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Detection Technology for IVHS

Volume I: Final Report

Research and Development Turner-Fairbank Highway Research Center 6300 Georgetown Pike McLean, Virginia 22101-2296

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FOREWORD

This report presents the results of a comprehensive study to measure the laboratory and field performance of commercial vehicle detectors under different traffic conditions on freeways and surface-street arterial sites. The detectors were installed in three states having diverse climates ranging from cold winter and snow in Minneapolis, Minnesota; humidity, rain, lightning, and heat in Orlando, Florida; warm, dry weather in Phoenix and Tucson, Arizona; and hot summer temperatures with thunderstorms in Phoenix. IVHS traffic parameter specification were developed for interconnected intersection control, isolated intersection control, freeway incident detection, traffic data collection, real time adaptive control and vehicle-roadway communications. This report assesses the best performing detector technologies by application.

Sufficient copies of the report are being distributed to provide a minimum of two copies to each FHWA regional and division office, and five copies to each State highway agency. Direct distribution is being made to division offices.

A. George Østensen, Director Office of Safety and Traffic Operations Research and Development

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16. Abstract						
This project identified traffic parameters and						
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identifying traffic parameters and accuracies.						
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surface-street and freeway sites in each of th	e three states. Dete	ector mounting, power avai	lability, data record	ing, ground truthing,		
and security were addressed. Task G consis						
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ACKNOWLEDGMENTS

Many people and organizations contributed to the success of this project. We feel fortunate to have had the generous support and expertise from several city and state departments of transportation. The Minnesota Department of Transportation (DOT) was instrumental in getting the project started correctly by supplying not only cables, equipment mounting racks, and power supplies, but indispensable knowledge of how to label, wire, and keep track of the hundreds of wires required to send power to the detectors and transmit information from them to the data logger. We followed the plans they developed at all of the test locations. The City of Minneapolis was a warm host to us as well during the Winter of 1993. They cut loops in their streets, cored holes for our magnetometers, and provided us with a test site not far from the best rib joint we found during the project. Our contacts and support in Minnesota were through Jim Wright, Ping Yi, Dave Long, and Tim Bangsund.

The Florida DOT helped us set up a unique test site along the I-4 corridor into Orlando where the same data acquisition trailer location was used for freeway and surface arterial detector evaluation. We simply moved the detectors from the freeway below to the overpass above when we were ready to switch highway types. In addition to the usual cutting of loops and coring for magnetometers, they designed a chain-link fence protective screen to shield our detectors from inquisitive onlookers. They also provided an out-of-the-ordinary technique for mounting the self-powered magnetometers under the overpass so that the vehicles above could be counted. Our Florida coordination was through George Gilhooley and Jon Cheney, with support from Steve Hull, Don Carmer, Mark Candella, and Larry Gross.

With the aid of the Arizona DOT, we selected a test site on the west side of the I-10 freeway in downtown Phoenix. We didn't use the pipe tree to support the overhead detectors at this site, but instead mounted them directly on the sign-bridge structure that spanned the westbound lanes. The cat-like ability and the fearlessness of the DOT personnel were greatly appreciated during this adventure. The Arizona DOT personnel who supported the project were Dan Powell, Sarath Joshua, Jim Shea, Larry Cummings, Andy Murray, and Sam Stubbs.

Not to be out done, the City of Tucson Department of Transportation provided a test location across the street from the largest shopping mall in the area. Only at this site did we bury our cable run from the signal mast arm and pole to the data acquisition trailer. After warding off prairie dogs and water from a spring storm, we got the detectors operating. Once more, the technicians made available to the project by the city were outstanding in their willingness and ability to aid us in mounting and diagnosing any problems with the detectors. Our appreciation is extended to Dennis Sheppard, Ray Svec, John Swanson, and Edwin Daugherty for arranging for the support of the city and assisting us in connecting and aiming the detectors.

The research division at FHWA provided an ideal technical representative. The project would not have been as successful without his many thought-provoking comments and suggestions and his general support. The efforts of the contracting officer to keep the proverbial checks in the mail were certainly appreciated. We are also indebted to the FHWA Program Manager for establishing the need for a project of this type and for his continued support throughout its many phases.

Don Savitt of Hughes Aircraft Company had the foresight to develop the strategy that led to the winning of this contract. With the assistance of JHK and Associates, we were able to develop a team that understood the need for acquiring accurate traffic parameter data and could develop methods for acquiring them. Many people at JHK helped develop one of the major outputs of the project, the Task A Report *Development of IVHS Traffic Parameter Specifications*. In particular, Scott MacCalden, Jr. and Craig Gardner provided the insights that are incorporated in the document.

Rick Anderson of Hughes and Steven Birch of Iron Mountain Systems designed the hardware and software used in the data logger to acquire and convert the detector output data into a userfriendly database format. Their expertise was instrumental in being able to simultaneously record and time-tag data from the approximately 20 detectors that represented the technologies under evaluation.

There is one more person to whom the project owes a great debt, Michael Kelley. As a key participant in the installation, data acquisition, and data analysis tasks, his contributions are priceless. He displayed his enthusiasm by spending long weeks and days in the field, getting up before sunrise and retiring after dark to make sure that the necessary data were recorded. With the encouragement of the Principal Investigator, he helped seek out the best ribs in each city we visited.

Lawrence A. Klein Principal Investigator

PREFACE

The Detection Technology for IVHS project, under Federal Highway Administration Contract DTFH61-91-C-00076, began in September 1991 and continued through April 1995. In the first part of the project, parameters used in characterizing traffic flow for conventional traffic control systems and for newer Intelligent Vehicle-Highway Systems (IVHS) applications were identified. IVHS applications may place higher accuracy requirements on traffic parameters measured by detectors and may also require the acquisition of traffic data not normally output by the more conventional detectors. The traffic parameter data accuracies developed for IVHS applications are based on available operational test data, traffic control algorithms, and performance prediction analyses. Even though an extensive effort was made to acquire traffic data accuracy requirements, there was not a great deal of this information available. We expect that the accuracies given in this report will be updated as new control algorithms and information continue to be developed.

Detector manufacturers were contacted to determine if they would make their devices available to the program. A cross section of detectors that represented different technologies were obtained, including inductive loop with conventional and high sampling rate detector amplifiers, magnetometers with relatively small detection zones, magnetometer arrays with large multilane detection zones, microwave radar, laser radar, ultrasound, acoustic microphone arrays, passive infrared, imaging infrared, and video image processing.

In the next part of the project, laboratory test plans were developed and tests were conducted for detectors that would eventually be exposed to diverse environmental and traffic conditions during the field tests. The laboratory tests demonstrated the operation and capabilities of the detectors and their limitations. These tests were performed at Hughes Aircraft Company facilities in Fullerton, CA and by the City of Los Angeles Department of Transportation on Exposition Boulevard in Los Angeles.

Once the laboratory tests were completed, the detectors were installed in three states having diverse climates that ranged from cold winter and snow in Minneapolis; humidity, rain, lightning, and heat in Orlando; warm, dry weather in Phoenix and Tucson; and hot summer temperatures with thunderstorms in Phoenix. A freeway and a surface-street arterial site were used sequentially in each state. The tests were conducted according to a test plan that described the mounting of the detectors, their power requirements, test patterns, data acquisition and reduction, ground truth procedures, and security at the test sites.

The recorded data were processed using application-specific software designed for each detector. This resulted in a database being created that contained the normal outputs from the detector when a vehicle passed through its field of view, the time of the event, videotape index number, and air temperature and wind speed and direction. By using the video index number, a specific event can be accessed and reviewed on a computer-controlled video recorder.

The feasibility of establishing a national detector evaluation facility was also studied. Letters were sent to the detector manufacturers and several universities soliciting their inputs and thoughts about such a center.

SI* (MODERN METRIC) CONVERSION FACTORS									
ļ	APPROXIMATE CONVERSIONS TO SI UNITS APPROXIMATE CONVERSIONS FROM SI UNITS								
Symbol	When You Know	Multiply By	To Find	Symbol	Symbol	When You Know	Multiply By	To Find	Symbol
		LENGTH					LENGTH		
in	inches	25.4	millimeters	mm	mm	millimeters	0.039	inches	in
ft	feet	0.305	meters	m	m	meters	3.28	feet	ft
yd	yards	0.914	meters	m	, m	meters	1.09	yards	yd
mi	miles	1.61	kilometers	km	km	kilometers	0.621	miles	mi
		AREA					AREA		
in²	square inches	645.2	square millimeters	mm²	mm²	square millimeters	0.0016	square inches	in²
ft²	square leet	0.093	square meters	m²	uu s	square meters	10.764	square leet	ft²
γd²	square yards	0.836	square meters	m²	m²	square meters	1.195	square yards	yd²
ac	acres	0.405	hectares	ha	ha	hectares	2.47	acres	ac
mi²	square miles	2.59	square kilometers	km²	km²	square kilometers	0.386	square miles	mi²
		VOLUME					VOLUME		
fioz	fluid ounces	29.57	milliliters	mL	mL	milliliters	0.034	fluid ounces	fl oz
gal	gallons	3.785	liters	1	L	liters	0.264	gailons	gal
41	cubic feet	0.028	cubic meters	г m ³	m3	cubic meters	35.71	cubic leet	ft ³
yd ^a	cubic yards	0.765	cubic meters	m³	m³	cubic meters	1.307	cubic yards	yd ^a
NOTE: V	olumes greater than 100	00 I shall be shown in	m³.						
		MASS					MASS	_	
oz	ouńces	28.35	grams	g	g	grams	0.035	ounces	oz
lb	pounds	0.454	kilograms	kg	kg	kilograms	2.202	pounds	lb
Т	short tons (2000 lb)	0.907	megagrams	Mg	Mg	megagrams	1.103	short tons (2000	lb) T
			(or "metric ton")	(or "t")	(or "t")	(or "metric ton")			
	TEMPER	RATURE (exact)				TEMP	ERATURE (exa	<u>ct)</u>	
٥F	Fahrenheit	5(F-32)/9	Celcius	°C	°C	Celcius	1.8C + 32	Fahrenheit	۰F
	temperature	or (F-32)/1.8	temperature			temperature		temperature	
		MINATION					LUMINATION		
fc	foot-candles	10.76	tux	ix	lx	lux	0.0929	foot-candles	fc
fi	foot-Lamberts	3.426	candela/m²	cd/m²	cd/m²	candela/m ²	0.2919	foot-Lamberts	1
	FORCE and PF	RESSURE or ST	RESS			FORCE and	PRESSURE or	STRESS	
lbf	poundforce	4.45	newtons	N	N	newtons	0.225		lbf
lbf/in²	poundforce per square inch	6.89	kilopascals	kPa	kPa	kilopascals	0.145	poundlorce per square inch	lbf/in²

* SI is the symbol for the International System of Units. Appropriate rounding should be made to comply with Section 4 of ASTM E380.

(Revised September 1993)

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1. SCOPE OF THE PROGRAM

1.1 INTRODUCTION

Maximizing the efficiency and capacity of the existing transportation network is made necessary by the continued increase in traffic volume and the limited construction of new highway facilities in urban, intercity, and rural areas. Smart street systems that contain traffic monitoring detectors, realtime adaptive signal control systems, and motorist communications media are being combined with freeway and highway surveillance and control systems to create smart corridors that increase the effectiveness of the ground transportation network. The infrastructure improvements and new technologies are, in turn, being married to smart cars to form Intelligent Vehicle-Highway Systems (IVHS). Since the inception of this contract, Intelligent Transportation Systems (ITS) has replaced IVHS to represent the marriage of smart vehicles with smart infrastructure systems. As IVHS is included in the contract title, it is retained in this report.

Vehicle detectors are an integral part of nearly every modern traffic control system. Moreover, detectors and communications media will be major elements in future traffic monitoring systems. The types of traffic flow data, their reliability, consistency, accuracy, and precision and detector response time are some of the critical parameters to be evaluated when choosing a vehicle detector. These attributes become even more important as the number of detectors proliferate and the real-time control aspects of IVHS put a premium on both the quantity and quality of traffic flow data used in traffic surveillance and control algorithms.

Current vehicle detection is based predominantly on inductive loop detectors installed in the roadway subsurface. When properly installed and maintained, they can provide real-time data and a historical database against which to compare and evaluate more advanced detector systems. Alternative detector technologies being developed provide direct measurement of a wider variety of traffic parameters, such as density, travel time, vehicle path, volume, and speed. These advanced detectors provide more accurate data; parameters that are not directly measured with previous instruments; inputs to area-wide surveillance and control of signalized intersections and freeways; and support of motorist information services. Furthermore, many of the advanced detector systems can be installed and maintained without disrupting traffic flow.

1.2 PURPOSE OF THE PROJECT

The objectives of the Federal Highway Administration (FHWA)-sponsored *Detection Technology for IVHS* project are to:

- Determine the traffic parameters and their corresponding accuracy specifications needed for future IVHS applications;
- Perform laboratory and field tests with detectors that apply technologies compatible with above-the-road, surface, and subsurface mounting to determine the ability of state-of-the-art detectors to measure traffic parameters with acceptable accuracy, precision, and repeatability;
- Determine the need and feasibility of establishing permanent vehicle detector test facilities.

In performing the technology evaluations and in analyzing the data, focus was placed on the underlying technology upon which the detectors were based. It was not the purpose of the program to determine which specific detectors met a set of requirements, but rather whether the sensing technology they used had merit in measuring and reporting traffic data to the accuracy needed for present and future applications. Obviously, there can be many implementations of a technology, some of which may be better exploited than others at any time. Thus, a technology may show promise for future applications, but the state-of-the-art of current hardware or software may be hampering its present deployment.

The project consisted of 12 major tasks:

Task A. Develop a working paper that defines IVHS traffic parameter specifications for the following application areas:

- · Interconnected Intersection Control,
- · Isolated Intersection Control,
- · Freeway Incident Detection,
- Traffic Data Collection,
- Real-Time Traffic Adaptive Control,
- · Vehicle-Roadway Communications.

Task B. Select sites for detector field tests. Test sites in three different regions of the country will be selected to provide a range of environmental and traffic conditions broad enough to ensure the utility of the test results on a nationwide basis.

Task C. Develop vehicle detector laboratory test specifications and a laboratory test plan.

Task D. Select and obtain vehicle detectors for testing.

Task E. Conduct laboratory detector tests and generate a report describing the results.

Task F. Develop vehicle detector field test specifications and field test plan.

Task G. Install vehicle detectors at field test sites and collect detection technology evaluation data.

Task H. Generate detection technology field test results.

Task I. Determine which of the currently available vehicle detectors meet the IVHS criteria of Task A.

Task J. Determine the need and feasibility of establishing permanent vehicle detector test facilities.

Task K. Prepare a draft final report.

Task L. Prepare the final report that incorporates comments received from FHWA and others.

1.3 ORGANIZATION OF THE FINAL REPORT

The final report documents the planning and the conclusions of the *Detection Technology for IVHS* program that ran from September 1991 through January 1995.

Section 1 contains an introduction to the project that outlines the various tasks that were included in the program and the contents of the final report.

Section 2 summarizes Task A by including descriptions of traffic parameters needed to characterize free flow and interrupted flow on freeways and surface streets. The accuracies of the parameters for several future IVHS applications are summarized in tables at the end of the section. The accuracies represent those needed for input data to as yet undefined future algorithms and paradigms that support the selected applications. As such, they are subject to revision as the specific algorithms, strategies, and applications become better known.

Section 3 describes the field test and evaluation site locations that were visited. The information for this section is taken from the Task B Report.

Section 4 discusses the detector selection process using information in the Task D Report. On-bench photographs of each detector and manufacturer's specifications are given.

Section 5 describes the theory of operation of the detector technologies and the types of information typically available from each. These technologies include those for abovethe-road mounted detectors, namely video image processing, microwave, active (transmit and receive) and passive (receive only) infrared, imaging infrared, passive acoustic arrays, and ultrasound, as well as those for conventional and newer applications of beneath-the-surface inductive loop, magnetic, and magnetometer detectors. Communications technologies, such as those used for automatic vehicle identification, are also discussed.

Section 6 reviews the Task C report by explaining the need for laboratory tests before venturing out for field tests and by describing the types of laboratory tests conducted.

Section 7 summarizes the results from the laboratory tests that were originally published in the Task E reports. These tests were conducted in the City of Los Angeles and at the Hughes Aircraft Company facility in Fullerton, CA.

Section 8 contains a summary of the Task F field test plan and procedures. Detector installation requirements are listed. The data logger hardware and software that played a major role in the data acquisition are discussed in this section and in Appendix C.

Section 9 describes the detector technology data collection and evaluation processes. Photographs and line drawings of the field sites with the installed detectors and the detector locations are shown. The data analysis process of converting the raw data files into Paradox database format is explained as are the ground truth procedures. Tabulations of the amount of data collected at each site are given.

Section 10 describes how to access the data storage media, presents the analyzed detector output data from several runs at each test site, and interprets the results. Not all the collected data have been analyzed as a part of this phase of the project. However, representative data have been plotted to show the types of results and analyses that can be performed on the extensive data set.

Section 11 compares the detector specifications for future IVHS applications developed in Section 2 with the performance of the presently available detectors. The accuracies of the detectors that were evaluated and their application to current traffic management areas are summarized. Where possible, recommendations are made as to how to improve the detector design to bridge the gap between the data and accuracy of present detectors and those needed for some specific IVHS applications.

Section 12 gives the general conclusions from the program and makes recommendations for future research.

Appendix A documents the results of Task J, determining the need and feasibility of establishing one or more permanent vehicle detector test facilities.

Appendix B lists the detector manufacturers and contact personnel that provided detectors and information during the evaluation program.

Appendix C describes the data logger hardware and software design and the formats used to record the analog, digital, and serial information output by the detectors in the technology evaluation study.

Appendix D illustrates the concepts involved in designing a continuous wave microwave radar to detect multiple vehicles in a given lane on a roadway.

Appendix E contains the pipe tree installation and intersection plan-view drawings used at the Minneapolis field sites.

Appendix F gives the azimuth and elevation ground footprints of the detectors as a function of mounting height, azimuth and elevation aperture beamwidth, and angle of incidence (with respect to nadir).

Appendix G contains the specifications for the inductive loops installed by the states that hosted the field tests.

Appendix H documents the connections made during the field tests from the detectors to the data logger and power supplies.

Appendix I contains pipe tree installation and selected construction plans for the State Route (SR 436) overpass at Interstate 4 (I-4) that describe the design of the truss for the sign bridge and the design of the SR 436 span over I-4.

Appendix J contains climatological data from the Minneapolis, Orlando-Altamonte Springs, Phoenix, and Tucson field sites as tabulated by the National Oceanic and Atmospheric Administration through the National Climatic Data Center in Asheville, North Carolina. Appendix K contains listings of the FORTRAN programs that were written to analyze the detector output data.

2. TASK A SUMMARY

DEVELOPMENT OF IVHS TRAFFIC PARAMETER SPECIFICATIONS

A working paper was developed in Task A to define traffic parameter specifications for IVHS applications that include:

- Interconnected intersection control,
- Isolated intersection control,
- Freeway incident detection,
- Traffic data collection,
- Real-time traffic adaptive control, and
- Vehicle-to-roadway communications.

Traffic parameters of value in these applications are described in this section. Projected accuracies for the measurement of the traffic parameters in support of future IVHS applications such as signalized intersection control, freeway incident detection, and freeway metering are then presented.

2.1 TRAFFIC FLOW PARAMETERS

Vehicle flow, speed, and density parameters are fundamental to the management of highway traffic. Over a given section of open roadway, such as a freeway, they are related through equation 2-1 and their values are usually expressed on a per lane basis. Hence,

Flow (vph) = Speed (mi/h) x Density (vpm) (2-1)

where

vph = vehicles per hour per lane,

mi/h= miles per hour, and

vpm = vehicles per mile per lane.

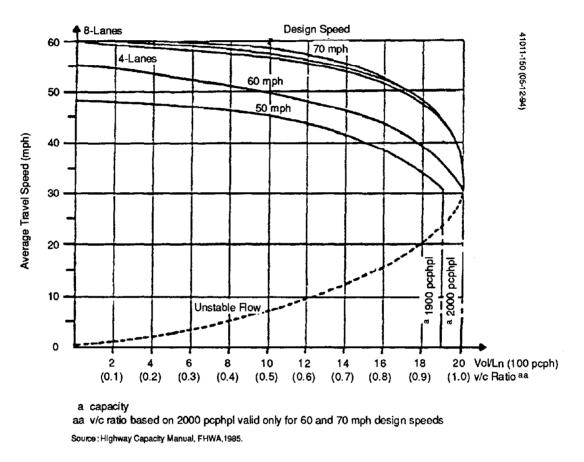
Flow or volume flow rate is the time rate of flow in vehicles per hour used to characterize traffic volume. A transition in terminology is occurring as "flow" or "flow rate" has taken the place of "volume."⁽¹⁾ Because of the mix of old and new terminology, there is some inconsistency in the use of "volume" and "flow rate" in the literature. This can be seen in the capacity curves of Figure 2-1 that illustrate the relation between speed and flow on the open roadway. Capacity is expressed as "volume/lane" in units of flow rate (passenger cars per hour). The term "flow" is also used to describe the general condition of traffic on the roadway, such as "free-flow" or "congested flow."⁽²⁾

The volume flow rate data by themselves are not sufficient to define how well traffic is moving. For example, if counts show a flow rate of 1200 vehicles per hour, it is not known whether traffic is moving briskly at 55 mi/h (88.5 km/h) or is congested and creeping along at 10 mi/h (16.1 km/h).

On the other hand, by measuring density and knowing the speed-flow characteristic for a given highway type, speed-density and flowdensity curves can be estimated as shown in Figures 2-2 and 2-3, respectively. When density is a performance indicator, as shown by the shape of the curve in Figure 2-2. there is no longer any ambiguity with respect to speed. If density is measured at 20 vehicles per mile per lane (32 v/km/lane), then speed is 55 mi/h (88.5 km/h). If density is 120 vehicles per mile per lane (192 v/km/lane), then speed is 10 mi/h (16.1 km/h). Likewise, Figure 2-3 shows that a flow rate of approximately 1200 vehicles per hour per lane (1920 v/h/lane) corresponds to these same density measurements of 20 and 120 vehicles per mile per lane, respectively.

2.2 TRAFFIC PARAMETERS FOR INTERRUPTED FLOW

Flow, speed, and density are used to characterize traffic flows on freeways and other open sections of roadway not affected by control devices such as traffic signals, stop signs, and ramp metering. When interrupted flow conditions are encountered, such as at signalized intersections, other traffic flow characteristics appear and additional



1 mi/h = 1.6 km/h

Figure 2-1. Highway Capacity Curve Showing Relation Between Speed and Flow Under Ideal Conditions

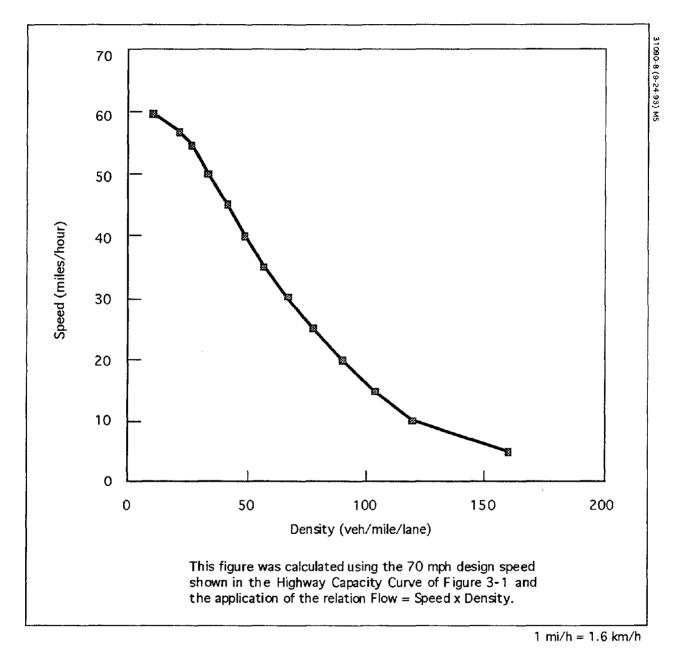
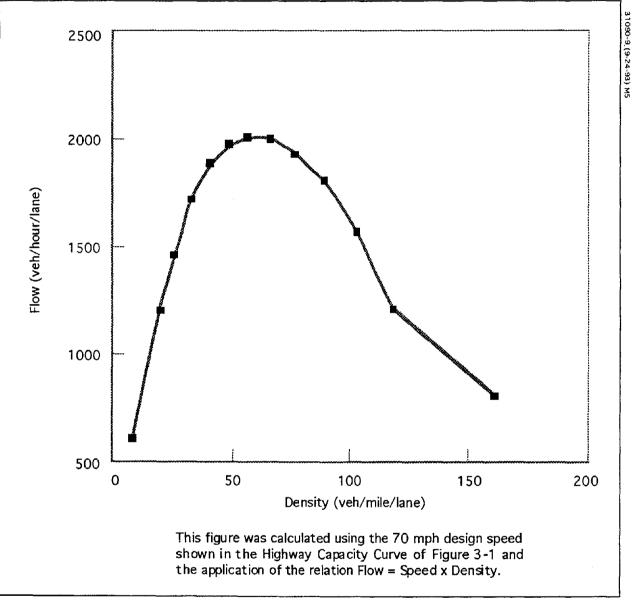


Figure 2-2. Speed-Density Curve



1 mi/h = 1.6 km/h



measures of flow are needed. Flow, speed, and density are still required by current and future IVHS applications for efficient management of interrupted flow, but to these are added measures such as delay, stops, and turning movements.

Some of the parameters are directly measurable in real time, while others are mathematically derived or estimated from the measurable parameters. Still others must be estimated from collected historical data. A generic discussion of commonly used traffic parameters considered relevant to IVHS is presented below, although specific parameters and accuracies will be a function of the IVHS application and the detector technology deployed.

2.3 TRAFFIC PARAMETER DEFINITIONS

Parameters that characterize traffic flow can be classified in terms of one of the following:

- *Quantity Measures:* How much or at what rate is traffic moving or waiting to move?;
- *Quality Assessment Measures:* How well is traffic moving?;
- Movement Measures: Where is traffic coming from and going to?; and
- Composition/Classification Measures: What kind of traffic is moving?

Parameters which fall into each of the above categories are discussed below.

2.3.1 Quantity Measures

Traffic quantity measures include volume, demand, time headways, and throughput.

2.3.1.1 Volume

Volume data are generally expressed in terms of flow rate. Flow rate is a temporal quantity measure defined as the number of vehicles passing a point in a given period of time, usually 1 hour. Flow rate q is the inverse of the average of the time headways measured over the same period such that

$$q = \frac{3600}{h}$$
 (2-2)

where

- q = hourly flow rate (vehicles per hour),
- h = average time headway (seconds per vehicle), and

3600 = number of seconds per hour.

Flow rates, both measured and forecasted, have many applications in traffic engineering, including developing traffic trends, analyzing accident data, determining sites for traffic signals, estimating future toll revenues, developing design requirements for new or reconstructed highways, and investigating operational improvements using capacity analysis.

On most facilities, traffic flow rates vary throughout the day and by direction. Figure 2-4 depicts these variations on the San Francisco-Oakland Bay Bridge, a 10-lane urban highway without shoulders. In addition, highways exhibit monthly variations in traffic flow rates that are dependent on the highway type and location. These variations are a function of urban versus rural facilities and recreational versus nonrecreational facilities, for example.

Traffic flow measurements can have different interpretations depending upon the conditions upstream and downstream of the measurement site, as well as at the detector locations. For example, if there is no congestion at the site (or upstream of it) to limit the arrival rate of the vehicles being measured, then the flow rate is equal to the existing demand. If, on the other hand, queuing exists at the site, then the measured flow rate reflects the downstream bottleneck capacity.

2.3.1.2 Demand

Demand is "the amount of traffic volume (or flow rate) that occurs on a facility under some given set of travel conditions." When not constrained by a highway's capacity, the actual flow rate measured on the highway will equal its demand. However, in cases where highway demand exceeds capacity, some queuing will occur and actual measured flow rates will be less than the demand.

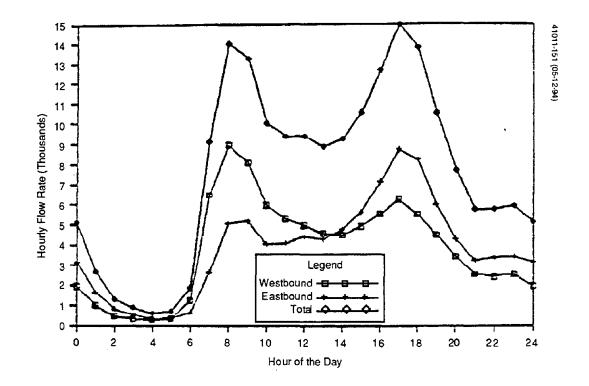


Figure 2-4. Hourly Traffic Flow on the San Francisco-Oakland Bay Bridge

Many IVHS applications make a distinction between volume and demand values. For optimal decision making, traffic control and traffic advisory subsystems often need the anticipated traffic demand for a given road at a future time (not just its current volume). For example, when advising motorists to use an alternate route around a freeway incident, an estimate of the expected demand for the alternate route is needed.

Unfortunately, demand values are difficult to obtain directly. If congestion is present either upstream of the diversion point on the freeway or on the alternate route, then measured flow rates may understate potential demand. Furthermore, the demand for a particular alternate route will vary over time and with the actual number of motorists being diverted. To predict the consequences of a routing decision, estimates for demand on the alternate route segments are projected for the future time when diverted motorists will encounter these demands along their route. Current and historic flow rate data and diversion percentage estimates are key inputs for such projections. In addition to projecting future flow rates, on-line traffic assignment techniques are used to estimate traffic demand on alternate routes.

2.3.1.3 Time Headway

Time headway between vehicles is defined as: "the elapsed time between the passage of an identical observation point by consecutive vehicles in the traffic stream." Time headway measurement can be performed manually with a stopwatch and automatically with any presence-type detector or with video image processors. Since the average of vehicle time headways past a point over some time interval is the reciprocal of the flow rate past that point, time headways present microscopic measures of flow past a point. Time headways are also frequently used as a quantitative measure of service or productivity at traffic signals and toll collection stations, that is, as a service headway expressed in terms of average number of seconds per vehicle.

The space-time diagram of Figure 2-5 shows the paths of several vehicles as they pass an observation point and the two components that make up time headway. The first component is the time it takes the vehicle to pass the observation point, or occupancy time. The second component is the time between the rear of one vehicle and the leading edge of the next, or gap time.

Highway capacity depends primarily on the gap times that individual drivers are comfortable with on the particular highway. Opportunities for passing, merging, or crossing are also determined by gaps provided by the appropriate time headway distributions. Two measures of the level of service closely associated with time headways are the percentage of time one vehicle is forced to follow another on two-lane highways and the frequency of speed adjustments that a driver makes to maintain a minimum headway.

2.3.1.4 Throughput

Throughput is defined as: "the vehicle-miles of travel carried by a given length of roadway for a given period of time." It is determined by measuring flow rates for each section of highway between points of entry or egress. It is often used to characterize the efficiency of a highway facility and to evaluate the "beforeand-after" effects of operational improvements. Appropriate comparisons are obtained by calculating the throughput for each travel direction and for comparable times of day.

2.3.2 Quality Assessment Measures

Quality measures determine how well traffic is flowing on a given roadway. They include speed, density, delay, and stops.

2.3.2.1 Speed

Speed is one of the three macroscopic traffic flow measures, the others being volume and occupancy. Speed expresses the rate at which traffic is moving and, therefore, is a natural measure of the quality of the flow. Three types of speed measurements are described below: spot speed, time mean speed, and space mean speed.

Spot speed is defined as: "the speed of an individual vehicle as it passes an observation point of the traffic stream." As spot speeds are instantaneous speeds of individual

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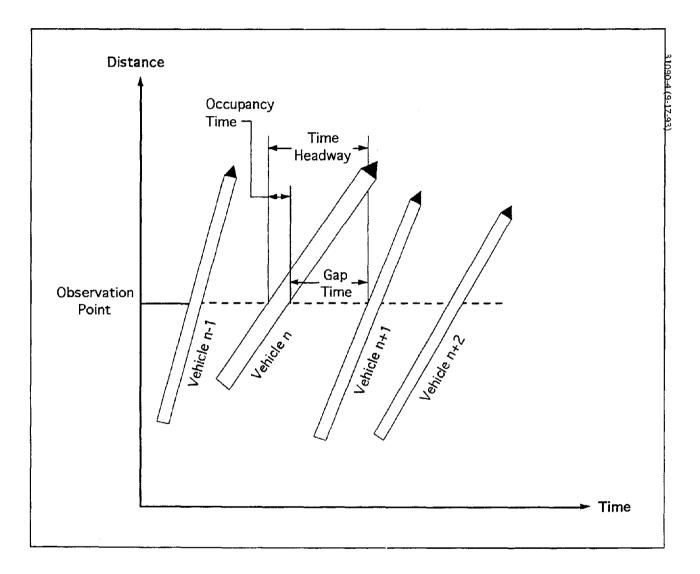


Figure 2-5. Time Headways of Consecutive Vehicles

vehicles, they can be determined from the slope of the vehicle traces on a space-time diagram such as Figure 2-5. Speed can be measured in several practical ways. First, using a speed trap station, a pair of detectors is placed on a length of roadway. Speed is calculated from the time it takes vehicles to transverse the distance between the start of the detection zones of the two detectors. Measurement accuracy depends on the distance between the detectors, the average speed of the traffic, and the detector sampling rate. Detectors used for this application include pneumatic tubes, piezoelectric strips, inductive loops, infrared, video image processors, and any other type of presence detector.

A second method for measuring spot speed is with a single-loop detector and an assumed average vehicle length. This approximate technique is employed by the Urban Traffic Control System (UTCS) to compute average speed S as

$$S = \frac{0.6818 \, VC \, (LL + VL)}{O} \tag{2-3}$$

where

S = speed in mi/h,

- 0.6818 = constant to convert from ft/s to mi/h,
 - *VC* = vehicle count during the time period,
 - LL = loop length in ft,
 - VL = vehicle length in ft, and
 - *O* = seconds of loop occupancy during the time period.

With current Inductive Loop Detector (ILD) technology, speed estimates from a single loop vary from the true value by as much as 30 percent. To obtain even these relatively crude measurements, volume, vehicle length, and occupancy must be known to within an error rate no greater than ± 10 percent. Of these, vehicle length is the most difficult to estimate accurately due to variations in the real-time vehicle mix. Its value is typically based on historical data.

Other techniques for spot speed measurement exist. Imagery from video cameras measures spot speeds based on vehicle movement across a calibrated distance in the field of view. Radar technologies, such as laser radar that transmits multiple beams and microwave radar that divides its field of view into multiple zones, determine spot speed by measuring the time it takes a vehicle to move between the beams or zones. Detector technologies such as ultrasound and Doppler microwave exploit the Doppler shift in the received signal to measure spot speed.

Time mean speed is defined as: "the arithmetic mean of individual spot speeds that are recorded for vehicles passing an observation point over a selected time period." An adequately sized sample of spot speeds is needed to ensure that the time mean speed approximates the population mean to within the desired accuracy.

Space mean speed is defined as: "the harmonic mean of individual speeds which are recorded for vehicles passing an observation point over a selected time period." The harmonic mean is calculated by converting the individual spot speeds to individual travel time rates, then calculating the average travel time rate, and finally inverting the average travel time rate to obtain an average speed.

The relationship between time mean speed and space mean speed is given by

Space mean speed can also be calculated from sample travel times gathered over a known length of highway and computing the inverse of an average travel time rate (in units of time divided by units of distance). Travel times can be obtained by matching license plates or some other distinctive vehicle feature, using image processing for example, or with floating cars used as probes. In the future, vehicles equipped with automatic vehicle identification (AVI) transponders will be another source of these data.

2.3.2.2 Density Characteristics

Density, or the density rate, is a spatial measure that describes the quantity of vehicles occupying a section of roadway. The 1985 Highway Capacity Manual bases its freeway level-of-service descriptions on density rather than speed because, as previously noted, there is a wide range of flow rates where speed is relatively constant.⁽²⁾ Moreover, the freedom to maneuver and the proximity to other vehicles are equally important factors that are directly related to density. Common density-related measures include density rate, occupancy, and distance headway.

Density is defined as: "the number of vehicles occupying a given amount of roadway space (generally a lane-mile)." While density is a fundamental measure of traffic flow, its use in freeway traffic assessment and control has been limited due to the difficulty in obtaining and analyzing the required data. Until recently, the only way to directly measure density rates was through photographs taken from a high vantage point (usually aerial photography). The vehicles in a given section of roadway were then manually counted from the photograph image. Density can also be estimated from speed and flow measurements or from percent occupancy measurements. With the development of imaging techniques, density data may be obtained automatically for real-time application to IVHS.

Occupancy is defined as: "the percent of time the detection zone of a detector is occupied by some vehicle." Occupancy and density are spatial parameters and their values are related. Both occupancy and density depend on the length of the vehicles in the traffic stream and the spacing between the vehicles.

Distance headway between vehicles is defined as: "the distance between identical points on consecutive vehicles in single file." Distance headways can be thought of as a microscopic view of density. The space-time diagram of Figure 2-6 shows the distance headway components and the location of the vehicles on the highway. As with time headways, distance headways have two parts: the actual length of the vehicle and the gap distance between vehicles. Distance headways and their statistical distributions are used for developing car-following models and for investigating the stability of traffic flow.

2.3.2.3 Delay Measures

Delay measures are used for freeways and signalized intersections to evaluate the benefits of operational improvements and to estimate cost-effectiveness.

Freeway delay occurs when travel speeds are less than some arbitrary "free-flow" threshold, usually 35 or 45 mi/h (56.3 or 72.4 km/h). The delay is measured in terms of flow rate and travel time in excess of the free-flow value. Delay is expressed in vehicle-hours (or person-hours).

Speed and travel time data were historically recorded on "tachograph" charts by equipment installed in floating car vehicles and were reduced manually. Newer methods record and store the data in electronic form, allowing them to be downloaded into a personal computer for easier analysis. For example, a surveillance system containing speed and traffic flow detectors spaced at 1/3-mi (1800-ft [548.6-m]) increments or less, depending on the desired accuracy of the delay estimate, can be used to construct speed profiles. With computer assistance, vehicle hours of delay can be calculated from the profiles without deploying floating vehicles. The automatic data collection approach also makes it easier to gather data samples at more frequent time intervals during a day or on more days during a week.

Intersection delay can be characterized by stopped delay, time in queue delay, and approach delay. Figure 2-7 depicts the timespace trace of a vehicle that comes to a stop several times on the same signalized intersection approach. This trace might occur at a congested location during peak volumes when a queue of stopped vehicles is not completely discharged during one green phase. It also represents a situation where there is considerable compression of the queue during a red phase, or where a lane is carrying both through and left-turn movements, or stopand-go conditions exist.

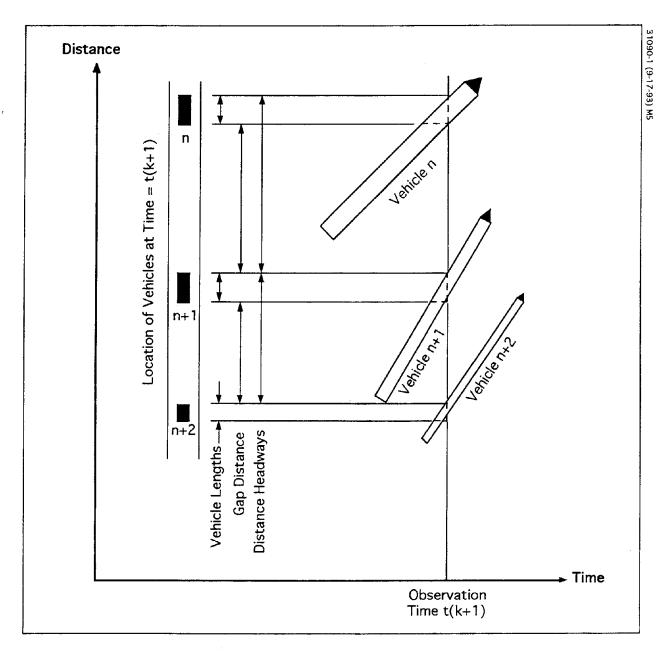
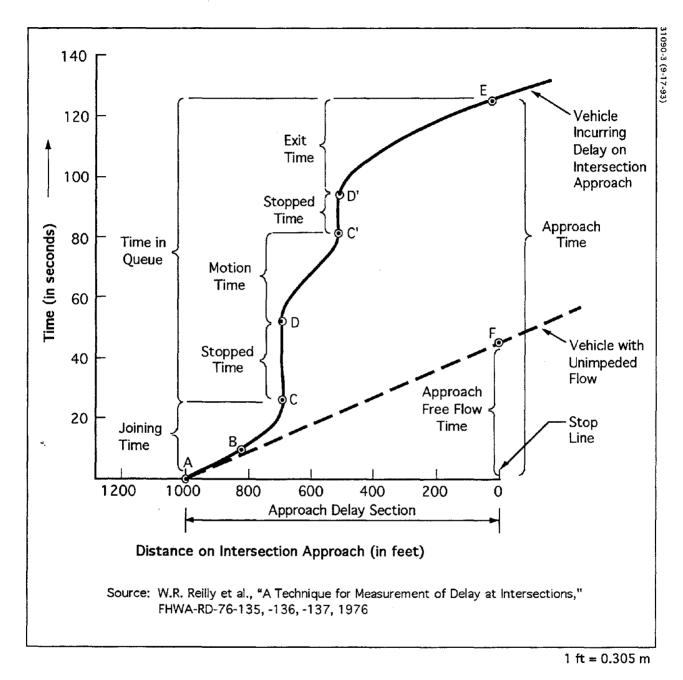


Figure 2-6. Distance Headways of Consecutive Vehicles at a Particular Time





- Stopped Delay: The sum of the stopped times, shown in Figure 2-7, equals the total stopped delay. Stopped delay, an obvious measure of traffic to the motorist, is also important when evaluating environmental impacts such as vehicle emissions. Comparisons of stopped delay between intersections may be misleading when one intersection is operating under conditions where the time of stop is short, but low speed movement in a long sluggish queue follows the stop. An associated parameter, percent of vehicles stopping. while not strictly a delay measure, is a useful statistic, particularly in evaluating both fuel consumption and emissions. It is defined as the number of vehicles that stop at least once, divided by the total number of vehicles using the approach, and is expressed as a percent.
- Time in Queue Delay: The time in queue is the sum of stopped time, motion time, and exit time as shown in Figure 2-7. It is equivalent to the total approach time minus the joining time. The time in queue delay is set equal to the time in queue, even though some progress is being made through the intersection during this time.

Time in queue delay often falls between stopped delay and approach delay. Time in queue delay can also be greater than approach delay because approach delay is equal to the difference between the actual time on the approach and the free-flow time of an unimpeded vehicle over the same distance.

 Approach Delay: The approach time is the total time required to traverse the approach section under study. The approach delay is equal to the approach time less the time required for an unimpeded vehicle to travel through the same section under free-flow conditions. Approach delay can be used directly in the analysis of road-user time costs. This measure also compares the efficiency of intersections having different modes of control, such as stop or yield signs and pretimed or vehicle-actuated traffic signals. Delay data collection techniques have been primarily manual. However, the advent of area-wide traffic control and systemcollected detector and signal status data have increased the information available for estimating delay at signalized intersections. Data collection techniques include point sample, input-output, and path trace.

The point sample method periodically samples the intersection approach to record the number of stopped vehicles at equally spaced time intervals. It determines the average number of stopped vehicles, calculates the total stopped time by multiplying the average number of stopped vehicles by the duration of the sample interval, and then calculates the average stopped delay by dividing the total stopped time by the number of vehicles passing the study section. It is analogous to taking a series of snapshots at regular intervals.

The input-output method samples data during intervals, rather than between intervals. It addresses the flow rates at the upstream and downstream boundaries of the approach area. The SCOOT adaptive traffic control system and the UTCS-enhanced area-wide traffic control system use the input-output technique.

The vehicle path trace method is essentially the same as the two other data collection techniques. Sample data are obtained by either running test vehicles through the approach area, measuring the various passage times of selected sample vehicles, or obtaining trace data from detector imaging techniques.

2.3.2.4 Intersection Stops

Intersection stops characterize the quality of traffic flow at signalized intersections. Stops are normally expressed as total stops or percent stops. Total stops are defined as the number of stops made by vehicles approaching an intersection. Percent stops is the percent of approaching vehicles making at least one stop. Both measures can be collected manually, although some traffic signal control systems estimate them using real-time flow data in combination with signal display status.

2.3.3 Movement Measures

Movement measures are based on data that describe the movement of vehicles in terms of the path they follow. The travel path may comprise an entire trip, as when origindestination data are collected, or it may occur within a small area, as when intersection turning movements are studied.

2.3.3.1 Origin-Destination Data

Origin-destination (O-D) data help to specify traffic flow volumes between established geographic zones or points of origin and destination. Hence the data are useful in evaluating traffic operations strategies and in making control decisions. In the past, the data have been difficult to obtain as expensive manual methods were needed to gather information from license plate surveys or traveler interviews. In the future, two-way communications between the vehicle and the operations center, such as with automatic vehicle location technology, may allow O-D data to be collected and acted upon in real time. In-vehicle navigation equipment may also be useful for some of the latter applications.

2.3.3.2 Turning Movements

Turning movement data define the volume or percent of traffic turning left, right, or traveling straight through an intersection approach. Today, most turning movements are collected manually using either a counter board or a notebook computer. Left and right turn and through movements at each intersection are typically counted separately for each approach and for each signal phase on that approach.

Detector imaging techniques are being developed to permit automatic recording of intersection turning movements. This will allow data to be collected over many more days than is presently feasible, and may result in more accurate data than with the manual method. Potentially, the resulting real-time data can significantly enhance the value of online control algorithms.

2.3.4 Composition and Classification Measures

Many traffic management strategies, including those for IVHS, require the identification of individual vehicles and their length, weight, or cargo specifications as an input to a vehicle classification process. These strategies include assessing fares for automatic toll collection, as well as law enforcement actions related to stolen vehicles, high-occupancy vehicle (HOV) violations, and peak period travel restrictions in central business districts. They are also used to improve commercial vehicle operations through automatic identification, weigh-in-motion, and hazardous material tracking.

Because of requirements to provide a broad spectrum of vehicle data, classification data can best be obtained through automatic vehicle identification and vehicle-to-roadside communications. However, until these technologies are more universally deployed, other means of vehicle detection and data gathering will continue to be used. Three types of vehicle classification categories are currently employed: function, configuration, and weight.

2.3.4.1 Functional Classification Data

Vehicles are frequently classified according to their function, such as passenger cars, vans, trucks, and buses. Some inductive loops, coupled with specially adapted digital detectors, can distinguish among these various types of vehicles from the unique signatures they produce while passing over the detector. Traffic signal systems with a bus priority feature have demonstrated this application.

The number of passengers per vehicle is another type of vehicle function data that may be required for HOV planning, lane enforcement, and transit operations. Loop detectors cannot provide this information, but it is conceivable that a future type of in-vehicle sensor-transmitter combination could sense the number of seats occupied and transmit the data via vehicle-to-road communications. The persons-per-vehicle count can be transmitted from the vehicle to a roadside communications device and, hence, to the operations center. Another approach to obtaining the number of passengers per vehicle may be with video image processing technology. By properly situating cameras, the number of passengers could be conceivably ascertained, while simultaneously observing privacy considerations that may be demanded by the public.

2.3.4.2 Configurational Classification

Tolls are often assessed based on the configuration of the vehicles passing through the toll plaza. Historically, separate schedules are developed for passenger vehicles and trucks, and these are further classified according to the number of axles. Overheight, overwidth, and overweight vehicles also need to be identified for safety and structural reasons. By tradition, these data are collected at truck inspection stations for commercial vehicles. With automatic vehicle identification tags, automatic classification and billing is technically feasible, especially for commercial vehicles. Because of the monetary aspects of toll collection, vehicle classification accuracy requirements can be greater for these than for other IVHS applications.

Improved commercial vehicle operations (CVO) are also obtained by expediting vehicle identification, for example, by using optical detectors to measure vehicles and weigh-inmotion equipment to speed trucks through weigh stations. Advantage I-75 and Crescent are two projects evaluating methods for improving CVO. The technologies demonstrated include vehicle-to-roadside communications to minimize the number of inspections requiring stops and the amount of paper work for trucks traveling between regions covered by the system.

Advantage I-75 uses a decentralized management approach and automatic vehicle identification to allow mainline preclearance of commercial vehicles. The Crescent Project is the demonstration phase of HELP (Heavy Vehicle Electronic License Plate), a long-term program to develop and use automatic vehicle classification, weigh-inmotion, onboard computers, and beacon technologies. Crescent uses a centralized system to electronically verify operating credentials and to monitor vehicle weights.

2.3.4.3 Weight Classification Data

The primary uses of vehicle weight information are to ensure the safety of roadway structures such as bridges and viaducts and to ensure that heavy, overweight trucks do not break down the pavement. These enforcement functions have traditionally required that data be obtained at truck inspection stations operated by highway police. Since enhanced commercial vehicle operations is a goal of IVHS, weigh-in-motion sensors are being deployed in these programs.

The same weight data required for enforcement are also valuable in updating planning and design information related to bridge live-load specifications and in establishing the required strength of highway pavements.

2.4 TRAFFIC PARAMETER AND ACCURACY SPECIFICATIONS FOR FUTURE IVHS APPLICATIONS

The traffic parameter accuracy specifications shown in this section are believed to be representative of requirements for selected IVHS applications. However, no claim is made as to their widespread applicability since traffic parameter specifications will necessarily vary with the particular traffic management system architecture, implementation strategies, selected components and signal processing algorithms, and system operational procedures.

The traffic parameter measurement accuracy specifications for a given management strategy must primarily take into account the data processing and traffic control algorithms for which these parameters serve as inputs. Specification of traffic parameter accuracy, therefore, cannot be separated from the overall system-level analysis and design process. For each contemplated IVHS service, there are likely to be many different system algorithms, procedures, and detection subsystem design options. Evaluating alternative implementations for a particular service is the responsibility of system analysts and designers. This discussion cannot serve as a substitute for a thorough systems analysis and design effort. Nonetheless, a suggested process for the development of traffic parameter specifications, including data types, collection interval, and accuracy, is proposed.

To structure the discussion and presentation of detector performance specifications, three general categories of traffic parameters are defined based on their intended use and the required timeliness of their input for the real-time traffic management strategy. These categories are *tactical*, *strategic*, and *historic*. While the same raw inputs may often feed each of the categories, each presents a somewhat different set of detection performance and sampling requirements. In fact, these differences can result in a detector technology or product being adequate for some applications and not for others.

The traffic parameter input ranges and accuracies identified are for some of the more common IVHS services, including signalized intersection control, freeway incident management, and freeway metering control. Traffic parameter range and accuracy requirements are derived or inferred from the values needed for use in a particular algorithm (when it is known) and from practical experience with operating systems. Many of the historic and strategic category parameters may also be applicable to a host of other static and dynamic trip/route planningrelated IVHS services. However, for these and other services where established strategies and algorithms are less commonly applied, a system-specific parameter requirements analysis is suggested. Such analysis is beyond the scope of this document.

Factors that may drive future IVHS traffic parameter and algorithm specifications are discussed at the end of the section. To a large extent, current traffic management systems are input constrained. That is, a complete microscopic (vehicle-by-vehicle) view of the traffic stream is not available in today's systems because of the lack of applicable real-time input data, even though the accelerating advances in computer processing and distributed system designs make possible advanced traffic optimization modeling and control in near real time. In this case, current systems rely heavily on prestored turning movement and origin-destination (O-D) data to supplement incomplete realtime data. In real-time control, the analysis and response to external events are performed and determined within specified time limits, usually on the order of seconds or milliseconds. In near real-time control, the feedback response is calculated within longer time intervals that are not small enough to respond to the stimuli in real time, but are sufficiently small to still have a positive impact on the events caused by the stimuli.

Future applications will not likely require a whole new set of traffic parameters. Rather, advanced detector technologies will provide greater area coverage with better vehicle characterization (e.g., presence, speed, classification, and turning movements), increased reliability, and reduced costs. Advanced control systems with vehicle tracking capabilities are also being developed and tested. These technology trends will be key enabling factors in the widespread deployment of control algorithms that may include neural network and expert system techniques. The net result will be an increased emphasis on tactical type inputs and on requirements for increased accuracy and precision.

2.4.1 Detector Specification Development

Figure 2-8 shows a formal process for development of traffic detector specifications. The first phase requires a detailed up-front systems analysis to properly specify all the subsystems that are part of the IVHS architecture. Among these is the detection subsystem highlighted by Figure 2-8. The critical first step in defining traffic parameter specifications, such as signal processing algorithms, types of output data (count, speed, occupancy, etc.), parameter accuracies, sample interval, and spatial resolution, is the identification of the overall IVHS requirements, shown as inputs to the systems analysis process. These are normally based on a higher level evaluation of system goals and objectives.⁽³⁾

To meet the requirements for a particular traffic management application, a number of subsystem architectures, algorithms, and traffic parameters can be selected to function either singularly, or in combination with one

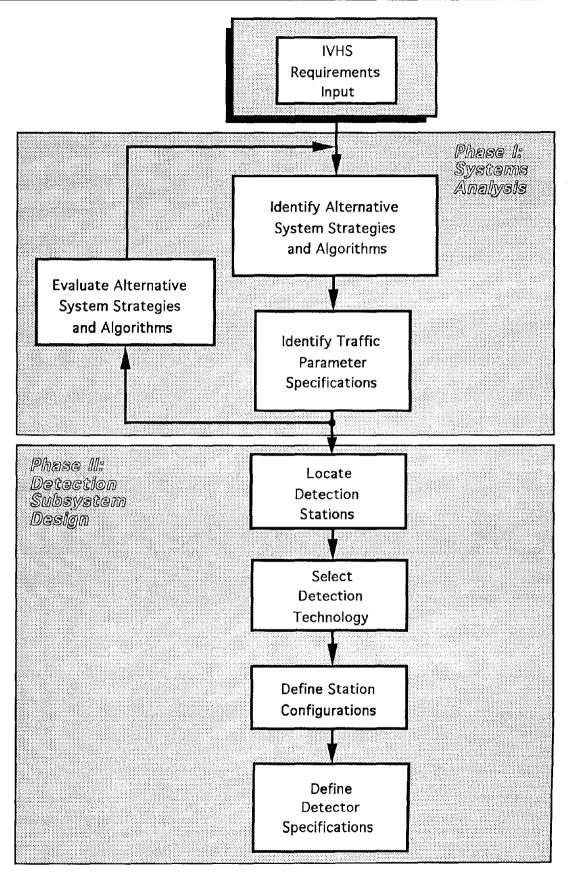


Figure 2-8. IVHS Detector Specification Process

another. The alternatives must then be analyzed and their performance compared with the overall system goals and objectives. The analysis of the alternatives not only requires a knowledge of the basic system requirements, but also a detailed understanding of the system's targeted operating environment and the constraints imposed by the available technologies that are a part of the solution. Knowledge of key technical specialty areas is needed so that they may be applied effectively in the development and implementation of traffic management systems. These specialties include traffic surveillance and control algorithm design, traffic flow theory, statistics and sampling theory, computer technology, communications technology, and detector technology.

Once the systems analysis phase is complete, the detection subsystem design phase can begin. The major components of this phase are location of the detector stations, selection of detector technologies (there may be more than one), definition of station configurations, and definition of detector specifications.

2.4.2 Traffic Parameter Categories

The definition of traffic parameter specifications for IVHS takes into account three categories of parameters: tactical, strategic, and historic. Each suggests different usage of the data by a traffic management application that, in turn, generally dictates a different set of parameter specifications, including data collection time interval, range, and accuracy.

2.4.2.1 Tactical Input Parameters

Tactical parameters are those utilized in tactical decision making. For this discussion, tactical decisions are defined as the expedient decisions made by a control system in response to real-time traffic parameter inputs. Tactical decisions are typically based on rote logic embedded in a predefined algorithm. One example is the real-time adjustment of a traffic adaptive controlled signalized intersection in response to the measured cyclic traffic flow profiles on each approach. Another example is the decision to declare a freeway "incident" condition in response to a mainline lane parameter value exceeding a prescribed threshold. Because tactical decisions are made in quick response to changing real-time traffic variables, tactical parameters are generally collected over short time intervals (usually on the order of a few seconds). They may also be event driven, as, for example, a vehicle detected by a presence detector. Since tactical parameters are collected on these shorter intervals, fewer vehicles are included in each sample. Variation from sample to sample will be exhibited due to the random nature of vehicle arrivals. The limited sample size will usually impose increased accuracy and precision on the measurement of tactical parameters. For example, the measurement of approach speed as an estimate of travel time for vehicles approaching a signalized intersection requires increased accuracy and precision when traffic signal offset decisions are being made, as compared to measuring average approach speeds for strategic background "plan-based" decision making.

2.4.2.2 Strategic Input Parameters

Strategic input parameters support strategic-level decisions. These traffic control and management decisions generally operate at a higher level in the system hierarchy than do tactical decisions. Strategic decisions are typified by the activation of a preplanned management strategy in response to broad indicators of traffic flow conditions.

Strategic-level decisions are often broader in geographic scope than tactical ones and often change the mode of an entire system or a large subsystem. Strategic decisions can be expert system rule-based, as in the Los Angeles Smart Corridor Management System, or algorithm-based, as used in UTCS plan selection. They frequently employ predefined scenarios and operator confirmation and approval processes.

Strategic traffic parameters are usually collected over a period of minutes rather than seconds; as a result, samples are larger. Most currently deployed freeway management and centralized traffic signal control systems use running averages and other filtering techniques to smooth out short-term variations in the traffic stream data. Strategic traffic parameters are often input to maintain onon-line databases of current traffic conditions used by the management systems.

One example of a strategic-level decision process is the selection of an incident management plan in response to a detected incident on a surface street network. When an incident is declared, the strategic decision process might monitor overall network conditions and implement an appropriate control plan overriding or adjusting the tactical-level decision-making process.

Under conditions of light to moderately heavy congestion, adaptive traffic signal network optimization methods, such as SCOOT and SCATS that operate largely at the tacticallevel, provide excellent results.⁽⁴⁻¹⁰⁾ However, in cases of very heavy congestion, such as those caused by an incident where severe blocking of intersections results and natural or controlled route diversion occurs, these tactical-level procedures begin to break down. Strategic-level decision logic is successfully used to solve such problems.

2.4.2.3 Historic Input Parameters

Historic input parameters are those used to maintain or update on-line historic traffic databases. These data bases typically include traffic data collected over periods of 5 minutes or greater and are archived by time of day and day of week, or by time of day and date. The primary purpose of these historic databases is to provide information for offline planning and design operations. However, historic data are also commonly used as inputs to on-line tactical and strategic decision processes. For example, most freeway management systems maintain a file of historic flow-rate data. This file is regularly used on-line as input for predicting future near-term traffic demands. In addition, some UTCS applications use historic flow-rate data as input to on-line detector failure monitoring logic.

2.4.3 Matching Traffic Parameter Needs to Selected IVHS Services

Individual traffic parameters and accuracies required for a given application are specified by the algorithms, strategies, and operating procedures used to implement that application. A list of criteria which can help select traffic parameters for use in a particular IVHS application includes:

- Convenience of parameter measurement;
- Amenability of resultant data to real-time processing;
- Existence of significant differences in parameter values within the range of traffic conditions that must be monitored.

Traffic parameters are identified below for signalized intersection control, freeway incident management, and freeway metering. Parameter range, collection interval, and accuracy specifications for these services are given in Tables 2-1 through 2-3. Unfortunately, the search of the available literature uncovered little universally applicable information regarding the required accuracy of traffic parameters for these or other IVHS services. Consequently, the specifications are based on: (1) the data that were located, (2) operating experience, and (3) sensitivity analyses developed during the study or found in the literature. The estimates are considered representative of those for the selected traffic parameters and are consistent with the general requirements of the particular application. However, a detailed analysis is recommended to derive parameter specifications for a specific system design or for IVHS services not covered. Such analyses are outside the scope of this report.

2.4.4 Signalized Intersection Control

Table 2-1 gives selected traffic parameter specifications for advanced signalized intersection control applications. Parameters are listed for the tactical, strategic, and historic categories. Tactical parameters include those relating to flow, speed, and occupancy measurements. For advanced signal control systems, typical flow-related parameters may include cyclically collected intersection approach flow rates, flow profile data, and turning volumes.

Tactical information related to intersection control is often collected on a cyclic basis and normalized to hourly rates. This minimizes the short-term parameter fluctuations caused

Tactical Parameters					
Parameter	Units	Range	Collection Interval	Allowable Error	
Approach Flow Profiles	vehicles	0-3	1 second	± 2 veh/signal cycle	
Turning Movement Vol	vehicles	0-200	1 cycle	± 2 veh/signal cycle	
Average Link Travel Time	seconds	0-240	1 cycle	± 2 seconds	
Average Approach Speed	mi/h	0-100	1 cycle	± 2 mi/h (0-55 mi/h)	
Queue Length	vehicles/lane	0-100	1 second	± 2 vehicles	
Demand Presence	Yes/No	-	10 Hz (minimum)	No missed vehicles	
Average Approach Delay	s/veh	0-240	1 cycle ± 2 seconds		
Approach Stops	stops	0-200	1 cycle	± 5% of stops	

Table 2-1. Signalized Intersection Control Traffic Parameter Specifications

Strategic Parameters

Parameter	TAP I LINITS (KONDA)		Collection Interval	Allowable Error
Flow Rate (Volume)	veh/h/lane	0-2500	5 min	± 2.5% @ 500 veh/h/lane
Occupancy	%/lane	0-100	5 min	± 5%
Average Speed	mi/h	0-100	5 min	± 2 mi/h (0-55 mi/h)
Average Delay	s/veh	0-240	5 min ± 2.5 seco	
Percent Stops	%	0-100	5 min (approx)	± 5%

Table 2-1. Signalized Intersection Control Traffic Parameter Specifications (continued)

Parameter	Units Range		Collection Interval	Allowable Error
Turning Movement Vol	veh/movement	0-2000	15 min	± 2.5% @ 500 veh/h
Flow Rate (volume)	veh/h/lane	0-2500	15 min	± 2.5% @ 500 veh/h
Occupancy	%	0-100	15 min	± 5%
Average Speed	mi/h	0-100	15 min	± 2 mi/h (0-55 mi/h)

Historic Parameters

1 mi/h = 1.61 km/h

by data collection intervals being inconsistent with whole multiples of the cycle length. Fluctuations can also be minimized by maintaining weighted running averages and other smoothing techniques.⁽¹¹⁾

Speed-based parameters are also of benefit to advanced signal control algorithms. From a tactical viewpoint, vehicle approach speeds can be used to estimate link travel time. However, speed accuracy is critical here because a small difference in measured speed can have a significant effect on calculated travel time. (This depends, of course, on the length of the approach section.) An error in calculated travel time of only a few seconds can have an adverse effect on operations if travel time is used as the basis for offset calculations. Another useful speed measure is the distribution of approaching vehicle speeds. The standard deviation of the measured speed can be an important input to the modeling of platoon dispersion from one signalized intersection to another.

Occupancy-based measures such as queue length, delay, and percent of stops collected on a cycle basis can also be tactical inputs to advanced signal control algorithms. Data from traditional inductive loop traffic detectors on an approach to a signalized intersection provide estimates for these parameters using an input-output model that receives the current green state of the traffic signal. These parameters provide feedback on the effectiveness of the current traffic control operation. Stop bar demand presence and queue overflow presence are two other occupancy-related parameters used by some signal control algorithms. The strategic-level parameters most often used by intersection control logic include smoothed volume. occupancy, and average speed indicators. Some systems also tabulate average approach delay and percent of vehicles stopping or total stops by approach. Strategic data are normally kept as smoothed values (weighted running averages) with collection intervals ranging from 1 to 5 minutes. In most instances, the purpose of strategic volume data collection is to tabulate current demands for network links. Similarly, occupancy parameters are often used to monitor the extent of current congestion on the roadway network. As discussed in a previous example,

strategic traffic parameters can be useful for implementing incident management strategies designed for surface-street applications.

Historic parameters used in intersection signal control applications include link-based volume, occupancy, and speed. Turning movement and O-D pattern information are also important as inputs to demand prediction algorithms. These data are currently available from manual studies.

2.4.5 Freeway Incident Management

Table 2-2 identifies selected parameter specifications for freeway incident management. Tactical parameters serve as key inputs to automated incident detection algorithms. Basic tactical inputs include lane-specific mainline flow rate, occupancy, and average speed. Other tactical parameters derived from these basic parameters include spatial occupancy differential and spatial average speed differential. For incident detection logic based on California-type algorithms, the spatial differential parameters provide measures of the difference in lane-specific values of occupancy or speed between successive upstream and downstream detection stations for a given direction of travel. These types of algorithms rely on the identification of an incident between mainline stations from significant differences in the measured values of parameters between the two stations. Another algorithm uses the standard deviation of vehicle speed to predict when freeways are reaching capacity and to initiate strategies such as speed limit reduction or metering ⁽¹²⁾

Strategic-level parameters are important as traffic monitoring inputs to the overall incident management process. Strategic-level parameters include mainline lane-specific flow rate, occupancy, average speeds, and freeway on-ramp and off-ramp flows. Alternative route data are also collected when applicable. As a minimum, flow rates and link speed or travel times should be maintained for significant alternate routes in the system. Strategic parameters are generally maintained on-line as 5-minute running averages.

Table 2-2. Freeway Incident Detection and Management Traffic ParameterSpecifications

Parameter	Units	Range	Collection Interval	Allowable Error	
Mainline Flow Rate	veh/h/lane	0-2500	20 s	± 2.5% @ 500 veh/h/lane	
Mainline Occupancy	% (by lane)	0-100	20 s	± 1%	
Mainline Speed	mi/h (by lane)	0-80	20 s	± 1 mi/h	
Mainline Travel Time	min		20 s	± 5%	

Tactical Parameters (Detection)

Strategic Parameters (Incident Management)

Parameter	Units	Range	Collection Interval	Allowable Error
Mainline Flow Rate	veh/h/lane	0-2500	5 min	± 2.5% @ 500 veh/h
Mainline Occupancy	%	0-100	5 min	± 2%
Mainline Speed	mi/h	0-80	5 min	± 1 mi/h
On-Ramp Flow Rate	veh/h/lane	0-1800	5 min	± 2.5% @ 500 veh/h/lane
Off-Ramp Flow Rate	veh/h/lane	0-1800	5 min	± 2.5% @ 500 veh/h/lane
Link Travel Time	seconds	_	5 min	± 5%
Current O-D Patterns	veh/h	-	5 min	± 5%

Table 2-2. Freeway Incident Detection and Management Traffic Parameter Specifications (continued)

Parameter	Units	Range	Collection Interval	Allowable Error
Mainline Flow Rate	veh/h/lane	0-2500	15 min or 1 hour	± 2.5% @ 500 veh/h/lane
Mainline Occupancy	%	0-100	15 min or 1 hour ± 2%	
Mainline Speed	mi/h	0-80	15 min or 1 hour	± 1 mi/h
On-Ramp Flow Rate	veh/h	0-1800	15 min or 1 hour	± 2.5% @ 500 veh/h
Off-Ramp Flow Rate	veh/h	0-1800	15 min or 1 hour	± 2.5% @ 500 veh/h
Link Travel Times	seconds	-	15 min or 1 hour	± 5%
Current O-D Patterns	veh/h	-	15 min or 1 hour	± 5%

Historic Parameters (Planning)

1 mi/h = 1.61 km/h

As with intersection control, historic parameters play a major role in many, if not most, freeway incident management systems. Parameters which parallel the strategic parameters described above are typically stored as historic files. Data are often maintained for a particular time of day and day of week for each detection station. New data are smoothed with data for the corresponding time interval of the previous week. In this way, files are maintained that represent typical time of day and day of week conditions on the highway network. These files are used for on-line demand estimation and are often archived for planning and design purposes. Historic parameters are typically collected in 15-minute intervals, although 5-minute and 1-hour intervals are also used. Some systems, such as the Burlington Skyway in Ontario, Canada and the Denver, CO Freeway Traffic Management System, store 5-minute values, but can derive 15-minute and 1-hour values upon request.

2.4.6 Freeway Metering Control

Table 2-3 contains selected parameter specifications for freeway metering control. Tactical parameters for this application include queue length, demand presence, passage count, approach volume, and queue overflow presence. When a queue length is used in current applications, it is typically estimated based on approach and passage volumes or is derived from data produced by one or more presence detectors on the approach to the metering signal. Other tactical inputs to the metering control algorithm include mainline occupancy, speed, and flow rate as described under freeway incident management.

Strategic parameters for metering include mainline and metered traffic flow rates. Mainline values are generally lane-specific and include volume, occupancy, and average speeds. Derived average freeway speeds based on volume and occupancy data from a single inductive loop detector will give reasonable results for strategic decisions because collection intervals are typically 5 minutes or longer and smoothing procedures are normally used. Historic parameters of value in freeway metering include those already identified as strategic plus on-ramp and off-ramp flow rates. The collection interval for historic data is lengthened to 15 minutes or 1 hour, to correspond to the intervals used with freeway incident detection and management.

2.4.7 Future Traffic Parameter Specifications

It is difficult to calculate the accuracy required of traffic parameters for applications where algorithms do not exist or where improved algorithms are being sought. Nonetheless, one can speculate that increased measurement accuracy will be required as advanced algorithms are deployed. These advanced algorithms will place a heavier reliance on tactical-type inputs for real-time control decisions. Future algorithms will not likely require new traffic parameters sets per se. Advances in detection technology will decrease data collection costs and, in some cases, will allow parameters such as queue lengths and origin-destination patterns to be more directly measured or estimated in real time.

Two technologies that will enable advanced algorithms to be deployed are imaging detectors and probe vehicle sampling, including AVI. Imaging detectors that track individual vehicles through a traffic scene have the advantage of monitoring actual vehicle traffic movements as they happen, thus allowing algorithms to be more demand responsive. Furthermore, stopped vehicle counts and standing queues can be directly monitored with imaging methods. Since queue buildup directly impacts delay, number of stops, fuel consumption, and emissions output, improved data and, therefore, control optimization will be possible.

AVI readers and other vehicle probe-based detection technologies are now being operationally tested. These have the potential to statistically monitor travel movements through a roadway network and provide automated collection of O-D data and travel time samples on a link-specific basis. Up-to-the-minute O-D data will enable improved incident and congestion management

Table 2-3. Freeway Metering Control Traffic Parameter Specifications

Parameter	Units	Range	Collection Interval	Allowable Error
Ramp Demand	Yes/No		0.1 s	0% (No missed vehicles)
Ramp Passage	Yes/No	-	0.1 s	0% (No missed vehicles)
Ramp Queue Length	vehicles	0-40	20 s	± 1 vehicle
Mainline Occupancy	%	0-100	20 s	± 2%
Mainline Flow Rate	veh/h/lane	0-2500	20 s	± 2.5% @ 500 veh/h/lane
Mainline Speed	mi/h	0-80	20 s	± 5 mi/h

Tactical Parameters (Local Responsive Control)

Strategic Parameters (Central Control)

Parameter	Units	Range	Collection Interval	Allowable Error
Mainline Occupancy	%	0-100	5 min ± 2%	
Mainline Flow Rate	veh/h/lane	0-2500	5 min ± 2.5% 0 veh/h/la	
Mainline Speed	mi/h	0-80	5 min	± 5 mi/h

Historic Parameters (Pretimed Operations)

Parameter	Units	Range	Collection Interval	Allowable Error
Mainline Occupancy	%	0-100	15 min or 1 hour	± 2%
Mainline Flow Rate	veh/h/lane	0-2500	15 min or 1 hour	± 2.5% @ 500 veh/h/lane
Mainline Speed	mi/h	0-80	15 min or 1 hour	± 5 mi/h
On-Ramp Flow Rate	veh/h	0-1800	15 min or 1 hour	± 2.5% @ 500 veh/h
Off-Ramp Flow Rate	veh/h	0-1800	15 min or 1 hour	± 2.5% @ 500 veh/h

1 mi/h = 1.61 km/h

strategies. The availability of link travel time data in real time should significantly improve the performance of automated

incident detection algorithms by reducing detection times and false alarm rates.

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3. TASK B SUMMARY

SELECT FIELD SITES FOR DETECTOR FIELD TESTS

3.1 TEST SITE SELECTION AND CRITERIA

Freeway and surface-street field test sites were selected in Minneapolis, Minnesota; Orlando, Florida; and Phoenix and Tucson, Arizona. In Minnesota and Florida, both types of sites are in the same cities. In Arizona, the freeway site is located in Phoenix and the surface-street site in Tucson. By choosing test sites in different climatic regions of the country, a variety of environmental test conditions were encountered as described by Table 3-1.

Test sites were selected to meet the following criteria:

- Mounting structures available for installing above-the-road detectors over the central portion of the lanes at heights prescribed by the manufacturers;
- Mounting available or easily put in place on the side of the road to install side-looking detectors;
- Power available for the detectors under test;
- Communications in place, or readily installed, for transmitting traffic data and video to a central processing facility (traffic operations center or traffic management center) or another environmentally controlled data collection location;
- Inductive loop detectors in place or capable of being installed;
- Traffic flows that range from light to heavy during a 24-hour period;
- Weather-protected roadside controllers available in which to install detector amplifiers and other signal processing equipment.

3.2 MINNESOTA TEST SITES

Seven potential field test sites were visited in Minneapolis and St. Paul, four suitable for monitoring traffic flows on freeways and three for surface-street arterials. The detector installation and intersection plan-view drawings for the selected Minneapolis sites are contained in Appendix E. The Minneapolis freeway test site was located on I-394 at the Penn Avenue crossing. I-394 is an east-west freeway linking the western suburbs with Minneapolis and is built along the U.S. Highway 12 right-of-way. The freeway has two unrestricted lanes in each direction at this location, as well as two reversible highoccupancy vehicle (HOV) lanes that are used during morning and evening rush hours. The HOV lanes are located between the normal eastbound and westbound lanes. Inductive loop detectors are installed at 0.5-mi (0.8-km) spacing to monitor traffic on I-394. The bridge crossing at Penn Avenue has a changeable message sign (facing westbound traffic) and various exit signs installed.

The eastbound lanes and the HOV lane closest to the eastbound lanes were used as the test bed. The photograph in Figure 3-1 was taken from the Penn Avenue Bridge looking west at eastbound traffic into Minneapolis. The photograph in Figure 3-2 shows the area that was monitored by the detectors on the east side of the bridge. The above-ground detectors were installed to observe downstream traffic moving away from the detectors into Minneapolis, as there is no obstruction on the east side of the bridge over the eastbound lanes. Similarly, detectors were mounted over the HOV lanes to monitor the westbound traffic out of Minneapolis during the afternoon and evening rush hours. Speed-measuring inductive loop detector pairs were installed in the three monitored lanes to obtain vehicle count and speed data to compare with those from radar, infrared, ultrasonic, acoustic, and video image processor (VIP) detector technologies. A camera was placed on the Penn Avenue bridge structure along with the overhead detectors to

	Minne	sota	Florida		Arizona	
Test Condition	Freeway	Surface Street	Freeway	Surface Street	Freeway	Surface Street
Times of Day						
Daylight	x	x	x	x	x	x
Dawn	x	x	x	x	x	x
Dusk	x	x	X	x	x	x
Night	x	x	x	x	x	x
Vehicles			1			
Passenger cars	x	x	x	x l	x	x
Trucks	x	x	X	x	x	x
Semi-trailers	x	x	x	x	x	x
Buses	x	x	x	x	x	x
Emergency vehicles	x	x	x	x	x	x
Motorcycles	x	x	x	x	x	x
Bicycles	Ŷ	x		x	Â	x
Road equipment	x	x	x	x	x	x
Traffic patterns	- <u>^</u>	<u>^</u>	<u>^</u>	<u>^</u>	^^	^
Multiple lanes	x	x	x	x	x	x
Normal traffic	x	x	x	x	x	x
Turning vehicles	^	x	Î î	x	Â	x
Congestion	x	x	x	x	x	x
Long queues*	x	x	x	x	x	x
Stopped vehicles	x	x	x	x	x	x
Adjacent-lane vehicles	x	x	x	x	x	x
Lane straddlers	x	x	Â	x	X	x
Weather	<u> </u>	<u>^</u>	<u> </u>	<u>^</u>	<u>^</u>	^
Clear					~	v
Overcast	X	X	X	X	X	X
	x	X	X	X	X	x
Fog			X	X		v
Abrupt lighting changes			X	X	X	x
(luminaries, lightning)			8			
Cold temperature extremes	×	X				
Hot temperature extremes	l		X	X	X	x
Heavy snow	X	X				
Heavy rain			×	x	X	x
Smog**					X	
Haze	_		X	X		
Artifacts						
Shadows	х	х	x	x	X	х
Sun glare	X	X	X	x	X .	х
Electromagnetic						
interference	X	X	X	X	X	X
Wind sway and vibration	Х	X	X	X	X	х

Table 3-1. Test Conditions Satisfied at Proposed Test Locations

* Long queues: For freeway application, on-ramps and mainline during congested hours. For surface-street application, at traffic signals.

** Experienced also during the laboratory tests of available detectors conducted in Los Angeles during Summer 1992.

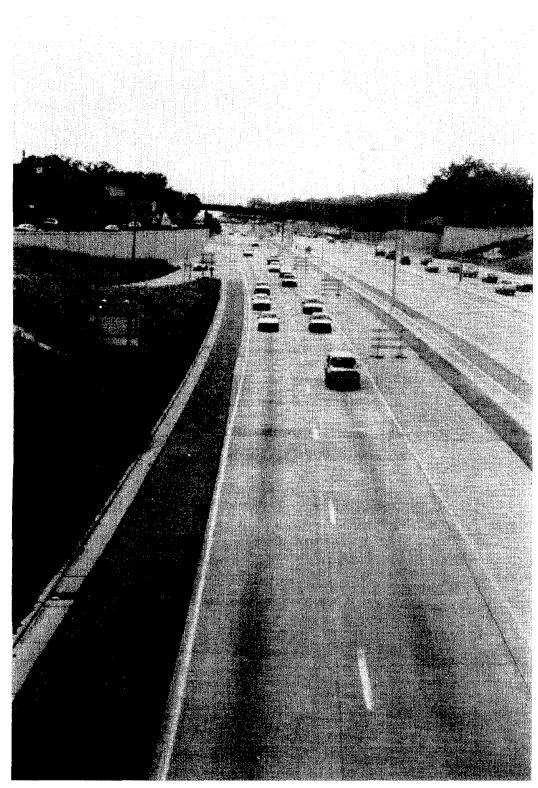


Figure 3-1. I-394 Freeway Test Location Photograph Looking at Eastbound Traffic into Minneapolis Approaching Penn Avenue

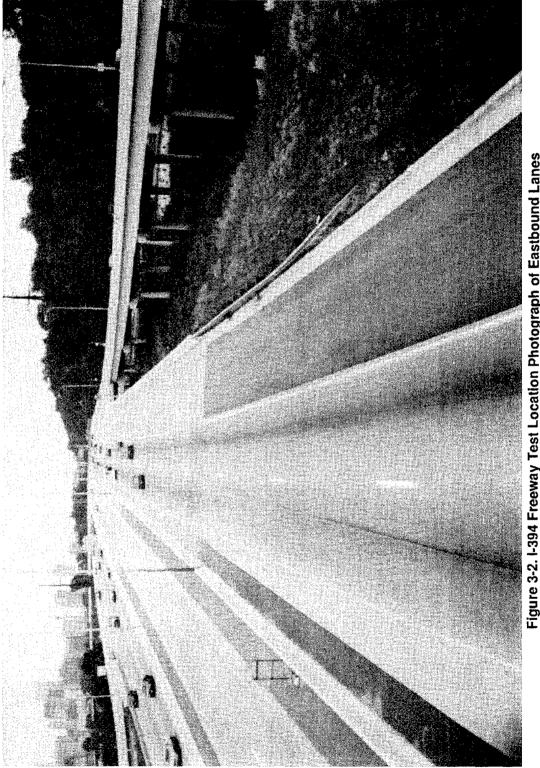


Figure 3-2. I-394 Freeway Test Location Photograph of Eastbound Lanes on East Side of Penn Avenue Bridge as Seen by Detectors obtain imagery of the traffic flow for ground truth and to serve as an input to the VIPs.

A trailer located on the southeast corner of the Penn Avenue/I-394 intersection was used for recording the outputs of the detectors. Type 170 controllers are used by the Minnesota Department of Transportation (MnDOT).

The selected Minneapolis surface-street site was located on Olson Highway (TH-55) between Lyndale Avenue North and Oak Lake Avenue just east of the I-94 overpass. A sign bridge spans the westbound lanes of TH-55 as shown in Figures 3-3 and 3-4. Detectors were mounted on the rear of the sign to monitor downstream traffic.

Westbound Olson Memorial Highway has three through-traffic lanes and a left and right turn pocket as it approaches Lyndale Avenue as shown in the figures. Fifty-foot (15.2-m) light poles were also available to install detectors for side-looking configurations. A set of single loops were already installed for signal control. The city installed a second loop in each lane to measure vehicle speed during the tests. National Electronic Manufacturers Association (NEMA) controllers are used by the City of Minneapolis.

A trailer located on the south side of Olson Highway was used for recording the outputs of the detectors.

3.3 FLORIDA TEST SITES

Several freeway test sites along Interstate 4 were explored in the Orlando area. The I-4 and SR 436 intersection in Altamonte Springs, north of Orlando, was selected because it accommodated both freeway and surface-street data acquisition and, thus, potentially minimized the setup time. It has an excellent alignment of the overpass with respect to the interstate for mounting the detectors. The detector installation and SR 436 overpass construction plans are contained in Appendix I.

The freeway contains three lanes in both the east and west directions at this location, with the innermost lanes reserved for car pools during peak traffic hours. The SR 436 bridge provides a mounting structure for the detectors overlooking the freeway. The three lanes of I-4 westbound traffic into Orlando, shown in Figure 3-5, were monitored from this vantage point where data from upstream (approaching) vehicles were acquired. A camera was mounted directly over the middle of the monitored freeway lanes to obtain ground truth of the freeway traffic and imagery for the VIPs. Double-loop inductive detectors were installed in all three westbound lanes to measure vehicle count and speed.

The westbound SR 436 surface-street test location, shown in Figure 3-6, has three through lanes and two left-turn lanes that lead to an entrance ramp for I-4 West toward Orlando. The sign bridge for mounting the overhead detectors is located directly over the freeway median. The signal controller cabinet is located on the Northwest corner at the end of the I-4 West off-ramp for SR 436. Double-loop inductive detectors were installed on the SR 436 through lanes to measure vehicle count and speed. A camera was mounted on the pipe tree over the middle lane to view the stop bar and traffic moving away from the overhead detectors.

3.4 ARIZONA TEST SITES

Two freeway sites were visited in Phoenix. The selected test site location, shown in Figures 3-7 and 3-8, is the east-west stretch of I-10 called the Papago Freeway near Thirteenth Street, just east of the tunnel.

There are three mainline westbound lanes and one high occupancy vehicle lane as shown in the figures. A changeable message sign hangs over lane 3 (the rightmost lane). The overhead detectors were mounted directly on the sign bridge structure without using the pipe trees. This was the only test location where the pipe trees were not used. Figure 3-9 shows the build plan for the freeway at the test site location. Double-loop speed measuring inductive detectors were installed in the three mainline lanes to assist in the technology evaluation.

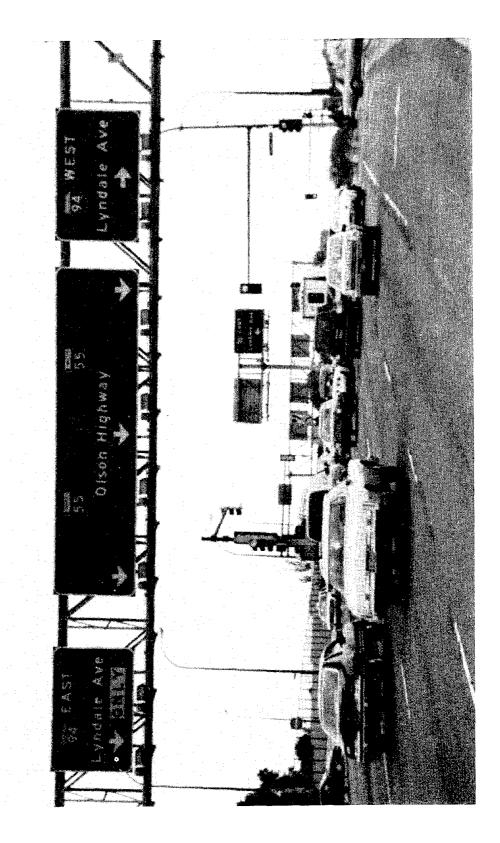


Figure 3-3. Olson Memorial Highway Surface Street Test Location Photograph of Westbound Traffic Lanes – Front of Sign Bridge

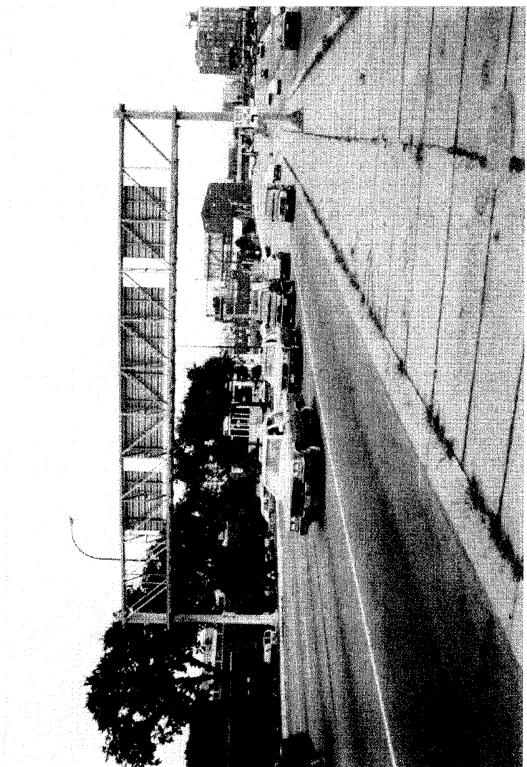


Figure 3-4. Olson Memorial Highway Surface Street Test Location Photograph of Westbound Traffic Lanes – Back of Sign Bridge

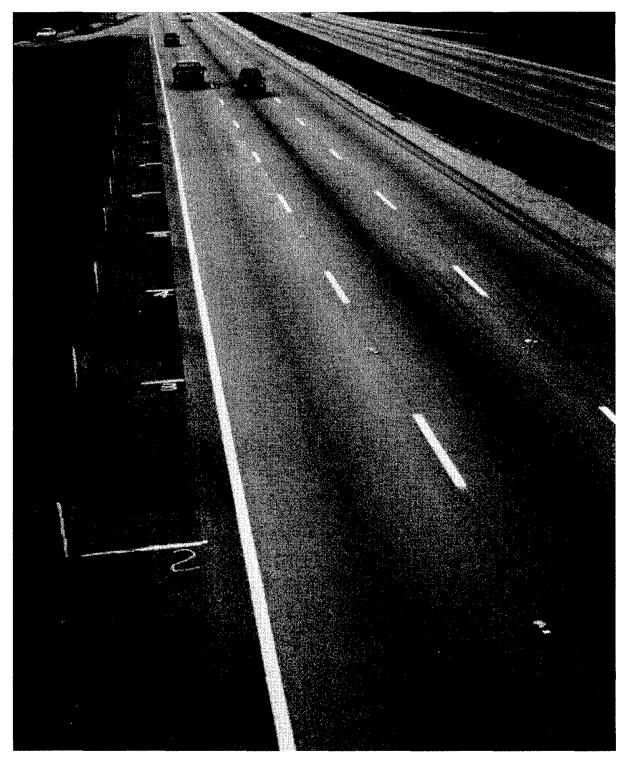
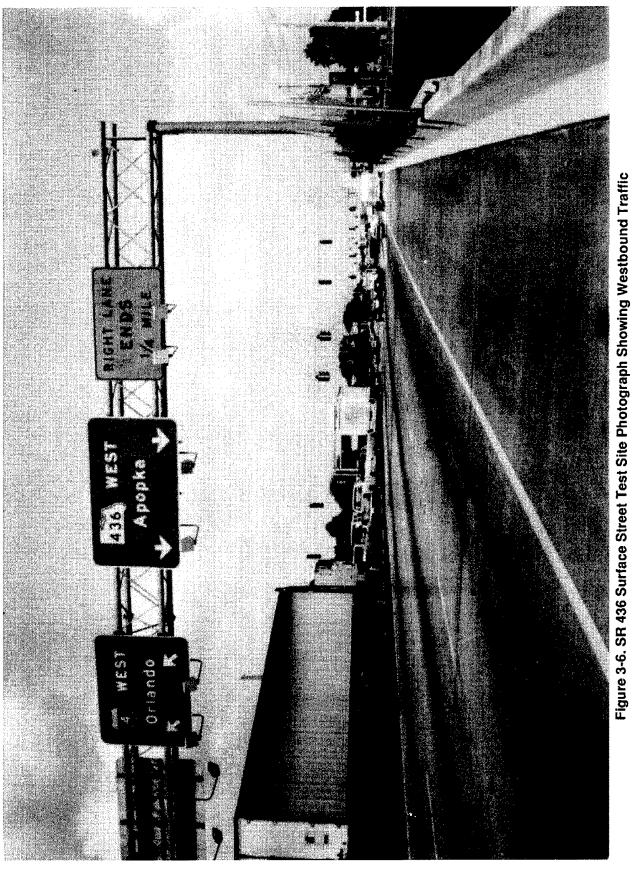
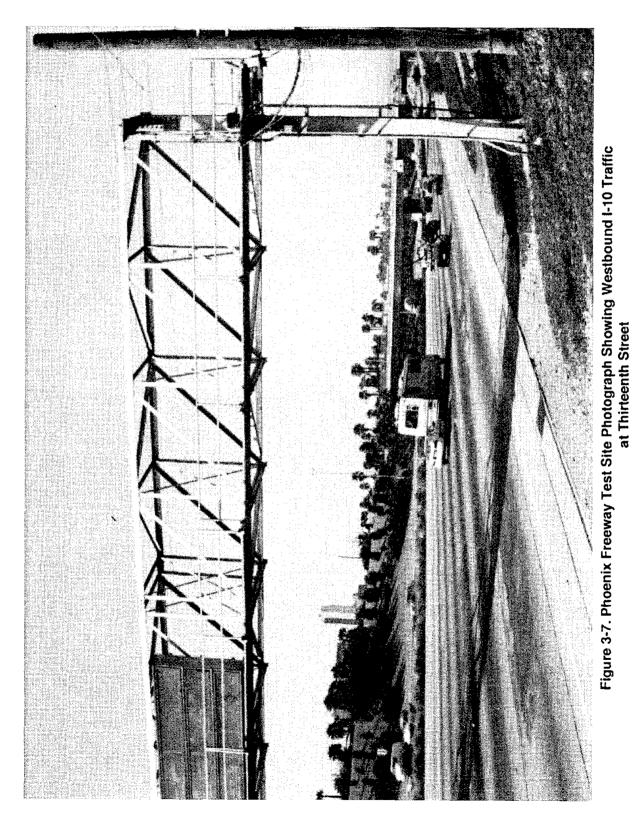


Figure 3-5. I-4 at SR 436 Freeway Test Site Photograph Showing Traffic on I-4 Westbound into Orlando





3-10



Figure 3-8. Phoenix Freeway Test Site Photograph Showing Westbound I-10 Traffic Leaving Deck Tunnel and Heading Toward Thirteenth Street

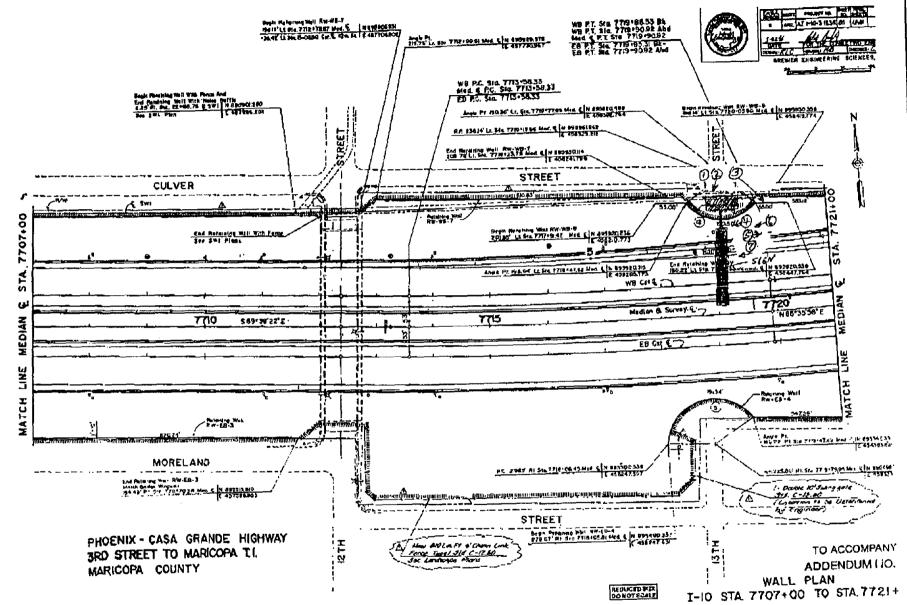


Figure 3-9. Plan-View Drawing for I-10 Freeway Near Thirteenth Street Showing Location of Sign Bridge

3-12

Six surface-street arterial test sites were visited in Tucson. The selected site was along Oracle Road at the intersection with Auto Mall Drive and across the street from the largest shopping mall in Tucson. Three lanes in each direction support north-south traffic. According to the City of Tucson, the traffic is well funneled into these lanes by the stoplight on the north side of the intersection. The overhead detectors were mounted on pipe trees and were supported by the signal light mast arm that controls southbound traffic as shown in the southbound view in Figure 3-10. Oncoming traffic southbound on Oracle Road is shown in Figure 3-11.

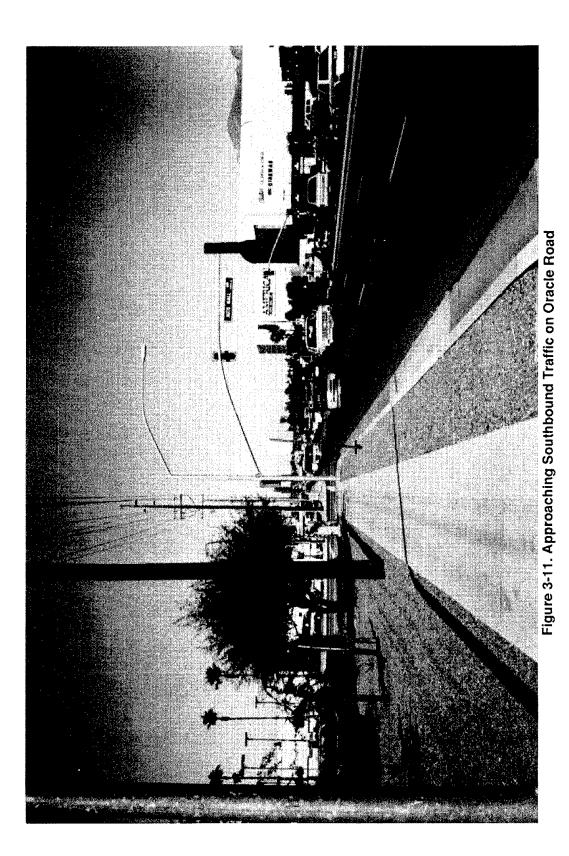
Double 6-ft by 6-ft (1.8-m by 1.8-m) rectangular loops were installed in the curb and center lanes, round loops in the curb lane,

and pairs of microloop detectors in the curb and center lanes in order that these types of loop data may be compared against one another, as well as against the overhead detector data. A trailer situated on the southwest corner of the intersection housed the data recording and analysis equipment.

The city-owned controller cabinet was used to supply the green phase signal for the southbound Oracle Road traffic. Temperatures in the cabinet can reach 170°F (77°C) without a fan during hot weather. The City of Tucson requires equipment to be specified for 80°C (176°F) operation. 115 VAC power came from the pole that supports the traffic signal mast arm.



Figure 3-10. Tucson Surface Street Test Site Photograph Showing Southbound Lanes on Oracle Boulevard



4. TASK D SUMMARY

SELECT AND OBTAIN VEHICLE DETECTORS

4.1 SELECTION CRITERIA

The criteria used to select vehicle detectors for use in the laboratory tests of Task E and the field tests of Task G were:

- Availability,
- Demonstrated capability,
- Compatibility with controllers in place at the field test locations,
- Representative of current technology, and
- Vendor support.

Availability implies that one or more units would be supplied by the vendor in time to support the field tests beginning in October 1992. This criterion was tightened to include delivery to support the laboratory tests scheduled to begin in May 1992 when possible.

Demonstrated capability implies that the detectors have either been tested by a municipality or Department of Transportation (DOT), or have undergone substantial testing by the vendor.

For compatibility with the controllers used at the test sites, an appropriate interface between the detector or amplifier and the controller must exist, or the interface must be capable of being easily put in place by personnel working for the DOTs.

To be representative of current technologies, a detector must contain design features that allow it to respond to moving and/or stationary vehicles of different sizes and colors; operate in light and heavy traffic flows under most weather conditions; be capable of day and night operation; and be immune to artifacts such as shadows and glint, and false detections from shoulder or adjacent lane objects and vehicles. The effects of these scenarios on each technology is different, as addressed in Section 5. Vendor support implies cooperation in supplying requested data and operating and mounting instructions, and in resolving problems that arise during the tests.

These criteria were applied to vehicle detectors representative of the following technologies:

- Ultrasonic,
- · Infrared (Passive and Active),
- Microwave,
- · Video Image Processing,
- · Acoustic Arrays,
- Inductive Loop, and
- Magnetic.

4.2 SELECTION PROCESS

Two general paths for selecting detectors for the field tests were considered. The first is an ideal path shown in the upper part of Figure 4-1. It is suitable if present-day detectors meet the IVHS requirements of the future as specified in Section 2.

The ideal detector selection path begins by establishing user requirements through discussions with city, county, state, regional, and federal transportation agencies and other major interested parties such as equipment manufacturers. These requirements are then analyzed and consolidated into categories that represent the IVHS applications and services surfaced through the discussions. Detectors that meet the requirements undergo further screening in laboratory tests, checking for operational compatibility with field site support services and anticipated traffic conditions (e.g., mounting configuration, communications, and weather and traffic volume environments), and verifying noninterference with the operation of other detectors. Finally, those detectors that pass the screen are chosen for further evaluation in the field tests.

In our case, it was found that none of the available detectors would meet all of the requirements developed in Section 2. Therefore, the detector selection path shown in the lower part of Figure 4-1 was used. Here the capabilities of currently available detectors are determined from the Federal Highway Administration (FHWA), user evaluations, vendors, conferences, journals, and other personal contacts. Instead of eliminating detectors that do not pass all IVHS requirements, all detectors are allowed to enter the screening process. Those that perform to the vendor's specifications are selected for further evaluation in the field tests.

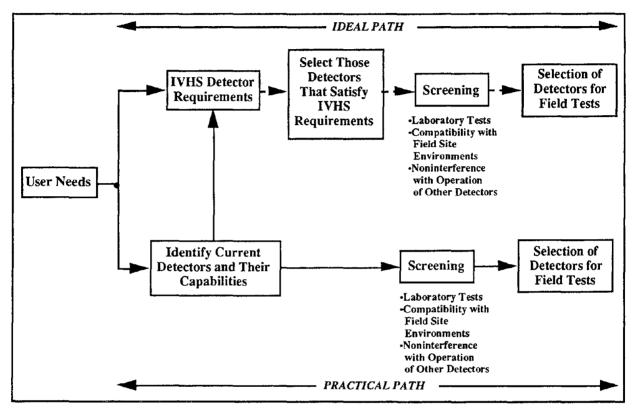


Figure 4-1. Detector Selection Processes

In applying the process just described, municipalities such as the City of Los Angeles; DOTs in Minnesota, Florida, Arizona, and California; and other user organizations such as the Enterprise Group were contacted to gather information about potential manufacturers and test results on their products. These contacts sometimes led to studies that evaluated detector performance, such as those conducted by the Institute of Transportation Studies at Berkeley and the Transportation Research Group at the California Polytechnic State University at San Luis Obispo.^(1,2) As the Detection Technology for IVHS Program progressed, other manufacturers were made known to the principal investigator by the Contracting Officer's Technical Representative (COTR) and personnel within Hughes Transportation Management Systems. Still other sources of detectors were gathered from reviews of industry journals, such as those published by the Institute of Transportation Engineers (ITE), and from attendance at conferences sponsored by the Transportation Research Board (TRB), IVHS America, American Society for Testing and Materials (ASTM), and ITE. Manufacturers also contacted the principal investigator at technical meetings and exhibits where they were present.

Lists of detector models and specifications by technology are shown in Tables 4-1 through 4-8 for above-the-road and in-ground

Detector	Detectable Objects	Transmit Frequency	I KAAM-I	Speed Measure- ment Range	Speed Measure- ment Accuracy	Detection Range	Min Vehicle Sepa- ration	Peak Output	Pulse Repetition Period (T ₀)	Pulse Width (Tp)	Signal Hold Time (T _h)
Sumitomo Vehicle Speed Detector SDU-200	Subcompact cars and larger	25.5 KHz ± 1 KHz	15 deg	4-120 km/h (2.5-75 mph)	± 10%	8 m (26 ft)	< 10 m (33 ft)	14 ± 3 V _{pp}	Not Applicable	Not Applicable	Not Applicable
Sumitomo Vehicle Detector SDU-300	Subcompact cars and larger	26 KHz ± 1 KHz	≈13 deg	Not Applicable	Not Applicable	1.5 to 8 m (4.9 to 26 ft)	1.2 m + vehicle speed in m/sec x 0.15 sec	<10 watts	33 ± 3 msec	2 ± 0.5 msec	115 msec ± 10%
Microwave Sensors TC-30C	Pedestrians, bicycles, and all motorized vehicles		≈20 deg	Not Applicable	Not Applicable	7 m (23 ft)	1.5 m (5 ft) at 70 mph	Transmitted acoustic energy is 110 dB at 20 μpascals at 1 m	100 msec	0.02 msec	0.25 to 10 sec

Table 4-1. Specifications of Ultrasonic Vehicle Detectors Evaluated

Detector	Instan- taneous Field of View (FOV)	Vehicle Classi- fication	Speed Measure- ment Range	Detection Range	Re- sponse Time	Flow	Presence Hold Time
Schwartz Electro- Optics 780D1000	 2 beams, each 1 mrad (El) by 9.5 deg (Az) Beam separation in El = 10 d eg 	Auto or truck	0 to > 80 mi/h with ±1 mi/h accuracy up to 70 mi/h	1.5 - 15 m (5 - 49 ft)	≈10 ms	0 to >1800 veh/h	For as long as vehicle is in FOV of detector

Table 4-2. Specifications of Active Infrared Detectors Evaluated

1 mi/h = 1.61 km/h

Table 4-3. Specifications of Passive Infrared Detectors Evaluat	Table	Specification	4-3.	0	Passive	Infrared	Detectors	Evaluate	d
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Detector	Detectable Objects	Detection Range and Footprint	Response Time	Maximum Speed at Which Vehicles Are Counted	Hold Time
Eltec 842*	Bicycle and any motorized vehicle	6.4 - 16 m (21 - 54 ft) slant range with corres- ponding foot- prints (El x Az) of 93.2 x 99.8 cm to 237.0 x 490.5 cm (36.7 x 39.3 in to 93.3 x 193.1 in)	<250 ms	>100 mi/h (160.9 km/h)	True presence detector with 6 minutes maximum hold time for vehicles in FOV of detector
Eltec 833*	Bicycle and any motorized vehicle	5 - 30 m (16 - 98 ft) down range with corres- ponding foot- print diameters of 0.4 to 2.2 m (1.3 to 7.2 ft)	50 to 100 ms	85 mi/h (136.8 km/h)	Pulse-type counting operation with count held for up to 4 seconds

* Photon-sensitive element is made of lithium tantalate (a type of pyroelectric material). Spectral response used is from 8 to 12 micrometers.

Detector	Detectable Objects	Transmit Frequency	Power Output	Polarization (Transmit & Receive)	3dB Beam- width	Speed Measurement Range	Speed Measurement Accuracy	Detection Range	Response Time
Microwave Sensors TC-20	Mopeds and larger traveling at speeds > 2 mph at signal- controlled intersections	10.525 GHz	-18 dBm (56,234 μV/m at 30 m distance)	Horizontal	16 deg Az, 15 deg El (Ant Gain = 16.4 dB)	Not Applicable	Not Applicable	1-30 m (3-100 ft)	0.165 sec
Microwave Sensors TC-26	Mopeds and larger traveling at speeds > 3 mph on city arterials and freeways	10.525 GHz	-18 dBm (56,234 μV/m at 30 m distance)	Horizontal	16 deg Az, 15 deg El (Ant Gain = 16.4 dB)	5-106 km/h (3-66 mph)	 Speed is segre- gated into 1 of 5 bins which together cover the range 5 to 106+ km/h Speed is also available in terms of Doppler fre- quency shift to within ± 1 mph 	Up to 61 m (200 ft) for autos; up to 107 m (350 ft) for trucks	0.165 sec
Whelen TDN-30	Any licensed motor vehicle separated by one car length and traveling at speeds > 5 mph	10.525 GHz	< 2.5 mW/cm ²	Horizontal	7 deg (1st sidelobe at -10 dB)	8 - 137 km/h (5 - 85 mph)	Within ± 2 mph at all speeds	Designed to project an ≈6-ft- diameter footprint at a mounting height of 32 ft	Not applicable since detector gives a direct speed measurement
Whelen TDW-10	Multiple-lane coverage of any licensed motor vehicle traveling at speeds > 5 mph	10.525 GHz	< 2 mW/cm ²	Horizontal	25 deg (1st sidelobe at -3 dB)	8 - 137 km/h (5 - 85 mph)	Within ± 3 mph at all speeds	Up to 30.5 m (100 ft)	Not applicable since detector gives a direct speed measurement

Table 4-4. Specifications of Microwave Detectors Evaluated

Detector	Detectable Objects	Transmit Frequency	Power Output	Polarization (Transmit & Receive)	3dB Beamwidth	Speed Measurement Range	Speed Measurement Accuracy	Detection Range	Response Time
Electronic Integrated Systems Remote Traffic Microwave Sensor (RTMS)	Presence and speed detector for motorcycles and larger	10.525 GHz	< 2.5 V/m at 3 m distance	Horizontal	 15 deg Az, 25 deg El Beam shaping results in a user- definable azimuth footprint of 10 to 15 ft at a range of 100 ft Beam shaping results in an effective elevation beamwidth of 50 deg 	0 - >160 km/hr (0 - >99 mph)	Within ± 10%	 Sidefire: Up to 12 lanes covered Up to 60 m (200 ft) with resolu- tion of 2 m (7 ft) in 12 detection zones Overhead: 1 lane covered Occupancy of a zone at < 2% error Traffic volume in a zone at < 5% error 	< 20 msec

Table 4-4. Specifications of Microwave Detectors Evaluated (continued)

Manufacturer/ Model	Number of Traffic Lanes Monitored ^a	Speed Measure- ment Range	Speed Measure- ment Accuracy ^b	Detection Range	Vehicle Tracking
Econolite/ Autoscope 2003 ^d	8	0 to > 80 mi/h	±2 mi/h	46 m (150 ft) ^c	No
Computer Recognition Systems/ Traffic Analysis System ^e	4	0 to > 80 mi/h	± 2 to 5%	46 m (150 ft) ^c	Yes
Traficon/ CCATS-VIP 2 ^f	4	0 to 112 mi/h	_	46 m (150 ft) ^c	Yes
Sumitomo/ IDET-1009	4	0 to 100 mi/h (3 lanes), 0 to 75 mi/h (4 lanes)	± 5%	-	Yes
EVA/ 2000 ^h	4	0 to 155 mi/h		29 m (95 ft) ^h	Yes

Table 4-5. Specifications of Video Image Processors Evaluated

a. Per camera.

1 mi/h = 1.61 km/h

b. Function of frame rate, camera resolution, vehicle speed, and camera mounting height. c. Based on vehicle occlusion as a function of camera mounting height, intervehicle gap, and vehicle height. Value in table reflects mounting height = 25 ft (7.6 m), intervehicle gap = 30 ft (9.1 m), and vehicle height = 5 ft (1.5 m).

d. Typical traffic data reported by Autoscope include volume (number of vehicles/time interval), lane occupancy (time vehicle is in detection zone divided by the time interval), headway over time (average number of seconds between consecutive vehicles during the time interval), speed of a single vehicle, average speed of all vehicles during the time interval, classification of a single detection based on vehicle length (three classes are available), and classification of time interval data.⁽³⁾

e. Typical traffic data reported by the Traffic Analysis System include mean speed of vehicles in each of three classes; overall mean speed; length of the vehicle; area of the vehicle; number of vehicles in each of the three classes; total number of vehicles; density of vehicles; occupancy; and per lane parameters that include number of vehicles, average speed, density, and occupancy.⁽⁴⁾

f. CCATS-VIP 2 incorporates a graphical data interpretation and display package that outputs total number of vehicles and number per lane, gap time between vehicles, occupancy per lane, vehicle classification (up to three types) based on length, mean length of all detected vehicles, and alarms at lower and upper thresholds set by user.⁽⁵⁾

g. Traffic data is reported by the IDET-100 by lane over an RS-232 interface. Data include vehicle detection with a 90 percent accuracy; vehicle type as small or large; velocity in km/h; vehicle motion as moving, recently stopped, or parked; and the pulse width of the detection signal. The maximum length of the detection zone is 20 meters. The speed measurement accuracy of \pm 10 percent is based on a field test of approximately 250 units in Japan.^(6,7)

h. EVA 2000 provides volume, average speed, density, occupancy, average spatial headway, and count, each on a per lane and vehicle type (two types are supported) basis. Tracks individual vehicles, even when they cross lanes.⁽⁸⁾

Table 4-6. Specifications of Passive Acoustic Detectors Evaluated

Manufacturer/ Model	Number of Traffic Lanes Monitored	Detection Frequency Band	Detection Beam Pattern	Detection Range	Response Time
AT&T/ SmartSonic TSS-1	Single detection zone in 1 lane from overhead mount		6 deg (3 dB) 20 deg (10 dB)	20 to 35 feet (6.1 to 10.7 m)	50 ms

Parameter	NEMA TS-1 1989	California July 1989	Connecticut 1991-1992	Florida May 1991
Reference to NEMA specifications made	Not Applicable	No	No	No, but many NEMA sections included
Type of vehicle detected	Class 1: small motorcycle Class 2: large motorcycle Class 3: automobile	All motor vehicles that can be licensed in California	Not specified	Class 1: small motorcycle Class 2: large motorcycle Class 3: automobile
Speed Range	5 to 80 mph	Not specified	Parked and speeds greater than 0 mph	5 to 80 mph
Sensitivity	A minimum of 3 settings	A minimum of 7 selectable sensitivity settings	Not specified	A minimum of 3 settings
	Shall be able to detect Class 1, 2, or 3 vehicle when connected to any test loop described below	Shall detect vehicle with minimum change in inductance of 0.02% at setting 6		Shall be able to detect Class 1, 2, or 3 vehicle when connected to any test loop described below
Response Time	For Class 1 vehicle, less than 126 msec; For Class 3 vehicle, less than 51 msec	5 ± 1 msec for sensitivity setting 2	Not specified	For Class 1 vehicle, less than 126 msec; For Class 3 vehicle, less than 51 msec
Detection zone	3 feet maximum beyond loop	3 feet maximum beyond loop	Not specified	3 feet maximum beyond loop
Pulse Mode	Output between 100 - 150 msec when test vehicle enters detection zone	Output pulse of 125 ± 25 msec when test vehicle enters detection zone	Output pulse not specified	Output between 75 to 150 msec when test vehicle enters detection zone

Table 4-7. Inductive Loop Detector Specifications

4-9

Parameter	NEMA TS-1 1989	California July 1989	Connecticut 1991-1992	Florida May 1991
Presence Mode	When a Class 2 vehicle is over a test loop, the detector output shall be maintained for at least 3 minutes if vehicle remains that long	At sensitivity setting 6, the minimum duration of the detector output shall be 3 minutes if vehicle remains that long	Detection shall persist up to at least 10 minutes	When a Class 2 vehicle is over a test loop, the detector output shall be maintained for at least 3 minutes if vehicle remains that long
Recovery from sustained occupancy	Detector shall recover 90% of normal sensitivity within 1 sec after vehicle leaves detection zone	Detector shall recover normal sensitivity within 1 sec after vehicle leaves detection zone	Not specified	Detector shall recover 90% of normal sensitivity within 1 sec after vehicle leaves detection zone
Environmental change	Detector shall automatically adjust for changes in loop/ lead-in properties which might be reasonably expected	Detector shall compensate for a change in inductance of 0.001% per sec, up to a total change of \pm 5.0%	Detector shall compensate for environmental drift	Detector shall automatically adjust for changes in loop/ lead-in properties which might be reasonably expected
		Temperature changes of up to 1 deg C per 3 minutes shall not affect detector operation	Detector shall operate properly between -30 deg F and 150 deg F	
Delay Operation	Detector output delayed from 0 to 15 sec in 1-sec increments, and from 16 to 30 sec in 2-sec increments	Not specified	Detector output delayed from 0 to 31 sec in 1-sec increments	Detector output delayed from 0 to 30 sec
Extended Operation	Detector output extended from time vehicle leaves loop by 0 to 7.5 sec in 1/2-sec increments	Not specified	Detector output extended from time vehicle leaves loop by 0 to 15.5 sec in 1/2-sec increments	Not specified

Table 4-7. Inductive Loop Detector Specifications (continued)

Parameter	Georgia	Missouri	New York June 1990	Oklahoma
Reference to NEMA specifications made	Not mentioned	Not mentioned	No	Yes
Type of vehicle detected	Not specified	Not specified	All licensed motor vehicles except mopeds	Not specified – see NEMA spec
Speed Range	0 to 80 mph	0 to 80 mph	Not specified	0 to 100 mph
Sensitivity	Shall detect a vehicle with minimum change in inductance of 0.02%	Not specified	A minimum of 7 selectable sensitivity settings	Not specified – see NEMA
			Shall detect vehicles with minimum change in inductance of 0.02% at setting 6	
Response Time	Not specified	Not specified	5 ± 1 msec for sensitivity setting 2	Not specified – see NEMA
Detection Zone	Not specified	Not specified	3 feet maximum beyond loop	Not specified – see NEMA
Pulse Mode	Output pulse not specified	Output pulse not specified	Output pulse of 125 ± 25 msec when test vehicle enters detection zone	Required, but not specified – see NEMA
Presence Mode	When a Class 2 vehicle is over the test loop, the detector output shall be maintained for at least 3 minutes.if vehicle remains that long	At sensitivity setting 6, the duration of the detector output shall be 3 minutes if vehicle remains that long	Detection shall persist up to at least 10 minutes	When a Class 2 vehicle is over a test loop, the detector output shall be maintained for at least 3 minutes if vehicle remains that long

Table 4-7. Inductive Loop Detector Specifications (continued)

Parameter	Georgia	Missouri	New York June 1990	Okiahoma
Recovery from sustained occupancy	Detector shall recover 90% of normal sensitivity within 1 sec after vehicle leaves detection zone	Detector shall recover normal sensitivity within 1 sec after veh. leaves detection zone	Not specified	Detector shall recover 90% of normal sensitivity within 1 sec after vehicle leaves detection zone
Environmental change	Detection shall automatically adjust for changes in loop/ lead-in properties which might be reasonably expected	Detector shall compensate for a change in inductance of 0.001% per sec, up to a total change of ± 5.0%	Detector shall compensate for environmental drift	Detector shall automatically adjust for changes in loop/ lead-in properties which might be reasonably expected
		Temperature changes of up to 1 deg C per 3 minutes shall not affect detector operation	properly between -30	
Delay Operation	Detector output delayed from 0 to 15 sec in 1- sec increments, and from 16 to 30 sec in 2- sec increments	Not specified	Detector output delayed from 0 to 31 sec in 1- sec increments	Detector output delayed from 0 to 30 sec
Extended Operation	Detector output extended from time vehicle leaves loop by 0 to 7.5 sec in 1/2-sec increments	Not specified	Detector output extended from time vehicle leaves loop by 0 to 15.5 sec in 1/2- sec increments	Not specified

 Table
 4-7.
 Inductive
 Loop
 Detector
 Specifications
 (continued)

Parameter	Value						
Operation Modes	Two, Pulse and Presence						
Vehicle Types	Auto, trucks, buses, motorcycles, motor bikes, bicycles						
Vehicle Speed	0 to 100 mi/h (160.9 km/h)						
Selectivity	High steel concentrated area shall not affect operation						
Output Signal	Pulse Mode: Relay contact closure of 25-ms minimum (Connecticut); 125 ± 25 ms (California) Presence Mode: Relay contact closure for duration of presence of the vehicle (Connecticut); same for California except add that indication shall cease within 100 ms						
Detection Area	18 inches (457.2 mm) minimum on either side of sensing head						
Distance Between Control Unit and Sensing Head	3000 feet (914.4 m) minimum						
Power Interruption	The control unit shall return to normal operation within 3 minutes following a power interruption						

Table 4-8. Magnetometer Specifications

detectors. The above-the-road models were evaluated during the laboratory and field tests. Inductive loops and magnetometers were evaluated with the above-the-road technology models during the field tests. The specific inductive loop detector amplifier models and magnetometers used in the field tests were selected in consultation with the host cities and states and the manufacturers. Inductive loops were cut using state-of-theart installation techniques. The detector amplifiers were supplied by the host agency and were representative of state-of-the-art signal processing technology. Loop and magnetome-ter manufacturers and distributors, including Indicator Controls Corporation, Detector Systems, Saratec Traffic, and 3M, were contacted to obtain copies of specifications and performance data for their most current products.

4.3 TECHNICAL JUSTIFICATION

The technical justification for detector selection and rejection in the field tests was based on:

- Detector performance in freeway and surface street demonstration tests conducted by Hughes, DOTs, and other evaluation projects funded by states or FHWA;
- Detector design criteria that allow operation in anticipated weather environments;
- Availability of detectors in time to meet laboratory and field test and evaluation schedules;
- Manufacturer support to help interpret specifications and evaluation data, and make available RS-232 serial data protocols that describe the data output by the detector.

Detector performance was judged against the specifications provided by the manufacturer.

If the laboratory or other demonstration test performance met the manufacturer's specifications and the specifications represented state-of-the-art performance, then the detectors were used in the field tests.

The manufacturers design criteria and test data helped determine if the detectors operated in cold, hot, fog, and wet weather environments and in electrical disturbances, such as lightning, anticipated for the field tests.

Availability of detectors became a consideration because of the lead time needed to set up equipment and build required mounting brackets and interface electronics. Some of the detectors are new development models whose production-model runs do not yet exist.

Manufacturer support in making available specifications, operating procedures, and test procedures not normally supplied with the detectors made the laboratory and field testing of these devices easier and more meaningful.

A selection matrix showing which of the technical criteria are satisfied by the detectors selected is given in Table 4-9.

All detectors that met these criteria were used in the field tests. As none of the detectors met all of the future IVHS requirements listed in Section 2, the field tests were instead used to verify performance of the current state-ofthe-art detectors and to make recommendations for future improvements.

4.4 ON-BENCH PHOTOGRAPHS OF DETECTORS

Pages 4-16 through 4-26 contain photographs of the detectors that represent the technologies evaluated in the project. The detectors not shown were not available during the photography sessions. The manufacturers and specification summary corresponding to each detector model can be found in Tables 4-1 through 4-6. A brief description of each detector is given in Section 10.6.

			Data						Environment					Mount	
Traffic Parameter Detector Technology and Model	Count	Presence	Speed	Speed Binning	Occupancy	Vehicle Length	Incident Detection	Adequate Range	Rain	Fog	Snow	Day	Night	Overhead*	Side Looking
Ultrasonic															
Sumitomo SDU-200 (RDU-101) Sumitomo SDU-300 Microwave Sensors TC-30C	x x x	x x	х		I x I	x	I I I	x x x	x x x	x x x	x x x	x x x	X X X	U N N	
Infrared (Active)															
Schwartz Electro-Optics	x	x	x		I	x	Ι	x	?	?	?	x	x	U,D	
Infrared (Passive)															
Eltec 842 Eltec 833	x x	x			I		l I	x x	? ?	? ?	? ?	x x	x x	U,D U,D	
Microwave Radar															
Microwave Sensors TC-20 Microwave Sensors TC-26 Whelen TDN-30 Whelen TDW-10 Electronic Integ. Systems RTMS	x x x x x x	x	x x x	x	x		I I I I	x x x x x x	x x x x x x	X X X X X	X X X X X	X X X X X	X X X X X	U,D U,D U,D U,D U,D	
Video Image Processing															ł
AutoScope 2003 Computer Recog. Systems TAS Golden River Traffic C-CATS Sumitomo IDET-100 EVA 2000	X X X X X	X X X X X	x x x x x	X X X X X	X X X X X X	X X X X X	X X X X X X	X X X X X	? ? ? ?	? ? ? ?	? ? ? ?	X X X X X	x x x x x x	U,D U,D U,D U,D U,D	x x x
Acoustic Array															
AT&T TSS-1	x	x			x			x	?	x	?	x	x	D	
Inductive Loop Detectors	x	x	I		x		I	x	x	x	x	x	x		
Magnetometers	x	x	I		x		I	x	x	x	x	x	x		

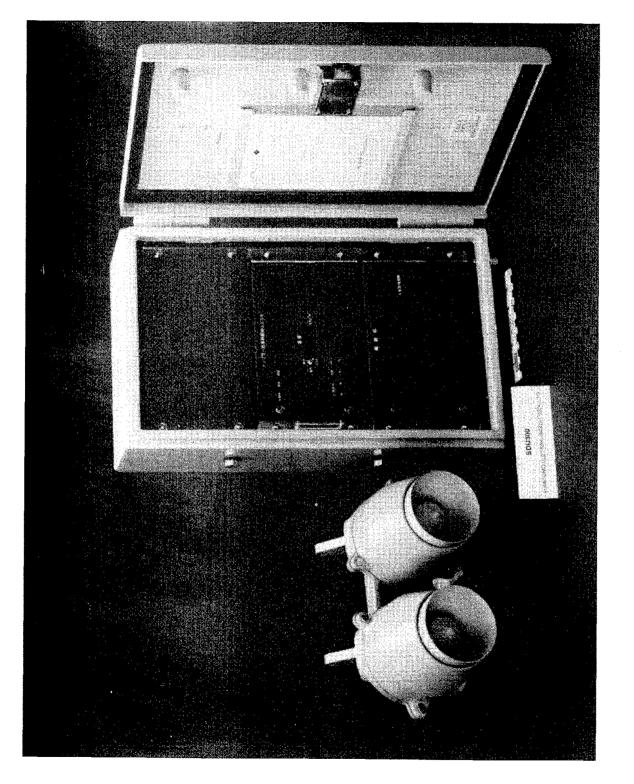
Table	4-9.	Detector	Output	Data	and	Operating	Environments
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* U = functions when viewing upstream, D = functions when viewing downstream, N = functions when viewing in nadir direction.

** Manufacturer recommends that Model 842 be mounted at an oblique angle to the traffic flow. *x* represents either (1) data that are measured directly, (2) acceptable operating environments, or (3) side-mounted operation.

I represents information available through processing of detector data, i.e., indirectly available information.

? represents a possible degradation in performance dependent on the severity of the environment.



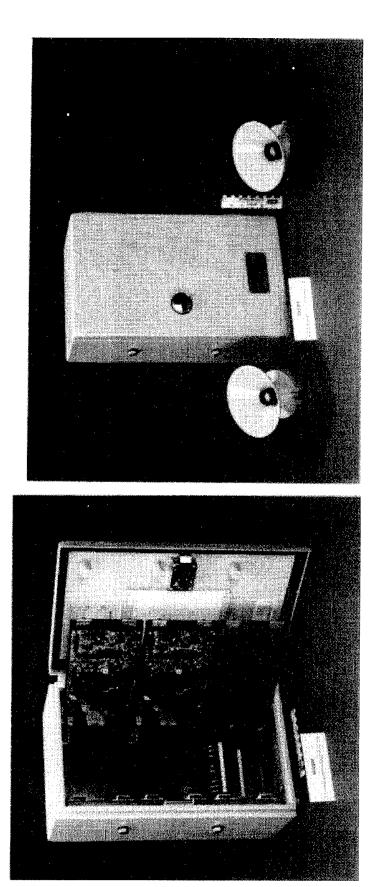


Figure 4-3. SDU-300 Ultrasonic Detector

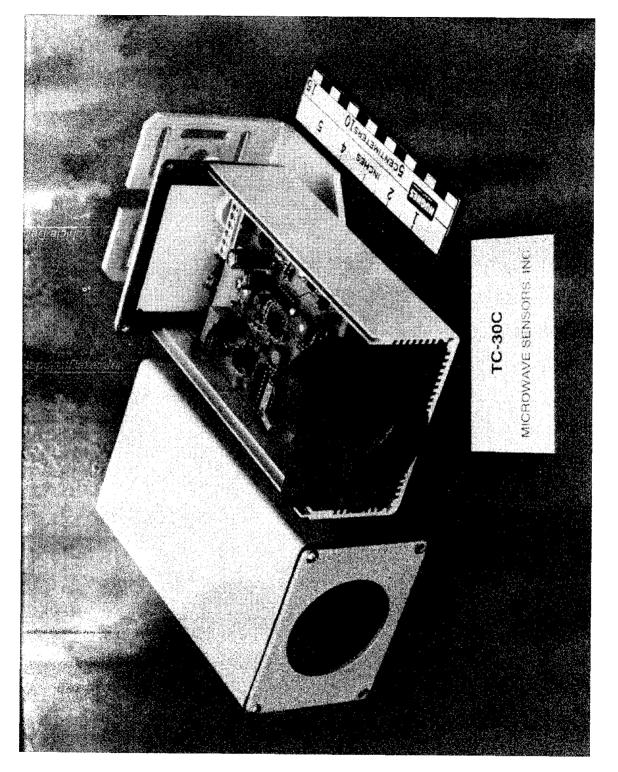


Figure 4-4. TC-30C Ultrasonic Detector

4-18

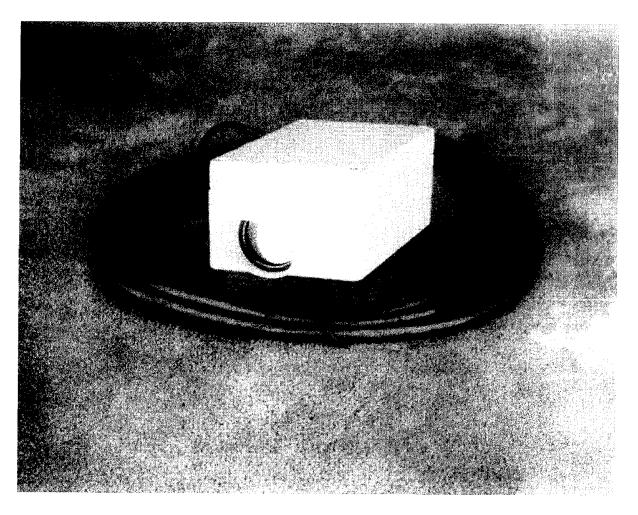


Figure 4-5. 842 Infrared Detector

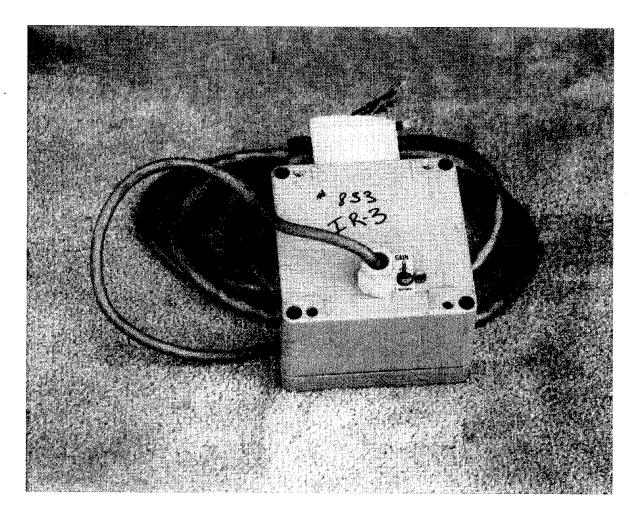
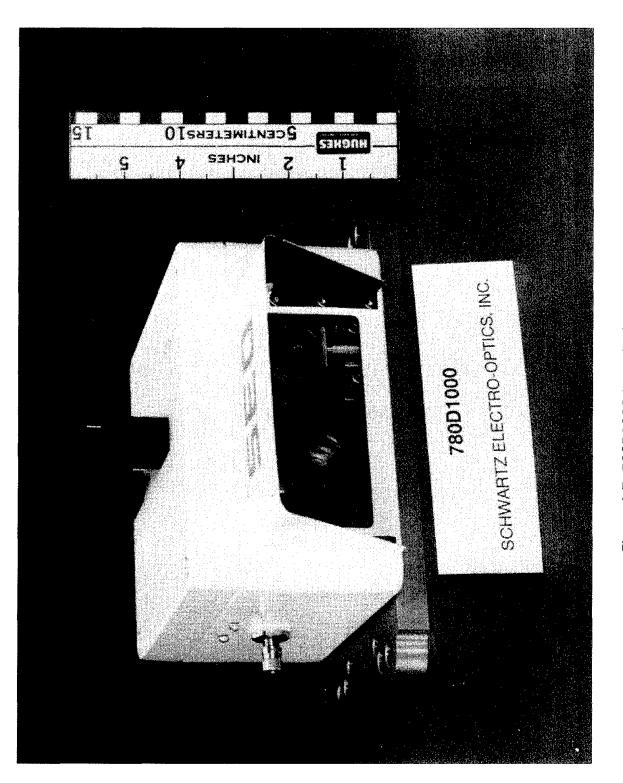


Figure 4-6. 833 Infrared Detector



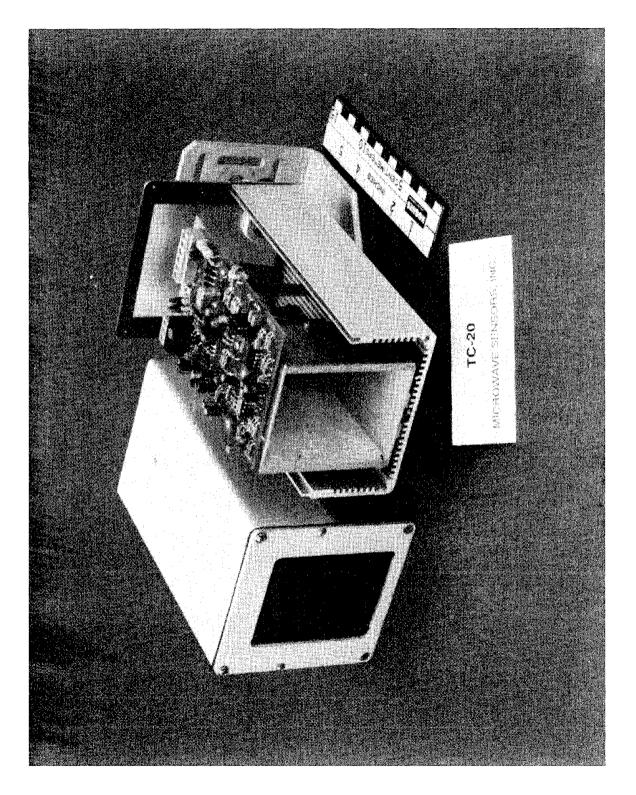
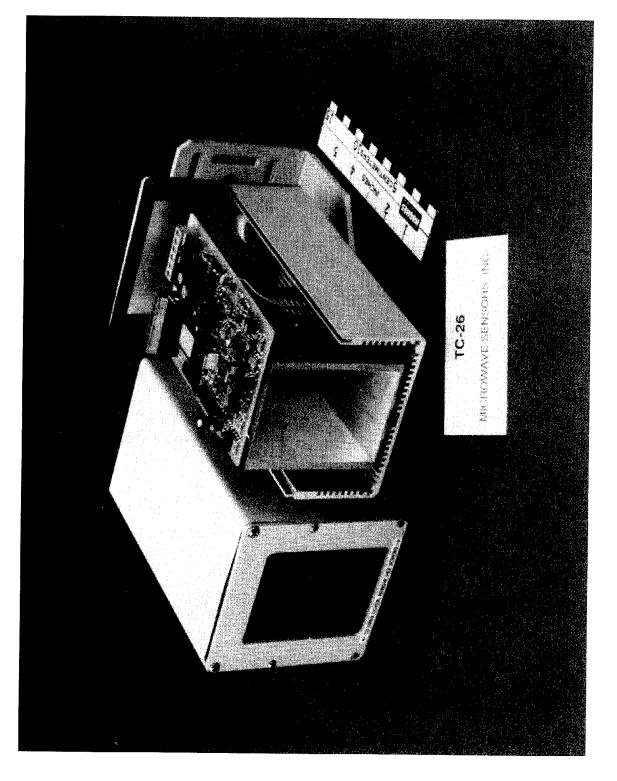
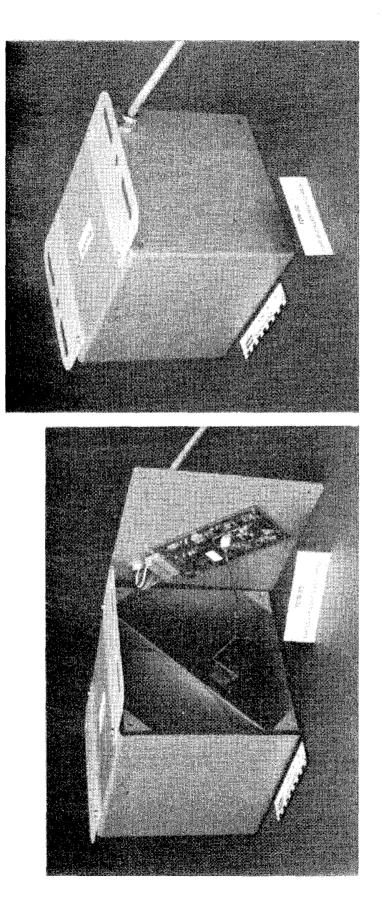
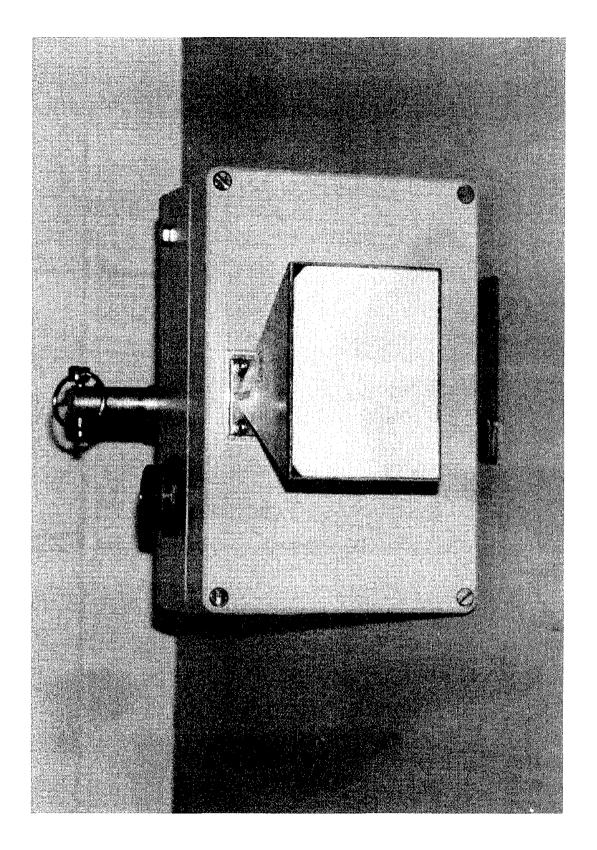


Figure 4-8. TC-20 Microwave Detector







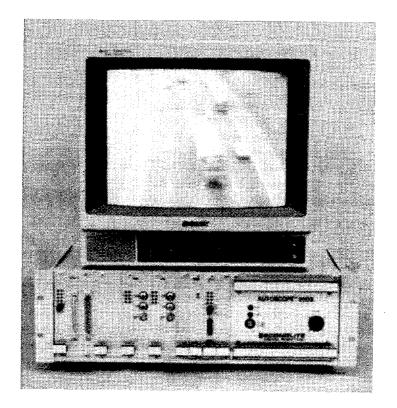
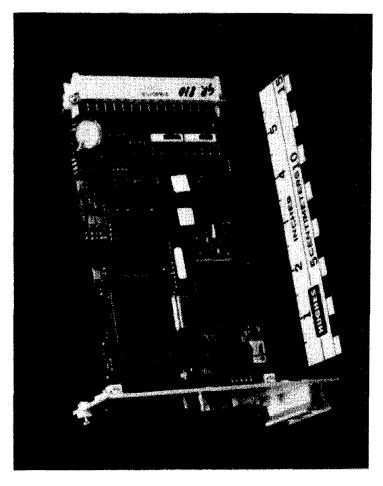
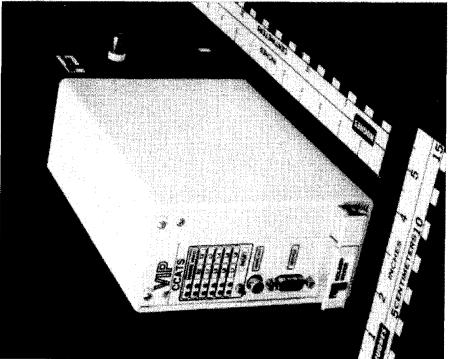


Figure 4-12. Autoscope 2003 Video Image Processor





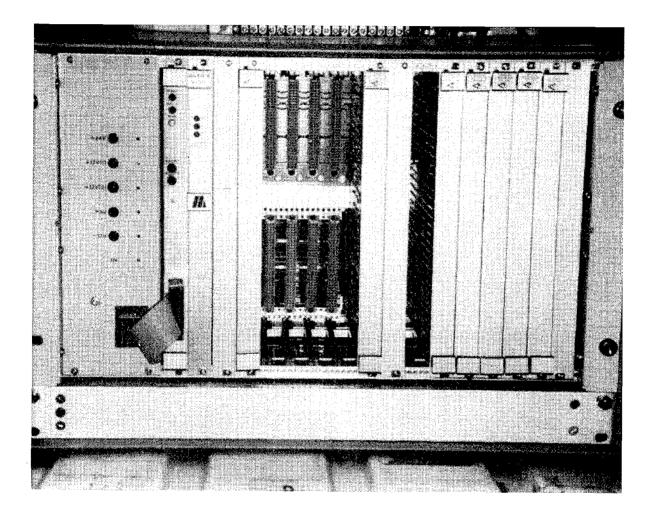


Figure 4-14. Traffic Analysis System Video Image Processor

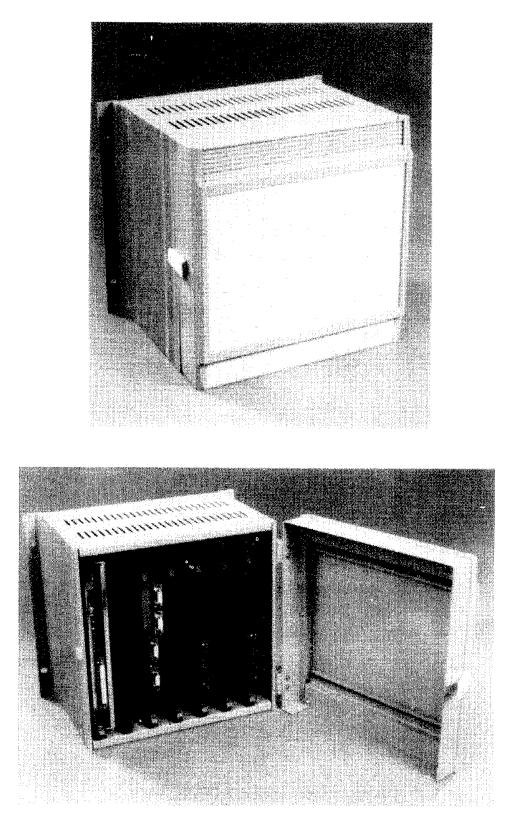


Figure 4-15. EVA 2000 Video Image Processor

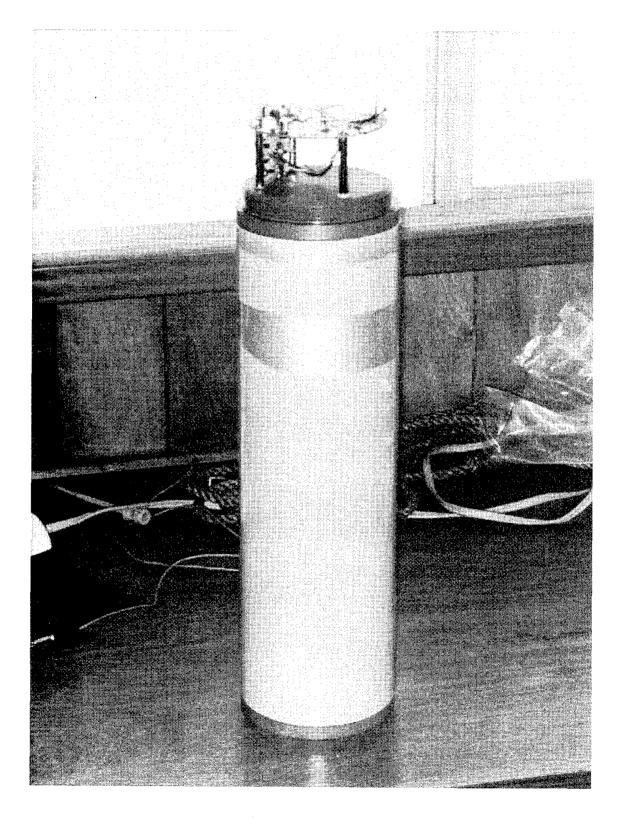


Figure 4-16. Self-Powered Vehicle Magnetometer Detector

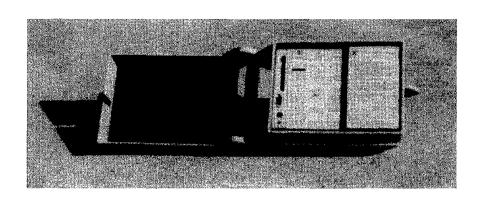


Figure 4-17. Delta I Vehicle Counter

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5. THEORY OF OPERATION OF DETECTOR TECHNOLOGIES

The quest for a reliable and cost-effective vehicle detection and tracking system that can be installed and maintained with safety and minimal disruption of traffic, and can provide traffic data at least as accurate as the loop detector has been underway for some time.^(1,2) Not only are detectors used to actuate traffic control devices and detect incidents, but they are also appearing in automatic vehicle identification applications associated with electronic toll and traffic management (ETTM) as discussed at the end of this section. Still other applications include sensing of vehicle presence, turning movements, and speed for advanced vehicle control systems.

This section reviews above-the-road and below-the-surface detector technologies. The above-the-road devices have the potential to replace inductive loop detectors for intersection control, traffic surveillance, and incident detection. Many of these technologies are in limited application in demonstration projects where their potential to supply accurate data is being evaluated.⁽³⁾ The lessons learned are anticipated to lead to further enhancements. The section concludes with a discussion of automatic vehicle identification applications.

5.1 VIDEO IMAGE PROCESSORS

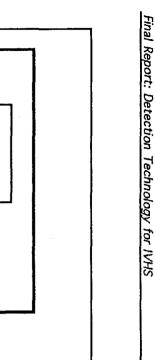
Video cameras were first introduced to provide roadway surveillance. They transmitted closed circuit television (CCTV) imagery to a human operator for interpretation. More advanced techniques now use video image processing to automatically analyze the scene of interest and extract information for traffic surveillance and control. Typically, the imagery is digitized in hardware that is hosted in a personal computer (PC) architecture. The PC also accommodates application-specific software used to calculate the desired traffic parameters. Video image processors (VIPs) can replace several in-ground inductive loops by a single above-the-road camera and signal processing that provide area-wide detection of vehicles and the promise of lower maintenance costs. Some VIP systems process data from more than one camera and thus increase the data collection area even further.

VIPs have the potential to classify vehicles and report vehicle presence, volume, occupancy, and speed for each class and for each lane observed. Other potentially available traffic parameters are density and link travel time.

5.1.1 Operation

Most current video image processors analyze imagery transmitted to them at full frame rates of 30 frames/s. Some can conserve transmission bandwidth by performing image processing in the camera or at the roadside controller and transmitting only lowbandwidth numerical traffic data to the operations center as shown in Figure 5-1. In addition to the traffic parameters, the detector interface module can transmit information that allows icons to be displayed on monitors in the traffic management center by using a combination of computer hardware and software located at the center. The icons represent the real-time traffic flow occurring on the freeway and the tracks of vehicles within the field-of-view of the camera. Different shaped and colored symbols can be created to represent automobiles, buses, trucks, motorcycles, etc. The icon representation of traffic flow, as compared to the display of full bandwidth video imagery, allows lower bandwidth transmission media to be used. The full bandwidth imagery is still available on demand for transmission to the operations center to verify and identify incidents and recurring congestion. By multiplexing video images from several cameras on one transmission line and sending the video only when requested, operating costs associated with leased transmission media are further reduced.

New generation VIPs are being developed to process high-resolution visible and infrared camera imagery with embedded algorithms



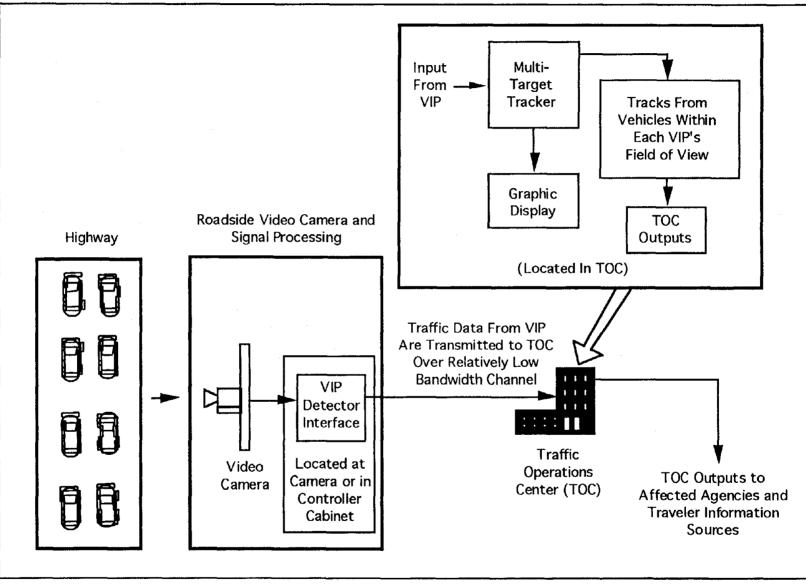


Figure 5-1. Modern Video I mage Processor Incorporating Roads ide Signal Processing

that are not susceptible to variations in ambient light, shadows, or other artifacts that can otherwise corrupt the traffic data. Several VIPs identify and track vehicles and then estimate the future position of the vehicle. These VIPs have the potential to transmit information to roadside displays and radios that alert drivers to factors that can lead to an incident. Other VIPs use information from a combination of sensors sensitive to visible, infrared, and ultraviolet wavelengths to detect vehicles and remove artifacts.

5.1.2 Mounting and Traffic Viewing Considerations

Table 5-1 shows how processing of upstream or downstream imagery influences VIP performance. The primary advantage of upstream viewing is that incidents are not blocked by the resulting traffic queues. However, tall trucks may block the line of sight and headlights may cause blooming of the imagery. Downstream viewing offers advantages of camera concealment so that driver behavior is not altered, easier identification and tracking of vehicles using information contained in the tail lights, and better acquisition of vehicle tracks because the vehicles are closer to the camera at track initiation.

Based on line-of-sight considerations, the detection distance at which a VIP can differentiate two closely spaced vehicles along the surface of a road is a function of camera mounting height, inter-vehicle distance or gap, and vehicle height as shown in Figure 5-2. The maximum detection distance D_{max} along a roadway without a grade is given by

$$D_{max} = h \frac{Veh_{gap}}{Veh_{height}}$$
(5-1)

where

h = camera mounting height,

 Veh_{gap} = inter-vehicle gap, and

 Veh_{height} = vehicle height.

Other factors to be considered when installing cameras used in VIP systems include: ⁽⁴⁾

- Vertical and lateral viewing angles,
- Number of lanes observed,

Stability with respect to wind and vibration,

and

• Image quality.

VIPs tolerate an oblique view of the highway if the mounting height is high, say 45 to 50 feet (13.7 to 15.2 m). For lower heights in the vicinity of 18 to 25 feet (5.5 to 7.6 m), a mounting location centered over the area of interest may be required. However, the lower the camera, the greater is the error in vehicle speed measurement, as the measurement error is proportional to the vehicle height divided by the camera mounting height.

The number of lanes of imagery analyzed by the VIP becomes important when the required field of view is larger than the VIP's capability. For example, if the VIP provides data from detection zones in three lanes, but five must be observed, that particular VIP may not be appropriate for the application.

VIPs sensitive to large camera motion may be adversely affected by strong winds. Algorithms that predict the future path of a vehicle (such as a Kalman filter) and smooth its track may reduce sensitivity to camera motion.

Image quality and interpretation can be affected by cameras that have automatic iris and automatic gain control. In tests conducted by California Polytechnic Institute at San Luis Obispo, these systems were disabled.⁽⁴⁾ In still other VIPs, the signal processing is tailored to take advantage of automatic light control systems.

Using the same camera for automatic vehicle detection with a VIP, and video surveillance with pan, tilt, and zoom features requires the camera to be repositioned for each application. If the field of view is not returned to the calibrated value for VIP operation, the performance of the VIP is adversely affected. It may be technically feasible, however, to reposition the camera at previously established VIP detection zones after it has been panned, tilted, or zoomed to view an incident location for verification and identification. In this case, one camera can be used for both applications. If the remote control of cameras and their return to calibrated fields of view is

Upstream Viewing	Downstream Viewing				
 Headlight blooming and glare from wet pavement 	Camera concealed from drivers				
 More blockage from tall trucks 	 More information from tail lights available for braking indication, vehicle classification, and turning movement identification 				
 With infrared imagery, there is no difference in information obtained from headlights or tail lights when a tracking algorithm is used 	 With visible imagery, more information is available to a tracking algorithm from tail light viewing 				
 Traffic incidents are not blocked by resulting traffic queues 	 Easier to acquire vehicles that are closer to the camera for the tracking algorithm application 				

Table 5	-1.	Video	Image	Processor	Characteristics	as	Used	in	Upstream	and
Downstream Viewing										

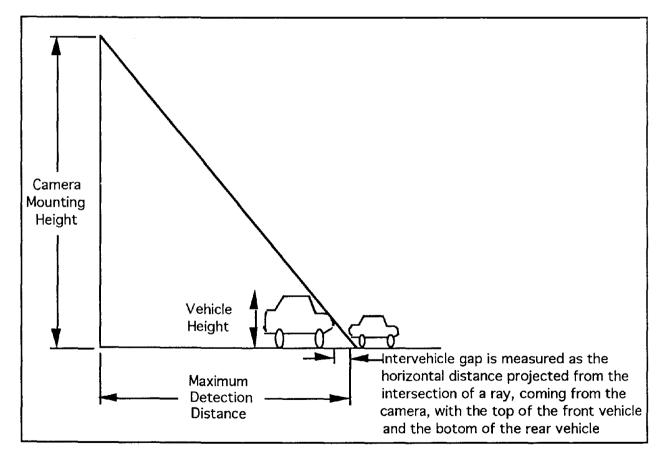


Figure 5-2. Video Image Processor Line-of-Sight Detection Geometry

5.1.3 Signal Processing

The data reduction and image formatting are performed with firmware that allows the algorithms to run in real time. The data reduction hardware is commonly implemented on a single formatter card in a personal computer. Once the data are digitized and stored by the formatter, spatial and temporal features are extracted from the vehicles in each detection zone with a series of image processing algorithms as illustrated in Figure 5-3. A detection process that establishes one or more thresholds is used to limit and segregate data passed on to the rest of the algorithms. It is undesirable to severely limit the number of potential vehicles during detection, for once data are removed they cannot be recovered. Therefore, false vehicle detections are permitted at this stage since the declaration of actual vehicles is not made at the conclusion of detection processing. Rather, algorithms contained in the steps still to come are relied on to eliminate false vehicles and retain the real ones.⁽⁵⁾ Image segmentation is used to divide the image area into smaller regions where features can be better recognized. The features are analyzed to generate vehicle presence, speed, and classification data. Alternatively, neural networks can be trained to recognize and count different classes of vehicles and detect incidents.⁽⁶⁾ Once individual vehicles are identified, they can be tracked by applying Kalman filter techniques. Tracking offers the potential ability to warn of impending incidents due to abrupt lane changes or weaving.

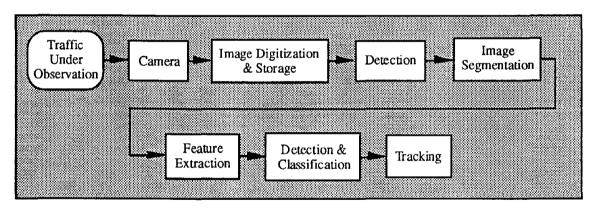


Figure 5-3. Conceptual Vehicle Detection, Classification, and Tracking System

There are two algorithmic approaches employed in image processors. In the first, VIPs detect vehicles at a number of fixed locations within the field of view of the camera by having the operator use interactive graphics to place the detection areas or zones. The zones can be oriented perpendicular, parallel, or at an oblique angle to the roadway lanes. Ideally, a signal is generated when a vehicle enters a detection zone. Some zone orientations, such as those parallel to a lane, were found to be less sensitive to vehicles than zones perpendicular to the travel direction. Newer software has apparently

remedied this problem. Since a single camera and VIP can provide detection zones across several lanes, the VIP system can replace many loops and provide wide-area vehicle detection.

VIPs employing the second approach track vehicles continuously through the field of view of the camera. Multiple detections of the vehicle along a track are used to validate the detection. Once validated, the vehicle is counted and its speed is measured.⁽⁷⁾ The detection zone approach estimates vehicle speed by using relatively closely spaced pairs of zones to measure the time between the signals generated by a vehicle traversing the adjacent zones. This is similar in concept to speed traps implemented with two inductive loop detectors. The tracking algorithm associates a series of detections with a vehicle to predict its future position and to calculate link travel times. The more advanced VIPs that track individual vehicles can directly calculate speed from the algorithm that tracks the vehicles.

VIP algorithms have been improved to ignore artifacts produced by shadows, illumination changes, and reflections, and to minimize effects of adverse weather. In addition, the heavy congestion that degraded early VIPs does not appear to present a problem to more modern systems. Combined results for clear and inclement weather show vehicle volume. speed, and occupancy measurement accuracies in excess of 95 percent using a single detection zone.⁽⁸⁾ VIPs with single detection zones in a lane are useful for monitoring traffic volumes on a freeway. For signalized intersection control, where vehicle detection accuracies of 100 percent are desired, the number of detection zones in the field of view is increased to between two and four, dependent on the camera mounting and road geometry.

5.2 MICROWAVE DETECTORS

The use of microwave radar for detecting objects had its beginnings before and during Word War II. In fact, the word *radar* was derived from the functions that it performs: *R*Adio *D*etection *A*nd *R*anging. The term *microwave* refers to the wavelength of the transmitted energy, usually between 1 and 30 cm corresponding to a frequency range of 1 GHz to 30 GHz. The prefix *giga* (G) represents 10⁹. Radar operating at frequencies above 30 GHz is referred to as millimeter-wave radar, again corresponding to the wavelength of the transmitted energy.

Unlicensed operation of microwave detectors for traffic data collection and monitoring is limited to frequencies in bands near 10.5 GHz and 24.0 GHz under Part 15 of Federal Communications Commission (FCC) regulations for microwave devices. Part 15.245 of the FCC rules for Field Disturbance Sensors allows unlicensed operation at frequency bands between 10.500 and 10.550 GHz and 24.075 and 24.175 GHz if the electrical field strength 3 meters from the transmitting antenna is 2.5 V/m or less. The field strength of harmonics present in the transmitted signal must be no greater than 25 mV/m at 3 meters distance. The signal must also be at least 50 dB down from its in-band value outside this band. Field disturbance sensors cannot carry information in their transmitted signal.

Part 15.209 of the FCC rules for general radiation emissions allows transmission in the 1- to 40-GHz frequency range if the field strength is limited to 500×10^{-6} V/m at 3 meters.

Licensed transmission in the 33.4- to 36.0-GHz band is allowed under Part 90 FCC regulations for local government radio service. The output power is specified in the authorization. Transmission is secondary to U.S. government service. Both the manufacturer and the user need licenses. The telephone number for the Gettysburg, PA, FCC office that has jurisdiction for this service is (717) 337-1212.

As shown in Figure 5-4, microwave detectors transmit energy toward an area of roadway from an antenna mounted overhead that illuminates approaching or departing traffic, or in a side-looking configuration that views traffic across several lanes. When a vehicle passes through the beam, a portion of the transmitted energy is reflected back to the antenna. The energy then enters a receiver where the detection is made.

Microwave detectors currently used in traffic applications transmit two types of waveforms. The first is a continuous wave of electromagnetic energy whose frequency does not change with time. A detector that uses this waveform is capable of detecting only moving vehicles. It measures the speed of vehicles in its field of view using the Doppler principle. Here the frequency of the received signal differs from that of the transmitted signal fby an amount f_D equal to the Doppler frequency produced by the vehicle speed. The frequency shift thus denotes the passage of a vehicle. The relation between f_D , f, and vehicle speed v is

$$f_D = \frac{2v}{c} f \cos \theta \qquad (5-2)$$

where θ is the angle between the direction of propagation of radar energy and direction of

travel of the vehicle, and *c* is the speed of light (3 x 10⁸ m/s). If the vehicle is traveling directly toward the detector, the Doppler shift is maximum and positive in value. At 10 GHz, the Doppler frequency shift is approximately 30 Hz per statute mile per hour of vehicle radial speed, which is calculated as ($v \cos \theta$). Doppler detectors that do not also include range measuring capability cannot detect motionless vehicles.

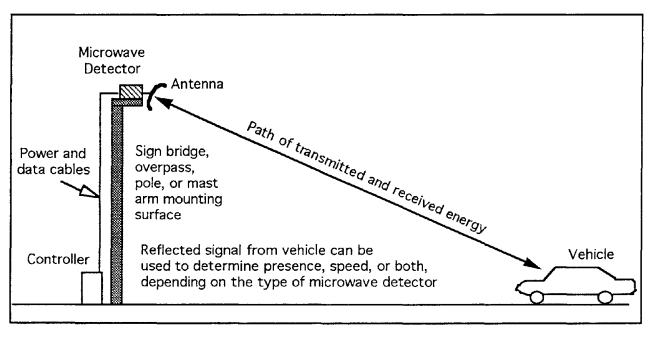


Figure 5-4. Microwave Detector

The second waveform is *sawtooth*, also called FMCW (frequency-modulated continuous wave), in which the transmitted frequency is

constantly changing with respect to time, as shown in Figure 5-5.

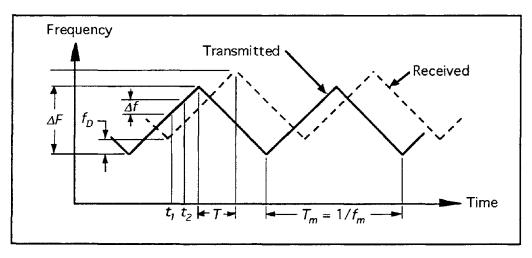


Figure 5-5. FMCW Waveform Parameters

Since the FMCW radar measures the range to the vehicle, it functions as a presence detector and can detect motionless vehicles. Range *R* is proportional to the difference in the frequency Δf of the transmitter at the time t_1 the signal is transmitted and the time t_2 at which it is received, as shown by

$$R = \frac{c\Delta f}{4\Delta F f_m} \tag{5-3}$$

where

- Δf = instantaneous difference in frequency, in Hz, of the transmitter at the times the signal is transmitted and received,
- ΔF = RF modulation bandwidth in Hz,

and

 $f_m = RF$ modulation rate in Hz.

Alternatively, the range may be calculated by measuring the time difference T between consecutive peaks in the transmitted and received signals, as shown in Figure 5-5, such that

$$R = cT/2 \tag{5-4}$$

when the transmitter and receiver are collocated.

The FMCW radar measures vehicle speed in two ways. The first method is used when the radar's field of view in the direction of vehicle travel is divided into range bins as shown in Figure 5-6(a). A range bin allows the reflected signal to be partitioned and identified from smaller regions than the entire antenna footprint.

Speed v is calculated from the time difference ΔT corresponding to the vehicle arriving at the leading edges of two range bins a known distance d apart as shown in Figure 5-6(b) and is given by

$$v = \frac{d}{\Delta T} \tag{5-5}$$

where d = distance between leading edges of the two range bins and ΔT = time difference corresponding to the vehicle arrival at the leading edge of each of the range bins.

The second method in which an FMCW radar measures speed is through the Doppler shift in frequency caused by the motion of a vehicle.⁽⁹⁾ Referring to Figure 5-5, the instantaneous frequency difference between the two curves when they have positive slopes (upsweep) is given by

$$\delta f_u = \frac{4\Delta F f_m R}{c} - f_D \qquad (5-6)$$

and by

$$\delta f_d = \frac{4\Delta F f_m R}{c} + f_D \qquad (5-7)$$

when they have negative slopes (downsweep). Equation 5-3 is still valid when Doppler is present, as Δf in equation 5-3 represents the average frequency difference measured when the slopes are positive and negative. The radial vehicle speed v_R is

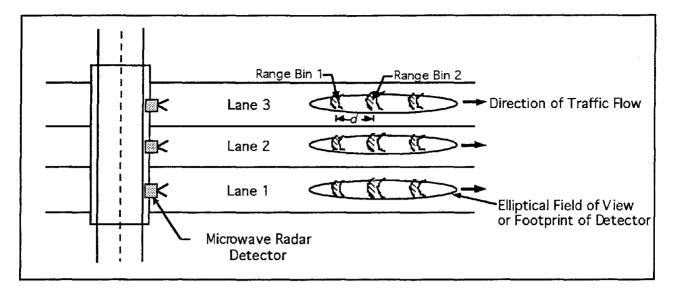
$$v_R = \frac{c}{4f} (\delta f_d - \delta f_u)$$
 or (5-8a)

$$v_R = \frac{\lambda}{4} \left(\delta f_d - \delta f_u \right) \tag{5-8b}$$

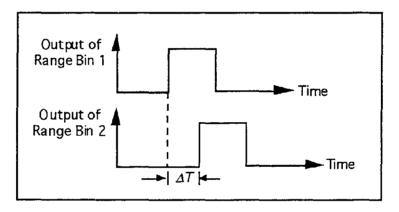
where $c = \lambda f$ and λ is the wavelength of the transmitted energy. If the radar is forward looking, radial speed is equal to the vehicle speed toward or away from the radar multiplied by the cosine of the angle between the direction of propagation of radar energy and direction of travel of the vehicle.

