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8,22 and. 7,20

THE NOISE EXPOSURE MODEL (MOD 4)

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AUGUST 1971 TECHNICAL REPORT

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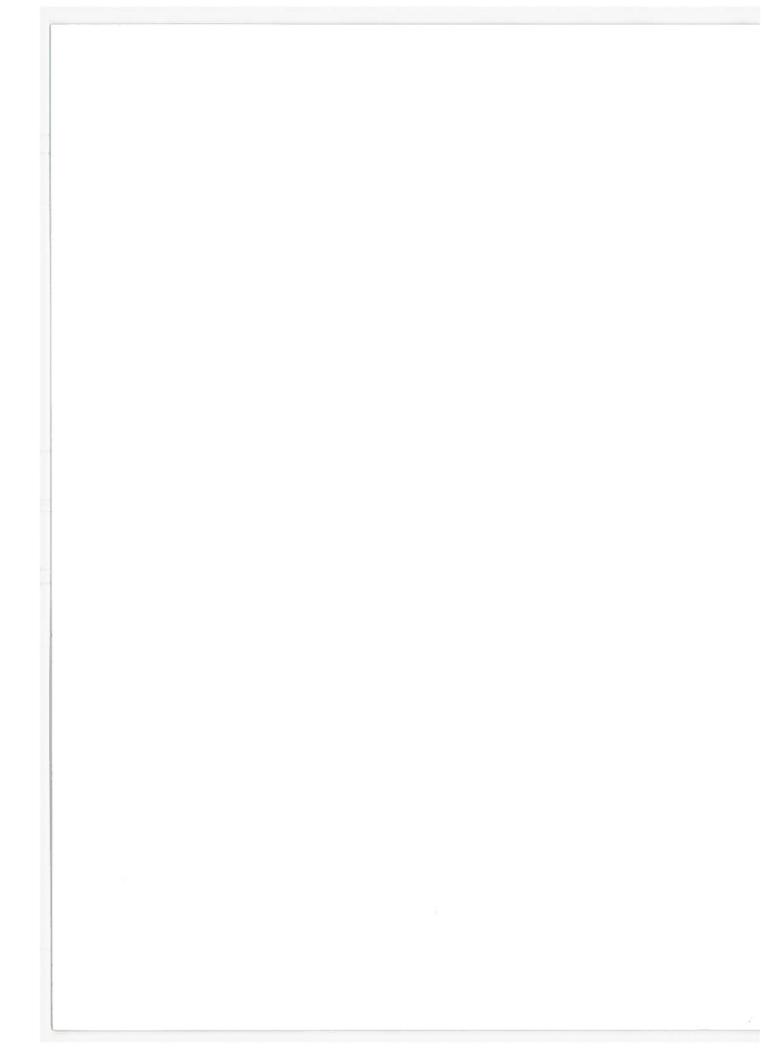
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16. Abstract

The purpose of this report is threefold:

- 1. To record the results of efforts at the Transportation Systems Center to refine and expand the Noise Exposure Model, which have specifically resulted in the MOD 4 version described herein;
- 2. To serve as a User's Manual for the preparation of input information for the Noise Exposure Model MOD 4; and
- 3. To document the computer program for the Noise Exposure Model MOD 4, primarily for the guidance of computer programmers.

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PREFACE

Special mention should be made of the contributions of the Service Technology Corporation, Cambridge, Massachusetts, and especially of Mr. Phil Shakir, for his programming efforts in preparing the Noise Exposure Model MOD 4.

