_n = s, a_n = a)$
- Here we consider $p(s'|s,a) = \begin{cases} 1, & s' = a \\ 0, & o.w. \end{cases}$

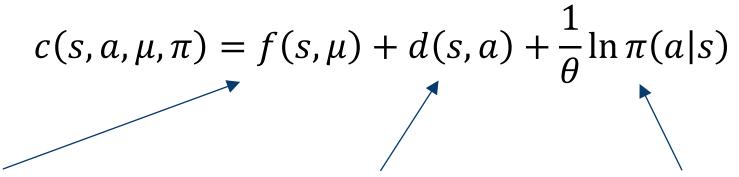
If I decide to choose path 1 tomorrow, I will choose it accordingly then

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Choose Choose
Action Path 2 Path 2

State Path 1 Path 2 Path 2

Cost function



Travel cost

e.g. travel time in routing

Switching cost^[1] for inertia

e.g.
$$d(s, a) = \epsilon \cdot 1_{s \neq a}$$

 $d(s, a) = \epsilon ||s - a||$

Entropy term for random residue

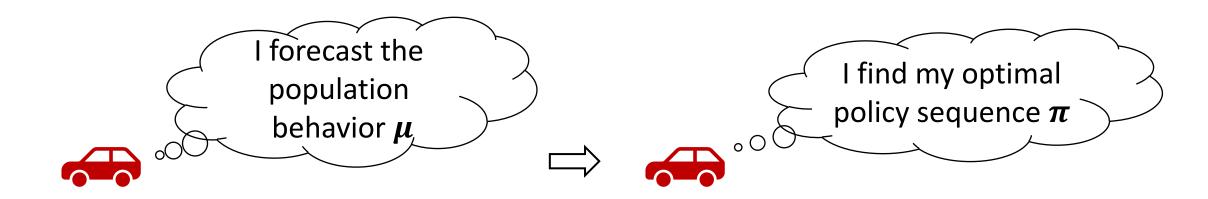
[1] Delle Site, P. (2018). A mixed-behaviour equilibrium model under predictive and static Advanced Traveller Information Systems (ATIS) and state-dependent route choice. Transportation Research Part C: Emerging Technologies, 86, 549–562.

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Individual response

Given the population behavior μ

$$\boldsymbol{\pi}^* = \Phi(\boldsymbol{\mu}) = \arg\min E[\sum_n c(s_n, a_n, \mu_n, \pi_n)]$$

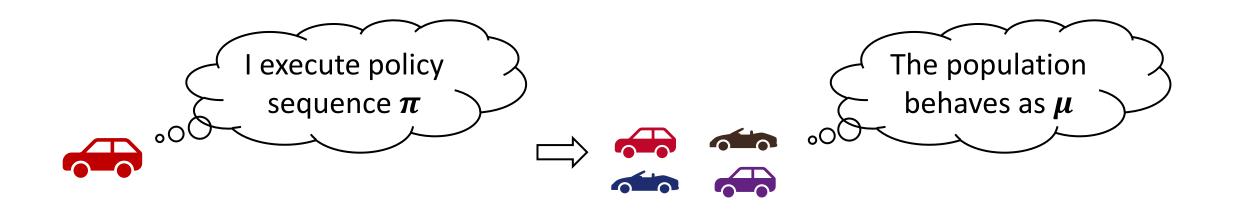


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Population behavior

Given a policy sequence $oldsymbol{\pi}$ and an initial distribution μ_0

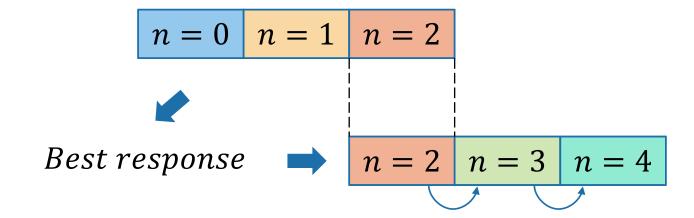
 $\mu = \Psi_{\mu_0}(\pi)$ can be recursively calculated as $\mu_{n+1}(s) = \sum_{x \in \mathcal{S}} \mu_n(x) \pi_n(s|x)$



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A motivating example of interaction protocol

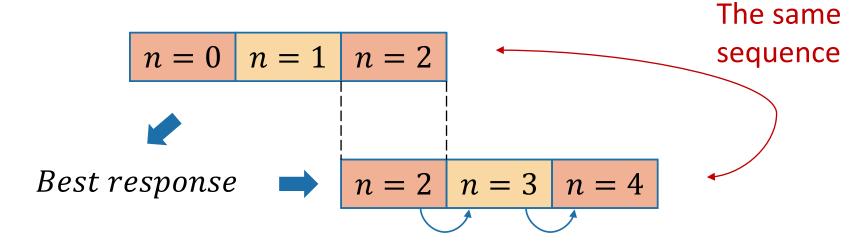
Suppose N = 3



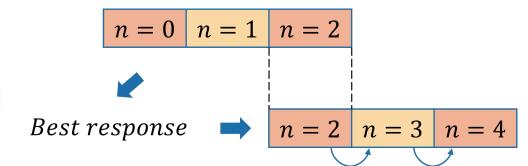
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A motivating example

