CALIFORNIA PATH PROGRAM
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Final Report: Mobile Surveillance and Wireless Communication Systems Field Operational Test Volume 2: FOT Objectives, Organization, System Design, Results, Conclusions, and Recommendations Lawrence A. Klein

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The contents of this report reflect the views of the authors who are responsible for the facts and the accuracy of the data presented herein. The contents do not necessarily reflect the official views or policies of the State of California. This report does not constitute a standard, specification, or regulation.

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Final Report: Mobile Surveillance and Wireless Communication Systems Field Operational Test

Volume 2: FOT Objectives, Organization, System Design, Results, Conclusions, and Recommendations

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Preface

The Mobile Surveillance and Wireless Communication Systems Field Operational Test (FOT) contained two evaluation tests, the Anaheim Special Event Test and the Interstate-5 (I-5) Test. The Anaheim Special Event Test assessed the ability of the surveillance trailers to transmit video imagery to a traffic management center in support of arterial traffic signal control. This test occurred during the Spring of 1997 in conjunction with heavy traffic experienced during hockey playoff games at the Arrowhead Pond in Anaheim, CA. The I-5 Test evaluated the ability of the mobile surveillance and ramp meter trailers to transmit video imagery and data in support of freeway ramp metering. It occurred a year later in Spring 1998 along I-5 in Orange County, CA. The results of these tests and other conclusions from the FOT are presented in three volumes. The first volume serves as the Executive Summary of the FOT. It describes the project objectives, results, conclusions, and recommendations in condensed fashion. The second volume discusses the overall goals and objectives of the FOT and the design of the mobile surveillance and wireless communication system in more detail. Technical and institutional issues that surfaced before either of the two FOT tests was conducted are described. The specific objectives of the Anaheim Special Event and the I-5 Tests, lessons learned, test results, and recommendations are expanded upon in this volume. Photographs and drawings are used liberally to illustrate the types of equipment and test configurations that were tested. Volume 2 also incorporates revisions to the evaluation plans that were originally prepared by Pacific Polytechnic Institute (PPI). The evaluation plans and preliminary results from the planning and design phases of the FOT and the Anaheim Special Event Test were originally published by California Partners for Advanced Transit and Highways (PATH) under Report 97-C34. The third volume consists of ten appendices that contain data and other information gathered during the tests.

The test planning and execution were a cooperative effort among the partner agencies and companies. These were the Federal Highway Administration, California Department of Transportation divisions in Sacramento and Orange County, California Partners for Advanced Transit and Highways, University of California at Irvine Institute of Transportation Studies, California Highway Patrol, City of Anaheim Department of Public Works, Hughes Aircraft Company (now Raytheon Systems Company), Pacific Polytechnic Institute, and Lawrence A. Klein, Consultant.

This report was prepared in cooperation with the State of California, Business Transportation and Housing Agency, Department of Transportation. The material is based on work supported by the Federal Highway Administration, the State of California, Department of Transportation under prime contract number RTA-65A0012, and the Regents of the University of California.

The contents of the report reflect the views of the authors who are responsible for the facts and the accuracy of the data presented herein. The contents do not necessarily reflect the official views or policies of the State of California, the Federal Highway Administration, or the Regents of the University of California. This report does not constitute a standard, specification, or regulation.

Synopsis of Project

The Mobile Surveillance and Wireless Communication Systems Field Operational Test (FOT) evaluated the performance of wireless traffic detection and communications systems in areas where permanent detectors, electrical power, and landline communications were not available. The FOT partners designed and built six surveillance and three ramp meter trailers, a video and data retransmission or relay site, and video and data reception facilities at the Caltrans District 12 and Anaheim Traffic Management Center (TMCs) and the University of California at Irvine Institute of Transportation Studies (UCI-ITS) Laboratory. The system was evaluated in two different types of tests. The Anaheim Special Event Test assessed the surveillance trailers in an application that transmitted video imagery in support of arterial traffic control during a special event. The Interstate-5 (I-5) Test examined the use of the mobile surveillance and ramp meter trailers to transmit video imagery and data in support of freeway ramp metering.

The primary tasks of the surveillance trailer are to acquire video imagery and traffic data, transmit metering rates to the ramp meter trailer, and transmit traffic flow data and imagery to the relay site. The major components of the surveillance trailer are a video image processor (VIP); two pan and tilt black-and-white cameras; one pan, tilt, and zoom color camera; one fixed black-and-white security camera; a 170 controller; wide and narrow bandwidth spread spectrum radios (SSRs) for video and data transmission; a telescoping 30-foot (9.1-meter) mast; a security system; and a propane-powered electrical generator and power supply system. The ramp meter trailer retransmits the metering rates to portable signal heads on the ramp and controls the meter-on sign. The major components of the ramp meter trailer are two traffic signal heads, a ramp meter-on sign, narrow band SSRs for data reception, and solar-powered electrical recharging systems for one signal head and the meter-on sign. The relay site on the Union Bank Building in Santa Ana, CA supports trailer locations along the I-5 reconstruction zone in Orange County, CA. Video imagery and data received at the relay site are retransmitted to the TMCs and to the UCI-ITS Laboratory.

Perhaps the biggest issue faced by the project was the schedule delay. This was mainly attributed to deficiencies in the planning and procurement processes and the changes in scope that persisted well into the procurement and integration phases of the project. Allowing the primary contractor a more direct method of parts procurement, perhaps through a project credit card, for items costing less than some predetermined amount would have been helpful. Closely related to the planning issues was the conflict over whether the FOT was developing prototypes or completely developed equipment that could support normal transportation management operations.

Three issues that affect the portability of the mobile surveillance and communications system became apparent. First, the size of the trailers limits where they can be placed in a construction zone. Second, since the configuration of a construction zone may change weekly or daily, the trailer is subject to frequent moves that are exacerbated by their size. Third, the current existence of only one relay site limits the areas in which the trailers can be deployed. Subgrade placement is not possible because of line-of-sight restrictions. Two recommendations based on these findings are that: (1) road construction contractors be made aware early in the planning process for the need to allocate sites for the surveillance, and perhaps ramp meter, trailers in the construction zones; (2) additional or supplemental relay sites be designed and deployed in areas from which Caltrans desires video and VIP data.

The item that most impacted the start of the I-5 Test once the trailers were deployed was the initial lack of ramp signal synchronization with vehicle demand and control commands from the surveillance trailer. The problem was remedied by reducing the transmission rate of the commands.

The most prevalent problem uncovered during the I-5 Test was frequent discharge of the surveillance trailer battery. After the FOT was completed, an extensive redesign of the generator, batteries, charging system, and power distribution architecture was completed. The new power system was installed in the six surveillance trailers, but was not evaluated as a part of the FOT.

Once the cameras and communications links were operational, camera control and picture quality were consistent from each test venue. Exceptions occurred when strong winds moved the antennas or the mast accidentally dropped because the locking pins were not fully extended.

The average percent differences between the permanent inductive loop detector (ILD)-and VIP-measured mainline total volume and average lane occupancy were –22 and 8, respectively, based on data gathered in the fourteen runs completed in the I-5 Test. These accuracies appear adequate for the rush-hour ramp-metering application as shown by the tracking of the metering rates produced by the ILD and VIP data. These errors were tolerable because a more restrictive metering rate (namely zero) than the prestored time-of-day (TOD) rate was calculated by the metering algorithm from the ILD and VIP real-time data. Therefore, the algorithm reverted to the less restrictive TOD rate for both sets of data.

The larger mainline volume measured by the VIP as compared to the ILD may lead to the reporting of erroneous levels of service on the mainline. This potential problem is caused by the VIPs over estimating the volume by as much as 53 percent or under estimating it by as much as 14 percent. It is more likely that the VIP will overcount when the camera is mounted as it was in this evaluation. Therefore, a method of compensating for vehicle overcount by the VIPs is needed in order to report valid mainline traffic volumes.

The ramp signals responded properly to vehicle demand an average of 85 percent of the time. This is not good enough for ramp-metering operation. A possible method to increase this average is to position the surveillance trailer, and hence the camera, closer to the ramp. This may provide a better perspective of the vehicles on the ramp and perhaps modify the camera's field of view to allow even more VIP detection zones to be created upstream of the ramp stop bar. The multiple detection zones can then be connected with OR logic to increase the probability that a stopped vehicle will be detected by the VIP.

The most likely estimate of LPG consumption by a surveillance trailer is approximately 0.00522 tank/hr or 0.460 gallon/hr. With an LPG cost of \$1.75/gallon, the estimated cost of fuel is \$0.80/hr for surveillance trailer operation.

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FIGURE 4-25.	SURVEILLANCE TRAILER LOCATION AT SOUTHBOUND ENTRANCE TO I-5 AT KATELLA WAY

1. Objectives and Project Organization

1.1 Introduction

Traditional inductive loop detectors and landline communications can be costly to maintain, are subject to damage and removal during construction, and generally cannot provide cost-effective surveillance and communications at special events or remote locations where these detectors and communications systems are not already in place. In the Mobile Surveillance and Wireless Communication Systems Field Operational Test (FOT), the California ITS partners designed, built, and evaluated a mobile trailer system that provides closed-circuit television surveillance, video image processing, inductive loop emulation, ramp metering, and communication of data and video imagery to transportation management centers and research facilities. The mobile system consists of surveillance and ramp meter trailers, a retransmission or relay site, and data reception facilities. The salient features of the system are:

- Mobile trailers that can be deployed to locations that have line-of-sight communications with a relay site;
- A color camera that provides surveillance of traffic conditions, two black-andwhite cameras that supply imagery to a video image processor (VIP), and a blackand-white camera used for trailer security;
- Video image processing of freeway mainline and onramp traffic to detect vehicles, control metering rates, and extract traffic volume, lane occupancy, and vehicle speed at construction areas, special events, or any other site where permanent vehicle detection systems are not installed or operating;
- Inductive loop emulation by the VIP to facilitate the incorporation of data into existing traffic management systems;
- Wireless spread spectrum radio (SSR) communications between surveillance and ramp meter trailers and between the trailers, traffic management centers, and research facilities.

The mobile surveillance and wireless communication system was tested under real traffic conditions on Orange County, CA freeways and Anaheim, CA arterial roadways in two tests. The Anaheim Special Event Test evaluated the ability of the surveillance trailers to provide video imagery in support of traffic management on arterial streets during a preplanned event. In the Interstate-5 (I-5) Test, the surveillance and ramp meter trailers were used to provide local-responsive ramp metering. During these tests, the wireless communication system transmitted traffic flow data and imagery to the California Department of Transportation (Caltrans) and California Highway Patrol (CHP) District 12 (Orange County) Transportation Management Center (TMC), the City of Anaheim TMC, and the University of California at Irvine Institute of Transportation Studies (UCI-ITS) Laboratory.

The Final Report was developed according to the FHWA Intelligent Vehicle Highway Systems Operational Test Evaluation Guidelines of November 1993. Three test evaluation and planning documents and an interim draft Final Report were also prepared by the evaluators. These were the Overall FOT Evaluation Plan, Anaheim Special Event Test Evaluation Plan, I-5 Test Evaluation Plan, and Evaluation Report for Mobile Surveillance and Wireless Communication Systems Field Operational Test, Interim Draft.

2

1.2 Other Portable Traffic Management Systems Designed for Temporary Use in Construction Areas

Two other mobile traffic management systems have been developed in recent years. FHWA and the Minnesota Department of Transportation sponsored the first and the Iowa DOT and FHWA sponsored the second.

1.2.1 Portable Traffic Management System

The Portable Traffic Management System (PTMS) application for a Smart Work Zone was developed by MnDOT with support from FHWA.¹ The project partners also included the University of Minnesota, ADDCO, ISS, Vano Associates, BRW, and SRF Consulting Group. The PTMS integrates existing, off-the-shelf, and emerging traffic management technologies into a wireless, portable traffic control system. It operates in a work zone and provides traffic engineers with speed, volume, and incident detection data that are communicated to the traveling public so that they may make informed travel decisions.

As developed for the work zone application, the PTMS consists of portable skids that contain a machine vision system, variable message sign (VMS), central processing unit (CPU), and spread spectrum radio communications. The skids are placed in strategic locations in the work zone and, when linked to one another by the spread spectrum radio, form nodes in the PTMS network. The nodes can include both vehicle detection devices and driver information devices. Figure 1-1 shows the PTMS skid deployed in the work zone with both types of devices installed. The inset in Figure 1-1 shows a close up of the top of the PTMS tower. The CPU and related components are housed in the cylindrical enclosure.

The PTMS consists of four subsystems: vehicle detection and surveillance, traffic control center, driver information, and communications. The vehicle detection and surveillance subsystem contains cameras and a video image processor. Video cameras placed at strategic locations in the work zone provide real-time traffic flow information to traffic management personnel. The video image processor analyzes the camera imagery to produce traffic volume, speed, incident detection, and alarms that indicate vehicle intrusion into the work zone. The camera is mounted at the top of the tower as illustrated in the left side of the inset in Figure 1-1.

The data from the vehicle detection and surveillance subsystem are transmitted to the traffic control center at the MnDOT Traffic Management Center. After review, operators use the data to make decisions regarding traffic control that are intended to improve traffic flow through the work zone. The traffic control changes are implemented by relaying messages to the motorist through the driver information subsystem that consists of full-size portable, variable message signs and smaller work zone portable variable message signs. The information can also be made available to the public on a World Wide Web page via the Internet.

^{1.} Portable Traffic Management System Smart Work Zone Application Operational Test Evaluation Report, SRF Consulting Group, Report Number 0942089.7/11, May 1997.

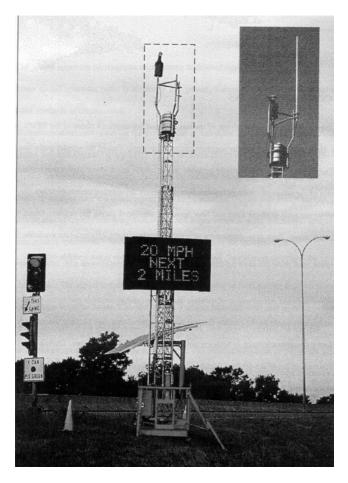


Figure 1-1. PTMS deployed on a skid
(From Portable Traffic Management System Smart Workzone Application, Final System
Design Report, MnDOT, May 1997)

The communications subsystem utilizes spread spectrum radio, cellular telephone, and the Integrated Services Digital Network (ISDN). The spread spectrum radio antenna is mounted at the top of the tower as shown on the inset in Figure 1-1. Each of the communication devices is used for specific links. This subsystem will eventually include a master controller and a radio link to the traffic control center.

The costs for the PTMS are summarized in Table 1-1. The minimum configuration for a PTMS requires the basic system, base station, and landline communications and control packages. The cost for this configuration is \$75,850.

1.2.2 Rural Smart Work Zone

During the 1997 Interstate-80 reconstruction in lowa, traffic engineers acted to mitigate the impact of traffic incidents in the work zone and reduce the number of secondary traffic accidents. The increased incidents and secondary accidents were caused by reduced work zone capacity, which combined with peak period demand to create traffic backups that brought about the accidents. Prior to the development of the Rural Smart Work Zone, traffic monitoring was provided by a single person in a roving vehicle who

monitored traffic and responded to observed incidents. The single roving vehicle technique, by itself, was inadequate for the large reconstruction area.

Table 1-1. Portable Traffic Management System costs (MnDOT project)

System	Cost
Basic System containing skid mount platform and 40-foot (12.2-meter) tower; CCTV camera, enclosure, pan, tilt, zoom assembly; video compressor and control processor; 900 MHz SSR communications; 600 W tilt and rotate solar panel with 3520 amp-hour battery	\$59,850
Base Station, Landline Communications, and Control System containing solar powered pole mount relay and termination; two ISDN routers, ADDCO Base Station Software	\$16,000
Optional systems: 3 x 6 foot, 24 x 48 pixel LED message sign AutoScope with field upgrade kit Speed (Doppler) radar Skid trailer assembly	\$9,800 \$21,700 \$2,000 \$4,000

The Rural Smart Work Zone consists of an incident detection unit (IDU) equipped with a Whelen microwave Doppler sensor to measure vehicle speed and a camera to acquire images of the traffic flow. When speeds drop below 35 mi/h (56.3 km/h), the IDU automatically places a series of four cellular telephone calls, three to activate Automated Traveler Information System (ATIS) devices [namely, two mobile changeable message signs (CMS) and a highway advisory radio (HAR)] and one to notify the roving vehicle. The camera operates independently of the speed sensor. The images from the camera can be viewed (for example, at the TMC) by calling the camera via cellular telephone. The images are transmitted by cellular communications as well. The viewer can select the image refresh rate up to a maximum of once every 2 to 3 seconds. Cellular communications was used because of the required transmission distances. CMS #1 is two miles from the IDU, CMS #2 is 10 miles (16.1 km) from the IDU, and the HAR is 20 miles (32.2 km) from the IDU.

The camera and its interface to the cellular communications system were provided by Denbridge Digital of San Leandro, California. The lowa DOT reports that the camera portion of the IDU has performed well. The Doppler sensor with its link to the cellular system was provided by Display Solutions (the CMS supplier). The sensor-cellular system fails whenever there is a temporary disruption in traffic flow. The problem arises because it takes a certain amount of time for the telephone to place the four cellular calls. If traffic clears [speeds rise above 35 mi/h (56.3 km/h)] before all four calls are completed, the system locks up. Iowa is attempting to remedy this problem. However, Display Solutions may have decided to discontinue their participation in the sensor market and may not support the product further. No formal evaluation was required or performed.

