

DOT HS 807 233 Final Report

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March 1987

Development and Implementation of a Rear Vision Device Test Protocol; Volume I, Physical Characteristics Measurement

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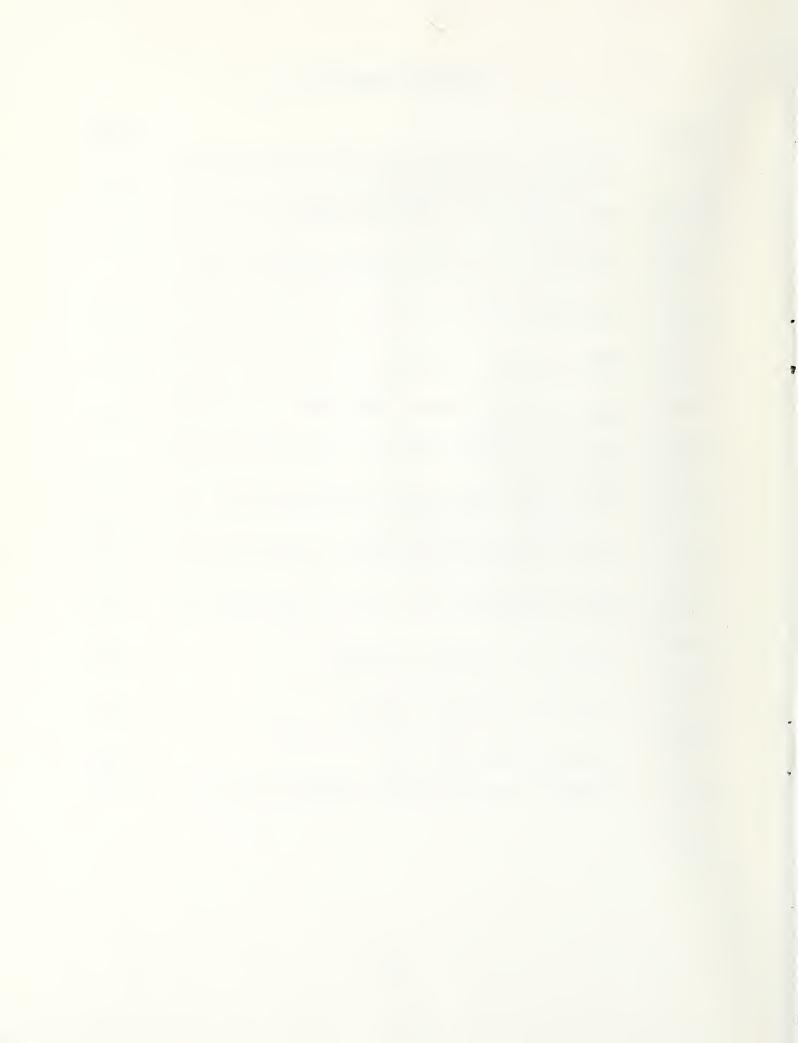
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1.0 INTRODUCTION

1.1 Background and Purpose

In the late 1960's the first sizable scientific evaluations of rear vision systems for motor vehicles were undertaken. Since those original studies, numerous others have followed, each attempting in its own way to evaluate the potential effectiveness of rear vision system characteristics for reducing motor vehicle collisions. A variety of performance measures have been used in laboratory, field-simulation and on-the-road driving situations. These have included target distance judgement error, lane change gap acceptance, motion judgement error, image size distortion and mirror viewing behavior based upon eye movement and other recordings. Today, after almost 20 years, there remains no accepted protocol to which a specific mirror or other rear vision device can be subjected in order to evaluate or estimate its effectiveness in reducing motor vehicle accidents.

Current Federal Motor Vehicle Safety Standards (FMVSS 111) specify minimum standards for rear view systems including certain physical characteristics (e.g., mirror surface curvature) which preclude the use of some recent types of devices such as non-spherical curved mirrors. There is, however, little theoretical and virtually no empirical basis for allowing or disallowing mirrors because of their physicharacteristics. The purpose of the cal present research/development program was to develop a standardized, valid and reliable method for evaluating the accident reduction potential of existing and near-future rear vision systems and to provide a basis for accepting/rejecting devices with unacceptable characteristics.

1.2 Overview of the Method

A method of evaluating rear vision systems which is based on the screening of such systems at successively more sophisticated levels was desired. Ideally, a system would be rejected from further consideration or accepted for further evaluation based upon a quick and inexpensive initial level of evaluation. Subsequent more costly evaluations would be limited to those systems exhibiting the most promise for safety enhancement. A three level measurement/evaluation approach, tiered in terms of incrementing cost and complexity, was envisioned. The three levels were:

- I. Measurement/Evaluation of Physical Device Characteristics
 - - * Field of View
 - * Magnification
 - * Surface Curvature or Radius of Curvature (ROC)

1 - 1

- * Accommodations Distance
- * Reflectance
- II. Measurement/Evaluation of Simulated-Use Performance
 * Use Performance
 - * Observer judgements of threat vehicle position and motion
- III. Measurement/Evaluation of Actual On-Road Use Performance

1.3 Organization

Volume I describes the background, development and results of applying a standardized method for measurement of rear vision system physical characteristics. Volume II describes in detail the development, implementation and results of applying a standardized method of evaluating simulated-use of systems. Actual on-road system performance, envisioned as a final level of evaluation was not developed as part of this research due to cost and safety considerations.

1.4 Contents of Volume I

Volume I 1) summarizes the development of the measurement protocol (Section 2.0), 2) describes the general test facility, equipment and methodology (Section 3.0), 3) provides a detailed description of the measurement protocol (Section 4.0), and 5) both summarizes measurement results (Section 5.0) and details measurement results for a variety of common and novel rear view systems (Appendix A).

2.0 DEVELOPMENT OF THE PROTOCOL

2.1 Overview

The purpose of rear vision device characteristics measurement/evaluation is to provide a range of descriptive measures of device characteristics which ultimately can be correlated with simulated-use and/or actual use performance measures. Ideally, these characteristics measures would be used for preliminary screening of rear vision devices as to their acceptability for certain applications and as candidates for more extensive simulated-use tests. Ultimately a set of decision rules might be developed which would be used to accept or reject devices based upon measures such as accommodation distance, magnification, etc.

2.2 Approach

The approach to development of a protocol for measurement of mirror characteristics involved the objectives of 1) low cost, 2) ease of implementation and 3) use of existing procedures and measurement equipment where possible. In all instances the objectives were met, as will be observed in subsequent measurement protocol descriptions.

2.3 Characteristics

Previous studies have identified number of rear vision device characteristics which are relevant to system performance, i.e., safety. These have included:

- * Field of View (horizontal and vertical),
- * Magnification or size distortion,
- * Radius of Curvature of the surface,
- * Accommodation Distance, and
- * Reflectance.

A general vehicle mock-up, described later in detail, served as a test-bed in which many characteristics measurements as well as simulated-use performance measurements were made. The mock-up and conventional photographic techniques comprised a simple integrated approach. It also maximized the use of the same equipment.

2.4 Characteristics Measurement

Concepts for various characteristics measurements are described here, along with the rational for selecting the specific protocol recommended.

2.4.1 Accommodation

Accommodation demand, i.e., the distance to which the eye must accommodate, is determined by the curvature of a mirrors surface and the distance to the object viewed in the mirror. The distance to which people of various age groups can accommodate is well documented. Therefore, use of large numbers of subjects viewing each mirror to determine the numbers of viewers who can or cannot accommodate to a particular mirror was unnecessary. Accommodation demand or distance, then, was more simply determined by measured eyeto-mirror distance and approximations of radius of curvature measures.

2.4.2 Reflectance

Light measurement is a tedious process requiring great precision and skill. An attempt was made to measure the reflectance of rear view mirrors at various locations on its surface using a Pritchard Photometer placed at the eye point in the vehicle mock-up. This technique, however, was extremely cumbersome and proved quite unreliable in practice. It was, therefore, discarded in favor of the existing standardized SAEJ964a procedure which while lacking the "in-use" geometry is quite simple and reliable.

2.4.3. Radius of Curvature

Two difficulties emerged in the measurement of the radius of curvature across a mirror's surface. First, measures near the edges were desirable but available sphereometers limit the closest measurement to a mirror edge to about .75 inches because of its design. Second, extremely accurate (beyond 1/10,000 inch) measures are necessary to accurately determine radii greater than about 100 inches.

Simple "lens-clocks" commonly used in optometry to measure lens curvature in diopters were tried and found to be far to crude. Subsequently, a depth gauge which permitted measurements to 1/1,000 inch, was mounted above a platform on which a mirror could be moved in x and y dimensions. Repeat measurements, however, were unreliable since only a few ten-thousandths of an inch resulted in several inch differences in ROC. An elaborate and expensive custom platform, and jig gauge to more precisely measure the depth was required to obtain desired reliability and accurate radii determinations.

A third technique was found to be the best compromise between cost, accuracy and reliability. An off-the-shelf, modified, depth gauge with three platform legs was used. Accuracy, reliability and ease of use were satisfactory.

2 – 2

Measures, however, were limited to within .75 inches of mirror edges.

2.4.4 Field of View and Magnification

A method using the vehicle mock-up to locate mirrors and "eyes", or viewing positions, in conjunction with a target grid was used to measure FOV and Magnification. Photographs of a grid viewed via a mirror from left, center and right eye positions provided hard copy of FOV and x y z coordinates for subsequent calculation of angular FOV, if desired. A projected grid permits grid size enlargements, if desired, for unique mirrors.

The hard copy photographs also permit measurement or magnification across a mirror's surface and correlation of magnification with FOV areas on the same photograph.

All magnification measures are expressed as a ratio of percent of a test mirror image size relative to a plane mirror image size for the same area viewed. This approach, therefore, includes in the measures, the effects of oblique viewing of extreme outboard objects. The measures for each eye--left and right--permit comparison of image size for each eye.

Finally, the method permits visual inspection of enlarged photographs of mirror-viewed grid elements for identification of other distortions of image quality which are otherwise difficult to quantify and measure.



3.0 TEST FACILITY AND GENERAL METHODOLOGY

3.1 Test Facility General Description

The facility for testing the various characteristics and performance capabilities of rear vision systems was comprised of a 1) vehicle mock-up with specific eye position(s) and mirror mounting location geometries, 2) photographic and photographic support equipment, 3) projection systems and projection surfaces and 4) variable projectable grid elements including grids and target vehicles (for simulated-use testing).

3.1.1 Test Buck Configuration

The test buck was comprised of a 6 x 6 foot square platform whose surface was calibrated in x and y dimensions and was marked in 1/8 inch increments. The platform provided for the placement of a camera or subject observer's eye position at desired locations simulating vehicle geometries. Also, the platform and affixed mounting hardware permitted installation of rear vision devices at various locations. A foamboard silhouette of a compact vehicle driver compartment was simulated. The test buck is illustrated in Figure 3-1.

3.1.2 Projection Equipment

Various visual stimuli to be viewed by subject observers or photographed were projected via a Kodak Ektagraphic Model III A projector with a BUHL 1.38 "EFL," F:2.5 (35 mm) series 7 wide angle lens. A movable 4 x 8 foot white foam board projection screen was used as a surface for all projections. The locations of the projector and projection screen were described in x, y and z coordinates relative to the "center eye" point for all measurements. The "center eye" point is a eyclopean eye midway between the eyes.

3.1.3 Stimulus Elements

Elements projected onto the screen for viewing included a 4 x 8 foot area grid comprised of 6 inch squares. Within the center of each square was a 3 x 3 inch cross-hair element.

3.1.4 Test Facility Equipment Positioning

The location of each photographic, projection, test device equipment element and viewer center eye position was defined in an x, y, z coordinate reference system. The overall measurement/test facility arrangement is illustrated in Figure 3-1. The x,y, z coordinates of reference points for each equipment element is specified in Table 3-1.

The center eye position in x (forward/rearward) and y (left/right) formed the origin of the coordinate system at



FIGURE 3.1 TEST FACILITY EQUIPMENT ARRANGEMENT

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TABLE 3-1 REFERENCE COORDINATES FOR TEST FACILITY SET-UP (CHARACTERISTICS MEASURES)

	х	У	Z
Eye Position Center	0.0	0.0	46.0
Right Mirror Center at Surface	+21.75	+46.5	+36.0
Left Mirror Center at Surface	+21.75	-20.0	+36.0
Center Mirror Center at Surface	+16.0	+13.25	+48.0
Projector Lens Center for Left Screen Projection	+67.0	-63.0	+36.0
Projector Lens Center for Center Screen Projection	+67.0	+13.25	+48.0
Projector Lens Center for Right Screen Projection	+67.0	+91.0	+36.0
Center of 4 x 8 foot Screen at Surface for Left Projection	-38.0	-63.0	+36.0
Center of 4 x 8 foot Screen at Surface for Center Projection	-38.0	0.0	+36.0
Center of 4 x 8 foot Screen at Surface for Right Projection	-38.0	+91.0	+36.0
	<pre>Right Mirror Center at Surface Left Mirror Center at Surface Center Mirror Center at Surface Projector Lens Center for Left Screen Projection Projector Lens Center for Center Screen Projection Projector Lens Center for Right Screen Projection Center of 4 x 8 foot Screen at Surface for Left Projection Center of 4 x 8 foot Screen at Surface for Center Projection</pre>	Eye Position Center0.0Right Mirror Center at Surface+21.75Left Mirror Center at Surface+21.75Center Mirror Center at Surface+16.0Projector Lens Center for Left Screen Projection+67.0Projector Lens Center for Center Screen Projection+67.0Projector Lens Center for Right Screen Projection+67.0Center of 4 x 8 foot Screen at Surface for Center Projection-38.0Center of 4 x 8 foot Screen at Surface for Center Projection-38.0	Eye Position Center0.00.0Right Mirror Center at Surface+21.75+46.5Left Mirror Center at Surface+21.75-20.0Center Mirror Center at Surface+16.0+13.25Projector Lens Center for Left Screen Projection+67.0-63.0Projector Lens Center for Center Screen Projection+67.0+13.25Projector Lens Center for Right Screen Projection+67.0+13.25Projector Lens Center for Right Screen Projection-63.0-63.0Center of 4 x 8 foot Screen at Surface for Center Projection-38.0-63.0Center of 4 x 8 foot Screen at Surface for Center Projection-38.00.0Center of 4 x 8 foot Screen at Surface for Center Projection-38.00.0

Notes; 1. All measures in inches. 2. Signs follow SAE procedure for Motor Vehicle Fiducial Marks (SAEJ182a)

ground level (z). The coordinates presented in Table 3-1 define the coordinates for left, center and right mirror systems measured and the coordinates for the projector and projection screen for testing mirrors in left, center and right locations. Equipment arrangement is briefly described below.

3.2 FACILITY SET-UP PROCEDURE

Equipment 3.2.1

order to set up the test facility for subsequent Ιn tests/measurement, the following is required:

- 6 x 6 foot platform with mirror mounting hardware;
- * Movable 4 x 8 foot projection screen;
- * Ektagraphic projector on adjustable stand;
- * 4 foot bubble level;
- *
- String Level; Large "T" square; *
- * Tape measures; and
- 米 20 x 30 foot enclosed light/sound controlled ventilated space.

3.2.2. Procedures

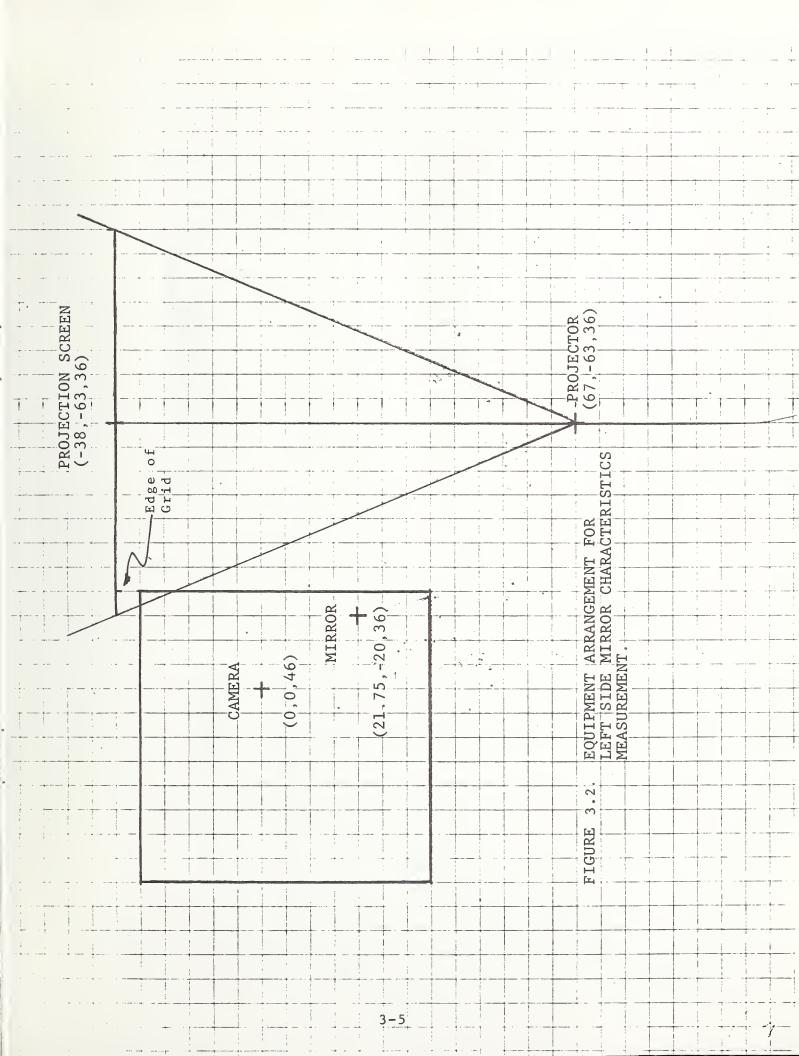
The procedures for setting-up the facility are as follows.