Consider the steady-state



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Definition

A pair (π, μ) is called a <u>multiday user equilibrium (MUE)</u> if $\pi = \Phi(\mu), \mu = \Psi_{\mu_{N-1}}(\pi)$

• By definition, the MF distribution sequence μ should have the same initial and final distribution

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The existence is generally ensured

Proposition

Under continuous cost $f(s, \mu)$, there always exists an MUE

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Connection with Wardrop Equilibrium

No sequential decision-making: no user inertia

MUE and logit-SUE are equivalent

Proposition

When d(s,s')=0, there exists a unique MUE, and it repeats the logit-SUE every day

Intuition: the framework reduces to Wardrop Equilibrium when there is no need for forward-looking

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Connection with Wardrop Equilibrium

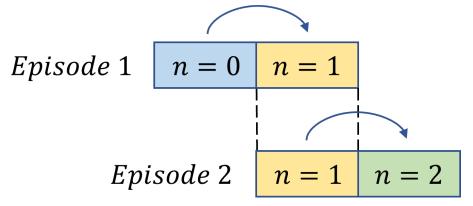
No sequential decision-making: short planning horizon

Proposition

When $d(s,s') \neq 0$ and N=2, the resulting MUE repeats SDSUE

State-dependent SUE: Similar to logit-SUE but consider switching costs^[1,2]

Intuition: When N=2, travelers essentially only consider the next day, letting the framework reduces back to Wardrop Equilibrium



^[1] Castaldi, C., Delle Site, P., & Filippi, F. (2019). Stochastic user equilibrium in the presence of state dependence. EURO Journal on Transportation and Logistics, 8(5), 535–559.

^[2] Castaldi, C., Site, P. D., & Filippi, F. (2017). Stochastic user equilibrium in the procedia, 22, 13–24.

Distinct flow pattern

• With sequential decision-making: generally, MUE cannot be stationary

Proposition

When $d(s,s') = \epsilon \cdot 1_{s \neq s'}$ and N > 2, generally the MUE cannot have time-invariant MF distribution

Intuition: the resulting MUE always have within-horizon fluctuations

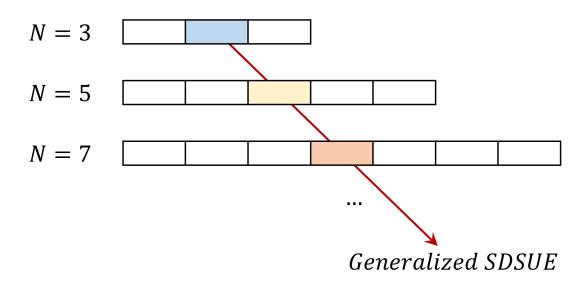
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Distinct flow pattern

• With sequential decision-making: MUE converges to a generalized SDSUE with longer horizon length (formal definition skipped here)

Proposition

Assume the episode length is odd, and denote it as $\mathcal{N}=\{0,\ldots,N-1\}.$ Denote the corresponding MUE as $(\boldsymbol{\pi}^N,\boldsymbol{\mu}^N).$ $\mu_{\scriptscriptstyle K}^{(N-1)/2}\to \bar{\mu}$ as $K\to\infty$



Intuition: $\bar{\mu}$ maintains a time-invariant MF distribution and policy

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Numerical experiments: departure time