1.3 Goals and Objectives of the Mobile Surveillance and Wireless Communication Systems FOT

The goals and objectives for the Mobile Surveillance and Wireless Communication Systems FOT were derived from those of the National ITS Program, namely:

^{2.} S.J. Gent, "Rural Smart Work Zone," ITE Journal, p. 18, Jan. 1998.

- Improve the safety of the Nation's surface transportation system;
- Increase the operational efficiency and capacity of the surface transportation system;
- Reduce energy and environmental costs associated with traffic congestion;
- Enhance present and future productivity;
- Enhance the personal mobility and the convenience and comfort of the surface transportation system; and
- Create an environment in which the development and deployment of ITS can flourish.

These program goals are expanded in ITS America's *Strategic Plan for Intelligent Vehicle-Highway Systems* and in the U.S. Department of Transportation's *IVHS Strategic Plan*.³

The overall goal of this FOT was to assess the application of traffic monitoring and management systems that utilize transportable surveillance and ramp meter trailers, video image processors, and wireless communications. This goal is consistent with the national objectives described above. For example, the FOT tested and evaluated technology that is designed to increase the operational efficiency of the freeway system by providing a ramp-metering system suitable for temporary deployment in construction zones. The FOT was conducted within the California ITS Test Bed, an area in Orange County containing both freeways and surface streets, that has been specified by Caltrans for the development and evaluation of ITS products. Therefore, the FOT occurred in an environment that was designed for the development and deployment of intelligent transportation systems.

1.3.1 Anaheim Special Event Test Objectives

The Anaheim Special Event Test had five objectives:

- 1. Examine the portability of the surveillance and ramp meter trailers for installation in a city pre-planned special event setting within range of the communications relay site:
- Demonstrate that the surveillance and ramp meter trailers are effective in supporting pre-planned special event traffic management where traditional traffic monitoring systems are not otherwise available;
- 3. Assess the relative impact of additional video surveillance with respect to special event traffic management;
- 4. Examine the institutional issues, benefits, and costs associated with sharing resources between agencies in a special event setting;
- Examine the institutional issues, benefits, and costs associated with sharing information between allied agencies.

^{3.} Strategic Plan for Intelligent Vehicle-Highway Systems in the United States, Final Draft (First Version), ITS America, Washington, D.C., March 25, 1992.

1.3.2 I-5 Test Objectives

The I-5 Test had the following four objectives:

- 1. Examine the portability of the surveillance and ramp meter trailers for installation in a freeway setting within range of the communications relay site;
- 2. Demonstrate that the surveillance and ramp meter trailers are effective in that they may be used for freeway traffic management where permanent traffic surveillance and control systems may be disabled or not otherwise available;
- 3. Examine the institutional issues, benefits, and costs associated with surveillance and ramp meter trailer deployment in a freeway setting;
- 4. Examine the institutional issues, benefits, and costs associated with information sharing in a freeway setting.

1.4 FOT Design

The FOT deployed surveillance and ramp meter trailers to selected locations and transmitted data and video imagery from multiple sites, in real-time, to TMCs and the UCI-ITS Laboratory. The FOT evaluated the operational effectiveness of the trailers for realtime traffic management on freeways and in special event settings that required traffic control on city arterials.

1.4.1 Anaheim Special Event Test Design

In the Anaheim Special Event Test, three surveillance trailers were placed on streets that fed traffic into the Arrowhead Pond in Anaheim, indicated on Figure 1-2. Only camera imagery was of interest in this test. The video was transmitted to the Anaheim and Caltrans District 12 TMCs during evenings when the Anaheim Mighty Ducks were involved in hockey playoff games. Anaheim had primary control of the trailer locations and cameras during this test as the emphasis was on controlling traffic ingress and egress operations to and from the streets and parking lot areas near the Pond.

1.4.2 I-5 Test Design

In the I-5 Test, surveillance and ramp meter trailers were located at six evaluation sites along a 7-mi (11.3-km) length of I-5 between State Route (SR)-22 and Culver Drive in Orange County, CA as shown in Figure 1-2. Video images of traffic flow and traffic flow data were transmitted to the Caltrans District 12 TMC, Anaheim TMC, and the UCI-ITS Laboratory. Caltrans had primary control of the cameras during the I-5 Test. Emphasis was on weekday, peak-period traffic operations.

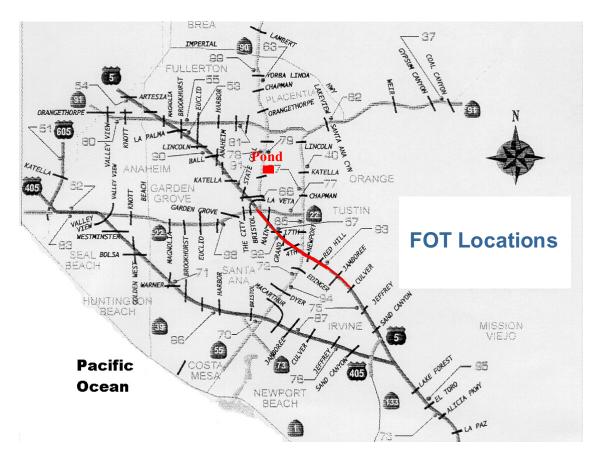


Figure 1-2. FOT locations

All six surveillance trailers and all three ramp meter trailers were used in this test. Three surveillance trailers were paired with ramp meter trailers at three onramps along the freeway. These surveillance trailers used SSRs to transmit camera imagery and VIP-generated traffic flow data to the TMCs and UCI. They also used SSR to transmit metering rates to the ramp meter trailer, which in turn controlled the ramp signals and the meter-on sign. The remaining three surveillance trailers were placed at other strategic venues along the freeway. These trailers transmitted only imagery to the TMCs and UCI.

1.5 Mobile Surveillance and Wireless Communication System Design and Operation

The mobile surveillance and wireless communication system consists of surveillance and ramp meter trailers, a video and data retransmission or relay site, and video and data reception facilities at TMCs and the UCI-ITS research laboratory. Six surveillance and three ramp meter trailers were assembled as part of the FOT. Figure 1-3 shows a surveillance trailer. Its major components are a video image processor; two pan and tilt black-and-white cameras; one pan, tilt, and zoom color camera; one fixed black-and-white security camera; a 170 controller; wide and narrow bandwidth spread spectrum radios for video and data transmission; a telescoping 30-foot (9.1-meter) mast; a security system; and a propane-powered electrical generator and power supply system.



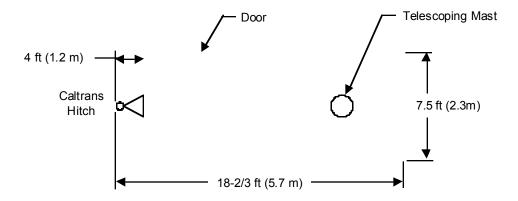
Figure 1-3. Surveillance trailer at First Street overlooking I-5 Freeway

Figure 1-4 shows a ramp meter trailer. Its major components are two traffic signal heads, a ramp meter-on sign, narrow band SSRs for data reception, and solar-powered electrical recharging systems for one of the signal heads and the meter-on sign.



Figure 1-4. Ramp meter trailer at Grand Avenue alongside I-5 Freeway

Trailer dimensions are displayed in Figure 1-5. The surveillance trailers can operate autonomously of the ramp meter trailers and thus be used in applications that do not require ramp metering. Each surveillance trailer can support two ramp meter trailers. However, in this FOT the surveillance trailers were programmed to operate only one ramp meter trailer.



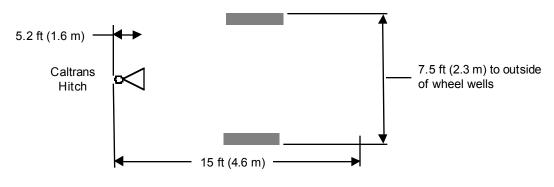
A fully-extended mast is 30 ft (9.1 m) high.

Since the floor of a surveillance trailer is approximately 2 ft (0.6 m) above the ground, the top of a fully-extended mast is approximately 32 ft (9.8 m) above the ground.

The roof of the surveillance trailer is 8-2/3 ft (2.6 m) above the ground.

The railing on the surveillance trailer roof is 3 ft (0.9 m) high.

(a) Surveillance trailer dimensions



(b) Ramp meter trailer dimensions

Figure 1-5. Trailer dimensions

The primary tasks of the surveillance trailer are to acquire traffic video imagery and data, transmit metering rates to the ramp meter trailer, and transmit traffic flow data and imagery to the relay site. The ramp meter trailer retransmits the metering rates to the signal heads and controls the meter-on sign. The primary signal head is connected by cable to the ramp meter trailer; the secondary signal head receives its commands via SSR from the ramp meter trailer. The meter-on sign receives its commands via an FM radio transmitter/receiver pair.

The relay site receives traffic flow data and imagery from the trailers and retransmits them to the state and city TMCs and the UCI-ITS Laboratory. The relay site on the Union Bank Building in Santa Ana, CA supports trailer locations along the I-5 reconstruction zone in Orange County, CA providing line-of-sight transmission exists.

Depending on their equipment, the TMCs and UCI may have remote surveillance trailer control, remote camera control, and remote VIP calibration control. Remote surveillance trailer control includes trailer selection, power-up, power-down, mast-extend, and mast-

retract control. Remote camera control includes image selection for display at the TMC and pan, tilt, and zoom control of the surveillance camera. Remote VIP calibration control includes video detection zone configuration and the ability to receive VIP data.

The Caltrans District 12 TMC is the only facility that can exercise all remote control options, namely remote trailer, camera, and VIP control. The Anaheim TMC has remote trailer and camera control, but lacks remote VIP control. The UCI-ITS Laboratory does not presently have any remote control capability. While researchers at UCI are able to view camera images, they must contact either the Caltrans District 12 TMC or the Anaheim TMC for assistance in selecting a particular image or scene transmitted by the SSR system. However, the UCI-ITS Laboratory can also receive imagery and data over a separate fiber optics backbone connected to Caltrans.

Table 1-2 lists the SSRs used in the mobile system to facilitate communications between surveillance and ramp meter trailers, the relay site, and the TMCs and UCI. The various video and data transmission paths are illustrated in Figure 1-6.

Table 1-2. Spread spectrum radios used in the mobile surveillance and wireless communications system

Manufacturer and Model	Qty	Spectrum	Bandwidth/ Channel	Location	Information
Cylink 19.2 ALM	1	902-928 MHz	1.5 MHz	Surveillance trailer	Metering and control data
Cylink 64 ALSM	1	2.4-2.48 GHz	5.1 MHz	Surveillance trailer	Data
Cylink 256 NSPALS	1	2.4-2.48 GHz	20.5 MHz	Surveillance trailer	Video
Cylink 19.2 ALM	1	902-928 MHz	1.5 MHz	Ramp meter trailer	Control data
Digital Wireless WIT915	2	902-928 MHz	1 MHz	Ramp meter trailer	Signal light control
Cylink 64 ALSM	2	2.4-2.48 GHz	5.1 MHz	Relay site	Data
Cylink 256 NSPALS	3	2.4-2.48 GHz	20.5 MHz	Relay site	Video
Cylink ALT1	1	5.725-5.850 GHz	125 MHz	Relay site	Data and video
Cylink ALT1	1	5.725-5.850 GHz	125 MHz	District 12 TMC	Data and video
Cylink 64 ALSM	1	2.4-2.48 GHz	5.1 MHz	Anaheim TMC	Data
Cylink 256 NSPALS	1	2.4-2.48 GHz	20.5 MHz	Anaheim TMC	Video
Cylink 64 ALSM	1	2.4-2.48 GHz	5.1 MHz	UCI-ITS	Data
Cylink 256 NSPALS	1	2.4-2.48 GHz	20.5 MHz	UCI-ITS	Video

The two pan and tilt black-and-white cameras on each surveillance trailer supply imagery to the VIP. In freeway operations, one camera is usually pointed at the mainline and the other at an onramp. For arterial applications, each camera can be pointed at a different

approach to an intersection. Once the detection zones are calibrated, the black-and-white cameras are not repositioned. In fact, the control cables are removed from the pan and tilt units for these cameras to prevent accidental camera movement once the VIP is operational.

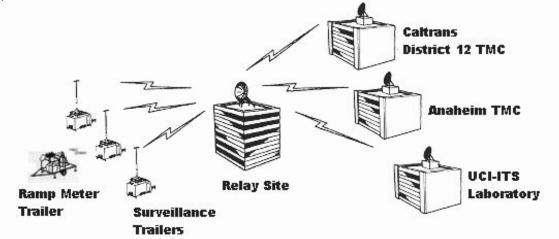


Figure 1-6. Transmission of video and data among trailers, relay site, TMCs, and UCI

(Adapted from System Information Manual, Mobile Video Surveillance Communications System, Hughes Aircraft Company, Feb. 1998)

The pan, tilt, and zoom color camera is used for traffic flow surveillance. The fixed position black-and-white security camera is pointed at the surveillance trailer door to enable TMC personnel to observe trailer entry. The surveillance trailers contain a security system that is connected to the Caltrans District 12 TMC. Up to two cameras from among a total of twenty-four (four at each of the six surveillance trailers) can be selected by the District 12 TMC to simultaneously transmit and display video imagery. Imagery from one camera can be selected for display by the Anaheim TMC. This concept is shown in Figure 1-7.

Figure 1-8 contains photographs of the two racks of equipment found in each of the surveillance trailers. The rack on the left contains the power distribution system, spread spectrum radios that transmit data to the ramp meter trailer and relay site, wide-area communications controller, AutoScope 2004 VIP, and the170 controller that processes the VIP data. The rack on the right contains a monitor, controls for selectively displaying the imagery from the color surveillance camera or the black and white VIP cameras on the monitor, digital video encoder, spread spectrum radio that transmits compressed video imagery to the relay site, pan-tilt-zoom camera controls, generator auto start/battery recharge system, and the automatic mast retraction circuit.

The video image processor analyzes the images of mainline and ramp traffic and provides traffic flow volume, lane occupancy, and vehicle speed to the 170 controller located in the surveillance trailer. The format of the VIP data is the same as that produced by permanent inductive loop detectors. Therefore, the VIP data are compatible for utilization by existing traffic control systems.

Since the surveillance and ramp meter trailers are self-powered and use wireless communications, they can be located where normal electric power and landline communications are not available. Thus, the equipment can replace in-pavement loop systems temporarily rendered inoperative at construction sites and supplement existing

traffic control systems at special pre-planned events or at long-duration emergencies. The system can also provide data for traffic management research.

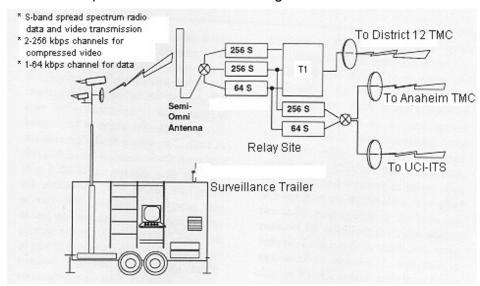


Figure 1-7. Selection of video images for transmission from surveillance trailers to TMCs and UCI. Video images from two cameras on any of the six surveillance trailers reach the District 12 TMC, while one camera image is transmitted to the Anaheim TMC and UCI.

(Adapted from System Information Manual, Mobile Video Surveillance Communications System, Hughes Aircraft Company, Feb. 1998)

The trailers and relay site operate without human operator intervention. As such, the surveillance and ramp meter trailers can be programmed to turn on and off automatically using the 170 controller. Outside of designated metering times, the associated surveillance trailers can be turned on and off remotely from the TMCs as needed.

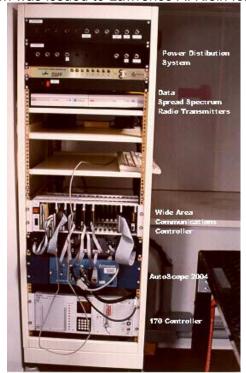
1.6 Project Management

The FOT was a cooperative effort among the test partners. The Federal Highway Administration (FHWA) and Caltrans sponsored the FOT. Other partners included California PATH, University of California at Irvine, Hughes Aircraft Company (now Raytheon Systems Company), City of Anaheim, the California Highway Patrol, Pacific Polytechnic Institute (PPI), and Lawrence A. Klein, Consultant (LAK). The partners were arranged into three teams: the Project Management Team, the Evaluation Team, and Technical Review Team. While each team had responsibilities that were distinct, the three teams worked as a group to support the objectives of FOT.

The Project Management Team (PMT), which included Caltrans, Hughes, FHWA, Anaheim, and UCI, was responsible for conducting the FOT. As such, they deployed and operated the surveillance and ramp meter trailers, assisted in test design, and collected test data. The PMT also provided the Evaluation Team with written reports on test activities, technology issues, institutional issues, and costs.