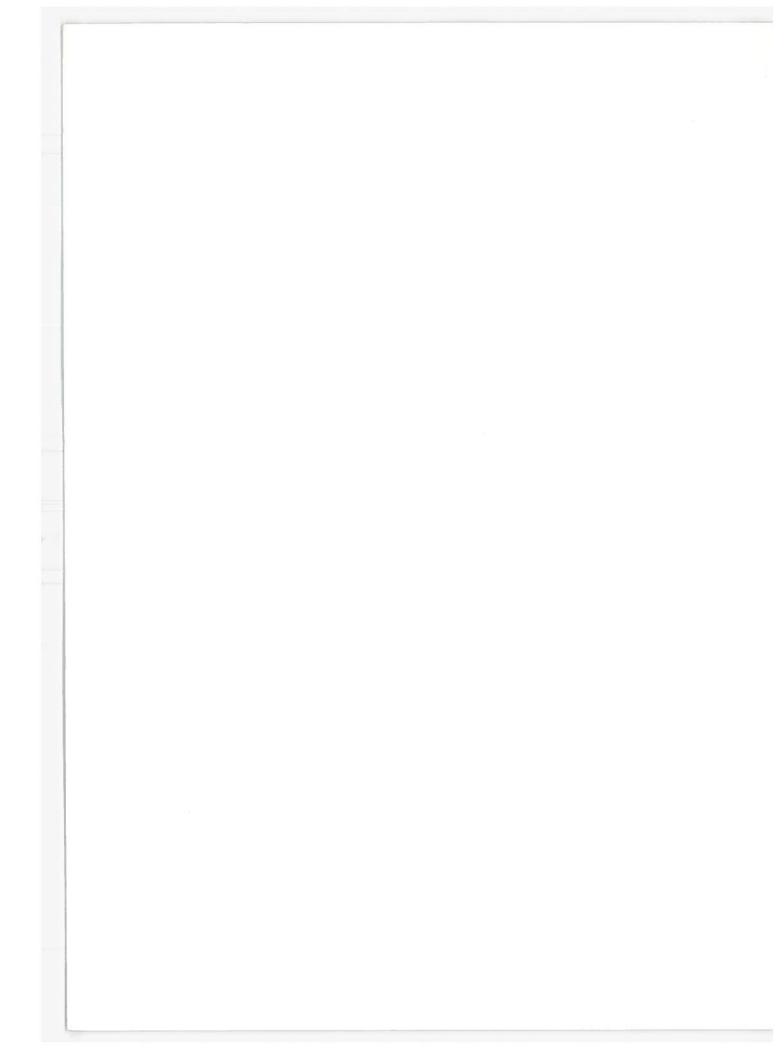
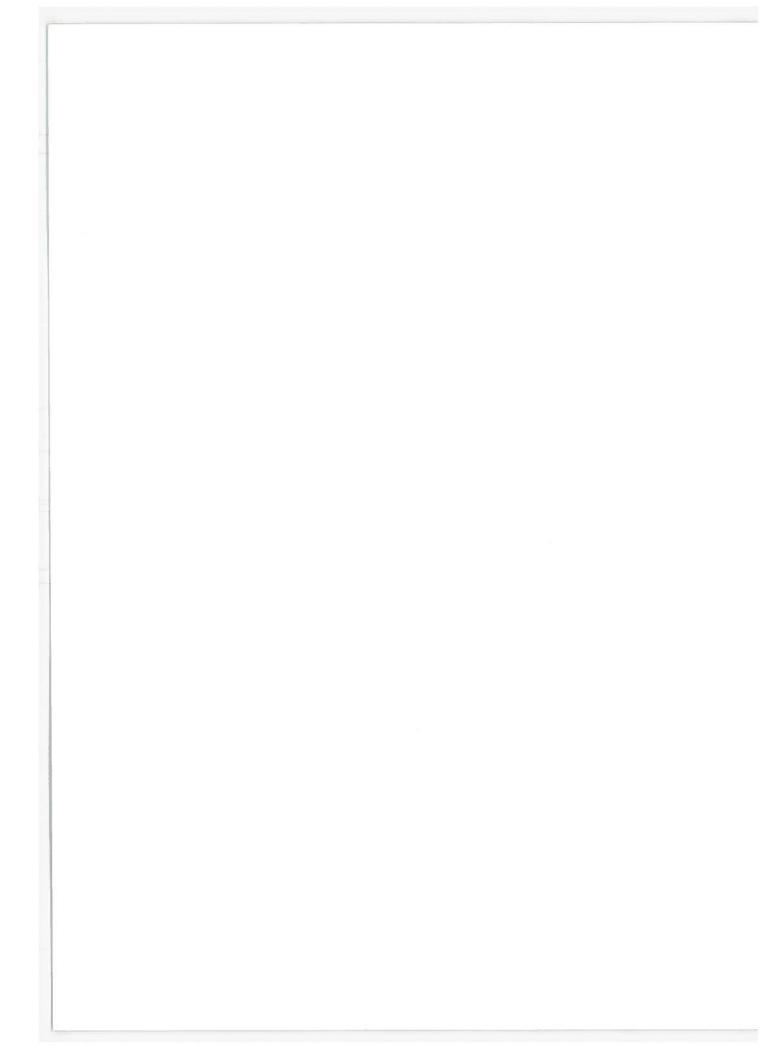