Total number of commuters: 6,000

Bottleneck capacity: 3,000 per hour

Planning horizon: 7 days

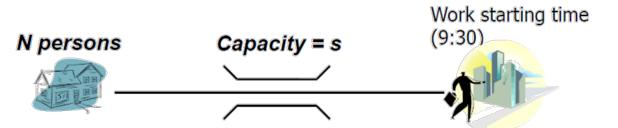
Departure time range: [0,3] hour

Discretized to 40 slices

Desired arrival time: 2 hour

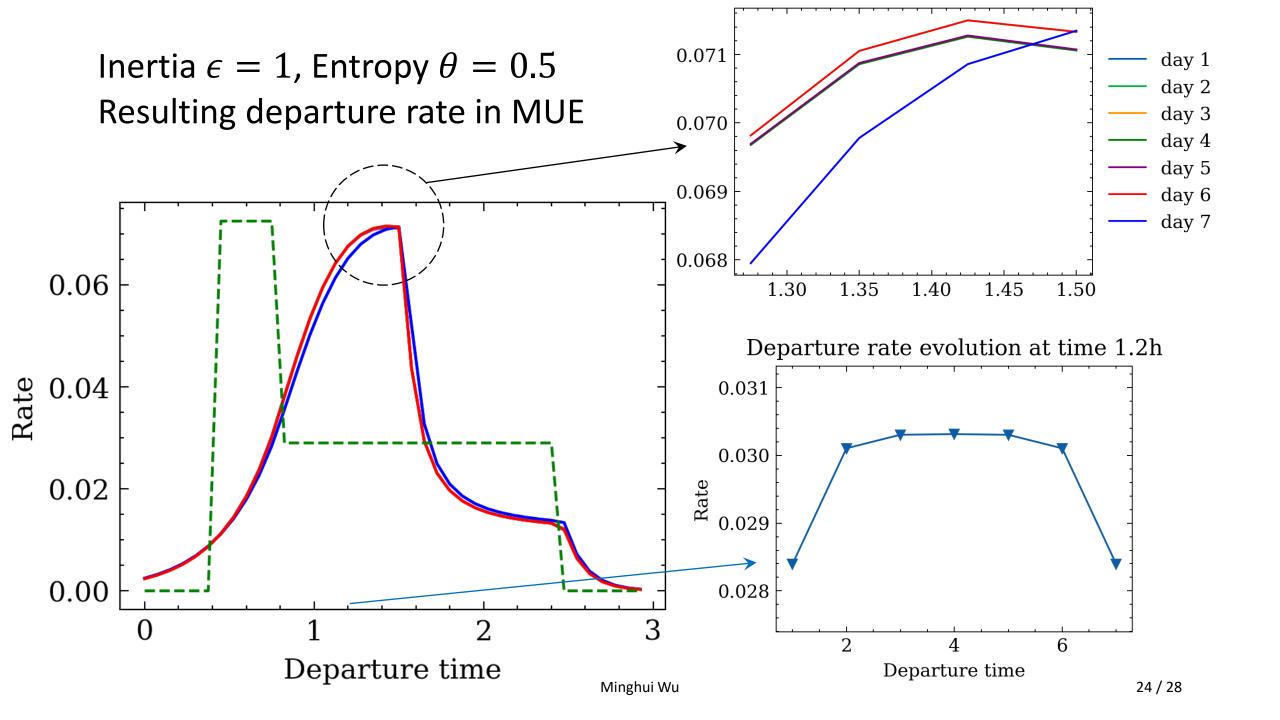
Scheduling cost: $\alpha = 10, \beta = 5, \gamma = 15$

Switching cost: $\epsilon |s - s'|$



Guo, R. Y., Yang, H., Huang, H. J., & Li, X. (2018). Day-to-day departure time choice under bounded rationality in the bottleneck model. Transportation Research Part B: Methodological, 117, 832–849.

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Numerical experiments: routing