The Evaluation Team, which included PPI (later LAK), PATH (later UCI), and FHWA, was responsible for performing an independent evaluation of the FOT. PPI performed the

independent evaluation from April 1994 through June 30, 1997. A contract to complete the independent evaluation was issued to Lawrence A. Klein for the



(a) Left equipment rack



(b) Right equipment rack

Figure 1-8. Surveillance trailer equipment racks

September 1, 1997 through April 30, 1999 period. PPI and LAK were the members of the Evaluation Team responsible for coordinating the collection of test data and preparing test procedures and reports. In this role, PPI and LAK provided the PMT with comments about the test design, observed test activities, analyzed test data, interviewed test participants, and prepared the final reports. California PATH served as evaluation manager, through a contract with Caltrans, when PPI was the evaluator. UCI-ITS served as the evaluation manager, also through a contract with Caltrans, when LAK was the evaluator. FHWA and its contractor, Booz-Allen & Hamilton, reviewed and approved test plans and reports. UCI retained Hughes to provide engineering services for the design, installation, and systems integration of the equipment.

The Technical Review Team (TRT), which included Caltrans and Anaheim, was responsible for reviewing technical issues related to the planning, design, and execution of the FOT. Members of the TRT were selected for their ability to assist in evaluating project objectives, plans, and evaluation procedures.

1.7 Evaluation Focus

Remote traffic surveillance by itself does not result in direct operational benefits. Traffic flow measurements and video surveillance produce benefits to freeway traffic management only when freeway operations personnel use the information appropriately. In the Caltrans District 12 TMC, Caltrans and CHP operators review all available incident and traffic information, coordinate activities with allied personnel, and refer to standard operating procedures in order to initiate traveler advisories and other traffic management decisions. The objective of their actions is to help preserve freeway safety and expedite the movement of freeway traffic.

The FOT partners focused the FOT evaluation on functions that are unique to the mobile surveillance and ramp meter trailers, wireless transmission of data and imagery, and the relay site. As such, the evaluation did not investigate the benefits of providing traffic surveillance video and data to operations facilities, nor did it explore the benefits of ramp metering or a comparison of VIP and inductive loop detector accuracies. Rather, the focus was on features such as transportability, self-contained power, wireless communications, and the ability to provide video and data that are of sufficient accuracy to support local-responsive ramp metering and the arterial traffic management goals of the FOT. Other issues explored dealt with the sharing of real-time video and data among traffic operations and research facilities.

1.8 Revisions to the FOT

The FOT partners initiated a series of revisions that affected the ultimate design of the FOT and the evaluation. The original plans included two segments. Segment 1 specified deployment of six surveillance trailers, three ramp meter trailers, and a vehicle-to-roadway communication (VRC) system. Segment 2 provided the option to deploy an additional nine surveillance trailers and an additional three ramp meter trailers on the condition that both FHWA and Caltrans agreed to extend their participation. Ultimately, the FOT partners decided to forego VRC deployment in Segment 1 and to omit Segment 2.

The VRC system was to include 500 transponders and 2 roadside readers. Five hundred vehicles were to be equipped with the transponders for use as probes. These probe vehicles would then provide an independent measure of traffic flow conditions within the I-5 construction zone. The partners agreed that the VRC measurements were not needed primarily because construction near the test sites was completed before the FOT evaluation could begin. Consequently, traditional surveillance systems had been restored and were available if an independent measure of traffic conditions was needed. Furthermore, the partners concluded that the independent measurement was no longer important since the FOT objectives had been revised away from issues associated with improved traffic flow. The objectives now were oriented towards transportability, setup, and effectiveness of the mobile system.

The FOT partners decided not to proceed with Segment 2 because delays had extended the FOT beyond the time when Segment 2 was feasible. The decision to omit Segment 2 affected the design of the field evaluation tests. The original FOT included three field tests. The Anaheim Special Event Test specified that the mobile surveillance trailers be deployed in the City of Anaheim to evaluate their potential to assist in the management of special event traffic. The I-5 Test required the mobile surveillance and ramp-metering trailers be deployed along a freeway where traditional loop detectors were disabled due to construction. A third test was conceived for using the mobile surveillance trailers along SR-91. This test was to evaluate issues related to the gathering and synchronization of data from successive trailer locations. When the FOT partners decided not to proceed with Segment 2, they also eliminated the SR-91 Test as it required the installation of one or more additional relay sites to support wireless communication along SR-91.

2. General Issues

Technical and institutional issues that are not specific to either the Anaheim Special Event or I-5 Tests are discussed in this section. A summary of the equipment costs for the surveillance and ramp meter trailers, the District 12 and Anaheim TMCs, the UCI-ITS Laboratory, and the relay site is also provided.

The issues below are addressed in this chapter:

- 1. Planning and Scheduling
- 2. Definition of Test Objectives
- 3. Cost Centers and Personnel-Year (PY) Allocations
- 4. Equipment Procurement
- 5. Trailer Hitch Redesign and Replacement
- 6. Portable Power Generation System
- 7. Automatic Mast Retraction
- 8. Caltrans TMC System Integration
- 9. Data Capture and Presentation
- 10. Shared Camera Selection and Control Among Agencies
- 11. Relay Site
- 12. Trailer Security
- 13. Technical Training
- 14. Trailer Transport and Setup
- 15. Ramp Meter Trailer Design
- 16. Equipment Costs

2.1 Planning and Scheduling

The execution of the FOT would have benefited from planning that acknowledged that additional requirements and tests could possibly emerge as the FOT progressed. Had the possibility for additional requirements been considered and formally communicated to the partner agencies and companies earlier in the planning cycle, some of the encountered delays could have been better accommodated or reduced.

Allotting more time to incorporate each increase in scope in the trailer's function would have allowed the contractor to adequately design, fabricate, and test each subsystem before it was integrated into the entire mobile system. Furthermore, some date on the schedule should have been chosen as a cut-off after which no further design changes were permitted. Belated design modifications aggravated the already difficult task of systems integration. Lack of early testing of some surveillance and communications subsystems postponed the timely identification of problems, thereby creating delays for other FOT tasks.

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The increase in time needed to complete the FOT was somewhat exacerbated by retirements and personnel reductions at Hughes. Consequently, there were four program managers assigned over the life of the project by Hughes. Although Hughes made every effort to transfer the details of the program to succeeding managers, some discontinuity and program delay were caused by the personnel changes.

2.2 Definition of Test Objectives

The FOT partners spent considerable time revising and finalizing the test objectives. Initially, the objectives dealt with measuring the improvement in traffic flow that resulted when the trailers were deployed in a special event area and a construction zone. Due to project delays, the construction at the designated I-5 Test locations was completed and traditional detection methods restored before the test could start. It was agreed that the I-5 Test continue as planned although construction in the selected freeway area was complete. This decision was made in order to avoid the complications of finding new locations for the trailers in ongoing reconstruction zones and testing for adequate signal strength. However, an added benefit was obtained by staging the test in the completed work area. This was the ability to compare ramp-metering rates calculated from VIP and permanent ILD measurement data.

The change in test conditions sparked considerable discussion about using the trailers to measure the benefits of mobile vehicle detection and traffic surveillance. The Evaluation Team recognized that surveillance alone delivers no operational benefit and that surveillance provides operational benefits only when the information is utilized by skilled personnel to manage traffic. It then became unclear how to distinguish the use of data from mobile detection and surveillance from data gathered with permanent detection and surveillance techniques. The Project Management Team also struggled with how to separate the contribution from the surveillance trailers from the contribution of traffic managers and their customary control systems.

The FOT partners then began to focus on the system attributes that were unique to the FOT including trailer transportability, use at special events, and sharing of video and data among multiple agencies through wireless communications. The final set of test objectives, as presented in Section 1.3, reflects this perspective.

2.3 Cost Centers and Personnel-Year (PY) Allocations

Caltrans District 12 maintenance and electrical personnel were important assets to the FOT partnership. Their expertise contributed to resolving design issues, such as the trailer hitch, and to the relative ease in transporting the trailers. Unfortunately, some maintenance and electrical personnel indicated that they initially had difficulty in making these contributions as no cost center was available for charging time spent on FOT activities. These personnel were assigned additional tasks without having the financial resources to support the work. At one point, the Electrical Supervisor instructed his personnel to refuse to work on the FOT explaining that the person-year (PY) allocations their department had been given were insufficient to support the FOT and their regular work load. Personnel previously relied on to perform routine trailer maintenance had also been told by their supervisors to adhere to Caltrans restrictions that prohibit them from performing such tasks. This issue was eventually resolved when appropriate accounts were established.

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2.4 Equipment Procurement

A unique aspect of the project was the indirect manner in which equipment and supplies were procured for integration and assembly into the surveillance and ramp meter trailers. Procurement involved three agencies: Caltrans, UCI, and Hughes. Caltrans supplied UCI with funds and approval to procure items required by Hughes. UCI, in turn, subcontracted the actual trailer and communications systems development and integration to Hughes. Consequently, the trailers were the property of UCI and each piece of equipment had a "Property of UCI" inventory tag. The trailers will be registered in Caltrans' name once the contract with UCI is closed.

Several reasons have been offered as to why responsibility for procurement was originally assigned to UCI. One was to provide a system of checks and balances to ensure high value purchases. Another was to permit sole-source contracting to Hughes for trailer systems development and integration, a contracting mechanism that Caltrans is not permitted to offer. Still another reason was to further the Testbed partnership between Caltrans and UCI. Unfortunately, as it was implemented, the procurement process developed problems and was identified by several of the partners as a primary cause of major delays. Allowing the primary contractor a more direct method of parts procurement, perhaps through a project credit card, for items costing less than some predetermined amount would have been helpful.

2.4.1 Procurement Process

The contracts and subcontracts entered into by Caltrans, UCI, and Hughes specified a six-step procurement process. (1) Hughes was responsible for identifying the required equipment, securing at least three vendor bids for each item or set of items, and providing those bids and a recommendation to the TRT. (2) The TRT was responsible for approving the recommendation or requesting alternate bids. (3) Once Hughes received approval, a request for a purchase order was delivered to the UCI purchasing office, which then sent a copy to the Caltrans Contract Manager for approval. (4) When approved, Caltrans returned the request to UCI, who (5) then created a purchase order according to University of California procedures and standards. (6) The purchased items were shipped to the Hughes Receiving Dock or to the office of one of the Hughes team members, depending on relative size and value of the items.

2.4.2 Procurement-Caused Project Delays

Because of the complex nature of the procurement process, there were numerous opportunities for delay. For example, if the TRT spent weeks discussing the submitted vendor bids, the bids would expire before Hughes had an opportunity to request a purchase order from UCI. This required Hughes to secure other bids or forego an opportunity for reduced prices, contributing to project delays or creeping costs. It is estimated that procurement difficulties delayed the project by many months. In many cases, the vendors either failed to deliver as promised, or were simply unable to supply the item in a timely manner. With no penalty provision in the contract, Hughes was unable to wield influence over delinquent vendors. While indirect procurement through UCI was found cumbersome, the FOT partners agreed that UCI handled procurement tasks with diligence. Allowing Hughes a more direct method of parts procurement, perhaps through a project credit card, for items costing less than some predetermined amount would have been helpful.

2.4.3 Modifications to the Procurement Process

Hughes, UCI, and Caltrans all agreed that a streamlined procurement process was required. A procurement procedure was preliminarily agreed to by the PMT members prior to the start of the systems integration portion of the FOT. The first Hughes Project Manager suggested that the Intelligent Power Controller (IPC) be purchased to test the process. A vendor bid was submitted to UCI in November 1994. A request for the IPC bids to be submitted to the TRT was made at a PMT meeting in February 1995. Not until early April did Caltrans give Hughes approval to request a purchase order from UCI. UCI then requested a quotation from Pulizzi Engineering, the chosen supplier. This quotation was received May 25 and the item was eventually received at Hughes in July of 1995. More than seven months was required to secure this item. Thus, it became clear than more streamlining was necessary.

After this experience, each individual involved in the procurement process agreed to give prompt attention to each assigned task. Still, there were serious delays. The Caltrans FOT Project Manager said in a July 13, 1996 memo to the second Hughes Program Manager, that he believed project slippage was "due to a failure to procure [equipment] in a timely manner," indicating that UCI and Hughes needed to communicate more clearly.

Better communication and delineation of responsibilities at the start of the project could have reduced or eliminated many of the problems. At the start of the project, Hughes believed that the UCI would negotiate with and select appropriate vendors. This misunderstanding led to problems and delays in purchasing items, until UCI made it clear that its function was solely to prepare purchase orders and that vendor negotiation was the responsibility of Hughes and Caltrans. Two reasons have been offered to explain UCI's limited involvement. One reason mentioned in an April 1997 telephone interview with UCI staff responsible for placing purchase orders is that the personnel assigned to this project did not have the technical expertise necessary to critically evaluate the bids and purchase orders. The second reason is that limited funding for purchase order support was provided to UCI. This reduced the priority assigned to the Hughes subcontract by the UCI purchasing office, which was also supporting several other projects.

Another factor that delayed the procurement process was the request for additional items after the purchase order was already processed. Two ways were found to deal with these requests: reprocess the purchase order or create a new purchase order following all the required procurement steps. Disputed items also caused delays, as did changes in scope and delays in other project areas. For example, a delay in executing the lease for the Union Bank building caused a delay in purchasing some items required for the relay site because Caltrans wanted to wait until the lease was finalized before purchasing this equipment.

UCI also noted during the April 1997 interview that University of California regulations required that all equipment purchased by UCI be inventoried and tagged, and that records of the purchases be maintained. However, because UCI had no storage area for the items and direct shipment to the Hughes Fullerton facility streamlined the procurement process, UCI never directly handled the procured items. Hughes assumed the responsibility for the tagging and inventory control. However, this was not a priority for Hughes who was trying to compensate for schedule delays. This caused problems with UCI's inventory records.

The property inventory tags were also an issue with Caltrans. Caltrans maintenance personnel are not permitted to transport or perform maintenance procedures on non-Caltrans vehicles. Exceptions were made to facilitate the FOT. Since the trailers belonged to UCI and not Caltrans during the FOT, storage by Caltrans became an issue. It was decided to store the trailers at Caltrans facilities whenever they were not in use. This required waiving Caltrans regulations that require all vehicles stored at Caltrans facilities to be registered in the Caltrans vehicle inventory.

2.5 Trailer Hitch Redesign and Replacement

The issues dealing with the trailer hitch design reveal the degree of cooperation that is necessary among the various departments concerned with the design, construction, and operation of the trailers. The design requirements for the surveillance trailers did not specify the type of trailer hitch. Mighty Movers, the company that constructed the trailers, attached a standard ball hitch to each trailer. It was later discovered that Caltrans uses a different type of hitch, the hook-and-pintel. This hitch is stronger than standard ball hitches and considerably more secure. The incompatibility between trailer and tow-truck hitches was identified when a Caltrans crew arrived at the Hughes Fullerton facility to transport one of the trailers. The crew was not able to attach their tow vehicle to the trailer. Mighty Movers was contacted to redesign and replace all trailer hitches.

Another issue concerned the relative heights of the hitches on the tow vehicles and trailers. As the final gross weight of the trailers was greater than expected, heavier trucks were needed to tow the trailers. The required trucks were easily located in the Caltrans inventory of tow vehicles. However, when the trailers were mated with the heavier tow truck, a height differential was discovered between the trailer and tow-truck sections of the hitch. Because the tow truck was higher than the trailer, the rear of the trailer was lowered when attached to the truck and, consequently, had insufficient ground clearance. Mighty Movers was again contacted to provide replacement hitches. The final hitch is a height-adjustable hook-and-pintel hitch that is compatible with all Caltrans tow vehicles.

Caltrans has investigated contracting the trailer towing operation. It is unknown whether the need for hook-and-pintel hitches has been addressed with outside contractors.

2.6 Portable Power Generation System

Several issues concerning the liquid propane gas (LPG) generators and battery power system arose. These included operating time between refueling, operating from external commercial AC power, generator fuel selection, battery recharging and maintenance, and photovoltaic charging systems.

2.6.1 Expected versus Actual Operating Time between Generator Refueling

The surveillance trailers required refueling approximately once per month during trailer assembly and systems integration according to Hughes. Refueling rates experienced during the FOT evaluation were obtained later from the trailer logs as part of the I-5 Test. Caltrans expected the average time between refueling to be about 10 to 14 days when the trailers were deployed and operating in automatic mode. This refueling interval is

acceptable to Caltrans for operational trailers, although it would be preferable to refuel less often. At first, refueling the trailers required the attendance of Caltrans personnel to unlock the trailer and supervise the operation. With experience, it was found that the trailer door to the LPG tank could be unlocked the day before the refueling occurred or at an appropriate time when Caltrans personnel were available.

In order to allow volume for propane gas to safely accumulate, the liquid propane tanks on the trailers can only be filled to 75 percent of their maximum capacity. Thus, surveillance trailers can hold 88 gallons of liquid propane and ramp meter trailers 33 gallons. Since the tanks cannot be filled to maximum capacity with liquid propane, the refueling frequency is increased.