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INTRODUCTION

The purpose of this report is threefold:

- 1. To record the results of efforts by the Transportation Systems Center to refine and expand the Noise Exposure Model, resulting in the MOD 4 version described herein;
- 2. To serve as a User's Manual for preparation of input information for the Noise Exposure Model MOD 4; and
- 3. To document the computer program for the Noise Exposure Model MOD 4, primarily for the guidance of computer programmers.

BACKGROUND

The initial version of the Noise Exposure Model (designated the MOD 0 version for identification) was developed by Serendipity, Incorporated, of Arlington, Virginia, under Contract DOT-OS-A9-018 to the Office of Noise Abatement, Office of the Secretary, Department of Transportation. In general, the model was based on the draft Aerospace Recommended Practice 1114 of the Society of Automotive Engineers, dated 24 March 1970: "Procedures for Developing Aircraft Noise Exposure Contours Around Airports". In September 1970, a copy of the MOD 0 version, originally programmed for a Burroughs 5500 computer, was delivered to the DOT Transportation Systems Center for refinement and expansion. The MOD 4 version described in this report is the result of TSC's efforts from September 1970 to May 1971.

The Noise Exposure Model MOD 4 is programmed in FORTRAN IV specifically for use with the IBM 7094 computer located at TSC. It includes the following features:

- a. Ability to calculate Noise Exposure (NE) using flight statistics for an entire 24-hour day, Noise Exposure Forecast (NEF) using flight statistics for two separate periods during a day (normally taken as 0700 2200 and 2200 0700), or Weighted Equivalent Continuous Perceived Noise Level (WECPNL) using a three-period day (normally 0700 1900, 1900 2200, and 2200 0700);
- b. Presentation of calculated results as a grid array of up to 20 points in the X-direction by 25 points in the Y-direction in the horizontal plane (Z=0), plus the option for automatic CALCOMP plotting of one, two, or three contours of selected value along with automatic calculation of the areas included within each plotted contour;
- c. Ability to handle up to 75 flights (a flight is defined as a combination of a single aircraft class, but any number of aircraft within a class, a specific runway, and a specific flight path);

^{* &}quot;A Study of the Magnitude of Transportation Noise Generation and Potential Abatement", Volume III - Airport/Aircraft System Noise, Report OST-ONA-71-1, November 1970.

- d. Ability to define flight paths as any combinations of straight-line and constant-radius curved segments projected onto a horizontal plane (Z = 0) plus a climb (or descent) angle;
- e. Ability to consider up to ten runways, the ends of which can be described by three (X,Y,Z) coordinates;
- f. Option to use either metric or English units of length and aircraft weight; and
- g. Option to use the values of takeoff ground roll and climb angle assumed in the SAE ARP 1114 procedure, which are included in the programmed model, or to override the programmed values with user-selected values of takeoff ground roll and initial climb angle.