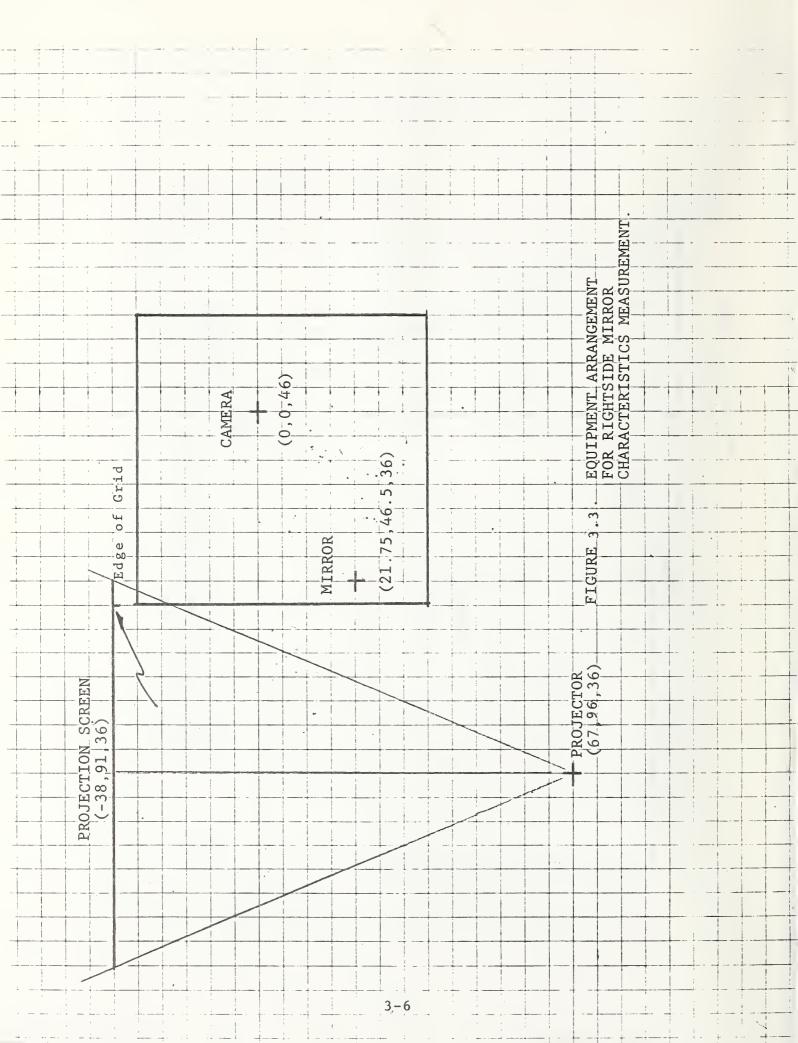
1) Place test buck platform approximately as shown in Figure 3-2 or 3-3, for left or right side mirror, relative to other equipment. Locate projection screen and projector approximately depending on mirror device location (left, center or right) to be tested.

2) Level platform in both x and y dimensions. Select a location on the platform to serve as the center eye position reference in x and y. Using a "T" square and tape, measure locations of mirror(s) in x and y. Clearly mark lines and points for later reference.

3) Locate the projection screen center as shown in the plan-view of Table 3-1. Level the screen and align its longitudinal axis so that it is perpendicular to the longitudinal axis of the test buck platform. After the center of the screen is properly located and aligned, assure that is is level and vertical using the bubble level.

4) Locate the projector so that a point representing the center of the surface of the lens is at the coordinates shown in Table 3-1. Place the test grid slide in the projector and focus. The projector is to be leveled using the horizontal grid lines. The grid center is then adjusted, using projector base





adjustments, so that it falls on the screen center.

5) Measure 6" grid square projected on screen and adjust projector, if required, so that the grid measures 6 inches square. The Grid is illustrated in Figure 3-4.

6) Finally, assume that all equipment is properly located by checking measurements against Table 3-1 values.

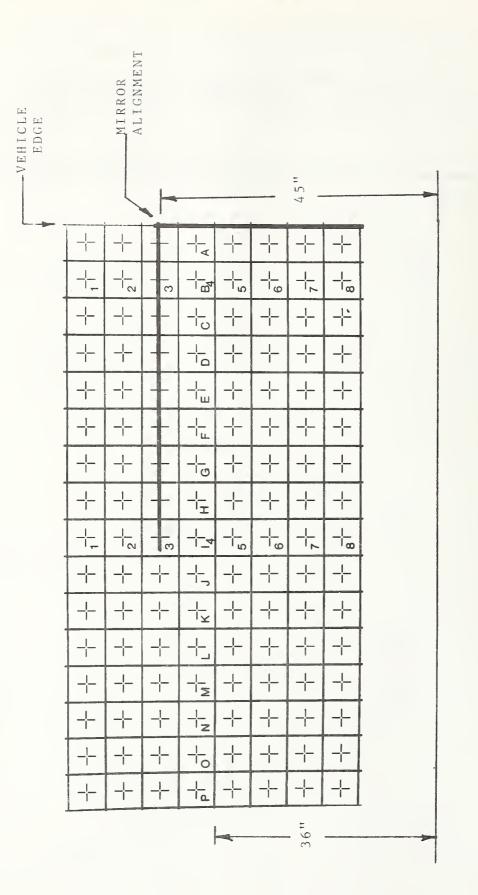


FIGURE 3.4 CHARACTERISTICS MEASUREMENT AND MIRROR ALIGNMENT GRID

4.0 CHARACTERISTICS AND SIMULATED-USE TEST METHODOLOGY AND PROTOCOL

4.0.1 Organization

This section describes the methodology and test protocol for the testing of Rear Vision Device Design Characteristics. Characteristics measured include:

- * Field of View (FOV);
- * Magnification (MAG);
- * Radius of Curvature (ROC);
- * Accommodation Distance (ACC); and
- * Reflectance (REFL).
- 4.1 FIELD OF VIEW (FOV) AND MAGNIFICATION MEASUREMENT (PRELIMINARY STEPS)

Both FOV and Magnification measurements of a rear vision device are made from photographs of the test grid. The procedure and equipment for making photographs is described below.

4.1.1 Equipment

The following equipment is required.

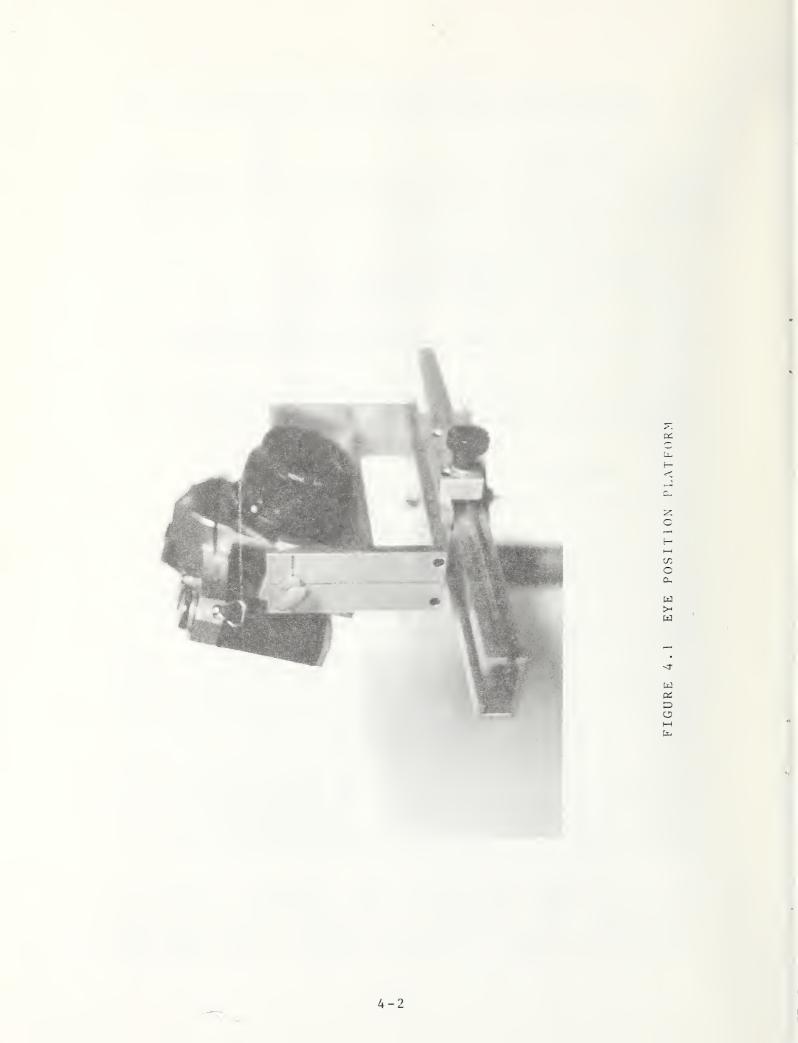
- * Test facility arranged as described.
- * Pentax K1000 SLR Camera with normal 50mm F 1.7 lens.
- * Eye positioning platform (EPP)
- * Test mirror or device.
- * TRI X PAN ASA 400 Film (to be exposed at ASA 800).

4.1.2 Procedure

1. Install EPP (Shown in Figure 4-1), adjust to proper viewing position and level. Install the camera on the EPP and adjust in x, y and z so that the focal plane of the camera is located at the eye position coordinates of Table 3-1. A plumb-line is used to adjust x and y dimensions while z is measured directly.

2. Install mirror at appropriate location. (The procedure described is for a left door mount mirror location). A universal photographic ball-joint and several spacers can be used to attach/adjust the mirror. The front surface of the center of the mirror is to be located as shown in Table 3-1. Other locations, eg. fender, can be used.

3. Adjust camera and rear vision device FOV. With the camera at the appropriate eye location, rotate it horizontally and vertically so that the mirror is in the camera FOV center. Slide the camera to the left eye position (the right eye position is used to align right side



mirrors). While observing the mirror an assistant adjusts the mirror horizontally so that the inner edge of its FOV falls on the inner most grid line representing the vehicle edge. Then adjust the mirror FOV vertically so that the top edge of the mirror views the horizontal grid line 45 inches above the ground. (See Figure 3-1).

4. Tighten mirror adjustment device. It may be desirable to epoxy the mirror adjustment device at this time so that the mirror need not be readjusted for subsequent use.

5. Photograph mirror FOV from left, center and right eye position. Check illumination for camera exposure and F stop. In order to obtain the best-focused print for variable radius of curvature devices several local distances and F stops should be used since depth of field is limited at low levels of illumination and the focal range may be large. It is recommended that several photos be taken so that the single best contrast/focus prints can be used for subsequent analysis. The process is repeated for center and right eye positions by sliding the camera from left to right at 1.25 inch increments from the left eye position.

6. Process film and obtain 8 x 10 or larger enlargements so that the mirror is approximately full scale or larger if desired. These photos are to be used for magnification and FOV measurement.

4.2 FIELD OF VIEW (FOV) MEASUREMENT

4.2.1 Purpose

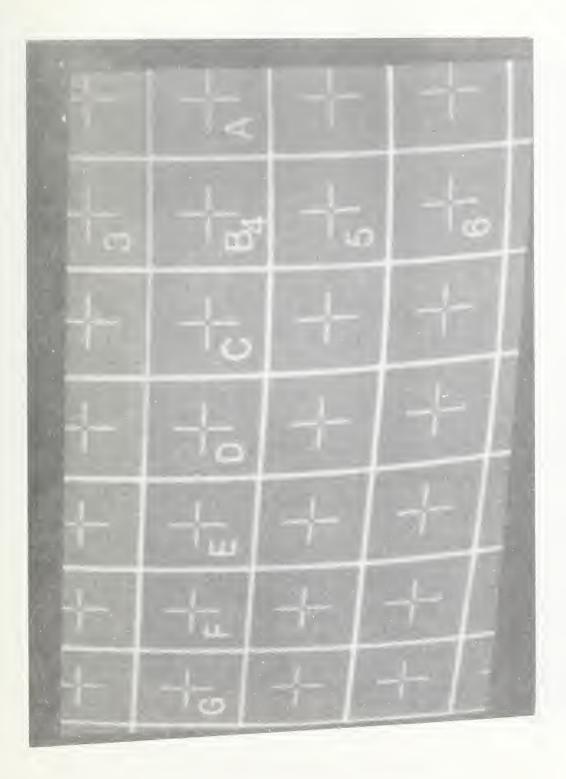
The purpose of FOV measurement is to determine the test rear vision device FOV grid area which is visible to either and/or both eyes.

4.2.2 Equipment

Enlarged photograph of FOV grid for both left and right eye position. (See Figure 4-2 and 4-3)

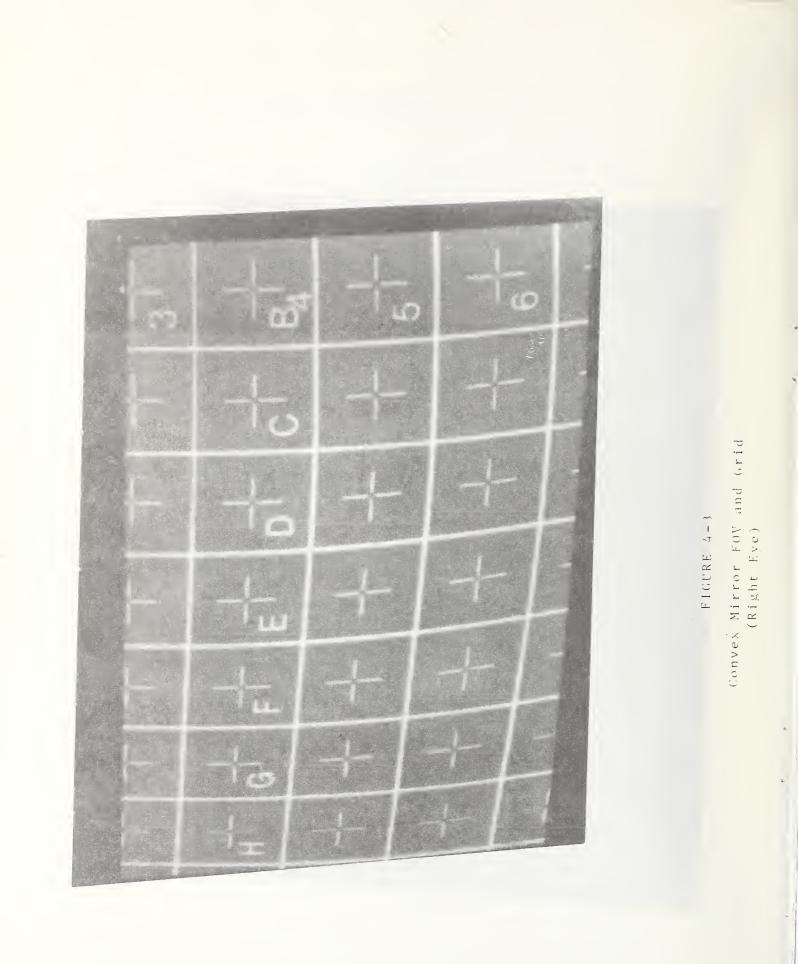
4.2.3 Procedure

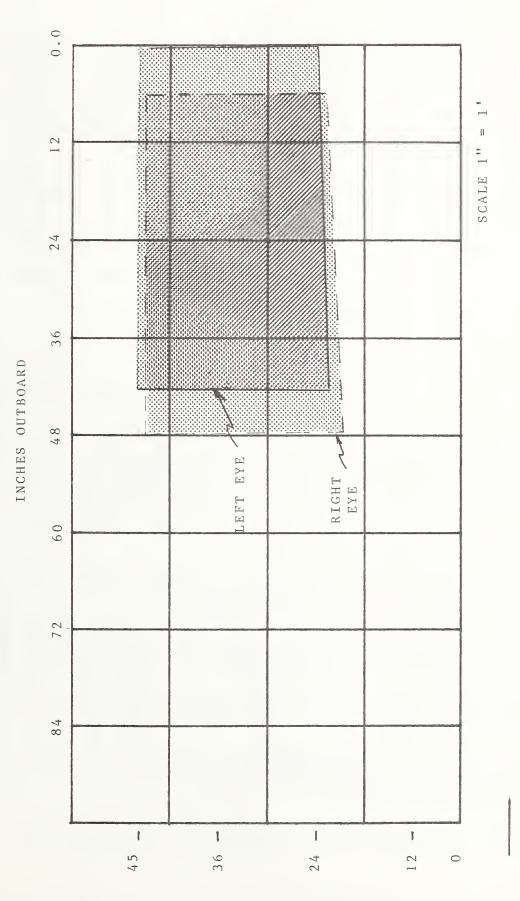
4.2.3.1 Examine left and right eye position photographs of the FOV grid and plot the perimeter of the grid points visible to each eye. See Figure 4-4 for an example.



Convex Mirror FOV and Grid (Left Eye)

F1GURE 4-2





6.5 X 4.0 INCH 40" ROC MIRROR FOV ON DRIVER SIDE FIGURE 4.4

4 - 7

4.3 MAGNIFICATION MEASUREMENT

4.3.1 Purpose

The purpose of magnification measurement is to determine the horizontal and vertical image size of the test rear vision device <u>relative</u> to that of a plane mirror, across the surface of the device. Magnification is the ratio of test device image size, in a specific target grid area viewed, to plane mirror image size in the same viewed grid area.

4.3.2 Equipment

The following equipment is required for magnification measurement:

- * Enlarged photo prints of FOV grid for left and right eye.
- * Magnifier with reticle scaled in .1mm or equivalent increments.
- * Recording forms
- * Tabled values generated for corrections.

4.3.3 Procedure

4.3.3.1 Obtain high-contrast quality 8 x "10 " enlargements of left and right eye photographs of the FOV grid.

4.3.3.2 Measure length of known object (eg. near edge of mirror mounting frame) in photo to the nearest lmm. Determine the ratio of the photo enlargement to actual size (eg. 140mm : 152mm). Determine the appropriate correction (eg. 152/140 = 1.086) to be applied to subsequent measures to correct for photographic image enlargement size discrepancy.

4.3.3.3 Measure the horizontal distance between grid cell vertical lines and the vertical distance between horizontal grid lines, using the magnifier/reticle, to .1mm. Since some devices may present images which are rotated, measures are to be made at the midpoint of the cell, as defined by the cell cross-hair element and along the direction of the element. Repeat horizontal and vertical measures for all cells visible on the photograph for left and right eye positions. Record measurements for each eye and orientation (horizontal and vertical) on a separate recording form (see Form M-1, Table 4-1).

4.3.3.4 Correct measurements on Form M-1 by applying the photo enlargement correction determined in 4.3.3.2 above to bring measures to the proper scale.

4.3.3.5 Relate test mirror image size to plane mirror image size. Magnification of image size of each grid cell for a

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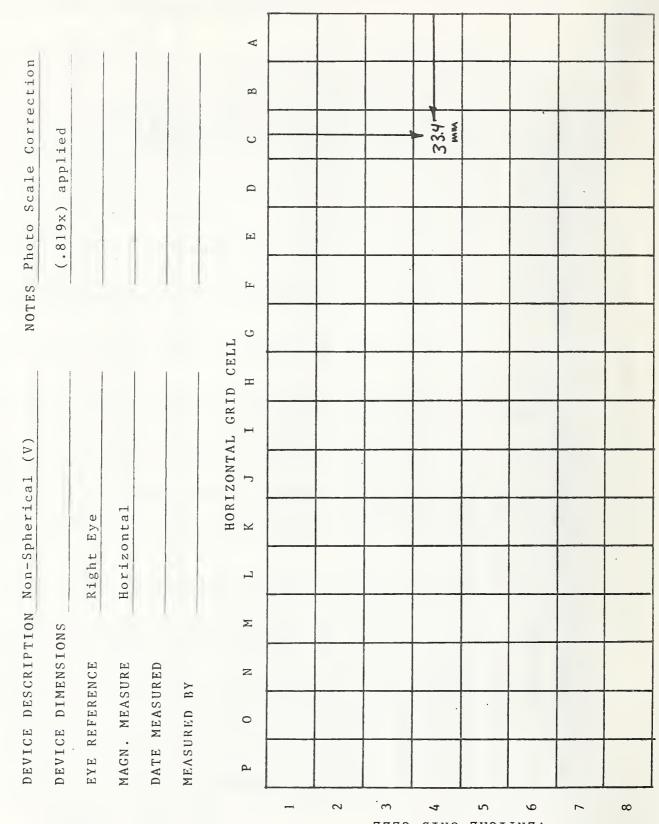
MAGNIFICATION RECORDING FORM (M-1)

TABLE 4.1

AEKTICAL GRID CELL

4 – 9

-Continued
(M-1)
FORM
RECORDING
MAGNIFICATION
4.1
TABLE



NEKTICAL GRID CELL

4-10

DEVICE DIMENSIONS EYE' REFERENCE													
EYE' REFERENCE	IS								(Ratio	of	Test Ce	Cell S	Size
	Ţ	Righ	Right Eye					1	to Plane	ane M	Mirror	Cell	
MAGN. MEASURE		Hori	Horizontal						Size)				
DATE MEASURED													
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MAGNIFICATION RECORDING FORM (M-1) - Continued TABLE 4.1

4 - 1 1

test mirror is expressed relative to the image size of a plane mirror for that same grid cell. Since the image size becomes smaller as a function of the increased viewing distance for further outboard objects (or grid cells), i.e., visual angle subtended by a grid cell decreases at increased viewing angles, the <u>plane</u> mirror image size for each grid cell needs to be determined. Grid cells of a plane mirror, however, beyond B or C, cannot be measured directly, since they are generally not visible in limited plane the mirror FOV. Therefore, they must be calculated.