To differentiate between multiple vehicles in the radar footprint, an FMCW radar can be designed with a three-segment waveform such as the one in Figure 5-7. T_s represents the time duration of each segment.

An independent measure of radial speed v_R is produced by the unmodulated horizontal portion of the waveform where df/dt = 0. The remainder of the frequency versus time curve is identical to the linear FM discussed above. Therefore, the differences in frequencies, δf_u and δf_d , between the transmitted and received



(a) Range-Binned Footprints of Radar Detectors in Traffic Lanes



(b) Time-Phased Outputs of Range Bins

Figure 5-6. Range-Binned Radar Footprint

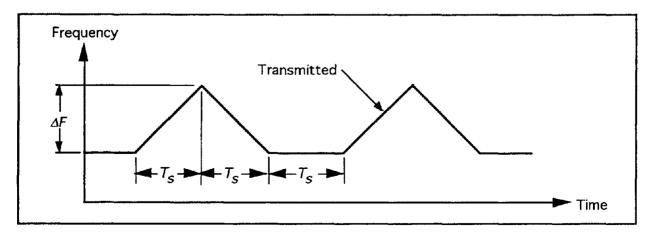


Figure 5-7. Segmented Linear FM Waveform

waveforms are identical to those given above. Since f_D has already been found from the unmodulated portion of the curve, δf_u and δf_d can be used to find the unambiguous range and speed of multiple vehicles that appear in the radar footprint as described in Appendix D.(10)

Range resolution δR of an FMCW radar is

$$dR = \frac{c}{2\Delta F} \tag{5-9}$$

Therefore, if the radar operates in the 10.500- to 10.550-GHz band where bandwidth is limited to perhaps 45 MHz to ensure that the field strength is down by 50 dB outside the band, the range resolution is, at best, 3.3 m (10.8 ft).

Speed or Doppler resolution is given by

$$\Delta f_D = 1/T_s \tag{5-10}$$

Presence-measuring radars can be used to control left-turn signals and monitor traffic queues. Radars that detect only moving vehicles from their Doppler frequency can be used to measure vehicular speed on both city arterials and freeways.

5.3 INFRARED DETECTORS

Infrared detection devices currently marketed consist of both active and passive models. Detectors are available for overhead mounting to view approaching or departing traffic or traffic from a side-looking configuration. In the active system, detection zones are illuminated with low-power infrared energy supplied by light-emitting diodes (LEDs) or with higher levels of energy supplied by laser diodes. None of the LED type of infrared detector was available for this study. The infrared energy reflected from vehicles traveling through the detection zone is focused by an optical system onto a detector matrix mounted on the focal plane of the optics. With infrared devices, the word detector takes on a new meaning, namely the energy-sensitive element(s) that converts the reflected energy into electrical signals. Real-time signal processing is used to analyze the received signals

and to determine the presence of a vehicle. Changes in received signal levels caused by environmental effects, such as weather and shadows, can be accounted for by the signal processing.

Active infrared detectors provide vehicle presence at traffic signals, vehicle counting, speed measurement, length assessment, and queue measurement. Active infrared detectors can be designed with different fields of view when required for stop-line presence detection and for presence detection in the intersection approach (e.g., a detection zone 68 to 100 feet (20.7 to 30.5 m) in advance of the stop line). The units accommodate mounting heights of between 15 and 30 feet (4.6 to 9.1 m). Multiple units can be installed at the same intersection without interference from transmitted or received signals.

Passive infrared detectors supply similar traffic parameters except for speed. They use an energy-sensitive element located at the optical focal plane to measure the thermal energy emitted by objects in the field of view of the detector and do not transmit energy of their own. The source of the emitted energy is gray-body radiation due to the non-zero temperature of emissive objects as illustrated in Figure 5-8. When a vehicle enters the field of view, the change in emitted energy from the scene is used to detect the vehicle.

An equation can be written for the difference in energy corresponding to a vehicle entering the detector's field of view. The emissivity of the vehicle and road surface in the wavelength region of interest are denoted by ε_V and ε_R , respectively, and their surface temperatures in degrees kelvin by T_V and T_R . The apparent temperature T_B of the vehicle, as sensed by the passive infrared detector, is

$$T_{B}(\theta,\phi) = \varepsilon_{V}T_{V} + (1 - \varepsilon_{V}) T_{Sky} \quad (5-11)$$

 T_{Sky} is a function of atmospheric and cosmic emission. θ and ϕ are the incident angle with respect to nadir and the angle in the plane of the road surface (the *x*-*y* plane), respectively.

One can write a similar expression for the apparent temperature of the road surface as

$$T_B(\theta,\phi) = \varepsilon_R T_R + (1 - \varepsilon_R) T_{Sky} \quad (5-12)$$

By subtracting the apparent temperature of the vehicle from that of the road, one gets an expression for the temperature difference $\Delta T_{B}(\theta,\phi)$ sensed by the passive infrared detector when a vehicle passes through its field of view. Thus,

$$\Delta T_B(\theta,\phi) = (e_R - e_V) (T_R - T_{Sky}) \quad (5-13)$$

when $T_R = T_V$.

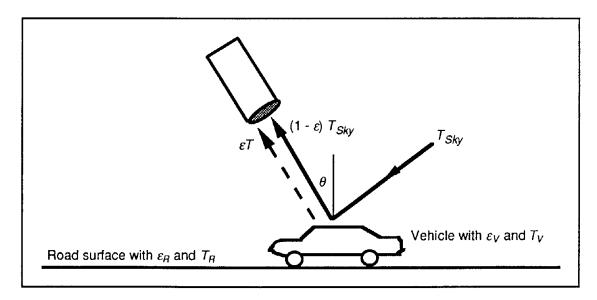


Figure 5-8. Emission of Energy by Vehicle and Road Surface

Hence, a vehicle generates a signal proportional to the product of the difference in emissivity between the road and the vehicle, and the difference between the absolute temperature of the road surface and the sky temperature. On overcast, high humidity, and rainy days, the sky temperature is greater than on clear days and the signal produced by a passing vehicle decreases. This, in itself, may not pose a problem to a properly designed passive infrared detector operating at the longer wavelengths of the infrared spectrum, especially at the relatively short operating ranges typical of traffic management applications.

Another attribute of infrared devices is their ability to image the scene of interest. Nonimaging infrared devices typically use one energy-sensitive detector on the focal plane to gather energy from the entire scene. Objects within the scene cannot be further divided into sub-objects or pixels (picture elements) with this device. Imaging sensors use staring two-dimensional arrays of detectors for traffic-monitoring applications, where each detector has a small instantaneous field of view. Here, more than one detector gathers energy from the scene, allowing details in the imaged area to be discerned. In an alternate method of obtaining imaging data, onedimensional arrays can be scanned over the scene of interest.

Several disadvantages of infrared detectors are often cited. With active devices, atmospheric effects may cause scatter of the transmitted beam and received energy. Glint from sunlight may cause unwanted and confusing signals. With respect to weather, the amount of energy reaching the focal plane is sensitive to water from fog, haze, and rain, as well as to other obscurants such as smoke and dust. In addition to scattering, these environmental effects can absorb energy that would otherwise be detected by both active and passive infrared devices.

5.4 ULTRASONIC DETECTORS

Ultrasonic vehicle detectors can be designed to receive range and Doppler speed data, the same information used by the radar detectors. Ultrasonic detectors transmit sound waves, at a selected frequency between 20 and 65 kHz, from overhead transducers into an area defined by the transmitter's beamwidth pattern. A portion of the energy is backscattered or reflected from the road surface or a vehicle in the field of view. The preferred viewing configurations for range-measuring (presence) ultrasonic detectors are downward (at a nadir incidence angle) and side viewing. The speed-measuring ultrasonic detector is forward-looking, facing approaching traffic. The transducers in both the presence and speed-measuring ultrasonic devices convert the received sonic energy into electrical energy that is fed to signal processing electronics, either collocated with the transducer or located in a roadside controller.

The range-measuring detector transmits a series of pulses of width T_p (typical values range between 0.02 and 2.5 ms) and

repetition period T_o (time between bursts of pulses), typically 33 to 100 ms, as shown in Figure 5-9. The detector measures the time it takes for the pulse to arrive at the vehicle and return to the transmitter. The receiver is gated on and off with a user-adjustable interval that helps to differentiate between pulses reflected from the road surface and those reflected from vehicles. The detection gate is usually set to allow detection of an object at a distance greater than approximately 0.5 m above the road surface. This is accomplished by closing the detection gate several milliseconds before the reflected signal from the road surface arrives at the detector. Automatic pulse repetition frequency control is used to reduce effects of multiple reflections and to improve the detection of high-speed vehicles. These goals are met by making the pulse repetition period as short as possible by transmitting the next pulse immediately after the reflected signal from the road is received.⁽¹¹⁾ A hold time T_h (composite values from manufacturers range from 115 ms to 10 s) is built into the detectors to enhance presence detection.

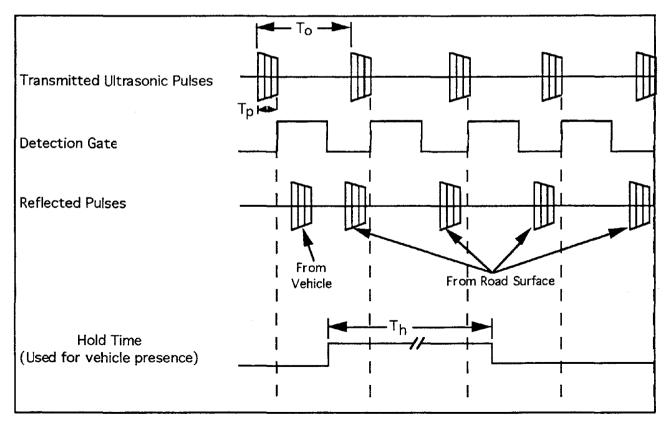


Figure 5-9. Operation of Range-Measuring Ultrasonic Detector

The speed (Doppler) measuring detector transmits a continuous wave of ultrasonic energy. It detects the passage of a vehicle by a shift in the frequency of the received signal. Vehicle speed can be calculated from the pulse width of an internal signal, generated by the detector's electronics, that is proportional to the speed of the detected vehicle.

5.5 PASSIVE ACOUSTIC DETECTOR ARRAYS

Vehicular traffic produces acoustic energy or audible sounds from a variety of sources within each vehicle and from the interaction of the vehicle's tires with the road. Although unintentional, the radiated sound acts as a beacon signal containing information that can be extracted by roadside acoustic energy detectors.

Arrays of passive acoustic microphones provide spatial directivity from which sounds are continuously detected and processed from a specific location along the highway. Sounds from locations outside the detection zone are rejected or attenuated. The size and shape of the detection zone are determined by the aperture size, processing frequency band, and installation geometry of the acoustic array.

When a vehicle passes through the detection zone, an increase in sound energy is detected by the signal processing algorithm and a vehicle presence signal is generated. When the vehicle leaves the detection zone, the sound energy level drops below the detection threshold and the vehicle presence signal is terminated. Passive acoustic arrays can replace magnetic induction loops by providing vehicle presence outputs in the form of contact closures. Using this input, a traffic signal controller can calculate various traffic flow measures, such as volume, occupancy, and average speed.

5.6 INDUCTIVE LOOP DETECTORS

The data supplied by inductive loop detectors are vehicle passage, presence, count, and occupancy. The principal components of an inductive loop detector are one or more turns of insulated wire buried in a shallow cutout in the roadway, a lead-in cable which runs from a roadside pull box to the controller, and an electronics unit located in the controller cabinet. The wire loop is excited with a signal ranging in frequency from 10 kHz to 200 kHz and functions as an inductive element in conjunction with the electronics unit. When a vehicle stops on or passes over the loop, its inductance is decreased. The decreased inductance increases the oscillation frequency and causes the electronics unit to send a pulse to the controller, indicating the presence or passage of a vehicle.

The introduction of digital signal processors has allowed more reliable, accurate, and precise measurement of the change in oscillation frequency or period associated with the loop output that is produced when a vehicle passes over the loop. The improved capability of the detector, in turn, has increased the accuracy of the presence, count, and occupancy measurements. The data processed in the electronics unit can be either the changes in frequency or period that are measured, or the ratio of the change to its initial value.⁽¹²⁾ The processing techniques are called:

- Digital frequency shift,
- Digital ratio frequency shift,
- Digital period shift, and
- Digital ratio period shift.

The inductive loop detector represents a mature technology. Reliability of the loop has been improved through better packaging and installation techniques. These include delivery of loops already encased by the manufacturer in protective materials, more thorough cleaning of debris from the sawcut, and the use of better sealants in the installation process.

The output of most current inductive loop detectors is a simple relay or semiconductor closure, signifying the presence or absence of a vehicle. In advanced detector processing systems, some vehicle classification and fault detection can be performed by digitizing the detector output and feeding it to a microprocessor containing embedded signal processing algorithms. These match the detector output to stored signatures for specific vehicle types or fault conditions. Digital codes can be output to identify the type of vehicle detected or report detection faults to a central processing unit.

In the past two decades, loop detector technology has become the most widely used and accepted traffic detector technology in America today. The loop detector system, however, may still suffer from poor reliability, primarily from improper connections made in the pull boxes and in the application of sealants over the sawcut. These problems are accentuated when loops are installed in poor pavement or in areas where utilities frequently dig up the roadbed. Reliability can be improved by installing loops using newer procedures and loop wire protective enclosures developed by manufacturers and user agencies. Improved traffic system operation can be obtained by holding daily loop status meetings at which the malfunctioning loop detector locations are identified and repair teams are dispatched. Another disadvantage of loops is their inability to directly measure speed. If speed is required, then a two-loop speed trap is employed or an algorithm involving loop length, average vehicle length, time over the detector, and number of vehicles counted is used with a single loop detector.

5.7 MAGNETIC DETECTORS

Magnetic detectors indicate the presence of a metallic object by the disruption it causes in an induced or natural magnetic field. These detectors may be active devices, as with magnetometers, or passive devices, as with magnetic detectors. An example of a magnetometer is the 1-inch (25.4-mm) diameter by 4-inch (101.6-mm) long (approximate) detector that is buried about 12 to 18 inches (304.8 to 457.2 mm) below the surface of a road. Two types of passive magnetic detectors exist. One is subsurface-mounted and the other is mounted flush with the roadway. The primary use of magnetic anomaly detectors is to supplement or enhance data from other types of traffic detectors, although they are sometimes used in stand-alone applications.

5.7.1 Magnetometers

Magnetometers are active devices, excited with an electrical current in windings around a magnetic core material. They measure the passage of a vehicle when operated in the pulse output mode and give a continuous output as long as a vehicle occupies the zone of detection when operated in the presence mode. They are used where point or small-area location of a vehicle is required, such as on bridge decks and viaducts where inductive loops are disrupted by the steel support structure or can weaken the existing structure.

The Self-Powered Vehicle Detector (SPVD), developed with FHWA support, is a magnetometer detector with a self-contained battery and transmitter that broadcasts passage or presence information to a receiver that can be located remotely in a controller cabinet. A direct connection (lead-in cable) is not required. An antenna is built into the housing that encloses the magnetometer electronics and battery. The current SPVD model fits into a cylindrical hole 6 inches (152.4 mm) in diameter and 22 inches (558.8 mm) deep. Most of the volume is occupied by the battery. SPVDs have applications where temporary installations are needed or where they can be easily mounted under bridges or viaducts. Their suitability for permanent installation is a function of traffic volume and battery type. Telemetry-based traffic counters can also use spread-spectrum transmission to broadcast vehicle-count data to a receiver that can be located several miles away from the detector.

5.7.2 Passive Magnetic Detectors

Passive magnetic detectors sense perturbations in the Earth's magnetic flux produced when a vehicle passes over the detection zone. They require some minimum vehicle speed for detection, usually 3 to 5 mi/h (4.8 to 8.0 km/h) and, hence, cannot be used as a presence detector.

The two types of passive magnetic detectors differ only in their installation and size. One type is installed by tunneling under the roadway and inserting it into non-ferrous conduit. The other type is installed flush with the pavement. The first is 2 inches (50.8 mm) in diameter by 20 inches (508.0 mm) long. The second is approximately 3 inches by 5 inches by 20 inches long (76.2 mm by 127.0 mm by 508.0 mm long), encased in a cast aluminum housing and flush-mounted with the road surface. Passive magnetic detectors are responsive to flux changes over a large area, covering up to three lanes. If the lanes are considerably wider than 12 feet (3.7 m), several detectors may be required to get a response from small vehicles and motorcycles.

5.7.3 Selection Criteria and Future Trends

The criteria for selecting a magnetic sensor include the desired occupancy and traffic flow accuracy, detector sensitivity, output data rate, minimum required vehicle speed, and cost.

The infusion of new digital processing technology in the area of magnetic anomaly detection promises to significantly improve the performance of existing magnetic detectors, justifying a reassessment of their supplementary role in vehicle detection. In addition, the ability to assemble a group of magnetometers into an array sharing a common signal processor promises the ability to locate, track, and classify vehicles in a multilane scenario using a row of aboveground detectors.

5.8 RELATIVE COST OF DETECTORS

A satisfactory cost comparison between various detector technologies can only be made when the specific application is known. For example, a relatively inexpensive ultrasonic, microwave, or passive infrared detector may seem to be the low-cost choice at first glance for instrumenting a surface-street intersection if inductive loop detectors are not desired. But when the number of detectors needed is taken into account along with the limited amount of directly measured data that may be available (e.g., speed is not measured directly by a passive infrared detector), a more expensive detector such as a video image processor may be the better choice. For example, if it requires 12 to 16 conventional

inductive loop detectors (or ultrasonic, microwave, or infrared, etc. detectors) to fully instrument an intersection, the cost becomes comparable to that of a VIP. Furthermore, the additional traffic data and visual information made available by the VIP may more than offset any remaining cost difference. In this example, the VIP is assumed to meet the other requirements of the application, such as the desired 100 percent detection of vehicles at the intersection.

Similar arguments can be made for freeway applications using multiple detectors and requiring information not always available from the less expensive detectors.

Still other applications, such as simple monitoring of multilane freeway or surface-street vehicle presence and speed, may be performed by two microwave radars mounted in a side-looking configuration. In this case, the radar detectors replace a greater number of loops that would otherwise need to be installed in the travel lanes. Furthermore, the radar poten-tially provides direct measurement of speed at a greater accuracy than provided by the loops.

Other factors that affect the cost and selection of detectors are the maturation of the designs and manufacturing processes for detectors that use the newer technologies, the attainment of reduced prices through quantity buys, and the availability of mounting locations and communications links at the application site.

5.9 AUTOMATIC VEHICLE IDENTIFICATION

Automatic vehicle identification (AVI) aids automated toll collection in many applications in North America, Europe, and Asia. Vehicles equipped with AVI transponders are used to determine travel times between fixed points as the vehicles move across a roadway network. As electronic toll collection continues to increase, the large universe of equipped vehicles will produce a secondary benefit by enabling automated measurements of travel time and congestion. In the New York/New Jersey region, the TRANSCOM program uses AVI observations to track individual vehicles for real-time measurement of travel time. The transponder-equipped vehicles are identified by AVI readers along the roadway. The data are used to determine speed and travel times for incident and congestion management.

Merging this technology with a beacon system can provide true two-way communication with the vehicle. With this capability, realtime traffic data such as origin-destination pairs, travel time, and spot speeds can be collected from the vehicle, while the driver obtains motorist information such as congestion delays, parking availability, and alternative route choices. There are a number of projects being conducted in the Commercial Vehicle Operations sector of IVHS that anticipate the use of Automated Vehicle Identification, Automated Vehicle Location, and Automated Vehicle Classification for fleet operations and regulatory uses. These include the HELP (Heavy Electronic License Plate)/Crescent Project and the Advantage I-75 Project which promise reductions in the time it takes freight to move across the participating regions of the United States and Canada.

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6. TASK C SUMMARY DEVELOP VEHICLE DETECTOR LABORATORY TEST SPECIFICATIONS AND LABORATORY TEST PLAN

6.1 LABORATORY TEST SPECIFICATIONS FOR VEHICLE DETECTORS

This section reviews the performance specifications and presents a test plan for state-of-the-art, above-the-road detectors that were evaluated in the laboratory tests conducted at the Hughes Aircraft Company, Fullerton, CA, facility and in the City of Los Angeles. These include ultrasonic, microwave, active infrared, passive infrared, and video image processors (VIPs). Although VIPs were not evaluated during the laboratory tests because they were not made available by the manufacturers at that time, they were later included in the field evaluations. The purposes of the laboratory tests were to have Hughes verify the performance of the detectors, with manufacturer assistance where needed, before field deployment and to train Hughes personnel in installing and operating the detectors.

6.1.1 Ultrasonic Detectors

Presence-only and speed-measuring ultrasonic detectors are currently manufactured. These enable direct measurements of vehicle presence, occupancy, and speed (depending on the detector type) to be made.

The following are the current performance characteristics of ultrasonic detectors.^(1,2,3)

- 1. Detectable objects. Detect subcompact cars and larger vehicles. Future applications will require detection of motorcycles and bicycles as well.
- 2. Waveform. Presence-measuring ultrasonic detectors transmit a pulse waveform, while speed (Doppler)measuring detectors use continuous wave (CW).
- 3. Frequency. The frequencies transmitted are between 25 kHz and 50 kHz, depending on the manufacturer and model.

- 4. Beamwidth. The beamwidth is designed to detect vehicles in single lanes. The upper limit to the beamwidth and sidelobe levels is driven by the requirement to reject vehicles in adjacent lanes. The lower limit is driven by the need to detect lane straddlers. The beamwidth is thus a function of vehicle width, lane width, transducer sidelobes, and mounting height. Typical beamwidths establish patterns on the road surface that are 4 feet (1.2 m) wide at the specified mounting height.
- Speed measurement range. Speedmeasuring ultrasonic detectors presently respond to vehicles traveling between 2.5 and 75 mi/h (4.0 and 120.7 km/h).
- 6. Speed measurement accuracy. Two types of vehicle speed are required: microscopic or spot vehicle speed and macroscopic or composite speed of a group of vehicles. Required accuracy for microscopic speed measurements is between 3 and 5 percent for signalized intersection applications and ±1 mi/h (1.6 km/h) for microscopic and macroscopic freeway incident detection applications.
- Minimum distance between vehicles. Current detectors will detect two separate vehicles when they are 1.5 to 10 meters apart, depending on detector design and speed of the vehicle.
- Detection Range. The required detection range is 8 to 20 meters for vehicle counting, occupancy, and speed measurements. Ultrasonic detectors may not be suitable for longer range surveillance applications as may be required for freeway incident detection.
- 9. Installation configuration. Both overhead and side-looking operations

are accommodated within the performance limits discussed above.

10. Power requirements. Must meet NEMA and Type 170 controller standards. These are 120 VAC, 60 Hz, with current draw not to exceed the capacity of the particular controller and installation. Some controllers have DC voltage available; however, the voltage and current availability vary and must be confirmed with the operating agency.

6.1.2 Microwave Detectors

By appropriate processing of the information in the received energy, direct measurements of vehicle presence, occupancy, and speed (depending on detector capability) can be obtained.

- 1. Detectable objects. Detectors sense subcompact cars and larger motorized vehicles. It is desirable to detect motorcycles and bicycles as well.
- Detection pattern. The antenna pattern may be designed to illuminate single or multiple traffic lanes. Some multiple-lane applications, such as vehicle counting, require signal processing to differentiate between vehicles detected in the different lanes. If designed for intersection traffic management, single-lane coverage is required for measurement of left-turn lane occupancy. Multiple-lane coverage may be acceptable for detecting through-lane occupancy.
- 3. Detection angle. Microwave detector incidence angles can be adjusted in both the azimuth and elevation planes.
- 4. Response time. The response time is defined as the time for an input, generated by a vehicle in the field of regard, to be processed by the detector and registered as an output in the form of a presence, count, or other appropriate indication. A

response time is also defined for the time required by the detector to drop an output when the vehicle leaves the field of regard. The response time of current models is <0.3 seconds. The upper limit may be unacceptable for counting high-speed vehicles in high-density traffic.

- 5. Hold time. Detector hold times are designed to eliminate dropout of vehicle detections as may occur when towing vehicles with long tongue couplings. A hold time retains vehicle presence during a potential dropout period until new data are received and averaged into the next vehicle presence or velocity calculation. Current detection hold times vary with the application, ranging from continuous for Doppler detectors to 1 second for detectors that respond to vehicle presence.
- 6. Mounting configuration. Microwave detectors are mounted above the roadway in forward-looking, rear-looking, and side-looking configurations.
- 7. Speed measurement range. The minimum vehicle speed measured is approximately 3 mi/h (4.8 km/h) for Doppler motion detectors and the maximum is 65 mi/h (104.6 km/h) to greater than 85 mi/h (136.8 km/h), depending on the model. True presence microwave detectors can detect stopped vehicles.
- 8. Speed measurement accuracy. Two types of vehicle speed measurement are required: microscopic or spot vehicle speed and macroscopic or composite speed of a group of vehicles. Required accuracy for microscopic speed measurements is ±3 to 5 percent for signalized intersection applications and ± 1 mi/h (±1.6 km/h) for microscopic and macroscopic freeway incident detection applications. Current microwave Doppler detectors measure speed within ±2 to 3 mi/h $(\pm 3.2 \text{ to } 4.8 \text{ km/h})$. One true presence microwave radar specifies

its speed measurement accuracy at ± 10 percent.

- 9. Power requirements. Must meet NEMA and Type 170 controller standards. These are 120 VAC, 60 Hz, with current draw not to exceed the capacity of the particular controller and installation. Some controllers have DC voltage available; however, the voltage and current availability vary and must be confirmed with the operating agency.
- 10. FCC approval. The operator does not need FCC approval as the manufacturer has obtained this and has marked the radar with the proper identifier, e.g., meets requirements of FCC Rules, Part 15. These rules specify the center frequency, bandwidth, and output power of the radar.

6.1.3 Active Infrared Detectors

Active infrared (IR) detectors transmit a beam of light and detect a portion of it that is reflected back to the detector by the objects in the field of view. They provide presence, speed, count, and occupancy data in day and night operation. When a laser diode is used as the transmitting energy source, the detector can also provide vehicle profile and shape data, and, hence, be used for vehicle classification.

Specifications for the IR detector that uses a laser diode as the active transmitting element are: (5,6)

- Detection indication. In addition to using LEDs as potential transmitters of infrared energy, high-intensity LEDs are also used as indicators of the output state of the detector, i.e., to alert the operator as to whether there is a vehicle in the field of view of the detector.
- Detection pattern. The footprint on the road surface should emulate a 1.8-m x 1.8-m (6-ft x 6-ft) loop at a range of 9.2 m (30 ft) for signalized intersection control and freeway incident detection. It is also

desirable to emulate a 4.3 -m x1.8-m (14-ft x 6-ft) loop and have a detection range of over 15.2 m (50 ft) for signalized intersection control and freeway ramp-metering applications.

- 3. Warmup time. The detector is operational within 10 seconds after application of power.
- 4. Stability. The detector must respond only to changes in scene reflectivity. Atmospheric effects, such as those caused by clouds shadowing the field of regard, shall not produce false vehicle detections in excess of those allowed for a particular IVHS application.
- 5. Response time. The response time is defined as the time for an input, generated by a vehicle in the field of regard, to be processed by the detector and registered as an output in the form of a presence, count, or other appropriate indication. A response time is also defined for the time required by the detector to drop an output when the vehicle leaves the field of regard. The response time of laser diode type IR detectors is ≈10 ms when a vehicle enters or leaves the field of regard.
- 6. Presence hold time. IR detectors using laser diode transmitters hold the presence for as long as a vehicle is in the field of view. This specification can be tailored, however, to meet individual operations requirements of the cognizant agency.
- Speed measurement range. Currently available detectors measure speeds between 0 and >80 mi/h (128.7 km/h).
- Speed measurement accuracy. The calculated accuracy for vehicle speed measurement is ±1 mi/h (±1.6 km/h) up to 70 mi/h (112.7 km/h).
- 9. Detection range. The vehicle detection range is 1.5 to 15 meters.

10. Power requirements. Must meet NEMA and Type 170 controller standards. These are 120 VAC, 60 Hz, with current draw not to exceed the capacity of the particular controller and installation. Some controllers have DC voltage available; however, the voltage and current availability vary and must be confirmed with the operating agency.

6.1.4 Passive Infrared Detectors

Passive infrared detectors sense objects through the energy that they emit. The detectors currently on the market usually have a single detector element that provides signals giving vehicle presence, occupancy, and count.

Characteristics of current passive infrared detectors include:⁽⁷⁾

- 1. Presence hold time. The presence signal is held as long as a vehicle remains in the field of view of the detector, up to 6 minutes maximum. This parameter can be designed to have other values as required.
- 2. Response time. Response times of current detectors are a maximum of 500 ms.
- 3. Speed measurement range. State-ofthe-art passive infrared detectors detect stopped vehicles and those traveling at freeway speeds.
- 4. Stability. For the scene under observation, the detector must respond only to changes in the temperature and emissivity of the vehicles which are to be detected. Atmospheric effects, such as those caused by clouds shadowing the field of regard or rain-induced cooling of the background, shall not produce false vehicle detections in excess of those allowed for a particular IVHS application.
- 5. Sensitivity. An operator-controlled sensitivity adjustment may be required to give adequate dynamic range to detect vehicles under the

anticipated weather conditions. The sensitivity must allow operation without continually changing settings to accommodate changing input levels due to varying climatic conditions.

- 6. Detection range. The vehicle detection range is 6.4 to 15 meters.
- 7. Power requirements. Must meet NEMA and Type 170 controller standards. These are 120 VAC, 60 Hz, with current draw not to exceed the capacity of the particular controller and installation. Some controllers have DC voltage available; however, the voltage and current availability vary and must be confirmed with the operating agency.

6.1.5 Video Image Processors

A video image processor is a combination of software and hardware components that extract desired information from the output of an imaging sensor, such as a conventional TV camera or an infrared camera. The combination of imaging hardware, processor, and software forms a VIP detector.

The following represent current VIP specifications. (8,9)

- 1. Detectable objects. Current VIPs sense motorcycles, subcompact cars, and larger motorized vehicles.
- 2. Number of lanes observed. Current systems provide vehicle data over at least three lanes. It is desirable to extend the coverage to the equivalent of five lanes in order to monitor emergency areas (such as highway shoulders), ramps for freeway applications, higher capacity freeways that have additional through-lanes, and multiple-lane surface-street intersections.
- Speed measurement range. VIP detectors are capable of measuring speeds between 0 and 160 mi/h (257.5 km/h).
- 4. Speed measurement accuracy. Two types of vehicle speed measurement

are required: microscopic or spot vehicle speed, and macroscopic or composite speed of a group of vehicles. Required accuracy for microscopic speed measurements is ± 3 to 5 percent for signalized intersection applications and ± 1 mi/h (± 1.6 km/h) for microscopic and macroscopic freeway incident detection applications.

- 5. Vehicle count accuracy. Counts are generally accurate to within ±5 percent.
- 6. Minimum distance between vehicles. VIP detectors are required to detect vehicles separated by 1/3 to 2/3 of a meter (1 to 2 feet) for the city arterial application. In freeway applications, the intervehicle spacing may be different (e.g., 10 to 30 m) depending on the comfort time of the driver (the time required or anticipated by the driver to stop the vehicle) and traffic congestion. In fact, in heavy congestion, the minimum vehicle separation may be the same as on an arterial. The maximum detection distance of a VIP along the surface of a road is a function of mounting height, intervehicle distance or gap, and vehicle height as described in Section 5.
- Detection Range. The detection range is 8 meters to 20 meters for applications requiring traffic data close to the mounting location, and a minimum of 92 meters (300 feet) for adaptive, real-time signal control at city intersections and for freeway incident detection and traffic management.
- Power requirements. Must meet NEMA and Type 170 controller standards. These are 120 VAC, 60 Hz, and current draw not to exceed the capacity of the particular controller and installation. Some controllers have DC voltage available; however, the voltage and current availability vary and must be confirmed with the operating agency.

- 9. Operator intervention requirements. The detector shall function without operator adjustments during setup or normal operation to account for:
 - a. Day-night transitions.
 - b. Shadows on the roadway.
 - c. Reflections from vehicles or pavement during rain.
 - d. Weather changes.

The following conditions do require operator intervention:

- e. Repositioning the field of view.
- f. Initialization.
- g. Resetting the vehicle detection zone.

6.1.6 Inductive Loop Detectors

The specifications for the inductive loop detector amplifier models actually used in tests coordinated with the City of Los Angeles Department of Transportation and the state transportation departments supporting the field tests are included in Appendix G. Catalog pages were provided in the Task D Report.

6.1.7 Magnetometers

The specifications for the models actually used in tests coordinated with the City of Los Angeles Department of Transportation and the state transportation departments supporting the field tests are included in the Task D Report.

6.1.8 Interface, Cost, and Environmental Requirements

The following requirements apply to all of the detectors.

- 1. Communications data rates.
 - a. Video imagery:

A maximum of 128 KB/s (112 KB/s desirable) shall be used for imagery transmission with a VSAT communications link. Bandwidth may also be limited by the capacity of available leased lines or spreadspectrum radio channels. b. Detector status data:

- (1) Urban application: 88 bytes/30 s from each intersection.
- (2) Freeways: 250 bytes/30 s from each site.
- (3) Identification and location of each vehicle equipped with a sensor/radio: 30 bytes/30 s.
- 2. Cost.
 - a. Must be competitive with the lifecycle cost of multiple inductive loop detectors as used in the desired application.
 - b. Periodic maintenance is acceptable. The time interval between maintenance operations should be as large as possible. A 2-month interval may be satisfactory for some applications. Maintenance requirements should be verified by consultation with the end customer.
- 3. Mounting configuration for city arterial application.

The following are preliminary guidelines for mounting detectors:

- a. Desirable to accommodate side mounting from a light pole or other utility pole. Detector should also be capable of being mounted at an intersection (on traffic light support pole) and looking 83 to 167 meters (250 to 500 feet) back toward oncoming traffic.
- b. Desirable for detectors to sense vehicles in multiple lanes to minimize the number of detectors needed to view the roadway. Utilization of a fish-eye lens to scan an intersection may help achieve this result with VIPs. (These comments also apply to freeway use of detectors.)

- c. Detector mounting height of 17 feet (5.2 m) is compatible with all utility poles.
- d. Traffic lanes are 10 to 12 feet (3.0 to 3.7 m) wide.
- e. Parking lane (lane nearest curb) is 17 feet (5.2 m) wide.
- f. Setback of traffic light from curb is 2 feet (0.6 m).
- g. Number of lanes to be monitored is one, two, or three.
- 4. Interfaces.

The interfaces depend on whether the test site uses a Type 170 or NEMA controller. The specific controller specification shall be used to define the interface between the detector, amplifier, and controller. General information about the amplifier/ controller interface is given below.

- a. Type 170 controller: (10)
 - (1) 6800 microprocessorbased.
 - (2) Cards are 6-1/2 inches by 4 inches (165.1 mm by 101.6 mm).
 - (3) Contact closure needed from detector.
 - (4) Input/output lines typically available are: ±24 volts, reset, two pair field connections, two pair controller connections.
- b. NEMA controllers: Some use an 8085, 8-bit processor. Use NEMA Pub. TS-1 for detailed interface specifications.
- 5. Voltage.

Per Type 170 and NEMA controller specifications.

6. Temperature.

The outside temperature extremes for the detectors are determined from the following considerations:

The NEMA range for outside ambient temperature extremes is -30°F (-34°C) $to + 165^{\circ}F (+74^{\circ}C).(11)$ Some application sites may require the full military specification temperature range of -30°C to +125°C; however, colder states such as Minnesota may require designs that accommodate lower minimum outside operating temperatures. Heaters in weatherproof enclosures may be needed to control the operating environment of the electronic and mechanical components. Conversely, agencies operating in desert environments may require components capable of operating at higher outside temperatures. Here coolers or fans may be needed in the enclosures.

7. Humidity.

The detectors shall be designed to operate under conditions where the relative humidity complies with Table 2-1 of the NEMA Pub. TS-1 (1989) for Traffic Control Systems.

8. Lightning protection.

Lightning protection is recommended for all types of detectors.

9. Vibration and shock.

Vibration and shock hardening are needed to withstand swinging from poles during high winds and earthquakes. The following NEMA standards may have to be improved to meet these goals. Also, some detectors, such as nonimaging IR and ultrasound, work best when they do not swing.

a. The NEMA vibration standard [paragraph 2.2.5 of TS-1 (1989)] requires the detector to maintain all of its functions and physical integrity when subjected to a vibration of 5 to 30 cycles/s up to 0.5g applied in each of three mutually perpendicular planes.

- b. The NEMA shock standard [paragraph 2.2.6 of TS-1 (1989)] specifies that the detector shall suffer neither permanent mechanical deformation nor any damage that renders the unit inoperable when subjected to a shock of 10g's $\pm 1g$ applied in each of three mutually perpendicular planes.
- 10. Electromagnetic energy health hazard.

The detector shall present no health hazard from emitted radiation. As a minimum, use current standards set by professional organizations and government agencies for safe levels of microwave and electromagnetic radiation power densities. The current standard is <1 mW/cm² (10 W/m²) for indefinitely prolonged exposure. A factor of 10 less exposure may be desirable for largescale public applications to further reduce anxiety in the public.

11. Other operating and storage conditions.

Use NEMA Publication TS-1 (1989) as a guide.

12. Vendor notification of extreme field test conditions.

The vendors will be notified of the anticipated outside temperature, humidity, wind, and vibration levels at each field test site, and will be required to make recommendations for proper operation of their detectors.

6.1.9 Summary

Table 6-1 compares the ability of the various overhead-mounted detector technologies to provide key traffic parameters such as presence, occupancy, flow, and speed on single and multilane roads. However, all detectors based on a given technology may not provide all of these parameters. The data available are a function of how the technology was implemented and the requirements set by the manufacturer or the transportation agency for measuring and transmitting particular data.

Table 6-1. General Qualitative Capabilities of Current Deter	tor Technologies
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Detector Technology	Presence	Occupancy	Volume	Speed	Multilane Coverage		
Ultrasonic	Direct	Direct	Direct	Direct & Indirect	No		
Microwave	Direct	Direct	Direct	Direct	Direct		
Active Infrared	Direct	Direct	Direct	Direct & Indirect	Direct		
Passive Infrared	Direct	Direct	Direct	indirect	Νο		
Video Image Processor	Direct	Direct	Direct	Direct	Direct		
Key: Direct = Via direct measurement of data Indirect = Via calculations based on measured data							

6.2 LABORATORY TEST PLAN

The laboratory test plan and equipment were used to confirm the performance of the overhead-mounted traffic detectors described in Section 1. These detectors were previously tested by the manufacturer before delivery to Hughes. Therefore, the tests described below are in the nature of end-to-end system evaluation tests that confirm proper detector operation, rather than more detailed tests that evaluate the performance of subsystems within each detector.

The specific objectives of these tests were:

- Verify that detector operation conforms to vendor specifications.
 - The specifications measured under this objective are those that do not require the use of special manufacturer-specific test equipment, unless it is normally supplied with the detector.
 - The intent of these tests is not to confirm all manufacturer specifications, but rather to verify those most critical to detector operation for the state field tests. Those specifications not directly verified at Hughes will be confirmed using manufacturer test data and reports.
- Identify and measure other detector performance characteristics that affect traffic parameter values.

6.2.1 Ultrasonic Detectors

The ultrasonic detector test procedures for vehicle presence and speed detectors are based on information obtained from the detector vendors.

The first three tests and measurements below apply to Sumitomo detectors.⁽¹²⁾

- 1. Transmit frequency and output power of the presence detector.
 - a. With the Sumitomo ultrasonic presence detector, the measure-

ment of transmit frequency and output power is performed by connecting the transmitterreceiver to the input/output (I/O) terminal of the detector cabinet. Other manufacturers' equipment may require the use of transducers (i.e., special microphones) to convert the transmitted ultrasonic energy into electrical energy in order to perform these measurements.

- b. The ultrasonic transmit frequency and peak output power will be within the tolerances specified by the vendor.
- 2. Field of view (FOV) of the presence detector.
 - a. The Sumitomo ultrasonic transmitter-receiver feeder will be connected to the I/O terminal of the detector cabinet. A cylinder will be placed in front of the transmitter-receiver as a standard reflection object, simulating a vehicle. The cylinder is approximately 0.2 m in diameter and 2 m in length. The distance between the cylinder and the transmitterreceiver is approximately 5 m.
 - b. The measured FOV will be 1.2 m ± 0.12 m (i.e., ± 10 percent) and the detection lamp on the detector cabinet will be on when the cylinder is within the FOV of the detector.
- 3. Speed measurement accuracy of the speed detector.

This test measures the Doppler frequency shift and the received signal amplitude using the transmitterreceiver of the ultrasonic speed detector.

a. Connect the ultrasonic receiver cable to the input/output (I/O) terminal of the detector cabinet. A pinwheel type of reflector will be placed in front of the transmitter-receiver as a standard reflection object to simulate the return from a vehicle. The reflector's turning fins simulate vehicle movement. The distance between the reflector and the transmitter-receiver will be about 2 m.

b. The received amplitude and frequency of the Doppler signal will be measured at the detector unit and verified to be within the range prescribed by the vendor.

The following end-to-end operational test applies to the ultrasonic detectors built by Microwave Sensors.⁽¹³⁾

- 4. End-to-end operational test.
 - a. Test equipment.
 - (1) Square reflector target at least 6 inches (152.4 mm) on a side.
 - (2) 10 to 24 VDC, 0.15-amp (min) power supply.
 - b. Operational test.
 - (1) Remove the enclosure cover.
 - (2) Connect power supply.
 - (3) Place square reflector 3 feet (0.9 m) from transmitter.
 - (4) Turn transmitter on after equipment warm-up time has elapsed.
 - (5) Verify that appropriate LED indicator is on.
- 5. Range test.
 - a. Objectives. This test applies to all ultrasonic detectors. The objectives are to learn how to optimally install the detectors

for the field tests and to examine their detection capabilities against real vehicles. Range testing will verify the detection range versus different size and shape motorized vehicles, speed (if the detector is designed to measure this parameter), and minimum spacing for differentiating between two vehicles in the same lane. The boresight direction of the ultrasonic speed and presence detectors will be determined before they are mounted on tower, light pole, and overhead sign structures used in these tests. A laser range finder may be used to aid in measuring the footprint on the ground.

Video imagery of the tests will be recorded to help document the results. To aid in data evaluation, markers will be placed on the test track at regular intervals. Data sheets will be prepared in advance of the tests to ensure that all required data are recorded and test equipment identified. Test procedures may be expanded as needed to ensure test integrity and repeatability.

- b. Detection zone. The size of the detection zone will be measured by rolling a vehicle or moving the standard reflection object through the field of view and noting when the detector gives an output.
- c. Minimum spacing between vehicles. The minimum spacing for differentiating between vehicles will be found by parking a vehicle at one end of the detection zone and rolling another towards it from the other end. The distance recorded when the detector no longer distinguishes between the two vehicles is the minimum spacing. For detectors

that respond to vehicles traveling above a minimum speed, a vehicle simulator, such as a metal plate, will be towed behind the first vehicle. The spacing between the vehicle and the plate will gradually be decreased from run to run to determine the minimum spacing required for vehicle differentiation. Alternatively, a second vehicle may be towed behind the first at a preset distance.

- d. Detection range. To characterize detection range versus vehicle type and speed, tests will be performed at the minimum and maximum operating ranges of the detectors. Automobiles and pickup trucks will be driven through the field of view of the detectors at speeds between 5 and 55 mi/h (8.0 and 88.5 km/h), in 10-mi/h (16.1-km/h) increments.
- e. Sensitivity to vehicle density. As time permits, the performance of the detectors will be verified against low-density (<800 vehicles per hour per lane) and high-density (>1800 vehicles per hour per lane) traffic flows. These data will aid in establishing optimal use of the detectors during field testing. The speed measurement accuracy of applicable detectors will be verified during these tests by using speed surveys performed by the host agency, e.g., the City of Los Angeles Department of Transportation. Techniques to be used include radar speed guns, infrared speed guns, and vehicles traveling at predetermined speeds through the detection zones.

6.2.2 Microwave Detectors

These tests for microwave vehicle presence and speed detectors supplement the signal-tonoise, speed calibration, and output level adjustment tests performed by the vendors. The end-to-end operational test applies to microwave detectors built by Microwave Sensors.⁽¹⁴⁾ Microwave radar detectors built by other vendors may require modifications to this test.

- 1. End-to-end operational test.
 - a. Test equipment.
 - (1) Square reflector target at least 6 inches (152.4 mm) on a side.
 - (2) 10 to 24 VDC, 0.25-amp (min) power supply.
 - b. Operational test.
 - (1) Remove the enclosure cover.
 - (2) Connect power supply.
 - (3) Place square reflector 3 feet (0.9 m) from transmitter.
 - (4) Turn transmitter on after equipment warm-up time has elapsed.
 - (5) Verify that appropriate LED indicator is on.
- 2. Minimum and maximum detectable radar cross section.

Calibrated corner reflectors (CRs) will be inserted into the FOV of the true presence detectors to determine the minimum detectable target size and the maximum target size that can be detected without saturating the detector. The latter result is not expected to affect detector operation for traffic management applications. An approximate range of CR sizes is from 5 m² to 100 m². Several reflectors in this range will be selected. Since the transmitted and received waveforms are linear and like polarized, trihedral (odd bounce) reflectors will be used.

- 3. Range test.
 - a. Objectives. This test applies to all microwave detectors. The objectives and testing techniques are the same as those discussed earlier for the ultrasonic detectors. The tests will verify boresight, detection range, sensitivity to intervehicle spacing, and beam patterns. If the detector measures speed, then its capability to measure speeds of individual and groups of vehicles will be verified.
 - b. Detection zone. The size of the detection zone will be measured by rolling a vehicle or inserting a corner reflector through the field of view and noting when the detector gives an output.
 - c. Minimum spacing between vehicles. The minimum spacing for differentiating between vehicles will be found by parking a vehicle at one end of the detection zone and rolling another towards it from the other end. The distance recorded when the detector no longer distinguishes between the two vehicles is the minimum spacing. For detectors that respond to vehicles traveling above a minimum speed, a vehicle simulator, such as a metal plate, will be towed behind the first vehicle. The spacing between the vehicle and the plate will gradually be decreased from run to run to determine the minimum spacing required for vehicle differentiation. Alternatively, a second vehicle may be towed behind the first at a preset distance.
 - d. Detection range. To characterize detection range versus vehicle type and speed, tests will be performed at the minimum and maximum operating ranges of the detectors, some of which extend

out to 300 feet (91.4 m). Automobiles and pickup trucks will be driven through the field of view of the detectors at speeds between 5 and 55 mi/h (8.0 and 88.5 km/h), in 10-mi/h (16.1-km/h) increments.

e. Sensitivity to vehicle density. As time permits, the performance of the detectors will be verified against low-density (<800 vehicles per hour per lane) and high-density (>1800 vehicles per hour per lane) traffic volume. These data will aid in establishing optimal use of the detectors during field testing. The speed measurement accuracy of applicable detectors will be verified during these tests by using speed surveys performed by the host agency, e.g., the City of Los Angeles Department of Transportation. Techniques to be used include radar speed guns, infrared speed guns, and vehicles traveling at predetermined speeds through the detection zones.

6.2.3 Active Infrared Detectors

The following laboratory procedures are for testing Schwartz Electro-Optics active IR detectors that use a laser diode as the transmitting energy source.⁽¹⁵⁾ This detector generates two beams to count and measure the speed of vehicles. Active IR detectors manufactured by other vendors may require modifications to the tests described below.

1. Setup.

The equipment for these tests consists of a sighting scope, IBM personal computer (PC), vendor-supplied test software, a black target having low reflectance, and a white target having high reflectance.

The layout for the laser radar IR detector functional tests is shown in Figure 6-1. The detector is oriented so

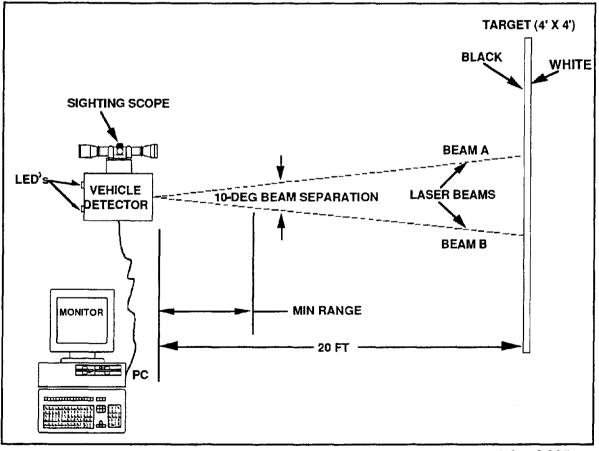
that the cross hairs of the sighting scope are centered on the black target at a distance of 20 feet (6.1 m). A PC is connected to the vehicle detector's serial interface. Initially, an opaque screen is used to block the laser transmitter beam at a distance less than the detector's minimum range (as specified by the vendor).

2. Self-test.

After the detector is warmed up, the manufacturer-supplied test software will initiate a series of five self-tests.

In the first, the integrity of the operating software in read-only memory (ROM) will be verified by calculating an 8-bit checksum. Each byte in ROM will be accumulated, ignoring overflow, to form an 8-bit value that will be compared with the checksum that is stored in ROM. The second self-test verifies proper functioning of the RAM through a nondestructive read/write test that toggles each bit in memory from on to off. The third self-test uses the microprocessor to measure the laser's pulse repetition frequency (PRF). The last two tests measure the power supply voltages and the detector's temperature using the microprocessor's A/D (analog-to-digital) converter.

If the traffic detector passes all five self-tests, the green LED will flash for about 2 seconds and then remain on continuously. If the red LED flashes and then remains on continuously, the detector has failed one or more of the self-tests.



1 ft = 0.305 m

Figure 6-1. Setup Used to Verify Functioning of Active IR Detector with Laser Diode Transmitter

3. Initialization.

With the laser beams blocked, the red LED indicator will glow continuously, indicating that the range is beyond the minimum/maximum limits. Upon removing the opaque screen, the red LED will turn off, indicating that the detector is measuring a range within its minimum/maximum limits.

If the screen is inserted in the beam at a range greater than the minimum range, but less than the range to the target minus 1 foot (0.3 m), the green LED will turn off. This corresponds to a vehicle-presence indication. When these tests are complete, turn on the PC and load the test software.

4. Return-signal strength.

With the vehicle detector viewing the black target at a distance of 20 feet (6.1 m), the return signal is displayed as a percent of full scale. If properly operating, the return signal will be within ± 10 percent of the baseline value supplied with the detector (for a given ambient temperature).

5. Range measurement.

If the laser power is within vendor specifications, the 20-foot (6.1-m) range to the black target is displayed on the monitor to within the ± 0.25 foot (76.2-mm) accuracy of the detector. When the target is reversed so that range measurements are made to the white surface, the range value displayed is the same as that for the black target to within the detector's accuracy.

6. Speed measurement function.

This test confirms that the detector's speed measurement circuit is functioning, but does not calibrate the speed measuring function. Pass the screen rapidly through the laser beams at a distance of 2 feet (0.6 m)

from the target. The PC monitor should indicate vehicle count and speed. The vehicle count should be increased in increments of one each time the procedure is repeated.

- 7. Range test.
 - a. Objectives. The objectives and test techniques for these range tests are the same as those for the ultrasonic detectors. The tests verify boresight, detection range, sensitivity to intervehicle spacing, and beam patterns. If the detector measures speed, then its capability to measure individual and group vehicle velocities is also verified.
 - b. Viewing angle. The detectors are installed on the tower or overhead structure at viewing angles that are a function of the manufacturer-specified mounting height.
 - c. Detection zone. The size of the detection zone is measured by rolling a vehicle or moving a reflector through the field of view and noting when the detector gives an output.
 - d. Minimum spacing between vehicles. The minimum spacing for differentiating between vehicles is found by parking a vehicle at one end of the detection zone and rolling another towards it from the other end. The distance recorded when the detector no longer distinguishes between the two vehicles is the minimum spacing.
 - e. Detection range. Detection range versus vehicle type and speed are measured to determine the minimum and maximum operating ranges of the detectors. Automobiles and pickup trucks are driven through the field of view of the detectors at speeds between 5 and 55 mi/h (8.0 and 88.5 km/h)

in 10-mi/h (16.1-km/h) increments.

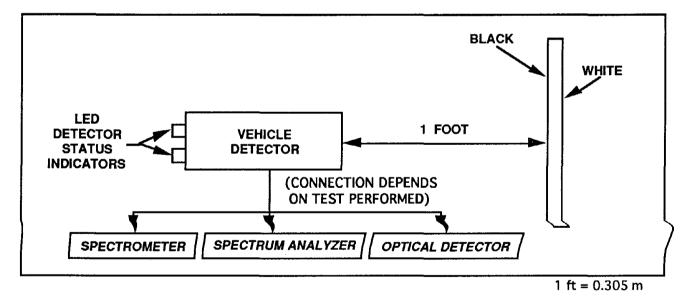
f. Sensitivity to vehicle density. The performance of the detectors are verified in low-density (<800 vehicles per hour per lane) and high-density (>1800 vehicles per hour per lane) traffic flows. These data aid in establishing optimal use of the detectors during field testing. The speed measurement accuracy of the laser radar is verified by using speed surveys performed by the host agency. Truth data are obtained from radar speed guns, infrared speed guns, and vehicles traveling at predeter-mined speeds in the detection zones.

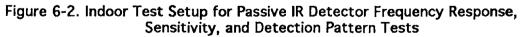
6.2.4 Passive Infrared Detectors

The indoor tests of the passive IR detectors are designed to measure frequency response, sensitivity, boresight, and effects of temperature changes on performance. The plans and equipment for testing passive infrared detectors are described below. (6)

1. Indoor test setup.

The passive infrared detector is mounted such that its field of view is focused on a calibrated "blackbody radiator" target as shown in Figure 6-2. After power is applied and the detector has stabilized, the blackbody emission source, whose temperature corresponds to that of an operating vehicle, is used to characterize the detector. The blackbody is located at a relatively short distance (e.g., 1 foot [0.3 m]) from the detector to obtain an accurate reading that is not degraded by background objects.





- 2. Indoor test.
 - a. Frequency response. A frequency spectrometer is used to measure the response of the

detector to different wavelengths of radiation.

b. Detector sensitivity. Distance between detector and calibration

source, size of the calibration source, its temperature, and its emissivity are variables that are parametrically varied for this measurement. The gain of the detector is adjusted to prevent saturation at maximum signal strength. The distance between the blackbody and the detector is increased until the radiance signal-to-noise ratio (S/N) drops below the level sufficient for detection. A spectrum analyzer is used to check the specific detector detectivity D* value (which is proportional to S/N).

- c. Detection pattern. The detection pattern is measured by plotting the output of the detector as a function of the range and azimuth position of a blackbody. An optical transducer is used to convert the output of the passive IR detector under test into units of volts that are then plotted against azimuth angle. The test is repeated at several ranges within the operational limits.
- 3. Range test.
 - a. Objectives. The objectives and test techniques for the range test are the same as those discussed earlier for the ultrasonic detectors. The tests provide vehicle tracking data as a function of vehicle speed (although the actual speed cannot be measured by the passive IR detectors), number of vehicles in the FOV, vehicle separation distance, and vehicle color. The tests verify boresight, detection range, and beam pattern.
 - b. Viewing angle. The detectors are installed at a viewing angle commensurate with the mounting height as specified by the vendor. Overhead and side-mounting operation are characterized.

- c. Detection zone. The size of the detection zone is measured by rolling a vehicle or moving an emissive object through the field of view and noting when the detector gives an output.
- d. Minimum spacing between vehicles. The minimum spacing for differentiating between vehicles is established by parking a vehicle at one end of the detection zone and rolling another towards it from the other end. The distance recorded when the detector no longer distinguishes between the two vehicles is the minimum spacing. These tests are performed for light- and dark-colored vehicles.
- e. Detection range. To characterize detection range versus vehicle type and speed, tests are performed at the minimum and maximum operating ranges of the detectors. Automobiles and pickup trucks are driven through the field of view of the detectors at speeds between 5 and 55 mi/h (8.0 and 88.5 km/h), in 10mi/h (16.1-km/h) increments.
- f. Sensitivity to vehicle density. The performance of the detectors is verified against low-density (<800 vehicles per hour per lane) and high-density (>1800 vehicles per hour per lane) traffic flows. These data aid in establishing optimal use of the detectors during field testing.

6.2.5 Video Image Processors

The VIP described below is typical of those that function as ILD replacements in that they provide vehicle count, presence, occupancy, and speed. Additional data that can be provided by more advanced VIP systems in development include vehicle classification and tracking from lane to lane. The VIP illustrated in Figure 6-3 contains four representative subsystems. The camera subsystem consists of an infrared or a visible-spectrum camera with an externally controllable and automatic iris mode, luminance/chrominance (Y/C) (when a color camera is configured) and National Television Standards Committee (NTSC) video outputs, and a fixed focal length lens. Additional items may include a filter, lens shade, zoom lens, and a remotely controlled rotatable pan/tilt camera mount.

The camera enclosure subsystem consists of a reinforced, environmentally controlled enclosure; transparent window; camera mount; and mounting brackets.

The processor subsystem contains the circuit boards and software that detect vehicles in the camera's field of view and calculate vehicle count, velocity, and length. This subsystem may be rack-mountable in a 19-inch (482.6-mm) chassis, but may be substantially smaller as well. In fact, some systems in development will perform the processing within the camera enclosure. The output data are transmitted through a communications interface (I/F) to a traffic management center. NTSC video can be made available on demand for surveillance or can be continuously transmitted over suitable bandwidth channels. Locally, data can be accessed on an RS-232 serial interface and video accessed from a standard BNC connector.

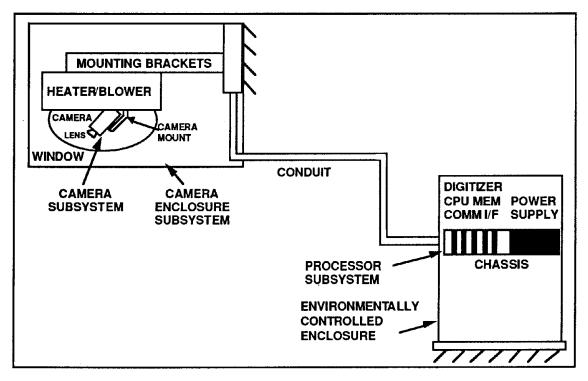


Figure 6-3. Representative Video Image Processor System

The cable subsystem consists of the video cable that transmits video from the camera to the processor subsystem, and the power and control cables that transmit all power, environmental, and operational control signals for the camera and enclosure from the processor subsystem to the camera.

The installation and test procedures for the VIPs consist of:

1. Installation.

The camera enclosure and subsystems are mounted over the traffic lanes to be monitored. The viewing angle is adjusted to give the camera an unobstructed view of the traffic lanes, while excluding the sky from the field of view of the camera.

The processor subsystem is housed in an environmentally controlled enclosure to maintain the required temperature range, with relative humidity 0 to 90 percent, noncondensing. The enclosure supplies standard 120 VAC, 60 Hz, 200 watts power with surge protection to the processor chassis. The processor is typically installed within 150 feet (45.7 m) of the mounted camera subsystem (the maximum length of the standard cables). However, video supplied over longer dedicated lines is also accept-able. If cable installation requires weatherproof or underground conduit, appropriate arrangements are to be made with local traffic engineers.

2. Test station.

Portable setup/test equipment is required for some VIP systems. The setup equipment can typically include a keyboard, two monitors, and a joystick. In this example, the user follows the procedures for the indoor tests and for detector placement in the video scene and initiation of the VIP functions specified in the range test.

3. Indoor test.

This test verifies basic operation of the detector algorithms using prerecorded imagery data.

Required equipment includes an optical disc player and the portable setup/test station described above. The preferred input for the recorded video is through the Red-Green-Blue (RGB) or Y/C connectors to the processor, although standard NTSC video can be used if necessary. The user performs the following setup procedure as though the data were from a live source:

- a. Connect the recorded video to the vehicle detector.
- b. View the video on the set up station monitor.

- c. Use the keyboard and joystick to place the detectors in the traffic lanes as seen on the monitor.
- d Start vehicle detector operation using the keyboard.

The number of vehicles detected by the VIP and their speeds are compared to the truth data set for the environmental and traffic conditions on the recorded video. Typical conditions that are evaluated include variations in the number of lanes, shadows, rain, and day/night transitions.

- 4. Range test.
 - a. Objectives. The objectives of these tests are to verify the detection range and zone boundaries, verify the ability of the detector to measure vehicle speed and vehicle count, and verify the resistance of the detector to artifacts such as shadows.
 - b. Mounting. The VIP camera is installed in an overhead-mounted configuration above the test track. If the detector is mounted between 18 and 24 feet (5.5 and 7.3 m) above the track, it is generally placed over the center of the traffic lanes to be monitored. With mounting heights of 40 to 50 feet (12.2 to 15.2 m), the camera may be located off to the side of the traffic flow. Higher mounting generally produces more accurate speed measurement.
 - c. Detection range and speed. The test vehicle is driven from a range of 300 feet (91.4 m) towards the camera to verify the detection-range boundaries and speed outputs of the VIP. The speed accuracy is checked at one or more specific speeds.
 - d. Multiple-vehicle detection. Single-lane traffic consisting of two or more vehicles separated

by 10 feet (3.0 m) verifies the ability of the VIP to detect multiple vehicles.

- e. Resistance to artifacts. Opposing traffic is used to verify the ability of the VIP to detect a vehicle and measure its velocity in the presence of an oppositemoving shadow in its lane.
- f. Truth data. Parameters (such as vehicle counts per lane, average vehicle speed, and vehicle lengths) obtained from the imagery using human analysts are used as "truth" data. Such data are gathered for various camera positions, traffic conditions, weather variations, and over a 24-hour period representative of various lighting conditions.

The speed measurement accuracy of the detectors is verified during these tests by using speed surveys performed by the host agency. Techniques used include radar speed guns, infrared speed guns, and vehicles traveling at predetermined speeds through the detection zones.

Effects of stationary and moving shadows from both man-made and natural objects, such as buildings, bridges, trees moving in the wind, and other vehicles are studied as they are available. Vehicle-length data probably cannot be generated in darkness when the vehicles themselves are not visible. Under these conditions, most present-day algorithms use vehicle lights to provide an indication of vehicle presence.

6.2.6 Summary

Detector specifications and a test plan have been developed to perform the required laboratory tests. These tests help ensure adequate testing at a minimum cost before subjecting the detectors to the more rigorous field trials. The detector manufacturers have provided detector specifications and selected laboratory test procedures. These procedures can be used to further understand the strengths and weaknesses of each type of detector.

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7. TASK E SUMMARY

CONDUCT LABORATORY DETECTOR TESTS

The Task E reports update the laboratory test plans and describe the results obtained from evaluation of above-the-road vehicle detectors conducted at Hughes Aircraft Company in Fullerton, CA and in the City of Los Angeles. Part I of the report describes the results obtained at the Munson test track at Hughes-Fullerton where vehicles were driven through the field of view of the detectors at low speed. Parameters such as power consumption, detection range, delay time, around illumination pattern, and detection sensitivity with respect to vehicle type were characterized. Passive infrared detectors, originally scheduled for evaluation on the test track and in the laboratory, were not available for these tests. Part II describes indoor bench tests and results for the microwave detectors. Here, output power and frequency, input power consumption, minimum detectable signal, response time, and antenna patterns were measured. Part III describes the results from tests performed by the City of Los Angeles Department of Transportation at their Exposition Boulevard test site under real traffic flow conditions. Here the performance of the above-the-road detectors were compared with those of inductive loops and magnetometers. Video image processors were not evaluated during any of the laboratory tests because they were not available at the time.

7.1 SCOPE

Tests conducted at Hughes Aircraft Company in Fullerton, CA evaluated:

- Detector outputs in response to motor vehicles traveling on a test track.
- Power consumption, detection range, and delay time.
- Detector beam patterns and sensitivity to different types of vehicles.

7.2 DETECTORS EVALUATED

The following detectors were evaluated during the laboratory tests:

Microwave Detectors

- Microwave Sensors Model TC-20
- Microwave Sensors Model TC-26
- Whelen Engineering Model TDN-30

Ultrasonic Detectors

- Microwave Sensors Model TC-30C
- Sumitomo Electric Industries Model SDU-200
- Sumitomo Electric Industries Model SDU-300

Laser Radar Detectors

 Schwartz Electro-Optics Model 780D1000

Passive Infrared Detectors

• Eltec Model 842 (Los Angeles only)

Inductive Loop Detectors

(Los Angeles only)

Magnetometers

(Los Angeles only)

Two of each detector were furnished by the manufacturers, with the exception of the Sumitomo SDU-200, where one was supplied. We later learned that the correct model number for the SDU-200 is the RDU-101. However, since the SDU-200 nomenclature was already in use for this detector, we kept it as the designation for the Sumitomo Doppler ultrasound detector.

7.3 MUNSON TRACK FACILITIES

A scissors lift, shown in Figure 7-1, was used at the Munson track to support the overhead detectors and adjust their heights.



Figure 7-1. Munson Test Track Shown are the scissors lift upon which the detectors are mounted, power supplies and meters, and a passing target vehicle.

7.3.1 Test Track

The portion of the track composed of a 350foot (106.7-m) straight section of conventional single-lane road was used during the test. The paved road had a 2-degree incline approaching the detector mounting location that was accounted for when adjusting the incidence angle of the detectors.

Marking the location of the scissors lift (i.e., the detector mounting location) as 0 feet, 150 feet (45.7 m) of the track was striped at 10-foot (3.0-m) intervals and the distance was marked along the edge. Additional markings were placed at 50-foot (15.2-m) intervals through 250 feet (76.2 m). These markers were used for estimating distances between the detector being evaluated and the vehicle when an event occurred. Additional markers were added at 5-foot (1.5-m) intervals in critical detection areas to more accurately measure detection ranges.

7.3.2 Detector Mounting

A scissors maintenance lift was used as the detector mounting platform. Attached to and protruding from the lift was a length of 1-inch (25.4-mm) galvanized pipe upon which the detectors were mounted as shown in Figure 7-2. The lift was elevated to the appropriate height for the detector performance measurements.

7.3.3 Target Vehicle Descriptions

Three vehicle types were used as targets.

Vehicle 1: 1985 Ford Mustang two-door sedan, representing a medium-sized automobile. Its external dimensions were:

Length = 180 inches (4.6 m); Width = 68 inches (1.7 m); Height = 45 inches (1.1 m).

Vehicle 2: 1986 Honda Goldwing 1200 motorcycle, representing the class of large motorcycles. Its external dimensions were:

Length = 98 inches (2.5 m); Width = 38 inches (0.97 m); Height = 59 inches (1.5 m). Vehicle 3: 1986 Honda Rebel 450 motorcycle, representing the class of small motorcycles. Its external dimensions were:

Length = 89 inches (2.3 m); Width = 34 inches (0.86 m); Height = 49 inches (1.2 m).

7.3.4 Detector Evaluation Procedure

Different procedures were established for detectors that relied on vehicle motion to produce an output and for those that were true presence detectors, capable of detecting stopped vehicles.

7.3.4.1 Speed/Motion-Sensing Detectors

Performance data for motion detectors were collected in one of two ways: (1) an observer located on the elevated scissors lift recorded the approaching vehicle with a camcorder, producing a record to be evaluated at a later time, or (2) a roadside observer, located at the range where vehicle detection was anticipated, recorded the vehicle position at the time an alarm sounded, signifying detection by the detector under test.

7.3.4.2 Presence-Sensing Detectors

The presence-sensing detectors available for these tests gave an output when a vehicle entered its field of view, but did not provide speed information. These detectors were evaluated for their presence-sensing consistency and beam-pattern size.

7.3.4.3 Detector Output Monitor

A detector output monitor was attached to the camcorder. Housed in a small plastic enclosure, it consisted of a battery, piezo-electric alarm, and a light-emitting diode (LED). The LED was mounted at the end of the enclosure on an arm that positioned the LED in the lower part of the field of view of the camcorder. When connected to an appropriate detector output, the LED was turned on and the piezoelectric alarm sounded when a vehicle was detected. The camcorder captured both the LED and audible signals during the recording process and helped identify the correct detection range.

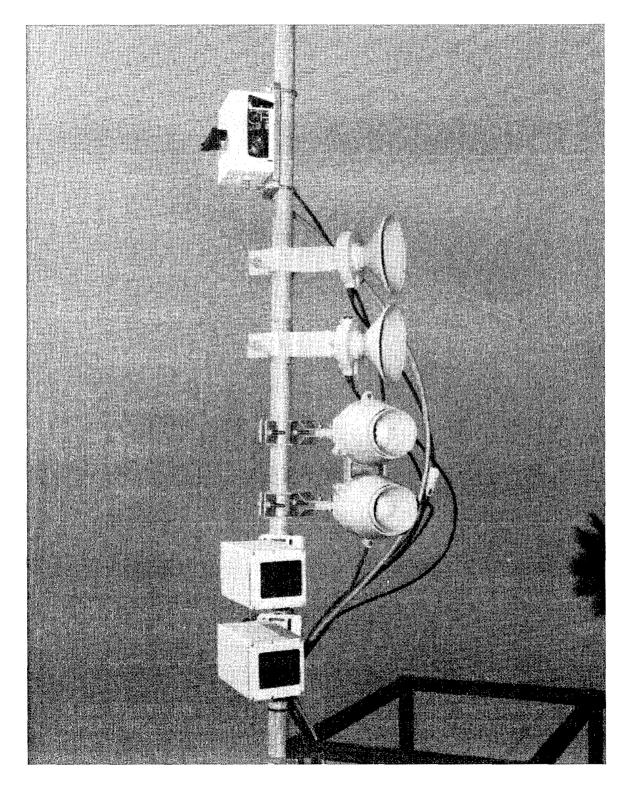


Figure 7-2. TC-30C, SDU-200, SDU-300, and 780D1000 Detectors (From Left to Right) Mounted On the Scissors Lift

7.3.4.4 Measurements

The sequence shown in Figure 7-3 illustrates the test event sequence.

Power:

The applied voltage was adjusted to the manufacturer's low and high limits and the current draw was measured at each voltage.

Delay Time:

Several detectors have adjustable delay times that maintain the detection signal after the vehicle passes through the detector's field of view. The minimum and maximum values were measured.

Detection Range:

The detection range was variable on several of the speed/motion and presence detectors

through a sensitivity adjustment. The detection ranges for minimum and maximum sensitivity settings were recorded when this adjustment was available.

Incidence Angle:

The incidence angle of most of the speed/motion and presence detectors can be varied to change the engagement range. The exception is the presence-type ultrasonic detectors that operate at a nadir (0 degree or straight down) incidence angle. As detector design and operation permitted, incidence angles of 45 and 70 degrees were used to measure detection range.

Inbound/Outbound Vehicle Detection:

This feature was evaluated if the detector had the capability of detecting both inbound and outbound vehicles.

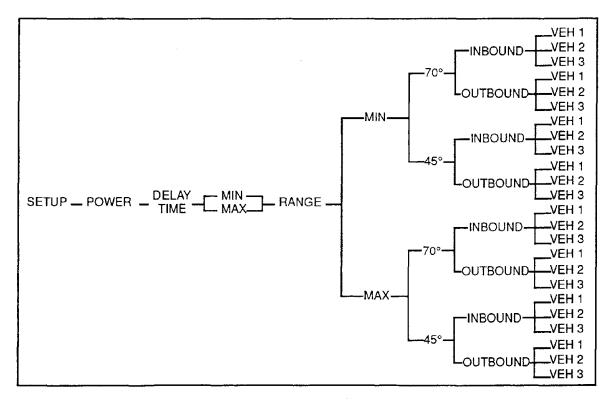


Figure 7-3. Munson Test Track Event Sequence

7.4 LESSONS LEARNED FROM TEST TRACK DETECTOR EVALUATION

Hughes tested seven vehicle detectors during June through July 1992 on the Munson test track. The detectors included three ultrasonic (SDU-200, SDU-300, TC-30C), three microwave (TC-20, TC-26, TDN-30), and an infrared laser radar (780D1000).

7.4.1 Microwave Detectors

The three microwave detectors, Microwave Sensors TC-20 and TC-26 and Whelen Engineering TDN-30, operated at an X-band frequency of 10.54 GHz.

7.4.1.1 TC-20

The TC-20 detector was raised to 17 feet (5.2 m) above the road surface with incidence angles of 70° and 45° with respect to nadir. Although only one traffic lane was used in the test, the wide-beam (16°) antenna should detect multiple lanes of traffic in a real traffic flow environment, since it has a 14foot (4.3-m) diameter 3-dB footprint approximately 60 feet (18.3 m) downstream when mounted at a 70° incidence angle. The potential to detect traffic outside the lane of interest is reduced by decreasing the detection range by turning the range adjust screw counterclockwise (CCW). The minimum hold time (hold time screw fully CCW) was 0.5 second.

7.4.1.2 TC-26

The TC-26 was operated at a height of 17 feet (5.2 m) with both inbound and outbound vehicles, at incidence angles of 70° and 45° with respect to nadir, and at high and low sensitivity settings. The detector can be operated with the low-range setting to minimize detection of adjacent-lane vehicles. In the low-range mode the footprint on the road surface is narrowed. However, even in this mode, the 15-foot-long (4.6-m-long) Ford Mustang was detected at a range of 200 feet (61.0 m).

7.4.1.3 TDN-30

The TDN-30 detector was configured for the freeway traffic management mode to

demonstrate its detection-range envelope. The TDN-30 has a narrow-beam antenna, requiring jumper JP8 to be installed on the electronics board in the housing. Jumper JP2 was installed to detect approaching vehicles or removed to detect departing vehicles. Other jumpers specify the serial communications data transmission rate and mode, dwell time, and application. When the detector is mounted parallel to the roadway surface, the antenna boresight is 45 degrees with respect to nadir.

The ability of the narrow-beam antenna to discriminate between two vehicles traveling at the same speed, one behind the other, was evaluated. In the first run, the Ford Mustang and a small Toyota pickup truck were driven at 10 mi/h (16.1 km/h) with 15 feet (4.6 m) separation. The detector indicated constant presence when the vehicles were driven into the detection zone. In the following run, the same two vehicles were driven at 15 mi/h (24.1 km/h) with an estimated separation distance of 20 feet (6.1 m). This time a momentary break in the tone from the detector output monitor was heard, indicating separate detection of both vehicles as they were driven through the detection zone.

7.4.2 Ultrasonic Detectors

Microwave Sensors' TC-30C and Sumitomo's SDU-200 and SDU-300 were the ultrasonic detectors evaluated. The TC-30C and the SDU-300 are presence detectors that mount directly over a lane and look straight down at the road surface at an incidence angle of 0 degrees. The SDU-200 (RDU-101) is a Doppler device that operates at an incidence angle of 45 degrees.

7.4.2.1 TC-30C

Operator adjustments on the TC-30C were the detection-range control and the relay hold time. The range control was set so that the receiver didn't trigger on the road surface, but instead detected the tops of vehicles 2 to 3 feet (0.6 to 0.9 m) above the road surface. The detection range was established by first turning the range-control screw clockwise until the detector detected the road surface and then turning the screw counterclockwise until the detection was dropped. The relay hold time was adjusted for minimum hold (0.25

seconds) by turning the appropriate screw fully counterclockwise. If vehicle detection did not occur, the receiver gain was adjusted.

7.4.2.2 SDU-200 (RDU-101)

The SDU-200 was evaluated for vehicle detection and speed-measuring capability.

Accurate speed measurements are dependent on the speed correction switch, DSW1, that controls the reading on the digital speed display. When the spring-loaded threeposition Display/Operate/Test switch is momentarily placed in the Test (down) position, the display should read between 92 and 96 km/h.

The digital display read 98 km/h when the three-position switch was placed in Test during the first run. Since this value was too high, DSW1 was adjusted from 9 (normal) to 8, corresponding to a 3 percent reduction in the displayed value. When the digital display was interrogated again, it showed 96 km/h, a reading within specifications.

The small vehicle/large vehicle discrimination value was adjusted next. It enables vehicle counts to be made in each of two vehicle size classes. A value is normally chosen to differentiate between vehicles below and above 6.0 m in length. Since the largest vehicle in these tests was 15 feet (4.6 m) long, SW1 was set to the minimum value of 4.4 m.

The VR2 sensitivity adjustment is used to specify whether vehicles in one or more lanes are detected. Since the test was designed to detect vehicles in one lane only, VR2 was set near the full clockwise or minimum sensitivity position.

7.4.2.3 SDU-300

The three switches located in the right corner behind the front panel of the SDU-300 control unit are set at the factory for normal operation. The detector functioned properly during the tests using these settings.

7.4.3 Infrared Laser Radar Detector

The Schwartz Electro-Optics 780D1000 active infrared laser radar was operated at

incidence angles of 0° (nadir), 45° , and 60° . It was designed to function with approaching traffic only at the time of these tests.

Detector data were evaluated by connecting the RS-232 connector to a personal computer that runs a setup and data acquisition program supplied by Schwartz. The detector functioned properly at 45° and 60° incidence angles. If the backscattered laser signal is too weak to be detected at 60°, as may happen with some reflecting surface shapes, the incidence angle must be reduced to increase the magnitude of the returned signal. Generally, in a normal installation, the incidence angle is 45° or less. Zero-degree incidence is beyond the normal operational design limit of the detector.

7.5 DETECTOR PERFORMANCE RESULTS FROM TEST TRACK MEASUREMENTS

The detectors were evaluated with respect to:

- Test vehicle,
- · Operating current,
- Delay time,
- Engagement range,
- Disengagement range,
- · Beam pattern, and
- Operational and functional anomalies.

7.5.1 TC-20 Microwave Detector

The TC-20 was evaluated at incidence angles of 45° and 70° .

7.5.1.1 Operating Current

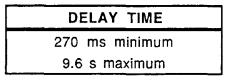
The operating voltages for the TC-20 are 10 to 24 VAC or 12 VDC at 250 mA. During the Munson tests, the voltages ranged from 18 to 24 VAC. Additional power consumption measurements for the microwave detectors are given in Section 6 of this chapter.

Table 7-1. Input Power for TC-20

VOLTAGE	CURRENT
18 VAC	223 mA
24 VAC	225 mA

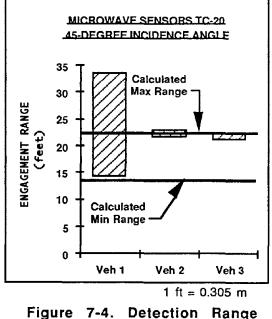
7.5.1.2 Delay Time Measurement

Table 7-2. Delay Time For TC-20



7.5.1.3 Detection Range

Figures 7-4 and 7-5 show the TC-20 engagement range using the detector's maximum range setting and 45° and 70° incidence angles, respectively, compared to the calculated engagement range. The calculated engagement range is based on geometrical factors that include mounting height, beamwidths, and incidence angle as tabulated in Appendix C of Part I of the Task E Report and Appendix F of this Final Report. It assumes that receiver output power, sensitivity, and target radar cross section are adequate to receive the signal at the detector. Vehicle 1 is the Ford Mustang, vehicle 2 is the large motorcycle, and vehicle 3 is the small motorcycle.



of TC-20 at 45-Degree Incidence Angle

7.5.2 TC-26 Microwave Detector

The TC-26 was evaluated at incidence angles of 45° and 70° .

7.5.2.1 Operating Current

The operating voltages for the TC-26 are specified at 12 to 24 VAC or VDC with a current of 350 mA.

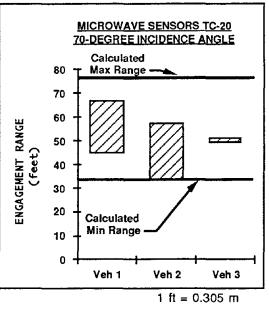


Figure 7-5. Detection Range of TC-20 at 70-Degree Incidence Angle

Table 7-3. Input Power for TC-26

VOLTAGE	CURRENT
18 VAC	505 mA
24 VAC	518 mA

7.5.2.2 Detection Range

Figures 7-6 and 7-7 show the engagement range of the TC-26 at the maximum range setting and 45° and 70° incidence angles, respectively, for inbound vehicles as compared to the calculated engagement range.

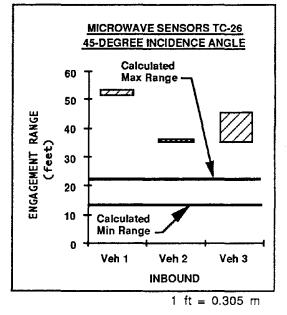
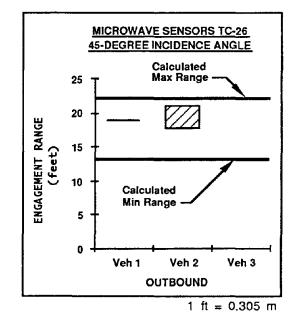


Figure 7-6. Detection Range of TC-26 at 45-Degree Incidence Angle, Vehicles Inbound





Figures 7-8 and 7-9 show the engagement range at the maximum range setting and 45° and 70° incidence angles, respectively, for outbound vehicles as compared to the calculated engagement range. Vehicle 1 is the Ford Mustang, vehicle 2 is the large motorcycle, and vehicle 3 is the small motorcycle.

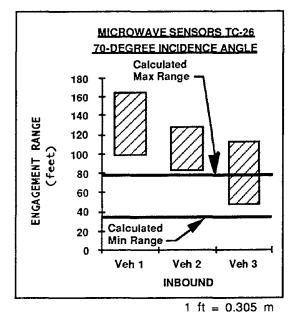


Figure 7-7. Detection Range of TC-26 at 70-Degree Incidence Angle, Vehicles Inbound

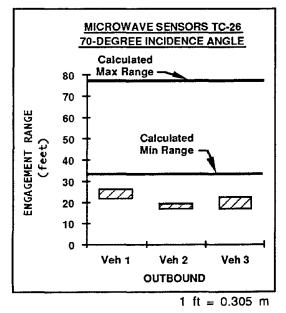


Figure 7-9. Detection Range of TC-26 at 70-Degree Incidence Angle, Vehicles Outbound

7.5.3 TDN-30 Microwave Detector

The TDN-30 operates at an incidence angle of 45° when the bottom of the detector housing is parallel to the road surface.

7.5.3.1 Operating Current

The specified operating voltages for the TDN-30 are 11 to 15 VDC at 200 mA.

Table 7-4. Input Power for TDN-30

VOLTAGE	CURRENT
11 VDC	150 mA
15 VDC	155 mA

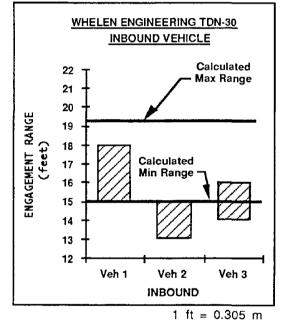


Figure 7-10. Inbound Vehicle Detection Range of TDN-30 at 45-Degree Incidence Angle

7.5.4 TC-30C Ultrasonic Detector

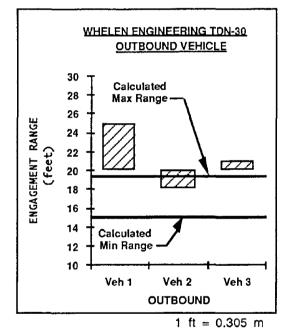
The TC-30C operates at 0° incidence angle.

7.5.4.1 Operating Current

The specified operating voltages for the TC-30C are 6 to 12 VDC or 12 to 24 VAC at 150 mA.

7.5.3.2 Detection Range

Figures 7-10 and 7-11 show the measured engagement range of the TDN-30 compared to the calculated range for inbound and outbound vehicles, respectively. The calculated range is based on geometrical factors that include mounting height, beamwidths, and incidence angle. Vehicle 1 is the Ford Mustang, vehicle 2 the large motorcycle, and vehicle 3 the small motorcycle.



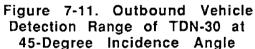


Table 7-5. Input Power for TC-30C

VOLTAGE	CURRENT
12 VAC	332 mA*
24 VAC	268 mA*

*With no vehicle in detection zone.

7.5.4.2 Delay Time Measurement

The delay time measurements compare favorably with the manufacturer's specification of 0.25-s minimum to 10-s maximum.

Table 7-6. Delay Time for TC-	TC-30C	for TC-	Time f	Delay	7-6.	Table
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DELAY TIME
270-ms minimum
9.6-s maximum

7.5.4.3 Detection Zone

Since the TC-30C operates at nadir, the range measurement nomenclature was changed to "detection zone" from "detection range."

Figure 7-12 shows the measured detection zone of the TC-30C at a 0° incidence angle as compared to the calculated zone. The calculated zone is based on geometrical factors that include mounting height, beamwidths, and incidence angle. It assumes that receiver output, sensitivity, and target reflective properties are adequate to receive the signal at the detector. Vehicle 1 is the Ford Mustang and vehicle 3 the small motorcycle.

The detection zone starts at the engagement range where the vehicles enter the beam. The nonzero nature of the minimum delay time affects the disengagement range measurement (i.e., the range at which the vehicle presence signal is dropped by the detector). Because of this, distances at which the vehicle presence was dropped were not measured. Vehicle 2 was not available when the TC-30C engagement range was measured.

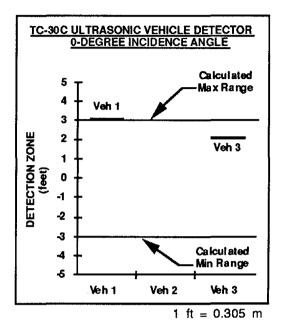


Figure 7-12. Detection Zone of TC-30C at 0-Degree Incidence Angle 7.5.4.4 Beam Pattern

The TC-30C beam pattern is shown in Figure 7-13. The measurements were taken at approximately 15 feet (4.6 m) below the detector.

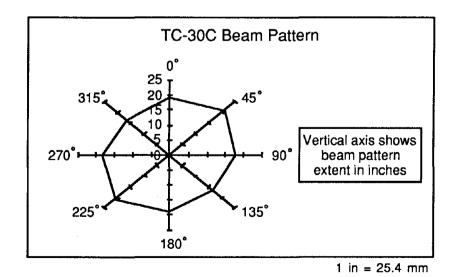


Figure 7-13. Beam Illumination Pattern of TC-30C Ultrasonic Detector

7.5.5 SDU-200 Ultrasonic Detector

The SDU-200 Doppler detector has a transmitting horn transducer and a receiving horn transducer that are mounted at 45° with respect to nadir. The horn furthest from a wall or other barrier is used as the transmitter.

7.5.5.1 Operating Current

The detector operates at a nominal voltage of 100 VAC. Its power consumption was measured at the minimum and maximum specified operating voltages.

Table	7-7.	Input	Power	for	SDU-200
1 4010		mput	1 01101	101	

VOLTAGE	CURRENT
80 VAC	102 mA
110 VAC	102 mA

7.5.5.2 Detection Range

Since the incidence angle of the detector must be at 45°, detection range measurements as a function of angle were not made, other than to confirm that the detector did sense the vehicles as they passed through its field of view.

7.5.6 SDU-300 Ultrasonic Detector

The SDU-300 is mounted at a nadir incidence angle.

7.5.6.1 Operating Current

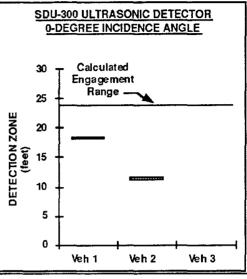
This presence detector operates at a nominal voltage of 100 VAC. Once again, its power consumption was measured at the minimum and maximum specified operating voltages.

Table 7-8. Input Power for SDU-300

VOLTAGE	CURRENT
80 VAC	54 mA
110 VAC	69 mA

7.5.6.2 Detection Zone

Figure 7-14 shows the measured detection zone of the SDU-300 at a 0° incidence angle as compared to the calculated zone.



1 ft = 0.305 m

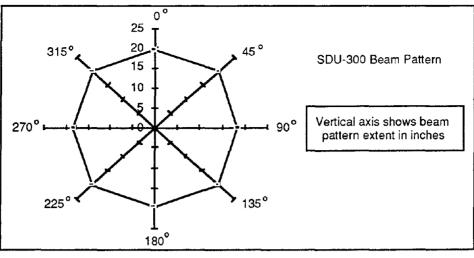
Figure 7-14. Detection Zone of SDU-300 at 0-Degree Incidence Angle

The calculated zone is based on the beamwidth, mounting height, and incidence angle of the detector. It assumes adequate receiver sensitivity and target reflective properties to detect a vehicle at the range calculated from the geometrical factors. Vehicle 1 is the Ford Mustang and vehicle 2 the large motorcycle. Vehicle 3, the small motorcycle, was not available for this test.

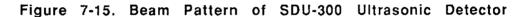
The detection point used in the measurements for vehicles 1 and 2 was the distance at which they entered the beam. The nonzero hold time affects the measurement of the distance at which the presence call is dropped when vehicles leave the beam. Because of this, the distance at which presence was dropped was not measured.

7.5.6.3 Beam Pattern

The beam pattern, shown in Figure 7-15, was measured at nadir from a height of approximately 13 feet (4.0 m) above the road surface.







7.5.7 780D1000 Laser Radar Detector

The 780D1000 laser radar detector is normally mounted at incidence angles of less than 45°. However, in these tests, the incidence angle envelope was stretched to measure the performance limits of the detector.

7.5.7.1 Operating Current

The nominal operating voltage for the laser radar detector is 115 VAC.

Table 7-9. Input Power for 780D1000

VOLTAGE	CURRENT
90 VAC	44 mA
130 VAC	34 mA

7.5.7.2 Vehicle Speed

Table 7-10 compares the speed measured by the 780D1000 to the speed recorded from the speedometer on vehicle 1. The vehicle speedometer was not calibrated by an independent source for this evaluation.

Table 7-10. Measurement of Vehicle 1 (1985 Ford Mustang) Speed With Laser Radar Detector

Incidence Angle (degrees)	Speedometer (mi/h)	780D1000 Measured Speed (mi/h)
45	8	7
45	15	15
4 5	20	21
4 5	20	19
60	11	12
60	8	7
60	8	8

1 mi/h = 1.61 km/h

7.6. DETECTOR PERFORMANCE RESULTS FROM BENCH TEST MEASUREMENTS

Bench tests were performed to measure radio frequency (RF) output power, output frequency, minimum detectable signal, input power consumption, and response time of the microwave traffic detectors (Microwave Sensors TC-20 and TC-26 and Whelen TDN-30). A photograph of the measurement equipment is shown in Figure 7-16 with the Whelen TDN-30 as the detector under test.

The instrumentation horn was used to capture the radiated energy from the detector under test and transmit it to other equipment. The connections made to the instrumentation horn for various measurements are shown in Table 7-11. Volt meters and current meters were used to measure the input power to the detector. The response time was found by measuring the time difference between the injected RF signal and the closure of a relay.

Table 7-11. Device Connected to Instrumentation Horn for Measuring Various Detector Characteristics

Measurement	Device Used
Output power	Power meter
Frequency	Spectrum analyzer
Minimum detectable signal	Sweep oscillator

A summary of the bench test measurements and the manufacturers specifications is shown in Table 7-12. A comparison of the input power consumption of the detectors as measured during the Munson track tests and the bench tests is given in Table 7-13.

Parameter	Whelen TDN-30 SN 00109 <i>Specified</i>	Whelen TDN-30 SN 00109 <i>Measured</i>	Microwave Sensors TC-20 SN 234242 Specified	Microwave Sensors TC-20 SN 234242 <i>Measured</i>	Microwave Sensors TC-26 SN 234326 Specified	Microwave Sensors TC-26 SN 234326 <i>Measured</i>
Output power	Not specified	4.6 dBm or 2.9 milli- watts	10 dBm or 10 milli- watts	10.2 dBm or 10.5 milli- watts	10 dBm or 10 milli- watts	11.9 dBm or 15.5 milli- watts
Output frequency	10.525 GHz	10.520 GHz	10.525 GHz	10.520 GHz	10.525 GHz	10.519 GHz
Minimum detectable signal	Not specified	Not able to perform test	Not specified	-54 dBm or 4 microwatts	Not specified	-60.7 dBm or 0.9 microwatts
Input power consumption	1.8 watts typical	2.2 watts	3.0 watts	2.8 watts	8.5 watts maximum	3.9 watts
Response time	Not specified	Not able to perform test	165 ms	8.4 ms average	250 ms	11.5 ms average

Table 7-12. Microwave Detector Bench Test Results

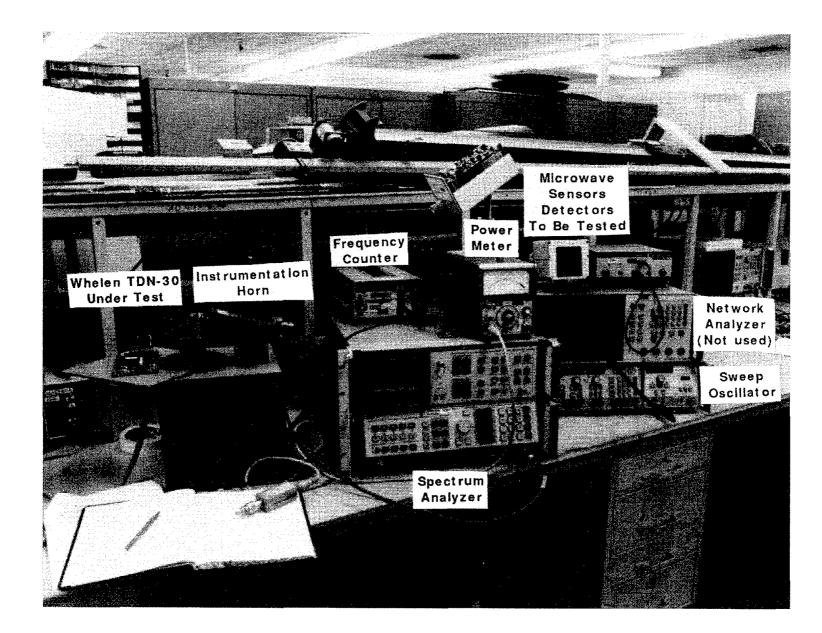


Figure 7-16. Bench Test Setup

Data Source	Whelen TDN-30	Microwave Sensors TC-20	Microwave Sensors TC-26
Manufacturer's Specification	1.8 (nominal) to 2.8 Watts (maximum) using 12 VDC and 14 VDC, respectively	6.0 Watts (maximum) using 10 to 24 VAC or 12 VDC	8.5 Watts (maximum) using 12 to 24 VAC/DC
Munson Test	1.65 to 2.3 Watts	4.0 to 5.4 Watts	9.1 to 12.4 Watts
	using 11 VDC and 15	using 18 VAC and 24	using 18 VAC and 24
	VDC inputs,	VAC inputs,	VAC inputs,
	respectively	respectively	respectively
Bench Test	2.2 Watts	2.8 Watts	3.9 Watts
	using 13.5 VDC input	using 13.5 VDC input	using 13.5 VDC input

Table 7-13. Munson Track and Bench Measurements of Input Power ConsumptionWith Different Voltage Sources

7.7 DETECTOR PERFORMANCE RESULTS FROM TESTS IN THE CITY OF LOS ANGELES

Beginning in August 1992, the City of Los Angeles Department of Transportation, in conjunction with Hughes Aircraft Company, evaluated the effectiveness and operating characteristics of various overhead vehicle detection systems. Eleven detectors comprising six different technologies were used: passive infrared, ultrasound, microwave, laser radar, inductive loop, and magnetometer. The inductive loops and magnetometers were already installed in the Exposition Boulevard test area. Their performance was compared with those of the overhead technologies. The first set of data was collected from August 25 to October 19, 1992. Computer data files were analyzed beginning with September 29 and continuing through October 19, 1992.

7.7.1 Test Site Description

The detector test site was located on Exposition Boulevard, near University Avenue, in the City of Los Angeles. Three eastbound lanes, shown in Figure 7-17, were already instrumented with inductive loops, magnetometers, passive IR, and ultrasonic detectors. The TC-30C, TC-26, 780D1000, and TDN-30 were mounted on the pole closest to the foreground. The middle pole contained the 842s. The pole farthest in the background supported the TC-20 and SDU-300. The traffic lanes monitored by each detector are shown in Table 7-14. Lane 1 is the leftmost lane.

7.7.2 Data Analysis Methods and Results

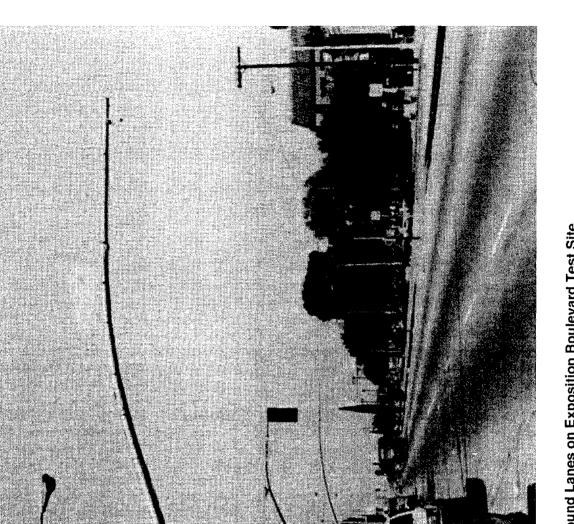
The count accuracy of the inductive loop detectors was 99.4 percent ± 0.6 percent as computed from the recorded imagery that provided visual verification of the count. Inductive loop volume data collected in the lanes monitored by the in-ground and aboveground detectors under test were used to determine the relative accuracy of the other detectors. Fifteen-minute data increments were used in the analysis.

7.7.2.1 Accuracy

The base accuracy for each detector in each 15-min period is expressed as a ratio of the count from the detector under test to the count from the calibrated loop detector. This detector accuracy ratio (DAR) is given by

$$DAR = \frac{Test \ Detector \ Count}{Calibrated \ Loop \ Detector \ Count}$$
(7-1)

Table 7-15 gives the accuracy ratios of the detectors. A ratio of unity indicates a 100-percent correlation between the detector under test and the calibrated loop detector. An accuracy ratio greater than unity indicates a tendency for the detector under test to overcount, while an accuracy ratio less than



Detector	Lane Location
Inductive Loops	1, 2, and 3
Magnetometers	1, 2, and 3
Sumitomo SDU-300 (Ultrasound)	3
Eltec 842 (Passive Infrared)	3
Microwave Sensors TC-20 (Microwave Detector)	2
Microwave Sensors TC-30C (Ultrasound)	1
Microwave Sensors TC-26 (Microwave Detector)	2
Schwartz Electro-Optics 780D1000 (Laser Radar)	3
Whelen TDN-30 (Microwave Detector)	3

Table 7-14. Detector Mounting Locations

Table 7-15. Accuracy of Detectors Under Test

Detectors Listed in Descending Order of Overall Accuracy	Accuracy Ratio
SEO 780D1000 Laser Radar Detector	0.996
Whelen TDN-30 Microwave Detector	1.020
Eltec 842 Infrared Detector (#430)	0.955
Microwave Sensors TC-20 Microwave Detector	0.954
Eltec 842 Infrared Detector (#429)	0.952
Magnetometer Lane #3	1.055
Sumitomo SDU-300 Ultrasonic Detector	0.944
Magnetometer Lane #1	1.102
Microwave Sensors TC-30C Ultrasonic Detector	1.113
Magnetometer Lane #2	0.774
Microwave Sensors TC-26 Microwave Detector	2.711

unity indicates a tendency for the detector under test to undercount.

Some of the tested detectors show a low accuracy ratio because of the long hold time built into the detector by the manufacturer. When there is a high frequency of occurrence of closely spaced, high-speed vehicle traffic, a short detector hold time is needed to obtain accurate volume measurements. Other applications may require a high resistance to multiple counts provided by the long hold time, as when detecting long wheelbase vehicles.

7.7.2.2 Reliability

The periods in which vehicle counts did not meet Chauvenet's criterion (i.e., those periods where readings were greater than 2.81 times the standard deviation of the mean daily counts) were treated as a failure of the detector under test to provide accurate data. This was in addition to any detector data dropout times recorded by the Los Angeles Department of Transportation's Automated Traffic Surveillance and Control (ATSAC) computers. The ATSAC analysis computation returns a zero accuracy value if the detector under test returns a zero volume when the inductive loop detector returns a non-zero volume. Thus, any 15-min period in which the test detector accuracy was zero was considered to be an undercount failure. An analysis algorithm also tested for ghost signals generated by the detector under test in the absence of vehicles detected by the calibrated loops.

As a measure of the reliability of detector data output, the detector data dropout ratio (D^3R) shown in Table 7-16 was computed as

 $D^3R = 96/(Number of Zero Accuracy)$ Results + Number of Ghost Signals) (7 - 2)

where 96 is the number of 15-min periods per day.

Detectors Listed in Descending Order of Detector Data Dropout Ratio	D ³ R in Hours*
Whelen TDN-30 Microwave Detector	74.67
Microwave Sensors TC-20 Microwave Detector	69.52
Sumitomo SDU-300 Ultrasonic Detector	59.29
Eltec Infrared Detector (#430)	51.69
Microwave Sensors TC-30C Ultrasonic Detector	42.89
Eltec Infrared Detector (#429)	42.00
Microwave Sensors TC-26 Microwave Detector	41.14
Magnetometer Lane #3	38.77
SEO 780D1000 Laser Radar Detector	36.08
Magnetometer Lane #1	27.24
Magnetometer Lane #2	19.02

Table 7-16. Detector Data Dropout Ratio for Detectors Under Test

*Detector data dropout ratio accounts for the number of 15-minute intervals in which: (1) the test detector returns a zero volume and the inductive loop detector returns a non-zero and (2) the test detector returns a non-zero volume and the inductive loop detector returns a zero. The laser radar dropout ratio calculated from the April to June 1993 data (shown in the table) was degraded by a 2.25-h interval on June 23 (survey day 16) during which no data were output by the laser radar. The problem was at the detector site and did not apparently involve the local signal controller or existing communication network. Whether the data dropout was due to the detector itself or to the detector's power supply could not be determined from the available information. However, even with this outage, the performance of the laser radar was comparable to that of the other detectors.

Sumitomo raised other issues that may have affected the accuracies reported in Table 7-15 with respect to undercounting of vehicles. They pointed out that vehicle lane changing may have occurred in the region between the overhead detectors and the calibrated loops, although this did not appear to be a significant problem.

The measures of data output reliability used in the Los Angeles evaluation (namely, daily percent downtime and detector data dropout ratio) are not meant to be absolute measures of the detector's hardware reliability. The data dropout ratios simply provide a comparison between the various detectors as they operate with the current California Type 170 Traffic Signal Controllers, and their ability to cope with the traffic conditions encountered during the tests. Therefore, some of the dropouts or gross inaccuracies in the detectors under test may be caused by either compatibility problems with local equipment or unusual traffic conditions. Hard reliability figures for the inductive loop detectors are not available. Hence, the numbers shown in Table 7-16 should be used only as relative values for comparing the data dropouts from the detectors during this test.

8. TASK F SUMMARY

DEVELOP VEHICLE DETECTOR FIELD TEST SPECIFICATIONS AND FIELD TEST PLAN

8.1 TEST OBJECTIVES

The primary objective of the field tests was to quantify the performance of traffic detector technologies with respect to the types and accuracy of the data they provide for the IVHS applications identified in the Task A report.⁽¹⁾ The detectors were evaluated in freeway and arterial street traffic. The video recording of the traffic flow in the detectors' field of view provided truth data for vehicle count and presence against which to compare detector output data from the technologies under test. Speed guns and probe vehicles were also used to supply truth data.

A second objective was to expose the detector technologies to a variety of weather conditions. This required the selection of geographically diverse test sites and seasons in which to conduct the tests and the capability to not only measure the accuracy of the traffic data supplied by the detectors, but also to monitor and record the environmental conditions prevailing throughout the tests.

The third objective was to compare the performance of the new detector technologies with that of current inductive loop detectors (ILDs) and magnetometers.

The fourth objective was to engage diverse vehicle and driver populations in different regions of the United States in the detector technology performance evaluation and, thus, enhance the national applicability of the test results.

8.2 DETECTOR TECHNOLOGIES EVALUATED

Table 8-1 lists the detectors and the technologies they represent that were evaluated in the field test program. Inductive loop detectors were also included in the test matrix, although they are not listed in the table. A list of detector manufacturers is provided in Appendix B.

8.3 TRAFFIC PARAMETERS MEASURED

Flow rate, speed, and density, or its surrogate occupancy, are an interrelated set of traffic parameters used to describe the quality of traffic flow on a highway. To measure flow rate accurately, detectors need to discriminate between vehicles where there are gaps on the order of 25 feet (7.6 m) and time headways of 1 to 2 seconds. Speeds can be measured using ILDs in speed traps composed of two closely spaced (15 to 20 feet [4.6 to 6.1 m] apart) loops excited by oscillators that are continuously dedicated to each loop in the pair, or less accurately with a single loop and an assumed vehicle length. Some microwave detectors, such as the device that transmitted a frequency modulated continuous wave (FMCW) and the laser radar evaluated in this project, measure speed by noting the time it takes for the vehicle to arrive at two points a known distance apart. Microwave Doppler and ultrasound detectors measure speed using the Doppler effect.

Density (vehicles per mile per lane) is difficult to measure directly, except with some type of picture format, such as video imaging or aerial photography. Consequently, lane occupancy (the percent of time the detection zone of a detector is occupied by a vehicle) has been used as a surrogate measure for density. In this case, the requirement to discern the boundaries of vehicles is much more stringent than for counting. Accurate occupancy measures require discriminating between vehicles and gaps to within 1 to 5 percent of their true values, as discussed in the Task A report.⁽¹⁾

Other traffic parameters important for traffic management are presence, queue length, travel time, intersection turning movements, and vehicle classification. Presence needs to be measured, even if the vehicle is stationary, for applications that include intersection control and ramp metering. Therefore, detectors which require motion in order to be

T 1 1 0 1 0 1			
lable 8-1. Detect	ors and Technologi	es Evaluated Duri	ng Field Tests

Symbol	Technology	Manufacturer	Model	Quantity
U-1	Ultrasonic Doppler	Sumitomo	SDU-200 (RDU-101)	1
U-2	Ultrasonic Presence	Sumitomo	SDU-300	2 heads, 1 controller
U-3	Ultrasonic Presence	Microwave Sensors	TC-30C	2
M-1	Microwave Detector Motion Medium Beamwidth	Microwave Sensors	TC-20	2
M-2	Microwave Detector Doppler Medium Beamwidth	Microwave Sensors	TC-26	2
M-4ª	Microwave Detector Doppler Narrow Beamwidth	Whelen	TDN-30	2
M-5	Microwave Detector Doppler Wide Beamwidth	Whelen	TDW-10	2
M-6	Microwave Radar Presence Narrow Beamwidth	Electronic Integrated Systems	RTMS-X1	2
IR-1	Active IR Laser Radar	Schwartz Electro- Optics	780D1000 (Autosense I)	1
IR-2	Passive IR Presence	Eltec	842	1
IR-3	Passive IR Pulse Output	Eltec	833	1
IR-4 ^b	Imaging IR	Grumman	Traffic Sensor	1
VIP-1	Video Image Processor	Econolite	Autoscope 2003	1
VIP-2	Video Image Processor	Computer Recognition Systems	Traffic Analysis System	1
VIP-3°	Video Image Processor	Traficon	CCATS-VIP 2	1
VIP-4 ^b	Video Image Processor	Sumitomo	IDET-100	1
VIP-5 ^d	Video Image Processor	EVA	2000	1
A-1e	Passive Acoustic Array	AT&T	SmartSonic TSS-1	1
MA-1	Magnetometer	Midian Electronics	Self-Powered Vehicle Detector	2
L-1 ^b	Microloop	3M	701	4
T-1 ^b	Tube-Type Counter	Timemark	Delta 1	1

a. M-3 was designated for a microwave radar detector that was not received.

b. Used at Tucson, Arizona test site only.

c. Used at all Arizona test sites.

d Used in Phoenix, Arizona 7/94 test only.

e. Used in Phoenix 11/93 and Tucson tests.

activated, such as passive magnetic detectors and others that transmit continuous wave energy, cannot perform this task. Queue length, as density, requires wide-area detection to be measured directly.

Travel time is inversely proportional to average speed. For travel time to be measured directly, the same vehicle has to be identified at several points along a highway using either (1) a roadside-mounted detector or (2) a vehicle identification device mounted on the vehicle that is interrogated by readers deployed along the highway system. Thus, travel time could be a side benefit of instituting an automatic vehicle identification (AVI) system in which the vehicles act as "probes." Vehicle classification could also be an offshoot of AVI if it was widely deployed. However, AVI systems are considered beyond the scope of the field testing portion of this project. Imaging systems, high-resolution ranging systems such as active infrared and some ultrasonic systems, and ILDs coupled with special vehicle transmitters and receiver amplifiers also have vehicle classification ability.

8.4 ENVIRONMENTAL FACTORS

The environmental factors considered during the field tests were precipitation, wind, temperature, barometric pressure, acoustic noise, electromagnetic interference, shadows, and vibration.

8.4.1 Precipitation

Precipitation in the form of rain and snow affects the operation of visible, infrared, and ultrasonic detectors. In addition, fog and mist have a detrimental effect on those detectors using the visible and infrared spectrum.

8.4.2 Wind

Wind is a factor in ultrasonic detector operation as it causes turbulence that can distort the ultrasonic waveform. The Sumitomo SDU-200 ultrasonic speed detector is designed to operate at wind speeds up to 56 mi/h (25 m/s). Wind is also a cause of detector movement, discussed further in the section on vibration.

8.4.3 Barometric Pressure

Barometric pressure changes may affect the speed of propagation of ultrasonic waves and thus the accuracy of range measurements. An automatic calibration feature on some ultrasonic detectors, such as those from Sumitomo, eliminates most weather-related effects.

8.4.4 Acoustic Noise

Acoustic noise in the audible or ultrasonic ranges could conceivably interfere with the operation of passive acoustic arrays and ultrasonic detectors. However, the relatively small and focused field of view used by the overhead detectors makes this event unlikely.

8.4.5 Electromagnetic Interference

Electromagnetic interference has the potential to affect the operation of all types of traffic detectors, as it can enter through the aperture of the detector or through the enclosure that protects the electronics that process the data. Broad-spectrum electromagnetic interference can thus insert noise into the signal and data processing hardware. For the special case of microwave detectors, interference may occur when the detector is operated in the vicinity of high-power radars transmitting at nearby frequencies. The use of radars for speed enforcement by local police did not interfere with the operation of the microwave detectors during the field tests. Computers and video monitors produced interference that degraded the operation of the SPVD magnetometer receiver when the receiver was not isolated on its own AC circuit.

8.4.6 Shadows

Shadows can affect the operation of video image processors. During cloudless midday operation, the contrast between shadow and sunlit areas can be great, perhaps leading to false declarations of shadows as vehicles. In addition, low-angle direct sunlight and glint from the reflection of sunlight off other surfaces can produce glare in the scene or on the detector lenses. These effects can be eliminated or reduced through advanced signal processing and proper mounting of the VIP camera.

8.4.7 Vibration

Vibration can pose a problem both for the image processing detectors and possibly for some of the other detectors mounted above ground. This is most likely to occur when the detectors are mounted on high poles, or when video images are obtained with a long focallength lens. Wind is likely to be a common cause of vibration; but for detectors located on structures, vibration could also develop from heavy trucks moving across or below the structure.

8.5 GROUND TRUTH

Accurate data against which to evaluate stateof-the-art detector technologies were obtained from the recorded video of the traffic flow. A video home system (VHS) format video camera and computer-controlled video cassette recorder (VCR) with stop-motion capability were used to manually sample the recorded video to obtain count, volume, and presence truth data. A data logger system that automatically records, time tags, and displays the vehicle detections from all the detectors under test was developed to simplify the data analysis process. The data logger is described later in this section and in Appendix C.

In addition to serving as a database from which traffic parameter truth data are obtained, the video provides a visual record of environmental conditions encountered during testing and a visual record to aid in resolving anomalies that may arise during data analysis.

By analyzing the video record off-line, manual counts were made to verify the realtime data collected by the detectors. The following comments illustrate how the video imagery was used to obtain ground truth data for selected traffic parameters.

8.5.1 Volume

Volume data were obtained manually by replaying the video to count the required vehicle types and movements, such as lane crossings. The time stamp of detector output events provided by the data logger, along with the recorded video tape index number, allowed correlation of video imagery with detector data.

8.5.2 Speed

Speed ground truth data were obtained by driving a marked probe vehicle through the detection zone during data collection periods. The driver recorded vehicle speed, lane, and approximate time for each run. The exact time was obtained from the corresponding time stamps supplied by the data logger. The probe vehicle was identified by hanging a flag from the radio antenna or the truck lid, by inserting a traffic cone through the window of the probe, by driving with the trunk open, or by waving a hat or other object from the window of the vehicle while driving through the field of view of the camera. Beginning with the Tucson runs, a Detector Systems vehicle-mounted transducer was used to emit a vehicle identification code that was picked up by the inductive loops and recorded by the data logger. Speed truth data were also manually recorded from a police radar during the evaluations at the Orlando freeway site.

8.5.3 Occupancy and Presence

Occupancy and presence data were verified by superimposing the detector relay closure event on the video whenever the detector sensed a vehicle within its capture zone. This procedure is controlled by the applicationspecific Phase II software written for the data analysis process.

8.5.4 Queue Length, Turning Movements, and Vehicle Classification

When available as outputs from detectors, these parameters can be manually verified from the video.

8.6 TRAFFIC DATA COLLECTION REQUIREMENTS

The data collection requirements differ slightly for the freeway and surface arterial test locations.

8.6.1 Freeway Test Locations

For the freeway test sites, count, flow rate, speed, and occupancy were measured by the detectors under test and compared with simultaneous data obtained from inductive loop detectors and video during peak and offpeak hours.

8.6.2 Surface Arterial Test Locations

Data to calculate presence, flow rate, speed, and occupancy were recorded for the signalized intersection environment on a signal cycle-by-cycle basis and categorized signal cycle-by-cycle basis and categorized for peak and off-peak periods. Queue length and turning movements were not output by any of the detectors evaluated.

8.7 TEST SITE LOCATIONS

The detector technology evaluation sites were located in Minneapolis, MN; Orlando, FL; Phoenix, AZ, and Tucson, AZ as shown in Table 8-2. The expected weather conditions are listed. Detailed descriptions are provided in the Task B report.⁽²⁾

City Freeway		Surface Arterial	Weather	Test Period	
Minneapolis	I-394 at Penn Avenue	Olson Highway at Lyndale Avenue	Cold, snow, sleet, fog	Winter 1992-1993	
Orlando	I-4 at SR 436	SR 436 at I-4	Hot, heavy rain, lightning	Summer 1993	
Phoenix	I-10 at 13th Street	Not applicable	Warm, heavy rain, lightning	Autumn 1993	
Tucson	Not applicable	Oracle Road at Auto Mall Drive	Cool to warm, heavy rain, lightning	Winter-Spring 1994	
Phoenix	l-10 at 13th Street	Not applicable	Hot, heat waves, heavy rain, lightning	Summer 1994	

Table 8-2. Test Sites

8.8 DETECTOR INSTALLATION

8.8.1 Site Preparation

Site preparation included arranging for the housing and installation of data recording equipment in a portable trailer, installing sufficient data and power cables to connect the detectors with the data recording apparatus and power supplies, painting of calibration marker distances on the roadway surface, and obtaining descriptions of each of the ILDs that were installed for the tests.

Calibration distance markers were painted across each lane or on the shoulder of the test section of roadway, where possible, to aid in measuring the distance of vehicles from the above-the-road detector mounting location and for VIP calibration. The stripes were painted at 5- to 25-foot (1.5- to 7.6-m) intervals (depending on the requirements for VIP setup and calibration) out to approximately 300 feet (91.4 m), with the zero-foot mark located at the detector mounting location.

8.8.2 Overhead Detector Mounting

In order to have space to mount and operate all the overhead detectors at the same time, they were attached to two or more grids constructed of 1.5-inch (38.1-mm) galvanized pipe and secured with various types of pipe clamps or manufacturersupplied mounting hardware. When the mounting of the detectors on the pipe grids was not practical, they were attached directly to the overhead structure.

The pipe grid was connected to a central ground in the trailer at the equipment rack to minimize ground currents that affect some detectors. An uninterruptable power supply and lightning protection devices on all input data lines were used to help protect data recording equipment.

8.8.3 Overhead Detector Layouts

The overhead detectors were configured into arrays at each evaluation site. Specific conditions, such as the number of active traffic lanes and the existing structures available on which to mount detectors, influenced the specific configuration and array mounting technique.

8.8.4 In-Ground Detectors

The detector evaluation site layout accommodated the requirement to compare ILD and magnetometer technology performance with that of the above-ground detectors. The location of the buried detectors were indicated by temporary pavement markings, sealants used in the installation process, or traffic cones on the shoulders when snow was present. These markings appear in the video record of the tests.

8.8.5 Cable Requirements

Detailed information about detector operation, mounting, power requirements, and output data are found in the detector manufacturers operations manuals and the Task D report that were supplied to the state agencies hosting the field tests.⁽³⁾ Summaries of the installation requirements to accommodate detector size, weight, data transmission, and power are given in Table 8-3. Input power sources included 115 VAC, 100 VAC, 12 VAC, 12 VDC, and 24 VDC. Wind-shear loads on the bolts that attach poles to the subground support structure were taken into account. About 200 lines were required for input power and data output. Detector output data and 115-VAC input power were not transmitted in the same cable to lessen the likelihood of data corruption by the power lines.

8.9 TEST PROCEDURES

8.9.1 Run Times

The detectors were operated for several multi-hour time intervals during a 24-h period to obtain data for various levels of traffic flow and different light levels and lighting transition periods throughout the day and night. Shadows and davlight-to-darkness transitions were encountered with this test regime. Typical runs started at predawn and continued through the end of the morning rush hours. A second run was made each day beginning at about 3:30 in the afternoon and continuing well into nighttime darkness. As these two runs spanned light and heavy traffic and various lighting conditions, a midday run was unnecessary most of the time. They were made, however, when traffic or weather conditions dictated.

8.9.2 Weather Data

Temperature and wind speed and direction were recorded on the data logger. Temperature sensors were generally placed in two locations, one on the detector mounting structure and another near the ground surface. The wind sensors were placed on an 8- to 15-foot (2.4- to 4.6-m) high pole near the trailer or the side of the road. When available, daily hour-by-hour weather records were obtained from local newspapers. A record of any visible precipitation was made on the video tapes recorded for each run. The official weather observations at each field test site were obtained from the National Climatic Data Center (NCDC) in Asheville, NC after the tests were completed as contained in Appendix Л.

8.9.3 Equipment Checkout Runs

Once the detectors were installed, checkout tests were performed to ensure that the equipment was functioning in a manner consistent with the laboratory tests described in the Task C and E reports and the specifications of the detector manufacturers.^(4,5) In the checkout tests, marked vehicles traveling at known speeds traveled through the detector test area. Normal traffic was also used to verify that the detectors are responding to vehicles passing through their fields of view.

Detector	Manufacturer	Input Power	Detection	Discrete	Serial Detector
Symbol	and Model Number	Power	Range (feet)	Detector Outputs	Outputs
			(leet)		Detection by vehicl
U-1	Sumitomo SDU-200	80-110 VAC 6 Watts	26 max	Relay Contacts: 2 amp max 500 V max	length: 1 bit; Speed (binary): 8 bi
				100 VA max	Speed (in terms of pulse width): 1 bit
				Relay Contacts:	
U-2	Sumitomo	80-110 VAC	5 to 26	2 amp max 500 V max	
	SDU-300	6 Watts		100 VA max	
	Microwave	6-12 VDC		Relay Contacts:	
U-3	Sensors	12-24 VAC	3 to 22	Form C, 5 A @ 24 VDC	
	TC-30C	150 mA	· · · · · ·		
	Microwave	10-24 VAC		Relay Contacts:	
M-1	Sensors	12 VDC	3 to 100	Form C, 2 A	
	TC-20	250 mA			
	Microwave	12-24 V	200 max	Relay Contacts:	
M-2	Sensors	AC or DC	(autos)	Form C, 5 A @ 24 VDC &	
	TC-26	350 mA	Į	5-5V logic level outputs	
	Whelen	11-15 VDC		Two opto-isolator	RS-232
M-4	TDN-30	200 mA	100 max	outputs: 40 V holdoff, ON <1 V @ 50 mA	@ 1200 or 2400 baud
	Whelen	11-15 VDC		Two opto-isolator	RS-232
M-5	TDW-10	200 mA	100 max	outputs: 40 V holdoff,	@ 1200 or
···· ~		200 117	TOO Max	ON <1 V @ 50 mA	2400 baud
	Electronic	95-135 VAC		12 isolated o.c.	RS-232
M-6	Integrated Systems	150 mA	200 max	contact pairs (1 pr/ln)	data bus
	RTMS-X1			rated for 50 mA @ 30 V	@ 9600 baud
	Schwartz	115 VAC			RS-232 for
IR-1	Electro-Optics 780D1000	20 Watts	5 to 50	Presence Relay	speed, count, and range
	Eltec	95-135 VAC		Relay Output:	
IR-2	842	10 watts max	21 to 54	3.5 A, 250 VAC 300 W	
	Eltec	100-130 VAC		Relay Output:	
IR-3	833 M2	22 mA	16 to 98	3.5 A, 120 VAC 200 VA	
	Grumman				RS-232 data
IR-4	IIR Traffic Sensor	115 VAC	up to 1000		@ 9600 baud
	Econolite/	115 VAC			RS-232 data
VIP-1	Autoscope	100 Watts	up to 300	RS-170 Video	@ 2400 or
	2003				9600 baud
	Computer Recognition Systems	95-132 VAC		CCIR standard or	RS-422, RS-232
VIP-2	Systems Traffic Analysis System	400 VA	up to 300	RS-170 Video. Also VME bus	Opto 22 Relays 16-bit parallel
					RS-232C data
VIP-3	Traficon CCATS-VIP 2	115 VAC	up to 300	RS-170 Video	@ 9600 baud
	Sumitomo	100 VAC			RS-232 data
VIP-4	IDET-100	≤ 200 VA		RS-170 Video	@ 9600 baud
		41 VAC ± 15%		RS-170 Video or	RS-232 data
VIP-5	EVA 2000	48 VDC ± 15%	up to 300	CCIR PAL	up to 19200 baud
		25 to 35 Watts			RS-422 to 64k bau
	AT&T	24 VDC		Two opto-isolator	170/NEMA
A-1	TSS-1	250 mA		outputs	interface

Table 8-3. Detector Installation Requirements

1 ft = 0.305 m

Detector Symbol	Depth (inches)	Width (inches)	Height (inches)	Weight (pounds)	Height Above Roadway (feet)	Angle From Vertical (degrees)	Beam- width (degrees)	Look Up- Stream?	Look Down- Stream?
U-1	6.6	11.8	7.2	Not available	16.4 to 18.0	34 to 55	15	Yes	No
U-2	6.3	6.3	5.1	Not available		0	13	Nadir	Nadir
U-3	7.0	4.5	4.0	3.0	12 to 18	0	20	Nadir	Nadir
M-1	7.5	4.5	4.5	4.0	12 to 18	20 to 70	16 Az 15 El	Yes	Yes
M-2	7.0	4.0	4.0	3.0	14 to 18	20 to 70	16 Az 15 El	Yes	Yes
M-4	10.0	12.0	10.0	10.5	16 to 32	Incidence angle is 45 deg when properly mounted	7	Yes	Yes
M-5	- 10.0	12.0	10.0	10.5	12 to 40	Incidence angle is ≈70 deg when properly mounted	25	Yes	Yes
M-6	6.0	11.0	9.0	10.0	16 to 32	· · · · · · · · · · · · · · · · · · ·	15 Az ≈50 El	Yes	Yes
IR-1	6.3	6.3	3.5	6.0	15 to 20	0 to 45	1 mrad (El) x 9.4º (Az)	Yes	No
IR-2	8.7	4.7	3.1	6.0	15 to 20	45 to 68	4	Yes	Yes
IR-3	8.3	4.7	3.2	3.0	13 to 20	14 to 43	-	Yes	Yes
IR-4	30	9.0	7.9	25.0			HFOV = 27 ^o 320 (H) x 240 (V) pixels	Yes	Yes
VIP-1	10	17.5	5.75					Yes	Yes
VIP-2								Yes	Yes
VIP-3	9.0	3.0	7.0					Yes	Yes
VIP-4				14.0				Yes	Yes
VIP-5	9.3	12.4	10.7	6.6	33 to >59			Yes	Yes
A-1	3.5	22.0	22.0	25.0	20 to 35		6 (3 dB) 20 (10 dB)	Yes	Yes

 Table 8-3. Detector Installation Requirements (continued)

1 in = 25.4 mm

1 ft = 0.305 m

1 lb = 0.454 kg

8.9.4. Video Feed to Image Processors

At most sites, black-and-white video imagery was supplied by a common camera and a video distribution amplifier to the VIPs, monitors, and VCR. The Autoscope system, however, used a separate camera designed specifically for its processor, except in Minnesota where a Burle camera supplied by MnDOT was used.

8.10 DATA RECORDING AND ANALYSIS

A PC-based data logger, shown in Figure 8-1, automatically recorded and time-tagged data and assisted in their analysis. Applicationspecific software run by the 386 PC formatted the VCR video tapes and issued stop and start commands to the VCR. Video tape index numbers were recorded by the data logger to correlate with the time tags and detector output events.

The data logger is capable of recording 8 analog signals, such as Doppler frequency, air temperature, and wind speed and direction; 16 relay-based detector output transitions; 40 optically isolated detector output transitions; and 16 RS-232 serial inputs. Since the protocols for reading the serial data are unique to each detector, the detector's serial output was connected to a specific RS-232 input port on the data logger as identified in Figure 8-1. Further description of the data logger is given in Appendix C.

The Phase II software developed for the data logger converts the raw input data into comma-delimited format, and Paradox software converts that into a database from which a direct comparison of speeds, counts, occupancies, etc. can be made across the detectors. The database values can be plotted as a function of time or green-phase cycle length using a program such as Mathcad to simultaneously display parameters from the selected detectors. Statistics such as means and standard deviations can also be computed to assess the accuracies of the detectors.

In Tucson, data produced by high-frequency sampling of the change in inductance produced by the passage of a vehicle over inductive loops were recorded on a dedicated personal computer and hard drive along with time stamps supplied by the data logger computer. The high sampling rate needed to reproduce the frequencies of interest required a separate computer and hard drive to prevent overloading of the drive on which the other detector output data are recorded. Waveforms associated with the passage of vehicles through the magnetic field produced by an array of magnetometers were recorded on a Metrum recorder located in the field trailer. These were transcribed onto suitable magnetic media that are compatible with the data analysis system.

8.11 SECURITY FOR THE EVALUATION SITE

Provisions were made to secure the trailer and equipment from burglary. These measures included the installation of extra locks and a cellular-phone-based security system that automatically notified appropriate authorities in the event of unauthorized access to the trailer or a fire. Land-line telephone service was installed in the trailer as well when it was available. When a possibility existed for the public to interfere with the operation of the overhead detectors, measures such as fencing off the detectors from public access were employed.

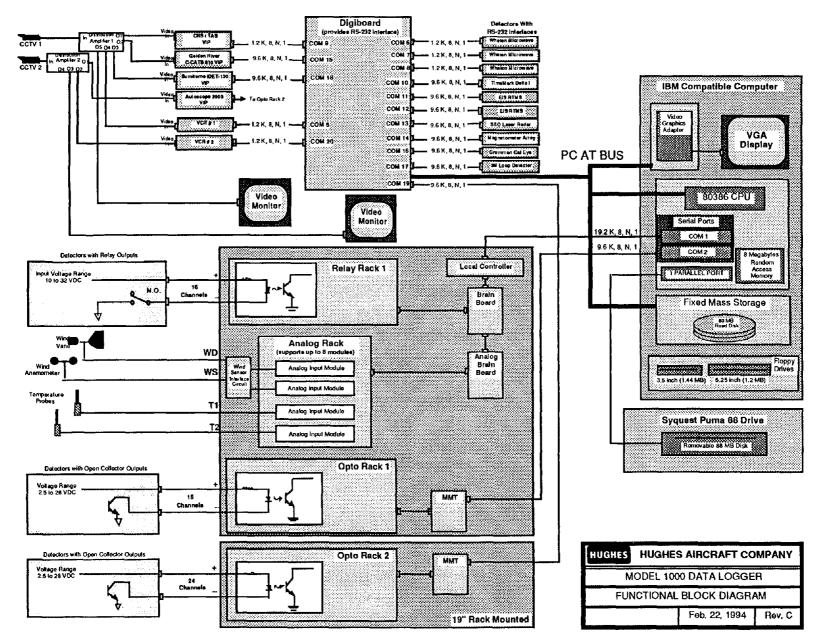


Figure 8-1. Data Logger

REFERENCES

- 1. <u>Detection Technology for IVHS: Task A Report Development of Traffic Parameter</u> <u>Specifications</u>, Federal Highway Administration Contract DTFH61-91-C-00076, U.S. Department of Transportation, Washington, D.C. (1994).
- <u>Detection Technology for IVHS: Task B Report Selection of Field Sites</u>, Federal Highway Administration Contract DTFH61-91-C-00076, U.S. Department of Transportation, Washington, D.C. (1994).
- 3. <u>Detection Technology for IVHS: Task D Report Select and Obtain Vehicle Detectors</u>, Highway Administration Contract DTFH61-91-C-00076, U.S. Department of Transportation, Washington, D.C. (1994).
- 4. <u>Detection Technology for IVHS: Task C Report Laboratory Test Specifications and Test Plan</u>, Federal Highway Administration Contract DTFH61-91-C-00076, U.S. Department of Transportation, Washington, D.C. (1994).
- <u>Detection Technology for IVHS:</u> Task E Report Laboratory Test Results, Parts I, II, and III, Federal Highway Administration Contract DTFH61-91-C-00076, U.S. Department of Transportation, Washington, D.C. (1993).

9. TASK G

INSTALL VEHICLE DETECTORS AT FIELD SITES AND COLLECT FIELD TEST DATA

Six field sites were selected in which to evaluate modern detector technologies suitable for traffic management on freeways and surface streets. Table 9-1 summarizes the location, evaluation period, weather, and traffic flow direction at each site. The Phoenix freeway site was visited twice in order to obtain hot weather data that were not gathered during the first visit. The detectors installed at the sites and the technologies they represent are listed in Table 9-2.

Table 9-1.	Descriptions	of	Detector	Technology	Evaluation	Sites	
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Location	Evaluation Period	Weather	Traffic Direction
Minneapolis freeway: I-394 at Penn Avenue	Winter 1993	Cold, snow, sleet, fog	Departing (AM); Departing and approaching (PM)
Minneapolis surface street: Olson Highway at East Lyndale Avenue North	Winter 1993	Cold, snow, sleet, fog	Departing
Orlando freeway: I-4 at SR 436	Summer 1993	Hot, humid, heavy rain, lightning	Approaching
Orlando surface street: SR 436 at I-4	Summer 1993	Hot, humid, heavy rain, lightning	Departing
Phoenix freeway: I-10 at 13th Street	Autumn 1993	Warm, rain	Approaching
Tucson surface street: Oracle Road at Auto Mall Drive	Winter 1994	Warm	Departing
Phoenix freeway: I-10 at 13th Street	Summer 1994	Hot, low humidity, thunder storms, lightning	Approaching

9.1 MINNEAPOLIS EVALUATION SITES

The Minneapolis freeway site at I-394 and Penn Avenue is shown in Figure 9-1 as the overhead detectors were installed. The boom truck was used to attach the pipe trees to the concrete overpass structure and adjust the alignment of the detectors so that they observed traffic in their designated lanes and at manufacturer-specified incidence angles. Details of the pipe tree attachment to the overpass are contained in Appendix E. This site was unique in that a reversible traffic flow lane was instrumented with several detectors along with the permanent eastbound freeway lanes. The reversible lane was located between the nonreversible westbound and eastbound lanes as shown in Figure 9-2. Data from approaching traffic using the reversible lane was recorded during afternoon rush hours. The approximate locations of the areas viewed by the detectors are indicated in the figure. The size of the ground footprints of the detectors is a function of the mounting height, aperture beamwidth, and incidence angle as tabulated in Appendix F.

Overhead detector mounting locations on the pipe tree are shown in Figures 9-3 and 9-4. Lane 1 refers to the reversible lane, lane 2 to the leftmost eastbound lane, and lane 3 to the rightmost eastbound lane. The lowest pipe on

Symbol	Technology	Manufacturer	Model	Output Data
U-1	Ultrasonic Doppler	Sumitomo	SDU-200 (RDU-101)	Count, speed
U-2	Ultrasonic Presence	Sumitomo	SDU-300	Count, presence
U-3	Ultrasonic Presence	Microwave Sensors	TC-30C	Count, presence
M-1	Microwave Detector Motion Medium Beamwidth	Microwave Sensors	TC-20	Count
M-2	Microwave Detector Doppler Medium Beamwidth	Microwave Sensors	TC-26	Count, speed binning
M-4 ^a	Microwave Detector Doppler Narrow Beamwidth	Whelen	TDN-30	Count, speed
M-5	Microwave Detector Doppler Wide Beamwidth	Whelen	TDW-10	Count, speed
M-6	Microwave Radar Presence Narrow Beamwidth	Electronic Integrated Systems	RTMS-X1	Count, presence, speed, occupancy
IR-1	Active IR Laser Radar	Schwartz Electro-Optics	780D1000 (Autosense I)	Count, presence, speed
IR-2	Passive IR Presence	Eltec	842	Count, presence
IR-3	Passive IR Pulse Output	Eltec	833	Count
IR-4 ^b	Imaging IR	Grumman	Traffic Sensor	Presence, speed
VIP-1	Video Image Processor	Econolite	Autoscope 2003	f
VIP-2	Video Image Processor	Computer Recognition Systems	Traffic Analysis System	ŧ
VIP-3 ^c	Video Image Processor	Traficon	CCATS-VIP 2	f
VIP-4 ^b	Video Image Processor	Sumitomo	IDET-100	f
VIP-5 ^d	Video Image Processor	EVA	2000	f
A-1 ^e	Passive Acoustic Array	ΑΤ&Τ	SmartSonic TSS-1	Count
MA-1	Magnetometer	Midian Electronics	Self-Powered Vehicle Detector	Count, presence
L-1 ^b	Microloop	3M	701	Count, presence
T-1 ^e	Tube-Type Vehicle Counter	Timemark	Delta 1	Count

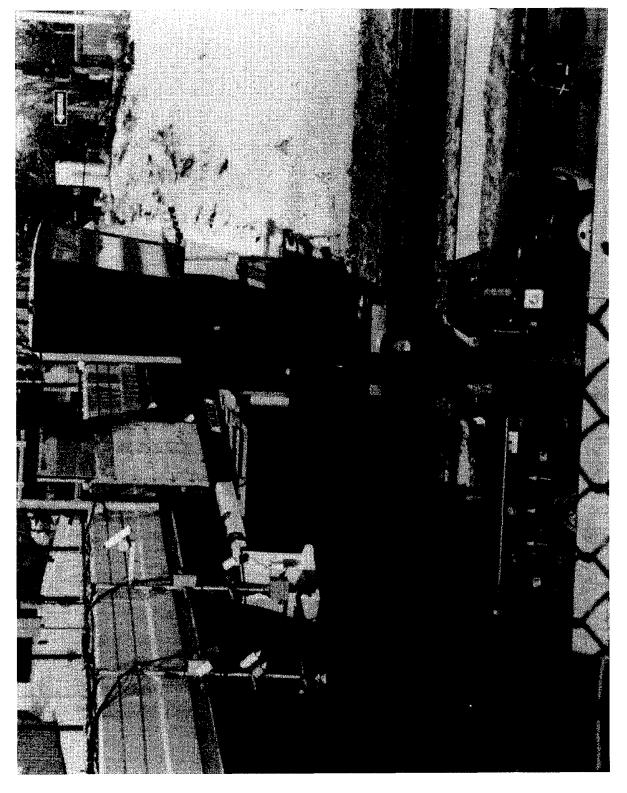
a. M-3 was designated for a microwave radar detector that was not received.

b. Used at Tucson, Arizona test site only. c. Used at all Arizona test sites.

d. Used in Phoenix, Arizona 7/94 test only.

e. Used in Phoenix 11/93 and Tucson tests.

f. Count, presence, occupancy, speed, classification based on length. Some provide headway, density, and alarm functions.





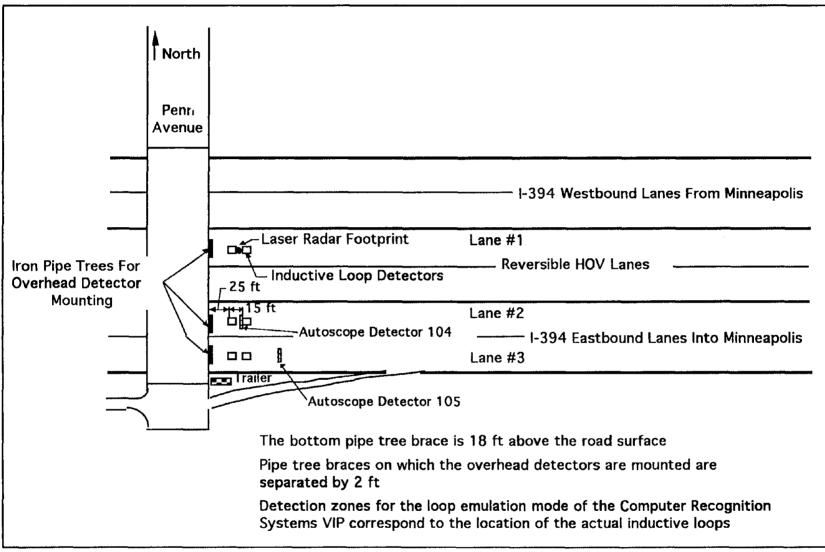


Figure 9-2. Location of Detectors on I-394

9-4

1 ft = 0.305 m

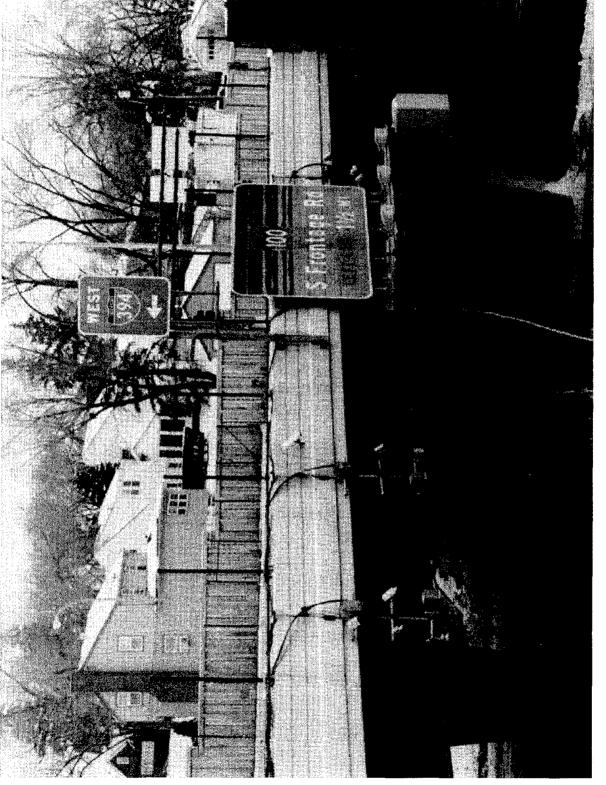


Figure 9-3. Detectors Over Eastbound and Reversible Lanes on I-394

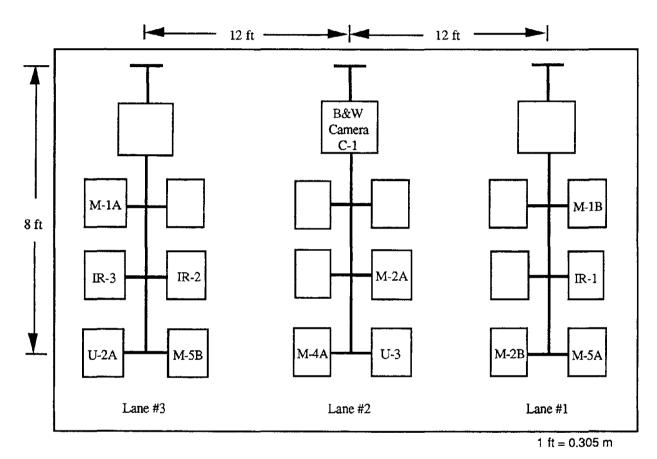


Figure 9-4. I-394 Overhead Detector Layout

the pipe tree was 18 feet (5.5 m) above the road surface and the separation between pipes was 2 feet (0.6 m). The black-and-white video camera was located 24 feet (7.3 m) above lane 2. A pair of 6-foot (1.8-m) square inductive loop detectors was installed in each of the three lanes with a 15-foot (4.6-m) leading-edge-to-leading-edge spacing. Inductive loop specifications used by each of the states are furnished in Appendix G. The self-powered magnetometers were not available at this site. Traffic cones were placed on the freeway shoulder at 50-foot (15.2-m) intervals to aid in video image processor field-of-view calibration.

The trailer that housed the detector data and video recording equipment, power supplies, and detector electronics is shown in Figure 9-5. It was located at the southeast corner of the intersection of Penn Avenue with the 1-394 freeway, behind a barrier rail. About 200 wires were run from the trailer to the detectors to supply power and record the output data as shown in Figure 9-6.

After data acquisition at the freeway site was completed, the trailer and overhead detectors were removed and transported to the surfacestreet evaluation site at Olson Highway and East Lyndale Avenue North. Here, westbound departing traffic was monitored as shown in Figure 9-7. The trailer is shown in Figure 9-8. The pipe trees were fastened to a sign bridge, as illustrated in Appendix E, that spanned the westbound lanes. Two of the overhead detectors, the TC-20 microwave detector and the 780D1000 laser radar, monitored approaching traffic. The laser radar could only respond to approaching traffic at this stage in its design (it was later modified to monitor both approaching and departing traffic), while the TC-20 was used to provide vehicle-count data to compare with the laser radar since the video camera did not record traffic flow in this region. Cables were run from the trailer on the south side of Olson Highway to the overhead sign structure on the north side of the street as shown in Figure 9-9. A high-gain antenna was mounted on one corner of the trailer to receive signals from the self-powered magnetometers. The overhead detector layout for the Olson High-way site is shown in Figures 9-10 and 9-11. White stripes,

spaced at intervals of 50 feet (15.2 m) as measured from the sign bridge, were painted on the edges of the westbound lanes to aid in calibration of the field of view seen by the video image processors.

Figure 9-12 shows Olson Highway being cored in the center of the loops in lane 2 (middle through lane) for the self-powered magnetometer detectors. The hole was approximately 22 inches (559 mm) deep by 6 inches (152 mm) in diameter. Two to three inches (51 to 76 mm) of cold patch were placed on top of the magnetometer to seal the hole as in Figure 9-13. The extra magnetometer in the upper part of the photograph shows the relative size of the detector that was buried. A side-mounted TC-30C ultrasonic detector and a Remote Traffic Microwave Sensor (RTMS) microwave radar were attached to a streetlight pole as shown in Figure 9-14. The TC-30C monitored traffic in lane 3 (the rightmost lane) of Olson Highway and the RTMS-monitored traffic in the three westbound lanes. Both detectors were lowered from the positions shown in the photograph before they were made operational. Since the video camera did not record traffic in this area, there is no video ground truth for these two devices. The time of occurrence of the green-phase signal at the Olson Highway-Lyndale Avenue intersection was recorded on a relay data logger input. The green phase was used to correlate the occurrence of vehicle queues with detector output.

The electronics racks that housed the power supplies, terminals for the outgoing power and input data, video recorder, video monitor, video image processor equipment, and inductive loop electronics cards at the Minneapolis sites are shown in Figure 9-15. In the lower left of the photograph is the data logger with the front panel removed. On the top of the leftmost rack is the video monitor used to observe traffic flow. Mounted in the rack, from top to bottom, are the Autoscope 2003 electronics, a personal computer (PC)controlled video recorder, sliding shelf on which the computer keyboard is shown, a Type 170 chassis in which inductive loop electronics cards were inserted, and powersupply modules. The power output to the detectors came from a panel on the right side of this rack. The rack on the right of the photograph shows the panel to which the

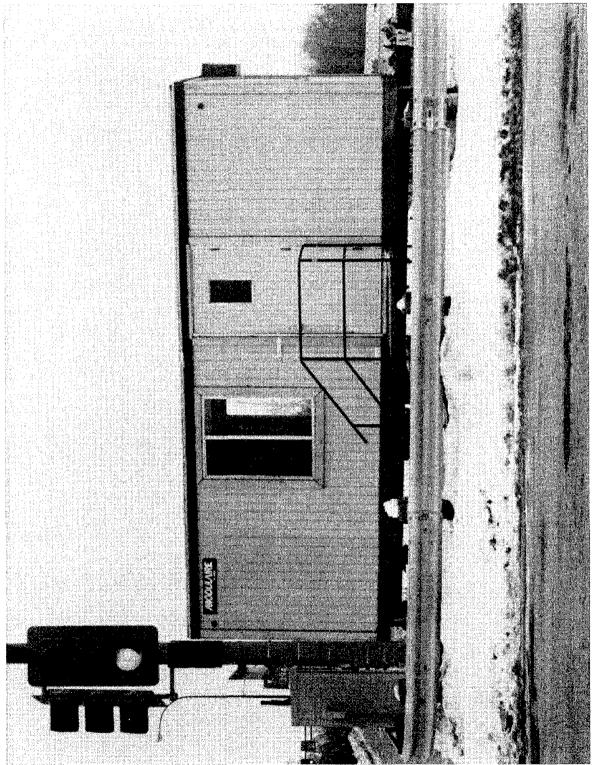
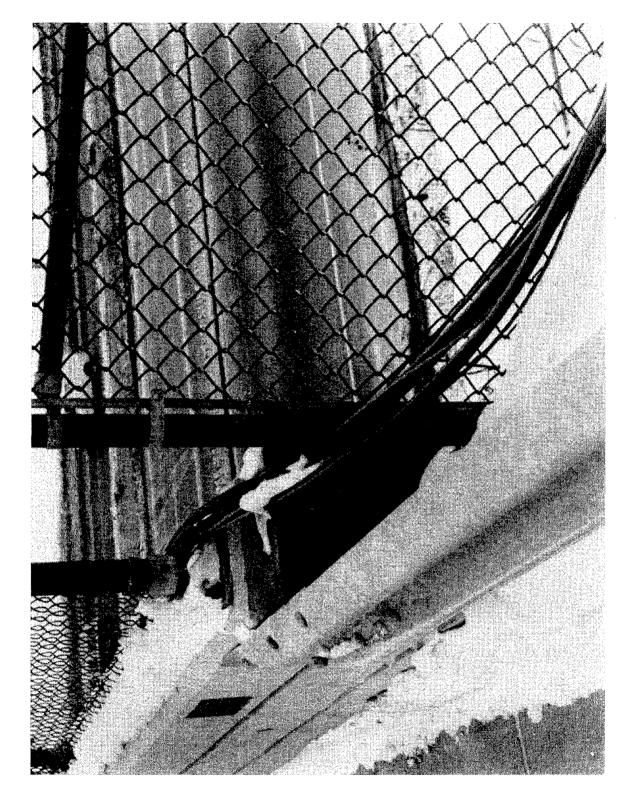
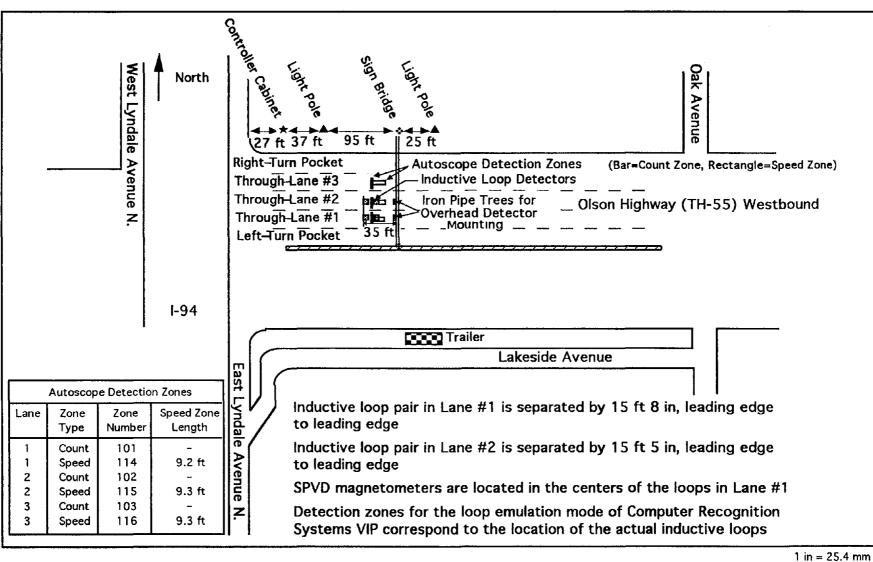


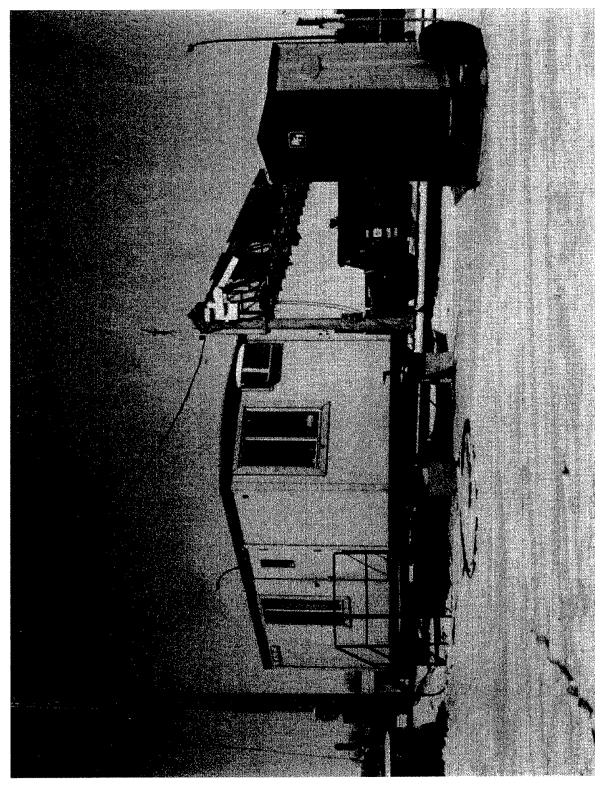
Figure 9-5. Data Acquisition Trailer at 1-394





1 in = 25.4 mm1 ft = 0.305 m

Figure 9-7. Olson Highway Surface-Street Site in Minneapolis





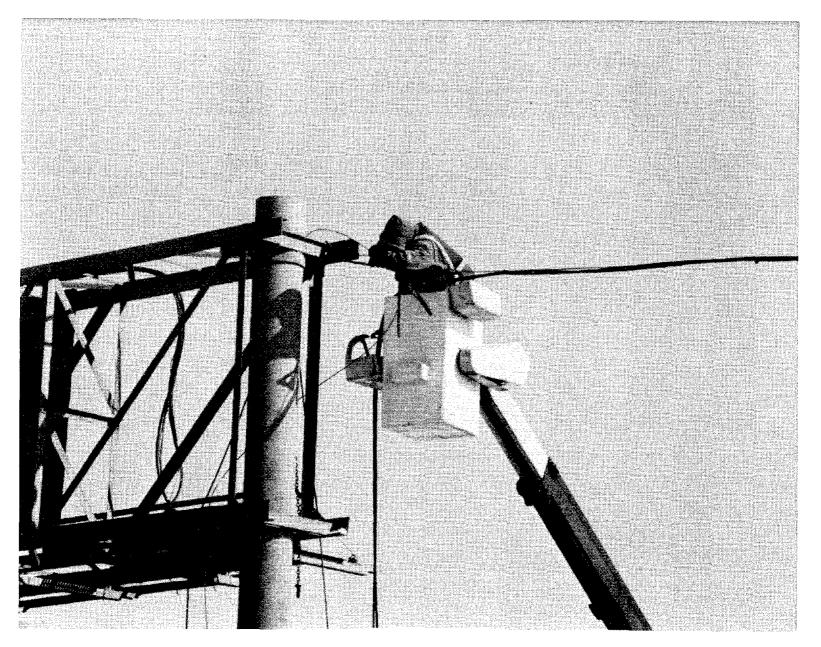


Figure 9-9. Installation of Detector Output Data Cables and Input Power Cables at Olson Highway Surface-Street Site



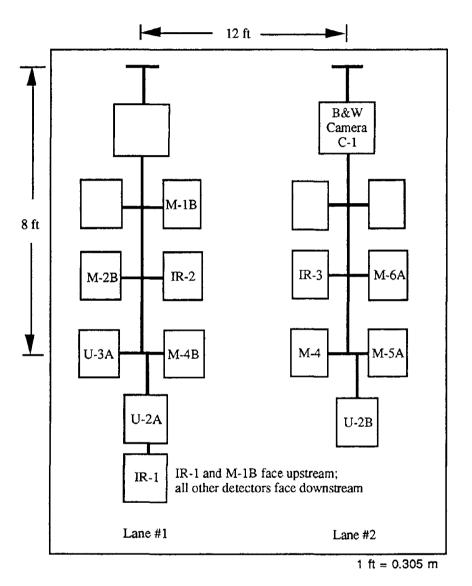


Figure 9-11. Olson Highway Overhead Detector Layout

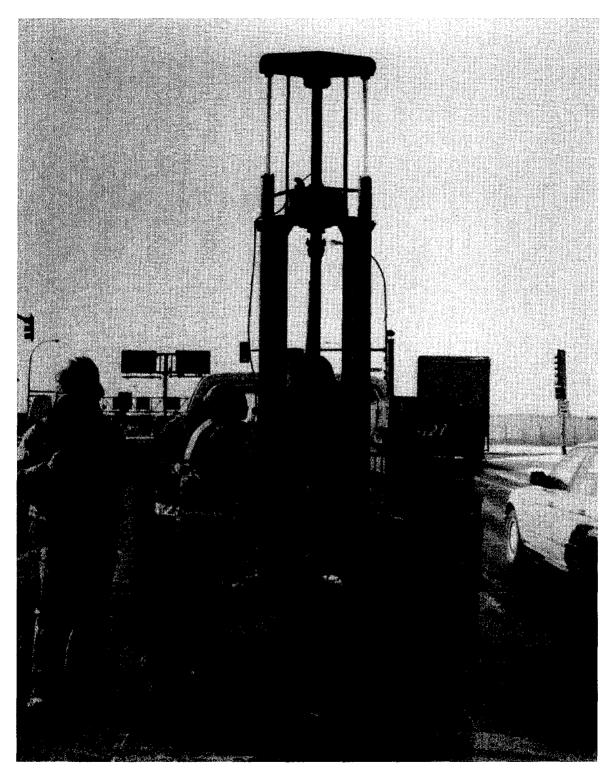
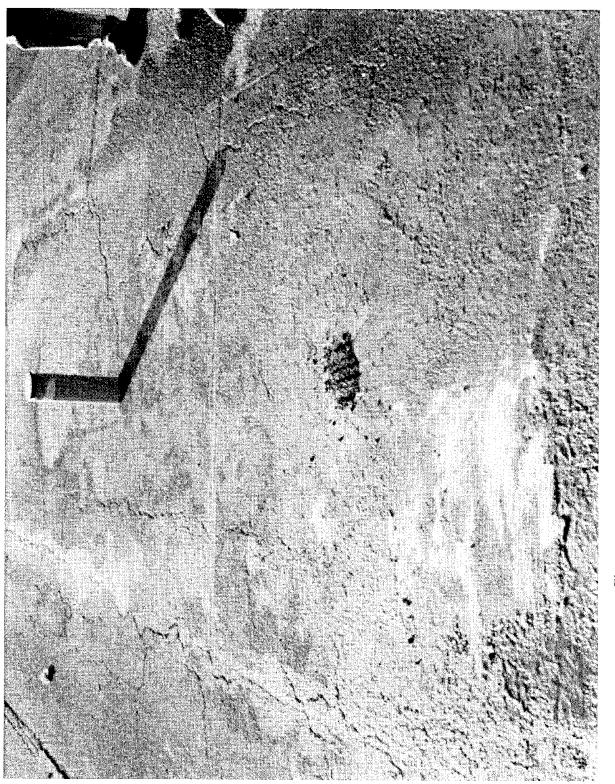
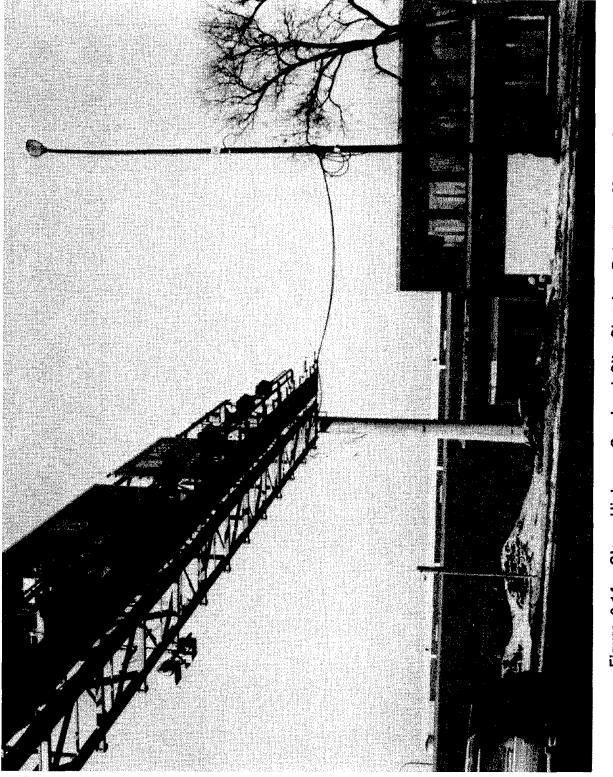
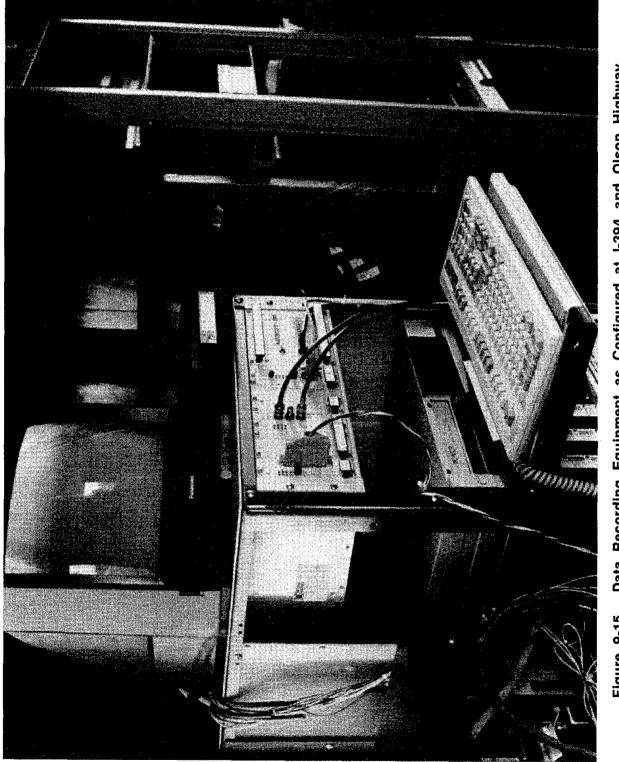


Figure 9-12. Coring of Olson Highway for Self-Powered Magnetometers







detector outputs were connected before being routed to the data logger. The connections from the detectors to the data logger and power supplies are shown in Appendix H for all the sites.

9.2 ORLANDO EVALUATION SITES

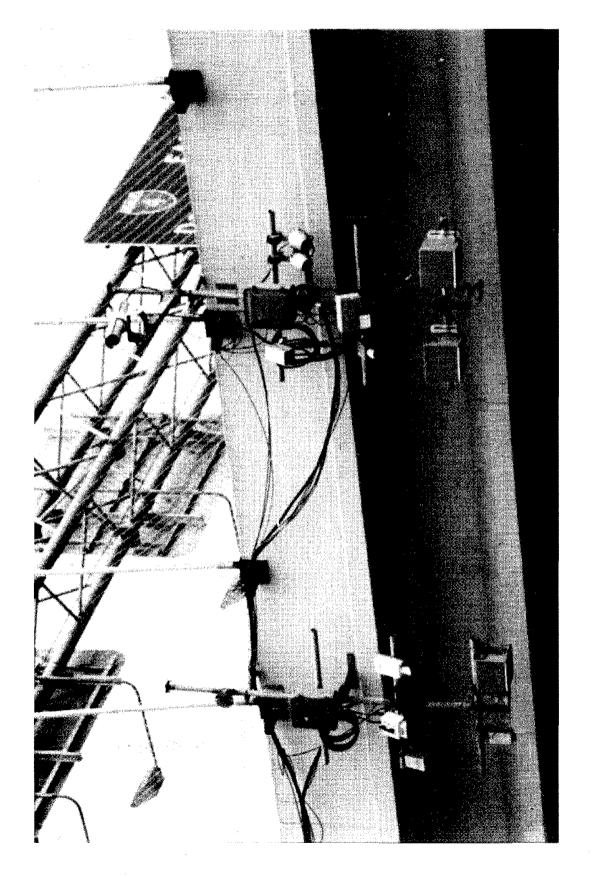
The Florida freeway detector evaluation site was located on I-4 at SR 436 just north of Orlando in Altamonte Springs. The overhead detector configuration of Figures 9-16 and 9-17 viewed approaching traffic in the leftmost and middle lanes (lanes 1 and 2, respectively) of the westbound freeway into Orlando. The pipe trees were attached to the north face of the SR 436 overpass. The bottom pipe was 16.56 feet (5.05 m) above the road surface in lane 1 and 16.26 feet (4.96 m) above the road surface in lane 2. Horizontal pipe sections were 2 feet (0.6 m) apart. The modified Burle camera supplied with the Autoscope VIP had an 8-mm, f/1.4 lens and was mounted 24.26 feet (7.39 m) above lane 2. Pairs of 6-foot (1.8-m) square inductive loop detectors were installed in lanes 1, 2, and 3 (the rightmost lane) as shown in Figure 9-18. The self-powered magnetometer detectors with 15-foot (4.6-m) center-to-center spacing were located in the center of the loops in lane 1. The Autoscope detection zones, inductive loop detectors, and camera field of view are shown in Figure 9-19. The south loop in each lane was not in the viewing area of the camera.