The model also includes diagnostic and control options for the display of intermediate computational steps and diagnostic information, as possible aids to better understanding the program operation. The program listing, included as Appendix C to this report (but bound separately for convenience), also includes comment entries for clearer identification of the functions of the various portions.

The limitations of the Noise Exposure Model MOD 4, noted above, are largely those imposed by the capacity of the IBM 7094 computer. To permit larger and more versatile calculations, development continues at the Transportation Systems Center on the MOD 5 version, adapted to the larger IBM 360/75 computer. This version should double the permissible number of individual flights (to 150), and permit the addition of new aircraft noise characteristics to override the basic SAE ARP 1114 information included in the MOD 4 The MOD 6 version at TSC is being developed for the Center's H-832/DDP-516 computer complex for on-line use of the model with interactive graphic input and display of calculated contours. The MOD 5 version was operational on 1 June 1971. It is anticipated that the MOD 6 version will be operational prior to 1 January 1972 and will be accessible from remote terminals over telephone links.

BASIC NOISE EXPOSURE RELATIONS

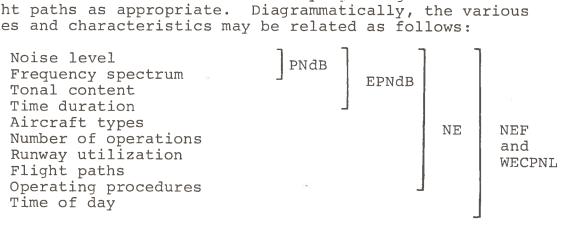
Noise exposure values are calculated quantities intended to represent the aircraft noise perceived by individuals on the ground near airports. The interpretation and use of these values is a complex subject by itself and is far beyond the scope of this report. A number of somewhat different methods for calculation of noise exposure values have developed, both in the United States and abroad. Three of these measures have been included in the Noise Exposure Model MOD 4 for convenience. These are:

- a. Noise Exposure (NE), which calculates the cumulative noise exposure at points on the ground around an airport, assuming equal weighting throughout the period considered (normally an average 24-hour day);
- b. Noise Exposure Forecast (NEF), which calculates the cumulative noise exposure in the same manner as the Noise Exposure procedure, but applies a heavier emphasis or weighting for nighttime flights (normally defined as those occurring between 2200 and 0700 during an average day); and
- c. Weighted Equivalent Continuous Perceived Noise Level (WECPNL), which again calculates the cumulative noise exposure as the two procedures above, but imposes an intermediate weighting for evening flights (normally defined as those occurring between 1900 and 2200 during an average day). The WECPNL procedure is that recommended by the International Civil Aviation Organization (ICAO) for international use. The NE and NEF procedures were developed within the United States.

In the calculation of noise exposure values, aircraft noise levels are expressed in terms of Effective Perceived Noise Levels (EPNL) in units of EPNdB. This calculated value represents the loudness sensation (called Perceived Noise Level in PNdB) created for an "average" observer, considering the sound intensity and frequency spectrum generated by an aircraft, plus corrections for single frequency (or pure tone) content in the noise spectrum (if any) and the time duration of the aircraft's flyby. In simulating the noise exposure near an airport, it is convenient to group aircraft into classes, based on noise characteristics and takeoff and landing profiles. Each class is assigned a set of EPNdB-versus-distance curves for takeoff and landing, and a set of takeoff climb profiles for appropriate

ranges of gross takeoff weight. A standard descent angle of 3° immediately prior to touchdown is assumed for all aircraft classes.

The total noise exposure produced by aircraft operations at an airport is represented by the sum of the effective perceived noise levels produced at each point on the ground by the different aircraft classes flying along simulated flight paths as appropriate. Diagrammatically, the various values and characteristics may be related as follows:



Noise Exposure (NE)

NE = 10 log
$$\sum_{i}$$
 antilog $\frac{NE(i,j)}{10}$

NE(i,j) = EPNL(i,j) + 10 log N(i,j) - 88

where:

EPNL(i,j) = Effective Perceived Noise Level produced at the point being considered by aircraft of class (i) traveling along flight path (j).