STEPS

1) First calculate the horizontal visual angle subtended by cell A (see grid) using the viewing distance to the screen via the mirror (eye to mirror plus mirror to screen). This is 92 inches for the left door mount mirror described in tests. The visual angle of cell A is 3.72 degrees.

2) Compute the horizontal visual angle of cells B-P. The visual angle of cell H is 3.00 degrees, for example.

3) Calculate the percent decrease in visual angle for each cell relative to cell A. Cell H, for example, is 80.6 percent of A. Construct a table of decreased horizontal visual angle for each cell for each mirror/eye position geometry of interest.

4) Apply these "corrections" to plane mirror measurements.

If a plane mirror cell A measured 52mm, then the calculated reference image sizes for cells B-P are as shown below;

<u>Cell</u> <u>Location</u>	Corrected Size (mm)
	(left door location)
А	52.0
В	51.7
С	51.2
D	49.6
E	47.8
F	46.1
G	45.0
Н	41.9
٠	•
Р	26.0

Note that the image size of cell P, if it were visible, would be only 50% of that of cell A.

5) Repeat the above procedure for each mirror mounting location since a new plane mirror reference image size

for each device/test location is required.

6) No corrections to vertical cell sizes are necessary if the vertical viewing angle to visible cells is small.

4.3.3.6 Record the results of 4.3.3.5 above on Form M-1, with proper notation as to corrections which have been made in the notes section.

4.3.3.7 Plot magnification on grid paper for left and right eyes for horizontal and vertical grid cell elements.

4.3.3.8 Sample Magnification Measurement

Figure 4-5 illustrates the grid imagery of a non-spherical curved mirror as viewed by the right eye. Grid cell C-4 (C=Vertical, 4= Horizontal) is measured as an example.

Step 1

Measure horizontal and vertical dimensions of cell with magnifier/reticle aligned along the cross-hair element. Both dimensions (H & V) measure 40.8 mm. Enter measures in appropriate cell of form M-1.

Step 2

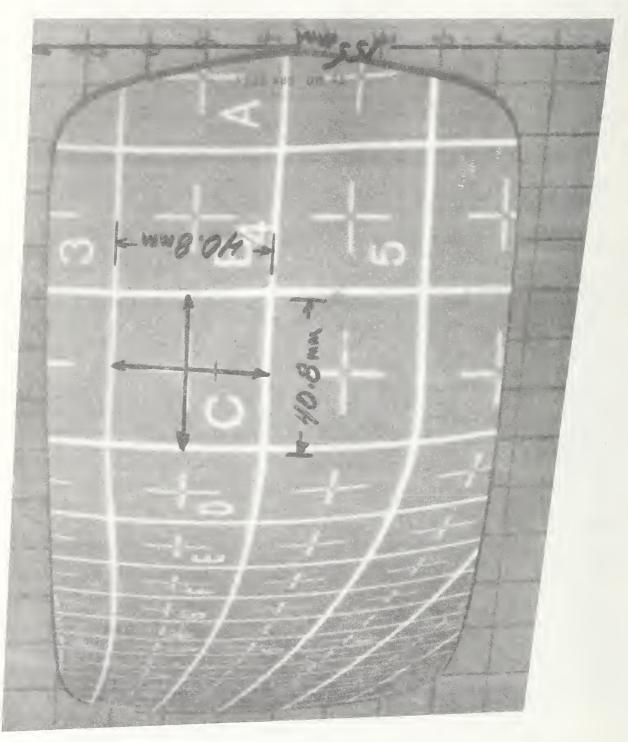
Determine correction for photo enlargement by measuring vertical height of mirror mounting plate at near edge. Vertical height measures 155 mm. The actual vertical height of the plate edge is 5 inches or 127 mm. Thus, the measures in Step 1 are "corrected" by multiplying each by .819 or 127/155. New values of 33.4 mm (H and V) are entered on Form M-1.

Step 3

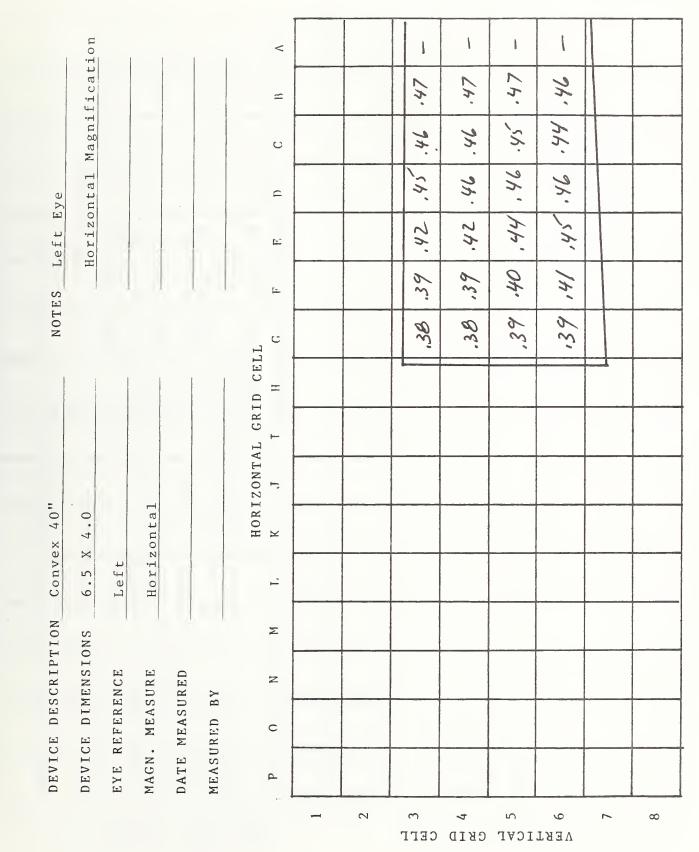
Correct measures above so that they represent the ratio of test mirror image size to plane mirror image size, using values described in 4.3.3.5.

Step 4

Repeat calculations for all grid cells for each eye position (left and right). Tables 4.2-4.5 show the horizontal and vertical magnification for left and right eye positions for each grid cell visible by a 40 inch ROC convex mirror.



MAGNIFICATION MEASURMENT OF MIRROR GRID CELLS FIGURE 4.5



4 - 1 5

TABLE 4.2 MAGNIFICATION RECORDING FORM (M-1)

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ы 4-

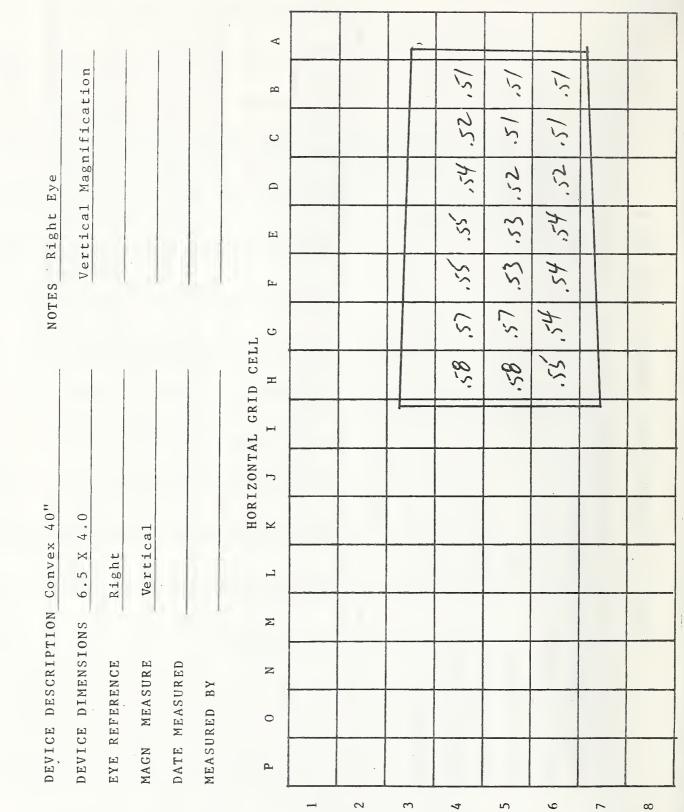
4-16

TABLE 4.3 MAGNIFICATION RECORDING FORM (M-1)

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VERTICAL GRID CELL

4-18

TABLE 4.5 MAGNIFICATION RECORDING FORM (M-1)

4.4 RADIUS OF CURVATURE MEASUREMENT (ROC)

4.4.1 Purpose

The purpose of ROC measurement is to determine the curvature of a test rear vision device across its surface vertically and horizontally at several points so as to describe the radius as a function of horizontal and vertical location across the surface.

4.4.2 Equipment

- * Test rear vision device
- * Sphereometer (Starrett, Model 655-611, See Figure 4-6)
- * Recording forms

4.4.3 Procedure

4.4.3.1 Determine the horizontal and vertical center of the device image surface. Then, using an appropriate marking device eg. grease pencil, draw vertical and horizontal lines at .5 inch increments across the surface in the horizontal and vertical dimensions. Trace the outline of the mirror onto Form R-1 to illustrate measurement coordinates (see Table 4.6).

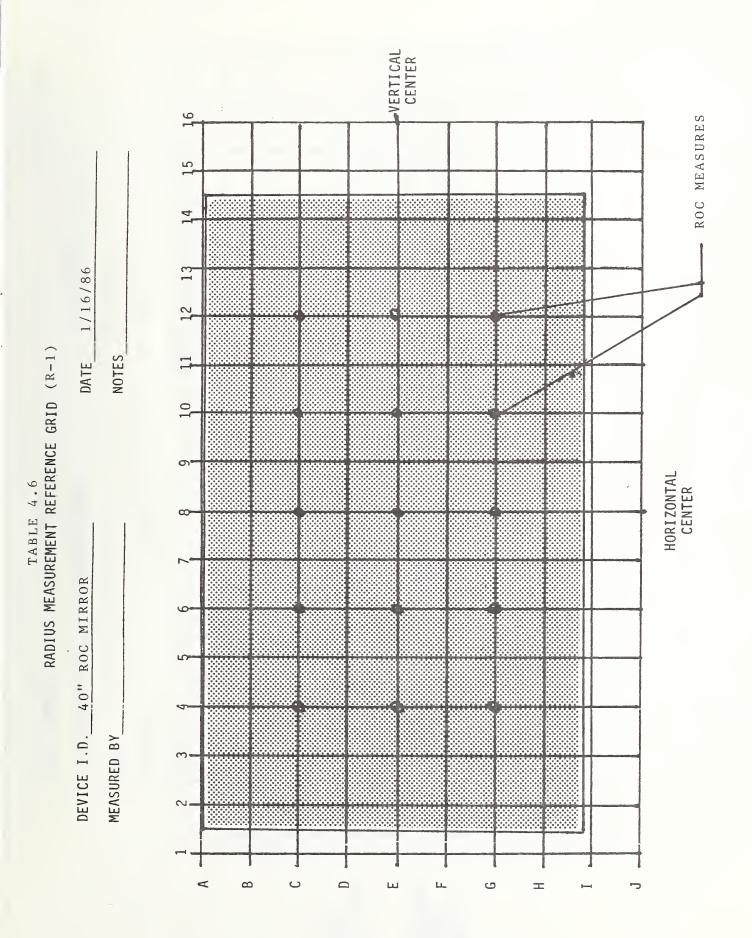
4.4.3.2 Determine the sphereometer "zero" reading for a known flat surface obtaining a dial reading, eg.1508 inch. Record this reading on Form R-2 (see Table 4-7) to be used later to correct subsequent dial readings.

4.4.3.3 Measure ROC of test device. Carefully place the measuring post of the sphereometer on the device surface at the intersection of each of the horizontal and vertical lines, keeping the exterior posts along the vertical line to measure vertical curvature and along the horizontal line to measure horizontal curvature.

When the sphereometer is in place, read the dial to .0001 inch and record in the appropriate cell of Form R-2. Take a dial reading measurement vertically and horizontally at the intersection of each vertical/horizontal line drawn on the surface. Record all dial readings.

4.4.3.4 Correct dial readings by subtracting the "zero" correction dial reading from 4.1.3.2 above from each vertical and horizontal dial reading on Form R-2. Record the results on Form R-2 with correction notations (see Table 4.8)





4 - 2 1

TABLE 4.7 RADIUS MEASUREMENT FORM (R-2)

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	5											X 40"			ATION	ctual)
	4			1783								CONVEX 40"			TYPE MEASURE/CALCULATION Uncorrected	dial reading (Actual)
	e											I.D.	D BY	1	ASURE/	readir
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					VERTICAL	GRID INTERSECTION										

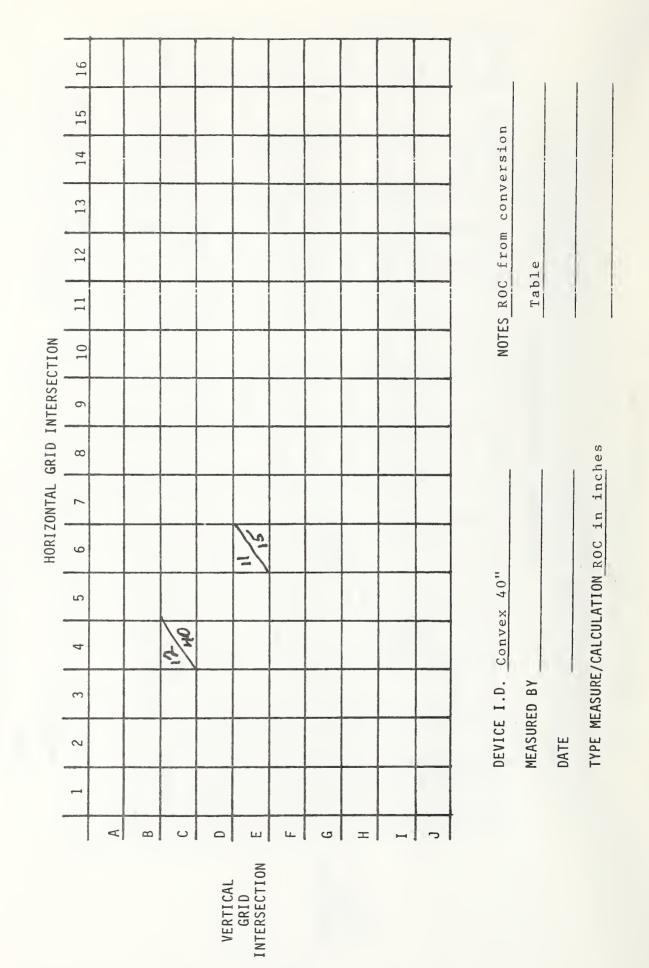
4 - 2 2

16 (Dial Reading in .0001) NOTES Correction of -.1560 15 14 13 12 applied 11 HORIZONTAL GRID INTERSECTION 10 б 00 TYPE MEASURE/CALCULATION "Corrected" \sim 189 9 26-CONVEX 40" ഹ 2233 4 Dial Reading DEVICE I.D. MEASURED BY ŝ DATE \sim ---0 ш \triangleleft æ ں L 5 . I I C l l -1 VERTICAL GRID INTERSECTION

RADIUS MEASUREMENT/FORM((R-2) TABLE 4.8

4 - 2 3

TABLE 4.9 RADIUS MEASUREMENT FORM (R-2)



4

4 - 24

4.4.3.5 Determine the ROC for each dial reading using values of Table 4.12 and record on Form R-2 (see Table 4.9) with appropriate notation.

4.4.3.6 Plot ROC for horizontal and vertical measures for each (H-V) location position measured. Tables 4.10 and 4.11 show the horizontal and vertical radius measurements (in inches) across the surface of a 40 inch ROC convex mirror.