Another factor that increased refueling frequency is the demand the electronic components place on generator-produced power. In the original surveillance trailer design, the 170 controller, wide area communications controller, and the 64 Kbps spread spectrum backbone radio were operated with AC power from a battery-driven inverter. All other surveillance trailer systems, including the AutoScope VIP; cameras; pan, tilt, and zoom controls; video compression system; and high bandwidth spread spectrum radios that support video transmission operated directly from AC generator power. The large AC generator power requirement caused the generator to turn on frequently. Conversations with the Hughes Project Manager indicated that a different design, in which all surveillance equipment operates on inverter AC power supplied by batteries, might be preferred. This alternate design utilized a larger battery/AC inverter system that required the generator to operate only when the batteries required charging. Further analysis was conducted to determine the effectiveness of this potential design change. Upon the completion of the FOT, all the surveillance trailers were returned to the trailer manufacturer for installation of the new AC inverter power system as discussed further in Section 2.6.4.

Surveillance trailer refueling was also affected by the increase in scope placed on the trailer systems during the development cycle. The trailers were initially designed to support ramp metering only, but scope creep increased the trailer requirements to allow remote viewing of imagery, remote switching and controlling of surveillance cameras, and the addition of a security camera. This increase in operational capability increased the demands on the battery and generator system, preventing it from operating for as long as desired between refueling.

2.6.2 Operation with Externally Supplied AC Power

The mobile surveillance trailers can operate from externally supplied AC power (i.e., public utility commercial power). The trailers are equipped with a transfer relay, allowing them to be safely switched between generator and external AC power. In fact, Hughes operated the trailers from externally supplied AC power during their development with no technical difficulties. The trailers were not operated from external AC power (with the exception of one trailer in the I-5 Test) during the FOT for two reasons: (1) the partners wanted to test the ruggedness and reliability of the portable power generation system and (2) Caltrans maintenance personnel were not available to provide AC service at all evaluation sites.

When deployed for the FOT, trailer operation from external AC power required Caltrans to install a rugged power cable for outdoor use and devise a locking mechanism for the AC outlet or power source. Hughes offered to assist Caltrans in safely making the connection to external AC power. In fact during the I-5 Test, the surveillance trailer at

Culver Drive was satisfactorily operated from commercial power and experienced less power system problems than any of the other trailers.

2.6.3 Selection of Propane as the Generator Fuel

Propane generators were selected for the mobile surveillance trailers for the following four reasons:

- Caltrans stated from the beginning of the project that they would utilize a contractor for refueling. Therefore, the need for special refueling equipment was not an issue.
- 2. Propane is safe to refuel.
- 3. Gasoline is extremely volatile, especially during hot weather, and presents significant safety hazards making it not desirable.
- 4. Diesel generators would generate visible and potentially harmful exhaust.

Hughes believed that diesel generators would probably provide more reliable operation and be suitable for the trailers. Most of the reliability problems with the propane generators were attributed to deficiencies with the analog generator control circuitry. This control circuit and its associated problems are described in the next section.

2.6.4 Charging and Maintenance of Batteries

The technical problems with the mobile surveillance and ramp meter trailer generator and battery systems can be traced to the original analog control system that regulated battery charging and the purchase of oversized generators. The technical problems included battery failure and generator starter maintenance. The Hughes engineering staff attributes the battery and generator starter problems to over discharging the batteries and commanding the generator to start while it was already running. The analog control system monitored the battery charging voltage and received generator start and stop requests from the wide area communications controller in the form of relay closures. The battery had to be charged to its maximum voltage before the generator turned off at the end of a charge cycle.

Battery Charging Control System - The primary deficiency of the analog control system was that it did not provide repeatable turn-on and turn-off of the generator at precise battery voltage levels, i.e., at predetermined thresholds to optimally maintain battery charge. Another problem with the analog control system was that it could not sense if the generator was on, allowing the generator starter to be engaged while the generator was already running.

The analog control system was replaced with a microprocessor-based system that corrected the lack of repeatability in generator control. The new microprocessor-based system utilizes two analog-to-digital (A/D) inputs to monitor battery charging voltage and generator-on status. The microprocessor-based system provides precise generator start and stop control based on the battery charging voltage reaching programmed start and stop thresholds. It can time-average the battery voltage and ensure that generator start and stop commands are not affected by short-time duration transients in battery

voltage. The system also provides a serial port for monitoring the wind speed indicator and solenoid outputs for controlling automatic mast retraction.

The microprocessor-based power control system appears to have corrected most of the battery charging system problems. Tests show that the generator start and stop battery voltage thresholds can now be adjusted to maintain optimal battery charge in the surveillance and ramp meter trailers. The surveillance and ramp meter trailers require different generator start and stop battery voltage thresholds because different loads are driven by their batteries. Hughes has recommended that Caltrans follow the maintenance procedures specified by the battery manufacturers.

Oversized Generators – The generators purchased for the surveillance trailers were oversized for their intended use, running at about 10 to 15 percent of full capacity. This type of generator operates best, however, at a 50 to 80 percent load. Since the generators were not loaded properly, the piston rings were never seated properly and glazing and carbon buildup occurred. This led to excess oil use. When the oil was low, a protective feature prevented the generator from starting. However, this protective mechanism did not function properly and further contributed to starting problems. It was later determined that isolating the battery that started the generator from the battery that powered the electronic equipment would have allowed better charging protocols to be designed. These problems were later corrected when a new power management and distribution system was designed and installed in the surveillance trailers.

Further enhancements to the battery charging system were recommended by Hughes. They included full disconnect of the DC power system from the battery if the microprocessor-based power control system failed to start the generator during normal operation. The DC power disconnect was designed to prevent the batteries from fully discharging if the generator failed to start and did not charge the batteries as needed.

At the conclusion of the FOT, the portable power generation system for the surveillance trailers was redesigned and a new power system was installed in the six surveillance trailers. The redesign included installation of two 12-volt batteries, reallocation of the equipment powered directly from batteries and directly from the generator, an improved generator auto start control, automatic disconnect of the DC power system, and improved access to the batteries by placing them under the roof hatch access structure inside the trailer.

2.6.5 Photovoltaic Charging Systems

The mobile surveillance and ramp meter trailers do not currently utilize photovoltaic cells to recharge the batteries in the surveillance trailer. Hughes estimated that it would cost approximately \$12,000 per surveillance trailer for a photovoltaic charging system. Caltrans indicated that solar operation of the trailers would not be desirable at this cost. One alternative to full solar operation is to power the security system with solar power. This would allow the security system to remain operational regardless of the charging state of the primary batteries.

Operation of the ramp meter trailers from solar power would be less costly because of reduced power requirements. The primary obstacle to using solar power to charge the ramp meter trailer primary battery is lack of a protected location for the photovoltaic panels.

Both the meter-on sign and the remote signal head that are part of the ramp-metering system do utilize solar power to supplement power supplied by the generator. The solar powered subsystems operated satisfactorily during the FOT. Hughes predicts that these components will run for approximately ten simultaneous cloudy days without a recharge. Their extended operation under solar-only power has not been field-tested.

2.7 Automatic Mast Retraction

In order to accommodate the installation specifications for the VIP and SSR equipment on the surveillance trailers, each was equipped with a retractable mast. The pneumatic mast selected for this application is capable of repeatedly lifting the cameras, their enclosures, and communications antennas. It is compatible with the other equipment contained within the trailers, does not require excessive modification to the trailer's structure, and had previously been used by Hughes with acceptable results.

When the mast is fully extended, the cameras are positioned approximately 32 feet (9.8 meters) above ground level. Econolite specifies this height as the minimum acceptable for roadside video image processing. Evidence of this was demonstrated by the difficulties encountered when Caltrans attempted to operate the surveillance trailers with the masts at less than full extension. Because the trailers sit at the side of a road, the cameras must be as high as possible to minimize shadowing of smaller vehicles by large trucks and the projection of the image from tall vehicles into adjacent lanes. The greater the camera height, the more accurate are the measured traffic flow parameters. Some permanent side-viewing VIP installations use cameras mounted at 60-feet (18.3-meter) heights. When the camera can be mounted over the middle of the monitored lanes, more accurate values of traffic volume, lane occupancy, and vehicle speed can be measured than from the side-viewing geometry (even with lower camera mounting heights).

Although Caltrans indicated that they would prefer a taller mast, attaining the current 32-foot (9.8-meter) height presented challenges. Outriggers were required to protect the trailers against tipping before the mast could be installed. The mast also needed to be stable during strong wind gusts to provide a stable platform for the VIP cameras. Too much movement in the mast would cause the image processor to lose calibration. Mighty Movers reinforced the floor of each trailer with thicker steel plates. This provided additional strength for the mast's mounts and ballast to the trailer.

Still, Caltrans was concerned that strong winds would cause the trailer to tip over or the mast to break. Caltrans requested that the masts be modified to retract automatically whenever strong winds are present. In response, Hughes ordered the necessary modification. The tops of the masts were equipped with wind-speed measurement sensors. When winds reach 70 mi/h (112.7 km/h), a relay is activated to open solenoid valves on the top three sections of the mast, retracting it into a safe position. Only the top three sections are lowered to avoid damaging the SSR antenna that transmits video and data to the relay site. This antenna has to be turned and reoriented manually before full mast retraction can occur.

The automatic mast retraction requirement was added after the initial design specification was released. This modification caused significant delays and presented serious technical and logistical challenges. As of June 30, 1997 (after the Anaheim Special Event Test was completed), the automatic mast retraction feature remained inoperable, delaying the Systems Acceptance Test. By the time the I-5 Test began in Spring 1998, automatic mast retraction had been installed and tested. Some of the FOT partners believe the 70-

mi/h (112.7-km/h) wind requirement placed an undue burden on the design. Others believe the wind requirement could have been met without automatic mast retraction.

Those who argue against automatic mast retraction point out that the trailers are being developed under a field operational test for testing a concept and are not intended to serve as permanent equipment. As such, it is appropriate to emphasize design and cost containment. Caltrans, on the other hand, was concerned about safety. This was a serious liability concern for Caltrans given that in recent years, two large overhead freeway signs had been brought down by wind and one resulted in the death of a motorist.

Those who argue against automatic mast retraction point out that the trailer structure is sufficient to protect against trailer tip over in strong wind. Furthermore, the mast structure is adequate to protect it from snapping. The worst case scenario is that a strong wind may cause the upper segment of the mast to break off, causing it to swing down and hang by the attached cables. These arguments, however, were formulated only after the trailers were delivered and team members had a chance to work with the trailers. Prior to trailer delivery, much was unknown about the strength of the trailer components. As such, many team members were motivated to take extra precautions.

2.8 Caltrans TMC System Integration

System integration issues included surveillance trailer and camera selection using the Automated Traffic Management System (ATMS) TMC software and display of trailer data on the TMC workstations.

2.8.1 Camera Selection Using the TMC Freeway Management Software

The freeway management software developed for the Caltrans District 12 TMC by National Engineering Technology (NET) did not exist when the Mobile Surveillance and Wireless Communications FOT Project was started. The remote-site user interface planned when the FOT was first initiated was PC based. The decision to increase the capabilities of the mobile surveillance trailers to include video image switching and camera control using the workstation-based TMC software significantly changed the scope of the software project and added new integration issues not previously planned. Additionally, some trailer control functionality was lost because of the integration of controls into the freeway management software, including the ability to monitor battery voltage. The camera control issues and their resolution are described below.

NET controlled the mobile surveillance trailer cameras with the freeway traffic management software by generating camera control commands transmitted through a terminal server. Hughes camera control software then passively listened to the commands and performed the camera movements without providing feedback to the TMC software. The primary problem encountered during the integration of the camera controls into the freeway management software was that NET could not reliably send camera control instructions from their terminal server to the Hughes interface. To support camera control and system troubleshooting, Hughes wrote a diagnostic program that showed when the Hughes software was receiving instructions from the TMC software. The diagnostic program allowed operators to determine if a surveillance trailer camera control problem was due to TMC software not providing the commands to the Hughes software, or due to Hughes software not receiving the commands and correctly transmitting them to the surveillance trailer. NET solved most of their terminal server problems within a few days. Caltrans and Hughes agree that this part of the integration is complete.

An additional video integration issue was related to the video switch in the TMC. This switch, which is not full-matrix but a tiered switch, requires surveillance video to enter the TMC on a single input. This use of a tiered switch, combined with the TMC database design, means that the TMC can view only one trailer video source at a time. Additional issues pertaining to video switching and control limitations encountered at the District 12 TMC, Anaheim TMC, UCI-ITS Laboratory are discussed in Section 2.10.

The final surveillance trailer camera integration problem relates to updating the District 12 TMC device database when a surveillance trailer is moved. Personnel at the TMC must modify the database to reflect the new trailer location and then restart the application software. If a new trailer icon is created, TMC software communication processes must also be restarted. If the database is not updated, the trailer icon on the workstation map will not reflect the actual trailer location. However, if the trailer location icon is updated, the data gathered at the previous trailer location are automatically removed from the database. This may present a problem if it is necessary to retrieve the previous data for later use. A solution may be to add alpha characters or in some other way modify the trailer name each time the trailer is moved. In this manner, the computer program will think a new trailer has been added to the array. The drawback with this approach is that the map will eventually become cluttered with icons representing nonexistent trailer locations.

Hughes and Caltrans believe that the system integration issues relating to display and control of camera video from the NET software are complete and have been resolved satisfactorily. Caltrans has stated that although the camera switching and controls are not optimal, they do perform according to the design specifications. Some care is needed in selecting cameras on a trailer using the icons at the workstation because the individual icons are closely spaced.

2.8.2 Integration of 170-Controller Data with Front End Processor

One of the issues affecting the integration of the 170-controller data in the surveillance trailers with the TMC Front End Processor (FEP) was the delay imposed by the communications backbone data transfer protocol. This delay caused the FEP to timeout while waiting for polled data to arrive from the surveillance trailer. The problem is that the surveillance trailer wireless backbone can not guarantee a response to polls from the FEP within the required 100 milliseconds. To resolve the timeout problem, the Hughes software continuously collects170 data received over the wireless SSR communications backbone and stores it locally within the TMC. The locally stored data are then retransmitted to the FEP within the required 100 milliseconds of being polled. The temporary storage of the 170-contoller data causes the FEP to receive data that is about 30 seconds old. The 30-second latency does not appear to have a negative effect on system operation due to the general slowness of the TMC software in displaying the 170-controller data on the graphical user interface at the TMC workstations.

If desired, the age of the 170 data supplied to the FEP from the mobile surveillance trailers can be decreased by upgrading the priority of the communications packets containing FEP polls and their responses over the wireless backbone. The reduction in 170 data packet response time would come at the expense of reduced responsiveness of the camera control system, which is not desirable.

2.9 Data Capture and Presentation

Each surveillance trailer is equipped with an AutoScope 2004 VIP whose outputs emulate inductive loop data. The VIP analyzes traffic video imagery to generate traffic data such as vehicle count, lane occupancy, and vehicle speed. Much discussion during the FOT dealt with interpreting and utilizing the emulated loop output data. The ability of the AutoScope to interface with the 170 controller and thereby potentially control ramp metering has been demonstrated as part of the FOT.

As of the conclusion of the FOT, the polled 170-controller data from the surveillance trailers had not been integrated with the District 12 TMC software such that they were displayed on a workstation graphical user interface. The evaluators also observed that the polled 170-controller data from the permanent inductive loops were not always updated in a periodic manner. Another issue that affected the transmission of 170controller data to the TMC was based on a Caltrans observation that the wide area communications controller crashed intermittently and then rebooted itself. This behavior was more frequent as the number of surveillance trailers online increased from one to six. Discussions were held with the ATMS software contractor and with Hughes concerning these issues.

Remedies were attempted, but the VIP data could not be accessed from the ATMS for the duration of the FOT. Consequently, the I-5 Test Evaluation Plan was modified to bypass this interface. Two laptop computers were used instead to poll and record data from the 170 controllers in the surveillance trailers (VIP data) and roadside cabinets (ILD data).

Only the District 12 TMC has purchased an AutoScope supervisory computer. Therefore, they are the only agency that can configure AutoScope detection zones and access the VIP traffic volume, lane occupancy, and vehicle speed data. For the Anaheim TMC or the UCI-ITS Laboratory to acquire VIP data from the trailers, they would need to purchase an AutoScope supervisory computer or some other hardware/software combination capable of displaying the loop-emulated outputs produced by the VIP. Neither agency has an immediate need to view these traffic data.

Anaheim has found it prohibitively expensive to perform the software modifications necessary to integrate the VIP trailer data into their traffic management system and has decided not to purchase the supervisory computer. However, UCI-ITS laboratory will eventually be able to receive surveillance trailer data over the fiber optics backbone that connects it to Caltrans TMCs.

Hughes was to provide three data loggers to record the emulated loop data and other data. The data loggers were to output a stream of comma-delimited text corresponding to the recorded sensor data or other information input to the data logger (such as "vehicle presence" or "communication packet dropped"). The comma-delimited format presents a minor problem for researchers seeking readily available PC-formatted traffic statistics, such as vehicle-by-vehicle detections or a series of five-minute vehicle counts or fiveminute average vehicle speeds. A plan for resolving some of these issues was proposed, e.g., performing relatively simple data averaging in real time and recording the results on the data logger, and using commercially available software to strip out the data fields. However, these procedures and satisfactory data logger operation were not demonstrated during the FOT.

2.10 Shared Camera Selection and Control Among Agencies

An objective of the wide-area wireless communications network was to allow the Caltrans District 12 TMC, Anaheim TMC, and UCI-ITS Laboratory to share remote control and access to video and data transmitted from a surveillance trailer. This would provide TMC operators and researchers real-time traffic flow information that might otherwise be available at only one facility.