The subtractive factor (88) is included to insure that the NE values which result are distinctly different in magnitude from the EPNL values, so that little likelihood will exist that the two values will be confused.

Noise Exposure Forecast (NEF)

NEF = 10 log
$$\sum_{i = j}$$
 antilog $\frac{\text{NEF (i,j)}}{10}$

$$NEF(i,j) = EPNL(i,j) + 10 log \left[ND(i,j) + 16.67 NN(i,j)\right] - 88$$

where:

NEF(i,j) = Noise Exposure Forecast value produced by aircraft of class (i) traveling along flight path (j)

Again, the subtractive factor (88) is applied to eliminate confusion between NEF and EPNL values.

Weighted Equivalent Continuous Perceived Noise Level (WECPNL)

WECPNL = 10 log
$$\left[\frac{1}{2} \text{ antilog } \frac{\text{ECPNLD}}{10} + \frac{1}{8} \text{ antilog } \frac{\text{ECPNLE+5}}{10}\right]$$

$$+\frac{3}{8}$$
 antilog $\frac{\text{ECPNLN} + 10}{10}$

ECPNLD = 10 log
$$\sum_{n}$$
 \sum_{j} $\left[\text{antilog } \frac{\text{EPNL}(n,i,j)}{10}\right] + 10 \log \frac{10}{T}$

where:

T = Total period of time (in seconds) included in interval under consideration (0700 - 1900 for daytime, 1900-2200 for evening, 2200 - 0700 for nighttime).

PROGRAM USAGE

Input information required for the Noise Exposure Model MOD 4 is entered into the computer via punched cards using a simple set of pre-printed coding sheets with six-character mnemonic identifiers. Preparation of the input coding is straightforward and systematic, although large airports with many runways, flights, flight paths, and operating procedures may involve a large number of lines of input data.

Input information may be considered in three parts:

- a. One-time processing instructions;
- b. Runway and flight path descriptions, prepared once and used repetitively in flight operations; and
- c. Aircraft flight operations.

Computer output calculations are printed grid values of noise exposure (NE, NEF, or WECPNL as selected), with the additional option of automatic CALCOMP plots of selected contour values with corresponding areas calculated within each plotted contour.

The following sections describe the entries required for each of the three types of input data. Appendix A furnishes samples of the pre-printed coding sheets suggested to simplify preparation of the input data. Appendix B displays a sample problem with the computer solution.

One-Time Processing Instructions

The first category of input data includes the problem title and one-time control and processing instructions.

Identifier	Meaning
TITLEE (Actual title apputilizing columns	(Instruction indicator) pears on card following TITLEE card, s 1-21 only.)
FEETLB MKSSYS	Input/Output data in feet and pounds. Input/Output data in meters and
DIAGLO	kilograms. No diagnostics printed.
DIAGL1	Extensive diagnostics printed.
DIAGL3	Complete diagnostics printed (normally for programmer's use only).
NEEVAL	Noise Exposure values to be calculated.

Identifier	Meaning
NEFCAL	Noise Exposure Forecast values to be calculated.
WECPNL	Weighted Equivalent Continuous Perceived Noise Level values to be calculated.
PRTALL	Print all input and output data and certain calculated tables.
CLCMPS	Small-size CALCOMP output plots.
CLCMPL	Large-size CALCOMP output plots.

Note: Where user-selected options are available among the one-time control and processing mnemonic instructions, only one can be included. Thus, either FEETLB or MKSSYS may be selected, but not both; either NEEVAL or NEFCAL or WECPNL but not more than one of these three; either CLCMPS or CLCMPL but not both; either DIAGLO or DIAGLI or DIAGLO but not more than one of these three, although one of this group does not have to be included for normal calculations.

The following one-time data are entered as the last cards in the program input deck.