TABLE 4.10 RADIUS OF CURVATURE MEASUREMENT FORM

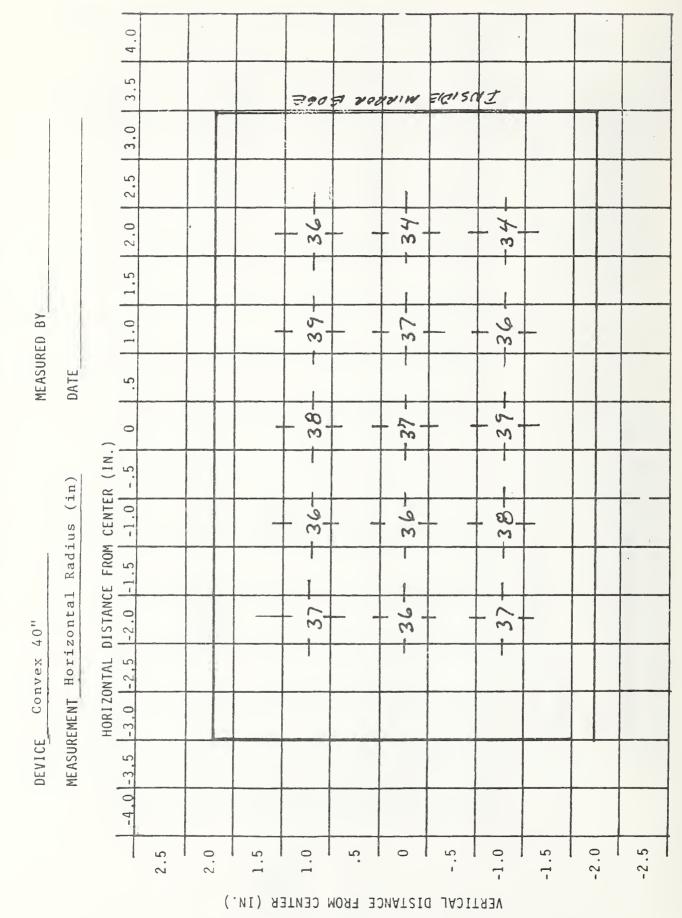


TABLE 4.11 RADIUS OF CURVATURE MEASUREMENT FORM

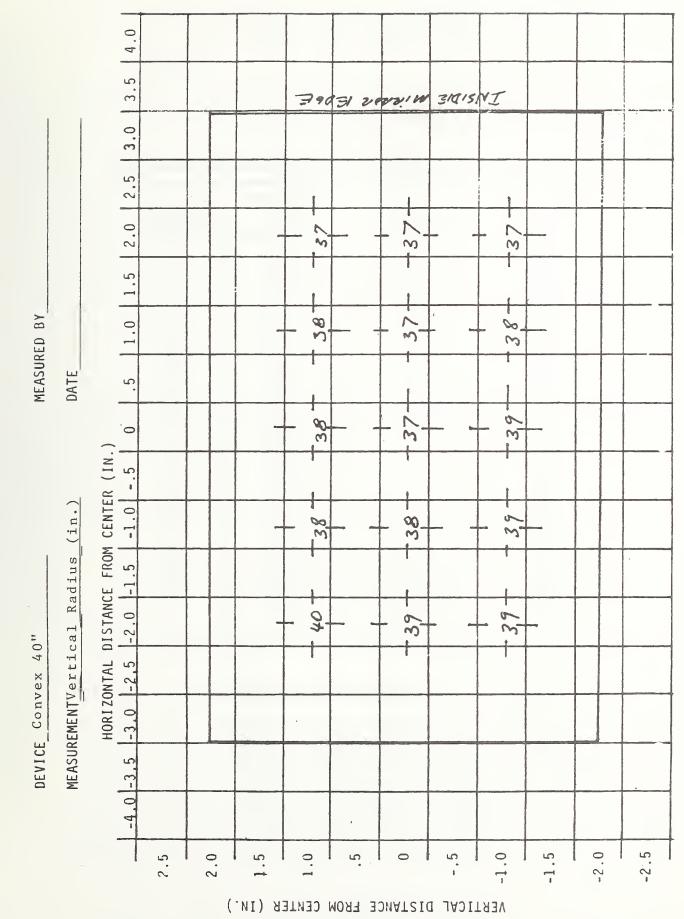


TABLE 4.12CONVERSION FROM DIAL READING TO
ROC (Adapted from FMVSS 111)

TABLE I-CONVERSION TABLE FROM SPHEROM-ETER DIAL READING TO RADIUS OF CURVA-TURE

_

Dial reading	Radius of curvature (in inches)
.00330	85.2
.00350	80.4
.00374	75.2
.00402	70.0
.00416	67.6
.00432	65.1
.00450	62.5
.00468	60.1
.00476	59.1
.00484	58.1
.00492	57.2
.00502	56.0
.00512	54.9
.00522	53.9
.00536	52.5
.00544	51.7
.00554	50.8
.00566	49.7
.00580	48.5
.00592	47.5
.00606	46.4
.00622	45.2
.00636	44.2
.00654	43.0
.00668	42.1
.00686	41.0
.00694	40.5
.00720	39.1
.00740	38.0
.00760	37.0
.00760	36.1
.00802	35.1
.00822	34.2
.00850	33.1
.00878	32.0
.00906	31.0
.00922	30.5
.00938	30.0
.00960	29.3

TABLE I---CONVERSION TABLE FROM SPHEROM-ETER DIAL READING TO RADIUS OF CURVA-TURE---Continued

Dial reading	Radius of curvature (in inches)
.00980	28.7
.01004	28.0
.01022	27.5
.01042	27.0
.01060	26.5
.01080	26.0
.01110	25.3
.01130	24.9
.01170	24.0
.01200	23.4
.01240	22.7
.01280	22.0
.01310	21.5
.01360	20.7
.01400	20.1
.01430	19.7
.01480	19.0
.01540	18.3
.01570	17.9
.01610	17.5
.01650	17.1
.01700	16.6
.01750	16.1
.01800	15.6
.01860	15.1
.01910	14.7
.01980	14.2
.02040	13.8
.02100	13.4
.02160	13.0
.02250	12.5
.02340	12.0
.02450	11.5
.02560	11.0
.02660	10.5
.02810	10.0
.02960	9.5
.03130	9.0
.03310	8.5
.00010	0.0

4.5. ACCOMMODATION DISTANCE DETERMINATION

4.5.1 Purpose

Accommodation distance is the nearest distance from the eye to an object at which the image can be brought into focus on the retina. The accommodation distance to a mirror is the distance from the eye to the focal point or plane. The procedure for calculating the required accommodation distance is described below for plane and curved mirrors.

4.5.2 Method

4.5.2.1 Plane Mirrors

Accommodation demand for a plane mirror image is equal to eye-mirror-object distance. Since other vehicles to be viewed are generally at a distance greater than 2-3 meters, the limit for the population of older drivers, accommodation to plane mirror images is generally of little interest.

4.5.2.2. Curved Mirrors

Accommodation demand for curved mirrors, however, is considerably less being the eye-mirror distance plus the mirror focal distance. Calculation of accommodation demand differs for spherical and non-spherical mirrors.

4.5.2.2.1 Spherical Mirrors

The accommodation distance for spherical mirrors is approximated by the formula: $D_{\rm ACC}$ = $D_{\rm EM}+$ 1/2 R

 D_{ACC} = Accommodation Distance Where D_{EM} = Eye to Mirror distance, R = Mirror radius curvature

For example, the required accommodation distance for a 40 inch ROC spherical mirror located 32 inches from the eye is 32 + 20 = 52 inches.

4.5.2.2.2 Non-Spherical Curved Mirror

Non-spherical curved mirrors, by definition, have a different radius of curvature across the mirror surface and thus require varying accommodation distances. The accommodation distances can be approximated by using the formula of 4.5.2.2.1 above, given the specific ROC of the surface upon which the viewed image is located. For example, a non-spherical curved mirror whose surface ROC ranges from (flat) to 6 inches at a 32 inch distance to the eye would require accommodation over a range from 64 to 35 inches.

4.6 REFLECTANCE MEASUREMENT

4.6.1 Purpose

The purpose of reflectance measurement is to determine the percentage incident light reflected from the surface of a rear view mirror.

4.6.2 <u>Method</u>

The method used to measure reflectance is SAE Standard J964a--Test Procedure for Determining Reflectivity of Rear View Mirrors. The procedure involves the use of a 1) standardized collimated light source, 2) photo receptor and 3) reflectance meter reading percent reflectance. Curved mirrors require the use of an integrating sphere.

4.6.3 Results

In order to verify the method, one non-spherical curved mirror, known as the "Mahon" mirror was tested by the Donnelly Corporation. The reflectance standard used is traceable to NBS Standard 2003C. The mirror reflectance was found to be 48.4 percent \pm 0.7 based upon the NBS Standard accuracy of \pm .5 percent.

5.0 CHARACTERISTICS MEASUREMENT SUMMARY

5.1 Summary of All Measures

The measurement characteristics of four mirrors, mounted on left and right side door locations are presented in Table 5.1. Detailed measures for all mirrors are presented in Appendix A. Measures include 1) physical size, 2) Field of View, 3) Magnification, 4) Radius of Curvature, and 5) Accommodation Distance. Horizontal FOV is expressed in degrees as well as lateral outboard distance visible. FOV is correlated with Simulated-use Figure of Merit scores described in Volume II.

5.2 Radius of Curvature

Figure 5.1 illustrates the horizontal radius of curvature of the four mirrors across their surface. All radii shown are referenced to the horizontal center of each mirror.

5.3 Magnification

Figure 5.2 illustrates, for the non-spherical (V) mirror, the magnification of each grid cell for left and right eye locations. Magnification or image size difference between the two eyes is at its maximum in horizontal grid cell "D". Images in this grid cell are approximately 40% narrower when viewed by the left eye relative to that viewed by the right eye. Fusing these two disparate images into a single clear image was at best difficult and impossible for many mirror users. Left/right eye image size differences for other mirrors tested were small.

SUMMARY OF MEASURED MIRROR CHARACTERISTICS
MIRROR
MEASURED
OF
SUMMARY
TABLE 5.1

** \	CURVED	HdS-NON	4.0 X 6.5	RT DOOR	72" (42) 15"-22"	.0660 .5065	6"-60" 28"-71"	51-78"	TBD
** \	CURVED	HdS-NON	4.0 X 6.5	LT DOOR	78" (49) 18" - 30"	.0660	6"- 60" 28"-71"	35-62"	TBD
40" ROC	CURVED	SPHER	4.0 X 6.5	RT DOOR	36" (20) 19"	0.43 0.53	37" 37"	68"	TBD
40" ROC	CURVED	SPHER	4.0 X 6.5	LT DOOR	48" (31) 23"	0.43 0.53	37" 37"	52"	TBD
PLANE	FLAT	FLAT	4.0 X 6.5	RT DOOR	14" (7) 9"		1 1		TBD
PLANE	FLAT	FLAT	4.0 X 6.5	LT DOOR	* 22.5" (14)** 12"	1	1 1		TBD
NAME	TYPE	SPEC. CHARACT.	SIZE (IN.)	MOUNT LOCAT.	FIELD OF VIEW * HORIZ. 22 VERT.	MAGNIFICATION HORIZ. VERT.	RADIUS HORIZ. VERT.	ACCOM. DIST.	REFLECTANCE

* AT 60" BEHIND MIRROR SURFACE

** APPROXIMATE FOV IN DEGREES

5 – 2

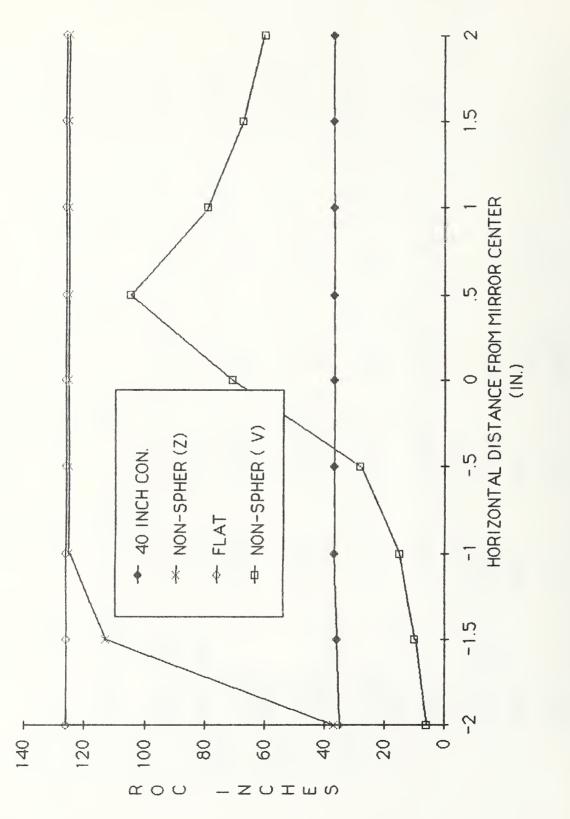
SUMMARY OF MEASURED MIRROR CHARACTERISTICS (CONTINUED) TABLE 5.1

K	FLAT/CURV.	FLAT/SPHER	3.7 X 4.1 /	RT DOOR	36" 36"	1.0/.13 1.0/.13	10" 10"	53"	TBD
20"ROC	CURVED	SPHER	3.6 X 4.4	RT DOOR	38" 27"	0.24 0.24	20" 20"	58"	TBD
"Z"	CURVED	H4S-NON	3.5 X 6.5	RT DOOR	24" (15) 9"	.2798 .5794	30"-FLAT 37"-FLAT	63-96"	TBD
"Zщ	CURVED	HdS-NON	3.5 X 6.5	LT DOOR	* 31" (23) 11"	** .2798 .5794	30"-FLAT 37"-FLAT	47-96"	TBD
NAME	TYPE	SPEC. CHAR.	SIZE	MOUNT LOC.	FIELD OF VIEW * HORIZ. VERT.	MAGNIFICATION ** HORIZ. VERT.	RADIUS HORIZ. VERT.	ACCOM. DIST.	REFLECTANCE

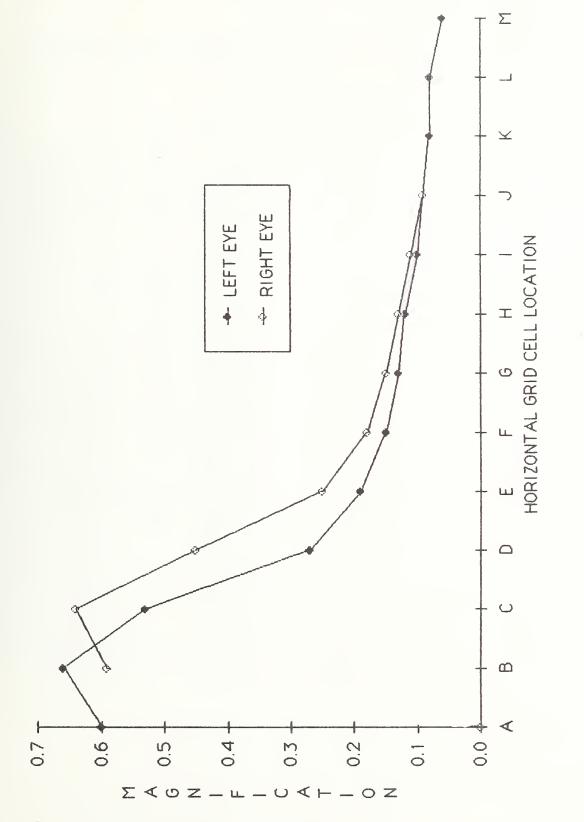
5-3

AT 60" BEHIND MIRROR SURFACE

*







LEFT AND RIGHT EYE HORIZONTAL MAGNIFICATION FOR ALL GRID CELLS FIGURE 5.2

5-5



APPENDIX A. RESULTS OF CHARACTERISTICS MEASUREMENTS

Characteristics measurements are presented in subsequent pages for the following mirrors; A-1. 4.0 x 6.5 inch flat mirror a. left door mount b. right door mount A-2. 4.0 x 6.5 inch 40 inch ROC spherical convex mirror a. left door mount b. right door mount A-3. 4.0 x 6.5 inch non-spherical curved (V) mirror a. left door mount b. right door mount 3.5 x 6.5 inch non-spherical curved (Z) mirror A-4. a. left door mount b. right door mount A-5. 4.4 x 6.6 inch 20 inch ROC convex mirror a. right door mount

A-6. 4.1 x 3.7 inch plane / 2.0 x 3.7 inch 10 inch ROC spherical convex (K) mirror

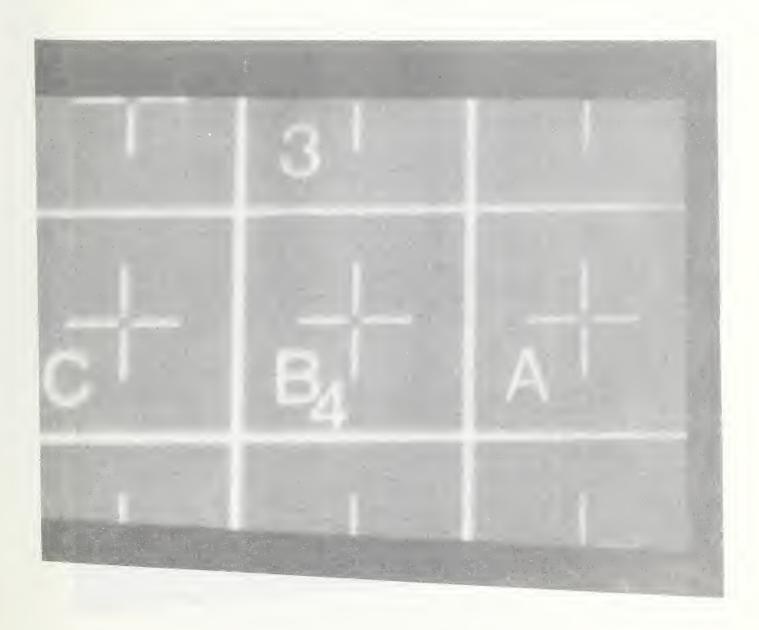
a. right door mount

A-1 DEVICE; 4.0 X 6.5 INCH FLAT MIRROR

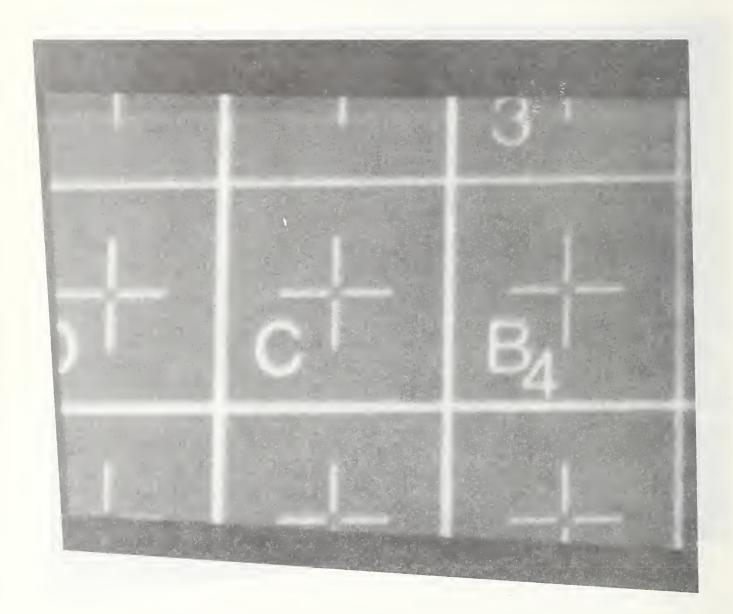
- A-1.1 LOCATION; LEFT DOOR MOUNT
 - A. GRID PHOTOS
 - LEFT EYE
 RIGHT EYE
 - B. FIELD OF VIEW
 - LEFT EYE/RIGHT EYE

 a. horizontal
 b. vertical
 - C. MAGNIFICATION (none)
 - D. RADIUS OF CURVATURE (none)
 - E. ACCOMMODATION
 - F. REFLECTANCE

GRID PHOTO, PLANE MIRROR, LEFT DOOR MOUNT, LEFT EYE



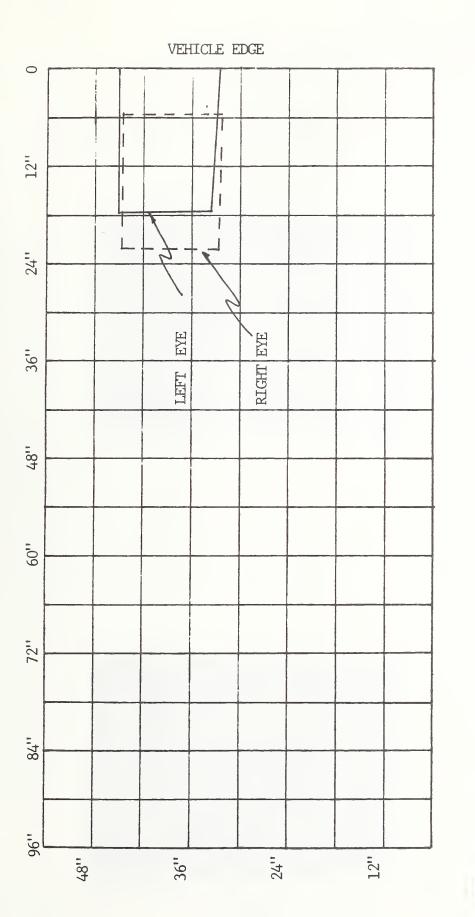
GRID PHOTO, PLANE MIRROR, LEFT DOOR MOUNT, RIGHT EYE