A TC-20 microwave detector was sidemounted on an overpass support in the median to view traffic in the left westbound lane of I-4 as shown in Figure 9-20. The traffic flow was at an angle of between 20 and 30 degrees with respect to the antenna boresight. A side-mounted RTMS microwave radar was bolted to a round wooden utility-type pole on the shoulder of the eastbound lanes. The antenna boresight of the detector was perpendicular to the traffic flow as in Figure 9-21. The pole was set in a grassy area 16 feet (4.9 m) from the right edge of the rightmost eastbound freeway lane and 27 feet (8.2 m) from the north face of the SR 436 overpass. It monitored traffic in the three westbound lanes within the viewing area of the video camera. In this way, the video

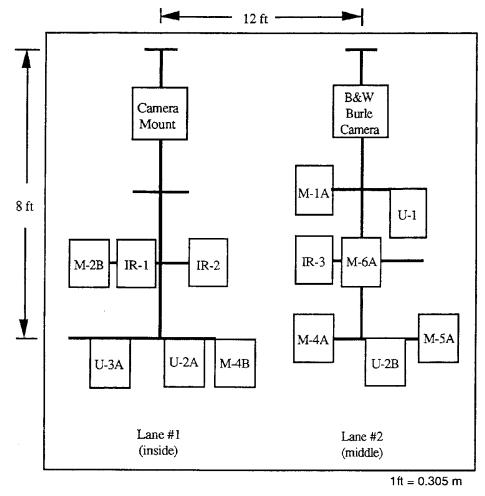
imagery could be used to obtain vehicle count ground truth to calibrate the RTMS detector. The side-mounted RTMS detector was also configured to monitor traffic in the three eastbound lanes. However, the video imagery did not cover this area. The trailer, video camera, overhead detectors, and chain-link fence are also shown in the photograph. Traffic cones and paint stripes numbered 1, 2, 3, ... (also shown in Figure 3-8) were placed on the right shoulder of the westbound freeway in 25-foot (7.6 m) intervals for video image processor calibration.

The trailer was located on the shoulder of the eastbound lanes under the SR 436 overpass. This location was chosen so that the overhead detectors could later be moved to the surface street above the freeway without moving the trailer. A high-gain antenna was mounted on one corner of the trailer to receive signals from the self-powered magnetometers. The cables were run from the trailer along the overpass to the detectors. A chain-link fence was installed on the overpass to prevent tampering with the overhead detectors and the cables.

The data recording configuration used in Orlando is shown in Figure 9-22. The edge of the PC keyboard is at the extreme lower left corner of the photo. To its right is the Puma 88 drive that contains the removable 88MB cartridges used to record the digital and analog outputs of the detectors during each run. The 386 PC containing the application-specific software that controls the data logger is to the right of the Puma drive. The interface for the 16 detector RS-232 serial inputs is on top of the computer. The main data logger is located to the right of the computer. It contains hardware and software that support the 8 analog detector outputs, 16 relay outputs, and 16 optically isolated detector outputs. To its right is a panel on which the outputs from the traffic detectors and environmental sensors are connected as they enter the trailer on cables. The Sumitomo electronics for the SDU-200 (RDU-101) and SDU-300 ultrasonic detectors were placed on the floor under the table. An uninterruptable power supply and surge protectors on each data line entering the trailer from the outside protected the recording equipment from lightning strikes.



Detectors Over Westbound Lanes at Orlando I-4 Freeway Site Figure 9-16.



U-1 SDU-200 U-2 SDU-300 U-3 TC-30C M-1 TC-20 M-2 TC-26 M-4 TDN-30 M-5 TDW-10 M-6 RTMS IR-1 780D1000 IR-2 842 IR-3 833

Figure 9-17. I-4 Overhead Detector Layout

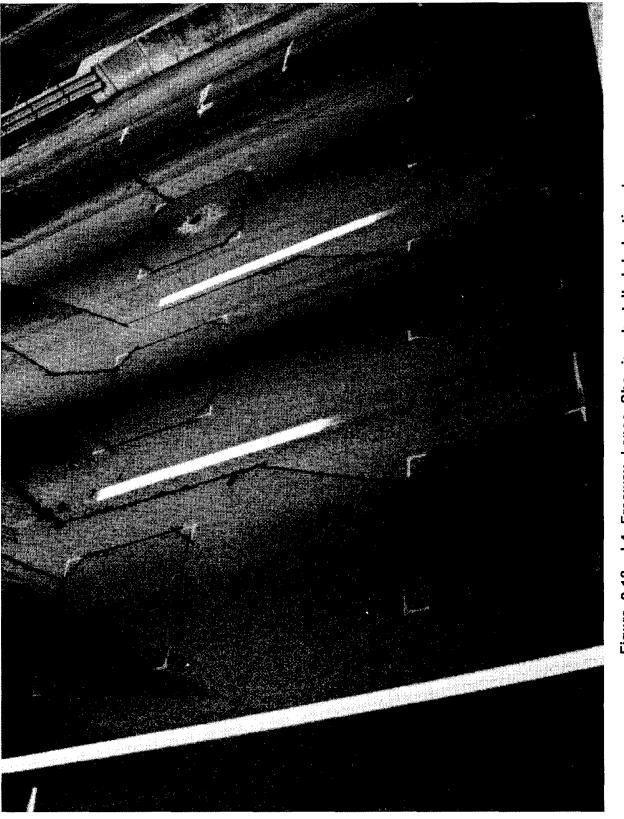


Figure 9-18. I-4 Freeway Lanes Showing Installed Inductive Loops and Self-Powered Magnetometers

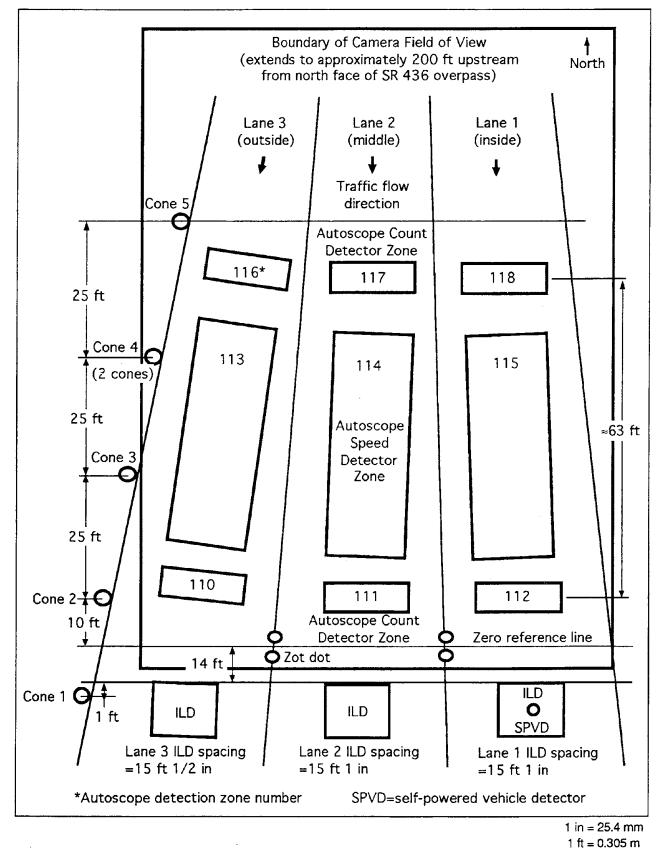


Figure 9-19. Location of Inductive Loop Detectors, Autoscope Detection Zones, and Camera Field of View on I-4



Figure 9-20. Side-Mounted TC-20 Microwave Detector on Overpass Support Structure on I-4 Freeway Median

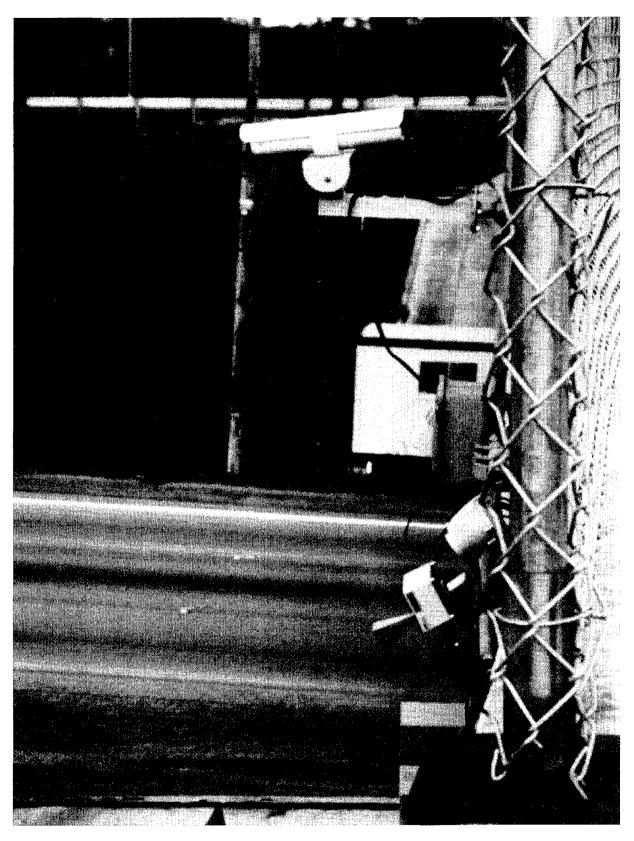


Figure 9-21. View Toward Eastbound I-4 Showing Side-Mounted RTMS Microwave Detector, Trailer, Video Camera, and Overhead Detectors

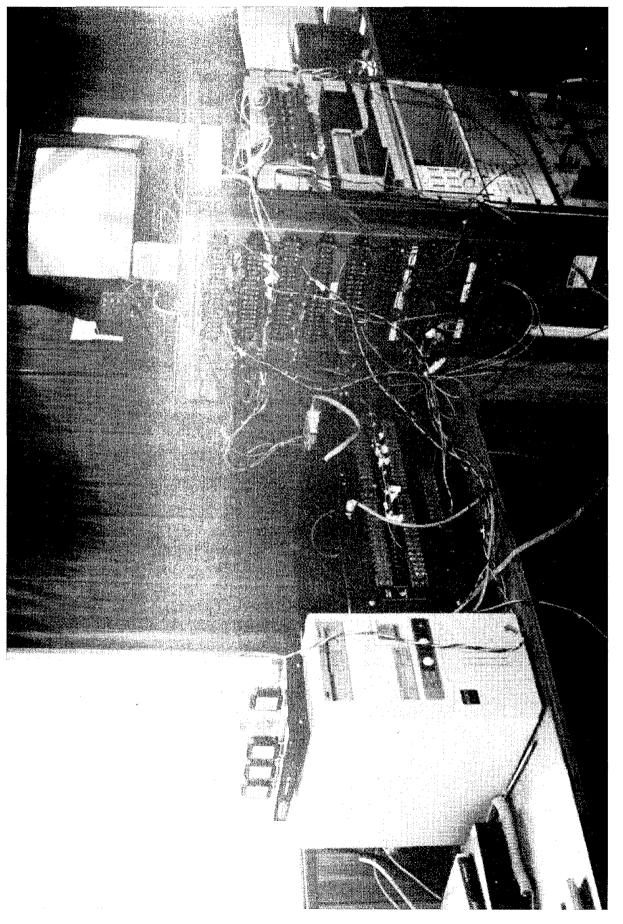


Figure 9-22. Data Recording Equipment as Configured at Orlando

Sitting on top of the 19-inch (483-mm) rack are a monitor that displays video of the traffic flow, the receiver for the selfpowered magnetometer detectors, and a speaker that emits a tone when a vehicle passes over the magnetometers. Mounted in the rack, from top to bottom, are the auxiliary data logger that records an additional 24 optically isolated detector outputs, a computer-controlled VHS video recorder upon which the traffic flow is recorded, a Type 170 electronics chassis in which inductive loop electronics cards were inserted, and the Autoscope 2003 video image processor electronics. Output power to the detectors is available on the right side of the rack (not shown).

When the evaluation on the I-4 freeway was completed, the overhead detectors were moved to the SR 436 overpass and mounted behind the signs on a sign-bridge structure. Here they monitored westbound departing traffic on the SR 436 surface arterial as shown in Figures 9-23 and 9-24. The construction details for the overpass are given in Appendix I. The software in the 780D1000 laser radar required it to monitor approaching traffic in lane 1. A monochrome, 1/2-inch (12.7mm) (6.4- x 4.8-mm) Charge Coupled Device (CCD) Cohu series 4910 camera with an 8- to 48-mm zoom lens was mounted 32 feet (9.8 m) above lane 2. RS-170 resolution was 580 horizontal TV lines by \geq 350 vertical TV lines. Figure 9-25 shows the road surface as marked for video image processor calibration. Since SR 436 went over a bridge at the evaluation site, the selfpowered magneto-meters were mounted under the road at the approximate center of the loops in lane 2 as indicated in Figure 9-26. The magnetometers were put into wooden boxes that were placed on bridge vertical support structures that were already located under the overpass.

An RTMS microwave radar was mounted on a specially erected pole on the south edge of the overpass across the road from the westbound lanes as in Figure 9-27. It was aimed at traffic (side viewing) in the stopbar region of the roadway. During its calibration, the video camera was repositioned to view traffic in the area observed by the RTMS. After calibration of the side-viewing unit, an interruption in the serial communication between the RTMS

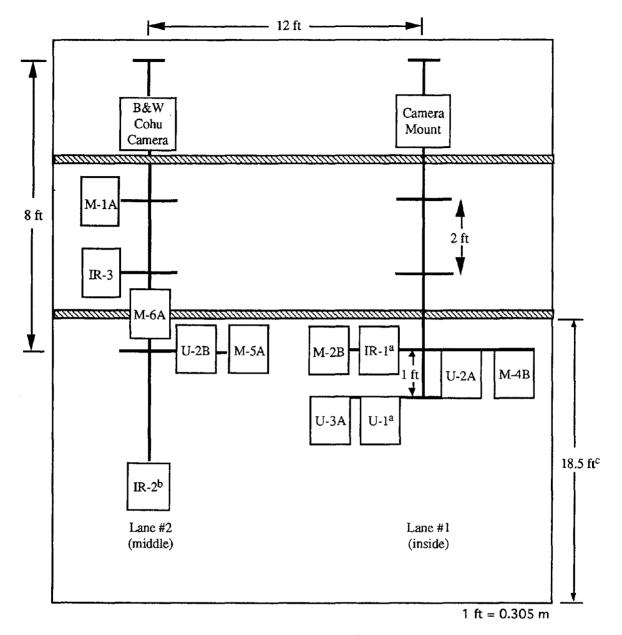
and the data logger occurred. As a result, no valid data were recorded for the side-looking unit at the Florida surface-street site. The locations of the loops, self-powered magnetometers, and Traffic Analysis System calibration zones are shown in Figure 9-28. The time of occurrence of the green phase signal at the SR 436 and I-4 off-ramp intersection was recorded using a relay data logger input.

9.3 PHOENIX EVALUATION SITE

The westbound I-10 freeway near Thirteenth-Street in Phoenix was used as the detector evaluation site for regions representative of warm and hot dry climates. This site was used twice, once in Autumn 1993 and again during the Summer of 1994. Approaching traffic was observed by the overhead detector configuration shown in Figures 9-29 and 9-30 during the Autumn 1993 evaluation and by Figures 9-31 and 9-32 during the Summer 1994 evaluation. The AT&T acoustic array was designed to look downstream and view departing traffic as shown in Figure 9-33. The AT&T array and Sumitomo IDET-100 video image processor were evaluated in the Autumn 1993 period. The EVA 2000 video image processor was evaluated during the Summer 1994 period. A side-mounted RTMS microwave radar, shown in Figure 9-34, was installed in the shoulder area on a wooden pole aligned with the first inductive loop.

The stub antenna that received the signals from the self-powered magnetometers installed in the center of the inductive loops in lane 2 was also mounted on this pole. We found that the larger, higher gain antenna was not needed since the trailer containing the magnetometer signal receiver was relatively close to the magnetometers. The higher gain antenna also appeared to pick up more of the noise generated by the PCs in the trailer, even though it was attached to the outside of the trailer. The noise prevented the receiver from generating tones corresponding to the signals transmitted by the magnetometers. Another remedy that eliminated most of the external noise from the magnetometer receiver was to connect the receiver to its own AC voltage circuit in the trailer.





- a. IR-1 and U-1 face approaching traffic. All other detectors face departing traffic.
- b. IR-2 mounted on sign-bridge light fixture above lane 2, looking at traffic in lane 1.
 M-6A mounted to sign-bridge span.
- c. Measured from bottom of sign-bridge to high point of roadway.

Existing sign-bridge span.

Figure 9-24. SR 436 Overhead Detector Layout

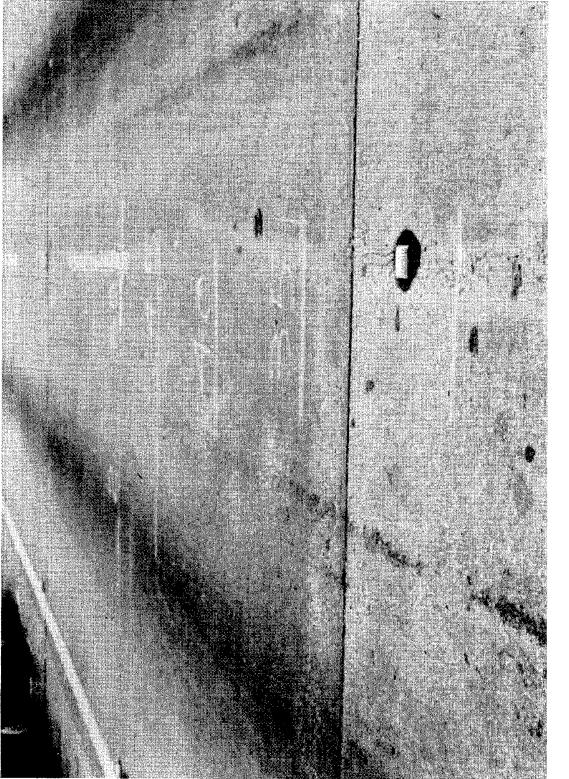
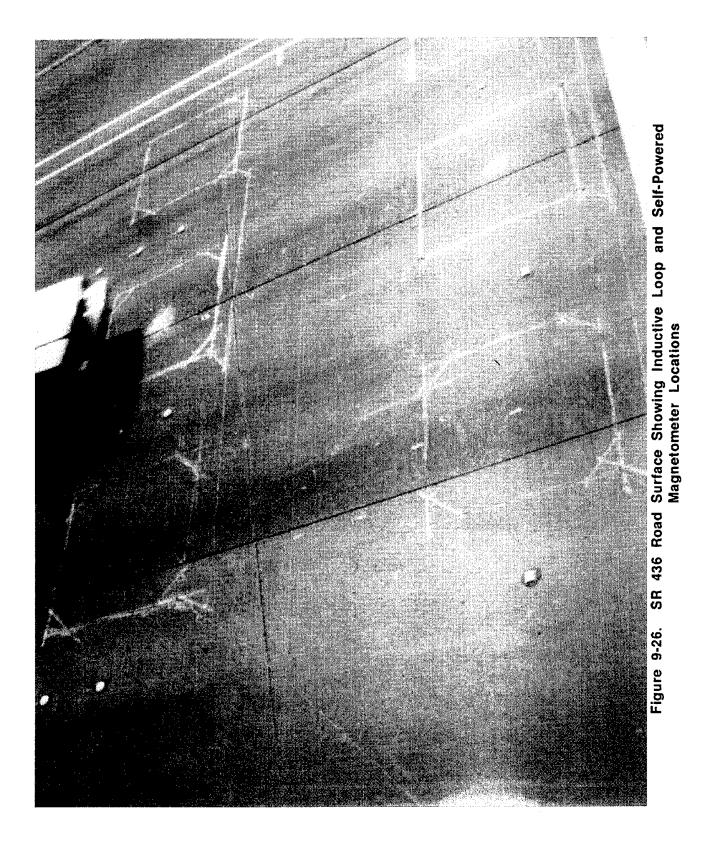
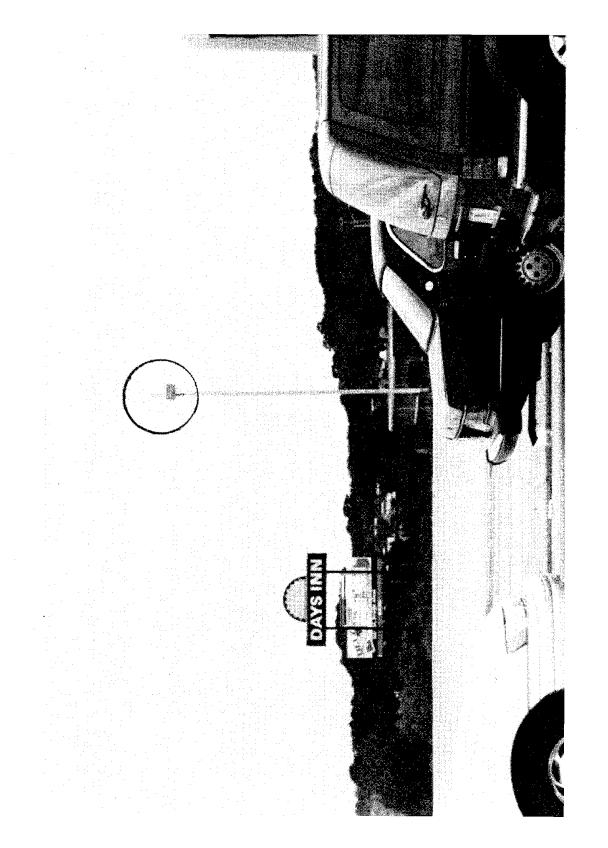
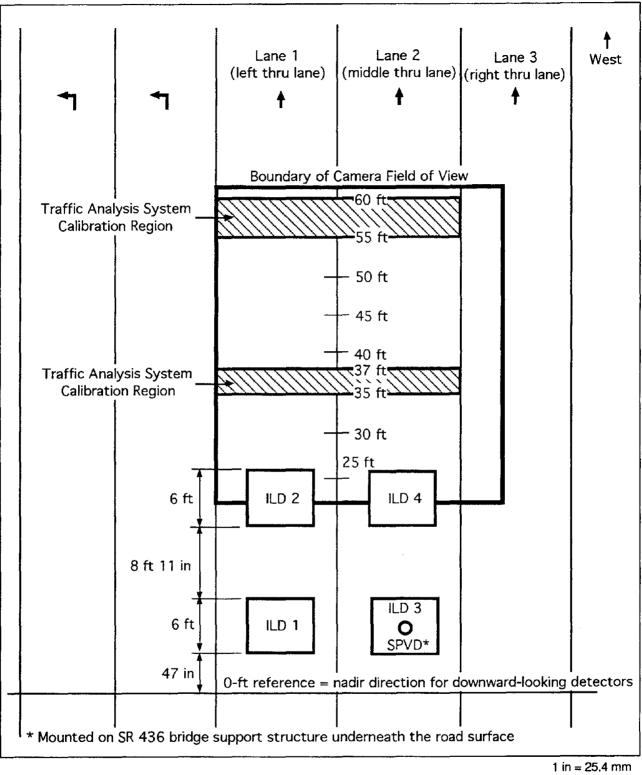


Figure 9-25. SR 436 Marked With Calibration Distances for Video Image Processors

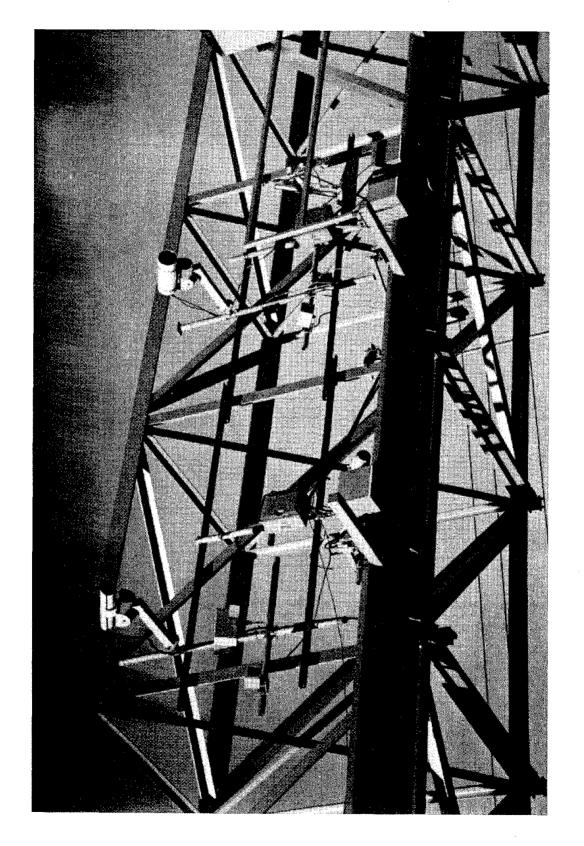






¹ ft = 0.305 m

Figure 9-28. Location of Inductive Loop Detectors, Self-Powered Magnetometers, Traffic Analysis System Calibration Regions, and Camera Field of View on SR 436



Detectors Over Westbound Lanes of Phoenix I-10 Freeway Site (Autumn 1993) Figure 9-29.

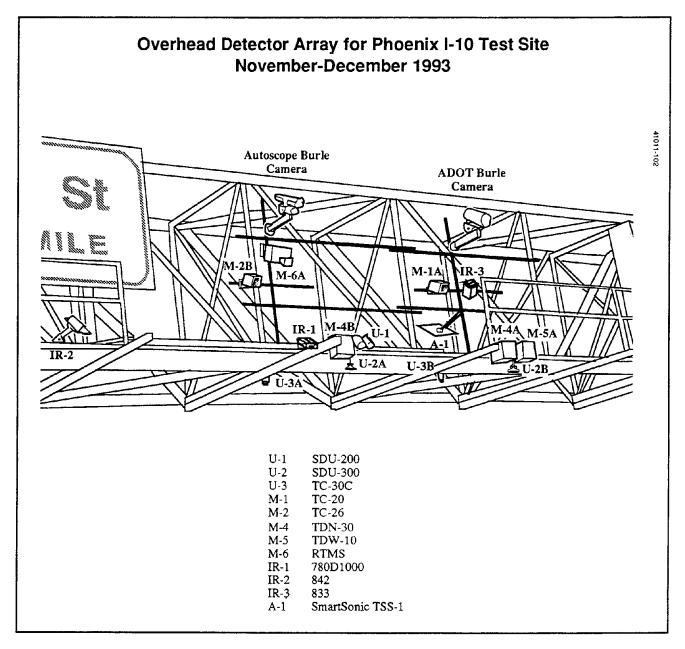


Figure 9-30. I-10 Overhead Detector Layout (Autumn 1993)

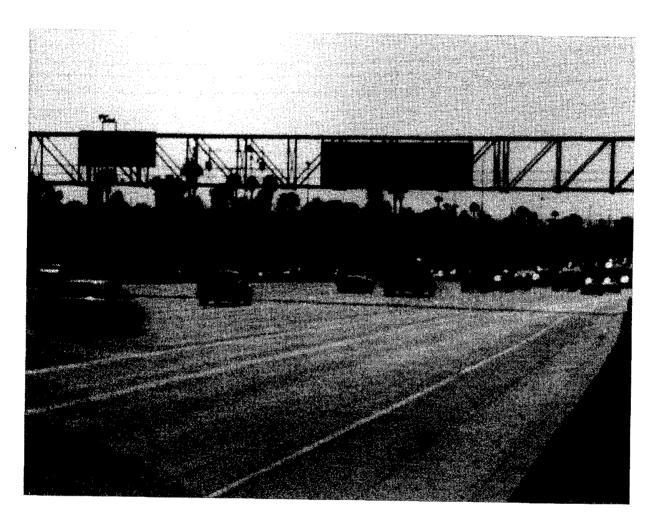


Figure 9-31. Detectors Over Westbound Lane of Phoenix I-10 Freeway Site (Summer 1994)

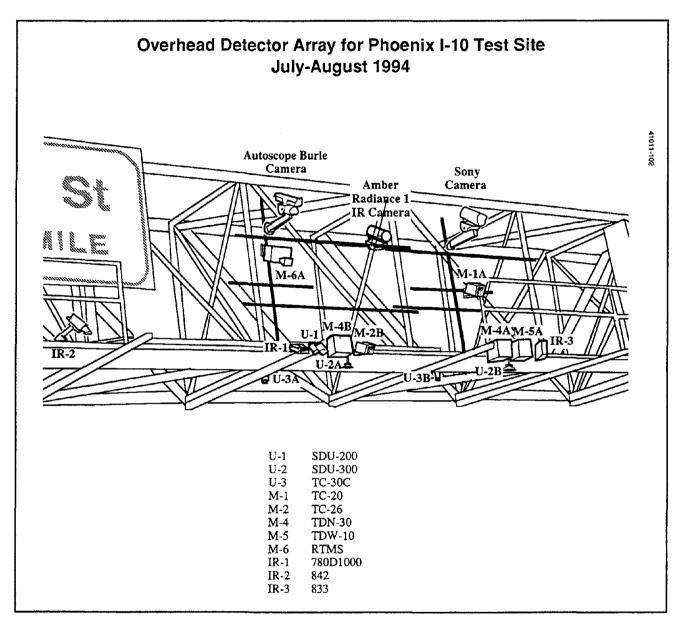


Figure 9-32. I-10 Overhead Detector Layout (Summer 1994)

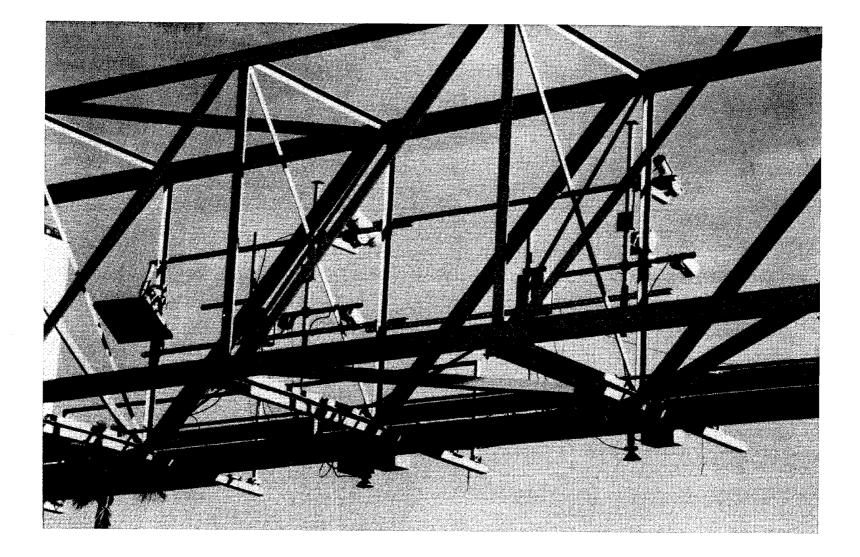
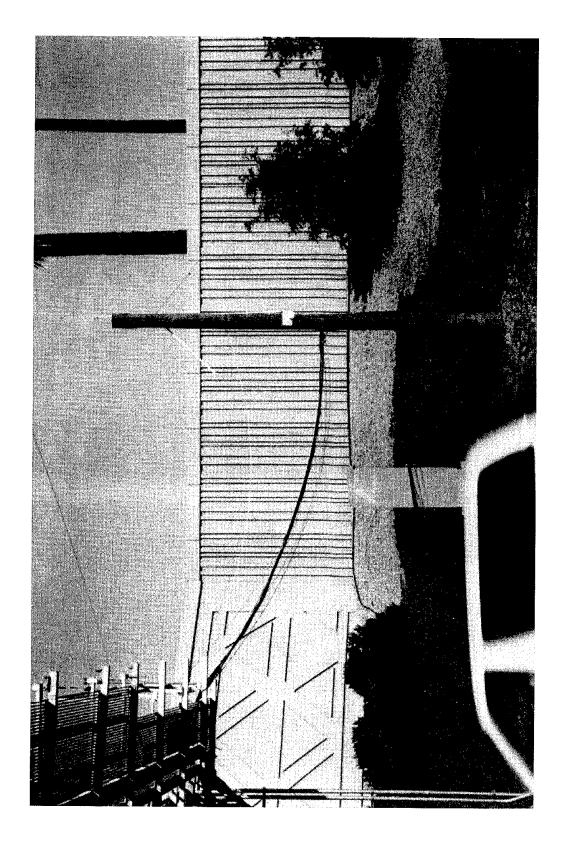


Figure 9-33. Overhead Detectors at I-10 Freeway Showing AT&T Acoustic Array Monitoring Departing Traffic (Autumn 1993)



Locations of in-ground detectors and video image processor calibration zones were measured from the poles that support the sign structure, as shown in Figures 9-35 and 9-36 for the Autumn 1993 evaluation and in Figure 9-37 for the Summer 1994 evaluation. The downward-looking detectors observed traffic directly below the sign structure. The others, with the exception of the acoustic array and the Eltec 833, observed approaching traffic in the vicinity of the inductive loops. The acoustic array was designed to detect departing traffic and was. therefore, aimed toward the other side of the sign structure, observing traffic in lane 2 (middle through-traffic lane).

The trailer was located at the far edge of the shoulder for the westbound lanes at the top of

an incline as shown in Figure 9-38. The cables were run out of the trailer through an opening in the bottom, along the ground and to the top of the wooden pole on which the sidelooking RTMS detector was mounted, and then over to the sign-bridge structure.

The sign structure was accessed with a ladder that led to a hatch in the walkway. The detectors were attached to the walkway, located 19 feet 8 inches (6.0 m) above the freeway, or to vertical and horizontal elements on the structure with an assortment of clamps. The walkway provided a relatively easy way to aim the overhead detectors at the desired traffic lanes. The heights of the detectors above the top surface of the walkway are shown in Table 9-3.

Detector	Symbol	Height Above Walkway
SDU-200 (RDU-101)	U - 1	36 inches
SDU-300	U-2A, U-2B	8 inches to center of horn aperture
TC-20	M-1A	37-3/4 inches to bottom of detector
TDN-30	M-4A, M-4B	0 inch
TDW-10	M-5A	0 inch
RTMS-X1	M-6A	50 inches
780D1000 (Autosense I)	IR-1	0 inch
842	IR-2	6 inches
833	IR-3	39 inches to bottom of detector 36 inches to center of lens
SmartSonic TSS-1	A-1	37 inches to bottom of array 43 inches to center of array

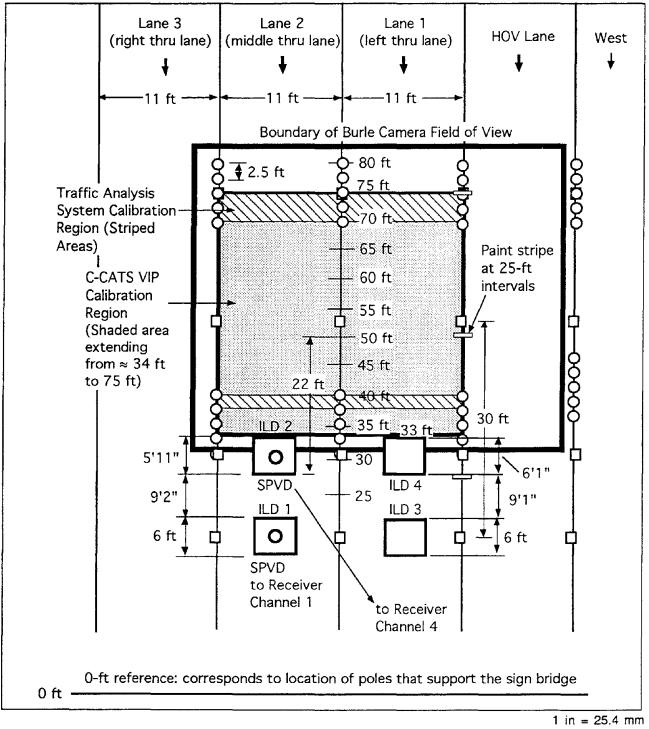
Table	9-3.	Heights	of	Detectors	Above	Walkwav*	at	Phoenix	1993	Evaluation
T UDIC	v v.	noigino	v .		710010	mannuy	~ ~		1000	

* Walkway is 19 feet 8 inches above freeway surface

Two video cameras were used in both the Phoenix and Tucson locations, one for the Autoscope video image processor and one for the other image processors. The Autoscope employed a specially modified camera to provide imagery features that maximized its performance. It was mounted 26-1/4 feet (8.0 m) above the freeway road surface. Since the Autoscope manufacturer believed that his camera would enhance the performance of the other image processors, we obtained a second camera from the Arizona Department of Transportation for the Autumn

1993 runs that provided imagery to the rest of the image processors. This camera was a Burle Model TC301 with a 12.5-mm, f/1.4 lens. It was also mounted 26-1/4 feet (8.0 m) above the road surface and covered the same viewing area as the Autoscope camera. In Summer 1994, the camera was supplied by Sumitomo and was the model recommended for use with the IDET-100 video image processor. Its characteristics were: 1/2inch (12.7-mm) CCD format (6.2 mm x 4.6 mm), auto iris on, Automatic Gain Control (AGC) off, and 525 useful Electronic

1 in = 25.4 mm1 ft = 0.305 m



1 ft = 0.305 m

Figure 9-35. Location of Inductive Loop Detectors, Self-Powered Magnetometers, Traffic Analysis System and CCATS Calibration Regions, and Burle Camera Field of View on I-10 (Autumn 1993)

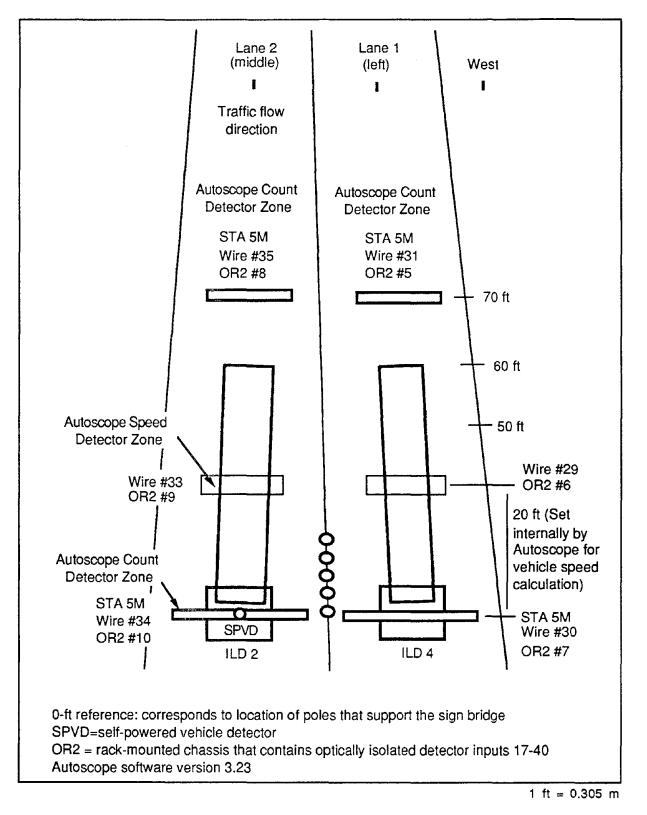


Figure 9-36. Location of Autoscope Detection Zones on I-10 (Autumn 1993 and Summer 1994)

Install Vehicle Detectors at Field Sites and Collect Field Test Data

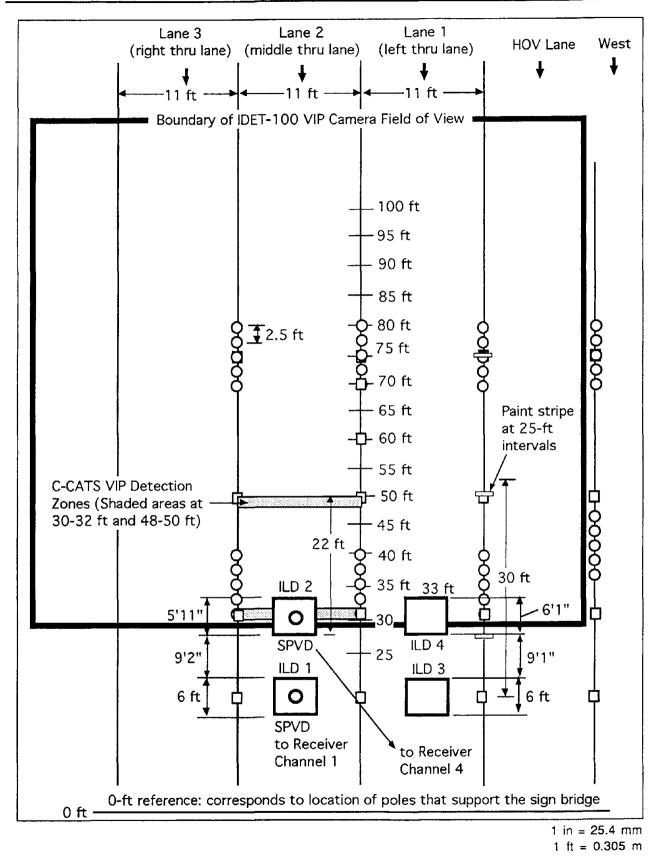


Figure 9-37. Location of In-Ground Detectors, CCATS Detection Zones, and IDET-100 Camera Field of View on I-10 (Summer 1994)

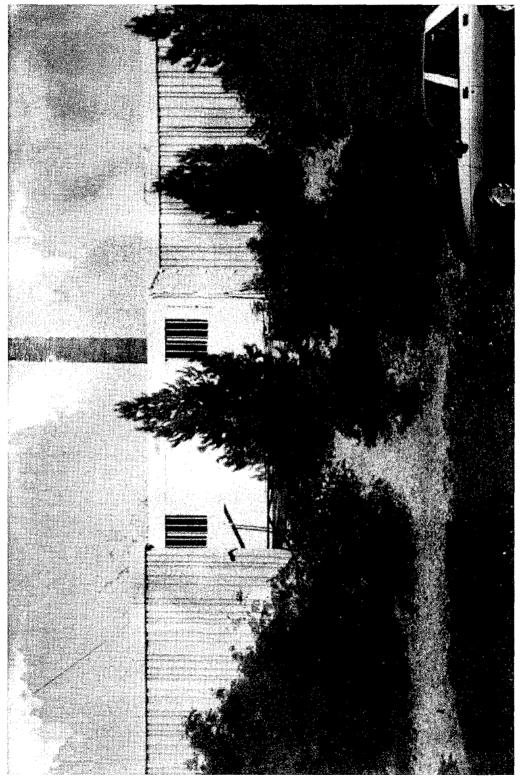


Figure 9-38. Data Acquisition Trailer on I-10

Industry Association (EIA) lines. During the Summer 1994 evaluation, an infrared camera was obtained from Amber and was used to record concurrent imagery of the traffic flow in the 8- to 12- μ m region of the infrared spectrum on a third video recorder. However, this infrared video was not frame or time synchronized with the other detector data recorded by the data logger. (The data logger was designed to operate with two VCRs only.) Because of lens focal length restrictions, the area monitored by the Amber camera was several hundred feet upstream of the sign bridge and did not coincide with the viewing area of the other detectors.

The equipment rack as configured for Phoenix in Autumn 1993 is shown in Figure 9-39. On the top is one of the monitors, the distribution amplifier for the video image processors except Autoscope, and the CCATS-VIP 2 video image processor. Mounted in the top of the rack is the Autoscope 2003. Below it are the two PC-controlled VCRs, the Type 170 interface that holds the inductive loop detector amplifier electronics cards and the AT&T SmartSonics card, and the power supply modules. Near the bottom of the rack is the auxiliary data logger that supports up to 24 optically isolated detector inputs. Mounted on the left side of the rack is the panel that accepts the outputs from the detectors. A connection panel on the right side of the rack, shown in Figure 9-40, supplies input power to the detectors.

Figure 9-41 shows the table on which were placed the data logger, keyboard, 386 PC and computer monitor, the video monitor for the Autoscope camera, and the Puma 88 disk drive. The DigiChannel interface for the RS-232 detector serial outputs is on top of the PC. The electronics for the Sumitomo SDU-200 (RDU-101) and SDU-300 ultrasonic detectors and IDET-100 video image processor were located under the table. The Traffic Analysis System (TAS) video image processor is next to the table with the laptop PC.

The equipment rack as configured for Phoenix in Summer 1994 is shown in Figure 9-42. The layout of the equipment is similar to that used before. On the left, above a monitor, is the EVA 2000 video image processor. The TAS video image processor is to the right of the rack on its shipping case. Unfortunately, it was not operational during the Summer 1994 Phoenix evaluation because it was not shipped with the configuration needed for freeway traffic data collection. The table with the rest of the electronics is shown in Figure 9-43. The self-powered magnetometer signal receivers and Detector Systems 613-SS inductive loop detector amplifiers are on the right side of the table. The data logger, computer, and monitor are to their left. The electronics for the Sumitomo ultrasonic detectors and the uninterruptable power supply are on the floor of the trailer as shown in Figure 9-44.

In the Phoenix 1994 evaluation, the Detector Systems Model 613-SS inductive loop detectors were used to aid in ground truth vehicle speed measurement. Used in pulse mode, they provided a solid-state optically isolated transistor closure each time a vehicle passed over the loops. In addition, a probe vehicle equipped with the Loop Comm Model 600A vehicle transmitter generated a pulse output on another wire each time it passed over one of the loops connected to a 613-SS detector. By mounting the transducer on the bumper of our probe vehicle, as shown in Figure 9-45, vehicle speed ground truth data were obtained by noting the time, lane number, and speed from the vehicle's speed indicator when the probe vehicle passed over a loop in a particular lane. This procedure was repeated several times during a run for each monitored traffic lane.

9.4 TUCSON EVALUATION SITE

The Tucson surface-street evaluation site was located at the southwest corner of Oracle Road and Auto Mall Drive, across the street from the Tucson Mall. All three southbound lanes were instrumented with loops and the right and center lanes (lane 3 and iane 2, respectively) had the overhead detectors installed above them as shown in Figures 9-46 and 9-47. The Autoscope and Sumitomo IDET-100 VIP video cameras were used in Tucson. The field of view for the IDET-100 camera (also used for CCATS) is shown in Figure 9-48, along with the locations of the other detectors. The Autoscope, CCATS, and Grumman imaging infrared celibration areas

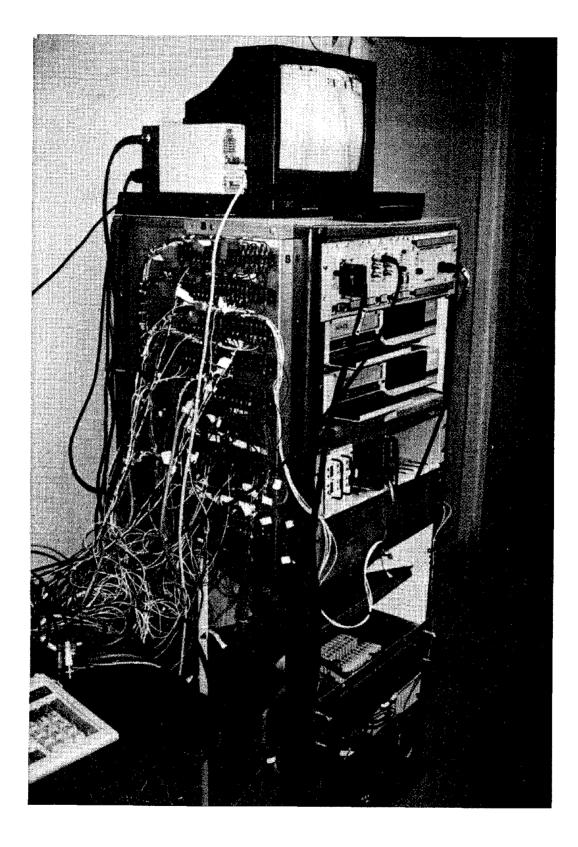


Figure 9-39. Data Recording Equipment Configured for I-10 (Autumn 1993)

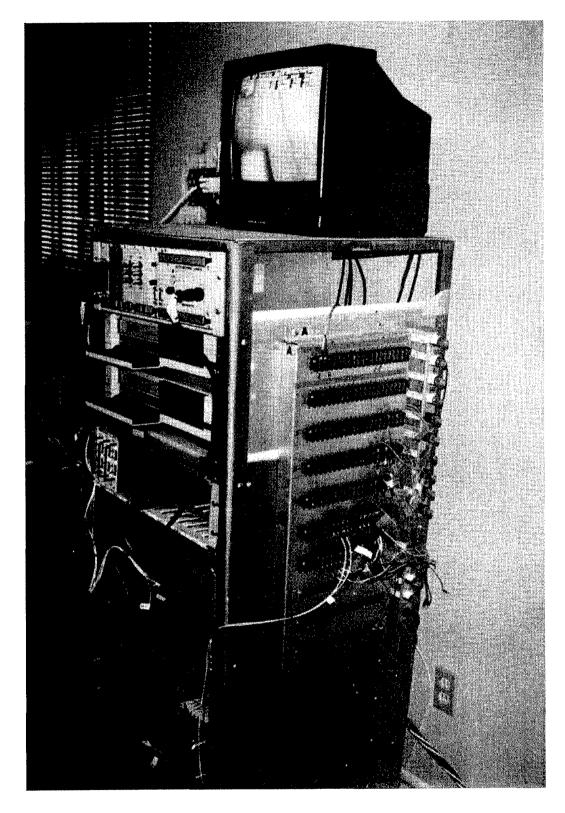


Figure 9-40. Data Recording Equipment Showing Detector Power Panel

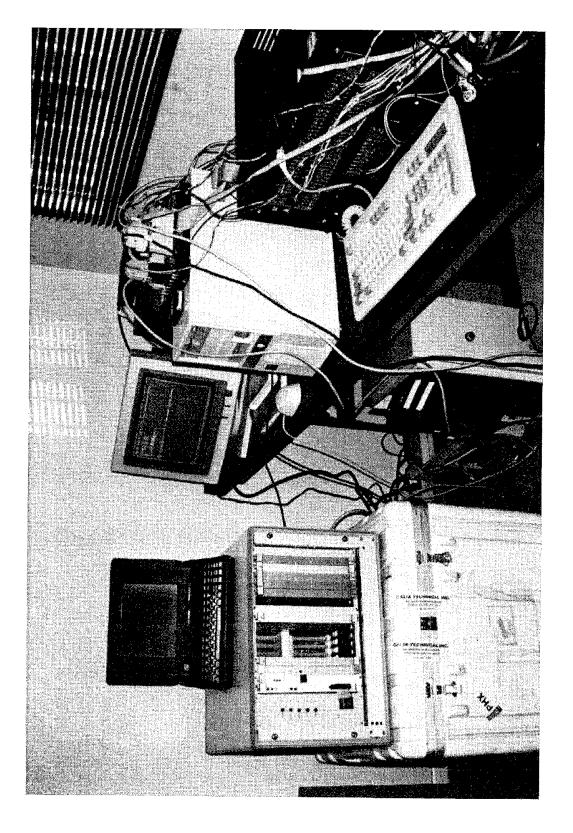


Figure 9-41. Data Logger, Computer, and Traffic Analysis System Video Image Processor As Used on I-10 (Autumn 1993)

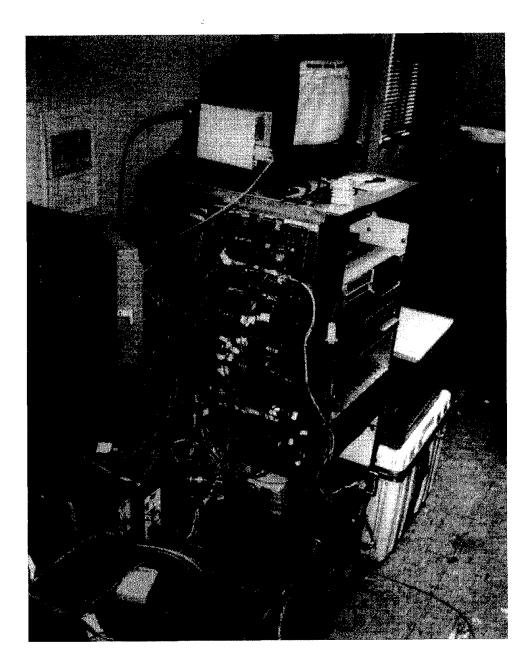


Figure 9-42. Data Recording Equipment Configured for I-10 (Summer 1994)

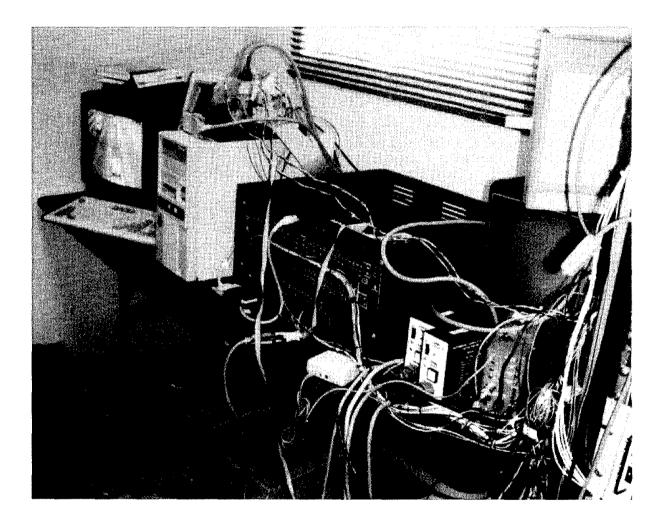


Figure 9-43. Data Logger, Computer, and Detectors as Configured for I-10 (Summer 1994)

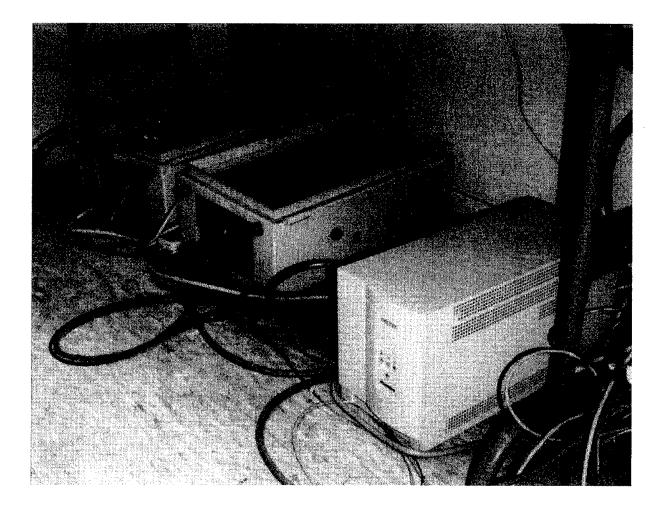
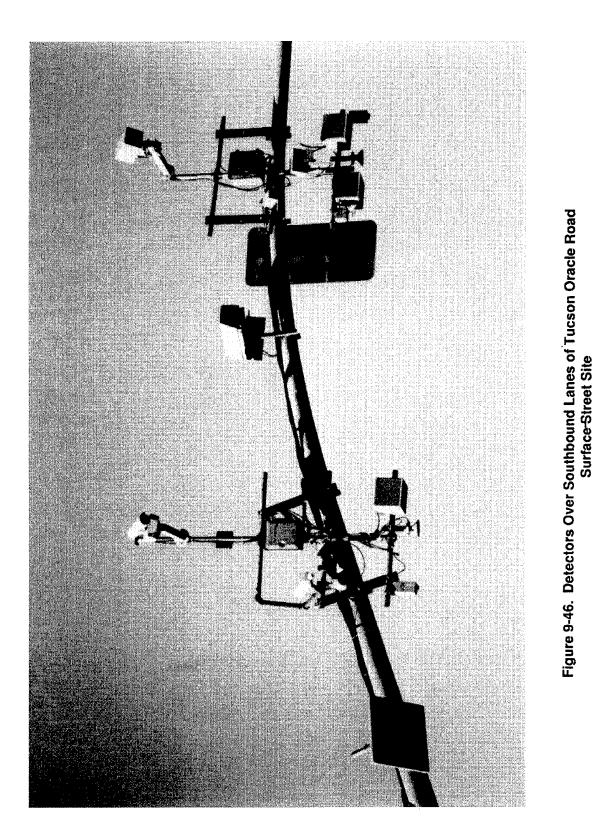
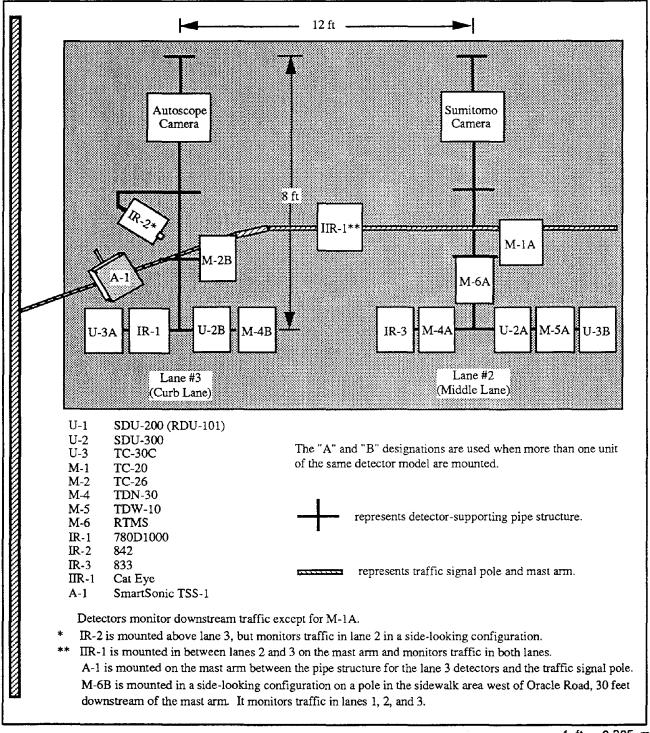


Figure 9-44. Sumitomo Ultrasonic Detector Electronics and Uninterruptable Power Supply in I-10 Trailer (Summer 1994)



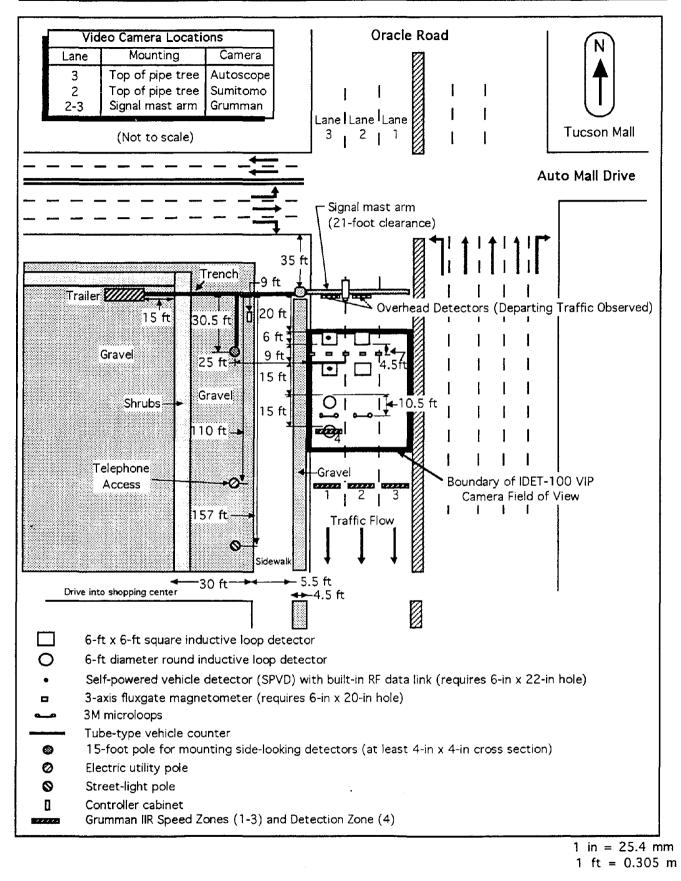
Figure 9-45. Detector Systems LoopComm Transducer Installed on Front Bumper of Probe Vehicle





1 ft = 0.305 m







are illustrated in Figure 9-49. A rubber tube for a Timemark Delta 1 traffic counter was installed across lane 3 at the leading edge of each square loop. The counter was modified with an RS-232 interface that transmitted the count information to the data logger. The AT&T sonic array was installed to monitor traffic in lane 3. In addition to the usual 6foot (1.8-m) square loop pairs, 6-foot (1.8m) diameter round loops installed by Max Kutter and 3M microloops were placed in lane 3 as shown in Figure 9-50. The microloops in lane 3 are in between the pair of round loops (near the 60-foot (18.2-m) mark) and in lane 2 are at the same relative location. The numbers on the pavement show the distance in feet from the mast arm on which the overhead detectors are mounted.

The wind speed and direction sensors and side-looking RTMS microwave radar, shown in Figure 9-51, were mounted on a 4-inch by 4-inch (101.6-mm by 101.6-mm) pole approximately 30 feet (9.1 m) south of the mast arm. The trailer and barricades around the trenches for the cables can be seen in the photo. The stub antenna for the magnetometer was mounted and hidden in a tree north of the pole. The time of occurrence of the greenphase signal at the southbound Oracle Road and Auto Mall Drive intersection was recorded using a relay data logger input.

The Tucson evaluation had other unique features. An array of five three-axis fluxgate magnetometers was installed across lanes 2 and 3 as sketched in Figure 9-48 and shown in the photograph of Figure 9-50 parallel with the 30-foot (9.1-m) paint mark. A sixth magnetometer was buried off the road near the 4-inch by 4-inch (101.6-mm by 101.6-mm) pole. Cables from the magnetometers ran to electronic signal amplifiers mounted on the 4-inch by 4-inch pole shown in the lower part of Figure 9-51. From here, cables brought the signals into the trailer where they were input to a Metrum recorder and recorded on VCR magnetic media as shown on the left side of Figure 9-52. The magnetometer array data was stripped from the VCR tapes in later processing at Hughes and placed into files that were archived on 1/4-inch (6.4-mm) magnetic tape used for 250MB PC backup systems.

A high sampling frequency Model 2020 detector built by 3M was connected to the second 6-foot by 6-foot (1.8-m by 1.8-m) square loop in lane 3. This allowed signals produced by the undercarriage of vehicles to be sampled and recorded by the data logger. Because of the high data rate output of the 2020 detector, a separate PC incorporating a fast serial input/output board with the 16550 Universal Asynchronous Receiver-Transmitter (UART) was used to record these data. The second PC also recorded the time code furnished by the data logger to aid in the correlation of the 2020 data with data from the other detectors.

As part of the data collection effort associated with the three-axis magnetometer array and high sample rate inductive loop detector, lane 3 was closed to normal traffic and several types of test vehicles were driven through the lane at slow speeds and were also stopped at several stations in the lane. In this way, signature data were obtained for known vehicles corresponding to known areas under the vehicle. The vehicles used in these tests are listed in Table 9-4. The large-boom lift truck is shown in Figures 9-53 and 9-54 and the Dodge Caravan in Figure 9-55. The stations are shown in Figure 9-56. In the tests where the vehicle was stopped in lane 3, the front bumper of each vehicle was stopped parallel to each station. At station 5, the vehicles were also stopped so that the middle of the vehicle and the rear bumper were parallel to the station.

An imaging infrared detector developed by Grumman Aircraft Company was evaluated at Tucson. The infrared camera was mounted on the mast arm between lanes 2 and 3, as shown in Figure 9-48, and viewed the area downstream from the second round loop between approximately 68 and 120 feet (20.7 and 36.6 m) from the mast arm. The infrared imagery processing electronics were located in the trailer as shown in the background of Figure 9-52. An infrared image of vehicles is shown in Figure 9-57. In the infrared spectrum, the hotter areas appear lighter in color and the colder areas appear darker. Since the character of the infrared image does not change appreciably from day to night (even when a vehicle's lights are on), it may be possible to use the same signal processing

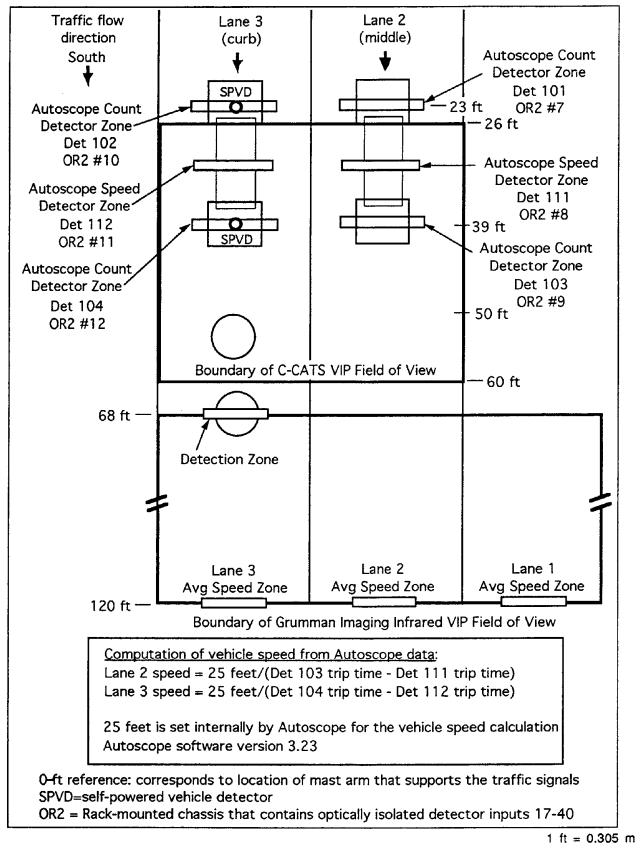


Figure 9-49. Fields of View and Calibration Areas for Autoscope, CCATS, and Grumman Video Image Processors on Oracle Road

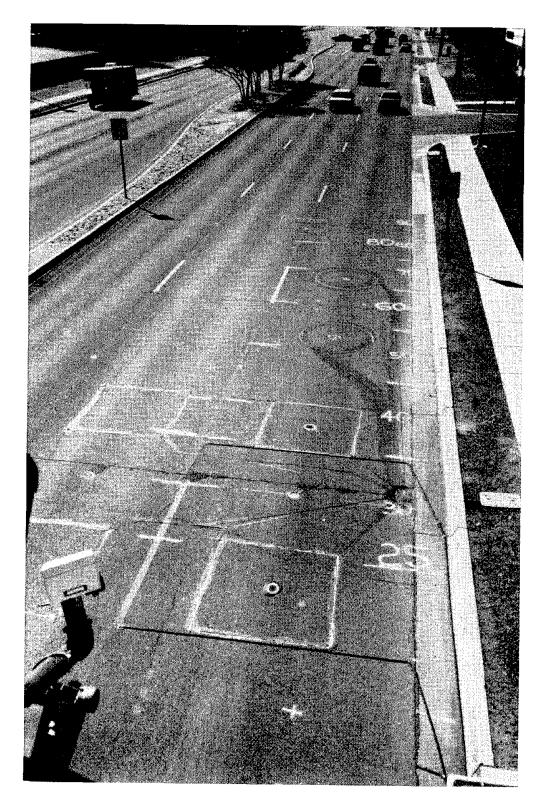


Figure 9-50. Oracle Road Marked with Calibration Distances for Video Image Processors and Subsurface Detectors

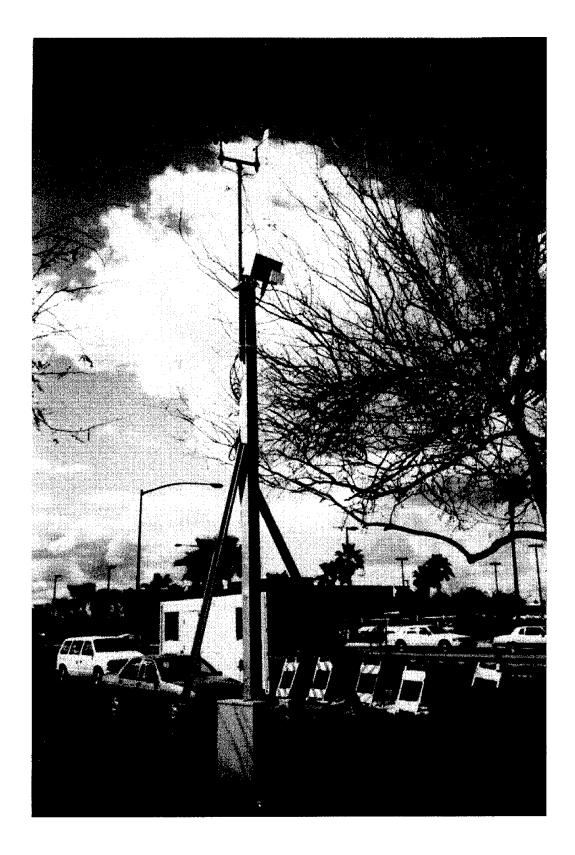


Figure 9-51. Pole-Mounted Wind Speed and Direction Sensors and Side-Viewing RTMS Microwave Detector at Oracle Road Site

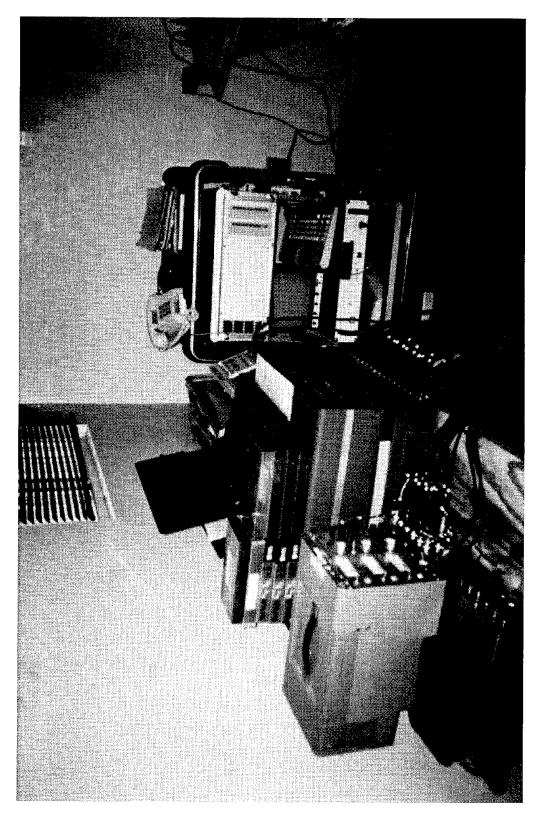


Figure 9-52. Metrum Recorder and Power Supplies Used to Record Three-Axis Magnetometer Signals at Oracle Road Site

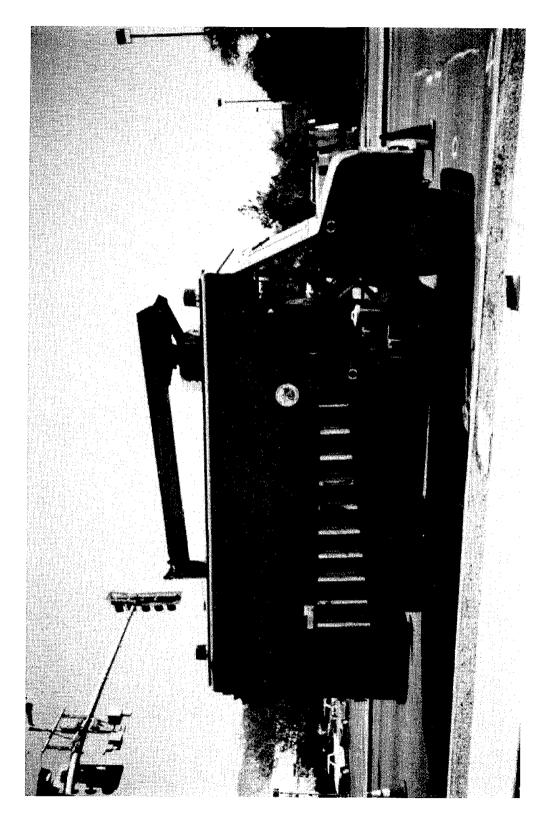


Figure 9-53. International S1600 Large Boom-Lift Truck (Side)

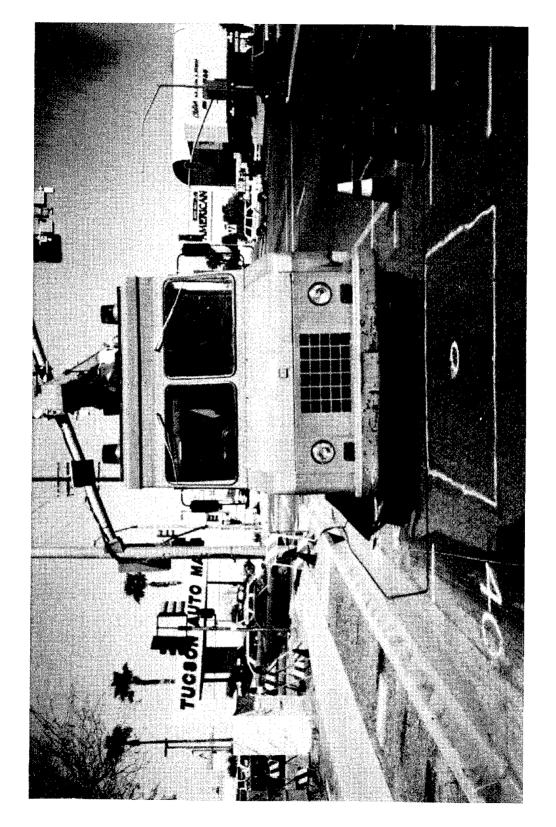


Figure 9-54. International S1600 Large Boom-Lift Truck (Front)



Figure 9-55. Dodge Caravan

Table	9-4.	Ve	hicles	Used	to	Groun	d Truth	Three-A	xis	Magne	etometer	Array
ar	nd l	ligh	Samp	ling F	req	uency	Inductive	Loop	Am	plifier	Signatur	es

Vehicle	Length (ft)	Width (ft)	
International S1600 (Model 1654) large boom-lift truck	27.25	•	
1980 Boyertown truck	22.0	7.0	
1985 Dodge Caravan	14.5	5.6	
1994 Chevrolet Corsica	15.0	5.0	
Kawasaki Arizona Highway Patrol Police 1000 Motorcycle	7.3	-	

1 ft = 0.305 m

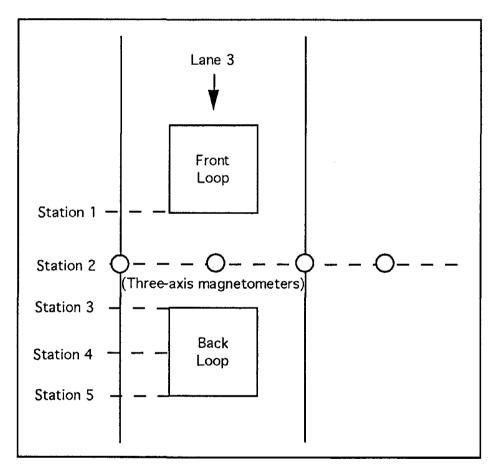


Figure 9-56. Stations Used to Record Signatures of Stopped Vehicles in Lane 3 on Oracle Road



Figure 9-57. Infrared Image of Vehicles Taken With Grumman Imaging Infrared Detector

algorithms for day and night operation. The infrared image processing technology may thus avoid possible performance degradation that can occur when transitioning from day to night algorithms in visible-spectrum video image processors.

The trailer was located in a shopping center parking lot on the southwest corner of the intersection. The cables were laid in a trench dug from the trailer to the sidewalk and then under the sidewalk to the pole that supported the mast arm upon which the detector pipe trees were hung. Additional trenches were dug for cables to the side-viewing RTMS microwave radar and the telephone service connection. Trenching had two drawbacks: flooding of the trench by a rain storm and having to erect barriers to prevent people from walking into the trench. Overhead cable installation is, therefore, preferable.

The equipment rack for Tucson is shown in Figure 9-58. On the top is one of the monitors used to view the traffic flow. To its right is the CCATS-VIP 2 image processor. The Autoscope 2003 is mounted in the top of the rack. Under it are the two PC-controlled VCRs that were used to record the traffic flow. Under these is the Type 170 electronics rack that held the Detector Systems inductive loop detectors, 3M 2020 high-frequency loop detector, and the AT&T SmartSonics detector. The power supply panel appears next. At the bottom of the rack is the auxiliary data logger for the additional 24 optically isolated detector inputs. The Detector Systems LoopComm inductive loop detector amplifiers are shown on the table to the left of the rack. They were connected to the downstream (second) square loop in lanes 2 and 3 to provide vehicle speed ground truth data. Behind them is the receiver for the selfpowered magnetometers.

Figures 9-59 and 9-60 show the inductive loop detector electronics, self-powered magnetometer receiver, main data logger, 386 PC and monitor, keyboards, a 486 PC and monitor on which the 3M 2020 highfrequency loop data were recorded, and a monitor for the second video camera, all located on a table in the trailer. The electronics for the Sumitomo SDU-300 ultrasonic detector, uninterruptable power supply, Sumitomo IDET-100 video image processor, and Sumitomo SDU-200 (RDU-101) ultrasonic detector were placed on the floor of the trailer under the table as shown in Figure 9-60.

In addition to the conventional traffic monitoring, we also mounted 4-foot by 8-foot (1.2-m by 2.4-m) sheets of styrofoam on the top of a Chevrolet Corsica and drove it through the field of view of the overhead detectors as shown in Figures 9-61 and 9-62. The purpose of these tests was to simulate the effects of snow on the performance of the ultrasonic, infrared, and microwave detectors. The styrofoam layers were 1, 2, and 3 inches (25.4, 50.8, and 76.2 mm) thick. This evaluation was performed at the same time lane 3 was closed to gather data for the three-axis magnetometers and high sample frequency inductive loop amplifier.

9.5 AMOUNT OF DATA COLLECTED AT EACH SITE

Table 9-5 shows the amount of data collected at each field test and evaluation site. Since the Tucson site included the three-axis magnetometer detector array, high sampling rate inductive loop detector amplifier, imaging infrared detector, circular inductive loops, and microloops not installed at the other sites, the data quantity at Tucson was greater than at the other sites.

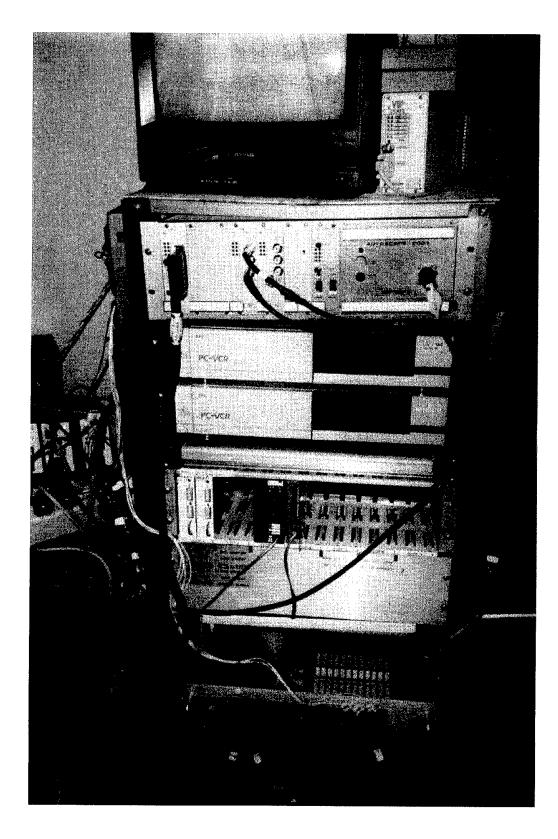


Figure 9-58. Data Recording Equipment as Configured for Oracle Road

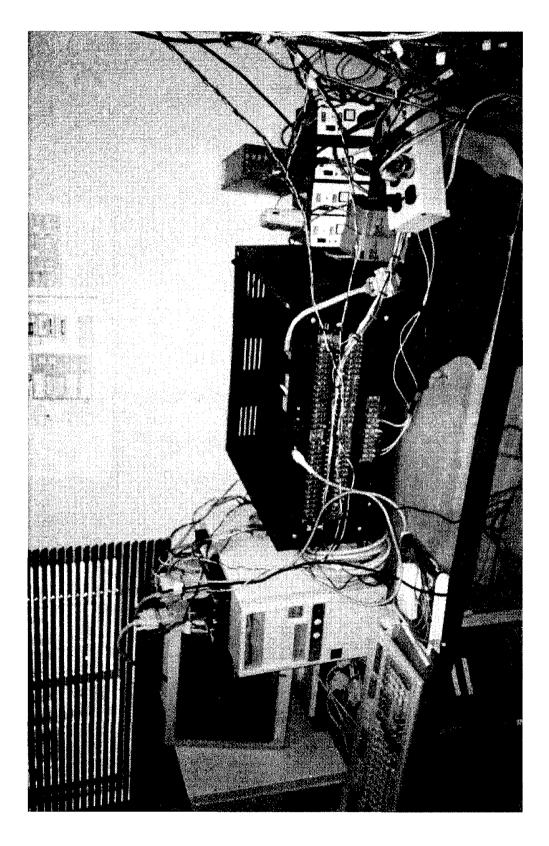


Figure 9-59. Data Logger, Computer, and Subsurface Detector Electronics at Oracle Road

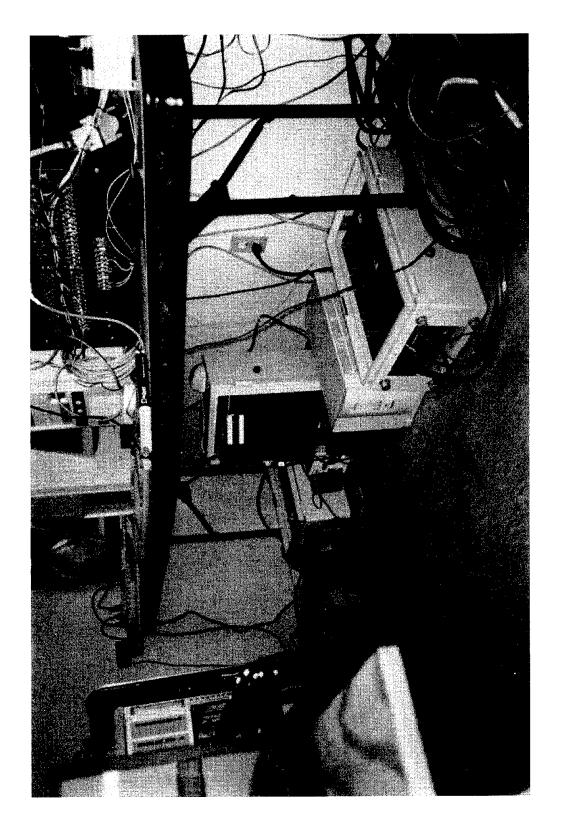


Figure 9-60. Sumitomo Detector Electronics and Uninterruptable Power Supply on Floor of Trailer



Figure 9-61. Chevrolet Corsica With Styrofoam Sheet Tied to Vehicle Top

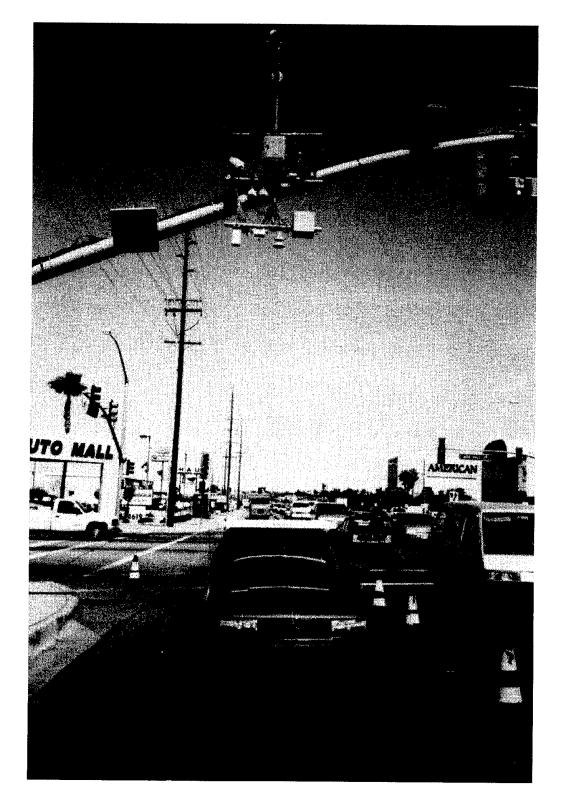


Figure 9-62. Corsica With Styrofoam Sheet Parked Under Detector Array

Location	Date	Runs	Data Collected (MB)		
Minneapolis Freeway	Winter 1993	15	200		
Minneapolis Surface Street	Winter 1993	7	32		
Orlando Freeway	Summer 1993	28	670		
Orlando Surface Street	Summer 1993	2 1	200		
Phoenix F	Autumn 1993	32	868		
Tucson Surface Street	Winter 1994	34	815		
Tucson Surface Street	Winter 1994	31	577 (with 3M 2020 high sampling rate amplifier)		
Tucson Surface Street	Winter 1994	16	1500 (from three-axis magnetometer array)		
Phoenix Freeway	Summer 1994	31	1060		

Table 9-5. Quantity of Data Acquired

-

10. TASK H

GENERATE FIELD TEST RESULTS

10.1 FIELD TEST OBJECTIVE

The primary objective of the field tests was to quantify the performance of traffic detector technologies with respect to the types and accuracy of data they provide under a variety of traffic flow and environmental conditions. In order to assess the data collected during the field tests, a methodology for reducing the data and presenting the results was established.

10.2 DATA COLLECTION AND ANALYSIS PROCESS

The detector data collection and analysis follows a four-step process: (1) acquisition, (2) conversion, (3) extraction, and (4) analysis. A flow chart describing the process is shown in Figure 10-1.

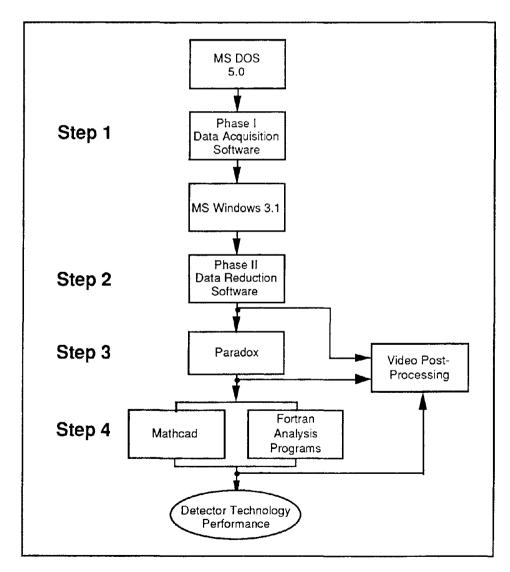


Figure 10-1. Data Collection and Analysis Process

10.2.1 Acquisition Phase

During data acquisition, all data available from each detector (shown in Tables 4-9 and 9-2) were recorded using a data logger. The data logger was designed to collect four types of output data: (1) Form C relay contact closures, (2) pulses from optically isolated outputs, (3) RS-232 serial transmissions, and (4) analog data in the form of output voltages. These detector outputs were timestamped and recorded in real time. Video index numbers or PG numbers, generated by the personal computer video cassette recorder (PC-VCR) at the rate of one per second, were recorded to allow data and video synchronization in post-processing Steps 3 and 4. Form C relay and optically isolated output transitions (the rising and falling edges of the detector output pulse) were recorded by the Phase I Data Acquisition Software which also computed the time interval between them. The interval represents the vehicle presence defined as the time duration over which the

detector output indicates a vehicle in its sensing area. The analog data were recorded through the same interface as the relay data. Serial data were recorded as they were generated through a Digiboard interface with the PC. The Phase I raw data files utilize a naming convention in which the first eight characters are numeric and represent the month, day, and military time at the beginning of the run. The raw data file is always given a .DAT extension. For example, a run conducted on April 11, beginning at 4:30 p.m., is designated 04111630.DAT as shown below:

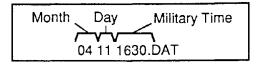


Figure 10-2 contains an excerpt from a typical raw data file.

 06:06 18 56 079 KS59 07:06 18 56 079 LS64
08:06 18 56 079 FS57
01:06 18 56 079 OPTO FREQ 3 254 318
02:06 18 56 079 MMT 002038FA FFFFFF7 0523 0000
* translated -> MMT H00 M08 S47 M934 Q0000 00000000,00001000,00000000
05:06 18 56 084 PG00008
06:06 18 56 084 NS66
07:06 18 56 084 JS62
08:06 18 56 084 LS60
01:06 18 56 084 OPTO PULSE 9 255 33
02:06 18 56 084 MMT 00203AC0 FFFFFF3 0514 0000
* translated -> MMT H00 M08 S48 M048 Q0000 00000000,00001100,00000000
06:06 18 56 084 LS67
07:06 18 56 084 HS63
08:06 18 56 084 FS50
19:06 18 56 090 MMT 0023FBD1 FFFFFFF 0540 0000
* translated -> MMT H00 M09 S49 M556 Q0000 000000000000000000000000000000
01:06 18 56 090 OPTO FREQ 3 254 206
02:06 18 56 090 MMT 00203AC2 FFFFFFB 0525 0000
* translated -> MMT H00 M08 S48 M048 Q0000 00000000,00000100,00000000

Figure 10-2. Raw Data File Excerpt

Figure 10-3 shows the data field assignments as they appear in the raw data files. The first number in a data line gives the channel or COM PORT number that is assigned to that device or output type. Channel 1 (designated 01), is dedicated to relay outputs and analog signals. Channels 2 and 19 are assigned to optically isolated detector outputs. Channels

3 and 4 are not used. Channels 5 through 20 were dedicated to RS-232 serial interfaces (the Channel 19 Opto Rack that contains provisions for 24 optically isolated inputs is connected to the data logger through the Digiboard, a device that serves as the interface from RS-232 output devices to the PC). The next four fields contain a time stamp that records the instant at which that event occurred (in hours, minutes, seconds, and hundredths of seconds according to the PC clock). The next fields contain data that are specific to the particular device or output type. Much of the data are of little use to the analyst in this form and must be translated in Step 2, using Phase II data reduction software, into a format that is more intuitive and easier to examine.

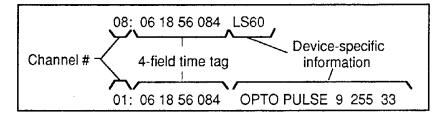
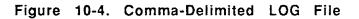


Figure 10-3. Data Field Assignments in Raw Data Files

10.2.2 Data Conversion Phase

The remainder of the steps shown in the data flow diagram are performed in postprocessing. The second step applies the Phase II Data Reduction Software to convert the raw data recorded in the acquisition phase into detector-specific information presented in a comma-delimited text format as illustrated in Figure 10-4. The output of the Phase II software is referred to as a log file and is given a .LOG extension.

```
242,6,11,51,610,85192,7,,-145,153,94,35,"VP1b",3,1,1158250,567818448,,,,,,,,,,,
243,6,11,51,610,85192,7,,-145,153,94,35,"MG2a",1,1,100000,...,.,,,,,
244,6,11,51,610,85192,7,,-145,153,94,35,"VP1b",1,1,384250,568662448,,,,,,,,,,,
245,6,11,51,610,85192,7,,-145,153,94,35,"MG1a",1,1,304000,219571448,,,,,,,,,,
246,6,11,51,610,85192,7,,-145,153,94,35,"IL1b",2,1,95000,219800198,,,,,,,,,,,
247,6,11,51,610,85192,7,,-145,153,94,36,"M4b",1,1,411000,219489948,,,,,,,,,,,
248,6,11,51,610,85192,7,,-145,153,94,36,"M4b",2,1,181250,219811698,,,,,,,,,,
249,6,11,51,610,85192,7,,-145,153,95,36,"IL1a",2,1,98000,219908698,,,,,,,,,,,
250,6,11,51,610,85192,7,,-145,153,95,36,"MG2a",2,1,110000,,,,,,,,,,,
251,6,11,51,610,85192,7,,-145,153,95,36,"IR1a",2,1,610000,,,,,,,,,,,
252,6,11,51,610,85192,7,,-145,153,95,36,"M6b",2,1,640750,568775698,,,,,,,,,,,
253,6,11,52,820,85193,7,,-145,153,95,36,"M5a",3,1,,,,26,,,,,,,
254,6,11,52,820,85193,7,,-145,153,95,36,"IL1a",3,1,108250,569604198,...,,,,,
255,6,11,52,820,85193,7,,-145,153,95,36,"M5a",1,1,294500,220315198,,,,,,,,,,,
256,6,11,53,200,85194,7,,-145,153,95,36,"VP4a",5,,,,1,54,0,,,,2,59,,,
257,6,11,53,200,85194,7,,-145,153,95,36,"M5a",2,1,107500,220609198,...,,
258,6,11,53,200,85194,7,,-145,153,96,36,"M1a",1,1,1110000,...,,,,,,
259,6,11,54,140,85195,7.0625,,-138,136,96,37,"VP3a",5,,,,0,0,,0,0,,,0,
260,6,11,54,140,85195,7.0625,,-138,136,96,37,"VP3a",5,,,,0,0,,0,0,,1,,,,
261,6,11,54,140,85195,7.0625,,-138,136,96,37,"M2b",1,1,880000,,,,,,,,,,,
262.6,11,54,790,85195,7.0625,..138,136,97.38,"M5a".3,1....33,......
263,6,11,55,10,85196,7.0625,,-138,136,97,38,"M6b",1,...,28,,,1,..,
```



The serial strings recorded during the acquisition phase are parsed and the device-specific parameters are stripped out by the Phase II software and placed into the appropriate data fields. The data field structure is discussed in 10.3.1.

10.2.3 Extraction Phase

The third step in the data collection and analysis process extracts specific data features from the log files. This step can be divided into two parts: (1) the importation of the log file's comma-delimited text into a more accessible database format, and (2) the utilization of database software that allows the user to extract specific parameters that are pertinent to a particular analysis. The database software used was Paradox for Windows.

Paradox has an IMPORT command that accepts the text file created in Step 2 (log file) and converts it into a Paradox database format. These files have a .DB extension. Figure 10-5 shows an example of a .DB (database) file. Once a database file has been created, the QUERY command can be used to filter out desired detector outputs and/or data parameters and extract them from the master database file. An example of a Paradox QUERY is given in Figure 10-6. The result of the QUERY is an ANSWER table. This table can be exported in a comma-delimited format and read as a text file during the analysis phase.

	Par	adox io	r Windox	vs - li abli	e : Dapdo	X TABL 102	011540.081	
Elle	<u>E</u> dit <u>Iab</u>	ile <u>R</u> e	cord Pr	roperties	₩indow	Help		
	5 0	С <u>р</u>	<u>р</u> и	44 4))) //			
02011548			Minutes	Seconds	Hun Secar			2-Wind Speed
1	1.00	1	49	52	0	95,622.00		12
2	2.00		49	52	0	85,622.00	6.06 3	12
3	3.00		49	52	۵	85,622.00		12
4	4.00		49		0			12
5	5.00	15	49	52	0			12
6	6.00	, p	49		0			12
7	7.00		49		0	85,622.00		12
6	8.00	6	49		170	-	6 E	12
9	9.00	15	49	52	170		0 6	12
10	8		49		170		6.06 3	12
11	11.00		49		170			12
12	12.00	15	49	52	170			12
13		15	49	52	170			12
14	14.00	15	49	52	170	85,622.00	6.06 3	12
15	15.00	15	49	52	170	85,622.00		12
16			49	52	170			12
17	17.00		49	52	220			12
18		9	49	52	220	85,622.00		12
19		9	49	52	220			12
20	20.00	15	49	52	220	85,622.00	6.06 3	12
4								
								•
Record 2	l of 86118						1	

Figure 10-5. Database File

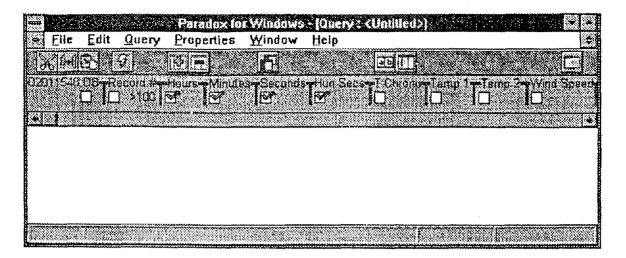


Figure 10-6. Paradox QUERY Illustration

10.2.4 Analysis Phase

The final step in the data analysis process involves the manipulation of the parameters extracted from the database file into a form that lends itself to interpretation by an analyst. This was accomplished by two different means. In the first, simple linear processes (such as the accumulation of vehicle counts over time) were modeled using a commercially available math analysis program called Mathcad that displayed tabular or graphical results quickly and easily. The program's simple user interface, however, restricts the ability to perform recursive looping, limiting its effectiveness when dealing with some of the more complex operations needed to adequately analyze traffic data and trends.

For this reason, a second approach utilizing application-specific FORTRAN programs were applied. The FORTRAN programs provided the capability to examine the data in greater detail. They are described in Section 10.4. The FORTRAN output can be imported into any number of commercially available graphical analysis programs and plotted. The graphing software used in this study was Kaleidagraph for the Macintosh platform.

10.3 TRAFFIC PARAMETER CALCULATION

In order to utilize the field test data to quantify detector performance, it is necessary to display detector attributes in terms of parameters that are commonly used and understood within the traffic-management community. These include count accuracy, vehicle speed, vehicle flow (sometimes referred to as volume), and lane occupancy. Some devices output such parameters directly; however, it is often necessary to calculate them using the available and sometimes rudimentary output data appearing in the .LOG files described in Table 10-1.

10.3.1 Parameter Descriptions

Field 1: Record Number

Assigns a sequential, integer record number to the events in chronological order.

Fields 2-5: PC Time Stamp

Assigns a four-field time tag to each event at the conclusion of the event (at falling edge of the waveform for pulse outputs). The event is stamped with the hour, minute, second, and hundredth of seconds that it was recorded using the time from the PC clock. The hundredths of seconds mark is converted into thousandths of seconds in the LOG file.

Field #	Field Name	Description
1	Record Number	Sequential record number
2	Hours	Event time tag (hours)
3	Minutes	Event time tag (minutes)
4	Seconds	Event time tag (seconds)
5	Hun Secs	Event time tag (hundredths of seconds)
6	T Chrono	Elapsed chronological time (seconds)
7	Temp 1	Temperature Probe 1 reading (degrees C)
8	Temp 2	Temperature Probe 2 reading (degrees C)
9	Wind Speed	Wind speed (mi/h)
10	Wind Dir	Wind direction
11	Frame # VCR1	Tape index number for VCR1
12	Frame # VCR2	Tape index number for VCR2
13	Det ID	Detector identification acronym
14	Det Int #	Detector interface number
15	V detect	Vehicle detect (unity when vehicle is detected)
16	V presence	Vehicle presence time (microseconds)
17	Spd Trp Timing	Speed trap timing
18	V count	Vehicle count
19	V speed	Vehicle speed (mi/h or km/h)
20	V type	Vehicle type (classification)
2 1	V occ	Vehicle occupancy
22	V volume	Vehicle volume
23	Special Field 1	Device-specific output #1
2 4	Special Field 2	Device-specific output #2
2 5	Special Field 3	Device-specific output #3

Table 10-1. Detector Output Data Fields as They Appear in .LOG and .DB Files

Field 6: T Chrono

Elapsed chronological time in seconds since the data logger last began operation (not necessarily since the beginning of a run). In most instances, the data logger hardware ran continuously whether or not data were being recorded, thus *T Chrono* usually is not equal to zero at the beginning of a run.

Fields 7-8: Temp 1 and Temp 2

When available, two separate temperature probes were employed to measure the

temperature in centigrade. Fields 7 and 8 are reserved for these values.

Fields 9-10: Wind Speed and Wind Direction

An anemometer was used to provide wind speed and wind direction readings at 5-second sampling intervals.

Fields 11-12: Frame # VCR1 and # VCR2

Tape address numbers were assigned every second for both PC-VCRs. These are used in post-processing to synchronize video to the

displayed data on a monitor. A single VCR was used in Minnesota and Florida. A second was added for the Arizona tests to record the video from two cameras that provided inputs to the video image processors.

Field 13: Detector ID

Contains the detector identification acronyms described in the Appendix H site hookup files.

Field 14: Detector Interface Number

Many detectors provided multiple outputs. The interface number distinguishes between these outputs in post-processing. A detailed listing of the detector interface numbers appears in the site hookup files in Appendix H.

Field 15: V detect

A value of unity appears in this field for all recorded events to aid in the accumulation of counts in Mathcad.

Field 16: V presence

Vehicle presence time in microseconds. Presence is defined as the time duration over which the detector output indicates a vehicle in its sensing area. It roughly corresponds to the time a vehicle occupies a detector's detection zone. Long electronic hold times can cause considerable errors in the presence measurement. Where adjustable, detector hold times were set to the minimum value. Even then, the presence measurement was sometimes in error when the traffic flow was heavy and the detector could not reset to record the passage of the next vehicle.

Field 17: Speed Trap Timing

Provides high resolution time stamp in 250-microsecond resolution increments. Obtained from the crystal oscillator on the Midwest Micro Tek (MMT) processor board in the data logger.

Field 18: V count

Shows cumulative vehicle count, usually over a manufacturer-specified integration interval, from detectors that output count from an RS-232 interface.

Field 19: V speed

Vehicle speed from devices that give direct speed output via a serial interface, such as radar or a video image processor. The analyst must note the units in which speed is recorded as some of the foreign devices output speed in metric units (km/h).

Field 20: V type

This field is used for detectors having a vehicle classification capability usually based on a user-selected length. The vehicle types displayed do not necessarily utilize standard classification definitions, so the vehicle type may differ from detector to detector.

Field 21: V occ

Field reserved for direct lane occupancy outputs from serial interface.

Field 22: V volume

Direct vehicle volume (or flow) data from serial interface.

Field 23: Defined as appropriate for specific detectors under evaluation.

Field 24: Defined as appropriate for specific detectors under evaluation.

Field 25: Defined as appropriate for specific detectors under evaluation.

10.3.2 Count Accuracy

One of the key goals of this program is to assess traffic parameter measurement accuracies from various detectors. A parameter of importance to the traffic management community is vehicle counts. In order to adequately compute count accuracies, a reference value must be established against which to compare the detector outputs. The determination of the count reference requires that the actual or "true" count is known. Since a video record of all the data collection runs exists, the video can be used for determining count reference values; however, it is not practical to have an observer ground truth all 500+ hours of video collected during the field tests.

A compromise was reached whereby vehicles were manually counted by a human observer for a representative time interval using samples from each test site. The results were compared against each detector utilized in that test. The detector that had the best accuracy for each test site was then used as the reference against which the accuracies of the other detectors were judged. In most cases, at least one detector could be found that was accurate to within \pm 0.5 percent.

It is possible to perform detailed accuracy analyses on a particular detector output by using the video and data synchronization capability built into the Phase II software. Various types of detector parameter data can be overlaid onto the video monitor and synchronized to correspond with video events. This capability allows any number of detailed examinations to be performed in postprocessing at the convenience of the analyst.

10.3.3 Speed

Another parameter employed in traffic analysis is vehicle speed. Speed can either be measured directly by a Doppler device or computed by means of a speed trap utilizing multiple detectors or multiple zones within a single detector. It is more difficult to ground truth speed than vehicle counts. One must know not only that an event has occurred, but how fast the vehicle was traveling. Another complication is the correlation of the measured or computed speed with a particular vehicle.

This problem was solved by using the Detector Systems Model 613 loop amplifier in conjunction with the Model 600A LoopComm vehicle transmitter mounted on a probe vehicle. The transmitter outputs a unique code that identifies the vehicle when it passes over an inductive loop. The vehicle is identified by a pulse output from the Model 613 loop amplifier. The pulse assists the analyst in assigning a particular vehicle speed to a unique vehicle (namely the probe vehicle) during post-processing. The test operator, when making the speed run, noted the time of day and speed that he was traveling from the vehicle's speedometer and recorded them in an engineering logbook. This gives the analyst an approximate time from which

to find the output pulse and compare the speed outputs from the detectors. The exact time is noted in the database file based on the occurrence of the Model 613 pulse output.

Before the Model 613 loop detector was available, the test operator drove a probe vehicle through the detection zones with the vehicle marked in some visual way to aid in locating it on the video tape during postprocessing. This approach is difficult to use because no unique signals automatically appear to identify the probe vehicle in the Paradox database file.

10.3.4 Flow

Vehicle flow is defined as the number of vehicles passing a fixed point in a given lane over some time interval (typically expressed in vehicles per hour per lane). Computing flows every several minutes and plotting the resulting values versus time of day was used to illustrate the measurement of the dynamic nature of traffic volume.

10.3.5 Density

Vehicle density is defined as the number of vehicles per lane per unit distance (typically 1 mile [1.6 km]). Most traffic detectors are incapable of monitoring long stretches of road; therefore, the most practical way to provide vehicle density is to calculate it from available detector data rather than measuring it directly. The density in vehicles per mile was expressed as the ratio of vehicle flow (in vehicles per hour) to average vehicle speed (in miles per hour). This allows the analyst to examine instantaneous vehicle densities.

10.4 FORTRAN PROGRAMS

Several FORTRAN programs were written to assist in the data reduction task. These programs manipulate the data extracted from the database into forms that are suitable for graphical presentation. Many of the parameters commonly used in traffic analysis were not directly output from the detectors. Instead they had to be calculated from the parameters that were available. The FORTRAN programs compute parameters such as vehicle counts, flow, speed, and density. Below are the individual program names, brief descriptions of the programs, and a list of inputs and outputs. The detailed program code is contained in Appendix K.

10.4.1 COUNT.FOR

Accumulates vehicle counts from a single detector output. Each count carries with it the time stamp recorded during the actual data collection session, so the COUNT.FOR output yields vehicle counts versus time of day. Outputs from several detectors can be plotted on the same graph to provide a visual comparison of the cumulative vehicle counts from detectors that monitored the same lane of traffic.

- Inputs: Eight-digit numerical file name with .Cl extension (#######.Cl)
 - Four-field PC clock time tag for each vehicle detection:
 - Hours Minutes Seconds Hun Secs
- Outputs: The same eight-digit numerical file name with .CO extension (#######.CO)
 - Text file yielding time in decimal hours and cumulative vehicle count for each vehicle detection

10.4.2 INT_CNT.FOR

Computes vehicle count accuracies and statistical measures of effectiveness over some user-defined time interval. Vehicle counts are accumulated over the desired time interval for two different detector outputs from the same lane of traffic. The first set of vehicle detections are from the detector that has been ascertained to yield the best count accuracy (usually inductive loops). These counts are used as the "truth" that the other detector counts are compared against. The program computes the count difference and the percentage difference between the values from the two detectors for each time interval. The mean of the count difference over all time intervals of the run and the standard

deviations of the count difference and the percentage count difference are also calculated.

- Inputs: Eight-digit numerical file name
 with .ILl extension
 (########.ILl)
 - Eight-digit numerical file name with .Cl extension (########.C1)
 - Four-field PC clock time tag for each vehicle detection:

Hours Minutes Seconds Hun Secs

Outputs: • Eight-digit numerical file name with .CO extension (########.CO)

10.4.3 DENSITY.FOR

Computes lane density, average speed, and vehicle flow for a user-defined time interval for detectors that occur in pairs within a given lane. The high-resolution time tags used for these pairs of events come from the speed trap times that are generated by a crystal oscillator with 250-microsecond resolution. Speeds are computed between the speed traps by computing the time change between events and dividing by the speed trap spacing. Density is computed as the ratio of vehicle flow to average speed over some integration time interval. Flow, speed, density, and time of day are output into a text file.

- Inputs: Eight-digit numerical filename
 with .DI extension
 (########.DI)
 - Four-field PC clock time tag for each vehicle detection:

Hours Minutes Seconds Hun Secs

• Detector Interface Number (e.g., lead loop = 1, following loop = 2)

- Speed trap time tag reference value
- Outputs: Eight-digit numerical filename with .DO extension (#######.DO) and parameters
 - Integration interval number
 - Time of day (hours)
 - Vehicle flow (vehicles/hour)
 - Average speed over interval (mi/h)
 - Lane density (vehicles/mile)

10.4.4 OVF.FOR

Computes lane occupancy versus vehicle flow for a user-defined time interval. Lane occupancy is calculated as the percentage of time that a detector output is in the active or "high" state over a user-defined time interval. Occupancy is commonly used as a surrogate for lane density and is dependent upon a detector's count accuracy, size and shape of the detection footprint on the ground, and the hold time of the detector electronics.

- Inputs: Eight-digit numerical filename with .IN extension (########.IN)
 - Four-field PC clock time tag for each vehicle detection:
 - Hours Minutes Seconds Hun Secs
 - Vehicle presence time (seconds)
- Outputs: Eight-digit numerical filename with .OFO extension (#######.OFO) and parameters
 - Time of day (hours)
 - Lane occupancy (percent)
 - Vehicle flow (vehicles/hour)

10.4.5 DENS_TOD.FOR

Computes density, speed, and vehicle flow over a user-defined integration interval.

- Inputs: Eight-digit numerical filename with .DI extension (########.DI)
 - Four-field PC clock time tag for each vehicle detection:
 - Hours Minutes Seconds Hun Secs
 - Detector interface number
- Outputs: Eight-digit numerical filename with .DO extension (#######.DO) and parameters
 - Time of day (hours)
 - Vehicle flow (vehicles/hour)

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- Average speed (mi/h)
- Lane density (vehicles/mile)

10.4.6 DENS_232.FOR

Computes the same parameters as DENS_TOD.FOR, but uses directly measured speed inputs from detectors having RS-232 serial outputs.

- Inputs: Eight-digit numerical filename with .DI extension (########.DI)
 - Four-field PC clock time tag for each vehicle detection:
 - Hours Minutes Seconds Hun Secs
 - Measured vehicle speed (mi/h)
- Outputs: Eight-digit numerical filename with .DO extension (#######.DO) and parameters
 - Time of day (hours)
 - Vehicle flow (vehicles/hour)
 - Average speed (mi/h)
 - Lane density (vehicles/mile)

10.4.7 GP_COUNT.FOR

Outputs vehicle counts versus time of day for the Tucson surface-street site. Counts are only noted for through-traffic, i.e., during the signal green phase.

- Inputs: Eight-digit numerical filename
 with .GPI extension
 (#######.GPI)
 - Four-field PC clock time tag for each vehicle detection:

Hours Minutes Seconds Hun Secs

- Eight-digit numerical filename with .GP extension (#######.GP)
- Four-field PC clock time tag for each falling edge of the green signal phase:
 - Hours Minutes Seconds Hun Secs
- Presence time for green phase (green duration)
- Outputs: Eight-digit numerical filename with .GPO extension (#######.GPO)
 - Vehicle counts accumulated over the green signal phases during the period of the run.

10.4.8 OCC.FOR

Computes lane occupancy values over a userdefined integration time interval. Presence values are accumulated for a given detector output over the integration interval chosen by the user. The accumulated presence is divided by the integration interval, yielding the percentage of the time that a given detector is in the active state during the integration window. Strictly speaking, the resulting value is not exactly the percentage of the time that a vehicle resided in the detection zone as the computed value is also a function of the electronic hold time of the detector.

- Inputs: Eight-digit numerical filename with .IN extension (########.IN)
 - Four-field PC clock time tag for each vehicle detection:

Hours Minutes Seconds Hun Secs

- Vehicle presence (seconds)
- Outputs: Eight-digit numerical filename with .OUT extension (#######.OUT)
 - Time of day (hours)
 - Lane occupancy (percent)

10.4.9 SVF.FOR

- Computes flow and average speed over a userdefined integration interval.
- Inputs: Eight-digit numerical filename
 with .SFI extension
 (########.SFI)
 - Four-field PC clock time tag for each vehicle detection:
 - Hours Minutes Seconds Hun Secs
 - · Measured vehicle speed (mi/h)
- Outputs: Eight-digit numerical filename with .SFO extension (#######.SFO) and parameters
 - Time of day (hours)
 - Accumulated interval count
 - Vehicle flow (vehicles/hour)
 - Average speed over interval (mi/h)

10.5 VIDEO/DATA SYNCHRONIZATION USING THE PC-VCR

The Phase II software provides the capability to overlay a variety of information onto the video monitor so that relevant parameters can be superimposed over the ground truth or any recorded video segment during postprocessing. Video/data synchronization enables the analyst to visually correlate the actions of individual vehicles with the measured or computed traffic parameters associated with them. The analyst may also revisit the field test data at his leisure and concentrate his attention on the performance of a particular detector.

An example of the utility of video/data synchronization is as follows. Perhaps the results of a certain run indicate that a video image processor is noticeably undercounting vehicles. Displaying the accumulated counts for that particular device in conjunction with the recorded video may indicate that the VIP was failing to detect dark-colored automobiles, possibly due to a problem in the brightness threshold setting. Or perhaps the VIP is overcounting and analysis shows that the device was detecting shadows from vehicles in adjacent lanes, or maybe a magnetometer is double- or triple-counting tractor-trailer rigs. Such trends will become evident when examined using this tool.

Using the video/data synchronization portion of the Phase II software requires the following items:

- (1) Copy of the raw data file (example, 02110625.DAT).
- (2) A file VCR.LOG containing the detector output data or attributes the analyst wishes to overlay.

Up to 10 attributes can be displayed on the video monitor. The numbers in Figure 10-7 represent the location of the 10 data items displayed in the video.

Each line of the VCR.LOG file consists of a video tape index number that exists both in the raw data file and on the tape itself (these are the reference markers that synchronize the video and the detector output data) and a

maximum of 10 attributes. The structure of each line is:

Tape Index PG #, Attribute 1, Attribute 2, ..., Attribute 10

The first field must contain the tape index numbers. The remaining fields (up to 10) may contain whatever information the analyst wishes to display, the order being up to the analyst. Microsoft Excel is a useful tool for manipulating the data columns. VCR.LOG must be in a comma-delimited format.

1	2
3	4
3 5 7	6
7	2 4 6 8
9	10

Figure 10-7. Configuration of Displayed Detector Data Attributes

10.6 A QUALITATIVE VIEW ON DETECTOR INSTALLATION AND APPLICATIONS TO TRAFFIC MANAGEMENT

In addition to the quantitative results from the field evaluations, several qualitative features, such as ease of use, setup difficulty, and reliability impact detector deployment.

Each detector has its own unique mounting requirements that may affect its suitability for a particular application. A broad spectrum of mounting locations were encountered during the *Detection Technology for IVHS* field tests. They allowed an assessment of the operation and deployment of the detectors under a wide range of traffic flow, environmental, and mounting conditions.

The mounting locations of the detectors were somewhat constrained due to the large number of detectors. Some of them were designed to look directly downward at nadir and, as such, were not obstructed by other detectors mounted below them. These devices were, therefore, located at the bottom of whatever mounting fixture was used. Doppler devices, which included some microwave detectors and some ultrasonic detectors, and the infrared detectors were mounted at an incidence angle between nadir and 90 degrees. The location of such a detector on a structure with a catwalk was high enough to avoid interference by the metal walkway grating and hand rails. Video image processors sometimes specified a higher optimum camera height than was obtainable on an existing overpass or signbridge structure. In these cases, the camera was mounted as high as possible.

The specific data output by each detector were shown in Tables 4-9 and 9-2, and the output type (discrete or serial) was shown in Table 8-4.

10.6.1 Ultrasonic Detectors

Sumitomo SDU-200 (RDU-101) Ultrasonic Doppler Detector (U-1)

This detector was inadvertently identified as a model SDU-200 at the start of the program. We later learned that the correct model identification was RDU-101. A dual horn transducer (one to transmit, one to receive) is provided along with electronics enclosed in a rugged cabinet. The device outputs separate pulses for long and short vehicles and these were recorded using the data logger's relay inputs. In theory, the sum of the long and short vehicle pulses should add to the total vehicle count, however, in practice, these outputs were but a small percentage of the true vehicle count. This detector also provided a digitized 8-bit speed output that was not compatible with the data logger's input types; therefore, the field tests were unable to evaluate this feature. One difficulty with this product is its 100-Volt AC power input, which requires a stepdown transformer to supply the specified input voltage.

Sumitomo SDU-300 Ultrasonic Presence Detector (U-2)

This device consists of a single transducer head and remote electronics packaged similarly to that of the SDU-200. The head is oriented directly downward over traffic, such that its footprint is circular and directly underneath the transducer. Three different heads are available to control the size of the footprint. Setting the sensitivity and gain to correspond to the mounting height requires an oscilloscope. Once the proper settings are obtained, the SDU-300 is a reliable, rugged device that yields vehicle counts and presence.

Micrówave Sensors TC-30C Ultrasonic Presence Detector (U-3)

This unit is extremely simple to mount and use. Once supplying power, setup time takes no more than 10 to 15 minutes. The compact detector package houses all of the detector electronics, including simple potentiometer adjustments for gain, range, and hold time. The detector has a light-emitting diode (LED) on the back of the housing that can be used to visually correlate the passing of a vehicle with the output of the detector during setup.

10.6.2 Microwave Detectors

Microwave Sensors TC-20 Medium Beamwidth Motion Detector (M-1)

The TC-20 is a low-cost, compact motion detector that operates on the Doppler principle. Its effectiveness in the field tests was limited by its inability to operate as a presence detector since it can only detect moving vehicles. Even then, its minimum electronic hold time was too long to accurately count vehicles in a high-speed, high-density traffic environment. Its primary function is to detect the arrival of vehicles approaching a signalized intersection, not to count individual vehicles or measure their presence times. The device is easy to mount and wire. The response to vehicle flow direction is changeable by moving a pair of jumpers. The output is a simple relay contact closure.

Microwave Sensors TC-26 Medium Beamwidth Motion Detector (M-2)

The TC-26 is a more sophisticated version of the TC-20. In addition to the relay output, the TC-26 provides five optically isolated speed bin outputs. The speed bin outputs utilize a +5 VDC transistor-to-transistor logic (TTL) level and provide a coarse speed indication without the need for an RS-232 serial line. Numerous difficulties were encountered in the field regarding the speed bins, such as spurious toggling of one or more bins. The response to traffic flow direction is easily set by means of a switch located inside the detector housing.

Whelen TDN-30 Narrow Beamwidth Motion Detector (M-4)

This device is a self-contained Doppler speed detector with two optically isolated outputs to emulate loops and a serial output for direct speed measurement. The direction of traffic flow is changed by means of a jumper setting. The lightweight, 1-foot (0.3-m) cube-shaped detector is easy to mount. The Whelen detectors experienced two problems during the testing effort: water seepage into the unit and loss of the serial communication data on several occasions. Power to the detector had to be cycled at the start of a run before the serial communication began. The latter problem could be serious if these devices were deployed in a traffic management application and a power grid went down. The detectors have since been redesigned with new housing and new seals to prevent the water leakage problem. The communication problem can be remedied, perhaps, with the introduction of a new RS-232 transmitter chip. When operating properly, the detectors appeared to provide high-accuracy count and speed data, and their serial data protocol was one of the easiest to decode.

Whelen TDW-10 Wide Beamwidth Motion Detector (M-5)

The TDW-10 is a wide-beam version of the TDN-30. The two units share common electronics. A jumper setting distinguishes between wide-beam and narrow-beam electronics operation, but the TDW-10 has a wide-beam antenna that distinguishes it from the narrow-beam version. The TDW-10 can monitor up to three or four lanes of traffic (all lanes must be moving in the same direction), depending on the mounting geometry and the width of the lanes, but it merges the data from the lanes into one detection zone.

Electronic Integrated Systems RTMS-X1 Microwave Radar Presence Detector (M-6)

The RTMS is unique among the microwave detectors employed in these tests due to its true presence-sensing and multizone vehicle detection capabilities. All of the other microwave detectors are Doppler devices that key off of vehicle movement, whereas the RTMS can detect motionless vehicles. The unit can be deployed in a forward-looking or sidelooking mode. It can also be used to look diagonally across an intersection. Detection parameters and location of the detection zones are set remotely by means of a software interface. This allows the user to perform a portion of the setup procedure without closing lanes. This device has 12 optically isolated outputs that can be used to determine vehicle queues in the forward-looking mode, or to monitor up to 8 separate lanes in side-looking mode. A single side-looking detector can monitor lanes traveling in opposite directions.

10.6.3 Infrared Detectors

Schwartz Electro-Optics Model 780D1000 Autosense I Laser Radar (IR-1)

This active infrared radar transmits two rows of laser beams in the near IR spectrum across a lane and detects the reflected energy when the beams impinge upon a passing vehicle. The unit has both relay and serial outputs. It could only detect approaching vehicles until late in the testing process, when the unit's firmware was modified to detect either approaching or departing traffic. Problems were experienced with the serial communication hardware early in the program. An RS-232 chip manufactured by a different supplier was eventually inserted to replace the original one and the unit's reliability improved.

Eltec Model 842 Passive Infrared Presence Detector (IR-2)

The 842, by virtue of its role as a presence detector, has a long electronic hold time. Its primary function is to provide intersection control. This affected its ability to accurately count vehicles in heavy traffic because the falling edge of its output pulse often did not occur prior to the entrance of another vehicle into the detection zone. Consequently, the vehicle count from the 842 was lower than that from other detectors. However, keep in mind that this detector was not designed for vehicle counting, although the detector was used in this manner. This device has a simple relay closure output.

Eltec Model 833 Passive Infrared Detector (IR-3)

The Eltec 833 is designed for traffic signal control and vehicle counting applications. The unit tested in the field had a much shorter hold time than the 842, making it a better candidate for high-speed, high-trafficvolume counting. The relay in the original unit was configured with a normally closed output. Over a period of time, this caused the relay contacts to burn and the unit eventually failed. After repair, it was configured to operate in the normally open mode and no further problems were experienced throughout the remainder of the field tests.

Grumman Imaging IR Traffic Sensor (IR-4)

This system uses high-resolution, passive infrared imaging over a wide field of view. Its infrared spectral operating region provides an advantage in adverse weather over video image processors that operate in the visible spectrum. The product employs a focal plane cooler to increase thermal sensitivity. Typically, coolers are not known for their longevity and devices that have them require more power than uncooled devices. However, the power requirement may not be limiting in traffic management applications. The unit can be used for both high-speed traffic management and controlling signalized intersections.

10.6.4 Video Image Processors

Econolite Autoscope 2003 (VIP-1)

The Autoscope 2003 is a wide-area vehicle detection system that uses video imaging as an alternative to inductive loops in multiple lanes and multiple directions of traffic. It accepts inputs from up to four video cameras and provides vehicle presence, flow, time headways, occupancy, speed, and classification based on vehicle length. Vehicle detection is provided either from loop detector compatible outputs on an external interface module (EIM) or from a serial output. The traffic data can be accumulated into 10-second to 1-hour intervals for individual lanes or multiple lanes. The full capability of the Autoscope could not be explored in the field tests because the output serial data protocol was not made available to the engineers performing the tests. This did not allow correlation of the parameters computed from the EIM loop detector compatible outputs with the serial output parameters computed by the Autoscope 2003. However, output detections from the EIM were time-tagged and recorded in order to calculate vehicle count and speed.

Econolite recommends using a Burle Model TC 650EA camera that incorporates automatic gain control circuitry and auto-iris to minimize difficulties caused by blooming from vehicle headlights during nighttime operation. It has 383-line resolution with a 510x492 pixel CCD array.

Computer Recognition Systems Traffic Analysis System (TAS) (VIP-2)

The TAS is based on automatic machine vision technology and edge detection algorithms. It performs traffic flow analysis by tracking vehicles on multi-lane highways; monitoring up to three lanes of traffic; and computing statistical traffic flow parameters such as average speed, lane occupancy, and lane density. It provides vehicle classification based on user-supplied lengths, traffic parameters based on vehicle class, and speed alarm notification. The standard package includes setup software.

Traficon CCATS-VIP 2 (VIP-3)

The CCATS-VIP 2 uses detection zones to monitor traffic flow. It is capable of monitoring up to four lanes of traffic from a single camera. This device incorporates graphical data interpretation and a display package that outputs total number of vehicles and number per lane, gap time between vehicles, lane occupancy, vehicle classification (up to three types) based on length, mean length of all detected vehicles, and alarms at lower and upper thresholds set by the user. This unit is neatly housed in a compact package. The software version evaluated in the field tests experienced problems detecting dark-colored vehicles in shadowed areas. Newer software supposedly corrects the problem.

Sumitomo IDET-100 (VIP-4)

The IDET-100 employs vehicle edge detection algorithms to compute traffic volume, vehicle type, and speed for up to four lanes of twoway traffic simultaneously. Vehicles can be tracked even as they change lanes.

Traffic data are reported by lane via an RS-232 interface. Data include vehicle detection with a claim of 90-percent accuracy, vehicle type (small or large), velocity in kilometers per hour, vehicle status (moving, recently stopped, or parked), and the pulse width of the detection signal.

EVA 2000 (VIP-5)

The EVA 2000 monitors up to four lanes of traffic from a single camera. The VIP tracks vehicles and provides traffic volume, average speed, density, occupancy, average spatial headway, and vehicle counts, each on a per lane and vehicle type (two types are supported) basis. The EVA 2000 can track individual vehicles even when they cross lanes.

10.6.5 Acoustic Array

AT&T SmartSonic TSS-1 (A-1)

This passive acoustic array was used in only two of the seven field test sites (Phoenix freeway in Autumn 1993 and Tucson surface street in Winter-Spring 1994). The detector was large, heavy, and cumbersome; its very size and weight presenting a challenge to the crew charged with its installation. Since the completion of the field tests, AT&T has produced a next-generation version of the unit in a dramatically smaller package (approximately half the size and weight). One of the attractive features of the AT&T acoustic array is its ability to emulate inductive loop outputs. The electronics card for the acoustic array fits into a Type 170 rack and, therefore, can be exchanged with existing loop amplifier electronics.

10.6.6 Magnetic Detectors

Midian Self-Powered Vehicle Detector (SPVD) Magnetometer

The SPVD is a system that detects the presence of a vehicle by measuring its magnetic field from beneath the roadway surface. As its name implies, the power for this unit is entirely self-contained within the SPVD. Traffic data and device status are transmitted to a roadside receiver by means of a radio frequency (RF) link that uses an antenna built into the housing of the buried magnetometer. An external antenna, connected to a receiver with a coaxial cable, is required to receive the data. The receiver may be located in a controller cabinet and may serve as the interface with a traffic management system.

3M Microloop Magnetometer (L-1)

The 3M Microloop probe is a small, cylindrical transducer that transforms changes in magnetic field intensity into inductance changes which can be sensed by loop detector electronics. The probes are inserted into 1-inch (25.4-mm) holes 16 to 24 inches (406.4 to 609.6 mm) beneath the road surface.

Each instrumented lane requires from one to three microloop probes, the number being a function of the lane width and the height of the vehicles to be detected. These devices are advertised to perform in high-iron environments, such as on or under bridge decks.

10.7 PRESENTATION OF DATA ANALYSIS RESULTS

Since reducing all the data collected during the field tests was beyond the scope of this phase of the project, a representative sample of the

data was analyzed to reflect the different sites and different traffic and weather encountered. The results, therefore, represent a wide spectrum of conditions chosen to stress the performance of the detectors under test. Figure 10-8 shows the structure in which the detector performance results are presented. The numbers appearing in parentheses in the boxes correspond to the section numbers in this chapter. The runs analyzed and the characteristics associated with them are given in Table 10-2. The column labeled Hookup Configuration refers to Appendix H, where the connections of the detector outputs to the data logger are shown along with the input power connections to the detectors.

Run	Site	Traffic Flow	Weather	Hookup Configuration
02081127	MN Freeway	Departing	Cold, overcast	Hookup 4A
02091626	MN Freeway	Depart & Approach	Cool, overcast	Hookup 4A
02110625	MN Freeway	Departing	Cold, light flurries	Hookup 1A
03091019	MN Street	Departing	Cold, snow	Hookup 6
03101343	MN Street	Departing	Cold, clear	Hookup 6
07221647	FL Freeway	Approaching	Hot, humid	Hookup I-4
07231329	FL Freeway	Approaching	Warm, heavy rain	Hookup I-4
07280615	FL Freeway	Approaching	Hot, humid	Hookup I-4
09071553	FL Street	Departing	Hot, humid	SR 436
09141730	FL Street	Departing	Hot, humid	SR 436
11090822	AZ Freeway	Approaching	Mild, dry	Phoenix 93
11221359	AZ Freeway	Approaching	Mild, dry	Phoenix 93
07281536	AZ Freeway	Approaching	Hot, dry	Phoenix 94
08041552	AZ Freeway	Approaching	Hot, dry	Phoenix 94
03101008	AZ Street	Departing	Warm, dry	Tucson
04121633	AZ Street	Departing	rting Warm, dry Tucson	
04131703	AZ Street	Departing	Warm, dry	Tucson

Table 10-2. Runs Analyzed in this Report

The detectors are referenced in the graphs and tables that give their performance by their model numbers. This designation was chosen so that specific designs and operating characteristics could be correlated with performance. A generic designation, such as microwave, does not account for the antenna beamwidth, hold time, or signal processing scheme that differ from device to device. These parameters must be noted, as in Tables 4-1 to 4-6 and 8-4, and taken into account to properly interpret the field test results.

Table 10-3 summarizes the ground truth from selected runs. Vehicles were counted manually by an observer from the video imagery of the traffic flow collected during the field tests. Ground truth data were tabulated for intervals ranging from 45 minutes to 2 hours, usually in 15-minute increments to reduce the error rate. A broad spectrum of traffic and weather conditions are represented. These values serve as the reference against which other detector outputs are compared when count accuracies and errors are reported. Some video was ground truthed multiple times in order to assess the accuracy and repeatability of the value recorded by the human observer. The results were typically repeatable to within ± 0.25 percent.

It is not possible to precisely compare outputs from every detector represented in the field tests with the ground truth value because the

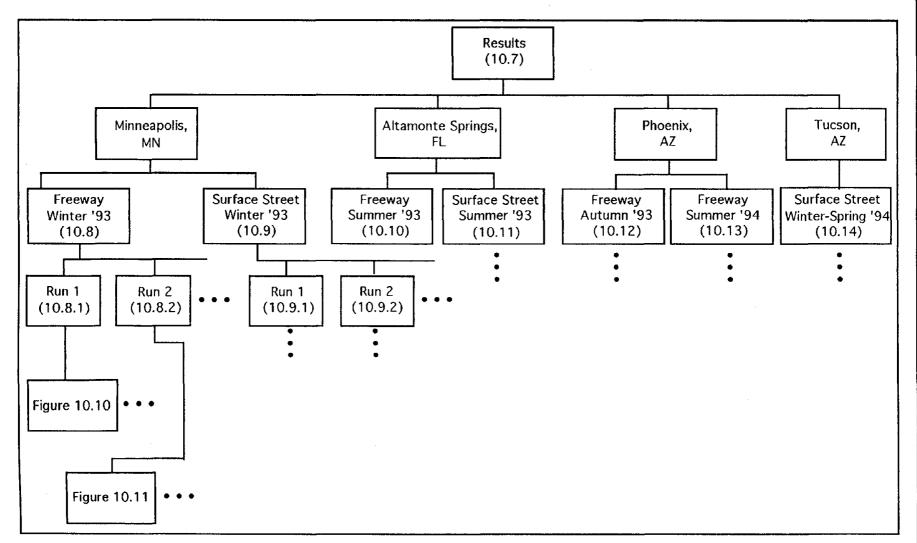


Figure 10-8. Roadmap for Detector Performance Results

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sensing areas associated with each device do not exactly coincide with one another. Therefore, frequent lane changes can cause anomalies in the counts recorded by devices monitoring different sections of the same lane. Although care was taken to select sites and detector mounting locations that minimized this problem, lane changing was unavoidable at the Tucson surface-street site. However, a software program was created to filter out the great majority of anomalies resulting from vehicles sweeping across multiple lanes when completing their turning movements. This is discussed in greater detail in Section 10.14.2.

Run	Site	Weather	Start	Stop	Veh	icle Co	unts
			Time	Time	Lane 1	Lane 2	Lane 3
02011159	MN Fwy	Cool, sunny	1201	1300	*	1127	1890
02091626	MN Fwy	Cool, overcast	1815	1900	+	846	1476
02110625	MN Fwy	Cold, light flurries	0700	0800	*	1816	1862
03091019	MN Street	Cold, snow	1200	1400	245	316	-
03101343	MN Street	Cold, windy	1630	1730	413	421	-
07150617	FL Fwy	Hot, humid	0745	0845	1215	944	1108
07211633	FL Fwy	Warm, rain	1700	1800	1013	1102	501
07231329	FL Fwy	Warm, heavy rain	1330	1426	959	1052	524
07280615	FL Fwy	Hot, humid	0730	0900	2281	2193	1360
09071553	FL Street	Hot, rain	1630	1830	1815	1778	-
09080725	FL Street	Hot, humid	0730	0930	1091	866	-
09081241	FL Street	Hot, humid	1300	1500	1716	1661	-
09141730	FL Street	Hot, humid	1800	2000	1512	1434	-
11090822	AZ Fwy	Mild, dry	0900	1000	750	1033	-
11221359	AZ Fwy	Sunny, dry	1600	1700	1603	1554	-
12021502	AZ Fwy	Mild, dry	1700	1800	1436	1423	-
12090620	AZ Fwy	Cool, dry	0625	0740	1.656	1951	-
07281536	AZ Fwy	Hot, dry	1900	2000	658	828	-
08041552	AZ Fwy	Hot, dry	1700	1800	1307	1399	-
04121633	AZ Street	Warm, dry	1700	1800	-	500	429

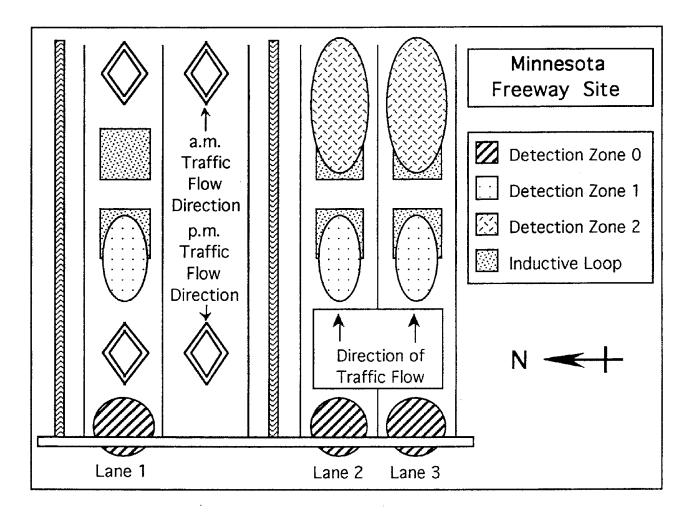
Table	10-3.	Vehicle	Count	Ground	Truth	Runs
Table	10-0.	venicie	Count	arouna	i i u cii	nuna

Lane 1 on I-394 MN freeway was a reversible HOV lane. The video camera did not monitor the traffic in this lane.

10.8 MINNESOTA FREEWAY DATA

This site was located on eastbound I-394 at Penn Avenue in Minneapolis, Minnesota. The detector layout configuration is shown in Figures 9-2 and 9-4. The I-394 freeway site was unique in that it had a pair of reversible HOV lanes as described in Section 9.1. One of these lanes was instrumented with detectors as were the two non-reversible eastbound lanes. All of the overhead detectors monitoring the HOV lane were directional devices, operating on either approaching or departing traffic, but not both at the same time. For this reason the lane 1 HOV overhead detector data were obtained only for evening runs when traffic flowed westward toward the detectors that were configured to monitor oncoming vehicles.

Figure 10-9 shows the approximate location of the sensing areas corresponding to the overhead devices and the physical locations of the inductive loops in each of the three



Zone		Lane 1		Lane 2		Lane 3
	Symbol	Model	Symbol	Model	Symbol	Model
0	IR1	Schwartz 780D1000	U3	MW Sensors TC-30C	U2	Sumitomo SDU-300
					IR2	Eltec 842
					IR3	Eltec 833
1	IL1A-2	Inductive Loop 2 (PM)	IL1B-2	Inductive Loop 1	IL1C-2	Inductive Loop 1
	M1B	MW Sensors TC-20	M2A	MW Sensors TC-26	M1A	MW Sensors TC-20
	M2B	MW Sensors TC-26	M4	Whelen TDN-30	VP1A-1	Autoscope 2003 VIP
			VP1A-3	Autoscope 2003 VIP	VP2A-2	TAS VIP
			VP2A-1	TAS VIP		
2	IL1A-1	Inductive Loop 1 (PM)	IL1B-1	Inductive Loop 2	IL1C-1	Inductive Loop 2
	M5A	Whelen TDW-10	VP1A-4	Autoscope 2003 VIP	VP1A-2	Autoscope 2003 VIP
			VP2A-3	TAS VIP	VP2A-4	TAS VIP
					M5B	Whelen TDW-10

Figure 10-9. Detection Zones on I-394 in Minneapolis, MN

instrumented lanes. The symbol column shows the detector mnemonic and interface designation for the relay and optically isolated detector outputs. Serial interfaces are not included in this table because they typically contain data that apply to several detection zones. The serial interfaces are included in the hookup files in Appendix H. Detection Zone 0 contains the footprints of the detectors that were oriented directly downward (or nearly so) toward nadir. Detection Zone 1 contains the westernmost inductive loops in each lane and the footprints of many of the Doppler microwave detectors. Zone 2 contains the easternmost loops in each of the monitored lanes. Two video image processors were evaluated at the Minneapolis freeway site, the Autoscope 2003 from Econolite and the Traffic Analysis System (TAS) from Computer Recognition Systems (CRS). Data from two optically isolated outputs, representing the traffic count in each of the eastbound lanes, were recorded for each

VIP. No serial outputs from either VIP were recorded at this site.

10.8.1 Run 02081127

This run is typical of light mid-day traffic on the I-394 freeway. The sky was overcast and the air temperature at noon was $24^{\circ}F$ (-4.4°C).

Vehicle Counts vs. Time of Day

Figure 10-10 shows accumulated vehicle counts in lane 2 over approximately 2 hours for two Doppler microwave detectors (Microwave Sensors TC-26 and Whelen TDN-30), an ultrasonic detector (Microwave Sensors TC-30C), a video image processor (CRS TAS), and an inductive loop. Count variations on the order of 20 percent were experienced by the TC-26 and TC-30C when compared with counts from the second loop in the lane. The TAS and TDN-30 each undercounted by about 10 percent in this midday run.

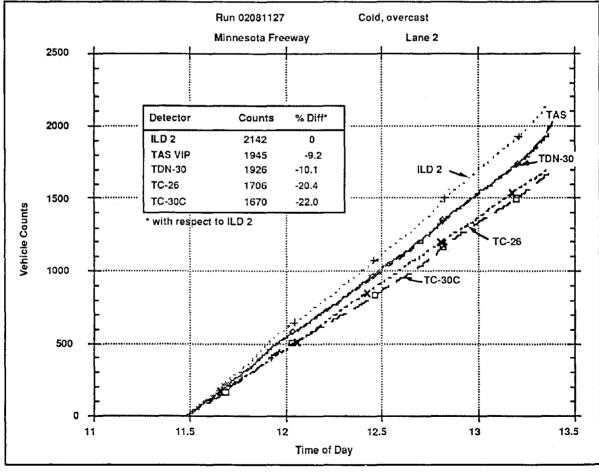


Figure 10-10. Comparison of Detector Vehicle Counts in Lane 2 During Light Traffic on Minneapolis Freeway Site

The difference between the counts from the TC-26 and the loop are attributed to the relatively long hold time of the TC-26. This resulted in an average TC-26 "on" time of 2.10 seconds per vehicle as compared to 0.14 second for the loop. The standard deviation of the TC-26 on time was 1.76 seconds.

Although ground truthing from other I-394 runs shows the inductive loop to be consistently among the most accurate detectors, the loop showed a tendency to overcount slightly (by less than 0.5 percent), while the microwave and ultrasonic detectors tended to undercount. Therefore, the percent difference in counts with respect to the loop may be slightly greater than the true percent error associated with video-based ground truthing. However, even video-based ground truthing would not eliminate the majority of the large percent differences noted in the figure. The TAS VIP tended to undercount, except during dark-to-light and light-to-dark transitions, when it overcounted.

10.8.2 Run 02091626

On this portion of a nighttime run on the 1-394 freeway, the count from one of the loops in lane 2 was used as the reference with which to compare counts from other detectors. The temperature was 32°F (0°C) at 6:00 p.m.

Vehicle Counts vs. Time of Day

Figure 10-11 relates vehicle counts to time of day for three detector technologies. Represented are inductive loops, Autoscope 2003 VIP, TAS VIP, and the Whelen TDN-30 narrow-beam microwave Doppler detector.

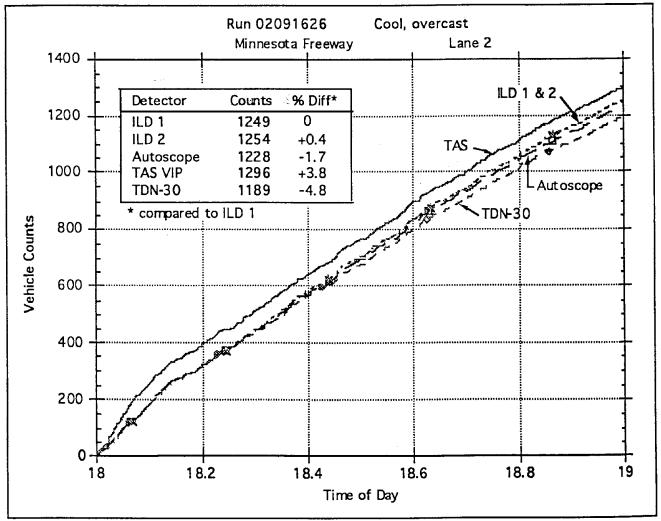


Figure 10-11. Comparison of Detector Vehicle Counts in Lane 2 During Nighttime Darkness on Minneapolis Freeway Site

Percent differences were computed for the vehicle counts given by the first inductive loop, Autoscope, TAS, and TDN-30 with respect to the second loop in the lane. The second loop was chosen as the reference because its detection zone more closely coincided with those of the VIP and the microwave detector.

The actual percent errors of the Autoscope and microwave detectors with respect to videobased ground truth are slightly less than the computed percent difference with respect to the loop, because the Autoscope and microwave detectors tend to undercount, whereas the inductive loops, although typically accurate to within 0.5 percent, tend to overcount. Therefore, a comparison with the video-based ground truth count could reduce the percent error by up to 1 percent. Conversely, the percent error (with respect to video-based ground truth) attributable to the TAS VIP is slightly greater than the 3.8 percent difference computed with respect to the loop because the TAS overcounted. The TAS counts are seen to be increasing with respect to the other detectors until shortly after 6 p.m. After this time, the TAS counts closely track those from the inductive loops.

The TAS does allow the operator to adjust a variety of setup and calibration parameters, a feature that theoretically should give more optimal performance in a true operational traffic management scenario. A factor that may have contributed to the observed performance of the TAS was the inability to position an ambient light monitoring zone sufficiently off the roadway due to the camera mounting height and location. Because of the zone's location, its ambient light monitoring function may have been affected by the headlights from oncoming vehicles.

10.8.3 Run 02110625

This run is representative of heavy volume morning rush hour traffic flow into Minneapolis. The temperature at the start of the run was 18°F (-7.8°C). Light flurries fell during the run. The first two figures from this run compare accumulated vehicle counts from the detectors, while the next three show speed, flow, and density, respectively, versus time of day. The sixth figure compares the vehicle speeds in adjacent lanes, while the last figure demonstrates the inverse relation between speed and flow that was observed in lane 2.

Vehicle Counts vs. Time of Day (Ground Truth Interval)

Figure 10-12 displays the vehicle counts in lane 2 (the leftmost of the two eastbound I-394 lanes) for a 1-hour ground truth interval as measured by five detectors. The detectors shown are the Econolite Autoscope 2003 VIP, CRS TAS VIP, Whelen TDN-30 narrow-beam microwave Doppler detector, Microwave Sensors TC-30C ultrasonic detector, and the second 6-foot by 6-foot (1.8-m by 1.8-m) inductive loop in the lane controlled by Detector Systems' 222B driver. The 7:00 a.m. to 8:00 a.m. counts generated by the detector outputs were compared to the ground truth count tabulated manually from video imagery during the post-processing analysis. The counts from the five detectors are within 0.3 to 1.6 percent of the ground truth value in this heavy traffic volume run. The TAS VIP overcounts early in the hour and undercounts for the rest of the hour, resulting in a 98.8-percent overall count accuracy.

Vehicle Count vs. Time of Day Over 4 Hours

Figure 10-13 shows accumulated vehicle counts in lane 2 as a function of time of day for the approximately 4-hour run. The counts from two Doppler microwave detectors (TDN-30 and TC-26), one ultrasonic detector (TC-30C), and a video image processor (TAS) are compared with those from the second inductive loop in the lane. Percent differences were computed using the inductive loop count over the 4-hour interval as the reference.

The TDN-30 count is within 0.9 percent of the loop, the TC-30C is within 3.7 percent, and the TAS is within 0.6 percent. The on time of the TC-30C averaged 0.29 second as compared to 0.14 second for the loop. The TC-26 significantly undercounted because of the long electronic hold time characteristic of this detector. The on time of the TC-26 averaged 5.47 seconds. The standard deviation of the TC-26 on time was 6.77 seconds and for the TC-30C it was 0.08 second.

The long hold time of the TC-26 caused missed detections when vehicles were closely spaced, such as in this heavy traffic volume run. The undercount is explained as follows. The TC-26 generates an electronic pulse when a vehicle is detected. If a second vehicle enters the detection zone before the falling edge of the original pulse occurs, then the TC-26 remains in the active state and does not detect the second vehicle as a separate event. Thus, an entire platoon of vehicles may trigger only a single detection pulse. The undercounting is more prevalent during heavy traffic when intervehicle gap times are at their minimum. The almost 5.5-second on time supports the hypothesis that the TC-26 is combining the

detection of several vehicles into a single output count.

The TAS VIP began the run overcounting vehicles until just after 7 a.m. This may be due to the VIP having difficulty transitioning from dark-to-light ambient lighting conditions. After this time, the TAS showed a tendency to undercount. However, the net result, a 99.4-percent counting accuracy with respect to the loop, is misleading. Had the run ended earlier than approximately 10:20 a.m., the percent difference would have been greater because the undercount interval would not have been long enough to compensate for the initial overcount interval. For example, if the run ended at 8 a.m., the TAS would show a percent difference of approximately +24 percent.

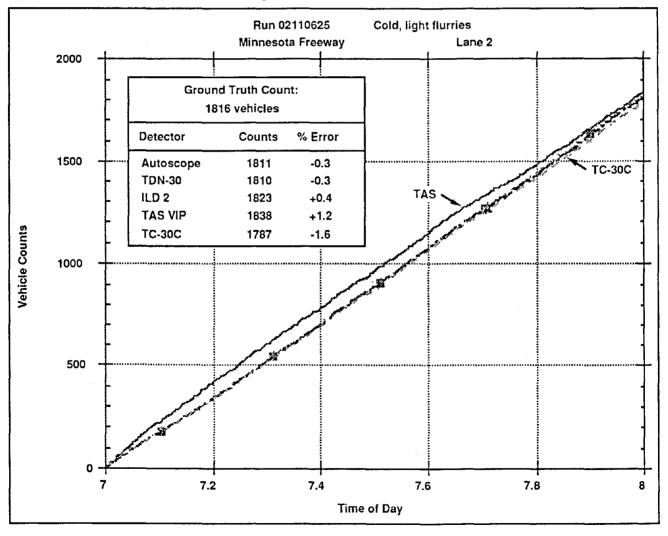


Figure 10-12. Vehicle Counts and Ground Truth in Lane 2 from I-394 Minneapolis Freeway Site

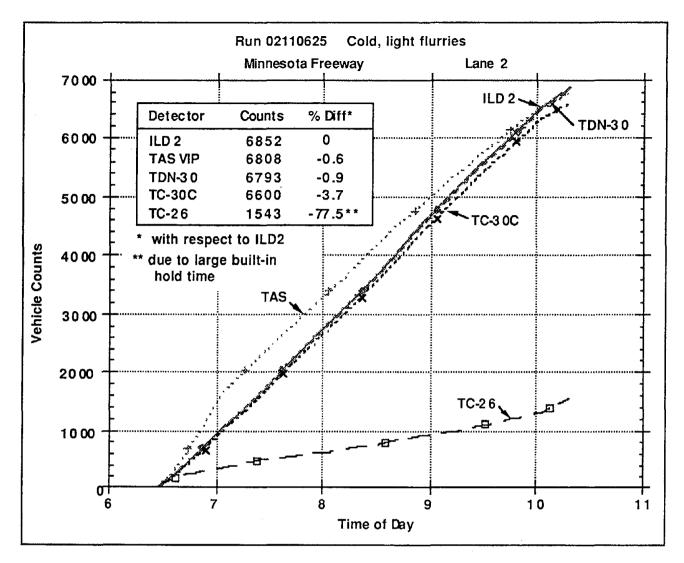


Figure 10-13. Vehicle Count Comparison Over 4-Hour Run Duration in Lane 2 on I-394 Minneapolis Freeway Site

Speed vs. Time of Day

The data in Figure 10-14 represent the entire duration of the run for all practical purposes (approximately the first 5 minutes of the run were omitted due to a "stacking up" of events in a buffer while the software began its initialization process). The plots of vehicle speed in lane 2 versus time of day were fitted with a fifth-order polynomial to the actual data in order to smooth out the spiky, discrete nature of the actual speeds. The plotted speeds are values obtained by averaging data from the TDN-30, Autoscope 2003, and a pair of inductive loops over 5-minute intervals. The three curves are consistent in their shape, with the only discernible difference being the magnitude of the speed. Speed was measured directly by the Whelen TDN-30 microwave detectors and output via an RS-232 interface to the data logger. The speeds calculated from the loops and the Autoscope VIP used the failing-edge time tag associated with each of two detection zones and knowledge of the spacings between those zones. The speeds noticeably decrease between 6:30 and 7:00 a.m. and resume free-flow conditions between 9:30 and 10:00 a.m.

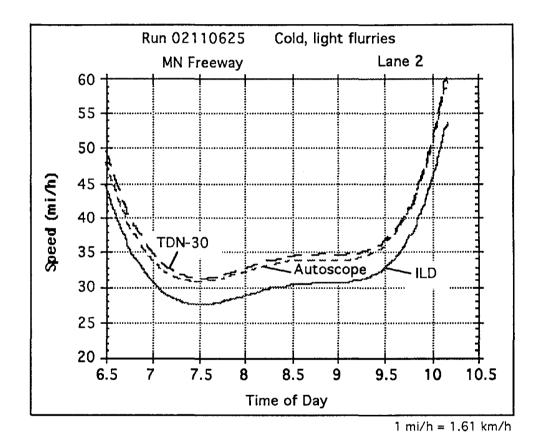


Figure 10-14. Comparison of Speed Data in Lane 2 from I-394 Freeway Site

The lower speed calculated from timing of pulses generated by the two-loop speed trap is attributed to a pair of factors. The first is the sequential scanning feature used in the Detector Systems 222B loop amplifier electronics. The two loops (driven by a single, two-channel card) are alternately turned off and on so as to minimize interference due to crosstalk. This may have caused timing problems that had a significant impact on the speed calculations. One can envision the lead loop being in the off state when a vehicle passes over it. Then when the loop is energized, the leading edge of the detection pulse does not necessarily correspond to the entrance of the vehicle into the loop's detection zone. The second difficulty stems from the width of the vehicle detection pulse. According to the loop amplifier's specification, the pulse width is 125 ± 25 milliseconds. This pulse width (and the associated 20-percent uncertainty) is quite long when compared to the 170 milliseconds necessary for a vehicle traveling at a freeway speed of 60 mi/h (96.6 km/h) to traverse the 15-foot (4.6-m) center-tocenter spacing between the two loops. The maximum percentage error in speed attributed to the pulse-width uncertainty for a vehicle traveling at 60 mi/h (96.6 km/h) is approximately 30 percent.

Flow vs. Time of Day

Figure 10-15 demonstrates the relationship between vehicle flow in lane 2 and time of day. The flow has units of vehicles per hour. These plots indicate an inverse proportionality of flow with speed; that is, as the speed increases (as depicted in Figure 10-14), the flow decreases. This decrease in traffic flow is attributed to a pronounced decline in demand beginning at around 9:30 a.m. The three different types of technology demonstrated here yield comparable results.

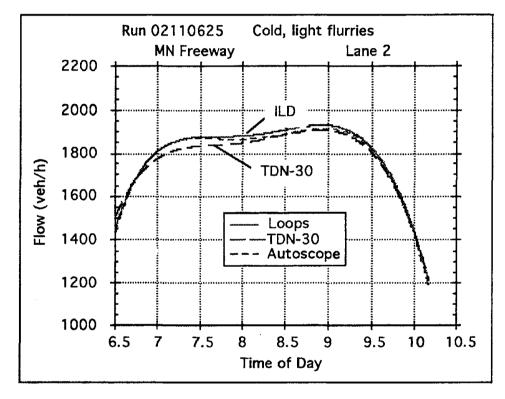


Figure 10-15. Comparison of Flow Data in Lane 2 from I-394 Freeway Site

Density vs. Time of Day

Figure 10-16 demonstrates the relationship between lane density in lane 2 and time of day. The lane density is the number of vehicles present within a 1-mile (1.6-km) distance in a given lane. Since it is not practical to measure this parameter directly without a wide-area detector, density is calculated from the available traffic data instead. The density is, therefore, computed as the ratio of vehicle flow (in vehicles per hour) to average speed (in miles per hour) over some integration interval. The density values in this example were calculated over 5-minute integration times. The interval can be defined by the user in the DENSITY.FOR program. The density plots bear out the assertion made in the preceding description of vehicle flow that the increase in speed between 9:30 and 10:00 a.m. and the corresponding decrease in vehicle flow indicate a decrease in demand during that time window.

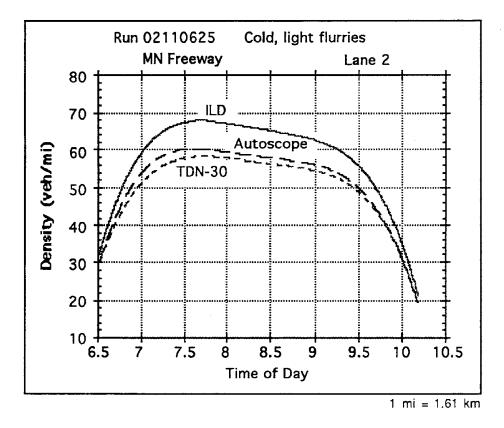
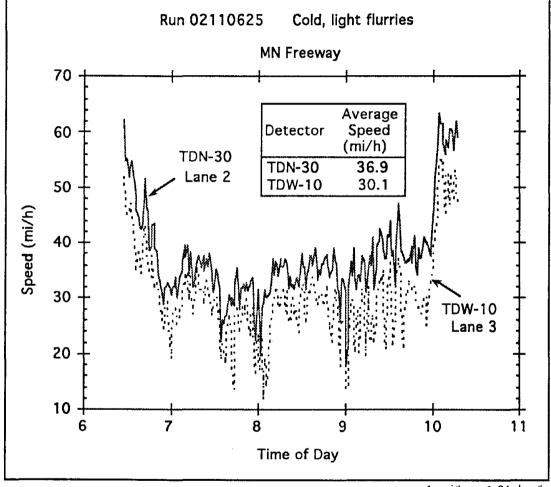


Figure 10-16. Density in Lane 2 as Computed From Data Collected at I-394 Freeway Site

Comparison of Speed From Two Detectors Monitoring Multiple Traffic Lanes

Figure 10-17 shows the relationship of speed as measured by two detectors located in adjacent traffic lanes 2 and 3. The vehicle speeds from each device were collected over a 1-minute integration interval and the average speed over that interval was computed. The uniformity in the shapes of the curves is a good indication that the detectors are correctly monitoring the traffic trends as they actually occurred. An average of the reported speeds was computed over the entire run. The TDN-30 in lane 2 (the leftmost of the two eastbound through lanes) reported an average speed of 36.9 mi/h (59.4 km/h) for the session, while the TDW-10 reported an average of 30.1 mi/h (48.4 km/h) in the right lane. The traffic in the right lane was observed, on average, to move slightly slower than the left lane. This was due to merging traffic both before and after the Penn Avenue off/on-ramp to I-394.

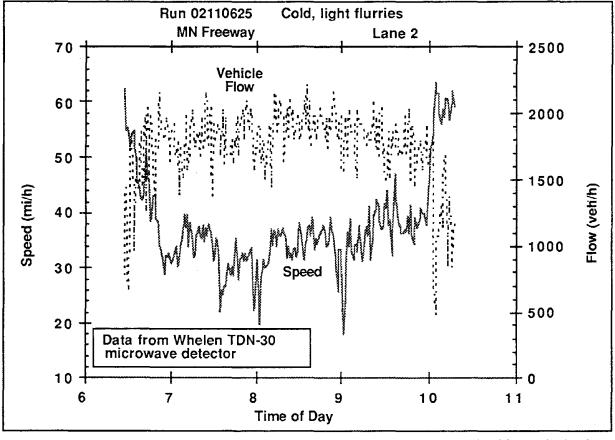


1 mi/h = 1.61 km/h

Figure 10-17. Speed Comparison of Doppler Microwave Detectors Located in Adjacent Lanes on I-394 Freeway Site, Minneapolis, MN

Comparison of Speed and Vehicle Flow

Figure 10-18 shows the inverse relationship between speed and flow in lane 2 during a typical morning rush hour at the I-394 freeway site. This is indicative of the types of data parameters that can be computed using simple, commercially available detectors. The data in this example was from the Whelen TDN-30 Doppler microwave detector. The speeds were recorded in real time from the radar's serial interface. Average speeds and vehicle flows were computed in postprocessing using a 1-minute integration interval. These computations could be made locally in real time to support traffic management applications such as freeway incident detection or interconnected intersection control on surface streets.

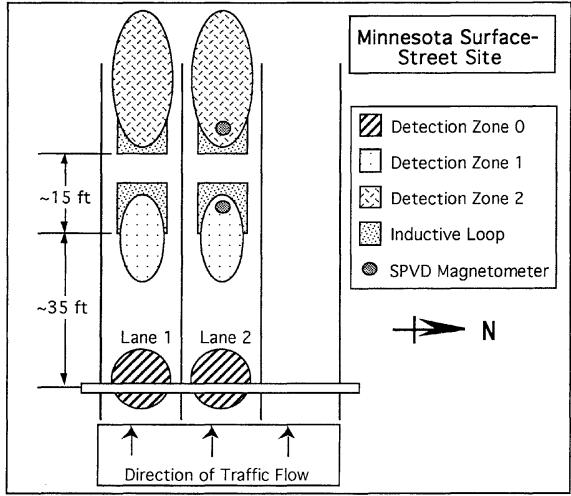


1 mi/h = 1.61 km/h

Figure 10-18. Comparison of Speed and Vehicle Flow in Lane 2 on I-394 Freeway Site in Minneapolis, MN

10.9 MINNESOTA SURFACE-STREET DATA

This site was located on Olson Highway (TH-55) at East Lyndale Avenue North in Minneapolis, Minnesota. The approximate locations of the detection zones are shown in Figure 10-19. The inductive loops generally coincided with the detectors having footprints in Zone 1 and Zone 2 at this site. Given the number of diverse technologies represented in these tests, it is difficult to calculate the precise location of the detection zones corresponding to the different detectors because they rarely coincide, whether they are transducer beam footprints, electromagnetic fields, or optical fields of view. (Theoretical detector footprint sizes and locations as a function of mounting heights and incidence angle are given in Appendix F.) However, if the amount



1 ft = 0.305 m

Zone		Lane 1		Lane 2
	Symbol	Model	Symbol	Model
0	U2A	Sumitomo SDU-300	U2B	Sumitomo SDU-300
	UBA	Microwave Sensors TC-30C	IR3	Eltec 833
	IR2	Eltec 842		
1	M4B	Whelen TDN-30	M4A	Whelen TDN-30
	IL1A-1	Inductive Loop	M6A-2	EIS RTMS-X1 (fwd-looking)
	VP1A-4	Autoscope VIP	IL1B-1	Inductive Loop
			VP1A-2	Autoscope 2003 VIP
			MG2A-1	SPVD Magnetometer
2	M2B	Microwave Sensors TC-26	M6A-3	EIS RTMS-X1 (fwd-looking)
	IL1A-2	Inductive Loop	IL1B-2	Inductive Loop
	VP1A-3	Autoscope VIP	VP1A-1	Autoscope 2003 VIP
			MG2A-2	SPVD Magnetometer
		· · · · · · · · · · · · · · · · · · ·	M5A	Whelen TDW-10

Figure 10-19. Detection Zones on Olson Highway in Minneapolis, MN

of lane changing is minimal, detector zone location in a particular lane should have little effect on vehicle count when the count is collected over a long time.

10.9.1 Run 03091019

The March 9 run was notable because of the appreciable amount of snowfall. The run was extended to 6 hours to gather as much data under these conditions as possible.

Counts in Multiple Detection Zones

The counts from detectors having multiple detection zones in lane 2 are compared in Figure 10-20. If there are a negligible number of vehicles changing lanes, then the counts from the two detection zones in the lane should be approximately equal. The figure illustrates the good agreement that generally exists between the inductive loops. The SPVD magnetometer in Zone 2 is within 1 percent of the inductive loop count. The lower value of the SPVD count in Zone 1 was likely due to electronic noise on the receiver input line generated by the computer and other electronics in the trailer. In later runs, the SPVD receiver was connected to its own AC power circuit to alleviate this problem. The RTMS radar counted well in Zone 1. In Zone 2, the footprint widened and most likely picked up vehicles in adjacent lanes. The poorer performance of Autoscope in Zone 1 was probably due to imprecise calibration during setup of the zones by the Autoscope personnel.

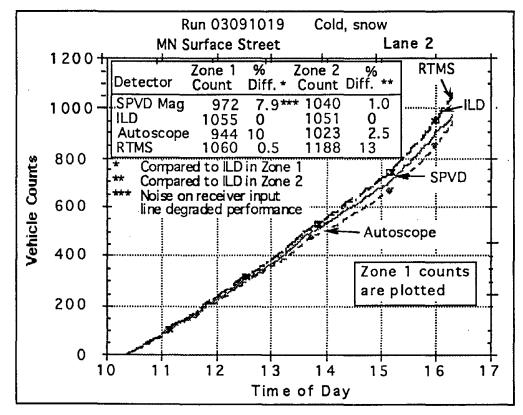


Figure 10-20. Vehicle Counts From Detectors With Multiple Detection Zones in Lane 2 of the Olson Highway Site

Figures 10-21 and 10-22 show the vehicle count data output by the detectors compared with ground truth obtained by manually counting the vehicles in lanes 1 and 2, respectively, on the video imagery of a 2hour interval. The lane 2 results appear within manufacturers' specifications. The poorer performance of the TDN-30 in lane 1 when compared to lane 2 may be due to moisture accumulation in the lane 1 unit. Possible explanations for the large error in the TC-30C's count include cold weather-

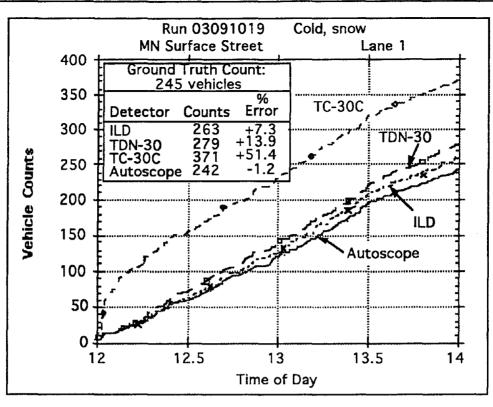


Figure 10-21. Comparison of Detector Vehicle Counts with Ground Truth in Lane 1 of the Olson Highway Site

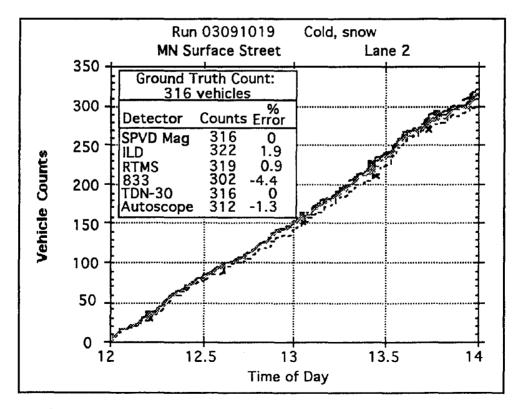


Figure 10-22. Comparison of Detector Vehicle Counts with Ground Truth in Lane 2 of the Olson Highway Site

related effects or reflection of signals from the snow flurries. However, the exact cause of the overcount could not be deduced.