GRIDCL	Instruction to set values for grid calculations. Must be followed by
	values assigned to each of the six
	following instructions.
DELTAX	X-increment between grid points to
	be calculated.
DELTAY	Y-increment between grid points to
	be calculated.
FIRSTX	Initial X value for grid calculations.
FIRSTY	Initial Y value for grid calculations.
NOOFXS	Number of X values for grid points
	(maximum of 20).
NOOFYS	Number of Y values for grid points
	(maximum of 25).
PROCES	Mandatory instruction to begin computer
	processing, using preceding input data.
	<u> </u>

runways on CALCOMP plot. Runway numbers are entered on this line using Format 8A6; that is, as many as eight runway designations may be entered as integers, beginning in columns 1, 7, 13, 19, etc.

Instruction to computer for labeling

ENDRUN

Mandatory final mnemonic instruction to indicate end of input data to program.

Instruction to computer to plot indicated noise exposure contours. Values of plotted contours are entered on this line using Format 3F10.1; that is, as many as three values may be entered with decimal points and one decimal, beginning in columns 1, 11, and 21.

Runway and Flight Path Descriptions

The second category of input information required for the Noise Exposure Model MOD 4 serves to define the geometry of the runways involved in the flight operations under consideration and the projected flight paths to be used by the simulated aircraft. In general, this information must be prepared once for each problem, but may be used repetitively throughout the problem.

Runways are defined by the three cartesian coordinates of the two ends of each runway, in the metric or English units (meters or feet) specified in the direction of the intended flight path (i.e., for a takeoff, the end at which the aircraft starts its takeoff roll is defined first, and the end toward which it accelerates for liftoff is defined second; for a landing, the threshold end of the runway is defined first, and the end toward which the aircraft rolls as it brakes to a halt is described second).

Flight paths are described as straight-line or constant-radius curved segments projected onto the horizontal reference plane (Z = 0), plus the angle of climb (or descent). For take-offs, Segment 1 is defined as the takeoff roll along the runway from brake release to liftoff. Segment 2 is the initial climb path immediately after liftoff, essentially a straight-line path with a specific angle of climb. The length of Segment 1 and the climb angle for Segment 2 are included in the Noise Exposure Model MOD 4 and depend on the aircraft class specified and the gross takeoff weight for that aircraft class.

The flight path segments beyond Segment 2 are called extensions and, if used, must be defined by input data describing the extent of each segment (angular extent if a curved segment), climb angle, thrust setting for the aircraft class being considered, and radius of the path (0 for straightline path, a negative (-) value for counterclockwise turn when viewed from above, a positive (+) value for clockwise turn viewed from above). If there are more than two segments for

each path, the length of Segment 2 (the initial climbout path) also must be defined.

For landings, the segments are numbered in reverse order from the path actually followed by an aircraft; that is, the landing roll along the runway from touchdown to the end of roll is defined as Segment 1, while the final glide slope just prior to touchdown is Segment 2. A landing roll (Segment 1) of 5280 feet and a final glide slope of 3° are assumed in the model. The sign convention for curved segments of the landing extensions also is reversed; that is, a counterclockwise turn when viewed from above will have a positive (+) radius, while a clockwise turn when viewed from above will have a negative (-) radius.

The runway and flight path descriptors are as follows:

RUNWAY	Instruction	to defin	ne runway.	Must be	e followed	by
	values assign	ned to	following	six inst	ructions.	

XCOORD	Value of X-coordinate of near end and far end of	
	runway (two values required, in units selected fo	r
	problem, meters or feet).	

YCOORD	Value of	Y-coordinate	of	near	and	far	ends	of
	runway.							

ZCOORD	Value of Z-coordinate of near and far ends of
	runway. Normally, both are set to zero (0).
	Actual provisions for non-zero values of Z are
	not presently included in the MOD 4 program.

TKGDRL	Distance along runway at which takeoff roll begins
	(i.e., brake-release point), normally assumed to
	be at near end of runway (i.e., zero value
	entered).