PLANE MIRROR FOV, LEFT DOOR MOUNT (LEFT AND RIGHT EYE)

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SCALE: 1"=1'

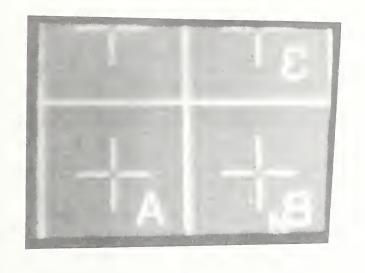
GROUND =0

A-5

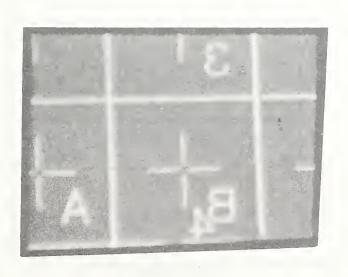
A-1.2 LOCATION; RIGHT DOOR MOUNT

- A. GRID PHOTOS
 - 1. RIGHT EYE 2. LEFT EYE
- B. FIELD OF VIEW
 - LEFT EYE/RIGHT EYE
 a. horizontal
 - b. vertical
- C. MAGNIFICATION (none)
- D. RADIUS OF CURVATURE (none)
- E. ACCOMMODATION
- F. REFLECTANCE (see left door mount data)

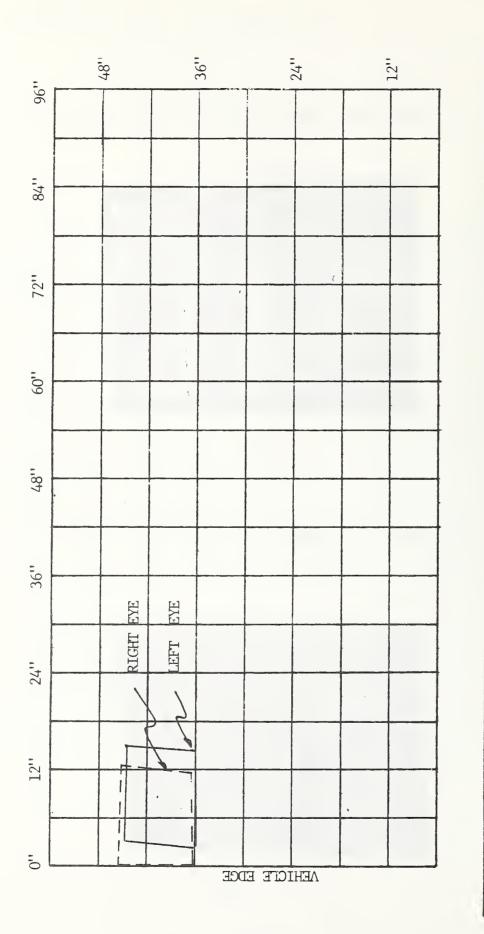
GRID PHOTO, PLANE MIRROR, RIGHT DOOR MOUNT, RIGHT EYE



GRID PHOTO, PLANE MIRROR, RIGHT DOOR MOUNT, LEFT EYE



PLANE MIRROR FOV, RIGHT DOOR MOUNT (RIGHT AND LEFT EYE)



GROUND =0

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SCALE 1"=1'

A.2 DEVICE; 4.0 X 6.5 INCH, 40 INCH ROC SPHERICAL MIRROR

A-2.1 LOCATION; LEFT DOOR MOUNT

A. GRID PHOTOS

LEFT EYE
 RIGHT EYE

B. FIELD OF VIEW

LEFT EYE/RIGHT EYE

 a. horizontal
 b. vertical

C. MAGNIFICATION

1. HORIZONTAL
 a. left eye
 b. right eye

2. VERTICAL
 a. left eye
 b. right eye

D. RADIUS OF CURVATURE

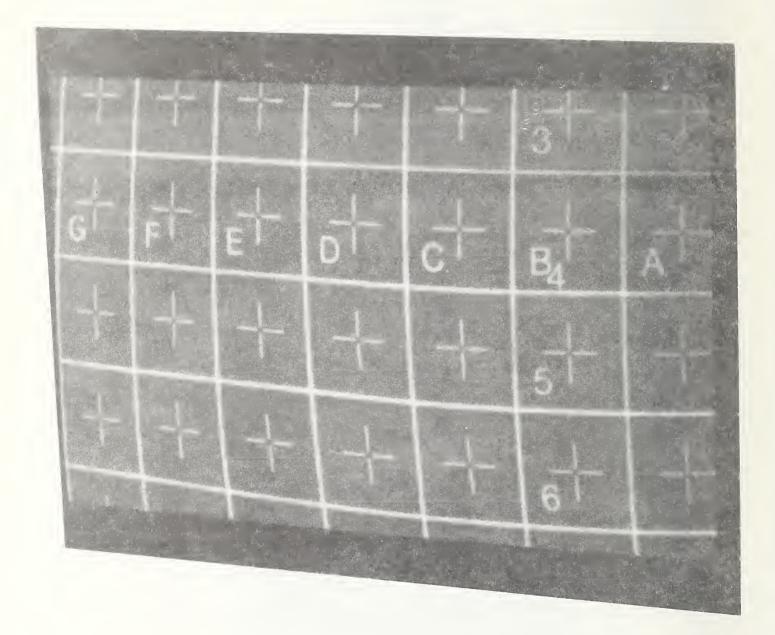
1. HORIZONTAL

2. VERTICAL

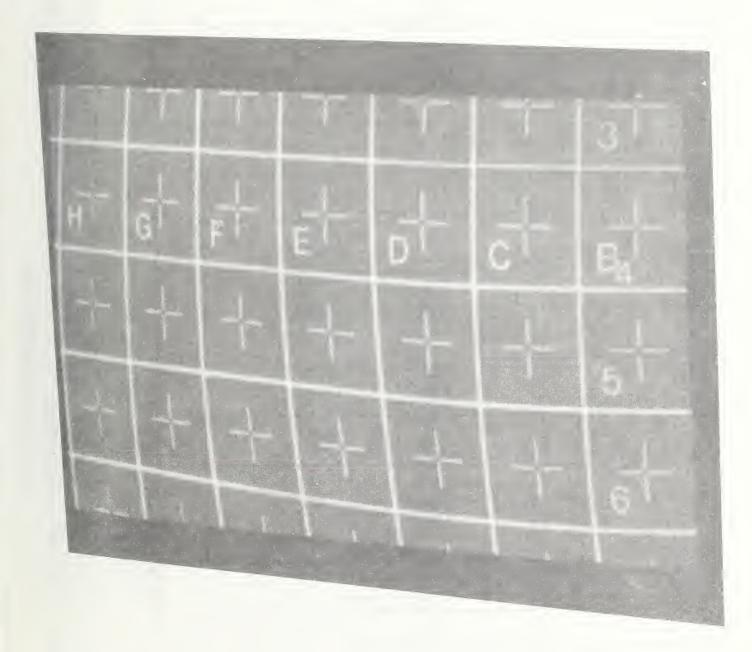
E. ACCOMMODATIONS DISTANCE

F. REFLECTANCE

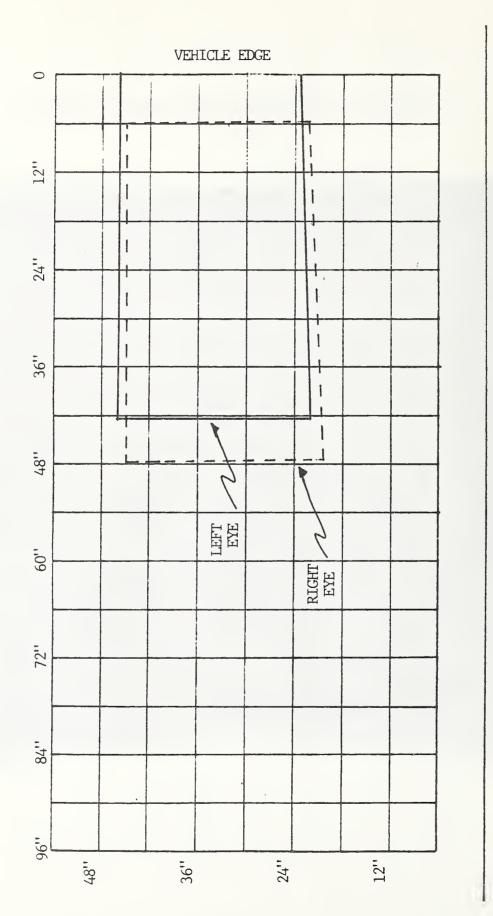
GRID PHOTO, 40" ROC MIRROR, LEFT DOOR MOUNT, LEFT EYE



GRID PHOTO, 40" ROC MIRROR, LEFT DOOR MOUNT, RIGHT EYE



40" ROC MIRROR FOV, LEFT DOOR MOUNT (LEFT AND RIGHT EYE)



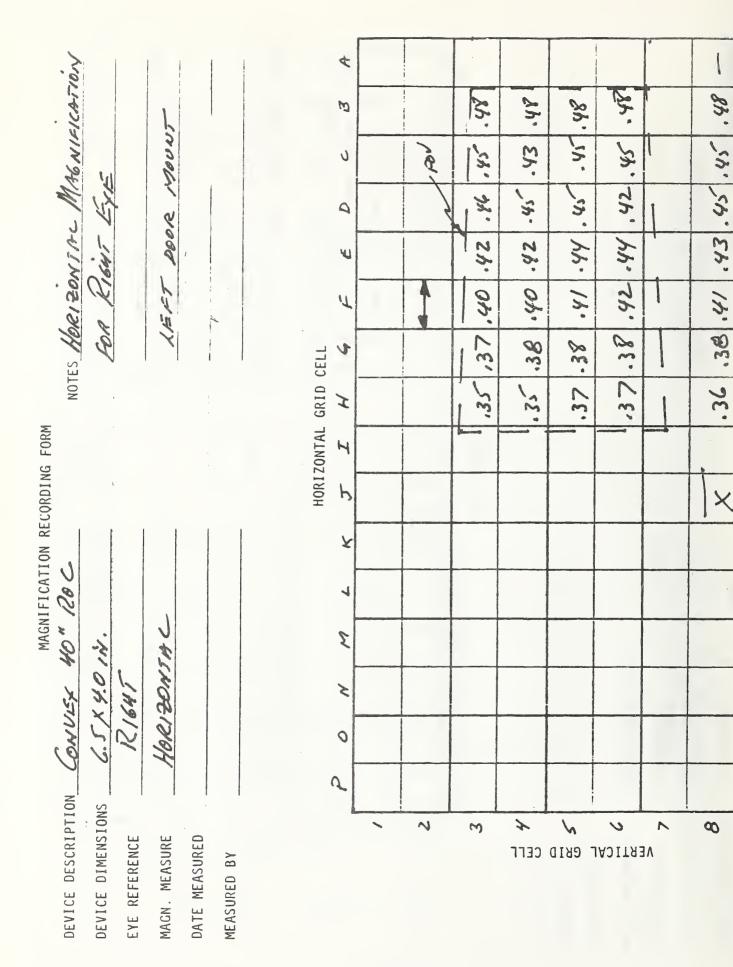
SCALE: 1''=1'

e

2

GROUND =0

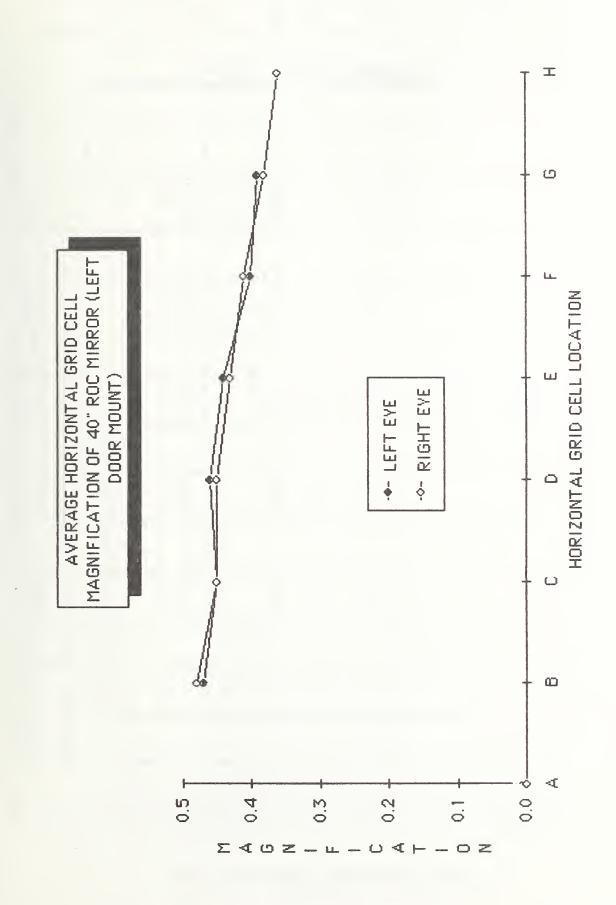
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FORM			:		HORIZONTAL GRID CELL								J×
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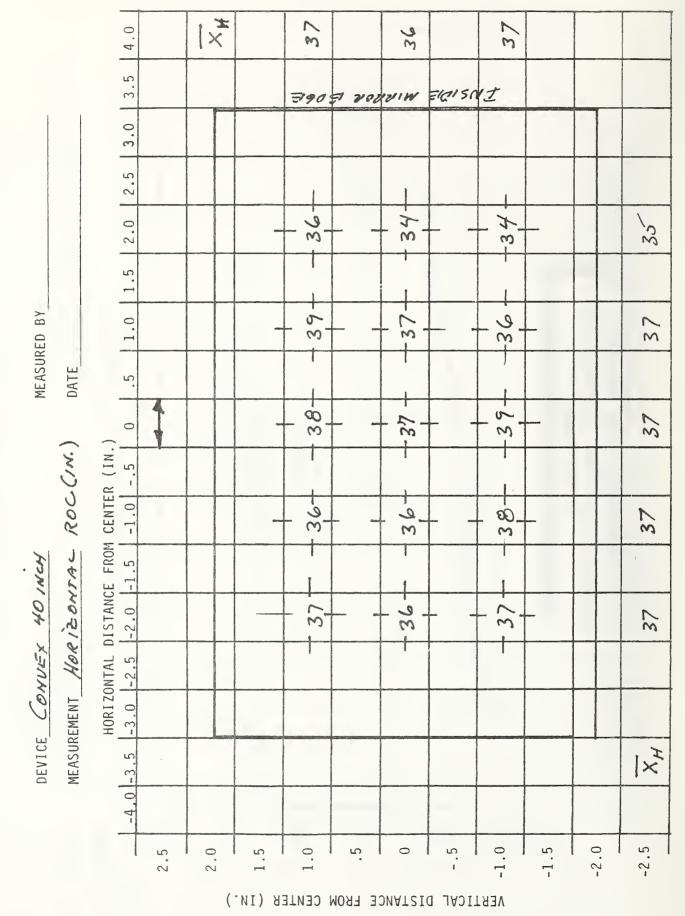
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ORDING FORM NOTES VERTICAC MAGNIFICATION	FOR RIGHT EYE		LEET DOOR HOUNT			HORIZONTAL GRID CELL	JIHGFEDC3A	1 401		1.58 .57 ,55 .55 .54 .52 .51 -	- 12. 12. 53. 53. 52. 52.	- 12. 12 .54 .54 .54 .52 .51 -	15. 12. 52. 42. 42. 52. 52. X
DEVICE DESCRIPTION CONVEY 40" 20C	DEVICE DIMENSIONS 6.5×4.0 12.	EYE REFERENCE RIGUT	MAGN. MEASURE USERICAC	DATE MEASURED	MEASURED BY		PONMLK	~	3		GRID		0



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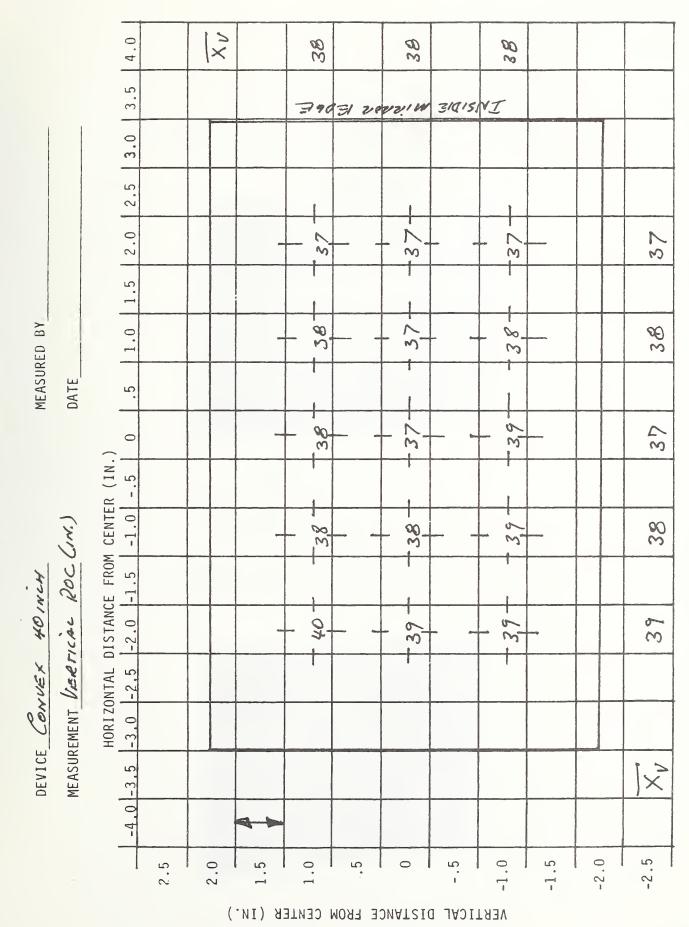
RADIUS OF CURVATURE MEASUREMENT FORM



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RADIUS OF CURVATURE MEASUREMENT FORM



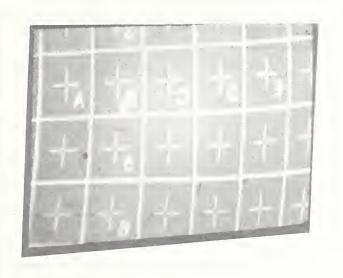
A-2.2 LOCATION; RIGHT DOOR MOUNT

- A. GRID PHOTOS
 - LEFT EYE
 RIGHT EYE
- B. FIELD OF VIEW
 - LEFT EYE/RIGHT EYE

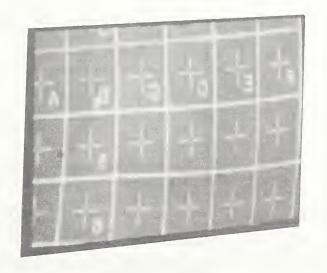
 a. horizontal
 b. vertical
- C. MAGNIFICATION
- HORIZONTAL

 a. left eye
 b. right eye
- 2. VERTICAL a. left eye b. right eye
- D. RADIUS OF CURVATURE (See left door mount data)
- E. ACCOMMODATIONS DISTANCE
- F. REFLECTANCE (See left door mount data)

