



A USDOT NATIONAL
UNIVERSITY TRANSPORTATION CENTER

Carnegie Mellon University



Smart Glasses for Improving Mobility of Low Vision People (Phase Two)

Principal Investigator: Yang Cai
<https://orcid.org/0000-0002-6767-0311>

FINAL RESEARCH REPORT

Contract # 69A3551747111

DISCLAIMER

The contents of this report reflect the views of the authors, who are responsible for the facts and the accuracy of the information presented herein. This document is disseminated under the sponsorship of the U.S. Department of Transportation's University Transportation Centers Program, in the interest of information exchange. The U.S. Government assumes no liability for the contents or use thereof.

Final Report 2021

Improving Mobility of Low Vision People with Super-Reality Glasses

PI: Yang Cai, Cylab, CMU, ycai@cmu.edu

DISCLAIMER

The contents of this report reflect the views of the authors, who are responsible for the facts and the accuracy of the information presented herein. This document is disseminated in the interest of information exchange. The report is funded, partially or entirely, by a grant from the U.S. Department of Transportation's University Transportation Centers Program. However, the U.S. Government assumes no liability for the contents or use thereof.

Introduction

According to the World Health Organization (WHO), there are about 10 million visually impaired people in the US [1]. This number is escalating rapidly as the population ages, implying a growing barrier to a wide range of mobility activities that require access to visual information, including following a driving lane, detecting obstacles, pedestrians, bikes, recognizing signs and work zones, navigating with maps, and reading dynamic displays. Low vision associates with two major types of visual impairment: central field loss (CFL) and low contrast sensitivity (LCS). Central field loss (CFL) is often caused by age-related macular degeneration (AMD), which affects up to 8 million Americans [4]. Low contrast sensitivity is common in aging population, when the visual signals become blurry. Bioptic telescopic spectacles (BTS) can be used for driving by people with visual acuity that is not sufficient to qualify for an unrestricted driver's license. Bioptic telescopic spectacles consist of either monocular or binocular telescopes mounted to a pair of spectacles. Bioptic telescopic spectacles can be used in about 40 states for this purpose, including New York, Ohio, West Virginia. The state of Pennsylvania has not accepted bioptic spectacles yet but is considering to change the regulation. The specific requirements for bioptic telescopic spectacles drivers are however different from state to state. For example, the training times range from 20 hours up to 90 hours. However, BTS alone does not fully improve visual contrast sensitivity.

We need to develop new technologies to improve the mobility of low vision people, not only for drivers, but also for non-driver in daily lives. Modern transportation systems such as autonomous driving vehicles, ride-sharing services, and assisted vehicle services are designed to help people to move from point A to point B, but they are not enough to cover the full spectrum of mobile activities such as indoor navigation within a subway, an airport, a hospital, or a campus. We need a wearable device for visual impaired people to obtain information on demand, on location, and tailored for visual enhancement, tactile, and auditory cues with artificial intelligence.

This project is to develop an assistive technology for the people with vision disabilities of central field loss (CFL) and low contrast sensitivity (LCS). Our technology includes a pair of super-reality (SR) glasses with enhanced image contrast, for example, highlighting objects, detect signs, and lanes. We call the technology "super-reality" because it provides more details than what the user can see, for example, thermal image and contours of pedestrians. In contrast to prevailing Augmented Reality (AR) and Virtual Reality (VR) technologies, which project either mixed reality objects or virtual objects to the glasses, Super Reality (SR) fuses real-time sensory information and enhance image from the reality. SR glasses technology has two advantages: it's relatively 'fail-safe.' If the battery dies or processor crashes, the glasses can still function because it is transparent. SR glasses can also be transformed to a VR or AR simulator when it overlays virtual objects such as pedestrians or vehicles onto the glasses for simulation. For over two years, the PI's lab has worked on prototypes of SR glasses for first responders for public safety missions such as search and rescue. In this project, we will further develop the technology for low vision users.

The real-time visual enhancement and alert information are overlaid on the transparent glasses. The visual enhancement module can be expanded to highlight details for macular degeneration and low contrast sensitivity people. The assistive technology also includes speech recognition interface, indoor navigation interface, and tactile feedback interface. The objective is to enable poor vision users to perform normal driving, to navigate inside public

transportation facilities, to interact with autonomous or ride-sharing vehicles, to navigate to the destination and back. We believe that the proposed assistive technology would increase mobility for visually impaired people using vehicle services, or even retain their driver's license after extended training and exams.

The tasks of the project include: first, survey of the state-of-the-art of low vision rehabilitation technologies and training procedures, the interface between our super-reality glasses and the bioptic telescope spectacles (BTS) and other existing rehabilitation devices. Second, we developed computer vision algorithms for enhancing contrast sensitivities with object detection of signs, lanes, pedestrians and vehicles with coded color edge enhancement, warning symbols, and audio signals. Third, we designed and implemented the holographic overlay algorithm to align the highlighted information with actual objects on screen.

Prototype One: Micro Video Heads-Up Display (HUD)

Our first generation of HUD is a micro video display system that is connected to an embedded computer. It can display live video with a zoom in function. It has the half-VGA resolution and at least 25 fps. However, the HUD obscures the view like many Bioptic Telescope products. In addition, we have not found any affordable OEMs for the video HUD component on the market. Figure 1 shows the first generation of the glasses.