10.9.2 Run 03101343

This session was conducted 1 day after the run discussed in the previous section. Vehicle counts were ground truthed in postprocessing for a 1-hour period between 4:30 and 5:30 p.m. when peak traffic occurred. Table 10-4 shows the counts and associated percent errors from several detectors in two lanes. The most consistent performers in each lane were the inductive loops, registering 98- to 99-percent accuracies in both lanes. The Autoscope 2003 video image processor showed good results in the second detection zone of each lane (although slightly undercounting as it had in Run 03091019), but poorer accuracies for both lead detection zones. The count accuracies of the TDN-30 microwave detectors were also within specifications in both lanes. The rest of the detectors did not perform as well as these. The 833 passive IR detector that undercounted during the snowy, low-traffic Run 03091019, overcounted during this run, which had approximately three times the traffic volume.

Table	10-4.	Count Accuraci	es for	Run	03101343	on	Olson	Highway
		Surface-Street	Site	in M	linneapolis,	MI	N	

	Lane 1			Lane 2	
Detector	Count	% Error	Detector	Count	% Error
ILD 1	418	1.2	SPVD Mag 1	340	-19.2
ILD 2	421	1.9	SPVD Mag 2	616	46.3
TDN-30	401	-2.9	ILD 1	426	1.2
TC-30C	467	13.1	ILD 2	425	1.0
TC-26	463	12.1	TDN-30	404	-4.0
Autoscope 1	383	-7.3	RTMS-X1 (1)	460	9.3
Autoscope 2	411	-0.5	RTMS-X1 (2)	521	23.8
			833	490	16.4
			Autoscope 1	379	-10.0
			Autoscope 2	412	-2.1
Ground Truth	413		Ground Truth	421	

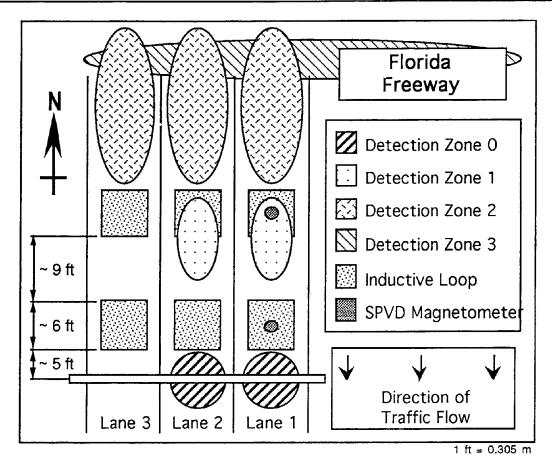
10.10 FLORIDA FREEWAY DATA

Traffic moving south was monitored in all three lanes of the westbound I-4 freeway just north of SR 436, which runs over the freeway. The overhead detector layout and video image processor detection zones are shown in Figures 9-17 and 9-19, respectively. A pair of inductive loops were installed in each of the three lanes. SPVD magnetometers were inserted in the center of the loops in lane 1 (leftmost lane). The detection zone locations are shown in Figure 10-23.

Detection Zone 0 contained footprints from detectors oriented toward or near nadir in

lanes 1 and 2. These included a TC-30C ultrasonic detector from Microwave Sensors and a Schwartz 780D1000 Autosense I laser radar in lane 1. Lane 2 was monitored by an Eltec Model 833 passive infrared detector, while both lanes 1 and 2 contained Sumitomo SDU-300 ultrasonic units. The second inductive loop in each pair and the second SPVD magnetometer were located in between detection Zones 0 and 1.

Detection Zone 1 contained the lead loops in each lane and the first magnetometer in lane 1. The other detectors in lane 1 were the Whelen TDN-30 and the Eltec 842. The footprints in lane 2 that were included in Zone 1 were from the Whelen TDN-30 and the



Zone		Lane 1		Lane 2		Lane 3
	Symbol	Model	Symbol	Modei	Symbol	Modei
0	U3A	MW Sensors TC-30C	U2B	Sumitomo SDU-300	IL1C-2	Inductive Loop
	U2A	Sumitomo SDU-300	IR3	Eltec 833		
	IL1A-2	Inductive Loop	IL1B-2	Inductive Loop		
	MG2A-2	SPVD Magnetometer				
	IR1	Schwartz 780D1000				
1	M4B	Whelen TDN-30	M4A	Whelen TDN-30	IL1C-1	Inductive Loop
	IR2	Eltec 842	IL1B-1	Inductive Loop		
	IL1A-1	Inductive Loop	U1	Sumitomo RDU-101		
	MG2A-1	SPVD Magnetometer	M6A-2	EIS RTMS (fwd-look)		
2	M2B	MW Sensors TC-26	M5A	Whelen TDW-10	VIP1A	Autoscope 2003 VIP
	VIP1C	Autoscope 2003 VIP	M6A-3	EIS RTMS (fwd-look)		
	M1B	MW Sensors TC-20	VIP1B	Autoscope 2003 VIP		
			M1A	MW Sensors TC-20		
3	M6A-5	EIS RTMS (side-look)	M6A-6	EIS RTMS (side-look)	M6A-7	EIS RTMS (side-look)

Figure 10-23. Detection Zones on I-4 in Altamonte Springs, FL

Sumitomo RDU-101 Doppler ultrasonic detector, and those included in the second zone were from the forward-looking RTMS-X1 true-presence microwave radar.

Five microwave detectors had footprints in Zone 2. Microwave Sensors TC-20 and TC-26 monitored lane 1, while a Whelen TDW-10, Microwave Sensors TC-20, and the first forward-looking RTMS-X1 range bin were in lane 2. A second TC-20 was mounted on a support column located in the freeway median of SR 436 and was side-fired into lane 1. The Autoscope 2003 video image processor monitored all three lanes in Zone 2.

Zone 3 overlaps Zone 2, representing the area covered by the side-looking RTMS-X1 radar mounted on a pole located on the eastbound side of the freeway near the trailer. This unit also monitored all three eastbound lanes, although ground truth is not available against which to compare these outputs.

10.10.1 Run 07221647

The run is representative of a typical evening rush hour. Westbound traffic is usually heavier in the morning when workers commute from the suburbs into Orlando. This session, as with most of the nighttime runs, continued into darkness in order to monitor the effect of the light-to-dark transition on video image processor operation.

Total Vehicle Counts

Table 10-5 shows vehicle count results collected over the entire 4-hour session. Vehicle counts were not ground truthed for this run. Instead, the percent difference was computed with respect to the first inductive loop in each of the three lanes. The loops have been shown to be accurate to within 0.5 percent in other Florida freeway runs. Thus, the percent difference computation yields a meaningful figure of merit.

	Lane 1			_ane 2		Lane 3		
Detector	Count	% Diff	Detector	Count	% Diff	Detector	Count	% Diff
ILD 1	2297	0.0	ILD 1	3632	0.0	ILD 1	1586	0.0
ILD 2	2292	-0.2	ILD 2	3634	0.1	ILD 2	1587	0.1
TDN-30	1562	-32.0	TDN-30	3436	-5.4	RTMS-X1**	1451	-8.5
SPVD Mag 1	2057	-10.4	RTMS-X1(1)*	3506	-3.5	Autoscope 1	1566	-1.3
SPVD Mag 2	2035	-11.4	RTMS-X1(2)*	4290	18.1	Autoscope 2	1406	-11.3
SDU-300	2198	-4.3	RTMS-X1**	3419	-5.9	Autoscope 3	1546	-2.5
TC-20	1718	-25.2	TC-20	2582	-28.9			
TC-30C	2070	-9.9	SDU-300	3562	-1.9			
RTMS-X1**	2023	-11.9	Autoscope 1	3588	-1.2			
Autoscope 1	2234	-2.7	Autoscope 2	3247	-10.6			
Autoscope 2	2202	-4.1	Autoscope 3	3576	-1.5			
Autoscope 3	2310	0.6						
ILD 1 Ref.	2297		ILD 1 Ref.	3632		ILD 1 Ref.	1586	

Table 10-5. Vehicle Counts for Run 07221647 on Florida Freeway

Forward-looking mode

* * Side-looking mode

The counts from the three loop pairs demonstrate consistency within 0.2 percent. The Autoscope 2003, although generally yielding counts within 3 percent of those of the loops in at least one zone, shows an inconsistency among its three detection zones in each lane. The second of these zones was set up as a speed detector. Zones 1 and 3 were set up as count detectors. The count outputs from zones 1 and 3 support a graceful transition from daylight to nighttime algorithms since the inaccuracies do not grow large over the approximately 5:00 to 9:00 p.m. run. The first detection zone of the RTMS-X1 in lane 2 counted to within 3.5 percent of the loop value, while the second detection zone overcounted by 18 percent. This is due to the difficulty in confining the elliptical beam footprint to a single lane. This causes "splashing," which is the detection of vehicles from adjacent lanes of traffic. A second RTMS-X1, operating in a side-looking mode, gave varying accuracy results. This single unit also monitored traffic in the three eastbound lanes, but there is no other data against which to compare these results. The TC-20s in lanes 1 and 2 undercounted due to their long electronic hold times, while the TDN-30 microwave detector in lane 1 is believed to have suffered damage from water seeping into the detector electronics. The TDN-30 in lane 2 agreed with the loop count to within 5 percent. The SDU-300 ultrasonic detector achieved 96- and 98-percent agreement with the loops in lanes 1 and 2, respectively.

10.10.2 Run 07231329

This run, though quite short in duration, is important in that it occurred during a heavy thunderstorm. This allows data to be compared with those from the run of the day before (07221647) to ascertain whether or not the heavy rain made an appreciable difference on the count accuracies. Results were ground truthed for this run, which enables percent error to be calculated.

Total Vehicle Counts

The results from Table 10-6 indicate that most of the detectors suffered little or no degradation in performance due to the extreme weather conditions present during the run. The only notable exception was the SPVD magnetometer. The lead magnetometer in lane 1 undercounted by nearly 50 percent, whereas on the previous day it was 10 percent under the count from the loops. The reason for this result is not apparent since the magnetometer count accuracy in subsequent runs, as observed in the Paradox database files, was closer to the performance demonstrated in the previous Florida freeway runs. The count accuracy of the second magnetometer was within 1 percent of the value recorded on the previous day. The TC-30C ultrasonic detector was not operational due to a failure that occurred prior to the run made earlier in the morning.

Lane 1			Lane 2			Lane 3		
Detector	Count	% Error	Detector	Count	% Error	Detector	Count	% Erroi
ILD 1	963	0.4	ILD 1	1057	0.5	ILD 1	522	-0.4
ILD 2	964	0.5	ILD 2	1057	0.5	ILD 2	521	-0.6
TDN-30	713	-25.7	TDN-30	1043	-0.9	RTMS-X1**	475	-9.4
SPVD Mag 1	493	-48.6	RTMS-X1(1)*	1057	0.5	Autoscope 1	511	-2.5
SPVD Mag 2	844	-12.0	RTMS-X1(2)*	1176	11.8	Autoscope 2	476	-9.2
SDU-300	938	-2.2	RTMS-X1**	1011	-3.9	Autoscope 3	493	-5.9
TC-20	609	-36.5	TC-20	696	-33.8			
TC-26	1020	+6.4	SDU-300	1033	-1.8			
RTMS-X1**	900	-6.2	Autoscope 1	1036	-1.5			
Autoscope 1	925	-3.5	Autoscope 2	1006	-4.4			
Autoscope 2	926	-3.4	Autoscope 3	1031	-2.0			
Autoscope 3	938	-2.2						
Ground Truth	959		Ground Truth	1052		Ground Truth	524	

Table 10-6. Vehicle Counts for Run 07231329 on Florida Freeway

Forward-looking mode

* Side-looking mode

One possible explanation for the magnetometer anomaly is RF noise due to either the lightning or, more likely, from nearby RF communications. The magnetometer receiver's frequencies of operation are not in a protected band, and spurious voice transmissions were heard from time to time during the field tests through a speaker connected to the output of the receiver.

10.10.3 Run 07280615

This run is representative of morning rushhour conditions on westbound I-4. The session began at 6:15 a.m. and continued until approximately 10:50 a.m. The results shown in the following figures compare vehicle counts and flow among the detectors.

Counts vs. Time of Day

Figure 10-24 compares vehicle counts versus time of day for six traffic detectors located in the fast lane of the westbound I-4 freeway. The vehicle counts were ground truthed by manually counting vehicles from the video tape made of the actual run during the interval from 7:30 to 9:00 a.m. This gives a true value with which to compare the counts from the detector outputs. The figure includes data from the RTMS-X1 microwave presence radar, a TDN-30 Doppler microwave detector, an SDU-300 ultrasonic detector, an inductive loop, the 780D1000 laser radar, and the Autoscope 2003 video image processor.

A wide variation in the vehicle count is shown. The best count results were achieved by the inductive loop, followed by the Schwartz laser radar relay output, the Autoscope VIP, and the Sumitomo SDU-300 ultrasonic detector in that order. The two microwave detectors, the side-looking RTMS and the Whelen TDN-30, showed poor results for this test. The RTMS generally provides better results in the forward-looking orientation; the Whelen TDN-30's problem was likely due to a failure of a rubber seal that allowed water from a number of thunderstorms to seep into the unit. Whelen has since improved the design of their housings and seals and drilled a hole in the bottom of their case to avoid accumulation of moisture.

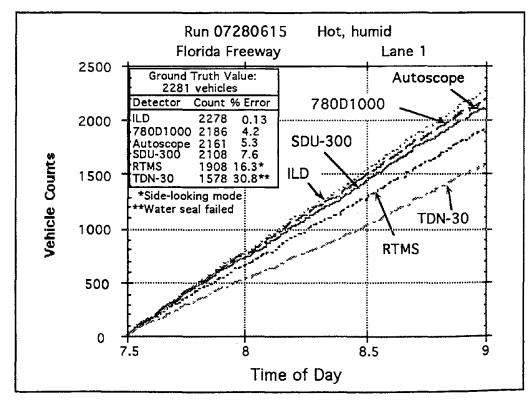


Figure 10-24. Comparison of Detector Count Data at Florida Freeway Site

Vehicle Flow vs. Time of Day

Figure 10-25 shows how the traffic flow varied during an approximate 4-hour period for the same six detectors represented in Figure 10-24. These curves are fifth order polynomial fits to the computed flow data that were calculated using 5-minute integration intervals. The plots illustrate a peak in the traffic volume occurring at 7:00 a.m. that steadily decreases until approximately 10:00 a.m. All the curves have the same basic shape, with the only discernible difference occurring in the plot representing the Autoscope 2003 video image processor. Here, the flow appears to fall off more rapidly after 8:30 a.m. for the Autoscope than for the other detectors. The reason for this is not known.

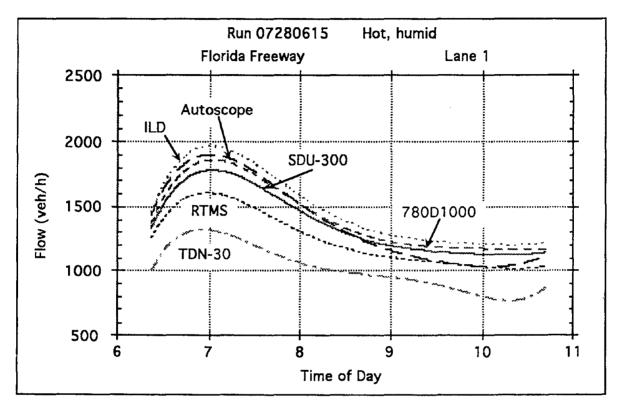


Figure 10-25. Comparison of Detector Flow Data at Florida Freeway Site

Histogram of Occupancy Computations

Figure 10-26 shows a histogram relating lane occupancy to the number of occurrences over the entire run of approximately 4 hours. Each bin of the histogram represents a 2.5percent increment in lane occupancy, defined as the percentage of an integration interval that a detector is in an active state. Occupancy is commonly used as a surrogate for lane density. The occupancy values were computed using a 30-second integration interval. The histogram shows that this detector, representing one of the detection zones from an Autoscope 2003 video image processor, measured occupancies of 2.5 to 15 percent approximately 80 percent of the time.

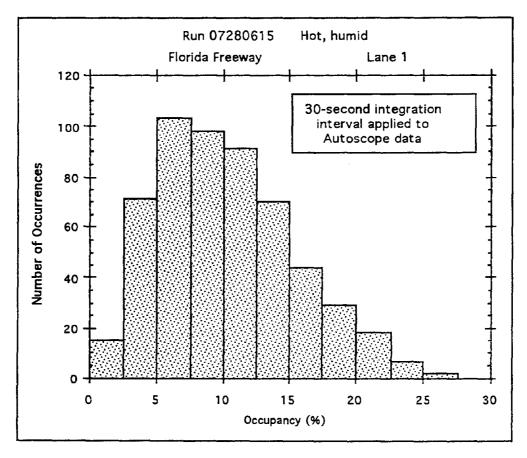


Figure 10-26. Occupancy Histogram at I-4 Freeway Site, Altamonte Springs, FL

Effect of Integration Interval on Fifth Order Polynomial Curve Fit

The effect of the integration interval on lane occupancy was computed using the Autoscope detection zone output from lane 1 of the I-4 freeway site. Occupancy was calculated by summing the vehicle presence times output by the detector interface over a selected integration interval and then dividing the sum by the interval time. This yielded the percentage of the time that the detector was in the active state over that interval. The resulting occupancy values were plotted versus time of day. The data were fitted to a fifth order polynomial curve in order to better examine the average trend that was somewhat masked by the discrete occupancy

values, as shown on the left in Figure 10-27 for a 30-second interval. This process was repeated using a 5-minute integration interval in order to assess the effect of a longer integration time on the discrete data points and the fitted curve as illustrated in the right graph in Figure 10-27. Integrating the data one-tenth as often eliminated the peak values evident in the left graph. Overlaying the curves fitted to the 30-second and 5minute integrated data showed no discernible difference in the fitted curves. This enabled the analyst to use a 5-minute integration interval in future analyses to speed up the data output process when average trends were desired. However, if peak values were needed, then the shorter integration intervals were used.

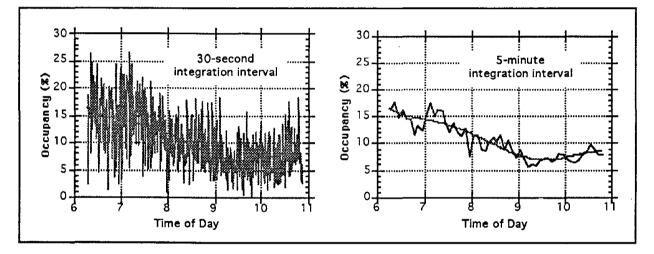
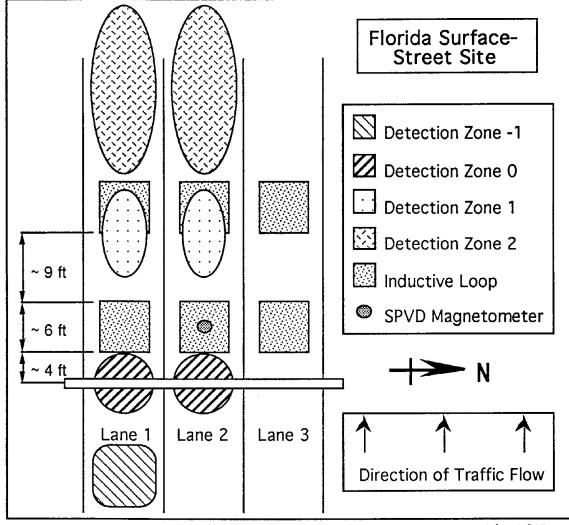


Figure 10-27. Effect of Integration Interval on Data Resolution

10.11 FLORIDA SURFACE-STREET DATA

The evaluation site on SR 436 had four concentrations of detection zones. The first zone, shown in the table accompanying Figure 10-28, is labeled detection Zone -1 due to its placement forward of the other zones. Two detectors monitored this area of lane 1 as they observed approaching traffic. The overhead detectors in the other zones observed the rear of the vehicles as they monitored departing traffic.

Detection Zone 0 contained the footprints of the detectors oriented toward nadir in lanes 1 and 2. The first pair of inductive loops were in between Zones 0 and 1. The second set of loops generally coincided with detectors having footprints in Zone 1. Zone 1 contained the viewing areas of devices that were oriented at approximately 45 degrees with respect to the plane of the roadway. These included a Whelen TDN-30 Doppler microwave detector in lane 1 and the first of the two range bins from the forward-looking RTMS-X1 true-presence microwave radar in lane 2. The furthest viewing area was detection Zone 2 that contained the approximate viewing areas of the TC-26 Doppler microwave in lane 1 and the TDW-10 Doppler microwave and second RTMS-X1 range bin in lane 2.



Zone		Lane 1	Lane 2				
	Symbol	Model	Symbol	Model			
- 1	U1	Sumitomo RDU-101					
	IR1	Schwartz 780D1000					
0	U2A	Sumitomo SDU-300	U2B	Sumitomo SDU-300			
	UBA	Microwave Sensors TC-30C	IR3	Eltec 833			
	IR2	Eltec 842	IL1B-1	Inductive Loop			
	<u>IL1A-1</u>	Inductive Loop					
1	M4B	Whelen TDN-30	MG2A-1	SPVD Magnetometer			
	IL1A-2	Inductive Loop	M6A-2	EIS RTMS-X1 (fwd-looking)			
			IL1B-2	Inductive Loop			
2	M2B	Microwave Sensors TC-26	M6A-3	EIS RTMS-X1 (fwd-looking)			
			M5A	Whelen TDW-10			

Figure 10-28. Detection Zones on SR 436 in Altamonte Springs, FL

10.11.1 Run 09071553

The weather during the run was hot and humid with heavy rain starting at about 5:15 p.m., tapering to thunder showers around 5:30.

Vehicle Counts in Lane 1 vs. Time of Day

Both the TDN-30 and the loops had a 1.5percent error with respect to the ground truth value of vehicle count in lane 1 as shown in Figure 10-29. In fact, all detectors, with the exception of the TC-26, performed within manufacturers' specifications. The TC-26 is not designed for a vehicle-counting application because of its long hold time. It is designed for signal control and detection of vehicles approaching an intersection that are within its field of view.

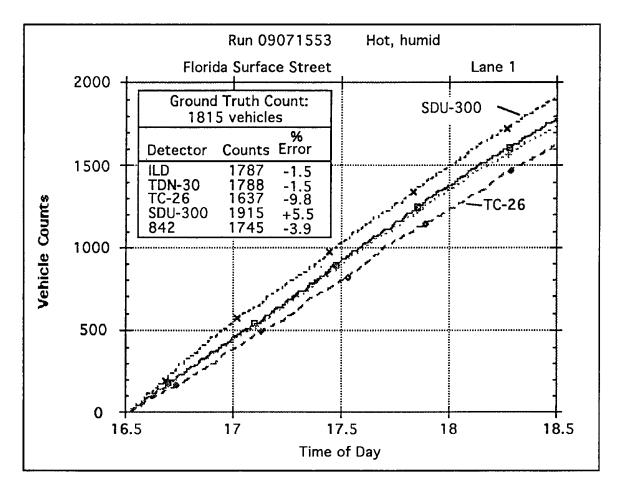


Figure 10-29. Comparison of Vehicle Count Data on Lane 1 of Florida Surface-Street Site

Vehicle Counts in Lane 2 vs. Time of Day

Figure 10-30 contains the vehicle count data from lane 2. The count from the forwardlooking RTMS-X1 microwave detector was closer to the ground truth value during this run than was the count from the inductive loop. The larger error shown by the 833 passive infrared detector was probably due to the relatively long hold time of the device. The hold time, however, is a design parameter that generally can be adjusted by the manufacturer to suit specific applications.

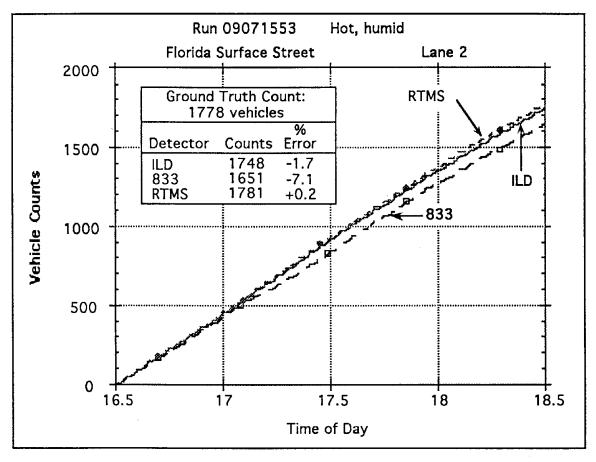


Figure 10-30. Comparison of Vehicle Count Data on Lane 2 of Florida Surface-Street Site

Vehicle Counts in Lane 2 Over 3-Minute Traffic Signal Cycle

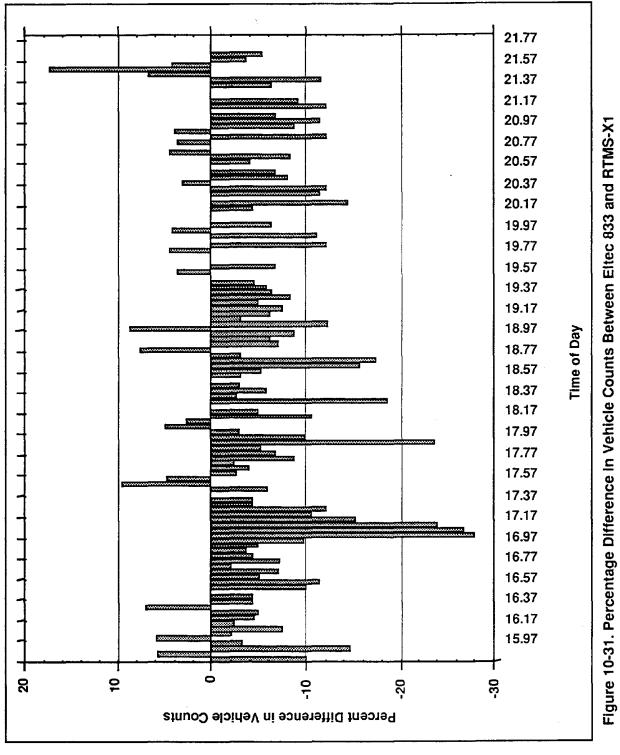
The data in this run were analyzed to determine the short-term count accuracy of the detectors over a time period consisting of one traffic signal cycle equal to 3 minutes. The counts from the forward-looking RTMS detector were closest to the 2-hour ground truth value of 1778 vehicles. Therefore, this detector was used as the reference for the analysis of short-term count stability shown in Figures 10-31 and 10-32.

Video imagery in future analyses can be used o ground truth the count over a time interval

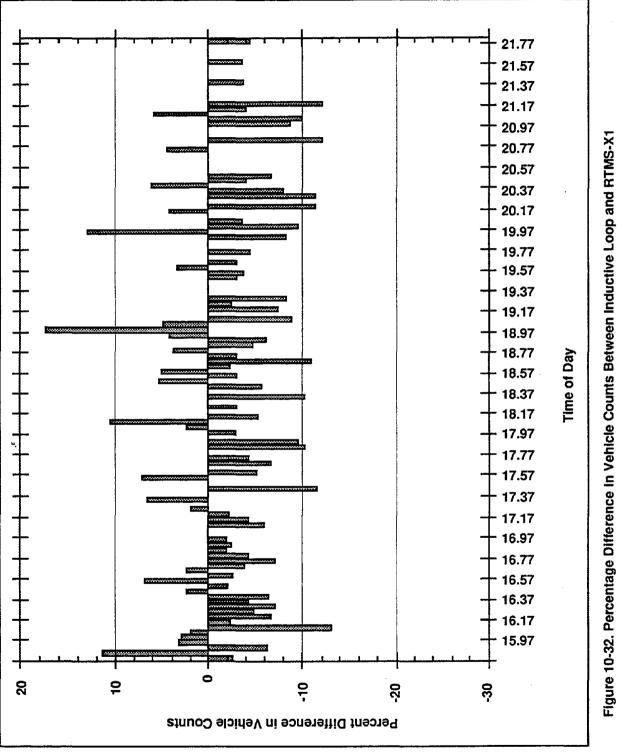
of only one signal cycle. In this way, the detector with the best short-term accuracy can be identified and used as the reference against which to compare the counts of the other detectors.

Comparison of Vehicle Counts From Eltec 833 With RTMS-X1

Figure 10-31 shows the short-term stability of the vehicle count obtained with the Eltec 833 and the RTMS-X1 in lane 2 (middle lane). The data span almost a 6-hour period. They were accumulated over 3-minute intervals corresponding to the cycle time of









the traffic signals at this intersection. The average value of the count difference was -1.94 counts and the standard deviation of the count difference was 2.83 counts. The standard deviation of the percent difference values was 7.22 percent. The Eltec 833 consistently undercounted as evidenced by the predominance of negative percent differences when compared with the RTMS counts. This indicates that the Eltec 833 IR detector is either missing some vehicles entirely (due to insufficient detector sensitivity to distinguish the thermal contrast between the vehicle and the road surface), or failing to discriminate between closely spaced vehicles.

Comparison of Vehicle Counts From Inductive Loop With RTMS-X1

Figure 10-32 shows the short-term stability of the vehicle count obtained with the first inductive loop and the RTMS-X1 in lane 2 (middle lane). The average value of the count difference was -0.75 counts per interval and the standard deviation of the count difference values was 1.73 counts. The standard deviation of the percent difference values was 5.35 percent. These results show that the loop did not consistently overcount or undercount with respect to the RTMS.

10.11.2 Run 09141730

The weather during this run was warm, humid, and clear. The duration of the session was approximately 3.5 hours with video ground truthing performed for a 2-hour window between 6:00 and 8:00 p.m.

Vehicle Counts vs. Time of Day

Vehicle counts were tabulated for the 6 p.m. to 8 p.m. around truth period for the detectors in lanes 1 and 2. The results are shown in Table 10-7. There are some differences between these results and those obtained from run 09071553 conducted 1 week earlier. The TC-26 microwave detector and Eltec 833 passive infrared detector undercounted by 9.8 and 7.1 percent, respectively, during the run of September 7, but overcounted by 9.9 and 8.2 percent, respectively, during this run. The Eltec 842 passive infrared detector undercounted by approximately 22 percent more than it did during the September 7 run. Conversely, the SDU-300 ultrasonic detector in lane 1 overcounted by 5.5 percent on September 7 and undercounted by 1.6 percent during this run. The inductive loops, TDN-30 microwave detector, and RTMS-X1 true-presence microwave radar all showed reasonable consistency in their respective count accuracies when compared to the run conducted 1 week prior. Further analysis needs to be performed to determine trends or patterns that may explain the inconsistency in the results. This entails overlaying the detection information for a given detector onto the video imagery and examining each missed or false detection.

	Lane 1 Lane 2				
Detector	Count	% Error	Detector	Count	% Error
ILD 1	1476	-2.4	ILD 1	1411	-1.6
ILD 2	1467	-3.0	ILD 2	1386	-3.3
TDN-30	1487	-1.7	RTMS-X1 (1)	1468	2.4
TC-30C	*	-	RTMS-X1 (2)	1523	6.2
TC-26	1661	9.9	833	1552	8.2
780D1000	* *	-	SDU-300	* * *	- 1
842	1125	-25.6	TC-20	873	-39.1
SDU-200	1131	-25.2			
SDU-300	1488	-1.6			
Ground Truth	1512		Ground Truth	1434	

Table 10-7. Vehicle Counts for Run 09141730 on Florida Surface Street

Mounting height exceeded manufacturer's maximum operating range

* * Not functioning

* * * Detector electronics were not calibrated for the large operating range at this site

10.12 PHOENIX AUTUMN 1993 FREEWAY DATA

The Phoenix I-10 freeway site was characterized by five detection zones over three lanes of westbound traffic. The five zones are shown in Figure 10-33. In keeping with the convention established for the Florida surface-street runs, Zone -1 was assigned to the area on the opposite side of the sign structure from that monitored by the other detectors. The AT&T passive acoustic array and the Eltec 833 passive infrared detector in Zone -1 monitored departing traffic because AT&T preferred to have their array face departing traffic, and the 833 provided counts to compare with those from the acoustic array. Because of the location of these footprints, video ground truth was not available for these detectors. However, due to the small amount of lane-changing observed at this location, the count variation with respect to the other lane 2 detectors is expected to be minimal.

Zone 0 contained footprints from detectors that are oriented at or near nadir. The Eltec 842 passive infrared device was mounted north of lane 1 as shown in Figure 9-30, but was side-looking into Zone 0 of lane 1. The second inductive loop in each lane and the second SPVD magnetometer in lane 2 were located between Zones 0 and 1.

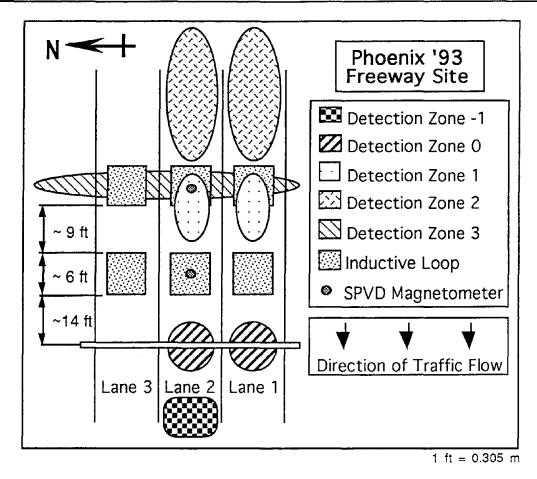
Zone 1 contained the lead loops in each of the three lanes and the lead magnetometer in lane 2. Most of the beam footprints from the forward-looking microwave detectors were found in Zone 1, with the exception of the first RTMS-X1 range bin located in Zone 2. The footprints of the wide-beam Whelen TDW-10 radar and Autoscope were also in Zone 2. Zone 3 overlaps Zone 1 and represents the area covered by the sidelooking RTMS-X1 microwave detector mounted on a pole on the north side of the freeway.

The inductive loops failed to operate properly throughout the Phoenix 1993 tests. The lead loop in lane 2 was affected the most and consistently registered false detections due to crosstalk between adjacent loops. The problem persisted in spite of trying many different types of loop amplifiers, adjusting the loop frequency and sensitivity settings, rechecking the electrical ground connections, and replacing the lead-in wire to the test trailer with premium quality shielded cable. Arizona DOT loop installation personnel spent a substantial amount of time attempting to ascertain the cause of the problem without success. The project was unable to obtain permission to close the freeway lanes and have the loops reinstalled.

10.12.1 Run 11090822

This was one of the first runs conducted at the Phoenix freeway site. The Autoscope VIP had not yet been installed. Vehicle counts were ground truthed for a 1-hour period between 9:00 and 10:00 a.m. for lanes 1 and 2 using the recorded video imagery. The results are shown in Table 10-8. The inductive loops and the Sumitomo SDU-300 ultrasonic detector vielded the best count accuracies in lane 1. All of the lane 1 detectors shown vielded at least 90-percent accuracies with the exception of the Eltec 842. This unit ceased to respond at all within 2 weeks from this date, so it may have been operating in an impaired state. Since the 842 was configured as a presence detector, the count accuracy suffered in high-volume applications due to the detector's long hold time.

Several detectors in lane 2 displayed good count accuracies. Both of the SPVD magnetometers and the Eltec 833 all achieved count accuracies greater than 99 percent, with the TDN-30 microwave detector and the SDU-300 ultrasonic detector close behind. The acoustic array overcounted by 21 percent. Since these tests, the sound processing algorithms in the acoustic detector have undergone a substantial amount of modification and the detector package size has been reduced considerably. The TC-20 Doppler microwave and the Eltec 842 passive infrared detectors undercounted by approximately 28 percent and 21 percent. respectively. This has been attributed to their relatively long hold times that cause undercounting in heavy traffic applications. Note that presence detection, and not vehicle counting, is the primary function of these detectors. Count accuracy could be vastly improved with a simple modification to the detector electronics that reduces hold time.



Zone		Lane 1		Lane 2	Lane 3		
	Symbol	Model	Symbol	Model	Symbol	Model	
1			A1	AT&T Acoustic Array			
			IR3	Eltec 833			
0	UЗA	MW Sensors TC-30C	υзв	MW Sensors TC-30C	IL1C-2	Inductive Loop	
	U2A	Sumitomo SDU-300	U2B	Sumitomo SDU-300			
	IL1A-2	Inductive Loop	IL1B-2	Inductive Loop			
	IR1	Schwartz 780D1000	MG2A-2	SPVD Magnetometer			
	IR2	Eltec 842					
1	IL1A-1	Inductive Loop	IL1B-1	Inductive Loop	IL1C-1	Inductive Loop	
	M4B	Whelen TDN-30	M4A	Whelen TDN-30			
	M2B	MW Sensors TC-26	M1A	MW Sensors TC-20			
	M6A-3	EIS RTMS (fwd-look)	MG2A-1	SPVD Magnetometer			
	U1	Sumitomo RDU-101					
2	VP1C	Autoscope 2003 VIP	VP1B	Autoscope 2003 VIP	VP1A	Autoscope 2003 VIP	
	M6A-2	EIS RTMS (fwd-look)	M5A	Whelen TDW-10			
3	M6A-5	EIS RTMS (side-look)	M6A-6	EIS RTMS (side-look)	M6A-7	EIS RTMS (side-look)	

Figure 10-33. Detection Zones on I-10 in Phoenix, AZ During Autumn 1993

	Lane 1		Lane 2					
Detector	Count	% Error	Detector	Count	% Error			
ILD 1	766	2.1	SPVD Mag 1	1025	-0.8			
ILD 2	789	5.2	SPVD Mag 2	1032	-0.1			
TDN-30	686	-8.5	ILD 1**	3030	193.3			
TC-30C	697	-7.1	ILD 2	944	-8.6			
780D1000	680	-9.3	TDN-30	1019	-1.4			
842*	590	-21.3	TC-20*	747	-27.7			
SDU-300	719	-4.1	833	1042	0.9			
			Acoustic Array	1251	21.1			
			SDU-300	1009	-2.3			
Ground Truth	750		Ground Truth	1033				

Table 10-8.	Vehicle	Counts	for	Run	11090822	on	Phoenix	Freeway
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Designed as a presence detector

* * Crosstalk between loops in the same lane on lanes 1 and 2

10.12.2 Run 11221359

The run commenced when traffic was moderate and continued through the time of peak traffic. The weather was mild and clear. Vehicle counts were ground truthed in postprocessing for the 4:00 to 5:00 p.m. interval.

Vehicle Counts vs. Time of Day

Figure 10-34 compares the vehicle counts from seven detectors in lane 2 at the Phoenix site with ground truth. All detectors, except the loops, appeared to perform within manufacturers' specifications. The poor performance of the loops at this site was traced to crosstalk between loops in the same lane. Therefore, this was the only site where the loops could not be relied on for accurate vehicle counts nor for the use of multipleloop speed traps. When the Phoenix site was revisited in the Summer 1994, only one loop was used in lanes 1 and 2, and the crosstalk problem was not encountered. The loops in lane 3 (the rightmost through-lane) did not experience crosstalk. Unfortunately, the detectors could not be moved over lane 3 because of the presence of a large variable message sign mounted on the sign-bridge structure.

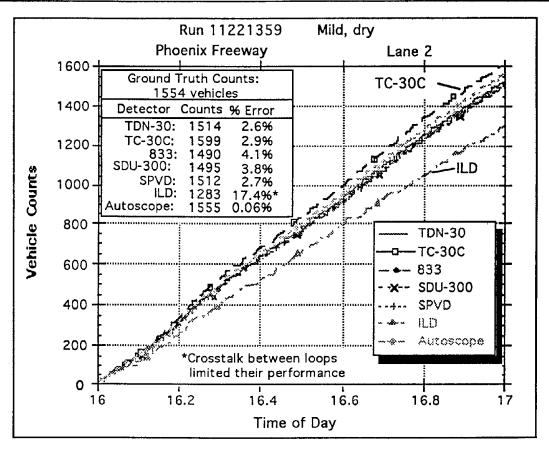


Figure 10-34. Comparison of Vehicle Count Data for Run 11221359 at Phoenix Freeway Site

Vehicle Flow vs. Time of Day

Figure 10-35 shows vehicle flow in lane 2 as calculated from the TC-30C and SDU-300 ultrasonic detectors and an SPVD magnetometer. Figure 10-36 shows vehicle flow in lane 2 based on data from the TDN-30 microwave detector, 833 passive infrared, and Autoscope 2003 video image processor. Two figures were used to show the flow data for the six detectors in order to make the individual curves more clear. The flows were computed based on 1-minute data integration intervals over a 1-hour period between 4 and 5 p.m. for which the ground truth vehicle counts were available. The result of using a 1-minute integration interval is a discrete. "spiky" curve. Shorter integration intervals, such as 30 seconds, produce flow values that reflect the microscopic movement of individual vehicles and thus may generate a curve that shows higher instantaneous flow rates. Short integration intervals may be

required when the maximum peak flow on a roadway is needed.

Detector count accuracy is also critical in applications requiring instantaneous traffic flows. In computing flow in units of vehicles per hour, the values for the flow are quantized in steps of 60 divided by the integration interval in minutes. Thus,

Instantaneous Flow =

$$\frac{n}{t_i} \times \frac{60 \text{ min}}{h} = \frac{60}{t_i} n \frac{\text{vehicles}}{\text{hour}} \quad (10-1)$$

where

n = number of vehicles in the integration interval

and

 t_i = integration interval in minutes.

For a 1-minute integration interval, each overcount or undercount of a vehicle equates to 60 vehicles per hour on the flow axis. Over a 5-minute integration interval, each vehicle represents 60/5 or 12 vehicles per hour in terms of flow. Hence, the shorter the integration interval, the greater the potential for variability in the computed traffic flow. However, on a percentage basis, the change in flow is the same as the change in vehicle counts. A detector that exhibits a consistent bias to either overcount or undercount could conceivably have its reported values adjusted by a correction factor in the software.

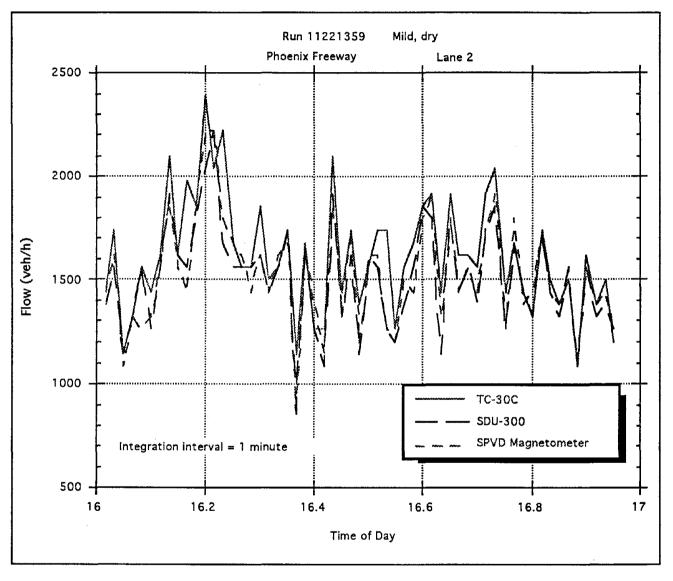


Figure 10-35. Vehicle Flow in Lane 2 Using Data From TC-30C, SDU-300, and SPVD Over 1-Hour Ground Truth Interval at Phoenix Site

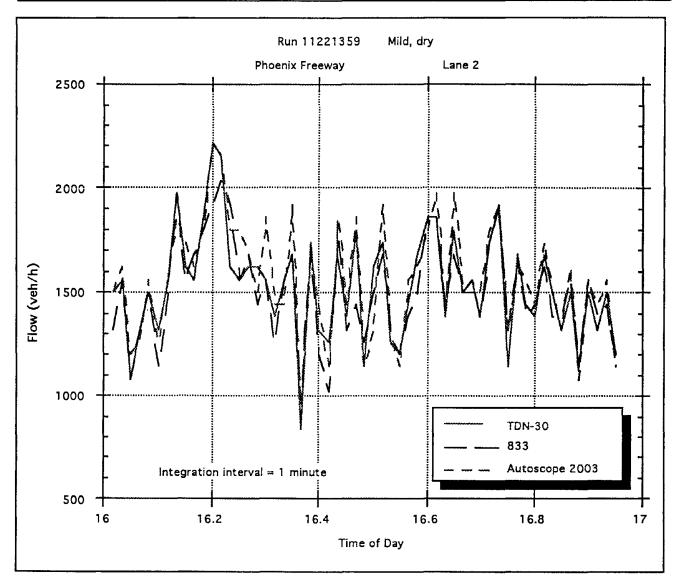


Figure 10-36. Vehicle Flow in Lane 2 Using Data From TDN-30, 833, and Autoscope 2003 Over 1-Hour Ground Truth Interval at Phoenix Site

Figure 10-37 shows flow versus time of day for three detectors located in lane 2 over the entire 3.5-hour run. The detectors represented are the TDN-30 microwave detector, SDU-300 ultrasonic detector, and the Autoscope 2003 video image processor. The flow was computed using a 5-minute data integration interval. If peak traffic flow information is required for a particular traffic management application, then a shorter integration interval that does not average the flow data as much should be used.

The three curves generally coincide except for a pronounced spike exhibited by the Autoscope

from about 3:00 to 3:10 p.m. Upon examining the database file from which the plots were drawn, it was found that the counts recorded from Autoscope detection zone 3 (downstream detection zone) on the data logger suspended temporarily. The rising edge of a pulse was received by the data logger (corresponding to a vehicle entering the Autoscope detection zone), but the falling edge of the pulse was not received for up to 51 seconds.

In total, eight separate detections, with presence times between 5 and 51 seconds, were reported over a 26-minute interval between 2:45 and 3:11 p.m. Six occurred

between 3:05 and 3:11. Seven of the eight detections occurred in lane 2 and one in lane 1. In each instance, the long presence values occurred for Autoscope zones 2 and 3 (the speed and downstream detection zones, respectively). Zone 1 (upstream detection zone) did not report long presence times. No presence times having the same duration were reported by the other detectors during this time period. Several vehicles were detected by other devices monitoring the same roadway segment during the times when Autoscope reported a single vehicle. The long presence values did not occur again during other time intervals in the run.

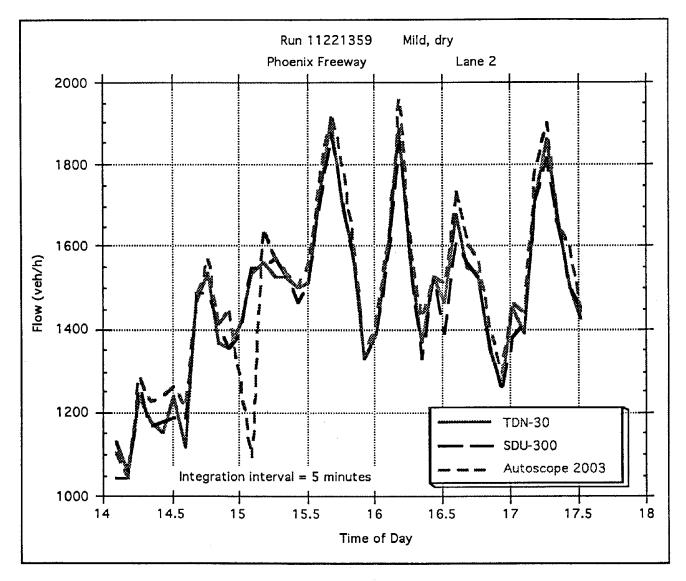


Figure 10-37. Vehicle Flow in Lane 2 for Run 11221359 at Phoenix Site

Figure 10-38 shows the data presented in Figure 10-37 fitted to a fifth-order polynomial. The discrete flow characteristics evident in Figure 10-37 are smoothed out by the curve fit. Fitting the data in this manner shows long-term traffic trends as opposed to the instantaneous flow.

Lane Occupancy vs. Time of Day

Figure 10-39 shows the lane occupancy for the same three devices represented in Figures 10-37 and 10-38 over the same approximate 3.5-hour period. Occupancy was computed as the sum of the vehicle presence times collected over a 5minute integration interval divided by the integration interval itself. This yielded the percentage of time that the detector was in the active state over the 5-minute interval. Plots are shown for both the individual calculated results and the fifth-order polynomial fit. The anomaly discussed with respect to Autoscope in Figure 10-37, which was manifested as low traffic flow, is seen here as a long presence time between 3:00 and 3:10 p.m.

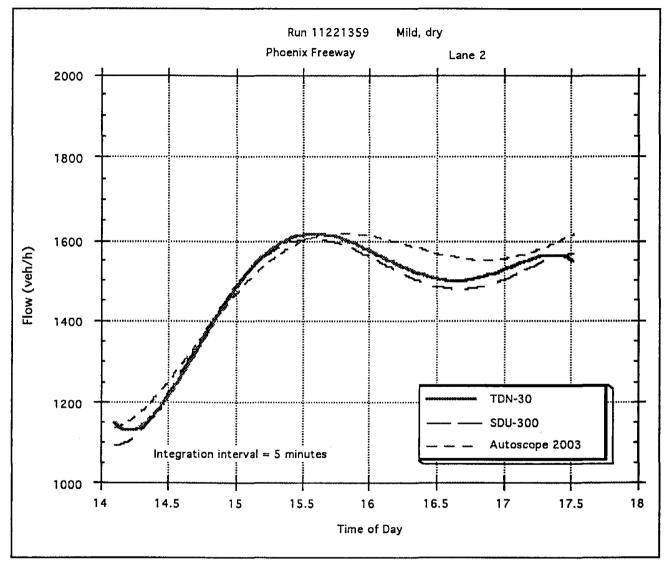


Figure 10-38. Lane 2 Vehicle Flow for Run 11221359 at Phoenix Site Fitted to Fifth-Order Polynomial

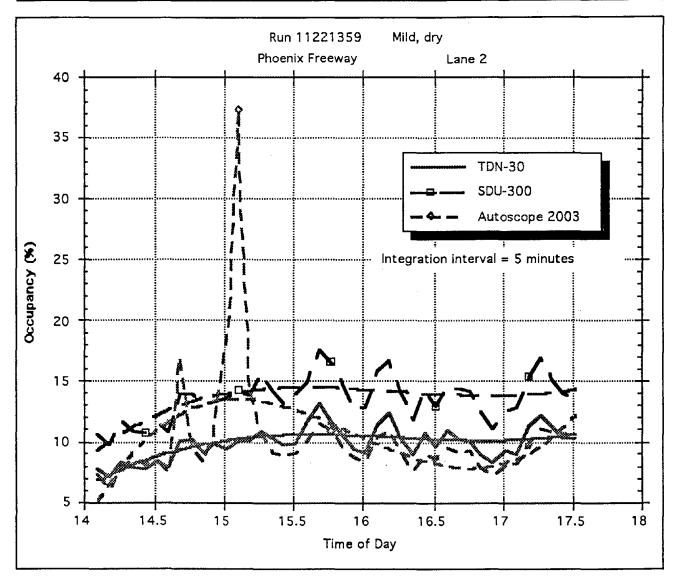


Figure 10-39. Lane 2 Occupancy for Run 11221359 at Phoenix Site Showing Curve Fit to Fifth-Order Polynomial and Unfitted Data

10.13 PHOENIX SUMMER 1994 FREEWAY DATA

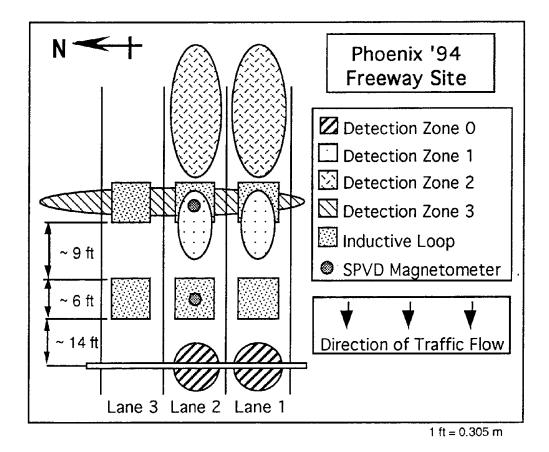
The Phoenix I-10 freeway site was revisited during the summer of 1994 in order to evaluate the performance of the detectors during the hot and dry desert weather. Since the AT&T acoustic array was not available during this period, only four detection zones were used.

The differences between the Autumn 1993 and Summer 1994 overhead detector configurations were as follows. The Eltec 833 passive infrared detector was pointed toward oncoming traffic in lane 2. The EVA 2000 video image processor monitored all three lanes of traffic and provided data through an RS-232 interface.

The detection zones and the detectors that they contained are shown in Figure 10-40.

10.13.1 Run 07281536

This run encompassed a variety of weather conditions over its approximate 4.5-hour duration. The temperature at the beginning of the session was greater than 100°F (37.8°C). High, gusty winds began blowing around 7:00 p.m., followed by thunderstorms. The video was ground truthed for a 1-hour



Zone		Lane 1		Lane 2		Lane 3
	Symbol	Model	Symbol	Model	Symbol	Model
0	U3A	MW Sensors TC-30C	U3B	MW Sensors TC-30C	IL1C-2	Inductive Loop
	U2A	Sumitomo SDU-300	U2B	Sumitomo SDU-300		
	IL1A-2	Inductive Loop	IL1B-2	Inductive Loop		
	IR1	Schwartz 780D1000	IR3	Eltec 833		
	IR2	Eltec 842	MG2A-2	SPVD Magnetometer		
1	IL1A-1	Inductive Loop	IL1B-1	Inductive Loop	IL1C-1	Inductive Loop
	M4B	Whelen TDN-30	M4A	Whelen TDN-30		
	M2B	MW Sensors TC-26	M1A	MW Sensors TC-20		
	M6A-3	EIS RTMS (fwd-look)	MG2A-1	SPVD Magnetometer		
	U1	Sumitomo RDU-101				
2	VP1C	Autoscope 2003 VIP	VP1B	Autoscope 2003 VIP	VP1A	Autoscope 2003 VIP
	M6A-2	EIS RTMS (fwd-look)	M5A	Whelen TDW-10		
3	M6A-5	EIS RTMS (side-look)	M6A-6	EIS RTMS (side-look)	M6A-7	EIS RTMS (side-look)

Figure 10-40. Detection Zones on I-10 in Phoenix, AZ During Summer 1994

period between 7:00 and 8:00 p.m. The following figures show the detector count accuracies referenced to these ground truth values.

Vehicle Counts vs. Time of Day

Figures 10-41 through 10-44 compare the accumulation of vehicle counts over time from several detectors with ground truth for lanes 1 and 2 of the westbound I-10 freeway. These plots group results from detectors occupying roughly coincident sensing areas. Figures 10-41 and 10-43 contain the counts for detector sensing areas in detection Zone 0 of lanes 1 and 2, respectively. Figures 10-42

and 10-44 give the lane 1 and 2 counts for detectors that have their sensing areas in detection Zones 1 and 2, respectively. The detection zones were defined in Figure 10-40.

The detectors represented in Figure 10-41 are the Schwartz laser radar, the Eltec 842 passive infrared detector, and the Sumitomo SDU-300 ultrasonic detector that view Zone 0 in lane 1. Both the laser radar and the ultrasonic detector agree with the ground truth value to within about 1 percent. The count from the 842 infrared unit falls off noticeably at around 7:45 p.m. The reason for this behavior has not been established.

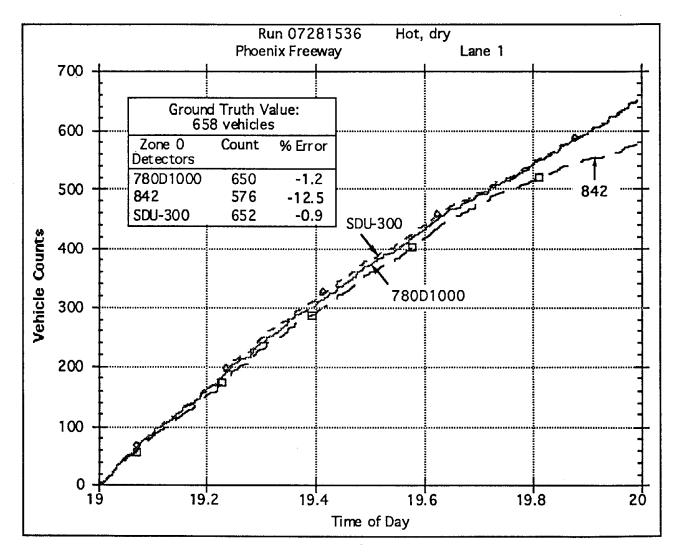


Figure 10-41. Detection Zone 0 Vehicle Counts with Ground Truth in Lane 1 Versus Time of Day at Phoenix 1994 Site

Figure 10-42 shows the count relationships among five detectors monitoring Zones 1 and 2 of lane 1. Represented are two RTMS truepresence microwave radars (one forward looking and the other side looking), an inductive loop, and the Autoscope 2003 and EVA 2000 video image processors. The 0.5-percent error attributed to the EVA VIP overstates the accuracy of the device during this run in that it overcounts until approximately 7:40 p.m. (or slightly after 19.6 hours) and then undercounts until the end of the run segment. Its total count converges toward the recorded ground truth value at the end of the 1-hour ground truth interval. The dip occurring shortly after 7:40 p.m. perhaps indicates an anomaly in the detection algorithms when they transition from daytime to nighttime operation.

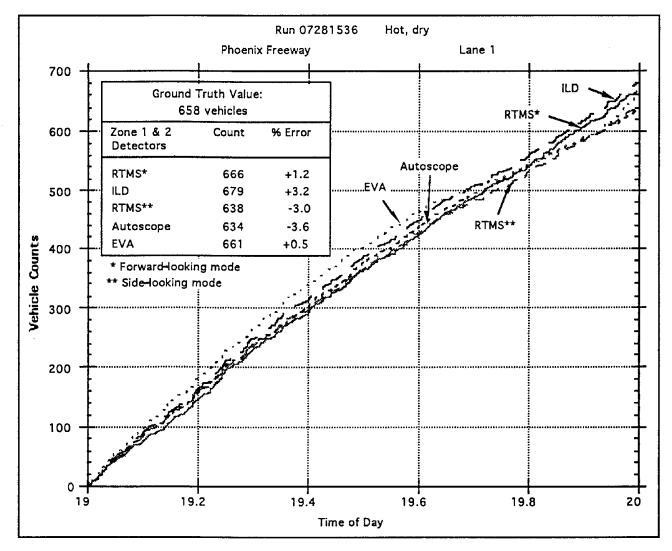


Figure 10-42. Detection Zones 1 and 2 Vehicle Counts with Ground Truth in Lane 1 Versus Time of Day at Phoenix 1994 Site

For optimum operation, EVA recommends that the camera mounting height be at least 33 feet (10.1 m) above the road surface. During our tests, the camera was 26-1/4 feet (8.0 m) above the road. Although camera mounting height affects speed measurement accuracy more than vehicle count, the less than optimum mounting height may have contributed to the behavior observed in the EVA count output.

Figure 10-43 gives vehicle counts for three detectors monitoring detection Zone 0 in lane

2. Represented in this graph are the Eltec 833 passive infrared detector, the Sumitomo SDU-300 ultrasonic detector, and the SPVD magnetometer. The count from the magnetometer was consistently low by 40 to 50 percent throughout the 1-hour period. An explanation for this anomaly could not be positively ascertained. It is thought that electromagnetic interference played a role in its degraded performance. The interference could have come from the lightning that accompanied the thunderstorm, or perhaps from radio transmissions in the area (the SPVD receiver does not operate in protected frequency bands). In any event, the less than optimum result seen here was transient in nature and better performance from the SPVD was observed in subsequent runs without any modification to the hardware.

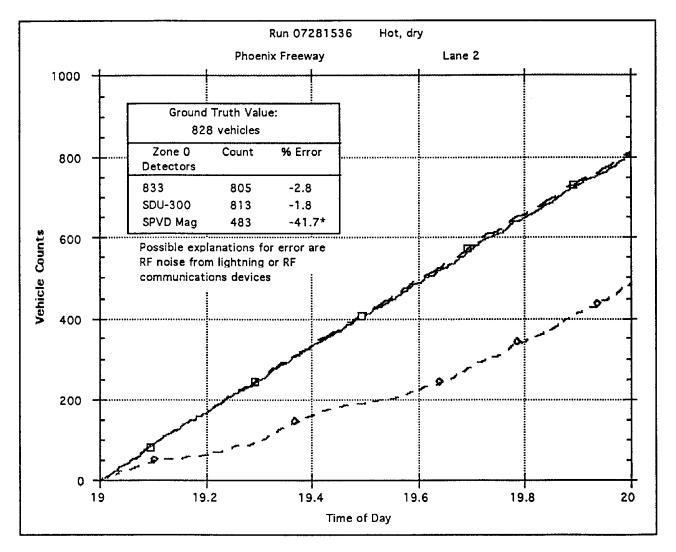


Figure 10-43. Detection Zone 0 Vehicle Counts with Ground Truth in Lane 2 Versus Time of Day at Phoenix 1994 Site

Figure 10-44 contains the counts for six detectors monitoring Zones 1 and 2 of lane 2. As in lane 1, the count from the EVA VIP begins to dip around 7:40 p.m., indicating that the unit is undercounting at night. The inductive loops overcount by approximately

3 percent in both lanes. This may be due to double-counting of tractor-trailer rigs. This postulate can be checked in future analyses by overlaying the loop counts on the video imagery and correlating the displayed counts with vehicle type.

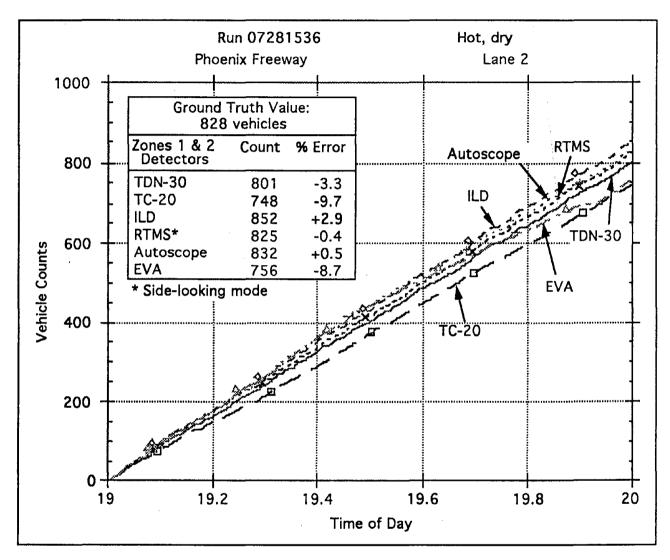


Figure 10-44. Detection Zones 1 and 2 Vehicle Counts with Ground Truth in Lane 2 Versus Time of Day at Phoenix 1994 Site

The vehicle counts from detection Zones 1 and 2 over the total run time are shown in Figures 10-45 and 10-46 for lanes 1 and 2, respectively. The purpose of these graphs is to examine the behavior of the EVA VIP over a longer time interval. Within the resolution of the scale, the EVA appears to overcount in lane 1 with respect to the RTMS in daylight and darkness, the overcount being 1.6 percent over the approximately 5-hour run duration. In lane 2, the EVA overcounts until approximately 8:30 p.m. and then undercounts for the

rest of the run with respect to the RTMS. In this lane, the total undercount was 3.2 percent. If the run time had been shorter, the overcount in lane 1 attributed to the EVA would be greater, and the undercount in lane 2 would change to an overcount.

The RTMS was used as the basis for count comparison in this discussion because it appeared to be the most accurate vehicle count detector during the run as deduced from the ground truth results.

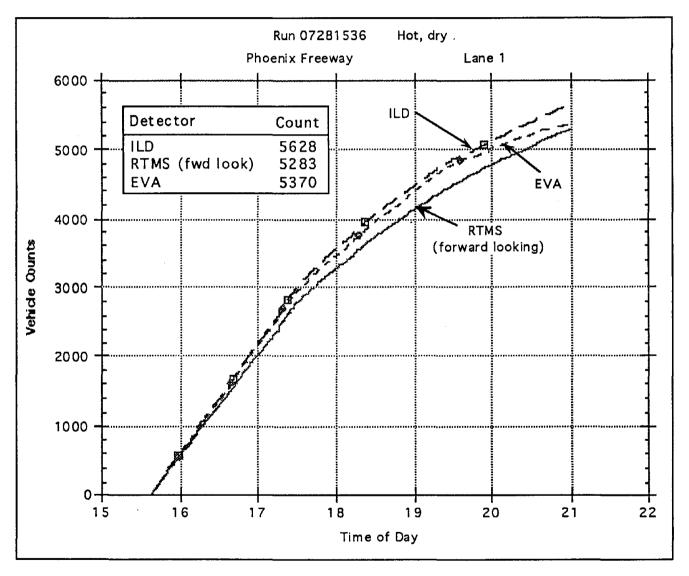


Figure 10-45. Vehicle Counts in Detection Zones 1 and 2 of Lane 1 for Entire Duration of Run 07281536 at Phoenix 1994 Site

Generate Field Test Results

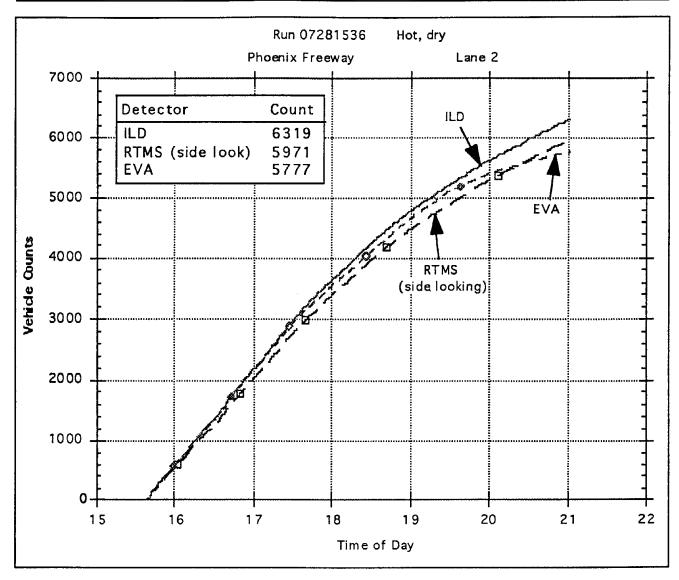


Figure 10-46. Vehicle Counts in Detection Zones 1 and 2 of Lane 2 for Entire Duration of Run 07281536 at Phoenix 1994 Site

10.13.2 Run 08041552

This run was characterized by intense dry heat (109°F [42.8°C] at the beginning of the run). The duration of the session was slightly more than 5 hours. Ground truth was obtained for a 1-hour period during the run, 5:00 to 6:00 p.m., by manually counting vehicles appearing in the recorded video imagery. The percentage errors listed in Table 10-9 are referenced to these ground truth values.

Vehicle Counts vs. Time of Day

Vehicle counts accumulated by the detectors over the 1-hour ground truth period were compared with the values recorded from the video imagery by a human observer. Nearly all of the detector count accuracies analyzed in this run were worse than those corresponding to the windy and stormy conditions evident in Run 07281536 as reported in Section 10.13.1. The inductive loops performed in a manner consistent with the results seen in earlier analyses of data from the Phoenix freeway site. Their tendency to overcount with respect to the observed ground truth data lends credence to the likelihood that the loops were double-counting tractor-trailer rigs. The side-looking RTMS measured detections to within a single count of the ground truth in lane 2, although the lane 1 results are inferior to those presented in 10.13.1. One notable change from Run 07281536 was the recovery of the SPVD magnetometer, which showed an undercount of 3.8 percent after the anomalous behavior exhibited during the run reported in 10.13.1.

L	ane 1		Lane 2				
Detector	Count	% Error	Detector	Count	% Error		
TDN-30	1201	-8.1	TDN-30	1331	-4.9		
TC-30C	529	-59.5	TC-30C	138	-90.1		
TC-26	1271	-2.8	TC-20	770	-45.0		
780D1000	1267	-3.1	833	1324	-5.4		
842	1162	-11.1	SDU-300	1333	-4.7		
SDU-300	1233	-5.7	SPVD Mag	1346	-3.8		
RTMS-X1 1 (fwd)	1170	-10.5	ILD	1447	+3.4		
RTMS-X1 2 (fwd)	1271	-2.8	RTMS-X1 (side)	1400	+0.1		
ILD	1341	+2.6	Autoscope 1	1336	-4.5		
RTMS-X1 (side)	1184	-9.4	Autoscope 2	777	-44.5		
Autoscope 1	1010	-22.7	Autoscope 3	1268	-9.4		
Autoscope 2	479	-63.4	EVA	1378	-1.5		
Autoscope 3	1218	-6.8					
EVA	1281	-2.0					
Ground Truth	1307		Ground Truth	1399			

Table 10-9. Vehicle Counts for Run 08041552 on Phoenix Freeway

10.14 TUCSON SURFACE-STREET DATA

The Tucson surface-street site was located at the southwest corner of Oracle Road and Auto Mall Drive. The detector layouts are shown in Figure 9-47. Four groups of detection zones in two lanes of traffic were present as illustrated in Figure 10-47. Zone 0 was dedicated to detectors oriented at or near nadir.

The detectors in Zone 1 were the lead square loops in each of the two instrumented lanes and the forward-looking RTMS-X1, Whelen TDN-30, and Eltec 842 in lane 2. The 842 was physically mounted over lane 3, but was side-looking into lane 2 per the manufacturer's suggestion. In lane 3 (curb lane) were the lead SPVD magnetometer, Sumitomo RDU-101, Whelen TDN-30, and Microwave Sensors TC-26.

Zone 2 corresponded to the area monitored by the side-looking RTMS-X1 true-presence microwave radar. An array of three-axis fluxgate magnetometers that were used to record analog vehicle signatures were buried in the roadway midway between the two pairs of square loops.

Detection Zone 3 contained the sensing area for the second square loop in each lane, as well as the second magnetometer and Autoscope 2003 VIP and Grumman passive imaging infrared VIP in lane 3. Beyond the square loops in lane 3 were a pair of 6-foot (1.8-m) diameter round loops. Two 3M microloop probes were placed in each of lanes 2 and 3, midway between the two round loops as shown in Figure 10-47. Other detectors in lane 2 of Zone 3 included the second range bin from the forward-looking RTMS-X1 and the Autoscope 2003 VIP.

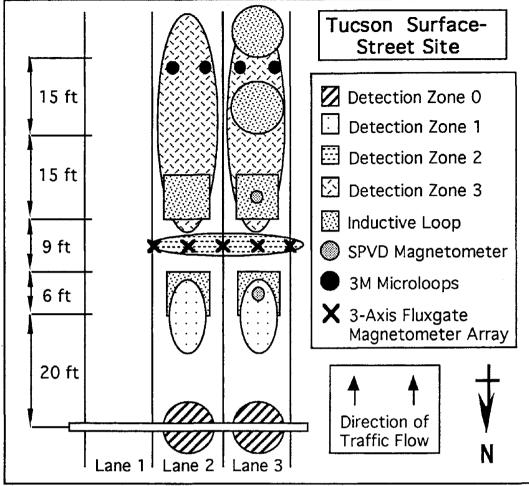
10.14.1 Run 03101008

This run was conducted with a special purpose in mind. It was hoped that the detectors would be tested in Minnesota under conditions that provided a significant amount of accumulated snow on the vehicles. Due to the absence of the desired weather conditions, it was decided to simulate these conditions in Tucson by attaching 1- and 2-inch (25.4- and 50.8-mm) sheets of styrofoam to the top of a probe vehicle and driving it repeatedly through one of the instrumented lanes that had been closed to normal traffic.

The styrofoam was applied in 1-, 2-, and 3-inch (25.4-, 50.8-, and 76.2-mm) thicknesses to determine its effect on vehicle detection. Of particular interest was the response of the microwave, ultrasonic, and infrared detectors to the styrofoam. It was postulated that the irregular surface of the layer may scatter or absorb a portion of the transmitted energy or modify the emitted energy, causing the detector to miss the vehicle. The results in Table 10-10 indicate otherwise. The TC-30C detected the styrofoam-covered probe vehicle in all of the passes, as did the other two overhead detectors examined, namely the 780D1000 laser radar and TDN-30 Doppler microwave detector. Detections were also tabulated for a pair of inductive loops that were not affected by the styrofoam addition to the top surface of the vehicle.

There were some other anomalies recorded during these drive-throughs. The second inductive loop failed to detect the probe vehicle on one occasion and double-counted the International S1600 bucket truck on another. The ultrasonic detector double-counted twice, once on a minivan and once on a police motorcycle. If this pattern held throughout the Tucson tests, one would expect the ultrasonic detector to produce vehicle counts that are consistently high with respect to the ground truth. To the contrary, the TC-30C tended to undercount slightly. It is possible that the ultrasonic detector picked up the presence of test personnel wandering through its detection zone after the passage of the target vehicle during the controlled drivethroughs. This cannot be ascertained from the video imagery as the TC-30C's detection zone is not within the field of view of the video camera.

The laser radar failed to detect three of the five passes made by tall bucket trucks, while having no problem with any other vehicles, including the motorcycle. The radar detector manufacturer did not attribute the missed truck detections to its large height. The reason for this anomaly is not known.



1 ft = 0.305 m

Zone		Lane 2	Lane 3			
	Symbol	Model	Symbol	Model		
0	U2B	Sumitomo SDU-300	U2A	Sumitomo SDU-300		
	U3B	MW Sensors TC-30C	U3A	MW Sensors TC-30C		
	IR3	Eltec 833	IR1	Schwartz 780D1000		
			A1	AT&T Acoustic Array		
1	IL1A-1	Inductive Loop	IL1B-1	Inductive Loop		
	M6A-2	EIS RTMS (fwd-look)	MG2A-1	SPVD Magnetometer		
	M4A	Whelen TDN-30	U1	Sumitomo RDU-101		
	IR2	Eltec 842	M4B	Whelen TDN-30		
			M2B	MW Sensors TC-26		
2	M6A-3	EIS RTMS (side-look)	M6A-2	EIS RTMS (side-look)		
3	IL1A-2	Inductive Loop	IL1B-2	Inductive Loop		
	M6A-3	EIS RTMS (fwd-look)	MG2A-2	SPVD Magnetometer		
	IL1A-3	3M Microloop	IL1B-3	3M Microloop		
· ·	VIP1A	Autoscope 2003 VIP	IL1C-1	Inductive Loop (Round)		
	M1A	MW Sensors TC-20	IL1C-2	Inductive Loop (Round)		
	M5A	Whelen TDW-10	VIP1B	Autoscope 2003 VIP		
			IIR-1	Grumman Imaging IR VIP		

Figure 10-47. Detection Zones on Oracle Road Site in Tucson, AZ

1 in = 25.4 mm

Event	Tape Index	Vehicle	Styrofoam	Ve	hicle	Detec	ted (Y/N)
Number	Number	Туре	Thickness	ILD1	ILD2	IR1	M4B	U3A
1	1890	Int'l S1600 Truck	N/A	Y	Y	Y	Y	Y
2	2284	Int'l S1600 Truck	N/A	Y	Y(x2)	Y	Y	Y
3	2288	Chevrolet Corsica	N/A	Y	Y	Y	Y	Y
4	2422	Dodge Caravan	N/A	Y	Y	Y	Y	Y(x2)
5	2526	Int'l S1600 Truck	N/A	Y	Υ	Ν	Y	Y
6	2788	Int'l S1600 Truck	N/A	Y	Y	Ν	Y	Y
7	3158	Kawasaki Motorcycle	N/A	Y	Y	Y	Y	Y(x2)
8	5731	Boyertown Truck	N/A	Y	Y	N	Y	Y
9	7062	Corsica w/ Styrofoam	2 "	Y	Υ	Y	Y	Y
10	7344	Corsica w/ Styrofoam	2 "	Y	Y	Y	Y	Y
11	7428	Corsica w/ Styrofoam	2 "	Y	N	Y	Y	Y
12	9287	Corsica w/ Styrofoam	3 "	Y	Y	Y	Y	Y
13	9414	Corsica w/ Styrofoam	3 "	Y	Y	Y	Y	Y
14	9642	Corsica w/ Styrofoam	3 "	Y	Y	Y	Y	Y
15	10119	Corsica w/ Styrofoam	1 "	Y	Y	Y	Y	Y
16	10181	Corsica w/ Styrofoam	1 "	Y	Y	Y	Y	Y
17	10349	Corsica w/ Styrofoam	1"	Y	Y	Y	Y	Y
18	10847	Corsica w/o Styrofoam	0 "	Y	Y	Y	Ŷ	Y
19	10973	Corsica w/o Styrofoam	0 "	Y	Y	Y	Y	Υ

Table 10-10.	Vehicle	Drive-Throughs	in	Lane	3	of	Tucson	Site	
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N/A = not applicable

10.14.2 Run 04121633

This run is representative of a typical evening rush hour. The session commenced at 4:33 p.m. and continued until approximately 9:15 p.m. This ensured that a light-to-dark transition occurred while the data collection was in process. The lighting change stresses the performance of the video image processors under daytime and nighttime conditions as well as the lighting transition period. The results shown in Figures 10-48 and 10-49 compare vehicle counts in the middle and curb lanes, respectively, for Doppler and truepresence microwave radars, ultrasonic detectors, video image processors, and magnetometers. Ground truthing indicated that the loop counts are accurate to approximately 1 percent as explained further under Comparison of Video Image Processor Counts at the end of this section.

Since the footprints of the various detectors are not necessarily coincident, vehicles moving from one lane to another may register counts on detectors in each of the two lanes. This problem can be particularly troublesome during the north-south red signal phase. During this time, the straight-through traffic on southbound Oracle Road is stopped north of the intersection, while right turns are made from Auto Mall Drive onto southbound Oracle. Left turns (from two lanes) are also made from the Tucson Mall onto southbound Oracle. These turning movements were seldom confined to a single lane, that is, vehicles tended to sweep out across multiple lanes of traffic on southbound Oracle Road during the completion of these turns. For example, a vehicle turning left from the Tucson Mall onto southbound Oracle may begin its turning movement by crossing over the middle lane (lane 2), thus tripping the detectors in that lane that have a steep incidence angle. The

vehicle can then complete its turning movement by entering the curb lane (lane 3) and registering counts for the detectors having detection zones further down the curb lane. While none of these vehicle detections was actually "invalid," the result is that apparent errors are introduced when count accuracies are assessed, because it is difficult to manually locate and observe the detection zones that are activated in each lane by the vehicles during the ground truth process.

This problem can be treated in three different ways. First, the assumption can be made that these anomalies will cancel each other out, i.e., the errors incurred as the result of the left-turn movements will be negated by the errors introduced by the right-turn movements. Second, plots can be grouped by detectors having similar detection zone locations, i.e., detectors looking straight down or at a steep angle of inclination can be compared to one another, while those that detect traffic further down the lane can be compared against one another. The third approach is somewhat more involved. An attempt can be made to filter out the vehicle detections that result from turning movements, thus allowing only the vehicles that pass during the north-south green signal phase to be considered as valid detections. This does not completely eliminate the detection of turning vehicles (some vehicles will make right turns against their red), but the number will certainly be much less and the turns will be more likely to be confined to a single lane. This filtering process was performed for the graphs shown in Figures 10-46 through 10-49 using GP_COUNT.FOR (the name stands for green-phase count).

Vehicle Counts vs. Time of Day

Figure 10-48 provides a comparison of vehicle counts for six different detectors (two passive infrared devices, two microwave presence radars, a video image processor, and an inductive loop) in the middle lane (lane 2) of traffic. Since the loops in Tucson appeared accurate to within approximately 0.5 percent (see *Comparison of Video Image Processor Counts* in the next section for the loop count error analysis), the count from the second square inductive loop in lane 2 was used as pseudo-ground truth, with which the counts

from the other detectors were compared. This is illustrated by the percentage difference calculation in the plots. The forward-looking RTMS microwave radar was the most accurate, having a percentage difference of 0.07 percent as compared to the loop count, over the entire duration of this particular run. The Eltec passive infrared detectors had accuracies greater than 96 percent.

Figure 10-49 shows curb lane (lane 3) results from the same run. Here the count from the first square inductive loop was used as pseudo-ground truth, with which the counts from the other detectors were compared. (The counts from the two square loops in the lane were within 1 percent of each other.) The plot contains data from the 780D1000 laser radar, TDN-30 Doppler microwave detector, SDU-300 ultrasonic detector, SPVD magnetometer, Autoscope 2003 video image processor, and inductive loop. The Whelen TDN-30 performed best in this lane, with its count being within 0.8 percent of that measured by the loop. All detectors had count accuracies of 6 percent or better.

Comparison of Video Image Processor Counts

Three visible-spectrum and one infrared video image processors were fielded during the Tucson field tests. The visible spectrum VIPs were the Autoscope 2003, Traficon CCATS-VIP 2, and Sumitomo IDET-100. Each of these was configured to provide data from the middle through-lane and the curb lane (lanes 2 and 3, respectively). The Grumman infrared VIP was set up with detection zones in all three lanes, but they were located some 120 feet (36.6 m) downstream from the mast arm on which the overhead detectors were mounted. The Grumman VIP also had a fourth detection zone that coincided with the second round loop in lane 3.

It is difficult to compare the performance of the VIPs over time intervals on the order of tens of seconds or minutes due to the lack of standardization of their data output intervals as shown in Table 10-11. For example, the IDET-100 outputs vehicle detections and computed speeds on a per vehicle basis via a serial communications interface, while the CCATS-VIP 2 outputs results accumulated over 5-second integration intervals (also via an RS-232 interface). The serial interface

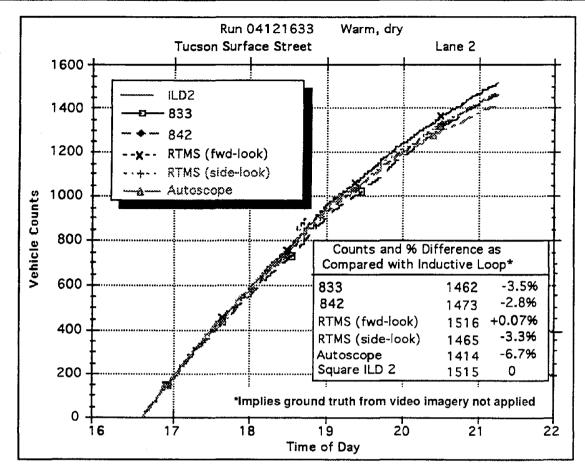


Figure 10-48. Comparison of Vehicle Counts From Six Detectors on Lane 2 of Tucson Street Site

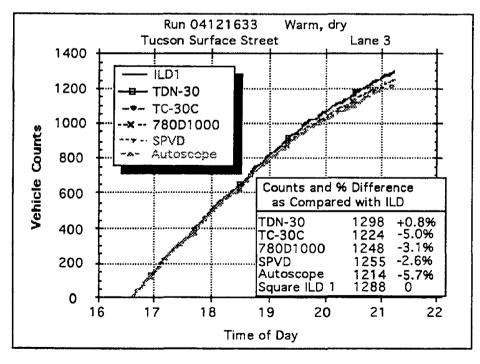


Figure 10-49. Comparison of Vehicle Counts From Six Detectors on Lane 3 of Tucson Street Site

protocol for the Autoscope was not available for the field tests. Thus, the only data recorded from the Autoscope was from the outputs of the optically isolated transistors that corres-ponded to the passage of a vehicle. In order to compare the outputs from these VIPs, the data must be integrated (during post-processing) over an interval equal to the least common multiple of the collection intervals used by the devices in the comparison group.

Table 10-11. Data and Update Intervals in Detector	s With	RS-232	Interfaces
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Detector	Update Interval	Count	Lane Occ.	Speed	Vehicle Type ^b
Whelen TDN-30 & TDW-10 Doppler Detectors	per vehicle	~		v	
EIS RTMS-X1 True-Presence Microwave Radar	10 seconds to 10 minutes ^a	~	~	~	
Econolite Autoscope 2003 VIP ^c	10 s to 1 h	~	~	~	 ✓
CRS Traffic Analysis System VIP	1 minute	~	~	~	v
Traficon CCATS-VIP 2	5 seconds	~		~	 ✓
Sumitomo IDET-100 VIP	per vehicle	~		~	~
EVA 2000 VIP	per vehicle	~	~	~	~
Grumman Infrared VIP	1 second	~		~	

^a User selectable in 10-s increments. Update interval set to minimum value of 10 s in field tests.

^b Based on user-selected vehicle lengths.

^c Autoscope serial data were not made available during the field tests.

Figures 10-50 and 10-51 show comparisons of the accumulated vehicle counts as output by the video image processors in lanes 2 and 3, respectively. The second square inductive loop in each lane was used as the count reference.

The count accuracy is difficult to analyze at this site due to the anomalies created by the tendency of vehicles to sweep out across multiple lanes when completing left or right turns onto southbound Oracle Road. A 1-hour time window was ground truthed for lanes 2 and 3 and compared to the counts reported by several detectors. The counts from the second inductive loop in each lane were approximately 2.5 percent higher than the observed ground truth. However, the decision to manually record a vehicle passage as a count was a judgment call on the part of the observer. Vehicles completing their turns may have passed through enough of a detector's sensing area to trigger a response. but may not have been recorded by the observer. The observer was deliberately conservative in his determination of what

constituted a detection and fully expected the detector outputs to be somewhat higher.

In the analyst's opinion, the second loop in each lane represents the vehicle count to within an error of no more than 1-percent of the actual number of vehicles traversing its detection zone. The 1-percent number is judged to be a better representation of the error, as compared to the 2.5-percent value, since some vehicles detected by the loop were purposely not counted by the analyst. This judgment is supported by the fact that counts are high by the same percentage in each lane with respect to the analyst's ground truth values. Also lending credence to the lower 1-percent count error for the loops is the close agreement among the counts given by the loops in lane 3 as seen in Figure 10-51. The second square inductive loop reported a total count of 1600 vehicles collected over nearly 5 hours. The first round loop located 15 feet (4.6 m) downroad from the second square loop reported 1603 vehicles, and the second round loop located another 15 feet (4.6 m) downroad reported 1608. The locations of

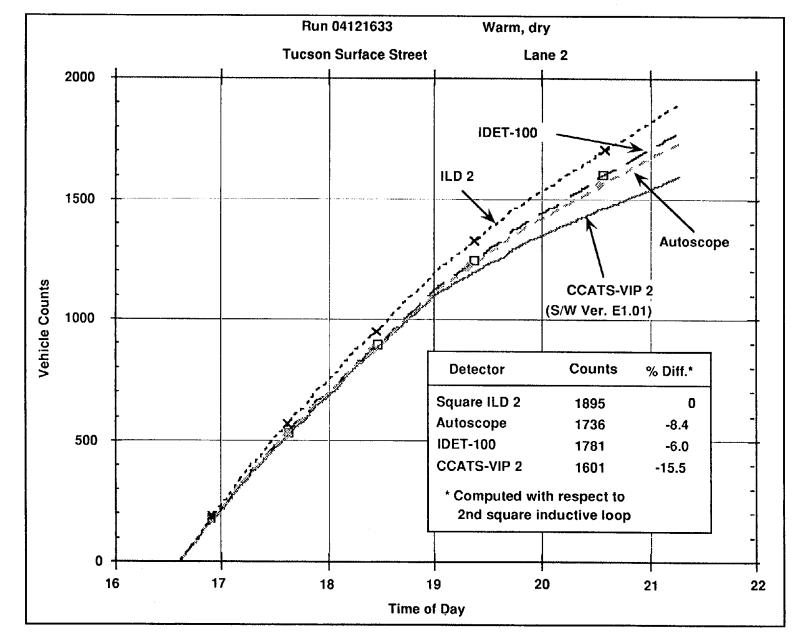


Figure 10-50. Comparison of Vehicle Counts in Lane 2 from VIPs in Run 04121633 at Tucson Site

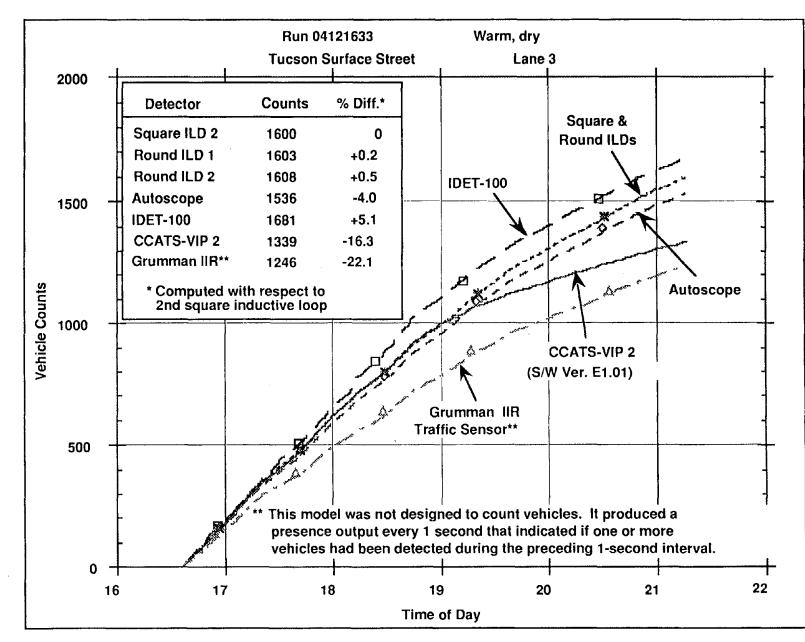


Figure 10-51. Comparison of Vehicle Counts in Lane 3 from ILDs and VIPs in Run 04121633 at Tucson Site

these three in-road detectors were well downstream and less susceptible to the maneuvering problems discussed previously. For these reasons, the counts represented in Figures 10-50 and 10-51 are compared with the outputs given by the second square inductive loop in lanes 2 and 3, respectively.

The vehicle counts from the CCATS-VIP 2 fall off from the others when darkness occurs. This is due to the particular algorithm in software version E1.01 supplied with the CCATS-VIP 2 that was tested. The algorithm was not able to distinguish all the darkcolored vehicles from the dark background. This phenomenon was observed in the field when viewing the television monitor that showed the traffic flow and the overlaid vehicle counts displayed by the VIP. The algorithm was written to prevent shadows from being recognized as vehicles. Traficon has since developed software version 2, which they claim increases the count between 9 and 20 percent, depending on the conditions of the run.

Zone 4 (overlapping the second round loop in lane 3 as shown in Figures 9-50 and 9-51) of the Grumman imaging infrared traffic sensor undercounted by 22 percent as compared to the second square loop. However, this particular model of the imaging infrared traffic sensor was not designed to count individual vehicles. It was designed to give a presence output every 1 second if one or more vehicles was within its detection zone in the preceding 1-second interval. Thus, if two or more vehicles passed through the detection zone in an interval, only one event would be registered by the sensor. From observation of the traffic flow, it appeared that multiple vehicles did pass through the sensor's detection zone during some of the 1-second intervals. Future analysis can verify the more than one vehicle per reporting interval hypothesis by overlaying the vehicle detections onto the video ground truth imagery and examining the correlation of reported and actual events. If the sensor consistently detects the first of two closely spaced vehicles but misses the second, this would indicate that the undercount is indeed due to the particular way the data are processed in the internal algorithms of the sensor. The crisp infrared imagery displayed on the television monitor

appears to produce good thermal contrast between the vehicles and the background during day and night operation. This indicates that there is sufficient information in the image to recognize individual vehicles.

10.14.3 Run 04131703

This run occurred the evening following the run discussed in the previous section. It was selected for analysis to assess the repeatability of the trends observed in the performance of the video image processors in Run 04121633. Count accuracies were computed relative to the counts recorded from the second inductive loop in lanes 2 and 3 as before. The session began just after 5:00 p.m. and continued for approximately 4 hours.

Comparison of Video Image Processor Counts

The performance of the four video image processors (three visible band and one infrared) is consistent with results presented in Section 10.14.2. Figure 10-52 shows the cumulative vehicle counts for the three visible wavelength VIPs and the second inductive loop in lane 2. These VIPs undercounted, with respect to the loop, by approximately 7 to 10 percent until about 7:00 p.m. as compared with undercounts of 6 to 8 percent the night before. After 7 p.m., the percentage differences between the Autoscope and IDET-100, as compared to the inductive loop, remained fairly constant for the remainder of the run. However, the CCATS-VIP 2 began to miss more vehicle detections after 7:00 p.m. as nighttime darkness occurred. The CCATS reported 18.9 percent fewer counts than did the loop in this run and an undercount of 15.5 percent in the previous night's run.

Figure 10-53 shows lane 3 count results from the visible spectrum VIPs represented in the lane 2 plot, as well as from the Grumman Traffic Sensor imaging infrared VIP and the two round inductive loops. The three loops (the second square loop and the two round loops) reported counts within 0.5 percent of each other. The Autoscope count was 5.1 percent below that reported by the second square loop. This result is consistent with the 4-percent undercount from the previous night's run. Similarly, the IDET-100 overcounted by 6.4 percent as compared to 5.1 percent the night before. Again, the counts from the CCATS decreased after 7:00 p.m. The unit reported 23.2 percent fewer counts than the loop, as compared to 16.3 percent from Run 04121633. The Grumman imaging infrared sensor undercounted by 19.5 percent, compared to 22.1 percent recorded in the previous night's run. As explained earlier, the Grumman algorithm evaluated in the field tests was not designed to count vehicles, but rather to give a presence output every 1 second if one or more vehicles were within its detection zone in the preceding 1-second interval.

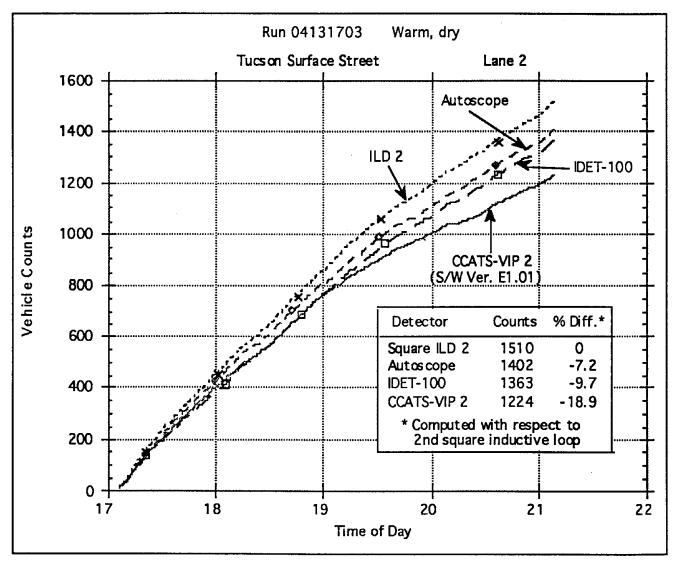


Figure 10-52. Comparison of Vehicle Counts in Lane 2 from VIPs in Run 04131703 at Tucson Site

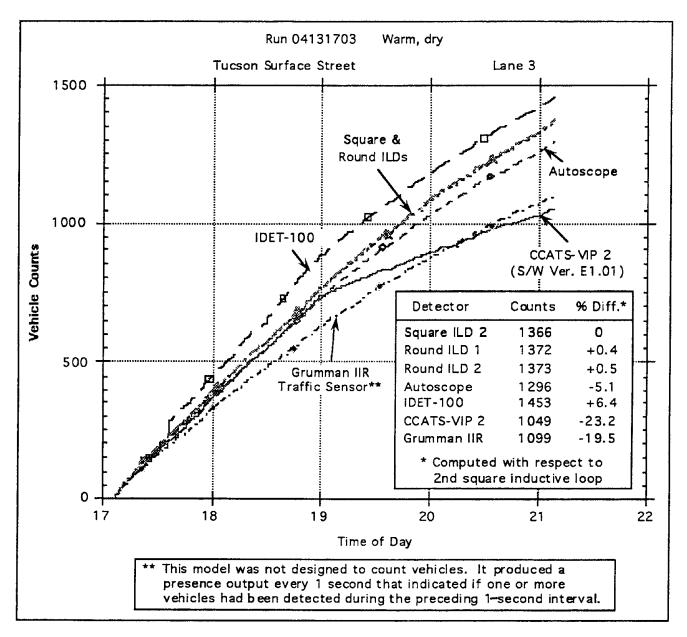


Figure 10-53. Comparison of Vehicle Counts in Lane 3 from ILDs and VIPs in Run 04131703 at Tucson Site

11. TASK I

DETERMINE WHICH OF THE CURRENTLY AVAILABLE DETECTORS MEET THE IVHS SPECIFICATIONS OF TASK A

Accuracies for traffic parameters that support future applications of signalized intersection control, freeway incident detection and management, and freeway metering control were presented in Section 2. Not all of the parameters can be addressed based on the results of the *Detection Technology for IVHS* field tests. Among the information that can be evaluated at this time are data relating to vehicle counts, speed, and, to some extent, presence.

Several flow requirements are listed in the Traffic Parameter Specifications tables in Section 2. In the signalized intersection control, freeway incident detection and management, and freeway metering control applications, the allowable error for measuring traffic flow is ± 2.5 percent at 500 vehicles per hour per lane. The data collection intervals vary by the period over which control of the traffic is exercised, namely, tactical, strategic, or historic.

For the postulated 20-second data collection interval for tactical control, an error of 0.07 in vehicle count for every 2.8 vehicles is implied at a flow of 500 vehicles per hour. Practically, this means that all vehicles must be detected during each 20-second interval. While no detector guaranteed 100-percent detection accuracy, some did perform with less than 1-percent error. Video image processors that use the detection zone approach to loop emulation can increase their detection accuracy by placing multiple zones in critical areas of the roadway.

For a 5-minute data collection interval typical of strategic control, the acceptable error is one vehicle count for every 41.7 vehicles at the specified flow rate. This requirement seems to be within the capability of currently available commercial technologies. As the data collection interval increases, as in the gathering of historic data, larger errors in count are acceptable (e.g., error of 3.1 in count for every 125 vehicles for a 15-minute interval and an error of 12.5 in count for every 500 vehicles during a 1-hour interval).

While inductive loops are probably the most consistently accurate detectors for vehicle counting applications currently available, several other candidates show a great deal of promise. Among them are video image processors, magnetometers, and microwave detectors. These technologies, as well as the ultrasonic, infrared, and acoustic devices, will continue to mature as they are deployed in support of new applications. Many of these technologies have only been applied to traffic management applications for a short time and will continue to improve as they gain acceptance and are used within the industry.

Unfortunately, many manufacturers cannot afford to develop their technology further without assurances, in the form of buy orders, from the traffic management community that a tangible market for their product exists.

The speed measurement requirement varies by application. Freeway metering control has the most relaxed accuracy of the applications that were studied, namely a mainline speed measurement accuracy of $\pm 5 \text{ mi/h}$ ($\pm 8.0 \text{ km/h}$) over a speed range of 0 to 80 mi/h (0 to 129 km/h). The data collection intervals for tactical, strategic, and historic collection periods are 20 seconds, 5 minutes, and 15 minutes or 1 hour, respectively. Signalized intersection control is postulated to have a future speed measurement requirement of $\pm 2 \text{ mi/h}$ (3.2 km/h) and a freeway incident detection requirement of $\pm 1 \text{ mi/h}$ (1.6 km/h).

Currently available Doppler microwave detectors are able to support the 5-mi/h (8.0-km/h) speed accuracy requirement on a per vehicle basis. The data collection interval can be under the control of the microprocessor that accumulates the data in the traffic

controller or traffic management center. Doppler detectors, however, cannot detect stopped or slow (nominally below 3 to 5 mi/h [4.8 to 8.0 km/h] traffic. The future and as vet in-development algorithms for signalized intersection control and freeway incident detection raise the speed measurement accuracy requirement further. The ± 1 -m/h (1.6-km/h) accuracy is beyond the current state of the art of most detectors. If the importance of zero speed measurement during bumper-to-bumper traffic conditions is not critical to the execution of the traffic control algorithm, as when a lower speed threshold greater than 3 to 5 mi/h (4.8 to 8.0 km/h) is set, then the Doppler detectors will suffice. If speeds less than 3 to 5 mi/h are needed, improved video image processors and truepresence microwave radars or laser radars may have to be used.

Vehicle presence is an important parameter in signalized intersection control. Although it is difficult to compare the actual presence times from detector to detector because of differences in hold time and sensing area, it is intuitively possible to correlate vehicle presence with vehicle count. That is, as a vehicle is counted, it can be assumed that the presence of the vehicle is also detected. although no inference about the length of the presence time can be made. If the assumption about vehicle presence and vehicle count correlation is valid, then those detectors having the most accurate counts will also provide the most accurate presence in terms of identifying that a vehicle is within the sensing area of the detector.

12. CONCLUSIONS

One of the goals of the field tests and subsequent data reduction was to ascertain the relative performance of various detector technologies in different traffic and climatic conditions. These results are useful for assessing the applicability or suitability of particular types of technology to specific traffic management applications. The assessments were made with respect to only detector performance and not cost. Cost considerations must be traded off by the procuring organization. The cost-effectiveness of a particular detector or type of technology can only be judged when applied to a specific application and should include total life-cycle costs (i.e., take into account purchase price, installation, data interface preparation, and maintenance over an extended time period of 10 to 20 years) and the equivalent number of lower cost detectors (e.g., inductive loops) that it replaces.

Candidate overhead detector technologies have been identified for several traffic management applications and operational requirements as listed in Table 12-1. The technologies were selected based on the capabilities and types of outputs currently available from a particular technology and their suitability to the application. This list does not take into account the performance of these technologies during the field tests. The quality of the technology performance is discussed in Section 12.1.

Table 12-2 lists advantages and disadvantages associated with each technology. A more detailed matrix was presented in Appendix A of the Task A Report. For example, infrared detectors have an advantage over visible wavelength sensors in foggy conditions, but their effectiveness may still be limited by heavy rain or snow. Each technology has strengths and weaknesses imposed by the physics that governs its operation and the resolution of the detector. These may cause a specific technology to be wholly unsuitable or ideally suited for a particular application. The diversity of operating conditions and applications demonstrates the detectorspecific selection that must be made for each

installation. There is no generic "best detector." Selection of the appropriate traffic management system components is dependent upon not only the traffic management application, but on the operating conditions (including weather) and mounting requirements (e.g., in-road versus overhead, mast arm versus pole, upstream or downstream viewing of traffic).

12.1 ASSESSMENT OF BEST PERFORMING TECHNOLOGIES BY APPLICATION

Both quantitative and qualitative observations were made regarding how well a particular technology performed relative to others at the evaluation sites employed during the field tests. Judgments were made regarding which technologies exhibited the best performance with respect to supplying different traffic parameters. Table 12-3 provides a summary of the conclusions based on the results from the limited number of runs reduced so far and the general qualitative opinions gained from using these devices over an 18-month evaluation period.

12.1.1 Most Accurate Vehicle Count for Low Traffic Volume

Most of the detectors gave good results when used under light traffic conditions. It should be stressed that some detectors had an inherent advantage in the results displayed in Section 10 by virtue of their multiple outputs or detection zones. The most favorable of the outputs, when more than one zone was available, was shown in the graphs. For example, if loop #1 showed better agreement with the ground truth value than loop #2 (for the same lane), then the loop #1 results were presented. Likewise, if a single traffic detector had multiple detection zones, the most favorable of the outputs was used in the plotted results. This affords a greater opportunity for these devices to appear in a favorable light; whereas, a simple detector having a single relay output was represented solely on the basis of that single output.

Application	Assumptions	Overhead Technology
 Signalized intersection control 	 Detect stopped vehicles Weather not a major factor 	 True-presence microwave radar Passive infrared Laser radar Ultrasound Video image processor
 Signalized intersection control 	Detect stopped vehiclesInclement weather	 True-presence microwave radar Ultrasound Long-wavelength imaging infrared video processor
Signalized intersection control	 Detection of stopped vehicles not required Inclement weather 	 True-presence microwave radar Doppler microwave detector Ultrasound Long-wavelength imaging infrared video processor
 Real-time adaptive signal control (e.g., SCOOT) 	 Desirable for detector footprint to emulate a 6-ft x 6-ft inductive loop Side-mounting capability 	 Video image processor True-presence microwave radar Passive infrared (with suitable aperture beamwidth)
 Vehicle counting (surface street or freeway) 	 Detect and count vehicles traveling at speeds > 2-3 mi/h 	 True-presence microwave radar Doppler microwave detector Passive infrared Laser radar Ultrasound Video image processor
Vehicle speed measurement	 Detect and count vehicles traveling at speeds > 2-3 mi/h 	 True-presence microwave radar Doppler microwave detector Laser radar Video image processor
Vehicle classification	By length	Video image processorLaser radar
Vehicle classification	By profile	Laser radar

1 ft = 0.305 m 1 mi/h = 1.61 km/h

Technology	Advantages	Disadvantages
Ultrasonic	Compact size, ease of installation	 Performance may be degraded by variations in temperature and air turbulence
Microwave Doppler	 Good performance in inclement weather 	 Cannot detect stopped or very slow-moving vehicles
	 Direct measurement of speed 	 Requires narrow-beam antenna to confine footprint to single lane in forward-looking mode
Microwave True Presence	 Good performance in inclement weather 	 Requires narrow-beam antenna to confine footprint to single lane in
	 Detects stopped vehicles 	forward-looking mode
	 Can operate in side-looking mode to service multiple lanes 	
Passive Infrared	 Greater viewing distance in fog than with visible-wavelength sensors 	 Performance potentially degraded by heavy rain or snow
Active Infrareḋ	 Greater viewing distance in fog than with visible-wavelength sensors Direct measurement of speed 	 Performance degraded by obscurants in the atmosphere and weather
Visible VIP	 Provides visible imagery with potential for incident management 	 Large vehicles can mask trailing smaller vehicles
	 Single camera and processor can service multiple lanes Rich array of traffic data available 	 Shadows, reflections from wet pavement, and day/night transitions can result in missed or false detections
Infrared VIP	 Possibility of using same algorithms for day and night operation and avoiding day/night algorithm transition problems Rich array of traffic data available 	 May require cooled IR detector focal plane for high sensitivity; implies somewhat more power and less reliability
Acoustic	 Potential for identifying specific vehicle types by their acoustic signature 	 Signal processing of energy received by the array is required to remove extraneous background sounds and to identify vehicles
Magnetometer	 Can detect small vehicles, including bicycles 	Difficulty in discriminating longitudinal separation between
	 Useful where loops cannot be installed 	closely spaced vehicles
Inductive Loop Detectors	 Standardization of loop amplifier electronics 	 Reliability and useful life are a strong function of installation procedures
	Excellent counting accuracyMature, well understood technology	 Traffic interrupted for repair and installation
. [.,	Decreases life of pavement
		 Susceptible to damage by heavy vehicles, road repair, and utilities

Table 12-2. Advantages and Disadvantages of Various Detection Technologies

Technology	Low-Volume Count	High-Volume Count	Low-Volume Speed	High-Volume Speed	Best In Inclement Weather
Ultrasonic	-	-	-		-
Microwave Doppler*	1	1	1	1	1
Microwave True Presence	1	1			1
Passive Infrared	-	-	_	-	-
Active Infrared			_		_
Visible VIP	1	1			-
Infrared VIP					
Acoustic Array	-	-			
SPVD Magnetometer	1		-	<u>-</u>	1
Inductive Loop	1	1	-	-	1

Table 12-3	. Qualitative Assessment	of Best Performing	Technologies for Gathering
	-	Specific Data	

✓ Indicates the best performing technologies.

Indicates performance not among the best, but may still be adequate for the application.
 No entry indicates not enough data reduced to make a judgment.

* Does not detect stopped vehicles.

The ultrasonic and infrared detectors exhibit count accuracies that make them suitable for a variety of applications, but they were typically not among the most accurate. The SPVD magnetometer performed well in low-volume applications, as demonstrated by the zero-percent error over a 2-hour run during snowfall conditions for the Minnesota surface-street Run 03091019 (reference Figure 10-22).

Microwave radars were also well suited to low-volume conditions. The presence-type microwave radar consistently provided better vehicle count results in forward-looking operation than in side-looking orientation. Forward-looking count accuracies to within 1 percent were not uncommon; however, these accuracies were typically provided by only a single detection zone, due to the difficulty in confining the detector's elliptical beam footprint to a single lane of traffic. Because of this footprint geometry, only one detection zone tends to be optimally matched to the dimensions of the traffic lane, while the remainder of the zones tend to undercount (in the narrow parts of the beam where the detection zones are not as wide as the lane) or overcount (where the wide part of the beam tends to spill over into adjacent lanes of traffic).

Doppler-type microwave detectors fare well in low-to-moderate traffic volume conditions, where free-flowing traffic consistently provides a component of motion in the detector's viewing direction that is necessary for the operation of these units. However, there can conceivably be traffic management applications where a knowledge of decreasing speeds can be used to infer that stopped vehicles are present even though the Doppler detector does not give an output indication. Again, care must be taken to ensure that the detector's beam footprint on the roadway is confined to the desired monitoring area.

Some video image processors exhibit counting characteristics similar to microwave detectors. The Autoscope 2003, for example, can be configured to have three separate detection zones per lane (two emulating a pair of inductive loops and a third configured as a speed trap). Data show that count results tend to be optimized for a given zone.

Inductive loops are among the most consistent performers, with count accuracies typically in the 99-percent range. Even so, problems with crosstalk and double- or triple-counting large trucks and tractor-trailer rigs have been seen when reviewing videotapes of the field tests.

12.1.2 Most Accurate Vehicle Count for High Traffic Volume

Many of the same observations made in the previous section apply here as well. However, counting vehicles at freeway speeds or during periods of heavy congestion presents additional difficulties. The electronic hold time of a detector begins to become an important factor when intervehicle gap times decrease. The hold time is the period over which a detector remains in the active state after the initial detection of a vehicle. Hold time is often adjustable by means of a potentiometer setting in the detector electronics or by software via a remote serial interface to the hardware.

For the field tests, the hold time of each device was always set to its minimum value. Increasing the hold time in heavy traffic conditions has a negative impact on count accuracy due to the detector's inability to determine when one vehicle departs the detection zone and another enters. With long hold times, a second vehicle enters the detection zone prior to the falling edge of the pulse created by the first vehicle. This can result in several closely spaced vehicles registering only a single count on a given detector. Such events are characterized by abnormally long presence times in the Paradox database file.

Although several detectors evaluated were designed with long hold times because of an initial traffic management requirement, devices of similar types can certainly be redesigned with shorter hold times as new applications arise.

12.1.3 Most Accurate Speed for Low Traffic Volume

Speed accuracy is a difficult parameter to assess due to the challenge of obtaining the true speeds against which to compare the detector speed outputs. Some detectors compute speeds based on average vehicle lengths. Such devices may yield acceptable accuracies over the long term, but not for applications that require periodic updates or vehicle-by-vehicle speeds. This requirement favors the implementation of detectors that make direct speed measurements, or pairs of detectors that can be used in a speed-trap configuration.

Speed traps are difficult to implement accurately due to the precision required in time-tagging the two pulse outputs that provide the time difference between passage of a vehicle over the two zones in the speedtrap. Further hindering the process is the probability that the two detectors have dissimilar sensing areas or detection zones. For instance, the fields associated with two inductive loops may not subtend the same sensing area due to differences in gain or sensitivity. They may have different response times or varying pulse widths. Although the two loops are similar, they do not necessarily share identical characteristics. These small differences are magnified greatly when monitoring the high speeds that occur in low-volume applications. In addition, the controller must have the programming capability to compute speeds from speed-trap timing pulses.

The simplest and most accurate way to measure speed is to use a detector that provides it directly, such as a Doppler microwave detector. Doppler devices require a component of motion in the direction of operation. Since free-flowing traffic is readily available in low-volume conditions, a Doppler device would seem a logical choice for such an application. Speed as measured by Doppler microwave detectors usually agreed within 1 to 2 mi/h (1.6 to 3.2 km/h) with readings from the speedometers of the probe vehicles. However, the imprecision associated with a human observer recording these values from an analog speedometer of unknown accuracy yields, at best, a reference value, not absolute truth.

Some detectors capable of providing speed outputs could not be evaluated with the single probe vehicle. These units output average speed data collected over some integration interval and, as such, do not give information on a per vehicle basis. Among these devices were several video image processors and the RTMS-X1 microwave true-presence radar. Thus, the selection of a preferred technology is application-dependent. If the requirement is for a unit that will supply average speed, occupancy, or some other statistically derived parameter, the choice should be one of the sophisticated detection systems employing enough processing capability to accurately compute the desired parameter(s). Conversely, if the data are required on a pervehicle basis, the choice narrows to devices that output the desired parameters in real time as they are acquired. Certainly the more sophisticated units, such as video image processors, multi-zone radars, and laser radars, have the ability to output data on a per vehicle basis as they must measure the characteristics of individual vehicles in order to produce their normal statistical outputs. However, the cost of these units will likely dictate that they be utilized only for applications that require statistical data or where their cost can be justified on an equivalent per detector basis or through lifecycle cost considerations.

12.1.4 Most Accurate Speed for High Traffic Volume

Many of the same points made in Section 12.1.3 apply here as well. The main difference in requirements between low- and high-volume applications stems from the

change in vehicle speeds. Vehicles in low-volume conditions are likely to be freeflowing and unconstrained in their movements, while vehicles in high-volume conditions, where the roadway is at or near its designed capacity, will be restricted in their speed. When the traffic demand exceeds the capacity of the roadway, speeds will obviously decrease. If the speeds slow significantly and bumper-to-bumper traffic conditions ensue, then Doppler detectors will significantly degrade in their ability to accurately measure vehicle speeds. Perhaps this will not matter as the necessity for zero speed measurement may decrease once the traffic flow falls below some fixed threshold.

12.1.5 Best Performance in Inclement Weather

The detectors that seemed the most impervious to inclement weather conditions were the microwave detectors. No appreciable change in performance was noted during conditions such as rain, snow, wind, and extreme cold or heat. As mentioned earlier, one of the Doppler microwave units demonstrated degraded performance when an appreciable amount of rain leaked into the unit, but this was not a limitation of the technology. Likewise, the SPVD magnetometers suffered some rain-related damage. but the failure stemmed from a crack in the cylindrical case housing the electronics. The magnetometers performed well in the snow during the Minneapolis surface-street tests. The inductive loops, when properly installed, performed reliably through a broad spectrum of weather conditions.

The technologies with the greatest extreme weather limitations include the ultrasonic, infrared, acoustic, and video image processors. This is not due to any flaw in the design of these units, but rather to physical limitations caused by weather-related phenomena, such as gusty winds (greater than 56 mi/h [>25 m/s] in the case of the Doppler ultrasound detector) or the presence of atmospheric obscurants. However, even these devices are relatively unaffected by inclement weather conditions when operating at the short ranges typically associated with their normal usage.

12.1.6 Microscopic Single-Lane vs. Macroscopic Multiple-Lane Data

Several of the detectors were better suited for collecting data that characterized individual vehicles in multiple lanes, while others were better for gathering data from groups of vehicles in multiple lanes. The detectors best suited for acquiring microscopic (individual vehicle) data over multiple lanes were the true-presence microwave radar and the video image processors. Those useful for collecting macroscopic (groups of vehicles) data were the wide-beam Doppler microwave detectors, true-presence microwave radar, and the video image processors. Sufficient data have not been reduced to rank these detectors for these applications.

12.2 LESSONS LEARNED

Many of the qualitative results were gained from the familiarity that came with utilizing these detectors day in and day out in a number of different weather and traffic environments. The dynamic nature of the field tests and the interest displayed by the detector manufacturers to participate in them caused the number of devices under evaluation to grow steadily. This necessitated changes to both the data logger hardware and the software (both to record and post-process the data) so that the expanding number of detector outputs could be accommodated. Each new serial interface required that device-specific code be written to provide the proper RS-232 communication interface. In order to minimize this problem in future applications, a standardization of serial communication protocols would be most helpful.

The considerable amount of time necessary to examine the processed data and video imagery in detail dictated that only a portion of the runs were analyzed in depth for this report. Analyzed runs were selected to be representative of the broadest possible spectrum of weather and traffic conditions encountered. While this approach provided the analyst with a diverse set of data to evaluate, it did not allow for any detailed statistical analyses to be performed. Such analyses and conclusions should be a part of future efforts that explore more of the available database.

12.3 CONCLUDING REMARKS

The Detection Technology for IVHS field tests provided a substantial database of traffic detector performance information for a broad spectrum of weather and traffic conditions. Future data reduction will include analyses of additional runs to produce a larger set of results from which statistical conclusions may be drawn. Additional runs will be subject to ground truth. Vehicle-count ground truth will be analyzed over short intervals (such as a signal cycle period) in addition to the 1- to 2-hour intervals prevalent in previous analyses. This will better determine whether existing technologies are able to meet the traffic parameter update accuracy requirements specified for applications such as real-time signalized intersection control.

Additional ground truthing also is required for the Tucson surface-street site in order to minimize the effect of anomalies that occur when vehicles sweep out into multiple lanes as they complete their turning movements. This entails overlaying the signal green phase status on the video imagery and counting only those vehicles exiting the intersection during the green or yellow phase. This will eliminate most of the false counts associated with left or right turns and allow the count to properly reflect the vehicles that travel straight through the intersection with minimal lane changes.

The project wishes to express its gratitude to the many people who provided support in the acquisition and evaluation of the detectors. Engineers and technicians from the various detector manufacturers were consulted frequently and responded with timely and helpful technical advice. Some personally assisted with the installation of their systems. Their willingness to provide evaluation units and the spirit of cooperation with which they participated are greatly appreciated.

The assistance of the state, county, and municipal DOTs was invaluable. They supplied personnel, equipment, and use of their facilities, and patiently accommodated numerous requests for lane closures and adjustment of the detector viewing angles. The professionalism demonstrated by these agencies was a critical ingredient in the success of the field tests.

APPENDIX A.

TASK J: DETERMINE NEED AND FEASIBILITY OF ESTABLISHING PERMANENT VEHICLE DETECTOR TEST FACILITY

Detector manufacturers participating in the Detection Technology for IVHS program and the three universities selected as IVHS Research Centers of Excellence (CoE) were contacted to ascertain their opinions and ideas concerning the need and feasibility of establishing a permanent detector test and evaluation facility. In addition, the advisability of establishing and methods of funding an independent detector evaluation facility were also addressed under a separate contract issued by FHWA to New Mexico State University. The results of these efforts are summarized in this appendix.

A.1 CONCLUSIONS FROM THE DETECTION TECHNOLOGY FOR IVHS PROGRAM

Potential advantages of having a national detector evaluation facility include:

- Reduction of detector testing costs by eliminating repetitive tests by multiple traffic management agencies;
- Developing a set of standardized test procedures and test facilities that are accepted by traffic management and transportation agencies and detector manufacturers;
- Training agencies in the installation, calibration, and maintenance of detectors that exploit technologies not historically associated with traffic management; and
- Promoting the use of standard serial data interfaces between the detector and the traffic management system to minimize the need to write detector-specific software that is otherwise required to interpret the serial output.

The need for a detector test and evaluation facility should not be an issue. One is needed. However, there are other issues associated with the establishment of such a facility. These are: gaining acceptance of the results by local, county, and state traffic management and data collection agencies; location or locations of the facility; selection of the test facility management; types of tests to be performed; calibration and types of ground truth equipment; establishment of standard protocols for output data; and funding.

When the detector manufacturers were contacted as part of this task for their ideas about participation, types of tests, and funding for a detector evaluation facility, they were not enthusiastic as evidenced by the lack of replies to the letter, shown in Figure A-1, that was mailed. Another letter, contained in Figure A-2, expressing similar thoughts was sent to an ASTM committee that was considering a similar issue. This letter was one of the inputs that lead to the eventual award of the contract to New Mexico State University to independently evaluate the need and operation of a national test center for traffic monitoring devices. Now that the Detection Technology for IVHS project is complete, a greater interest in new detector technologies appears to have been generated and exhibited by the traffic management community. Hence there is more interest in the detector manufacturing community to have their products accepted and purchased. Based on the favorable experience with manufacturers making their products available for the detection technology program, they very likely will make their products available again for evaluation at a permanent facility when one is established.

A set of letters and telephone conversations were also exchanged with the IVHS Research CoEs, listed in Table A-1, about their capabilities and interest in hosting the detector evaluation facility. The substance of these letters is contained in Figure A-3. Naturally all CoEs were enthusiastic about

February 7, 1994

Name of Manufacturer's Contact Person Manufacturer Company Name Mail Stop Street or P.O. Box City, State, Zip

Dear (first name of contact person),

On behalf of Hughes Aircraft Company and the Federal Highway Administration, I want to thank you for your support of the Detection Technology for IVHS Program. Your prompt response to questions about detector operation and to repairing equipment have made the program successful. We are presently at the last planned test location in Tucson, although there may be an opportunity to return to Phoenix this summer for further hot weather evaluation of the detectors. In the meantime, Michael Kelley and I are reducing the data we have already obtained.

In addition to evaluating the detectors in three states, the program requires us to determine the need and feasibility of establishing a permanent vehicle detector test facility or facilities. The wording for this task as it appears in the contract is:

The total life cycle cost of a vehicle detector is difficult to predict since vehicle detector hardware designs and installation techniques are continually improving. National vehicle detector test and evaluation facility/ies may be needed to provide up-to-date performance information on new vehicle detectors performance. Determine if national vehicle detector test and evaluation facility/ies are needed and develop a test plan for implementing such facilities. Determine if laboratory tests should be conducted at a single center with multiple field sites; determine the feasibility of testing environmental sensors for sensing roadway environmental conditions. Determine the feasibility of this facility/ies operating on a self-supporting basis. Document the results of this Task as an Appendix to the draft final report.

My initial approach for fulfilling these requirements is to contact the three IVHS Research Centers of Excellence designated by FHWA and obtain their thoughts, comments, and ideas about the need for implementing detector test and evaluation centers. These centers are Texas A&M, Virginia Polytechnic Institute, and the University of Michigan. At a minimum, I believe that the test and evaluation center should conduct temperature, humidity, and vibration tests in an environmental chamber to some accepted levels such as those established by NEMA. In addition, the center should expose the detectors to real traffic environments on both a freeway, where traffic parameters such as volume, speed, and density are important, and a surface street arterial where presence, queue length, and turning movements are important. Other parameters such as vehicle classification based on length or pattern recognition could also be verified if the detector provides this output. For that matter, the test center would have to be prepared to measure whatever type of detector output data were available in order to evaluate the detector's accuracy and ability to provide the specified data.

As FHWA pointed out, we need to determine the feasibility of the centers being self-supporting. To this end, I wish to inquire of you whether such a test and evaluation facility will be of value in verifying, to potential local, regional, and state transportation agencies, that your products satisfy the specifications that either you develop or an accepted professional organization such as NEMA or ASTM develops? If so, what would you be willing to pay such a facility for conducting the tests? Are there any seed monies or special test equipment that you could contribute to help set up the facility? What types of tests do you consider to be necessary to aid in selling your products? What are your comments about conducting extended, perhaps six-month, simultaneous outdoor evaluations of the product at locations with hot and cold weather environments?

Please send me your thoughts about the test and evaluation center, including funding options and types of tests you deem important. If you have any questions, please call me at (714) 732-7995 or fax me at (714) 732-2613.

Sincerely,

Lawrence A. Klein, Principal Investigator

Figure A-1. Letter Sent to Detector Manufacturers

January 1993

Emerging technologies are being applied to traffic management in areas such as weigh-in-motion, automatic vehicle classification, congestion management, and incident detection. Products that incorporate newer technologies create a need for standardized methods to test and verify device performance and to compare their data with data collected by other products performing the same function. This need has been expressed by several organizations and agencies, including the Federal Highway Administration, state and city departments of transportation, equipment manufacturers, and standard-setting groups such as ASTM.

The types of products to be tested cover the spectrum of Intelligent Vehicle-Highway System applications. They include axle count and weight detectors; vehicle presence and speed detectors; imaging detectors installed on highways and surface streets; traveler information devices such as changeable message signs, in-vehicle displays, and video displays in areas where large numbers of people gather (e.g., shopping centers, amusement parks, office buildings, etc.); and communications media including roadside-to-vehicle radios, satellite transmission devices, and vehicle identification tags and other in-vehicle transmitters that send various types of information and data to roadside receivers.

In order to: (1) determine what facilities, tests, and resources are available, and (2) obtain user input as to the types of testing that are desired, ASTM is conducting a survey of state and city departments of transportation. We ask that the information indicated below be provided, along with any other pertinent comments you choose to make.

1. Test facilities available or planned. These can include outdoor ranges, indoor environmental chambers, instrumented highway segments, state-run or national laboratories located within your jurisdictional area (please list specific facilities you would use in these laboratories), university assets, private industry assets, etc. Specify which of these facilities are available for outside use.

List the technologies that your facilities can evaluate. For example, axle weight detectors can be based on bending plates, piezoelectric devices, and rubber tube technologies. The response, in this case, should identify which of the technologies can be tested and what facilities and equipment are used, available, or proposed for the tests. As another example, consider vehicle count and presence detectors. These can employ inductive loops, magnetics, microwave or laser radar, passive infrared, ultrasound, acoustic arrays, and video image processors to gather data. Once again, the response should specify which of these technologies can be accommodated in the available or planned test facilities. Communications media are still another type of device. These include leased or dedicated line communications, spread spectrum radio, highway advisory radio, satellite terminals, microwave and laser links, etc. The types of communications devices that can be tested should be noted.

II. Personnel conducting the tests. Are they state employees, university employees, contractors, consultants, etc.

III. Current tests performed and procedures used. Include devices currently tested. If possible, estimate the cost for each test.

IV. Calibration or accreditation procedures used to ensure accurate test data are obtained. Include items such as how often the test equipment is calibrated and the calibration techniques that are used. If satellite test facilities are used, how frequently are they visited to ensure that the standard and approved test methods are being followed?

V. Types of products you use or products requiring test data before a purchase decision can be made. List types of test data required and associated measurement accuracy (if known).

Figure A-2. Draft of Letter Mailed in Response to a Request From ASTM Committee 17.52

January 25, 1994

Contact Person IVHS Research Center of Excellence University Name Street or P.O. Box City, State, Zip

Dear (name of contact person),

To follow up on our telephone conversation of last week, I will describe the task that I am required to perform under my present contract with FHWA to determine the need and feasibility of establishing a permanent vehicle detector test facility or facilities. The task in the contract reads as follows:

The total life cycle cost of a vehicle detector is difficult to predict since vehicle detector hardware designs and installation techniques are continually improving. National vehicle detector test and evaluation facility/ies may be needed to provide up-to-date performance information on new vehicle detectors performance. Determine if national vehicle detector test and evaluation facility/ies are needed and develop a test plan for implementing such facilities. Determine if laboratory tests should be conducted at a single center with multiple field sites; determine the feasibility of testing environmental sensors for sensing roadway environmental conditions. Determine the feasibility of this facility/ies operating on a self-supporting basis. Document the results of this Task as an Appendix to the draft final report.

My initial thoughts are to contact the three IVHS Research Centers of Excellence designated by FHWA and obtain their thoughts, comments, and ideas about the need for implementing detector test and evaluation centers. At a minimum, I believe that such a center should conduct temperature, humidity, and vibration tests in an environmental chamber to some accepted levels such as those established by NEMA. In addition, the center should expose the detectors to real traffic environments on both a freeway, where traffic parameters such as volume, speed, and density are important, and a surface street arterial where presence, queue length, and turning movements are important. Other parameters such as vehicle classification based on length or pattern recognition could also be verified if the detector provides this output. For that matter, the test center would have to be prepared to measure whatever type of detector output data were available in order to evaluate the detector's accuracy and ability to provide the specified data.

As FHWA pointed out, we need to determine the feasibility of the centers being self-supporting. To this end, I will write to the detector manufacturers who are participating in the Detection Technology for IVHS Program and solicit their thoughts about the center and how much they might be willing to pay to have one of their detectors tested and evaluated at the center.

Please send me your thoughts about the test and evaluation center, including funding options and types of tests you deem important. Include a description of your Research Centers of Excellence facilities that could be used to support this activity. Would there be a need for multiple test centers to evaluate the detectors under all of the anticipated real-world traffic conditions? Should the test center provide some pre-established certification for operation in one or more applications or should the center simply verify that the detector meets the manufacturer's specifications?

I would appreciate your comments and any other inputs about any of the issues encompassed by the above task. If you have any questions, please call me at (714) 732-7995 or fax me at (714) 732-2613.

Sincerely,

Lawrence A. Klein, Principal Investigator

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Figure A-3. Substance of Letters Sent to IVHS Research Centers of Excellence

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managing such a facility. The responses from the Center for Transportation Research at Virginia Tech and the Texas Transportation Institute at Texas A&M are shown as Figures A-4 and A-5, respectively. The semigovernmental agencies, such as the Jet Propulsion Laboratory and the Department of Energy laboratories, also want to be the facility manager. They all appear to have pockets of excellence, but it is difficult to say if any one presently has all the expertise required to run the series of tests that most likely will be required. Fortunately, the knowledge to execute any group of detector evaluation tests and procedures that is deemed necessary can be easily acquired, and after some learning period, the tests will most likely be performed flawlessly by any of these institutions.

Table	A-1 .	IVHS	Research	Centers	of	Excellence
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Dr. Tony Hobeika	Dr. Thomas Urbanik, II	Dr. Steven Underwood
Director, Center for Transportation Research	Division Head-Transportation Systems	University of Michigan
Virginia Tech	Texas Transportation Institute	IVHS Program
106 Faculty Street	The Texas A&M University System	4110 EECS Building
Blacksburg, VA 24061	College Station, TX 77843-3135	Ann Arbor, MI 48109-2122

Perhaps a way to begin the process of selecting the test facility manager is to convene a working group composed of members of the CoEs and other universities with active transportation research programs, the DoE laboratories, NASA laboratories, private industry with ongoing FHWA programs, and traffic management agencies. The group would initially be chaired by an employee of FHWA. The chair could remain in the hands of FHWA or be passed onto another public or private sector employee whose employer will not run the detector evaluation facility. Suggestions from the participants will be solicited for the types of tests (field or laboratory) to be performed, test locations (cold and hot weather sites, rain and fog sites, etc.), length of the tests, distribution of results, and other issues that are generated.

A.2 NEW MEXICO STATE UNIVERSITY INVESTIGATION

Most of the issues described above have been addressed by New Mexico State University in the execution of their contract with FHWA to investigate the feasibility of establishing a national center to test monitoring devices used by state highway agencies to gather traffic data. Under the leadership of Dr. Rudi Schoenmackers of the Southwest Technology Development Institute at New Mexico State, representatives from 10 state highway and transportation agencies, the American Association of State Highway and Transportation Officials (AASHTO), Iowa State University, New Mexico State University, FHWA, and the Alliance for Transportation Research initially participated in a 2-day working session that:

- Determined the types and uses of traffic monitoring devices to be tested;
- Investigated the need for standard test procedures;
- Recognized need to specify laboratory and field test environments;
- Recognized need to develop a process to disseminate test results;
- Determined extent of manufacturer participation;
- Addressed representation of state highway agencies and national associations in the management of the test facility;
- Explored relationship of a national testing program for traffic monitoring devices to other existing national testing programs and

CENTER FOR

TRANSPORTATION RESEARCH

Virginia

Tech

FAX COVER

TO: Lawrence A. Klein FAX NUMBER: (714) 732-1185 FROM: Robert D. James Date: 2/9/94

Dear Larry,

Dr Hobeika asked me to respond to your letter of January 25, 1994. Thank you for your interest in the Center's activities in regard to IVHS test facilities. We do believe that a national test facility for IVHS detector technology is necessary and important. We have already taken a number of steps toward establishing Virginia Tech as a major test facility for these technologies.

We are currently planning to make the Virginia Tech region a national testbed for IVHS technologies. Our particular focus has been on establishing and defining the infrastructure requirements (heavily communications oriented) for future roadways. In fact we have started a \$5.95 million "Smart Road" project funded by FHWA and VDOT to define the infrastructure requirements for IVHS-related architecture. The "Smart Road" is the first highway designed from the ground up to contain the IVHS technology. The road is a 6-mile stretch of road between Blacksburg and I-81 near Roanoke. The road has already passed its environmental impact study and is well on its way to becoming the most technically advanced road in the country. Once the infrastructure is in place we will be able to have real-time access to data from a wide range of sensor technologies.

The Center for Transportation Research is already involved in the testing of several sensors under real-traffic conditions. The Center has been evaluating the data collected by AT& T's Passive Acoustic sensor. Recently several of these sensors have been installed on Route 460 near Virginia Tech. Data will be collected in order to evaluate the reliability and accuracy of this specific type of sensor. Also, we will suggest specific algorithms that will allow the sensor to detect, count, classify and track vehicles. Also, the Center is working closely with a French company that has already developed a video-based sensor for incident detection.

In addition to the ongoing activities mentioned above, the Center is planning to set up a traffic control center parallel to the VDOT Salem District traffic center. This way, we will have access to all the real-time data coming to the Salem traffic control center. Another near-term plan is to establish a direct communication line between the traffic control center in Northern Virginia and Virginia Tech. This will enable us to access the real-time urban freeway data. This is a logical extension of the Center's ongoing research efforts for developing real-time traffic control and incident management algorithms. For the last five years, the Center has been conducting research in developing real-time traffic control algorithms for alleviating non-recurrent congestion. Several prototype models, such as static and dynamic O-D estimation models, Dynamic Traffic Assignment model area-wide incident management expert system and others, have already been developed. The next reasonable step is to test, evaluate and modify these models before the full deployment. Therefore, the need for real-time information was vital to the continuation of our research.

Virginia Tech is also strongly qualified to help in the assessment of candidate communication systems and technologies. With expertise in cellular, satellite, PCS, spread spectrum and fiber-optic communications, in addition to good knowledge of other systems and technologies, Tech can assume a major role in technology assessment.

Figure A-4. Reply from the Center of Transportation Research at Virginia Tech Concerning National Detector Test and Evaluation Facilities

The communication groups at Virginia Tech are part of the Center for Wireless Telecommunications, a technology development center of the Virginia Center for Innovative Technology, and the Fiber and Electro-Optics Research Center (FEORC), a leading center for fiber-optics research in the nation.

The Fiber and Electro-Optics Research Center of Virginia Tech, one of the University partners of IVHS Research Center of Excellence, is heavily involved in developing fiber sensors. They are extremely experienced in evaluating the effects of temperature variation, humidity and contaminant build-up on the orientation of sensors. They perform the environmental studies at Virginia Tech using a Thermetron environmental testing chamber. With this chamber it will be possible to cycle any sensor through the expected operating temperature and humidity ranges to determine the sensitivity of the sensor to adverse environmental conditions. The FEORC group is also experienced in evaluating the effects of contaminants, such as petroleum products, on the integrity of the sensor components.

FEORC is involved in developing and testing fiber-optic sensors for different purposes. They have already developed and tested under real-traffic conditions a fiber-optic sensor to measure the velocity and quantity of vehicles in motion on a roadway. They have also developed a parking lot sensor. They have conducted extensive tests at Virginia Tech's commuter lot.

The Mobile Portable Radio Group (MPRG) at Virginia Tech is nationally renown for its extensive database and lab testing capabilities They have conducted many studies for all the major telecommunication companies. They have also been very active in IVHS communication issues. Their satellite and cellular research is well known in the IVHS arena.

The AT&T Passive Acoustic detector project is a great example of how industry and state can work together to fund the testing of these sensors. This project has been funded by AT&T with matching funding from Virginia's Center for Innovative Technology. VDOT has provided significant technical and financial assistance for the installation of the sensors on the roadway. We see the Federal Government contributing to the initial setup for the national testbed and industry in combination with various Federal, State and local agencies involved in paying for the testing of individual sensors. Industry benefits by having their sensor evaluated based upon national standards and having access to an independent team of experts for system development. Also, with the use of graduate students the cost for data collection and analysis can be kept very low. Government agencies benefit by having candidate technologies tested under real-world conditions and performance based upon a national standard. This makes for a win-win situation!

In summary, our vision is to start a national test lab for advanced IVHS technologies around Virginia Tech, first on Route 460 and I-81, then on the "Smart Road." This unique setting will give us the opportunity of testing different sensors under real-traffic conditions. Moreover, the road expertise of the various Virginia Tech centers involved in IVHS Research Centers of Excellence and the availability of high-tech labs at the Virginia Tech campus will give us the capability of testing and evaluating different types of sensors, ranging from more conventional embedded types of sensors to the cellular and satellite types of sensors.

I will send you some materials on the various facilities at the University. If there is anything else you need please let me know and I will be happy to help. I look forward to working with you in future efforts along these lines. If there are any programs you would like to work together on, please let me know. I can be reached at (703) 231-7740 or FAXed at (703) 231-5214. Thank you for your interest.

Sincerely,

Robert D. James

Figure A-4. Reply from the Center of Transportation Research at Virginia Tech Concerning National Detector Test and Evaluation Facilities (continued)

TEXAS TRANSPORTATION INSTITUTE

TRAFFIC MONITORING PROGRAM

Area Code	409
Telephone	846-1728
TexAn	867-1728
FAX	845-6008

February 28, 1994

Mr. Lawrence A. Klein Ground Systems Group MS N302 P.O. Box 3310 Fullerton, Ca 92634-3310

Dear Mr. Klein:

The Texas Transportation Institute (TTI) would be very interested in becoming a detector test and evaluation center, should such centers become desirable. TTI continues to maintain a prominent position of leadership in IVHS activities by hosting IVHS symposia, by leadership in various IVHS initiatives such as IVHS America, and by being designated as an IVHS Center of Excellence. This leadership exemplifies TTI's continuing interest in IVHS activities and the capabilities of TTI personnel in a wide variety of research endeavors. TTI is well equipped to conduct laboratory testing using controlled temperature and humidity, and using standardized testing methods. A description of the environmental test equipment and the vibration test equipment is provided.

Environmental Test Chambers. Twelve walk-in temperature chambers maintain environmental conditions at precise levels. The chambers have temperature ranges from -20F to 140F and humidity may be varied from 25% to 100%. They control temperature to within $\pm 2F$, and humidity to within $\pm 4\%$. Designed to maintain good stability, the chambers are available for either short-term or long-term tests.

One of the rooms is fully equipped with computerized control and data acquisition.

The system is capable of cycling the environmental conditions and can directly control specimen temperature and humidity (as opposed to simply controlling room conditions) using a feedback system. Provision is also made for control of ultraviolet lighting in this room.

Environmental Test Cabinets. The Instron Environmental Test System is compatible with the Instron and Gilmore testing machines. In addition, researchers have access to two large (40" width x 50" height x 22" depth), elevated temperature cabinets. They can produce temperatures from ambient to approximately 400F, and are accurate to within $\pm 2F$. Another temperature cabinet with the same capabilities uses the MTS systems.

Servo-Hydraulic Testing System. Two materials testing systems, the MTS Systems 810 and 810.22, are available for research applications including creep testing, indirect tension testing, compression testing, vibration and repetitive load testing, and non-destructive testing. The MTS systems are closed-loop, enabling programming of waveforms for lead, displacement, or stroke control for tension or compression. Used with the computerized microprofiler or digital function generator, virtually any combination of wave variation can be generated.

I agree with you that the minimum tests should include temperature, humidity, and vibration testing within ranges that are not expected to be exceeded in "rcal-world" applications. Going beyond these laboratory tests, there must also be qualitative and quantitative testing in at least the two environments you suggested-signalized arterial surface streets and urban freeways. In these non-laboratory tests, various weather, lighting, and traffic conditions must be included. The standardization of the test procedure must normalize these conditions because testing each system under the exact same conditions would be difficult, if not impossible.

Figure A-5. Reply from the Texas Transportation Institute at Texas A&M Concerning National Detector Test and Evaluation Facilities

Based on TTI's test equipment, its several satellite offices in large urban areas, and its very capable and diverse research staff, there should be no need to establish multiple test facilities unless weather conditions in Texas are not suitable for all outdoor tests. If the testing of a new device is to occur within a reasonable time frame, it is anticipated that some tests must be done indoors. Temperature and humidity testing must be done under laboratory conditions because ambient conditions at certain times of the year at any one location would not represent the extremes needed to test a new product. It is assumed that longevity testing will not be included.

If new equipment is to be tested under hot and cold extremes outdoors, Texas would provide adequate high temperatures and other weather conditions such as fog and rain. Another state should be selected with other extremes, including low temperatures. Testing would need to occur in the varied weather extremes of summer in Texas and winter in the northern state selected. Periods of inclement weather, to include poor visibility, would be used to fully evaluate the test systems. TTI has satellite facilities in Houston, Dallas, and San Antonio in close proximity to both signalized arterials and urban freeways where systems could be deployed for a prescribed test period.

One of the fundamental issues to be addressed by the FHWA is the manner in which such centers will be funded, and furthermore, whether they can be self-sufficient. Your contacts with detector manufacturers will provide insight into their willingness to participate in funding all or part of the expense involved in testing their products. The manufacturer's perspective must consider the benefits to them in having a facility that can conduct qualitative testing in an unbiased manner. The primary question for them is, *Why should the manufacturers want to pay to have a device tested*? Possible answers to this question include the following:

- 1. A law has been passed requiring manufacturers to pay for testing.
- 2. Manufacturers hope to reduce potential litigation due to product failure.
- 3. Customers will not buy the device unless it has undergone rigorous testing.
- 4. Manufacturers hope to gain a competitive advantage by having their detection system thoroughly tested.

Adherence to electrical and other codes for safety falls within the realm of Item 1. Manufacturers of vehicle detection devices routinely submit their equipment for testing by Underwriters Laboratories. This program also addresses Item 2.

Item 3 is prevalent in many devices and products evaluated under the National Type Testing program of the National Institute of Standards and Technology (NIST). In this program, standards and test procedures are developed or adopted from some other source, such as the American Society for Testing and Materials (ASTM) or the American National Standards Institute (ANSD). NIST then approves testing agencies to whom manufacturers submit sample equipment for evaluation and pay a fee for the service.

If the device passes the relevant tests in the National Type Testing program, it is certified as having done so. Customers then will purchase the device if it otherwise meets their needs based on cost, quality, service, and so forth. The device does not have to undergo rigorous testing by every purchaser.

Item 4 would be important to a manufacturer that has a device that is clearly superior to the competition and wants to make that fact known. For example, if a manufacturer has based a product on new technology that is not yet incorporated into its competitor's products, it might want an independent laboratory to compare the two and publish the results.

If I can be of further assistance to you in your current research effort, or if you want to discuss TTI's interest in the detector test and evaluation center, please do not hesitate to give me a call.

Sincerely,

Dan Middleton, P.E. Assistant Research Engineer

cc: Tom Urbanik

Figure A-5. Reply from the Texas Transportation Institute at Texas A&M Concerning National Detector Test and Evaluation Facilities (continued)

centers such as the Highway Innovative Technology Evaluation Center; and

- Identified sources of income from states, counties, other municipal agencies, and manufacturers as sponsors of the test center; testing fees from manufacturers; and startup funds.
- Developed three budgets based on:
 - No memberships in the test center by sponsor states or manufacturers in the first year of operation;
 - Greater reduction in membership growth, staffing, and testing than in the first budget;
 - No memberships in the test center by sponsor states or manufacturers in the first year, reduced membership growth, and staffing reduced to two professionals.

The group recommended that the testing program initially evaluate volume counters, vehicle classifiers, speed monitors, and weigh-in-motion equipment. The types of traffic devices evaluated in the Detection Technology program were not specifically included in the New Mexico State program. However, they can certainly be added as devices to be tested if the proper personnel and test equipment are made available.

In the Fall of 1994 a report was issued that identified:

• A mission statement for a national test center;

- Types of testing to be included (pre-qualification, quality control, and verification);
- A test flow procedure;
- Identification of typical concerns that transportation agencies and detector manufacturers may have;
- Funding options that include income from full memberships, associate memberships, and testing fees; and
- Management structure for the test facility.

Their future plans include finalizing a business plan after review by the states and detector manufacturers, preparing a report on test procedures, and obtaining startup funds and memberships.

A.3 RECOMMENDATIONS

- Continue to explore where the detection technology evaluation facilities should be located;
- Establish a process to select a facility manager and center management procedures that include inputs from the IVHS Research Centers of Excellence;
- Review the facility funding options developed under the New Mexico State University contract for realism;
- Obtain firm commitments from traffic management agencies to use the results of the detection technology evaluation facility as this will induce detector manufacturers to support the facility with equipment and testing fees.

APPENDIX B. DETECTOR MANUFACTURERS AND CONTACT PEOPLE

AT&T

1919 South Eads Street, Suite 300 Arlington, VA 22202-2886 (703) 271-7319; Fax (703) 271-7676 Attention: Greg Pieper or Joe Lee at (919) 279-7744

Computer Recognition Systems 639 Massachusetts Avenue Cambridge, MA 02139 (617) 491-7665 Fax (617) 491-7753 Attention: Sal D'Agostino

Condition Monitoring Systems 2412 East First Street Long Beach, CA 90803 (310) 438-4875 Attention: Kay Dermer or Bob Nasburg

Detector Systems 661 Distel Drive Los Altos, CA 94022 (415) 948-6243 Fax (415) 949-1651 Attention: John Kluga or Gary Mayder at (800) 828-7775

Econolite/Autoscope 3360 East La Palma Avenue Anaheim, CA 92806-2856 (714) 630-3700 Fax (714) 630-6349 Attention: Gary Duncan

Electronic Integrated Systems, Inc. 150 Bridgeland Avenue North York, Ontario, Canada M6A 1Z5 (416) 785-9248 Fax (416) 785-9332 Attention: Dan Manor

Eltec Instruments, Inc. P.O. Box 9610 Daytona Beach, FL 32120 (800) 874-7780 or (904) 252-0411 Fax (904) 258-3791 Attention: David Cima (Technical) Douglas Armstrong (Sales and Mktg) Eva, Inc. 300 Montgomery Street Suite 633 San Francisco, CA 94104 (415) 433-7653; Fax (415) 433-7654 Attention: Ignacio Lopez or Renato Martínez

Golden River Traffic Ltd. Churchill Road, Bicester Oxfordshire, OX6 7XT England 011 44 869 240400 Fax 011 44 869 246858 Attention: Michael Dalgleish

Image Sensing Systems 1600 University Avenue West Suite 500 St. Paul, MN 55104-3825 (612) 642-9904 Attention: Craig Anderson

Intelligent Vision Systems, Inc. 6575 West Loop South Suite 498 Bellaire, TX 77401 (713) 662-0004 Fax (713) 662-3147 Attention: Paul Mayeaux

Max Kutter, Inc. 16150 Lindbergh Street Van Nuys, CA 91406 (818) 994-0953 Fax (818) 994-2780 Attention: Ralph Ferguson

Microsense Inc. 4800 Bethania Station Road Winston-Salem, North Carolina 27105-1201 (919) 744-5333 Fax (919) 744-5054 Attention: Ann Hayes

Microwave Sensors 7885 Jackson Road Ann Arbor, MI 48103 (800) 521-0418 Fax (313) 426-5950 Attention: Don Johnston or Bob Hunter Midian Electronics, Inc. 2302 East 22nd Street Tucson, AZ 85713 (602) 884-7981 Fax (602) 884-0422 Attention: Chuck Soulliard or Bud Ward

Northrop-Grumman Corporation 1111 Stewart Avenue Bethpage, NY 11714-3580 Attention: Joseph Franachio, M.S. 0835 (516) 346-2769 or 575-3294 Fax (516) 346-3670

Schwartz Electro-Optics, Inc. 3404 North Orange Blossom Trail Orlando, FL 32804 (407) 298-1802 Fax (407) 297-1794 Attention: Robert Gustavson or Bob Hoffman

Sumitomo Electric U.S.A., Inc. 3235 Kifer Road Suite 150 Santa Clara, CA 95051 (408) 737-8517 Fax (408) 737-0134 Attention: Takehiko Barada Traficon N.V: Bissegemsestraat 45 B-8501 Kortrijk, Belgium + 32 56 37 22 00 Fax + 32 56 37 21 96 Attention: Jo Versavel

3M Center Building 225-4N-14 St. Paul, MN 55144-1000 (612) 733-4056 Fax (612) 736-2298 Attention: George Palm or Earl Hoekman at (612) 733-6416

Timemark, Inc. P.O. Box 12947 Salem, OR 97309 (800) 755-5882 or (503) 363-2012 Fax (503) 363-1716 Attention: Dan Gossack

Whelen Engineering Company Route 145, Winthrop Road Chester, CT 06412-0684 (203) 526-9504 Fax (203) 526-4078 Attention: Tom Fredericks

APPENDIX C. DATA LOGGER

C.1 FUNCTION OF DATA LOGGER

The data logger system, shown in Figure C-1, simultaneously time tags and records data output by the detectors under test. It also includes software and hardware that permit later data analysis and the overlay of selected detector output data on imagery previously

recorded on video tape.⁽¹⁾ Typical recorded detector data are vehicle count, presence, speed, lane occupancy, and classification, depending on the specific detector. Some detectors output both discrete and serial (RS-232) traffic parameter data, while others output only discrete data using Form C relay closures or optically isolated outputs.

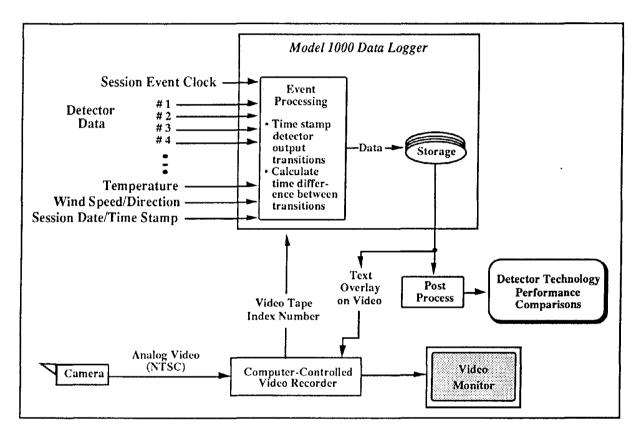


Figure C-1. Data Logger Recording and Analysis System

The application-specific Phase II software, represented by the Post Process box, converts the raw data into comma-delineated fields that can then be transformed into a database format using almost any commercial database software. Paradox database software was used in this project to extract similar output data from several detectors for display as a function of time or another variable, and as inputs to analysis programs that calculated their mean values and standard deviations. Mathcad, KaleidaGraph, and custom FORTRAN

e Se di programs were used to analyze and generate plots of the data. Selected detector outputs or analysis results can also be superimposed onto the video tape that was recorded during the data collection process. Superimposed information includes detector technology type, associated traffic parameters (e.g., count and speed), and mean and standard deviation of the traffic data parameter. The visual presentation facilitates a qualitative comparison of the performance of the different detector technologies.

C.2 TYPES OF DETECTOR OUTPUTS SUPPORTED

Up to 16 serial detector outputs, 40 optically isolated outputs, 16 Form C relay closure outputs, and 8 analog outputs that include environmental data (e.g., temperature, wind speed, wind direction) and analog detector outputs, such as Doppler frequency, can be recorded. The first 16 optically isolated outputs are monitored by the main logger chassis shown in Figure C-2 and the remaining 24 by an auxiliary opto chassis. The auxiliary opto chassis is connected to the main logger by power and data cables as shown in Figure C-3. The lower portion of the figure describes how to verify that an opto module on the data logger is functioning properly.

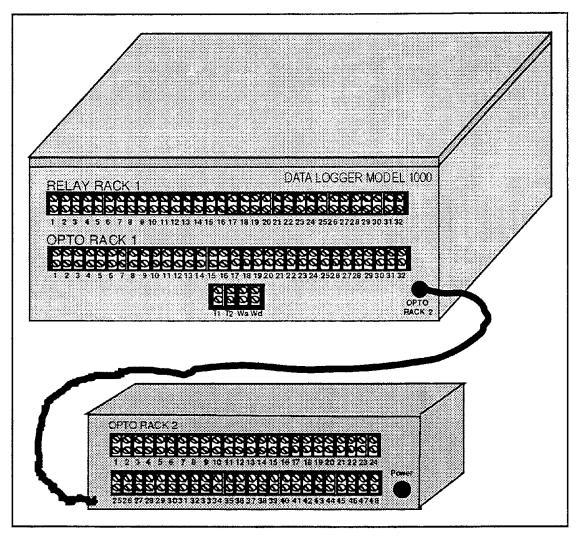


Figure C-2. Data Logger Main and Auxiliary Chassis

C.3 MAJOR DATA LOGGER ASSEMBLIES

The data logger consists of five major assemblies, namely a main processing unit (MPU), removable storage unit (RSU), intelligent serial interface system (ISIS), discrete interface system (DIS), and video control system (VCS).

C.3.1 Main Processing Unit

The main processing unit consists of a personal computer (PC) containing an Intel 80386 40-MHz processor in an advanced technology (AT) architecture, 8 megabytes (MB) of random access memory (RAM), 80

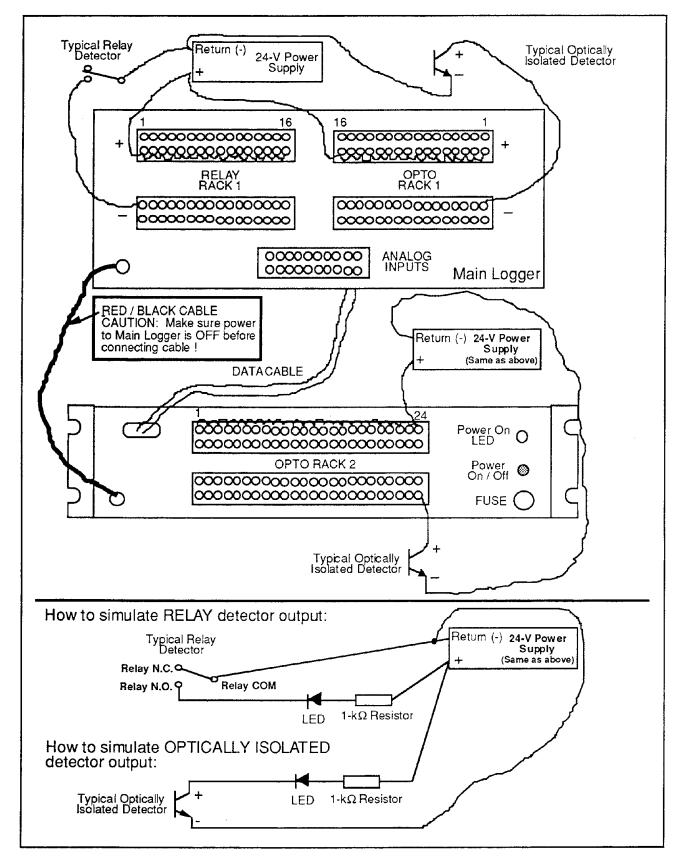


Figure C-3. Connection of Auxiliary Data Logger Opto Chassis to Main Data Logger Along with Test Connections for Verifying Proper Opto Operation MB of hard-disk storage, video graphics adapter, two serial ports, and one parallel port. The MPU stores and executes the operating system, application-specific software, and user interface. The RSU, ISIS, DIS, and VCS are connected to the MPU either through the internal bus or via the external serial and parallel connectors.

C.3.2 Removable Storage Unit

The removable storage unit consists of an external hard drive that stores data on 88-MB cartridges, an internal high-density 5.25-inch (1.2-MB) floppy disk drive, and an internal high-density 3.5-inch (1.44-MB) floppy disk drive. The external drive is connected to the MPU through the parallel connector, while the floppy drives are connected internally through the bus.

C.3.3 Intelligent Serial Interface System

The intelligent serial interface system uses a 16-channel Digiboard to transfer serial outputs from the detector outputs to the 88-MB cartridges and to communicate with other components in the data logger. Specific Digiboard ports communicate with video image processors, computer-controlled video cassette recorders (VCRs), non-imaging detectors, and the DIS. The ISIS is connected to the MPU through the internal bus.

C.3.4 Discrete Interface Subsystem

The discrete interface subsystem is based on an Opto 22 industrial process controller. It uses a digital brain board to communicate from the local controller to the digital input modules that accept the 40 optically isolated outputs and 16 Form C relay closure outputs. An analog brain board executes communications from the local controller to the analog input modules that accept up to eight analog detector or environmental sensor outputs. The DIS is connected to the MPU through the internal bus.

C.3.5 Video Control System

The video control system consists of up to three VCRs and the distribution amplifiers, video switcher, and video monitor required for recording, distributing, switching, and displaying the video signals, respectively. Connections to the VCS are through the ISIS.

C.4 DATA ANALYSIS SOFTWARE

The data recording and analysis flow is shown in Figure C-4. MS-DOS is used as the operating system and Windows 3.1 as the graphical user interface. The Phase II software hosted on the PC performs three functions:

- Displays specific screens for each of the detectors under test so that the detector input connections to the data logger are easily recorded,
- (2) Contains detector data conversion software that transforms the recorded raw data record into a comma-delimited, databasecompatible record, and
- (3) Supports the overlaying of selected detector data onto the video tape.

Paradox allows the data to be segregated by detector technology, time of run, weather, data type, or any combination of criteria desired. Paradox can also perform some data analysis, such as vehicle speed calculation using vehicle detection times recorded by two appropriately positioned optically isolated detectors (or from one detector having two optically isolated outputs available). Mathcad analyzes the selected data and summarizes the data in the form of tables, graphs, and statistical measures.

C.5 DATA RECORDING

The analog outputs from the detectors that are connected to the analog input modules are polled at 10-millisecond intervals. Exceptions are the wind speed and temperature sensors that are sampled at 10-second intervals because of their more slowly varying data. The time of an event captured by a detector using relay outputs is recorded when the relay output returns to its deactivated state. The time between relay activation and deactivation is also recorded as the pulse width. Relay output levels, such as

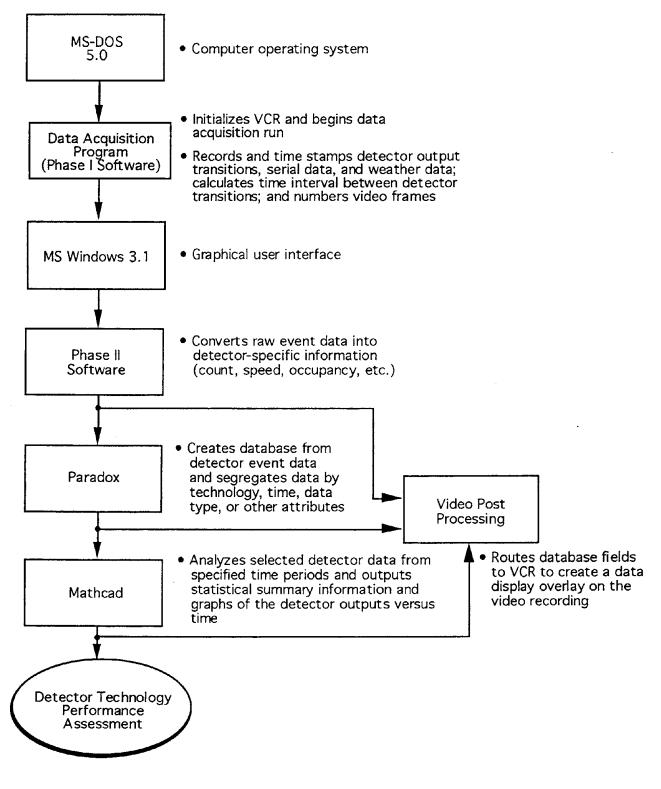
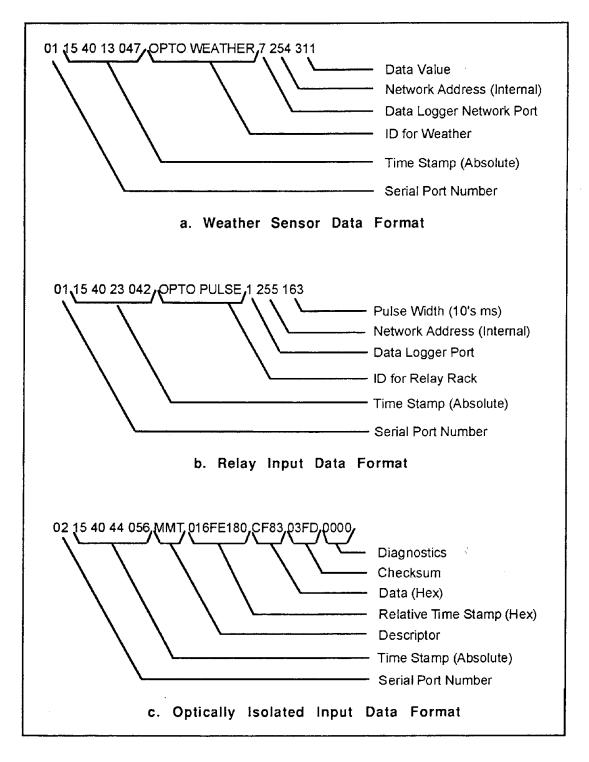


Figure C-4. Data Recording and Analysis Flow

those from Form C relays, are measured with 10-millisecond resolution. The recording of optically isolated detector outputs is event driven. When an event such as vehicle passage occurs, the time at which the level of the appropriate optically isolated output changes is recorded relative to the number of 250-microsecond intervals that have elapsed since the data logger was turned on. RS-232 serial data are recorded as events occur.

Records containing the serial input port number, absolute time stamp (generated by the PC), detector identification, data address, and data value are stored on the 88-MB cartridge in ASCII format to facilitate readability, portability, and post analysis. Records from the optically isolated detector outputs contain two additional pieces of

information, a relative time stamp that contains the number of 250-microsecond intervals that have elapsed since the data logger was turned on and a checksum. The weather sensors, analog detector outputs, and Form C relays use serial port 01 to input data that are recorded by the data logger. The weather data format is shown in Figure C-5a and the relay data format in Figure C-5b. Optically isolated detector outputs are recorded on serial port 02 in the format shown in Figure C-5c. The video frame numbers are synchronized with the absolute time stamp using serial port 05, as shown in Figure C-5d. Detectors with RS-232 serial outputs use ports 06 through 20. An example of a serial detector data record is shown in Figure C-5e.