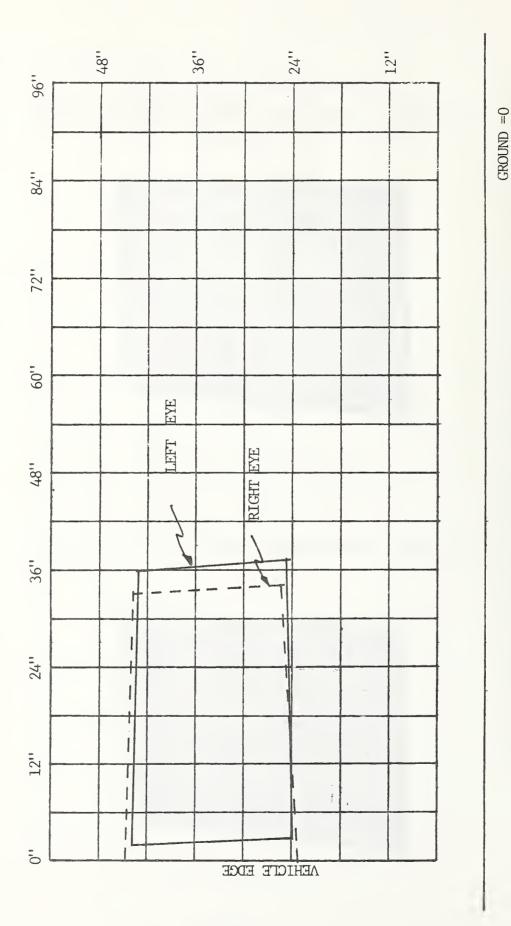
GRID PHOTO, 40 " ROC MIRROR, RIGHT DOOR MOUNT, RIGHT EYE



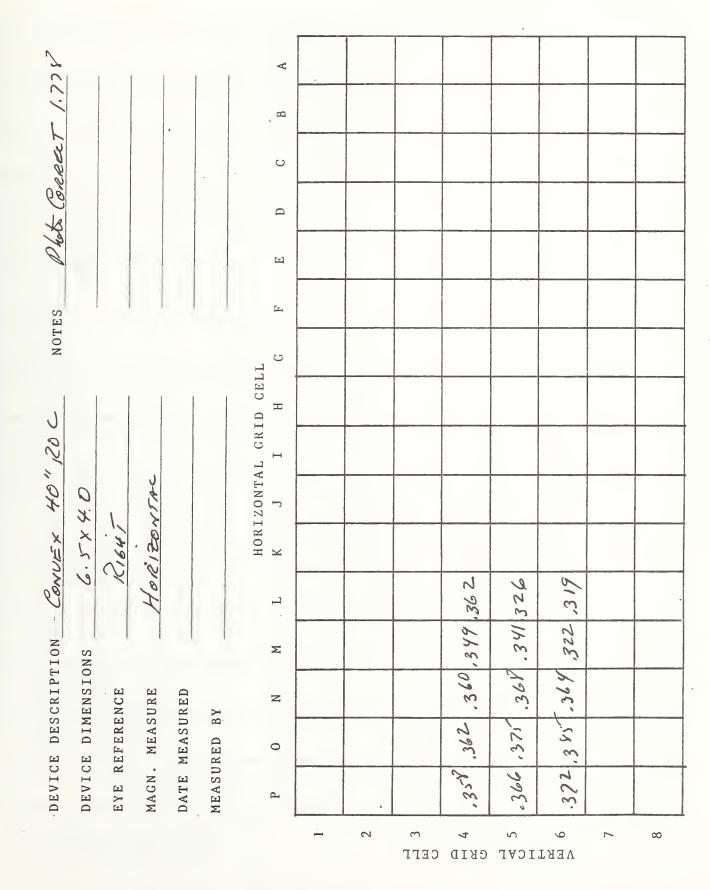
GRID PHOTO, 40 " ROC MIRROR, RIGHT DOOR MOUNT, LEFT EYE

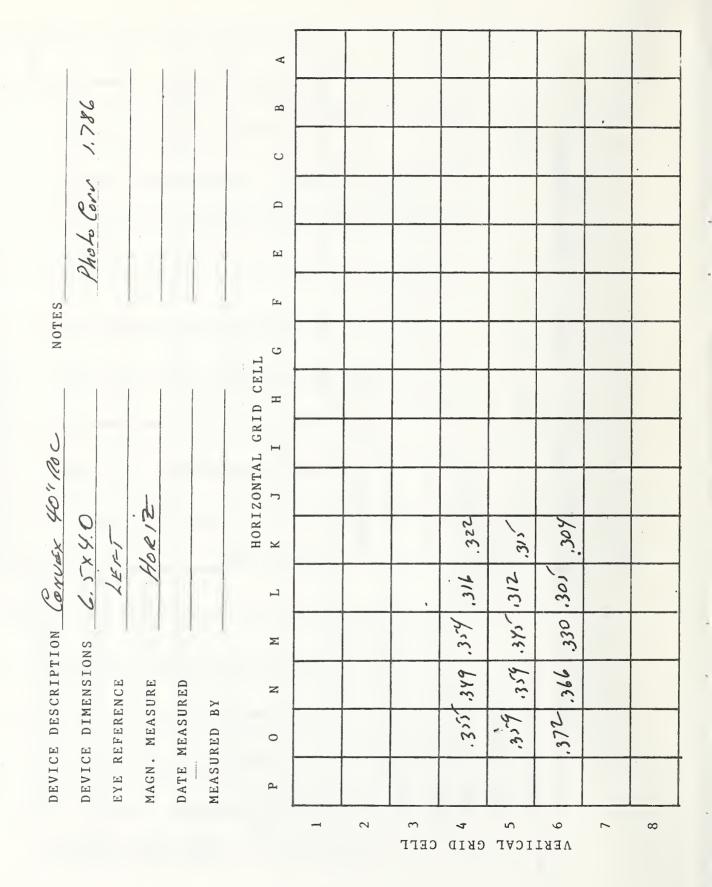


40" ROC SPHERICAL MIRROR FOV, RIGHT DOOR MOUNT (LEFT AND RIGHT EYE)



SCALE 1"=1'





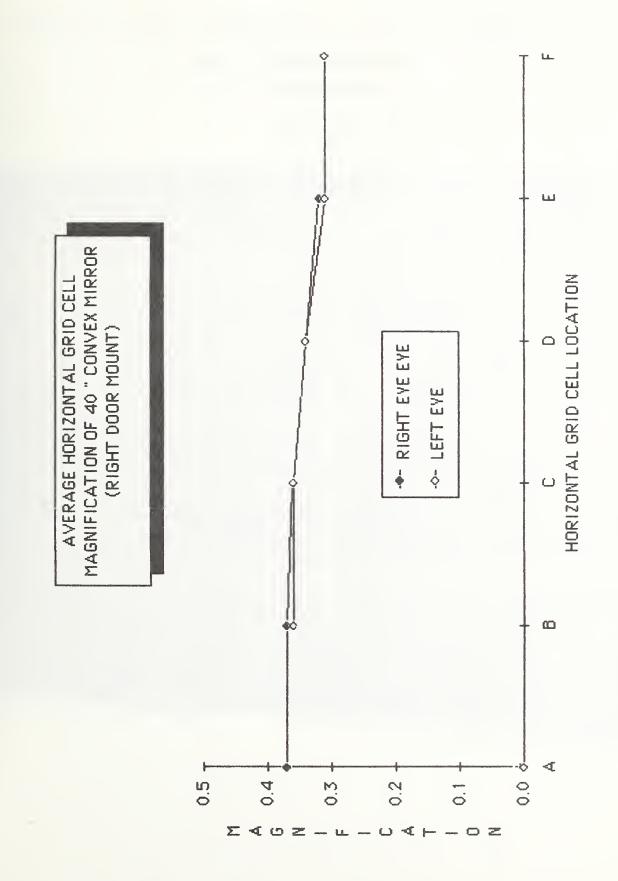
R Photo Cor 1,728 B C Q [±] ſ. NOTES and the second Ċ HORIZONTAL GRID CELL DEVICE DESCRIPTION CONVEX 40" R C Н Η 6.5×4.0 1/ERACUE È RIGUT 83 4. Kat. 144. 124. 174. Ken. 446 .459 .461 .474 .490 .493 Х Ц Σ DEVICE DIMENSIONS EYE REFERENCE MAGN. MEASURE DATE MEASURED Z MEASURED BY o` JYY. ρ. Ś 9 4 ω , nine 2 c \sim CEFF GKID VERTICAL

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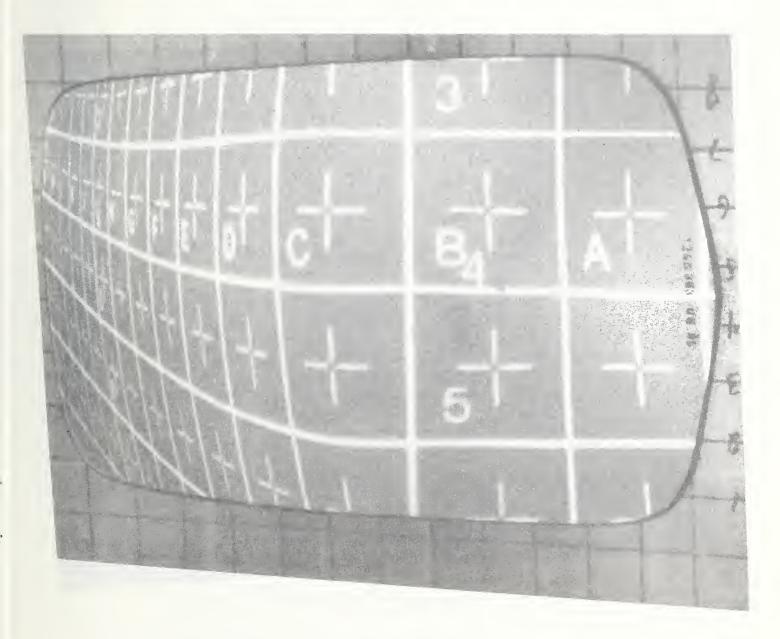
A – 27

A-3 DEVICE; 4.0 X 6.5 NON-SPHERICAL/CURVED (V) MIRROR

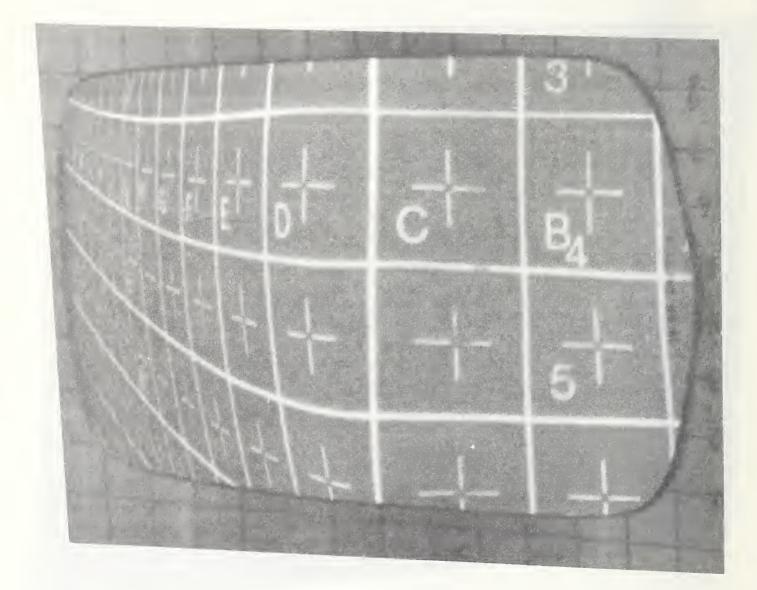
- A-3.1 LOCATION; LEFT DOOR MOUNT
 - A. GRID PHOTOS
 - 1. LEFT EYE
 - 2. RIGHT EYE
 - B. FIELD OF VIEW
 - LEFT EYE/RIGHT EYE
 a. horizontal
 b. vertical
 - C. MAGNIFICATION
 - HORIZONTAL

 a. left eye
 b. right eye
 - 2. VERTICAL
 a. left eye
 b. right eye
 - D. RADIUS OF CURVATURE
 - 1. HORIZONTAL
 - 2. VERTICAL
 - E. ACCOMMODATIONS DISTANCE
 - F. REFLECTANCE

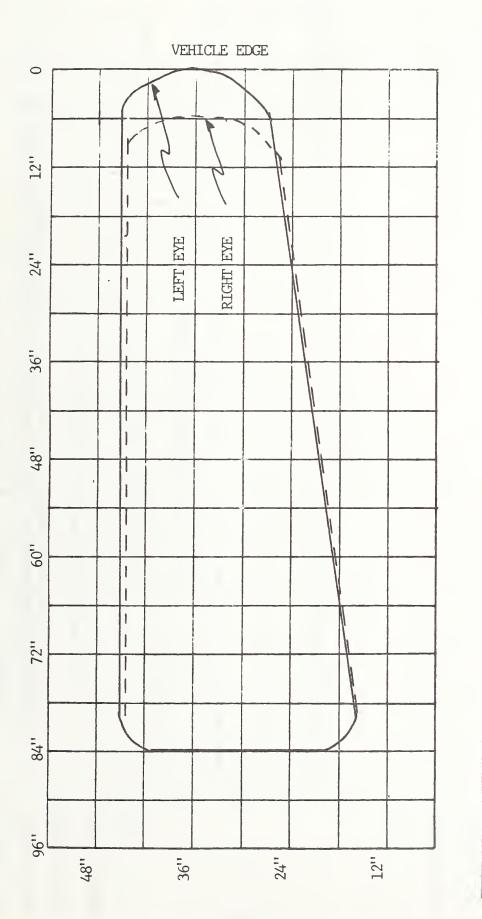
GRID PHOTO, NON-SPHERICAL/CURVED MIRROR, LEFT DOOR MOUNT, LEFT EYE



GRID PHOTO, NON-SPHERICAL/CURVED (V) MIRROR, LEFT DOOR MOUNT, RIGHT EYE



NON-SPHERICAL/CURVED (V) MIRROR FOV, LEFT DOOR MOUNT (LEFT AND RIGHT EYE)



SCALE: 1"=1'

GROUND =0

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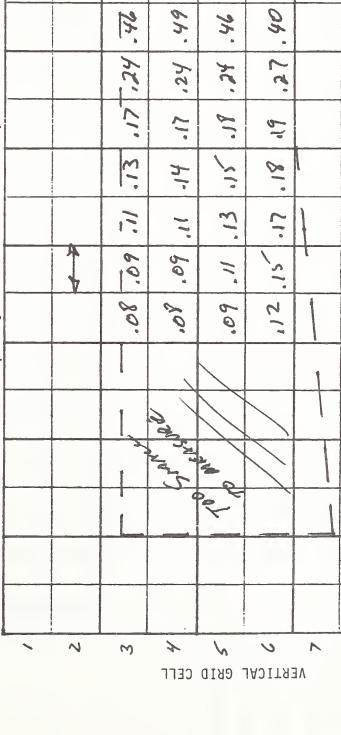
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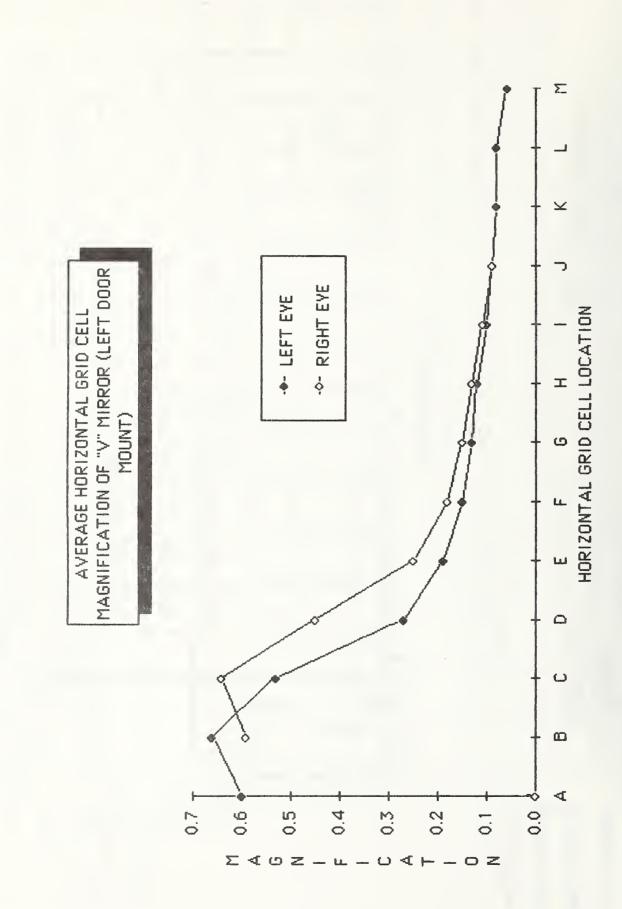
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NOTES VERTICAL MAGNIFICATION 4 Į .62 62. 3 Ŋ LEIET DOUR MOUNT 12. 65. 42. 10. 1 ,65 FOR RIGHTEYE J .65 .65 1 S. 9 ,62 l Y . 53 09. .53 .53 .59 19. L 200 .53 .54 .52 .55 5 HORIZONTAL GRID CELL 2 .53 I .54 MAGNIFICATION RECORDING FORM .51 .50 .52 .53 12. 49. 47. 47 .49 .51 H .52.54 .52 .54 5 2 DEVICE DESCRIPTION NON-SPHERICE (CORVER Y Ŗ 25. 64. 4 94. 15. 6.5X4.0 IN. 3 VERTICAC Rieur ک 0 2 X DEVICE DIMENSIONS イ 5 ~ 0 ~ 5 2 3 EYE REFERENCE MAGN. MEASURE DATE MEASURED VERTICAL GRID CELL MEASURED BY



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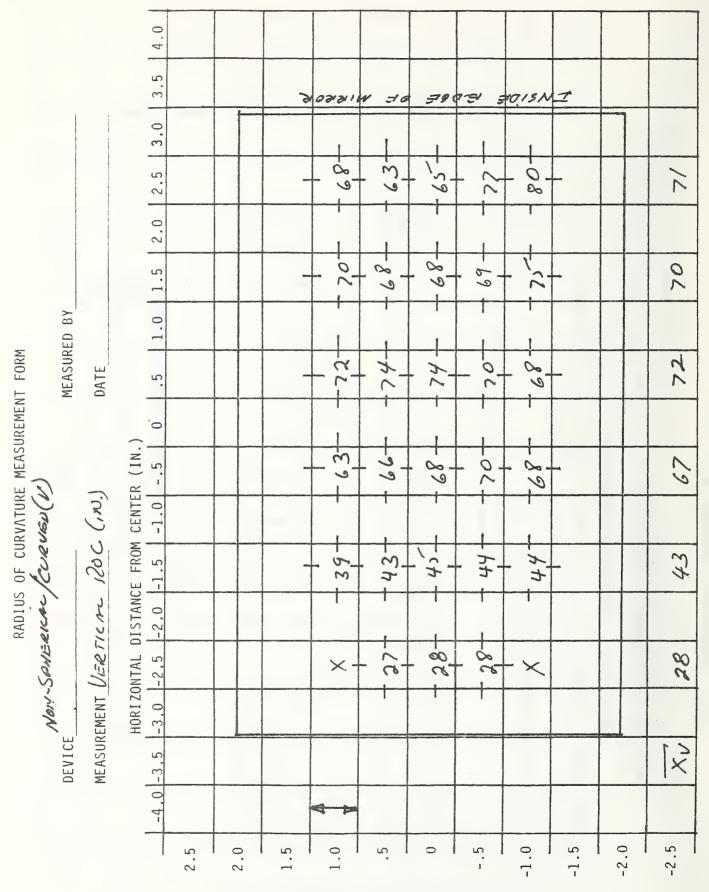
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VERTICAL DISTANCE FROM CENTER (IN.)