Figure 1. Prototype One: Micro Video HUD (left), test scene of the building in distance (middle) and the HUD view (right)

Prototype Two: Holographic HUD

Our second prototype is to project the live video from the OLED to the beam-split lens, which forms the virtual enlarged image in front of the glasses. The advantage of the holographic design is that the enlarged image is overlaid on top of the lens without obscuring the view. In this prototype, we used more compact embedded computer, smaller, and lighter OLED. Due to constraints of the length of signal cables for the OLED and camera, we have not reached the optimal alignment yet. We also need to redesign optical components to reach the desirable telescopic results.



Figure 2. The optometrist Dr. Paul Freeman from AGH Vision Lab tested the holographic HUD at the VIS Lab

Prototype Three

Digital zooming can amplify an image at any ratio but it increases blurriness. In order to obtain a clear telescopic view, we need to use a telescopic lens. Most telescopic lens are too big for glasses. To optimize the size and magnification ratio, we selected a miniature 2.2X lens, combining with digital zooming. Figure 3 shows two prototypes of the telescopic lens with the miniature camera in the 3D printed box. There are two possible locations: at the center and on the side. The test shows that the telescopic lens improves the clarity of the image significantly. The user can view the distant object from the magnified image projected onto the holographic HUD.



Figure 3. The traditional bioptic telescopic lens (left) and the holographic HUD with telescopic lens (middle and right)

Conclusions

We have developed prototypes of the holographic heads-up display (HUD) for assisting low-vision user's mobility. The holographic HUD approach does not obscure the field of view like prevailing bioptic glasses; and it is relatively lighter as well. Compared to the phone-based HUD glasses on the market, our approach is more affordable and expendable. Our future work would include: adaptive holographic HUD for outdoor usage, miniaturizing the camera, the embedded computer, and batteries, and more vision-assistance functions such as text recognition and contour enhancement.

Output

We have developed a new method to fuse multi-sensor information for detecting user's activities and pavement obstacles. We will file the Invention Disclosure to CMU Technology Transfer office and follow up with Provisional Patent. We participated NIST's Haptic Interfaces Challenge and won the First Place Award in 2019. We are also participating the NIST's AR Interface Challenge at Phase III in 2020.

Outcomes

1. Yang Cai, Learn on the Fly, Proceedings of AHFE Conference, Springer, 2020
2. Yang Cai, Florian Alber, Sean Hackett, Indoor Localization on Helmet, Proceedings of AHFE Conference, Springer, 2020
3. Yang Cai, Sean Hackett and Florian Alber, Path Markup Language for Indoor Navigation, Proceedings of ICCS Conference, Springer, 2020
4. Yang Cai, et al. Heads-Up LiDAR on Helmet. Accepted to appear on Imaging Science and Technology Conference, Jan, 2020
5. Sean Hackett, Florian Alber, and Yang Cai. A Hyper-Reality Helmet for Virtual and Live Emergency Response, Proceedings of HCII Conference, Springer, 2020

6. Yang Cai, Angelo Genovese, Mel Siegel, et al. IoT-based Architectures for Sensing and Local Data Processing in Ambient Intelligence: Research and Industrial Trends, Proceedings of IEEE I2TMC, 2019
7. S. Hackett, Y. Cai and M. Siegel. Sensor Fusion-Based Activity Recognition from Fireman's Helmet, ICSP-BMEI Conference, Huajiao, Oct. 2019

Partner

Our vision research and deployment partner is Dr. Paul Freeman, OD, from Department of Ophthalmology, Allegheny General Hospital, Low Vision Rehabilitation Services of Beaver County Association for the Blind and Keystone Blind Association. As an optometrist with over 40 years of providing low vision rehabilitation, Dr. Freeman works extensively with patients who are visually impaired and legally blind, many of whom either have difficulty driving or are not able to legally drive in Pennsylvania.

References

1. Fact Sheet Blindness and Low Vision | National Federation of the Blind. [Accessed: 02-Jul-2017]; [Online]. Available: <https://nfb.org/fact-sheet-blindness-and-low-vision>.
2. Pascolini D, Mariotti SP. Global estimates of visual impairment: 2010. Br. J. Ophthalmol. 2011 Dec.[PubMed]
3. Geruschat D, Dagnelie D. Assistive Technology for Blindness and Low Vision. CRC Press; 2012. Low Vision: Types of Vision Loss and Common Effects on Activities of Daily Life.
4. Friedman DS, O'Colmain BJ, Tomany SC et al. Prevalence of age-related macular degeneration in the United States. Arch Ophthalmol 2004; 122: 564–572.
5. Browsers AR, et al. Evaluation of a paradigm to investigate detection of road hazards when using a bioptic telescope. Optim. Vis. Sci. 2018, vol. 95(9).
6. Bronstad PM, et al. Driving with central field loss III: vehicle control. Clinical and Experimental Optometry, 2016.
7. Wilkinson ME and McGehee DV. Auditory global positioning system and advanced driver assistance systems: a safer alternative to bioptic telescopes for drivers who are visually impaired? Optom. Vis. Sci. TBD.
8. Tadin D, Lappin JS, and Sonsino J. Recognition speed using a bioptic telescope. Optometry and Vision Science, vol. 85, no. 12, December 2008
9. Owsley C. Driving with bioptic telescopes: organizing a research agenda. Optom. Vis. Sci. vol. 89, no.9 September 2012.
10. Dougherty BE, et al. Vision, training hours, and road testing results in bioptic drives. Optom. Vis. Sci. vol. 92, no. 4, April 2015