A grid network: 12 links, 6 paths

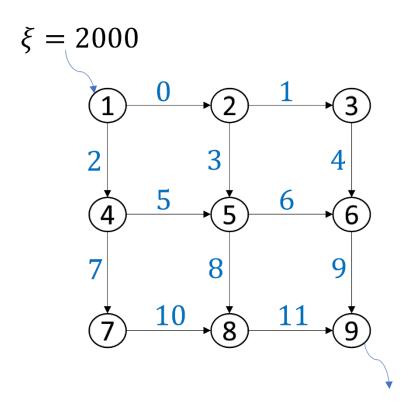
Link travel time: BPR type

Switching cost: $\epsilon \cdot \mathbf{1}_{S \neq S'}$

Entropy term: $\frac{1}{\theta} \ln \pi(s'|s)$

Planning horizon: 7 days

Total inflow: 2000 from Node 1 to Node 9



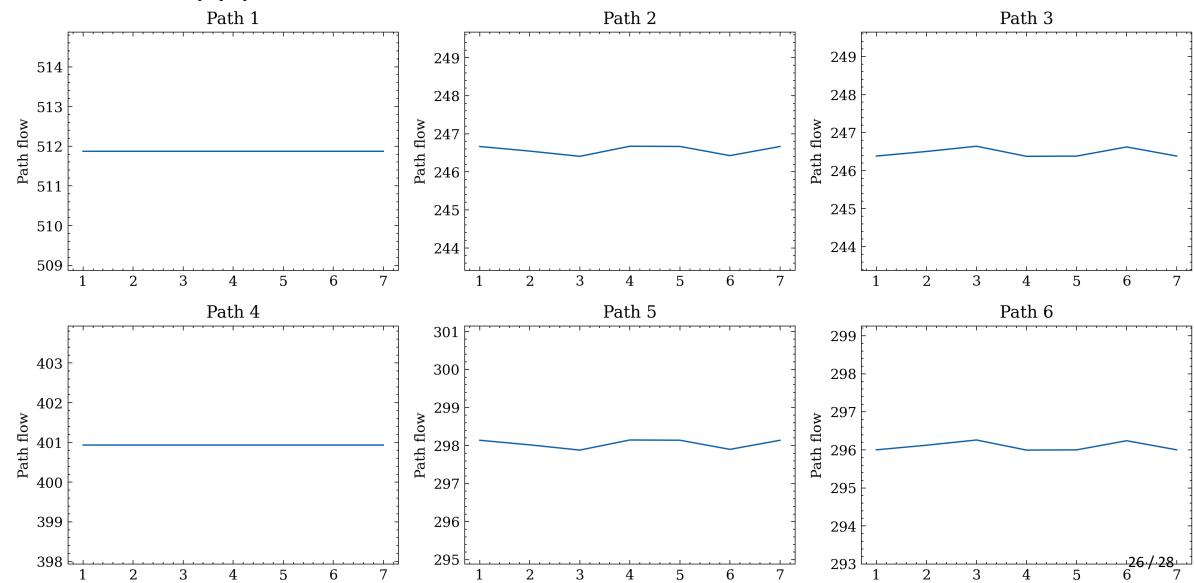
He, X., & Peeta, S. (2016). A marginal utility day-to-day traffic evolution model based on one-step strategic thinking. Transportation Research Part B: Methodological, 84, 237–255.

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• No inertia $\epsilon = 0$

Resulting path flow evolution in MUE Stationary for the entire episode

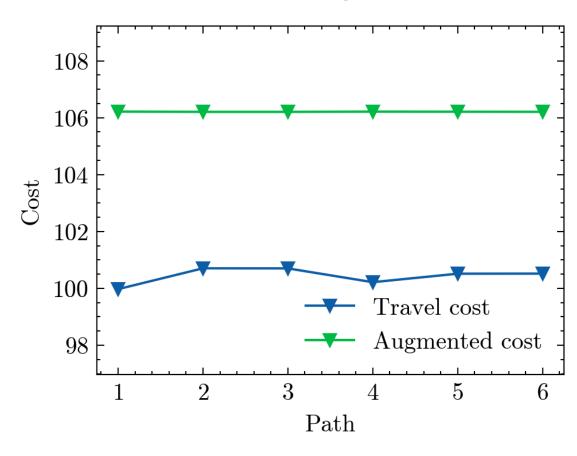
• Entropy parameter $\theta = 1$



Numerical experiments: routing

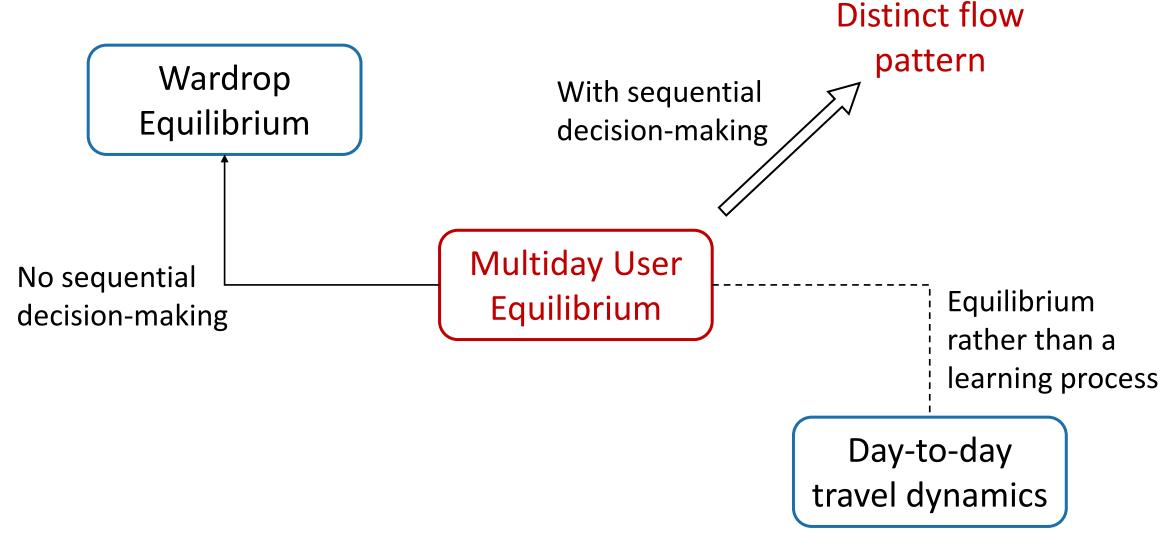
• No inertia ($\epsilon = 0$), $\theta = 1$: resulting MUE

Equivalent to logit-SUE



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Summary



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Thank You!

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