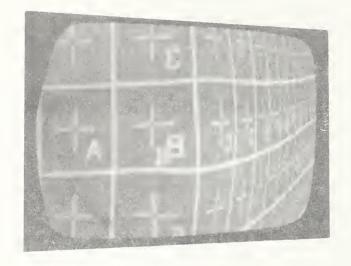
A-3.2 LOCATION; RIGHT DOOR MOUNT

- A. GRID PHOTOS
 - LEFT EYE
 RIGHT EYE
- B. FIELD OF VIEW
 - LEFT EYE/RIGHT EYE

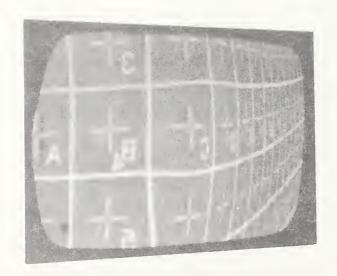
 a. horizontal
 b. vertical
- C. MAGNIFICATION
 - HORIZONTAL

 a. right eye
 b. left eye
 - 2. VERTICAL
 a. right eye
 b. left eye
- D. RADIUS OF CURVATURE (See left door mount data)
- E. ACCOMMODATIONS DISTANCE
- F. REFLECTANCE (See left door mount data)

GRID PHOTO, NON-SPHERICAL/CURVED (V) MIRROR, RIGHT DOOR MOUNT, RIGHT EYE

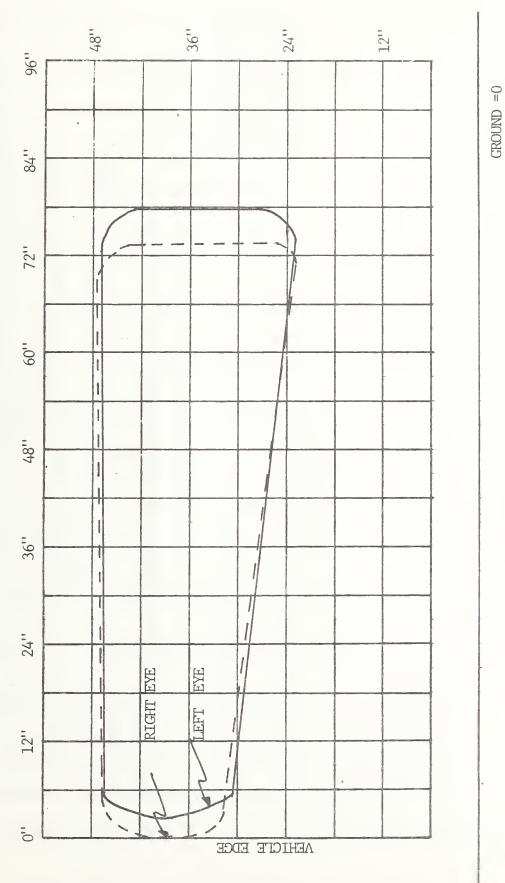


GRID PHOTO, NON-SPHERICAL/CURVED (V) MIRROR, RIGHT DOOR MOUNT, LEFT EYE



NON-SPHERICAL/CURVED (V) MIRROR FOV, RIGHT DOOR MOUNT (RIGHT AND LEFT EYE)

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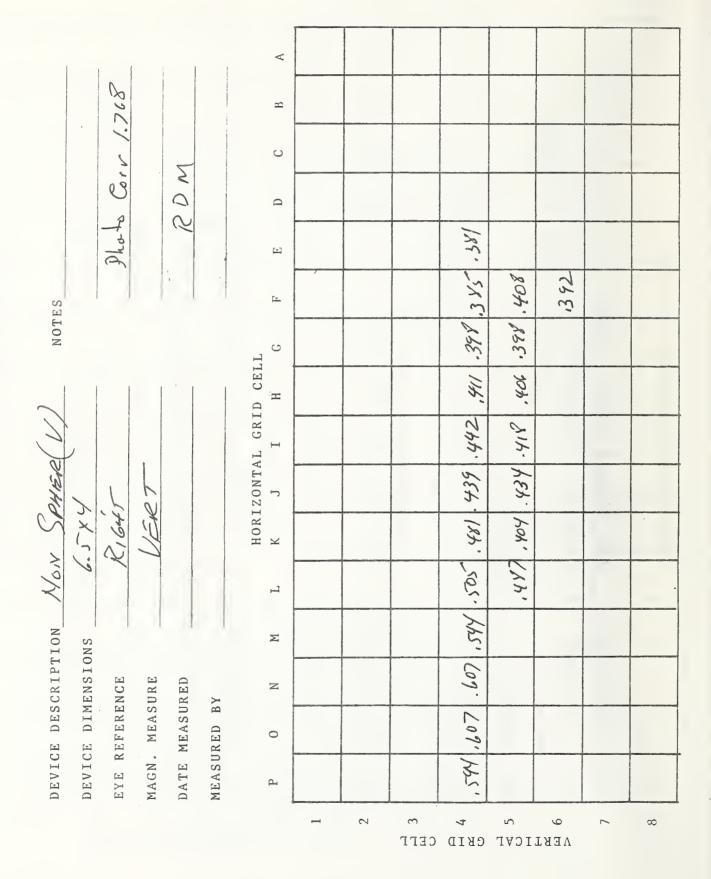


SCALE 1"=1"

A Phats Cove 1.768 В C ND 2 240' -150. .039 Ω 420, 820. 867. 669, 990 038 .033 150. 250. [1] 420 140. [240. [240. [200. Ē NOTES 150' 150. 090.060 c HORIZONTAL GRID CELL Н .003 620. 280. Н DEVICE DESCRIPTION NON SHER (V) 190. .066 Г 6.5×4.0 102 580' 40212 .417 .1 42 .096 .093 LEFT М 411. .199 .131 Г 415-173 Σ DEVICE DIMENSIONS 10%. EYE REFERENCE MAGN. MEASURE DATE MEASURED Z MEASURED BY 542 15-49 195. 0 ٩ 2 e 4 Ś 9 ~ ----- ∞ CELL GKID VERTICAL

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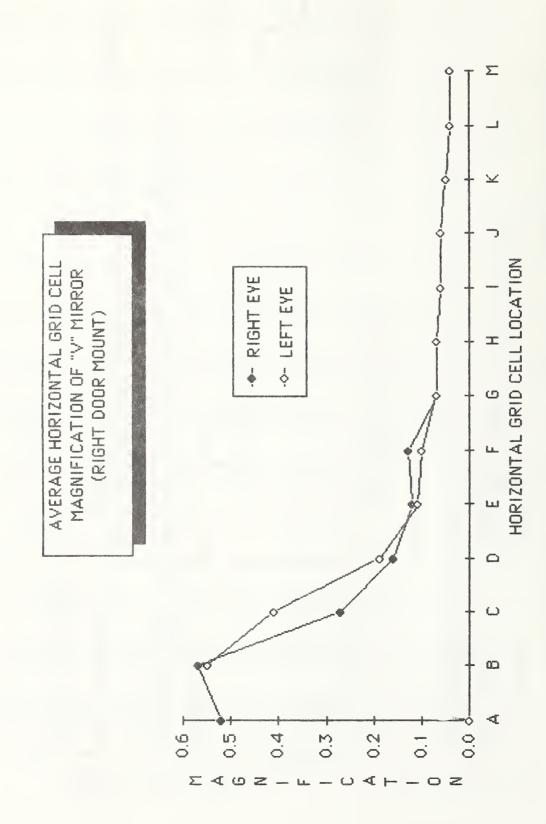
¥, . В 1.768 C RDM Ω Yes. 850. 939. 53P . M EED. 140. [240. ۲<u>ـ</u> .052 220. 250. 480 Г NOTES 120. c HORIZONTAL GRID CELL 840. .068 140. 820. Non SPHER (V) Н (10) 190' 50. Н <02. 135 .068 1357.071 ſ CHXJ? 40212 1(164] (17. × 201. 111. 091. 096. (6): 051 111. 012. DEVICE DESCRIPTION Σ DEVICE DIMENSIONS 522, 575, 252 EYE REFERENCE MAGN. MEASURE DATE MEASURED Z MEASURED BY 255 yes. 0 ١ \ Ы e 2 4 Ś 9 ~ ∞ _ **AEKTICAL GRID CELL**



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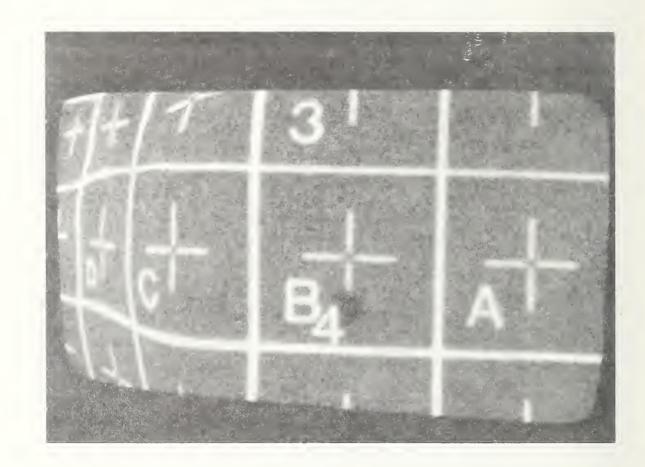
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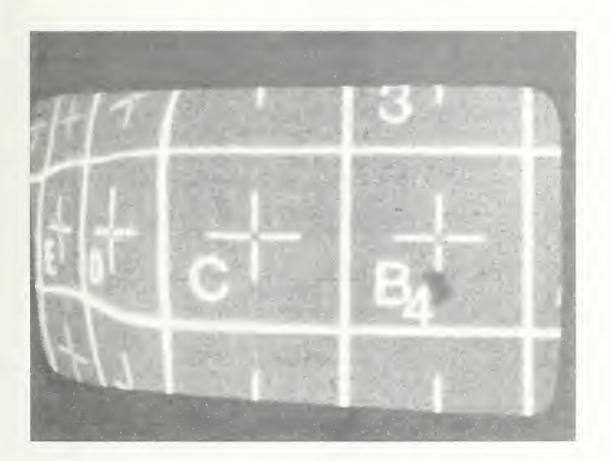
A-4 DEVICE; 3.5 X 6.5 INCH NON-SPHERICAL/CURVED (Z) MIRROR

- A-4.1 LOCATION; LEFT DOOR MOUNT
 - A. GRID PHOTOS
 - LEFT EYE
 RIGHT EYE
 - B. FIELD OF VIEW
 - LEFT EYE/RIGHT EYE
 a. horizontal
 b. vertical
 - C. MAGNIFICATION
 - 1. HORIZONTAL
 a. left eye
 b. right eye
 - 2. VERTICAL
 a. left eye
 b. right eye
 - D. RADIUS OF CURVATURE
 - 1. HORIZONTAL
 - 2. VERTICAL
 - E. ACCOMMODATION DISTANCE
 - F. REFLECTANCE

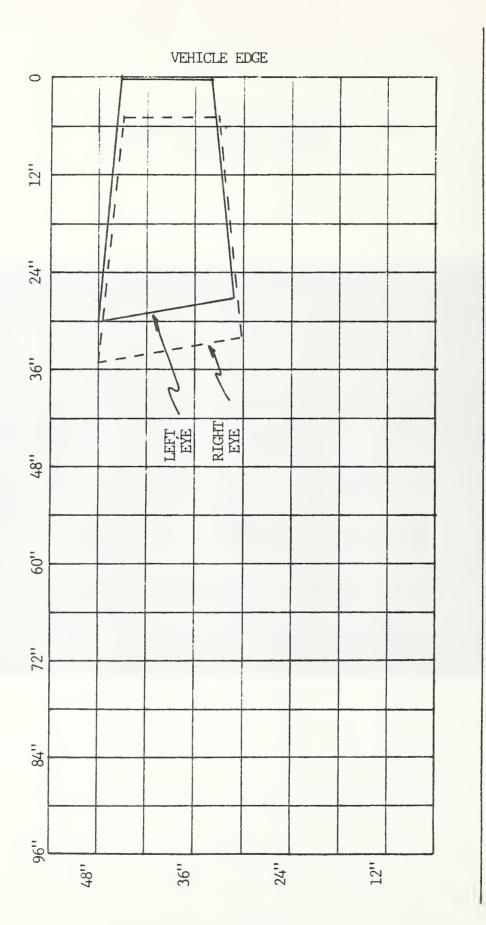
GRID PHOTO, NON-SPHERICAL/CURVED MIRROR (Z), LEFT DOOR MOUNT, LEFT EYE



GRID PHOTO, NON-SPHERICAL/CURVED MIRROR (Z), LEFT DOOR MOUNT, RIGHT EYE



NON-SPHERICAL/CURVED (Z) MIRROR FOV, I.EFT DOOR MOUNT (LEFT AND RIGHT EYE)



SCALE: 1"=1'

GROUND =0

79. 79. 80. 86. 62. NOTES HORIZONTAC MAGNICICATION ٢ ¢ 142 .97 .97 L +132 -54 -67 ß .65 ŝ, HEFT LOOR MOUNT 0 Par LEFT EYE .26 .27 9 ч 4 L \mathbf{D} 5 X HORIZONTAL GRID CELL Z Non-Someria MAGNIFICATION RECORDING FORM H Ь Y 1 6.5 X 3.5 1N HORIZONTAC 2 LEFT Σ 0 2 DEVICE DESCRIPTION DEVICE DIMENSIONS 2 7 ~ 5 0 0 3 ~ EYE REFERENCE MAGN. MEASURE DATE MEASURED VERTICAL GRID CELL MEASURED BY

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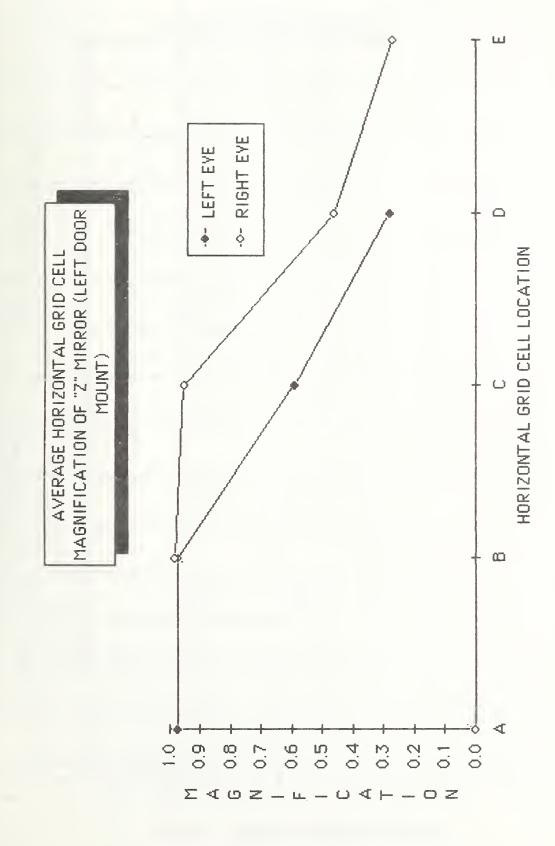
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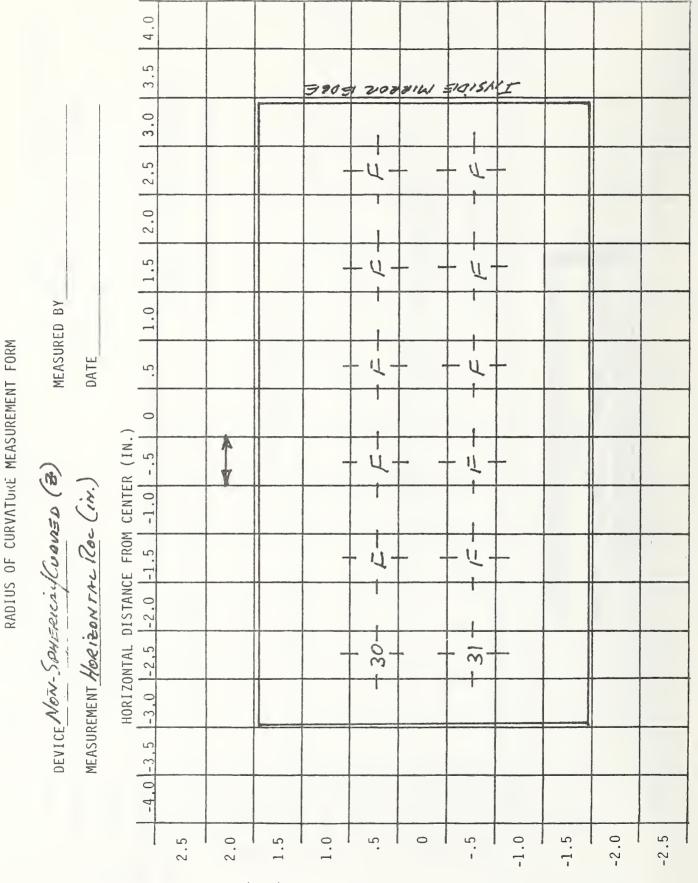
NOTES HORIZON 1AC MAGNICICATION 4 98. 86. 59. 34. CC. ŋ 0 EFT LOOR MOUNT .95 J FOR RIGHT EYE 47. 25 .45 9 L .35 22 Y L 4 5 HORIZONTAL GRID CELL × I MAGNIFICATION RECORDING FORM H Ь (h) Y DEVICE DESCRIPTION NON SOMERICA CORNED 4 HORIZONIAC 2 DEVICE DIMENSIONS 6.5×3.5/3. ک RIGHT 0 2 N 1 5 5 00 ~ N 3 DATE MEASURED EYE REFERENCE MAGN. MEASURE VERTICAL GRID CELL MEASURED BY

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.93 .57 .60 .89 1.93 .93 ¢ 1 .93 m NOTES VERTICAC MAGNIFICATION -nno/~ pozi. . 89 0 FOR LEET EYE *<i><i>YC* . 46 9 IEFT DOR ,62 12, 1 Y II. $[\times$ 5 HORIZONTAL GRID CELL F 4-DEVICE DESCRIPTION NON - SPHERICAL (CORVED (3) H 5 Y 4 3 6.5×3.5 12. VERTICAL 501 ≿ 0 2 DEVICE DIMENSIONS 7 ~ N 5 5 0 3 2 EYE REFERENCE DATE MEASURED MAGN. MEASURE VERTICAL GRID CELL MEASURED BY

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DEVICE DESCRIPTI	DEVICE DIMENSIONS	EYE REFERENCE	MAGN. MEASURE	DATE MEASURED	MEASURED BY			`	~	м	ح CELL	евтр	АЛІСАL	A AE	Ø





VERTICAL DISTANCE FROM CENTER (IN.)