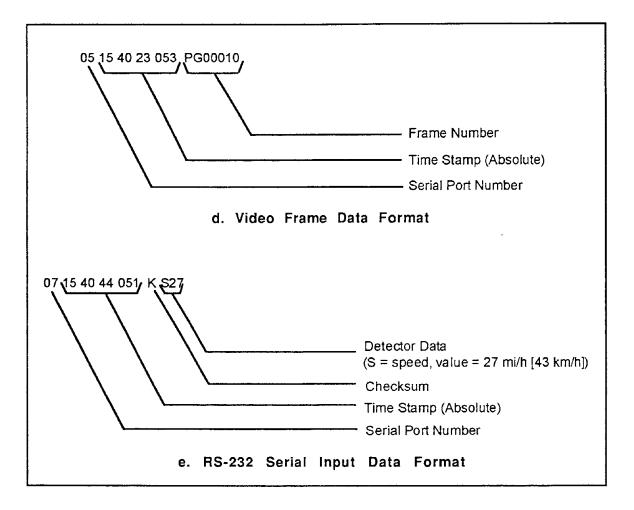


Figure C-5. Detector Input Data Formats as Recorded by Data Logger (continued)

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REFERENCES

1. Klein, Lawrence A., MacCalden, Jr., M. Scot, and Mills, Milton, "Detection Technology for IVHS," Presented at IVHS AMERICA Third Annual Meeting, April 1993, Washington, D.C.

APPENDIX D.

CONCEPTUAL DESIGN OF AN FMCW MICROWAVE RADAR THAT RESOLVES MULTIPLE VEHICLES IN ITS FIELD OF VIEW

D.1 FMCW WAVEFORM PARAMETERS

The triangular FMCW (frequency-modulated continuous wave) waveform shown in Figure D-1 illustrates the vehicle range and speed information contained in the received signal. The range information is contained in the instantaneous frequency difference Δf between the backscattered signal received at the radar (corresponding to the frequency transmitted

at time t_1) and the radar's present transmitted frequency (corresponding to the frequency at time t_2). In the absence of Doppler frequencies, the frequency difference is the same for the upsweeps and downsweeps of the waveform and is proportional to the time delay *T* between transmission of a segment of the waveform and the reception of the backscattered signal from that same segment.

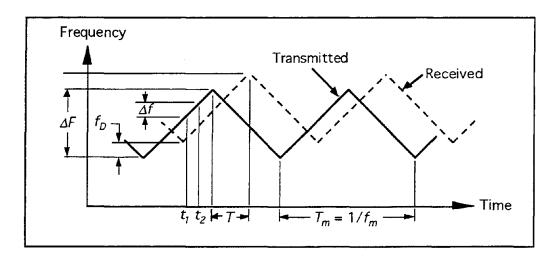


Figure D-1. Two-Segment FMCW Waveform and Defining Parameters

Thus,

$$\Delta f = \frac{2 \ \Delta F \ T}{T_m} \qquad (D-1)$$

where

- ΔF = radio frequency (RF) modulation bandwidth equal to the difference between the highest f_H and lowest f_L frequencies in the transmitted wave and
- T_m = modulation period.

The range *R* is calculated from the waveform parameters as

$$R = \frac{c\Delta f}{4\Delta F f_m} \qquad (D-2)$$

where *c* is the speed of light and f_m is the RF modulation rate equal to $1/T_m$. Equations D-1 and D-2 can be derived from one another by using the relation

$$R = c T/2 \qquad (D-3)$$

A Doppler-shifted target modifies the received waveform by producing two difference frequencies as shown in the figure, one for the upsweep δf_u and one for the downsweep δf_d . The frequencies δ_u and δf_d contain both the Doppler shift frequency and the frequency shift caused by target range.

When the Doppler shift is smaller than the range shift, δf_{u} represents the difference between the range and Doppler frequencies, and δf_{d} represents the sum of the two frequencies. Assuming the slopes of the two sweeps are additive inverses (equal magnitudes, different signs) leads to the calculation of the Doppler shift frequency component f_{D} and range shift frequency component Δf as

$$f_D = (\delta f_d - \delta f_u)/2 \qquad (D-4)$$

$$\Delta f = (\delta f_d + \delta f_u)/2 \qquad (D-5)$$

D.2 RESOLVING MULTIPLE VEHICLES IN THE FOOTPRINT

If two or more vehicles are present in the radar antenna footprint, then each produces a backscatter signal at the radar with each signal having a unique instantaneous frequency difference. The composite signal is the sum of the backscattered signals. A spectrum analysis of the upsweep and down-sweep frequency differences gives the individual vehicles in different frequency bins, assuming they are resolvable in range and Doppler frequency. An example of such spectra is given in Figure D-2.⁽¹⁾

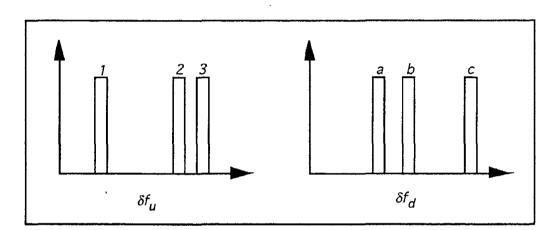


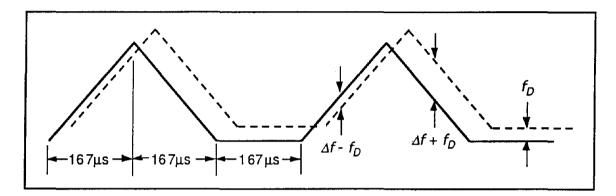
Figure D-2. Spectra Corresponding to Upsweep and Downsweep Frequencies

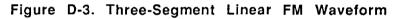
As shown, the spectra do not contain information that links an upsweep difference frequency (1, 2, 3) to a downsweep difference frequency (a, b, c). Therefore, vehicles detected by a waveform of the type shown in Figure D-1 produce scrambled return signals. To unscramble the information. an unmodulated third waveform segment is added. The Doppler shifts of the multiple vehicles are obtained from a spectrum analysis of the returns produced by the unmodulated continuous wave segment. Then through trial-and-error pairing of the upsweep and downsweep difference frequencies, pairings are found that produce the same Doppler shifts as the unmodulated waveform segment.

The following example illustrates this concept. Suppose that the radar illumination

waveform is as shown in Figure D-3. Each sweep segment is 167 μ s in duration. This corresponds to a Doppler resolution of 6000 Hz, more than three times that produced by a vehicle traveling at 96.6 km/h (60 mi/h) illuminated by a radar operating at a center frequency of 10.525 GHz. The RF bandwidth is 45 MHz to lie within the Federal Communications Commission (FCC) limit of 50 MHz.

Suppose the spectrum analysis of the upsweep shows three echoes at 70.433 kHz, 88.276 kHz, and 106.12 kHz; the downsweep three echoes at 73.567 kHz, 91.724 kHz, and 109.88 kHz; and the unmodulated segment three echoes at 1567 Hz, 1724 Hz, and 1880 Hz. The task is to find the range and speed of the three vehicles. It is known from the unmodulated waveform segment that three Doppler shifts are present: 1567 Hz, 1724 Hz, and 1880 Hz. Assume the upsweep frequency of 70.433 kHz is paired with the downsweep frequency of 91.724 kHz. From equation D-4, the Doppler shift of this pairing is 10.645 kHz. This does not match one of the known Doppler shifts and, therefore, this pairing must be incorrect. Next, we pair the 70.433-kHz upsweep with the 73.567-kHz downsweep. This gives a Doppler shift of 1567 Hz, which is one of the known Doppler frequencies. This pairing could, therefore, be correct. As a check, pairing the 88.276-kHz upsweep with the 91.724 Hz downsweep gives a Doppler of 1724 Hz that is, again, one of the known Doppler frequencies. The final pairing of the 106.12-kHz upsweep with the 109.88-kHz downsweep gives the last Doppler frequency.





The range to the vehicles can be calculated from the paired upsweep and downsweep frequencies using equations D-5 and D-2. Thus, the range to the vehicle with the 1567-Hz Doppler shift is 40 m, to the vehicle with the 1724-Hz Doppler is 50 m, and to the vehicle with the 1880-Hz Doppler is 60 m.

The radial velocity v_R of the vehicles is found by converting the Doppler frequency to velocity using

$$v_R = \frac{cf_D}{2f} \tag{D-6}$$

where *f* is the transmitted frequency of 10.525 GHz. Applying this equation gives speeds of 22.3 m/s (50 mi/h), 24.6 m/s (55 mi/h), and 26.8 m/s (60 mi/h) for the three vehicles, respectively.

REFERENCES

1. Edde, Byron, *Radar: Principles, Technology, Applications*, PTR Prentice Hall, Englewood Cliffs, NJ, 1993.

APPENDIX E.

PIPE TREE INSTALLATION AND INTERSECTION PLAN-VIEW DRAWINGS FOR MINNEAPOLIS SITES

This appendix contains portions of the drawings made for attaching the pipe trees to the overpass at I-4 and Penn Avenue and the

sign bridge at Olson Highway and Lyndale Avenue North. Plan-view drawings of the two sites are also provided.

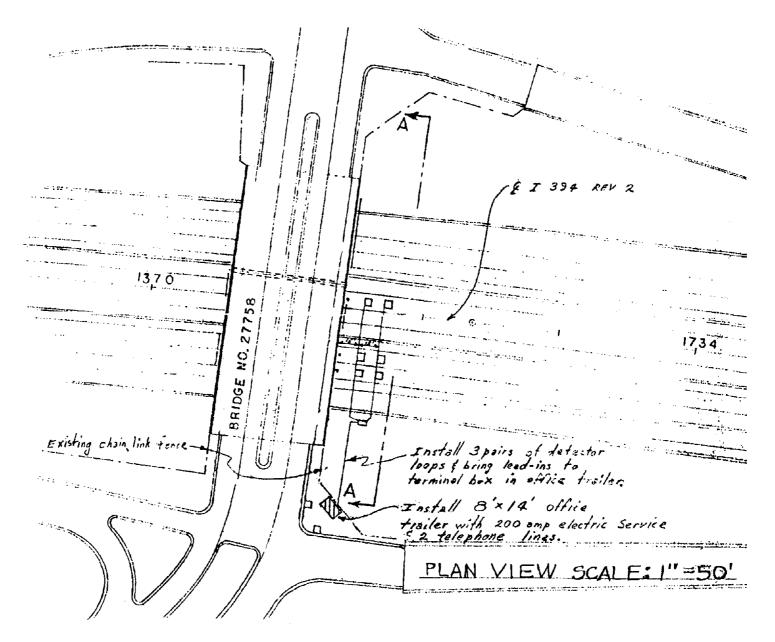
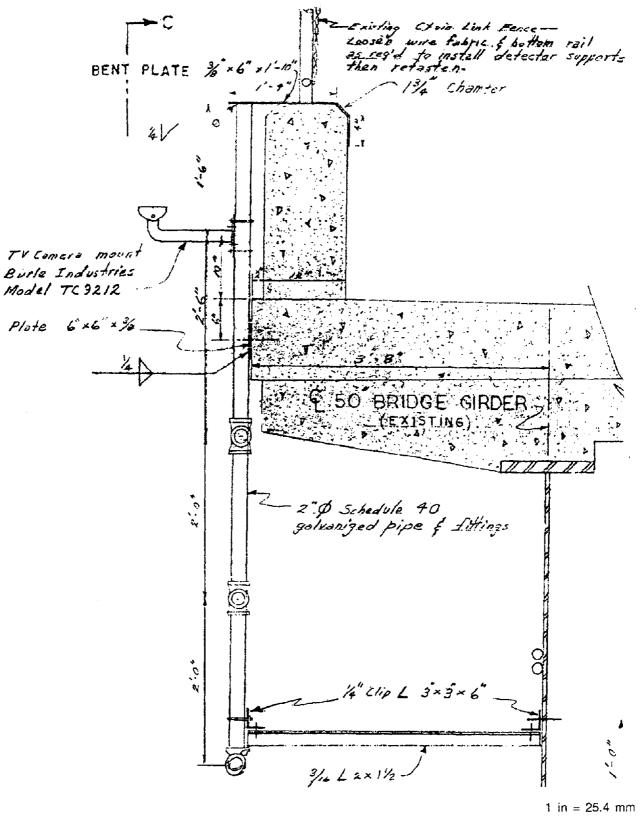
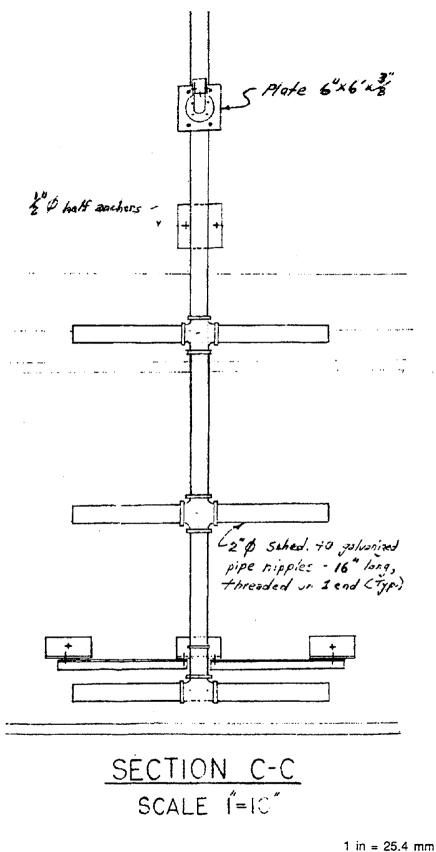


Figure E-1. Plan View of I-394 and Penn Avenue Site



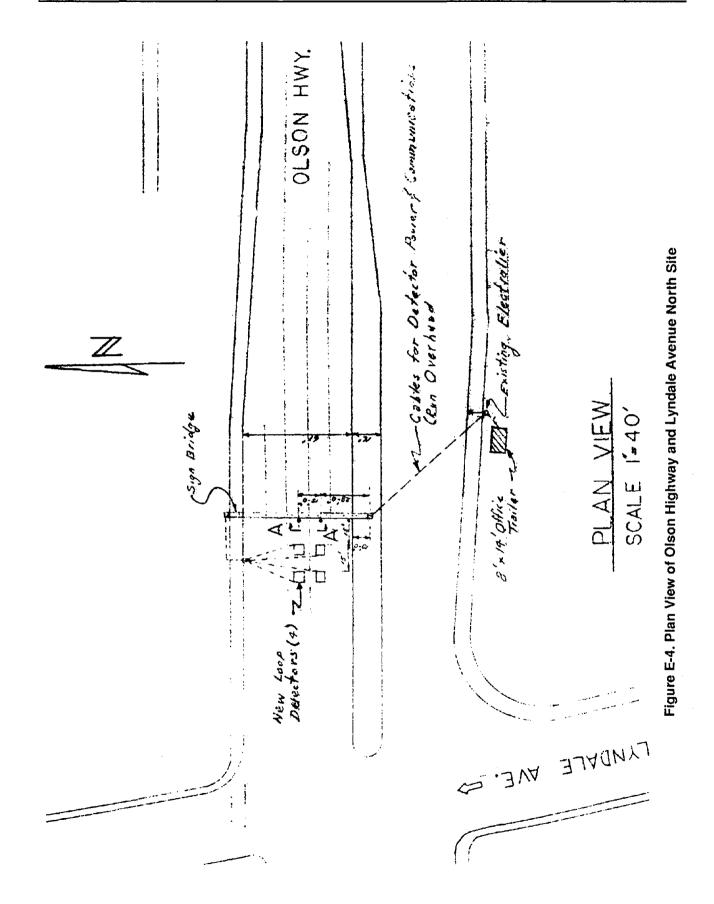
1 ft = 0.305 m

Figure E-2. Mounting of Pipe Trees to Penn Avenue Bridge Girder



1 in = 25.4 mm 1 ft = 0.305 m





E-5

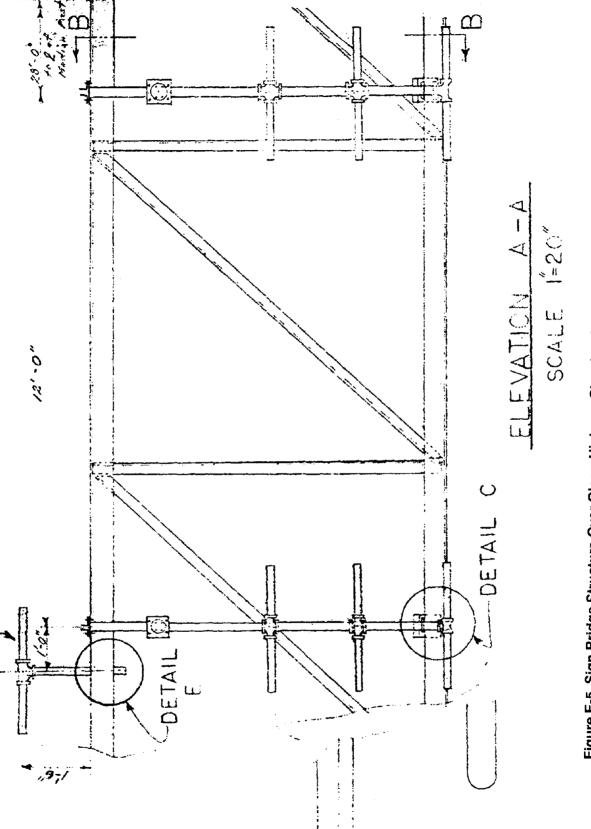
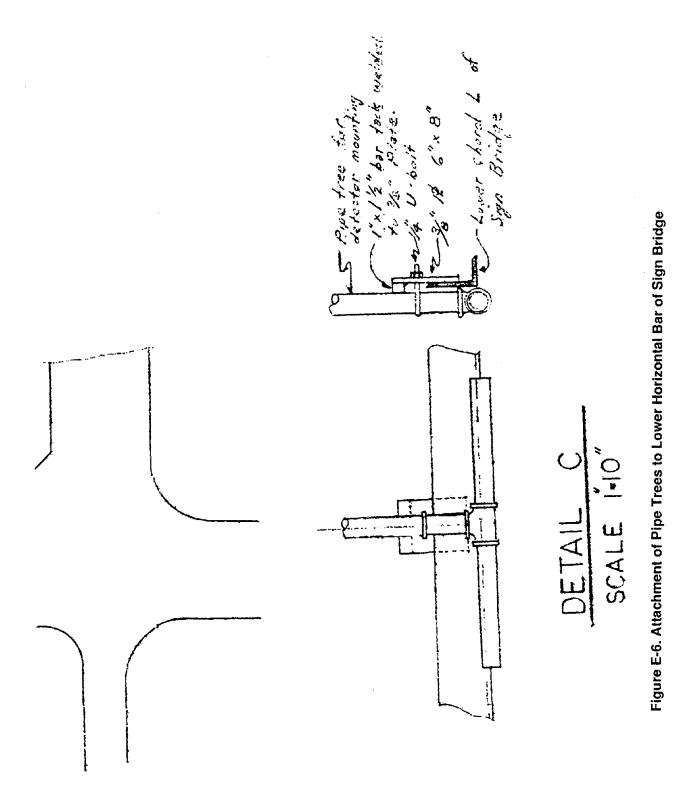
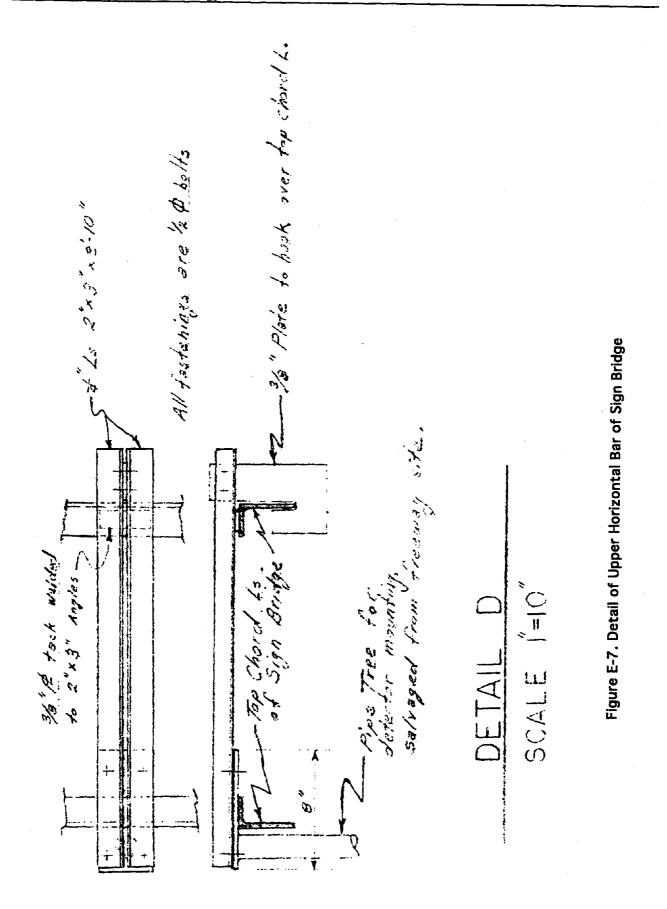
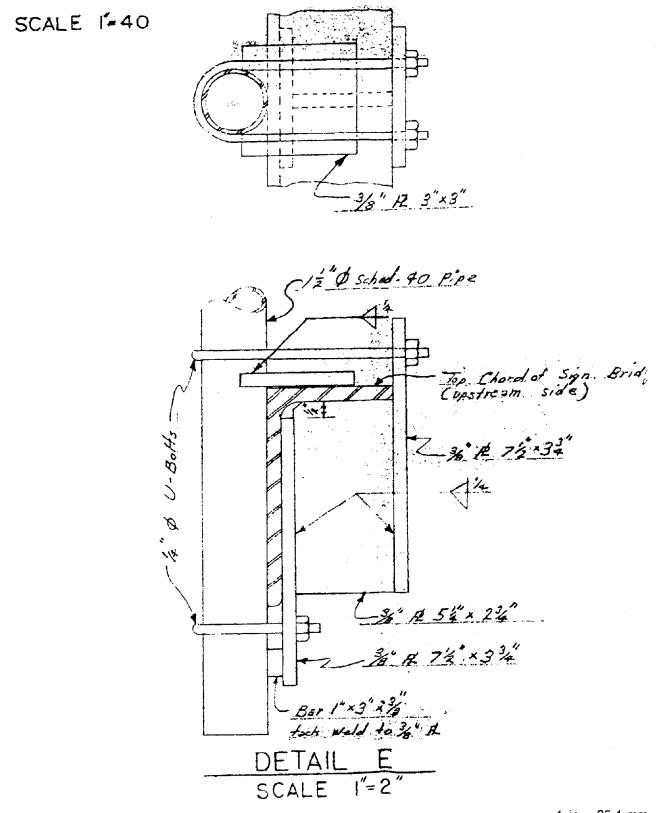


Figure E-5. Sign Bridge Structure Over Olson Highway Showing Attachment of Pipe Trees





E-8



1 in = 25.4 mm1 ft = 0.305 m

Figure E-8. Attachment of Pipe Tree to Upper Horizontal Bar of Sign Bridge

APPENDIX F.

DETECTOR FOOTPRINTS AS A FUNCTION OF APERTURE BEAMWIDTH, MOUNTING HEIGHT, AND ANGLE OF INCIDENCE

The theoretical azimuth and elevation ground footprint areas of the detectors are given in the following tables as a function of mounting height, azimuth and elevation aperture beamwidth, and angle of incidence (with respect to nadir). The detectors for which these data are available are the TC-20, TC-26, TDN-30, TDW-10, RTMS-X1, TC-30C, SDU-200 (RDU-101), SDU-300, and the 780D1000 (Autosense I).

The data in the tables were generated at more viewing angles and mounting heights than were actually used in the laboratory tests so that a database of detector footprints would be available for future applications or tests.

The azimuth footprint length L_{az} is calculated from

$$L_{az} = (2H \tan \theta_{az}/2)/\cos \theta \qquad (F-1)$$

where

H = detector mounting height above the highway surface,

 θ_{az} = 3-dB azimuth beamwidth corresponding to the detector aperture,

 θ = viewing angle with respect to nadir.

The elevation footprint length L_{el} is calculated from

$$L_{\theta l} = H[\tan(\theta + \theta_{\theta l}/2) - \tan(\theta - \theta_{\theta l}/2)]$$
(F-2)

where

 θ_{el} = 3-dB elevation beamwidth corresponding to the detector aperture.

The first term in equation F-2 gives the maximum range in the elevation plane and the second term gives the minimum range in the elevation plane.

The 3-dB beamwidths were obtained from the detector manufacturers, either from data sheets or from telephone conversations.

			Microwave S	ensors TC-20 & TC-20	5		
Mounting	Viewing	Azimuth	Azimuth	Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint	3dB BW	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)	(deg)	(Feet)	(Feet)	(Feet)
10.0	20.0	16.0	3.0	15.0	5.2	2.2	3.0
12.0	20.0	16.0	3.6	15.0	6.2	2.7	3.6
15.0	20.0	16.0	4.5	15.0	7.8	3.3	4.5
17.0	20.0	16.0	5.1	15.0	8.8	3.8	5.1
20.0	20.0	16.0	6.0	15.0	10.4	4.4	6.0
22.0	20.0	16.0	6.6	15.0	11.5	4.9	6.6
25.0	20.0	16.0	7.5	15.0	13.0	5.5	7.5
30.0	20.0	16.0	9.0	15.0	15.6	6.7	9.0
	-						
Mounting	Viewing	Azimuth	Azimuth	Elevation	Maximum		******************************
Height	Angle	3dB BW	Footprint	3dB BW	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)	(deg)	(Feet)	(Feet)	(Feet)
10.0	30.0	16.0	3.2	15.0	7.7	4.1	3.5
12.0	30.0	16.0	3.9	15.0	9.2	5.0	4.2
15.0	30.0	16.0	4.9	15.0	11.5	6.2	5.3
17.0	30.0	16.0	5.5	15.0	13.0	7.0	6.0
20.0	30.0	16.0	6.5	15.0	15.3	8.3	7.1
22.0	30.0	16.0	7.1	15.0	16.9	9.1	7.8
25.0	30.0	16.0	8.1	15.0	19.2	10.4	8.8
30.0	30.0	16.0	9.7	15.0	23.0	12.4	10.6
Mounting	Viewing	Azimuth	Azimuth	Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint	3dB BW	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)	(deg)	(Feet)	(Feet)	(Feet)
10.0	45.0	16.0	4.0	15.0	13.0	7.7	5.4
12.0	45.0	16.0	4.8	15.0	15.6	9.2	6.4
15.0	45.0	16.0	6.0	15.0	19.5	11.5	8.0
17.0	45.0	16.0	6.8	15.0	22.2	13.0	9,1
20.0	45.0	16.0	8.0	15.0	26.1	15.3	10.7
22.0	45.0	16.0	8.7	15.0	28.7	16.9	11.8
25.0	45.0	16.0	9.9	15.0	32.6	19.2	13.4
30.0	45.0	16.0	11.9	15.0	39.1	23.0	16.1
Mounting	Viewing	Azimuth	Azimuth	Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint	3dB BW	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)	(deg)	(Feet)	(Feet)	(Feet)
	70.0			4.5.0		10.0	05.0
10.0	70.0	16.0	8.2	15.0	45.1	19.2	25.9
12.0	70.0 70.0	16.0	9.9 12.3	15.0	54.1	23.1	31.1
17.0	70.0	<u>16.0</u> 16.0	12.3	15.0	67.7	28.8	<u>38.8</u> 44.0
20.0	70.0	16.0	16.4	<u> </u>	<u>76.7</u> 90.2	<u>32.7</u> 38.4	<u></u>
22.0	70.0	16.0	18.1	15.0	90.2	42.3	57.0
25.0	70.0	16.0	20.5	15.0	112.8	42.3	64.7
	,		ະ ພູບ,ບີ ໂ	N 10.0 1	116.0		U-+ . /

	*****		Whelen TDN-30				
	Vita sulta a				1 1	3	Flamatics
Mounting Height	Viewing Angle	Azimuth 3dB BW	Azimuth Footprint	Elevation 3dB BW	Maximum Range	Minimum Range	Elevation Footprin
(Feet)	(deg)	(deg)	(Feet)	(deg)	(Feet)	(Feet)	(Feet)
(1001)	(deg)	(ueg)	11000		(reer)	(/ eet)	(1 eet)
10.0	20.0	7.0	1.3	7.0	4.3	3.0	1.4
12.0	20.0	7.0	1.6	7.0	5.2	3.6	1.7
15.0	20.0	7.0	2.0	7.0	6.5	4.4	2,1
17.0	20.0	7.0	2.2	7.0	7.4	5.0	2.4
20.0	20.0	7.0	2.6	7,0	8.7	5.9	2.8
22.0	20.0	7.0	2.9	7.0	9.6	6.5	3.0
25.0	20.0	7.0	3.3	7.0	10.9	7.4	3.5
30.0	20.0	7.0	3.9	7.0	13.0	8.9	4.2
Mounting	Viewing	Azimuth	Azimuth	Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint	3dB BW	Range	Range	Footprin
(Feet)	(deq)	(deq)	(Feet)	(deg)	(Feet)	(Feet)	(Feet)
						hand the second second second	······
10.0	30.0	7.0	1.4	7.0	6.6	5.0	1.6
12.0	30.0	7.0	1.7	7.0	7.9	6.0	2.0
15.0	30.0	7.0	2.1	7.0	9.9	7.5	2.4
17.0	30.0	7.0	2.4	7.0	11.3	8.5	2.8
20.0	30.0	7.0	2.8	7.0	13.2	10.0	3.3
22.0	30.0	7.0	3.1	7.0	14.6	11.0	3.6
25.0	30.0	7.0	3.5	7.0	16.5	12.5	4.1
30.0	30.0	7.0	4.2	7.0	<u> 19.9 </u>	15.0	4.9
Mounting	Viewing	Azimuth	Azimuth	Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint	3dB BW	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)	(deg)	(Feet)	(Feet)	(Feet)
		<u></u>				······	
10.0	45.0	7.0	1.7	7.0	11.3	8.8	2.5
12.0	45.0	7.0	2.1	7.0	13.6	10.6	2.9
15.0	45.0	7.0	2.6	7.0	17.0	13.3	3.7
17.0	45.0	7.0	2.9	7,0	19.2	15.0	4.2
20.0	45.0	7.0	3.5	7.0	22.6	17.7	4.9
22.0	45.0	7.0	3.8	7.0	24.9	19.5	5.4
25.0	45.0	7.0	4.3	7.0	28.3	22.1	6.1
30.0	45.0	7.0	5.2	7.0	33.9	26.5	7.4
Mounting	Viewing	Azimuth	Azimuth	Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint	3dB BW	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)	(deg)	(Feet)	(Feet)	(Feet)
10.0	70.0	7.0	3.6	7.0	33.8	23.0	10.8
12.0	70.0	7.0	4.3	<u> </u>	40.5	27.6	12.9
15.0	70.0 70.0	7.0	5.4 6.1	7.0	50.6 57.4	34.5 39.1	<u>16.1</u> 18.3
20.0	70.0	7.0	7.2	7.0	67.5	46.0	21.5
22.0	70.0	7.0	7.9	7.0	74.3	50.6	23.7
25.0	70.0	7.0	8.9	7.0	84.4	57.5	26.9
		7.0	······	7.0	~ 7 . 7	69.0	32.3

1 ft = 0.305 m

			Whelen TDW-10				
Mounting	Viewing	Azimuth	Azimuth	Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint	3dB BW	Range	Range	Footprin
(Feet)	(deg)	(deg)	(Feet)	(deg)	(Feet)	(Feet)	(Feet)
						·····	
10.0	20.0	25.0	4.7	25.0	6.4	1.3	5.1
12.0	20.0	25.0	5.7	25.0	7.6	1.6	6.1
15.0	20.0	25.0	7.1	25.0	9.6	2.0	7.6
17.0	20.0	25.0	8.0	25.0	10.8	2.2	8.6
20.0	20.0	25.0	9.4	{ 25.0	12.7	2.6	10.1
22.0	20.0	25.0	10.4	25.0	14.0	2.9	11.1
25.0	20.0	25.0	11.8	25.0	15.9	3.3	12.6
30.0	20.0	25.0	14.2	25.0	19.1	3.9	15.2
Mounting	Viewing	Azimuth	Azimuth	Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint	3dB BW	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)	(deg)	(Feet)	(Feet)	(Feet)
			<u> </u>				
10.0	30.0	25.0	5.1	25.0	9.2	3.2	6.0
12.0	30.0	25.0	6.1	25.0	11.0	3.8	7.2
15.0	30.0	25.0	7.7	25.0	13.7	4.7	9.0
17.0	30.0	25.0	8.7	25.0	15.6	5.4	10.2
20.0	30.0	25.0	10.2	25.0	18.3	6.3	12.0
22.0	30.0	25.0	11.3	25.0	20.2	6.9	13.2
25.0	30.0	25.0	12.8	25.0	22.9	7.9	15.0
30.0	30.0	25.0	15.4	25.0	27.5	9.5	18.0
Mounting	Viewing	Azimuth	Azimuth	Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint	3dB BW	Range	Range	Footprint
(Feet)			(Feet)		(Feet)	(Feet)	(Feet)
	(ded)	(1001)					
Ireei	(deg)	(deg)	<u>}</u>	(deg)			
			1	}		6.4	9,3
10.0	45.0	25.0	6.3	25.0	15.7	6.4	9.3
10.0 12.0	45.0 45.0	25.0 25.0	6.3 7.5	25.0 25.0	15.7 18.8	6.4 7.6	9.3 11.2
10.0	45.0 45.0 45.0	25.0 25.0 25.0	6.3	25.0 25.0 25.0	15.7 18.8 23.5	6.4	9.3
10.0 12.0 15.0	45.0 45.0	25.0 25.0	6.3 7.5 9.4	25.0 25.0	15.7 18.8	6.4 7.6 9.6	9.3 11.2 14.0
10.0 12.0 15.0 17.0	45.0 45.0 45.0 45.0	25.0 25.0 25.0 25.0	6.3 7.5 9.4 10.7	25.0 25.0 25.0 25.0 25.0 25.0	15.7 18.8 23.5 26.7	6.4 7.6 9.6 10.8	9.3 11.2 14.0 15.9
10.0 12.0 15.0 17.0 20.0	45.0 45.0 45.0 45.0 45.0	25.0 25.0 25.0 25.0 25.0 25.0	6.3 7.5 9.4 10.7 12.5	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	15.7 18.8 23.5 26.7 31.4 34.5 39.2	6.4 7.6 9.6 10.8 12.7	9.3 11.2 14.0 15.9 18.7
10.0 12.0 15.0 17.0 20.0 22.0	45.0 45.0 45.0 45.0 45.0 45.0 45.0	25.0 25.0 25.0 25.0 25.0 25.0 25.0	6.3 7.5 9.4 10.7 12.5 13.8	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	15.7 18.8 23.5 26.7 31.4 34.5	6.4 7.6 9.6 10.8 12.7 14.0	9.3 11.2 14.0 15.9 18.7 20.5
10.0 12.0 15.0 17.0 20.0 22.0 25.0 30.0	45.0 45.0 45.0 45.0 45.0 45.0 45.0 45.0	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	6.3 7.5 9.4 10.7 12.5 13.8 15.7 18.8	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	15.7 18.8 23.5 26.7 31.4 34.5 39.2 47.1	6.4 7.6 9.6 10.8 12.7 14.0 15.9 19.1	9.3 11.2 14.0 15.9 18.7 20.5 23.3 28.0
10.0 12.0 15.0 17.0 20.0 22.0 25.0 30.0 Mounting	45.0 45.0 45.0 45.0 45.0 45.0 45.0 45.0	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	6.3 7.5 9.4 10.7 12.5 13.8 15.7 18.8 Azimuth	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	15.7 18.8 23.5 26.7 31.4 34.5 39.2 47.1 Maximum	6.4 7.6 9.6 10.8 12.7 14.0 15.9 19.1 	9.3 11.2 14.0 15.9 18.7 20.5 23.3 28.0 Elevation
10.0 12.0 15.0 17.0 20.0 22.0 25.0 30.0 Mounting Height	45.0 45.0 45.0 45.0 45.0 45.0 45.0 45.0	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	6.3 7.5 9.4 10.7 12.5 13.8 15.7 18.8 Azimuth Footprint	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	15.7 18.8 23.5 26.7 31.4 34.5 39.2 47.1 Maximum Range	6.4 7.6 9.6 10.8 12.7 14.0 15.9 19.1 Minimum Range	9.3 11.2 14.0 15.9 18.7 20.5 23.3 28.0 Elevation Footprint
10.0 12.0 15.0 17.0 20.0 22.0 25.0 30.0 Mounting	45.0 45.0 45.0 45.0 45.0 45.0 45.0 45.0	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	6.3 7.5 9.4 10.7 12.5 13.8 15.7 18.8 Azimuth	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	15.7 18.8 23.5 26.7 31.4 34.5 39.2 47.1 Maximum	6.4 7.6 9.6 10.8 12.7 14.0 15.9 19.1 	9.3 11.2 14.0 15.9 18.7 20.5 23.3 28.0 Elevation
10.0 12.0 15.0 17.0 20.0 22.0 25.0 30.0 Mounting Height (Feet)	45.0 45.0 45.0 45.0 45.0 45.0 45.0 45.0	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	6.3 7.5 9.4 10.7 12.5 13.8 15.7 18.8 Azimuth Footprint (Feet)	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	15.7 18.8 23.5 26.7 31.4 34.5 39.2 47.1 Maximum Range (Feet)	6.4 7.6 9.6 10.8 12.7 14.0 15.9 19.1 Minimum Range (Feet)	9.3 11.2 14.0 15.9 18.7 20.5 23.3 28.0 Elevation Footprin (Feet)
10.0 12.0 15.0 17.0 20.0 22.0 25.0 30.0 Mounting Height (Feet) 10.0	45.0 45.0 45.0 45.0 45.0 45.0 45.0 45.0	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	6.3 7.5 9.4 10.7 12.5 13.8 15.7 18.8 Azimuth Footprint (Feet) 13.0	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	15.7 18.8 23.5 26.7 31.4 34.5 39.2 47.1 Maximum Range (Feet) 76.0	6.4 7.6 9.6 10.8 12.7 14.0 15.9 19.1 Minimum Range (Feet) 15.7	9.3 11.2 14.0 15.9 18.7 20.5 23.3 28.0 Elevation Footprini (Feet) 60.3
10.0 12.0 15.0 17.0 20.0 22.0 25.0 30.0 Mounting Height (Feet) 10.0 12.0	45.0 45.0 45.0 45.0 45.0 45.0 45.0 45.0	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	6.3 7.5 9.4 10.7 12.5 13.8 15.7 18.8 Azimuth Footprint (Feet) 13.0 15.6	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	15.7 18.8 23.5 26.7 31.4 34.5 39.2 47.1 Maximum Range (Feet) 76.0 91.1	6.4 7.6 9.6 10.8 12.7 14.0 15.9 19.1 Minimum Range (Feet) 15.7 18.8	9.3 11.2 14.0 15.9 18.7 20.5 23.3 28.0 Elevation Footprin (Feet) 60.3 72.3
10.0 12.0 15.0 17.0 20.0 22.0 25.0 30.0 Mounting Height (Feet) 10.0 12.0 15.0	45.0 45.0 45.0 45.0 45.0 45.0 45.0 45.0	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	6.3 7.5 9.4 10.7 12.5 13.8 15.7 18.8 Azimuth Footprint (Feet) 13.0 15.6 19.4	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	15.7 18.8 23.5 26.7 31.4 34.5 39.2 47.1 Maximum Range (Feet) 76.0 91.1 113.9	6.4 7.6 9.6 10.8 12.7 14.0 15.9 19.1 Minimum Range (Feet) 15.7 18.8 23.5	9.3 11.2 14.0 15.9 18.7 20.5 23.3 28.0 Elevation Footprin (Feet) 60.3 72.3 90.4
10.0 12.0 15.0 17.0 20.0 22.0 25.0 30.0 Mounting Height (Feet) 10.0 12.0 15.0 17.0	45.0 45.0 45.0 45.0 45.0 45.0 45.0 45.0	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	6.3 7.5 9.4 10.7 12.5 13.8 15.7 18.8 Azimuth Footprint (Feet) 13.0 15.6 19.4 22.0	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	15.7 18.8 23.5 26.7 31.4 34.5 39.2 47.1 Maximum Range (Feet) 76.0 91.1 113.9 129.1	6.4 7.6 9.6 10.8 12.7 14.0 15.9 19.1 Minimum Range (Feet) 15.7 18.8 23.5 26.7	9.3 11.2 14.0 15.9 18.7 20.5 23.3 28.0 Elevation Footprin (Feet) 60.3 72.3 90.4 102.4
10.0 12.0 17.0 20.0 22.0 25.0 30.0 Mounting Height (Feet) 10.0 12.0 15.0 17.0 20.0	45.0 45.0 45.0 45.0 45.0 45.0 45.0 45.0	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	6.3 7.5 9.4 10.7 12.5 13.8 15.7 18.8 Azimuth Footprint (Feet) 13.0 15.6 19.4 22.0 25.9	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	15.7 18.8 23.5 26.7 31.4 34.5 39.2 47.1 Maximum Range (Feet) 76.0 91.1 113.9 129.1 151.9	6.4 7.6 9.6 10.8 12.7 14.0 15.9 19.1 Minimum Range (Feet) 15.7 18.8 23.5 26.7 31.4	9.3 11.2 14.0 15.9 18.7 20.5 23.3 28.0 Elevation Footprin (Feet) 60.3 72.3 90.4 102.4 120.5
10.0 12.0 15.0 17.0 20.0 22.0 25.0 30.0 Mounting Height (Feet) 10.0 12.0 15.0 17.0	45.0 45.0 45.0 45.0 45.0 45.0 45.0 45.0	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	6.3 7.5 9.4 10.7 12.5 13.8 15.7 18.8 Azimuth Footprint (Feet) 13.0 15.6 19.4 22.0	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	15.7 18.8 23.5 26.7 31.4 34.5 39.2 47.1 Maximum Range (Feet) 76.0 91.1 113.9 129.1	6.4 7.6 9.6 10.8 12.7 14.0 15.9 19.1 Minimum Range (Feet) 15.7 18.8 23.5 26.7	9.3 11.2 14.0 15.9 18.7 20.5 23.3 28.0 Elevation Footprin (Feet) 60.3 72.3 90.4 102.4

	1	1	Electronic	Integr	ated Systems	RTMS-X1	1	
	Operating r	ance is up			resolution of		detection ZO	nes)
		<u></u>		/	1	·····		······································
Mounting	Viewing	Azimuth	Azimuth		Effective	Maximuml	Minimum	Elevation
Height	Angle	3dB BW	Footprint		Elevation	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)		BW (deg)	(Feet)	(Feet)	(Feet)
	·······		{					
10.0	20.0	15.0	2.8		50.0	10.0	-0.9	10.9
12.0	20.0	15.0	3.4		50.0	12.0	- 1.0	13.0
15.0	20.0	15.0	4.2		50.0	15.0	-1.3	16.3
17.0	20.0	15.0	4.8		50.0	17.0	- 1.5	18.5
20.0	20.0	15.0	5.6	*****	50.0	20.0	-1.7	21.7
22.0	20.0	15.0	6.2		50.0	22.0	-1.9	23.9
25.0	20.0	15.0	7.0		50.0	25.0	-2.2	27.2
30.0	20.0	15.0	8.4		50.0	30.0	-2.6	32.6
		1	i i					1
Mounting	Viewing	Azimuth	Azimuth		Effective	Maximum	linimum	Elevation
Height	Angle	3dB BW	Footprint		Elevation	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)		BW (deg)	(Feet)	(Feet)	(Feet)
		}	}				1	1
10.0	30.0	15.0	3.0		50.0	14.3	0.9	13.4
12.0	30.0	15.0	3.6		50.0	17.1	1.0	16.1
15.0	30.0	15.0	4.6		50.0	21.4	1.3	20.1
17.0	30.0	15.0	5.2		50.0	24.3	1.5	22.8
20.0	30.0	15.0	6.1		50.0	28.6	1.7	26.8
22.0	30.0	15.0	6.7		50.0	31.4	1.9	29.5
25.0	30.0	15.0	7.6		50.0	35.7	2.2	33.5
30.0	30.0	15.0	9.1		50.0	42.8	2.6	40.2
	1							1
Mounting	Viewing	Azimuth	Azimuth		Effective	Maximum	linimum	Elevation
Height	Angle	3dB BW	Footprint		Elevation	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)		BW (deg)	(Feet)	(Feet)	(Feet)
10.0	45.0	15.0	3.7		50.0	27.5	3.6	23.8
12.0	45.0	15.0	4.5		50.0	33.0	4.4	28.6
15.0	45.0	15.0	5.6		50.0	41.2	5.5	35.8
17.0	45.0	15.0	6.3		50.0	46.7	6.2	40.5
20.0	45.0	15.0	7.4		50.0	54.9	7.3	47.7
22.0	45.0	15.0	8.2		50.0	60.4	8.0	52.4
25.0	45.0	15.0	9.3		50.0	68.7	9.1	59.6
30.0	45.0	15.0	11.2		50.0	82.4	10.9	71.5
	<u> </u>							
Mounting	Viewing	Azimuth	Azimuth		Effective	Maximum	,	Elevation
Height	Angle	3dB BW	Footprint		Elevation	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)		BW (deg)	(Feet)	(Feet)	(Feet)
		<u>.</u>						4
10.0	60.0	15.0	5.3		50.0	114.3	7.0	107.3
12.0	60.0	15.0	6.3		50.0	137.2	8.4	128.8
15.0	60.0	15.0	7.9		50.0	171.5	10.5	160.9
17.0	60.0	15.0	9.0		50.0	194.3	11.9	182.4
20.0	60.0	15.0	10.5		50.0	228.6	14.0	214.6
22.0	60.0	15.0	11.6		50.0	251.5	15.4	236.1
25.0	60.0	15.0	13.2		50,0	285.8	17.5	268.2
30.0	60.0	15.0	15.8		50.0	342.9	21.0	321.9

			Microwave	Sensors TC	2-30C			
Mounting	Viewing	Azimuth	Azimuth		Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint		3dB BW	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)		(deg)	(Feet)	(Feet)	(Feet)
10.0	0.0	20.0	3.5		20.0	1.8	-1.8	3.5
12.0	0.0	20.0	4.2		20.0	2.1	-2.1	4.2
15.0	0.0	20.0	5.3		20.0	2.6	-2.6	5.3
17.0	0.0	20.0	6.0		20.0	3.0	-3.0	6.0
20.0	0.0	20.0	7.1		20.0	3.5	-3.5	7.1
	0.0	20.0	7.8		20.0	3.9	-3.9	7.8
25.0	0.0	20.0	8.8		20.0	4.4	-4.4	8.8
30.0	0.0	20.0	10.6		20.0	5.3	-5.3	10.6
Mounting	Viewing	Azimuth	Azimuth		Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint		3dB BW	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)		(deg)	(Feet)	(Feet)	(Feet)
	~~~~~				*****			
10.0	20.0	20.0	3.8		20.0	5.8	1.8	4.0
12.0	20.0	20.0	4.5		20.0	6.9	2.1	4.8
15.0	20,0	20.0	5.6		20.0	8.7	2.6	6.0
17.0	20. <b>0</b>	20.0	6.4		20.0	9.8	3.0	6.8
20.0	20.0	20.0	7.5		20.0	11.5	3.5	8.0
22.0	20.0	20.0	8.3		20.0	12.7	3.9	8.8
25.0	20.0	20.0	9.4		20,0	14.4	4.4	10.0
30.0	20.0	20.0	11.3		20.0	17.3	5.3	12.0
Mounting	Viewing	Azimuth	Azimuth		Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint		3dB BW	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)		(deg)	(Feet)	(Feet)	(Feet)
10.0	30.0	20.0	4.1		20.0	8.4	3.6	4.8
12.0	30.0	20.0	4.9		20.0	10.1	4.4	5.7
15.0	30.0	20.0	6.1		20.0	12.6	5.5	7.1
17.0	30.0	20.0	6,9		20.0	14.3	6.2	8.1
20.0	30.0	20.0	8.1		20.0	16.8	7.3	9.5
22.0	30.0	20.0	9.0		20.0	18.5	8.0	10.5
25.0	30.0	20.0	10.2	******	20.0	21.0	9,1	11.9
30.0	30.0	20.0	12.2		20.0	25.2	10.9	14.3
Mounting	Viewing	Azimuth	Azimuth		Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint		3dB BW	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)		(deg)	(Feet)	(Feet)	(Feet)
10.0	45.0	20.0	5.0		20.0	14.3	7.0	7.3
12.0	45.0	20.0	6.0		20.0	17.1	8.4	8.7
15.0	45.0	20.0	7.5		20.0	21.4	10.5	10.9
17.0	45.0	20.0	8.5		20.0	24.3	11.9	12,4
20.0	45.0	20,0	10.0		20.0	28.6	14.0	14.6
22.0	45.0	20.0	11.0		20.0	31.4	15.4	16.0
25.0	45.0	20.0	12.5		20.0	35.7	17.5	18.2
30.0	45.0	20.0	15.0		20.0	42.8	21.0	21.8
{								
Mounting	Viewing	Azimuth	Azimuth		Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint		3dB BW	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)		(deg)	(Feet)	(Feet)	(Feet)
					······			
10.0	70.0	20.0	10.3		20.0	56.7	17.3	39.4
12.0	70.0	20.0	12.4		20.0	68.1	20.8	47.3
15.0	70.0	20.0	15.5	·······	20.0	85.1	26.0	59.1
17.0	70.0	20.0	17.5		20.0	96.4	29.4	67.0
20.0	70.0	20.0	20.6		20.0	113.4	34.6	78.8
20.0					20.0	124.8	38.1	86.7
	70.0	200	8 227 1		200			
22.0	70.0 70.0	20.0 20.0	22.7 25.8		20.0	141.8	43.3	98.5

			Sumitomo S	Speed Dete	ector SDU-2	00 (RDU-10		
Mounting	Viewing	Azimuth	Azimuth		Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint	~~~~~~	3dB BW	Range	Range	Footprin
(Feet)	(deg)	(deg)	(Feet)	******	(deg)	(Feet)	(Feet)	(Feet)
10.0	20.0	15.0	2.8		15.0	5.2	2.2	3.0
12.0	20.0	15.0	3.4		15.0	6.2	2.7	3.6
15.0	20.0	15.0	4.2		15.0	7.8	3.3	4.5
17.0	20.0	15.0	4.8		15.0	8.8	3.8	5.1
20.0	20.0	15.0	5.6		15.0	10.4	4.4	6.0
22.0	20.0	15.0	6.2	****	15.0	11.5	4.9	6.6
25.0	20.0	15.0	7.0		15.0	13.0	5.5	7.5
30.0	20.0	15.0	8.4	······	15.0	15.6	6.7	9.0
								Flowedles
Mounting Height	Viewing Angle	Azimuth 3dB BW	Azimuth		Elevation 3dB BW	Maximum	Minimum Range	Elevation Footprin
(Feet)			Footprint			Range	(Feet)	(Feet)
	(deg)	(deg)	(Feet)		(deg)	(Feet)	(reet)	Treet
10.0	30.0	15.0	3.0		15.0	7.7	4.1	3.5
12.0	30.0	15.0	3.6		15.0	9.2	5.0	4.2
15.0	30.0	15.0	4.6		15.0	11.5	6.2	5.3
17.0	30.0	15.0	5.2		15.0	13.0	7.0	6.0
20.0	30.0	15.0	6.1	~~~~~	15.0	15.3	8.3	7.1
22.0	30.0	15.0	6.7		15.0	16.9	9.1	7.8
25.0	30.0	15.0	7.6		15.0	19.2	10.4	8.8
30.0	30.0	15.0	9.1		15.0	23.0	12.4	10.6
Mounting	Viewing	Azimuth	Azimuth		Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint	*******	3dB BW	Range	Range	Footprin
(Feet)	(deg)	(deg)	(Feet)		(deg)	(Feet)	(Feet)	(Feet)
10.0	45.0	15.0	3.7	*****	15.0	13.0	7.7	5.4
12.0								
15.0	45.0	15.0	4.5		15.0	15.6	9.2	6.4
17.0	45.0 45.0	15.0 15.0	5.6		15.0 15.0	19.5 22.2	<u>11,5</u> 13,0	8.0 9.1
20.0	45.0	15.0	6.3		15,0	<u>26.1</u>	15.3	10.7
22.0	45.0	15.0	B.2		15.0	28.7	16.9	11.8
25.0	45.0	15.0	9.3	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	15.0	32.6	19.2	13.4
30.0	45.0	15.0	11 2	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	15.0	39.1	23.0	16.1
Mounting	Viewing	Azimuth	Azimuth		Elevation	Maximum	Minimum	Elevation
Height (Feet)	Angle	3dB BW	Footprint		3dB BW	Range	Range	Footprint
	<u>(deg)</u>	(deg)	(Feet)	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	(deg)	(Feet)	(Feet)	(Feet)
10.0	70.0	15.0	7.7		15.0	45.1	19.2	25.9
12,0	70.0	15.0	9.2		15.0	54.1	23.1	31.1
15.0	70.0	15.0	11.5		15.0	67.7	28.8	38.8
17.0	70.0	15.0	13.1		15.0	76.7	32.7	44.0
20.0	70.0	15.0	15.4		15.0	90.2	38.4	51.8
22.0	70.0	15.0	16.9		15.0	99.2	42.3	57.0
25.0	70.0	15.0	19.2		15.0	112.8	48.0	64.7
30.0	70.0	15.0	23.1		15.0	135.3	57.6	77.7

			Sumitomo	Presence D	etector SDL	J-300		
Mounting	Viewing	Azimuth	Azimuth		Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint		3dB BW	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)	<u></u>	(deg)	(Feet)	(Feet)	(Feet)
10.0	0.0	13.0	2.3		13.0	1.1	- 1 , 1	2.3
12.0	0.0	13.0	2.7		13.0	1.4	-1.4	2.7
15.0	0.0	13.0	3.4		13.0	1.7	-1.7	3.4
17.0	0.0	13.0	3.9 4.6		13.0 13.0	<u>1.9</u> 2.3	-1.9 -2.3	<u>3.9</u> 4.6
20.0 22.0	0.0	<u>13.0</u> 13.0	<u>4.0</u> 5.0		13.0	2.5	-2.5	5.0
25.0	0.0	13.0	5.7		13.0	2.8	-2.8	5.7
30.0	0.0	13.0	6.8		13.0	3.4	-3.4	6.8
Mounting	Viewing	Azimuth	Azimuth		Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint		3dB BW	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)		(deg)	(Feet)	(Feet)	(Feet)
		10.0			100			
10.0	20.0	13.0	2.4	<b>.</b>	13.0	5.0	2.4	2.6
<u>12.0</u> 15.0	20.0 20.0	<u>13.0</u> 13.0	2 <u>9</u> 3,6		13.0 13.0	<u>6.0</u> 7.5	2.9 3.6	<u>3.1</u> 3.9
17.0	20.0	13.0	<u>4.1</u>		13.0	8.5	4.1	4.4
20.0	20.0	13.0	4.8		13.0	10.0	4.8	5.2
22.0	20.0	13.0	5.3		13.0	11.0	5.3	5.7
25.0	20.0	13.0	6.1		13.0	12.5	6.0	6.5
30.0	20.0	13.0	7.3		13.0	15.0	7.2	7.8
Mounting Height	Viewing Angle	Azimuth 3dB BW	Azimuth Footprint		Elevation 3dB BW	Maximum Range	Minimum Range	Elevation Footprint
(Feet)	(deg)	(deg)	(Feet)		(deg)	(Feet)	(Feet)	(Feet)
<u>h</u> if		<u>)</u>	<u>·······</u>		{	f		
10.0	30.0	13.0	2.6		13.0	7.4	4.3	3.1
12.0	30.0	13.0	3.2		13.0	8.9	5.2	3.7
15.0	30.0	13.0	3.9		13.0	11.1	6.5	4.6
17.0 20.0	<u>30.0</u> 30.0	<u>13.0</u> 13.0	<u>4.5</u> 5.3		13.0 13.0	12.6	7.4 8.7	<u>5.2</u> 6.1
20.0	30.0	13.0	5.8		13.0	14.8 16.3	9,6	6.7
25.0	30.0	13.0	6.6		13.0	18.5	10.9	7.6
30.0	30.0	13.0	7.9		13.0	22.2	13.0	9.2
*								
Mounting	Viewing	Azimuth	Azimuth		Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint		3dB BW	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)		(deg)	(Feet)	(Feet)	(Feet)
10.0	45.0	13.0	3.2		1.3.0	12.6	8.0	4.6
12.0	45.0	13.0	3.9		13.0	15.1	9.5	5.5
15.0	45.0	13.0	4.8		13.0	18.9	11.9	6.9
17.0	45.0	13.0	5.5		13.0	21.4	13.5	7.8
20.0	45.0	13.0	6.4		13.0	25.1	15.9	9.2
22.0	45.0	13.0	7.1		13.0	27.7	17.5	10.2
25.0 30.0	45.0 45.0	13.0	<u>8.1</u> 9.7		13.0	<u>31.4</u> 37.7	19.9	11.5
30.0	45.0	13.0	3./		13.0	37.7	23.9	13.9
Mounting	Viewing	Azimuth	Azimuth		Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint		3dB BW	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)		(deg)	(Feet)	(Feet)	(Feet)
10.0	70.0	13.0	6.7		13.0	41.7	20.1	21.6
12.0 15.0	70.0 70.0	13.0 13.0	8.0		13.0	50.0	24.1	25.9
17.0	70.0	13.0	10.0 11.3		13.0 13.0	62.5 70.8	<u>30.1</u> 34.1	<u>32.4</u> 36.7
20.0	70.0	13.0	13.3		13.0	83.3	40.1	43.2
22.0	70.0	13.0	14.7		13.0	91.6	44.1	47.5
25.0	70.0	13.0	16,7		13.0	104.1	50.1	54.0
30.0	70.0	13.0	20.0		13.0	125.0	60.2	64.8

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2		Schwartz	Electro-Op	tics	780D1000	(Autosens	e I)	
	(Two Bear		mrad (EI)			) Separate	d by 10 d	eq in Ei)
······			r,			/		
Mounting	Viewing	Azimuth	Azimuth		Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint		3dB BW	Range	Range	Footprin
(Feet)	(deg)	(deg)	(Feet)		(deg)	(Feet)	(Feet)	(Feet)
**************************************	······································	······································	()					
10.0	15.0	9.5	1.7		0.057	2.7	2.7	0.0
12.0	15.0	9.5	2.1		0.057	3.2	3.2	0.0
15.0	15.0	9.5	2.6		0.057	4.0	4.0	0.0
17.0	15.0	9.5	2.9		0.057	4.6	4.5	0.0
20.0	15.0	9.5	3.4		0.057	5.4	5.3	0.0
22.0	15.0	9.5	3.8		0.057	5.9	5.9	0.0
25.0	15.0	9.5	4.3		0.057	6.7	6.7	0.0
30.0	15.0	9.5	5.2		0.057	8.1	8.0	0.0
Mounting	Viewing	Azimuth	Azimuth		Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint		3dB BW	Range	Range	Footprint
(Feet)	(deq)	(deq)	(Feet)		(deg)	(Feet)	(Feet)	(Feet)
	~~~~							~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~
10.0	20.0	9.5	1.8		0.057	3.6	3.6	0.0
12.0	20.0	9.5	2.1		0.057	4.4	4.4	0.0
15.0	20.0	9.5	2.7		0.057	5.5	5.5	0.0
17.0	20.0	9.5	3.0		0.057	6.2	6.2	0.0
20.0	20.0	9.5	3.5		0.057	7.3	7.3	0.0
22.0	20.0	9.5	3.9		0.057	8.0	8.0	0.0
25.0	20.0	9.5	4.4		0.057	9.1	9.1	0.0
30.0	20.0	9.5	5.3		0.057	10.9	10.9	0.0
Mounting	Viewing	Azimuth	Azimuth		Elevation	Maximum	Minimum	
Height	Angle	3dB BW	Footprint		3dB BW	Range	Range	Footprint
(Feet)	()) / E = = + 1		کا (محام)	(Feet)	/ [(Feet)
	(deg)	(deg)	(Feet)		(deg)	<u> </u>	(Feet)	
10.0	25.0	9.5	1.8		0.057	4.7	4.7	0.0
10.0 12.0	25.0 25.0	<u>9.5</u> 9.5	1.8 2.2		0.057 0.057	4 <u>.</u> 7 5.6	4.7 5.6	0.0
10.0 12.0 15.0	25.0 25.0 25.0	9.5 9.5 9.5	1.8 2.2 2.8		0.057 0.057 0.057	<u>4.7</u> 5.6 7.0	4.7 5.6 7.0	0.0 0.0 0.0
10.0 12.0 15.0 17.0	25.0 25.0 25.0 25.0	9.5 9.5 9.5 9.5 9.5	1.8 2.2 2.8 3.1		0.057 0.057 0.057 0.057 0.057	4.7 5.6 7.0 7.9	4.7 5.6 7.0 7.9	0.0 0.0 0.0 0.0 0.0
10.0 12.0 15.0 17.0 20.0	25.0 25.0 25.0 25.0 25.0 25.0	9.5 9.5 9.5 9.5 9.5 9.5	1.8 2.2 2.8 3.1 3.7		0.057 0.057 0.057 0.057 0.057 0.057	4.7 5.6 7.0 7.9 9.3	4.7 5.6 7.0 7.9 9.3	0.0 0.0 0.0 0.0 0.0 0.0
10.0 12.0 15.0 17.0 20.0 22.0	25.0 25.0 25.0 25.0 25.0 25.0 25.0	9.5 9.5 9.5 9.5 9.5 9.5 9.5	1.8 2.2 2.8 3.1 3.7 4.0		0.057 0.057 0.057 0.057 0.057 0.057	4.7 5.6 7.0 7.9 9.3 10.3	4.7 5.6 7.0 7.9 9.3 10.2	0.0 0.0 0.0 0.0 0.0 0.0 0.0
10.0 12.0 15.0 17.0 20.0 22.0 25.0	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5	1.8 2.2 2.8 3.1 3.7 4.0 4.6		0.057 0.057 0.057 0.057 0.057 0.057 0.057 0.057	4.7 5.6 7.0 7.9 9.3 10.3 11.7	4.7 5.6 7.0 7.9 9.3 10.2 11.6	0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0
10.0 12.0 15.0 17.0 20.0 22.0	25.0 25.0 25.0 25.0 25.0 25.0 25.0	9.5 9.5 9.5 9.5 9.5 9.5 9.5	1.8 2.2 2.8 3.1 3.7 4.0		0.057 0.057 0.057 0.057 0.057 0.057	4.7 5.6 7.0 7.9 9.3 10.3	4.7 5.6 7.0 7.9 9.3 10.2	0.0 0.0 0.0 0.0 0.0 0.0 0.0
10.0 12.0 15.0 17.0 20.0 22.0 25.0 30.0	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5	1.8 2.2 2.8 3.1 3.7 4.0 4.6 5.5		0.057 0.057 0.057 0.057 0.057 0.057 0.057 0.057	4.7 5.6 7.0 7.9 9.3 10.3 11.7 14.0	4.7 5.6 7.0 7.9 9.3 10.2 11.6 14.0	0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0
10.0 12.0 15.0 17.0 20.0 22.0 25.0 30.0 Mounting	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5	1.8 2.2 2.8 3.1 3.7 4.0 4.6 5.5 Azimuth		0.057 0.057 0.057 0.057 0.057 0.057 0.057 0.057 0.057 Elevation	4.7 5.6 7.0 7.9 9.3 10.3 11.7 14.0 Maximum	4.7 5.6 7.0 7.9 9.3 10.2 11.6 14.0 Minimum	0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0
10.0 12.0 15.0 17.0 20.0 22.0 25.0 30.0 Mounting Height	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5	1.8 2.2 2.8 3.1 3.7 4.0 4.6 5.5 Azimuth Footprint		0.057 0.057 0.057 0.057 0.057 0.057 0.057 0.057 0.057 Elevation 3dB BW	4.7 5.6 7.0 7.9 9.3 10.3 11.7 14.0 Maximum Range	4.7 5.6 7.0 7.9 9.3 10.2 11.6 14.0 Minimum Range	0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0
10.0 12.0 15.0 17.0 20.0 22.0 25.0 30.0 Mounting	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5	1.8 2.2 2.8 3.1 3.7 4.0 4.6 5.5 Azimuth		0.057 0.057 0.057 0.057 0.057 0.057 0.057 0.057 0.057 Elevation	4.7 5.6 7.0 7.9 9.3 10.3 11.7 14.0 Maximum	4.7 5.6 7.0 7.9 9.3 10.2 11.6 14.0 Minimum	0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0
10.0 12.0 15.0 17.0 20.0 22.0 25.0 30.0 Mounting Height (Feet)	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5 Azimuth 3dB BW (deg)	1.8 2.2 2.8 3.1 3.7 4.0 4.6 5.5 Azimuth Footprint (Feet)		0.057 0.057 0.057 0.057 0.057 0.057 0.057 0.057 Elevation 3dB BW (deg)	4.7 5.6 7.0 7.9 9.3 10.3 11.7 14.0 Maximum Range (Feet)	4.7 5.6 7.0 7.9 9.3 10.2 11.6 14.0 Minimum Range (Feet)	0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 Elevation Footprint (Feet)
10.0 12.0 15.0 17.0 20.0 22.0 25.0 30.0 Mounting Height (Feet) 10.0	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5 Azimuth 3dB BW (deg)	1.8 2.2 2.8 3.1 3.7 4.0 4.6 5.5 Azimuth Footprint (Feet) 1.9		0.057 0.057 0.057 0.057 0.057 0.057 0.057 0.057 Elevation 3dB BW (deg) 0.057	4.7 5.6 7.0 7.9 9.3 10.3 11.7 14.0 Maximum Range (Feet) 5.8	4.7 5.6 7.0 7.9 9.3 10.2 11.6 14.0 Minimum Range (Feet) 5.8	0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 Elevation Footprint (Feet) 0.0
10.0 12.0 15.0 17.0 20.0 22.0 25.0 30.0 Mounting Height (Feet) 10.0 12.0	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5 Azimuth 3dB BW (deg) 9.5 9.5	1.8 2.2 2.8 3.1 3.7 4.0 4.6 5.5 Azimuth Footprint (Feet) 1.9 2.3		0.057 0.057 0.057 0.057 0.057 0.057 0.057 0.057 Elevation 3dB BW (deg) 0.057 0.057	4.7 5.6 7.0 7.9 9.3 10.3 11.7 14.0 Maximum Range (Feet) 5.8 6.9	4.7 5.6 7.0 7.9 9.3 10.2 11.6 14.0 Minimum Range (Feet) 5.8 6.9	0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 Elevation Footprint (Feet) 0.0 0.0
10.0 12.0 15.0 17.0 20.0 22.0 25.0 30.0 Mounting Height (Feet) 10.0 12.0 15.0	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5 Azimuth 3dB BW (deg) 9.5 9.5 9.5 9.5	1.8 2.2 2.8 3.1 3.7 4.0 4.6 5.5 Azimuth Footprint (Feet) 1.9 2.3 2.9		0.057 0.057 0.057 0.057 0.057 0.057 0.057 0.057 Elevation 3dB BW (deg) 0.057 0.057	4.7 5.6 7.0 7.9 9.3 10.3 11.7 14.0 Maximum Range (Feet) 5.8 6.9 8.7	4.7 5.6 7.0 7.9 9.3 10.2 11.6 14.0 Minimum Range (Feet) 5.8 6.9 8.7	0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 Elevation Footprint (Feet) 0.0 0.0 0.0 0.0
10.0 12.0 15.0 17.0 20.0 22.0 25.0 30.0 Mounting Height (Feet) 10.0 12.0 15.0 17.0	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5 Azimuth 3dB BW (deg) 9.5 9.5 9.5 9.5 9.5	1.8 2.2 2.8 3.1 3.7 4.0 4.6 5.5 Azimuth Footprint (Feet) 1.9 2.3 2.9 3.3		0.057 0.057 0.057 0.057 0.057 0.057 0.057 0.057 Elevation 3dB BW (deg) 0.057 0.057 0.057 0.057	4.7 5.6 7.0 7.9 9.3 10.3 11.7 14.0 Maximum Range (Feet) 5.8 6.9 8.7 9.8	4.7 5.6 7.0 7.9 9.3 10.2 11.6 14.0 Minimum Range (Feet) 5.8 6.9 8.7 9.8	0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 Elevation Footprint (Feet) 0.0 0.0 0.0 0.0 0.0
10.0 12.0 15.0 17.0 20.0 25.0 30.0 Mounting Height (Feet) 10.0 12.0 15.0 17.0 20.0	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5 Azimuth 3dB BW (deg) 9.5 9.5 9.5 9.5 9.5 9.5 9.5	1.8 2.2 2.8 3.1 3.7 4.0 4.6 5.5 Azimuth Footprint (Feet) 1.9 2.3 2.9 3.3 3.8		0.057 0.057 0.057 0.057 0.057 0.057 0.057 0.057 Elevation 3dB BW (deg) 0.057 0.057 0.057 0.057 0.057	4.7 5.6 7.0 7.9 9.3 10.3 11.7 14.0 Maximum Range (Feet) 5.8 6.9 8.7 9.8 11.6	4.7 5.6 7.0 7.9 9.3 10.2 11.6 14.0 Minimum Range (Feet) 5.8 6.9 8.7 9.8 11.5	0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 Elevation Footprint (Feet) 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0
10.0 12.0 15.0 17.0 20.0 22.0 25.0 30.0 Mounting Height (Feet) 10.0 12.0 15.0 17.0	25.0 25.0 25.0 25.0 25.0 25.0 25.0 25.0	9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5 9.5 Azimuth 3dB BW (deg) 9.5 9.5 9.5 9.5 9.5	1.8 2.2 2.8 3.1 3.7 4.0 4.6 5.5 Azimuth Footprint (Feet) 1.9 2.3 2.9 3.3		0.057 0.057 0.057 0.057 0.057 0.057 0.057 0.057 Elevation 3dB BW (deg) 0.057 0.057 0.057 0.057	4.7 5.6 7.0 7.9 9.3 10.3 11.7 14.0 Maximum Range (Feet) 5.8 6.9 8.7 9.8	4.7 5.6 7.0 7.9 9.3 10.2 11.6 14.0 Minimum Range (Feet) 5.8 6.9 8.7 9.8	0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 Elevation Footprint (Feet) 0.0 0.0 0.0 0.0 0.0

		Schwartz	Electro-Op	tice	780D1000	(Autosens	se I)	
		****					~~~~~	dog in Ell
	(тwo веа	ms, Each	1 mrad (El)	<u> </u>	9.5 deg (A	z) separat	ed by 10	leg III EI)
Mounting	Viewing	Azimuth	Azimuth		Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint		3dB BW	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)	~~~~~~	(deg)	(Feet)	(Feet)	(Feet)
	***************************************		······		·····		······	
Mounting	Viewing	Azimuth	Azimuth		Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint	*****	3dB BW	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)		(deg)	(Feet)	(Feet)	(Feet)
	·····		<u> </u>			·····	·····	
10.0	35.0	9.5	2.0		0.057	7.0	7.0	0.0
12.0	35.0	9.5	2.4		0.057	8.4	8.4	0.0
15.0	35.0	9.5	3.0		0.057	10.5	10.5	0.0
17.0	35.0	9.5	3.4	~~~~~~	0.057	11.9	11.9	0.0
20.0	35.0	9.5	4.1		0.057	14.0	14.0	0.0
22.0	35.0	9.5	4.5		0.057	15.4	15.4	0.0
25.0	35.0	9.5	5.1	*****	0.057	17.5	17.5	0.0
30.0	35.0	9.5	6.1		0.057	21.0	21.0	0.0
10.0	40.0	9.5	2.2		0.057	8.4	8.4	0.0
12.0	40.0	9.5	2.6		0.057	10.1	10.1	0.0
15.0	40.0	9.5	3.3		0.057	12.6	12.6	0.0
17.0	40.0	9.5	3.7		0.057	14.3	14.3	0.0
20.0	40.0	9.5	4.3	*****	0.057	16.8	16.8	0.0
22.0	40.0	9.5	4.8	••••••	0.057	18.5	18.4	0.0
25.0	40.0	9.5	5.4		0.057	21.0	21.0	0.0
30.0	40.0	9.5	6.5	••••••	0.057	25.2	25.1	0.1
	_		ł					
Mounting	Viewing	Azimuth	Azimuth		Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint		3dB BW	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)		(deg)	(Feet)	(Feet)	(Feet)
10.0	45.0	9.5	2.4		0.057	10.0	10.0	0.0
12.0	45.0	9.5	2.8		0.057	12.0	12.0	0.0
15.0	45.0	9.5	3.5		0.057	15.0	15.0	0.0
17.0	45.0	9.5	4.0		0.057	17.0	17.0	0.0
20.0	45.0	9.5	4.7		0.057	20.0	20.0	0.0
22.0	45.0	9.5	5.2		0.057	22.0	22.0	0.0
25.0	45.0	9.5	5.9		0.057	25.0	25.0	0.1
30.0	45.0	9.5	7.1		0.057	30.0	30.0	0.1
Mounting	Viewing	Azimuth	Azimuth		Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint		3dB BW	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)		(deg)	(Feet)	(Feet)	(Feet)
10.0	50.0	9.5	2.6		0.057	11.9	11.9	0.0
12.0	50.0	9.5	3.1		0.057	14.3	14.3	0.0
15.0	50.0	9.5	3.9		0.057	17.9	17.9	0.0
17.0	50.0	9.5	4.4		0.057	20.3	20.2	0.0
20.0	50.0	9.5	5.2		0.057	23.9	23.8	0.0
22.0	50.0	9.5	5.7		0.057	26.2	26.2	0.1
25.0	50.0	9.5	6.5		0.057	29.8	29.8	0.1
30.0	50.0	9.5	7.8		0.057	35.8	35.7	0.1
							4	ft = 0.305 m

		Schwartz	Electro-O	ptics	780D1000	(Autosens	ie I)	
	(Two Bea	ms, Each	1 mrad (E	l) by	9.5 deg (A	z) Separat	ed by 10	deg in El)

								• • • • • • • • • • • • • • • • • • • •
Mounting	Viewing	Azimuth	Azimuth		Elevation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint		3dB BW	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)		(deg)	(Feet)	(Feet)	(Feet)
10.0	65.0	9.5	3.9		0.057	21.5	21.4	0.1
12.0	65.0	9.5	4.7		0.057	25.8	25.7	0.1
15.0	65.0	9.5	5.9		0.057	32.2	32.1	0.1
17.0	65.0	9.5	6.7		0.057	36.5	36.4	0.1
20.0	65.0	9.5	7.9		0.057	42.9	42.8	0.1
22.0	65.0	9.5	8.7		0.057	47.2	47.1	0.1
25.0	65.0	9.5	9.8		0.057	53.7	53.5	0.1
30.0	65.0	9.5	11.8		0.057	64.4	64.3	0.2
Mounting	Viewing	Azimuth	Azimuth		Elevation	Maximum		Elevation
Height	Angle	3dB BW	Footprint		3dB BW	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)		(deg)	(Feet)	(Feet)	(Feet)
100		~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~			0.057	~~~~		~ 1
<u>10.0</u> 12.0	70.0	9.5 9.5	<u>4.9</u> 5.8		0.057	<u>27.5</u> 33.0	<u>27.4</u> 32.9	0.1
15.0	70.0	9.5	7.3		0.057	41.3	41.1	0.1
17.0	*****	*****	******		Annun	******	******	
20.0	70.0	9.5	8.3 9.7		0.057	46.8	46.6	0.1
20.0	70.0	9.5		~~~~~~	0.057	55.0	54.9	0.2
	70.0	9.5	10.7		0.057	60.5	60.4	0.2
25.0 30.0	70.0	9.5	12.1		0.057	68.8	68.6	0.2
	70.0	9.5	14.6		0.057	82.6	82.3	0.3
Mounting	Viewing	Azimuth	Azimuth		Flovation	Maximum	Minimum	Elevation
Height	Angle	3dB BW	Footprint		3dB BW	Range	Range	Footprint
(Feet)	(deg)	(deg)	(Feet)	~~~~~	(deg)	(Feet)	(Feet)	(Feet)
					······			
10.0	75.0	9.5	6.4		0.057	37.4	37.2	0.1
12.0	75.0	9.5	7.7		0.057	44.9	44.7	0.2
15.0	75.0	9.5	9.6		0.057	56.1	55.9	0.2
17.0	75.0	9.5	10.9		0.057	63.6	63.3	0.3
20.0	75.0	9.5	12.8		0.057	74.8	74.5	0.3
22.0	75.0	9.5	14.1		0.057	82.3	81.9	0.3
25.0	75.0	9.5	16.1		0.057	93.5	93.1	0.4
30.0	75.0	9.5	19.3	1	0.057	112.2	111.7	0.4

,

APPENDIX G.

INDUCTIVE LOOP DETECTOR SPECIFICATIONS FOR LOOPS INSTALLED DURING THE DETECTOR FIELD EVALUATIONS

Table G-1. Inductive Loop Detector Installation Information for I-394in Minneapolis, Minnesota

Location of Loop: I-394 and Penn Avenue

Wire Loop Information:

Manufacturer: Triangle Cable Company Model_____

Shape and Size: 6 ft x 6 ft (1.8 m x 1.8 m) Date loop installed: 11/17/92

Loop Construction (wire laid in pavement, wire in conduit laid in pavement, wire encased in epoxy or other compound and then laid in pavement, etc.): Sawcut concrete, 1-1/2 inches (38.1 mm) deep

Gauge of wire used in loop: #12 AWG Number of turns: 3

Type of insulation: RHW Type of conduit used, if any: PVC

Lead-in cable length: 65 ft (19.8 m) Type of splice: 3M and soldered

Description or drawing of cross section of road where loop is installed. Indicate at what depth loop is located.

Please supply a set of loop installation specifications if not already supplied.

Detector Amplifier Information:

Manufacturer: Detector Systems Model: 222B

Number of Channels: 2 Date last tuned: Unknown

Settings of switches, jumpers, etc. on amplifier:

Sensitivity: 4 = Medium, Response time = 2 ms Medium pulse mode

Oscillator Frequency

	Lane 1	Lane 2	Lane 3
First Loop Encountered	MEDLO	MED HI	MED HI
Second Loop Encountered	MED LO	MED HI	MED LO

Table G-2. Inductive Loop Detector Installation Information for TH 55in Minneapolis, Minnesota

Location of Loop: Westbound Olson Highway (TH 55) at Northbound Lyndale Avenue North

Wire Loop Information:

Manufacturer: _____ Model_____

Shape and Size: 6 ft x 6 ft (1.8 m x 1.8 m) Date loop installed: 11/3/92, Tested 11/9/92

Loop Construction (wire laid in pavement, wire in conduit laid in pavement, wire encased in epoxy or other compound and then laid in pavement, etc.): Wire laid in pavement

Gauge of wire used in loop: #12 AWG Number of turns: 3

Type of insulation: XLP - U.S.E. Type of conduit used, if any: _____

Lead-in cable length_____ Type of splice: Soldered

Description or drawing of cross section of road where loop is installed. Indicate at what depth loop is located.

Sawcut depth: 2 inches (50.8 mm); Roadway condition: poor, asphalt severely cracked.

Please supply a set of loop installation specifications if not already supplied.

Detector Amplifier Information:

Manufacturer: Detector Systems Model: 222B

Number of Channels: 2 Date last tuned: Unknown

Settings of switches, jumpers, etc. on amplifier:

Sensitivity: 4 = Medium (detects automobiles on all size loops up to 600 ft² [55.7 m²]) Response time = 2 ms

Long presence mode

Oscillator Frequency

	Lane 1	Lane 2
First Loop Encountered	MED LO	Q
Second Loop Encountered	MED LO	ы

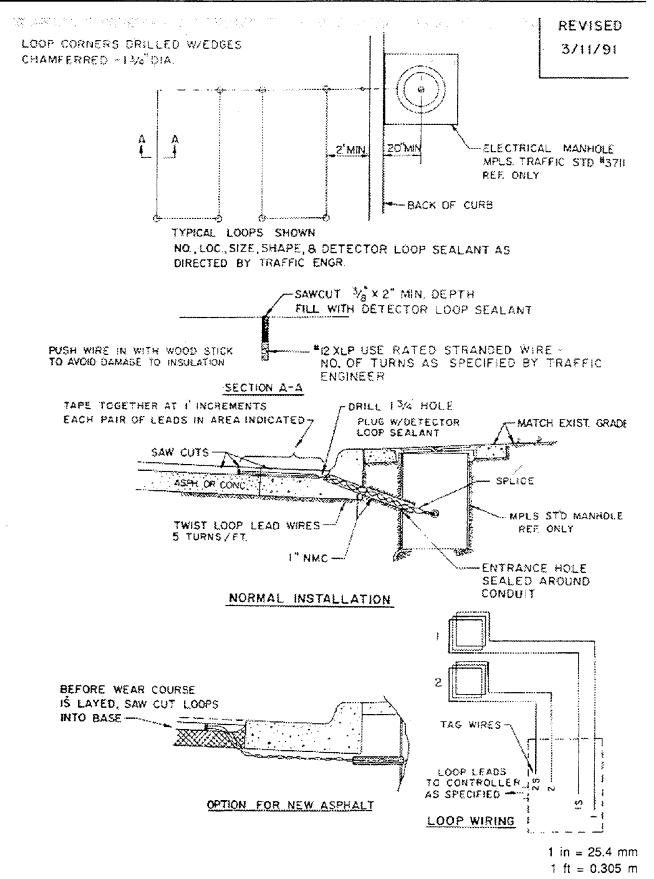


Figure G-1. City of Minneapolis Inductive Loop Installation Specification

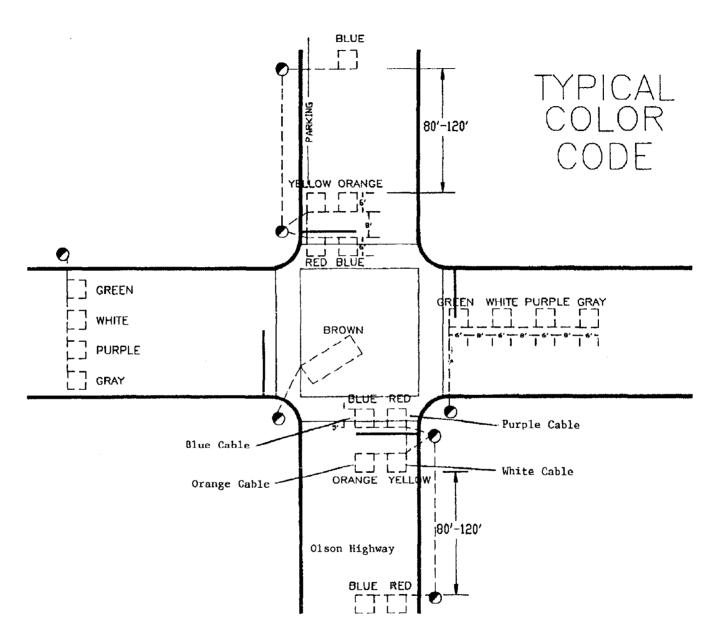


Figure G-2. Wire Color Codes Used to Connect Inductive Loops to Pull Box at Olson Highway Site

Table G-3. Inductive Loop Detector Installation Information for I-4 and SR 436in Altamonte Springs, Florida

Location of Loop: I-4 at SR 436

Wire Loop Information:

Manufacturer: Rome Cable

Model: Rome XHHW stranded copper wire per spec 2100 for Rome Cable

Shape and Size: 6 ft x 6 ft (1.8 m x 1.8 m) Date loop installed: 5/19/93

Loop Construction (wire laid in pavement, wire in conduit laid in pavement, wire encased in epoxy or other compound and then laid in pavement, etc.): Wire laid in pavement, encased in GAF Type III steep asphalt.

Gauge of wire used in loop: #14 AWG Number of turns: 3

Type of insulation: XLPE Type of conduit used, if any: PVC

Lead-in cable length: 210 inches (5.3 m) Type of splice: per FDOT Std. Index 17781

Lead-in cable for each loop used 1 pair of a multi-pair C2550 cable manufactured by Carol Cable to IMSA 50-2 specification

Description or drawing of cross section of road where loop is installed. Indicate at what depth loop is located.

Sawcut depth: 2 inches (50.8 mm).

Please supply a set of loop installation specifications if not already supplied.

Detector Amplifier Information:

Manufacturer: Detector Systems Model: 222D

Number of Channels: 2

Settings of switches, jumpers, etc. on amplifier:

Sensitivity: 1, Response time = 1 ms

Presence Mode: 7/7, 7/8, 7/9

Pulse Mode: 7/13 till end of test. Pulse specification is 125 ± 25 ms. Detector resumes full sensitivity within 0.75 second.

Date last tuned: Unknown

Oscillator Frequency

	Lane 1	Lane 2	Lane 3*
First Loop Encountered	н	MED HI	ні
Second Loop Encountered	HI	MED HI	Н

* Lane 3 loops used on I-4 freeway only.

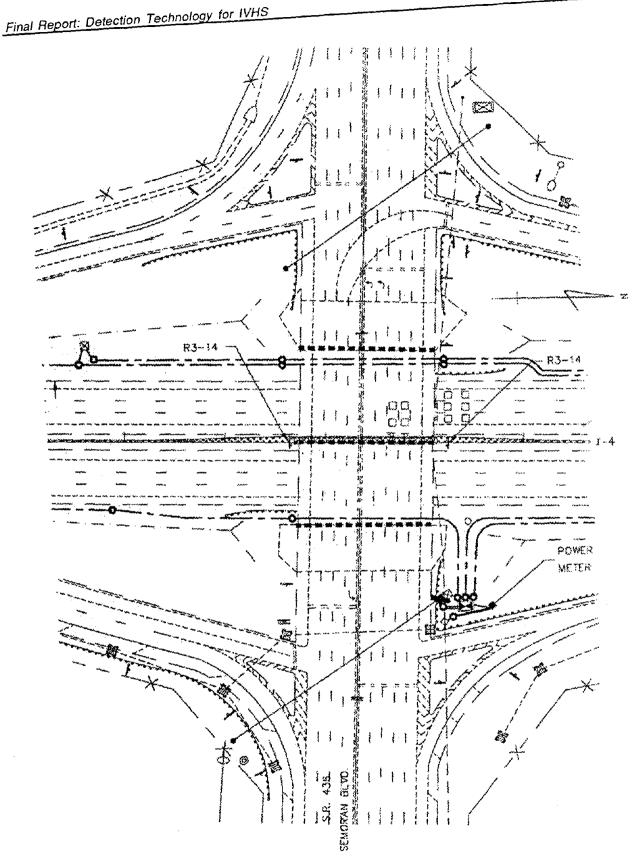
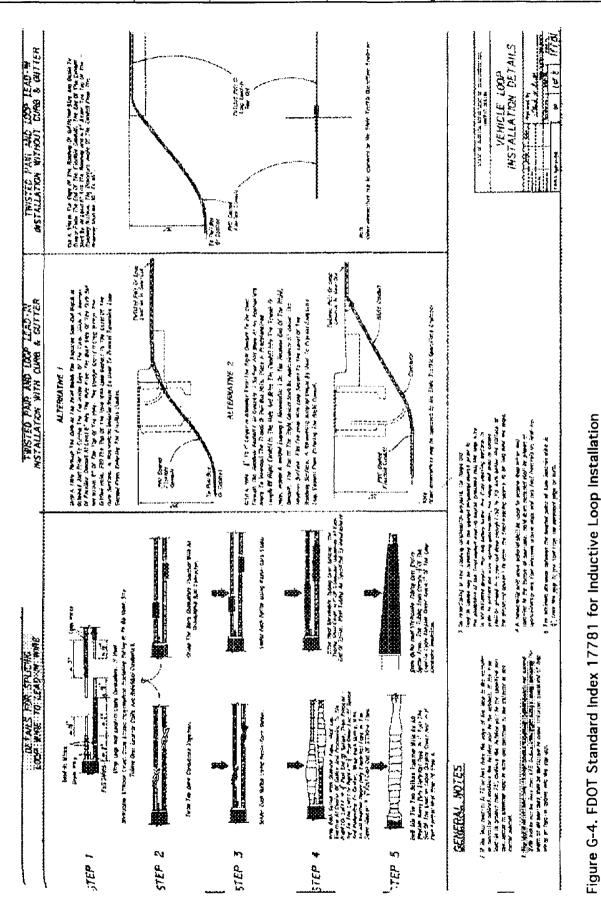


Figure G-3. I-4 and SR 436 Intersection In Altamonte Springs, Florida Showing Locations of Inductive Loops



G-7

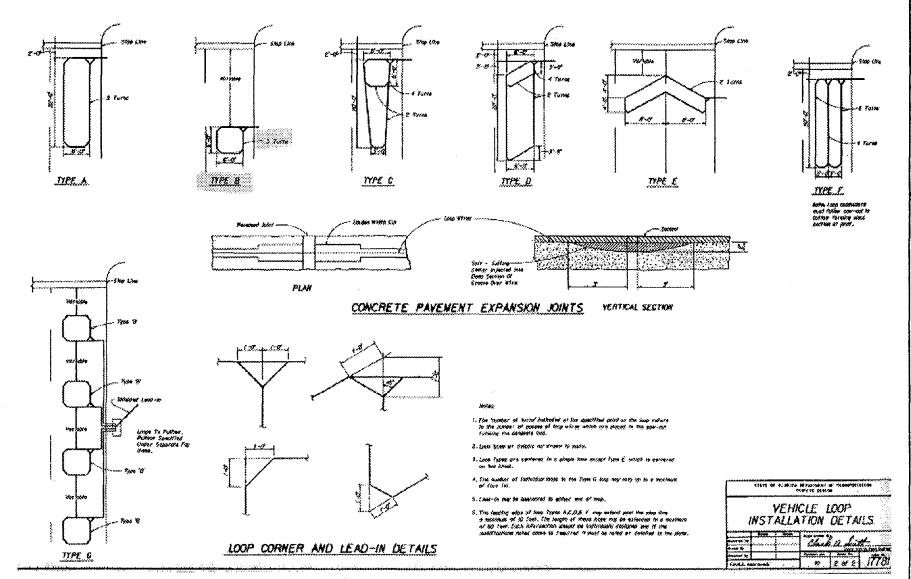


Figure G-4. FDOT Standard Index 17781 for Inductive Loop Installation (continued)

G-8

Final Report: Detection Technology for IVHS



. SUBMETTAL NO. 1-661.70.112 THIS SUB ISSACH WAS DIED REVIEWED AND APPEARS TO COMPLY ONTH THE OUTBRIDG OF THE CONTRACT DRAWINGS AND SPECIFICATIONS. AND IS SUBMITTED FOR DESIGNER APPROVAL.

Surface Print +

Sand BOREARLP TYPE PHONE STAT

Rome-XLP Insulation

SPEC 2100 April 1, 1987 Supersedes issue 1-1-87

Copper

HUBBARD CONSTRUCTION COMPANY By CO Date 2/1/92

ROME XHHW

Rome-XLP Insulation, 600 Volts

- APPLICATION: 1. General purpose writing for lighting and power--rasidential, commer-cial, industrial buildings in accentience with National Electrical Code, maintains conductor lengershare of 90 °C in dry locations and 75°C in wel locations, 600 volts, for installation is conduit or other recognized
- accounts of the set of the second seco

- STUNDARDS: 1. Listadby Undermitters Laboratories at Type XORW per UL Standard 44 for Rubberhausted Wrise and Cables. 2. Contempt to KCEA Pub. No. S-56-524, utilizing Column B thick-
- Continuents to Faderal Specification J-C-30A
 Continuents to Faderal Specification J-C-30A
 Castle complias with the sequences is all OSHA when insisted and used in accordance with the NEC.
- CONSTRUCTION: According moont conductor Rome-XLP thermately

	1	1	1					Coppe	Conductor	•							
Size		insu- lation Thick-	Noti.		SC arity		000 Fi.		idarð kaçn				Rock	hema	æ		
icu.	No. of Strande	rie 33 Milts	Diarn. Diarn. Inchas	75°C Viet	erc Dry	tiel	Ship- phig	Length	Put-up	1	2	3	•	5	6	7	
						SI	randed										
••	•	20	16	201	251		77 21	500 CL 2500	Cin NA met	8 5	555	5	\$ \$	8	8	s	
	7	30	.16	251	301	27	28 23	500° CL 2500°	Can NiR recti	5	\$ 3	****	****	****	s	\$	١.
10	7	30	.18	35 f	401	40	41	500° Ca. 2500°	Cas NR mel	5 5	8	\$ \$	\$	\$ \$	5	3	
8	7	45	24	50	\$ 5	66	87 59	\$00° CL 2500	Cini NR repi	\$ \$							
\$	7	45	28	65	75	\$7	105	1000	NAR men	\$							l
2	7	-45 45	-12 -78	860) 1150)	952	145 225	160	1000	NRmet	s				í			Į.
1	10	45 55	.44	1202	1500	225	310	1000'	NR redi NR task	6) W							ĺ
1.0	19	\$5	.48	1500	1732	350	380	10007	NR reak	5							ŀ
2.0	19	\$ \$.52	1750	1950	450	<70	1000	NR met	5							
340	18	55	- 54	200	225	590	580	1000	NPL roal	S							
*0	19	\$ 5	.63	230	363	700	730	1000	NFI read	5							į.
250 310	37	65	.70	255	290	630	865	1000.	NB met	\$	f	1	1		Ì		
	37	똜	.75	285	320	990	1050	NS	NFI resi	S						1	1
350 133	37	55 65	.£0 _85	310	360 360	\$130 1350	1210 1370	1000' NS	NR reei	S			1	1		i	
									NB seel	~ 1		- 1					
800	37	5	93	380	430	1620	1750	1000	NF rect	5		- 1	1	ł	į		
600 152	61 83	80 80	1.04	420 475	475 535	1950	2080	NS	NR sea	5	- 1			1			
000	61	80	1.14	545	530 615	2445 3340	2545 3380	NS	NR rest	s	- 1	1		1	- {	1	

*Amplically in accordance with NEC for sol more there there conductors in raceway, 75% conductor temperature for well docations, 95% conductor temperature for the locations, 50°C antibles temperature.

The over current protection shall not exceed 15 amounds for 14 AMC, 30 amperes for 12 AMC and 30 amperes for 10 AMC oppar

NOTES: D Dokar Cooler I black, 2 while, 3 key, 4 blue, 5 grown, 5 yellow, 7 orange, 8 prown. 2: On non-stocking items, contact Reme Cable for minimum acceptable exercisionung quantities. 3: For three while, single phase shuffing services, file allowable ampacities are as follows:

SLO ANYO	Copper-Amps
	100
2	125
ŧ	150
1/0	175
20	200

Figure G-5. Rome Cable Spec 2100



SPEC 2100 4-1-87

Specification

ROME XHHW

Rome-XLP Insulation, 600 Volts

1. SCOPE

1.1 This specification describes single conductor Rome XHHW, a general purpose building wire insulated with crossfinked polyethylene (XLPE) intended for lighting and power circuits at 600 volts or less, in residential, commercial and industrial buildings. The wire may be operated at 90°C maximum continuous conductor temperature in dry locations and 75°C in wet locations and is listed by Underwriters Laboratories for use in accordance with Article 310 of the National Electrical Code.

2. APPLICABLE SPECIFICATIONS

- 2.1 The following specifications form a part of this specification to the extent specified herein:
 - 2.1.1 Underwriters Laboratories Standard 44 for Rubber-Insulated Wires and Cables.
 - 2.1.2 ICEA Pub. No. S-56-524, NEMA Pub. No. WC7 for Crosslinked-Polyeithylene-insulated Wire and Cable.
 - 2.1.3 Federal Specification J-C-30A.

3. CONDUCTORS

3.1 Conductors shall be Class B stranded annealed uncoated copper per UL Standard 44.

4. SEPARATOR

4.1 A suitable separator over the conductor may be used at the option of the manufacturer.

5. INSULATION

- 5.1 Each conductor shall be insulated with Rome-XLP, a crosslinked polyethytene complying with the physical and electrical requirements of UL Standard 44 for Type XHHW.
- 5.2 The average thickness of insulation, for a given conductor size, shall be as specified in UL Standard 44 for Type XHHW. The minimum thickness at any point shall be not less than 90% of the specified average thickness. The insulation shall be applied lightly to the conductor and shall be free-stripping.

6. IDENTIFICATION

6.1 The wire shall be identified by surface marking indicating manufacturer's identification, conductor size and melai, voltage rating, UL Symbol and type designation.

7. TESTS

7.1 Wire shall be tested in accordance with the requirements of UL Standard 44 for Type XH/W wire.

8. LABELS

8.1 The wire shall bear the Underwriters Laboratories labels for Type XHHW.

Figure G-5. Rome Cable Spec 2100 (continued)

		<u>, </u>	COLDI	-CODIE PO	YETHYLEISE	INSUL ATION		1997-12	1. 144 - 1
							<u></u>		ED THINED
DUTETHTLENE JACKET				1021 1	FOR SHIELD	المنسة متنافية عس	£ ¥B	LANDED TINN DRAW WH	
CATALON	80. OF			NOM. HISULATION THICKNESS		THEXNESS		D.D.	
	COMB.	SIZE	STRAM	MCHEE	Will "	INCHES	NH	ACHES	14114
C:2551	2	18	16	.030	0.76	.030	0.76	285	724.
C2553	-2	16	26	.030	0.76	.030	0.76	.310	7 87
C2550	2.	14		636	0.76	030	079	340	8.64
~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~						@2020C020000000000			

# **Product Construction**

### Conductor:

- Stranded tinned copper per ASTM-B-33
- Insulation: Premium grade low density polyethytene

### Shield

- Flexfoit# Aluminum/Polyester/ Aluminum Foil
- 100% coverage, 25% overlap, foil facing out
- Stranded tinned copper drain wire one gauge size smaller than the conductor size

### Jacket:

 Premium grade black polyethylene -20°C to +60°C

## **Application:**

 Interface cable between traffic loop and signal control station

### **Industry Approvals:**

Meets IMSA 50-2 specifications

### Packaging:

2500 ft (762 M)

	Distributed by:	
CAROL CABLE CO., INC. PAWTUCKET, RI 02862	Cablanarie Commutileation 5750 Edgewater Dr. Orlando, Fl. 52610	

### Figure G-6. Carol Cable Lead-In Cable Specifications

Table G-4. Physical Requirements of GAF Type III Steep Roofing Asphalt

Requirement	Minimum V	alue	Maximum	Value	Test	Method
Softening Point (°F)	185		205		AST	M D36
Flash Point (°F)	475		-		ASTM D92	
Penetration Units:						
at 32°F	6		-			
at 77°F	15		35			
at 115ºF	· –		90			
Ductility at 77°F (cm)	2.5		-		ASTI	M D113
Solubility in Trichloroethylene (%)	99		•		ASTN	1 D2042

(F - 32)/1.8 = °C

Asphalts shall be homogenous and free of water and shall conform to the physical properties in the table. Product meets ASTM D312, giving assurance each shipment meets or exceeds the physical requirements of roofing asphalts for softening point, flash, penetration, and ductility.

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# Table G-5. Inductive Loop Detector Installation Information for I-10in Phoenix, Arizona (Autumn 1993)

Location of Loop: I-10 near 13th Street in downtown Phoenix

Wire Loop Information:

Manufacturer: _____ Model: Detectaduct

Shape and Size: 6 ft x 6 ft (1.8 m x 1.8 m) Date loop installed: 8/21/93

Loop Construction (wire laid in pavement, wire in conduit laid in pavement, wire encased in epoxy or other compound and then laid in pavement, etc.): Wire laid in pavement, encased in 3M sealant.

Gauge of wire used in loop: #14 AWG Number of turns: 4

Type of insulation: TNNN Type of conduit used, if any: PVC sleeve

Lead-in cable length: 60+ ft (18.3+ m) Type of splice: solder

Description or drawing of cross section of road where loop is installed. Indicate at what depth loop is located.

Sawcut depth: 3 inches (76.2 mm); wire lies 2-1/2 inches (63.5 mm) below surface. Road surface concrete is PCCP.

Please supply a set of loop installation specifications if not already supplied.

## Detector Amplifier Information:

Manufacturer: Detector Systems Model: 272

Number of Channels: 2 Date last tuned: Unknown

Settings of switches, jumpers, etc. on amplifier:

Sensitivity: 3, Response time = 5 ms

Pulse Mode

## **Oscillator Frequency**

	Lane 1*	Lane 2*	Lane 3
First Loop Encountered	HI	Û	HI
Second Loop Encountered	വ	MED	വ

* Could not eliminate cross talk between pairs of loops in lanes 1 and 2.

Self-Powered Magnetometer DataUsed Receiver Channels 1 (47.140 MHz) and 4 (47.060 MHz)

## Table G-6. Inductive Loop Detector Installation Information for I-10in Phoenix, Arizona (Summer 1994)

Location of Loop: I-10 near 13th Street in downtown Phoenix

Wire Loop Information:

Manufacturer: _____ Model: Detectaduct

Shape and Size: 6 ft x 6 ft (1.8 m x 1.8 m) Date loop installed: 8/21/93

Loop Construction (wire laid in pavement, wire in conduit laid in pavement, wire encased in epoxy or other compound and then laid in pavement, etc.): Wire laid in pavement, encased in 3M sealant.

Gauge of wire used in loop: #14 AWG Number of turns: 4

Type of insulation: TNNN Type of conduit used, if any: PVC sleeve

Lead-in cable length: 60+ ft (18.3+ m) Type of splice: solder

Description or drawing of cross section of road where loop is installed. Indicate at what depth loop is located.

Sawcut depth: 3 inches (76.2 mm); wire lies 2-1/2 inches (63.5 mm) below surface. Road surface concrete is PCCP.

Please supply a set of loop installation specifications if not already supplied.

## **Detector Amplifier Information:**

Manufacturer	Model	Number Channels	Sens.	Response Time	Mode	Where Used
Detector Systems	613-SS	1	3	1 ms	Pulse	First loop, lane 1
Detector Systems	613-SS	1	3	1 ms	Pulse	First loop, lane 2
Detector Systems	272	2	3	5 ms	Pulse	First loop, lane 3
Detector Systems	272	2	3	5 ms	Pulse	Second loop, lane 3

* Only used one loop in each of lanes 1 and 2 because of cross talk.

#### Self-Powered Magnetometer Data: Used Receiver Channels 1 (47.140 MHz) and 4 (47.060 MHz)

## Table G-7. Inductive Loop Detector Installation Information for Oracle Road in Tucson, Arizona

Location of Loop: Oracle Road at Auto Mall Drive in Tucson

## Wire Loop Information:

Manufacturer: Sun State Wire Model: Detectaduct, round cross section, 1/4-inch (6.4-mm) diameter

Shape and Size: 6 ft x 6 ft (1.8 m x 1.8 m) Date loop installed:

Loop Construction (wire laid in pavement, wire in conduit laid in pavement, wire encased in epoxy or other compound and then laid in pavement, etc.): Wire laid in asphalt, 1/4-inch (6.4-mm) wide saw cut with epoxy seal, Briggs loop.

Gauge of wire used in loop: #14 AWG Number of turns: 3

Type of insulation: THHN-THWN Type of conduit used, if any: Home run to pull box, 3-inch (76.2-mm) PVC

Lead-in cable length: 8 ft (2.4 m) Type of splice: Heat-shrink insulation, solder splice

Description or drawing of cross section of road where loop is installed. Indicate at what depth loop is located.

Sawcut depth: 1 inch (25.4 mm). First loop (northern loop) encountered in curb lane is number 4, second loop (southern loop) in curb lane is number 3, first loop in middle lane is number 2, second loop in middle lane is number 1.

6-ft (1.8-m) diameter round loops in lane 3 were installed by Max Kutter to their specifications. 3M microloops in lane 3 were installed according to 3M specifications.

Manufacturer	Model	Number Channels	Sens.	Response Time	Mode	Where Used
Detector Systems	613-SS	1	3	1 ms	Pulse	First sq. loop, lane 2
Detector Systems	613-SS	1	3	1 ms	Pulse	Second sq. loop, lane 2
Detector Systems	613-SS	1	3	1 ms	Pulse	First sq. loop, lane 3
Detector Systems	262A	2	4	10 ms, min 20 ms, max	Pulse	Second sq. loop, lane 3
Detector Systems	262A	2	4	10 ms, min 20 ms, max	Pulse	First round loop, lane 3
Detector Systems	262A	2	4	10 ms, min 20 ms, max	Pulse	Second round lop, lane 3
Detector Systems	262A	2	4	10 ms, min 20 ms, max	Pulse	3M microloop in lane 2
Detector Systems	262A	2	4	10 ms, min 20 ms, max	Pulse	3M microloop in lane 3

## **Detector Amplifier Information:**

Amplifier	Lane 2	Lane 3
613-SS	MED	MED
613-SS	വ	-
262A	-	
262A	-	വ
262A	-	MED HI
262A	HI	HI
	613-SS 613-SS 262A 262A 262A 262A	613-SS MED 613-SS LO 262A - 262A - 262A -

## Oscillator Frequency

6 ft = 1.8 m

## APPENDIX H.

## DETECTOR CONNECTIONS TO DATA LOGGER AND POWER SUPPLIES AT THE FIELD SITES

This appendix contains tabulations of the connections from the detector output data terminals to the terminals on the data distribution panel and the data logger, and connections from the power supplies to the detector power input terminals for the configurations used in Minneapolis, Orlando, Phoenix, and Tucson.

#### HOOKUP1A.DAT

FEBRUARY 10, 1993 MINNEAPOLIS I-394 & PENN AVE. SITE

LANE 1 IS HOV LANE 2 IS EAST BOUND FAR LANE 3 IS EAST BOUND NEAR

FIRST CONFIGURATION NAME OF LOG FILE:

DETECTOR SIGNAL NAME

#### DATA LOGGER PORT

M5A	LANE 1 (HOV) RS232GND RS232XMIT RS232REC OPTO1 + OPTO2 +	1A 2A 4A 5A 7A	ORG ORG/GRN ORG/BLK ORG/WHT/BLU ORG/BLK/GRN	RS232 # 2 (COM 6) RS232 # 2 (COM 6) RS232 # 3 (COM 6) NOT CONNECTED NOT CONNECTED
M1B	LANE 1 (HOV) RELAY 1 N.O.	10A	ORG/BLK/WHT	<b>RR #</b> 1
M2B	LANE 1 (HOV) RELAY N.C. <35 MPH 36-45 MPH 46-55 MPH 56-65 MPH 66 + MPH DOPP FREQ GROUND	23A 24A 25A 26A 27A 28A 29A 30A	RED RED/GRN RED/BLK RED/WHT RED/BLK/GRN RED/BLK/WHT GRN GRN/WHT	RR # 2 NOT CONNECTED NOT CONNECTED NOT CONNECTED NOT CONNECTED NOT CONNECTED NOT CONNECTED

.

IR1 LANE 1 (HOV)

NOTE: THIS DETECTOR NEEDS TO BE CONNECTED TO COM PORT 20 WHICH IS RS232 #16 ON DIGICHANNEL BOX

	RECEIVE RELAY N.O. RX/XMT GND XMT	33A 36A 37A 38A	GRN/BLK GRN/BLK/WHT GRN/BLK/ORG WHT	RS232 #16 (COM 20) RR # 3 RS232 #16 (COM 20) RS232 #16 (COM 20)
M4	LANE 2			
	RS232 GND	41A	WHT/BLK	RS232 # 4 (COM 8)
	TRANSMIT	42A	WHT/RED	RS232 # 4 (COM 8)
	DATA CARRIER	43A	WHT/RED/ORG	NOT USED
	<b>RECEIVE DATA</b>	44A	WHT/RED/BLK	R\$232 # 4 (COM 8)
	OPTO #1 +	45A	WHT/RED/GRN	NOT CONNECTED
	OPTO #2 +	47A	WHT/RED/BLU	NOT CONNECTED

M2A	LANE 2			
	RELAY N.C.	52A	BLU	RR # 4
	<35 MPH	53A	BLU/BLK	

	36-45 MPH 46-55 MPH 56-65 MPH 66+ MPH DOPPLER SIGNAI GROUND	57A	BLU/RED BLU/WHT/ORG BLU/WHT/BLK BLK	OR #16 OR #15 AR # 3+ AR # 3-
U3	LANE 2 RELAY N.O.	63A	BLK/WHT/ORG	RR # 5
M1A	LANE 3 RELAY 1 N.O.	81A	BLK/RED	RR # 6
IR3	LANE 3 RELAY N.C.	89A	BLK/RED/WHT	RR # 7
M5B	LANE 3 RS232 GND RS232 XMIT RS232 REC OPTO1 + OPTO2 +	93A 94A 96A 97A 99A	RED (CABLE B) WHT (CABLE B)	RS232 # 3 (COM 7) RS232 # 3 (COM 7) RS232 # 3 (COM 7) NOT CONNECTED NOT CONNECTED
U2	LANE 3 RELAY N.O.	106A	YELLOW (CABLE A)	RR # 9
IR2	LANE 3 RELAY N.O.	101A	BLACK (CABLE A)	RR # 8
****************				

#### LOOPS

DETECTOR SYSTEMS 222B

HOV EAST OPTO +	161A	GREEN	OR # 1
HOV WEST OPTO +	162A	WHITE	OR # 2
LANE 2 (EAST) OPTO +	163A	GREEN	OR # 3
LANE 2 (WEST) OPTO +	164A	WHITE	OR # 4
LANE 3 (EAST) OPTO +	165A	GREEN	OR # 5
LANE 3 (WEST) OPTO +	166A	WHITE	OR # 6

******

#### AUTOSCOPE 2003

**EIM-2 CONNECTOR** 

DB 37 PINOUT

PIN 1 24 VDC GROUND

PIN 18 24 VDC POWER

PIN 29 DET 109	LANE 3	GREEN	<b>OR</b> #10
30 DET 105	LANE 3	WHITE	OR # 9
31 DET 108	LANE 2	GREEN	OR # 8
32 DET 104	LANE 2	WHITE	OR # 7

****

#### COMPUTER RECOGNITION SYSTEMS

#### TRAFFIC ANALYSIS SYSTEM (TAS):

PIN 16	ZONE 1 (W LOOP ON LANE 2)	RED	<b>OR</b> #11
14	ZONE 2 (W LOOP ON LANE 3)	RED	OR #12
10	ZONE 3 (E LOOP ON LANE 2)	RED	OR #13
8	ZONE 4 (E LOOP ON LANE 3)	RED	OR #14

## PINS 7, 9, 13, AND 15 (OF THE WIEDEMULLER CONNECTOR) ARE TIED TOGETHER (BLACK) AND CONNECTED TO THE 24 VOLT GROUND ON THE TERMINAL STRIP

#### *********

TEMP PROBES ARE	CONNECTED ON THE BRIDGE TRAILER	AR #10 AR #11
WEATHER	WIND SPEED WIND DIRECTION	AR # 8 AR # 7

#### HOOKUP02.DAT

JANUARY 23, 1993 MINNEAPOLIS I-394 & PENN AVE. SITE

LANE 1 IS HOV LANE 2 IS EAST BOUND FAR LANE 3 IS EAST BOUND NEAR

FIRST CONFIGURATION NAME OF LOG FILE:

DETECTOR	SIGNAL	DATA LOGGER
NAME		CONNECTION

M5A LANE 1 (HOV) RS232GND 1A ORG RS232 (2) RS232XMIT 2A ORG/GRN (COM 6) RS232REC 4A ORG/BLK OPTO1 + 5A ORG/WHT/BLU NOT CONNECTED OPTO2 + 7A ORG/BLK/GRN NOT CONNECTED

M1B LANE 1 (HOV) RELAY 1 N.O. 10A ORG/BLK/WHT RR #2

M2B LANE 1 (HOV) RELAY N.C. 23A RED RR #4 <35 MPH 24A RED/GRN 36-45 MPH 25A RED/BLK 46-55 MPH 26A RED/WHT 56-65 MPH 27A RED/BLK/GRN 66 + MPH 28A RED/BLK/WHT DOPPLER FREQ 29A GRN GROUND 30A GRN/WHT

IR1 LANE 1 (HOV)

NOTE: THIS DETECTOR NEEDS TO BE CONNECTED TO COM PORT 20 OR RS232 # 16 (ONLY).

RECEIVE33AGRN/BLKRS232 #16RELAY N.O.36AGRN/BLK/WHTRR #6RX/XMT GND37AGRN/BLK/ORGRS232 #16XMT38AWHTRS232 #16

M4 LANE 2 RS232 GND 41A WHT/BLK RS232 # 4 TRANSMIT 42A WHT/RED RS232 # 4 DATA CARRIER 43A WHT/RED/ORG NOT CONNECTED RECEIVE DATA 44A WHT/RED/BLK RS232 # 4 OPTO #1 + 45A WHT/RED/GRN NOT CONNECTED OPTO #2 + 47A WHT/RED/BLU NOT CONNECTED

M2A LANE 2 RELAY N.C. 52A BLU RR # 8 <35 MPH 53A BLU/BLK 36-45 MPH 54A BLU/WHT 46-55 MPH 55A BLU/RED

	56-65 MPH 56A BLU/WHT/ORG 66+ MPH 57A BLU/WHT/BLK DOPPLER SIGNAL 58A BLK AR # 3 GROUND 59A BLK/WHT RETURN LINE
U3	LANE 2 RELAY N.O. 63A BLK/WHT/ORG RR # 10
M1A	LANE 3 RELAY 1 N.O. 81A BLK/RED RR # 12
IR3	LANE 3 RELAY N.C. 89A BLK/RED/WHT RR # 14
M5B	LANE 3 RS232 GND 93A GREEN (CABLE B) RS232 #3 RS232 XMIT 94A RED (CABLE B) RS232 #3 RS232 REC 96A WHT (CABLE B) RS232 #3
U2	LANE 3 RELAY N.O. 106A YELLOW (CABLE A) RR # 18
IR2	LANE 3 RELAY N.O. 101A BLACK (CABLE A) RR # 16

******

## LOOPS

DETECTOR SYSTEMS 222B

HOV EAST	OPTO +	161A GREEN	OR #2
HOV WEST	OPTO +	162A WHITE	OR #4
LANE 2 (EAST	T) OPTO +	163A GREEN	OR #6
LANE 2 (WES'	T) OPTO +	164A WHITE	OR #8
LANE 3 (EAST	T) OPTO +	165A GREEN	<b>OR</b> #10
LANE 3 (WES'	T) OPTO +	166A WHITE	OR #12

AUTOSCOPE 2003

EIM-2 CONNECTOR

DB 37 PINOUT

PIN 1 24 VDC GROUND PIN 18 24 VDC POWER

PIN 29 DET 109	LANE 3		
30 DET 105	LANE 3		OR #20
31 DET 108	LANE 2		OR #19
32 DET 104	LANE 2		OR #18
		OR #16	

******

#### COMPUTER RECOGNITION SYSTEMS

TAS

#### ***********

TEMPERATURE PROBES ARE CONNECTED ON THE BRIDGE AR 10 TRAILER AR 11

WEATHER

WIND SPEED AR 8 WIND DIRECTION AR 7

#### HOOKUP4A.DAT

FEBRUARY 10, 1993 MINNEAPOLIS I-394 & PENN AVE. SITE

LANE 1 IS HOV LANE 2 IS EAST BOUND FAR LANE 3 IS EAST BOUND NEAR

FIRST CONFIGURATION NAME OF LOG FILE:

DETECTOR	SIGNAL	DATA LOGGER
NAME		CONNECTION

- M5A LANE 1 (HOV) ORG RS232 # 2 (COM 6) RS232GND 1A RS232XMIT 2A ORG/GRN RS232 # 2 (COM 6) RS232REC 4A ORG/BLK RS232 # 3 (COM 6) OPTO1 + 5A ORG/WHT/BLU NOT CONNECTED OPTO2 + 7A ORG/BLK/GRN NOT CONNECTED
- M1B LANE 1 (HOV) RELAY 1 N.O. 10A ORG/BLK/WHT RR # 2
- M2B LANE 1 (HOV) RELAY N.C. 23A RED RR #4 24A RED/GRN <35 MPH 36-45 MPH 25A RED/BLK NOT CONNECTED 46-55 MPH 26A RED/WHT OR #29 27A RED/BLK/GRN OR #31 56-65 MPH 28A RED/BLK/WHT NOT CONNECTED 66 + MPH DOPPLER FREO 29A GRN AR # 3+ GROUND 30A GRN/WHT AR # 3-

IR1 LANE 1 (HOV)

NOTE: THIS DETECTOR NEEDS TO BE CONNECTED TO COM PORT 20 WHICH IS RS232 #16 ON DIGICHANNEL BOX

 RECEIVE
 33A
 GRN/BLK
 R\$232 #16 (COM 20)

 RELAY N.O.
 36A
 GRN/BLK/WHT
 RR # 6

 RX/XMT GND
 37A
 GRN/BLK/ORG
 R\$232 #16 (COM 20)

 XMT
 38A
 WHT
 R\$232 #16 (COM 20)

M4 LANE 2 RS232 GND 41A WHT/BLK RS232 # 4 TRANSMIT 42A WHT/RED RS232 # 4 DATA CARRIER 43A WHT/RED/ORG NOT USED RECEIVE DATA 44A WHT/RED/BLK RS232 # 4 OPTO #1 + 45A WHT/RED/GRN NOT CONNECTED OPTO #2 + 47A WHT/RED/BLU NOT CONNECTED

M2A	LANE 2			
	RELAY N.C.	52A	BLU	RR # 8
	<35 MPH	53A	BLU/BLK	
	36-45 MPH	54A	BLU/WHT	NOT CONNECTED
	46-55 MPH	55A	BLU/RED	NOT CONNECTED

56-65 MPH 56A BLU/WHT/ORG NOT CONNECTED 66+ MPH 57A BLU/WHT/BLK NOT CONNECTED DOPPLER SIGNAL 58A BLK NOT CONNECTED GROUND 59A BLK/WHT NOT CONNECTED LANE 2 U3 RELAY N.O. 63A BLK/WHT/ORG RR #10 M1A LANE 3 RELAY 1 N.O. 81A BLK/RED RR #12 IR3 LANE 3 RELAY N.C. 89A BLK/RED/WHT RR #14 M5B LANE 3 RS232 GND 93A GREEN (CABLE B) RS232 # 3 (COM 7) 94A RED (CABLE B) RS232 # 3 (COM 7) RS232 XMIT 96A WHT (CABLE B) RS232 # 3 (COM 7) RS232 REC 97A GREEN NOT CONNECTED OPTO1 + OPTO2+ 99A RED NOT CONNECTED U2 LANE 3 RELAY N.O. 106A YELLOW (CABLE A) RR #18 IR2 LANE 3 RELAY N.O. 101A BLACK (CABLE A) RR #16 ********** LOOPS DETECTOR SYSTEMS 222B 161A GREEN HOV EAST OPTO +OR # 2 HOV WEST OPTO + 162A WHITE OR # 4 163A GREEN LANE 2 (EAST) OPTO + OR # 6 164A WHITE LANE 2 (WEST) OPTO + OR # 8 LANE 3 (EAST) OPTO + 165A GREEN OR #10 166A WHITE LANE 3 (WEST) OPTO + OR #12 *********** AUTOSCOPE 2003 **EIM-2 CONNECTOR DB 37 PINOUT** PIN 1 24 VDC GROUND PIN 18 24 VDC POWER PIN 29 DET 109 LANE 3 GREEN OR #20 30 DET 105 LANE 3 WHITE OR #18 31 DET 108 LANE 2 OR #16 GREEN 32 DET 104 LANE 2 WHITE OR #14 ****** COMPUTER RECOGNITION SYSTEMS

TRAFFIC ANALYSIS SYSTEM (TAS):

PIN 16 ZONE 1 (WEST LOOP ON LANE 2)	OR #22
14 ZONE 2 (WEST LOOP ON LANE 3)	OR #24
10 ZONE 3 (EAST LOOP ON LANE 2)	OR #26
8 ZONE 4 (EAST LOOP ON LANE 3)	OR #28

PINS 7, 9, 13, AND 15 (OF THE WIEDEMULLER CONNECTOR) ARE TIED TOGETHER AND CONNECTED TO THE 24 VOLT GROUND ON THE TERMINAL STRIP

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*****

TEMPERATURE PROBES ARE CONNECTED ON THE BRIDGE AR #10 TRAILER AR #11

WEATHER WIND SPEED AR # 8 WIND DIRECTION AR # 7

#### HOOKUP6.TXT

MARCH 6, 1993 OLSON HIGHWAY (TH 55) AND E.LYNDALE AVE. N. SITE

LANE 1 IS SOUTHMOST THROUGH LANE WESTBOUND LANE 2 IS MIDDLE THROUGH LANE WESTBOUND LANE 3 REPRESENTS DETECTORS MOUNTED ON POLE 25 FT EAST OF SIGN BRIDGE

FIRST CONFIGURATION NAME OF LOG FILE:

DETECTOR	SIGNAL	DATA LOGGER
SYMBOL		CONNECTION

M-1B LANE 1 (SOUTHMOST THRU LANE WESTBOUND) RELAY 1 N.O. 9A ORG/BLK/WHT RR # 2

M-2B LANE 1

RELAY N.C.	23A	RED	RR # 4
<35 MPH	24A	RED/GRN	NOT CONNECTED
36-45 MPH	25A	RED/BLK	NOT CONNECTED
46-55 MPH	26A	RED/WHT	NOT CONNECTED
56-65 MPH	27A	RED/BLK/	GRN NOT CONNECTED
66 + MPH	28A	RED/BLK/	WHT NOT CONNECTED
DOPPLER FR	EQ 29	9A GRN	AR # 3+
GROUND	30A	GRN/WHT	Г AR # 3-

- M-4B LANE 1 RS232 GND 1A WHT/BLK RS232 # 4 (COM 8) TRANSMIT 2A WHT/RED RS232 # 4 (COM 8) DATA CARRIER 3A WHT/RED/ORG NOT USED WHT/RED/BLK RS232 # 4 (COM 8) RECEIVE DATA 4A OPTO #1 + 5A WHT/RED/GRN NOT CONNECTED OPTO #2 + 7A WHT/RED/BLU NOT CONNECTED
- IR-1 LANE 1 RELAY N.O. 36A GRN/BLK/WHT RR # 6 RECEIVE 33A GRN/BLK RS232 #16 (COM 20) XMT 38A WHT RS232 #16 (COM 20) RX/XMT GND 37A GRN/BLK/ORG RS232 #16 (COM 20)
- IR-2 LANE 1 RELAY N.O. 18A BLACK (CABLE A) RR #16
- U-2A LANE 1 RELAY N.O. 106A YELLOW (CBL A) RR #18
- U-3A LANE 1 RELAY N.O. 17A BLK/WHT/ORG RR #10
- M-4A LANE 2 (MIDDLE THRU LANE WESTBOUND) RS232 GND 41A WHT/BLK RS232 # 3 (COM 7) TRANSMIT 42A WHT/RED RS232 # 3 (COM 7) DATA CARRIER 43A WHT/RED/ORG NOT USED RECEIVE DATA 44A WHT/RED/BLK RS232 # 3 (COM 7) 45A WHT/RED/GRN NOT CONNECTED OPTO 1+ OPTO 2+ 47A WHT/RED/BLU NOT CONNECTED

M-5A	LANE 2			
	RS232 XMIT	54A	ORG/GRN	RS232 # 2 (COM 6)
	RS232 REC	56A	ORG/BLK	RS232 # 2 (COM 6)
	RS232 GND	53A	ORG	RS232 # 2 (COM 6)

M-6A	LANE	2		
	OPTO 1+	61A	BLU/WHT/OR	G OR #10
	OPTO 2+	63A	BLU/WHT/BL	K OR #12
	OPTO 3+		NOT CO	ONNECTED
	OPTO 4+		NOT CO	ONNECTED
	OPTO 5+		NOT CO	DNNECTED
	TX	67A	RS232 #	7 (COM 11)
	RX	68A	RS232 #	7 (COM 11)
	SERIAL G	ROUND	69A	RS232 # 7 (COM 11)

IR-3 LANE 2 RELAY N.C. 51A BLK/RED/WHT RR #22

U-2B LANE 2 RELAY N.O. 108A BLUE RR #24

M-1A LANE 3 (SIDE VIEW OF WESTBOUND LANES - MIDDLE DETECTOR ON POLE) RELAY 1 N.O. 149A BLK/RED RR #8

M-6B LANE 3 (SIDE VIEW OF WESTBOUND LANES - TOP DETECTOR ON POLE) OPTO 1+ 121A RED/WHT OR #30

OF IO IT	1417		/ ** 111	OK #30
OPTO 2+	122A	RED	/BLK/GRN	OR #32
OPTO 3+			NOT CO	NNECTED
OPTO 4+			NOT CO	NNECTED
OPTO 5+			NOT CO	NNECTED
TX	128A		RS232 # 8	3 (COM 12)
RX	127A		RS232 # 8	3 (COM 12)
SERIAL G	ROUND	129A		RS232 # 8 (COM 12)

U-3B LANE 3 (SIDE VIEW OF RIGHT-TURN POCKET LANE - BOTTOM DETECTOR ON POLE)

**RELAY N.O. 143A BLU/WHT RR #2**0

INDUCTIVE LOOPS

DETECTOR SYSTEMS 222B AMPLIFIERS

162A WHI 163A GREI 164A WHI	TE         OR # 4           EN         OR # 6           TE         OR # 8	*****
TRONICS		
FTWARE REL	EASE NUMBER AND I	DATE:
	162A WHI 163A GREJ 164A WHI TRONICS WHITE GREEN	162A WHITE OR # 4 163A GREEN OR # 6 164A WHITE OR # 8 TRONICS WHITE RR #12

EIM-2 CONNECTOR DB 37 PINOUT PIN 1 24 VDC GROUND PIN 18 24 VDC POWER

PIN 29 DET 109	LANE 1	GREEN	OR #14	
30 DET 105	LANE 1	WHITE	OR #16	
31 DET 108	LANE 2	GREEN	OR #18	
32 DET 104	LANE 2	WHITE	OR #20	
*****	*******	*****	*****	*****

COMPUTER RECOGNITION SYSTEMS: TRAFFIC ANALYSIS SYSTEM (TAS):

PIN 16 ZONE 1 (EAST LOOP ON LANE 1)	OR #22
14 ZONE 2 (EAST LOOP ON LANE 2)	OR #24
10 ZONE 3 (WEST LOOP ON LANE 1)	OR #26
8 ZONE 4 (WEST LOOP ON LANE 2)	OR #28

OUTPUT FROM TAS SERIAL PORT 2

RS232 # 5 (COM 9)

LANES 1, 2, 3 (THE 3 THRU WESTBOUND LANES)

 RECEIVE TO DELTA RECORDER
 145A
 RS232 # 6 (COM 10)

 TRANSMIT FROM DELTA RECORDER
 146A
 RS232 # 6 (COM 10)

 RS232 GROUND
 147A
 RS232 # 6 (COM 10)

GREEN SIGNAL PHASE FROM WESTRBOUND SIGNAL AT INTERSECTION OF OLSON HWY AND

E. LYNDALE AVE. N (NORTHEAST CORNER OF INTERSECTION)

WEATHER WIND SPEED AR # 8 WIND DIRECTION AR # 7

#### HOOKUPI4.TXT

JUNE 29, 1993 I-4 @ SR-436, Altamonte Springs, Fla.

LANE 1 IS INSIDE LANE WESTBOUND I-4 (Fast Lane) LANE 2 IS MIDDLE LANE WESTBOUND I-4 LANE 3 IS OUTSIDE LANE WESTBOUND I-4 (Slow Lane)

FIRST CONFIGURATION NAME OF LOG FILE:

DETECTOR	SIGNAL	WIRE COLOR	CONNECTION
SYMBOL		INTO PANEL B	

M-1B	LANE 1 (Semi-sidefi	ring. Detector n	nounted on sur	port beam)
	RELAY 1 N.O.	130A	YELLOW	RR #6
	RELAY COM	131A	ORANGE	+24 V GND
	KLEAT COM	151A	ORAIOL	+2+ V GIND
M-2B	LANE 1			
	RELAY COM	22A	VIOLET	+24 V GND
	RELAY N.C.	23A	BLUE	RR #12
	<35 MPH	24A	VIOLET	OR2 #20
	36-45 MPH	25A	GRAY	OR2 #21
	46-55 MPH	26A	RED	OR2 #22
	56-65 MPH	27A	BROWN	OR2 #23
	66 + MPH	28A	RED	OR2 #24
	DOPP. FREQ	29A	ORANGE	AR #3+
	GROUND	30A	RED	AR #3-
M-4B	LANE 1			
	RS232 GND	1A	WHITE	RS232 # 3 (COM 7)
	TRANSMIT	2A	ORANGE	RS232 # 3 (COM 7)
	DATA CARR.	3A	WHITE	NOT USED
	RECEIVE DATA		GREEN	RS232 # 3 (COM 7)
	OPTO #1 +	5A	WHITE	OR1 #7
	OPTO #1 -	6A	BLUE	+24 V GND
	OPTO #2 +	7A	WHITE	OR1 #8
	OPTO #2 -	8A	GRAY	+24 V GND
IR-1	LANE 1			
	RELAY N.O.	36A	BLACK	RR #13
	RELAY COM	35A	BROWN	+24 V GND
	RECEIVE	33A	GRAY	RS232 #9 (COM 13)
	XMT	38A	BLACK	RS232 #9 (COM 13)
	RX/XMT GND	37A	GREEN	RS232 #9 (COM 13)
		JIA	GILLEN	R6252 #7 (COM 15)
IR-2	LANE 1			
	RELAY N.O.	18A	GREEN	RR #14
	RELAY COM	19A	RED	+24 V GND
U-2A	LANE 1			
0-2A	RELAY N.O.	136B	WHITE	DD #10
			WHITE	RR #10
	RELAY COM	137B	RED	+24 V GND
U-3	LANE 1			
	RELAY COM	16A	BROWN	+24 V GND
	RELAY N.O.	17A	VIOLET	RR #11
				<b>_</b>

U-1 LANE 2

RLY N.C. (S)	1 <b>12B</b>	RED	RR #5
RELAY COM	113B	GREEN	+24 V GND
RLY N.C. (L)	114B	GREEN	RR #4

*NOTE: WE ARE RECORDING BOTH THE LONG VEHICLE AND SHORT VEHICLE OUTPUTS FROM THE SUMITOMO SDU-200, PENDING MORE INFORMATION FROM THE VENDOR.

M-4A	LANE 2			
IVI-4A	LANE 2 RS232 GND	41A	WHITE	RS232 #4 (COM 8)
	TRANSMIT	42A	ORANGE	RS232 #4 (COM 8)
	DATA CARR	43A	WHITE	NOT USED
	RCV DATA 44A		RS232	#4 (COM 8)
	OPTO 1+	45A	WHITE	OR1 #11
	OPTO 1-	46A	BLUE	+24 V GND
	OPTO 2+	47A	WHITE	OR1 #12
	OPTO 2-	48A	GRAY	+24 V GND
M-5A	LANE 2			
	RS232 XMIT	54A	ORANGE	RS232 #2 (COM 6)
	RS232 REC	56A	GREEN	RS232 #2 (COM 6)
	RS232 GND	53A	VIOLET	RS232 #2 (COM 6)
		VIOLET	OR1 #13	
	OPTO 1-	58A	BLUE	+24 V GND
		VIOLET	OR1 #14	
	OPTO 2- 60A	GRAY	+24 V GND	
M-6A	LANE 2			
		VIOLET	OR1 #9	
	OPTO 1-	62A	YELLOW	+24 V GND
	OPTO 2+	63A	RED	OR1 #10
	OPTO 2-	64A	CREAM	+24 V GND
	OPTO 3+ OPTO 3-	65A	ORANGE	NOT CONNECTED
	TX	66A 67A	WHITE BROWN	NOT CONNECTED RS232 # 7 (COM 11)
	RX	68A	GRAY	RS232 # 7 (COM 11) RS232 # 7 (COM 11)
	SERIAL GND	69A	PINK	RS232 # 7 (COM 11) RS232 # 7 (COM 11)
		0711		
IR-3	LANE 2			
	RELAY N.C.	51A	YELLOW	RR #15
	RELAY COM	50A	GREEN	+24 V GND
U-2B	LANE 2			
	RELAY N.O.	140B	BLACK	
	RELAY COM	139B	WHT/BLK	+24 V GND
M-1A	LANE 2			
	RELAY 1 N.O.	10A	YELLOW	<b>RR</b> #16
	RLY 1 COM 11A	ORANGE	+24 V GND	
M-6B	SIDE-FIRING ACRO	SS ALL 6 LAN	ES, MOUNT	ED ON POLE
		VIOLET	OR2 #1 (EE	
		YELLOW	+24 V GND	
		RED		(EB MIDDLE)
		CREAM	+24 V GND	
		ORANGE	OR2 #3 (EH	-
	OPTO 3- 91A	WHITE	+24 V GND	

0.0.00			0.000 // // //	
OPTC OPTO	• • • • • •	VIOLET	OR2 #4 (W +24 V GND	•
OPTO		YELLOW 94A	RED	OR2 #5 (WB MIDDLE)
OPTO		95A	CREAM	
OPTC	-	96A	ORANGE	OR2 #6 (WB SLOW)
OPTO		97A		+24 V GND
TX		BROWN	RS232 # 8 (	
RX	034	84A		RS232 # 8 (COM 12)
	AL GND	85A	PINK	RS232 # 8 (COM 12)
02111		0011		
******	*****	*****	********	*****
INDUCTIVE LOC	OPS			
DETECTOR SYS	TEMS 222D	AMPLIFIERS		
	To at ) 161 A	WHITE	OR1 #1	
LN 1 OPTO 1+ (I LN 1 OPTO 2+ (I		162A	GREEN	OR1 #2
LN 2 OPTO 1+ (N			OREEN OR1 #3	OK1 #2
LN 2 OPTO 2+ (N				
			OR1 #4 OR1 #5	
LN 3 OPTO 1+ (S LN 3 OPTO 2+ (S	Mow) 105A	CDEEN		
LN 3 0P10 2+ (3	510W) 100A	GREEN	OR1 #6	
*****	*****	****	****	******
MAGNETOMET	ERS			
SPVD MFG BY N	AIDIAN ELEO	CTRONICS		
		0.5.4.1.0.5	<b>DD</b> (10)	
LN 1 (Fast) Unit 1				
CHANNEL 4 CO		122A	VIOLET	+24 V GND
LN 1 (Fast) Unit 2	. ,		RR #7	
CHANNEL 3 CO		124A	GREEN	+24 V GND ******
AUTOSCOPE 20				
AUTOSCOPE 200	JJ ENTERS	OUT I WAKE KE	LEASE NUI	VIDER. 5.2.1
PIN 29	DET 116	LANE 3 (SLO	W)	OR2 #7
30 DET 11.	3	LANE 3 (SLO	W)	OR2 #8
31 DET 110	0	LANE 3 (SLO	W) OR2 #9	
32				
33 DET 117	LANE 2 (M	IDDLE)	OR2 #10	
34 DET 114	LANE 2 (M	IDDLE)	OR2 #11	
35 DET 111	•		OR2 #12	
36	· ·	,		
10 DET 118	LANE 1 (FA	AST)	OR2 #13	
11 DET 115			OR2 #14	
12 DET 112		LÁNE 1 (FAS	T) OR2 #1	5
18&37	+24 V dc	•		
20 & 1	+24 V GND			
******	******	******	*****	*****

COMPUTER RECOGNITION SYSTEMS: TRAFFIC ANALYSIS SYSTEM (TAS):

16 ZONE 1	OR2 #
14 ZONE 2	OR2 #
10 ZONE 3	OR2 #
8 ZONE 4	OR2 #

OUTPUT FROM TAS SERIAL PORT 2 RS232 #5 (COM 9)

PINS 7, 9, 13, AND 15 (OF THE WIEDEMULLER CONNECTOR) ARE TIED TOGETHER AND CONNECTED TO THE 24 VOLT GROUND *******

TIMEMARK VC-1 VEHICLE CLASSIFIER

PIN

RECEIVE TO DELTA RECORDER	NOT CONNECTED
TRANSMIT FROM DELTA RECORDER	NOT CONNECTED
RS232 GROUND	NOT CONNECTED
*****	**********
GREEN SIGNAL PHASE	

GREEN PHASE N/A GROUND OR REFERENCE N/A ********* TEMPERATURE PROBE IS CONNECTED ON THE BRIDGE AR #10

WEATHER	WIND SPEED	AR # 8		
	WIND	AR # 7		
***************************************				

#### SR436.TXT

Aug. 29, 1993 I-4 @ SR-436, Altamonte Springs, Fla.

LANE 1 IS INSIDE LANE WESTBOUND I-4 (Fast Lane) LANE 2 IS MIDDLE LANE WESTBOUND I-4 LANE 3 IS OUTSIDE LANE WESTBOUND I-4 (Slow Lane)

FIRST CONFIGURATION NAME OF LOG FILE:

DETEC SYMBC			WIRE COLOR INTO PANEL B	CONNECTION
M-2B	LANE 1 RELAY COM RELAY N.C. <35 MPH 36-45 MPH 46-55 MPH 56-65 MPH 66 + MPH DOPP. FREQ GROUND	22A 23A 24A 25A 26A 27A 28A 29A 30A	VIOLET BLUE VIOLET GRAY RED BROWN RED ORANGE RED	+24 V GND RR #12 OR2 #20 OR2 #21 OR2 #22 OR2 #23 OR2 #24 AR #3+ AR #3-
M-4B	LANE 1 RS232 GND TRANSMIT DATA CARR. RECEIVE DATA OPTO #1 + OPTO #1 - OPTO #2 + OPTO #2 -	1A 2A 3A 4A 5A 6A 7A 8A	WHITE ORANGE WHITE GREEN WHITE BLUE WHITE GRAY	RS232 # 3 (COM 7) RS232 # 3 (COM 7) NOT USED RS232 # 3 (COM 7) OR1 #7 +24 V GND OR1 #8 +24 V GND
IR-1	LANE 1 RELAY N.O. RELAY COM RECEIVE XMT RX/XMT GND	36A 35A 33A 38A 37A	BLACK BROWN GRAY BLACK GREEN	RR #13 +24 V GND RS232 #9 (COM 13) RS232 #9 (COM 13) RS232 #9 (COM 13)
IR-2	LANE 1 (Mount RELAY N.O. RELAY COM	ed in lane 18A 19A	2, looking at lane 1) GREEN RED	RR #14 +24 V GND
U-2A	LANE 1 RELAY N.O. RELAY COM	136B 137B	WHITE RED	RR #10 +24 V GND
U-3	LANE 1 RELAY COM RELAY N.O.	16A 17A	BROWN VIOLET	+24 V GND RR #11
U-1	LANE 2 RLY N.C. (S) RELAY COM	112B 113B	RED GREEN	RR #5 +24 V GND

RLY N.C. (L) 114B

*NOTE: WE ARE RECORDING BOTH THE LONG VEHICLE AND SHORT VEHICLE OUTPUTS FROM THE SUMITOMO SDU-200, PENDING MORE INFORMATION FROM THE VENDOR.

M-5A	OPTO 1-	56A 53A VIOLET 58A VIOLET	ORANGE GREEN VIOLET OR1 #13 BLUE OR1 #14 +24 V GND	RS232 #2 (COM 6) RS232 #2 (COM 6) +24 V GND
M-6A	LANE 2 OPTO 1+ 61A OPTO 1- OPTO 2+ OPTO 2- OPTO 3+ OPTO 3- TX RX SERIAL GND	VIOLET 62A 63A 64A 65A 66A 67A 68A 69A	OR1 #9 YELLOW RED CREAM ORANGE WHITE BROWN GRAY PINK	+24 V GND OR1 #10 +24 V GND NOT CONNECTED NOT CONNECTED RS232 # 7 (COM 11) RS232 # 7 (COM 11) RS232 # 7 (COM 11)
IR-3	LANE 2 RELAY N.C. RELAY COM	51A 50A	YELLOW GREEN	
U-2B	LANE 2 RELAY N.O. RELAY COM	140B 139B	BLACK WHT/BLK	RR #9 +24 V GND
M-1A	LANE 2 RELAY 1 N.O. RLY 1 COM 11A	10A ORANGE	YELLOW +24 V GND	
M-6B	OPTO 1- 87A	VIOLET YELLOW RED CREAM ORANGE WHITE	OR2 #1 (EE +24 V GND OR2 #2	B SLOW) (EB MIDDLE) B FAST) B FAST) OR2 #5 (WB MIDDLE) +24 V GND OR2 #6 (WB SLOW) +24 V GND

******

INDUCTIVE LOOPS

DETECTOR SYSTEMS 222D AMPLIFIERS

LN 1 OPTO 1+ (Fast) LN 1 OPTO 2+ (Fast) LN 2 OPTO 1+ (Middle) LN 2 OPTO 2+ (Middle) LN 3 OPTO 1+ (Slow) LN 3 OPTO 2+ (Slow)	162A 163A WHITE 164A GREEN 165A WHITE	OR1 #1 GREEN OR1 #3 OR1 #4 OR1 #5 OR1 #6	OR1 #2
*****************	****	*******	*****
MAGNETOMETERS SPVD MFG BY MIDIAI	N ELECTRONICS		
LN 1 (Fast) Unit 1 (Ch4) CHANNEL 4 COMMON LN 1 (Fast) Unit 2 (Ch3) CHANNEL 3 COMMON AUTOSCOPE 2003 EN EIM-2 CONNECTOR	122A 123A BLUE 124A ************************************	VIOLET RR #7 GREEN	+24 V GND ******
DB 37 PINOUT			
PIN 1 24 VDC GROU PIN 18 24 VDC POWE			
	29 DET 109 LA ANE 1 (FAST) ANE 2 (MIDDLE)	OR2 #	OR2 #

**********

32 DET 104 LANE 2 (MIDDLE)

OR2 #

,

#### COMPUTER RECOGNITION SYSTEMS: TRAFFIC ANALYSIS SYSTEM (TAS):

PIN

16 ZONE 1	OR2 #
14 ZONE 2	OR2 #
10 ZONE 3	OR2 #
8 ZONE 4	OR2 #

#### OUTPUT FROM TAS SERIAL PORT 2 RS232 #5 (COM 9)

RECEIVE TO DELTA RECORDER	NOT CONNECTED
TRANSMIT FROM DELTA RECORDER	NOT CONNECTED
RS232 GROUND	NOT CONNECTED
**********	*****

**GREEN SIGNAL PHASE** 

GREEN PHASE	RR #1	
GROUND OR REFERENCE	+24 V GND	
******	* * * * * * * * * * * * * * * * * * * *	****
TEMPERATURE PROBE IS CONNECTED	ON THE BRIDGE	AR #10

WEATHER	WIND SPEED	AR # 8	
	WIND	AR # 7	
*****	*******	*******	******

#### I-10 West at 13th Street (Phoenix Autumn 1993)

## Lane 1 (Inside General Traffic Lane)

Detector	Trmnl #	Wire Color	Panel A # (Power)	Panel B # (Data)	Function	Data Logger	Notes
M4B	1	White	128		Ground		
	2	Brown	99		12 VDC		Fuse 10
	3	White	<u> </u>	1A	RS232 Ground	COM #7	Digiboard #3
	4	Orange		2A	RS232 Transmit	COM #7	Digiboard #3
	5	White		3A	Data Carrier	Not used	
	6	Green	Í	4A	RS232 Receive	COM #7	Digiboard #3
	7	White		5A	Opto #1 +	OR1 #7	
	8	Blue		6A	Opto #1 -		24 V GND
	9	White		7A	Opto #2 +	OR1 #8	
	10	Grey		8A	Opto #2 -		24 V GND
U3A	11	Yellow	95		12 VDC		Fuse 12
	12	Brown	126		Ground		
·····	13	Yellow		71A	Relay N.C.	Not used	
	14	Orange		72A	Relay Common		24 V GND
	15	Yellow		73A	Relay N.O.	RR #6	
M2B	21	Violet	77		24 VDC		Fuse 8
	22	Brown	107		Ground		
	23	Violet		21A	Relay N.O.	RR #12	
	24	Orange		22A	Relay Common		24 V GND
	25	Violet	1	23A	Relay N.C.	Not used	
	26	Green		24A	<35 mi/h	OR2 #20	
	27	Violet	·	25A	36-45 mi/h	OR2 #21	
	28	Blue		26A	46-55 mi/h	OR2 #22	
	29	Violet		27A	56 -65 mi/h	OR2 #23	
· · · · · · · · · · · · · · · · · · ·	30	Grey	·····	28A	66+ mi/h	OR2 #24	<u> </u>
	31	Red		29A	Doppler Freq.		
	32	Brown		30A	Doppler Ground		
104				001	DC000 Data	001 #10	Disting and #
IR1	33	Red		32A	RS232 Receive	COM #13	Digiboard #
	34	Orange		33A	RS232 Transmit	COM #13	Digiboard #
	35	Red		34A	RS232 Ground	COM #13	Digiboard #
	36	Green	ļ	35A	Relay N.O.	RR #13	
	37	Red		36A	Relay Common		24 V GND
	38	Blue			Ground		<u> </u>
	39	BLK	T1/1		115 VAC		Fuse 1
-	40	CLR			AC Neutral		

1 mi/h = 1.61 km/h

## Lane 1 (Inside General Traffic Lane)

Detector	Trmnl #	Wire Color	Panel A # (Power)	Panel B # (Data)	Function	Data Logger	Notes
IR2	46	Orange		19A	Relay N.O.	RR #14	
	47	Black		20A	Relay Common		24 V GND
	48	Green			Ground		
	49	Black	T1/2		115 VAC		Fuse 2
	50	Blue			AC Neutral		
U1	L1	Red		112	······································	RR #4	
	Com	Green		113			24 V GND
	S1	Green		114	Small Veh Count	RR #5	
U2A		White/Black		139	Relay Common		24 V GND
		Black		140	Relay N.O.	RR #10	
M6A		Green	T1/4		115 VAC		Fuse 4
		Black			AC Neutral		
		Violet		61	Range Bin 1	OR1 #9	
		Yellow		62	Opto 1 return		24 V GND
		Red	*	63	Range Bin 2	OR1 #10	
		Cream		64	Opto 2 return		24 V GND
	·	Orange		65	Range Bin 3	Not used	
· ·		White		66	Opto 3 return		24 V GND
		Brown		67	RS232 TX	COM #11	Digiboard #7
		Gray		68	RS232 RCV	COM #11	Digiboard #7
		Pink		69	RS232 Ground	COM #11	Digiboard #7
ILD (back-1A)		White		161	Opto +	OR1 #1	
ILD (front-1B)		White		162	Opto +	OR1 #2	
Vehicle ID		Black		127	Relay N.O.	RR #3	
Camera	16	Green	T1/6		115 VAC		Fuse 14
(Autoscope)	17	Yellow			AC Neutral		
·····	18	Blue			Ground		

## Lane 2 (Middle General Traffic Lane)

.

Detector	Trmni #	Wire Color	Panel A # (Power)	Panel B # (Data)	Function	Data Logger	Notes
M4A	1	White	127		Ground		·
	2	Brown	75		12 VDC		Fuse 9
_	3	White	,	41A	RS232 Ground	COM #8	Digiboard #4
	4	Orange		42A	RS232 Transmit	COM #8	Digiboard #4
	5	White		43A	Data Carrier	Not used	Digiocaia "
	6	Green		44A	RS232 Receive	COM #8	Digiboard #4
	7	White		45A	Opto #1 +	OR1 #11	<u>Bigieraia</u>
	8	Blue		46A	Opto #1 -		24 V GND
	9	White		47A	Opto #2 +	OR1 #12	
	10	Grey		48A	Opto #2 -		24 V GND
U3B	11	Yellow	79		12 VDC		Fuse 7
	12	Brown	124		Ground		
	13	Yellow		15A	Relay N.C.	Not used	
	14	Orange		16A	Relay Common		24 V GND
	15	Yellow		17A	Relay N.O.	RR #11	
	16	Green			Spare		
	17	Yellow			Spare		
M5A	21	Violet	125		Ground		
	22	Brown	97		12 VDC		Fuse 11
	23	Violet		53A	RS232 Ground	COM #6	Digiboard #2
	24	Orange		54A	RS232 Transmit	COM #6	Digiboard #2
	25	Violet		55A	Data Carrier	Not used	
	26	Green		56A	RS232 Receive	COM #6	Digiboard #2
	27	Violet		57A	Opto #1 +	OR1 #13	
	28	Blue		58A	Opto #1 -		24 V GND
	29	Violet		59A	Opto #2 +	OR1 #14	
	30	Grey		60A	Opto #2 -		24 V GND
M1A	31	Red			12 VAC		12 V Xforme
	32	Brown			Ground		
	33	Red		10A	Relay N.O.	RR #16	
	34	Orange		11A	Relay Common		24 V GND
	35	Red			Spare		
100	20			E 1 A			
IR3	36	Green		51A	Relay N.O.	RR #15	OA V OND
	37	Red		50A	Relay Common		24 V GND
	38	Blue	T. /0		Ground		<b>E</b>
	39 40	Black Clear	T1/3		115 VAC AC Neutral		Fuse 3

.