With the original design of the video switching and camera control system, only the District 12 TMC had full, autonomous control of the system. The Anaheim TMC would contact the District 12 TMC by telephone to request a particular camera image or to move a camera left, right, up, down, or have the lens zoomed. Midway through the project, this arrangement was deemed unsatisfactory to Anaheim TMC personnel in planning for their key role in the Anaheim Special Event Test. In response, Caltrans asked Hughes to upgrade the video switching and camera control capabilities at the Anaheim TMC. The UCI-ITS Laboratory remains without autonomous video switching and camera control.

2.11 Relay Site

Wireless communications to and from the mobile surveillance trailers are limited to line-of-sight distances. Therefore, it was necessary to locate and build a relay site to retransmit video and data from the trailers to the TMCs and UCI-ITS Laboratory. Video and data reception were also required at the Hughes Fullerton facility during trailer systems integration as shown in Figure 2-1. In addition to being in the line-of-sight of the trailers, the relay location had to be free from interference from electronic noise and blockage by fixed objects, such as buildings and trees, that attenuate signals.



Figure 2-1. Trailer assembly at Hughes in Fullerton, CA showing ramp trailers and signal heads in foreground and surveillance trailers in background

2.11.1 Relay Site Selection

Several potential locations were identified for the relay site, including a local radio station tower, the rooftop of the Union Bank building, and the summit at Santiago Peak in central Orange County. Santiago Peak, because of its 5670-foot (1728-meter) elevation, could provide a significantly wider area of coverage than the other locations. However, the unimproved road leading to Santiago Peak created installation and maintenance difficulties and increased expense. Furthermore, the reduction in the scope of the FOT relaxed the requirement for wide-area coverage extending into southern Orange County. The local radio station tower option was also rejected because of potential interference and the prohibitively high rent expense. Following extensive line-of-sight and signal-strength testing, the rooftop of the Union Bank building in Santa Ana was selected as the relay site location.

2.11.2 Lease Agreement

UCI negotiated a lease agreement with the Segerstrom Office Center, the owner of the Union Bank building. The terms of the lease set the monthly rent and stipulated several other conditions that ultimately increased the overall cost of the relay site. One condition was to modify the rooftop by creating walkways constructed of resilient materials. Furthermore, liability and fire insurance policies providing one million dollars of coverage needed to be purchased. Lastly, the installation of valuable communications equipment on the roof of the building could potentially increase the building's market value, as assessed by the local tax authority. The terms of the lease agreement dictated that any increase in annual property taxes caused by the additional equipment would be the financial responsibility of UCI. The relay site selection process, culminating in a lease, was a time consuming task taking fifteen months to complete.

2.11.3 Relations with Union Bank Building Management

The Union Bank relay site has worked exceptionally well according to the Hughes Project Manager. This site, which had some anticipated access problems, has been easy to use and much less expensive than the other alternatives. The building's managers have been accommodating in providing rooftop access to Hughes and Caltrans technical personnel, even on weekends. The building's managers have also provided advance warning to Hughes prior to scheduled power outages. Power outages and power "spikes" within the Union Bank building can cause technical problems at the relay site. Fortunately, unplanned power disruptions for which advance warning cannot be given are infrequent.

2.11.4 Coverage Area

The antenna on top of the Union Bank building has met its objective of supporting wireless communications. Hughes is extremely pleased with the performance of the 270-degree sector coverage of the antenna. The antenna provides a 23-dB path margin for communications at the 5-mile (8.0-km) boundary. Even communications between the relay site and trailers parked at the Hughes facility 8.5 miles (13.7 km) away have been reliable during system development. Hughes has stated that they have not yet situated a trailer within the specified five-mile (8.0-km) line-of-sight operational radius that could not be supported. The worst case encountered was the surveillance trailer location near the First Street onramp to I-5. Obstructions that at first hindered line-of-sight communications to the Union Bank relay site were alleviated by moving the trailer a couple of hundred feet from its initial location.

2.11.5 Proposals for Increasing Deployment Range

During the FOT, trailer deployment was limited to locations that were within range of the relay site on top of the Union Bank building in Santa Ana, CA. The relay site permitted wireless communication within a five-mile (8-km) radius as long as the line-of-sight to the surveillance trailer was unobstructed. This range was adequate for planned FOT activities.

Several meetings of the PMT were held to discuss five options for extending the effective range of the trailers that were presented by Hughes. These were the construction of a new retransmission site on the top of Santiago peak in Orange County, a series of relay sites along the I-5 and SR-91 corridors linked with SSRs, a combination of the Santiago

Peak and local relay site approaches, integration of local relay sites with existing fiber optics lines, and use of RF amplifiers to propagate signals along the relay path. At present, no action has been taken to implement any of the alternatives.

2.12 Trailer Security

Since the equipment located within each of the surveillance trailers is valuable, the need for adequate security became apparent. The chosen security system is cellular-based. Alternative designs that were considered include a radio-based system and a private security service. The radio-based system was rejected because it provided a smaller area of coverage and offered no cost savings. The use of a private security service was also rejected because of cost.

Security system intrusion sensors are located on the surveillance trailers and the ramp meter trailers. Other parts of the security system, located in the surveillance trailer, include a wireless receiver, a control panel/communicator, and a cellular telephone interface transmitter. The wireless receiver accepts status notifications, such as "ramp meter trailer fuel low", and security alert signals that warn of a potential intruder. The wireless receiver passes these signals through the control panel/ communicator to the cellular telephone interface transmitter and on to the cellular telephone network. The receiver at the District 12 TMC is "dialed up" by the cellular telephone network to deliver status notifications and security alerts.

The surveillance trailer also contains a fixed-position black-and-white camera from which TMC staff can view activity at the door to the trailer and a loud-sounding alarm that is triggered upon trailer break-in. Adding the fixed-position camera represented a change in scope in the security system design that was initiated mid-way through its implementation. Once the TRT determined that a security surveillance camera was needed, and the option of relying on the pan, tilt, zoom (PTZ) mast-mounted color camera for security was rejected, it was decided that a fourth camera would be added to each surveillance trailer. The TRT reasoned that the PTZ mast-mounted color camera would normally be monitoring traffic flow and would, therefore, not be available for security surveillance

One area of the TMC has been designated as the trailer security and system monitoring station. It contains a workstation, telephones, and dot matrix printer that are monitored by District 12 and CHP personnel. Each time the security system delivers a signal to the TMC, an "attention" tone is sounded and the corresponding output is produced at the printer. Standard operating procedure requires that a TMC operator go over to the security station, read the output, and determine whether a security alert has been received. If the TMC operator finds the output to be a low priority status notification, no action is taken. If the TMC operator finds the output to be a high-priority security alert, the operator requests that a CHP officer be dispatched to the trailer.

The graphical user interface (GUI) at the security workstation provides the following information:

- 1. Date
- 2. Time
- 3. Battery voltage in both the surveillance and ramp meter trailers
- 4. High and low voltage settings that control generator turnon and turnoff

- 5. Outside and inside temperatures at a surveillance trailer
- 6. LED status that shows the state of the generator/battery system
 - Yellow to indicate voltage is within the preset high/low range
 - Yellow flashing to indicate the generator is on
 - Red to indicate the voltage is below the low-voltage threshold
 - Red flashing to indicate the generator tried to start three times and failed
 - Green to indicate the voltage is above the high-voltage threshold
 - Green flashing to indicate the generator is on and charging the battery
- 7. Historical data in five-minute intervals from a saved database file
- 8. Alarms that indicate a system malfunction.

Operating the security system presented challenges early in the project. For instance, one trailer at a freeway onramp sustained minor damage because of an attempted breakin that went undetected. Additionally, early communication between project staff and the CHP was incomplete. Consequently, officers were uncertain as to their responsibility when responding to trailer security alarms. Furthermore, it was found they did not know the exact location of each surveillance trailer.

Perhaps the most serious problem identified in conjunction with the security system was the procedure by which the TMC operators were detecting and responding to potential break-ins in Spring 1997. During these months, the TMC "attention" tone would sound dozens of times each day. Initially, a member of the TMC staff would go over to the security station and investigate the cause of each tone. Finding each case to be one of a status notification that required no immediate action, rather than an intruder-initiated security alarm, the TMC staff eventually lost interest and stopped checking the security system output. This is a classic case of "The Boy who Cried Wolf." The alarm is no longer sounded for a status notification.

Two other issues were identified. The first was that at least one TMC operator does not hear the TMC "attention" tone when it is sounded. The particular pitch used by the system is within a range of tones that are undetectable by persons with hearing difficulties. Therefore, a visual indicator was installed. The second is that the output produced by the printer is encoded. As such, it cannot be interpreted without the assistance of a separate sheet of paper that explains what each code means. Such a paper is now taped to the printer or left nearby in a clear protective folder.

2.13 Technical Training

Another aspect of the FOT was the technical training provided by Hughes for the benefit of Caltrans maintenance and engineering personnel responsible for trailer operations. Specific training dates were agreed to by the PMT based upon the project schedule provided by Hughes. Formal training on the AutoScope VIP was held the first week of October 1996. Econolite delivered this training at their facility in Anaheim, CA. In attendance were three Caltrans maintenance and engineering personnel, the Caltrans New Technology project manager, and representatives from both Hughes and the Evaluation Team. The training was held simultaneously with a tour of an incomplete surveillance trailer at the Econolite facilities. Originally scheduled to coincide with trailer deployment and System Acceptance Test (SAT) activities, this training session was completed eight months prior to deployment and SAT because of project delays. Consequently, refresher training was necessary.

Some uncertainty existed as to what training was to be provided by Hughes. The contract required eight hours of formal maintenance training and no less than twelve hours of on-the-job (OTJ) operations training. Midway through systems integration, the Hughes project manager indicated that he believed Caltrans had received the specified number of OTJ training hours. Caltrans disagreed, indicating that the lead Caltrans engineer had not had demonstrations of all the systems. The engineer's familiarity with the trailers gained through his close working relationship with the Hughes personnel who assembled the trailers was not adequate preparation for him to train other Caltrans personnel. Hughes refused to provide operations training beyond the experience the Caltrans engineer received from working on the trailers.

Hughes personnel, however, did demonstrate the care and handling of the surveillance trailers during a half-day training seminar at the Hughes Fullerton site on the same day the AutoScope training occurred at Econolite. This included a demonstration of hitching the trailer, lowering and raising the stabilizer legs and retractable mast, starting and shutting down the generator, and replacing the oil and battery fluids. The training did not include a demonstration of ramp meter trailer use because the trailers were not completed at the time. It was understood that this training did not adequately cover the safe handling of propane. In a personal interview in January 1997 with the lead Caltrans engineer, he indicated that the special requirements of handling propane-filled generators were not taken into consideration when structuring training sessions and stated this item should have been included, since no other Caltrans equipment utilizes propane as its primary fuel.

Most of the training requirements were fulfilled through OTJ training that allowed Caltrans personnel to observe and ask questions during initial trailer setup and test. Although some maintenance personnel indicated that they would have appreciated being trained prior to their initial contact with the equipment, OTJ training may have been the second most effective and cost-beneficial method of providing adequate training in terms of minimizing the number of person-hours required.

Caltrans District 12 TMC operators required an informal training session to learn how to pan, tilt, and zoom the cameras, switch between cameras, and remotely turn the trailers on and off. Again because of project delays, the TMC training demonstration was conducted many months before TMC operators were able to utilize these features. As result, most operators had forgotten everything from the demonstration and had to relearn the procedures through OTJ.

Anaheim declined participation in the full series of planned training activities because they could not afford the staff time. Anaheim TMC personnel received a demonstration of the trailer and camera control interface keyboard on the night of the initial deployment for test activities. This consisted of a Hughes representative demonstrating all the features of the software interface and allowing the Anaheim operator time to practice and ask questions regarding the procedures. An instruction guide was prepared and provided to the Anaheim TMC operator. This training was found to be adequate and beneficial because of the ease of use of the keyboard and because it was quickly reinforced through experience during operation of the trailers that evening.

2.14 Trailer Transport and Setup

Issues related to trailer transport and setup were addressed at different stages of the project and were evaluated in both the Anaheim Special Event and I-5 Tests. As such, most aspects of this activity are contained in other sections. The issues identified below were uncovered outside of the specific Anaheim Special Event and I-5 Tests during meetings and system testing.

- 1. When loading the trailers, beware of gross weight limitations. The ramp meter trailers exceeded the legal weight limit when the stabilizing plates were added.
- 2. When towing the trailers, beware of low hanging tree branches and other height obstructions. The whip antenna atop a trailer was damaged during one transport event.
- 3. Position the trailer with the door facing the freeway. It is believed that such positioning would have prevented an attempted trailer break-in.
- 4. Locate the trailer away from ant hills, if possible. Ants are attracted to the warmth of the equipment. They can eat wire insulation and cause electrical short circuits.
- 5. Position the trailer and rotate the mast such that the antenna will not block the camera from viewing desired traffic flow patterns.

2.15 Ramp Meter Trailer Design

The items identified in this section were noted during preliminary testing of the ramp meter trailers before the I-5 Test was begun.

- 1. Each ramp meter trailer is paired with a particular surveillance trailer. A given ramp meter trailer cannot be made to work with any other surveillance trailer without reprogramming the SSRs.
- 2. Initially attached to each signal head was a sign that read either "One Car Per Green" or "Two Cars Per Green." As all ramps in the FOT were programmed for "One Car Per Green", some signs had to be replaced. In future day-to-day operations upon completion of the FOT, spare signs should be stored on the ramp trailers to accommodate both metering configurations.
- Onramps with metering signals on both sides of the ramp require that the two signals be synchronized. This task is performed by the control data sent by the surveillance trailer to the ramp meter trailer.

2.16 Equipment Costs

The equipment costs for the surveillance and ramp meter trailers, Caltrans District 12 TMC, Anaheim TMC, ITS laboratory at UCI, and the relay site are shown in Tables 2-1 through 2-6. Table 2-7 summarizes the costs for the equipment listed in the first six tables. Prices for some equipment, such as the security system telephones and security alarm receiver and printer located in the Caltrans District 12 TMC, were not available. The cost for the winch and hydraulic crane that were used to service the generators is shown on the District 12 TMC equipment list, although it is a service item. Figure 2-2

6

illustrates the relative contributions of the six surveillance trailers, three ramp meter trailers, District 12 and Anaheim TMCs, UCI-ITS Laboratory, and the relay site to the total equipment expenditure. The six surveillance trailers represent 70 percent (\$749,778) of the total equipment cost, the three ramp meter trailers 16 percent (\$171,540), the District 12 TMC 5 percent (\$50,552), the Anaheim TMC 2 percent (\$23,654), the UCI-ITS Laboratory 2 percent (\$24,399), and the relay site 5 percent (\$57,109). One surveillance trailer and its associated equipment therefore cost approximately \$125,000 and one ramp meter trailer and its equipment approximately \$57,000.