4.0 .5 1.0 1.5 2.0 2.5 3.0 3.5 INTION MIRAGE IEIDENE T I R MEASURED BY L U 1 DATE 0 11 L 17 HORIZONTAL DISTANCE FROM CENTER (IN.) DEVICE NON-SOMERICAL CORVENSIO (2) MEASUREMENT VISERICAL ROC (iN.) -4.0 -3.5 -3.0 -2.5 -2.0 -1.5 -1.0 -.5 11 11 L 120 100 120 47 33 34 4-4 -2.0 -2.5 1.0 <u>ى</u> -1.0 -1.5 2.0 0 - 2 1.5 2.5

VERTICAL DISTANCE FROM CENTER (IN.)

A-57

RADIUS OF CURVATURE MEASUREMENT FORM

A-4.2 LOCATION; RIGHT DOOR MOUNT

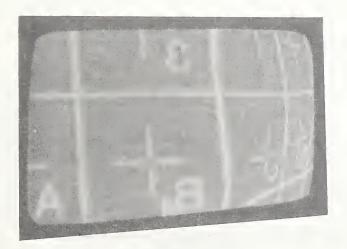
- A. GRID PHOTOS
 - 1. LEFT EYE 2. RIGHT EYE
- B. FIELD OF VIEW
 - 1. LEFT EYE/RIGHT EYE
 a. horizontal
 b. vertical
- C. MAGNIFICATION
 - HORIZONTAL

 right eye
 left eye
 - 2. VERTICAL
 a. right eye
 b. left eye
- D. RADIUS OF CURVATURE (See left door mount data)
- E. ACCOMMODATION DISTANCE
- F. REFLECTANCE (See left door mount data)

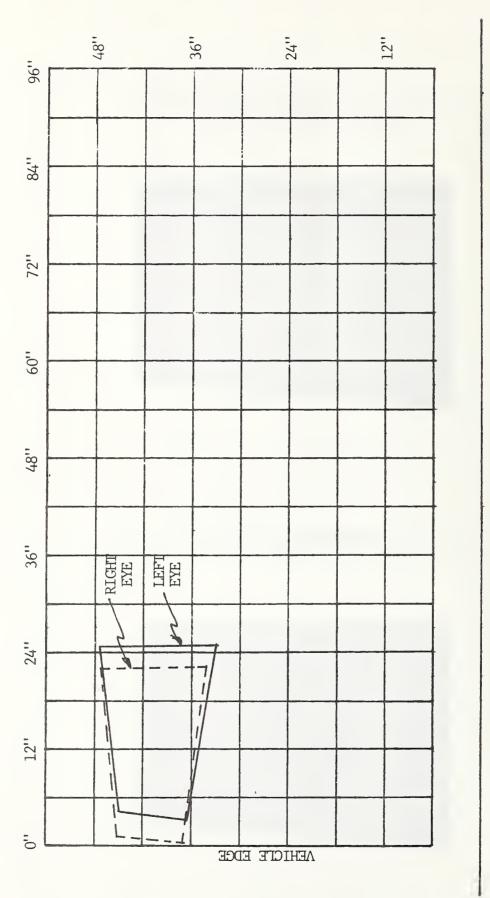
GRID PHOTO, NON-SPHERICAL/CURVED (Z) MIRROR, RIGHT DOOR MOUNT, RIGHT EYE



GRID PHOTO, NON-SPHERICAL/CURVED (Z) MIRROR, RIGHT DOOR MOUNT, LEFT EYE



NON-SPHERICAL/CURVED (Z) MIRROR FOV, RIGHT DOOR MOUNT (RIGHT AND LEFT EYE)



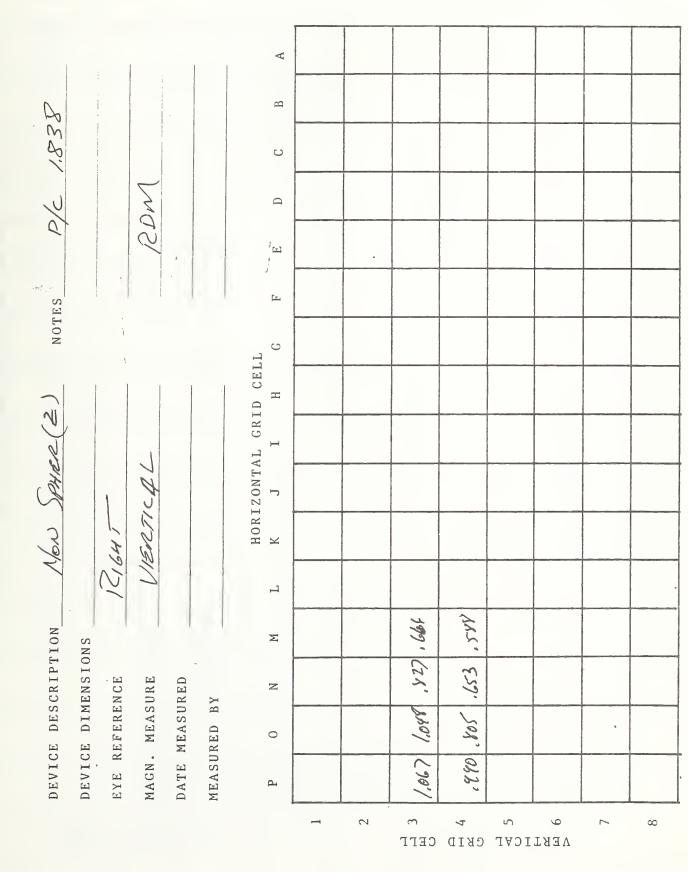
GROUND =0

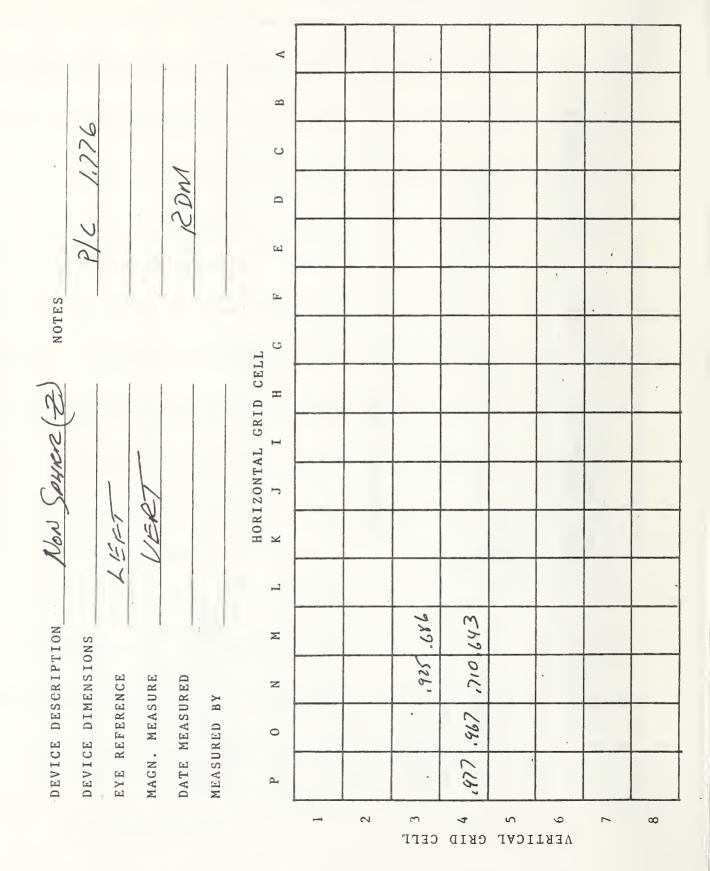
SCALE 1''=1'

 \leq \simeq ٩ P/C 1.838 C 12DM \square r_____ NOTES C HORIZONTAL GRID CELL Η Now Spurce (2) H ſ ¥ 10 . 1 ,131 (1) DEVICE DESCRIPTION Σ DEVICE DIMENSIONS .813 .259 1.024 ,1449 .313 EYE REFERENCE MAGN. MEASURE DATE MEASURED z MEASURED BY 0 1.024 م t ∼ CKID CEFF 2 Ś 9 ∞ -2 VERTICAL

< . \cong C ,226 ROM \square <u>[-]</u> ſ±, NOTES c HORIZONTAL GRID CELL Н Now SOHRR (Z) H H0212 ECT \bowtie צוגי 462, 234. 734. DEVICE DESCRIPTION $\mathbf{\Sigma}$ DEVICE DIMENSIONS 914' 465' MAGN. MEASURE EYE REFERENCE DATE MEASURED Z MEASURED BY 0 р 2 c 4 S 9 ~ ω -CEFF **AEKTICAL GRID**

A-62





- A-5 DEVICE; 4.4 X 6.6 INCH 20 INCH ROC CONVEX MIRROR
- A-5.1 LOCATION; RIGHT DOOR MOUNT
 - A. GRID PHOTOS
 - 1. RIGHT EYE 2. LEFT EYE
 - B. FIELD OF VIEW
 - RIGHT EYE/LEFT EYE
 a. horizontal
 b. vertical
 - C. MAGNIFICATION
 - HORIZONTAL

 a. right eye
 b. left eye
 - 2. VERTICAL
 a. right eye
 b. left eye

GRID PHOTO 20 INCH ROC SPHERICAL CONVEX MIRROR, RIGHT AND LEFT EYE, RIGHT DOOR MOUNT

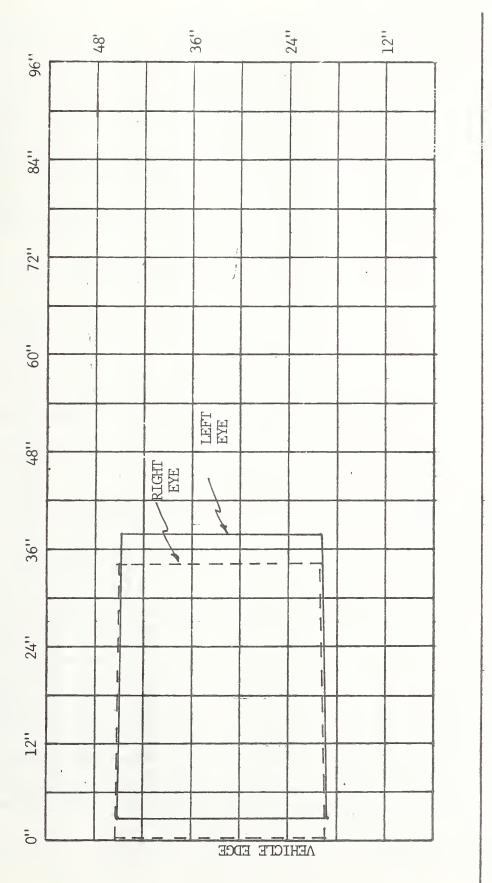
RIGHT EYE



LEFT EYE



20 INCH ROC SPHERICAL CONVEX MIRROR FOV, RIGHT DOOR MOUNT (RIGHT AND LEFT EYE)

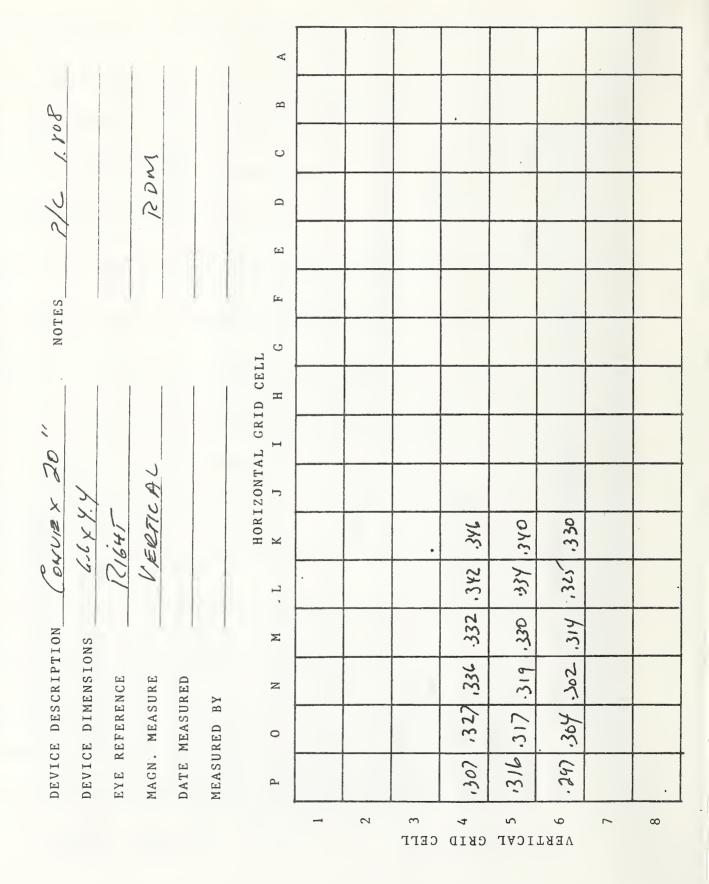


O= ONNOYO

SCALE 1''=1'

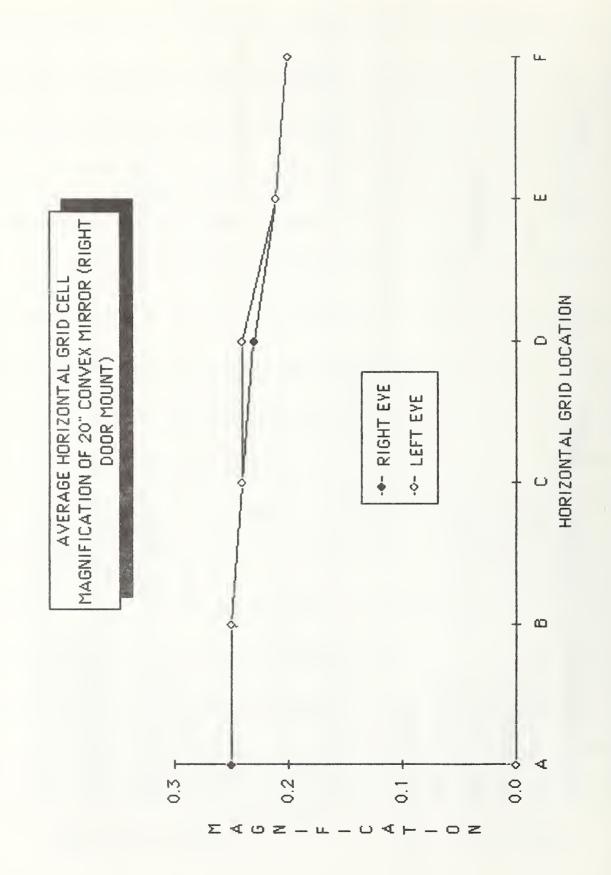
A , В D/C 1.808 C 2 D M Ω (H) Ē NOTES c HORIZONTAL GRID CELL H CONVER 20' Η HORIZ 6.644.4 ſ 101641 Х ,220 202. 412. 112' 112. 622, 252 PYL. Ц .22' 125. 244. 244 ,236 ,285 152. DEVICE DESCRIPTION Μ DEVICE DIMENSIONS 24C 1-52. EYE REFERENCE MAGN. MEASURE DATE MEASURED Z MEASURED BY 520. 57. 1249.251 0 .239 172. 1254 ρ. 9 2 e 4 Ś 7 ∞ -CELL VERTICAL GRID

< ŝ 1.808 C 12DW 0 :.; . <u>.</u> NOTES С HORIZONTAL GRID CELL Ξ LONKY 20 " H -512021 くにいし .203 194 238 .231 JUL. 196 746 236 .223 ×207. 189 ١ 6.6 V P.J \mathbf{x} ,207 .234.223.207 1 7 .23 .238 .277 DEVICE DESCRIPTION Σ DEVICE DIMENSIONS . 23Y EYE REFERENCE MAGN. MEASURE DATE MEASURED z MEASURED BY 240 144 244 253 0 d 2 c 4 S 9 \sim l ∞ CEFF CKID LEKTICAL



V D/C 1.808 В C Ω ы ۱ Ē NOTES ì c HORIZONTAL GRID CELL H CONVER 20" Н or trea ŗ 2.6×44 121-7 332.335 347 340 346 ,321 ,336 . 350 ,349 \mathbf{M} ٦ 108 323 DEVICE DESCRIPTION Σ DEVICE DIMENSIONS ,33 P EYE REFERENCE MAGN. MEASURE **DATE MEASURED** z MEASURED BY ,325 YIC. 1314 1.321 • 0 316 1 ٩ n CEFF S 9 2 4 -----2 ∞ GKID VERTICAL

A-71

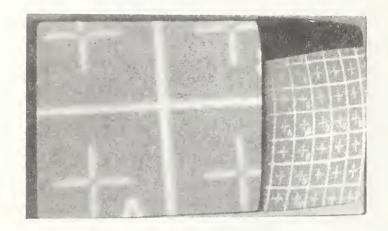


A-72

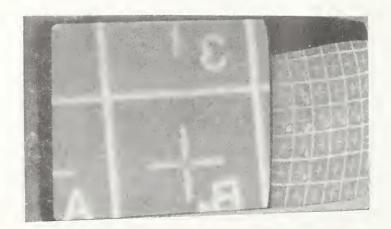
- A-6 DEVICE; 4.1 X 3.7 INCH PLANE/2.0 X 3.7 INCH 10 INCH ROC CONVEX (K) MIRROR
- A-6.1 LOCATION; RIGHT DOOR MOUNT
 - A. GRID PHOTOS
 - 1. RIGHT EYE
 - 2. LEFT EYE
 - B. FIELD OF VIEW
 - 1. LEFT EYE/RIGHT EYE
 - a. horizontal
 - b. vertical

GRID PHOTO, PLANE/10 INCH ROC SPHERICAL CONVEX (K) MIRROR, RIGHT AND LEFT EYE, RIGHT DOOR MOUNT

RIGHT EYE



LEFT EYE



PLANE 10 INCH ROC SPHERICAL (K) MIRROR FOV, RIGHT DOOR MOUNT (RIGHT AND LEFT EYE)