I-10 Westbound at 13th Street (Phoenix Autumn 1993)

## Lane 2 (Middle General Traffic Lane)

Detector	Trmnl #	Wire Color	Panel A # (Power)	Panel B # (Data)	Function	Data Logger	Notes
		Ded/Orenet	<u> </u>	· · · · · · · · · · · · · · · · · · ·	0411/00		Even C
S1 (AT&T)		Red/Orange	57		24 VDC		Fuse 6
		Black/Black	109	407	Ground	0.01 #45	
		Red		167	Ch 1	OR1 #15	
·		Green		168	Ch 2	OR1 #16	
U2B		Red		137	Relay Common		24 V GND
		White		138	Relay N.O.	RR #9	
Mag 4		Orange		141	Relay N.O.	RR #8	
(in ILD 2A)		Purple		142			
Mag 1		Red		143	Relay N.O.	RR #7	
(in ILD 2B)		Black		144			
Temperature				133		Analog T1A	
· · · · · · · · · · · · · · · · · · ·				134		Analog T1B	
ILD (back-2A)		White		163	Opto +	OR1 #3	
ILD (front-2B)		White		164	Opto +	OR1 #4	
Vehicle ID		Black		128	Relay N.O.	RR #2	
Camera	18	Blue	T1/5		115 VAC		Fuse 13
(ADOT-Burle)	19	Yellow	-		AC Neutral		
· · · · · · · · · · · · · · · · · · ·	20	Grey			Ground		

Lane 3 (Outside General Traffic Lane)

Detector	Trmnl #	Wire Color	Panel A # (Power)	Panel B # (Data)	Function	Data Logger	Notes
ILD (back-3A)		White		165	Opto +	OR1 #5	
ILD (front-3B)		Green		166	Opto +	OR1 #6	

## Multilane Detectors

Detector	Trmnl #	Wire Color	Panel A # (Power)	Panel B # (Data)	Function	Data Logger	Notes
M6B		Green	T2/4		115 VAC		
(Side-firing		Black			AC Neutral		
on Lns 1,2,3)		Brown		83	RS232 TX	COM #12	Digiboard #8
		Gray		84	RS232 RCV	COM #12	Digiboard #8
		Pink		85	RS232 Ground	COM #12	Digiboard #8
		Purple		86	Range Bin 1	OR2 #2	
		Yellow		87	Opto 1 return		24 V GND
		Red		88	Range Bin 2	OR2 #3	
		Cream		89	Opto 2 return		24 V GND
		Orange		90	Range Bin 3	OR2 #4	
		White		91	Opto 3 return		24 V GND
		Di il or		·		0.00 //5	1
VIP 1	<u> </u>	Black 31			1st det zone	OR2 #5	Lane 1
(Econolite/	<u> </u>	Black 29			1st speed zone	OR2 #6	Lane 1
Autoscope	ļ	Black 30			2nd speed zone	OR2 #7	Lane 1
2003)		Black 35			1st det zone	OR2 #8	Lane 2
		Black 33			1st speed zone	OR2 #9	Lane 2
		Black 34			2nd speed zone	OR2 #0	Lane 2
		Black 18	114		+24 VDC		
		White 20	108		24 Volt Ground		
		White 1	108		24 Volt Ground		
VIP 2						COM #9	Digiboard # 5
(CRS/TAS)						COM #9	Digiboard # 5
						COM #9	Digiboard # 5
VIP 3						COM #15	Digiboard #11
(Traficon	ļ					COM #15	Digiboard #11
CCATS-VIP2)						COM #15	Digiboard #11
VIP 4	<b> </b>					COM #18	Digiboard #14
(Sumitomo/	†					COM #18	Digiboard #14
IDET-100)						COM #18	Digiboard #14

## Lane 1 (Inside General Traffic Lane)

Detector	Trmnl #	Wire Color	Panel A # (Power)	Panel B # (Data)	Function	Data Logger	Notes
M4B	1	White	128		Ground		······································
	2	Brown	99		12 VDC		Fuse 10
	3	White		1A	RS232 Ground	COM #7	Digiboard #3
	4	Orange		2A	RS232 Transmit	COM #7	Digiboard #
	5	White		3A	Data Carrier	Not used	- 9
	6	Green		4A	RS232 Receive	COM #7	Digiboard #:
	7	White		5A	Opto #1 +	OR1 #7	
	8	Blue		6A	Opto #1 -		24 V GND
	9	White		7A	Opto #2 +	OR1 #8	
	10	Grey		3A	Opto #2 -		24 V GND
	10			0/1			211 0.10
U3A	11	Yellow	95		12 VDC		Fuse 12
	12	Brown	126		Ground		
<b>.</b>	13	Yellow		71A	Relay N.C.	Not used	
	14	Orange		72A	Relay Common		24 V GND
	15	Yellow		73A	Relay N.O.	RR #6	
						l	
M2B	21	Violet	77		24 VDC		Fuse 8
	22	Brown	107		Ground		
	23	Violet		21A	Relay N.O.	RR #12	
	24	Orange		22A	Relay Common		24 V GND
	25	Violet		23A	Relay N.C.	Not used	
	26	Green		24A	<35 mi/h	OR2 #20	
	27	Violet		25A	36-45 mi/h	OR2 #21	
	28	Blue	_	26A	46-55 mi/h	OR2 #22	
	29	Violet		27A	56 -65 mi/h	OR2 #23	
	30	Grey		28A	66+ mi/h	OR2 #24	
	31	Red		29A	Doppler Freq.		
	32	Brown		30A	Doppler Ground		
IR1	33	Red		32A	RS232 Receive	COM #13	Digiboard #
	34	Orange		33A	RS232 Transmit	COM #13	Digiboard #
	35	Red		34A	RS232 Ground	COM #13	Digiboard #
	36	Green	-	34A 35A	Relay N.O.	RR #13	
	37	Red		36A	Relay Common		24 V GND
····	38	Blue			Ground		
· · · · · · · · · · · · · · · · · · ·	39	Black	T1/1		115 VAC		Fuse 1
	40	Clear	· · ·		AC Neutral		

1 mi/h = 1.61 km/h

## Lane 1 (Inside General Traffic Lane)

Detector	Trmni #	Wire Color	Panel A # (Power)	Panel B # (Data)	Function	Data Logger	Notes
IR2	46	Orange		19A	Relay N.O.	RR #14	
	47	Black		20A	Relay Common		24 V GND
	48	Green			Ground		
	49	Black	T1/2		115 VAC		Fuse 2
	50	Blue			AC Neutral		
Ü1	L1	Red		112		RR #4	
	Com	Green		113			24 V GND
	S1	Green		114	Small Veh Count	RR #5	
U2A		White/Black		139	Relay Common		24 V GND
02/1		Black		140	Relay N.O.	RR #10	
M6A		Green	T1/4		115 VAC		Fuse 4
		Black			AC Neutral		
		Violet		61	Range Bin 1	OR1 #9	
		Yeilow		62	Opto 1 return		24 V GND
		Red		63	Range Bin 2	OR1 #10	
		Cream		64	Opto 2 return		24 V GND
		Orange		65	Range Bin 3	Not used	
		White		66	Opto 3 return		24 V GND
		Brown		67	RS232 TX	COM #11	Digiboard #7
		Gray		68	RS232 RCV	COM #11	Digiboard #7
		Pink		69	RS232 Ground	COM #11	Digiboard #7
ILD		White		162	Opto +	OR1 #1	
Vehicle ID		Black		127	Relay N.O.	RR #3	
Camera	16	Green	T1/6		115 VAC		Fuse 14
(Autoscope)	17	Yellow			AC Neutral		
(	18	Blue			Ground		

## Lane 2 (Middle General Traffic Lane)

Detector	Trmnl #	Wire Color	Panel A # (Power)	Panel B # (Data)	Function	Data Logger	Notes
M4A	1	White	127		Ground		
	2	Brown	75		12 VDC		Fuse 9
	3	White	15	41A	RS232 Ground	COM #8	Digiboard #4
	4	Orange		41A 42A	RS232 Transmit	COM #8	Digiboard #4
	5	White		42A 43A	Data Carrier	Not used	Digiboard #4
	6	Green		44A	RS232 Receive	COM #8	Digiboard #4
· · · · · · · · · · · · · · · · · · ·	7	White		44A 45A	Opto #1 +	OR1 #11	Digiboard #4
	8	Blue		45A 46A	Opto #1 -		24 V GND
	9	White		46A 47A		OR1 #12	24 V GIND
					Opto #2 +	UR1 #12	
	10	Grey		48A	Opto #2 -		24 V GND
U3B	11	Yellow	79		12 VDC		Fuse 7
	12	Brown	124		Ground		
	13	Yellow		15A	Relay N.C.	Not used	
	14	Orange		16A	Relay Common	1101 0000	24 V GND
	15	Yellow		17A	Relay N.O.	RR #11	
	16	Green			Spare		
	17	Yellow			Spare		
		10.01			opaio		
M5A	21	Violet	125		Ground		
	22	Brown	97		12 VDC		Fuse 11
	23	Violet		53A	RS232 Ground	COM #6	Digiboard #2
	24	Orange		54A	RS232 Transmit	COM #6	Digiboard #2
	25	Violet		55A	Data Carrier	Not used	
	26	Green		56A	RS232 Receive	COM #6	Digiboard #2
	27	Violet		57A	Opto #1 +	OR1 #13	
	28	Blue		58A	Opto #1 -		24 V GND
	29	Violet		59A	Opto #2 +	OR1 #14	·······
	30	Grey		60A	Opto #2 -		24 V GND
M1A	31	Red			12 VAC		12 V Xformer
10117	32	Brown			Ground		(E + ) ((())))))
	33	Red		10A	Relay N.O.	RR #16	
	34	Orange		11A	Relay Common	101 #10	24 V GND
		Orange			riciay common		
	35	Red			Spare		
IR3	36	Green		51A	Relay N.O.	RR #15	<u></u>
	37	Red		50A	Relay Common		24 V GND
	38	Blue			Ground		
	39	Black	T1/3		115 VAC		Fuse 3
	40	Clear			AC Neutral		

#### Lane 2 (Middle General Traffic Lane)

Detector	Trmni #	Wire Color	Panel A # (Power)	Panel B # (Data)	Function	Data Logger	Notes
U2B		Red		137	Relay Common		24 V GND
		White		138	Relay N.O.	RR #9	
Mag 4		Orange		141	Relay N.O.	RR #8	
(in ILD 2A)		Purple		142			
Mag 1		Red		143	Relay N.O.	RR #7	
(in ILD 2B)		Black		144			
Temperature			<u> </u>	133		Analog T1A	
	<b></b>			134		Analog T1B	
ILD		White		164	Opto +	OR1 #2	
Vehicle ID		Black		128	Relay N.O.	RR #2	
Camera	18	Blue	T1/5		115 VAC		Fuse 13
(ADOT-Burle)	19	Yellow			AC Neutral		
······································	20	Grey			Ground		

## Lane 3 (Outside General Traffic Lane)

Detector	Trmnl #	Wire Color	Panel A # (Power)	Panel B # (Data)	Function	Data Logger	Notes
ILD (back-3A)		White		165	Opto +	OR1 #3	
ILD (front-3B)		Green		166	Opto +	OR1 #4	

## Multilane Detectors

Detector	Trmni #	Wire Color	Panel A # (Power)	Panel B # (Data)	Function	Data Logger	Notes
· · · · · · · · · · · · · · · · · · ·							
M6B		Green	T2/4		115 VAC		
(Side-firing		Black			AC Neutral		
on Lns 1,2,3)		Brown		83	RS232 TX	COM #12	Digiboard #8
		Gray		84	RS232 RCV	COM #12	Digiboard #8
		Pink		85	RS232 Ground	COM #12	Digiboard #8
		Purple		86	Range Bin 1	OR2 #2	
		Yellow		87	Opto 1 return		24 V GND
		Red		88	Range Bin 2	OR2 #3	
		Cream		89	Opto 2 return		24 V GND
		Orange		90	Range Bin 3	OR2 #4	
		White		91	Opto 3 return		24 V GND
VIP 1		Black 31			1st det zone	OR2 #5	Lane 1
(Econolite/		Black 29	-		1st speed zone	OR2 #6	Lane 1
Autoscope		Black 30			2nd speed zone	OR2 #7	Lane 1
2003)		Black 35			1st det zone	OR2 #8	Lane 2
		Black 33			1st speed zone	OR2 #9	Lane 2
		Black 34			2nd speed zone	OR2 #10	Lane 2
		Black 18	114		+24 VDC		
		White 20	108		24 Volt Ground		
		White 1	108		24 Volt Ground		¢
VIP 3						COM #15	Digiboard #11
(Traficon/					· · · · · · · · · · · · · · · · · · ·		
CCATS-VIP2)							
VIP 5						COM #14	Digiboard #10
(EVA 2000)							

		Oracle R	oad Sou	thbound	at Auto Mall D	rive	
Tucson Lane	2 (M	iddle Lane)					
Detector	Trmnl	Wire Color		Panel B#	Function	Data Logger	Notes
	#		(Power)	(Data)			
M4A	1	White	127		12V Ground		
	2	Brown	75		12 VDC		Fuse 9
	3	White		<u>41A</u>	RS232 Ground	COM #8	Digiboard #4
******	4	Orange		42A	RS232 Transmit	COM #8	Digiboard #4
*****	5	White		43A	Data Carrier	Not used	
	6	Green		44A	RS232 Receive	COM #8	Digiboard #4
	7	White		45A	Opto #1 +	OR1 #11	
	8	Blue		46A	Opto #1 -		24 V GND
	9	White		47A	Opto #2 +	OR1 #12	
	10	Grey		48A	Opto #2 -		24 V GND
U3B	11	Yeilow	79		12 VDC		Fuse 7
	12	Brown	124		12V Ground		
	13	Yellow		15A	Relay N.C.	Not used	
	14	Orange	-	16A	Relay Common		24 V GND
1038/03000000000000000000000000000000000	15	Yellow		17A	Relay N.O.	RR #11	1977 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 799 / 790 / 799 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 790 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 / 700 /
*****	1.0			~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~			
	16	Green			Spare		
	17	Yellow			Spare		
Camera	18	Blue	T1/5		115 VAC		Fuse 13
(Sumitomo)	19	Yellow			AC Neutral		
	20	Grey			Ground		
M5A	21	Violet	125		12V Ground		
	22	Brown	97		12 VDC		Fuse 11
	23	Violet	+	53A	RS232 Ground	COM #6	Digiboard #2
	24	Orange		54A	RS232 Transmit	COM #6	Digiboard #2
	25	Violet		55A	Data Carrier	Not used	
	26	Green		56A	RS232 Receive	COM #6	Digiboard #2
~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	27	Violet	+	57A	Opto #1 +	OR1 #13	Digibourd #2
	28	Blue	••••••	58A	Opto #1 -		24 V GND
	29	Violet		59A	Opto #2 +	OR1 #14	
	30	Grey		60A	Opto #2 -		24 V GND
<u>M1A</u>	31	Red			12 VAC		12 V Xformer
	32	Brown			Ground		
	33	Red		10A	Relay N.O.	RR #16	
	34	Orange		<u>11A</u>	Relay Common		24 V GND
	35	Red			Spare		
IR3	36	Green		51A	Relay N.O.	RR #15	
	37	Red		50A	Relay Common		24 V GND
	38	Blue			Ground		
	39	Red	T1/3		115 VAC		Fuse 3
	40	Grey	<u>↓</u>		AC Neutral		
	h		+				

4.8 Green Ground Fuse 2 5.0 Black T1/2 115 VAC Fuse 2 5.0 Blue AC Neutral Fuse 2 U2A Red 13.7 Relay Common 24 V GN White 13.8 Relay N.O. RR #9 24 V GN M6A Green T1/4 115 VAC Fuse 4 M6A Green T1/4 115 VAC Fuse 4 White 13.8 Relay N.O. RR #9 24 V GN M6A Green T1/4 115 VAC Fuse 4 White 61 Range Bin 1 OR1 #9 Violet 61 Range Bin 2 OR1 #10 Crearm 64 Opto 2 Return Not used 24 V GN White 66 Opto 2 Return Not used 24 V GN Brown Rs232 Transmit COM #11 Digiboard COM #11 Digiboard Gray 68 RS232 Ground COM #11 Digiboard ILD-Square Yellow 1		ļ	Oracle R	oad Sou	thbound	at Auto Mall Di	ŗīve	ļ
Detector Trmn1 Wire Color Panel A# Panel B# Function Data Logger Notes IR2 46 Orange 19A Relay N.O. RR #14 47 Black 20A Relay Common 24 V GN 48 Green Ground - - - 49 Black T1/2 115 VAC Fuse 2 50 Blue - AC Neutral - U2A Red 137 Relay Common 24 V GN White 138 Relay N.O. RR #9 - M6A Green T1/4 115 VAC Fuse 4 White 138 Relay N.O. RR #9 - M6A Green T1/4 115 VAC Fuse 4 White 61 Range Bin 1 OR1 #9 - Yellow 62 Opto 1 Return 24 V GN - Grampe 65 Range Bin 2 OR1 #110 - White	Tueses Lane	2 /84	iddlo (cpo)		}			
# (Power) (Data) Relay N.O. RR #14 47 Black 20A Relay Common 24 V GN 48 Green 20A Relay Common 24 V GN 49 Black T1/2 115 VAC Fuse 2 50 Blue AC Neutral 7 U2A Red 137 Relay Common 24 V GN White 138 Relay N.O. RR #9 7 M6A Green T1/4 115 VAC Fuse 4 Violet 61 Range Bin 1 OR1 #9 7 Violet 61 Range Bin 2 OR1 #10 24 V GN Cream 64 Opto 2 Return 24 V GN 7 Orange 65 Range Bin 3 Not used 24 V GN	Tucson Lane		lodie Lane)			1		
# (Power) (Data) Relay N.O. RR #14 47 Black 20A Relay Common 24 V GN 48 Green Ground Fuse 2 50 Black T1/2 115 VAC Fuse 2 50 Blue AC Neutral - - U2A Red 137 Relay Common 24 V GN White 138 Relay N.O. RR #9 - WA Red 137 Relay N.O. RR #9 White 138 Relay N.O. RR #9 White 138 Relay N.O. RR #9 M6A Green T1/4 115 VAC Fuse 4 White 61 Range Bin 1 OR1 #9 Crearm 64 Opto 2 Return 24 V GN Crearm 64 Opto 2 Return 24 V GN Gray 68 RS232 Transmit COM #11 U24 V GN Red 69 RS232 Receive COM #11	Detector	Trmnl	Wire Color	Panel A#	Panel B#	Function	Data Logger	Notes
IR2 4.6 Orange 19A Relay Common 24 V GN 4.7 Black 20A Relay Common 24 V GN 4.8 Green Ground Fuse 2 50 Blue AC Neutral Fuse 2 50 Blue AC Neutral Fuse 2 U2A Red 137 Relay Common 24 V GN White 138 Relay NO. RR #9		#						
47 Black 20A Relay Common 24 V GN 48 Green Ground Ground Fuse 2 50 Blue AC Neutral Fuse 2 U2A Red 137 Relay Common 24 V GN Ward Red 138 Relay N.O. RR #9 M6A Green T1/4 115 VAC Fuse 4 Black AC Neutral Fuse 4 10 10 Violet 61 Range Bin 1 OR1 #9 24 V GN Black AC Neutral 24 V GN 24 V GN 24 V GN Corange 65 Range Bin 2 OR1 #10 24 V GN Cream 64 Opto 2 Return 24 V GN 24 V GN Mateix 68 Rs232 Transmit COM #11 Digiboard <td>IR2</td> <td>46</td> <td>Orange</td> <td></td> <td>19A</td> <td>Relay N.O.</td> <td>RR #14</td> <td></td>	IR2	46	Orange		19A	Relay N.O.	RR #14	
48 Green Ground Fuse 2 50 Black T1/2 115 VAC Fuse 2 50 Blue AC Neutral Fuse 2 U2A Red 137 Relay Common 24 V GN White 138 Relay NO. RR #9 24 V GN M6A Green T1/4 115 VAC Fuse 4 White 138 Relay NO. RR #9 24 V GN M6A Green T1/4 115 VAC Fuse 4 White 61 Range Bin 1 OR1 #9 24 V GN Violet 61 Range Bin 2 OR1 #10 24 V GN Brown Red 63 Range Bin 3 Not used 24 V GN White 66 Opto 2 Return Not used 24 V GN 24 V GN Brown RE3232 Transmit COM #11 Digiboard Digiboard Brown Brosen 133 Analog T1A Analog T1A Med-to-Red 133 Analog T1A <t< td=""><td></td><td>47</td><td></td><td>1</td><td></td><td></td><td></td><td>24 V GND</td></t<>		47		1				24 V GND
50 Blue AC Neutral U2A Red 137 Relay Common 24 V GN White 138 Relay NO. RR #9 24 V GN M6A Green T1/4 115 VAC Fuse 4 White 61 Range Bin 1 OR1 #9 24 V GN Violet 61 Range Bin 1 OR1 #9 24 V GN Violet 61 Range Bin 2 OR1 #10 24 V GN Violet 61 Range Bin 2 OR1 #10 24 V GN Cream 64 Opto 1 Return 24 V GN Orange 65 Range Bin 3 Not used 24 V GN White 66 Opto 2 Return 24 V GN 000000000000000000000000000000000000		48	Green					
U2A Red 137 Relay Common 24 V GN White 138 Relay N.O. RR #9 24 V GN M6A Green T11/4 115 VAC Fuse 4 M6A Green T11/4 115 VAC Fuse 4 Wolet 61 Range Bin 1 OR1 #9 24 V GN Violet 61 Range Bin 1 OR1 #9 24 V GN Violet 61 Range Bin 1 OR1 #9 24 V GN Violet 61 Range Bin 2 OR1 #10 24 V GN Cream 64 Opto 2 Return 24 V GN Orange 65 Range Bin 3 Not used White 66 Opto 3 Return Not used 24 V GN Brown RS232 Transmit COM #11 Digiboard Gray 68 RS232 Ground COM #11 Digiboard Pink 69 RS232 Ground COM #11 Digiboard ILD-Square Yellow 161 2A OR1 #1 Inth		49	Black	T1/2		115 VAC		Fuse 2
White 138 Relay N.O. RR #9 M6A Green T1/4 115 VAC Fuse 4 Black AC Neutral Fuse 4 Violet 61 Range Bin 1 OR1 #9 Yellow 62 Opto 1 Return 24 V GN Red 63 Range Bin 2 OR1 #10 Crearm 64 Opto 2 Return 24 V GN Orange 65 Range Bin 3 Not used White 66 Opto 3 Return Not used White 66 Opto 3 Return Not used Gray 68 RS232 Transmit COM #11 Digiboard Gray 68 RS232 Ground COM #11 Digiboard Temperature 133 Analog T1A Analog T1A ILD-Square Yellow 161 2A OR1 #1 (front-2A) Purple 127 (613-SS. detector) RR #3 ILD-Square Yellow 162 2B OR1 #2 (back-2B)		50	Blue			AC Neutral		
White 138 Relay N.O. RR #9 M6A Green T1/4 115 VAC Fuse 4 Black AC Neutral Fuse 4 Violet 61 Range Bin 1 OR1 #9 Yellow 62 Opto 1 Return 24 V GN Red 63 Range Bin 2 OR1 #10 Crearm 64 Opto 2 Return 24 V GN Orange 65 Range Bin 3 Not used White 66 Opto 3 Return Not used White 66 Opto 3 Return Not used Gray 68 RS232 Transmit COM #11 Digiboard Gray 68 RS232 Ground COM #11 Digiboard Temperature 133 Analog T1A Analog T1A ILD-Square Yellow 161 2A OR1 #1 (front-2A) Purple 127 (613-SS. detector) RR #3 ILD-Square Yellow 162 2B OR1 #2 (back-2B)	1124		Rod		137	Belay Common		24 V GND
M6A Green T1/4 115 VAC Fuse 4 Black AC Neutral Fuse 4 Violet 61 Range Bin 1 OR1 #9 Yellow 62 Opto 1 Return 24 V GN Red 63 Range Bin 2 OR1 #10 Cream 64 Opto 2 Return 24 V GN Orange 65 Range Bin 3 Not used White 66 Opto 3 Return Not used Brown RS232 Transmit COM #11 Digiboard Gray 68 RS232 Ground COM #11 Digiboard Pink 69 RS232 Ground COM #11 Digiboard ILD-Square Yellow 161 2A OR1 #1 (front-2A) Purple 127 (613-SS detector) RR #3 Red-to-Red 182 Ital Vehicle ID Ital Orange-to-Green 182 Ital Ital Ital Red-to-Red 183 OR1 #2 Ital Ital			******		*****		RR #9	
BlackAC NeutralViolet61Range Bin 1OR1 #9Yellow62Opto 1 Return24 V GNRed63Range Bin 2OR1 #10Cream64Opto 2 Return24 V GNOrange65Range Bin 3Not usedWhite66Opto 3 Return24 V GNBrownRS232 TransmitCOM #11DigiboardGray68RS232 ReceiveCOM #11DigiboardPink69RS232 GroundCOM #11DigiboardPink69RS232 GroundCOM #11DigiboardPink69RS232 GroundCOM #11DigiboardPink69RS232 GroundCOM #11DigiboardILD-SquareYellow1612AOR1 #1Ventrele127(613-SS detector)RR #3ILD-SquareYellow1622BOR1 #2Ventrele183Red-to-Red183Red-to-Red183Red-to-Red183Red-to-Red183Red-to-Red183Red-to-Red183NameGrage-to-Green184NameNeto-Red184NameNeto-Red184NameNeto-Red184NameNeto-Reen184NameNeto-Reen184NameNeto-R			******					
Violet 61 Range Bin 1 OR1 #9 Yellow 62 Opto 1 Return 24 V GN Red 63 Range Bin 2 OR1 #10 Orange 64 Opto 2 Return 24 V GN Orange 65 Range Bin 3 Not used White 66 Opto 3 Return Not used Brown RS232 Transmit COM #11 Digiboard Gray 68 RS232 Receive COM #11 Digiboard Pink 69 RS232 Ground COM #11 Digiboard Temperature 133 Analog T1A Analog T1A ILD-Square Yellow 161 2A OR1 #1 (front-2A) Purple 127 (613-SS detector) RR #3 Red-to-Red 181 Vehicle ID Image Mathematical Action Image Mathematical Action ILD-Square Yellow 162 2B OR1 #2 Image Mathematical Action ILD-Square Yellow 162 2B OR1 #2 Image Mathematic	M6A		Green	T1/4		115 VAC		Fuse 4
Yellow62Opto 1 Return24 V GNRed63Range Bin 2OR1 #10Cream64Opto 2 Return24 V GNOrange65Range Bin 3Not usedWhite66Opto 3 ReturnNot usedBrownRS232 TransmitCOM #11DigiboardGray68RS232 ReceiveCOM #11DigiboardPink69RS232 GroundCOM #11DigiboardTemperature133Analog T1AILD-SquareYellow1612AOR1 #1Orange-to-Green182Itel CompareItel CompareItel CompareILD-SquareYellow1622BOR1 #2Itel CompareILD-SquareYellow1622BOR1 #2Itel CompareILD-SquareYellow1622BOR1 #2Itel CompareOrange-to-Green184Itel CompareItel CompareItel Compare			Black			AC Neutral		
Yellow62Opto 1 Return24 V GNRed63Range Bin 2OR1 #10Orrange64Opto 2 Return24 V GNOrrange65Range Bin 3Not usedWhite66Opto 3 ReturnNot usedBrownRS232 TransmitCOM #11DigiboardGray68RS232 ReceiveCOM #11DigiboardPink69RS232 GroundCOM #11DigiboardTemperature133Analog T1AILD-SquareYellowILD-SquareYellow1612AOR1 #1Orange-to-Green182ItalVehicle IDItalILD-SquareYellow1622BOR1 #2ILD-SquareYellow1622BOR1 #2Orange-to-Green182ItalItalOrange-to-Green184ItalItalOrange-to-Green184ItalItalOrange-to-Green184ItalItalOrange-to-Green184ItalItalOrange-to-Green184ItalItalOrange-to-Green184ItalItalOrange-to-Green184ItalItal			Violet		61	Range Bin 1	OR1 #9	
Red63Range Bin 2OR1 #10Orange64Opto 2 Return24 V GNOrange65Range Bin 3Not usedWhite66Opto 3 ReturnNot usedBrownRS232 TransmitCOM #11DigiboardGray68RS232 ReceiveCOM #11DigiboardPink69RS232 GroundCOM #11DigiboardTemperature133Analog T1AILD-SquareYellow1612AOR1 #1ILD-SquareYellow1612AOR1 #1Orange-to-Green182ILD-SquareYellow1622BOR1 #2ILD-SquareYellow183Red-to-Red183Vehicle IDRed-to-Red183Orange-to-Green184	******		**********					24 V GND
Cream64Opto 2 Return24 V GNOrange65Range Bin 3Not usedWhite66Opto 3 ReturnNot used24 V GNBrownRS232 TransmitCOM #11DigiboardGray68RS232 ReceiveCOM #11DigiboardPink69RS232 GroundCOM #11DigiboardTemperature133Analog T1AILD-SquareYellow1612ARed-to-Red181Vehicle IDItalILD-SquareYellow1622BOrange-to-Green183ItalRed-to-Red183ItalRed-to-Red183ItalOrange-to-Green184Ital			Red		*****		OR1 #10	
Orange65Range Bin 3Not usedWhite66Opto 3 ReturnNot used24 V GNBrownRS232 TransmitCOM #11DigiboardGray68RS232 ReceiveCOM #11DigiboardPink69RS232 GroundCOM #11DigiboardTemperature133Analog T1AILD-SquareYellow1612AOR1 #1(front-2A)Purple127(613-SS detector)RR #3Red-to-Red181Vehicle IDILD-SquareYellow1622BOrange-to-Green182(613-SS detector)RR #3ILD-SquareYellow1622BOR1 #2Orange-to-Green183Orange-to-Green184Ital			Cream		64			24 V GND
White6.6Opto 3 ReturnNot used24 V GNBrownRS232 TransmitCOM #11DigiboardGray6.8RS232 ReceiveCOM #11DigiboardPink6.9RS232 GroundCOM #11DigiboardTemperature1.33Analog T1AILD-SquareYellow1.612AOR1 #1(front-2A)Purple1.27(613-SS detector)RR #3ILD-SquareYellow1.622BOR1 #2Orange-to-Green1.82000ILD-SquareYellow1.622B0R1 #2Orange-to-Green1.83000Orange-to-Green1.83000Orange-to-Green1.83000Orange-to-Green1.8400Orange-to-Green1.8400					65		Not used	****
BrownRS232 TransmitCOM #11DigiboardGray68RS232 ReceiveCOM #11DigiboardPink69RS232 GroundCOM #11DigiboardTemperature133Analog T1AAnalog T1AILD-SquareYellow1612AOR1 #1Red-to-Red181Vehicle IDRR #3ILD-SquareYellow1622BOR1 #2ILD-SquareYellow1622BOR1 #2ILD-SquareYellow1622BOR1 #2ILD-SquareYellow1622BOR1 #2Orange-to-Green183Const #4Const #4Orange-to-Green183Const #4Const #4Orange-to-Green184Const #4Const #4Orange-to-Green184Const #4Const #4			White		66			24 V GND
Gray68RS232 ReceiveCOM #11DigiboardPink69RS232 GroundCOM #11DigiboardTemperature133Analog T1AILD-SquareYellow1612AOR1 #1ILD-SquareYellow1612AOR1 #1Orange-to-Green182ItalVehicle IDItalILD-SquareYellow1622BOR1 #2ILD-SquareYellow1622BOR1 #2Orange-to-Green183ItalItalItalILD-SquareYellow1622BOR1 #2Orange-to-Green183ItalItalItalILD-SquareYellow1622BItalILD-SquareYellow1622BItalILD-SquareYellow1622BItalILD-SquareYellow1622BItalILD-SquareYellow1622BItalILD-SquareYellow1622BItalILD-SquareYellow1622BItalILD-SquareYellow1622BItalILD-SquareYellow1622BItalILD-SquareYellow162183ItalILD-SquareYellow162183ItalILD-SquareYellow162183ItalILD-SquareYellow162184ItalILD-SquareYellow162184ItalILD-Square			Brown			RS232 Transmit	COM #11	Digiboard #7
Temperature133Analog T1ATemperature134Analog T1B134Analog T1B12-SquareYellow1612AOR1 #1(front-2A)Purple127Red-to-Red181Vehicle IDOrange-to-Green1LD-SquareYellow1622B00000000000000000000000000000000000			Gray		68		COM #11	Digiboard #7
ILD-SquareYellow134Analog T1BILD-SquareYellow1612AOR1 #1(front-2A)Purple127(613-SS detector)RR #3Red-to-Red181Vehicle IDOrange-to-Green182UD-SquareYellow1622BOR1 #2ILD-SquareYellow1622BOR1 #2Orange-to-Green183Orange-to-Green184			Pink		69	RS232 Ground	COM #11	Digiboard #7
ILD-SquareYellow134Analog T1BILD-SquareYellow1612AOR1 #1(front-2A)Purple127(613-SS detector)RR #3Red-to-Red181Vehicle IDOrange-to-Green182UD-SquareYellow1622BOR1 #2ILD-SquareYellow1622BOR1 #2Orange-to-Green183Orange-to-Green184	Temperature				133			
ILD-SquareYellow1612AOR1 #1(front-2A)Purple127(613-SS detector)RR #3Red-to-Red181Vehicle IDOrange-to-Green182ILD-SquareYellow1622BOR1 #2(613-SS detector)Red-to-Red183Orange-to-Green184	remperature		*********					
(front-2A) Purple 127 (613-SS detector) RR #3 Red-to-Red 181 Vehicle ID Orange-to-Green 182 ILD-Square Yellow 162 2B OR1 #2 (back-2B) Red-to-Red 183 Orange-to-Green 184								
Red-to-Red 181 Vehicle ID Orange-to-Green 182 ILD-Square Yellow Yellow 162 (back-2B) (613-SS detector) Red-to-Red 183 Orange-to-Green 184								
Orange-to-Green 182 Image: Constraint of the second secon	(front-2A)		***************************************				<u>RR #3</u>	
ILD-Square Yellow 162 2B OR1 #2 (back-2B) Red-to-Red 183 613-SS detector) Orange-to-Green 184 184					~~~~~	Vehicle ID		
(back-2B) (613-SS detector) Red-to-Red 183 Orange-to-Green 184			Orange-to-Green		182			
(back-2B) (613-SS detector) Red-to-Red 183 Orange-to-Green 184	ILD-Square		Yellow		162	2B	OR1 #2	
Red-to-Red 183 Orange-to-Green 184						(613-SS detector)		
Orange-to-Green 184			Red-to-Red		183			
2M Miero Loop Croop Discut Discut								
	3M Micro Loop		Green		Direct	2C	OR2 #5	
Sim Micro Loop Green Direct 2C OR2 #5			Gieen		Direct	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	<u>UT2 #5</u>	