Table 2-1. Surveillance trailer equipment

Surveillan ce Traile r	Item	Price
TalerBody	MightyMoverModel 6.5NHMFA:6115C Includes generatorLPG tank, chager, batteles.compressor, teelscoping mastairconditioner	
	sabilizes, equipment acks, hitch moidrations	\$48403
Equipment	Wide Aea Communications Contoller	\$6750
	Inteligent Power Cort olle,r PulizzIPC 3102 2157	\$1074
	Global Postioning System Receive Antenna, Timble Pacer 400	\$645
	Cellul a Security System with 2WayVoice	\$5667
	SpreadSpectum Ralio (S&) @mponents	
	192 Klops SSR, Clink ALMI 9E-0 OAE	\$2795
	26 Kops SSR, Clink NSPALS256EI A530	\$4495
	64Kbps \$5RCylink LASM6405 AE EIA-530	\$2995
	2vayRF @wer Spliet/Combine; ClinkZAPD-4-N	\$120
	Bust Synch Cable 139 1010	\$50
	Ygi Antenna, Cushc aft Signals RC904N	\$40
	Seni Parebolic Antenna, Cylink 08/7903	\$110
	Andog 8 Chamnel Radio, LineaWR 168R	\$149
	NTSC Video Monitor JC 14 TM 431SU	\$330 \$3.5
	Kethoad, FC, Mtsumi RQE9 9ZC1 3	\$35
	Pan and TillAssembly American Dynamics AD123624 (dy 4)	\$3183
	Receive / Drive / for he Pan Tilt Zoom, American Dynamics AD1641S2 (xty4) Video Distruction Amplife, rAmerican Dynamics AAAD142 (xty4)	\$1852
	Video Patch PaneAnixerCatabgue 12/387	\$820 \$206
	Video Switcher Unit American Dynamics AD 1404A	\$690
	Came a Contol Kelpoard, American Dynamics Model 166B	\$499
	Video Encode r Enerdyne ENC20 0 0R2	\$6912
	Video Image Porcesor, Econolite Attoscope 20 4 P1 C1 M1 1/2 RM	\$18320
	AutoscopeB &W Cameass 16, 25mmlenses (Cohu) (dy 2)	\$4741
	Color Carnera with Motorized 880 mm Zoom Lens Pelo POHC4602)	\$1726
	SecurityB&W Camera (BurleTC355AC)	\$328
	Color Suveillance @mera Envi onmental Enclosure Pedo EH4 72 22	\$250
	Burle Can ea Enclosures wHeaterFan, Burle TO 3832 (qty)	\$561
	170E Trafic Cort pller	\$850
	Geneator Auto StarPaneland Electronics	\$1056
	Weather Station, Poet Brothess Ultime to 500	\$239
	Wind Moni or YG6 68 1 00 S 74 4	\$744
	PowerTransforme/Cicuit Beaker	\$40
	Elect pmechanical RelayBoard, Compute rBba ds CIQERB24	\$189
Mis e llaneous	Diodes Coil, & Vairous Elet pnics	\$840
	Solenoid Air Vaule	\$900
	Coi \$,Socktes	\$123
	Junior Gage Head Kit (fir LPG fuel level monitoring)	\$894
	Cicuit Beakes	\$201
	DCDC Solid State Power Convertes	\$105
	Cables	\$783
	Plugs, Camps, Guide Pris	\$552
	Items #82 Cables)	\$1733
	Items #89 Cables)	\$1568
	Connectors	\$100
	9 18VDC PowrSupply	\$300

To a I \$124,963

Table 2-2. Ramp meter trailer equipment

Ramp Meter Trailer	Item	Price
Trailer Body	Flex-O-Lite TRFC Model 2001 Special. Includes generator,	
	LPGtank, charger, battery, signals, cables, solar panels, signal and meter on sign supports, tool chest, hitchmodifications	\$40,334
Equipment	Wide Area Communications Controler	\$6,750
	Analog1 Channel Radio, Linear MR161T Analog8 Channel Radio, Linear MR168T	\$1 <i>2</i> 3 \$1 <i>4</i> 1
	Analog1 Channel Radio, Linear MR161R	\$123
	Intelligent Power Cortroller, Pulizzi IPC 3102-2157	\$1,074
	Generator Auto-Start Panel	\$1,056
	Programmable Tiny Drive Controller	\$169
	Spread Spectrum Radio (SSR) Components:	
	192 KbpsSSR, Cylink ALM19E-00AE	\$2,795
	Digital SSR, Digital Wireless WIT 915 (qty 2)	\$1,976
	Yagi Antenna, Cushcraft Signals PC904N	\$40
Signal Lights	Signal Lights - Halogen (qty2)	\$34
Miscellaneous	Signal Lights LED (Red 8", 12" 2 each; Amber 8" 4 each) Junior Gage Head Kit	\$2,067 \$1 <i>4</i> 9
Miscalaricous	Diodes, coil , & various electronics	\$140
	Cables	\$130
	Padlock (qty4)	\$44
	DC-DC Sdid StatePo wer Converter	\$35
	To tal	\$ 57 ,1 80

Table 2-3. Caltrans District 12 equipment

Cal trans District12 TMC	Item	Price
Backroom Equipment	Video Decoder, Enerdyne DEC 2000R2 (qty 2)	\$14,400
	Wide Area Communication Controller	\$6,750
	Digital Service Multiplexer, Digital Link DL100 Encαe	\$3,737
	Airlink T1 Cable	\$296
	T1 Access Unit, Cylink ALT-OUAAAU	\$1,495
	GPS Receiver & Antenna, Trimble Placer 40	\$64.5
	SVGA Monitor, NEC 14" Multisync C40 0	\$365
	NTSC Video Monitor, JVC 14 TM-131SJ	\$330
	Keyboard, PC, Mitsumi KPQ-E99ZC-13	\$35
	Cabinet, Free Standing	\$2,111
	Camera Control Keyboard, American Dynamics Model 1676B	\$499
Rof Equipment	Parabolic Solid Antenna, 2ft diameter, Cylink 0807-0032	\$890
	Roof Mount (Non Penetrating), Mororeflect 99540	\$499
	Yagi Antenna, Cushcraft/Signals PC904N	\$40
	T1 SSR Radio, Cylink ALT1-4XAA	\$7,995
Test Equipment	Bit Error Rate Tester	\$495
	Auto Sope Supervisor Computer, Bilink AS-SC486	
	with modem, digitizer, and software	\$8,501
Service Equipment	Winch and Hydraulic Or ane	\$1,469
	Total	\$50,552

Table 2-4. Anaheim TMC equipment

Anaheim TMC	It em	Price
	Spread Spedrum Radio (SSR) Components:	
	256 Klps SSR, Cylirk NSPALS 256 EIA - 530	\$4,495
	64 Ktps SSR, Cylink AlSM64-05 AEEI A-530	\$2,995
	BurstSynolo Cable 13981-010	\$50
	2-way RF Power Splitter Combiner, CylinkZAPD-4N	\$120
	Tripod, Non-Penetating, 8-ft Antenna Mount, Microflet 91199	\$345
	Paabolic Grid Antema, 3-ft diameter, ComsatRSI P24A36GN1	\$795
	Yagi An tema, Cushoraf t/Signals PC904N	\$40
	Wide Area Communications Cont oller	\$6,750
	Camera Control Keyboard American Dynamis Model 1676B	\$499
	Vide o Decoder, Enerdyne DEC 2000 R2	\$7,200
	Vide o Manitor, JVC 14", TM-131SU	\$330
	Key boa rd, PC, Mitsumi KPQ-E99ZC-13	\$35
	T ct al	\$2 3 65 4

Table 2-5. UCI-ITS Laboratory equipment

UCI-ITSLabora tory	l te m	Price
Equipment in bldg:	Video Decader, EnerdyneDEC20 00R2	\$7,200
	Wide Area Communications Controller	\$6,750
	SVGA Monit at, NEC 14" Multisync C400	\$365
	Video Monit ar, JVC 1 4" TM-13 1SU	\$330
	Keyboard, PC, Mit sumi KPQ-E99ZC-13	\$35
Equipment on roof:	Rectangular Non-Penetrating Antenna Mount, Microllect 99 54 0	\$499
	Equipment Cabine t	\$500
	Spread Spectrum Radio (SSR) Components:	
	256 Ktps SSR, Cylink NSPALS 256 EIA-530	\$4,495
	64 Kbps SSR, Cylink ALSM64-05 AE EIA-530	\$2,995
	2-way RF Power SplitterCombiner, Cylink ZAPD-4-N	\$120
	Ya gi Antenna, Cushcraff Signals PC 90 4N	\$40
	Parab dic Grid Antenna, 3-ft diameter, Consat RSI P 24A36GNI	\$795
	S-BandIsolato, Cylink	\$ <i>2</i> 75
	Total	\$24, 399

Relay Site	It em	Price
	Spread Spectrum Radio (SSR) Components:	
	256 Klops SSR, Cylink NSPALS256 EIA-530 (gty 3)	\$13,485
	64 Ktps SSR, CylinkALSM64-05AE EIA-530 (dy 2)	\$5,990
	Digital Sevice Multiplexer, Digital Link DL100 ENC-P-06	\$3,737
	2-way RF Power Splitter/Combiner, Cylink ZAPD-4-N (¢y 2)	\$240
	3-way RF Power Splitter/Combiner, Cylink ZA30D-4-N	\$180
	T1 SSR, Cylink ALT1-4XAA	\$7,995
	T1 Mounting Kit	\$150
	T1 Access Unit, Cylink ALT1-OUAA-AU	\$1,495
	Artenna Cables and Mounting Kits	\$1,900
	Omni Antenna, Vertically Polarized, SCALA MMV12/A MMDS/ITF	\$16,848
	Artenna, 3-ft Parabolic Grid, Comsat RSI P 24 A36GN1 (qty 2)	\$1,590
	Artenna, 2-ft Parabolic Solid, Cylink 0807-0032	\$890
	Rectangular Non-Penetrating Antenna Mount, Mcroreflect 99540	\$425
	Intelligent Power Controller, Pulizzi IPC 3102-2157	\$1,074
	Junction Boxes	\$300
	Equipment Cabinet	\$500
	Roof Deck Walk Pads	\$310
	To tal	\$5 7, 10 9

Table 2-7. Equipment cost summary

Item	Unit Cost	Quantity	Tdal
SurveillanceTrailers			
Trailer, Generatr, Mast etc.	\$48,403	6	\$ 290, 41 8
Equipment	\$76,560	6	\$ 459, 36 0
Subtotal	\$124,963	6	<i>\$749, 778</i>
Ramp Meter Trailes			
Trailer, Generatr, Signals, etc.	\$40,334	3	\$ 121,002
Equipment	\$16,846	3	\$50,538
Subtotal	\$57,180	3	<i>\$171,5</i> 40
Caltans Distid 12 TMC	\$50,552	1	<i>\$50, 5</i> 52
AnaheimTMC	\$23,654	1	\$23, 654
UCI-ITS Laborato iy	\$24,399	1	\$24, 399
RelaySite	\$57,109	1	<i>\$57, 109</i>
Grand Total			\$1,077,082

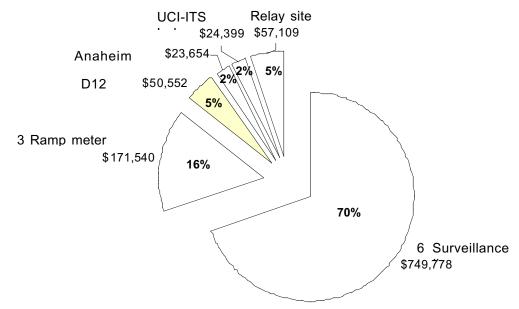


Figure 2-2. Relative contributions of the six surveillance trailers, three ramp meter trailers, District 12 and Anaheim TMCs, UCI-ITS Laboratory, and the relay site to the total equipment expenditure

3. Anaheim Special Event Test Evaluation

This section describes how the evaluation plan developed for the Anaheim Special Event Test was applied and discusses the test results. This test utilized three self-powered surveillance trailers to obtain and transmit video images via wireless SSR communications to the Anaheim TMC and the Caltrans District 12 TMC. Anaheim had the primary interest in the video and used it to modify traffic signal phases. The surveillance trailers were placed at intersections near the Arrowhead Pond in Anaheim where permanent video surveillance equipment did not exist.

3.1 Objectives

The five objectives of the Anaheim Special Event Test were designed to evaluate the use of the mobile surveillance trailers for special event traffic management.

- Objective1 examined the deployment of surveillance trailers to support a special event in a city within range of the relay site. To meet this objective, Caltrans and Hughes transported and set up the trailers and prepared written statements about the experience. The evaluators coordinated data collection, observed trailer deployment, received and analyzed data, and interviewed personnel.
- Objective 2 evaluated how well the surveillance trailers operated and supported
 the special event traffic management. To meet this objective, Anaheim TMC
 personnel observed the camera images and recorded test data. The evaluators
 coordinated data collection, observed camera use, received and analyzed data,
 and interviewed personnel.
- Objective 3 assessed the relative impact of the added video surveillance on special event traffic management. Anaheim TMC personnel observed traffic flow on the streets and exiting parking lots surrounding the Arrowhead Pond and recorded test data. The evaluators coordinated data collection, observed traffic flow, received and analyzed data, and interviewed personnel.
- Objective 4 assessed institutional issues, benefits, and costs related to sharing resources between agencies in support of special event traffic management. Caltrans and Anaheim personnel negotiated the use of the trailers by Anaheim and prepared written statements. The evaluators observed negotiations, received and analyzed written statements, and interviewed personnel.
- Objective 5 explored institutional issues, benefits, and costs related to sharing
 information between city and state agencies. Caltrans and Anaheim personnel
 negotiated the sharing of the video imagery and prepared written statements. The
 evaluators observed video sharing, received and analyzed written statements,
 and interviewed personnel.

3.2 Test Description

The Anaheim Special Event Test was conducted in conjunction with five special events, namely hockey games played April 1st, April 4th, April 9th, May 6th, and May 8th, 1997. At a PMT meeting following the May 8th game, it was determined that extending the test to additional events would not add useful information and, after approval by the partner agencies, the test was concluded.

Prior to the April 1st event, Caltrans District 12 delivered three surveillance trailers to the Arrowhead Pond area in the City of Anaheim. During the test, the surveillance trailers were under the control of the Anaheim TMC, which had the ability to power up and power down the trailers, select and position cameras, and select the image to be displayed on a monitor in the TMC. The video imagery could also be viewed at the Caltrans District 12 TMC. In this test, pan and tilt control were permitted for the two blackand-white VIP cameras since the VIP itself was not used. Hence, these black-and-white cameras were simply used as additional surveillance cameras. Pan. tilt, and zoom control was available for the color surveillance camera. Video imagery from the black-and-white security camera was also transmitted to both TMCs. Each trailer was equipped with a security alarm system connected to the District 12 TMC.

The images from the cameras were used by the TMC operators as if they were produced by a permanent camera. The operations personnel performed all other special event tasks in accordance with the Anaheim TMC Special Event Management Standard Operating Procedures. During the hockey games, when no manual traffic management was required, the TMC operations personnel worked with the Evaluation Team to record data in accordance with the Anaheim Special Event Test Evaluation Plan.

The Evaluation Team conducted an independent evaluation of the test results. The PMT supported the evaluation by providing the Evaluation Team with written reports concerning test activities, technology issues, institutional issues, and costs.

3.3 Test Evaluation

The measures of performance and data gathered to support the Anaheim Special Event Test objectives are discussed in this section.

3.3.1 Objective 1 –Portability

The first objective evaluated the portability of the surveillance trailers for use in a city special event setting within the range of the relay site. The measures of performance for this objective are listed below along with the data items that support each measure.

Measure 1.1: Pre-transport preparations

Data 1.1.1: Identity of pre-transport preparations

Data 1.1.2: Level of effort for pre-transport preparations

Measure 1.2: Time to hitch, transport, set in place, and make operational

Data 1.2.1: Number of minutes to hitch

Data 1.2.2: Number of minutes to transport

Data 1.2.3: Number of minutes to set in place

Data 1.2.4: Number of minutes to make operational

Measure 1.3: Transport and Setup Obstacles and Problems

Data 1.3.1: Identity of transport and set in place obstacles and problems

Data 1.3.2: Severity of obstacles and problems

3.3.1.1 Measure 1.1 - Pre-transport preparations

Data 1.1.1: Identity of pre-transport preparations

A number of planning meetings occurred prior to the actual deployment of the trailers. Based on these meetings, the evaluator assembled a preliminary list of pre-transport preparations and requested written statements from Caltrans District 12 confirming that this list was complete. The list below represents Data 1.1.1, the identity of the four pre-transport preparation activities:

Preparation 1: Site Selection

Preparation 2: Site Survey

Preparation 3: Site Readiness

Preparation 4: Trailer Readiness

Data 1.1.2: Level of Effort for pre-transport preparations

PMT members with relevant first-hand experience submitted written statements characterizing the efforts required for each pre-transport preparation. These statements may be found in Appendix A, which is located in Volume 3 of the Final Report. The evaluator conducted follow-up interviews, as necessary, to clarify and investigate essential issues. Anaheim project management reported spending 2 to 3 hours per day for 1 week in these activities. Anaheim field personnel reported spending 4 hours attending planning meetings and about 2 to 3 hours at each set of trailer deployments. The lead Caltrans engineer reported spending the better part of 1 year in these activities. Other Data 1.1.1 and 1.1.2 entries are summarized below.

Site Selection: Two special event venues were considered for this test, Anaheim Stadium (now named Edison International Field) and Arrowhead Pond. Arrowhead Pond was selected because the Mighty Ducks hockey game schedule provided more opportunities to utilize the trailers. A number of deployment sites around the Arrowhead Pond were considered. One important issue was identifying sites with enough space to accommodate the trailers. Since each of the surveillance trailers is 18'-8" (5.7 m) long and 7'-6" (2.3 m) wide, they are too large to be placed on city sidewalks. Consequently, parking lots became the deployment site of choice.

Another issue was finding sites where surveillance was needed and not already available from permanent surveillance equipment. Three locations were recommended.

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These intersections are listed below in order of their value to the special event traffic management.

- Ball Road and Phoenix Club Drive
- Cerritos Avenue and Sunkist Street
- State College Boulevard and Cerritos Avenue

Site Survey: Each proposed site was investigated to determine if it was suitable for trailer deployment. The site survey process is outlined below.

- Step 1 Confirm the identified property is available. Along city streets, parking lots are ideal except they are generally private property.
- Step 2 Confirm adequate space for parking the surveillance trailers. Several parking spaces are required to accommodate the trailer.
- Step 3 Confirm proper camera placement. Close placement to the road does not necessarily guarantee a usable view of traffic flow in the direction required for traffic management because of obstruction by trees, other foliage, power poles, transmission lines, buildings, and other structures.
- Step 4 Confirm adequacy of received signal strength at the relay site. The signal must be strong enough at the relay site to retransmit video to the Anaheim TMC.

Hughes performed the signal strength testing (Step 4 above) at the three sites in 1996. Anaheim performed Steps 1 through Step 3 in March 1997. Anaheim personnel began the site selection process by viewing an aerial map and conducting site visits. They systematically eliminated intersections that did not have adequate space for parking the trailers. Having narrowed their options, property owners were identified and meetings held to ensure space availability on the days of the Arrowhead Pond events. When the event dates were finalized, a written agreement was prepared by Anaheim and signed by the property owners allowing the trailers to be situated on their property. Important factors in securing permission to use the desired property were:

- Conveying the importance of the tests to managing local traffic flow;
- Expressing the appreciation of the test partners for the cooperation of the property owners;
- Creating the least amount of intrusion into the normal operation of the property;
- Informing the owners of the precise length of time the surveillance trailers would be on their property and of the exact location of the trailers;
- Sending follow-up letters of appreciation to the property owners once the evaluation tests were completed.