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		Uracie F	10au 500	nuodina	at Auto Mall I	711VE	
Tucson La	ine 3	(Curb Lan	e)				
Detector	Trmnl	Wire Color	Panel A#	Panel B#	Function	Data Logger	Notes
	#		(Power)	(Data)	······································		***************************************
M4B	1	White	128		12V Ground		
	2	Brown	99		12 VDC		Fuse 10
	3	White		1A	RS232 Ground	COM #7	Digiboard #
	4	Orange	*******	2A	RS232 Transmit	COM #7	Digiboard #
	5	White		3A	Data Carrier	Not used	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~
	6	Green		4A	RS232 Receive	COM #7	Digiboard #
	7	White		5A	Opto #1 +	OR1 #7	~~~~~
	8	Blue		6A	Opto #1 -		24 V GND
~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	9	White		7A	Opto #2 +	OR1 #8	
	10	Grey		8A	Opto #2 -		24 V GND
		******			***************************************		~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~
U3A	1 1	Yellow	95		12 VDC		Fuse 12
	12	Brown	126		12V Ground		
	13	Yellow		71A	Relay N.C.	N/U	
	14	Orange		72A	Relay Common		24 V GND
	15	Yellow		73A	Relay N.O.	RR #6	
Camera	16	Green	T1/6		115 VAC	Fuse 14	
Autoscope)	17	Yellow			AC Neutral		
	18	Blue			Ground		
	19	Yellow			Spare		
	20	Grey			Spare		~~~~~
M2B	21	Violet	77		24 VDC		Fuse 8
	22	Brown	107		24V Ground		······
	23	Violet		21A	Relay N.C.	Not used	
	24	Orange	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	22A	Relay Common		24 V GND
	25	Violet		23A	Relay N.O.	RR #12	
	26	Green		24A	<35 mi/h	OR2 #20	
	27	Violet		25A	<u>36-45 mi/h</u>	OR2 #21	
	28	Blue		26A	46-55 mi/h	OR2 #22	
	29	Violet		27A	<u>56-65 mi/h</u>	OR2 #23	
	30	Grey		28A	66+ mi/h	OR2 #24	
	31	Red		29A	Doppler Freq.		
~~~~~	32	Brown		<u>30A</u>	Doppler Ground		
IR1	33	Red		32A	RS232 Receive	COM #13	Digiboard #
1 [] 1	34	Orange		32A 33A	RS232 Transmit	COM #13	Digiboard #
	35	Red	~~~~~	33A 34A	RS232 Transmit RS232 Ground	COM #13	Digiboard #
	35	Green		34A 35A	Relay N.O.	RR #13	Digibualu #
	37	Red		36A	Relay Common	<u> </u>	24 V GND
	38	Blue			Ground		
	39	BLK	T1/1		115 VAC		Fuse 1
	40	CLR			AC Neutral		

1 mi/h = 1.61 km/h

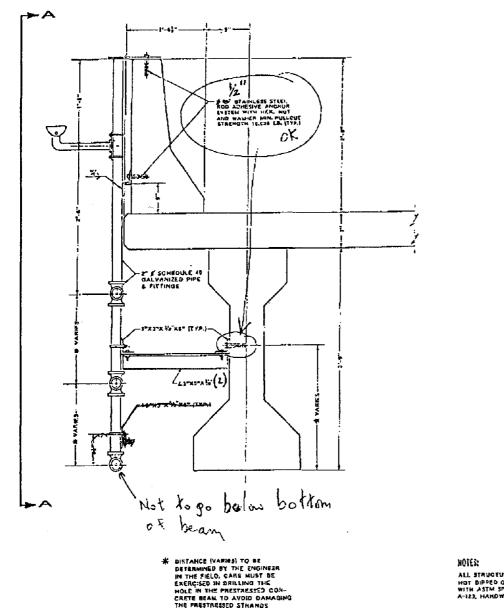
	5 5	Oracle R	oad Sou	ithbound	at Auto Mall Driv	e	
Tucson Lane	; ; 3 (C	urb Lane)					
Detector	T	Wire Color	Damal A#	Panel B#	Function	Data Logger	Notes
Detector	Trmnl #	WIE COOI	(Power)		Function		INDIES
U1	L1	Red		112	Large Veh Count	RR #4	Not used
	Com	Green		113			
	<u>S1</u>	Green		114	Small Veh Count	RR #5	Not used
U2B		Red		137			
~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~		White		138	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~		
	C-/2	White/Black		139	Relay Common		24 V GND
	B+/2	Black		140	Relay N.O.	RR #10	
ILD-Square		White		163	ЗА	OR1 #3	
(front-3A)	*****	Red-to-Red		185	(613-SS detector)		
		Orange-to-Green		186		*****	
		Purple		128	Veh ID	RR #2	
ILD-Square		White		162	3B	OR1 #4	
(back-3B)					(3M 2020 detector)		Digiboard #1
ILD-Round		White		165	зс	OR1 #5	
(back)					(272 detector)		
ILD-Round		Green		166	3D	OR1 #6	
(front)		Gibbin			(272 detector)		
3M MicroLoop		Green		Direct	3E	OR2 #6	
		Green		Direct	(272 detector)	0112 #0	
A1 (AT&T)		Red/Orange	57		24 VDC	*****	Fuse 6
		Black/Black	109		Ground		ruse o
		Red		167	Ch 1	OR1 #15	
		Green		168	Ch 2	OR1 #16	
Mag 1		Red		121	Relay N.O.	RR #8	
		Black		122	Relay Common		24 V GND
Mag 4		Orange		123	Relay N.O.	RR #7	
******		Purple		124	Relay Common		24 V GND
Timemark		Red		76	RS232 Transmit	COM #10	Digiboard #6
Delta 1		White		77	RS232 Receive	COM #10	Digiboard #6
		Green		78	RS232 Ground	COM #10	Digiboard #6

		Oracle F	load Sou	thbound	at Auto Mall	Drive	
Tucson Multil	ane D	etectors (La	nes 2 &	3)			
Detector	Trmnl	Wire Color	Panel A#	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	Function	Data Logger	Notes
	#		(Power)	(Data)			
<u>M6B</u>		Green	<u>T2/4</u>		115 VAC		
(side-firing		Black			AC Neutral		
on Lanes 2 & 3)		Brown		83	RS232 Transmit		Digiboard #8
*****		Gray		84	RS232 Receive	COM #12	Digiboard #8
		Pink		85	RS232 Ground	COM #12	Digiboard #8
		Purple		86	Range Bin 1	OR2 #2	
~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~		Yellow		87			24 V GND
		Red		88	Range Bin 2	OR2 #3	
		Cream		89			24 V GND
		Orange		90	Range Bin 3	OR2 #4	
		White		91			24 V GND
3-axis Fluxgate						COM #14	Digiboard #10
Mag Array							
Autoscope		Black			Lane 2 Near	OR2 #7	Det 101
2003		Black			Ln 2 Speed Trap	OR2 #8	Det 111
		Black			Lane 2 Far	OR2 #9	Det 103
		Black			Lane 3 Near	OR2 #10	Det 102
		Black			Ln 3 Speed Trap	OR2 #11	Det 112
		Black			Lane 3 Far	OR2 #12	Det 104
Traficon						COM #15	Digiboard #11
CCATS-VIP2							
Sumitomo						COM #18	Digiboard #14
IDET-100							
Grumman IIR						COM #16	Digiboard #12
Traffic Sensor	000000000000000000000000000000000000000	***************************************	*******	000000000000000000000000000000000000000			

APPENDIX I.

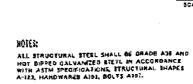
PIPE TREE INSTALLATION AND SR 436 AT I-4 OVERPASS CONSTRUCTION PLANS

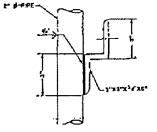
This appendix contains the design for attaching the pipe trees to the SR 436 bridge structure above the I-4 westbound lanes, asbuilt drawing for I-4 at SR 436, plan view for the traffic signals at the I-4 exit ramp at SR 436, truss design for overhead signs, standard bar bending details, plan and elevation boring data for the widening of SR 436, superstructure spans for the widening of SR 436, and reinforcing bar list for the widening of SR 436.





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HER. BOLT & HUTS

C 2"X1\$"X3\6" X3"-3"

- ********* #* PLATE

-L 3"X 1"X ¹⁴6" K 6"

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SECTION A-A

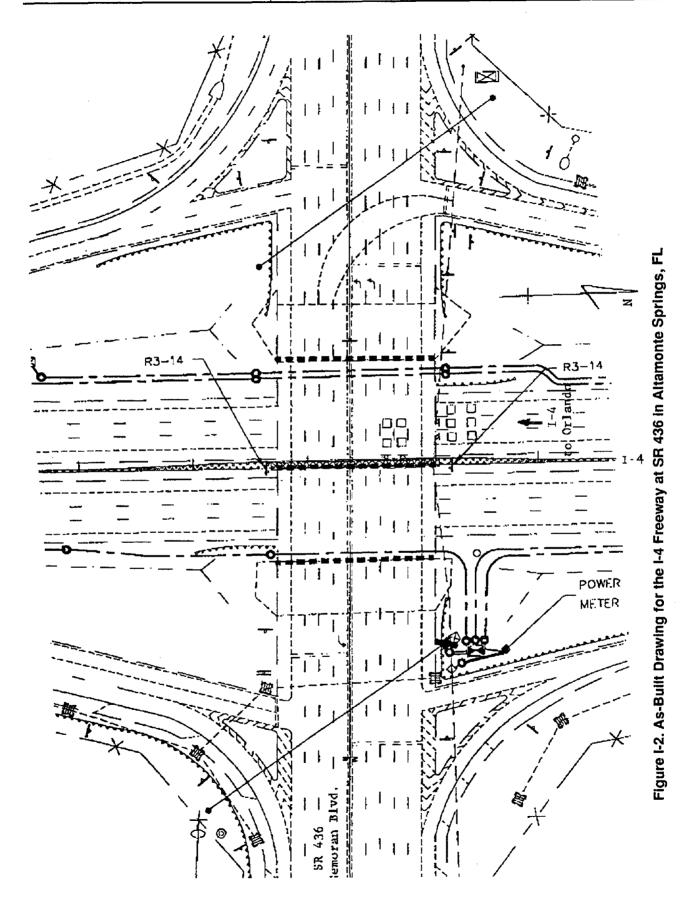
SCALE 14" = 1'-0"

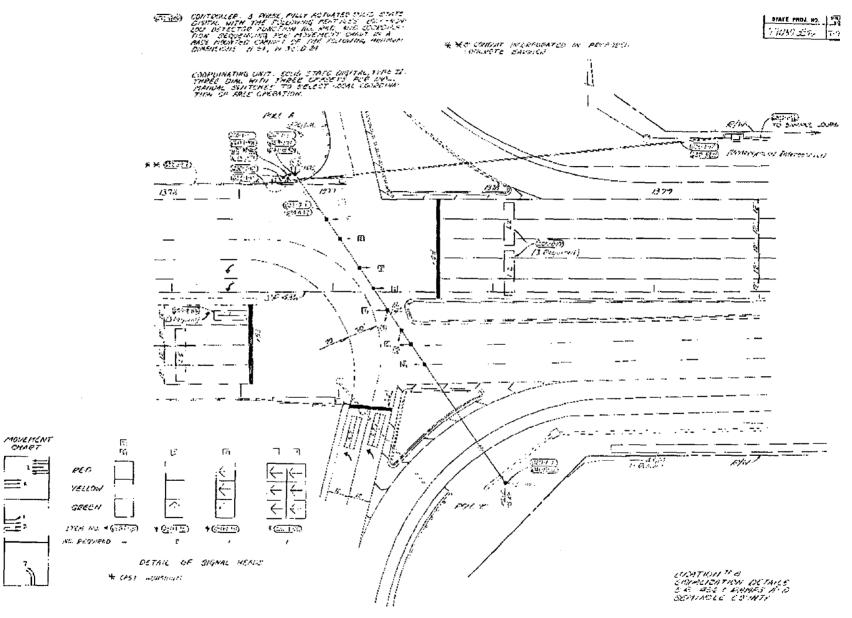
SEE DETAIL-

2" / SCHEDULE IS-GALVANILED PIPE MIPPLES IS" LONG, THAEADED ON ONE END (TTP.)



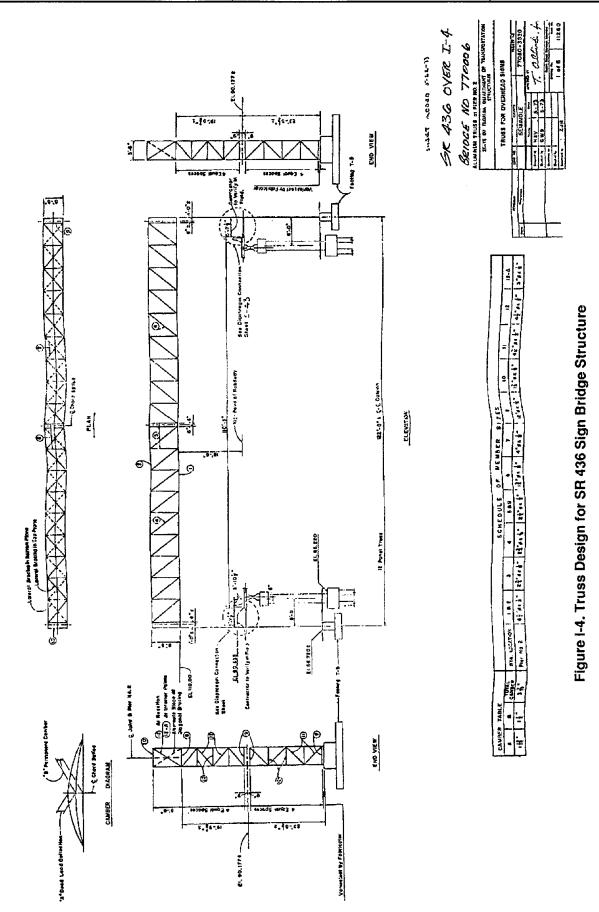
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SCALE 1 20 7-13-62 CLN

Figure I-3. Plan View of Traffic Signals at I-4 Westbound Exit Ramp at SR 436



1-5

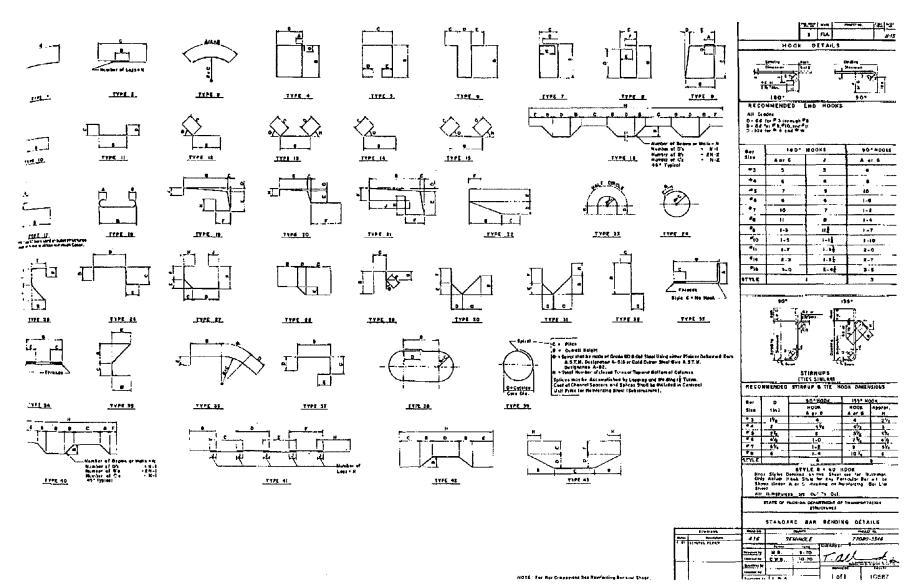


Figure I-5. Standard Bar-Bending Details

Final Report: Detection Technology for IVHS

-6

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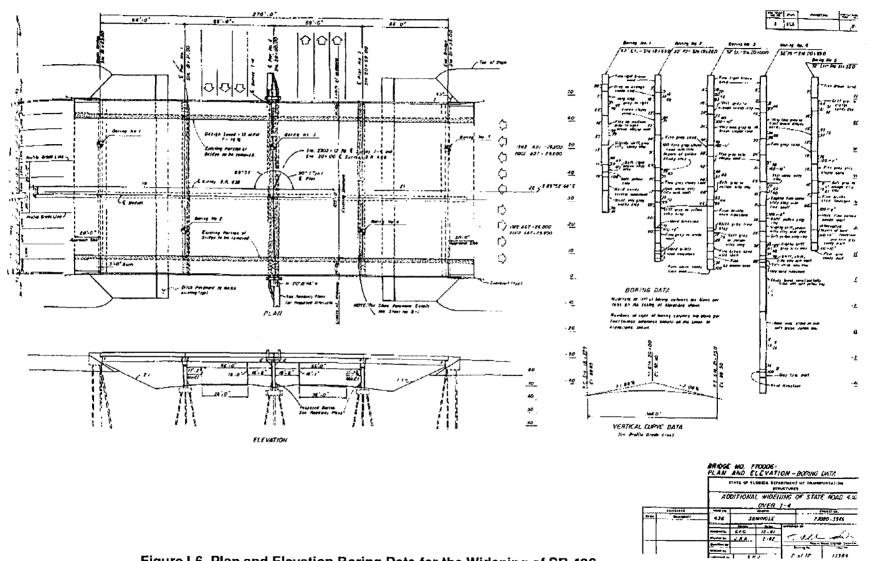
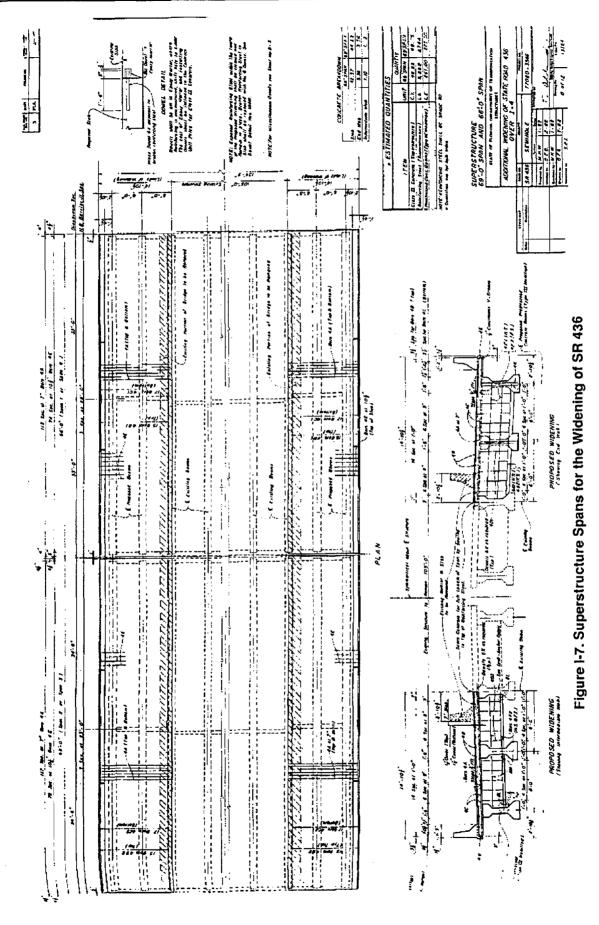


Figure I-6. Plan and Elevation Boring Data for the Widening of SR 436



1-8

A 1 R X UNRIN N TO TO <th></th> <th>Location Side support PEA NO. AC2UMICO - 2 A B-4 3 4 4 5 4 4 5 4 4 5 4 5 4 5 5 3 3 3 5 5 3 3 3 5 5 3 3 5 5 3 3 5 5 3 3 5 5 3 3 5 5 3 3 5 5 3 3 5 5 3 3 5 5 3 3 5 5 3 5 5 3 3 5</th> <th>1011 - IRINKVIZ, KA STRUL BE GAUE 60</th> <th>REWORD/WC BAP LIST REWORD/WC BAP LIST REMORD/WC BAP LIST</th>		Location Side support PEA NO. AC2UMICO - 2 A B-4 3 4 4 5 4 4 5 4 4 5 4 5 4 5 5 3 3 3 5 5 3 3 3 5 5 3 3 5 5 3 3 5 5 3 3 5 5 3 3 5 5 3 3 5 5 3 3 5 5 3 3 5 5 3 3 5 5 3 5 5 3 3 5	1011 - IRINKVIZ, KA STRUL BE GAUE 60	REWORD/WC BAP LIST REWORD/WC BAP LIST REMORD/WC BAP LIST
1 1 <td>1 1<td></td><td></td><td>1 1</td></td>	1 1 <td></td> <td></td> <td>1 1</td>			1 1

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APPENDIX J.

LOCAL CLIMATOLOGICAL DATA FROM FIELD SITES

Climatological data from the Minneapolis, Orlando-Altamonte Springs, Phoenix, and Tucson field sites are contained in this appendix. The data include monthly summaries of temperature, snow accumulation, precipitation, wind, sunshine, and sky cover, as well as sky cover, visibility, temperature, and wind measured in 3-hour intervals on a daily basis. The data were tabulated by the National Oceanic and Atmospheric Administration (NOAA) through the National

Conversion factors for climatological data:

1 in = 25.4 mm 1 ft = 0.305 m 1 kn = 1852 m/h (F-32)/1.8 = °C Climatic Data Center in Asheville, North Carolina. Their address and telephone number are:

National Climatic Data Center Federal Building 37 Battery Park Avenue Asheville, NC 28801-2733

(704) 271-4800



LOCAL CLIMATOLOGICAL DATA Monthly Summary

	l	SS	5 N	0	1	9	8	-	2	7	4	5
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INTERNATIONAL AIRPORT

_			LATIT	IUDE 44	1° 53'	N	LONGITU	DE 9	3° 13	. M	ELEVA	TION IGR	DUNDI	834 F	EE 1		1	IME Z	ONE	CENT	RAL		1	4922	
			TEMPE	RATURE	۰ŧ		DE GREI BASE	E DAYS 65°F	NEATH 1 FOG	ER TYPES	SNOW ICE Pellets	PRECIPI	TATION	AVERAGE STATION PRESSURE				NIND P.H.				SUNSHI	INE	SKY C itent	
	- DATE	∾ MAXINUN	NUN HIN O	► AVERAGE	U DEPARTURE U FROM NORMAL	- AVERAGE DEN POINT		COOLING ISEASON BEGINS WITH JANI	4 JCE 5 HAIL 6 GLAZ 7 DUST 8 SHOP	NDERSTORM PELLETS PE	OR ICE ON GROUND AT D600 INCHES 9	- WATER EQUIVALENT O (FNCHES)	- SNOH, ICT PELLETS	IN INCHES ELEV. 838 FEET ABOVE M.S.L. 12	🕁 RESULTANT DIR.	🚽 RESULTANI SPEED	G AVERAGE SPEED		AK UST NOIIJJUIO 17		TEST MIN NOILIJJUIG 19	S MINUTES	~ PERCENT OF 1 TOTAL POSSIBLE	SUNRISE 10 SUNSET	N HIDNIGHT V 10 MIDNIGHT
L, M	01 02 03 04 05	42 35 34 33 31	33 33 32 29 26	38 34 33 31 29	-3 -7 -7 -8 -10	32 32 29 25 22	27 31 32 34 36	0 0 0 0	1 4 1 1		04 55 5	0.57 0.63 0.22 0.04	0.1	29.010 28.440 28.720 29.010 29.210	35 27 32 33	8.6	15.5 10.3 9.0 12.1 9.0	28 21 15 26 23	NE N N N N	20 15 12 16 13	06 04 25 31 32	0 0 2 0	0 0 0 0	10 10 10 10 10	10 10 10 10 10
92 PAL	06 07 08 09	28 27 36 48 48	23 21 25 35 35	26 24= 31 42 42=	-12 -14 -6 5 6	17 18 26 38 33	39 41 34 23 23	0 0 0 0	1 1 1		5 5 4 T	T T D.02 T	T T 0.0 0.0	29.420 29.370 29.170 29.020 29.135	16 12 14 27	9.2 10.8	6.9 6.2 11.0 9.6 12.0	13 13 21 20 26	E SE SE NH	9 9 15 15 17	06 14 12 14 30	0 57 2 74 6	0 10 13 13	10 10 10 10 10	10 10 10 9 10
	1 2 3 4 5 6	46 41 32 30 33 38	25 29 24 20 16 28	36 35 28 25 25	1 -6 -9 -8	28 24 18 17 15	29 30 37 40 40	000000000000000000000000000000000000000	1	6	0 0 1 1 0	0.00 0.02 T 0.00	T D.1 T D.0	29.200 28.915 29.080 29.300 29.375	30 29 30 19	8.0 2.5	9.5 16.0 13.6 8.5 4.9	20 41 28 16 12	SH NH NH SE	15 28 18 13 9	22 31 31 29 15	438 322 1 66 425	75 56 0 11 74	0 4 10 9 4	1 5 8 9 5 10
D d	7 8 9	35 38 39 39	28 32 31 34	33 32 35 35 37	0 0 3 4 6	25 25 29 30 34	32 33 30 28	000000000000000000000000000000000000000	1 1 1 1 4		0 0 2 0	0.00 T 0.11 0.17 0.15	1.8 0.5 7	29.110 29.310 29.430 29.350 28.990	36 09 08 02	7.3	10.7 5.9 7.3 11.3 9.8	16 14 21 21	N N E N	14 13 10 18 14	01 36 09 09 35	17 0 0 0	300000	10 10 10 10 10 10	10 10 10 10
NNE/	12345	36 34 32 36 35	32 31 30 30 27	34 33 31 33 31	43243	27 25 25 25 25	31 32 34 32 34	000000000000000000000000000000000000000		8	0 0 T 0	0,00 0,00 T T T	0.0 T T T	29.110 29.025 29.090 29.250 29.250	05 08 36 01	8.7 3.8 3.2 2.5	11.8 9.4 4.8 4.6 13.3	22 21 12 10 26	N E NE N NE	20 14 9 7 18	31 06 08 36 36	0 0 0 0	000000000000000000000000000000000000000	10 10 10 10	10 10 10 10 10
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	E	SUR 1077 Ay6. 35.9	SUR 803 AV6. 26.8	AV6. 31.4	DE P - 1.8		1003 1003 DEP 49	TDTAL O DEP. O	PRECI		11	101AL 1.95 DEP 0.66	101AL 12.2	29.130	34	2.4	1HE M 9.4	ONTH: 41 DATE:	NH 12	28 DATE :		10TAL 2514 Possible 17241	7 788 89874 15	SUK 254 Avg. 8.5	SUN 249 Ave. 8,3
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* EXTREME FOR THE MONTH - LAST OCCURRENCE IF HORE THAN ONE.

T EXIMENT FUN INL HUNIN - LAST OLLOWMENCE ST HUN T TRACE AMOUNT. + ALSO ON EARLIER DATE(S). HEAVY FOG: VISIBILITY 1/4 MILE OR LESS. BLANK ENTRIES DENOTE MISSING OR UNREPORTED DATA.

DATA IN COLS 6 AND 12-15 ARE BASED ON 21 OR MORE OBSERVATIONS AT HOURLY INTERVALS. RESULTANT WIND IS THE VECTOR SUM OF WIND SPEEDS AND DIRECTIONS DIVIDED BY THE NUMBER OF OBSERVATIONS COLS 16 & 17: PEAK GUST - HIGHEST INSTANTANEOUS WIND SPEED ONE OF THO WIND SPEEDS IS GIVEN UNDER COLS 18 & 19: FASTEST MILE - HIGHEST RECORDED SPEED FOR WHICH A MILE OF WIND PASSES STATION IDIRECTION IN COMPASS POINTSI. FASTEST OBSERVED ONE MINUTE WIND - HIGHEST ONE WINUTE SPEED IDIRECTION IN TENS OF DEGREES]. ERRORS WILL BE CORRECTED IN SUBSEQUENT PUBLICATIONS.

I CERTIFY THAT THIS IS AN OFFICIAL PUBLICATION OF THE NATIONAL DCEANIC AND ATMOSPHERIC ADMINISTRATION, AND IS COMPILED FROM RECORDS ON FILE AT THE NATIONAL CLIMATIC DATA CENTER



NATIONAL OCEANIC AND ATHOSPHERIC ADMINISTRATION NATIONAL ENVIRONMENTAL SATELLITE, DATA AND INFORMATION SERVICE

NATIONAL CLINATIC DATA CENTER ASHEVILLE NORTH CAROLINA

all D Waden Sen

DIRECTOR National climatic data center

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MAXIMUM SHORT DURATION PRECIPITATION

TIME PERIOD (MINUTES)	5	10	15	20	30	45	60	80	100	120	150	180
PRECIPITATION (INCHES)	0.07	0.07	0,10	0.10	0,10	0.10	0.10	0.14	0.15	0.16	0.17	0.19
ENDED: DATE	03	03	03	01	01	01	01	01	02	02	02	02
ENDED: TIME	0148	0148	0255	2257	2257	2257	2257	2357	0022	0022	0112	0112

THE PRECIPITATION ABOUNTS FOR THE INDICATED TIME INTERVALS MAY OCCUR AT ANY TIME DURING THE NONTH. THE TIME INDICATED IS THE ENDING TIME OF THE INTERVAL. DATE AND TIME ARE NOT ENTERED FOR TRACE AMOUNTS.

PAGE 2

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WEATHER CODES

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Ŝ,	SNOW	1F	ICE FOG		

CEILING: UNL INDICATES UNLIMITED WIND DIRECTION: DIRECTIONS ARE THOSE FROM WHICH THE WIND BLOWS, INDICATED IN TENS OF DEGREES FROM TRUE NORTH: I.E., O9 FOR EAST, 18 FOR SOUTH 27 FOR WEST. AN ENTRY OF OD INDICATES CALM. SPEED: THE OBSERVED AVERAGE ONE-MINUTE VALUE, EXP RESSED IN KNOTS (MPH=KNOTS X 1.15).

PAGE 3

SUMMARY BY HOURS

			AV	ERAG	ES				ILTANT 1 ND
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NATIONAL CLIMATIC BATA CENTER Federal Building 37 Batiery Park Ave Asheville, North Carolina 28B01-2733

OFFICIAL BUSINESS PENALTY FOR PRIVATE USE \$300 FIRST CLASS POSTAGE AND FEES PAID NDAA PERMIT G-19

LCD-21-14922-PD-9309

4574C JHK & ASSOCIATES ATTN: M SCOTT MACCALDEN JR PO EOX 193727 SAN FRANCISCO CA 94119

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DEC 1992 RINNEAPOLIS-ST.PAUL, NN NAT'L NEA SER FCST OFC FEDERAL AVIATION BUILDING

LOCAL CLIMATOLOGICAL DATA Monthly Summary

155N 0198-2745



INTERNATIONAL AIRPORT

			LATIT	UDE 44	° 53′	N	LONGITU	DE 9	3.	13°H		ELEVA	TION (GR	ומאט	8 34 F	EEI		T	IME Z	ONE	CENT	RAL		1	4922	
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* EXTREME FOR THE MONTH - LAST OCCURRENCE IF MORE THAN ONE. T TRACE AMDUNT. + ALSO ON EARLIER DATE(S). HEAVY FOG: VISIBILITY 1/4 MILE OR LESS. BLANK ENTRIES DENOTE MISSING OR UNREPORTED DATA.

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I CERTIFY THAT THIS IS AN OFFICIAL PUBLICATION OF THE NATIONAL DCEANIC AND ATHOSPHERIC ADMINISTRATION, AND IS COMPILED FROM RECORDS ON FILE AT THE NATIONAL CLIMATIC DATA CENTER



NATIONAL OCEANIC AND ATHOSPHERIC ADMINISTRATION NATIONAL ENVIRONMENTAL SATELLITE, DATA AND INFORMATION SERVICE

NATIONAL CLIMATIC DATA CENTER ASHEVILLE NORTH CAROLINA

Se met D Wadeen

DIRECTOR National climatic data center

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MAXIMUM SHORT DURATION PRECIPITATION

TIME PERIOD (MINUTES)	5	10	15	20	30	45	60	80	100	120	150	180
PRECIPITATION (INCHES)	0.02	0.03	0.04	0.06	0.08	0.12	0.13	0.15	0.17	0.17	0.20	0.22
ENDED: DATE	29	29	13	13	13	13	13	13	13	13	13	13
ENDED: TIME	0020	0029	2210	2204	2210	2210	2210	2234	2210	2325	2309	2325

THE PRECIPITATION AMOUNTS FOR THE INDICATED TIME INTERVALS MAY OCCUR AT ANY TIME DURING THE MONTH. THE TIME INDICATED IS THE ENDING TIME OF THE INTERVAL. DATE AND TIME ARE NOT ENTERED FOR TRACE AMOUNTS.

PASE 2

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WEATHER CODES

2	TORNADO	SH	SNOW SHOWERS	GF	GROUND FOG
Т	THUNDERSTORM	\$G	SNOW GRAINS	BD	BLOWING DUST
G	SQUALL	SP	SNOW PELLETS	BN	BLOHING SAND
R	RAIN	10	ICE CRYSTALS	BS	BLOWING SNOW
RH	RAIN SHOWERS	1P	ICE PELLETS	BY	BLOWING SPRAY
ZR	FREEZING RAIN	IPH	ICE PELLET SHOWERS	к	SMOKE
L	DRIZZLE	A	HAIL	н	HAZE
ZŁ	FREEZING DRIZZLE	F	FOG	D	DUST
s	SNOW	1F	ICE FOG		

CEILING: UNL INDICATES UNLIMITED MIND DIRECTION: DIRECTIONS ARE THOSE FROM WHICH THE WIND BLOWS, INDICATED IN TENS OF DEGREES FROM TRUE NORTH: I.E., 09 FOR EAST, 18 FOR SOUTH 27 FOR WEST. AN ENTRY OF 00 INDICATES CALM. SPEED: THE OBSERVED AVERAGE ONE-MINUTE VALUE, EXP RESSED IN KNOTS (MPH=KNOTS X 1.15).

PAGE 3

SUMMARY BY HOURS

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NATIONAL CLIMATIC DATA CENTER Federal Building 37 Battery Park Ave Asheville, North Carolina 28801-2733

OFFICIAL BUSINESS PENALTY FOR PRIVATE USE \$300 FIRST CLASS PSEASE AND FEES PAID NOAA PERMIT G-19

LCD-21-14922-PD-9309

45740 JHK & ASSOCIATES ATTN: M SCOTT MACCALDEN JR PO BOX 193727 SAN FRANCISCO CA 94119

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JAN 1993 WINNEAPOLIS-ST.PAUL. WN NAT'L MEA SER FEST OFC FEDERAL AVIATION BUILDING

LOCAL CLIMATOLOGICAL DATA Monthly Summary

ISSN 0198-2745



INTERNATIONAL AIRPORT

LATITUDE 44° 53'N LONGITUDE 93° 13' # ELEVATION (GROUND) 834 FEET TIME ZONE CENTRAL 14922 NEATHER ITPES SNDE AVEDIEF DEGREE DAYS BASE 65°F MIND SKY COVER TEMPERATURE OF PRECIPITATION SUNSHINE ICE STATION (H.P.H.) (TENTHS) FOG PELLET PRESSURE HEAVY FOG FASTES 0R PEAK ISEASON 2 18 ASPH SPEEI VALENT PELLEI BLE THUNDERSTORM ICE ON INCHES 018. 1-HIN 2 6Ū51 HI IN ICE PELLETS GROUND 392 SUMPLSE 10 SUNSET MIDNIGHI DEPARIURE From Normal PERCENT OF TOTAL POSSI 5 ELEV NOI HAIL AT IANT Ξ S EQUI SNOR, ICE FINCHESI RE SUL LAHT AVERAGE Dem point HEATTHG Degins H COOLING H **GLAZE** 0600 MATER EQU 838 FEET HUH MQM **JAVERAGE** MINUTES AVERAGE 103BI0 17 RESULI BUSTSTORM SPEED SPEED 12 DI RECI ININ DATE MAXI ABOVE SHOKE, HAZE INCHES 9 BLOWING SHOW H.S.L 21 22 23 14 18 20 4 5 7A 7B 8 10 11 12 16 29.710122.6 29.1801411.5 28.940272.7 29.2003110.4 29.385302.8 NW 4.9 12.0 6.5 10.5 4.2 4 29 33 -16* -6* 17 24 9 9 -19 12 17 464 87 0 2 10 01 -12 71 14 24 24 22 10 £ 10 Û 1 Ť 44444 48 ŜΕ 15 Ó 16 26 1 0 4 6 0.02 0 10 02 1 15 2 2 41 56 56 10 5 8 03 12 Ō 6 0.02 Ť ŇĤ 15 31 126 24 89 10 15 16 -3 0 0 NW 31 64 6 0.00 0.0 10 4 0.1 7 34 336 63 05 N 6 1 1993 ST.PAUL 29.330 22 7.2 29.260 22 3.8 29.460 02 3.3 29.690 03 11.7 29.680 05 7.9 7.6 15 9 15 0.0 90 79 235 9 -7 -11 ~4 64 62 62 53 52 S SE 13 22 485 25 06 1 0 6 8.00 4 426 412 -2 8 12 17 11 14 -5 -9 26 03 07 3 -9 0 1 -ģ ŝ 0 00 0.0 76 3 0 R 1 444 N 16 18 22 15 09 8 7 12 13 23 Ō 0.0 NE 05 372 69 10 10 0 0.00 8.1 NĒ 12 10 2 Û 0.00 0.0 06 82 6 6 29.490 10 10.6 29.170 06 13.0 29.210 35 10.0 29.350 25 5.2 29.220 18 4.6 0.8 6.2 1.6 11,1 13,3 10,4 21 23 28 331 201 7 15 24 23 12 5 10 21 50 41 61 37 10 10 11 22 28 27 24 16 4 0 0 4 0.05 ŗ 16 69 10 18 15 12 9 20 13 ŇE 10 04 0.63 12 6 10 7 4 10 9 0 55 74 13 19 12 20 42 Ô 10 34 302 N JAN MINNEAPOLIS-SW S 14 15 11 53 11 11 0.6 T 6.6 36 14 24 18 - 1 1 n 0.02 409 -6 -6 õ 501 91 1 8 1 15.4 10.3 8.5 8.8 9.8 28.9452510.9 29.330298.5 29.520167.3 29.6101777.8 29.325119.6 16 17 8 -7 -5 14 -2 1 24 21 22 482 555 307 27 11 19 46 0 8 11 NW 20 31 31 20 19 10 87 5 50959 1 14 20 25 32 61 59 47 44 16 16 15 15 -6 4 £ 11 0.00 0.0 H S S S E 100 55 1 10 18 19 6 Û 10 11 18 21 7 9 14 65 41 0 0 10 0,00 0.0 18 366 6 10 18 20 1 6 10 0.17 0.0 229 28.98022 4.8 28.98020 4.7 28.86035 8.4 29.32027 7.3 29.42016 6.6 0.9 27 19 18 14 29 22 35 39 6.1 20 24 14 102 477 18 10 2 10 10 5 7 2 3 21 22 23 24 25 32 32 30 26 27 10 8 Û 10 0.07 SN 24 1 6 Õ 10 0,00 8.6 15.6 8.2 Ě 12 25 15 08 84 1 6 23 5 3 36 20 22 38 20 23 18 15 38 Ô 10 0.07 0.7 ŇH 33 28 5 97 -7 -2 55 57 10 10 31 16 555 32 Û 0 00 NH Õ 0.0 8.0 S 18 457 1 0.00 80 29.010,27,11,8 29.170,11,2,1 29.250,30,13,9 29.580,22,9,8 29.145,23,114,0 29.050,29,11,1 26 27 28 29 16.6 6.5 14.5 10.4 39 17 16 23 37 0.1 39 23 26 231 40 28 0 1 10 0.01 N 7 5850 24 28 14 16 13 26 14 35 20 24 25 14 26 15 20 30 505 582 10 5 0 11 8 49 52 0.06 1.0 5 87 -2 4 ñ £ 10 31 22 22 28 999 ŏ 1 ŇH 10 õ 0.00 0.0 SH 00 63 0 14.3 24 1 11.5 25 FOR THE MONINE 39 30 12 13 20 39 n ٩ 0,00 0.0 509 87 5 55 40: 0.00 101AL 1.25 27 25 Total Tot 0.0 TOTAL 488 83 451 34 30 £ SUR SUN TOTAL Z Fer SUM AL SUR 12.0 29.280 25 1.6 9.6 39 H 26 31 11188 FCR DATE: 28 PSSTBLE HDRIN 194 731 1.72 185 AV5. AV6. AVG. DEP DATE:26 AVE. AVE. AVG. DEP 14.6 17220 65 6 23.6 0.30 3 6 NUMBER OF DAYS GREATEST IN 24 HOURS AND DATES GREATEST DEPTH ON GROUND OF SNOW, ICE PELLETS OR ICE AND DATE
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T TRACE AMOUNT. + ALSO ON EARLIER DATE(S). HEAVY FOG: VISIBILITY 1/4 HILE OR LESS.

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NATIONAL DCEANIC AND ATMOSPHERIC ADMINISTRATION NATIONAL ENVIRONMENTAL SATELLITE, DATA AND INFORMATION SERVICE

NATIONAL CLIMATIC DATA CENTER ASHEVILLE NORTH CAROLINA

2 D Wadee Te DIRECTOR

NATIONAL CLIMATIC DATA CENTER

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MAXIMUM SHORT DURATION PRECIPITATION

TIME PERIOD IMINUTESI	5	10	15	20	30	45	60	80	100	120	150	180
PRECIPITATION (INCHES)	0.02	0.03	0.03	0.05	0.06	0.08	0.10	0.12	0.13	0.14	0.16	0.18
ENDED: DATE	12	12	12	12	12	12	12	12	12	12	12	12
ENDED: TIME	1006	1014	1014	0310	1030	0310	0310	1038	0328	1038	1038	1038

THE PRECIPITATION AMOUNTS FOR THE INDICATED TIME INTERVALS MAY DCCUR AT ANY TIME DURING THE MONTH. THE TIME INDICATED IS THE ENDING TIME OF THE INTERVAL. DATE AND TIME ARE NOT ENTERED FOR TRACE AMOUNTS.

PAGE 2

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WEATHER CODES

≭T0 RRH ZR L	TORNADO THUNDERSTORM SQUALL RAIN RAIN SHOWERS FREEZING RAIN DRIZZLE FREEZING DRIZZLE	SH SG SP IP IPH A F	SNOW SHOWERS SNOW GRAINS SNOW PELLETS ICE CRYSTALS ICE PELLETS ICE PELLET HAIL FOG	GF BDN BBSY BBKHD	GROUND FOG BLOWING DUST BLOWING SAND BLOWING SAND BLOWING SPRAY SMOKE HAZE DUST
S	FREEZING DRIZZLE	IF	FOG ICE FOG	D	DUST

CEILING: UNL INDICATES UNLIMITED WIND DIRECTION: DIRECTIONS ARE THOSE FROM WHICH THE WIND BLOWS, INDICATED IN TENS OF DEGREES FROM TRUE NORTH: I.E., O9 FOR EAST, 18 FOR SOUTH 27 FOR WEST. AN ENTRY OF OO INDICATES CALM. SPEED: THE OBSERVED AVERAGE ONE-MINUTE VALUE, EXP RESSED IN KNOTS IMPH=KNOTS X 1.15).

PAGE 3

SUMMARY BY HOURS

			AV	ERAG	ES			•	JL TANT IND
	HS I		TEM	PERAT	URE		-	<u> </u>	
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INQUIRIES/CONMENTS CALL (704) 271-4800

INTERNATIONAL AIRPORT

LOCAL CLIMATOLOGICAL DATA Monthly Summary

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* EXTREME FOR THE MONTH - LAST OCCURRENCE IF MORE THAN ONE. T TRACE AMOUNT. + ALSO ON EARLIER DATE(S). HEAVY FOG: VISIBILITY 1/4 HILE OR LESS. BLANK ENTRIES DENOTE MISSING OR UNREPORTED DATA.

DATA IN COLS 6 AND 12-15 ARE BASED ON 21 OR HORE OBSERVATIONS AT HOURLY INTERVALS. RESULTANT WIND IS THE VECTOR SUM OF WIND SPEEDS AND DIRECTIONS DIVIDED BY THE NUMBER OF OBSERVATIONS. COLS 16 & 17: PEAK GUST - HIGHEST INSTANTANEOUS WIND SPEED. ONE OF TWO WIND SPEEDS IS GIVEN UNDER COLS 18 & 19: FASTEST MILE - HIGHEST RECORDED SPEED FOR WHICH A MILE OF WIND PASSES STATION IDIRECTION IN COMPASS POINTSI. FASTEST OBSERVED ONE MINUTE WIND - HIGHEST ONE MINUTE SPEED (DIRECTION IN TENS OF DEGREESI. ERRORS WILL BE CORRECTED IN SUBSEQUENT PUBLICATIONS.

ERRATA - JAN 1993 - CORRECT HEATING DEGREE DAYS Departures to read - MTH: -111 Season: 1

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1993

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NATIONAL OCEANIC AND ATMOSPHERIC ADMINISTRATION

NATIONAL ENVIRONMENTAL SATELLITE, DATA AND INFORMATION SERVICE

NATIONAL CLIMATIC DATA CENTER ASHEVILLE NORTH CAROLINA

Kenneth D Wadeen

DIRECTOR NATIONAL CLIMATIC DATA CENTER

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MAXIMUM SHORT DURATION PRECIPITATION

TIME PERIOD (MINUTES)	5	10	15	20	30	45	60	80	100	120	150	180
PRECIPITATION (INCHES)	0.01	0.01	0.01	0.02	0.02	0.02	0.03	0.03	0.03	0.04	0.04	0.05
ENDED: DATE	22	22	22	21	21	22	21	22	22	22	22	22
ENDED: TIME	0733	0733	0733	2309	2309	0505	2135	0505	0638	0201	0733	0638

THE PRECIPITATION AMOUNTS FOR THE INDICATED TIME INTERVALS MAY OCCUR AT ANY TIME DURING THE MONTH. THE TIME INDICATED IS THE ENDING TIME OF THE INTERVAL. DATE AND TIME ARE NOT ENTERED FOR TRACE AMOUNTS.

PAGE 2

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WEATHER CODES

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CEILING: UNL INDICATES UNLIMITED WIND DIRECTION: DIRECTIONS ARE THOSE FROM WHICH THE WIND BLOWS, INDICATED IN TENS OF DEGREES FROM TRUE NORTH: I.E., 09 FOR EAST, 18 FOR SOUTH 27 FOR WEST. AN ENTRY OF OO INDICATES CALM. SPEED: THE OBSERVED AVERAGE ONE-MINUTE VALUE, EXP RESSED IN KNOTS IMPH=KNOTS X 1.15).

PAGE 3

SUMMARY BY HOURS

			AV	ERAG	ES				ILTANT IND
ļ	ŝ		TENF	PERAT	URE		-		
HOUR L.S.1	SKY COVER (TENTHS)	STATION PRESSURE (INCHES)	AIR IEMP of	NET BULB OF	Jo INIOd N30	REL HUMEDITY X	HIND SPEED THPHI	DIRECTION	SPEED (MPH)
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GMF ASHEVILLE NC 288 06/15/93 20:22

FIRST CLASS POSTAGE AND FEES PAID NOAA PERMII G-19

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OFFICIAL BUSINESS PENALTY FOR PRIVATE USE \$300

LCD-21-14922-PD-9309

45740 JHK 3 ASSOCIATES ATTN: M SCOTT MACCALDEN JR PO BOX 193727 SAN FRANCISCO CA 94119

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INQUIRIES/COMMENTS CALL (704) 271-4800

LOCAL CLIMATOLOGICAL DATA



INTERNATIONAL AIRPORT

Monthly Summary

			LA711	UDE 44	° 53	N	LONGITU	9 30	3° 13			TION (GR	OUNDI	834 F	£ET		1	IME 2	ONE	CENT	RAL		1	4922	
			TEMPE	RATURE	٩		DEGREI Base	E DAYS 65°F	NEATH 1 Fog	IER TYPES	SNOH ICE PELLETS	PRECIPI	TATION	AVERAGE STATION PRESSURE			(M	WIND P.H				SUNSH	INE	SKY C Eten	
		~ HAXIHUN	HUNIN 2	∽ AVERAGE	DEPARTURE FROM NORMAL	© AVERAGE © DEH POLNI	- NEATING ISEASON	COOLING (SEASON) BEGINS HITH JAN)	3 THU 4 1CE 5 HAI 5 GLA 7 DUS 8 SMO		OR ICE ON GROUND AT OGOO INCHES 9		- SNOH, ICE PELLETS	IN INCHES ELEV. 838 FEET ABOVE M.S.L. 12	G RESULIANT DIR.	🖂 RESULIANI SPEED	G AVERAGE SPEED		AK UST NOTI JENE 17		TEST MIN 101103010 19	S ALINUTES	→ PERCENT OF	SUNRISE 10 SUNSEI	NIDNIGHT
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* EXTREME FOR THE MONTH - LAST OCCURRENCE IF MORE THAN ONE.

T TRACE AMOUNT. T TRACE AMOUNT. + ALSO ON EARLIER DATE(S). HEAVY FOG: VISIBILITY 1/4 MILE OR LESS. BLANK ENTRIES DENOTE MISSING DR UNREPORTED DATA.

DATA IN COLS 6 AND 12-15 ARE BASED ON 21 OR MORE OBSERVATIONS AT HOURLY INTERVALS. RESULTANT WIND IS THE VECTOR SUM OF WINC SPEEDS AND DIRECTIONS DIVIDED BY THE NUMBER OF OBSERVATIONS. COLS 16 & 17: PEAK GUST - HIGHEST INSTANTANEOUS WIND SPEED. ONE OF TWO WIND SPEEDS IS GIVEN UNDER COLS 18 & 19: FASTEST MILE - HIGHEST RECORDED SPEED FOR WHICH A MILE OF WIND PASSES STATION (DIRECTION IN COMPASS POINTS), FASTEST OBSERVED ONE MINUTE WIND - HIGHEST ONE MINUTE SPEED (DIRECTION IN TENS OF DEGREES). ERRORS WILL BE CORRECTED IN SUBSEQUENT PUBLICATIONS.

I CERTIFY THAT THIS IS AN OFFICIAL PUBLICATION OF THE NATIONAL OCEANIC AND ATMOSPHERIC ADMINISTRATION, AND IS COMPILED FROM RECORDS ON FILE AT THE NATIONAL CLIMATIC DATA CENTER



NATIONAL DCEANIC AND ATMOSPHERIC ADMINISTRATION NATIONAL ENVIRONMENTAL SATELLITE, DATA AND INFORMATION SERVICE

NATIONAL CLIMATIC DATA CENTER ASHEVILLE NORTH CARDLINA

Kenned D Hadeen

DIRECTOR NATIONAL CLIMATIC DATA CENTER

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MAXIMUM SHORT DURATION PRECIPITATION

TIME PERIOD (MINUTES)	5	10	15	20	30	45	60	80	100	120	150	180
PRECIPITATION (INCHES)	0.02	0.03	0.03	0.04	0.04	0.06	0.08	0.09	0.11	0.12	0.14	0.17
ENDED: DATE	30	30	30	30	30	30	30	30	30	30	30	30
ENDED: TIME	1356	1404	1404	1122	1421	1158	1158	1228	1228	1243	1326	i404

THE PRECIPITATION AMOUNTS FOR THE INDICATED TIME INTERVALS MAY OCCUR AT ANY TIME DURING THE MONTH. THE TIME INDICATED IS THE ENDING TIME OF THE INTERVAL. DATE AND TIME ARE NOT ENTERED FOR TRACE AMOUNTS.

PAGE 2

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WEATHER CODES

CEILING: UNL INDICATES UNLIMITED WIND DIRECTION: DIRECTIONS ARE THOSE FROM WHICH THE WIND BLOWS, INDICATED IN TENS OF DEGREES FROM TRUE NORTH: 1.E., OP FOR EAST, 18 FOR SOUTH 27 FOR WEST. AN ENTRY OF OO INDICATES CALM. SPEED: THE OBSERVED AVERAGE ONE-MINUTE VALUE, EXP RESSED IN KNOTS IMPHEKNOTS X 1.15).

PAGE 3

SUMMARY BY HOURS

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NATIONAL CLIMATIC DATA CENTER FEDERAL BUILDING 37 BATTERY PARK AVE ASHEVILLE, NORTH CAROLINA 28801-2733

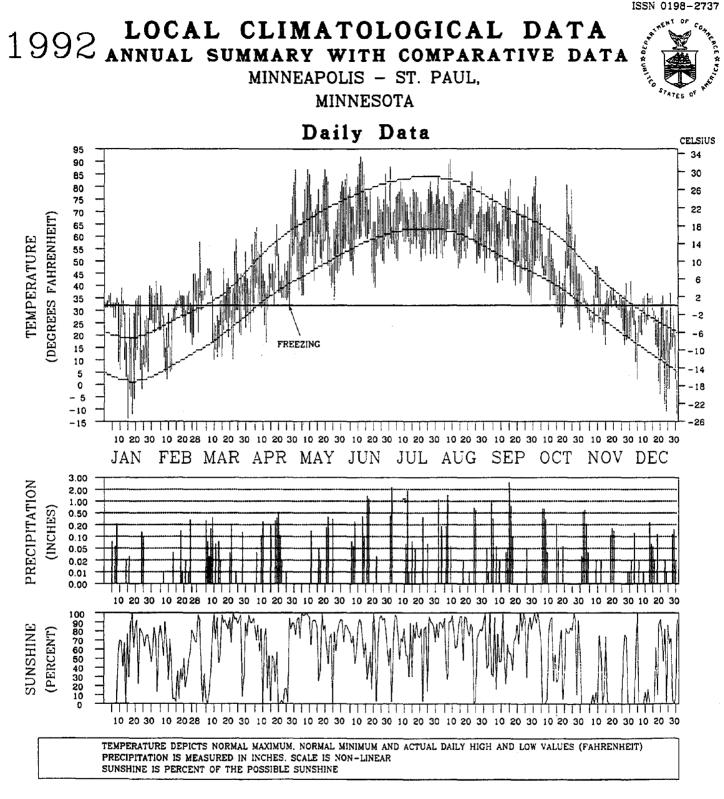
OFFICIAL BUSINESS PENALTY FOR PRIVATE USE \$300 FIRST CLASS POSTAGE AND FEES PAID NOAA PERMIT G-19

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45740 JHK & ASSOCIATES ATTN: M SCOTT MACCALDEN JR PO BOX 193727 SAN FRANCISCO CA 94119

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I CERTIFY THAT THIS IS AN OFFICIAL PUBLICATION OF THE NATIONAL OCEANIC AND ATMOSPHERIC ADMINISTRATION, AND IS COMPILED FROM Records on File at the National Climatic Data Center, Asheville, North Carolina, 2000:

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NATIONAL

NATIONAL ENVIRONMENTAL SATELLITE, DATA AND INFORMATION SERVICE

NATIONAL CLIMATIC DATA CENTER ASHEVILLE NORTH CAROLINA

well D Wadeen DIRECTOR NATIONAL CLIMATIC DATA CENTER

METEOROLOGICAL DATA FOR 1992

MINNEAPOLIS - ST. PAUL, MINNESOTA

JAN FEB MAR APR MAY JUNE JULY AUG SEP OCT NOV DEC YEAR TEMPERATURE *7: ***********************************	LATITUDE: 44 °53'N LO	NG1TUDE	: 93 °	13' W	ELEVAT	10N: FT	GRND	834 B	ARO	860 TI	ME ZONE	: CENTR	AL WB	AN: 14922
Answert Part and		1												YEAR
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-Greatest (24 hrs) 3.6 3.4 3.9 0.6 0.0 0.0 0.0 T T 0.8 6.5 3.9 28-29 NOV 1-2 WIND: Resultant -Direction (!!) 265 305 004 026 194 073 284 218 194 337 341 248 268 -Speed (mph) 1.6 2.0 2.7 1.5 2.7 0.8 1.9 1.7 4.8 1.5 2.4 3.0 0.9 9.9 Average Speed (mph) 1.6 2.0 2.7 1.5 2.7 0.8 1.9 1.7 4.8 1.5 2.4 3.0 0.9 0.9 Average Speed (mph) 9.8 9.9 9.7 11.4 11.2 9.8 9.3 9.2 11.6 9.8 9.4 10.4 10.1 Fastest Obs. 1 Min. 31 32 33 15 17 22 26 26 32 29 31 29 23 28 30 35 24 29 29 23 28						-			-	_				45.0
Resultant -Direction (!!) 265 305 004 026 194 073 284 218 194 337 341 248 268 -Direction (!!) 1.6 2.0 2.7 1.5 2.7 0.8 1.9 1.7 4.8 1.5 2.4 3.0 0.9 Average Speed (mph) 9.8 9.9 9.7 11.4 11.2 9.8 9.3 9.2 11.6 9.8 9.4 10.4 10.1 Fastest Obs. 1 Min. - - - - 11.2 2.2 26 26 32 29 31 29 22 -Speed (mph) 31 32 33 15 17 22 26 26 32 29 31 29 22 -Speed (mph) 31 29 23 28 30 35 24 29 29 23 28 32 35 -Date 23 6 31 30 10 17 3 1 27 12 12 25 JUN 17<	-Greatest (24 hrs)	3.6	3.4	3.9	0.6	0.0 0.0			T	T	0.8	6.5	3.9	45.0 6.5 NOV 1- 2
-Direction (!!) 265 305 004 026 194 073 284 218 194 337 341 248 268 -Speed (mph) 1.6 2.0 2.7 1.5 2.7 0.8 1.9 1.7 4.8 1.5 2.4 3.0 0.9 Average Speed (mph) 9.8 9.9 9.7 11.4 11.2 9.8 9.3 9.2 11.6 9.8 9.4 10.1 Fastest Obs. 1 Min. - - - 9.8 9.2 22 26 26 32 29 31 29 22 -Direction (!!) 31 32 32 15 17 22 26 26 32 29 31 29 22 -Speed (mph) 31 29 23 28 30 35 24 29 23 28 32 35 -Date 23 6 31 30 10 17 3 1 27 12 12 25 JUN 17 Peak Gust - <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td>														
Fastest Obs. 1 Min. -Direction (!!) 31 32 33 15 17 22 26 26 32 29 31 29 22 -Speed (mph) 31 29 23 28 30 35 24 29 29 23 28 32 35 -Date 23 6 31 30 10 17 3 1 27 12 12 25 JUN 17 Peak Gust -Direction (!!) NW NW N SE H S W SW NW	-Direction (!!) -Speed (mph)	1.6	305 2.0	2.7	1.5	2.7	0.8	1.9	1.7	4.8	1.5	2.4	3.0	0.9
Peak Gust -Direction (!!) NW NW N SE W SW NW S NW	Fastest Obs. 1 Min.		1					1				ļ .		
Peak Gust -Direction (!!) NW NW N SE W SW NW S NW	-Speed (mph)	31	29	23	28	30		24	29	29	23	28	32	35 JUN 17
-Speed (mph) 41 38 32 38 49 51 33 39 40 32 41 -Date 23 7 24 5 2 17 3 1 27 22 12	Peak Gust	NW	NW	N	SE	W	s	W	SW	NW	s	NW		
					38		Į 51			40	32		1	

(!!) See Reference Notes on Page 68 Page 2

NORMALS, MEANS, AND EXTREMES

MINNEAPOLIS - ST. PAUL, MINNESOTA

LATITUDE: 44 °53 N	LONG	TUDE :	93 °13,		EVATION	. 57 C		34 BARO	- 860	TIME	ZONE: C		ЦР	AN: 14922
LATITODE: 44 55 N	la)	JAN	FEB	MAR	APR	MAY		JULY	AUG	SEP	OCT	NOV	DEC	YEAR
TEMPERATURE °F:														
Normals -Daily Maximum		19.9	26.4 8.5	37.5 20.8	56.0	69.4 47.6	78.5 57.7	83.4 62.7	80.9	71.0	59.7	41.1	26.7	54.2
-Daily Minimum -Monthly		2.4	8.5 17.5	20.8 29.2	36.0 46.0	47.6 58.5	57.7 68.1	62.7 73.1	60.3 70.6	50.2 60.6	39.4 49.6	25.3 33.2	11.7 19.2	54.2 35.2 44.7
Extremes						_								
-Record Highest -Year	54	58 1944	60 1981	83 1986	95 1980	96 1978	102 1985	105 1988	102 1947	98 1976	89 1953	75 1944	63 1982	105 JUL 1988
-Record Lowest -Year	54	-34 1970	-28 1965	-32 1962	2 1962	18 1967	34 1945	43 1972	39 1967	26 1974	15 1972	-17 1964	-29 1983	-34 JAN 1970
NORMAL DEGREE DAYS: Heating (base 65°F		1668	1330	1110	570	238	4 1	12	16	160	488	954	1420	8007
Cooling Ibase 65°F		0	0	0	0	36	134	263	190	28	11	0	Q	662
X OF POSSIBLE SUNSHINE	54	53	59	57	58	61	66	72	69	62	55	39	42	58
MEAN SKY COVER (tenths Suncise - Sunset MEAN NUMBER OF DAYS:	54	6.3	6.3	6.7	6.5	б.4	6.1	5.3	5.3	5.6	5.8	7.1	7.0	6.2
Sunrise to Sunset -Clear	54	8.3	7.7	6.9 7.4	7.0	7.1	7.3	10.0	10.3	9.9	9.9	5.6	6.4	96.4
-Partly Cloudy -Cloudy	54 54	7.4	6.9 13.6	7.4	7.7	9.1 14.8	10.4 12.3	11.9 9.2	11.1 9.6	8.6 11.6	7.6	6.5 17.9	6.4 18.2	100.9 167.9
Precipitation .01 inches or more	54	8.5	7.4	10.3	10.2	11.3	11.6	9.7	9.9	9.6	8.0	8.5	9.3	114.5
Snow,lce pellets,ha 1.0 inches or more	54	3.2	2.7	3.0	0.8	0.1	0.0	0.0	0.0	0.*	0.1	2.2	3.1	15.2
Thunderstorms	54	0.*	0.2	1.0	2.7	5.2	7.5	7.6	6.5	4.3	1.8	0.6	0.1	37.5
Heavy Fog Visibility 1/4 mile on less Temperature f	54	1.2	1.4	1.3	0.4	0.5	0.5	0.3	0.6	0.9	1.0	1.2	1.4	10.6
-Maximum 90° and above 32° and below -Minimum	33 33	0.0 23.4	0.0 17.7	0.0 8.7	0.1 0.3	0.8 0.0	2.8 0.0	6.3 0.0	3.7 0.0	0.8 0.0	0.0	0.0 7.0	0.0 21.4	14.6 78.5
32° and below 0° and below	33 33	30.8 13.6	27.3 8.1	25.0 1.8	11.0 0.0	1.1 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.5 0.0	7.7 0.0	22.9 0.7	29.8 8.0	156.2 32.3
AVG. STATION PRESS. (mb	20	987.3	988.2	985.0	984.2	983.6	983.0	984.8	985.7	986.0	986.3	985.9	987.5	985.6
RELATIVE HUMIDITY (%) Hour 00	33	72	73	72	. 67	67	72	75	77	79	74	77	76	73
Hour 06 Hour 12 (Local Tim	33 33 33	74	75	72 76 61	75 52	76 52	72 79 54	81 54	84 56	85 59	81 58	80 66	78 70	73 79 60
Hour 18	33	68	66	61	51	50	52	53	56	61	6ŏ	69	72	60
PRECIPITATION (inches) Water Equivalent														
-Normal -Maximum Monthly	54	0.82	0.85 2.14	1.71	2.05 5,88	3.20 8.03	4.07 9.82	3.51 17.90	3.64 9.31	2.50 7.53	1.85 5.68	1.29	0.87	26.36 17.90
-Year -Minimum Monthly	54	1967 0,10	1981 0.06	1965	1986 0.16	1962 0.61	1990 0.22	1987 0.58	1977	1942 0.41	1971 0.01	1991 0.02	1982 T	JUL 1987 T
-Year -Maximum in 24 hrs	54	1990	1964	1958 1.66 1965	1987 2.23 1975	1967 3,03	1988 3.00	1975 10.00	1946	1940 3.55	1952 2.95	1939	1943 2.47	DEC 1943 10.00
-Year		1967	1966	1965	1975	1965	1986	1987		1942	1966	1940	1982	JUL 1987
		1.207									1	i		
Snow,Ice pellets,hai -Maximum Monthly	54	46.4		40.0	21.8	3.0	T	0,0	T	1.7	8.2	46.9	33.2	46.9
-Maximum Monthly -Year -Maximum in 24 hrs	54	46.4 1982 18.5	26.5 1962 9.3	40.0 1951 14.7	21.8 1983 13.6	3.0 1946 3.0	1989 T	0.0 J.0	1992 T	1942 1.7	1991 8.2	1991 21.0	1969 16.5	NOV 1991 21.0
-Maximum Monthly -Year -Maximum in 24 hr: -Year	54	46.4 1982	26.5 1962	40.0 1951	21.8 1983	3.0 1946	1989		1992	1.7 1942 1.7 1942	1991	1991	1969	NOV 1991
-Maximum Monthly -Year -Maximum in 24 hrs -Year WIND: Mean Speed (mph)	54 54 54	46.4 1982 18.5	26.5 1962 9.3	40.0 1951 14.7	21.8 1983 13.6	3.0 1946 3.0	1989 T		1992 T	1942 1.7	1991 8.2	1991 21.0	1969 16.5	NOV 1991 21.0
-Maximum Monthly -Year -Maximum in 24 hrs -Year WIND: Mean Speed (mph) Prevailing Direction through 1963	54 54 54	46.4 1982 18.5 1982	26.5 1962 9.3 1939	40.0 1951 14.7 1985	21.8 1983 13.6 1983	3.0 1946 3.0 1946	1989 T 1989	ა.0	1992 1 1992	1942 1.7 1942	1991 8.2 1991	1991 21.0 1991	1969 16.5 1982	NOV 1991 21.0 NOV 1991
-Maximum Monthly -Year -Maximum in 24 hrs -Year WIND: Mean Speed (mph) Prevailing Direction through 1963 Fastest Obs. 1 Min -Direction (!!)	54 54 54 13	46.4 1982 18.5 1982 10.5 NW	26.5 1962 9.3 1939 10.4 NW 34	40.0 1951 14.7 1985 11.4 NW 08	21.8 1983 13.6 1983 12.2 NW 19	3.0 1946 3.0 1946 11.2 SE 23	1989 1989 1989 10.5 SE .01	0.0 9.4 S 35	1992 1992 9.3 SE 20	1942 1.7 1942 10.0 S 18	1991 8.2 1991 10.5 SE 33	1991 21.0 1991 10.9 NW 25	1969 16.5 1982 10.4 NW 34	NOV 1991 21.0 NOV 1991 10.6 NW 32
-Maximum Monthly -Year -Maximum in 24 hr: -Year WIND: Mean Speed (mph) Prevailing Direction through 1963 Fastest Obs. 1 Min -Direction (!!) -Speed (MPH) -Year	54 54 54	46.4 1982 18.5 1982 10.5 NW 32	26.5 1962 9.3 1939 10.4 NW	40.0 1951 14.7 1985 11.4 NW	21.8 1983 13.6 1983 12.2 NW	3.0 1946 3.0 1946 11.2 SE	1989 T 1989 10.5 SE	0.0 9.4 5	1992 1992 9.3 SE	1942 1.7 1942 10.0 S	1991 8.2 1991 10.5 SE	1991 21.0 1991 10.9 NK	1969 16.5 1982 10.4 NW	NOV 1991 21.0 NOV 1991 10.6 NW
-Maximum Monthly -Year -Maximum in 24 hrs -Year WIND: Mean Speed (mph) Prevailing Direction through 1963 Fastest Obs. 1 Min -Direction (!!) -Speed (MPH) -Year Peak Gust -Direction (!!)	54 54 54 13	46.4 1982 18.5 1982 10.5 NW 32 51 1986 NW	26.5 1962 9.3 1939 10.4 NW 34 37 1987 NW	40.0 1951 14.7 1985 11.4 NW 08 33 1985	21.8 1983 13.6 1983 12.2 NW 19 41 1984 SW	3.0 1946 3.0 1946 11.2 SE 23 35 1986 N	1989 1989 10.5 SE 01 46 1980	0.0 9.4 S 43 1980 NW	1992 1992 9.3 SE 20 44 1983 W	1942 1.7 1942 10.0 S 18 36 1988 N	1991 8.2 1991 10.5 SE 33 1981 NW	1991 21.0 1991 10.9 NW 25 41 1986 W	1969 16.5 1982 10.4 NW 34 35 1989 NW	NOV 1991 21.0 NOV 1991 10.6 NW 32 51 JAN 1986 W
-Maximum Monthly -Year -Maximum in 24 hrs -Year WIND: Mean Speed (mph) Prevailing Direction through 1963 Fastest Obs. 1 Min -Direction (!!) -Speed (MPH) -Year Peak Gust	54 54 54 13	46.4 1982 18.5 1982 10.5 NW 32 51 1986	26.5 1962 9.3 1939 10.4 NW 34 37 1987	40.0 1951 14.7 1985 11.4 NW 08 33 1985	21.8 1983 13.6 1983 12.2 NW 19 41 1984	3.0 1946 3.0 1946 11.2 SE 23 355 1986	1989 T 1989 10.5 SE 01 46	0.0 9.4 5 43 1980	1992 1992 9.3 SE 20 44 1983	1942 1.7 1942 10.0 S 18 36 1988	1991 8.2 1991 10.5 SE 33 33 1981	1991 21.0 1991 10.9 NW 25 41 1986	1969 16.5 1982 10.4 NW 34 35 1989	NOV 1991 21.0 NOV 1991 10.6 NW 32 51 JAN 1986

(!!) See Reference Notes on Page 68. Page 3 PRECIPITATION (inches)

MINNEAPOLIS - ST. PAUL, MINNESOTA

YEAR	JAN	FEB	MAR	APR	MAY	JUNE	JULY	AUG	SEP	OCT	NOV	DEC	ANNUAL
1963	0.46	0.41	1.18	2.07	5.06	1.91	1.53	1.55	3,47	0.81	0.52	0.60	19.57
1964	0.47	0.06	1.35	2.98	3.44	2.18	2.02	5.42	5,21	0.57	1.19	1.08	25.97
1965	0.47	1.59	4.75	3.52	7.86	4.01	4.69	4.04	4,90	0.90	1.98	1.23	39.94
1966	0.95	1.55	2.48	0.89	1.46	3.51	2.47	4.40	1,69	3.53	0.39	1.02	24.34
1967	3.63	1.59	0.96	4.07	0.61	7.53	1.36	2.79	0,63	1.73	0.09	0.45	25.44
1968	0.71	0.13	1.89	2,94	3.74	6.78	6.46	0.75	6.15	5.62	0.54	2.21	37.93
1969	2.05	0.31	0.90	1,55	1.98	2.93	2.95	0.99	0.49	2.53	0.65	2.06	19.39
1970	0.47	0.16	2.05	3,55	4.77	1.27	3.66	2.19	3.19	4.97	3.82	0.43	30.53
1971	1.22	1.74	1.21	1,11	3.14	3.52	3.94	1.78	2.73	5.68	2.67	0.70	29.44
1972	0.84	0.49	1.25	1,69	2.18	3.31	5.12	2.48	1.96	1.77	1.11	1.57	23.77
1973	0.92	0.84	1.12	2.32	2.48	1.06	2.90	3.05	2.08	1.29	1.97	1.10	21.13
1974	0.17	1.06	1.00	2.42	2.08	5.21	1.14	2.75	0.58	1.69	0.66	0.35	19.11
1975	2.82	0.79	1.67	5.40	3.81	7.99	0.58	4.92	1.31	0.27	4.80	0.79	35.15
1976	0.87	0.59	2.83	0.80	1.13	3.86	2.45	1.39	1.42	0.49	0.16	0.51	16.50
1977	0.65	0.93	2.66	1.84	2.86	3.57	3.72	9.31	4.43	2.34	1.42	1.15	34.88
1978	0.38	0.24	0.79	3.63	3.79	7.09	3.19	5,77	2.47	0.19	1.84	0.88	30.26
1979	1.09	1.39	2.55	0.66	4.55	4.78	2.34	7,04	2.20	3.16	0.98	0.33	31.07
1980	0.94	0.67	1.12	0.83	2.29	5.52	2.30	3,26	3.68	0.66	0.26	0.24	21.77
1981	0.30	2.14	0.71	2.17	2.18	4.42	4.09	4,73	1.46	2.69	2.16	0.92	27.97
1982	2.45	0.43	2.09	1.62	4.99	1.44	0.92	3,80	1.50	3.45	3.27	4.27	30.23
1983	0.67	1.19	3.22	3.97	6.20	5.22	3.07	3.12	3.34	2.61	4.93	1.53	39.07
1984	0.88	1.64	1.47	3.86	2.29	7.95	3.03	5.15	2.65	5.48	0.31	2.24	36.95
1985	0.87	0.50	4.48	1.81	3.65	2.18	2.20	5.02	4.37	3.66	1.72	1.20	31.66
1986	0.90	0.84	2.03	5.88	3.48	5.34	4.11	4.44	6.90	1.77	0.62	0.31	36.62
1987	0.63	0.13	0.64	0.16	1.88	1.95	17.90	3.67	1.28	0.60	2.07	1.25	32.16
1988	1.37	0.30	1.33	1,58	1.70	0.22	1.17	4.29	2.79	0.80	2.86	0.67	19.08
1989	0.52	1.04	2.19	2,66	3.38	3.50	3.50	2.92	1.28	0.53	1.38	0.42	23.32
1990	0.10	0.77	3.66	3,80	3.36	9.82	5.06	1.71	1.88	1.23	0.65	1.01	33.05
1991	0.49	1.03	2.29	3,58	6.35	2.57	2.95	3.14	5.43	2.52	5.29	1.05	36.69
1992	0.66	0.57	1.56	1,99	1.15	3.68	5.21	4.54	5.20	2.11	1.95	1.05	29.67
Record Mean	0.83	0.86	1.61	2.17 Se	3.38 e Refer	4.14 ence No Page	3.53 tes on e 4A	3.37 Page 6B	2.90	2.02	1.45	0.95	27.21

AVERAGE TEMPERATURE (deg. F) MINNEAPOLIS - ST. PAUL. MINNESOTA

YEAR	JAN	FEB	MAR	APR	MAY	JUNE	JULY	AUG	SEP	OCT	NOV		ANNUAL
1963 1964 1965 1966 1966	2.9 20.0 10.0 3.3 14.6	12.1 23.9 11.8 16.3 8.7	34.2 25.8 19.5 35.8 29.8	47.3 46.8 41.8 42.2 44.7	55.4 61.5 58.7 53.6 52.3	69.8 68.7 66.5 68.4 65.9	73.5 76.0 70.5 76.8 68.8	68.9 68.5 68.6 68.2 66.2	62.2 58.9 52.3 60.3 60.3	58,1 48,2 50,7 47,5 46,3	38.3 35.0 33.1 30.1 30.7	10.0 14.8 28.0 18.1 21.8	44.4 45.7 42.7 43.4 42.6
1968 1969 1970 1971 1972	ាមលាស ក្រុម ភូមិសាស ភូមិសាស	15.2 19.3 15.4 17.0 10.5	38.8 24.1 26.0 28.0 26.5	48.5 49.3 46.1 47.0 41.9	53.4 60.6 58.5 55.4 61.3	67.2 61.8 71.2 71.5 66.0	71.1 73.6 75.2 68.8 68.5	70.7 74.4 71.9 69.6 69.8	61.1 63.0 61.2 62.8 57.9	50.7 46.5 49.6 51.4 43.7	34.0 33.6 32.7 32.7 32.2	16.9 20.3 18.2 18.4 11.3	45.2 44.7 44.3 44.1 41.3
1973 1974 1975 1976 1977	17.4 11.9 14.5 11.6 0.3	21.6 16.9 15.5 27.8 22.7	40,2 29,5 22,1 31,4 37,5	44.4 47.1 38.9 51.8 53.0	55.2 54.4 60.9 58.9 66.9	69.5 65.5 68.8 71.7 68.4	73.8 76.6 76.3 76.1 74.8	73.4 67.3 71.7 73.3 66.1	60.1 55.3 57.7 61.8 60.5	53.8 49.8 52.8 44.6 47.1	34.3 33.7 37.5 28.3 30.8	16.7 24.4 21.3 13.6 14.4	46.7 44.4 44.8 45.9 45.2
1978 1979 1980 1981 1982	5,2 3,2 15,0 18,0 2,3	11.6 10.0 15.3 23.4 15.8	30.0 28.9 27.3 37.7 29.0	45.2 44.0 49.2 49.1 43.8	61.8 55.5 61.5 57.1 62.5	67.8 67.3 67.6 67.0 63.7	71,1 73,6 75,2 70,9 75,6	72.2 69.9 70.7 69.3 71.8	67.3 63.4 59.0 60.9	49.8 46.6 45.1 46.7 50.3	32.5 31.7 36.6 38.0 31.5	15.2 26.0 19.8 17.5 25.7	44.2 43.3 45.2 46.2 44.4
1983 1984 1985 1986 1987	19.6 12.0 10.1 17.5 21.2	26.9 27.5 16.5 15.7 31.6	34.2 24.8 35.6 33.9 38.7	42.3 47.1 52.1 49.6 53.5	54.6 56.0 62.24 53.5	68.0 69.7 63.9 68.6 72.8	77.2 72.2 73.9 73.9 76.0	76.8 73.5 67.6 67.1 69.0	62.6 57.9 59.8 59.8 59.5	48,4 50,7 47,5 49,2 44,6	34.0 33.3 24.8 28.2 37.9	3.7 17.9 7.7 24.7 25.0	45.7 45.2 43.5 45.6 49.7
1988 1989 1990 1991 1992	10,4 21,2 26,3 12,5 21,9	13.9 8.6 23.7 24.4 28.0	33.8 26.6 35.7 34.3 33.1	47,4 45.3 46.8 49.1 43.6	65.4 57.5 56.3 61.9 60.5	74.4 68.4 69.5 72.9 65.6	78.1 76.4 71.3 72.3 65.8	73.9 70.8 70.6 71.1 65.9	62.4 50.9 64.4 59.6	44.0 49.9 48.1 47.2 47.4	32.7 28.0 37.4 24.5 31.4	20.5 10.6 16.9 21.2 21.2	46.4 43.7 47.3 45.9 45.3
Record Mean Max Min	13,2 21.8 4.6	17.3 25.9 8.5	30.1 38.4 21.8	46.0 55.8 36.3 Se	58.3 68.5 48.0 e Refer	68.0 77.9 58.0 ence No	73.2 83.2 63.1 tes on #8	70.7 80.6 60.7 Page 6B	61.5 71.3 51.6	49.6 59.0 40.2	32.8 40.4 25.2	19.2 26.7 11.6	45.0 54.1 35.8

HEATING DEGREE DAYS Base 65 deg. F MINNEAPOLIS - ST. PAUL, MINNESOTA

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SEASON	JULY	AUG	SEP	OCT	NOV	DEC	JAN	FEB	MAR	APR	MAY	1	TOTAL
1963-64 1964-65 1965-66 1966-67 1967-68	1 0 7 0 36	32 63 40 65	129 22685 186 166	216 515 447 536 577		1703 1551 1140 1446 1335	1390 1702 1909 1556 1567	1186 1486 1358 1572 1440	1209 1405 899 1086 808	543 690 678 600 491	154 211 357 408 358	49 19 40 40 40 40 40 40 40 40 40 40 40 40 40	7405 8760 8194 8497 7929
1968-69 1969-70 1970-71 1971-72 1972-73	10 5 36 34	20 20 20 20 20 20 20 20 20 20 20 20 20 2	143 131 190 164 218	451 580 476 413 651	959	1486 1379 1443 1438 1664	1723 1842 1811 1844 1474	1274 1382 1341 1576 1208	1261 1204 1139 1 188 761	461 577 537 687 611	204 249 297 204 299	136 20 18 73 13	8099 8302 8219 8587 7959
1973-74 1974-75 1975-76 1976-77 1977-78	1 1500	3 48 4 7 4 5	185 289 231 162 145	350 467 387 632 548	915 933 818 1092 1016	1493 12540 1359 156	1642 1561 1650 2005 1842	1344 1379 1074 1180 1488	1092 1324 1031 844 1080	535 775 405 365 584	338 188 195 75 162	72 39 11 17 46	7970 8255 7170 7966 8511
1978-79 1979-80 1980-81 1981-82 1982-83	500 10	7 24 12 11 14	89 105 194 172 168	464 566 611 568 448	968 992 845 803 997	1538 1203 1396 1466 1212	1914 1535 1455 1940 1400	1537 1435 1160 1374 1061	1112 1165 838 1111 947	623 484 472 629 673	307 184 249 117 313	38 34 28 71 49	8602 7729 7258 8274 7282
1983-84 1984-85 1985-86 1986-87 1987-88	NDOON	0200 1200 420	161 251 240 177 106	514 435 537 480 623	923 943 1201 1096 804	1901 1453 1774 1243 1236	1641 1694 1466 1352 1688	1082 1355 1377 929 1479	1240 904 957 809 962	531 4034 3457 523	284 123 212 134 76	7 104 30 13 4	8286 7682 8276 6623 7532
1988-89 1989-90 1990-91 1991-92 1992-93	1 0 2 3 2	1 6 6 6 6 7 6 7 7	116 159 136 228 182	6470 4706 5442 542	963 1100 1206 1003	1373 1683 1484 1354 1351	1353 1194 1624 1333	1576 1151 1130 1067	1184 899 945 981	583 569 486 636	251 274 197 190	44 37 38 72	8106 7547 7343 7630

See Reference Notes on Page 63. Page 5A

COOLING DEGREE DAYS Base 65 deg. F MINNEAPOLIS - ST. PAUL MINNESOTA

YEAR	JAN	FEB	MAR	APR	MAY	JUNE	JULY	AUG	SEP	ост	NOV	DEC	TOTAL
1969 1970 1971 1972	0000	0000	0000	07 r 0 0	76 54 54	49 213 218 109	276 323 141 148	22 22 20 20 20 20 20 20 20 20 20 20 20 2	77 83 106 13	121630	0000	0000	788 920 643 572
1973 1974 1975 1976 1977	00000	00000	00000	1 INO 4 N	4 18 66 14 145	158 93 153 223 129	280 369 371 351 310	271 127 220 269 76	47 6 18 72 19	8 16 7 0	00000	00000	769 619 850 950 691
1978 1979 1980 1981 1982	00000	00000	00000	00,000	72 17 82 10 46	138 113 121 96 40	201 275 322 200 338	236 181 194 151 232	164 55 38 28 53	0 0 1 0 0	00000	00000	811 651 774 485 709
1983 1984 1985 1986 1987	00000	00000	00000	0 0 22 1 11	03366 446	145 155 77 148 253	389 237 284 286 346	3680 2111 159	984307 307 37	\$0000	00000	00000	1008 709 637 627 903
1988 1989 1990 1991 1992	00000	00000	00000	1 28 3	905 25 200 100	296 153 178 246 96	412 359 208 234	3099 1908 1908	45 445 125 50 8	081-02	00000	00000	1152 779 740 857 337

See Reference Notes on Page 68. Page 53

SNOWFALL (inches)

MINNEAPOLIS - ST. PAUL, MINNESOTA

SEASON		AUG	SEP	OCT	NOV	DEC	JAN	FEB	MAR	APR	MAY		TOTAL
1963-64 1964-65 1965-66 1966-67 1967-68	0.0000000000000000000000000000000000000		0.0 0.0 0.0 0.0	0.0 T 0.2 0.3	T 4.3 1.6 3.4 0,8	7.6 8.1 1.2 12.7 2,4	5.0 10.5 11.9 35.3 10,6	1.0 11.7 6.8 23.7 2.2	9.7 37.1 14.2 2.6 0.8	5.0 2.4 0.4 0,4	0.0 T 0.3 0.0	0.0 0.0 0.0 0.0	28.9 73.7 36.1 78.4 17.5
1968-69 1969-70 1970-71 1971-72 1972-73	0.0 0.0 0.0 0.0	0.00 0.00 0.00 0.0	0.0 0.0 0.0 T	7 2.4 T 0.0	4,9 3,8 6,3 13,2 1,1	28.7 33.2 5.5 12.8 15.3	21.6 9.8 19.9 12.2 11.6	5.3 4.3 13.9 7.6 11.3	7.3 8.6 7.0 10.4 0.4	0.3 1.3 1.9 8.0 2.0	0.0 T 0.2 0.0 0.0	0.0 0.0 0.0 0.0	68.1 63.4 54.7 64.2 41.7
1973-74 1974-75 1975-76 1976-77 1977-78	0.0 0.0 0.0 0.0	0,0 0,0 0,0 0,0	0.0 0.0 0.0 0.0	0.0 0.0 2.3 3.0	0.1 1.2 16.2 1.4 11.7	17.9 6.1 5.6 8.3 14.2	2.5 27.4 12.8 13.4 6.8	15.7 9.0 5.1 1.8 4.6	7.7 18.3 13.6 14.6 8.5	7.3 2.2 0.0 1.8 1.9	0.0 0.0 1.2 0.0	0.0 0.0 0.0 0.0	51.2 64.2 54.5 43.6 50.7
1978-79 1979-80 1980-81 1981-82 1982-83	0.0 0.0 0.0 0.0		0.000	0.0 T 0.9 1.4	16.5 7.7 0.9 14.0 3.6	15.1 1.7 2.8 10.6 19.3	14.2 12.9 4.6 46.4 3.2	13.5 8.8 11.0 7.4 10.8	8.4 13.7 0.1 10.9 14.3	0.7 8.5 1.7 4.8 21.8	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0	68.4 53.3 21.1 95.0 74.4
1983-84 1984-85 1985-86 1985-87 1987-88	0.0 0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0	0.0 0.0 0.4 0.0 0.0	0.3 T 0.3	30.4 2.0 23.9 4.4 4.5	21.0 16.3 13.5 4.2 7.5	10,6 13,1 10,3 5,5 19,5	9.3 4.3 12.2 4.5	17.3 36.8 8.7 2.1 3.7	9,8 T 0,4 T 2,4	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	98.4 72.7 69.5 17.4 42.4
1988-89 1989-90 1990-91 1991-92 1992-93	0.0 0.0 0.0 0.0	0.0 0.0 0.0 T T	0.0 0.0 0.0 0.0 T	0.2 0.0 T 8.2 1.3	15.8 11.3 5.0 46.9 12.2	7.2 7.0 11.7 6.7 9.2	6.0 1.1 6.5 5.0	17.3 10.7 14.2 5.9	22.7 3.2 4,4 10.8	0.8 2.2 1.5 0.6	0.1 0.0 0.3 0.0	T 0.0 0.0 0.0	70.1 35.5 43.6 84.1
Record Mean	0.0	T	Ţ	0.5 See	7.9 Refere	9.4 nce Not Page	9.7 es on P. 6A	8.5 age 6B.	10.8	2.9	0.1	Т	49.9

REFERENCE NOTES

MINNEAPOLIS - ST. PAUL, MINNESOTA

GENERAL T - TRACE AMOUNT. BLANK ENTRIES DENOTE MISSING/UNREPORTED DATA. # INDICATES A STATION OR INSTRUMENT RELOCATION. SEE STATION LOCATION TABLE ON PAGE 8. SPECIFIC PAGE 2 PM - INCLUDES LAST DAY OF PREVIOUS MONTH ASOS - AUTOMATED SURFACE OBSERVING SYSTEM IN OPERATION DURING THESE MONTHS.	EXCEPTIONS PAGES 4A, 4B, 6A Record means are through the current year, Beginning in 1891 for temperature 1891 for precipitation 1939 for Snowfall
PAGE 3 1a1 - LENGTH OF RECORD IN YEARS, ALTHOUGH INDIVIDUAL MONTHS MAY BE MISSING. 0.* OR * - THE VALUE IS BETWEEN 0.0 AND 0.05 NORMALS - BASED ON THE 1951-1980 RECORD PERIOD. EXTREMES - DATES ARE THE MOST RECENT DCCURRENCE HIND DIR NUMERALS SHOK TENS OF DEGRESS CLOCKHISE FROM TRUE NORTH CO- INDICATES CALM. RESULTANT DIRECTIONS ARE GIVEN TO WHOLE DEGREES. BOLD VALUES INDICATE EXTREME VALUES WHICH OCCURRED AFTER THE ASOS SYSTEM HAS COMMISSIONED.	
PAGE 4B RECORD HEAN PRECIPITATION IS THE MEAN OF ALL DAILY PRECIPITATION AMOUNTS DURING THE PERIOD OF RECORD. RECORD MAX(MIN) TEMPERATURE IS THE MEAN OF ALL DAILY MAX(MIN) TEMPERATURES DURING THE PERIOD OF RECORD. RECORD MEAN TEMPERATURE IS THE SUM OF THE RECORD MAX AND RECORD HIN DIVIDED BY 2. AVERAGE TEMPERATURE IS THE SUM OF THE MEAN DAILY MAX AND HIN TEMPERATURE DIVIDED BY 2.	

Page 6B

MINNEAPOLIS - ST. PAUL, MINNESOTA

The Twin Cities of Minneapolis and St. Faul are located at the confluence of the Mississippi and Minnesota Rivers over the heart of an artesian water basin. Its flat or gently rolling terrain varies little in elevation from that of the official observation station at International Airport. Numerous lakes dot the surrounding area. Minneapolis alone boasts of 22 lakes within the city park system. The largest body of water, nearly 15,000 acres, is Lake Minnetonka, located about 15 miles west of the airport. Most bodies of water are relatively small and shallow and are ice covered during winter.

The climate of the Minneapolis-St. Paul area is predominantly continental. Seasonal temperature variations are quite large. Temperatures range from less than -30 degrees to over 100 degrees. The growing season is 166 days. Because of this favorable growing season, all crops generally mature before the autumn freeze occurs.

The Twin Cities lie near the northern edge of the influx of moisture from the Gulf of Mexico. Severe storms such as blizzards, freezing rain (glaze), tornadoes, wind and hail storms do occur. The total annual precipitation is important. Even more significant is its proper distribution during the growing season. During the five month growing season. May through September. the major crops produced are corn, soybeans, small grains, and hay. During this period, the normal rainfall is over 16 inches, approximately 65 percent of the annual precipitation. Winter snowfall is nearly 48 inches. Winter recreational weather is excellent because of the dry snow. These conditions exist from about Christmas into early March. Snow depths average 6 to 8 inches in the city and 8 to 10 inches in the suburbs during this period.

Floods occur along the Mississippi River due to spring snow melt, excessive rainfall, or both. Occasionally an ice jam forms and creates a local flood condition. The flood problem at St. Paul is complicated because the Minnesota River empties into the Mississippi River between the two cities. Consequently, high water or flooding on the Minnesota River creates a greater flood potential at St. Paul. Flood stage at St. Paul can be expected on the average once in every eight years.

STATION LOCATION

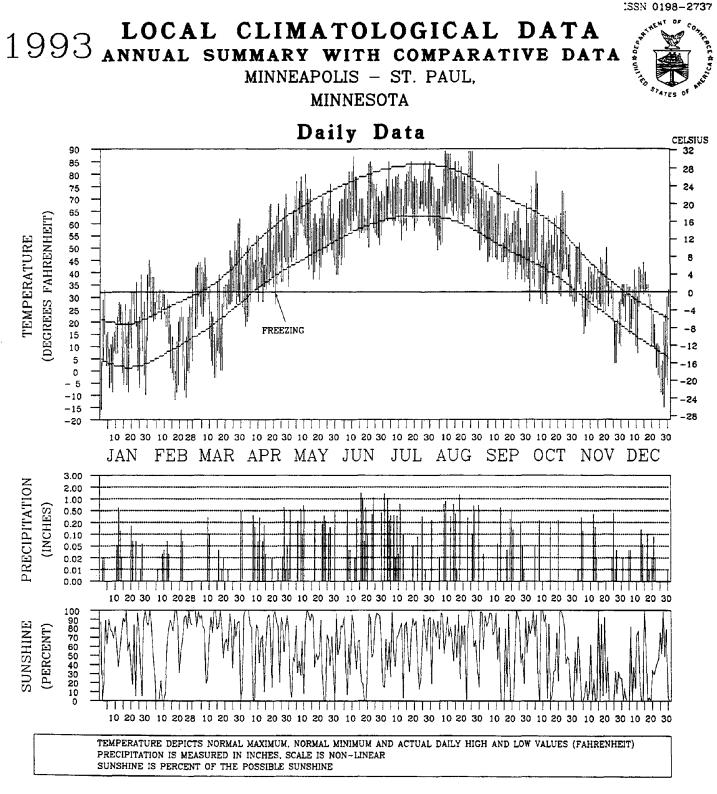
MINNEAPOLIS-ST.	PAUL,	MINNESOTA
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															MIN	NEAPOLIS-ST. PAUL, MINNESOTA
				L	b	L		ELEV		DN AL					A U T	* <u>Type</u>
				A T 1		SEA LEVEL			(ROU					Ó	M = AMOS I = AUTOB
LOCATION	OCCUPIED FROM	OCCUPIED	AIRLINE DISTANCES AND DIRECTIONS FROM PREVIOUS LOCATION	1 U D E	Î U D E WEST	GROUND TEMPERATURE	JHZO HZOHRUZWZHO	МХНЧПЗОЗУЛНН ПЗПУНУ	₽ SYU#ROMEHER	NSHINE S	TIPPING BUCKET	WHIGHING RAIN GAGE	8 INCH RAIN GAGE	HY GROT TEREONETER	MGDHAMMENH * Mahhu omsmerenng	S = ASOS W = Anos Remarks
COOPERATIVE																
Dr. C.L. Anderson Corner Helen & 2nd St.		12/31/59		44°59'	93°181	839										Surgeon General & Smithsonian Institute to 1870.
Mr. Wm. Cheney, Corner Douglas & Freemonet St.	11/01/64	6/30/01		44°58'	93°20'	850										
Mr. J.H. Aschenbeck 721 6th Avenue North	11/25/87	10/?/95		45°00'	93°19'	850		18					3			
Mr. J.H. Aschenbeck 731 6th Avenue North	10/?/95	9/?/23	2 blocks	45°00'	93°19'	825		4					3			Thermometers 99', RG 95' to 11/1/04; anemometer 192' to 4/96.
Mr. J.H. Aschenbeck 1730 Penn. Avenue N.	9/?/23	10/?/36	1.5 mi. NW	45°01'	93°21'	888		4					3			Precipitation only after 2/23/29. Temperature obs. 7A, 2P and 9P.
CITY	1															
U.S. Court House, cor. Marquette Ave. & 3rd St	11/06/90	4/10/38		44°59'	93°18'	839	105	105	104		97		96			
<u>AIRPORT</u> Administration Bldg. Wold-Chamberlain AP	1/27/34	10/16/37		44°53'	93°13 ا خ	832	61	32					1			
Administration Bldg. Minneapolis-St. Paul International Airport Wold-Chamberlain Field	10/16/37	Present	NA	44°53'	93°13'	æ34	2123	f43	f42	*5 0	e41	<u>9</u> 41	e41	6 55		Several minor moves of instru- ments but no significant changes in elevations other than given below. St. Paul WBAS was integrated with Minneapolis WBAS 6/1/53. a - Ground elevation 830 to 1/1/60 & 822! to 5/24/63. b - 75' to 9/18/58. c - Installed 11/20/53. Eleva- tion 41' to 10/24/62. d - Commissioned on field site 1/1/60; moved 800' WNW 5/31/63. fter 10/24/62. f - Standby after 10/24/62. f - Standby after 10/24/62. f - Standby after 10/24/62. f - Standby after 10/24/62. f - Raised 10/17/81. i - Effective 11/5/64. j - Type change 12/11/85.
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NATIONAL

NATIONAL ENVIRONMENTAL SATELLITE, DATA AND INFORMATION SERVICE

NATIONAL CLIMATIC DATA CENTER ASHEVILLE NORTH CAROLINA

el D Wadeen

DIRECTOR National climatic data center

METEOROLOGICAL DATA FOR 1993

MINNEAPOLIS - ST. PAUL, MINNESOTA 860 TIME ZONE: CENTRAL WBAN: 14922 LATITUDE: 44 °53' N LONGITUDE: 93 °13' W ELEVATION: FT. GRND 834 BARO JAN | FEB | MAR | APR | MAY | JUNE | JULY | AUG | SEP | OCT | NOV | DEC YEAR TEMPERATURE OF: Averages -Daily Maximum 79.6 61.2 70.4 61.4 56.6 36.3 46.5 34.6 52.2 34.8 43.5 34.4 38.6 20.3 29.5 21.1 54.5 33.9 44.2 29.4 66.3 48.1 57.2 45.4 73.6 55.4 64.5 54.0 78.1 62.5 70.3 64.3 45.6 55.0 45.9 37.6 23.6 28.8 15.5 22.2 23.6 5.5 14.6 9.5 24.4 9.9 17.2 -Daily Minimum -Monthly -Monthly Dewpt. 30.6 11.0 16 0 61.0 Extremes 52 3 3 27 89 84 12 44 45 42 62 29 72 80 87 85 89 81 -Highest -Date AUG 26 15 28 18 2 6 26 31 31 -16 11 37 11 30 26 49 -12 17 -3 14 39 53 12 36 -16 -Lowest 28 JAN 1 20 1 31 1 -Date DEGREE DAYS BASE 65 °F: 302 1025 1322 8154 1557 1335 1096 617 243 70 3 18 566 Heating 0 451 Cooling 0 Û 0 Û 12 60 176 195 8 0 0 71 60 57 24 33 58 60 72 70 52 58 60 % OF POSSIBLE SUNSHINE 65 AVG. SKY COVER [tenths] 6.4 6.0 7.0 6.3 Sunrise - Sunset Midnight - Midnight NUMBER OF DAYS: 6.5 6.4 7.1 6.4 6.5 5.6 6.3 5.9 5.9 5.7 8.3 7.8 7.5 7.9 6.7 6.4 6.3 5.3 5.3 7.6 Sunrise to Sunset 80 5 5 8 35 55 -Clear -Partly Cloudy 8 7 14 7 3 11 8 15 10 9 14 q 96 10 6 15 13 2ž 17 12 13 21 189 13 13 19 16 -Cloudy Precipitation 7 15 10 4 10 11 127 .01 inches or more 11 8 14 12 13 12 Snow.Ice pellets.hail 10 1.0 inches or more 3 1 3 0 0 0 0 0 0 0 2 1 9 3 35 Ο 0 1 0 2 9 9 1 1 ٥ Thunderstorms Heavy Fog, visibility 1/4 mile or less 0 3 3 0 1 0 1 Ω Û Û 0 0 8 Temperature ^oF -Maximum 90° ani 0 77 0 22 0 0 0 0 07 0 15 90° and above 32° and below 0 7 0 0 0 0 26 õ Ō Ō Õ Õ Ō -Minimum 32 and 32⁰ and below 0⁰ and below 28 30 9 0 0 Û 0 0 11 25 30 163 30 32 ĩž 4 Ō Õ Õ Ō Ō ñ ۵ ñ 7 983.1 991.5 991.5 989.2 984.1 983.7 983.1 985.4 985.4 985.6 986.1 985.6 986.1 AVG. STATION PRESS. (mb) RELATIVE HUMIDITY (%) 86 91 72 79 77 79 79 78 Hour 00 80 79 82 81 66 79 83 61 62 Hour 06 (Local Time) 81 71 85 69 71 81 87 81 72 83 83 86 55 57 63 64 49 66 64 60 61 60 66 71 Hour 18 76 64 46 57 64 62 63 76 PRECIPITATION (inches): Water Equivalent 5.58 1.44 6.50 1.65 8- 9 2.04 0.84 19-20 0.79 0.26 20 0.55 0.20 13-14 0.39 0.19 21-22 6.28 1.94 16-17 32.21 1.94 JUN 16-17 1.25 . 25 1.99 4.02 1.57 -Totaľ 0.50 0.83 0.57 -Greatest (24 hrs) 0.64 0.66 26-27 -Date Snow,Ice pellets,hail -Total 12.0 6.2 12 5.3 2.7 21-22 6.9 4.0 0.0 4.5 36.9 0.5 0.0 0.0 0.0 7.7 T T -Greatest (24 hrs) 0.5 14-15 0.0 0.0 Ť 0.0 4.6 6.2 JAN 12 21-22 9-10 1 30 -Date WIND: Resultant -Direction (!!) 287 1.7 7.6 022 2.7 10.9 255 2.9 10.8 277 4.7 11.3 266 2.4 10.7 219 249 253 321 347 153 190 266 -Speed (mph) Average Speed (mph) Fastest Obs. 1 Min. -Direction (!!) 1.6 9.6 1.8 1.1 11.8 1.3 1.8 2.5 1.2 8.9 31 26 28 32 29 16 25 17 17 32 29 16 22 30 7 18 30 30 32 31 31 05 30 16 26 8 33 38 33 30 33 38 28 -Speed (mph) -Date 19 18 2Õ 19 29 AUG 18 Peak Gust -Direction (!!) -Speed (mph) NW 43 W Ν NW Ν NW NW SW NW NW N₩ NW S 48 15 44 52 AUG 18 39 25 21 41 **3**7 44 52 18 41 44 40

> (!!) See Reference Notes on Page 68 Page 2

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-Date

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NORMALS, MEANS, AND EXTREMES

MINNEAPOLIS - ST. PAUL, MINNESOTA

MINNEAPOLIS - SI. PAOL, MINNESOTA LATITUDE: 44 °53'N LONGITUDE: 93 °13'W ELEVATION: FT, GRND 834 BARO, 860, TIME ZONE: CENTRAL, WBAN: 14922														
LATITUDE: 44 53'N L	ONGI (a)		93 °13, FEΒ	MAR	APR	MAY		34 BARU JULY	are Ang	SEP	OCT	NOV	DEC	YEAR
TEMPERATURE PF:														
Normals -Daily Maximum -Daily Minimum -Monthly		20.7 2.8 11.8	26.6 9.2 17.9	39.2 22.7 31.0	56.5 36.2 46.4	69,4 47,6 58,5	78.8 57.6 68.2	84.0 63.1 73.6	80.7 60.3 70.5	70.7 50.3 60.5	58.8 38.8 48.8	41.0 25.2 33.2	25.5 10.2 17.9	54.3 35.3 44.9
Extremes -Record Highest -Year -Record Lomest -Year	55 55	58 1944 -34 1970	60 1981 -28 1965	83 1986 -32 1962	95 1980 2 1962	96 1978 18 1967	102 1985 34 1945	105 1988 43 1972	102 1947 39 1967	98 1976 26 1974	89 1953 15 1972	75 1944 -17 1964	63 1982 -29 1983	105 JUL 1988 -34 JAN 1970
NORMAL DEGREE DAYS: Heating (base 65°F)		1649	1319	1054	558	244	41	11	22	167	502	954	1460	7981
Cooling (base 65°F)		0	0	0	0	43	137	278	192	32	0	0	0	682
% OF POSSIBLE SUNSHINE	55	53	59	57	58	61	. 65	72	69	62	55	39	42	58
MEAN SKY COVER (tenths) Sunrise - Sunset MEAN NUMBER OF DAYS:	55	6.3	6.3	6.7	6.5	6.4	6.1	5.3	5.3	5.6	5.8	7.1	7.0	6.2
Sunrise to Sunset -Clear -Partly Cloudy -Cloudy Precipitation	55 55 55	8.3 7.4 15.3	7.7 6.9 13.7	7.1 7.3 16.6	7.0 7.7 15.2	7.1 9.1 14.8	7.2 10.4 12.3	9.9 11.8 9.3	10.2 11.1 9.7	9.8 8.6 11.6	9,9 7.6 13.5	5.5 6.5 .18.0	6.4 6.4 18.2	96.1 100.8 168.3
.01 inches or more Snow,Ice pellets,hail	55	8,7	7.3	10.3	10,3	11.3	11.7	9.8	10.0	9.6	7.9	8.5	9.4	114.7
1.0 inches or more	55	3.2	2.7	3.0	0.7	0.1	0.0	0.0	0.0	0.*	0.1	2.2	3.1	15.1
Ihunderstorms Heavy Fog Visibility	55	0.*	0.2	1.0	2.6	5.1	7.5	7.6	6.5	4.3	1.8	0.6	0.1.	37.4
1/4 mile or less Temperature F	55	1.1	1.4	1.3	0.4	0.5	0.5	0.3	0.6	0.9	0.9	1.1	1.3	10.5
-Maximum 90° and above 32° and below -Minimum	34 34	0.0 23.4	0.0 17.9	0.0 8.7	0.1 0.3	0.8 0.0	2.7 0.0	6.1 0.0	3.6 0.0	0.8 0.0	0.0 0.1	0.0 7.0	0.0 21.2	14.2 78.5
32° and below 0° and below	34 34	30.8 13.5	27.3 8.1	25.2 1,9	11.0 0.0	1.1 0.0	0.0	0.0 0.0	0.0	0.5 0.0	7.8 0.0	23.0 0.7	29.9 8.0	156.4 32.3
AVG. STATION PRESS. (mb)	21	987.5	988.3	985.2	984.2	983.6	983.0	984.7	985.6	986.0	986.3	985.9	987.4	985.6
RELATIVE HUMIDIIY (%) Hour 00 Hour 06 (Local Time) Hour 18	34 34 34 34	73 74 67 68	74 76 65 66	72 76 61 61	67 75 52 51	68 76 52 50	72 79 54 52	75 81 54 53	77 84 57 56	79 85 59 61	74 81 58 60	77 80 66 69	76 78 70 73	74 79 60 60
PRECIPITATION (inches): Water Equivalent -Normal -Maximum Monthly -Year -Minimum Monthly -Year -Maximum in 24 hrs -Year	55 55 55	0.95 3.63 1967 0.10 1990 1.21 1967	0.88 2.14 1981 0.06 1964 1.10 1966	1.94 4.75 1965 0.32 1958 1.66 1965	2.42 5.88 1986 0.16 1987 2.23 1975	3.39 8.03 1962 0.61 1967 3.03 1965	4.05 9.82 1990 0.22 1988 3.00 1986	3.53 17.90 1987 0.58 1975 10.00 1987	3.62 9.31 1977 0.43 1946 7.36 1977	2.72 7.53 1942 0.41 1940 3.55 1942	2.19 5.68 1971 0.01 1952 2.95 1966	1.55 5.29 1991 0.02 1939 2.91 1940	1.08 4.27 1982 T 1943 2.47 1982	28.32 17.90 JUL 1987 T DEC 1943 10.00 JUL 1987
Snow,Ice pellets,hail -Maximum Monthly -Year -Maximum in 24 hrs -Year	55 55	46.4 1982 18.5 1982	26.5 1962 9.3 1939	40.0 1951 14.7 1985	21.8 1983 13.6 1983	3.0 1946 3.0 1946	T 1989 T 1989	T 1993 T 1993	T 1992 1992 1992	1.7 1942 1.7 1942	8.2 1991 8.2 1991	46,9 1991 21.0 1991	33.2 1969 16.5 1982	46.9 NOV 1991 21.0 NOV 1991
WIND: Mean Speed (mph)	55	10.5	10.4	11.3	12.2	11,1	10,5	9.4	9.3	10.0	10.5	10.9	10.4	10.5
Prevailing Direction through 1963		NW	NW	NW	NW	SE	SE	S	SE	S	SE	NW	NW	NW
Fastest Obs. 1 Min. -Direction (!!) -Speed (MPH) -Year	14 14	32 51 1986	34 37 1987	08 33 1985	19 41 1984	23 35 1986	01 46 1980	35 43 1980	20 44 1983	18 36 1988	33 33 1981	25 41 1986	34 35 1989	32 51 JAN 1986
Peak Gust -Direction (!!) -Speed (mph) -Date	10 10	NW 67 1986	NW 55 1987	W 60 1988	SW 61 1984	N 67 1985	S 51 1992	NW 51 1984	W 71 1988	N 52 1989	NW 53 1987	W 66 1986	NW 48 1989	W 71 AUG 1988

(!!) See Reference Notes on Page 68. Page 3 PRECIPITATION (inches)

MINNEAPOLIS - ST. PAUL, MINNESOTA

YEAR	JAN	FEB	MAR	APR	MAY	JUNE	JULY	AUG	SEP	OCT	NOV	DEC	ANNUAL
1964	0.47	0.05	1,35	2.98	3.44	2.18	2.02	5.42	5.21	0.57	1.19	1.08	25.97
1965	0.47	1.59	4,75	3.52	7.86	4.01	4.69	4.04	4.90	0.90	1.98	1.23	39.94
1966	0.95	1.55	2,48	0.89	1.46	3.51	2.47	4.40	1.69	3.53	0.39	1.02	24.34
1967	3.63	1.59	0,96	4.07	0.61	7.53	1.36	2.79	0.63	1.73	0.09	0.45	25.44
1968	0.71	0.13	1,89	2.94	3.74	6.78	6.46	0.75	6.16	5.62	0.54	2.21	37.93
1969	2.05	0.31	0.90	1.55	1.98	2,93	2.95	0.99	0.49	2.53	0.65	2.06	19.39
1970	0.47	0.16	2.05	3.55	4.77	1,27	3.66	2.19	3.19	4.97	3.82	0.43	30.53
1971	1.22	1.74	1.21	1.11	3.14	3,52	3.94	1.78	2.73	5.68	2.67	0.70	29.44
1972	0.84	0.49	1.25	1.69	2.18	3,31	5.12	2.48	1.96	1.77	1.11	1.57	23.77
1973	0.92	0.84	1.12	2.32	2.48	1,06	2.90	3.05	2.08	1.29	1.97	1.10	21.13
1974	0.17	1.05	1.00	2.42	2.08	5.21	1.14	2.75	0.58	1.69	0.66	0.35	19.11
1975	2.82	0.79	1.67	5.40	3.81	7.99	0.58	4.92	1.31	0.27	4.80	0.79	35.15
1976	0.87	0.59	2.83	0.80	1.13	3.86	2.45	1.39	1.42	0.49	0.16	0.51	16.50
1977	0.65	0.93	2.66	1.84	2.86	3.57	3.72	9.31	4.43	2.34	1.42	1.15	34.88
1978	0.38	0.24	0.79	3.63	3.79	7.09	3.19	5.77	2.47	0.19	1.84	0.88	30.26
1979	1.09	1.39	2.55	0.66	4.55	4.78	2.34	7.04	2.20	3.16	0.98	0,33	31.07
1980	0.94	0.67	1.12	0.83	2.29	5.52	2.30	3.26	3.68	0.66	0.26	0,24	21.77
1981	0.30	2.14	0.71	2.17	2.18	4.42	4.09	4.73	1.46	2.69	2.16	0,92	27.97
1982	2.45	0.43	2.09	1.62	4.99	1.44	0.92	3.80	1.50	3.45	3.27	4,27	30.23
1983	0.67	1.19	3.22	3.97	6.20	5.22	3.07	3.12	3.34	2.61	4.93	1, 5 3	39.07
1984	0.88	1.64	1.47	3.86	2.29	7.95	3.03	5.15	2,65	5.48	0.31	2.24	36.95
1985	0.87	0.50	4.48	1.81	3.65	2.18	2.20	5.02	4,37	3.66	1.72	1.20	31.66
1986	0.90	0.84	2.03	5.88	3.48	5.34	4.11	4.44	6,90	1.77	0.62	0.31	36.62
1987	0.63	0.13	0.64	0.16	1.88	1.95	17.90	3.67	1,28	0.60	2.07	1.25	32.16
1988	1.37	0.30	1.33	1.58	1.70	0.22	1.17	4.29	2,79	0.80	2.86	0.67	19.08
1989	0.52	1.04	2.19	2.66	3.38	3.50	3.50	2.92	1.28	0.53	1.38	0.42	23.32
1990	0.10	0.77	3.66	3.80	3.36	9.82	5.06	1.71	1.88	1.23	0.65	1.01	33.05
1991	0.49	1.03	2.29	3.58	6.35	2.57	2.95	3.14	5.43	2.52	5.29	1.05	36.69
1992	0.66	0.57	1.56	1.99	1.15	3.68	5.21	4.54	5.20	2.11	1.95	1.05	29.67
1993	1.25	0.39	1.25	1.99	4.02	6.28	5.58	6.50	2.04	0.79	1.57	0.55	32.21
Record Mean	0,83	0.85	1.60	2.17 Se	3.38 e Refer		3.55 tes on a 4A	3.40 Page 68	2,89	2.01	1.45	0.94	27.26

AVERAGE TEMPERATURE (deg. F)

MINNEAPOLIS - ST. PAUL, MINNESOTA

YEAR	JAN	FEB	MAR	APR	MAY	JUNE	JULY	AUG	SEP	OCT	NOV	DEC	ANNUAL
1964	20.0	23.9	25.8	46.8	61.5	68.7	76.0	68.5	58.9	48.2	35.0	14.8	45.7
1965	10.0	11.8	19.5	41.8	58.7	66.5	70.5	68.6	52.8	50.7	33.1	28.0	42.7
1966	3.3	16.3	35.8	42.2	53.6	68.4	76.8	68.2	60.3	47.5	30.1	18.1	43.4
1967	14.6	8.7	29.8	44.7	52.3	66.9	68.8	66.2	60.3	46.3	30.7	21.8	42.6
1968	14.3	15.2	38.8	48.5	53.4	67.2	71.1	70.7	61.1	50.7	34.0	16.9	45.2
1969 1970 1971 1972 1973	9.4 5.6 5.5 17.4	19.3 15.4 17.0 10.5 21.6	24.1 26.0 28.0 26.5 40.2	49.3 46.1 47.0 41.9 44.4	60.6 58.5 55.4 61.3 55.2	61.8 71.2 71.5 66.0 69.5	73.6 75.2 68.8 68.5 73.8	74.4 71.9 69.6 69.8 73.4	63.0 61.2 62.8 57.9 60.1	46.5 49.6 51.4 43.7 53.8	33.6 32.7 32.7 32.2 34.3	20.3 18.2 18.4 11.3 16.7	44.7 44.3 44.1 41.3 46.7
1974	11.9	16.9	29.5	47.1	54.4	65.5	76.6	67.3	55.3	49.8	33.7	24.4	44.4
1975	14.5	15.5	22.1	38.9	60.9	68.8	76.3	71.7	57.7	52.8	37.5	21.3	44.8
1976	11.6	27.8	31.4	51.8	58.9	71.7	76.1	73.3	61.8	44.6	28.3	13.6	45.9
1977	0.3	22.7	37.5	53.0	65.9	68.4	74.8	66.1	60.5	47.1	30.8	14.4	45.2
1978	5.5	11.6	30.0	45.2	61.8	67.8	71.1	72.2	67.3	49.8	32.5	15.2	44.2
1979	3.2	10.0	28.9	44.0	55.5	67.3	73.6	69.9	63.4	46.6	31.7	26.0	43.3
1980	15.3	15.3	27.3	49.2	61.5	67.6	75.2	70.7	59.5	45.1	36.6	19.8	45.2
1981	18.0	23.4	37.7	49.1	57.1	67.0	70.9	69.3	60.0	46.7	38.0	17.5	46.2
1982	2.3	15.8	29.0	43.8	62.5	63.7	75.6	71.8	60.9	50.3	31.5	25.7	44.4
1983	19.6	26.9	34.2	42.3	54.6	68.0	77.2	76.8	62.6	48.4	34.0	3.7	45.7
1984	12.0	27.5	24.8	47.1	56.0	69.7	72.2	73.5	57.2	50.7	33.3	17.9	45.2
1985	10.1	16.5	35.6	52.1	62.2	63.9	73.9	67.6	59.9	47,5	24.8	7.7	43.5
1986	17.5	15.7	33.9	49.6	59.4	68.6	73.9	67.1	59.8	49.2	28.2	24.7	45.6
1987	21.2	31.6	38.7	53.5	63.5	72.8	76.0	69.0	62.5	44.6	37.9	25.0	49.7
1988	10.4	13.9	33.8	47.4	65.4	74.4	78.1	73.9	62.4	44.0	32.7	20.5	46.4
1989	21.2	8.6	26.6	45.3	57.5	68.4	76.4	70.8	60.9	49.9	28.0	10.6	43.7
1990	26.3	23.7	35.7	46.8	56.3	69.5	71.3	70.6	64.4	48.1	37.4	16.9	47.3
1991	12.5	24.4	34.3	49.1	61.9	72.9	72.3	71.1	59.0	47.2	24.5	21.2	45.9
1992	21.9	28.0	33.1	43.6	60.5	65.6	65.8	65.9	59.6	47.4	31.4	21.2	45.3
1993	14.6	17.2	29.5	44.2	57.2	64.5	70.3	70.4	55.0	46.5	30.6	22.2	43.5
Record Mean Max Min	13.2 21.8 4.6	17.3 25.9 8.6	30.1 38.4 21.8	46.0 55.8 36.3 Se	58.3 68.5 48.0 e Refer	67.9 77.8 58.0 ence No	73.2 83.2 63.1 tes on # 48	70.6 80.5 60.7 Page 68	61.4 71.3 51.5	49.5 59.0 40.1	32.8 40.4 25.2	19.2 26.7 11.7	45.0 54.1 35.8

					-								
SEASON	JULY	AUG	SEP	OCT	NOV	DEC	JAN	FEB	MAR	APR	MAY	JUNE	TOTAL
1964-65 1965-66 1966-67 1967-68 1968-69	0 7 0 36 10	63 40 40 65 28	224 368 185 166 143	515 447 536 577 451	894 950 1042 1024 922	1551 1140 1446 1335 1486	1702 1909 1556 1567 1723	1485 1358 1572 1440 1274	1405 899 1086 808 1261	690 678 600 491 461	211 357 404 358 204	19 41 30 62 136	8760 8194 8497 7929 8099
1969-70 1970-71 1971-72 1972-73 1973-74	53 164 34	010 010 010 010	131 190 164 218 185	580 476 413 651 350	933 959 962 974 915	1379 1443 1438 1664 1493	1842 1811 1844 1474 1642	1382 1341 1576 1208 1344	1204 1139 1188 761 1092	577 537 687 611 535	249 297 204 299 338	20 18 73 13 72	8302 8219 8587 7959 7970
1974-75 1975-76 1976-77 1977-78 1978-79	000 t	48 7 4 35 7	289 231 162 145 89	467 387 632 548 464	933 818 1092 1016 968	1252 1346 1590 1565 1538	1561 1650 2005 1842 1914	1379 1074 1180 1488 1537	1324 1031 844 1080 1112	775 405 365 584 623	188 195 75 162 307	39 11 17 46 38	8255 7170 7966 8511 8602
1979-80 1980-81 1981-82 1982-83 1983-84	00011102	24 12 11 14 0	105 194 172 168 161	566 611 564 448 514	992 845 803 997 923	1203 1396 1466 1212 1901	1536 1453 1945 1400 1641	1436 1160 1374 1061 1082	1165 838 1111 947 1240	484 472 629 673 531	184 249 117 313 284	34 28 71 49 7	7729 7258 8274 7282 8286
1984-85 1985-86 1986-87 1987-88 1988-89	50021	12 28 43 29 16	251 240 177 106 116	435 537 483 623 646	943 1201 1096 804 963	1453 1774 1243 1236 1373	1694 1466 1352 1688 1353	1355 1377 929 1479 1576	904 957 809 962 1184	403 454 347 523 583	123 212 134 76 251	104 30 13 4 44	7682 8276 6623 7532 8106
1989-90 1990-91 1991-92 1992-93 1993-94	002703 807 803	សមាលល ភ្លេង 1	159 136 228 182 302	470 516 548 542 566	1105 820 1206 1003 1025	1683 1484 1354 1351 1322	1194 1624 1333 1557	1151 1130 1067 1335	899 945 981 1096	569 481 636 617	274 197 190 243	37 3 72 70	7547 7343 7630 8080
	I I	I	1	1	1	1	1	I	L	1	1	1	1

See Reference Notes on Page 68. Page 5A

COOLING DEGREE DAYS Base 65 deg. F MINNEAPOLIS - ST. PAUL, MINNESOTA

YEAR	JAN	FEB	MAR	APR	MAY	JUNE	JULY	AUG	SEP	ост	NOV	DEC	TOTAL
1969 1970 1971 1972 1973	00000	00000	00000	0 17 2 0 1	76 54 54 94	49 213 218 109 158	276 323 141 148 280	298 225 168 208 271	77 83 106 13 47	12 5 30 8	00000	00000	788 920 643 572 769
1974 1975 1976 1977 1977	00000	00000	00000	5 0 14 12 0	18 66 14 145 72	93 159 223 129 138	369 371 351 310 201	127 220 269 76 236	6 18 72 19 164	1 16 7 0 0	00000	00000	619 850 950 691 811
1979 1980 1981 1982 1983	00000	00000	00000	0 16 00 0	17 82 10 46 0	113 121 96 40 145	275 322 200 338 389	181 194 151 232 368	65 38 28 53 98	0 1 0 8	00000	00000	651 774 485 709 1008
1984 1985 1986 1987 1988	00000	00000	00000	0 22 1 11 1	1335 4455 99	155 77 148 253 296	237 284 286 348 412	280 118 115 159 302	24 93 32 37 45	00000	00000	00000	709 637 627 903 1152
1989 1990 1991 1992 1993	00000	00000	00000	0 28 8 3 0	26 11 109 56 12	153 178 246 96 60	359 206 238 64 176	192 191 205 88 195	41 125 51 28 8	8 1 0 N O	00000	00000	779 740 857 337 451

See Reference Notes on Page 68. Page 58

SNOWFALL (inches)

MINNEAPOLIS - ST. PAUL, MINNESOTA

SEASON	JULY	AUG	SEP	OCT	NOV	DEC	JAN	FEB	MAR	APR	MAY		TOTAL
1964-65 1965-66 1965-67 1967-68 1968-69	0.0 0.0 0.0 0.0		0.0 0.0 0.0 0.0	0.0 0.2 T	4.3 1.6 3.8 0.9	8,1 1,2 12,7 2,4 28,7	10.5 11.9 35.3 10.6 21.6	11.7 6.8 23.7 2.2 5.3	37.1 14.2 2.6 0.8 7.3	04 N 4 0 N 0 0 0 0	T 0.3 0.0	0.0 0.0 0.0 0.0	73.7 36.1 78.4 17.5 68.1
1969-70 1970-71 1971-72 1972-73 1973-74	0.0 0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 T 0.0	2.4 T 0.0 T 0.0	3,8 6,3 13,2 1,1 0,1	33,2 5,5 12,8 15,3 17,9	9.8 19.9 12.2 11.6 2.5	4.3 13.9 7.6 11.3 15.7	8.6 7.0 10.4 0.4 7.7	1.3 1.9 8.0 2.0 7.3	T 0.2 0.0 0.0	0.0 0.0 0.0 0.0	63.4 54.7 64.2 41.7 51.2
1974-75 1975-76 1976-77 1977-78 1978-79	0.0 0.0 0.0 0.0 0.0	0,0 0,0 0,0 0,0	0.0 0.0 0.0 0.0 0.0	0.0 2.3 3.0	1.2 16.2 1.4 11.7 16.5	6.1 5.6 8.3 14.2 15.1	27.4 12.8 13.4 6.8 14.2	9.0 5.1 1.8 4.6 13.5	18.3 13.6 14.6 8.5 8.4	2,2 0,0 1,8 1,9 0,7	0.0 1.2 0.0 0.0	0.0 0.0 0.0 0.0 0.0	64.2 54.5 43.6 50.7 68.4
1979-80 1980-81 1981-82 1982-83 1983-84	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0	T 0.9 1.4 T	7,7 0,9 14,0 3,6 30,4	1.7 2.8 10.6 19.3 21.0	12.9 4.6 46.4 3.2 10.6	8.8 11.0 7.4 10.8 9.3	13.7 0.1 10.9 14.3 17.3	8.5 1.7 4.8 21.8 9.8		0.0 0.0 0.0 0.0	53.3 21.1 95.0 74.4 98.4
1984-85 1985-86 1986-87 1987-88 1988-89	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.4 0.0 0.0 0.0	0.3 T 0.3 0.2	2.0 23.9 4.4 4.5 15.8	16.3 13.5 4.2 7.5 7.2	13.1 10.5 5.5 19.0	4.2 12.3 1.2 4.5 17.3	36.8 8.7 2.1 3.7 22.7	T 0.4 T 2.4 C.8	0.0. 0.0 0.0 0.1	0.0 0.0 0.0 0.0 T	72.7 69.5 17.4 42.4 70.1
1989-90 1990-91 1991-92 1992-93 1993-94	0.0 0.0 0.0 0.0	0.0 0.0 T T 0.0	0.0 0.0 0.0 T 0.0	0.0 T 8.2 1.3 T	11.3 5.0 46.9 12.2 7.7	7.0 11.7 6.7 9.2 4.5	1.1 6.5 5.0 12.0	10.7 14.2 5.9 5.3	3.2 4.4 10.8 6.9	2.2 1.5 0.5	0.0 0.3 0.0	0.0 0.0 0.0	35.5 43.6 84.1 47.4
Record Mean	т	т	т	0.5 See	7.9 Refere	9.3 nce Not	9.8 es on P	8.4 age 6B.	10.7	2.8	0.1	Т	49.6

Page 6A

REFERENCE NOTES

MINNEAPOLIS - ST. PAUL, MINNESOTA

 INDICATES A STATION OR INSTRUMENT RELOCATION. SEE STATION LOCATION TABLE ON PAGE 8. SPECIFIC PAGE 2 PM - INCLUDES LAST DAY OF PREVIOUS MONTH ASOS - AUTOMATED SURFACE OBSERVING SYSTEM IN 	EXCEPTIONS PAGES 4A, 4B, 6A RECORD MEANS ARE THROUGH THE CURRENT YEAR. BEGINNING IN 1891 FOR TEMPERATURE 1891 FOR PRECIPITATION 1939 FOR SNOWFALL
OPERATION DURING THESE MONTHS. PAGE 3 (a) - LENGTH OF RECORD IN YEARS, ALTHOUGH INDIVIDUAL MONTHS MAY BE MISSING. 0.* OR * - THE VALUE IS BETHEEN 0.0 AND 0.05 NORMALS - BASED ON THE 1961-1990 RECORD PERIOD. EXTREMES - DATES ARE THE MOST RECENT DECURRENCE HIND DIR NUMERALS SHOH TENS OF DEGRESS CLOCKHISE FROM TRUE NORTH. "OC" INDICATES CALM. RESULTANT DIRECTIONS ARE GIVEN TO WHOLE DEGREES.	
BOLD VALUES INDICATE EXTREME VALUES WHICH OCCURRED AFTER THE ASOS SYSTEM WAS COMMISSIONED. PAGE 48 RECORD = PERIOD OF RECORD RECORD MEAN PRECIPITATION IS THE MEAN OF ALL DAILY PRECIPITATION AMDUNTS DURING THE PERIOD OF RECORD. RECORD MAXIMIN) TEMPERATURE IS THE MEAN OF ALL DAILY MAXIMIN) TEMPERATURES DURING THE PERIOD OF RECORD. RECORD MEAN TEMPERATURE IS THE SUM OF THE RECORD MAX AND RECORD MIN DIVIDED BY 2. AVERAGE TEMPERATURE IS THE SUM OF THE MEAN DAILY	
MAX AND MIN TEMPERATURE DIVIDED BY 2.	

Page 68

MINNEAPOLIS – ST. PAUL, MINNESOTA

The Twin Cities of Minneapolis and St. Paul are located at the confluence of the Mississippi and Minnesota Rivers over the heart of an artesian water basin. Its flat or gently rolling terrain varies little in elevation from that of the official observation station at International Airport. Numerous lakes dot the surrounding area. Minneapolis alone boasts of 22 lakes within the city park system. The largest body of water, nearly 15,000 acres, is Lake Minnetonka, located about 15 miles west of the airport. Most bodies of water are relatively small and shallow and are ice covered during winter.

The climate of the Minneapolis-St. Paul area is predominantly continental. Seasonal temperature variations are quite large. Temperatures range from less than -30 degrees to over 100 degrees The growing season is 166 days. Because of this favorable growing season, all crops generally mature before the autumn freeze occurs.

The Twin Cities lie near the northern edge of the influx of moisture from the Gulf of Mexico. Severe storms such as blizzards, freezing rain (glaze), tornadoes, wind and hail storms do occur. The total annual precipitation is important. Even more significant is its proper distribution during the growing season. During the five month growing season. May through September, the major crops produced are corn, soybeans, small grains, and hay. During this period, the normal rainfall is over 16 inches, approximately 65 percent of the annual precipitation. Winter snowfall is nearly 48 inches. Winter recreational weather is excellent because of the dry snow. These conditions exist from about Christmas into early March. Snow depths average 6 to 8 inches in the city and 8 to 10 inches in the suburbs during this period.

Floods occur along the Mississippi River due to spring snow melt, excessive rainfall, or both. Occasionally an ice jam forms and creates a local flood condition. The flood problem at St. Paul is complicated because the Minnesota River empties into the Mississippi River between the two cities. Consequently, high water or flooding on the Minnesota River creates a greater flood potential at St. Paul. Flood stage at St. Paul can be expected on the average once in every eight years.

Notice of Correction

Any previously received edition of the "Local Climatological Data Annual Summary for 1993" should be discarded. This revised edition contains updates to the "Normals" based upon the 1961-1990 record period as noted in the "Reference Notes" on Page 6B.

STATION LOCATION

MINNEAPOLIS-ST. PAUL, MINNESOTA

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				A T	Ö. N G	LEVEL			. (GROUN	Ð				Ť	N = AMOS T = AUTOB
LOCATION	OCCUPIED FROM	OCCUPIED	AIRLINE DISTANCES AND DIRECTIONS DIRECTIONS PREVIOUS LOCATION	τ υ Έ	U U D E WEST	GROUND TEMPERATURE	JHZO HROMORED	UXFRUEW FRUENCS	P MY CIEROEUHUR	SUZNEHZE NUMCE	RAIN GAGE	WEI-GHING RAIN GAGE	8 ⊢NCH RAHN GAGE	T	HOULAMENT *	
COOPERATIVE	1/01/54	12/71/60		44°59'	93°18'	839										Surgeon General & Smithsonian
Dr. C.L. Anderson Corner Helen & 2nd St.		12/31/59														Surgeon General & Smithsonian Institute to 1870.
Mr. Wm. Cheney, Corner Douglas & Freemonet St.	11/01/64	6/30/01		י44°58	93°20'	850										
Mr. J.H. Aschenbeck 721 6th Avenue North	11/25/87	10/?/95		45°00'	93°19'	850		18					3			
Mr. J.H. Aschenbeck 731 Ath Avenue North	10/?/95	· 9/?/23	2 blocks	45°00'	93°19'	825		4					3			Thermometers 99' RG 95' to 11/1/04; anemometer 192' to 4/96.
Mr. J.H. Aschenbeck 1730 Penn. Avenue N.	9/?/23	10/?/36	1.5 mi. ₩√	45°01'	93°21'	888		.4					3			Precipitation only after 2/23/29. Temperature obs. 7A, 2P and 9P.
<u>CITY</u> U.S. Court House, cor, Marquette Ave. & 3rd St AIRPORT	11/06/90	4/10/38		44°59'	93°18'	839	105	105	104		97		%			
Administration Blog. Wold-Chamberlain AP	1/27/34	10/16/37		44°53'	93°13'	832	61	32								
Administration Bldg. Minneapolis-St. Paul Intermational Airport Wold-Chamberlain Field	10/16/37	Present	NA	44°53'	93°13' č	2634	22			¥50 142		s£1	e41	655	í	Several minor moves of instru- ments but no significant changes in elevations other than given below. St. Paul WBAS was integrated with Minneapolis WBAS 6/153. a Ground elevation 650; to b - 71 to 0/18/58 c - Installed 11/20/53. Eleva- tion 41; to 10/24/62. d - Commissioned on field site 17/70; moved 800; WMU 5/31/63. e - Standby after 10/24/62. f - Standby after 10/24/62. f - Standby after 10/24/62. f - Standby after 10/24/62. f - Effective 11/270. g - Effective 11/270. f - Effective 11/276. j - Type change 12/11/85.
SUBSCRIPTION: Price and ordering info	l mation a	l vailable	! through: Nat	ional Cl I NGUIR IE	l imatic [S/COMMEN]) Data Ce TS CAL	i i enter L: i			l Bui -480				lle	i , Noi USi	i rth Carolina 28801. COMM-NOAA-ASHEVILLE, N.C 850
National Climatic Data Cer Federal Building 37 Battery Park Avenue Asheville NC 28801-273	nter												P	OS	FI TA(RST CLA SS GE & FEES PAID
OFFICIAL BUSINESS PENALTY FOR PRIVAT FORWARD AND ADDR	E USE SE ESS COR	800 RECTION	t									Uni				Department of Commerce Permit No. G - 19



LOCAL CLIMATOLOGICAL DATA Monthly Summary





INTERNATIONAL AIRPORT

INQUIRIES/CONMENTS CALL (704) 271-4800

LATITUDE 28° 26'N LONGITUDE

			LATIT	UDE 28	° 26	'n	LONGITU	0E _ 8	1° 19'N	ELEVA	TION IGRI	DUNDI	96 F	EET		1	INE Z	ONE	EAST	ERN		1	2815	
			TEMPE	RATURE	°F		DE GREI BASE		NEATHER TYPES	SNON ICE Pellets	PRECIPI	TATION	AVERAGE STATION PRESSURE				NIND .P.H.	.)			SUNSH	INE	SKY C ITEN	
	_ DATE	~ HAXIMUN	HUMININ 🗠	≁ AVERAGE	U DEPARTURE FROM NORMAL	• AVERAGE • DEM POINT		CODLING (SEASON BEGINS HITH JANE	2 HEAVY FOG 3 THUNDERSTORM 4 ICE PELLETS 5 HAIL 6 GLAZE 7 DUSISTORM 8 SMOKE, HAZE 9 BLOHING SNOW 8	OR ICE ON GROUND AT 0700 INCHES 9	- MATER EQUIVALEN	- SHOH, ICE PELLETS	IN INCHES ELEV. 105 FEET ABOVE M.S.L. 12	E RESULTANT DIR.	RESULIANT SPEED	G AVERAGE SPEED		AK JST NOTICIBLO 17		ILST NOILD3810 9	S 31UNIN 20	~ PERCENT OF 101AL POSSIBLE	SUNRISE 10 SUNSEI	∼ HIDNIGHI ™ TO HIDNIGHI
	01 02 03 04 05	83 75 74 82 83	64 57 50 58 61	74 66 62 70 72	5 -3 -7 1 3	63 52 49 60 61	0 0 3 0 0	9 1 0 5 7	3 1 3	0 0 0 0	0.63 0.00 0.00 0.00 0.44	0.0	29.720 29.840 30.010 29.870 29.700	10	3.1 6.5 8.6	16.5 14.3 8.7 10.3 15.0	38 37 18 23 33	SH H N E SH	26 25 14 16 23	21 29 02 09 26			7 2 6 10 7	6 1 6 10 6
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* EXTREME FOR THE MONTH - LAST OCCURRENCE IF MORE THAN ONE. T TRACE AMOUNT. + ALSO ON EARLIER DATE(S). HEAVY FOG: VISIBILITY 1/4 MILE OR LESS. BLANK ENTRIES DENOTE MISSING OR UNREPORTED DATA.

DATA IN COLS 6 AND 12-15 ARE BASED ON 21 OR MORE OBSERVATIONS AT HOURLY INTERVALS. RESULTANT WIND IS THE VECTOR SUM OF HIND SPEEDS AND DIRECTIONS DIVIDED BY THE NUMBER OF OBSERVATIONS COLS 16 & 17: PEAK GUST - HIGHEST INSTANTANEOUS WIND SPEED ONE OF THO WIND SPEEDS IS GIVEN UNDER COLS 18 & 19: FASTEST MILE - HIGHEST RECORDED SPEED FOR WHICH A MILE OF HIND PASSES STATION IDIRECTION IN COMPASS POINTSI. FASTEST OBSERVED ONE MINUTE WIND - HIGHEST ONE MINUTE SPEED IDIRECTION IN TENS OF DEGREESI. ERRORS WILL BE CORRECTED IN SUBSEQUENT PUBLICATIONS

I CERTIFY THAT THIS IS AN OFFICIAL PUBLICATION OF THE NATIONAL OCEANIC AND ATMOSPHERIC ADMINISTRATION, AND IS COMPILED FROM RECORDS ON FILE AT THE NATIONAL CLIMATIC DATA CENTER



APR 1993

NATIONAL OCEANIC AND ATMOSPHERIC ADMINISTRATION NATIONAL ENVIRONMENTAL SATELLITE, DATA AND INFORMATION SERVICE

NATIONAL CLIMATIC DATA CENTER ASHEVILLE NORTH CAROLINA

Kennel D Wadeen DIRECTOR

NATIONAL CLIMATIC DATA CENTER

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MAXIMUM SHORT DURATION PRECIPITATION

TIME PERIOD (MINUTES)	5	10	15	20	30	45	60	80	100	120	150	180
PRECIPITATION (INCHES)	0.08	0.15	0.21	0.24	0.25	0.27	0.29	0.33	0.39	0.44	0.53	0.60
ENDED: DATE	15	15	15	15	15	15	15	15	15	15	15	15
ENDED: TIME	2003	2005	2010	2012	2020	2036	2054	2111	2133	2155	2225	2252

THE PRECIPITATION AMOUNTS FOR THE INDICATED TIME INTERVALS MAY OCCUR AT ANY TIME DURING THE MONTH. THE TIME INDICATED IS THE ENDING TIME OF THE INTERVAL. DATE AND TIME ARE NOT ENTERED FOR TRACE AMOUNTS.

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PAGE 2

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WEATHER CODES

NT QR RW ZR LZL	TORNADO THUNDERSTORM SQUALL RAIN RAIN SHOWERS FREEZING RAIN DRIZZLE FREEZING DRIZZLE	A F	SNOW SHOWERS SNOW GRAINS SNOW PELLETS ICE CRYSIALS ICE PELLETS ICE PELLET SHOWERS HAIL FOG	GF BDN BSS BSY HD	GROUND FOG BLOWING DUST BLOWING SAND BLOWING SNOW BLOWING SPRAY SMOKE HAZE DUST
ZL S	SNOW	F IF	ICE FOG	U	DUSI

CEILING: UNL INDICATES UNLIMITED WIND DIRECTION: DIRECTIONS ARE THOSE FROM WHICH THE WIND BLOWS, INDICATED IN TENS OF DEGREES FROM TRUE NORTH: 1.E., O9 FOR EAST, 18 FOR SOUTH 27 FOR WEST. AN ENTRY OF OO INDICATES CALM. SPEED: THE OBSERVED AVERAGE ONE-MINUTE VALUE, EXP RESSED IN KNOTS (MPH=KNOTS X 1.15).

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SUMMARY BY HOURS

			AV	ERAG	ES				ILTANT IND
1	ŝ		TEM	PERA	TURE		_		
HOUR L.S. I	SKT COVER (TENTHS)	STATION PRESSURE FINCHES)	AIR IENP OF	HEI BULD OF	DEM POINT OF	REL HUNIDLIY X	HIND SPEED (NPH)	DIRECTION	SPEED (HPH)
01 04 07 10 13 16 19 22	4444	29.910 29.880 29.920 29.945 29.910 29.865 29.880 29.930	60 61 72 77 77 71	59 57 58 63 63 63 59	555532255	83 86 82 54 43 42 53 72	7.8 7.2 13.0 12.5 13.1 11.3 9.8	27 31 01 14 20 18 11 31	2.0 1.3 0.8 1.7 2.0 1.3 3.0 1.4

NATIONAL CLIMATIC DATA CENTER FEDERAL BUILDING 37 BATTERY PARK AVE ASHEVILLE, NORTH CAROLINA 28801-2733

OFFICIAL BUSINESS PENALTY FOR PRIVATE USE \$300 FIRST CLASS POSTAGE AND FEES PAID NOAA PERMIT G-19

LCD-08-12815-PD-9309

45740 JHK & ASSOCIATES ATTN: M SECTT MACCALDEN JR PO BOX 193727 SAN FRANCISCO CA 94119

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LOCAL CLIMATOLOGICAL DATA Monthly Summary





(704) 271-4800 INTERNATIONAL AIRPORT

INQUIRIES/COMMENTS CALL

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$ \begin{array}{c} 03 & 80 & 65 & 73 & -1 & 64 & 0 & 8 \\ 05 & 89 & 66 & 78 & 3 & 66 & 0 & 13 \\ 05 & 89 & 66 & 78 & 3 & 66 & 0 & 13 \\ 05 & 89 & 66 & 78 & 3 & 66 & 0 & 13 \\ 05 & 89 & 66 & 78 & 3 & 66 & 0 & 13 \\ 05 & 89 & 66 & 78 & 3 & 66 & 0 & 14 \\ 05 & 89 & 66 & 78 & 3 & 66 & 0 & 14 \\ 05 & 88 & 69 & 79 & 4 & 65 & 0 & 14 \\ 05 & 88 & 69 & 79 & 4 & 65 & 0 & 14 \\ 08 & 86 & 65 & 76 & 0 & 63 & 0 & 11 \\ 08 & 86 & 65 & 76 & 0 & 63 & 0 & 11 \\ 08 & 81 & 62 & 73 & -3 & 59 & 0 & 8 \\ 10 & 83 & 62 & 73 & -3 & 59 & 0 & 8 & 1 & 0 & 0 & 00 & 0 & 29 & 950 & 19 & 56 & 78 & 32 \\ 11 & 84 & 61 & 73 & -3 & 58 & 0 & 8 \\ 12 & 87 & 67 & 77 & 1 & 62 & 0 & 12 \\ 13 & 85 & 66 & 76 & -1 & 60 & 0 & 11 & 0 & 0 & 00 & 0 & 29 & 950 & 19 & 76 & 87 & 21 \\ 14 & 85 & 66 & 76 & -1 & 60 & 0 & 11 & 0 & 0 & 00 & 0 & 0 & 29 & 950 & 19 & 76 & 87 & 21 \\ 14 & 85 & 66 & 76 & -1 & 60 & 0 & 11 & 0 & 0 & 0.00 & 0 & 0 & 29 & 950 & 19 & 76 & 87 & 21 \\ 15 & 87 & 657 & 77 & 1 & 62 & 0 & 12 & 0 & 1 & 0 & 0 & 29 & 950 & 19 & 76 & 87 & 21 \\ 14 & 85 & 66 & 76 & -1 & 60 & 0 & 11 & 0 & 0 & 0.00 & 0 & 0 & 29 & 950 & 10 & 76 & 87 & 21 \\ 15 & 87 & 652 & 775 & -2 & 60 & 0 & 10 & 0 & 0 & 0 & 0 & 29 & 950 & 10 & 76 & 87 & 21 \\ 15 & 87 & 652 & 775 & -2 & 60 & 0 & 10 & 0 & 0 & 0 & 0 & 29 & 800 & 27 & .77 & 12 & 23 & 8 \\ 16 & 90 & 655 & 78 & 1 & 60 & 0 & 11 & 0 & 0 & 0.00 & 0 & 0 & 29 & 800 & 27 & .77 & 12 & 23 & 8 \\ 17 & 30 & 655 & 78 & 1 & 60 & 0 & 13 & 1 & 0 & 0 & 0 & 0 & 0 & 29 & 800 & 27 & .77 & 52 & 25 & 17 & 12 & 23 \\ 20 & 89 & 66 & 78 & 0 & 62 & 0 & 13 & 0 & 0 & 0 & 0 & 0 & 29 & 800 & 27 & .77 & 52 & 22 & 84 & 17 & 23 & 8 \\ 18 & 304 & 77 & 78 & 14 & 4 & 65 & 0 & 16 & 1 & 0 & 0 & 0 & 0 & 0 & 29 & .800 & 27 & .77 & 20 & 21 & .81 & 17 & .81 & .4 & .4 & .55 & 0 & 16 & 1 & 0 & 0 & 0 & 0 & 0 & .29 & .800 & 27 & .77 & .20 & 11 & .1 & 28 & .8 & .17 & .25 & .6 & .17 & .16 & .17 & .16 & .17 & .16 & .17 & .16 & .17 & .16 & .17 & .16 & .17 & .16 & .17 & .16 & .17 & .16 & .17 & .16 & .17 & .16 & .17 & .17 & .16 & .17 & .16 & .17 & .17 & .18 & .17 & .25 & .18 & .17 & .17 & .18 & .17 & .25 & .18 & $					J. DEPARTURE J. FROM NORMAL	AVE DEH	HEAFING BEGINS	COOLING ISEA Begins with	2 HEAVY FOG 3 THUNDERSTORM 4 ICE PELLETS 5 HAIL 6 GLAZE 7 DUSTSTORM 8 SMOKE, HAZE 9 BLOWING SNOW	OR ICE ON GROUND AT D700 INCHES		SHON, ICE ITHCHESI	IN INCHES ELEV. 106 FEEI ABOVE M.S.L.	RESULTANT	RE SUL TANT	AVERAGE	SPEED	DIRECTION IS	SPEED	DIRECTION NI		~ PERCENI OF - TOTAL POSSIBLE	N SUNRISE	~ NIDNIGHI ™ TO NIDNIGHI
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* EXTREME FOR THE MONTH - LAST OCCURRENCE IF MORE THAN ONE. T TRACE AMOUNT. + ALSO ON EARLIER DATE(S). HEAVY FOG: VISIBILITY 1/4 MILE OR LESS. BLANK ENTRIES DENOTE MISSING OR UNREPORTED DATA.

DATA IN COLS 6 AND 12-15 ARE BASED ON 21 OR MORE OBSERVATIONS AT HOURLY INTERVALS. RESULTANT WIND IS THE VECTOR SUM OF WIND SPEEDS AND DIRECTIONS DIVIDED BY THE NUMBER OF OBSERVATIONS. COLS 16 & 17: PEAK GUST - HIGHEST INSTANTANEOUS WIND SPEED. ONE OF THO WIND SPEEDS IS GIVEN UNDER COLS 18 & 19: FASTEST MILE - HIGHEST RECORDED SPEED FOR WHICH A MILE OF WIND PASSES STATION IDIRECTION IN COMPASS POINTSJ. FASTEST OBSERVED ONE MINUTE WIND - HIGHEST ONE MINUTE SPEED (DIRECTION IN TENS OF DEGREES). ERRORS WILL BE CORRECTED IN SUBSEGUENT PUBLICATIONS.

I CERTIFY THAT THIS IS AN OFFICIAL PUBLICATION OF THE NATIONAL OCEANIC AND ATMOSPHERIC ADMINISTRATION, AND IS COMPILED FROM Records on file at the national climatic data center



NATIONAL OCEANIC AND ATHOSPHERIC ADMINISTRATION

NATIONAL ENVIRONMENTAL SATELLITE, DATA AND INFORMATION SERVICE

NATIONAL CLIMATIC DATA CENTER ASHEVILLE NORTH CAROLINA

mell D Wadeen

DIRECTOR NATIONAL CLIMATIC DATA CENTER

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MAXIMUM SHORT DURATION PRECIPITATION

TIME PERIOD (MINUTES)	5	10	15	20	30	45	60	80	100	120	150	180
PRECIPITATION (INCHES)	0.35	0.65	0.97	1,11	1.17	1,18	1.18	1,18	1,18	1,19	1.20	1.25
ENDED: DATE	29	29	29	29	29	29	29	29	29	29	29	29
ENDED: TIME	1443	1448	1452	1455	1500	1517	1517	1517	1517	1559	1659	1731

THE PRECIPITATION AMOUNTS FOR THE INDICATED TIME INTERVALS MAY OCCUR AT ANY TIME DURING THE MONTH. THE TIME INDICATED IS THE ENDING TIME OF THE INTERVAL. DATE AND TIME ARE NOT ENTERED FOR TRACE AMOUNTS.

PAGE 2

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WEATHER CODES

CEILING: UNL INDICATES UNLIMITED WIND DIRECTION: DIRECTIONS ARE THOSE FROM WHICH THE WIND BLOWS, INDICATED IN TENS OF DEGREES FROM TRUE NORTH: I.E., 09 FOR EAST, 18 FOR SOUTH 27 FOR WEST. AN ENTRY OF 00 INDICATES CALM. SPEED: THE OBSERVED AVERAGE ONE-MINUTE VALUE, EXP RESSED IN KNOTS (MPH=KNOTS X 1.15).

PAGE 3

SUMMARY BY HOURS

			AV	ERAG	ES				LTANT IND
	HS H	-	TEM	PERAT	TURE		_		
HOUÁ L.S.I	SKY COVER ITENTHS!	STATION PRESSURE Linchesi	AIR ICHP OF	NET BULB of	Jo INIOd N30	REL HUMIDITY X	HIND SPEED (HPHI	DIRECTION	SPEED (MPH)
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LOCAL CLIMATOLOGICAL DATA **Monthly Summary**

ISSN 0198-1390

HENT OF ANERCENCONTRACT IND # DEP 100 STATES OF

17041 271-4800 INTERNATIONAL AIRPORT

INQUIRIES/CONNENTS CALL

81° 19'H LATITUDE 28° 26'N LONGITUDE FLEWATION (GROUND) 96 FEFT TIME ZONE FASTERN 12815 WEATHER TYPES SNO AVERAGE NIND (M.P.H.) DEGREE DAYS SKY COVER TEMPERATURE OF 1CE PRECIPITATION STATION SUNSHINE BASE 65°F (TENTHS) 1 FOG PELLET PRESSUR FASTES HEAVY FOG 0R LISEASON PEAK I SEASON HITH JANI 2 ŦN SPEED 100 331 **I VALENI** PELLET DIR. PI OF POSSIBLE 3 THUNDERSTORM INCHES SPEED GUST 1-MIN 4 ICE PELLETS | GROUND DEPARIURE From Normal GHI ELEV 5 HAIL RE SUL I AN I DIRECTION RE SUL I ANT DIRECTION PERCENT OF 101AL POS SUNRISE 10 SUNSET SNOH, ICE LINCHESI 1991 NIONIGHI TO HIGHI HEATING Begins H CODLING BEGINS H 6 GLAZE 7 DUSTSTORM 0700 106 FEET AVERAGE Dem point HATER COU HUH **G AVERAGE** NINUTES HUMINIM AVERAGE SPEED SPEE0 DATE B SMOKE, HAZE 9 BLOWING SNOW MAXI INCHES ABOVE M.S.L 12 23 7A 78 11 14 18 19 10 13 21 22 Δ 5 6 8 1E 17 0.0 29.640 03 0.0 29.745 16 0.0 29.830 25 0.0 29.860 22 0.0 29.930 26 3.8 4.1 5.3 3.7 5.8 01 94 71 70 71 6.4 6.4 E 13 04 83 0 0 0.00 18 45433 33213 Ð 18 4 32 14 16 16 02 93 92 92 92 73 ō 29 12 15 12 28 26 15 29 5 83 18 1 3 1.03 72 70 Ó 1Ž 0 4 SH SE 82 69 8 0.00 6 633 000 04 0.00 81 68 70 16 6.0 7.5 1 05 71 83 18 ō 0.00 R 0.0 29.990 27 0.0 29.980 07 0.0 29.960 13 0.0 29.980 13 0.0 29.990 13 0.0 29.990 13 69 71 71 3.7 2.2 7.4 16 17 21 12 14 17 27 86 94 71 75 83 0 18 0 0.00 7.0 NW Se Ee 2 2 4 365 12 96≭ 95 86× 85 0 21 20 0.00 6.7 07 1 00 6 75 08 1 1 1 09 93 95 73 73 23 71 Õ O Õ 0.00 8.3 5.6 9 4 21 21 17 24 83 18 13 71 Ō 8.0 3 10 84 19 0.00 11 29.970 14 29.950 14 29.910 14 29.870 06 29.880 04 7.6 2.7 5.0 4.0 7.7 69 72 72 0.0 21 46 SE E NE 11 94 73 84 0 19 0 0 00 8.5 12 07 55 5 32421 16 93 94 33 72 ŏ õ 0.99 12 13 83 18 0 5994 3 30 25 18 76 74 0.0 89 85 0 20 3 Ó 8 03 92 14 72 0 0 0.13 29.6. 29.880/04 39.020 06 8.9 30.020 06 10.6 1 30.050 07 10.4 1 40.020 08 9.8 10.09 8.9 E NE 83 18 17 3 5 12 07 91 73 82 0.02 ŏ.ŏ 8.8 13 05 6 E NE 16 17 89 73 81 0 71 ¢ 16 15 13 0.10 0.0 9.9 30 20 20 18 07 6 4 4 0000 28 29 88 71 80 68 67 Õ 0 0.0 11.2 08 08 5 7 78± 18 88 681 - 3 634 EEE 26 22 19 71 70 -1 -2 0.6 89 80 68 0 15 Ô 0.0 18 08 5 89 68 Ó 0.01 0.0 16 6 80 15 9.8 09 0.0 29.950 09 0.0 29.880 17 0.0 29.910 18 0.0 30.005 10 6.0 5.3 1.7 6.1 3.6 21 22 23 24 92 71 69 70 D 17 7.9 24 5 5798 82 0 1 0 Ε 16 23 12 18 3 I 11 SHEEE 8.2 6.7 8.4 93 73 83 000 18 3. 0000 0.11 31 23 10 5 70 70 71 89 90 72 73 71 15 29 25 81 - 1 16 17 0.00 10 8 08 82 Û 3 0.60 25 92 82 Ò Ó 17 ŝ Ō 0.02 0.0 30.020 12 8.0 18 09 8 8 0.0 29.975 10 0.0 29.940 19 0.0 29.950 23 0.0 29.950 25 0.0 29.950 25 0.0 29.920 26 92 89 73 71 1.9 3.5 4.3 6.7 9.8 6.5 7.3 7.3 26 27 72 24 25 31 26 29 N NH **Q7** 83 0 18 3 0 0.07 16 97 97 15 15 17 31 35 25 31 72 73 0 0 00 0.39 19 80 -2 -2 1 33 28 29 30 72 88 80 * ģ 88 89 87 82 ō 74 72 Ô 3 00 0.02 ž 14 9 8 NR ģ 72 î 23 8 80 -2 0 15 0.26 10.6 TOTAL INTAL FOR THE MONTH: SUM TOTAL TOTAL TOTAL SUN SUN Z 2746 NUMBER OF DAYS 4.47 DEP. -11 2.4 8.1 46 E TOR 180 1151 514 DEP. 31 07 DEP. 0.0 29.930 167 DEP. AVG. 0.8 70.3 AVG. AVG. PRECIPITATION ROBIN AVG. AVG. A¥G P0551811 DATE: 12
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 SEASON TO DAIE
 SNOW, TCE PEL
 TOTAL
 <td 72.2 81 9 14 6054 ICE PELLETS NUMBER OF BAYS GREATEST IN 24 HOURS AND DATES GREATEST DEPTH ON GROUND DF 0 SNOH, ICE PELLETS OR ICE AND DATE 12 PRECIPITATION SNOK, ILE PELLETS I MINIBUR TERP MAXIMUM TEMP 900 4 2 03 02 0.0 010

* EXTREME FOR THE MONTH - LAST OCCURRENCE IF MORE THAN ONE. T TRACE AMOUNT

TRACE AMOUNT. ALSO ON EARLIER DATE(S)

HEAVY FOG: VISIBILITY 1/4 MILE OR LESS. BLANK ENTRIES DENOTE MISSING OR UNREPORTED DATA.

DATA IN COLS 6 AND 12-15 ARE BASED ON 21 OR MORE OBSERVATIONS AT HOURLY INTERVALS. RESULTANT WIND IS THE VECTOR SUM OF WIND SPEEDS AND DIRECTIONS DIVIDED BY THE NUMBER OF OBSERVATIONS. COLS 16 & 17: PEAK GUST - HIGHEST INSTANTANEOUS WIND SPEED. ONE OF THO WIND SPEEDS IS GIVEN UNDER COLS 18 & 19: FASTEST MILE - HIGHEST RECORDED SPEED FOR WHICH A MILE OF WIND PASSES STATION IDIRECTION IN COMPASS POINTS). FASTEST OBSERVED ONE MINUTE WIND - HIGHEST ONE MINUTE SPEED IDIRECTION IN TENS OF DEGREES]. ERRORS WILL BE CORRECTED IN SUBSEQUENT PUBLICATIONS.

ERRATA - FEB 1993 - CORRECT HEATING DEGREE DAYS Departures to read - MTH: -41 Season: -235

I CERTIFY THAT THIS IS AN OFFICIAL PUBLICATION OF THE NATIONAL OCEANIC AND ATMOSPHERIC ADMINISTRATION, AND IS COMPILED FROM Records on file at the national climatic data center



JUN 1993), FL

ORI ANDO

NATIONAL OCEANIC AND ATHOSPHERIC ADMINISTRATION

NATIONAL ENVIRONMENTAL SATELLITE, DATA AND INFORMATION SERVICE

NATIONAL CLIMATIC DATA CENTER ASHEVILLE NORTH CAROLINA

Kennel D Wadeen

DIRECTOR NATIONAL CLIMATIC DATA CENTER

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MAXIMUM SHORT DURATION PRECIPITATION

TIME PERIOD IMINUTESI	5	10	15	20	30	45	60	80	100	120	150	180
PRECIPITATION (INCHES)	0.25	0.50	0.60	0.85	1,00	1.00	1.03	1.03	1.03	1.03	1.03	1.03
ENDED: DATE	02	02	02	02	02	02	02	02	02	02	02	02
ENDED: TIME	1750	1750	1750	1752	1804	1810	1815	1815	1815	1815	1815	1815

THE PRECIPITATION AMOUNTS FOR THE INDICATED TIME INTERVALS MAY OCCUR AT ANY TIME DURING THE MONTH. THE TIME INDICATED IS THE ENDING TIME OF THE INTERVAL. DATE AND TIME ARE NOT ENTERED FOR TRACE AMOUNTS.

PAGE 2

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WEATHER CODES

¥ T G R H Z R L Z	TORNADO THUNDERSTORM SQUALL RAIN RAIN SHOWERS FREEZING RAIN DRIZZLE EPEFETUG DDITTE	SH SG SP IP IP A	SNOW SHOWERS SNOW GRAINS SNOW PELLETS ICE CRYSTALS ICE PELLETS ICE PELLETS ICE PELLET SHOWERS HAIL	GF BDN BSS BSY H	GROUND FOG BLOWING DUST BLOWING SAND BLOWING SNOW BLOWING SPRAY SMOKE HAZE DUST	
ZL	FREEZING DRIZZLE	F	FOG	D	DUST	
S	SNOH	IF	ICE FOG			

CEILING: UNL INDICATES UNLIMITED WIND DIRECTION: DIRECTIONS ARE THOSE FROM WHICH THE WIND BLOWS, 'INDICATED IN TENS OF DEGREES FROM TRUE NORTH: I.E., O9 FOR EAST, 18 FOR SOUTH 27 FOR WEST. AN ENTRY OF OO INDICATES CALM. SPEED: THE OBSERVED AVERAGE ONE-MINUTE VALUE, EXP RESSED IN KNOTS (MPH=KNOTS X 1.15).

PAGE 3

SUMMARY BY HOURS

			AV	ERAG	ES			1	JLTANT IND
	ES I		TEHI	PERA	TURE		-		
HOUR L.S.1	SKY COVER LIENTHS!	STATION PRESSUAE LINCHES)	AIR TEKP OF	HET BULB OF	3º INIO4 H3Q	REL NUKIOTTY Z	(HUN SPEED (NPH)	DIRECTION	(HdH) (JJJdS
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NATIONAL CLIMATIC DATA CENTER Federal Building 37 Battery Park Ave Asheville, North Carolina 28801-2733

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LCD-03-12315-PD-9309

45740 JHK & ASSOCIATES ATTN: N SCOTT MACCALDEN JR PO BOX 193727 SAN FRANCISCO CA- 94119

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LOCAL CLIMATOLOGICAL DATA Monthly Summary

INTERNATIONAL AIRPORT

INGUIRIES/COMMENTS CALL (704) 271-4800



			LATIT	UDE 28	° 26'	N	LONG] TU	DE +8	1° 19'W		TION (GRO	DUND	96 F	EE 1		1	INE Z	ONE	EAST	ERN		1	2815	
			TENPE	RATURE	°F		DEGREE Base		NEATHER TYPES	SNON ICE Pellets	PRECIPI	TATION	AVERAGE STATION PRESSURE				HIND P.H.	. 1			SUNSH	INE	SKY C (Tent	
- CATE		~ HAXINUN	HUMININ w	← AVERAGE	DEPARTURE FROH NORMAL	o AVERAGE OEH POINT	Z HEATING ISEASON BEGINS HITH JUER	2 COOLING ISEASON BEGINS WITH JANI	2 HEAVY FOG 3 THUNDERSTORM 4 ICE PELLETS 5 HAIL 6 GLAZE 7 DUSTSTORM 8 SNOKE, HAZE 9 BLOWING SNOW 8	GROUND A1 0700 Inches	- HATER EQUIVALENT - LINCHESI	- SNON, ICE PELLETS	IN INCHES ELEV. 106 FEET ABOVE M.S.L. 12	E RESULIANT DIR.	Z RESULIANT SPEED	G AVERAGE SPEED		AK IST NOTICIEN IN		TEST MIN NOILDJAHO 9	© MINUTES	~ PERCENI OF - IDIAL POSSIBLE	SUNRISE 10 SUNSET	NIDNIGHT Be 10 MIDNIGHT
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* EXTREME FOR THE MONTH - LAST OCCURRENCE IF MORE THAN ONE. T TRACE AMOUNT. + ALSO ON EARLIER DATE(S). HEAVY FOG: VISIBILITY 1/4 MILE OR LESS. BLANK ENTRIES DENOTE MISSING OR UNREPORTED DATA.

DATA IN COLS 6 AND 12-15 ARE BASED ON 21 OR HORE OBSERVATIONS AT HOURLY INTERVALS. RESULTANT WIND IS THE VECTOR SUM OF WIND SPEEDS AND DIRECTIONS DIVIDED BY THE NUMBER OF DBSERVATIONS. COLS 16 & 17: PEAK GUST - HIGHEST INSTANTANEOUS WIND SPEED. ONE OF TWO WIND SPEEDS IS GIVEN UNDER COLS 18 & 19: FASTEST MILE - HIGHEST RECORDED SPEED FOR WHICH A MILE OF WIND PASSES STATION IDIRECTION IN COMPASS POINTSI. FASTEST OBSERVED ONE MINUTE WIND - HIGHEST ONE MINUTE SPEED [DIRECTION IN TENS OF DEGREES]. ERRORS WILL BE CORRECTED IN SUBSEQUENT PUBLICATIONS.

I CERTIFY THAT THIS IS AN OFFICIAL PUBLICATION OF THE NATIONAL OCEANIC AND ATMOSPHERIC ADMINISTRATION, AND IS COMPILED FROM Records on file at the national climatic data center



NATIONAL OCEANIC AND ATMOSPHERIC ADMINISTRATION NATIONAL ENVIRONMENTAL SATELLITE, DATA AND INFORMATION SERVICE

NATIONAL CLIMATIC DATA CENTER ASHEVILLE NORTH CAROLINA

Kenneth D Wadeen

DIRECTOR NATIONAL CLIMATIC DATA CENTER

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MAXIMUM SHORT DURATION PRECIPITATION

TIME PERIOD (MINUTES)	5	10	15	20	30	45	60	80	100	120	150	180
PRECIPITATION (INCHES)	0.33	0.55	0.93	1.22	1.54	2.09	2.53	2.60	2.60	2.60	2.60	2.60
ENDED: DATE	31	31	31	31	31	31	31	31	31	31	31	31
ENDED: TIME	1714	1714	1715	1714	1715	1715	1726	1737	1737	1737	1737	1737

THE PRECIPITATION AMOUNTS FOR THE INDICATED TIME INTERVALS MAY OCCUR AT ANY TIME DURING THE MONTH. THE TIME INDICATED IS THE ENDING TIME OF THE INTERVAL. DATE AND TIME ARE NOT ENTERED FOR TRACE AMOUNTS.

PAGE 2

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WEATHER CODES

X I Q R R R R Z R	TORNADO THUNDERSTORM SQUALL RAIN RAIN SHOWERS FREEZING RAIN		SNOW SHOWERS SNOW GRAINS SNOW PELLETS ICE CRYSTALS ICE PELLETS ICE PELLETS SHOWERS	BD BD BS BS K	GROUND FOG BLOWING DUST BLOWING SAND BLOWING SNOW BLOWING SPRAY SMOKE
		IPH		ĸ	
Ĺ	DRIZZLE	А	HAIL	н	HAZE
ZL	FREEZING DRIZZLE	F	FOG	D	DUST
S	SNOW	IF	ICE FOG		

CEILING: UNL INDICATES UNLIMITED WIND DIRECTION: DIRECTIONS ARE THOSE FROM WHICH THE WIND BLOWS, INDICATED IN TENS OF DEGREES FROM TRUE NORTH: 1.E., 09 FOR EAST, 18 FOR SOUTH 27 FOR WEST. AN ENTRY OF OO INDICATES CALM. SPEED: THE OBSERVED AVERAGE ONE-MINUTE VALUE, EXP RESSED IN KNOTS IMPH=KNOIS X 1.151.

PAGE 3

SUMMARY BY HOURS

			AV	ERAG	ES			1	ALTANT
	fs:		TENI	PERA	TURE		_	H	IND
HOUR L.S.T	SKY COVER FIENTHS	STATION PRESSURE IINCHEST	AIR IEMP of	NEI BULB OF	DEN POINT OF	HEL HUMIDITY X	HIND SPEED IMPHI	DIRECTION	SPEED INPHI
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LOCAL CLIMATOLOGICAL DATA Monthly Summary



INTERNATIONAL AIRPORT

LATITUDE 28° 26'N

INOUIRIES/COMMENTS CALL 17041 271-4800

81° 19 H

LONGITUDE

ELEVATION (GROUND) 96 FEET TIME ZONE EASTERN

12815

														· · · · · ·										
		TEMPE	RATURE	۰F		DEGRET BASE	E DAYS 65°F	NEATHER 1 FOG	IYPES	SNOW ICE Pellets	PRECIPI	TATION	AVERAGE STATION PRESSURE	1		(M	HIND .P.H.				SUNSHI	NE	SKY C LTEN	
- 31	НАХІМИМ	MINIMUM	AVERAGE	DEPARTURE From Normal	AVERAGE DEN POINE	HEATING (SEASON) BEGINS WITH JULI	COOLENG ESEASON BEGINS WEEN JANI	2 HEAVY I 3 THUNDEI 4 ICE PEI 5 HAIL 6 GLAZE 7 DUSTSTI 8 SMOKE,	RSTORM Llets Orm	OR ICE ON GROUND At 0700 Inches	HATER EQUIVALENT FINCHEST	SHOH, ICE PELLEIS IPACHESI	IN INCHES ELEY. 106 FEET ABOVE	RESULTANT DIR.	AESULTANT SPEED	AVERAGE SPEED		AK DIRECTION		OIRECTION NIT	H JNUTES	PERCENT OF Total possible	SUNRISE 10 SUNSET	HIONIGHT
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* EXTREME FOR THE MONTH - LAST OCCURRENCE IF MORE THAN ONE.

* EINGRE FOR THE HOUTE - ENSI OCCORRENCE IN HON T TRACE AMOUNT, + ALSO ON EARLIER DATE(S). HEAVY FOG: VISIBILITY 1/4 MILE OR LESS. BLANK ENTRIES DENOTE MISSING OR UNREPORTED DATA.

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I CERTIFY THAT THIS IS AN OFFICIAL PUBLICATION OF THE NATIONAL OCEANIC AND ATMOSPHERIC ADMINISTRATION, AND IS COMPILED FROM RECORDS ON FILE AT THE NATIONAL CLIMATIC DATA CENTER



AUG 1993

NATIONAL OCEANIC AND ATMOSPHERIC ADMINISTRATION

NATIONAL ENVIRONMENTAL SATELLITE, DATA AND INFORMATION SERVICE

NATIONAL CLIMATIC DATA CENTER ASHEVILLE NORTH CAROLINA

Kennel D Wadeen

DIRECTOR NATIONAL CLIMATIC DATA CENTER

									0BS	SER	VAT			T 3-1	HOUR	IN	ITEF	RVA	LS				AUG Orl/	19' Andi	93 0, Fl		12	2815			
	_	BIL	1- 17		TEN	PERA	TURE		HI	ND			VISI- Billiy	,	TEN	PERA	TURE		NI.	ND	-		V S B L	Ι- ΤΥ		TE	PERA	TURE		N I	NO
HOUR L.S.I.	SKY COVER TTEHTUS Efiling in Rundreds of feet			NEATHER	AIR of	HET BULB OF	Jo INIOG HJO	ACL HUMEDIT X	OIRECTION	SPEED IKHOFS)	SKT COVER ITENTHS	HUNDREDS OF FEET	HINDLE MILES	45 4 1 11	AIR of	HET BULB OF	DEN POINT OF	REL HUNIDITY X	DIRECTION	SPEED IKNOISI	SKY COVER LIENINS!	CELLING IN HUMDREDS OF FEEL	MLCS		HEATHE	AIR of AIR	HEI BULB OF	OCH POLNI OF	REL NUMIOITY X:	DIRECTION	SPEED (KHOTS)
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MAXIMUM SHORT DURATION PRECIPITATION

TIME PERIOD (MINUTES)	5	10	15	20	30	45	60	80	100	120	150	180
PRECIPITATION (INCHES)	0.25	0.50	0.73	0.95	1.29	1.46	1.55	1.56	1.61	1.69	1.73	1.80
ENDED: DATE	29	29	29	29	29	29	29	29	29	29	29	29
ENDED: TIME	1432	1432	1437	1443	1451	1456	1459	1521	1536	1559	1635	1659

THE PRECIPITATION AMOUNTS FOR THE INDICATED TIME INTERVALS MAY OCCUR AT ANY TIME DURING THE MONTH THE TIME INDICATED IS THE ENDING TIME OF THE INTERVAL. DATE AND TIME ARE NOT ENTERED FOR TRACE AMOUNTS.

PAGE 2

	OBSERVATIONS AT 3-HOUR INTERVALS											AUG 1993 Orlando, Fl					12815																	
Γ	5		915 811	1- 117			TEMP	ERA	IURE		H I	ND	-		VISI BILLI	Y		TENF	ERA	TURE		¥1	ND	5		VISI Bili	- ΤΥ		151	PERI	TURE	-	H	ND
HOUR L.S.I.	SKY COVER FIENINS	CETLING IN HUMOREDS OF FEET	NHOLE HILES	IGTHS HILE	MEATH	ER	AIR of	HET BULB OF	DCH POINT OF	REL HUNIDITY 2	DIRECTION	SPEED (KNOTS)	SKY COVER LIENTHSI	CELLENG IN HUNDREDS OF FEET	HHOLE MILES	IbfHS AILE	IEATHER	Alg of	HE L BUL8 °F	DEN POINT OF	REL HUMIDITY X	DIRECTION	SPEED IKHOISI	SKY COVER LIENTHSI	CETLING IN Hundreds of feet	NHOLE MILES	161HS MILE	WEATHE	All of	HEI BULB OF	Jo INIOd NJG	REL HUNIOIIY 2	DIRECTION -	SPEED (KHOISI
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WEATHER CODES

* T OR RZL ZL	TORNADO THUNDERSTORM SQUALL RAIN RAIN SHOWERS FREEZING RAIN DRIZZLE FREEZING DRIZZLE	SW SNOW SHOWERS SG SNOW GRAINS SP SNOW PELLETS IC ICE CRYSTALS IP ICE PELLETS IPW ICE PELLET SHOWERS A HAIL F FOG	GF BD BS BS K H D	GROUND FOG BLOWING DUST BLOWING SAND BLOWING SNOW BLOWING SPRAY SMOKE HAZE DUST
ZL S	FREEZING DRIZZLE	IF ICE FOG	U	0051

CEILING: UNL INDICATES UNLIMITED WIND DIRECTION: DIRECTIONS ARE THOSE FROM WHICH THE WIND BLOWS, INDICATED IN TENS OF DEGREES FROM TRUE NORTH: 1.E., 09 FOR EAST, 18 FOR SOUTH 27 FOR WEST. AN ENTRY OF OO INDICATES CALM. SPEED: THE OBSERVED AVERAGE ONE-MINUTE VALUE, EXP RESSED IN KNOTS (MPH=KNOTS X 1.15).

PAGE 3

SUMMARY BY HOURS

			JLTANT IND						
	HSI		TEN	PERAT	IURE		_		
HOUR L.S.I	SKY COVER CTENTHSI	STAFTON PRESSURE	AIR IEMP OF	HEI BULB OF	DEN POINI OF	REL HUNIDITY X	HIND SPEED LINH	DERECTION	SPEED (HPH)
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1 118

	HOURLY PRECIPITATION									(WA	ITER	EQI	JIVA	LENT			CHES HO	5) <mark>0</mark>	UG 19 RLAND SCOMM ENDI	0, FL - NOA	<u>ia – a</u> A T	12815 A - ASHEVILLE. NC 20 D T L						
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SEP 1993 Orlando, Fl Nat'l Wea ser ofc Suite 100

INQUIRIES/COMMENTS CALL {704) 271-4800

INTERNATIONAL AIRPORT

LOCAL CLIMATOLOGICAL DATA Monthly Summary



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* EXTREME FOR THE MONTH - LAST DCCURRENCE IF MORE THAN ONE. T TRACE AMOUNT. + ALSO ON EARLIER DATE(S). HEAVY FOG: VISIBILITY 1/4 MILE OR LESS. BLANK ENTRIES DENOTE MISSING OR UNREPORTED DATA.

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NATIONAL CLIMATIC DATA CENTER ASHEVILLE NORTH CAROLINA

Kennell D Wadeen

DIRECTOR NATIONAL CLIMATIC DATA CENTER

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KOUR L.S.T.	SKY COVER ITENTIAL	CELLING IN HUNDREDS DF FEET	HOLE MILES	ISTHS MILE	NEA	I HE R	AIR of	NCT BULB OF	DEN POINT OF	REL HUMFDITY X	DIRECTION	SPEED (KNOTS)	SKY COVER LTENTHSI	CETLING IN HUNDREDS OF FEET	WILES		KEATHER	ALA OF	HET BULB OF	DEH POINT of	REL HUMJDITY X	DIRECTION	SPEED IKNUISI	SKY COVER LIENTHSI	CETLING IN RUXUREDS OF FEET	NHOLE KILES	161HS MILE	WEATHER	AIR of	HET BULB OF	Je INIOd N30	REL HUNIDITY I	DIRECTION	SPEED (KN0151
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01 07 10 13 16 19 22	35248763	UNL UNL UNL 41 250 250 UNL	7 8 10 10 10				75 74 75 84 87 91 77 76	74 73 74 78 78 77 74 73	73 72 73 75 74 71 73 72	94 94 75 52 88 88	16 15 12 13 10 15 14 23	549910 1155	0 6 7 8 7 8 0	UNL UNL 250 250 250 UNL UNL	10 7 10 10 7 10 10			74 73 75 85 83 87 81 78	73 73 74 77 77 77 75 75	73 73 74 75 73 72 73	97 94 70 77 63 74 85	10 00 10 12 06 15 12 14	3 4 10 10 12 7 6	0 5 8 4 7 8 6 1	UNL 25 UNL 250 250 UNL UNL	10 8 7 10 10 10 10 7			74 76 85 89 89 83 79	73 73 75 77 77 78 75 75	73 73 74 73 71 73 72 75	97 97 94 67 55 59 70 88	07 17 20 10 22 12 11 10	3 3 3 8 3 1 8 5
\square					\$E P	4th											SEP 5th											SEP 6th						
01 04 10 13 16 19 22	0 1 3 2 8 6 8 3	UNL UNL UNL 37 49 48 UNL	10 8 10 8 10 10		RW		76 75 85 87 89 85	74 74 75 78 77 77 77 77	73 73 74 75 72 72 73 72	91 94 94 72 61 57 67 72	17 13 12 18 23 32 06 32	53558445	9 4 7 4 7 10	UNL 250 UNL 250	10 8 10 10 10 10 7		Ŧ	78 75 76 86 90 84 74 75	75 74 74 78 77 77 71 71	74 73 73 74 71 74 69 73	88 94 91 68 54 72 85 94	25 22 00 13 24 27 12 31	43045774	10 10 7 4 7 10 10	250 250 140 UNL 37 95 90 250	7 7 10 10 7 10 10		TRM	73 73 74 85 90 73 76 77	72 73 77 78 72 75 75	71 73 73 73 73 72 74 75	94 94 97 67 58 97 94 94	04 00 14 16 11 05 34 00	5 0 4 7 4 4 4 0
				·	SEP	7th											SEP 8th							ł				SEP 9th						
01 07 10 13 16 19 22	7 4 1 3 7 9 10	UNL UNL UNL 250 250 35	7 7 10 10 10	bi l	1 R		75 74 76 85 89 84 77 71	74 73 75 77 77 76 71 70	73 73 74 74 72 73 68 70	94 97 94 70 57 70 74 97	08 00 08 23 17 29 26 06	404468205	7 7 5 9 10 9	250 250 UNL 100 250 250 250 UNL	7 7 10 10 10 10 7			73 71 73 80 86 81 80 76	72 70 72 75 77 77 75 75 75	71 70 72 73 75 73 75	94 97 97 55 82 79 97	11 00 17 20 28 31 03 14	10 3 6 7 7 4 7	2 0 3 6 9 10 6	UNL UNL 250 36 250 250 UNL	7 7 10 8 10 10 10		T	74 73 74 84 88 84 79 77	73 73 78 78 78 78 77 77 77 75	73 73 72 75 74 74 76 74	97 94 75 63 72 91 91	00 18 20 19 27 27 30 11	0 4 3 9 7 6 8 5
\square					SEP	10th										Ş	EP 111	I I										SEP 12ti						
04 07 10 13 16 19 22	7 4 8 9 10 10	250 UNL 250 250 250 250 250 UNL	7 8 10 7 10 10		T		75 74 75 86 83 78 78 78 78	74 73 74 78 75 75 75 75	73 73 74 75 72 74 74 74	94 97 97 70 70 88 88 88	21 20 19 25 25 23 20 23	4771214654	8 9 10 9 10 9 10 9	UNL 250 250 250 21 250 UNL	7 7 10 7 1 7		Ť TRN	75 74 76 85 84 76 73 73	74 75 79 80 73 72 72	74 74 75 76 78 71 71 72	97 100 97 82 85 94 97	23 19 22 33 36 09 13 11	4 4 5 6 5 12 3 4	1 27 54 58 2	UNL 80 UNL UNL 250 UNL	4 5 10 10 10 10 7		F F F	72 70 71 83 87 87 87 87 87 87	72 70 71 75 75 77 76 75	72 70 71 70 72 73 73 74	100 100 67 57 61 77 91	14 03 07 08 03 11 09 05	3 4 5 7 7 8 8 6
\square					SEP	13th								-		5	EP 14th						•					SEP 15t						
01 04 07 10 13 16 19 22	0 1 3 4 7 9 10 9	UNL UNL UNL 42 80 250 25	7 6 70 10 10 10 10		F		75 74 76 85 90 83 80 77	74 73 74 77 77 77 76 76 74	73 73 74 72 75 74 72 75 74 72	94 97 91 70 56 77 82 85	03 03 13 14 05 05 07	54578997	10 3 2 8 9 10 9 3	UNL UNL 250 80 120 120 UNL	7 7 10 10 10 10 10			74 72 74 83 79 81 78 76	73 71 72 74 74 75	72 71 74 72 68 72 74	94 97 90 74 65 82 94	10 36 03 10 11 03 03 02	7 7 8 14 5 4	2 2 7 7 5 7 9 10	UNL UNL 250 UNL 250 220 200	10 7 10 10 10 10 7			75 74 73 85 88 89 82 79	74 73 72 76 76 77 76 76	73 73 72 72 70 71 74 75	94 97 55 55 77 88	02 03 03 08 13 09 11 05	6 4 10 8 12 10 6
					SEP	16th				•						:	iEP 17tł											SEP 18t		1.75		1.0.4		
01 04 10 13 16 19 22	5 1 6 7 8 7 5 0	UNL UNL 120 250 UNL UNL	7 7 10 10 10 10 10 10			-	77 76 75 85 89 87 82 78	76 75 73 77 78 77 77 77 76	75 74 72 73 73 73 75 75	94 94 90 67 59 63 79 91	04 06 15 12 07 08 07	56768976	0 8 10 5 6	UNL 250 250 250 UNL 250 250	7 7 10 10 10 10 10			76 75 76 84 90 88 81 79	75 75 78 77 77 77 75 76	75 75 75 75 72 72 72 72 74	97 100 97 56 59 74 85	04 01 15 10 07 11 07	4 6 7 8 10 8 6	10 5 10 8 7 7 5 5	250 UNL 250 250 250 250 UNL UNL	10 10 10 10 10			76 75 76 84 88 86 82 78	75 75 78 76 78 76 75	74 75 75 71 75 73 73 74	94 100 97 75 57 70 74 88	06 35 01 09 36 09 10 11	5 4 6 4 12 9 6

MAXIMUM SHORT DURATION PRECIPITATION

TIME PERIOD (MINUTES)	5	10	15	20	30	45	60	80	100	120	150	180
PRECIPITATION (INCHES)	0.50	0.75	0.98	1.14	1.26	1.43	1.46	1.47	1.47	1.47	1.47	1.47
ENDED: DATE	11	11	11	11	11	11	11	11	11	11	11	11
ENDED: TIME	1613	1613	1615	1618	1628	1643	1658	1708	1708	1708	1708	1708

THE PRECIPITATION AMOUNTS FOR THE INDICATED TIME INTERVALS MAY OCCUR AT ANY TIME DURING THE MONTH. THE TIME INDICATED IS THE ENDING TIME OF THE INTERVAL. DATE AND TIME ARE NOT ENTERED FOR TRACE AMOUNTS.

PAGE 2

										OB:	SER	٧A	TIC	NS	AT	3-H	OUR	IN	TEF	RVA	LS				SEP 1 ORLAD	993 100, F	i		12	815			
	-		WISI BILII	Y		TEM	PERA	TURE		H I	ND	1		VISI Bilit	Y		TEN	PERA	TURE		¥1	ND	12		VISI- Bilit	Y		TEMF	ERA	IURE		NI	10
HOUR 1.5.1.	SKY COVER ITENTHSI	CENTENS IN HUNDREDS OF FEET	NHOLE NILES		ATHER	AIR of	NET BULB OF	DEN POINT OF	REL HURIDITY X	DIRECTION	SPEED IKNOTSI	SKI COVER ITENTHS	CELLERG IN Humdreds of feet	WHOLE WILLS	19102 1161	EATHEF	AIR OF	NCT BULB OF	jo INiOd HJO	REL HUNIDITY X	01RECT10N	SPEED (KNOTS)	SKY COVER LTENTHSI	CETLING IN HUMDREOS OF FEET	HHOLE MILES	HEA	THER	AIR of	NET BULB OF	Jo INIOd H30	REL HUNIDITY X	DIRECTION	SPEED IKHOTSI
				SE	P 19ti	<u>۱</u>									SE	P 20t	h									SEP	21st						
01 04 07 10 13 16 19 22	10025530	UNL UNL UNL UNL UNL UNL UNL UNL	7 7 10 10 10 10 7			75 75 85 90 81 81 78	74 75 75 77 77 77 75 75	74 75 75 74 71 72 72 72	97 100 97 70 54 61 74 85	32 30 33 20 04 05 07 10	34 4 3 7 10 7 5	03068642	25 37 95 UNL	7 7 10 10 10 10 10			75 74 76 85 88 86 81 77	74 73 75 77 78 76 76 75	73 73 74 74 74 72 73 73	63 63 77	01 03 34 06 08 09 07 07	35379277	2 0 6 4 9 10	25 UNL UNL 250	7 7 8 10 8 7 7			75 74 76 85 91 89 82 79	74 73 74 77 78 77 74 74	73 73 74 73 71 70 72	94 97 91 70 56 55 67 79	05 07 05 12 10 07 32	54386983
				ŞE	P 22n	4									SE	P 23r	d									SEP	24th						
104 107 113 116 122	8 5 8 1 3 0 0	250 UNL 250 UNL UNL UNL UNL UNL	7 7 10 10 10 10			74 72 74 84 90 89 81 77	71 73 76 74 75 75	70 -71 72 73 66 69 72 74	87 97 94 70 45 52 74 91	26 32 36 34 26 02 07 09	64464585	26053423	UNL 60 250 250 UNL UNL UNL	5 5 8 10 10 10 7	FFF		76 73 75 85 89 89 80 76	75 73 75 77 76 75 74 72	74 73 75 74 70 68 71 70	94 100 70 54 50 74 82	29 30 04 29 07 05	53457666	10 10 10 10 10 10 10 10 10 10 10 10 10 1	UNL 55 120 UNL UNL UNL UNL UNL	7 6 5 10 10 10 10	F		74 73 74 84 89 80 75	72 72 73 74 73 73 73 72 72	71 72 65 65 68 70	90 94 94 61 47 45 67 85	29 25 32 33 03 25 08 09	33368375
				SE	P 25tl	1 <i>77</i>		<u> </u>		•					SE	P 26t	h									SEP	27th						
01 04 07 10 13 16 19 22	0 2 0 3 4 9 7 0	UNL UNL UNL UNL 55 250 UNL	7 7 10 10 5 10	R	H	73 71 73 84 89 77 73 74	70 70 71 75 76 74 71 72	69 70 71 70 72 70 71	87 93 90 65 54 85 90 90	07 00 04 09 11 18 04 11	30474945	559	UNL 120 UNL 120 UNL UNL 80 140	10 10 10 10 10 10 7 7 7			74 72 73 83 89 90 73 73	73 71 72 77 78 76 73 72	72 71 72 74 73 69 73 71	94 97 97 74 59 50 100 94	11 20 15 16 17 19 03 08	6 3 4 9 10 6 5 7	5 7 7 10 10	UNL 250 250 110 90 250	7 7 10 10 10 10 8 10	RH		72 73 84 88 80 78 76	71 72 78 77 73 75 74	71 72 75 73 69 74 73	97 97 75 61 69 88 91	15 17 18 22 20 29 13 27	45598683
	1			SE	P 2811	3									SE	P 29t	ħ									SEP	30th						
01 04 107 10 13 16 19 22	2	UNL UNL 250 250 250 250	7 2 5 10 10 10 10 10	E F		73 72 73 83 88 84 77 75	73 72 73 76 76 76 76 72 70	73 72 73 73 71 72 70 68	100 100 72 57 67 79 79	17 00 33 04 30 03 01 36	7 0 6 9 5 9 9 1	74989958	UNL 200 250 250 250 UNL UNL	7 10 10 10 10 10 10 10			73 71 69 79 82 80 74 71	70 66 64 69 67 65 65	68 63 62 62 59 61	84 76 73 56 51 49 62 71	36 35 01 02 03 36 35	8 11 9 12 13 11 6 8	8 9 9 8 7 9 10	250 UNL 250 250 250 250 250 250	10 10 10 10 10 10 10			68 67 66 77 81 81 72 68	64 62 66 67 66 63 61	62 62 59 59 59 59 55 55 55	81 84 78 54 47 42 57 63	33 33 35 02 05 02 01	8 7 10 8 10 10 10

SUMMARY BY HOURS

			AV	ERAG	ES				ILTANT IND
	1S1		TEM	PERAT	TURE		-		
HOUR L.S.T	SKT COVER LIENTHS!	STATION PRESSURE	AIR IERP OF	HET BULB OF	DEN POINT OF	REL HUMIDITY X	HIND SPEED (HPH)	DIRECTION	SPEED INPHI
01 04 07 10 13 16 19 22	44567775	29.940 29.920 29.950 29.970 29.940 29.900 29.900 29.920 29.960	73 74 84 87 85 79	73 72 73 76 76 75 74 73	72 72 72 73 71 71 71 71 72	93 96 93 69 59 65 79 87	54588984	08 36 05 11 10 08 07 07	1.8 0.9 1.7 3.0 1.7 4.2 4.3 3.5

WEATHER CODES

CEILING: UNL INDICATES UNLIMITED WIND DIRECTION: DIRECTIONS ARE THOSE FROM WHICH THE WIND BLOWS, INDICATED IN TENS OF DEGREES FROM TRUE NORTH: I.E., O9 FOR EAST, 18 FOR SOUTH 27 FOR WEST. AN ENTRY OF OO INDICATES CALM. SPEED: THE OBSERVED AVERAGE ONE-MINUTE VALUE, EXP RESSED IN KNOTS (MPH=KNOTS X 1.15).

PAGE 3

P&DF ASHEVILLE NC 288 11/24/93 19:1/

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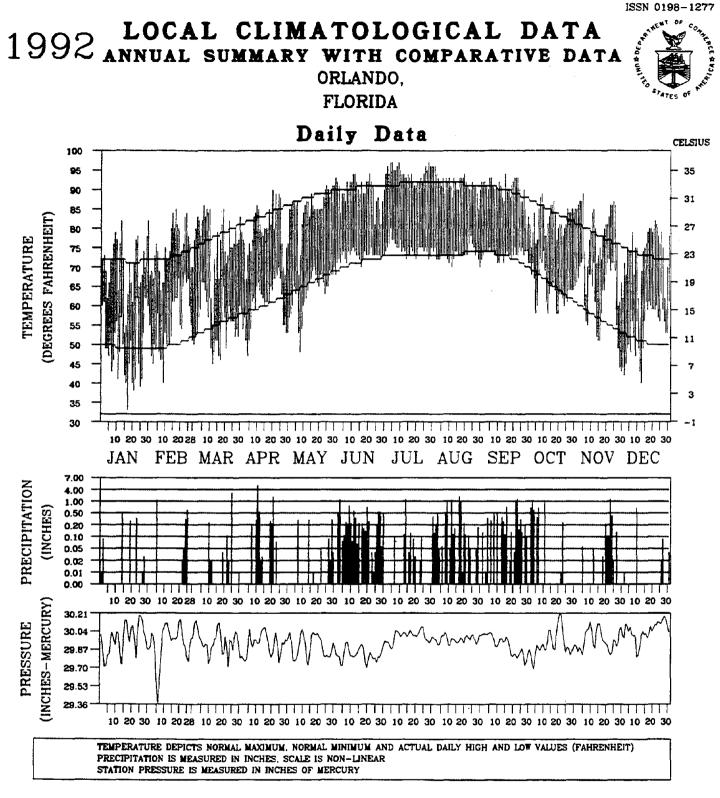
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المرا بمقالية أمراك المراجعة المقربة المتعمل المتعمل المتعمل المتعمل المتعمل المتعام المتعارية

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ΙE			A	Μ.	HOL	JR E	NDI	NG	A T							⊃ <u>.M</u> .	HO	UR	ENDI	NG	AT				Ľ.
DA	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3	4	5	6	7	8	9	10	11	12	MO
01 02 03 04 05 06 07 09 10 11 12 13 14 15 16 17 18 19 20	1	Ţ.	3	4	5	6	7	8	9	10	11	12 T	1 0.05 T 0.01 T	T	0.08	0.22	I 0.01	0.80 T 0.01 0.06	7 0.02 T	T	9	0.01		12	01 02 03 04 05 06 07 08 99 10 11 12 13 14 15 16 17 18 19 20
21 22 23 24 25 26 27 28 29 30															T	0.47 T	0.03 0.01 T	0.62	1						21 22 23 24 25 26 27 28 29 30



I CERTIFY THAT THIS IS AN OFFICIAL PUBLICATION OF THE NATIONAL OCEANIC AND ATMOSPHERIC ADMINISTRATION, AND IS COMPILED FROM RECORDS ON FILE AT THE NATIONAL CLIMATIC DATA CENTER, ASHEVILLE, NORTH CAROLINA, 20801

n n a a detanic and environmental satellite, data climatic data center direct	TOR NAL CLINATIC DATA CENTER
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METEOROLOGICAL DATA FOR 1992 ORLANDO, FLORIDA

				ORL	ANDO, I	FLORIDA	L						
LATITUDE: 28 °26 N LO	NGITUDE	: 81° FEB	MAR	ELEVAT	ION: FT		96 8 JULY		94 TI SEP	me zone OCT	: easte NOV	rn wb DEC	AN: 12815 YEAR
TEMPERATURE OF:													
Averages -Daily-Maximum -Daily Minimum -Monthly Dewpt. Extremes	70.3 49.0 59.7 48.5	74.8 54.8 64.8 54.1	77.2 55.5 66.4 53.5	79.6 60.2 69.9 58.2	85.9 63.8 74.9 62.3	89.6 72.8 81.2 73.0	94.3 74.6 84.5 73.2	91.5 73.1 82.3 73.3	89.9 73.3 81.6 73.2	82.2 64.5 73.4 64.2	78.3 62.4 70.4 61.7	73.3 53.6 63.5 55.6	82.2 63.1 72.7 62.6
-Highest -Date -Lowest -Date	82 30 33 17	85 17 40 9	86 6 45 12	90 20 ⁻ 47 4	93 31 48 8	94 21 70 16	97 28 72 28	96 1 70 30	94 15 71 30	89 9 58 20	89 5 43 30	82 22 40 13	97 JUL 28 33 JAN 17
DEGREE DAYS BASE 65 °F: Heating	187	79	51	19	8	0	o	0	0	0	47	102	493
Cooling	28	79	101	175	325	496	612	540	507	265	217	62	3407
X OF POSSIBLE SUNSHINE													
AVG. SKY COVER (tenths) Sunrise - Sunset Hidnight - Midnight NUHBER OF DAYS: Sunrise to Sunset	6.8 6.4	7.2 7.1	6.0 5.9	6.3 5.8	4.8 4.5	7.8 7.1	4.2 3.9	7.5 7.4	7.2 6.6	5.9 5.4	7.6 7.1	6.6 5.9	6.5 6.1
-Clear -Partly Cloudy -Cloudy	4 11 16	4 9 16	11 3 17	5 15 10	8 17 6	0 13 17	13 13 5	0 14 17	1 16 13	8 10 13	3 6 21	6 9 16	63 136 167
Precipitation .01 inches or more	7	5	8	10	8	26	10	20	20	8	10	5	137
Snow, Ice pellets, hail 1.0 inches or more	0	0	0	0	O	0	o	0	0	0	0	o	٥
Thunderstorms	2	4	2	7	5	19	14	26	17	2	5	0	103
Heavy Fog, visibility 1/4 mile or less	1	3	2	2	0	0	٥	2	Ţ	3	0	4	18
Temperature ^o F -Maximum 90 ⁰ and above 32 ⁰ and below	00	0	0	1 0	7 0	17 0	31 0	27 0	22 0	0	0	0	105 0
-Minimum 32 ⁰ and below 0° and below	0 0	00	0 0	0 0	0 0	0	000	0 0	0 0	0 0	0	0 0	00
AVG. STATION PRESS. (mb)	1014.6	1013.5	1013.9	1013.2	1012.5	1009.8	1015.6	1014.7	1012.9	1013.2	1014.6	1017.3	1013.9
RELATIVE HUHIDITY (%) Hour 01 Hour 07 Hour 13 (Local Time) Hour 19	83 85 54 66	86 92 54 66	83 86 47 57	88 86 53 68	89 90 46 61	94 94 67 80	90 91 53 67	94 95 62 84	95 95 65 84	91 92 58 77	87 89 63 76	90 92 62 78	89 91 57 72
PRECIPITATION (inches):													
Water Equivalent -Total -Greatest (24 hrs) -Date	1.35 0.54 14	2.42 1.36 5-6	3.67 3.19 25-26	9.10 5.65 11-12	1,19 0,33 29	8.68 1.48 3	2.60 1.55 14	8.03 3.07 17-18	7.13 2.57 22-23	5.17 1.82 2-3	2.74 1.57 23	0.88 0.72 10	52.96 5.65 APR 11-12
Snow,Ice pellets,hail -Total -Greatest (24 hrs) -Date	0.0 0.0	0.0 0.0	Ţ 25	T T 10	0.0 0.0	0.0 0.0	0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	T APR 10
HIND: Resultant -Direction (!!) -Speed (mph) Average Speed (mph) Fastest Obs. 1 Min.	305 3.0 9.8	267 1.8 9.8	260 1.9 9.9	039 2.1 9.6	357 0.8 8.7	187 4.5 8.9	192 2.3 7.2	141 2.7 7.5	049 3.3 6.3	011 3.2 8.1	061 2.6 10.2	360 2.8 7.9	015 0.4 8.7
-Direction (!!) -Speed (mph) -Date	24 29 23	27 35 5	30 33 25	16 32 10	04 20 22	15 25 25	18 22 23	03 25 18	21 23 23	23 22 4	21 32 23	28 28 10	27 35 FEB 5
Peak Gust -Direction [!!) -Speed (mph) -Date	SW 45 23	H 43 5	NW 53 25	E 53 10	SW 31 30	E 37 12	NE 39 14	S 38 3	SE 35 4	NE 31 20	SH 32 23	H 35 10	E 53 APR 10

(!!) See Reference Notes on Page 68 Page 2

NORMALS, MEANS, AND EXTREMES

					ORLAN	NDO. FI	ORIDA							
LATITUDE: 28°26'N L	ONG1 (a)		81 ° 194 FEB	h el MAR	EVATION APR	FT. C MAY		96 BARO	•	TIME SEP	zone: e OCT	astern NOV	HB Dec	AN: 12815 YEAR
TEMPERATURE ^O F: Normals -Daily Maximum -Daily Minimum		71.7 49.3 60.5	72.9 50.0	78.3 55.3	83.6 60.3	88.3 66.2	90.6 71.2	91.7 73.0	91.6 73.4	89.7 72.5	84.4 65.4 74.9	78.2 56.8 67.5	73.1 50.9	82.8 62.0 72.4
-Monthly Extremes -Record Highest -Year -Record Lowest	50 50	87 1991 19	61.5 90 1962 28	66.8 92 1970 25	72.0 96 1968 38	77.3 102 1945 48	80.9 100 1985 53	82.4 100 1961 64	82.5 100 1980 64	81.1 98 1988 56	95 1986 43	89 1992 29	62.0 90 1978 20	102 MAY 1945 19
-Year NORMAL DEGREE DAYS: Heating (base 65°F)		1985 212	1970 172	1980 68	1987 0	1992 0	1984 0	1981 0	1957 0	1956 0	1957 0	1950 47	1983 157	JAN 1985 656
Cooling (base 65°F)		73	74	124	214	381	477	539	543	483	307	122	64	3401
X OF POSSIBLE SUNSHINE														
MEAN SKY COVER (tenths) Sunrise - Sunset MEAN NUMBER OF DAYS: Sunrise to Sunset	44	5.7	5.7	5.6	5.1	5.4	6.4	6.4	6.4	6.5	5.5	5.2	5.7	5.8
-Clear -Partly Cloudy -Cloudy Precipitation	44 44 44	9.1 10.3 11.5	8.7 8.6 11.0	9.3 10.4 11.3	10.3 11.3 8.4	8.8 13.5 8.7	4.2 14.3 11.5	3.4 16.7 10.9	3.1 17.1 10.8	3.8 14.6 11.6	9.6 11.3 10,1	10.3 10.2 9.5	9.8 9.3 12.0	90.4 147.5 127.3
.01 inches or more Snow,Ice pellets.hail	50	6.2	7.0	7.6	5.6	8.6	14.0	17.1	16.0	13.6	8.5	5.7	5.9	115.7
1.0 inches or more	50	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
Thunderstorms Heavy Fog Visibility 1/4 mile or less Temperature of	48 44	1.0 5.5	1.5 3.3	2.9 2.5	3.4 1.4	7.7 1.5	14.6 0.8	19.2 0.5	17.5 0.9	9.6 1.2	2.5 1.7	1.2 2.7	1.0 -4.4	82.2 26.4
-Maximum 90° and above 32° and below	29 29	0.0 0.0	0.0 0.0	0.4 0.0	4.0 0.0	11.0 0.0	19.6 0.0	25.1 0.0	25.6 0.0	18.5 0.0	3.5 0.0	0.0 0.0	0.* 0.0	107.7 0.0
-Minimum 32 ⁰ and below 0 ⁰ and below	29 29	1.6 0.0	0.5 0.0	0.1	0.0	0.0	0.0	0.0	0.0	0.0 0.0	0.0	0,1	0.6	2.9 0.0
AVG. STATION PRESS. (mb)	20	1016.6	1015.8	1014.3	1013.7	1012.4	1012.9	1014.5	1013.8	1012.5	1013.5	1015.2	1016.9	1014.3
RELATIVE HUMIDITY (%) Hour 01 Hour 07 Hour 13 (Local Time) Hour 19	28 29 29 29	85 88 56 68	83 87 52 63	84 88 50 61	84 88 47 58	86 88 49 63	89 89 57 72	90 90 59 75	91 92 60 77	90 92 60 77	87 89 56 74	87 89 56 73	87 88 57 73	87 89 55 70
PRECIPITATION (inches): Water Equivalent -Mormal -Maximum Monthly -Year -Minimum Monthly -Year -Maximum in 24 hrs -Year	50 50 50	2.10 7.23 1986 0.15 1950 4.19 1986	2.83 8.32 1983 0.10 1944 4.38 1970	3.20 11.38 1987 0.16 1956 5.03 1960	2.19 9.10 1992 0.14 1977 5.65 1992	3.96 10.36 1976 0.43 1961 3.18 1980	7.39 18.28 1968 1.97 1948 8.40 1945	7.78 19.57 1960 2.60 1992 8.19 1960	6.32 16.11 1972 2.92 1980 5.29 1949	5.62 15.87 1945 0.43 1972 9.67 1945	2.82 14.51 1950 0.35 1967 7.74 1950	1.78 10.29 1987 0.03 1967 5.87 1988	1.83 5.33 1983 T 1944 3.61 1969	47.82 19.57 JUL 1960 T DEC 1944 9.67 SEP 1945
Snow,lce pellets,hail -Maximum Monthly -Year -Maximum in 24 hrs -Year	20 20	T 1977 T 1977	0.0 0.0	T 1992 1992	T 1992 T 1992	0.0 0.0	0.0 0.0	T 1991 T 1991	T 1989 T 1989	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	MAR 1992 MAR 1992
WIND: Mean Speed (mph) Prevailing Direction	44	9.0	9.6	9.9	9.4	8.8	8.0	7.4	7.2	7.6	8.6	8.7	-8.5	8.5 S
through 1963 Fastest Obs. 1 Min. -Direction (!!) -Speed (MPH) -Year Peak Gust	43 43	NNE 25 42 1953	S 25 45 1969	S 29 45 1955	5E 02 50 1956	SE 17 46 1981	SW 32 64 1970	5 14 46 1961	S 32 50 1957	ENE 24 46 1969	N 05 48 1950	N 26 46 1968	NNE 07 32 1968	32 64 JUN 1970
-Direction (!!) -Speed (mph) -Date	9	NH 48 1991	N 51 1991	SH 56 1991	53 1992	5 68 1991	62 1985	₩ 68 1991	SW 58 1991	NW 54 1988	м 40 1990	NE 41 1984	ы 43 1984	H 68 JUL 1991

(!!) See Reference Notes on Page 6B. Page 3 PRECIPITATION (inches)

ORLANDO, FLORIDA

YEAR	JAN	FEB	MAR	APR	MAY	JUNE	JULY	AUG	SEP	OCT	NOV		ANNUAL
1963 1964 1965 1966 1967	3.17 6.18 1.79 4.45 0.84	4.76 3.42 3.67 6.31 5.49	2.69 4.65 3.02 2.57 1.31	1.23 2.14 0.66 1.92 0.28	3.56 2.74 0.52 6.57 1.69	6.67 6.11 7.36 9.77 11.16	3.83 6.68 11.55 6.73 4.63	3.54 9.00 5.49 7.76 6.83	6.72 9.47 5.99 6.28	0.46 1.64 4.06 1.98 0.35	6.39 0.45 1.06 0.09 0.03	2.26 1.91 2.23 0.99 2.42	45.28 54.39 47.40 55.39 40.91
1968	0.65	2.76	2.27	0,30	3.72	18.28	5.60	3.44	5,91	5.47	2,82	0.88	52.10
1969	2.22	3.30	5.52	2,38	1.40	5.04	6.73	7.17	6,44	9.45	0,87	4.66	55.18
1970	4.05	6.77	3.66	0,45	4.08	4.92	5.97	5.91	3,25	2.60	0,24	2.06	43.96
1971	0.45	2.98	1.46	1,52	4.31	4.39	8.29	7.51	2,98	3.06	1,21	1.93	40.09
1972	0.99	4.96	5.06	1,39	3.76	6.33	3.98	16.11	0,43	2.34	4,11	1.89	51.35
1973	4.82	2.73	4.13	2.82	4.74	6.63	6.24	7.33	11.53	1.10	0.74	2.56	55.37
#1974	0.18	0.63	3.67	1.17	2.69	15.28	6.01	6.56	5.78	0.48	0.31	1.62	44.38
1975	0.98	1.49	1.10	1.36	7.52	9.70	9.26	4.75	4.97	4.74	0.66	0.51	47.04
1976	0.37	0.83	1.72	2.16	10.36	9.93	7.05	3.25	5.87	0.74	2.03	2.77	47.08
1977	1.81	1.76	1.82	0.14	1.47	4.47	6.61	6.28	7.03	0.43	2.60	3.70	38.12
1978	2.49	5.45	2.14	0.61	3.16	10.00	11.92	5.13	4,31	1.51	0.18	3.69	50.59
1979	6.48	1.45	3.24	1.08	7.66	4.00	7.95	5.88	9,19	0.43	1.93	0.94	50.23
1980	2.45	1.64	1.51	4.07	6.96	5.25	5.14	2.92	3,70	0.55	6.55	0.47	41.21
1981	0.21	4.36	1.85	0.18	2.02	12.49	3.53	5.60	8,26	3.13	2.50	2.97	47.10
1982	1.72	1.34	4.85	6.27	5.29	6.06	11.81	5.03	6,96	0.74	0.53	1.01	51.61
1983	2.08	8.32	5.37	3.21	1.77	7.82	6.49	4.83	5.16	3.78	1.36	5.33	55.52
1984	2.01	2.73	1.85	6.21	3.20	5.32	6.19	7.89	6.19	0.56	2.10	0.19	44.44
1985	0.91	1.27	4.59	1.69	3.00	4.54	7.28	11.63	5.45	2.55	0.82	3.46	47.19
1986	7.23	1.84	2.63	0.49	0.88	9.50	5.85	5.99	4.50	5.63	1.69	3.60	49.83
1987	1.27	1.74	11.38	0.59	1.40	3.54	7.95	6.07	8.64	3.41	10.29	0.51	56.79
1988	3.12	1.38	6.07	2.02	2.82	4.17	9.44	7.94	5.67	1.42	7.44	1.00	52,49
1989	3.80	0.15	1.35	2.28	2.38	6.79	4.74	6.20	10.29	1.75	1.44	4.49	45,66
1990	0.23	4.13	1.92	1.73	0.55	6.22	6.68	3.78	2.46	2.10	1.05	0.83	31,68
1991	2.37	0.98	6.66	7.72	9.48	5.98	10.78	7.13	4.53	4.76	0.27	0.24	60,90
1992	1.35	2.42	3.67	9.10	1.19	8.68	2.60	8.03	7.13	5.17	2.74	0.88	52,96
Record Mean	2.17	2.72	3.47	2.63 Se	3.42 e Refer	7.03 ence No Page	tes on	6.69 Page 6B	6.76	3.34	1.91	1.93	49.94

AVERAGE TEMPERATURE (deg. F) ORLANDO. FLORIDA

YEAR	JAN	FEB	MAR	APR	MAY	JUNE	JULY	AUG	SEP	OCT	NOV	DEC	ANNUAL
#1963	59.5	57.2	69.5	73.6	77,9	82.4	82.9	83.9	80.5	73.8	65.4	56.5	71.9
1964	58.5	58.3	68.1	74.1	77,1	82.4	81.6	82.8	79.8	72.5	70.5	64.4	72.5
1965	60.0	64.1	67.0	74.8	77,1	79.0	80.5	82.2	80.8	74.2	69.5	62.6	72.7
1966	58.7	62.3	64.4	70.5	77,4	78.0	82.3	82.3	80.1	75.8	65.8	60.1	71.5
1967	63.2	60.0	68.3	74.3	78,3	80.2	82.4	82.0	79.7	74.0	67.5	65.9	73.0
1968	59.6	54.8	61.4	73.5	76,7	78.8	81.3	82.3	80.3	74.3	63.4	58.7	70.4
1969	59.8	57.8	60.4	72.5	76,9	82.9	84.4	82.2	81.2	77.9	64.0	58.7	71.6
1970	55.1	58.7	67.0	75.8	77,7	81.8	83.8	82.3	83.5	77.0	63.4	64.6	72.6
1971	62.0	64.1	64.8	72.1	78,2	81.7	83.1	83.3	81.8	79.0	69.5	71.4	74.2
1972	68.9	62.0	68.7	72.7	77,4	82.2	83.2	82.8	81.8	76.8	68.9	66.1	74.3
1973	62.4	59.7	71.1	71.1	78.3	83.1	84.2	81.8	81.4	75.6	70.9	60.4	73.3
#1974	71.6	60.5	70.2	71.4	78.0	80.3	80.7	82.0	81.8	72.6	67.6	60.9	73.1
1975	65.8	67.6	67.4	72.4	79.1	80.8	80.5	82.3	80.7	76.6	67.4	60.2	73.4
1976	56.5	63.7	70.4	71.3	76.8	79.7	82.4	81.9	80.5	72.6	63.0	60.1	71.6
1977	50.6	57.4	69.7	70.6	75.2	82.6	82.0	81.5	82.6	72.9	69.6	61.0	71.3
1978	56.8	55.8	66.3	73.4	79.3	82.9	82.6	82.6	81,7	75.0	72.3	66.8	73.0
1979	58.2	58.4	64.6	73.4	75.4	80.7	83.3	82.4	81,3	74.4	68.3	62.6	71.9
1980	60.5	57.2	68.2	70.4	76.4	80.1	83.5	83.6	81,7	75.4	67.1	59.0	71.9
1981	51.3	61.7	64.0	73.1	76.7	83.2	84.1	82.9	80,0	76.4	65.3	60.5	71.6
1982	60.0	68.4	70.4	72.6	75.3	82.0	82.6	82.2	80,2	74.1	70.8	66.7	73.8
1983	58.0	59.9	63.5	68.6	76.4	80.5	83.2	83.5	80.6	76.5	65.8	61.2	71.5
1984	57.8	61.2	64.7	69.2	75.6	78.4	80.7	81.5	78.9	75.4	65.8	66.0	71.3
1985	54.7	62.2	68.4	70,7	77.2	82.4	82.1	82.3	79.8	79.4	73.0	58.8	72.6
1986	59.8	64.3	65.4	69.3	76.7	81.7	82.3	83.3	81.7	77.5	75.8	67.3	73.8
1987	58.8	62.7	65.9	66.8	76.8	83.1	83.5	85.0	82.7	72.2	69.0	64.2	72.6
1988 1989 1990 1991 1992	58.5 66.9 65.8 66.3 59.7	50.4 64.5 69.1 64.2 64.8	65,5 69,7 69,3 67,7 66,4	72.0 71.9 71.5 75.3 69.9	75.5 77.9 79.4 79.5 74.9	80.3 81.9 81.9 81.1 81.1 81.2	80.7 83.2 82.8 82.6 84.5	82.8 83.3 83.5 83.0 82.3	83.9 82.2 82.0 81.7 81.6	73.7 75.3 77.1 75.3 73.4	70.5 69.0 69.3 65.8 70.4	62.4 55.5 65.5 65.5 63.5	72.2 73.4 74.8 74.0 72.7
Record Mean Max Min	60.5 71.5 49.4	62.2 73.4 50.9	66.8 78.1 55.6	71.8 83.2 60.4 Se	77.3 88.2 66.3 e Befer	81.2 90.9 71.5 ence No	82.4 91.8 73.0	82.6 91.6 73.5 Page 68	81.0 89.6 72.4	74.8 84.1 65.6	67.6 77.9 57.3	62.2 72.9 51.4	72.6 82.8 62.3

HEATING DEGREE DAYS Base 65 deg. F

ORLANDO, FLORIDA

SEASON	JULY	AUG	SEP	OCT	NOV	DEC	JAN	FEB	MAR	APR	MAY	JUNE	TOTAL.
*1963-64 1964-65 1965-66 1966-67 1967-68	00000	00000	00000	3 7 1 20	72 14 19 70 29	272 84 112 169 80	235 178 215 119 191	199 89 122 157 293	39 822 725 149	40000	00000	00000	8454 544 544 74 74 74
1968-69 1969-70 1970-71 1971-72 1972-73	00000	00000	00000	19 0 0 0	120 93 120 26 54	237 204 79 105	168 316 165 51 160	206 187 115 124 169	16982 9924 12	00000 00000	00000	00000	919 858 591 240 509
#1973-74 1974-75 1975-76 1976-77 1976-77	00000	00000	00000	Φ004 Φ	13 40 85 118 38	193 163 174 197 179	0 73 278 440 275	173 44 104 218 255	15 57 18 41 71	8 10 1 8 0	00000	00000	408 387 660 1026 824
1978-79 1979-80 1980-81 1981-82 1982-83	00000	0000	00000	0 0 1 04	0 47 67 75 16	56 119 190 205 94	230 161 416 204 233	214 245 119 21 148	71 61 76 33 105	0 4 1 7 13	00000	00000	571 637 870 545 623
1983-84 1984-85 1985-86 1986-87 1987-88	00000	00000	00000	00000	63 68 14 0 39	188 71 228 42 97	252 340 180 216 221	137 146 82 97 169	862 205 105 48 71	18 12 66 7	00000	00000	744 659 613 469 604
1988-89 1989-90 1990-91 1991-92 1992-93	00000	00000	00000	01 00 0 0 0 0	11 27 14 85 47	135 308 69 76 102	32 71 75 187	119 34 88 79	59 11 52 51	4 50 19	0008	00000	350 477 304 505

See Reference Notes on Page 68 Page 5A

COOLING DEGREE DAYS Base 65 deg. F ORLANDO, FLORIDA

.

YEAR	JAN	FEB	MAR	APR	MAY	JUNE	JULY	AUG	SEP	ОСТ	NOV	DEC	TOTAL
1969 1970 1971 1972	12 19 77 181	10 14 97 44	32 128 90 146	232 330 238 243	376 399 411 391	544 511 505 524	608 586 569 570	540 544 573 561	495 565 510 509	406 380 440 374	68 77 167 179	16 72 214 148	3339 3625 3897 3870
1973 #1974 1975 1976 1977	88 213 105 18 1	28 51 121 75 13	207 183 141 194 192	198 207 237 196 182	421 410 442 374 324	548 463 489 449 534	602 492 489 549 537	529 536 541 529 521	501 510 479 474 536	341 241 366 247 257	199 125 167 65 185	58 43 49 62	3720 3474 360 3219 3344
1978 1979 1980 1981 1982	26 26 27 0 56	3 31 25 34 123	116 65 169 52 211	259 260 172 253 241	449 330 362 372 325	541 479 459 552 518	550 575 582 582 550	554292 554292 554292	508 498 508 458 465	321 299 3359 303	225 153 138 89 196	1153 532 752 152	3666 331 337 340 368
1983 1984 1985 1986 1987	22 37 27 25 32	11 35 74 69 38	68 84 137 124 82	129 151 191 139 127	361 332 386 372 376	473 411 531 506 549	573 490 539 543 582	582 520 548 573 627	476 426 451 507 540	362 331 454 392 230	959 992 2633 163	77 107 45 121 78	322 302 364 370 342
1988 1989 1990 1991 1992	26 101 102 121 28	43 111 156 71 79	95 213 156 143 101	223 216 206 315 175	336 408 453 455 325	466 509 514 490 496	496 5739 5533 552	559 579 565 565 540	573 523 518 508 507	275 346 388 326 265	182 153 149 118 217	61 19 116 98 62	3333 375 3899 376 340

See Reference Notes on Page 6B. Page 5B

SNOWFALL (inches)

ORLANDO. FLORIDA

SEASON	JULY	AUG	SEP	OCT	NOV	DEC	JAN	FEB	MAR	APR	MAY	JUNE	TOTAL
1970-71 1971-72	0.0	0.0	0.0 0.0	0.0	0.0	0.0	0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0	0.0	0.0
1972-73	ŏ.ŏ	0.0	0.0	ŏ.ŏ	0.0	0.0	0.0	0.0	ō.ŏ	0.0	0.0	0.0	0.0
#1973-74 1974-75	0.0	0.0	0.0	0.0	0.0	0.0 0.0	0.0	0.0 0.0	0.0 0.0	0.0	0.0 0.0	0.0	0.0 0.0
1975-76 1976-77	0.0	0.0	0.0	0.0	0.0	0.0	o o	0.0	0.0	0.0	0.0	0.0 0.0	0.0 T
1977-78	õ.õ	0.0	ō.ŏ	ŏ.ŏ	0.0	ŏ.ŏ	0.0	ō,ō	0.0	0.0	0.0	0.0	0.0
1978-79 1979-80	0.0	0.0	0.0	0.0 0.0	0.0	0.0 0.0	0.0 0.0	0.0	0.0	0.0	0.0 0.0	0.0	0.0
1980-81 1981-82	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 0.0	0.0 0.0
1982-83	0.0	õ.õ	ō.ō	õ,õ	0.0	ō.ō	0.0	ō,ō	ō,ō	0.0	0.0	0.0	0.0
1983-84 1984-85	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
1985-86 1986-87	0.0	0.0	0.0	0.0	0.0 0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
1987-88	õ.õ	õ.õ	0.0	0.0	0.0	õ.õ	0.0	ŏ.ŏ	0.0	0.0	0.0	0.0	0.0
1988-89 1989-90	0.0	0,0	0.0	0.0 0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 Ť
1990-91	ŏįŏ	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0_0	0 ₁ 0	0.0	0.0	0 <u>,</u> 0
1992-93	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0		'	0.0	0.0	1
Record Mean	I	т	0.0	0.0	0.0	0.0	T	0.0	т	т	0.0	0.0	т
	• •	• •	<u>−</u> ♥ (See			es on P		, ,		5.0		
						⊢age	01						

REFERENCE NOTES

ORLANDO, FLORIDA

EXCEPTIONS

GENERAL T - TRACE ANDUNT. BLANK ENTRIES DENOTE MISSING/UNREPORTED DATA. # INDICATES A STATION OR INSTRUMENT RELOCATION. SEE STATION LOCATION TABLE ON PAGE 8. SPECIFIC PAGE 2 PM - INCLUDES LAST DAY OF PREVIOUS MONTH ASOS - AUTOMATED SURFACE OBSERVING SYSTEM IN OPERATION DURING THESE MONTHS. PAGE 3 1.1 - LENGTH OF RECORD IN YEARS, ALTHOUGH INDIVIDUAL MONTHS MAY BE MISSING. 0.x OR * - THE VALUE IS BETHEEN 0.0 AND 0.05 NORMALS - BASED ON THE 1551-1980 RECORD PERIOD. EXTREMES - DATES ARE THE MOST RECENT OCCURRENCE MIND DIR. - NUMERALS SHON TENS OF DEGRESS CLOCKHISE FROM TRUE NORTH. "OO" INDICATES CALM. RESULTANT DIRECTIONS ARE GIVEN TO WHOLE DEGREES. BOL VALUES INDICATE EXTREME VALUES WHICH OCCURRED AFTER THE ASOS SYSTEM HAS COMMISSIONED. PAGE 4B RECORD FERIOD OF RECORD RECORD MAXINIS THEPERATURE IS THE MEAN OF ALL DAILY MAXIMIN TEMPERATURES DURING THE PERIOD OF RECORD. RECORD MAXINIS TEMPERATURE IS THE BUN OF THE RECORD. MAX AND RECORD MIN IS THE REAN OF THE RECORD. MAXIMIN TEMPERATURES DURING THE PERIOD OF RECORD. MAXIMIN TEMPERATURE IS THE SUM OF THE RECORD. MAXIMIN TEMPERATURE IS THE SUM OF THE RECORD. MAX AND RECORD MIN DIVIDED BY 2. AVERAGE TEMPERATURE IS THE SUM OF THE MEAN DAILY MAX AND HIN TEMPERATURE DIVIDED BY 2.

PAGES 4A, 4B, 6A RECORD MEANS ARE THROUGH THE CURRENT YEAR, BEGINNING IN 1943 FOR TEMPERATURE 1943 FOR PRECIPITATION 1943 FOR SNOWFALL

Page 68

Orlando is located in the central section of the Florida peninsula, surrounded by many lakes. Relative humidities remain high the year-round, with values near 90 percent at night and 40 to 50 percent in the afternoon. On some winter days, the humidity may drop to 20 percent.

The rainy season extends from June through September, sometimes through October when tropical storms are near. During this period, scattered afternoon thunderstorms are an almost daily occurrence, and these bring a drop in temperature to make the climate bearable. Summer temperatures above 95 degrees are rather rare. There is usually a breeze which contributes to the general comfort.

During the winter months rainfall is light. While temperatures, on infrequent occasion, may drop at night to near freezing, they rise rapidly during the day and, in brilliant sunshine, afternoons are pleasant. Frozen precipitation in the form of snowflakes, snow pellets, or sleet is rare. However, hail is occasionally reported during thunderstorms.

Hurricanes are usually not considered a great threat to Orlando, since, to reach this area, they must pass over a substantial stretch of land and, in so doing, lose much of their punch. Sustained hurricane winds of 75 mph or higher rarely occur. Orlando, being inland, is relatively safe from high water, although heavy rains sometimes briefly flood sections of the city.

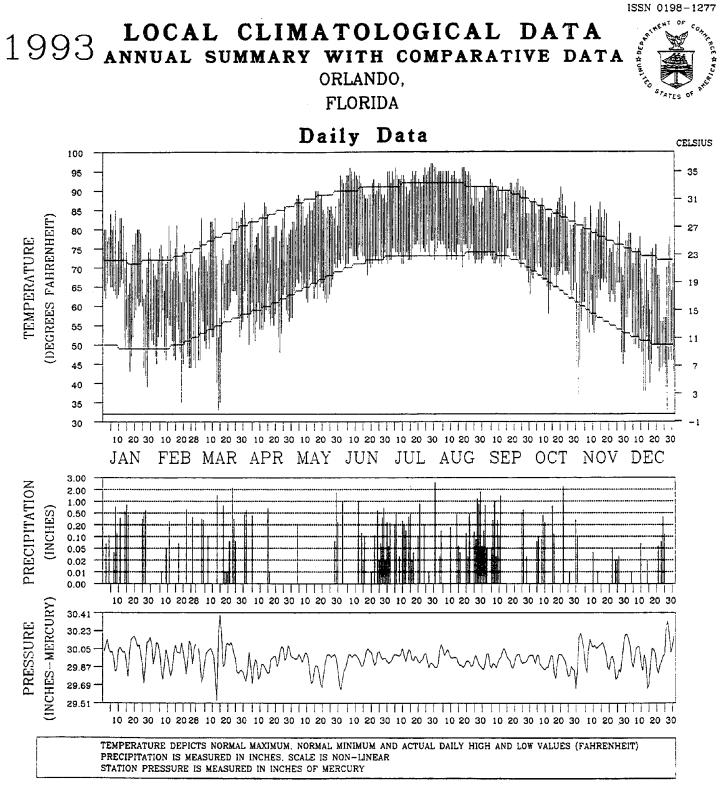
STATION LOCATION

		-		-
ORL	ANDO,	FL	ORI	DA

				-			· • •	••••								ORLANDO, FLORIDA
				Ļ	۲.			ELE	VATIO	ON AE	BOVE				Â	* Type
				Ŧ	м.	LEVEL			1	ROU	Ð				T	H = MOS T = AUTOB
LOCATION	OCCLIPIED FROM	BI 9000	AIRLINE DISTANCES AND DIRECTIONS FROM PREVIOUS LOCATION	Ť U E North	O NG IT D D E NEST	GROUND TEMPERATURE	WIND INSTRUMENTS	uxtrutu thurtoture	A SYUXRONUTUR	U A R H H K K K K K K K K K K K K K K K K K	RAHN GAGE	BUHGIMING RAHN GAGU	8 INCH RAIN GAGE	HYGROTHERMONETER	MATIC OBSERVING	REMARKS
COOPERATIVE NOTE:	or perio	d Januery	1892 throug	-	3, 1916	refe	to	prev	aus	edi	tian	•				
319 N. Orange Avenue	8/01/16	6/20/21	300 ft. N	28°33'	81°22'	107		4	.				3			
1022 South Hughey	6/21/21		1.3 mi.SS₩	28"32'	81°Z'	106		5					4			
946 Bradshaw Terrace			2000 ft. E	28"32'	81°Z'	80		5					4			
117 Annie Street			400 ft. S	28°32'	81°23'	80 67		4					2			
Fern Creek and Harding	11/11/31	5/1934	1 m.i. S	28"31"	81*22'	95		•					5			
1537 Clay Street Winter Park	5/1934	9/16/36	3.75 ml. MM	28°35 '	81°22'	93										
933 Bradshaw Terrace	9/17/36	12/1942	3 mi. S	28"32'	81°23'	80		5					3		ļ	
AIRPORT Terminal Building Municipal Airport 2 miles east of Post Office	1/01/43	1/03/51	2.6 mî. NE	28°33'	81°20'	106	a4 0	4	4			3	3			Observations were commenced at the airport by an airway ob- server on 4/1/29 and at a later date taken over by CAA. Weather Bureau effective 2/15/44. a - 44 feet to 9/10/47.
Administration Building Herndon Airport *	1/03/51	1/31/74	400 ft .um v	æሜ'	81°20'	g108	a2 0	Ы6	c16			ď13	e13	f4		 Name adopted 3/18/6]. a - 41 feet to 2/16/51 and 53 feet to 1/9/60 b - 6 feet to 2/16/50 and 18 feet to 12/1/63 c - 5 feet to 2/16/50 and 17 feet to 12/1/63 d - 3 feet to 3/11/52: 4 feet to 4/6/60 and 14 feet to 12/1/63. e - 3 feet to 12/1/63 f - Commissioned 12/1/63 on the to 12/1/63.
																field 1700 feet east of thermometer. g - 106 feet to 12/1/63.
Weather Service Office Orlando Jetport + at McCoy	1/31/74	9/19/84	8 mî. S	28°26'	81°19'	%	12 20ز	NA 15	₹ 20	NA	SCS	3021S	16222	NA A10	NA	A - AN/TMO-11 on field site. h - Effective 5/7/74. i - Effective 7/26/74. j - Effective 5/20/74. k - Added 3/18/76.
+ International Airport eff. 11/26/76														-		m - Hygrothermaneter commissioned 3/25/76. n - Relocated 7/22/77.
Weather Service Bldg. Orlando International Airport	9/19/84	Present	Unichowin	28°26'	81°19'	96	33	NA	6	NA	5	5	5	æ	NA	Noved from 9501 Benford Road to 5390 Bear Road p - Type change 5/30/85
SUBSCRIPTION: Price and ordering info	naetion a	i Vaitable 1	i i through: Net J	ional C INQUIRIE	i Simetic I Simetic	ata Co IS CAL	: Inter L: i	. Fei (704)	era Z/1	: 1. Bui - 480	i ldir D	ng, <i>I</i>	i Ishevi	ille	, No US	: rth Carolina 28801. COMM-NDAA-ASHEVILLE, N.C 500
National Climatic Data Cer Federal Building 37 Battery Park Avenue Asheville NC 28801-273:	ter												P	OS ^r	FI FA(RST CLASS GE & FEES PAID Department of Commerce
OFFICIAL BUSINESS PENALTY FOR PRIVAT FORWARD AND ADDR	e use se Ess cor	100 RECTION	ł													Permit No. G - 19

LCD-08-12815-PD-9309

45740 JHK & ASSOCIATES ATTN: M SCOTT MACCALDEN JR PO 30X 193727 SAN FRANCISCO CA 94119



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NATIONAL OCEANIC AND ATMOSPHERIC ADMINISTRATION NATIONAL ENVIRONMENTAL SATELLITE, DATA AND INFORMATION SERVICE NATIONAL CLIMATIC DATA CENTER ASHEVILLE NORTH CAROLINA

D Wallen DIRECTOR

NATIONAL CLIMATIC DATA CENTER

METEOROLOGICAL DATA FOR 1993

ORLANDO, FLORIDA

	28 °26' N I			19'W						04 71	NE 200			ANI 10015
LATITUDE:	20 25'N I	ONGITUDE	FEB	MAR	APR	וז: אסנו MAY	JUNE	96 E JULY	4	94 TI SEP	OCT	E: EASTE NOV	DEC	AN: 12815 YEAR
TEMPERATURE	°F:			1			1							
Average ≁Dail ∽Dail -Dail	es Ly Maximum Ly Minimum thfy thly Dewpt.	75.4 57.2 66.3 58.8	71.2 50.0 60.6 49.2	75.5 54.1 64.8 52.8	79,4 57,1 68.3 53,8	85.5 65.4 75.5 62.4	91.5 72.2 81.9 70.3	93.7 74.0 83.9 72.7	92.5 73.9 83.2 72.3	90.0 72.3 81.2 71.7	83.6 66.5 75.1 67.3	77.5 59.0 68.3 60.1	69.8 48.0 58.9 48.9	82.1 62.5 72.3 61.7
-High -Date -Lowe -Date	nest est	95 8 39 28	61 16 35 19	67 31 33 . 14	87 13 48 23	90 18 57 1	96 7 68 18	97 30 71 11	96 19 70 18	93 23 66 30	91 21 44 31	87 15 37 1	79 4 33 27	97 JUL 30 33 DEC 27
DEGREE DAYS Heating	S BASE 65 ^o f: G	73	131	80	12	0	0	0	0	0	10	45	201	552
Cooling		120	14	80	118	334	514	591	573	492	331	146	18	3331
% OF POSSIE	BLE SUNSHINE			ļ								ļ		
Sunrise Midnigh NUMBER DF D	VVER (tenths) - Sunset ht - Midnight MYS: to Sunset	8.1 7.3	6.7 6.4	6.4 6.2	5.7 4.9	5.7 5.2	6.0 5.4	6.4 5.8	6.2 5.4	6.3 5.6	6.9 6.5	6.3 6.1	6.2 5.3	6.4 5.8
-Clea	ar Ly Cloudy	3 6 22	5 11 12	8 7 16	8 14 8	8 12 11	5 16 9	1 18 12	5 14 12	3 17 10	7 6 18	7 9 14	9 6 16	69 136 160
Precipi .01 inc	tation thes or more	12	6	13	4	4	14	17	16	12	11	6	7	122
	pellets,hail hes or more	0	0	0	0	o	0	0	0	Ó	0	٥	0	0
Thunder	storms	3	2	5	3	2	12	25	18	10	5	0	2	87
Heavy Fo 1/4 mile	g, visibility or less	5	3	1	0	د ا	0	0	0	0	1	3	1	14
-Maxi 900 320	iture ^o F mum and above and below	0	0	0	0	3	20	30 0	23 0	25 0	1	0	00	102 0
-Minj 320 00	and below	0	0	0	0	0	0	0	00	00	0	C O	0	0
AVG. STATIO	N PRESS. (mb)	1016.6	1014.9	1014.2	1012.7	1012.2	1013.5	1014.2	1013.5	1013.9	1012.2	1015.9	1015.6	1014.2
RELATIVE HU Hour O1 Hour O7 Hour 13 Hour 19	(Local Time)	92 93 64 79	81 87 54 64	84 89 52 61	83 82 43 53	85 85 48 59	89 88 55 68	89 89 54 73	90 91 56 70	93 93 59 79	92 94 65 80	90 90 63 78	88 88 54 70	88 89 56 70
PRECIPITATI	ON (inches):							1						
-Tota	test (24 hrs)	4.89 1.30 15-16	1.48 0.65 22	6.26 2.35 23-24	1.78 0.71 15-16	2.32 1.80 29-30	4.47 1.03 2	6.49 2.60 31	5.95 2.58 28-29	5.35 1.47 11	4.61 2.27 22	0.17 0.05 22	0.76 0.52 24-25	44.53 2.60 JUL 31
-Tota	test (24 hrs)	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	T T 31	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	T JUL 31
-Spee Average Fastest -Dire	ction (!!) d (mph) Speed (mph) Obs. 1 Min, ction (!!)	039 2.4 8.5 34	330 1.7 9.2 25	244 1.7 11.0 24	249 0.1 10.4 21	100 3.6 9.8 13	112 2.4 8.1	205 2.2 6.8 21 35	158 1.8 7.4 29	079 2.8 7.1	355 2.7 8.4 20	008 5.1 9.3 22 22	324 4.2 9.4 26 26	030 0.9 8.8 24
-Spee -Date Peak Gu		25 26	24 12	46 13	26 1	21 29	33 12	35 31	30 14	23 26	26 30	22 6	26 15	46 MAR 13
-Dire	ction (!!) d (mph)	S 32 8	W 32 12	W 62 13	SE 38	W 30 20	E 46 12	SW 53 31	W 41 14	SW 40 1	SW 39 30	NE 29 26	W 35 15	W 62 MAR 13

(!!) See Reference Notes on Page 68 Page 2

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NORMALS, MEANS, AND EXTREMES ORLANDO, FLORIDA

					ORLAN	NDO, FL	ORIDA,							
LATITUDE: 28°26'N L	ONGI (a)		81 °19' FEB	₩ EL MAR	EVATION APR	: ft. g MAY		96 BARO JULY		TIME SEP	zone: e OCT	astern NOV	wв DEC	AN: 12815 YEAR
TEMPERATURE °F:														
Normals -Daily Maximum -Daily Minimum -Monthly		70.8 48.6 59.7	72.7 49.7 61.2	78.0 55.2 66.7	83.0 59.4 71.2	87.8 65.9 76.9	90.5 71.8 81.1	91.5 73.1 82.3	91.5 73.4 82.5	89.7 72.4 81.0	84.6 65.8 75.2	78.5 57.5 68.0	72.9 51.3 62.1	82.6 62.0 72.3
Extremes -Record Highest -Year -Record Lowest -Year	51 51	87 1991 19 1985	90 1962 28 1970	92 1970 25 1980	96 1968 38 1987	102 1945 48 1992	100 1985 53 1984	100 1961 64 1981	100 1980 64 1957	98 1988 56 1956	95 1986 43 1957	89 1992 29 1950	90 1978 20 1983	102 MAY 1945 19 JAN 1985
NORMAL DEGREE DAYS: Heating (base 65°F)		234	164	65	5	0	0	0	0	0	0	54	164	686
Cooling (base 65°F)		70	58	117	191	369	483	536	543	480	316	144	74	3381
% OF POSSIBLE SUNSHINE														
MEAN SKY COVER (tenths) Sunrise - Sunset MEAN NUMBER OF DAYS: Sunrise to Sunset	45	5.7	5.7	5.6	• 5.1	5.4	6.4	6.4	6.4	6.5	5.5	5.2	5.7	5.8
-Clear -Partly Cloudy -Cloudy Precipitation	45 45 45	9.0 10.2 11.8	8.6 8.7 11.0	9.2 10.4 11.4	10.2 11.4 8.4	8,8 13,5 8,7	4.2 14.3 11.5	3.4 16.7 10.9	3.1 17.0 10.9	3.8 14.6 11.6	9.6 11.2 10.2	10.2 10.2 9.6	9.8 9.2 12.1	89.9 147.3 128.1
.01 inches or more Snow,Ice pellets,hail	51	6.3	6.9	7.7	5.5	8.5	14.0	17.1	15.0	13.6	8.5	5.7	5.9	115.8
1.0 inches or more	51	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
Thunderstorms Heavy Fog Visibility	49	1,0	1.5	2.9	3.4	7.6	14.6	19.3	17.5	9.7	2.6	1.1	1.1	82.3
1/4 mile or less Temperature F	45	5.5	3.2	2.5	1.4	1.4	0.8	0.5	0.9	1.2	1.7	2.7	4.3	26.1
-Maximum 90° and above 32° and below -Ninimum	30 30	0.0 0,0	0.0	0.4 0.0	3.9 0.0	10,7 0,0	19.6 0.0	25.2 0.0	25.5 0.0	18.7 0.0	3.4 0.0	0.0 0.0	0.* 0.0	107.5 0.0
-Ninimum 32° and below 0° and below	30 30	1.5 0.0	0.5	0.1	0.0	0.0	0.0 0.0	0.0	0.0	0.0	0.0	0.1	0.6	2.8 0.0
AVG. STATION PRESS. (mb)	21	1016.6	1015.8	1014.3	1013.6	1012.4	1012.9	1014.4	1013.8	1012.6	1013.4	1015.3	1016.8	1014.3
RELATIVE HUMIDITY (%) Hour 01 Hour 07 Hour 13 Hour 19	29 30 30 30	85 88 56 69	83 87 52 63	84 88 50 61	84 87 46 58	86 88 49 62	-189 -189 -189 -199 -199 -199 -199 -199	90 90 58 75	91 92 60 77	90 92 60 77	87 89 56 74	87 89 56 73	87 88 57 73	87 89 55 70
PRECIPITATION (inches): Water Equivalent -Maximum Monthly -Year -Minimum Monthly -Year -Maximum in 24 hrs -Year	51 51 51	2.30 7.23 1986 0.15 1950 4.19 1986	3.02 8.32 1983 0.10 1944 4.38 1970	3.21 11.38 1987 0.16 1956 5.03 1960	1.80 9.10 1992 0.14 1977 5.65 1992	3.55 10.36 1976 0.43 1961 3.18 1980	7.32 18.28 1968 1.97 1948 8.40 1945	7.25 19.57 1960 2.50 1992 8.19 1960	6.78 16.11 1972 2.92 1980 5.29 1949	6.01 15.87 1945 0.43 1972 9.67 1945	2.42 14.51 1950 0.35 1967 7.74 1950	2.30 10.29 1987 0.03 1967 5.87 1988	2.15 5.33 1983 1 1944 3.61 1969	48.11 19.57 JUL 1960 T DEC 1944 9.67 SEP 1945
Snow,Ice pellets,hail -Maximum Monthly -Year -Maximum in 24 hrs -Year	21 21	1977 1977 1977	0.0	T 1992 T 1992	T 1992 T 1992	0.0 0.0	0.0 0.0	T 1993 1993	ĭ 1989 T 1989	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	JUL 1993 JUL 1993 JUL 1993
WIND: Mean Speed (mph)	45	9.0	9.6	9.9	9.4	8,8	8,0	7.4	7.2	7.6	8.6	8.7	8.6	8.5
Prevailing Direction through 1963		NNE	Ş	S	SE	SE	SW	S	S	ENE	Ň	N	NNE	S
Fastest Obs. 1 Min. -Direction (!!) -Speed (MPH) -Year	44 44	25 42 1953	25 46 1969	24 46 1993	02 50 1956	17 46 1981	32 54 1970	14 46 1961	32 50 1957	24 46 1969	05 48 1950	26 46 1958	07 32 1968	32 64 JUN 1970
Peak Gust -Direction (!!) -Speed (mph) -Date	10 10	NW 48 1991	W 51 1991	W 62 1993	53 1992	S 68 1991	W 62 1985	₩ 68 1991	SW 58 1991	NW 54 1988	W 40 1990	NE 41 1984	W 43 1984	W 68 JUL 1991

(11) See Reference Notes on Page 68. Page 3

PRECIPITATION (inches)

ORLANDO, FLORIDA

YEAR	JAN .	FEB	MAR	APR	MAY	JUNE	JULY	AUG	SEP	OCT	NOV	DEC	ANNUAL
1964 1965 1966 1967 1968	6.18 1.79 4.45 0.84 0.65	3.42 3.67 6.31 5.49 2.76	4.65 3.02 2.57 1.31 2.27	2,14 0,62 1,98 0,30	2.74 0.52 6.57 1.69 3.72	6.11 7.36 9.77 11.16 18.28	6.68 11.55 6.73 4.63 5.60	9.00 5.49 7.76 6.83 3.44	9.47 5.99 6.25 5.88 5.91	1.64 4.06 1.98 0.35 5.47	0.45 1.09 0.03 2.82	1.91 2.23 0.99 2.42 0.88	54.39 47.40 55.39 40.91 52.10
1969	2.22	3.30	5.52	2.38	1.40	5.04	6.73	7.17	6.44	9.45	0.87	4.66	55.18
1970	4.05	6.77	3.66	0.45	4.08	4.92	5.97	5.91	3.25	2.60	0.24	2.06	43.96
1971	0.45	2.98	1.46	1.52	4.31	4.39	8.29	7.51	2.98	3.06	1.21	1.93	40.09
1972	0.99	4.96	5.06	1.39	3.76	6.33	3.98	16.11	0.43	2.34	4.11	1.89	51.35
1973	4.82	2.73	4.13	2.82	4.74	6.63	6.24	7.33	11.53	1.10	0.74	2.56	55.37
#1974	0.18	0.63	3.57	1.17	2.69	15.28	6.01	6.56	5.78	0.48	0.31	1.62	44.38
1975	0.98	1.49	1.10	1.36	7.52	9.70	9.26	4.75	4.97	4.74	0.66	0.51	47.04
1976	0.37	0.83	1.72	2.16	10.36	9.93	7.05	3.25	5.87	0.74	2.03	2.77	47.08
1977	1.81	1.76	1.82	0.14	1.47	4.47	6.61	6.28	7.03	0.43	2.60	3.70	38.12
1978	2.49	5.45	2.14	0.61	3.16	10.00	11.92	5.13	4.31	1.51	0.18	3.69	50.59
1979	6.48	1.45	3.24	1.08	7.66	4.00	7.95	5.88	9.19	0.43	1,93	0.94	50.23
1980	2.45	1.64	1.51	4.07	6.96	5.25	5.14	2.92	3.70	0.55	6,550	0.47	41.21
1981	0.21	4.36	1.85	0.18	2.02	12.49	3.53	5.60	8.26	3.13	2,553	2.97	47.10
1982	1.72	1.34	4.85	6.27	5.29	6.06	11.81	5.03	6.95	0.74	0,536	1.01	51.61
1983	2.08	8.32	5.37	3.21	1.77	7.82	6.49	4.83	5.16	3.78	1,36	5.33	55.52
1984	2.01	2,73	1.85	6.21	3.20	5,32	6.19	7.89	6.19	0.56	2.10	0.19	44.44
1985	0.91	1,27	4.59	1.69	3.00	4,54	7.28	11.63	5.45	2.55	0.82	3.46	47.19
1986	7.23	1,84	2.63	0.49	0.88	9,50	5.85	5.99	4.50	5.63	1.69	3.60	49.83
1987	1.27	1,74	11.38	0.59	1.40	3,54	7.95	6.07	8.64	3.41	10.29	0.51	56.79
1988	3.12	1,38	6.07	2.02	2.82	4,17	9.44	7.94	5.67	1.42	7.44	1.00	52.49
1989	3.80	0.15	1.35	2.28	2,38	6.79	4.74	6.20	10.29	1.75	1.44	4.49	45.66
1990	0.23	4.13	1.92	1.73	0,55	6.22	6.68	3.78	2.46	2.10	1.05	0.83	31.68
1991	2.37	0.98	6.66	7.72	9,48	5.98	10.78	7.13	4.53	4.76	0.27	0.24	60.90
1992	1.35	2.42	3.67	9.10	1,19	8.68	2.60	8.03	7.13	5.17	2.74	0.88	52.96
1993	4.89	1.48	6.26	1.78	2,32	4.47	6.49	5.95	5.35	4.61	0.17	0.76	44.53
Record Mean	2.23	2.70	3.53	2.62 Se	3.40 e Refer	6.98 ence No Page	7.83 tes on e 4A	6.68 Page 6B	6.74	3.36	1.88	1.91	49.84

AVERAGE TEMPERATURE (deg. F) ORLANDO. FLORIDA

1964		FEB	MAR	APR	MAY	JUNE	JULY	AUG	SEP	OCT	NOV	DEC	ANNUAL
1965 1966 1967 1968	58.5 60.7 58.2 59.6	58.3 64.1 62.3 60.0 54.8	68.1 67.0 64.4 68.3 61.4	74.1 74.8 70.5 74.3 73.5	77.1 77.1 77.4 78.3 76.7	82.4 79.0 78.0 80.2 78.8	81.6 80.5 82.3 82.4 81.3	82.8 82.2 82.3 82.0 82.3	79.8 80.8 80.1 79.7 80.3	72.5 74.2 75.8 74.0 74.3	70.5 69.5 65.8 67.5 63.4	64:4 62.6 60.1 65.9 58.7	72.5 72.7 71.5 73.0 70.4
1959	59.8	57.8	60.4	72.5	76.9	82.9	84.4	82.2	81.2	77.9	64.0	58.7	71.6
1970	55.1	58.7	67.0	75.8	77.7	81.8	83.8	82.3	83.6	77.0	63.4	64.6	72.6
1971	62.0	64.1	64.8	72.1	78.2	81.7	83.1	83.3	81.8	79.0	69.5	71.4	74.2
1972	68.9	62.0	68.7	72.7	77.4	82.2	83.2	82.8	81.8	76.8	68.9	66.1	74.3
1973	62.4	59.7	71.1	71.1	78.3	83.1	84.2	81.8	81.4	75.6	70.9	60.4	73.3
#1974	71,6	60.5	70.2	71,4	78,0	80.3	80.7	82.0	81,8	72.6	67,6	60,9	73.1
1975	65,8	67.6	67.4	72,4	79,1	80.8	80.5	82.3	80,7	76.6	67,4	60,2	73.4
1976	56,5	63.7	70.4	71,3	76,8	79.7	82.4	81.9	80,5	72.6	63,0	60,1	71.6
1977	50,6	57.4	69.7	70,6	75,2	82.6	82.0	81.5	82,6	72.9	69,6	61,0	71.3
1978	56,8	55.8	66.3	73,4	79,3	82.9	82.6	82.6	81,7	75.0	72,3	65,8	73.0
1979	58.2	58.4	64.6	73.4	75.4	80.7	83.3	82.4	81.3	74.4	68,3	62.6	71.9
1980	60.5	57.2	68.2	70.4	76.4	80.1	83.6	83.6	81.7	75.4	67.1	59.0	71.9
1981	51.3	61.7	64.0	73.1	76.7	83.2	84.1	82.9	80.0	76.4	65.3	60.5	71.6
1982	60.0	68.4	70.4	72.6	75.3	82.0	82.6	82.2	80.2	74.1	70.8	66.7	73.8
1983	58.0	59.9	63.5	68.6	76.4	80.5	83.2	83.5	80.5	76.5	65.8	61.2	71.5
1984	57.8	61.2	64.7	69.2	75.6	78.4	80.7	81.5	78.9	75.4	65.8	66,0	71.3
1985	54.7	62.2	68.4	70.7	77.2	82.4	82.1	82.3	79.8	79.4	73.0	58,8	72.6
1986	59.8	64.3	65.4	69.3	76.7	81.7	82.3	83.3	81.7	77.5	75.8	67,3	73.8
1987	58.8	62.7	65.9	66.8	76.8	83.1	83.5	85.0	82.7	72.2	69.0	64,2	72.6
1988	58.5	60.4	65.5	72.0	75.5	80.3	80.7	82.8	83.9	73.7	70.5	62,4	72.2
1989	66,9	64.5	69.7	71.9	77.9	81,9	83.2	83.3	82.2	75.3	69,0	55.5	73.4
1990	65.8	69.1	69.3	71.5	79.4	81,9	82.8	83.5	82.0	77.1	69,3	66.3	74.8
1991	66.3	64.2	67.7	75.3	79.5	81,1	82.6	83.0	81.7	75.3	65,8	65.5	74.0
1992	59.7	64.8	66.4	69.9	74.9	81,2	84.5	82.3	81.5	73.4	70,4	63.5	72.7
1993	66.3	60.6	64.8	68.3	75.5	81,9	83.9	83.2	81.2	75.1	68,3	58.9	72.3
Record Mean Max Min	60.5 71.6 49.5	62.2 73.4 50.9	66.8 78.0 55.5	71.8 83.1 60.4 Se	77.2 88.1 56.3 e Refer	81.2 90.9 71.5 ence_No	82.4 91.8 73.0 tes on 4B	82.6 91.6 73.5 Page 6B	81.0 89.6 72.4	74.8 84.0 65.6	67.6 77.8 57.4	62.1 72.8 51.3	72,5 82,7 62,3

HEATING DEGREE DAYS Base 65 deg. F ORLANDO. FLORIDA

SEASON	JULY	AUG	SEP	OCT	NOV	DEC	JAN	FEB	MAR	APR	MAY	JUNE	TOTAL
1964-65 1965-66 1966-67 1967-68 1968-69	00000	00000	00000	7 1 2 19	14 19 70 29 120	84 112 169 80 237	178 215 119 191 168	89 122 157 293 206	82 725 249 149	00000	00000	00000	4546220 55420 571 91
1969-70 1970-71 1971-72 1972-73 #1973-74	00000	00000	00000	r000	93 120 26 54 13	204 79 105 193	316 165 51 160 0	187 115 124 169 173	58 92 12 15	00 20 69 8	00000	00000	858 591 240 509 408
1974-75 1975-76 1976-77 1977-78 1978-79	00000	00000	00000	004 40	40 85 118 38 0	163 174 197 179 56	73 278 440 275 230	44 104 218 255 214	57 18 41 71 71	10 1 8 0 0	00000	00000	387 660 1026 824 571
1979-80 1980-81 1981-82 1982-83 1983-84	00000	00000	00000	0 1 14 0	47 67 75 16 63	119 190 205 94 188	161 416 204 233 252	245 119 21 148 137	61 763 105 86	4 1 7 13 18	00000	00000	637 870 545 623 744
1984-85 1985-86 1986-87 1987-88 1988-89	00000	00000	00000	00000	68 14 0 39 11	71 228 42 97 135	340 180 216 221 32	146 82 97 169 119	2058 1049 719	12 4 66 7 4	00000	00000	659 613 469 604 360
1989-90 1990-91 1991-92 1992-93 1993-94	0000	00000	00000	21 6 0 10	27 14 85 45 45	308 69 76 102 201	71 75 187 73	34 88 79 131	11 52 51 80	50 19 12	00080	0000	477 304 505 445

See Reference Notes on Page 68. Page 5A

COOLING DEGREE DAYS Base 65 deg. F ORLANDO, FLORIDA

YEAR	JAN	FEB	MAR	APR	MAY	JUNE	JULY	AUG	SEP	ост	NOV	DEC	TOTAL
1969 1970 1971 1972 1973	12 19 77 181 88	10 14 97 44 28	32 128 90 146 207	232 330 238 243 198	376 399 411 391 421	544 511 505 524 548	608 586 569 570 602	540 544 573 561 529	495 565 510 501 501	406 380 440 374 341	68 77 167 179 199	16 72 214 148 58	3339 3625 3891 3870 3720
#1974 1975 1976 1977 1978	213 105 18 1 26	51 121 75 13 3	183 141 194 192 116	207 237 196 182 259	410 442 374 324 449	463 481 449 534 541	492 489 549 537 550	534 549 521 553	510 479 474 536 508	241 366 247 257 321	125 167 65 185 225	43 329 492 115	3474 3601 3219 3344 3666
1979 1980 1981 1982 1983	26 27 0 56 22	31 25 34 123 11	65 169 52 211 68	260 172 253 241 129	330 362 372 325 361	479 4592 518 473	575 586 602 550 573	555522 555522	498 508 458 465 476	299 331 359 303 362	153 138 196 195	53 12 732 152 77	3315 3371 3403 3682 3229
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See Reference Notes on Page 6B. Page 5B

SNOWFALL (inches)

ORLANDO, FLORIDA

SEASON	JULY	AUG	SEP	OCT	NOV	DEC	JAN	FEB	MAR	APR	MAY	JUNE	TOTAL
1970-71 1971-72 1972-73 #1973-74	0.0 0.0 0.0 0.0	0.0 0.0 0.0	0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0	0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0	0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0
1974-75 1975-76 1976-77 1977-78 1978-79	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0	0.0 0.0 T 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0	0.0 0.0 T 0.0 0.0
1979-80 1980-81 1981-82 1982-83 1983-84	0.0 0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0,0 0,0 0,0 0,0		0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0		0.0 0.0 0.0 0.0 0.0
1984-85 1985-86 1986-87 1987-88 1988-89	0.0 0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.00	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0
1989-90 1990-91 1991-92 1992-93 1993-94	0.0 0.0 T 0.0 T	T 0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0	0,0 0,0 0,0 0,0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 T 0.0	0.0 0.0 T 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0	0.0 T 0.0
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REFERENCE NOTES

ORLANDO, FLORIDA

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GENERAL T - TRACE AMOUNT. BLANK ENTRIES DENOTE HISSING/UNREPORTED DATA. # INDICATES A STATION OR INSTRUMENT RELOCATION. SEE STATION LOCATION TABLE ON PAGE 8. SPECIFIC PAGE 2 PM - INCLUDES LAST DAY OF PREVIOUS MONTH ASDS - AUTOMATED SURFACE OBSERVING SYSTEM IN OPERATION DURING THESE MONTHS. PAGE 3 (a1 - LENGTH OF RECORD IN YEARS, ALTHOUGH INDIVIDUAL MONTHS MAY BE HISSING. 0.* OR * - THE VALUE IS BEIWEEN 0.0 AND 0.05 NORMALS - BASED ON THE 1961-1990 RECORD PERIOD. EXTREMES - DATES ARE THE MOST RECORD TO COURRENCE WIND DIR.- NUMERALS SHOW TENS OF DEGRESS CLOCKHISE FROM TRUE NORTH. "OO" INDICATE SCHWEN TO WHOLE DEGREES. BOLD VALUES INDICATE EXTREME VALUES WHICH OCCURRED ATTER THE ASOS SYSTEM WAS COMMISSIONED. PAGE 4B RECORD MEAN PRECIPITATION IS THE MEAN OF ALL DAILY PRECIPITATION AMOUNTS DURING THE PERIOD OF RECORD. RECORD MEAN TEMPERATURES IS THE MEAN OF ALL DAILY MAXIMIN) TEMPERATURE IS THE SUM OF THE RECORD. RECORD MEAN THEPERATURE IS THE SUM OF THE RECORD. RECORD MEAN TEMPERATURE IS THE SUM OF THE RECORD. RECORD MEAN TEMPERATURE IS THE SUM OF THE RECORD. RECORD MEAN TEMPERATURE IS THE SUM OF THE RECORD. RECORD MEAN TEMPERATURE IS THE SUM OF THE RECORD. MAX AND RECORD MIN OTVIDED BY 2.

EXCEPTIONS PAGES 4A, 4B, 6A RECORD MEANS ARE THROUGH THE CURRENT YEAR, BEGINNING IN 1943 FOR TEMPERATURE 1943 FOR PRECIPITATION 1943 FOR SNOWFALL

Page 6B

Orlando is located in the central section of the Florida peninsula, surrounded by many lakes. Relative humidities remain high the year-round. with values near 90 percent at night and 40 to 50 percent in the afternoon. On some winter days, the humidity may drop to 20 percent.

The rainy season extends from June through September, sometimes through October when tropical storms are near. During this period, scattered afternoon thunderstorms are an almost daily occurrence, and these bring a drop in temperature to make the climate bearable. Summer temperatures above 95 degrees are rather rare. There is usually a breeze which contributes to the general comfort.

During the winter months rainfall is light. While temperatures, on infrequent occasion, may drop at night to near freezing, they rise rapidly during the day and, in brilliant sunshine, afternoons are pleasant. Frozen precipitation in the form of snowflakes. snow pellets, or sleet is rare. However, hail is occasionally reported during thunderstorms.

Hurricanes are usually not considered a great threat to Orlando, since, to reach this area, they must pass over a substantial stretch of land and, in so doing, lose much of their punch. Sustained hurricane winds of 75 mph or higher rarely occur. Orlando, being inland, is relatively safe from high water, although heavy rains sometimes briefly flood sections of the city.

Notice of Correction

Any previously received edition of the "Local Climatological Data Annual Summary for 1993" should be discarded. This revised edition contains updates to the "Normals" based upon the 1961-1990 record period as noted in the "Reference Notes" on Page 6B.

STATION LOCATION

ORLANDO, FLORIDA

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LOCATION	OCCLIPIED FROM	OCCUPIED	AIRLINE DISTANCES AND DIRECTIONS PREVIOUS LOCATION	† U ₽ E	N T U E Hest		NHRD HRSTRUEER	UXFRUXU FRUREORUFURO		SHHNE SUHTCH	RAHR GAGE	WEIGHING RAIN GAGE	8 INCH RALN GAGE	HY GROTHEWREDEWITHER		
COOPERATIVE NOTE:			1892 throug				to	prev	ous	edit	ions	}.	.,			
319 N. Orange Avenue	8/01/16		300 ft. N	28°33'	81°22'	107		4					3			
1022 South Hughey	6/21/21		1.3 mi.SSW	28°32	81°23'	106		5					4			
946 Bradshaw Terrace			2000 ft. E	28°32'	81°23'	80		5					4		}	
117 Annie Street			400 ft. S	28°32'	81°231	80		4					2 3			
Fern Creek and Harding Avenue	11/11/31		1 mi. S	28°31	81°22'	95		4					2			
1537 Clay Street Winter Park	5/1934	9/16/36	3.75 mi. NNW	28°35'	81°22'	93							_	a .		
933 Bradshaw Terrace	9/17/36	12/1942	3 mi. S	28°32'	81°23'	80		5					3		ł	
AIRPORT Terminal Building Municipal Airport 2 miles east of Post Office	1/01/43	1/03/51	2.6 mi. NE	28°33'	81°20'	106	ə40	4	4			3	3			Observations were commenced at the airport by an airway ob- server on 4/1/29 and at a later date taken over by CAA. Weather Bureau effective 2/15/44, a - 44 feet to 9/10/47.
Administration Building Herndon Airport *	1/03/51	1/31/74	400 ft.www	28°33'	81°20'	g108	a20	b16	c16			d13	e13	f4		* Name adopted 3/18/61 a - 41 feet to 2/16/51 and 53 b - 6 feet to 1/2/60 and 18 feet to 1/2/60 and 18 feet to 1/2/63 c - 5 feet to 4/60 and 17 feet to 1/2/63 d - 3 feet to 3/1/52; 4 feet to 3/1/52 d feet to
Weather Service Office Orlando Jetport + at McCoy + International Airport eff. 11/26/76		9/19/84	8 mĩ. S	28°26'	81°19†	96	j12 j20	ŇĐ	2556	NA	SUG	2772 2772	163 13	NA A10 M4		 e - 3 feet to 4/6/60 and 14 feet to 12//60 and 14 f - Commissioned 12/1/63 an field 1700 feet east of themmometer. g - 100 feet to 12/1/63. A - AN/TMQ-11 on field site. h - Effective 2/7/74. i - Effective 2/7/74. j - Effective 5/20/74. K - Added 3/18/76. m - Hygrothermaneter commissioned 3/25/76. n - Relocated 7/22/77.
Weather Service Bldg. Orlando International Airport	9/19/84	Present	Unknown	28°26'	81°19'	96	33	NA	6	NA	5	5	5	p2	NA	Moved from 9501 Benford Road to 5390 Bear Road p - Type change 5/30/85
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National Climatic Data Cc Federal Building 37 Battery Park Avenue Asheville NC 28801-273 OFFICIAL BUSINESS PENALTY FOR PRIVAT FORWARD AND ADDF	nter 3 TE USE S	300											P ted :	OS Stat	FI TA es I	RST CLASS GE & FEES PAID Department of Commerce Permit No. G - 19

NOV 1993 PHOENIX, AZ NATIONAL WEATHER SERVICE OFC. 2633 EAST BUCKEYE ROAD

INQUIRIES/COMMENTS CALL (704) 271-4800

LOCAL CLIMATOLOGICAL DATA

ISSN 0198-0475



SKY HARBOR INTL AIRPORT

Monthly Summary

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			TEMPE	RATURE	٩		DEGREE Base	DAYS 65°F		ICE PELLETS	PRECIPI	TATION	STATION			W [M]	IND P.H.	1			SUNSHI	INE	SKY CO (Tenti	
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I CERTIFY THAT THIS IS AN OFFICIAL PUBLICATION OF THE NATIONAL OCEANIC AND ATMOSPHERIC ADMINISTRATION, AND IS COMPILED FROM RECORDS ON FILE AT THE NATIONAL CLIMATIC DATA CENTER



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MAXIMUM SHORT DURATION PRECIPITATION

TIME PERIOD (MINUTES)	5	10	15	20	30	45	60	80	100	120	150	180
PRECIPITATION (INCHES)	0.05	0.09	0.12	0.15	0.19	0.24	0.28	0.34	0.40	0.44	0.51	0.59
ENDED: DATE	14	14	14	14	14	14	14	14	14	14	14	14
ENDED: TIME	1314	1312	1317	1317	1317	1325	1340	1408	1420	1432	1821	1844

THE PRECIPITATION AMOUNTS FOR THE INDICATED TIME INTERVALS MAY OCCUR AT ANY TIME DURING THE MONTH. THE TIME INDICATED IS THE ENDING TIME OF THE INTERVAL. DATE AND TIME ARE NOT ENTERED FOR TRACE AMOUNTS.

PAGE 2

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WEATHER CODES .

* Q R R Z R Z R	TORNADO THUNDERSTORM SGUALL RAIN RAIN SHOWERS FREEZING RAIN DRIZZLE	SW SG SP IP IPW	SNOW SHOWERS SNOW GRAINS SNOW PELLETS ICE CRYSTALS ICE PELLETS ICE PELLET SHOWERS HAIL	GF BDN BSY K	GROUND FOG BLOWING DUST BLOWING SAND BLOWING SNOW BLOWING SPRAY SMOKE HAZE
ZR				ĸ	
L		Α.	HAIL	H	HAZE
ΖL	FREEZING DRIZZLE	F	FOG	D	DUST
S	SNOW	IF	ICE FÓG		

CEILING: UNL INDICATES UNLIMITED WIND DIRECTION: DIRECTIONS ARE THOSE FROM WHICH THE WIND BLOWS, INDICATED IN TENS OF DEGREES FROM TRUE NORTH: I.E., 09 FOR EAST, 18 FOR SOUTH 27 FOR WEST. AN ENTRY OF OC INDICATES CALM. SPEED: THE OBSERVED AVERAGE ONE-MINUTE VALUE, EXP RESSED IN KNOTS (MPH=KNOTS X 1,15).

PAGE 3

SUMMARY BY HOURS

			AV	ERAG	ES				ILTANT IND
	HS1		TEMI	PERAT	IURE		_		
H008 L.S.T	SKY COVER (FENINS)	STATION PRESSURE	AIR ILHP of	HEI BULB OF	DEN POINT OF	REL HUMIDITY X	NIND SPEED THPHI	DERECTION	SPEED (MPH)
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NATIONAL CLIMATIC DATA CENTER Federal Building	FIRST CLASS
37 BATTERY PARK AVE Asheville, North Carolina 28801-2733	POSTAGE AND FEES PAID
OFFICIAL BUSINESS	NDAA
PENALTY FOR PRIVATE USE \$300	PERMIT G-19

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LOCAL CLIMATOLOGICAL DATA Monthly Summary



SKY HARBOR INTL AIRPORT

LATITUDE 33° 26'N

INQUIRIES/COMMENTS CALL (704) 271-4800

LONGITUDE 112° 01'W

ELEVATION (GROUND) 1110 FEET

TIME ZONE MOUNTAIN

23183

			TEMPE	RATURE	°F		DEGREE Base	65°F	WEATHER TYPES	SNOW ICE PELLETS	PRECIPI	TATION	AVERAGE STATION PRESSURE			1 (M)	W1ND .P.H.				SUNSH	INE	SKY CO (Tent	
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* EXTREME FOR THE MONTH - LAST OCCURRENCE IF MORE THAN ONE. T TRACE AMOUNT. + ALSO ON EARLIER DATE(S). HEAVY FOG: VISIBILITY 1/4 MILE OR LESS. BLANK ENTRIES DENOTE MISSING OR UNREPORTED DATA.

DATA IN COLS 6 AND 12-15 ARE BASED ON 21 OR MORE OBSERVATIONS AT HOURLY INTERVALS. RESULTANT WIND IS THE VECTOR SUM OF WIND SPEEDS AND DIRECTIONS DIVIDED BY THE NUMBER OF OBSERVATIONS. COLS 16 & 17: PEAK GUST - HIGHEST INSTANTANEOUS WIND SPEED ONE OF TWO WIND SPEEDS IS GIVEN UNDER COLS 18 & 19: FASTEST MILE - HIGHEST RECORDED SPEED FOR WHICH A MILE OF WIND PASSES STATION (DIRECTION IN COMPASS POINTS). FASTEST OBSERVED ONE MINUTE WIND - HIGHEST ONE MINUTE SPEED IDIRECTION IN TENS OF DEGREESJ. ERRORS WILL BE CORRECTED IN SUBSEQUENT PUBLICATIONS.

I CERTIFY THAT THIS IS AN OFFICIAL PUBLICATION OF THE NATIONAL OCEANIC AND ATMOSPHERIC ADMINISTRATION, AND IS COMPILED FROM Records on file at the National Climatic data center



DEC 1993

NATIONAL OCEANIC AND ATMOSPHERIC ADMINISTRATION

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NATIONAL ENVIRONMENTAL SATELLITE, DATA AND INFORMATION SERVICE

NATIONAL CLIMATIC DATA CENTER ASHEVILLE NORTH CAROLINA

Kenneth D Wadeen

DIRECTOR NATIONAL CLIMATIC DATA CENTER

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02 05 08 11 14 17 20 23	- 21	UNL UNL UNL UNL UNL UNL UNL	35 35 60 60 35 35				48 47 46 50 70 72 58 54	41 39 45 49 51 47 46	31 29 27 25 26 34 36	52 50 52 29 18 18 41 51	11 07 09 13 13 00 11	6 4 7 5 4 0 6	7 9 10 10 9 9 8	UNL 250 250 250 250 200 200	35 45 45 45 35 35				49 50 51 58 65 63 57 53	43 42 46 50 50 49 47	35 32 31 33 35 40 40	59 50 47 39 30 37 53 52	11 12 10 08 13 00 34 00	4 5 7 5 4 0 3 0	1 0	UNL UNL UNL UNL UNL UNL UNL UNL	35 35 35 35 35 35 35 35 35			4 4 4 5 7 7 6 5	445554	52283307	11 39 36 36 36 36 36 36 36 36 36 36 36 36 36	74 80 66 42 29 28 46 59	11 36 07 13 36 31 31 08	4 4 5 3 4 3 3 3 3
				[EC '	10th											DEC 1	1th				•							DEC 12					1	•••	
02 05 08 11 14 17 20 23	3 8 9	UNL UNL UNL UNL UNL UNL 250	30 35 50 50 55 50 55 55 55 55 55 55 55 55 55				51 47 62 71 72 58	45 42 48 53 53 50 48	38 37 36 33 35 35 35 38 37	61 68 66 34 27 26 41 46	11 10 14 14 32 26 28 13	47533643	9 7 8 7 9 6 10 9	180 140 140 140 140 UNL 100 90	3550 555 555 355 355 355		RW		54 55 55 71 64 60	46 47 48 51 55 53 52 52	37 40 38 40 37 41 45	53 59 57 37 33 30 43 58	09 10 12 09 27 26 10 33	4 8 3 5 7 3 5 6	10 0 0 2 0 0 0	60 UNL UNL UNL UNL UNL UNL	35 350 60 60 35 35			55556655		3 7 5 5 5 7 7 3 1	47 39 37 32 31 28 30 27	65 55 39 32 28 40 40	00 29 28 29 27 27 27 28	0 14 9 16 12 11 5 6
				[EC -	13th											DEC 1	4th											DEC 15							
02 05 08 11 14 17 20 23	0010232	UNL UNL UNL UNL UNL UNL UNL UNL	35 35 50 50 35 35				46 42 55 62 55 49	40 39 38 44 45 46 45 45 42	31 34 31 24 27 32 33	56 73 63 23 23 27 42 54	08 14 08 12 35 31 26 08	3 4 5 3 4 4 3	0 2 5 7 5 0 0 0	UNL UNL UNL UNL UNL UNL UNL UNL	35 35 45 45 35 35 35				45 43 56 56 55 59	40 38 38 44 48 50 45 43	34 32 28 29 33 34 36	66 65 34 27 29 45 61	09 07 08 11 14 14 33 00	7 4 7 9 5 3 3 0	3 3 1 5 2 5	UNL UNL UNL UNL 60 UNL UNL	35 35 45 45 35	· · · · ·	RH	4 4 5 5 5 4 4		2 1 5 5 3	37 33 34 35 34 39 41 39	71 58 61 47 39 64 74 74	00 27 00 27 24 06 08 10	0 4 0 11 12 4 5 4
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02 05 08 11 14 17 20 23	0 0 0 1 3	UNL UNL UNL UNL UNL UNL UNL UNL	35 35 35 35 35 35 35 35 35 35 35 35 35 3				45 41 49 59 59 51 47	42 39 38 43 47 45 43 41	38 36 35 33 27 34 34	77 83 86 59 38 30 52 61	11 12 11 11 06 23 00 14	7 6 6 3 4 0 3	0 0 3 6 8 8 9	UNL UNL UNL UNL UNL UNL 250	35 55 55 50 55 55 35 35 35				43 40 42 54 61 62 53 51	39 37 38 44 45 45 44 43	334 332 326 2332 24 332 332 332 332 332 332 332 332	68 79 71 43 26 23 47 48	27 23 00 09 12 00 00	3 0 0 5 3 0 0	9 10 8 3 0 1 0 2	180 180 UNL	355 355 450 455 355 355 355			44456655		3 2 7 1 5 3	36 32 34 35 33 34 32 33	61 52 56 44 28 31 40 50	00 13 09 00 09 28 27 00	03605630

MAXIMUM SHORT DURATION PRECIPITATION

TIME PERIOD (MINUTES)	5	10	15	20	30	45	60	80	100	120	150	180
PRECIPITATION (INCHES)	0.01	0.01	0.01	0.01	0.01	0.01	0.01	0.01	0.01	0.02	0.02	0.02
ENDED: DATE	15	15	15	15	15	15	15	15	15	15	15	15
ENDED: TIME	1719	1719	1719	1719	1719	1719	1719	1719	1719	1759	1759	1759

THE PRECIPITATION AMOUNIS FOR THE INDICATED TIME INTERVALS HAY OCCUR AT ANY TIME DURING THE MONTH. THE TIME INDICATED IS THE ENDING TIME OF THE INTERVAL. DATE AND TIME ARE NOT ENTERED FOR TRACE AMOUNTS.

PAGE 2

											0B	SER	VA		NS		13.	-HC	UR	ΙN	TEF	RVA	LS				DE C Phoi	FNT.	93 X,_AZ		23	183			
	5		VIS 811]- ТҮ			TEX	PERA	TURE		WI	ND	-5		VISI BILI	ι- <u>ΙΥ</u>			TEM	PERA	TURE		HI	ND	15		VIS B1L1	Ι- ΙΥ		TEMP	ERAT	IURE	\Box	¥11	ND
HOUR L.S.1.	SKY COVER ITENTASI	CETLING IN HUNDREDS OF FEET	HHOLE MILES	INTER ATE	HEA	THER	AIR of	HET BULB OF	DEH POINT OF	REL HUNIDITY X	DIRECTION	SPEED (KNOIS)	SKY COVER (TENTHS)	CEILING IN HURDREDS OF FEET	HOLE NILES	16THS MILE	NEAT	HER	AiR of	HET BULB OF	DEH POINT OF	REL HUHIDITY 2	DIRECTION	SPEED IKHOISI	SKY COVER (TENTHS)	CEILING IN HUNDREDS OF FEET	HHOLE MILES	16THS NILE	NEATHER	AIR of	HET BULB OF	OEN POINT OF	REL HUNIOIIY X	DIRECTION	SPEED (KHOIS)
				1	DEC	19th											DEC	20th											DEC 21st						
02 05 08 11 14 17 20 23	7357		35 35 35 35 35 35 35 35				49 46 50 50 53 49	42 41 40 44 47 47 45 43	34 35 36 37 33 33 35 35	56 66 61 36 38 51 59	07 10 00 13 13 27 07 11	46053534	J (1)	UNL UNL UNL UNL UNL UNL 140	35 35 25 50 35 35				44 41 54 63 53 52	40 38 45 46 46 44	34 34 34 27 25 33 31	68 76 76 47 27 24 47 45	09 00 11 15 11 33 22 34	6 0 3 3 4 4 3	10	140 130 140 140 140 UNL UNL	40			48 47 52 54 55 50 46	39 37 39 41 43 43 41 38	26 22 23 25 28 28 29 27	42 37 36 35 37 36 45 48	27 28 23 27 11 23 23 01	67535545
					DEC	22nd											DEC 2	23r d											DEC 24th						
02 05 11 14 17 23		UNL Unl Unl	35 35 35 35 35 70 35 35				40 37 38 54 59 60 50 44	37 35 36 39 41 37 34	32 33 32 13 9 8 14 17	73 86 79 20 14 13 24 34	12 10 28 31	4 3 7 5 3 4	0 0 0 0 0 0	UNL UNL UNL UNL UNL UNL UNL	35 35 50 50 50 35 35				40 36 35 47 60 57 53 51	33 31 30 36 41 40 37 36	20 21 22 17 9 11 8 6	4559 59 130 16 16	36 36 13 29 03 03 02 05	3 4 5 9 16 14 11 6	000000000000000000000000000000000000000	UNL UNL UNL UNL	35 35 60 70 70 35 35			47 40 37 53 59 59 59 50 46	34 30 29 38 40 40 37 35	5 10 11 11 6 4 13 16	19 29 34 19 12 11 23 30	23 10 33 05 10 27 23 12	10 4 3 7 4 4 3
					DEC	25 t h											DEC 2	26th]				DEC 27th						
025 08 11 17 20 23	0 0 1 4 6 4 2	UNL UNL UNL UNL UNL UNL	35 35 60 70 70 35 35				44 39 41 69 69 69 61 54	34 32 33 43 48 48 48 44 41	17 19 19 17 19 22 22 23	18	11 00 07 09 09 09 08 13	7 0 14 11 7 6 4	4 9 10	UNL UNL 250 250 180 250 250	35 60 60 70 35 35				50 49 48 59 67 65 58 53	39 38 37 44 48 48 46 44	24 19 23 23 26 31 32	36 30 32 25 25 25 25 25 25 25 25 25 25 25 25 25	10 13 10 13 11 23 24 10	67547343	10 10 10	130	45 40 40			51 52 58 65 65 65 58	43 43 43 47 49 50 49 47	33 32 32 34 32 33 34 33	50 48 47 41 29 30 35 42	09 11 09 07 12 33 27 00	55555370
					DEC	28th											DEC 2	29th											DEC 30th						
02 05 11 14 17 20 23	6 7 6 1 0 0 0	90 95 85 UNL UNL UNL UNL UNL	35 35 35 35 35 35 35 35			<u></u>	56 53 53 69 69 61 56	47 46 51 54 54 51 49	36 39 40 38 39 40 41 42	47 59 66 40 34 35 48 60	00 00 16 32 27 28 00	0 0 5 4 9 5 0		UNL UNL UNL UNL UNL UNL UNL	35 35 45 35 60 70 35 35				50 47 47 62 69 69 62 61	46 44 43 49 50 50 47- 46	41 40 38 34 30 29 29 28	71 77 35 23 23 29 29	18 00 00 14 03 05 02 08	5 0 4 8 5 8 3	000000000000000000000000000000000000000	UNL UNL UNL UNL	35			58 55 63 68 68 68 68 57	45 44 50 52 52 50 48	29 30 37 37 37 37 37 39 39	33 37 42 38 32 32 32 44 51	06 08 07 07 06 05 26 12	9 10 13 15 8 6 3 4
					DEC	31st				1.80																									
02 05 08 11 14 17 20 23	10 10 7 0 0 0	UNL 250 UNL UNL UNL UNL UNL UNL	35 45 45 35 45 35 35				54 52 62 70 70 60 55	47 45 51 54 54 50 49	40 39 38 40 40 40 41 42	59 61 59 45 34 34 50 62	23 10 11 07 11 31 00 00	3 4 7 5 4 4 0 0		<u>.</u>					-							_				±		-			

WEATHER CODES

* TORNADO T THUNDERSTORM G SQUALL R RAIN SHOWERS ZR FREEZING RAIN L DRIZZLE ZL FREEZING DRIZZLE S SNOW	SW SG IC IP IPW A F IF	SNOW SHOWERS SNOW GRAINS SNOW PELLETS ICE CRYSTALS ICE PELLETS ICE PELLET SHOWERS HAIL FOG ICE FOG	G B B B B B K H D	GROUND FOG BLOWING DUST BLOWING SAND BLOWING SNOW BLOWING SPRAY SMOKE HAZE DUST
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CEILING: UNL INDICATES UNLIMITED WIND DIRECTION: DIRECTIONS ARE THOSE FROM WHICH THE WIND BLOWS, INDICATED IN TENS OF DEGREES FROM TRUE NORTH: I.E., 09 FOR EAST, 18 FOR SOUTH 27 FOR WEST. AN ENTRY OF 00 INDICATES CALM. SPEED: THE OBSERVED AVERAGE ONE-MINUTE VALUE, EXP RESSED IN KNOTS IMPH=KNOTS X 1.15).

PAGE 3

SUMMARY BY HOURS

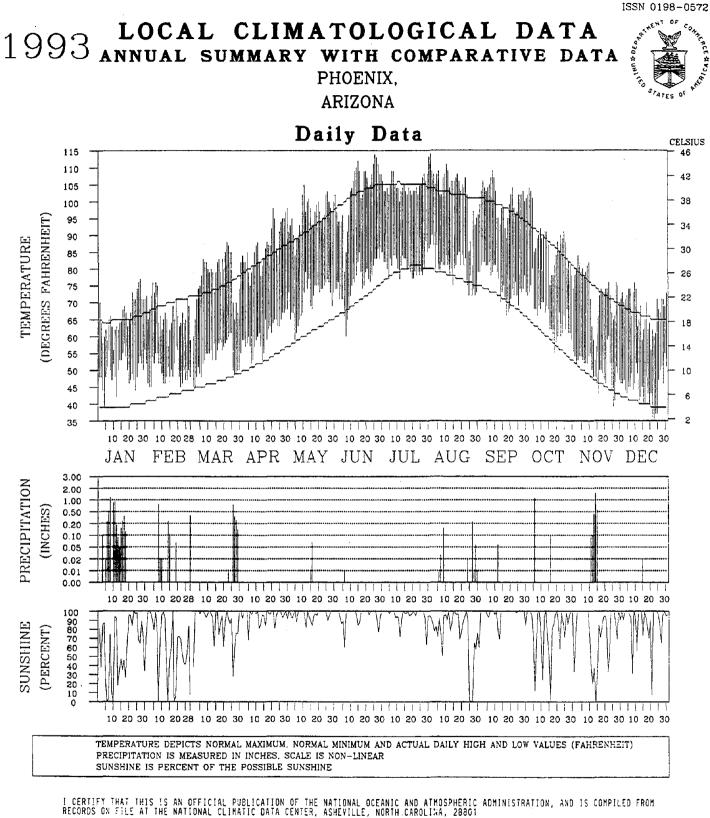
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				AV	ERAG	ES			•	JLTANT IND
		ISI		TEMI	PERA	IURE		-		
	HOUR L.S.T	SKY COVER (TENTHS)	STATTON PRESSURE (THCHES)	ALR TEMP OF	HET BULB OF	DEH POINT OF	REL RUNIDITY X	NIND SPEED (HPH)	DIRECTION	SPEED (MPH)
•	02 05 08 11 14 17 20 23	3	28.900 28.900 28.930 28.950 28.880 28.880 28.885 28.885 28.910	58 65 65	42 40 45 48 48 45 43	32 31 30 29 27 27 32 32	55 58 56 35 25 26 40 47	5.0 5.2 7.1 6.4 3.9 3.6	11 10 09 09 07 29 31 09	2233 103 103 103 103 103 103 103 103 103 1

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				.M.				NG		1.11		LUI				P.M.		,, <u>u</u>	<u>scomm</u> ENDI	- NOA	<u> </u>	SHEVIL	<u>.lē, n</u>	<u>c</u>	300
DATE	1	2	· · ·	,		· · · · · · · · · · · · · · · · · · ·				10	11	12		12			r	· · · · ·				10	1 1	12	<u>N</u>
012033045 067 0809 091011213445 1678990 223425 2678930 222345 2678930	4	Ţ	3	4	5	6	7	8	9	10	11	12	1	2	3	<u>4</u>	0.01	0.01	7	8	9	т	11		Image: Wight of the second s



METEOROLOGICAL DATA FOR 1993 PHOENIX. ARIZONA

				PHC	ENIX, A	RIZONA	L I						
LATITUDE: 33 °26' N LO	NGITUDE				ION: FT		, 1110 E	1 7			MOUNT		AN: 23183
	JAN	FEB	MAR	APR	MAY	JUNE	JULY	AUG	SEP	OCT	NOV	DEC	YEAR
TEMPERATURE OF:			:										
Averages -Daily Maximum	66.6	66.8	77.6	86.8 60.7	96.3	103.0	104.6	102.9	100.3	87.8	72.6 50.1	67.8	86.1
-Daily Minimum -Monthly	49.8 58.2	49.6 58.2	53.7 65.7	60.7 73.8	71.1 83.7	76.2 89.6	81.1 92.9	102.9 80.2 91.6	75.5	87.8 65.5 76.7	50.1 61.4	44.6 56.2	63.2 74.7
-Monthly Dewpt. Extremes	44.1	41.3	44.2	33.9	41.2	39.0	51.4	58.7	48.0	44.2	34.4	30.2	42.6
-Highest	77	76	88	98	105	114	113	114	109	104	84	76	114
-Date -Lowest	27 39	45	22 45 2	30 52	11 59	26 60	31 77	72	9 66	3 55	39 39	10 35	AUG 1 35
-Date	4	22	2	7	5	7	21	29	18	31	26	23	DEC 23
DEGREE DAYS BASE 65 ^o F: Heating	205	184	61	0	0	0	0	D	o	0	125	264	839
Cooling	1	1	89	271	585	746	871	832	695	369	24	0	4484
% OF POSSIBLE SUNSHINE	59	62	86	95	96	95	96	76	97	79	77	87	85
AVG. SKY COVER (tenths)									~ -	~ ^			о F
Sunnise - Sunset Midnight - Midnight	7.3	6.3 6.2	4.1 3.5	3.1	2.3 2.0	1.8 1.6	2.1 2.1	3.5 4.0	0.5	3.4 3.2	4.1 3.5	3.0 3.0	3.5 3.3
NUMBER OF DAYS: Suncise to Sunset			1										
-Clear	59	87	14 10	20	20 10	23	24	17 11	29 1	19 6	15 5	20	214 83
-Partly Cloudy -Cloudy	17	13	7	5	10	1	Ó	3	o o	6	10	6 5	68
Precipitation .01 inches or more	14	7	5	0	2	1	0	8	1	2	5	1	46
Snow, Ice pellets, hail													
1.0 inches or more	0	0	0	0	0	0	0	0	0	0	0	0	0
Thunderstorms	1	3	3	0	1	0	0	4	1	2	0	Û	15
Heavy Fog, visibility 1/4 mile or less	0	0	C	0	0	0	0	0	0	0	0	0	0
Temperature ^O F -Maximum													
-Maximum 90° and above 32° and below	0	0	0	9	28 0	28 0	31 0	28	29 0	12 0	0	0	165 0
-Minimum	0	0	0	0	ů O	0	0	o	Ő	ů ů	o o	0	. 0
32° and below 0° and below	ŏ	Ŏ	Ő	0 0	0	ŏ	ŏ	ŏ	· 0	ŏ	Ŏ	ŏ	ŏ
AVG. STATION PRESS. (mb)	976.3	976.3	976.3	971.2	970.0	967.8	970.4	971.2	971.6	973.9	977.0	978.7	973.2
RELATIVE HUMIDITY (%) Hour 05	79	75	71	41	36	28	37	52	41	49	57	50	5 0
Hour 11 (Legal Time)	60	56	44	21	20	16	24	33	26	31	40	58 35	52 34 25 40
Hour 17 (Cocar Thile) Hour 23	49 69	43 61	31 52	14 24	15 24	11 18	18 26	42	17 28	24 39	30 47	26 47	25 40
PRECIPITATION (inches):		·····								· · · ·			
Water Equivalent	F 99						.				0.70		
-lotai -Greatest (24 hrs)	5.22 1.84	1.72 0.84	1.62	0.00	0.08 0.08	0.01 0.01		0.55	0.06 0.06	1.27 1.17	2.79 2.16	0.02	2.16
-Date	10-11	8-9	26-27		15-16	6	12	27-28	12	6	14-15	15	NOV 14-15
Snow,Ice pellets,hail -Total	T	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	T
-Greatest (24 hrs)	Ť 18	0.0	0.0	ŏlŏ	0.0	ŏ.ŏ	0.0	ŏ.ŏ	0.0	ŏlŏ	ŏ.ŏ	ŏ.ŏ	Ť JAN 18
-Date	10												JAN 10
HIND: Resultant)					
-Direction (!!) -Speed [mph]	078 2.2	074 1.3	126 1.3	227 1.1	262 1.6	254 1.7	258 1.3	129	120 1.2	086 2.4	100	085 1.6	116
Average Speed (mph) Fastest Obs. 1 Min.	5.9	6.2	6.8	4.8	5.1	4.2	4.6	5.8	4.4	5.5	4.9	5.4	0.6 5.3
-Direction (!!)	27	27	25	25	12	25	14	31	11	06	27	08	25
-Speed (mph) -Date Date	25 18	18 20	29 26	18 30	24 15	18 6	23 11	23	24 10	26 27	24 11	21 30	25 29 MAR 26
Peak Gust -Direction (!!)	M	W	W	M	Ĕ	W	SE	NW	Ę	NE	H,	N	NH
-Speed (mph) -Date	33 18	30 28	39 26	28 30	40 15	30 6	30 11	45	31	36 27	37 11	39 23	45 AUG 6
				_	. .		-						

(!!) See Reference Notes on Page 68 Page 2

NORMALS, MEANS, AND EXTREMES

					PHOE	NIX. AR	IZONA							
LATITUDE: 33 °26'N L	ONGI (a)	TUDE: 1 JAN	12 °01 ′ FEB	μ el MAR	EVATION APR	: FT. G MAY	IND 11	10 BARO JULY	1109 AUG	TIME SEP	ZONE: M OCT	ountain NOV	₩B DEC	an: 23183 YEAR
TEMPERATURE °F:														
Normals -Daily Maximum -Daily Minimum -Monthly		65.9 41.2 53.6	70.7 44.7 57.7	75.5 48.8 62.2	84.5 55.3 69.9	93.6 63.9 78.8	103.5 72.9 88.2	105.9 81.0 93.5	103.7 79.2 91.5	98.3 72.8 85.6	88.1 60.8 74.5	74.9 48.9 61.9	66.2 41.8 54.1	85.9 59.3 72.6
Extremes -Record Highest -Year -Record Lowest -Year	56 56	88 1971 17 1950	92 1986 22 1948	100 1988 25 1966	105 1992 32 1945	113 1984 40 1957	122 1990 50 1944	118 1989 61 1944	116 1975 60 1942	118 1950 47 1965	107 1980 34 1971	93 1988 25 1938	88 1950 22 1948	122 JUN 1990 17 JAN 1950
NORMAL DEGREE DAYS: Heating (base 65°F)		362	227	182	75	8	o	o	0	0	17	134	345	1350
Cooling (base 65 ⁰ F)		8	22	95	222	436	696	884	822	618	311	41	7	4162
% OF POSSIBLE SUNSHINE	98	78	80	84	89	93	94	85	85	89	88	84	78	86
MEAN SKY COVER (tenths) Sunrise - Sunset MEAN NUMBER OF DAYS:	48	4.7	4.6	4.3	3.4	2.7	1.9	3.7	3.3	2.3	2.8	3.4	4.1	3.4
Sunrise to Sunset -Clear -Partly Cloudy -Cloudy Precipitation	56 56 56	13.9 7.0 10.1	12.6 6.7 8.9	14,4 8,1 8,5	17.2 7.3 5.6	20.8 6.8 3.5	23.1 4.7 2.2	16.6 10.3 4.2	17.6 9.6 3.8	21.6 5.4 3.0	20.3 6.2 4.4	17.7 6.2 6.1	15.3 6.3 9.4	211.0 84.6 69.7
.01 inches or more Snow,Ice pellets,hail	54	4.1	3.9	3.7	1.7	1.0	0.7	4.2	4.9	2.9	2.7	2.6	3.9	35.5
1.0 inches or more	56	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
Thunderstorms Heavy Fog Visibility	54	0.4	Q.6	0.9	0.7	1.0	1.0	6.1	7.1	3.5	1.4	0.5	0.6	23.7
1/4 mile or less Temperature ^o F	56	0.6	0.1	0.1	0.0	0,0	0.0	0.0	0.0	0.0	0.*	0.2	0.5	1.6
-Maximum 90° and above 32° and below	33 33	0.0	0.1 0.0	2.0 0.0	9.8 0.0	23.1 0.0	29.2 0.0	30.9 0.0	30.6 0.0	27.6 0.0	15.2 0.0	0.5 0.0	0.0 0.0	169.0 0.0
-Minimum 32° and below 0° and below	33 33	3.3 0.0	1.3 0.0	0.4	0.0	0.0	0.0	0.0	0.0 0.0	0.0	0.0	0.2	1.8 0,0	7.0 0.0
AVG. STATION PRESS. (mb)	21	978.3	977.5	974.4	972.6	970.6	969.7	971.2	971.6	971.7	974.0	976.5	978.3	973.9
RELATIVE HUMIDITY (%)														
Hour 05 Hour 11 (Local Time) Hour 17 Hour 23	33 33 33 33	67 46 33 56	60 39 27 48	57 34 24 43	43 23 16 28	35 19 13 23	31 16 12 20	44 28 20 33	51 33 23 38	49 31 23 38	50 30 22 40	57 36 27 48	67 46 34 57	51 32 23 39
PRECIPITATION (inches): Water Equivalent														
-Normal -Maximum Monthly -Year -Minimum Monthly -Year	56 56 56	0.67 5.22 1993 0.00 1972 1.84	0.68 2.23 1944 0.00 1967 1.49	0.88 4.16 1941 0.00 1959 2.04	0.22 2.10 1941 0.00 1962	0.12 1.06 1976 0.00 1983	0.13 1.70 1972 0.00 1983	0.83 5.15 1984 T 1993	0.96 5.56 1951 1975	0.85 4.23 1939 0.00 1973	0.65 4.40 1972 0.00 1973	0.66 3.04 1952 0.00 1980	1.00 3.98 1967 0.00 1981	7.66 5.56 AUG 1951 0.00 MAY 1983
-Maximum in 24 hrs -Year	36	1993	1987	1983	1.38 1941	0.96 1976	1.64 1972	2.75 1984	3,07 1943	2.43 1970	2.32 1988	2,16 1993	1,89 1967	3.07 AUG 1943
Snow,lce pellets,hail -Maximum Monthly -Year -Maximum in 24 hrs -Year	56 56	1993 1993 1993	0.6 1939 0.6 1939	T 1991 T 1991	T 1949 T 1949	T 1992 T 1992	0.0	0.0 0.0	0.0 0.0	0.0 0.0	T 1992 T 1992	0.0 0.0	0.4 1990 0.4 1990	0.6 FEB 1939 0.6 FEB 1939
WIND: Mean Speed (mph)	48	5.3	5.9	. ,	(0	7 0		7 4			_			()
Prevailing Direction through 1963	40	р.,з Е	5.9 E	6.7 E	6.9 E	7.0 E	5.8 E	7.1 W	6.6 E	6.3 E	5.8 E	5.3 E	5.1 E	6.2 E
Fastest Obs. 1 Min. -Direction (!!) -Speed (MPH) -Year	8 8	27 32 1988	14 26 1992	26 35 1992	27 28 1986	11 35 1992	03 31 1986	08 35 1991	10 35 1989	- 05 35 1990	21 28 1986	29 29 1990	09 26 1988	26 35 MAR 1992
Peak Gust -Direction (!!) -Speed (mph) -Date	56 56	W 60 1983	54 1980	ы 51 1989	W 49 1981	SSE 59 1954	NE 73 1978	Si 86 1976	E 78 1978	SW 75 1950	W 61 1981	ม 60 1982	ы 68 1953	SE 86 JUL 1976

(!!) See Reference Notes on Page 6B. Page 3 PRECIPITATION (inches)

PHOENIX, ARIZONA

YEAR	JAN	FEB	MAR	APR	MAY	JUNE	JULY	AUG	SEP	OCT	NOV	DEC	ANNUAL
1964 1965 1966 1967 1968	0.22 1.22 0.35 0.25 0.19	0.01 0.91 0.95 0.00 1.20	0.37 1.39 0.34 0.43 1.04	0.10 1.35 7 0.08 T	0.16 0.05 T	0.00 0.91 0.22 0.47 0.00	0.60 0.16 0.09 0.99 1.70	1.29 0.18 2.17 0.02 0.59	1.80 0.60 2.00 0.13 0.00	0.17 0.20 0.25 0.67 0.35	0.35 0.92 0.38 1.27 0.91	1.09 3.19 0.52 3.98 0.69	6.00 11.19 7.27 8.34 6.67
1969 1970 1971 1972 1973	1.37 T 0.22 0.00 0.13	0.78 0.30 0.35 T 1.35	0.56 2.26 T T 1.69	0.03 T 0.13 T 0.07	0.26 T T 0.10	0.00 0.00 0.00 1.70 T	0.28 0.48 0.24 0.72 1.30	0.14 1.02 0.99 1.20 T	2.11 2.85 0.92 0.28 0.00	0.08 0.44 0.27 4.40 0.00	0.65 0.02 1.01 1.36	0.68 0.26 0.47 1.56 0.00	6.94 7.63 3.59 10.87 6.01
1974 1975 1976 1977 1978	0.57 0.02 T 0.35 2.33	0.02 0.33 0.47 0.06 2.21	1.37 0.63 0.40 0.27 2.14	0.01 0.43 0.67 0.06 0.20	0.00 T 1.06 0.16 T	0.00 T 0.09 0.10 0.01	0.84 0.38 1.48 0.30 1.44	1.15 T 0.12 0.18 1.79	1.07 0.82 1.69 0.53 T	2.12 0.23 0.70 0.61 0.35	0.44 0.55 0.43 T 2.30	0.59 1.12 0.85 0.54 2.46	8.18 4.51 7.96 3.16 15.23
1979 1980 1981 1982 1983	2.16 1.58 0.71 0.81 0.70	0,09 2.09 1.08 0.67 1.17	1.78 0.86 0.98 1.30 3.17	0.02 0.44 0.20 T 0.18	0.75 0.21 0.03 0.50 0.00	0.04 0.03 T 0.00	0.34 0.56 1.14 0.43 0.38	1.18 0.06 0.11 1.97 2.48	0.09 0.13 0.18 0.12 2.43	0.09 0.02 1.34 T 0.71	0.12 0.95 0.50 0.43	0.13 0.08 0.00 1.64 1.16	6.80 6.06 6.72 9.94 12.81
1984 1985 1986 1987 1988	0.31 0.95 0.07 0.67 0.90	0.00 0.18 1.19 2.06 0.23	0.00 0.46 1.58 0.28 0.17	0.91 0.17 0.01 0.09 1.09	0.18 T 0.06 0.00	0.18 0.00 0.01 0.01 0.02	5.15 0.98 1.19 1.08 0.87	0.87 0.21 1.27 0.45 0.63	3.36 1.60 0.47 0.57 0.00	0.31 0.92 0.41 0.47 2.38	0.71 1.59 0.03 1.04 0.78	2.93 0.86 1.38 1.62 0.14	14.91 7.92 7.61 8.40 7.21
1989 1990 1991 1992 1993	1.19 0.80 0.63 1.62 5.22	T 0.70 0.56 0.90 1.72	1.25 0.35 2.05 2.49 1.62	0.00 0.17 0.00 0.49 0.00	T 0.16 0.00 1.05 0.08	0.00 0.04 T 0.04 0.01	0.13 1.05 0.14 2.95 T	1.11 2.70 0.12 1.30 0.55	0.47 1.11 0.81 0.03 0.06	0.46 0.04 1.16 0.26 1.27	0.14 0.15 1.25 0.03 2.79	0.19 0.46 1.63 3.08 0.02	4.94 7.73 8.35 14.24 13.34
Record Mean	0.82	0.74	0.77	0.33 Se	0.14 e Refer	0.09 ence No Page	0.93 tes on #4A	1.01 Page 68	0.78	0.53	0.65	0.91	7.71

AVERAGE TEMPERATURE (deg. F)

PHOENIX, ARIZONA

YEAR	JAN	FEB	MAR	APR	MAY	JUNE	JULY	AUG	SEP	OCT	NOV	DEC	ANNUAL
1954 1965 1966 1967 1968	46.7 52.7 48.2 50.7 52.4	49.3 52.4 49.7 55.7 59.7	56.5 56.1 61.2 62.8 59.9	65.2 63.4 69.8 62.4 66.7	73.7 71.8 80.1 75.1 76.6	82.6 79.0 86.8 81.1 86.2	90.6 91.0 93.6 91.6 91.6 90.2	86.2 89.0 90.9 91.0 86.5	80.9 79.2 82.9 84.8 83.6	74.9 73.8 70.9 73.5 72.7	5.1 60.9 63.9 59.2	52.9 52.9 52.2 52.2 52.2 52.2 5 48.5	67,8 68.6 70.5 70.1 70,3
1969 1970 1971 1972 1973	54.9 52.1 52.2 51.4 51.2	53.0 60.2 56.3 59.1 57.5	56.9 59.3 50.6 56.6	68.5 64.7 66.5 71.4 67.2	78.3 79.6 73.3 78.3 80.9	84.2 88.1 85.3 87.8 88.1	93,1 95.0 94.9 54.4 93.5	94,4 92,6 99,9 99,4	86.0 82.2 85.6 84.8 84.7	69.5 69.1 69.3 71.9 74.4	62 1 61 4 59 7 58 1 60 8	54.8 52.6 50.2 52.1 55.4	71.3 71.4 70.5 72.5 72.0
1974 1975 1976 1977 1978	54.0 52.3 55.4 53.8 56.6	56.7 54.0 60.7 61.7 58.7	64.5 59.0 61.5 60.8 65.6	70.6 62.6 68.7 73,5 69.2	80.2 76.7 80.7 75.7 78.5	92.2 86.6 87.9 91.4 90.9	92.4 94.3 91.6 95.0 94.6	91.2 91.9 90.7 94.1 91.4	87.2 86.2 83.0 87.6 86.3	75.9 72.9 74.0 78.7 78.6	61.5 60.9 64.1 65.8 61.5	50.6 54.8 55.6 59.9 51.7	73.1 71.0 72.8 74.9 73.6
1979 1980 1981 1982 1983	50.1 56.6 59.2 53.9 56.0	55.7 60.6 61.4 60.1 58.4	60,4 60,7 63,8 62,4 62,2	70,1 69.0 76.0 72.5 66.6	78.1 76.0 80.5 80.4 80.6	89.5 88.9 93.4 88.1 88.6	93.8 95.6 95.2 93.7 95.5	89.4 92.8 93.7 93.6	90.2 87.3 89.2 86.7 91.0	77.2 75.6 73.6 73.5 77.2	58.2 64.1 66.1 61.9 62.4	55.9 61.3 58.6 54.1 57.2	72.4 74.0 76.0 73.4 74.0
1984 1985 1986 1987 1988	57.4 54.3 61.4 54.7 55.1	60,1 57,4 61,0 59,7 62,5	67.6 62.8 69.3 63.4 66.3	70.7 75.1 74.2 77.9 73.0	87.0 84.2 82.3 82.6 81.4	88.9 92.4 92.8 93.0 93.1	91.7 94.9 92.3 93.1 96.2	91.2 94.5 94.5 92.9 93.9	87.5 82.3 84.1 86.9 87.4	71.4 75.1 74.7 80.9 82.4	61,9 61,3 65,0 63,1 64,4	53.7 55.9 56.4 52.7 55.7	74.1 74.2 75.7 75.0 76.0
1989 1990 1991 1992 1993	54.4 555.4 555.4 56	61.9 56.6 66.0 62.1 58.2	70,1 67,2 60,3 64,7 65,7	80.1 76.2 72.2 77.0 73.8	83.1 81.1 79.7 83.1 83.7	92.1 93.8 87.8 90.1 89.6	97.4 93.6 95.1 92.8 92.9	93.7 90.8 94.5 92.3 91.6	89.9 87.6 88.5 90.5 87.9	77.3 78.7 80.2 79.8 76.7	66.9 65.5 61.5 61.4	57.0 53.6 57.3 53.8 56.2	77.0 75.1 75.1 75.3 74.7
Record Mean Max Min	52.4 65.3 39.4	56,3 69,6 43,0	61.1 74.9 47.3	68.7 83.6 53.8 Se	76.9 92.3 61.4 e Refer	86.2 102.1 70.3 ence No		89.7 102.3 77.0 Page 68	84.2 98.0 70.4	72.7 87.3 58.0	60.5 74.7 46.2	53.0 66.1 40.0	71.1 85.1 57.1

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HEATING DEGREE DAYS Base 65 deg. F PHOENIX, ARIZONA

SEASON	JULY	AUG	SEP	OCT	NOV	DEC	JAN	FEB	MAR	APR	MAY	JUNE	TOTAL
1964-65 1965-66 1966-67 1967-68 1968-69	00000	00000	04000	0000	281 116 139 72 173	396 370 397 512 473	375 516 437 386 306	343 4256 1527 327	999275 1065 24075	132392 132392 12	14 10 10 13	00000	1004 1004 1004 1004 100 100 100
1969-70 1970-71 1971-72 1972-73 1973-74	00000	00000	00000	12 19 79 38 2	95 1195 185 205 156	307 376 455 395 291	393 396 414 422 333	134 241 174 200 229	166 123 254 254 77	603295	00000	00000	1167 1327 1341 1553 1093
1974-75 1975-76 1976-77 1977-78 1978-79	00000	00000	00000	21 15 20 1	112 152 112 122 148	439 310 285 155 405	388 296 3354 255	301 123 122 172 254	191 134 149 67 143	107 52 33 25 30	40000	00000	1563 1089 1042 715 1436
1979-80 1980-81 1981-82 1982-83 1983-84	00000	00000	00000	11 12 1 1 0	204 108 56 103 154	277 122 196 331 236	254 181 335 272 228	130 131 151 181 139	129 74 99 120 16	35 8 4 53 23	00000	00000	1040 636 842 1061 796
1984-85 1985-86 1986-87 1987-88 1988-89	00000	00000	00000	70000	126 149 43 98 135	345 274 260 375 284	328 110 318 311 321	222 158 172 100 133	100000 00000 4	มั 200	01000	00000	1135 760 892 965 919
1989-90 1990-91 1991-92 1992-93 1993-94	00000	00000	00000	1 0 34 0 0	36 65 107 127 125	243 348 233 340 264	291 275 260 205	253 27 89 184	76 161 56 61	057 0	0000	0000	900 881 786 917

See Reference Notes on Page 68. Page 5A

COOLING DEGREE DAYS Base 65 deg. F PHOENIX, ARIZONA

YEAR	JAN	FEB	MAR	APR	MAY	JUNE	JULY	AUG	SEP	ост	NOV	DEC	TOTAL
				*									
1969 1970 1971 1972 1973	00700	0 4 2 11 0	22 4 76 200 0	123 58 107 212 109	4395 4405 440 40 40	582 700 614 691 701	878 938 934 919 894	918 862 773 780 885	637 65239 6599	158 151 220 259 302	16 18 30 4 36	00000	3768 3721 3651 4094 4024
1974 1975 1976 1977 1978	0 0 0 0 0 0 0	204 04 30 1	69 12 325 92	182 42 169 295 158	477 374 495 334 422	825 654 692 797 787	853 933 936 928	821 839 804 907 828	673 640 548 683 644	365 2659 431 431	13 45 91 73 49	0 1 0 1 0	4285 37955 4525 4343
1979 1980 1981 1982 1983	NOMOO	056 321 1	11 2 40 24 38	191 187 345 234 112	411 344 489 481 489	741 724 857 697 715	901 956 943 899 951	763 852 961 897 861	764 675 731 658 787	397 346 277 272 388	7 885 95 12 85	0 13 500	4186 4192 4784 4195 4429
1984 1985 1986 1987 1988	0 0 3 3 10	2 17 52 30 31	107 40 209 51 108	203 316 282 396 265	688 603 543 553 520	724 826 844 846 851	836 934 853 879 972	-821 920 921 850 904	681 525 585 665 678	208 319 307 499 543	41 47 51 48 124	00103	4311 4547 4648 4820 5009
1989 1990 1991 1992 1993	1 5 0 1	495 61 13 1	210 150 252 50 89	459 339 227 373 271	56657 56657 5568 558	820 873 691 762 746	1013 895 937 868 871	897 806 920 851 832	751 683 712 771 695	392 431 514 464 369	87 101 70 30 24	00000	5243 4814 4619 4753 4484

See Reference Notes on Page 68. Page 58

SNOWFALL (inches)

PHOENIX, ARIZONA

SEASON	JULY	AUG	SEP	ОСТ	NOV	DEC	JAN	FEB	MAR	APR	MAY	JUNE	TOTAL
1964-65 1965-66 1966-67 1967-68 1968-69	0.0 0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 T T	0.0 0.0 0.0 0.0	0,0 0,0 0.0 0.0		0,0 0,0 0,0 0,0 0,0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 T T
1969-70 1970-71 1971-72 1972-73 1973-74		0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0		0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0,0 0.0 0.0 0.0		0,0 0,0 0,0 0,0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0
1974-75 1975-76 1976-77 1977-78 1978-79	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0000000000000000000000000000000000000	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	T 0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 T 0.0 0.0	0,0 0,0 0,0 0,0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	T T 0.0 0.0 0.0
1979-80 1980-81 1981-82 1982-83 1983-84	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.00 0.00 0.00 0.00	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0
1984-85 1985-86 1986-87 1987-88 1988-89	0,0 0,0 0,0 0,0	0.00 0.00 0.00 0.00	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.1 0.0 0.0	0.0 0.0 T 0.0	0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0	T 0.1 T 0.0 0.0
1989-90 1990-91 1991-92 1992-93 1993-94	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0	0.0 0.0 0.0 T	0.0 0.0 0.0 0.0	0.0 0.4 0.0 0.0 0.0	0.0 0.0 0.0 T	0.0 0.0 0.0	0.0 T 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 T 0.0	0.0 0.0 0.0 0.0	0.0 0.4 T T
Record Mean	0.0	0,0	0.0	I See	0.0 Refere	T nce Not Page	T es on P 6A	T age 68.	Ŧ.	Ţ	T	0.0	τ

REFERENCE NOTES

PHOENIX, ARIZONA

GENERAL I - TRACE AMOUNT. BLANK ENTRIES DENOTE MISSING/UNREPORTED DATA. # INDICATES A STATION OR INSTRUMENT RELOCATION. SEE STATION LOCATION TABLE ON PAGE 8. SPECIFIC PAGE 2 PM - INCLUDES LAST DAY OF PREVIOUS MONTH ASOS - AUTOMATED SURFACE OBSERVING SYSTEM IN OPERATION DURING THESE MONTHS. PAGE 3 (a) - LENGTH OF RECORD IN YEARS, ALTHOUGH INDIVIDUAL MONTHS MAY BE MISSING. 0.* OR * - THE VALUE IS BETHEEN 0.0 AND 0.05 NORMALS - BASED ON THE 1961-1990 RECORD PERIOD. EXTREMES - DATES ARE THE MOST RECENT OCCURRENCE HIND DIR NUMERALS SHOH TENS OF DEGRESS CLOCKHISE AFTER THE ASOS SYSTEM WAS COMMISSIONED. PAGE 48 RECORD MEAN PRECIPITATION IS THE MEAN OF ALL DAILY PRECIPITATION AMOUNTS DURING THE PERIOD OF RECORD. RECORD MEAN PRECIPITATION IS THE MEAN OF ALL DAILY PRECORD MEAN TEMPERATURE IS THE SUM OF THE RECORD. RECORD MEAN TEMPERATURE IS THE SUM OF THE RECORD RECORD MEAN TEMPERATURE IS THE SUM OF THE RECORD MAX AND RECORD HIN IVIDED BY 2.	 PEAK GUST HINDS ARE AS OBSERVED JANUARY 1938 THROUGH OCTOBER 1953 AND FROM RECORDER THEREAFTER. PERCENT OF POSSIBLE SUNSHINE IS FROM CITY OFFICE AUGUST 1895 THROUGH OCTOBER 1953 AND FRCM SKY HARBOR AIRPORT THEREAFTER. MEAN SKY COVER IS 1940, 1941, AND 1948 TO DATE.

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PHOENIX, ARIZONA

Phoenix is located in the Salt River Valley at an elevation of about 1,100 feet. The valley is oval shaped and flat except for scattered precipitous mountains rising a few hundred to as much as 1,500 feet above the valley floor. Sky Harbor Airport, where the weather observations are taken, is in the southern part of the city. Six miles to the south of the airport are the South Mountains rising to 2.500 feet. Eighteen miles southwest, the Estrella Mountains rise to 4,500 feet, and 30 miles to the west are the White Tank Mountains rising to 4,100 feet. The Superstition Mountains, over 30 miles to the east, rise to as much as 5.000 feet. The valley, though located in the Sonora Desert, supports large acreages of cotton. citrus, and other agriculture along with one of the largest urban populations in the United States. The water supply for this complex desert community is partly from reservoirs on the impounded Salt and Verde Rivers, and partly from a large underground water table.

Temperatures range from very hot in summer to mild in winter. Many winter days reach over 70 degrees and typical high temperatures in the middle of the winter are in the 60s. The climate becomes less attractive in the summer. The normal high temperature is over 90 degrees from early May through early October, and over 100 degrees from early June through early September. Many days each summer will exceed 110 degrees in the afternoon and remain above 85 degrees all night. When temperatures are extremely high, the low humidity does not provide much comfort. Indeed, the climate is very dry. Annual precipitation is only about 7 inches, and afternoon humidities range from about 30 percent in winter to only about 10 percent in June. Rain comes mostly in two seasons. From about Thanksgiving to early April there are periodic rains from Pacific storms. Moisture from the south and southeast results in a summer thunderstorm peak in July and August. Usually the break from extreme dryness in June to the onset of thunderstorms in early July is very abrupt. Afternoon humidities suddenly double to about 20 percent, which with the great heat, gives a feeling of mugginess. Fog is rare, occurring about once per winter, and is unknown in the other seasons.

The valley is characterized by light winds. High winds associated with thunderstorms occur periodically in the summer. These occasionally create duststorms which move large distances across the deserts. Strong thunderstorm winds occur any month of the year, but are rare outside the summer months. Persistent strong winds of 30 mph or more are rare except for two or three events in an average spring due to Pacific storms. Winter storms rarely bring high winds due to the relatively stable air in the valley during that season.

Based on the 1951-1980 period, the average first occurrence of 32 degrees Fahrenheit in the fall is December 13 and the average last occurrence in the spring is February 7

Notice of Correction

Any previously received edition of the "Local Climatological Data Annual Summary for 1993" should be discarded. This revised edition contains updates to the "Normals" based upon the 1961-1990 record period as noted in the "Reference Notes" on Page 6B.

STATION LOCATION

PHOENIX, ARIZONA

				Ļ	L			ELEV	ATIC	ON AL	BOVE				A U	* <u>Туре</u>
			į	Ą	0 N G	SEA LEVEL				ROU	Ø				Ť	M = AMOS T = AUTOB
LOCATION	OCCUPIED FROM	OCCUPIED	AIRLINE DISTANCES AND DIRECTIONS FROM PREVIOUS LOCATION	t U E North	U D E WEST	GROUND TEMPERATURE	3HZD HZWHRDEWZHW		0.のとしまな011世上世界	NDINEHINU NDIH-UE	RAN GAGM HINDNG BOOME-	JEIGHING RAIN GAGE	8 INCH RANN GAGE	HYUROF-HUREONU-UR	HATIC DBOURVING	s = Asos W = Anos Remarks
CITY NOTE: For per Talbot Building SW corner First Avenue at Adams	od Januai 8/1/01	74728 73724713	76 through / 300 ft. NW	ugust 1 33°27	1128051	f ^e f855	to pr 58	evio: 50	50°	litio Unk	B21		41			b - Added 6/1/06.
Federal Building 230 N. First Avenue	3/24/13	6/27/16	500 ft.NNW	י33°27י	112°05 '	1086	81	76	76	Unk	68		68			
Water Users Building 145 W Van Buren Street	6/27/16	9/4/24	100 ft. W	33°27'	112°05'	1086	81	11	11	Unk	68		68			Wind instruments & rain gage equipment left on roof of Fed- eral Building. Thermometer shelter moved to lawn between the buildings.
Ellis Building Basement 137 N Second Avenue	9/4/24	8/22/33	300 ft. S	33°27'	112°05'	1086	82	10	10	Unk	56		56			Thermometer shelter in Ellis Court, exposure poor, moved back to Federal Blog, lawn on 7/18/25.
Ellis Building 5th Floor 137 N Second Avenue	8/22/33	10/22/36	NA	33°27'	112°05'	1086	107	10	10	Unk	81		81			Ellis Building was raised 2 stories.
Post Office Building 500 N Central Avenue	10/22/36	12/16/36	1200 ft. NNE	33°27'	י112°04 י	1083	51	39	39	Unk	36		36			Shelter on flat gravelled roof.
Post Office Building 500 N Central Avenue	12/16/36	10/22/53	NA	33°27'	112°04'	1083	87	39	39	Unk	36		36			Psychrometric observations moved to WBAS at Sky Harbor Airport on 7/1/39.
Posts Office Building 500 N Central Avenue	10/22/53	8/15/68	NA	33°27'	112*04+	1083		39				39	36		•	Combined at Airport 10/22/53. Psychrometer, wind equipment & tipping bucket gage removed 11/1/53.
AlRPORT Administration Building Sky Harbor Airport	5/2/33	12/19/52	3 mi. ESE of P.D.	33°26'	112°02'	1108	29	5	5	NA			3	d		Station closed 7/27/35 to 1/1/38, Cotton Region Shelter moved 110 feet NE & Standard Shelter added 10/1/40.
New Terminal Building Sky Harbor Airport	12/19/52	5/29/58	0.8 mi. SE	33°26'	112°01'	1114	32	5	5	dUni		c 5	3	d		c - Added 11/1/53. d - Telepsychrometer (5') s/1/49:12/2001 Hygro.
FAA Operations Bldg. Sky Harbor Airport + + Sky Harbor int i AP effective 1971.	5/29/58	1/25/78	0.3 mi. NW	33°26'	112°01'	-1109 51112	41 138 138	5	5	35		4	3	₽ 7 7		c - Added 11/1/53. d - Jelepsychoareter (5') comm, 3200'E of office 12/20/60. e - Effective 12/20/60 f - Moved 2000 g - Effective 9/19/75.
Wea. Svc. Forecast Off. Sky Harbor Int'l AP	1/25/78	Present	3000 ft.S₩	33°26'	112°01'	1110	33	5	5	7	5	5	5	5	NA	
SUBSCRIPTION:										l			i l			1

SUBSCRIPTION: Price and ordering information available through: National Climatic Data Center, Federal Building, Asheville, North Carolina, 28801. INQUIRIES/COMMENTS CALL: (704) 271-4800

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TIME ZONE: MOUNTAIN

LOCAL CLIMATOLOGICAL DATA

PHOENIX, AZ SKY HARBOR INTL AIRPORT

JULY 1994

published by: National Climatic Data Center

L	ATITU	DE: 33	° 26′ 1	N	LONG	TUDE:	112°	011 1	N	ELEVA	TION	(GROU	ND):	110	FEET	TIME	ZO		IOUN1 STANE			ISS WBA	N# N#	0198		15		
		TE	MPERAT	URE F		-	DEG I BASE			/ICE	PRECIPI	TATION	PRES: (INCHES		WIN		PEED = IR = T		OF DE	EGREE	s	SUNSE	INE	NE CLOUDINESS				
	Σ	Σ	ы	Σ	<u>н</u>	, m	ប្អ	ប្អ	SIGNIFICANT	0500	1100			พช	പ			ப			(MUM 2-M	TN	Ŋ	μ			MN-MN	1
μ	MAXIMUM	MUMINIM	AVERAGE	EP FROM NORMAL	AVERAGE DEW PT	BUI	HEATING	COOLING	WEATHER	LST #	LST cc >		ER	AVERAGE STATION	RAG EA :VEL	LTA SP:	DIR	RAG. EED			8		AL UTE	CENT	LE TER H5	LITE HS	RETER HS LITE '45	
DATE	MAX	MHM	AVE	DEP NOR	AVI	AVERAGE WET BULE	HE?	č		DEPTH	WATER EQUIV	SNOW- FALL	WATER Equiv	AVE ST7	AVERAGE SEA LEVEL	RESULTANT WIND SPEED	RES	AVERAGE SPEED	SPEED	DIR	SPEED	DIR	TOTAL MINUTES	PERCENT POSSIBLE	TENT TENT	TENT	CEILOMET TENTHS SATELLI TENTHS	
1	2	3	4	5	6	7	8	9	10	11	<u>_12</u>	13	14	15	16	<u>17</u>	18	19	20	21	22	23		25	5 26	27	28 29	1
01 02		86 87	98 99	6	55 55	70 70	0	33 34		0		0.0		28.57				6.2 8.0	24	14 27	20	14 28	509 846	59 98	0	1	0 1	
03 04		86 79	98 94	6 1	49 43	67 64	0	33 29		0 0		0.0	$0.00 \\ 0.00$	28.55 28.58	29.65	4.4	27 26	8.1 8.2	26	28 24	22	25 25	859 859	$\begin{array}{c} 100 \\ 100 \end{array}$	0	0 0	0 0	1 P G
05	105	81	93	0	51	67	0	28		0		0.0		28.65		3.9	26	7.7	17	28	16	30	857	100	0	1	0 0	HOL
06 07	109	78 75	91 92	-2 -1	43 43	63 63	0	26 27		0 0		0.0		28.66 28.57			19	6.5 5.2	17 17	25 28	14 13	30 25	857 856	$\begin{array}{c} 100 \\ 100 \end{array}$	0	0	0 0	HH
	112* 109	78 82	95 96	23	39 44	63 65	0	30 31		0		0.0		28.58 28,70		.9 1.5	12 1	5.9		27 29	15 13		856 736	100 86	0	0 0	0 0	
	108	83	96	3	51	68	0	31		0		0.0	0.00	28.72	29.83	3.1	28	5.6	20	29	16	29	854	100	0	1	0 1	0 X
11 12		84 81	97 95	4	50 44	68 65	0	32 30		0 0		0.0		28.67		4.5		7.1 5.8		30 28	17 15		853 853	$\frac{100}{100}$	0	2 2	0 1 0 1	
13 14	109 109	78 82	94 96	0	42 44	64 65	0	29 31		0		0.0		28.61 28.63		1.5	6	5.1		19 17	11 14		852 850	100	0	2 0	0 1	
15	107	80	94	0	45	65	0	29		0		0.0	0.00	28.69	29.80	2.3	1	3.9	11	03	10	03	850	100	0	2	0 1	
16 17	104 96	81 77	93 87	-1 -7	48 65	66 72	0	28 22	TRH	0		0.0		28.71 28.75		4.4		6.0	21 30	25 13	18 25	26 13	638 102	75 12	0	3 8	0 4	
18 19	90 94	73* 75	82* 85	-12 -9	67 65	72 71	0	17 20	RFH R	0		0.0		28.78	29.91	3.8	27	4.6	15 24		13		440	52 66	4	4	4 4 2 2	
20	102	77	90	-4	61	71	0	25		Ő		0.0		28.71				5.3				16	844	100	ō	0	0 1	
21 22	106	83 85	95 97	1 3	58 58	70 71	0	30 32		0		0.0		28.70 28.68		1.1		5.6		31 17	13 21		788 760	93 90	0	1	0 4	
23	108 108	89 86	99* 97	5	60 61	72 72	0	34 32	R	0 0		0.0	чг	28.69	29,79	2.1	27	5.2	17		14	26	600 706	71 84	0	4	0 3	
25		86	97	3	60	72	Ő	32		Ő		0.0		28.70		4.2		8.2		25	20		804	96	ŏ	1	0 3	
26 27	103 106	89 88	96 97	2 3	56 59	70 71	0	31 32	R	0		0.0	т 0,00	28.67		2.2		4.5 6.3	15 21	26 28		26 26	254 736	30 88	0	7	0 6	
28 29	109 104	78 79	94 92	0 -2	64 66	74 74	0	29 27	TRH	0		0.0	0.05	28.66	29.76		15	8.0 5.3		13	43 14	13	757 775	91 93	0		1	
30		85 87	94	03	61 56	72 70	0	29 31		0		0.0	0.00	28.68	29.79	2.6	21	9.8 5.8	20	12 12 26	14 18 14	16	753	91 92	0	1	0 3	
	105.8		93.9	0.4	53.6	68.6	Į'		MONTHLY	AVERA	GES				29.78	1.9	25	6.3		l			RAGES					-
	DEPAR	TURE	MONTHL	DEGRE	E DAYS		0 DATE		TOTAL SNOW			.58	AL PRECIPITATION: 0.25 TOTAL DATE			SUNSHINE TOTALS: 22620 TOTAL POSSIBLE : 2626						6 PERCENT					-	
\Box	1. 0.9 MONTHLY SEASON TO DATE TOTAL DEPARTURE TOTAL DEPARTURE HEATING: 0 0 0 0							RE	GREATEST 24-HR PRECIPITATION: 0.18						18 WIND SPEED DIRECTIO						DATE 28	-						
	COOLING		04	20		431	68		GREATEST SNOW DEPTH: 0								MAXIMUM 5-SECOND : MAXIMUM 2-MINUTE : PRECIPITATION > 0.01 IN						43		13		28	4
DAYS WITH -> CLEAR PARTLY CLOUDY CLOUDY N														0	PR	ECIPIT	OITA	N <u>></u> 1	0.10		н :	1	<-		BER OF			
DATS WITH 21 3 2 THUNDERSTORMS : 2 HEAVY FOG : 0 SNOWFALL \geq 1.0 INCH : 0 DAYS WITH																												

HOURLY PRECIPITATION (WATER EQUIVALENT IN INCHES)

JULY 1994

WBAN #23183

1				A.1	ч. н	OUR	(L.S	.т.)	END	ING A	١T		យ				р.м.	HOU	R (L	.s.T	•) E	NDIN	IG AT			ЦШ
DATE	1	2	3	4	5	6	7	8	9	10	11	12	DATE	1	2	3	4	5	6	7	8	9	10	11	12	DATE
01 02 03 04 05													01 02 03 04 05													01 02 03 04 05
6 7 8 9													06 07 08 09 10									-				06 07 08 09 10
11 12 13 14 15													11 12 13 14 15													11 12 13 14 15
16 17 18 19 20		- - - -				0.14	0.02	0.03 T		0.03	0.18		16 17 18 19 20					TT	T T	T			0.01	0.01		16 17 18 19 20
21 22 23 24 25			т	т									21 22 23 24 25													21 22 23 24 25
26 27 28 29 30 31										т			26 27 28 29 30 31		Т	Т					0.02	т	0.01	т		26 27 28 29 30 31

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MAXIMUM SHORT DURATION PRECIPITATION (MSDP) **

										1			
*The sum of the hourly otals follows the * when	TIME PERIOD (MINUTES)	5	10	15	20	30	45	60	80	100	120	150	180
ſ					· · · · · · · · · · · · · · · · · · ·								
t disagrees with the aily total on page 1.	PRECIPITATION (INCHES)	0.06	0.07	0.07	0.08	0.10	0.13	0.18	0.18	0.18			
WS does not edit ASOS ourly precipitation but	ENDED: DATE	18	18	18	18	18	18	18	18	18			
ay edit daily and month-	ENDED: TIME	0527	0530	0527	0527	0530	0550	1059	1059	1059			

 $\star \star_{\text{NCDC}}$ derives MSDP data from one-minute ASOS data. The MSDP data are not printed when inconsistent with ASOS hourly totals.

The time indicated is the ending time of the interval. Date and time are not entered for trace amounts.

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it disagrees with the daily total on page 1. NWS does not edit ASOS hourly precipitation but may edit daily and monthly totals. Hourly, daily and monthly totals are printed as reported by the ASOS site.

REFERENCE NOTES : WFO = WEATHER FORECAST OFFICE. ASOS = AUTOMATED SURFACE OBSERVING SYSTEM. * = EXTREME FOR THE MONTH (LAST OCCURRENCE IF MORE THAN ONE). T = TRACE PRECIPITATION AMOUNT. + = ALSO OCCURS ON EARLIER DATES. F+ = HEAVY FOG, VISIBILITY .25 MILES OR LESS. BLANK ENTRIES DENOTE MISSING OR UNREPORTED DATA. THE HEATING DEGREE DAY SEASON BEGINS JULY 1. THE COOLING DEGREE DAY SEASON BEGINS JANUARY 1. CEILOMETER (30-SECOND) DATA ARE USED TO DERIVE CLOUDINESS AT OR BELOW 12,000 FEET. THIS CLOUDINESS IS THE MEAN CLOUD COVER DETECTED DURING THE TIME INTERVAL (HOUR, SUNRISE TO SUNSET, OR MIDNIGHT TO MIDNIGHT). SATELLITE DATA ARE USED TO DERIVE CLOUDINESS ABOVE 12,000 FEET. EFFECTIVE CLOUD AMOUNT IS BASED ON THE CLOUD COVER AND THE TRANSPARENCY OF THE CLOUDS WITHIN THE SATELLITE FIELD OF VIEW	TEMPERATURE - HUMIDITY INDEX (STEADMAN, 1979) RELATIVE HUMIDITY (PERCENT) 0 10 20 30 40 50 60 70 80 90 100 0 120 107 116 130 148 APPARENT 115 103 111 120 135 151 APPARENT 110 99 105 112 123 137 150 TEMPERATURE 41 100 91 95 112 123 135 149 100 91 95 99 104 110 120 132 144 100 91 95 99 90 93 96 100 106 113 122 41 90 83 85 87 90 93 96 100 106 113 122 100 91 95 87 90 93 96 100 106 113 122 101 90 83 85 87 90
 (APPROX. 50 x 50 KM). SKY CONDITION IS BASED ON THE SUM (NOT TO EXCEED 10) OF THE SUMRISE TO SUMSET CLOUD COVER BELOW AND ABOVE 12,000 FEET. BOTH CEILOMETER AND SATELLITE DATA MUST BE PRESENT TO COMPUTE SKY CONDITION. CLEAR = 0 -3 TENTHS, PARTLY CLOUDY = 4 - 7 TENTHS, AND CLOUDY = 8 - 10 TENTHS. RESULTANT WIND IS THE VECTOR SUM OF THE WIND SPEEDS AND DIRECTIONS DIVIDED BY THE NUMBER OF OBSERVATIONS. WIND DIRECTION IS RECRDED IN TENS OF DEGREES (2 DIGITS) CLOCKWISE FROM TRUE NORTH. '00' INDICATES CALM. '36' INDICATES CALM. SR-SS = SUNRISE TO SUNSET. MN-MN = MIDNIGHT TO MIDNIGHT. SNOWFALL IS FOR THE 24-HOUR PERIOD ENDING AT THE TIME INDICATED IN COLUMN HEADING. WATER EQUIVALENT OF SNOW ON THE GROUND IS REPORTED ONLY WHEN THE DEPTH IS 2 OR MORE INCHES. H, F, F+, P-, R, S, AND ZR ARE REPORTED FROM ASOS AUTOMATED SENSORS. OTHER WEATHER TYPES MAY BE ADDED TO THE REPORT BY STATION 'A PERSONNEL OR BE PROVIDED BY THE WEATHER FORECAST OFFICE (WFO). 	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$
AHAILGL GLAZESGSNOW GRAINSBDBLOWING DUSTHHAZESPSNOW PELLETSBNBLOWING SANDICICE CRYSTALSTTHUNDERBSBLOWING SNOWIFICE FOGVVOLCANIC ASHBYBLOWING SPRAYIPICE PELLETSZLFREEZING DRIZZLEDDUSTKSMOKEZRFREEZING RAINFFOGLDRIZZLE&TORNADOF+HEAVY FOGP-UNKN. PRECIP.&CFUNNEL CLOUDGFGROUND FOGRRAIN&WWATERSPOUTSSNOWSNOWSNOWSNOWSNOW	-30 -30 -36 -58 -72 -81 -88 -93 -97 -100 -102 ADDITIONAL INFORMATION :
NORMALS ARE FOR THE YEARS 1961 - 1990. A HEATING (COOLING) DEGREE DAY IS THE DEFERENCE BETWEEN THE AVERAGE DAILY TEMPERATURE AND 65 [°] F. DEW POINT IS THE TEMPERATURE TO WHICH THE AIR MUST BE COOLED TO ACHIEVE 100% RELATIVE HUMIDITY. WET BULB IS THE TEMPERATURE THE AIR WOULD HAVE IF THE MOISTURE CONTENT WAS INCREASED TO 100% RELATIVE HUMIDITY.	

WBAN # 23183

JULY 1994

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	~	≤ 12K	SATEL	LITE	> 12	к гт	Я		TEMP	ERATU	JRE	_	WIN	D	PRF	SSUR			< 12K	SATELI	JTE > 1	2K FT				ERATURE		WIND	PRE	SSURE	1
	£ -	FEET	z	<u>е</u> Р	00'5	OF PT	S)	æ		•F		្ត្រ 🗂			(1HC	HES, R	;)	- 1 N	FEET	z	100'5	OF FT	1 ~ I	~		• F	1 L		~	IES,HG)	
	빈	CEILOMETER TENTHS CEILING 100'S OF F1	OBSERVATION TIME (LST)	741	. 8	H 8	VISIBILIT (MILES)	WEATHER		Ę		<u>ا</u> ک	(HZH)	NO	~		- i -	- M.		OBSERVATION TIME(LST)	17 C	. 8	ILES)	WEATHER		<u>ب</u>	ы и и и	(HEH)	ы и	1	ļ
	<u>م</u>	CELLOMETE CELLING CELLUNG	RVA (1)	EFF CLD TENTHS	LOWEST CLOUD TOP	HIGHEST TOUD TOT	(MILE	AT	BULB	POINT	EINE			50	3 11	4.1		2	SH SN S	BSERVATIO	TENTRS TENTRS CLOWER CLOWER	HIGHEST TOP	ISIBII (MILE:	AT!	BULB	POINT	RELATIVE HUMIDITY		NOILYLS		
	HOUR	STE S	SE SE		50	HIGH	SI'	WE	2		60 E1	RELAT	CEESS	DIRECT	STATIC	SEA	- 18		S I I	SEI SHI		HOIO	ISIV (M)	Ĩ			RELAT	SPEED	s 5	SEA SEA	
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	02	0 NC	0124				10.00		93	55	69	28				4 29.			0 NC	0124	0 NT	NT	10.00		83	32 5			0 28.5	9 29.70	
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	14	0 NC					10.00		104	54	72	19	7		28.6				0 NC	1325					105	49 7				2 29.73	
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	OBSERVATIONS AT 3-HO	OURLY INTERVALS	JULY 1994 WBAN # 23183 PHOENIX, AZ
$\begin{array}{c c} < 12K & \text{SATELLITE} > 12K & \text{FT} \\ \hline \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline $	$\begin{array}{c c} & \text{TEMPERATURE} \\ & F \\ & F \\ & F \\ & & & & \\ & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ $	C 12K SATELLITE > 12K FT FEET C 2 H 100'S OF PT 5 0 F	TEMPERATURE F UND PRESSURE
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SUNRISE: 0529 02 0 UC 0124 0 UT NT 10.00 05 0 UC 0427 0 UT NT 10.00 05 0 UC 0427 0 UT NT 10.00 08 0 UC 0723 0 HT NT 10.00 11 0 UC 1050 0 NT NT 10.00 14 0 UC 1325 5 190 190 10.00 17 0 NC 10.00 10.00 20 0 IC 1925 11T NT 10.00 20 0 IC 1925 11T NT 10.00 23 0 IC 2250 4 260 460 10.00 10.00 10.00 10.00 10.00 10.00 10.00 10.00 10.00 10.00 10.00 10.00 10.00 10.00 </td <td>JUL 15 SUNSET: 1939 86 40 61 20 0 00 28.64 29.75 82 41 59 23 5 13 28.68 29.78 86 47 63 26 5 06 28.77 29.88 96 40 64 14 5 36 28.77 29.88 103 45 68 14 7 06 28.71 29.82 106 48 70 14 3 34 28.64 29.75 101 48 68 17 3 01 28.62 29.74 97 44 66 16 5 32 28.66 29.78 JUL 16 SUNSET: 1938</td> <td>05 0 HC 0427 0 HT NT 10.00 08 0 HC 0723 0 HT HT 10.00 11 0 HC 1050 0 HT HT 10.00 14 0 HC 1325 0 HT HT 10.00 17 HC 10.00 10.00 10.00 10.00 20 HC 1925 2 180 440 10.00</td> <td>86 62 70 45 5 07 28.72 29.83 84 62 70 48 5 10 28.73 29.84 87 61 70 42 7 13 28.77 29.89 96 59 72 29 5 13 28.76 29.88 103 56 72 21 5 24 28.70 29.80 106 56 73 19 8 29 28.61 29.74 101 54 71 21 9 27 28.64 29.74 97 56 71 25 6 26 28.68 29.74</td>	JUL 15 SUNSET: 1939 86 40 61 20 0 00 28.64 29.75 82 41 59 23 5 13 28.68 29.78 86 47 63 26 5 06 28.77 29.88 96 40 64 14 5 36 28.77 29.88 103 45 68 14 7 06 28.71 29.82 106 48 70 14 3 34 28.64 29.75 101 48 68 17 3 01 28.62 29.74 97 44 66 16 5 32 28.66 29.78 JUL 16 SUNSET: 1938	05 0 HC 0427 0 HT NT 10.00 08 0 HC 0723 0 HT HT 10.00 11 0 HC 1050 0 HT HT 10.00 14 0 HC 1325 0 HT HT 10.00 17 HC 10.00 10.00 10.00 10.00 20 HC 1925 2 180 440 10.00	86 62 70 45 5 07 28.72 29.83 84 62 70 48 5 10 28.73 29.84 87 61 70 42 7 13 28.77 29.89 96 59 72 29 5 13 28.76 29.88 103 56 72 21 5 24 28.70 29.80 106 56 73 19 8 29 28.61 29.74 101 54 71 21 9 27 28.64 29.74 97 56 71 25 6 26 28.68 29.74
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JULY 1994 WBAN # 23183

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\sim	<u>≤ 12K</u>	SATEL	LITE	> 12	2K FT	ו או		TEMP	ERATU	IRE	_	WIND		PRE	SSURE		< 12K	SATE	LLIT	E > 12	K FT	~		TEM	PERATU	JRE	~ W	THD	PRE	SSURE
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J-99

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SUPPLEMENTARY HOURLY PRECIPITATION UNIVERSAL RAIN GAUGE (WATER EQUIVALENT IN INCHES)

JULY 1994

LATITUDE 33° 26'N LONGITUDE 112° 01'W

PHC	DENIX	<u>, AZ</u>																	•			LOI	GITU	DE 11.	2 01	<u>w</u> ,	
DATE				A.1	1. но	OUR (L.S.	.T.)	END:	ING A	Υ		ធ្ម				р.м.	нои	R (L	.s.T	.) E	NDIN	G AT			DATE	DAILY
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	PUB	LISHE	D BY:	NCDC	, Ash	EVILL	E, NC	•															мо	NTHLY	TOTA	L	0.25

SUPPLEMENTARY MAXIMUM SHORT DURATION PRECIPITATION (MSDP)

TIME PERIOD (MINUTES)	5	10	15	20	30	45	60	80	100	120	150	180
PRECIPITATION (INCHES)	0.05	0.06	0.06	0.06	0,07	0.07	0.08	0.08	0.09	0.09	0.10	0.10
ENDED: DATE	18	18	18	18	18	18	18	18	18	18	18	18
ENDED: TIME	1005	1006	1006	1006	1025	1025	0617	0650	0650	0729	0729	0729

The National Weather Service has determined that the ASOS Heated Tipping-Bucket (HTB) rain gauge may not measure water equivalent precipitation accurately during frozen precipitation events. Precipitation data from a nearby site is provided on this page to supplement the ASOS HTB data.

The time indicated is the ending time of the interval.

Date and time are not entered for trace amounts.

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РНО	UST 19 ENTX, HARBO	AZ	L AIRP	ORT.	上(JC.		J jah	CLI ed by: N								ł	D	A']	! /	Ţ	UNITE			5		
ĿA	TITUD	E: 33	° 26′ 1	N	LONG	ITUDE:							IND):				z 0	NE: M	IOUNT.	AIN ARD		SN# BAN#		8-04	175		
\prod		'TE	MPERAT	URE 'F		.	DEG I BASE			SNOW	/ICE	PRECIP	ITATION HES)	PRES				PEED = IR = T		DEG		SUNSI		1	נסטס	INESS	
DATE	MAXIMUM	WOWINIW	AVERAGE	DEP FROM NORMAL	AVERAGE DEW PT	AVERAGE WET BULB	HEATING	COOLING	SIGNIFICANT WEATHER	0500 LST HL430	1100 LST AJINO EQUIV	SNOW-IT 0 SNOW-IT 0 FALL FALL	WATER Equiv	AVERAGE STATION	AVERAGE SEA LEVEL	RESULTANT WIND SPEED	RES DIR	AVERAGE SPEED	<u>5-se</u>	AXIM C 2 M	SPEED NUM	HE	PERCENT POSSIBLE	LOMETER SUTHS	ELLITE CO	CEILOMETER W TENTHS U SATELLITE W	
1	2	3	4	5	6	17	8	9	10	11	전 G 전 G 12	_13_	14	_15	16	17	2 18	19	20	21	0 0 22 2	F 2 24	표요 25	記 記 26	27	응답 등 28 2	5.
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AUGUST 1994

TOCAT CT TMAMOT OCTCAT



J-101

HOURLY PRECIPITATION (WATER EQUIVALENT IN INCHES)

AUGUST 1994 PHOENIX, AZ WBAN #23183

																					JENIX	,				
A.M. HOUR (L.S.T.) ENDING AT										AT'		щ				P.M.	нои	R (L	.S.T	.) E	NDIN	g at		_	DATE	
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PUBLISHED BY: NCDC, ASHEVILLE, NC.

*The sum of the hourly totals follows the * when it disagrees with the daily total on page 1. NWS does not edit ASOS hourly precipitation but may edit daily and monthly totals. Hourly, daily and monthly totals are printed as reported by the ASOS site.

MAXIMUM SHORT DURATION PRECIPITATION (MSDP) **

										<u> </u>	'		
ly en	TIME PERIOD (MINUTES)	5	10	15	20	30	45	60	80	100	120	150	180
	PRECIPITATION (INCHES)												
•	ENDED: DATE												
t h-	ENDED: TIME												
1													

* *NCDC derives MSDP data from one-minute ASOS data. The MSDP data are not printed when inconsistent with ASOS hourly totals.

The time indicated is the ending time of the interval. Date and time are not entered for trace amounts.

REFERENCE NOTES :	
 WFO = WEATHER FORECAST OFFICE. ASOS = AUTOMATED SURFACE OBSERVING SYSTEM. * = FXTREME FOR THE MONTH (LAST OCCURRENCE IF MORE THAN ONE). T = TRACE PRECIPITATION AMOUNT. * = ALSO OCCURS ON EARLIER DATES. F+ = HEAVY FOG, VISIBILITY .25 MILES OR LESS. BLANK ENTRIES DENOTE MISSING OR UNREPORTED DATA. THE HEATING DEGREE DAY SEASON BEGINS JANUARY 1. CEILOMETER (30-SECOND) DATA ARE USED TO DERIVE CLOUDINESS AT OR BELOW 12,000 FEET. THIS CLOUDINESS IS THE MEAN CLOUD COVER DETECTED DURING THE TIME INTERVAL (HOUR, SUNRISE TO SUNSET, OR MIDNIGHT TO MIDNIGHT). SATELLITE DATA ARE USED TO DERIVE CLOUDINESS ABOVE 12,000 FEET. EFFECTIVE CLOUD AMOUNT IS BASED ON THE CLOUD COVER AND THE TRANSPARENCY OF THE CLOUDS WITHIN THE SATELLITE FIELD OF VIEW (APPROX. 50 x 50 KM). SKY CONDITION IS BASED ON THE SUM (NOT TO EXCEED 10) OF THE SUNRISE TO SUNSET CLOUD COVER BELOW AND ABOVE 12,000 FEET. BOTH CEILOMETER AND SATELLITE DATA MUST BE PRESENT TO COMPUTE SKY CONDITION. CLEAR = 0 -3 TENTHS, PARTLY CLOUDY = 4 - 7 TENTHS, AND CLOUDY = 8 - 10 TENTHS. RESULTANT WIND IS THE VECTOR SUM OF THE WIND SPEEDS AND DIRECTIONS DIVIDED BY THE NUMBER OF OBSERVATIONS. WIND DIRECTION IS RECREDED IN TENS OF DEGREES (2 DIGITS) CLOCKWISE FROM TRUE NORTH. '00' INDICATES CALM. '36' INDICATES CALM. SR-SS = SUNRISE TO SUNSET. M-HM = MIDNIGHT TO MIDNIGHT. SNOWFALL IS FOR THE 24-HOUR PERIOD ENDING AT THE TIME INDICATED IN COLUMN HEADING. WATER EQUIVALENT OF SNOW ON THE GROUND IS REPORTED ONLY WHEN THE DEFTH IS 2 OR MORE INCHES. H, F, F+, P-, R, S, AND ZR ARE REPORTED FROM ASOS AUTOMATED SENSORS. 	TEMPERATURE ° F TEMPERATURE ° F 101-050505 100050505 100050505 100050505 1000505 100050505 100050505 10005005 1000505 100
OTHER WEATHER TYPES MAY BE ADDED TO THE REPORT BY STATION PERSONNEL OR BE PROVIDED BY THE WEATHER FORECAST OFFICE (WFO). A HAIL GL GLAZE SG SNOW GRAINS BD BLOWING DUST H HAZE SP SNOW PELLETS	-15 -20 -25 -30
BN BLOWING SAND IC ICE CRYSTALS T THUNDER BS BLOWING SNOW IF ICE FOG V VOLCANIC ASH BY BLOWING SPRAY IP ICE PELLETS ZL FREEZING DRIZZLE D DUST K SMOKE ZR FREEZING RAIN F FOG L DRIZZLE & TORNADO F+ HEAVY FOG P- UNKN. PRECIP. &C FUNNEL CLOUD GF GROUND FOG R RAIN &W WATERSPOUT S SNOW SNOW SNOW SNOW SNOW	ADDIT
NORMALS ARE FOR THE YEARS 1961 - 1990. A HEATING (COOLING) DEGREE DAY IS THE DEFERENCE BETWEEN THE AVERAGE DAILY TEMPERATURE AND 65°F. DEW POINT IS THE TEMPERATURE TO WHICH THE AIR MUST BE COOLED TO ACHIEVE 100% RELATIVE HUMIDITY. WET BULB IS THE TEMPERATURE THE AIR WOULD HAVE IF THE MOISTURE CONTENT WAS INCREASED TO 100% RELATIVE HUMIDITY.	

			TEMP	ERATU	RE - 1	HUMID	ITY 1	INDEX	(STEA	DMAN,	1979)
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TEMPERATURE	95	87	90	93	96	101	107	114	124	136		
Ξ	90	83	85	87	90	93	96	100	106	113	122	
ម្ម	85	78	80	82	84	86	88	90	93	97	102	108
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	75	69	70	72	73	74	75	76	77	-78	79	80
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WIND CHILL EQUIVALENT TEMPERATURE (SIPLE & PASSEL, 1945)

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2	15	15	11	-3	-11	-17	-22	-25	-27	-29	-30	
ធ	10	10	6	-9	-18	-24	-29	-33	35	-37	-38	
TEMPERATURE	5	5	0	-15	-25	-31	-36	-41	-43	-45	-46	
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E-I	-5	-5	-10	-27	-38	-46	-51	-56	-58	-60	-62	
	-10	-10	-15	-34	-45	-53	-59	-64	-67	-69	-70	
	-15	15	-21	-40	~51	-60	66	-71	-74	-76	-78	
	-20	-20	~26	-46	-58	-67	-74	-79	-82	-84	-85	
	~25	-25	-31	-52	-65	-74	-81	-86	-89	-92	-93	
	-30	-30	-36	-58	-72	-81	-88	93	-97	-100	~102	

ADDITIONAL INFORMATION :

OBSERVATIONS AT 3-HOURLY INTERVALS AUGUST 1994 WBAN # 23103

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AUGUST 1994 WBAN # 23183 PHOENIX AZ

£								PHO	ENIX, AZ	
< 12K SATELLITE > 12K FT	TEM	PERATURE	WIND	PRESSURE	< 12K	SATELLITE > 12K FT	54	TEMP	ERATURE	- WIND PRESSURE
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			0 NC					10.00		100	60	73	27	6	21	28.5	4 29	9.64				23	ō	2	94	61	72	35	28.60	29.77	10.00	7	2	27	
			0 NC	2250	0	NT	NT	10.00		91	65	73	42						I		l	24	0	3	92	61	72	37	28.67	29.78	10.00	[7	0	0	

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J-106

PAGE 6

SUPPLEMENTARY HOURLY PRECIPITATION UNIVERSAL RAIN GAUGE (WATER EQUIVALENT IN INCHES)

AUGUST	1	9	9	4
PHOENIX.	A	2		

LATITUDE 33° 26'N LONGITUDE 112° 01'W

1	UENIX T	,					·····												-			LOS	GITU	DE 11.	2 01	'W	
DATE				A.1	м. но	OUR	(L.S	.т.)	END	ENG A	ΥТ		щ				P.M.	HOU	R (L	.s.T	.) E	NDIN	g at			DATE	DAILY
	1	2	3	4	5	6	7	8	9	10	11	12	DATE	1	2	3	4	5	6	7	8	9	10	11	12	DA	TOTAL
01 02 03 04 05													01 02 03 04 05							т	T					01 02 03 04 05	0.00 0.00 0.00 0.00 T
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21 22 23 24 25													21 22 23 24 25													21 22 23 24 25	0.00 0.00 0.00 0.00 0.00
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	PUBLISHED BY: NCDC, ASHEVILLE, NC.												<u></u>			L <u></u>	L	L	I	1		L	моі	NTHLY	TOTA		

SUPPLEMENTARY MAXIMUM SHORT DURATION PRECIPITATION (MSDP)

TIME PERIOD (MINUTES)	5	10	15	20	30	45	60	80	100	120	150	180
PRECIPITATION (INCHES)	0.04	0.07	0.08	0.08	0.08	0.08	0.08	0.08	0.08	0.08	0.08	0.08
ENDED: DATE	08	08	08	80	08	08	08	08	08	08	08	80
ENDED: TIME	0206	0206	0206	0206	0206	0206	0206	0206	0206	0206	0206	0206

The National Weather Service has determined that the ASOS Heated Tipping-Bucket (HTB) rain gauge may not measure water equivalent precipitation accurately during frozen precipitation events. Precipitation data from a nearby site is provided on this page to supplement the ASOS HTB data.

The time indicated is the ending time of the interval.

Date and time are not entered for trace amounts.

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Inquiries/Comments Call: (704) 271-4682

To change your address, please return a copy of the mailing label with your address to: National Climatic Data Center (Subscription Service).

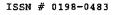
NATIONAL CLIMATIC DATA CENTER FEDERAL BUILDING 37 BATTERY PARK AVE ASHEVILLE, NORTH CAROLINA 28801-2733

OFFICIAL BUSINESS PENALTY FOR PRIVATE USE \$300 FIRST CLASS POSTAGE AND FEES PAID NOAA PERMIT G-19 MAR 1994 TUCSON, AZ NAT'L WEA SER OFC INTERNATIONAL AIRPORT

INQUIRIES/COMMENTS CALL (704) 271-4800 VOICE 271-4010 TDD/271-4876 FAX

INTERNATIONAL AIRPORT

LOCAL





CLIMATOLOGICAL DATA

MONTHLY SUMMARY

	LA?	TITUI	DE 32	° 07	'N L	ONGIT	UDE	110°	56'W EI	EVAT	ON (G	ROUNE) 2584	4 F.	EET		TIME	ZON	E I	MOUNT	AIN		23	160
			TEMPE	RATU	RE °	F	DFGREI BASE	E DAYS	WEATHER TYPES	SNOW/ ICE	PRECIPIT (INCH		AVERAGE STATION			WI	ND P.H.	\ \			SUNSI	IINE	SKY COVE TENT	8
					(E AAL	E			1 FOG 2 HEAVY FOG 3 THUNDERSTORMS	ON GRD	INT	STS	PRESSURE (INCHES	110	E		PE/ GUS	λK.	FAST				Ŧ	
	- DATE	MAXIMUM	MINIMUM	AVERAGE	DEPARTURE ^{IN} FROM NORMAL	MUERAGE DEW POINT	A HEATING	DNITOOD 7B	4 ICE PELLETS 5 HAIL 6 GLAZE 7 DUSTSTORM 8 SMORE, HAZE 9 BLOWING SNOW 8	GRD AT 0500 (IN.) 9	UNTER EQUIVALENT	H ICE PELLETS	OF Hg) ELEV. 2555 (FT.NSL) 12	TRSULTANT	L RESULTANT P SPEED	L AVERAGE	Q334S 16	BIG 17	CIERD 18	HIG 19	NINUTES	PERCENT POSSIBLE	N TO SUNSET	C HIDNIGHT
	01	75	42	59	3	27	6	0	<u> </u>	0	0.00	0.0	27.470	-	1.8	7.1	16	SE	7	NW	690	100	0	0
	02 03 04 05	82 85 82 81	46 57 51 48	64 71 67 65	8 15 11 9	24 31 33 28	1 0 0 0	0 6 2 0		0 0 0	0.00 0.00 0.00 0.00	0.0 0.0 0.0 0.0	27.440 27.420 27.410 27.340	19 23	10.1 4.1 1.6 2.4	10.8 8.7 7.4 8.8	33 20 21 24	e Sw W W	16 10 12 13	s W	474 477 685 698	69 69 99 100	10 7 3 0	9 8 3 0
94 AZ	06 07 08 09 10	82 62 64 73 82	50 48 41 40* 44	66 55 53 57 63	9 -2 -4 0 6	28 41 39 37 30	0 10 12 8 2	1 0 0 0	3	0 0 0 0	0.00 0.18 0.00 0.00 0.00	0.0	27.260 27.300 27.370 27.410 27.360	31 34 15	9.1 3.4 2.3 0.9 4.6	11.8 8.4 7.7 7.5 9.6	32 23 20 17 26	SE	20 15 11 9 12	W NW NW	207 580	100 30 83 100 99	4 9 5 0 4	2 7 3 0 3
19	11 12 13 14 15	78 70 65 76 83	47 49 49 52 49	63 60 57 64 66	5 2 -1 6 8	29 36 36 37 37	2 5 8 1 0	0 0 0 1		0 0 0 0	T 0.00 0.00 0.00 0.00	0.0	27.400 27.490 27.350	36 11 12	2.6 11.7	12.3 8.9 12.8 11.1 7.5	36 20 33 33 18		27 13 19 14 9	SW NW NE E NW	608 529 359 683 717	86 74 50 96 100	7 5 7 3 4	5 5 3 3
TUCSON	16 17 18 19 20	90* 88 79 76 70	52 55 54 53 52	71 72* 67 65 61	12 13 8 6 2	36 37 44 52 50	0 0 0 0 4	6 7 2 0 0		0 0 0 0	0.00 0.00 0.08 0.54 0.22	0.0 0.0 0.0	27.290	24 14 17	2.5 2.9 2.3 5.0 2.6	8.7 7.8 8.7 10.1 8.8	23 24 30 38 26	NE W SW W W	17 12 17 26 16	NW SW SW W W	679 716 261 169 327	94 99 36 23 45	5 8 10 10 9	5 8 8 10 9
	21 22 23 24 25	77 81 77 80 71	149 53 51 48 50	63 67 64 64 61	3 7 4 4 0	46 39 38 37 38	2 0 1 1 4	0 2 0 0		0 0 0 0	0.00 0.00 0.00 0.00 T	0.0	27.350 27.180 27.190 27.210 27.200	21 23 20	6.6 8.2	6.6 10.6 10.4 11.2 12.8	20 29 35 33 36	SW SW SW	7 18 24 25 25	W SW SW SW S	728 648 573 735 404	100 89 78 100 55	0 6 9 1 10	0 7 7 1 8
	26 27 28 29 30 31	60 68 74 81 86 86	46 43 47 45 50 51	53* 56 61 63 68 69	-8 -5 0 2 6 7	42 34 15 27 30 31	12 9 4 2 0 0	0 0 0 3 4		0 0 0 0	0.12 0.00 0.00 0.00 0.00 0.00	0.0 0.0 0.0 0.0 0.0	27.360 27.490 27.435 27.420	32 10 26 09	3.4 4.0 5.2 0.8 1.9 2.5	8.6 9.2 9.1 7.1 8.4 8.3	26 28 23 22 28 24	N W E N NW	20 11 11	NE NW NW	269 616 701 651 672 748	36 83 94 87 90 100	8 2 1 3 3 0	7 2 3 6 3 0
1		SUM	SUM	\sim	> <	\leq	_	TOTAL	NUMBER OF	DAYS	TOTAL	TOTAL	27.340	FC	7		_	W		SW	TOTAL 17710	* FOR	SUM S	
		2384 AVG.	1512 AVG.	AVG.	DEP.	I AVG.	94 DEP.	34 DEP.	PRECIPITATI		1.14 DEP.	0.0	21.340	118		- 3.3		£:19		E:11	POSS	MONTH	AVG	AVG
		76.9	48.8	62.9	4.2	35.1	-135	1	≥ .01 INCH	5	0.42				_				DEP		22306		4.91	4.5
		N	UMBER (OF DAY	ſS		SEASON TOTAL	TO DATE	SNOW, ICE P ≥ 1.0 INCH	ELLETS 0	GREAT	EST IN	1 24 HOUI	RS A	ND DA	TES					GROUN OR IC			
		MAXIN	NUM TEM	_	NIMUM	TEMP.	1257	38			PRECIP	_			E PEL	LETS		DATE					-	
		≥ 90	_	<u> </u>	32' ≤		DEP.	DEP.	HEAVY FOG	0	0.75 Y CLOUI	<u>19-2</u>	0 0 CLOUD	.0_	9		L	0						
	- 1	1	0	1	0	0	-317	0	CLEAR 12	PARTI		<u>ui 10</u>		±	<u> </u>									

* EXTREME FOR THE MONTH - LAST OCCURRENCE IF MORE THAN ONE. DATA IN COLS 6 AND 12-15 ARE BASED ON 21 OR MORE OBSERVATIONS AT T TRACE AMOUNT. + ALSO ON EARLIER DATE(5). HEAVY FOG: VISIBILITY 1/4 MILE OR LESS. BLANK ENTRIES DENOTE MISSING OR UNREPORTED DATA. BLANK ENTRIES DENOTE

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Kenneth D Hadee

NATIONAL NATIONAL OCEANIC AND OCEANIC AND INFORMATION SERVICE

NATIONAL

DIRECTOR CLIMATIC DATA CENTER DIRECTOR ASHEVILLE, NORTH CAROLINA NATIONAL CLIMATIC DATA CENTER

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			LTY.		TEME	ERAT	URE		WI	ND			Y'T'			TEM	PERAT	TURE		WI	NÐ	3)	5	YT1.		TE	IPER	TURE		WI	ND
HOUR L.S.T.	SKY COVER (TENTHS)	CEILING IN HUNDEREDS OF FEET	WHOLE MILES VISIBILITY 16THS MILE	WEATHER	AIR °F	WET BULB °F	DEW POINT °F	REL HUMIDITY 8	DIRECTION	SPEED (KNOTS)	SKY COVER (TENTHS)	CEILING IN HUNDEREDS OF FEET	WHOLE MILES VISIBILITY 16THS MILE		MENTHER	AIR [°] F	WET BULB °F	DEW POINT °F	REL NUMIDITY &	DIRECTION	SPEED (KNOTS)	SKY COVER (TENTHS)	CEILING IN HUNDEREDS OF FEET	WHOLE MILES VISIBILITY	WEATHER	AIR *F	WET BULB °F	A. INION MAD	REL HUMIDITY	DIRECTION	SPEED (KNOTS)
02 05 08 11 14 17 20 23	000000	UNL UNL UNL UNL UNL UNL UNL	30 30 60 60 60 30 30	MAR 01	44 42 46 64 72 74 65 52	38 36 38 49 50 47 41	29 28 28 31 22 22 26 27	56 58 50 29 15 14 23 38	14 14 16 36 01 32 32 12	47	7 10 10 10 10 10	UNL 220 220 220 220 UNL 250 250	30 50 50 45 30 30	MAR	02	48 49 52 71 78 78 64 64	39 39 41 49 52 52 47 46	27 24 25 22 23 23 26 25	44 38 35 16 13 13 24 23	13 14 14 12 11 09 09 08	8 7 12 17 14 11 6 7	10 9 8 3 8 8	250 220 120 150 UNL 110 110 UNL	30 30 55 50 50 30 30	MAR 0	3 6 6 7 8 8 7 4 6	46 47 54 58 56 54	27 28 30 35 34 34	29 27 17 17	19 14 12 16 21 28 30 19	6 11 6 10 10
02 05 08 11 14 17 20 23	5 6 4 2 1 0	95 UNL UNL UNL UNL UNL UNL UNL	30 30 50 50 50 70 30 30	MAR 04	58 54 56 72 80 80 70 63	47 44 52 56 55 51 47	36 33 34 32 33 32 32 32 30	44 45 44 23 18 25 29	16 15 13 34 29 32 33 20	5 5 3 6 2 5 6	0 1 2 0 0	UNL UNL UNL UNL UNL UNL UNL	30 30 50 60 50 30	MAR	03	54 50 54 71 81 80 67 58	44 42 52 54 52 48 44	31 31 34 25 21 25 26	42 48 42 26 13 11 20 29	14 13 13 25 26 29 23 15	7 5 11 4 9 10 3 7	0 1 10 2 0 0	UNL UNL 140 UNL UNL UNL UNL	30 30 50 50 50 30 30 30	MAR 0	6 5 5 7 7 7 6 6	42 44 53 54 51 47	31 33 33 28 20 20	45 47 45 23 15 11 15 24	12 13 16 19 22 20 20 23	8 5 17 12 18 12 5
02 05 08 11 14 17 20 23	0 5 10 10 9 7 7 10	UNL 75 35 35 45 55 45	30 30 30 15 50 30	MAR 07 RW	52 50 53 53 61 59 56 49	42 42 47 50 52 51 48 48	30 31 40 47 45 44 40 46	43 48 62 80 56 58 55 90	04 00 31 29 20 01 31 20	5 0 9 16 10 6 12 10	7 3 7 6 0	48 UNL 85 UNL 75 85 UNL UNL	30 30 50 50 50 30	MAR	08	45 44 56 61 56 49	43 43 43 49 49 49 48 45	41 41 40 37 37 39 40	86 89 55 41 41 53 71	19 12 17 28 30 31 34 16	5 3 5 7 10 8 4	0 0 0	UNL UNL UNL UNL UNL UNL UNL	30 30 50 50 40 30	MAR 0	9	39 40 50 53 52 50	37 36 40 38 31 36	عو ا	15 16 15 02 32 01 33 13	E .
02 05 08 11 14 17 20 23	093030	UNL UNL UNL UNL UNL UNL UNL	30 30 50 50 50 30 30	MAR 10	47 47 51 73 80 81 69 62	43 42 44 52 53 52 50 46	39 36 35 30 22 19 30 28	74 66 55 20 12 10 23 28	13 15 16 13 19 28 30 19	6 8 7 13 7 8 7 5	59955	UNL 250 UNL UNL UNL UNL 65	30 30 50 50 15 15	MAR	11	52 47 53 70 76 72 63 57	42 39 42 50 52 50 47 48	29 29 27 29 28 24 30 38	41 50 37 22 17 17 29 49	14 15 14 20 25 24 24 31	8 7 9 14 17 14 14	10 4 5 4 7 5	UNL 90 UNL UNL UNL UNL UNL UNL	30 30 40 40 30 30	MAR 1	2 55566	46 49 51 50 48	38 39 35 34 31 35		16 19 36 35 35	
02 05 08 11 14 17 20 23	3 8 9 10 1	UNL 200 100 55 UNL UNL UNL	30 30 40 40 30 30 30	MAR 13	50 55 57 60 62 57 56	43 45 46 47 48 50 46 46	35 33 35 37 35 37 35 35 36	57 44 47 47 39 40 44 47	18 11 12 10 09 07 09	3 9 20 20 17 14 9 6	0 2 6 4 1	UNL UNL UNL UNL UNL 100 100	30 50 50 50 50 30 30	MAR	14	54 56 68 74 75 67 64	46 46 47 52 55 55 51 51	37 36 37 38 38 36 35 39	53 47 49 33 27 24 31 40	08 14 12 13 05 06 12 15	8 15 18 11 9 7 8	0 0 1 7 8 6	UNL UNL UNL UNL UNL UNL UNL	30 50 50 50 30 30	MAR 1	5 5 5 7 80 82 7 6	46 47 55 56	40 40 38 35 34	20	15 13 13 30 30 34 15	6
02 05 08 11 14 17 20 23	05	UNL UNL UNL UNL UNL UNL UNL	30 30 50 40 40 60 30 30	MAR 16	56 54 58 80 88 88 77 67	46 45 48 57 59 59 56 52	34 35 37 38 35 33 37 37	44 49 46 22 15 14 24 33	13 15 13 15 22 05 33 21	8 11 7 10 5 10 6	10 10 4 6 9 10 8 4	UNL UNL UNL UNL UNL UNL UNL	30 30 40 45 60 30 30	MAR	17	62 57 60 79 85 86 76 66	49 56 58 59 56	38 36 35 36 37 38 38	41 46 44 20 17 18 25 36	14 14 15 34 35 27 25 24	6 7 5 10 10 7 8	0 10 10 10 10 10 6	UNL 250 150 140 70 130 250	300 50 50 100 30 30	MAR 1 R R	8 5 5 7 7 5 5	49 49 56 55 57 57	38 39 39 38 52 54 53	41 46 26 26 90 93	14 13 15 33 34 28 13 12	8 9 6 7 10 9 5 7

MAXIMUM SHORT DURATION PRECIPITATION

TIME PERIOD (MINUTES)	5	10	15	20	30	45	60	80	100	120	150	180
PRECIPITATION (INCHES)	0.07	0.13	0.16	0.16	0.18	0.20	0.21	0.23	0.25	0.27	0.27	0.28
ENDED: DATE	19	19	19	19	19	19	19	19	19	19	19	19
ENDED: TIME (LST)	1833	1840	1842	1842	1842	1912	1925	1943	1943	1943	1943	1943

THE PRECIPITATION AMOUNTS FOR THE INDICATED TIME INTERVALS MAY OCCUR AT ANY TIME DURING THE MONTH. THE TIME INDICATED IS THE ENDING TIME OF THE INTERVAL. DATE AND TIME ARE NOT ENTERED FOR TRACE AMOUNTS.

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WEATHER CODES AND NOTES

*	TORNADO	SW	SNOW SHOWERS	GF	GROUND FOG
т	THUNDERSTORM	SG	SNOW GRAINS	зD	BLOWING DUST
0	SQUALL	52	SNOW PELLETS	ΒN	BLOWING SAND
R	RAIN	IC	ICE CRYSTALS	BS	BLOWING SNOW
RW	RAIN SHOWERS	IP	ICE PELLETS	ВY	BLOWING SPRAY
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EAST, 18 FOR SOUTH, 27 FOR WEST. AN ENTRY OF 00 INDICATES CALM. SPEED: THE OBSERVED AVERAGE ONE-MINUTE VALUE (MPH=KNOTS X 1.15).

SUMMARY BY HOURS

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HOUR L.S.T.	SKY COVER (TENTHS)	STATION PRESSURE (INCHES)	AIR 'F	YET BULB °F	A . TNIO4 WED	REL HUMIDITY &	SPEED (MPH)	DIRECTION	SPEED (MPH)
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11	5	27.380	69	52	35	33	9.9	17	3.8
14	5	27.320	75	53	32	23	11.7	27	4.6
17	5	27.290	74	53	32	27	12.3	29	5.3
20	5	27.320	66	51	35	37	9.2	30	3.8
23	4	27.350	59	48	37	48	7.5	18	2.د

NATIONAL CLIMATIC DATA CENTER ROOM 120 151 PATTON AVENUE ASHEVILLE, NORTH CAROLINA 28801-5001

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INQUIRIES/COMMENTS CALL CLIMATOLOGICAL DATA (704) 271-4800 VOICE 271-4010 TDD/271-4876 FAX

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9 0 -372 35 CLEAR 14 PARTLY CLOUDY 10 CLOUDY 6 ٥ 0

* EXTREME FOR THE MONTH - LAST OCCURRENCE IF MORE THAN ONE. DATA IN COLS 6 AND 12-15 ARE BASED ON 21 OR MORE OBSERVATIONS AT

T TRACE AMOUNT. + ALSO ON EARLIER DATE(S). HEAVY FOG: VISIBILITY 1/4 MILE OR LESS. BLANK ENTRIES DENOTE MISSING OR UNREPORTED DATA.

HOURLY INTERVALS. RESULTANT WIND IS THE VECTOR SUM OF WIND SPEEDS AND DIRECTIONS DIVIDED BY THE NUMBER OF OBSERVATIONS. COLS 16 & 17 : PEAK GUST - HIGHEST INSTANTANEOUS WIND SPEED. ONE OF TWO WINDS IS GIVEN UNDER COLS 18 & 19 : FASTEST MILE- HIGHEST RECORDED SPEED FOR WHICH A MILE OF WIND PASSES STATION (DIRECTIONIN COMPASS POINTS). FASTEST OBSERVED ONE MINUTE WIND - HIGHEST ONE MINUTE SPEED (DIRECTION IN TENS OF DEGREES). ERRORS WILL BE CORRECTED IN SUBSEQUENT PUBLICATIONS.

I CERTIFY THAT THIS IS AN OFFICIAL PUBLICATION OF THE NATIONALOCEANIC AND ATMOSPHERIC ADMINISTRATION. AND IS COMPILED FROM RECORDS ON FILE AT THE NATIONAL CLIMATICDATA CENTER.

Kenneth D Hadean

NATIONAL NATIONAL OCEANIC AND OCEANIC AND NATIONAL ENVIRONMENTAL SATELLITE. DATA. AND INFORMATION SERVICE

NATIONAL CLIMATIC DATA CENTER DIRECTOR ASHEVILLE, NORTH CAROLINA NATIONAL CLIMATIC DATA CENTER



ISSN # 0198-0483

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			YT1.		TEM	PERA	TURE]	WI	ND			TTY.	1		TEM	PERA	TURE		WI	ND			ΙTΥ		TEM	PERA	TURE	<u> </u>	WI	ND -
HOUR L.S.T.	SKY COVER (TENTHS)	CEILING IN HUNDEREDS OF FEET	ATLA MILE VISIBILITY	WEATHER	AIR [°] F	MET BULB F	DEW POINT 'F	& ALICINNII TEN	DIRECTION	SPEED (KNOTS)	SKY COVER (TENTHS)	CEILING IN HUNDEREDS OF FEET	VHOLE MILES VISIBILITY		WEATHER	AIR °F	WET BUI,B 'F	DEM POINT 'F	REL HUMIDITYS	DIRECTION	SPEED (KNOTS)	SKY COVER (TENTHS	CEILING IN HUNDEREDS OF FEET	WHOLE MILES VISIBILITY	WEATHER	AIR ° F	WET BULA F	J. INTOA MAG	REC RUMIDITY	DIRECTION	SPEED (KNOTS)
02 05 08 11 14 17 20 23	0 0 0 5 10 10 8	UNL UNL UNL UNL UNL UNL UNL	30 30 50 50 50 50 30 30	APR 0	1 55 62 81 86 86 76 65	46 44 47 55 56 55 50 48	36 32 31 30 27 21 19 28	49 42 31 16 12 9 12 25	15 14 14 18 28 28 28 15	7 10 13 4 10 12 5 9	00000	UNL UNL UNL UNL UNL UNL UNL	30 30 50 50 45 60 30 30	APR	02	56 54 61 78 84 84 74 62	45 43 46 52 54 55 51 48	32 30 27 24 21 24 27 33	40 40 28 13 10 11 17 34	10 15 13 18 23 30 35 15	6 7 9 4 10 10 8 6	0 3 7	UNL UNL UNL UNL 250 250	3000000 550000 300000000000000000000000	APR 0:	3 52 63 81 87 84 76 67	45 43 48 55 56 54 49 48	33 31 31 29 25 23 14 26	42 45 30 15 10 11 9 21	13 13 15 21 23 22 28 14	7 5 11 7 10 14 5 5
C2 05 08 11 14 17 20 23	10 1 10 10 4	250 250 UNL 250 250 UNL 100	30 30 50 50 50 30 30	APR 0	4 62 64 77 78 76 70 63	46 48 52 52 50	27 26 30 24 24 17 19 22	23 25 28 14 13 11 14 21	15 24 00 28 26 26 29 29	8 4 0 10 18 15 14 8	N O O O O O O O	UNL UNL UNL UNL UNL UNL UNL	30 30 50 50 70 30 30	APR	05	57 49 58 67 72 73 63 52	44 40 44 43 46 45 42 38	28 29 26 4 4 2 7 14	33 46 29 8 7 6 11 22	23 14 32 30 31 32 36 15	7 8 15 17 16 5 6	7 9 0 3 9 2	UNL UNL UNL UNL UNL UNL UNL	30 30 50 50 50 30 30	APR 00	47 47 52 73 79 79 71 60	35 34 37 47 50 50 47 43	15 12 11 11 8 15 21	28 24 19 6 12 22	16 13 13 21 34 30 27 11	7 12 11 4 9 12 7 7
02 05 08 11 14 17 20 23	3 6 10 7 10 7	UNL UNL UNL UNL UNL UNL UNL	30 30 60 50 45 30 30	APR 0	7 59 52 61 75 83 80 70 62	43 39 44 55 42 57 47	21 21 23 21 24 22 28 30	23 30 23 13 11 12 21 30	16 00 13 34 26 29 31 21	7	9	UNL UNL UNL 230 UNL UNL UNL	30 30 50 45 40 30	APR	08	55 56 63 77 79 79 69 63	445 485 53 54 48 44	31 32 33 28 27 29 22 19	40	13 12 15 22 21 23 23 23	3 7 18 20 19 13 6	0 2 3 9 7	250 UNL UNL UNL 250 UNL UNL	30 30 50 45 45 30 30	APR 09	60 56 59 76 74 66	45 44 47 50 52 52 49 46	27 31 34 29 27 28 30 30	29 39 23 16 18 26	20 24 13	13 8 4 12 18 18 18 18 6
C2 05 08 11 14 17 20 23	00105200	UNL UNL UNL UNL UNL UNL UNL	30 30 50 50 50 50 40 30 30	APR 1	0 55 51 56 65 67 69 62 57	44 43 47 46 48 47 45 45	30 34 37 24 26 20 25 31	39 52 49 21 21 15 24 37	17 20 33 29 28 30 34 30	5 6 10 16 16 12 7	0000000	UNL UNL UNL UNL UNL UNL UNL UNL	30 30 50 50 50 50 30 30	APR	11	48 46 54 68 75 77 69 61	39 38 43 50 53 52 50 46	28 28 30 32 30 26 30 29	46 50 40 26 19 35 23 30	17 19 13 34 34 31	5 7 5 3 7 12 9 4	8 9 10 10 10 7	UNL UNL UNL UNL UNL UNL UNL UNL	30 30 50 50 50 50 30 30	APR 12	51 51 60 79 84 83 74 63	42 42 47 53 53 52 50 45	30 31 33 27 16 15 20 22	45 47 36 15 8 13 21	13 14 12 17 36 01 33 16	77489765
02 05 08 11 14 17 20 23	7 4 10 10 9 4 2	UNL UNL UNL UNL UNL UNL UNL	30 30 40 50 50 30 30	APR 1	3 54 54 63 82 88 86 74 69	41 46 53 55 54 50 48	24 24 22 19 20 23 24	31 31 23 11 8 9 15 18	14 14 25 33 29 33 30	6 9 11 3 8 11 4 3	3 2 2 1 1 0 0 0	UNL UNL UNL UNL UNL UNL UNL	30 30 50 45 30 30	APR	14	62 53 66 81 86 86 77 67	46 42 48 53 55 54 50 48	27 27 26 24 21 15 14 27	27 37 22 12 9 7 9 22	00 13 12 31 20 24 28 16	0 5 6 13 14 10 3		UNL UNL UNL UNL UNL UNL UNL	30 30 50 50 30 30 30	APR 15	58 53 64 79 88 90 81 72	42 40 46 52 57 58 55 55 52	20 22 23 21 27 28 29 32	23 30 21 11 11 11 15 23	14 13 15 36 01 34 33 26	6 8 9 4 7 10 8 3
02 05 08 11 14 17 20 23	000035	UNL UNL UNL UNL UNL UNL UNL	30 30 40 25 25 25 30 30	APR 1	5 59 73 90 94 81 78	46 52 58 59 57 52 52	31 31 30 28 25 19 18 21	34 35 20 11 8 6 9 12	13 12 14 10 09 12 10 12	6 10 12 16 13 6 7 15	6 6 10 10 10 10	UNL UNL 250 250 250 250	30 30 40 40 40 40 30 30	APR	27	75 72 78 89 94 93 80 77	50) 48 52 56 57 57 51 49	22 19 21 19 17 18 13 11	14 13 12 8 6 8 8	11 11 12 12 12 12 12 10 12	16 16 19 14 10	10 10 10 10 10 10	UNL 250 250 250 150 UNL UNL	30 30 50 35 40 30 30	APR 19	70 65 74 87 95 90 81 72	46 44 50 55 58 57 54 51	12 13 20 21 18 22 26 29	11 13 13 9 6 8 13 20	11 12 16 07 31 33 23 00	5 6 10 3 12 17 4 0

MAXIMUM SHORT DURATION PRECIPITATION

TIME PERIOD (MINUTES)	5	10	15	20	30	45	60	80	100	120	150	180
PRECIPITATION (INCHES)	0.02	0.02	0.02	0.03	0.03	0.03	0.03	0.03	0.03	0.03	0.03	0.03
ENDED: DATE	27	27	27	27	27	27	27	27	27	27	27	27
ENDED: TIME (LST)	1053	1053	1053	1053	1053	1053	1053	1053	1053	1053	1053	1053

THE PRECIPITATION AMOUNTS FOR THE INDICATED TIME INTERVALS MAY OCCUR AT ANY TIME DURING THE MONTH. THE TIME INDICATED IS THE ENDING TIME OF THE INTERVAL. DATE AND TIME ARE NOT ENTERED FOR TRACE AMOUNTS.

_	<u>,</u>			.		0	BS	ER	VF	YT:	10	NS	A	т 3	-H	OU	JR	I	NT	ΈF	۲V	AL	S	APR TUCS	199 SON,	AZ	2316	0			
	5	E E	YTI,		TEMP	ERAT	URE		WI	ND		ы	TLY		Т	EMPI	ÉRAT	URE		WI	ND	(2	E.	ΥT			TEM	PERAT	TURE		WIND
HOUR L.S.T.	SKY COVER (TENTHS)	CEILING IN HUNDEREDS OF FEET	WHOLE MILES 16THS MILE VISIBILITY	WEATHER	AIR °F	WE' BULB 'F	DEW POINT ° F	REL HUMIDITY &	DIRECTION	SPEED (KNOTS)	SKY COVER (TENTHS)	CEILING IN HUNDEREDS OF FEET	WHOLE MILES VISIBILITY	16THS MILE WEATHER		AIR °F	WET BULB °F	DEW POINT 'F	REL HUMIDITY &	DIRECTION	SPEED (KNOTS)	SKY COVER (TENTHS)	CEILING IN HUNDEREDS OF FEET	WHOLE MILES VISIBILITY	16THS MILE	WEATHER	AIR°F	WET BULB °F	DEW POINT & F	REL HUMIDITY &	DIRECTION SPEED (KNOTS)
02 05 08 11 14 17 20 23	1 0 0 3	UNI UNI UNI UNI UNI UNI UNI UNI UNI UNI	30 30 50 40 40 40 30 30	APR 19	67 61 76 90 96 96 84 79	49 47 54 58 60 56 56	29 31 32 29 28 31 35	32 20 11 9 9	16 12 15 10 27 27 27 15	6 7 8 4 9 4 10	3 5 10 10	UNL UNL UNL UNL 80 80 120	30 30 50 50 50 30 30	APR 2		92	52 50 55 61 60 59 57	35 35 38 36 35 42 39 42	29 33 26 14 13 22 21 30	12 16 16 34 20 23 17 13	5 7 4 5 15 10	N 0 0 E	UNL UNL UNL UNL 80 120 UNL	30 30 50 50 50 40 30 30	1	APR 21	69 65 75 88 93 93 79 73	54 55 62 62 62 60 58	42 46 45 42 40 39 45 47	38 50 34 20 16 15 30 40	13.5 139 1510 327 228 2914 129 0000
02 05 08 11 14 17 20 23	00162	UNL UNL UNL UNL 80 UNL UNL UNL	30 30 50 50 50 45 30 30	APR 22	69 63 75 89 92 93 84 77	57 54 60 62 63 61 59 56	47 49 43 42 35 38 39	56 40 20 18 13 20	13 12 15 21 07 26 27 34	8 10 10 6 10 12 5	7 3 6 1 0	UNL 95 UNL 85 UNL UNL UNL	30 30 40 40 40 45 30 30	APR 2		74 87 91 89	53 55 60 64 63 59 59 59	39 44 49 48 44 32 39	42 41 26 20 13	15 12 11 16 23 22 25 23	7 9 10 16 17 15 7	4 0 5	UNL UNL UNL UNL UNL 65 60	30 30 30 30 20 20 25	7	APR 24	65 60 68 78 80 75 64 50	48 47 50 50 52 51 51 45	30 33 32 15 18 26 39 40	27 36 26 9 10 16 40 69	18 6 17 6 20 12 23 16 22 20 25 18 32 11
02 05 08 11 14 17 20 23	0 0 10 10	UNL	30 30 40 40 40 30 30	APR 25	48 45 56 66 75 76 65 59	45 42 46 49 49 45 42	41 39 36 32 16 12 17 17	47 28	17 19 33 25 27 29 23	6 7 5 12 16 7 12	0 4 9 3	UNL UNL UNL 70 UNL UNL 55	30 300 400 30 30	APR 2		51 58 59 72 52	42 39 46 50 52 50 49 47	25 25 29 31 36 25 35 36	33 39 30 25 30 17 37 46	18 15 17 22 24 25 25 25	3 7 14 14 14 20 15 19	0	50 45 UNL 55 55 UNL UNL UNL	30 30 30 30 30 30 30		APR 27 RW	49 48 54 63 67 60 49	47 44 47 52 50 48 45 42	44 39 41 37 26 33	83 74 57 45 38 21 27 54	32 10 31 10 07 3 27 10 15 4 30 10 31 6 14 4
02 05 08 11 14 17 20 23	1 0 0	UNL UNL UNL UNL 90 90	30 30 50 50 50 50 30 30	APR 28	46 44 57 71 78 76 65 61	40 38 45 49 50 49 46 46	33 31 31 22 15 12 24 27	60 37 16	16 12 14 23 25 28 28	6 6 7 1 16 7 1 16 7 8	000000000000000000000000000000000000000	UNL UNL UNL UNL UNL UNL UNL	30 30 50 50 50 50 50 30	APR 2	54 56 77 6	18 59 59 74 75 59	43 42 48 49 52 51 49 48	34 35 37 28 28 25 28 25 28 31	52 61 44 22 18 16 22 30	15 20 29	6 8 6 13 16 8 5	00015	UNL UNL UNL UNL UNL UNL UNL UNL	30 30 50 50 50 30 30	A 	APR 30	54 48 61 78 84 86 77 67	43 39 47 52 54 55 52 49	28 28 31 25 23 21 24 28	37 46 32 14 11 9 14 23	16 6 13 6 13 6 24 5 20 3 31 10 34 12 25 6

WEATHER CODES AND NOTES

*	TORNADO	SW	SNOW SHOWERS	GF	GROUND FOG
Т	THUNDERSTORM	SG	SNOW GRAINS	BD	BLOWING DUST
Q	SQUALL	SP	SNOW PELLETS	BN	BLOWING SAND
R	RAIN	IC	ICE CRYSTALS	<u>8</u> 5	BLOWING SNOW
RW	RAIN SHOWERS	IP	ICE PELLETS	ΞY	BLOWING SPRAY
ZR	FREEZING RAIN	IPW	ICE PELLET SHOWERS	ĸ	SMOKE
L	DRIZZLE	A	HAIL	E	HAZE
ZL	FREEZING DRIZZLE	F	FOG	D	DUST
S	SNOW	IF	ICE FOG		

CEILING: UNL INDICATES UNLIMITED WIND DIRECTION: DIRECTIONS ARE THOSE FROM WHICH THE WIND IS BLOWING, INDICATED IN TENS OF DEGREES FROM TRUE NORTH: I.E. 09 FCR

EAST, 18 FOR SOUTH, 27 FOR WEST. AN ENTRY OF 00 INDICATES CALM. SPEED: THE OBSERVED AVERAGE ONE-MINUTE VALUE (MPH=KNOTS X 1.15).

SUMMARY BY HOURS

			AV.	ERAGE	s				JLTANT
	(SI	e e	TEMP	eratu	RE			w.	IND
HOUR L.S.T.	SKY COVER (TENTHS	STATION PRESSURE (INCHES)	AIR · F	WET BULB °F	DEG POINT 'F	REL NUMIDITY &	SPEED (HPH)	DIRECTION	SPEED (MPH)
02	3	27.310	58	45	30	37	7.5	15	5.8
05	3	27.305	55 64	44 48	30 31	42 31	8.6 9.2	14 15	6.8 7.6
11	3	27.330	78	53	27	17	9.5	24	3.6
14	5	27.270	83	54	25	13	13.3	25	7.4
17	5	27.230	82	54	23	12	15.9	27	11.8
20	4	27.260	73	51	26	19	10.9	28	7.0
23	4	27.300	65	48	29	28	7.9	20	2.7

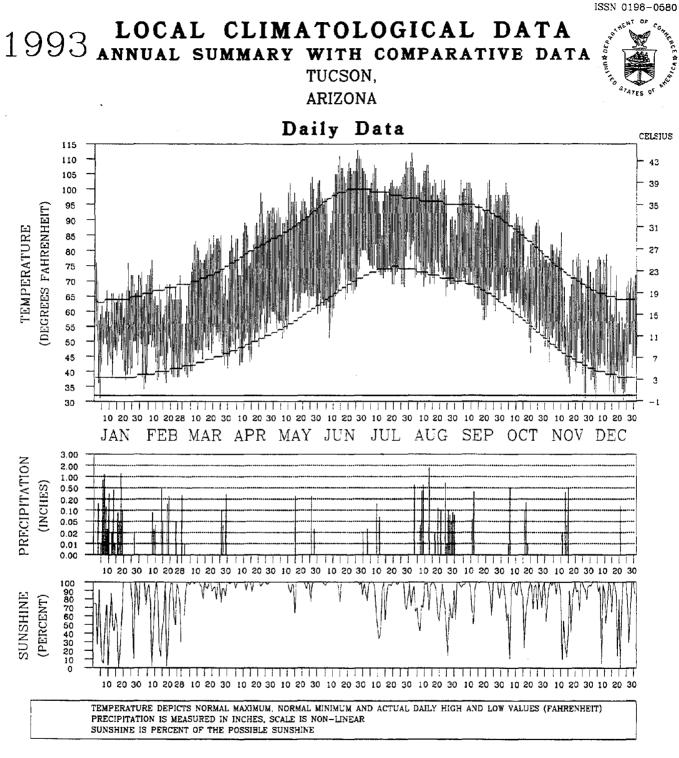
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DATE	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3	4	5	6	7	8	9	10	11	12	
01 02 03 04 05																									01 02 03 04 05
06 07 08 09 10																									06 07 08 09 10
11 12 13 14 15																									11 12 13 14 15
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26 27 28 29 30		т									0.03	т													26 27 28 29 30

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NATIONAL ENVIRONMENTAL SATELLITE, DATA AND INFORMATION SERVICE

NATIONAL CLIMATIC DATA CENTER ASHEVILLE NORTH CAROLINA

11. D Wades DIRECTOR NATIONAL CLIMATEC DATA CENTER

METEOROLOGICAL	DATA	FOR	1993

TUCSON, ARIZONA GITUDE: 110 °56' W ELEVATION: FT. GRND 2584 BARO 2589 TIME ZONE: MOUNTAIN HBAN: 23160 JAN FEB MAR APR MAY JUNEJULY AUG SEP OCT NOV DEC YEAR LATITUDE: 32 °07 · N LONGITUDE: 110°564 W TEMPERATURE OF: Averages -Daily Maximum -Daily Minimum 102.6 67.3 85.0 35.3 101.5 74.4 88.0 53.4 65.5 44.8 55.2 41.9 65.8 42.2 54.0 37.3 76,5 46.1 61.3 38.0 85.8 51.3 68.6 27.7 94.8 61.4 78.1 40.1 98.6 72.4 85.5 62.1 96.4 66.4 81.4 49.7 86.0 59.1 72.6 42.8 72.9 67.3 39.5 53.4 29.3 84.5 55.8 70.2 40.9 -Monthly -Monthly Dewpt. 58.8 33.6 Extremes 76 22 31 77 99 21 42 7 109 31 102 86 10 79 113 85 104 113 112 103 -Highest JUN 26 -Date 25 38 26 51 26 51 7 22 57 11 34 2 68 27 46 20 31 30 23 30 DEC 23 65 24 -Lowest ĩģ -Date 4 3 6 DEGREE DAYS BASE 65 °F: 298 299 129 28 .0 0 0 0 0 5 186 355 1300 Heating 1 0 22 142 413 604 721 641 500 250 11 3 3308 Cooling 67 85 % OF POSSIBLE SUNSHINE 62 94 99 97 98 87 75 94 82 79 80 AVG. SKY COVER (tenths) Sunrise - Sunset Midnight - Midnight NUMBER OF DAYS: 7.9 7.0 5.0 4.3 1.7 4.4 3.8 6.7 4.3 3.4 2.9 2.5 1.3 5.6 5.1 4.2 4.1 4.3 3.9 Sunrise to Sunset -Clear -Partly Cloudy 27 2 1 16 6 9 15 21 8 175 3 6 19 11 23 15 11 iõ 10 93 97 65 82 10 13 6 13 ó -Cloudy 20 15 6 10 10 6 Precipitation .01 inches or more 15 9 4 0 З 1 3 15 2 5 4 1 62 Snow, Ice pellets, hail 1.0 inches or more 0 0 0 0 0 0 0 Û 0 0 0 0 0 Δ 1 19 Thunderstorms 1 2 0 4 4 3 2 0 n 40 Ĵ, Heavy Fog, visibility 1/4 mile or less 0 0 0 0 0 0 Q 0 0 0 0 1 1 Temperature ^oF "Maximum 90° and above 32° and below 0 0 0 9 0 25 27 30 27 9 0 ¢ 153 26 Ō Ő ē Ō 0 Ò Ö Ō Ó Ō Ó ō -Minimum 32° and below 0° and below 7 10 00 0 0 Û 0 0 4 00 00 Û ٥ 00 20 ŏ ŏ ŏ Ö ΰ AVG. STATION PRESS. (mb) 926.9 926.5 927.2 923.5 922.8 921.3 924.1 924.8 924.8 925.8 927.5 928.5 925.3 RELATIVE HUMIDITY (%) 80 62 52 77 Hour 05 Hour 11 77 50 43 17 49 21 31 14 52 28 24 39 71 40 57 31 63 37 31 54 60 41 59 34 74 37 56 32 (Local Time) Hour 17 42 70 26 57 11 28 18 31 10 19 41 20 26 47 30 53 28 48 Hour 23 62 PRECIPITATION (inches): Water Equivalent 0.98 0.57 14-15 4.81 1.46 6- 7 0.49 0.34 29 0.00 0.59 0.29 15 0.02 0.02 30 0.26 0.16 4.93 1.81 13 0.46 0.46 11-12 0.81 0.53 5- 6 0.14 0.14 21 14,99 1,81 1.50 0.49 -Greatest (24 hrs) -Date 14 AUG 13 Snow,Ice pellets,hail -Total 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 T T T 0 0 0 0 -Greatest (24 hrs) 0.0 Õ,Õ 0.0 0.0 õ.õ Õ.Õ 9 AUG 9 -Date WIND: Resultant nesultant
 -Direction (!!)
 -Speed (mph)
Average Speed (mph)
Fastest Mile
 -Direction (!!)
 -Speed (mph)
 -Date 148 4.2 8.5 157 3.5 8.9 159 2.7 210 1.4 8.4 236 2.5 8.8 217 2.2 9.2 239 3.0 9.6 210 4.5 9.5 164 3.4 8.9 156 2.6 8.2 140 2.5 8.1 150 179 2.4 3.1 8.5 SW 29 81 รม 27 4 NW 23 9 S 28 11 S 30 17 S 29 11 SW 25 24 ы 30 SW 25 22 SE 25 27 s s s 25 12 34 34 AUG 19 -Date Peak Gust 26 19 11 S₩ 39 20 S 45 E 60 9 -Direction (!!) -Speed [mph] SE 48 S 43 11 SE 46 27 SE 39 25 SW 37 W 36 NH S 39 W 43 Ε 60 43 AUG -Date 8 23 6 11 30 13

> (!!) See Reference Notes on Page 6B Page 2

NORMALS, MEANS, AND EXTREMES

LATITUDE: 32 °07'N		TUDE: 1	10 957 -	ы г .	EVATION				0500	7765	7015 - 1	OLINITATE	1.1.1	
LATITUDE: 32 07'N	LONGI (a)	1	FEB	MAR	APR	11. 6 MAY	JUNE	JULY	2589 AUG	SEP	ZONE: M OCT	NOV	DEC	BAN: 23160 YEAR
TEMPERATURE °F:												İ	· ·	
Normals ~Daily Maximum	1	63.9	67.8	72.8	81.2	89.9	99.6	99.4	96.8	93.3 67.5	84.3	72.7	64.3	82.2
-Daily Minimum -Monthly		38.6 51.3	41.0 54.4	44.6 58.7	50.4 65.8	58.0 74.0	67.9 83.8	73.6 86.6	72.1 84.5	80.4	56.6 70.4	45.6 59.2	39.8 52.0	54.6 68.4
Extremes -Record Highest	53	87	92	99	104	107	117	114	112	107	102	90	84	117
-Year -Record Lowest	53	1953	1957 20	1988 20	1989 27	1958 38	1990 47	1989 59	1993	1990	1993 26	1988	1954 16	JUN 1990
-Year NORMAL DEGREE DAYS:		1949	1955	1965	1945	1950	1955	1992	1956	1965	1971	1979	1974	DEC 1974
Heating (base 65°F)		425	302	229	97	7	0	0	0	0	27	188	403	1678
Cooling (base 65°F)		0	5	33	121	286	564	670	605	462	194	14	0	2954
OF POSSIBLE SUNSHINE	46	80	82	86	92	93	93	78	80	87	88	85	79	85
IEAN SKY COVER (tenths) Sunrise - Sunset IEAN NUMBER OF DAYS: Sunrise to Sunset	52	4.7	4.6	4.5	3.4	2.8	2.3	5.2	4.6	3.0	2.9	3.5	4.5	3.8
-Clear -Partly Cloudy	53 53 53	13.7 7.1	12.8 6.4	14.7 6.8	17.2 7.3 5.5	20.1 6.8	21.5	10.2 12.2	12.3 12.1	19.3 6.9	19.9 6.4	17.6	14.8	194.0 90.3
-Cloudy Precipitation	1	10.3	9.0	9.4		4.1	6.0 2.5	8.6	6.6	3.8	4.8	6.3	10.1	81.0
.01 inches or more Snow,Ice pellets,hai		4.7	3.8	4.3	2.0	1.5	1.7	10.3	9.5	4.7	3.4	2.9	4.6	53.3
1.0 inches or more	53	0.2	0.2	0.1	0.*	0.0	0.0	0.0	0.0	0.0	0.0	0.*	0.1	0.5
Thunderstorms Heavy Fog Visibility	53	0.4	0.3	0.5	0.7	1.6 0.0	2.5 0.0	13.7 0.0	13.6 0.0	5.4 0.*	2.0 0.0	0.5	0.3	41.4
1/4 mile or less Temperature F -Maximum	23	0.5	0.2	0.*	0.0	0.0	0.0	0.0	0.0	0.*	0.0	0.2	0.4	1.0
90° and above 32° and below	53 53	0.0 0.0	0.* 0.0	0.5 0.0	4.7 0.0	17.7 0.0	28.2 0.0	29.3 0.0	29.6 0.0	23.9 0.0	9.1 0.0	0.* 0.0	0.0 0.0	142.0 0.0
-Minimum 32° and below 0° and below	53 53	6.2 0.0	4.0 0.0	1.1 0.0	0,* 0,0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	G.¥ 0.0	1.5 0.0	5.C 0.0	17.8 0.0
VG. STATION PRESS.(mb)	21	927.8	927.1	925.0	924.0	922.8	922.7	924.7	925.0	924.4	925.7	926.9	927.9	925.3
RELATIVE HUMIDITY (%) Hour 05	53	63	59	54	42	35	32	57	65	55	52	54	62	53
Hour 11 Hour 17 (Local Time	1 22	41 33	35 27	29 23	42 21 16	35 17 13	32 •16 13	32 28 47	38 33	32 26	52 30 25 43	32 28	40 35	53 30 25 43
Hour 23	53	58	50	43	31	24	23	47	53	44	43	48	57	43
RECIPITATION (inches): Water Equivalent -Normal		0.87	0.70	0.72	0.30	0.18	0.20	2.37	2.19	1 7 7	, or	0.67	1.07	12.00
-Maximum Monthly -Year	53	4.81	2.90	2.26	1.66 1951	1,11	1,46 1954	6.17 1981	7.93 1955	1.67 5.11 1964	1.06 4.98 1983	1,90	5.02	12.00 7.93 AUG 1955
-Minimum Monthly -Year	53	T 1970	0.00	0.00	0.00	0.00 1974	0.00 1983	0.26 1993	0.23	0.00	0.00	0.00	0.00	0.00 JUN 1983
-Maximum in 24 hrs -Year	53	1.46 1993	1.49 1942	1.19 1952	0.91 1988	0.89 1943	1_27 1954	3.93 1958	2.48 1961	3.05	3.58 1983	1.86 1968	1.54 1967	3.93 JUL 1958
Snow,Ice pellets,hail		4 -				-				~	_			
-Maximum Monthly -Year	53 60	4.7 1987	3,9 1965	5.7 1964	2.0 1976	1992	0.0	0.0	1993	1990 T	T 1991	6.4 1958	6.8 1971	6.8 DEC 1971
-Maximum in 24 hrs -Year	52	4.3 1987	3,9 1965	5.7 1964	2.0 1976	1992	0.0	0.0	1993	1990	T 1991	6.4 1958	6.8 1971	6.8 DEC 1971
IND: Mean Speed (mph)	48	7.9	8.1	8.5	8.9	8.8	8.7	8.4	7.9	8.3	8.2	8.1	7.8	8.3
Prevailing Direction through 1963		SE	SE	SE	SE	SE	SSE	SE	SE	SE	SE	SE	SE	SE
Fastest Mile ~Direction [!!]	45	E	Ē	SE	SW	SE	SE	SE	NE	SE	SE 47	ε	W	SE 71
-Speed (MPH) -Year Pack Guat	45	40 1962	59 1952	41 1955	46 1986	43 1984	50 1961	71 1971	54 1969	54 1960	47 1948	55 1 95 1	44 1949	71 JUL 1971
Peak Gust -Direction [!!] -Speed (mph)	10 10	SH 45	Е 46	SE 53	SH 55	SE 55	SW 47	5E 66	SE 71	SE 71	NW 47	Е 46	SE 47	SE 71
-Date	'`	1988	1987	1986	1984	1984	1991	1985	1988	1990	1988	1990	1988	SEP 1990

(!!) See Reference Notes on Page 6B. Page 3

PRECIPITATION (inches)

TUCSON, ARIZONA

YEAR	JAN	FEB	MAR	APR	MAY	JUNE	JULY		SEP	OCT	NOV	DEC	ANNUAL
1964	0.14	0.13	0.81	0.67	0.00	0.01	4.82	3.90	5,11	0.91	0,68	0.81	17.99
1965	0.45	0.64	0.27	0.23	T	0.01	2.13	1.12	0,82	0.07	0,77	5.02	11.53
1966	1.74	2.25	0.19	0.12	0.11	0.02	2.57	3.31	3,53	0.32	0,05	0.19	14.41
1967	0.04	0.13	0.41	0.29	0.62	0.42	2.72	2.00	1,35	1.03	0,48	3.44	12.93
1968	0.18	0.99	1.79	0.62	T	0.00	1.97	1.12	T	0.09	1,86	0.32	8.94
1969	0.74	0.50	0.34	0.60	0.46	0.00	1.51	2,57	1,31	0.03	1.06	0.82	9,94
1970	T	0.34	1.13	0.45	0.03	0.33	2.53	1,43	3,58	1.73	0.00	0.43	11,98
1971	0.04	0.50	T	0.56	0.01	T	2.18	3,29	1,75	1.18	0.69	1.97	12,17
1972	0.00	0.00	0.01	0.00	0.24	0.68	3.49	2,93	1,09	4.51	1.30	0.61	14,86
1973	0.06	1.60	2.20	0.02	0.09	0.50	1.74	0,54	T	0.00	0.47	0.00	7,22
1974	0.93	T	0.55	T	0.00	0.01	4.44	1.04	1,69	2.12	0.81	0.33	11.92
1975	0.36	0.13	0.95	0.27	0.11	0.00	2.38	0.32	1,26	T	0.34	0.52	6.64
1976	0.06	0.53	0.38	0.57	0.23	0.10	1.18	0.23	1,68	0.37	0.48	0.47	6.28
1977	1.83	0.04	0.74	0.43	0.08	0.06	0.76	0.80	1,41	2.36	0.33	1.33	10.17
1978	2.05	1.75	0.89	0.01	0.61	0.22	0.79	1.59	1,66	1.86	1.58	2.73	15.73
1979	2.94	0.42	0.64	0.04	0.67	0.53	2.04	2.60	0.02	0.33	0.01	0.15	10.39
1980	0.73	2.90	1.22	0.08	T	0.23	1.78	1.95	2.93	0.22	0.00	0.19	12.23
1981	1.29	0.71	1.98	0.56	0.26	0.16	6.17	0.80	1.10	0.05	0.61	0.00	13.70
1982	1.55	0.06	1.26	0.05	0.51	0.13	2.13	2.51	2.69	0.00	1.30	1.59	13.79
1983	1.70	0.94	1.28	0.14	T	0.00	1.99	4.24	4.28	4.98	1.71	0.61	21.86
1984	0.62	0.00	0.00	0.36	0.06	1.05	2.92	4.19	1.81	0.77	0.45	3.30	15.53
1985	1.71	1.08	0.20	0.45	T	0.07	3.14	1.97	1.13	2.03	0.95	0.15	12.88
1986	0.93	1.13	1.30	T	0.44	0.06	1.82	3.56	0.31	0.50	0.42	1.28	11.80
1987	0.59	1.64	0.83	0.80	0.74	0.16	0.37	2.79	2.30	0.34	0.44	1.50	12.50
1988	0.41	0.53	0.35	1.15	0.02	0.15	1.69	3.64	0.60	2.09	0.75	0.05	11.63
1989	0.96	0.23	0.62	0.00	0.13	0.06	1.42	0.90	0.02	1.84	0.12	0.18	6.48
1990	0.96	0.71	0.38	0.10	0.03	0.64	5.45	2.70	1.63	0.58	0.23	1.54	14.95
1991	1.15	0.91	1.40	0.00	0.00	0.20	0.44	2.17	1.54	0.73	0.80	1.44	10.78
1992	1.21	1.80	2.12	0.19	1.11	0.07	0.93	4.55	0.94	0.03	T	3.47	16.42
1993	4.81	1.50	0.49	0.00	0.59	0.02	0.25	4.93	0.46	0.81	0.98	0.14	14.99
Record Mean	0.90	0.83	0.74	0.34 Se	0.21 e Refer	0.25 ence No Pagi	2.20 tes on ≥ 4A	2.22 Page 6B	1.31	0.72	0.74	1.03	11.49

AVERAGE TEMPERATURE (deg. F)

TUCSON, ARIZONA

YEAR	JAN	FEB	MAR	APR	MAY	JUNE	JULY	AUG	SEP.	OCT	NOV	DEC	ANNUAL
1964 1965 1966 1967 1968	47.5 53.6 47.7 51.4 52.4	47.7 51.1 47.8 55.6 59.1	54.8 55.1 60.1 62.1 58.7	63.2 64.5 66.8 62.1 63.2	73.2 70.1 76.1 71.9 73.3	82.0 77.6 82.8 80.7 83.5	86.2 85.3 85.3 85.4 84.9	81.6 84.0 82.9 84,6 81.3	76.3 76.8 78.3 80.7 80.7	72.1 71.9 68.1 71,6 71.7	55.2 61.9 58.3	52.4 52.1 52.4 52.6 50.6	65.0 67.1 67.4 68.1 68.1
1969	55.5	53.1	54.3	66.6	74.9	80.7	86.1	86.3	81.2	66.8	58,6	52.4	58.0
1970	50.5	57.0	55.9	61.1	75.2	83.4	87.2	84.8	76.4	65.1	60,1	51.8	57.3
1971	50.5	52.3	59.8	62.8	69.3	81.2	87.5	81.3	79.1	64.2	56,8	47.1	55.0
1972	50.4	55.8	65.0	65.8	72.3	81.6	86.6	82.9	78.6	66.5	53,0	49.0	57.3
1973	47.6	53.4	51.6	59.7	73.0	81.4	84.3	84.7	79.6	70.7	58,4	52.3	55.4
1974	50.2	51.9	60.1	66.1	74.3	86.9	83,5	83.0	77.8	69.1	57,5	47.0	67.3
1975	49.8	50.7	55.3	57.9	69.8	80.5	84,2	85.8	80.0	69.5	59,3	53.0	55.3
1976	52.6	58.4	58.2	64.8	74.5	83.4	83,9	85.3	77.7	67.8	60,0	52.2	58.3
1977	50.7	56.9	55.7	67.0	70.8	84.7	87,0	86.4	82.0	73.3	61,7	56.9	69.4
1978	53.1	53.6	61.8	65.2	73.1	85.8	88,1	84.7	80.9	73.8	58,5	49.7	59.0
1979	48.4	53.8	56.4	65.6	72.2	83.1	87.5	83.4	84.2	73,0	56,6	55.0	68.3
1980	54.3	57.9	57.5	65.6	71.5	84.9	88.6	84.5	80.5	69.6	59,5	58.1	69.4
1981	54.8	57.1	57.1	69.1	73.4	86.1	85.2	86.4	80.7	68.1	62,2	55.0	69.6
1982	50.7	54.7	57.7	66.1	72.3	80.5	84.8	83.9	79.2	67.0	57,7	50.1	57.0
1983	52.9	53.8	57.3	60.4	73.8	81.6	86.9	84.0	82.2	69.5	57,4	53.5	67.8
1984	51.8	53.7	60.5	64.0	79.9	83.1	84.2	82.9	81.5	66.3	57.8	51.5	58.1
1985	50.3	53.1	58.7	68.7	75.9	85.8	87.5	86.1	77.4	70.0	58.0	52.9	68.7
1986	58.7	56.9	63.8	69.0	76.8	85.6	85.5	85.1	79.0	69.6	59.8	52.3	70.3
1987	50.9	54.2	57.9	70.1	74.3	86.3	87.4	85.1	79.9	75.1	58.9	50.3	59.2
1988	53.0	59.4	61.4	68.0	76.4	86.3	87.9	85.9	80.4	75.3	59.2	51.9	70.5
1989	49.9	58.2	65.0	73.8	77.4	85.4	90.0	85.6	84.5	71.1	61.7	53.0	71.4
1990	51.8	52.8	61.8	69.7	75.2	88.7	85.0	82.6	82.2	73.1	61.6	51.1	69.6
1991	52.3	59.8	55.4	65.2	73.5	81.5	87.5	86.6	80.7	74.0	58.9	54.3	69.1
1992	51.6	57.3	59.4	70.8	76.7	84.5	86.8	85.1	83.6	74.2	56.1	51.4	69.8
1993	55.2	54.0	61.3	68.6	78.1	85.0	88.0	85.5	81.4	72.6	58.8	53.4	70.2
Record Mean Max Min	50.6 64.4 36.8	53.6 67.8 39.3	58.0 73.0 43.0	64.9 81.1 48.8 Se	73.0 89.7 56.3 e Refer	82.4 99.1 65.7	86.1 99.3 72.9	84.1 96.8 71.4 Page 68	80.1 94.1 66.1	69.7 84.9 54.5	58.3 73.1 43.5	51.5 65.3 37.7	67.7 82.4 53.0
				•••		Page	∋ 4B		•				

HEATING DEGREE DAYS Base 65 deg. F TUCSON, ARIZONA

SEASON	JULY	AUG	SEP	OCT	NOV	DEC	JAN	FEB	MAR	APR	MAY	JUNE	TOTAL
1964-65 1965-66 1966-67 1967-68 1968-69	00000	00000	00000	5 30 14 4	293 110 126 89 204	383 396 386 502 440	348 532 416 384 288	383 473 256 170 328	305 166 115 200 339	114 26 113 91 34	21 20 20 35	00000	1852 1744 1452 1450 1672
1969-70 1970-71 1971-72 1972-73 1973-74	00000	00000	00000	55 58 120 96 23	188 143 249 358 216	384 403 548 489 390	455 445 444 533 451	224 350 259 320 362	274 200 73 410 161	132 111 50 174 49	8 10 19 บ	00000	1720 1722 1743 2399 1657
1974-75 1975-76 1976-77 1977-78 1978-79	00000	00000	00000	53 38 45 1 15	218 191 178 117 213	552 365 390 242 470	465 378 435 365 511	393 180 221 313 311	299 221 287 144 260	217 88 65 64 76	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	00000	2226 1466 1630 1270 1876
1979-80 1980-81 1981-82 1982-83 1983-84	00000	00000	00000	26 66 34 41 0	252 197 106 211 232	302 210 304 456 348	323 310 437 371 402	202 220 291 309 323	227 244 223 239 140	84 31 46 168 110	300 1060	00000	1419 1278 1451 1801 1555
1984-85 1985-86 1986-87 1987-88 1987-88	00000	00000	00000	49 9 11 0 0	221 217 154 188 220	413 369 387 452 402	448 1999 426 3661	328 244 299 171 199	200 117 225 161 82	4 1 224 4 9	0 6 12 4	00000	1700 1177 1529 1396 1377
1989-90 1990-91 1991-92 1992-93 1993-94	00000	00000	00000	2 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5	107 152 195 261 186	361 427 325 418 355	402 384 408 298	340 140 215 299	156 296 169 129	16 47 24 28	3300 0	0000	1410 1454 1392 1433

See Reference Notes on Page 68. Page 5A

COOLING DEGREE DAYS Base 65 deg. F TUCSON, ARIZONA

YEAR	JAN	FEB	MAR	APR	MAY	JUNE	JULY	AUG	SEP	ост	NOV	DEC	TOTAL
1969 1970	00	05	15	87 25	348	477	658 693	669	49 3 347	118 68	1	00	2866 2656
1971 1972 1973	0000	010	452 820	51 82 21	152 236 272	493 506 495	706 678 603	514 563 615	430 414 445	101 150 206	12 1 26	NOO	2510 2713 2685
1974 1975 1976 1977 1978	00000	00000	18 4 14 54	87 11 89 133 76	301 184 306 198 283	564 471 557 597 630	581 604 597 691 721	564 656 639 665 616	387 458 386 517 483	185 182 139 266 293	1 27 333 28 28	00000	2788 2592 2760 3099 3184
1979 1980 1981 1982 1983	00000	0 4 8 4 0	1 1 4 4 8	101 109 159 36	249 211 267 244 288	551 606 639 471 503	706 742 633 622 688	576 615 670 594 600	580 474 476 437 523	282 216 137 112 145	67 27 20 10	00000	3052 3018 3022 2570 2801
1984 1985 1986 1987 1988	NONOO	0 1 3 0 1 3 1 3	6 7 82 12 58	87 159 150 184 142	469 345 378 297 374	549 633 653 644 658	601 704 643 702 716	562 660 657 630 657	503 379 431 452 471	96 173 158 325 327	124 32 51	00001	2885 3075 3186 3260 3470
1989 1990 1991 1992 1993	00001	16 6 1 0 0	8 6 6 4 2 2	281 164 504 142	397 327 274 372 413	619 719 501 590 604	780 625 703 683 721	676 553 675 627 641	592 522 479 560	221 260 341 250	16 56 21 1	00003	3687 3297 3063 3335 3308

See Reference Notes on Page 68. Page 58

SNOWFALL (inches)

TUCSON, ARIZONA

SEASON	JULY	AUG	SEP	OCT	NOV	DEC	JAN	FEB	MAR	APR	MAY	JUNE	TOTAL
1964-65 1965-66 1966-67 1967-68 1968-69	0.0 0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0,0 0,0 0,0 0,0	0.0 0.0 0.0 0.0	0.1 0.0 0.0 0.0 0.0	0.0 0.3 T 1.6 0.4	0.0 T 0.0 0.0 0.0	3,9 1,2 0,0 0,0	0.0 0.0 0.0 0.0 T	0.0 0.0 T 0.0 0.0	0.0 0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0	4.0 1.5 T 1.6 0.4
1969-70 1970-71 1971-72 1972-73 1973-74	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0		0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	T 0.0 6.8 0.0	0.0 1 0.0 T 0.4	0.0 T 0.0 0.0	T 0.0 0.0 0.0 T	T 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0	T 5.8 T 0.4
1974-75 1975-76 1976-77 1977-78 1978-79	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 T 0.0 0.0		0.0 0.0 0.0 0.0 1.2	T 0.0 0.0 0.0	0.5	0.0 2.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0	0.5 5.8 0.0 0.0 1.2
19 79- 80 1980-81 1981-82 1982-83 1983-84	0.0 0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 T 0.0	0.0 0.0 T 0.0 0.0	0,0 0,0 0,0 0,0	T T 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0	
:984-85 1985-86 1986-87 1987-88 1988-89	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0	0,0 0,0 0,0 0,0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	T 0.0 3.6 T	0.0 0.0 4.7 0.0 0.0	2.2 0.0 0.0 T	0.0 0.0 T 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0	0.0 0.0 0.0 0.0 0.0	2.2 T 4.7 3.6 T
1989-90 1990-91 1991-92 1992-93 1993-94	0.0 0.0 0.0 0.0	0.0 T 0.0 T	0.0 J 0.0 0.0 0.0	0.0 0.0 T 0.0	0.0 0.0 0.0 0.0	0.0 0.6 T 0.0 0.0	2.7 0.0 0.0 0.0	0.0 0.0 5 ¹ 3	0.0 0.3 T 0.0	T 0.0 0.0 0.0	0.0 0.0 T 0.0	0.0 0.0 0.0 0.0	5.0 0.9 T T
Record Mean	0,0	т	Т	T See	0.1 Refere	0.3 nce Not Page	0.3 es on P 6A	0.2 age 6B.	0.3	0.1	Т	0.0	1.3

REFERENCE NOTES

TUCSON, ARIZONA

EXCEPTIONS

E	1	A	N N	T K D	R	Ē	N A	T T	R	I S	£	SA		D 5	Ē	N A	T	1	01	Ņ		Q) 3	2	1	Ν	s	ĩ	R	U	М	Ε	0 I N G I	F	Ę	? E	L	DO	A C	ī A	Â	i	0	N	•				
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÷		a IO X II E	X RTN SL	M R D U D			I SEJ AA	N* SR NL	ם ז	I	V D S	I BDNF1	DHAAURRI	UESTHOEN	A EEEMCD	LYDSR T1	A A T I C	M L O A L R O A			() 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1		EWRET	H B I R	AE9HTHGE	YISOE IM		BETSE	EE1 - NV	N9R00 A	H 9EFOTL	10000 - 00					DRCSCE1	DCSA C	0 U T D H	PRCEE	ERLSS	R C R	N C C E	C K A E	ÊKLS	1 M	•		
Ρ	RRPRRA	EEREMENV	CECACAE	OCCOXOXR	A A A A A A	D DPDMDAG	I I N E	MTMNKD	EAAIE T	ATX ARE	Ñ] (TNEM	OME CP	PNIMTOE		ĒA)EMDA	CH RP T	1 OTAEMU							RUU1DH		N E I D	6 N T S	I G H B U	T S EYM	H T	ĒTHS20	H E U F	P E			0 A 1	D N D T	D H	D D E	F F O	FR	R	E L R C	Ē	C R	Ōi D	D A		r

PAGES 4A, 4B, 6A RECORD MEANS ARE THROUGH THE CURRENT YEAR, BEGINNING IN 1900 FOR TEMPERATURE 1900 FOR PRECIPITATION 1941 FOR SNOWFALL

Page 68

Tucson lies at the foot of the Catalina Mountains, north of the airport. The area within about 15 miles of the airport station is flat or gently rolling, with many dry washes. The soil is sandy, and vegetation is mostly brush, cacti, and small trees. Rugged mountains encircle the valley. The mountains to the north, east, and south rise to over 5,000 feet above the airport. The western hills and mountains range from 500 to 4,000 feet.

The climate of Tucson is characterized by a long hot season, from April to October. Temperatures above 90 degrees prevail from May through September. Temperatures of 100 degrees or higher average 41 days annually, including 14 days each for June and July, but these extreme temperatures are moderated by low relative humidities. The temperature range is large, averaging 30 degrees or more a day.

More than 50 percent of the annual precipitation falls between July 1 and September 15. and over 20 percent falls from December through March. During the summer, scattered convective or orographic showers and thunderstorms often fill dry washes to overflowing. On occasion, brief, torrential downpours cause destructive flash floods in the Tucson area. Hail rarely occurs in thunderstorms. The December through March precipitation occurs as prolonged rainstorms that replenish the ground water. During these storms, snow often falls on the higher mountains, but snow in Tucson is infrequent, particularly in accumulations exceeding an inch in depth.

From the first of the year, the humidity decreases steadily until the summer thunderstorm season, when it shows a marked increase. From mid-September, the end of the thunderstorm season, the humidity decreases again until late November. Occasionally during the summer, humidities are high enough to produce discomfort, but only for short periods. During the hot season, humidity values sometimes fall below 5 percent. Tucson lies in the zone receiving more sunshine than any other section of the United States. Cloudless days are commonplace, and average cloudiness is low.

Surface winds are generally light, with no major seasonal changes in velocity or direction. Occasional duststorms occur in areas where the ground has been disturbed. During the spring, winds may briefly be strong enough to cause some damage to trees and buildings. Wind velocities and directions are influenced by the surrounding mountains, and the general slope of the terrain. Usually local winds tend to be in the southeast quadrant during the night and early morning hours, veering to northwest during the day. Highest velocities usually occur with winds from the southwest and east to south.

While dust and haze are frequently visible, their effect on the general clarity of the atmosphere is not great. Visibility is normally high.

Based on the 1951-1980 period, the average first occurrence of 32 degrees Fahrenheit in the fall is November 29 and the average last occurrence in the spring is February 28.

Notice of Correction

Any previously received edition of the "Local Climatological Data Annual Summary for 1993" should be discarded. This revised edition contains updates to the "Normals" based upon the 1961-1990 record period as noted in the "Reference Notes" on Page 6B.

APPENDIX K.

FORTRAN DATA ANALYSIS PROGRAMS

Listings of the FORTRAN programs used to analyze the detector output data are given in this appendix. The programs, described in Section 10.4, are:

- COUNT.FOR
- INT_CNT.FOR
- DENSITY.FOR

• OVF.FOR

- DENS_TOD.FOR
- DENS 232.FOR
- GP_COUNT.FOR
- OCC.FOR
- SVF.FOR

END

```
THIS PROGRAM OUTPUTS VEHICLE COUNTS VS.
^{\star}
                                             *
C*
     TIME OF DAY
С
        INTEGER TIME
С
        DIMENSION TIME(15000,4), DECTIME(15000)
С
        CALL OPEN
С
C****INITIALIZE COUNTER TO DETERMINE # OF ROWS****
С
        KOUNT=0
C
C****READ IN ARRAY VALUES FROM THE PARADOX DATA****
С
  100
        KOUNT=KOUNT+1
        READ(1, \star, END=999) (TIME(KOUNT, J), J=1, 4)
        GO TO 100
С
  999
       KOUNT=KOUNT-1
С
C****COMPUTE DECIMAL TIME FROM THE FOUR TIME FIELDS****
С
       DO 150 I=1, KOUNT
         DECTIME (I) = TIME(I, 1) + (TIME(I, 2)/60.) + (TIME(I, 3)/3600.)
                   +(TIME(I,4)/3600000.)
     &
          WRITE(2,10) DECTIME(I), I
       CONTINUE
  150
С
       FORMAT(1X, F7.4, 2X, 15)
  10
С
       STOP
       END
       SUBROUTINE OPEN
       CHARACTER*11 FNO
       CHARACTER*11 FNI
       CHARACTER FILENAME(8)
       WRITE(6,*) 'ENTER THE 8 DIGIT NUMERICAL FILENAME: '
       READ(5,225) (FILENAME(J), J=1,8)
 225
       FORMAT(8A1)
       FNI=FILENAME(1)//FILENAME(2)//FILENAME(3)//FILENAME(4)//
    &
         FILENAME(5)//FILENAME(6)//FILENAME(7)//FILENAME(8)//'.CI'
       FNO=FILENAME(1)//FILENAME(2)//FILENAME(3)//FILENAME(4)//
         FILENAME(5)//FILENAME(6)//FILENAME(7)//FILENAME(8)//'.CO'
    &
       WRITE(6,230) FNI
       WRITE(6,230) FNO
 230
       FORMAT(1X, 20A)
       OPEN(1, FILE=FNI, STATUS='OLD')
       OPEN(2, FILE=FNO, STATUS='OLD')
       RETURN
```

K.-2

K.2 INT_CNT.FOR

```
C******
             C*
     THIS PROGRAM COMPUTES VEHICLE COUNT ACCURACIES AND
C*
     STATISTICAL MEASURES OF EFFECTIVENESS OVER A
C*
     USER-DEFINED INTEGRATION INTERVAL
С
        INTEGER TIME1, TIME2, SUM1, SUM2, DIFF, DIFSUM, SOSUM
С
        REAL OLD, NEW, MEAN
С
        DIMENSION TIME1(7000,4), DECTIME1(7000), TIME2(7000,4),
                  DECTIME2(7000), SUM1(500), SUM2(500), DIFF(500),
     &
     &
                  PDIFF(500), SAMTIM(500)
С
        CALL OPEN
С
C*
  ***INITIALIZE COUNTER TO DETERMINE # OF ROWS****
С
        KOUNT1=0
        KOUNT2=0
С
C****READ IN ARRAY VALUES FROM THE PARADOX DATA****
С
  100
        KOUNT1=KOUNT1+1
        READ(1,*,END=999) (TIME1(KOUNT1,J),J=1,4)
        GO TO 100
С
  999
        KOUNT1=KOUNT1-1
C
        KOUNT2=KOUNT2+1
  110
        READ (3, *, END=998) (TIME2 (KOUNT2, J), J=1, 4)
        GO TO 110
C
  998
        KOUNT2 = KOUNT2 - 1
C
C****COMPUTE DECIMAL TIME FROM THE FOUR TIME FIELDS****
С
        DO 150 I=1,KOUNT1
          DECTIME1(I)=TIME1(I,1)+(TIME1(I,2)/60.)+(TIME1(I,3)/3600.)
                   +(TIME1(I,4)/3600000.)
     &
С
          WRITE(2,10) DECTIME(I), I
  150
        CONTINUE
С
        DO 160 I=1, KOUNT2
         DECTIME2(I)=TIME2(I,1)+(TIME2(I,2)/60.)+(TIME2(I,3)/3600.)
                   +(TIME2(I,4)/360000.)
     &
  160
        CONTINUE
С
        WRITE(6,*) 'ENTER THE DESIRED COUNT ACCUMULATION TIME (MINS):
       READ(5,*) TINT
       HSTART=FLOAT((TIME1(1,1)))+((TIME1(1,2)+1)/60.)
       HEND=FLOAT((TIME1(KOUNT1,1)))+(TIME1(KOUNT1,2)/60.)
       DELMIN=(HEND-HSTART) *60.
       NINT=INT (DELMIN/TINT)
       OLD=HSTART
       NEW=HSTART+TINT/60.
С
       J=1
       DO 50 I=1,500
```

```
50
         CONTINUE
         DO 51 I=1,500
           SUM2(I)=0
  51
         CONTINUE
С
         DO 200 I=1,KOUNT1
           IF (DECTIME1(I).GE.NEW) THEN
             J = J + 1
             IF(J.GT.NINT) GO TO 200
             OLD=NEW
             NEW=NEW+TINT/60.
             IF((DECTIME1(I).GE.OLD).AND.(DECTIME1(I).LT.NEW)) THEN
               SUM1(J) = SUM1(J) + 1
             ENDIF
           ELSE
             IF ( (DECTIME1 (I).GE.OLD). AND. (DECTIME1 (I).LT.NEW) ) THEN
               SUM1(J) = SUM1(J) + 1
             ENDIF
           ENDIF
  200
        CONTINUE
С
         J = 1
        OLD=HSTART
        NEW=HSTART+TINT/60.
С
        DO 210 I=1,KOUNT2
           IF (DECTIME2(I).GE.NEW) THEN
             J=J+1
             IF(J.GT.NINT) GO TO 210
             OLD=NEW
             NEW=NEW+TINT/60.
             IF ((DECTIME2(I).GE.OLD).AND. (DECTIME2(I).LT.NEW)) THEN
               SUM2(J) = SUM2(J) + 1
             ENDIF
           ELSE
             IF ((DECTIME2(I).GE.OLD).AND. (DECTIME2(I).LT.NEW)) THEN
               SUM2(J) = SUM2(J) + 1
             ENDIF
           ENDIF
        CONTINUE
  210
С
        SOSUM=0
        DIFSUM=0
        DO 300 I=1,NINT
           SAMTIM(I) = HSTART + (I-1) * TINT / 60.
          DIFF(I) = SUM2(I) - SUM1(I)
           PDIFF(I) = (FLOAT(DIFF(I))/FLOAT(SUM1(I))) * 100.
          DIFSUM=DIFSUM+DIFF(I)
           SQSUM=SQSUM+(DIFF(I))**2
           PDSUM=PDSUM+PDIFF(I)
           SQPD=SQPD+(PDIFF(I))**2
  300
        CONTINUE
С
        XDIFSM=DIFSUM*1.0
        XINT=NINT*1.0
        MEAN=XDIFSM/XINT
        STDDEV=SQRT(FLOAT((NINT*SQSUM-DIFSUM**2)/(NINT*(NINT-1))))
        SIGMA=SQRT((NINT*SQPD-PDSUM**2)/(NINT*(NINT-1)))
```

SUM1(T)=0

WRITE(2,*) 'ACCUMULATION INTERVAL TIME: '.TINT.' MINS' WRITE(2,*) 'MEAN DIFFERENCE= ', MEAN WRITE(2,*) 'STANDARD DEVIATION OF THE DIFF VALUES= ', STDDEV WRITE(2,*) 'STANDARD DEVIATION OF THE % DIFF VALUES= ', SIGMA WRITE(2, 5)WRITE(6,*) 'ACCUMULATION INTERVAL TIME: ',TINT,' MINS' WRITE(6,*) 'MEAN DIFFERENCE= ', MEAN WRITE(6,*) 'STANDARD DEVIATION OF THE DIFF VALUES= ', STDDEV WRITE(6,*) 'STANDARD DEVIATION OF THE % DIFF VALUES= '.SIGMA WRITE(6, *)WRITE(6.5)5 FORMAT(1X,2X,'INT',4X,'TIME',3X,'SUM1',1X,'SUM2',1X,'DIFF',1X, & '%DIFF') C DO 400 I=1,NINT WRITE(2,10) I, SAMTIM(I), SUM1(I), SUM2(I), DIFF(I), PDIFF(I) WRITE(6,10) I, SAMTIM(I), SUM1(I), SUM2(I), DIFF(I), PDIFF(I) 400 CONTINUE 10 FORMAT(1X, 14, 2X, F8.4, 2X, 2(13, 2X), 13, 2X, F5.1) C STOP END SUBROUTINE OPEN CHARACTER*11 FNO CHARACTER*11 FNI CHARACTER*12 FNL CHARACTER FILENAME(8) WRITE(6,*) 'ENTER THE 8 DIGIT NUMERICAL FILENAME: ' READ(5,225) (FILENAME(J), J=1,8) 225 FORMAT(8A1) FNI=FILENAME(1)//FILENAME(2)//FILENAME(3)//FILENAME(4)// FILENAME(5)//FILENAME(6)//FILENAME(7)//FILENAME(8)//'.CI' æ FNO=FILENAME(1)//FILENAME(2)//FILENAME(3)//FILENAME(4)// FILENAME(5)//FILENAME(6)//FILENAME(7)//FILENAME(8)//'.CO' Se FNL=FILENAME(1)//FILENAME(2)//FILENAME(3)//FILENAME(4)// FILENAME(5)//FILENAME(6)//FILENAME(7)//FILENAME(8)//'.ILI' & WRITE(6,230) FNI WRITE(6,230) FNO WRITE(6,230) FNL 230 FORMAT(1X,20A) OPEN(1, FILE=FNL, STATUS='OLD') OPEN(2, FILE=FNO, STATUS='OLD') OPEN(3, FILE=FNI, STATUS='OLD') RETURN

END

K.3 DENSITY.FOR

```
C^{*}
     THIS PROGRAM COMPUTES DENSITY, SPEED,
C* AND FLOW FOR A USER-DEFINED TIME INTERVAL *
C*****
       С
        INTEGER DETINT1, DETINT2
С
       REAL*8 TIME, FACTOR, TEMP, TIME1, TIME2, DELTAT, NEWTIME,
         HOUR1, HOUR2, TMIC1, TMIC2, CONST
     &
С
       DIMENSION SAMPLE(2000), DENS(2000), FLOW(2000),
         ICOUNT(2000), SPDSUM(2000), AVESPD(2000), TAG(2000)
     &
C
       CALL OPEN
C
C****INITIALIZE COUNTERS****
С
       KOUNT=0
       NCYCLE=0
       FACTOR=4.294967295E9
С
C****READ IN ARRAY VALUES AND COMPUTE TIMES FROM SPEED TRAP TIME TAGS***
С
       READ(1,*) THOUR, TMIN, TSEC, THSEC, INTNUM1, SPDTRP1
       TIME=SPDTRP1
       TIMTAG=THOUR+TMIN/60.
       WRITE(3) INTNUM1, TIME
       HOUR1=THOUR+TMIN/60.+TSEC/3600.+THSEC/3600000.
       TMIC1=TIME
  100
       KOUNT=KOUNT+1
       READ(1, *, END=999) THOUR, TMIN, TSEC, THSEC, INTNUM2, SPDTRP2
       IF (SPDTRP2.LT.SPDTRP1) NCYCLE=NCYCLE+1
       TIME=SPDTRP2+NCYCLE*FACTOR
       WRITE(3) INTNUM2, TIME
       INTNUM1=INTNUM2
       SPDTRP1=SPDTRP2
       GO TO 100
 999
       KOUNT=KOUNT-1
       HOUR2=THOUR+TMIN/60.+TSEC/3600.+THSEC/3600000.
       TMIC2=TTME
       CONST=(HOUR2-HOUR1)*3.6E9/(TMIC2-TMIC1)
       WRITE(6, *) 'CONSTANT = ', CONST
C
C****SOLICIT INPUT FOR DESIRED OCCUPANCY TIME INTERVAL****
С
       WRITE(6, *)
       WRITE(6,10)
       READ(5, *) SPACE
       WRITE(6,*)
       WRITE(6,15)
 10
       FORMAT(1X, 'ENTER THE SPACING BETWEEN DETECTION ZONES (FT) ')
       FORMAT(1x, 'ENTER THE DESIRED INTEGRATION TIME INTERVAL (MINS) ')
 15
       READ(5,*) DELTAM
       WRITE(6,16) DELTAM
 16
       FORMAT(1X, 'DELTA M = ', F6.3, 1X, 'MINUTES')
       HDELT=DELTAM/60.
       WRITE(6, \star)
       WRITE(6,*) 'ENTER THE DETECTOR INTERFACE # FOR ZONE 1 '
       READ(5,*) DETINT1
       WRITE(6, *)
```

```
WRITE(6,*) 'ENTER THE DETECTOR INTERFACE # FOR ZONE 2 '
        READ(5, *) DETINT2
        WRITE(6,*) 'NCYCLE= ',NCYCLE
С
C****THROW OUT "NON-PAIRED" DATA AND COMPUTE SPEED****
C
        KOUNTR=0
        REWIND 3
        READ(3) INTNUM1, TIME1
        DO 500 I=2, KOUNT
          READ(3) INTNUM2, TIME2
           IF((INTNUM1.EQ.DETINT1).AND.(INTNUM2.EQ.DETINT2)) THEN
             KOUNTR=KOUNTR+1
            DELTAT=(TIME2-TIME1)*CONST
            NEWTIME=TIME2*CONST/3.6E9
             SPEED=SPACE/DELTAT*3.6E9/5280.
            WRITE(4) NEWTIME, SPEED
           ENDIF
          INTNUM1=INTNUM2
          TIME1=TIME2
  500
        CONTINUE
        WRITE(6, *) 'KOUNTR = ', KOUNTR
C
C****SET UP SAMPLING INTERVAL AND OCCUPANCY ARRAY****
C
        XHOUR2=INT (NEWTIME)
        XMIN2=INT((NEWTIME-INT(NEWTIME))*60.)
        REWIND 4
        READ(4) NEWTIME, SPEED
        XHOUR1=INT (NEWTIME)
        XMIN1=INT((NEWTIME-INT(NEWTIME))*60.)
С
        START=XHOUR1+XMIN1/60.
        END=XHOUR2+XMIN2/60.
        INUM=((END-START)/HDELT)+1
С
        WRITE(6,*) 'START = ', START.' END = ', END, ' INUM = ', INUM
        WRITE(6, \star)
С
        DO 200 K=1, INUM
          SAMPLE(K) = START+(K-1) * HDELT
          TAG(K) = TIMTAG+(K-1) * HDELT
  200
        CONTINUE
С
C****COMPUTE VEHICLE FLOWS AND AVERAGE SPEEDS****
С
        DO 400 I=1, INUM
          REWIND 4
          DO 410 J=1,KOUNTR
            READ(4) NEWTIME, SPEED
            IF (NEWTIME.LE.SAMPLE(I)) THEN
              GO TO 410
            ELSE
              IF ( (NEWTIME.GT.SAMPLE(I) ).AND. (NEWTIME.LE.
     æ
                SAMPLE(I)+HDELT)) THEN
                  ICOUNT(I) = ICOUNT(I) + 1
                  SPDSUM(I)=SPDSUM(I)+SPEED
              ELSE
                GO TO 405
```

ENDIF ENDIF 410 CONTINUE 405 FLOW(I) = (FLOAT(ICOUNT(I)))/HDELT AVESPD(I)=SPDSUM(I)/ICOUNT(I) DENS(I) = FLOW(I) / AVESPD(I)400 CONTINUE WRITE(6,17) WRITE(6,18) WRITE(6,21) 17 FORMAT (1X, 1X, 'INTRVL', 1X, 'SAMPLE', 6X, 'FLOW', 8X, 'AVG', 6X, 'LANE') æ 18 FORMAT(1X, 3X, 'NUM', 3X, 'TIME', 7X, 'RATE', 7X, 'SPEED', 3X, 'DENSITY') & 21 FORMAT(1X,9X,'(HRS)',4X,'(VEH/HR)',5X,'(MPH)',3X,'(VEH/MI)') DO 300 I=2, INUM-1 WRITE(6,19) I, TAG(I), FLOW(I), AVESPD(I), DENS(I) WRITE(2,22) TAG(I), FLOW(I), AVESPD(I), DENS(I) 300 CONTINUE 19 FORMAT(1X, 15, 2X, F7.4, 2X, F9.2, 2X, F9.2, 2X, F7.2) 22 FORMAT(1X, F7.4, 2X, F7.2, 2X, F6.2, 2X, F7.2) STOP END SUBROUTINE OPEN CHARACTER*11 FNO CHARACTER*11 FNI CHARACTER FILENAME(8) WRITE(6,*) 'ENTER THE 8 DIGIT NUMERICAL FILENAME: ' READ(5, 225) (FILENAME(J), J=1, 8) 225 FORMAT(8A1) FNI=FILENAME(1)//FILENAME(2)//FILENAME(3)//FILENAME(4)// æ FILENAME(5)//FILENAME(6)//FILENAME(7)//FILENAME(8)//'.DI' FNO=FILENAME(1)//FILENAME(2)//FILENAME(3)//FILENAME(4)// & FILENAME(5)//FILENAME(6)//FILENAME(7)//FILENAME(8)//'.DO' WRITE(6,230) FNI WRITE(6,230) FNO 230 FORMAT(1X, 20A)OPEN(1, FILE=FNI, STATUS='OLD') OPEN(2, FILE=FNO, STATUS='OLD') OPEN(3, FILE='MICSEC.DAT', STATUS='OLD', ACCESS='SEQUENTIAL', æ FORM='UNFORMATTED') OPEN(4, FILE='DENS.DAT', STATUS='OLD', ACCESS='SEQUENTIAL', FORM='UNFORMATTED') æ

RETURN

C* THIS PROGRAM COMPUTES OCCUPANCY VERSUS C* FLOW FOR A USER-DEFINED TIME INTERVAL * С INTEGER TIME С DIMENSION TIME (7000, 4), PRES (7000), DECTIME (7000), SAMPLE(7000), SUM(7000), HPRES(7000), OCC(7000), & SEC(7000), FLOW(7000), ICOUNT(7000) & С CALL OPEN С C****INITIALIZE COUNTER TO DETERMINE # OF ROWS**** С KOUNT=0С C****READ IN ARRAY VALUES FROM THE PARADOX DATA**** С 100 KOUNT=KOUNT+1 READ(1,*,END=999) (TIME(KOUNT,J),J=1,4), PRES(KOUNT) HPRES (KOUNT) = PRES (KOUNT) / 3.6E9 GO TO 100 С 999 KOUNT=KOUNT-1 С C****COMPUTE DECIMAL TIME FROM THE FOUR TIME FIELDS**** С DO 150 I=1,KOUNT DECTIME (I) = TIME (I, 1) + (TIME (I, 2) / 60.) + (TIME (I, 3) / 3600.)+(TIME(I,4)/3600000.)ŵ CONTINUE 150 C C****SOLICIT INPUT FOR DESIRED OCCUPANCY TIME INTERVAL**** С WRITE(6,15) 15 FORMAT(1X, 'ENTER THE DESIRED OCCUPANCY TIME INTERVAL (MINS) ') READ(5,*) DELTAM WRITE(6,16) DELTAM FORMAT(1X, 'DELTA M = ', F6.3, 1X, 'MINUTES') 16 HDELT=DELTAM/60. WRITE(6, *)С C****SET UP SAMPLING INTERVAL AND OCCUPANCY ARRAY**** С XHOUR1=TIME(1,1) XMIN1=TIME(1,2)XHOUR2=TIME(KOUNT, 1) XMIN2=TIME(KOUNT, 2) С START=XHOUR1+XMIN1/60. END=XHOUR2+XMIN2/60. INUM=((END-START)/HDELT)+1 С WRITE(6,*) 'START = ', START,' END = ', END,' INUM = ', INUM WRITE $(6, \star)$ С DO 200 K=1, INUM SAMPLE(K) = START+(K-1) * HDELT SUM(K) = 0.0

```
С
C****SUM UP THE PRESENCE TIMES FOR EACH SAMPLING PERIOD****
С
        DO 250 I=1, INUM
           DO 260 J=1,KOUNT
             IF (DECTIME (J).LE.SAMPLE (I)) THEN
               GO TO 260
             ELSE
               IF((DECTIME(J).GT.SAMPLE(I)).AND.(DECTIME(J)-HPRES(J).LT.
     &
                 SAMPLE(I))) THEN
                   SUM(I) = SUM(I) + DECTIME(J) - SAMPLE(I)
               ELSE
                 IF(((DECTIME(J)-HPRES(J)).GE.SAMPLE(I)).AND.(DECTIME(J))
     &
                 .LE.SAMPLE(I)+HDELT)) THEN
                     SUM(I) = SUM(I) + HPRES(J)
                 ELSE
                   IF(((DECTIME(J).GT.(SAMPLE(I)+HDELT)).AND.
     Sc.
                   ((DECTIME(J)-HPRES(J)).LT.(SAMPLE(I)+HDELT)))) THEN
                       SUM(I) = SUM(I) + (HPRES(J) - DECTIME(J) + SAMPLE(I) +
                       HDELT)
     &
                   ELSE
                     IF(((DECTIME(J)-HPRES(J)).LT.(SAMPLE(I))).AND.
     &
                        (DECTIME(J).GT. (SAMPLE(I)+HDELT))) THEN
                           SUM(I)=SUM(I)+HDELT
                     ELSE
                       GO TO 250
                     ENDIF
                   ENDIF
                 ENDIF
               ENDIF
             ENDIF
  260
          CONTINUE
  250
        CONTINUE
С
C****COMPUTE OCCUPANCIES AND WRITE OUTPUTS****
С
        DO 265 I=1, INUM
           OCC(I) = SUM(I) * 100/HDELT
           SEC(I) = SUM(I) * 3600.
  265
        CONTINUE
С
C****COMPUTE VEHICLE FLOWS AT SPECIFIED INTEGRATION TIMES****
С
        DO 400 I=1, INUM
          DO 410 J=1, KOUNT
             IF (DECTIME (J).LE.SAMPLE (I)) THEN
               GO TO 410
             ELSE
               IF((DECTIME(J).GT.SAMPLE(I)).AND.(DECTIME(J).LE.
     æ
                 SAMPLE(I)+HDELT)) THEN
                   ICOUNT(I)=ICOUNT(I)+1
               ELSE
                 GO TO 405
               ENDIF
            ENDIF
  410
          CONTINUE
  405
            FLOW(I) = (FLOAT(ICOUNT(I))) / HDELT
  400
        CONTINUE
```

WRITE(6,17) WRITE(6,18) WRITE(6,21) FORMAT(1X,1X,'INTRVL',1X,'SAMPLE',4X,'INTRVL',5X,'INTRVL',13X, 17 'FLOW') & 18 FORMAT(1X, 3X, 'NUM', 3X, 'TIME', 1X, 2(3X, 'PRESENCE'), 4X, 'OCC', 5X, δ 'RATE') 21 FORMAT(1X,9X,'(HRS)',5X,'(HRS)',6X,'(SECS)',4X,'(%)',3X, & '(VEH/HR)') DO 300 I=2, INUM-1 WRITE(6,19) I, SAMPLE(I), SUM(I), SEC(I), OCC(I), FLOW(I) WRITE(2,22) SAMPLE(I),OCC(I),FLOW(I) 300 CONTINUE 19 FORMAT(1X, 15, 2X, F7.4, 2X, E10.4, 2X, F7.3, 2X, F7.3, 2X, F7.2) 22 FORMAT(1X, F7.4, 2X, F7.3, 2X, F7.2) STOP END SUBROUTINE OPEN CHARACTER*12 FNO CHARACTER*11 FNI CHARACTER FILENAME(8) WRITE(6,*) 'ENTER THE 8 DIGIT NUMERICAL FILENAME: ' READ(5,225) (FILENAME(J), J=1,8) 225 FORMAT(8A1) FNI=FILENAME(1)//FILENAME(2)//FILENAME(3)//FILENAME(4)// FILENAME(5)//FILENAME(6)//FILENAME(7)//FILENAME(8)//'.IN' & FNO=FILENAME(1)//FILENAME(2)//FILENAME(3)//FILENAME(4)// FILENAME(5)//FILENAME(6)//FILENAME(7)//FILENAME(8)//'.OFO' & WRITE(6,230) FNI WRITE(6,230) FNO 230 FORMAT(1X,20A) OPEN(1, FILE=FNI, STATUS='OLD') OPEN(2, FILE=FNO, STATUS='OLD') RETURN

K.5 DENS_TOD.FOR

```
С*
    THIS PROGRAM COMPUTES DENSITY, SPEED,
C*
    AND FLOW FOR A USER-DEFINED TIME INTERVAL *
С
        INTEGER TIME
С
        REAL NEWTIME
        DIMENSION TIME(13000,4), DECTIME(13000), INTNUM(13000),
          SAMPLE(1000), DENS(1000), SPEED(6500), FLOW(1000),
     &
          ICOUNT(1000), NEWTIME(6500), SPDSUM(1000), AVESPD(1000).
     &
          DELTAT(6500)
     &
С
        CALL OPEN
C
C****INITIALIZE COUNTER TO DETERMINE # OF ROWS****
C
        KOUNT=0
С
C****READ IN ARRAY VALUES FROM THE PARADOX DATA****
С
  100
        KOUNT=KOUNT+1
        READ(1,*,END=999) (TIME(KOUNT,J),J=1,4), INTNUM(KOUNT)
        GO TO 100
С
  999
        KOUNT=KOUNT-1
С
C****COMPUTE DECIMAL TIME FROM THE FOUR TIME FIELDS****
С
        DO 150 I=1.KOUNT
          DECTIME(I) = TIME(I, 1) + (TIME(I, 2) / 60.) + (TIME(I, 3) / 3600.)
                    +(TIME(I,4)/360000.)
     &
  150
        CONTINUE
C
C****SOLICIT INPUT FOR DESIRED OCCUPANCY TIME INTERVAL****
С
        WRITE(6, *)
        WRITE(6,10)
        READ(5, \star) SPACE
        WRITE(6, *)
        WRITE(6,15)
  10
        FORMAT(1X,'ENTER THE CENTER-TO-CENTER LOOP SPACING (FT) ')
  15
        FORMAT(1x,'ENTER THE DESIRED INTEGRATION TIME INTERVAL (MINS) ')
        READ(5,*) DELTAM
        WRITE(6,16) DELTAM
  16
        FORMAT(1X, 'DELTA M = ', F6.3, 1X, 'MINUTES')
        HDELT=DELTAM/60.
        WRITE(6, *)
С
C****THROW OUT "NON-PAIRED" DATA AND COMPUTE SPEED****
C
        DO 500 I=1,KOUNT
          IF((INTNUM(I).EQ.1).AND.(INTNUM(I+1).EQ.2)) THEN
            KOUNTR=KOUNTR+1
            NEWTIME (KOUNTR) = DECTIME (I+1)
            DELTAT(KOUNTR) = (DECTIME(I+1) - DECTIME(I))
            SPEED (KOUNTR) = SPACE/DELTAT (KOUNTR) / 5280.
          ELSE
          ENDIF
```

```
WRITE(6,*) 'KOUNTR = ',KOUNTR,' NEWTIME(FINAL) = ',
          NEWTIME (KOUNTR)
     æ
        WRITE(6, *) 'NEWTIME(1) = ', NEWTIME(1)
        WRITE(6,*) 'DECTIME(1) = ',DECTIME(1)
        WRITE(6,*) 'DECTIME(2) = ', DECTIME(2)
        WRITE(6,*) 'DECTIME(3) = ', DECTIME(3)
        WRITE(6, *) 'DELTAT(1) = ', DELTAT(1)
        WRITE(6, *) 'SPEED(1) = ', SPEED(1)
С
C****SET UP SAMPLING INTERVAL AND OCCUPANCY ARRAY****
С
        XHOUR1=INT (NEWTIME (1))
        XMIN1=INT((NEWTIME(1)-INT(NEWTIME(1)))*60.)
        XHOUR2=INT (NEWTIME (KOUNTR))
        XMIN2=INT((NEWTIME(KOUNTR)-INT(NEWTIME(KOUNTR)))*60.)
С
        START=XHOUR1+XMIN1/60.
        END=XHOUR2+XMIN2/60.
        INUM=((END-START)/HDELT)+1
С
        WRITE(6,*) 'XMIN1= ',XMIN1
        WRITE(6,*) 'START = ', START,' END = ', END,' INUM = ', INUM
        WRITE(6, *)
С
        DO 200 K=1, INUM
          SAMPLE(K) = START+(K-1) * HDELT
  200
        CONTINUE
С
C****COMPUTE VEHICLE FLOWS AND AVERAGE SPEEDS****
С
        DO 400 I=1, INUM
          DO 410 J=1, KOUNTR
             IF (NEWTIME (J).LE.SAMPLE (I)) THEN
               GO TO 410
            ELSE
               IF ((NEWTIME(J).GT.SAMPLE(I)).AND.(NEWTIME(J).LE.
     £
                 SAMPLE(I)+HDELT)) THEN
                   ICOUNT(I) = ICOUNT(I) +1
                   SPDSUM(I) = SPDSUM(I) + SPEED(J)
               ELSE
                 GO TO 405
              ENDIF
            ENDIF
  410
          CONTINUE
  405
            FLOW(I) = (FLOAT(ICOUNT(I)))/HDELT
            AVESPD(I)=SPDSUM(I)/ICOUNT(I)
  400
        CONTINUE
        WRITE(6,17)
        WRITE(6,18)
        WRITE(6,21)
  17
        FORMAT(1x,1x,'INTRVL',1x,'SAMPLE',6x,'FLOW',8x,'AVG',6x,
          'LANE')
     æ
  18
        FORMAT(1X, 3X, 'NUM', 3X, 'TIME', 7X, 'RATE', 7X, 'SPEED', 3X,
          'DENSITY')
     &
 21
        FORMAT(1x,9x,'(HRS)',4x,'(VEH/HR)',5x,'(MPH)',3x,'(VEH/MI)')
        DO 300 I=1, INUM
```

WRITE(6,19) I,SAMPLE(I),FLOW(I),AVESPD(I),DENS(I)
WRITE(2,22) SAMPLE(I),FLOW(I),AVESPD(I),DENS(I)
CONTINUE
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300 CONTINUE

19 FORMAT(1X, 15, 2X, F7.4, 2X, F9.2, 2X, F9.2, 2X, F7.2)
22 FORMAT(1X, F7.4, 2X, F7.2, 2X, F6.2, 2X, F7.2)

STOP END

225

230

SUBROUTINE OPEN

CHARACTER*11 FNO CHARACTER*11 FNI CHARACTER FILENAME(8)

WRITE(6,*) 'ENTER THE 8 DIGIT NUMERICAL FILENAME: '
READ(5,225) (FILENAME(J),J=1,8)
FORMAT(8A1)

FNI=FILENAME(1)//FILENAME(2)//FILENAME(3)//FILENAME(4)//
& FILENAME(5)//FILENAME(6)//FILENAME(7)//FILENAME(8)//'.DI'

FNO=FILENAME(1)//FILENAME(2)//FILENAME(3)//FILENAME(4)//
FILENAME(5)//FILENAME(6)//FILENAME(7)//FILENAME(8)//'.DO'

WRITE(6,230) FNI WRITE(6,230) FNO FORMAT(1X,20A)

OPEN(1,FILE=FNI,STATUS='OLD')
OPEN(2,FILE=FNO,STATUS='OLD')

RETURN

K.6 DENS 232.FOR

```
C*
     THIS PROGRAM COMPUTES DENSITY, SPEED,
C* AND FLOW FOR A USER-DEFINED TIME INTERVAL *
С
        INTEGER TIME
С
        DIMENSION TIME(13000,4), DECTIME(13000), SPEED(13000),
     3
          SAMPLE(1000), DENS(1000), FLOW(1000),
          ICOUNT(1000), SPDSUM(1000), AVESPD(1000)
     £
C
        CALL OPEN
С
C****INITIALIZE COUNTER TO DETERMINE # OF ROWS****
С
        KOUNT=0
С
C****READ IN ARRAY VALUES FROM THE PARADOX DATA****
С
  100
        KOUNT=KOUNT+1
        READ(1, *, END=999) (TIME(KOUNT, J), J=1, 4), SPEED(KOUNT)
        GO TO 100
С
  999
        KOUNT=KOUNT-1
С
C****COMPUTE DECIMAL TIME FROM THE FOUR TIME FIELDS****
C
        DO 150 I=1,KOUNT
          DECTIME(I) =TIME(I,1) + (TIME(I,2)/60.) + (TIME(I,3)/3600.)
                    +(TIME(I,4)/3600000.)
     &
  150
        CONTINUE
С
        WRITE(6,15)
  15
        FORMAT(1X, 'ENTER THE DESIRED INTEGRATION TIME INTERVAL (MINS) ')
        READ(5, *) DELTAM
        WRITE(6,16) DELTAM
  16
        FORMAT(1X, 'DELTA M = ', F6.3, 1X, 'MINUTES')
        HDELT=DELTAM/60.
        WRITE(6, *)
C
C****SET UP SAMPLING INTERVAL AND OCCUPANCY ARRAY****
С
        XHOUR1=INT (DECTIME(1))
        XMIN1=INT((DECTIME(1)-INT(DECTIME(1)))*60.)
        XHOUR2=INT (DECTIME (KOUNT))
        XMIN2=INT((DECTIME(KOUNT)-INT(DECTIME(KOUNT)))*60.)
С
        START=XHOUR1+XMIN1/60.
        END=XHOUR2+XMIN2/60.
        INUM=((END-START)/HDELT)+1
С
       WRITE(6,*) 'XMIN1= ',XMIN1
       WRITE(6,*) 'START = ',START,' END = ',END,'
                                                     INUM = ', INUM
       WRITE(6, *)
С
       DO 200 K=1, INUM
          SAMPLE(K) = START+(K-1) * HDELT
  200
       CONTINUE
С
C****COMPUTE VEHICLE FLOWS AND AVERAGE SPEEDS****
                                   K-15
```

С

	DO 400 I=1,INUM DO 410 J=1,KOUNT IF(DECTIME(J).LE.SAMPLE(I)) THEN GO TO 410 ELSE
æ	<pre>IF((DECTIME(J).GT.SAMPLE(I)).AND.(DECTIME(J).LE. SAMPLE(I)+HDELT)) THEN ICOUNT(I)=ICOUNT(I)+1 SPDSUM(I)=SPDSUM(I)+SPEED(J)</pre>
	ELSE GO TO 405 ENDIF ENDIF
410 405	CONTINUE FLOW(I) = (FLOAT(ICOUNT(I)))/HDELT AVESPD(I) = SPDSUM(I)/ICOUNT(I) DENS(I) = FLOW(I)/AVESPD(I)
400	CONTINUE
	WRITE(6,17) WRITE(6,18) WRITE(6,21)
17 &	<pre>FORMAT(1X,1X,'INTRVL',1X,'SAMPLE',6X,'FLOW',8X,'AVG',6X, 'LANE')</pre>
18 &	<pre>FORMAT(1X, 3X, 'NUM', 3X, 'TIME', 7X, 'RATE', 7X, 'SPEED', 3X, 'DENSITY')</pre>
21	FORMAT(1X,9X,'(HRS)',4X,'(VEH/HR)',5X,'(MPH)',3X,'(VEH/MI)')
300	<pre>DO 300 I=2,INUM-1 WRITE(6,19) I,SAMPLE(I),FLOW(I),AVESPD(I),DENS(I) WRITE(2,22) SAMPLE(I),FLOW(I),AVESPD(I),DENS(I) CONTINUE</pre>
19 22	FORMAT(1X, I5, 2X, F7.4, 2X, F9.2, 2X, F9.2, 2X, F7.2) FORMAT(1X, F7.4, 2X, F7.2, 2X, F6.2, 2X, F7.2)
	STOP END
	SUBROUTINE OPEN
	CHARACTER*11 FNO CHARACTER*11 FNI CHARACTER FILENAME(8)
225	WRITE(6,*) 'ENTER THE 8 DIGIT NUMERICAL FILENAME: ' READ(5,225) (FILENAME(J),J=1,8) FORMAT(8A1)
æ	<pre>FNI=FILENAME(1)//FILENAME(2)//FILENAME(3)//FILENAME(4)// FILENAME(5)//FILENAME(6)//FILENAME(7)//FILENAME(8)//'.DI'</pre>
æ	<pre>FNO=FILENAME(1)//FILENAME(2)//FILENAME(3)//FILENAME(4)// FILENAME(5)//FILENAME(6)//FILENAME(7)//FILENAME(8)//'.DO'</pre>
230	WRITE(6,230) FNI WRITE(6,230) FNO FORMAT(1X,20A)

OPEN(1,FILE=FNI,STATUS='OLD')
OPEN(2,FILE=FNO,STATUS='OLD')

RETURN

K.7 GP_COUNT.FOR

```
C*
    THIS PROGRAM OUTPUTS VEHICLE COUNTS VS.
                                          *
C* TIME OF DAY FOR THE TUCSON SURFACE STREET
                                          *
C* SITE. COUNTS ARE ONLY NOTED FOR THRU-TRAFFIC*
C* i.e. DURING THE SIGNAL GREEN PHASE
С
       INTEGER TIME, GPTIME
С
       REAL NEWTIME
С
       DIMENSION TIME (10000, 4), DECTIME (10000), VPRES (10000),
    S.
                NEWTIME(10000), GPTIME(2000,4), GDECTIME(2000)
С
       CALL OPEN
C
C****INITIALIZE COUNTERS****
С
       KOUNT=0
       KNTGP=1
       NUM=0
       NUMGP=0
С
C****READ IN ARRAY VALUES FROM THE PARADOX DATA****
С
 100
       NUM=NUM+1
       READ(1, *, END=999) (TIME(NUM, J), J=1, 4)
       GO TO 100
C
 999
       NUM=NUM-1
C
 110
       NUMGP=NUMGP+1
       READ(3, *, END=499) (GPTIME(NUMGP, J), J=1, 4), VPRES(NUMGP)
       GO TO 110
C
 499
      NUMGP=NUMGP-1
C
C****COMPUTE DECIMAL TIME FROM THE FOUR TIME FIELDS****
С
       DO 150 I=1,NUM
        DECTIME (I) = (TIME(I, 1) + (TIME(I, 2)/60.) + (TIME(I, 3)/3600.)
                 +(TIME(I,4)/3600000.))*3600.
    &
 150
       CONTINUE
С
       DO 160 I=1, NUMGP
        GDECTIME(I) = (GPTIME(I,1) + (GPTIME(I,2)/60.) + (GPTIME(I,3)/3600.)
    &
                   +(GPTIME(I,4)/3600000.))*3600.
        VPRES(I) = VPRES(I)/1.0E6
 160
       CONTINUE
С
C****TUCSON SURFACE STREET SITE HAD A 4 SECOND YELLOW PHASE FOLLOWED***
C****
                   BY A 2 SECOND "ALL RED" PHASE
                                                            ****
DO 200 I=1,NUM
        IF((DECTIME(I).GT.(GDECTIME(KNTGP)-VPRES(KNTGP)+1)).AND.
    &
          DECTIME(I).LE. (GDECTIME(KNTGP)+6)) THEN
          KOUNT=KOUNT+1
          NEWTIME (KOUNT) = DECTIME (I)
```

```
ELSE
            IF (DECTIME (I).GT. (GDECTIME (KNTGP)+6)) THEN
              KNTGP=KNTGP+1
            ENDIF
          ENDIF
  200
        CONTINUE
C
        WRITE(6, *) 'KOUNT= ', KOUNT, '
                                        NUM= ', NUM
        PERGRN=FLOAT (KOUNT) / FLOAT (NUM) *100.
        WRITE(6,*) 'PERCENTAGE OF COUNT OCCURRING DURING GREEN PHASE = '
     &
                    , PERGRN
С
        DO 300 I=1, KOUNT
          NEWTIME(I)=NEWTIME(I)/3600.
          WRITE(6,*) NEWTIME(I), I
          WRITE(2,10) NEWTIME(I), I
  300
        CONTINUE
C
  10
        FORMAT(1X, F10.7, 2X, 15)
C
        STOP
        END
        SUBROUTINE OPEN
        CHARACTER*12 FNO
        CHARACTER*12 FNI
        CHARACTER*11 FNGP
        CHARACTER FILENAME(8)
        WRITE(6,*) 'ENTER THE 8 DIGIT NUMERICAL FILENAME: '
        READ(5,225) (FILENAME(J), J=1,8)
 225
        FORMAT(8A1)
        FNI=FILENAME(1)//FILENAME(2)//FILENAME(3)//FILENAME(4)//
    &
          FILENAME(5)//FILENAME(6)//FILENAME(7)//FILENAME(8)//'.GPI'
        FNO=FILENAME(1)//FILENAME(2)//FILENAME(3)//FILENAME(4)//
    &
          FILENAME(5)//FILENAME(6)//FILENAME(7)//FILENAME(8)//'.GPO'
        FNGP=FILENAME(1)//FILENAME(2)//FILENAME(3)//FILENAME(4)//
    &
          FILENAME(5)//FILENAME(6)//FILENAME(7)//FILENAME(8)//'.GP'
       WRITE(6,230) FNI
       WRITE(6,230) FNO
 230
       FORMAT(1X,20A)
       OPEN(1, FILE=FNI, STATUS='OLD')
        OPEN(2, FILE=FNO, STATUS='OLD')
       OPEN(3, FILE=FNGP, STATUS='OLD')
       RETURN
```

K.8 OCC.FOR

```
THIS PROGRAM DOES ARRAY MANIPULATION
C*
C*
    AND COMPUTES OCCUPANCY VALUES FOR A
C*
    USER-DEFINED TIME INTERVAL
C
        INTEGER TIME
С
       DIMENSION TIME (9000,4), PRES (9000), DECTIME (9000),
          SAMPLE(9000), SUM(9000), HPRES(9000), OCC(9000),
     δ.
         SEC(9000)
     &
С
        CALL OPEN
С
C****INITIALIZE COUNTER TO DETERMINE # OF ROWS****
С
       KOUNT=0
        FACTOR=0.0
С
C****READ IN ARRAY VALUES FROM THE PARADOX DATA****
С
  100
       KOUNT=KOUNT+1
       READ(1,*,END=999) (TIME(KOUNT,J),J=1,4), PRES(KOUNT)
       HPRES (KOUNT) = PRES (KOUNT) /3.6E9
       FACTOR=PRES (KOUNT) + FACTOR
       GO TO 100
С
  999
       KOUNT=KOUNT-1
       AVEPRES=FACTOR/KOUNT
C****COMPUTE DECIMAL TIME FROM THE FOUR TIME FIELDS****
С
       DO 150 I=1, KOUNT
         DECTIME (I) = TIME (I, 1) + (TIME (I, 2) / 60.) + (TIME (I, 3) / 3600.)
                   +(TIME(I,4)/3600000.)
     δ
  150
       CONTINUE
С
C****SOLICIT INPUT FOR DESIRED OCCUPANCY TIME INTERVAL****
С
       WRITE(6, 15)
       FORMAT(1X, 'ENTER THE DESIRED OCCUPANCY TIME INTERVAL (MINS) ')
  15
       READ(5,*) DELTAM
       WRITE(6,16) DELTAM
  16
       FORMAT(1X, 'DELTA M = ', F6.3, 1X, 'MINUTES')
       HDELT=DELTAM/60.
       WRITE(6, *)
С
C****SET UP SAMPLING INTERVAL AND OCCUPANCY ARRAY****
С
       XHOUR1=TIME(1,1)
       XMIN1=TIME(1,2)
       XHOUR2=TIME(KOUNT, 1)
       XMIN2=TIME(KOUNT, 2)
С
       START=XHOUR1+XMIN1/60.
       END=XHOUR2+XMIN2/60.
       INUM=((END-START)/HDELT)+1
С
       WRITE(6,*) 'START = ', START,' END = ', END,' INUM = ', INUM
       WRITE(6, *)
```

DO 200 K=1, INUM SAMPLE(K) = START+(K-1) * HDELT SUM(K) = 0.0200 CONTINUE С C****SUM UP THE PRESENCE TIMES FOR EACH SAMPLING PERIOD**** С DO 250 I=1, INUM DO 260 J=1,KOUNT IF (DECTIME (J). LE. SAMPLE (I)) THEN GO TO 260 ELSE IF((DECTIME(J),GT.SAMPLE(I)).AND.(DECTIME(J)-HPRES(J).LT. & SAMPLE(I))) THEN SUM(I) = SUM(I) + DECTIME(J) - SAMPLE(I) ELSE IF(((DECTIME(J)-HPRES(J)).GE.SAMPLE(I)).AND.(DECTIME(J)) & .LE.SAMPLE(I)+HDELT)) THEN SUM(I) = SUM(I) + HPRES(J)ELSE IF(((DECTIME(J).GT.(SAMPLE(I)+HDELT)).AND. & ((DECTIME(J)-HPRES(J)).LT.(SAMPLE(I)+HDELT)))) THEN SUM(I) = SUM(I) + (HPRES(J) - DECTIME(J) + SAMPLE(I) + HDELT) & ELSE IF(((DECTIME(J)-HPRES(J)).LT.(SAMPLE(I))).AND. & (DECTIME(J).GT.(SAMPLE(I)+HDELT))) THEN SUM(I)=SUM(I)+HDELT ELSE GO TO 250 ENDIF ENDIF ENDIF ENDIF ENDIF 260 CONTINUE 250 CONTINUE С C****COMPUTE OCCUPANCIES AND WRITE OUTPUTS**** С DO 265 I=1, INUM OCC(I) = SUM(I) * 100 / HDELTSEC(I) = SUM(I) * 3600. 265 CONTINUE WRITE(6,17) WRITE(6,18) WRITE(6,21) 17 FORMAT(1X,1X,'INTRVL',1X,'SAMPLE',4X,'INTRVL',5X,'INTRVL') 18 FORMAT(1X, 3X, 'NUM', 3X, 'TIME', 1X, 2(3X, 'PRESENCE'), 4X, 'OCC') FORMAT(1X,9X,'(HRS)',5X,'(HRS)',6X,'(SECS)',4X,'(%)') 21 DO 300 I=2, INUM-1 WRITE(6,19) I, SAMPLE(I), SUM(I), SEC(I), OCC(I) WRITE(2,22) SAMPLE(I), OCC(I) 300 CONTINUE WRITE(6,*) 'AVERAGE PRESENCE IN MICROSECONDS = ', AVEPRES 19 FORMAT(1X, 15, 2X, F7.4, 2X, E10.4, 2X, F7.3, 2X, F7.3)

С

22 FORMAT(1X, F7.4, 2X, F7.3)

> STOP END

225

SUBROUTINE OPEN

CHARACTER*12 FNO CHARACTER*11 FNI CHARACTER FILENAME(8)

WRITE(6,*) 'ENTER THE 8 DIGIT NUMERICAL FILENAME: ' READ(5,225) (FILENAME(J), J=1,8) FORMAT(8A1)

FNI=FILENAME(1)//FILENAME(2)//FILENAME(3)//FILENAME(4)// & FILENAME(5)//FILENAME(6)//FILENAME(7)//FILENAME(8)//'.IN'

FNO=FILENAME(1)//FILENAME(2)//FILENAME(3)//FILENAME(4)// FILENAME(5)//FILENAME(6)//FILENAME(7)//FILENAME(8)//'.OUT' &

WRITE(6,230) FNI WRITE(6,230) FNO FORMAT(1X,20A)

230

OPEN(1,FILE=FNI,STATUS='OLD') OPEN(2, FILE=FNO, STATUS='OLD')

RETURN

K.9 SVF.FOR

```
C*
     THIS PROGRAM COMPUTES FLOW RATES AND AVERAGE *
C*
     SPEEDS FOR A USER-DEFINED SAMPLING TIME
С
        INTEGER TIME
C
        DIMENSION TIME(9000,4), SPEED(9000), DECTIME(9000),
     &
          SAMPLE(9000), SPDSUM(9000), ICOUNT(9000), AVESPD(9000),
     æ
          FLOW(9000)
С
        CALL OPEN
С
C****INITIALIZE COUNTER TO DETERMINE # OF ROWS****
C
        KOUNT=0
C
C****READ IN ARRAY VALUES FROM THE PARADOX DATA****
С
  100
        KOUNT=KOUNT+1
        READ(1, \star, END \approx 999) (TIME(KOUNT, J), J = 1, 4), SPEED(KOUNT)
        GO TO 100
C
  999
        KOUNT=KOUNT-1
С
C****COMPUTE DECIMAL TIME FROM THE FOUR TIME FIELDS****
C
        DO 150 I=1,KOUNT
          DECTIME(I) = TIME(I, 1) + (TIME(I, 2) / 60.) + (TIME(I, 3) / 3600.)
                    +(TIME(I,4)/3600000.)
     &
  150
        CONTINUE
С
C****SOLICIT INPUT FOR DESIRED OCCUPANCY TIME INTERVAL****
C
        WRITE (6, *)
        WRITE(6,15)
        FORMAT(1x,'ENTER THE DESIRED SAMPLING TIME INTERVAL (MINS) ')
  15
        READ(5,*) DELTAM
        WRITE(6,16) DELTAM
  16
        FORMAT(1X, 'DELTA M = ', F6.3, 1X, 'MINUTES')
        HDELT=DELTAM/60.
        WRITE(6, *)
C
C****SET UP SAMPLING INTERVAL****
С
        XHOUR1=TIME(1,1)
        XMIN1=TIME(1,2)
        XHOUR2=TIME(KOUNT, 1)
        XMIN2=TIME(KOUNT,2)
С
        START=XHOUR1+XMIN1/60.
        END=XHOUR2+XMIN2/60.
        INUM=((END-START)/HDELT)+1
С
        WRITE(6,*) 'START = ', START,' END = ', END,' INUM = ', INUM
        WRITE(6, *)
C
        DO 200 K=1, INUM
          SAMPLE(K) = START + (K-1) * HDELT
 200
        CONTINUE
```

```
С
C****COMPUTE AVERAGE SPEEDS AND FLOW RATES****
С
        DO 250 I=1, INUM
          DO 260 J=1,KOUNT
             IF (DECTIME (J).LE.SAMPLE (I)) THEN
               GO TO 260
             ELSE
               IF ((DECTIME(J).GT.SAMPLE(I)).AND.(DECTIME(J).LE.
                 SAMPLE(I)+HDELT) ) THEN
     &
                   SPDSUM(I) = SPDSUM(I) + SPEED(J)
                   ICOUNT(I) = ICOUNT(I) + 1
               ELSE
                 GO TO 250
               ENDIF
             ENDIF
  260
          CONTINUE
  250
        CONTINUE
C
        DO 265 I=1, INUM
          AVESPD(I)=SPDSUM(I)/ICOUNT(I)
          FLOW(I) = (FLOAT(ICOUNT(I)))/HDELT
  265
        CONTINUE
        WRITE(6.17)
        WRITE(6,18)
        WRITE(6,21)
  17
        FORMAT(1x,1x,'INTRVL',1x,'SAMPLE',2x,'INTRVL',2x,'FLOW',5x,
          'AVG')
     æ
  18
        FORMAT(1X, 3X, 'NUM', 3X, 'TIME', 3X, 'COUNT', 3X, 'RATE', 4X, 'SPEED')
  21
        FORMAT (1X, 9X, '(HRS)', 8X, '(VEH/HR)', 2X, '(MPH)')
        DO 300 I=2, INUM-1
          WRITE(6,19) I, SAMPLE(I), ICOUNT(I), FLOW(I), AVESPD(I)
          WRITE(2,19) I, SAMPLE(I), ICOUNT(I), FLOW(I), AVESPD(I)
  300
        CONTINUE
  19
        FORMAT(1X, 15, 2X, F7, 4, 2X, 14, 2X, F7, 2, 2X, F7, 3)
        STOP
        END
        SUBROUTINE OPEN
        CHARACTER*12 FNO
        CHARACTER*12 FNI
        CHARACTER FILENAME(8)
        WRITE(6,*) 'ENTER THE 8 DIGIT NUMERICAL FILENAME: '
        READ(5,225) (FILENAME(J), J=1,8)
 225
        FORMAT(8A1)
        FNI=FILENAME(1)//FILENAME(2)//FILENAME(3)//FILENAME(4)//
     Se.
          FILENAME(5)//FILENAME(6)//FILENAME(7)//FILENAME(8)//'.SFI'
        FNO=FILENAME(1)//FILENAME(2)//FILENAME(3)//FILENAME(4)//
     &
          FILENAME(5)//FILENAME(6)//FILENAME(7)//FILENAME(8)//'.SFO'
        WRITE(6,230) FNI
        WRITE(6,230) FNO
```