Some rework of site survey tasks was required because of the sequence in which they were performed and the changes in personnel participating in different stages of the test. For example, Caltrans and Hughes used a bucket truck to check line-of-sight and measure radio signal strength at each of the three sites in 1996. Later, the proposed location at Ball Road and Phoenix Club Drive was found to have insufficient space for the trailer. Caltrans decided to then test the signal strength one block to the west near SR-57 at a location within the Caltrans right-of-way. This location had satisfactory signal

strength and afforded the cameras a view Phoenix Club Drive. The exact placement of the trailer to optimize viewing of traffic and avoid tree interference with imagery and signal transmission was not found until the trailer was actually deployed. The final surveillance trailer location sites are listed below and shown in Figure 3-1.

- Ball Road at the Northbound onramp to SR-57
- Cerritos Avenue and Sunkist Street
- State College Boulevard and Cerritos Avenue.

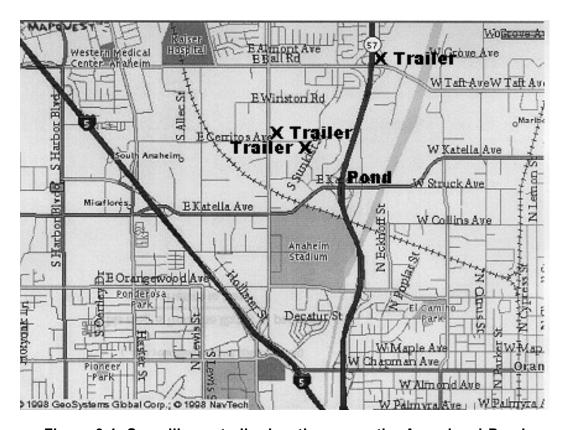


Figure 3-1. Surveillance trailer locations near the Arrowhead Pond

The trailers were placed in these locations for the April 1 event and then moved among the locations, prior to the other events, to gain more experience in transporting the trailers and to gather more data on trailer setup times.

Figures 3-2 through 3-4 show the trailers in position at the Anaheim Special Event Test sites.



Figure 3-2. Trailer being positioned at Cerritos Avenue and Sunkist Street



Figure 3-3. Trailer operational at Cerritos Avenue and Sunkist Street



Figure 3-4. Trailer operational at State College Boulevard and Cerritos Avenue

Site Readiness: Anaheim coned or taped off the lanes required for parking the surveillance trailer in the privately owned parking lots. Often, this was not required because a sufficient number of parking spaces was available in the parking areas. When needed, the parking lanes were reserved early in the morning or the night before the trailers were moved. Additional Caltrans vehicles were needed for a temporary ramp closure while moving the trailer into its test location in the Caltrans right-of-way at Ball Road and SR-57. Between the April 4 and April 9 events, the parking lots where two of the trailers had been located were scheduled for repaving. The property managers were contacted and they agreed to postpone the repaving by two weeks until after the test was complete.

Problems encountered during execution of the pre-transport preparations included:

- Identifying and contacting the property owners in the short time between the identification of the trailer location sites and the start of the first hockey game;
- Alleviating the property owners' concerns about hindering normal parking for the tenants and liability issues as these affected the willingness of the owners to give permission to use their property;
- Moving the trailers from site-to-site as this activity created more uncertainty for the property owners about trailer location, movement dates, and impact on their

tenants. Availability of Caltrans personnel to move the trailers was also an issue associated with this problem;

 Since permission to park the trailers at the specified locations was based on earlier measurements of signal strength and camera view direction, trailers sometimes had to be relocated to improve the signal strength or camera view direction within the permitted trailer placement area.

Liability and theft issues concerning the surveillance trailers were not of primary concern to the property owners. However, they did want to know how accidents and thefts related to the FOT that occurred on their property would be handled. These issues were resolved through the inclusion of a clause in the permission agreement that contained language to the effect: "The City of Anaheim and Caltrans release the property managers and owners of any liability arising out of theft, vandalism, accidents, or damage to such trailers, except when intentionally caused." Prior to the issuance of this letter to the property owners by the City of Anaheim, Caltrans had provided a letter to Anaheim indicating that Anaheim would not incur major liability for damage to the trailers as long as reasonable care was taken in the use of the trailers. This release of liability by Caltrans assisted Anaheim in releasing the property owners, in turn, from liability.

Trailer Readiness: Caltrans engineering sent a notice to Caltrans maintenance ten days prior to the first trailer deployment informing them of the trailer deployment activities for the first three events. Caltrans maintenance supported the FOT by providing appropriate tow vehicles and assistance in closing the onramp at Ball Road and SR-57. At the conclusion of Event 3, maintenance personnel suggested that, upon completion of the FOT, a contractor be hired to transport the trailers so that normal Caltrans maintenance activities and responsibilities were not impacted by trailer moves.

Another issue involved with trailer readiness was scheduled trailer maintenance. Since trailer assembly was not complete when the Anaheim Special Event Test was conducted, a list of trailer maintenance tasks, schedule, and responsibility had not been finalized. The maintenance tasks that sometimes delayed trailer deployment included checking trailer tire pressure, checking generator oil level, checking battery water level, ensuring that safety chain clamps were available for each trailer, and checking liquid propane gas level for running the generator during the FOT events. The lists of scheduled maintenance and trailer turnon procedures eventually prepared by Hughes are found in Appendix B.

Other more serious delays were sometimes encountered. These arose from failures of the generator starter in some trailers and the failure of a battery due to lack of water. Another trailer experienced a failure in the data communications hardware.

After the deployment of Trailer #113 on March 26, prior to the first event, the Anaheim TMC could control the cameras, but not receive video. Hughes corrected this problem by fixing equipment at the Anaheim TMC.

The trailers were turned on and off manually as the automatic generator on/off system was not functioning properly. Often, it failed to turn the trailers off after the battery was recharged, causing fuel waste. The circuit has since been redesigned. Typically, the trailers were turned on manually by Caltrans or Hughes the day of the event, and turned off manually the day after the event. After Event 2, Hughes changed the oil and checked the battery water level in all three trailers used in the FOT.

On April 9, prior to the start of Event 3, Caltrans inspected the trailers to ensure that they were functioning. High winds had apparently shifted the antenna and camera positions. Hughes realigned the antennas so that the Anaheim TMC could again receive optimal video signals.

3.3.1.2 Measure 1.2 - Time to hitch, transport, set in place, and make operational

The evaluator observed each trailer transport and coordinated the collection of transport time data and observations. The data collected in support of the performance measures are:

- Data 1.2.1: Number of minutes to hitch = "Hitched" minus "Began."
- Data 1.2.2: Number of minutes to transport = "Arrived" minus "Hitched."
- Data 1.2.3: Number of minutes to set in place = "Set" minus "Arrived."
- Data 1.2.4: Number of minutes to make operational = "Departed" minus "Set."

The data for calculating the hitch, transport, set in place, and make operational times are listed in Table 3-1 for the five events. These data and relevant comments about the deployments were recorded on the data sheets shown in Appendix C.

The number of minutes to hitch, transport, set in place, and make operational are summarized in Table 3-2, as are the mean and standard deviation of the calculated performance measures. The standard deviation σ is given by

$$\sigma = \sqrt{\frac{\sum x_i^2}{n} - x^2} \tag{3-1}$$

where x_i is the value of an individual hitch, transport, setup, or make operational time; n is the number of entries (here equal to 12); and * is the mean value of the corresponding time.

Data 1.2.1: Number of minutes to hitch

The time to hitch had a moderate standard deviation value, due to the learning and problems experienced with the some of the trailer moves. The largest hitch times occurred when equipment, such as safety chain *D*-rings, was missing or when a trailer was not operational and attempts were made to repair it.

Data 1.2.2: Number of minutes to transport

Since the distances between the originating location and the destination location of the trailers varied, the standard deviation of the transport time was expected to be large. However, the value was relatively small in comparison with the other standard deviation values.

Table 3-1. Trailer hitched, arrived, set, and departed data

Event Number	Move Date	Trailer Number	Began	Hitched	Arrived	Set	Departed	Comments
1	3/26/9	111	8:00am	8:34am	8:59am	9:20am	9:48am*	Computer

	7 3/26/9 7	113	10:13a m	10:35a m	11:05am	11:20am	12:30pm	card failure Video not observable at Anaheim TMC
	3/27/9 7	115	8:03am	8:51am	9:12am	9:25am	9:52am	Trailer hitch raised; safety chain D-rings missing; had to travel to another trailer to borrow D-rings
2	4/2/97	115	8:10am	8:27am	8:31am	8:45am	9:07am	
	4/2/97	113	9:15am	9:34am	9:40am	9:50am	10:10am	
3	4/8/97	111	9:00am	9:32am	9:44am 11:01am	11:06am	11:20am	Temporarily stow trailer at SE corner lot
	4/8/97	115	9:49am	10:05a m	10:28am	10:38am	10:45am	
4 and 5	5/6/97	115	7:35am	8:45am	9:02am	9:15am	9:16am*	Hughes presented
	5/6/97	113	9:32am	9:48am	10:10am	10:42am	10:55am	Weak signal at Anaheim TMC

^{*} Checkout not completed for reasons stated in the table. Therefore, the time to make the trailer operational could not be calculated for this data set.

Data 1.2.3: Number of minutes to set in place

The set in place time showed some decrease as the number of trailer moves increased, demonstrating that learning took place. The relatively large setup time for Trailer 113 before Event 4 was caused by adjusting the trailer position several times in an attempt to increase the signal strength at the Anaheim TMC.

Data 1.2.4: Number of minutes to make operational

The make operational time also showed a downward trend as the number of trailer moves increased. The large make operational time for Trailer 113 at Event 1 was due to the time expended trying to correct the lack of video reception at the Anaheim TMC. If this large value for the make operational time is removed, the mean value of the make operational time is reduced to 17 minutes and the standard deviation to 7 minutes. The checkout of Trailer 111 on March 26 and Trailer 115 on May 6 were not completed during the initial portion of the move because of the problems noted in Table 3-1. Therefore, the make operational times for these trailer moves are not available.

Event Number	Trailer Move Date	Trailer Number	Hitch Time (min)	Transport Time (min)	Set in Place Time (min)	Make Operational Time (min)
1	3/26/97	111	34	25	21	*
	3/26/97	113	22	30	15	70
	3/27/97	115	48	21	13	27
2	4/2/97	115	17	4	14	22
	4/2/97	113	19	6	10	20
3	4/8/97	111	32	12	5	14
	4/8/97	115	16	23	10	7
4 and 5	5/6/97	115	70	17	13	*
	5/6/97	113	16	22	32	13
Mean			30	18	15	25
Std. Deviation			18	8	7	19

Table 3-2. Hitch, transport, set in place, and make operational times

3.3.1.3 Measure 1.3 – Transport and Set in Place Obstacles and Problems

The two data items that supported this performance measure were the identity of transport and set in place obstacles and problems and their severity.

Data 1.3.1: Identity of transport and set in place obstacles and problems

The data sheets in Appendix C were reviewed for comments that indicated problems and obstacles encountered during transportation and deployment. Six problems were noted:

- Obstacle 1: Learning Curve
- Obstacle 2: Maneuverability
- Obstacle 3: Training
- Obstacle 4: Trailer Configuration
- Obstacle 5: Signal Interference
- Obstacle 6: Equipment Failure.

Data 1.3.2: Severity of obstacles and problems

Learning Curve: The times to hitch, transport and arrive, set in place, and make operational were reduced as personnel gained more experience with trailer transportation and operation. Exceptions to this general statement did occur when problems arose such as equipment failures, need to perform routine maintenance, or gathering of required equipment.

Maneuverability: One difficulty occurred while positioning the trailers in the parking lots with the large tow truck. It was at first thought that a smaller truck would allow greater

^{*} Checkout not completed because of problems listed in Table 3-1.

ease of maneuvering and positioning of the trailers in confined areas. However, when the operator of the large tow truck was changed, the new operator had significantly less trouble backing and positioning the trailer. Therefore, the issue is one of tow truck operator training more than it is of the size of the tow vehicle.

Training: Training the Anaheim TMC staff in trailer placement and operation procedures was complicated by the fact that Hughes had not yet prepared a list of required actions and checks. However, the Anaheim staff learned what was required through a combination of verbal instructions and hands-on experience. An issue for future use of the surveillance trailers by Anaheim is finding a source of funds for the trailer transportation and setup.

Trailer Configuration: During transport of the ramp meter trailers, a solar powered signal head was placed too far forward on the trailer. This reduced the turn radius of the tow vehicle as the signal head interfered with the rear of the tow vehicle when it made a sharp turn. Although it might be unusual to make such a turn during normal transport, it is likely that such maneuvering would become necessary during normal positioning of the trailer. This problem was easily alleviated by repositioning the signal head on the trailer.

Signal Interference: The cameras on Trailer 115 produced a significant amount of color bar noise at the Anaheim TMC during Event 4. The trailer was moved several times in the parking area in an attempt to improve the signal strength. Some small improvements were noted during the test. However, the noise was never totally removed. This problem indicates the susceptibility of SSR technology to interference when the line-of-sight between transmitter and receiver is not clear.

Equipment Failure: On a number of occasions during the test, various trailer components failed to function. These problems were quickly remedied through the efforts of those present during the setup process. The types of problems involved a variety of trailer components ranging from one of the outriggers not functioning, difficulty in attaching safety chains to tow vehicles, to a failure of components on the automatic mast retraction system. These problems were considered minor. More thorough testing before deployment could potentially reduce the number of failures of this nature; however, it is unlikely that failures of this type can be completely avoided given the complexity of the trailers.

3.3.2 Objective 2 – Effectiveness of Trailers for Special Event Management

The second objective evaluated whether the surveillance trailers were effective for special event traffic management where traditional traffic management systems were not available. Anaheim TMC personnel observed the camera images and entered their findings on data sheets that were analyzed by the evaluators. The measures of performance for this objective are listed below along with the data items that support each measure.

Measure 2.1: Camera image and control availability

Data 2.1.1: Camera image percent up time

Data 2.1.2: Camera control percent up time

Measure 2.2: Camera image and control problems

Data 2.2.1: Identity of camera image and control problems

Data 2.2.2: Severity of camera image and control problems

3.3.2.1 Measure 2.1: Camera image and control availability

Test data were collected by Anaheim TMC special event operators. The operators were given Camera Operability Data Sheets on which to record the quality of the camera image and camera control. A "check" ($\sqrt{}$) mark indicated that image or control was available and an "x" indicated that image or control was unavailable. Whenever an "x" was entered, the operator indicated the nature of the problem on the data sheets found in Appendix D. Figure 3-5 shows the Anaheim TMC work area with the camera control keyboard on the desk and monitor on a counter in the background.



Figure 3-5. Anaheim TMC work area

Data 2.1.1 Camera image percent up time

Camera image percent up time was determined from the ratio of the number of times the image was clear divided by the number of times the image clarity was polled. The percent of time the camera image was clear (Data 2.1.1) was calculated with data from the five test events. The results are given in Tables 3-3 to 3-5 for Trailers 111, 113, and 115, respectively. Camera 1 denotes the color surveillance camera, Camera 2 the first VIP black-and-white camera, Camera 3 the second VIP black-and-white camera, and Camera 4 the black-and-white security camera.

Although the initial evaluation plan called for checks every 15 minutes, it was soon obvious that the checks did not have to be performed this often for several reasons. First, a round of checks took 15 minutes in itself. Therefore, the original schedule would have required continuous testing of the camera image and control for the duration of the special event. Second, experience showed that the camera controls were reliable and the imagery stable (except that from the color camera as darkness fell). Therefore, the interval between tests was lengthened to 45 minutes and then to 1 hour.

Table 3-3. Trailer 111 camera image availability

Camera Number	# Available/# Checks	Percent
1	10/14	71%
2	10/14	71%
3	11/14	79%
4	11/14	79%

Table 3-4. Trailer 113 camera image availability

Camera Number	# Available/# Checks	Percent
1	27/32	84%
2	27/32	84%
3	31/32	97%
4	31/32	97%

Table 3-5. Trailer 115 camera image availability

Camera Number	# Available/# Checks	Percent
1	21/31	68%
2	29/31	94%
3	29/31	94%
4	29/31	94%

Data 2.1.2: Camera control percent up time

Camera control percent uptime was defined as the ratio of the number of times control was available divided by the number of times the control functions were polled. The percent of time camera control was available (Data 2.1.2) was obtained from the data sheets filled out by the TMC operators. Two types of tables are used to summarize Data 2.1.2 as illustrated in Tables 3-6 to 3-8 corresponding to the three trailers. Table (a) for each trailer denotes the percent of time camera control was available for all cameras on a trailer. Table (b) provides the percent of time each camera was available on the trailer. In some instances, control could not be determined because the image was unavailable. If control was consistently available for all checks prior to then, it was assumed that control was available even when the image could not be clearly seen. If control was unavailable for checks prior to losing image quality, then it was assumed that control was unavailable during the period of degraded imagery. The camera designations are the

same as for the preceding tables. When a function test is not applicable, the "n/a" symbol is inserted in the table.

Table 3-6. Trailer 111 camera control availability

(a) All camera data

Function	# Available/# Checks	Percent
Pan	36/42	86%
Tilt	36/42	86%
Zoom	12/14	86%

(b) Individual camera data

Camera	Pa	an	Til	t	Zoo	m
1	12/14	86%	12/14	86%	12/14	86%
2	12/14	86%	12/14	86%	n/a	n/a
3	12/14	86%	12/14	86%	n/a	n/a
4	n/a	n/a	n/a	n/a	n/a	n/a

Table 3-7. Trailer 113 camera control availability

(a) All camera data

Function	# Available/# Checks	Percent
Pan	93/96	97%
Tilt	93/96	97%
Zoom	31/32	97%

(b) Individual camera data

Camera	Pa	ın	Ti	lt	Zoo	m
1	31/32	97%	31/32	97%	31/32	97%
2	31/32	97%	31/32	97%	n/a	n/a
3	31/32	97%	31/32	97%	n/a	n/a
4	n/a	n/a	n/a	n/a	n/a	n/a

Table 3-8. Trailer 115 camera control availability

(a) All camera data

Function	# Available/# Checks	Percent
Pan	100/100	100%
Tilt	100/100	100%
Zoom	31/31	100%

(b) Individual camera data

Camera	Р	an	Т	ilt	Zoo	om
1	31/31	100%	31/31	100%	31/31	100%
2	31/31	100%	31/31	100%	n/a	n/a
3	31/31	100%	31/31	100%	n/a	n/a
4	n/a	n/a	n/a	n/a	n/a	n/a

3.3.2.2 Measure 2.2: Camera image and control problems

Camera image and control problems were identified by Anaheim TMC Special Event Operators and were recorded on Part II of the Camera Operability Data Sheets as shown in Appendix D.

Data 2.2.1: Identity of camera image and control problems

Tables 3-9a through 3-9e show that at no time during the five events in the test was the ability to control or switch cameras lost. However, some learning was required to use the camera control keypad before the camera could be positioned by the operator. The problems with camera control were identified by reviewing the data sheets presented to the evaluator. Image quality is a function of the camera design specifications, ambient lighting, and camera placement relative to the subject of interest.

Table 3-9a. Camera control and imagery problems experienced on April 1, 1997

Trailer 111	Not operational due to computer card failure. This trailer location was deemed the most valuable for traffic management at this event.
Trailer 113	Trees and road geometrics limited the downstream view of traffic when the color cameras on 113 and 115 were zoomed. Black-and-white camera provided an excellent view of traffic arrival and dispersion at the intersection.
Trailer 115	Black-and-white camera allowed surveillance of traffic arrival in the advanced detection setback zone and of mid-intersection traffic.

Table 3-9b. Camera control and imagery problems experienced on April 4, 1997

Trailer 111	Trailer 111 operational. Provided an unobstructed view of downstream
	signal at ball road and phoenix club drive.

Trailer 113	Same comment as for event 1.
Trailer 115	Provided an improved view of the desired traffic flow.
Table 3-9c.	Camera control and imagery problems experienced on April 9, 1997
Trailer 111	Camera perspective and view from all cameras at all trailers were the same as in the previous event. Heavy winds may have caused weak reception of video at the TMC. However, camera control functions worked satisfactorily at all the trailers.
Trailer 113	Non-responsive to remote control commands for the cameras. Repairs by Hughes completed after the start of the inbound traffic flow for the event.
Trailer 115	Weak signal reception at TMC (color bars observed on video monitor). Repairs by Hughes completed after the start of the inbound traffic flow for the event.

Table 3-9d. Camera control and imagery problems experienced on May 6, 1997

Trailer 111	Not Used
Trailer 113	The imagery from one of the black-and-white cameras was observed to change color on the monitor in the TMC, apparently from loss of video synch due to a weak signal.
Trailer 115	Imagery useful in setting timing plan for traffic exiting the Pond and turning left onto Sunkist toward Katella Avenue. Traffic was observed to be getting heavier, allowing the TMC operator to change the timing plan to allow for maximum left-turn signal time.

Table 3-9e. Camera control and imagery problems experienced on May 8, 1997

Trailer 111	Not Used.
Trailer 113	Color camera image lost clarity as it became dark outside.
Trailer 115	No comments reported.

Observations made by Caltrans personnel from the video tape of the traffic flow, as recorded by the Ball Road and SR-57 surveillance trailer, indicated that it was easy to differentiate between cars and trucks and to estimate the number of vehicles. There was a little glare from some headlights that were pointed in the direction of the cameras; however, this did not cause a problem in observing the flow of traffic.

The imagery from the color camera degraded as darkness fell and less background lighting was available. This effect was not observed with the permanently installed CCTV cameras currently in use by the City of Anaheim. Therefore, it appears that higher sensitivity color cameras can be procured if additional surveillance trailers are built. Another type of image degradation occurred when the signal transmitted to the Anaheim TMC was weak. Under these conditions, the black-and-white image was observed to change color on the monitors in the TMC. The antenna on the trailers was realigned in an attempt to correct this problem. More often than not, the weak signal reception persisted.

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However, the imagery received at the TMC still provided satisfactory information for traffic management purposes.	

3.3.3 Objective 3 - Benefits of Additional Surveillance

The third objective of the Anaheim Special Event Test was to compare the time it took the parking lots to empty with and without the use of cameras at locations where permanent video surveillance was not available. Anaheim personnel provided the relevant traffic egress data, which were analyzed by evaluators. The evaluators also accompanied Anaheim Traffic Officers in their vehicles during the first three events to observe traffic management strategies. Comments obtained from interviews and the evaluators' observations are noted in Data 3.1.2. The measure of performance for this objective is:

Measure 3.1: Decrease in event traffic egress duration with temporary video surveillance

- Data 3.1.1: Average event traffic egress duration without mobile surveillance trailers
- Data 3.1.2: Average event traffic egress duration with mobile surveillance trailers

Data 3.1.1: Average egress duration without mobile surveillance trailers

Five major freeways connecting with different regions of Orange and Los Angeles Counties service Arrowhead Pond. Several major surface streets, including Katella Avenue and Ball Road, lead to the arena's seven parking lots. More than 4,500 parking spaces are located within walking distance of the Pond's main entrance. Limousine, bus, and handicap parking are located adjacent to the arena. Therefore, there is heavy traffic flow out of the Pond after a sell-out event.

Table 3-10 shows historical parking lot egress data gathered between January 6, 1997 and March 14, 1997 over the course of 10 events at the Arrowhead Pond. The average attendance for these events was 17,240. The average egress duration was 52.7 minutes, with a standard deviation of 12.2 minutes.

Table 3-10. Historical times to empty parking lot (without mobile surveillance trailers)

Date	Attendance	Event End Time	Outbound End Time	Egress Duration (min)
1/6/97	17,012	22:00	22:45	45
1/8/97	17,182	21:54	23:00	66
1/10/97	17,398	22:20	22:55	35
1/22/97	17,231	22:02	22:50	48
1/31/97	17,372	21:52	23:00	68
2/26/97	17,246	22:15	23:10	55
3/5/97	Not available	21:40	22:45	65
3/7/97	Not available	22:25	23:00	35
3/12/97	Not available	22:00	23:00	60
3/14/97	Not available	22:00	22:50	50

Data 3.1.2: Average event traffic egress duration with mobile surveillance trailers

Table 3-11 shows the parking lot egress duration measured for the five events. The average parking lot egress duration was 36.2 minutes, with a standard deviation of 1.9 minutes. This average is approximately 31 percent less than the average historical egress duration. The 36.2-minute time represents an average egress period that is 1.3 standard deviations less than the historical average egress duration. The analysis of this limited amount of data indicates that the egress times for Events 1 to 5 also had a smaller standard deviation that did parking lot egress when the mobile surveillance cameras were not present. However, the data sample is too small to substantiate these statistics with high confidence. Other factors, described below, may have contributed to the larger egress durations and standard deviation recorded in the historical database.

Table 3-11. Times to empty parking lots at Arrowhead Pond during Events 1 to 5 (with mobile surveillance trailers)

Event Number*	Date	Event End Time	Outbound End Time	Egress Duration (min)
1 (Hockey only)	Tuesday April 1, 1997	22:42	23:17	35
2 (Hockey & baseball)	Friday April 4, 1997	22:15	22:55	40
3 (Hockey & baseball)	Wednesday April 9, 1997	22:20	22:56	36
4 (Hockey only)	Tuesday May 6, 1997	22:40	23:15	35
5 (Hockey only)	Thursday May 8, 1997	0:25	1:00	35

^{*} The hockey games were sold out for the above 5 events. The baseball game was held at neighboring Anaheim Stadium.

Anaheim attributes the variability in the historical egress durations to differences in the expertise of individual event operators, daily fluctuations in field conditions, and the accuracy of recorded times. It is not unlikely that the five test events had less variability simply because great care was taken during the FOT events to accurately record event end time and outbound end time.

The evaluation team observed that much of the traffic congestion on Katella Avenue in front of the arena was due to heavy pedestrian traffic. Police gave priority to pedestrians in order to prevent large, uncontrollable pedestrian groups from forming.

Police officers controlling the egress did not believe their unit was consulted about optimum trailer placement. If the trailers are to be successfully used in the future to supplement existing traffic controls and strategies, all interested parties should have input.

3.3.4 Objective 4 - Institutional Issues: Resource Sharing

The fourth objective of the Anaheim Special Event Test evaluated institutional issues, benefits, and costs related to sharing resources among agencies participating in managing a city special event. The objective was met by observing pre-test activities and interviewing personnel involved with the various aspects of the test. The measures of performance and supporting data for this objective are:

Measure 4.1: Advantages of resource sharing

Data 4.1.1: Identity of advantages of resource sharing

Measure 4.2: Disadvantages of resource sharing

Data 4.2.1: Identity of disadvantages of resource sharing

Measure 4.3: Costs of resource sharing

Data 4.3.1: Identity of cost items related to resource sharing

Many members of the PMT and their supporting staff had first-hand experience with resource sharing between Anaheim and Caltrans. Consequently, they were able to supply the advantages of resource sharing. The evaluator prepared an initial list of advantages and disadvantages and requested written statements from team members to confirm that the list was complete and to identify cost items. The evaluator conducted follow-up interviews with Caltrans and Anaheim engineers regarding the advantages and disadvantages of resource sharing.

Data 4.1.1: Identity of advantages of resource sharing

The advantages of resource sharing as determined from the PMT members were:

- Advantage R1: Provides surveillance at Anaheim street locations that do not have permanent cameras
- Advantage R2: Facilitates inter-agency cooperation between the Anaheim TMC and Caltrans District 12
- Advantage R3: Provides resources for future traffic management at intersections undergoing construction
- Advantage R4: Determines effectiveness of placing a camera at a location prior to incurring costs associated with permanent installation
- Advantage R5: Stimulates ideas for future projects
- Advantage R6: Provides insight into viability of future projects
- Advantage R7: Directly provides Caltrans with information about upcoming freeway traffic following special events.

Data 4.2.1: Identity of disadvantages of resource sharing

The disadvantages of resource sharing as determined from the PMT members were:

- Disadvantage R1: Requires complex inter-agency coordination
- Disadvantage R2: Requires Caltrans to limit city liability

- Disadvantage R3: Requires city to acquire new expertise
- Disadvantage R4: Requires special security arrangements
- Disadvantage R5: Requires extra training for city personnel
- Disadvantage R6: City police cannot provide special monitoring for trailers
- Disadvantage R7: Requires special arrangements for locating trailers on private
 - property
- Disadvantage R8: Benefits not commensurate with amount of human, time, and
 - fiscal resources required to utilize the trailers.

Data 4.3.1: Identity of cost items related to resource sharing

The cost items determined from statements prepared by PMT members were:

- Cost Item R1: Caltrans delivery of trailers
- Cost Item R2: City participation in trailer setup
- Cost Item R3: Installation of equipment at the Anaheim TMC
- Cost Item R4: Training of Anaheim personnel
- Cost Item R5: Upkeep of Anaheim radio receivers and other equipment
- Cost Item R6: Exposure to liability
- Cost Item R7: Increased insurance costs
- Cost Item R8: Opportunity costs
- Cost Item R9: Maintenance and service per 100 hours use.

3.3.5 Objective 5 - Institutional Issues: Information Sharing

The fifth objective of the Anaheim Special Event Test assessed institutional issues, benefits, and costs related to sharing the video information between city and state agencies. This was accomplished by observing pre-test activities and interviewing traffic operations personnel about their use of information for managing special events. The measures of performance and supporting data are:

Measure 5.1: Advantages of event traffic video sharing

Data 5.1.1: Identity of advantages of traffic video sharing

Measure 5.2: Disadvantages of event traffic video sharing

Data 5.2.1: Identity of disadvantages of traffic video sharing

Measure 5.3: Costs of information sharing

Data 5.3.1: Identity of cost items related to information sharing.

Many members of the PMT and their supporting staff had first-hand experience with the decision to provide video sharing between Anaheim and Caltrans. Consequently, they were able to name the advantages of information sharing. The evaluator prepared an

initial list of advantages and disadvantages of video sharing and requested written statements from team members to confirm the completeness of the list and to identify cost items. The evaluator conducted follow-up interviews with TMC operators concerning the advantages and disadvantages, and an interview with the lead city field technician regarding potential cost items.

Data 5.1.1: Identity of advantages of event traffic video sharing

The advantages of event traffic video sharing determined from PMT members were:

- Advantage R1: Allows Caltrans District 12 to better manage freeway operations in the vicinity of the Arrowhead Pond
- Advantage R2: Facilitates inter-agency cooperation between the Anaheim and Caltrans District 12
- Advantage R3: Provides each agency with a better understanding of the other's operations
- Advantage R4: Directly provides Caltrans with information about upcoming freeway traffic following special events.

Data 5.2.1: Identity of disadvantages of event traffic video sharing

The disadvantages of event traffic video sharing determined from PMT members were:

- Disadvantage R1: Requires operators at different facilities to share common video controls
- Disadvantage R2: Requires prioritizing camera control and, hence, limiting primary control to one agency
- Disadvantage R3: Increases potential for technical problems if planning meetings and tests are not conducted.

Data 5.3.1: Identity of cost items related to information sharing

The cost items related to information sharing determined from PMT members were:

- Cost Item R1: State and city power consumption
- Cost Item R2: Initial installation of equipment at the Anaheim TMC.

3.3.6 Issues Indirectly Related to the Anaheim Special Event Test

During the field operational test, several problems or obstacles were noted through direct observation, interviews, or prepared statements. These items were related to the test, but not directly linked to any specific test objective. They include ATMS software icon and database setup, training for accessing the database, trailer malfunctions associated with trailer turnon and turnoff, delayed camera control response, image blooming, and obstacles to trailer refueling.

3.3.6.1 ATMS Icon and Database Setup and Training

Moving the surveillance trailers from I-5 to the locations needed for the Anaheim Special Event Test required modification of the trailer and camera selection icons and corresponding ATMS database. This marked the first time that Caltrans staff had to create the icons and database. Previously, NET had performed these tasks. Therefore, there was a learning curve for Caltrans, causing the icons not to be ready for the first Anaheim Special Event Test event. In addition, rebooting of the ATMS was required once the new trailer and icon locations were in place. The need to restart the system was not known to Caltrans until they tried to use the new icon set. The problems in setting up the new icons did not adversely impact control and operation of the surveillance trailers by the Anaheim TMC. However, they did hamper the process of trailer and camera control from the Caltrans District 12 TMC.

3.3.6.2 Malfunction Associated with Trailer Turn-on and Turn-off

At Event 1, all trailer generators were turned on and off remotely from the Anaheim TMC. However, the poor reliability of the remote on/off system caused the trailer's generator to run for long periods of time without turning off, depleting the liquid propane gas fuel quicker than expected. Therefore, at later events the trailers were turned on and off manually before and after the events. A microprocessor-controlled on/off battery charging system has since been designed and installed in the six surveillance trailers.

3.3.6.3 Delayed Camera Control Response

At Event 2, a delay occurred between the issuance of a pan, tilt, or zoom command (by the TMC camera control unit at Anaheim) for a trailer-mounted color camera and its execution by the pan, tilt, and zoom assembly on the trailer. This delay was observed on the monitor at the Anaheim TMC by noting the delay time for the image to change as compared to the time of command initiation at the TMC. Telephone conversations with the District 12 TMC confirmed the change in pan, tilt, or zoom, even though the change was not observed as yet at the Anaheim TMC.

Another type of delay was associated with the compressed video. It caused the operator to pass through the desired camera pan or tilt setting. The operator noted, however, that with some training this deficiency was overcome.

3.3.6.4 Image Blooming

Operators experienced blooming when panning near or through streetlights during nighttime viewing. This was not judged a major problem. The black-and-white cameras did provide sharp images, however.

3.3.6.5 Obstacles to Trailer Refueling

Before Event 3, difficulties in getting the trailers refueled prevented the systems continuity check from being performed at the new trailer locations.