TCHDWN	Distance along runway at which touchdown occurs
	during landings, normally assumed to be 300 meters
	(1000 feet) to simulate fact that aircraft do not
	normally touchdown exactly at runway threshold.

NOFLTS	Number of flights using this runway, not to exceed 20. A flight is defined as one aircraft class (may include any number of individual aircraft of the same class) following one flight path. If more than 20 flights are required, the same runway should be redefined and considered as a
	new runway.

NOEXTS

Number of extensions in the flight path being described. If a simple takeoff roll and straight climbout (or straight-in glide slope and landing roll) are being simulated, enter 0.

PRSEG2

Extent of Segment 2 projected on horizontal reference plane (Z = 0); required if NOEXTS $\neq 0$.

EXTNSN

Identification instruction that begins definition of extension segment. Must be followed by four following instructions.

EXTENT

Extent of extension segment, expressed in meters (or feet) for straight-line segment, or degrees-of-turn for a constant-radius curved segment, as projected on the horizontal reference plane (Z = 0). Enter 0 if segment is infinite (i.e., last segment of path).

ELEVAT

Angle of climb (or descent) in degrees.

THRUST

Thrust setting for aircraft class simulated during this extension. For takeoffs, 100% thrust setting is normally assumed, unless a noise abatement cutback is to be simulated. During landings, a 45% thrust setting is normally assumed. The Noise Exposure Model MOD 4 includes noise level corrections for reduced thrust settings, appropriate to each aircraft class.

RADIUS

Radius of constant-radius curved flight segment, expressed in meters (or feet) as projected onto the horizontal reference plane (Z = 0). Enter 0 if the segment being described is a straight line, - value if turn is counterclockwise when viewed from above, + value if turn is clockwise for take-off paths, and the reverse sign convention for landing paths. Normally the farthest segment (last segment for takeoffs, first segment for landings) defined for any flight path should be a straight line; otherwise the program will simulate a helical climb (or descent) path and will calculate corresponding noise values.

Aircraft Flight Operations

The remaining general category of input information for the Noise Exposure Model MOD 4 serves to define the numbers and types of aircraft classes which operate from each of the runways and along each of the flight paths defined in the second information category. As noted previously, aircraft have been grouped into classes having similar noise characteristics and landing and takeoff profiles. The Noise Exposure Model MOD 4 assumes a 3° glide slope for all classes of aircraft for landing. The takeoff profile will depend, however, on the gross weight of each aircraft at takeoff (i.e., the heavier the aircraft is loaded, the more shallow will be its climb during takeoff). The takeoff profiles for each aircraft class, corresponding to their potential gross takeoff weights, are included in the computer program and require only that the aircraft class and gross weight be defined. At the user's option, length of takeoff roll and initial climb angle may be specified, overriding programmed data.

A third required definition for each aircraft class is the thrust setting used during takeoff and landing. Engine noise characteristics change with thrust or power setting, generally decreasing in intensity with decreased thrust. The relation between Effective Perceived Noise Level and thrust setting for each aircraft class is included in the Noise Exposure Model MOD 4 program. Normally, 100% thrust is used for takeoff, while 45% thrust is applied during final landing approach. Many airports require noise abatement power cutbacks after takeoff to reduce annoyance to airport neighbors. A thrust cutback with its associated decrease in rate of climb may be included in the Noise Exposure Model MOD 4 as an extension in the takeoff flight path.

The aircraft flight operations descriptors are the following:

FLIGHT	Instruction to define a single aircraft class flight.
LANDING	Indicates that the flight is a landing operation.
TAKEOFF	Indicates that the flight is a takeoff operation.
ACWGHT	Weight of the aircraft class in kilograms (or pounds).
THRUST	Thrust setting for aircraft class engines during the operation being described, in percent of full thrust.

ACTYPE

class.

One or two digit number code for aircraft

NDAYOP

Number of daytime operations of the aircraft class. For NE calculations, the daytime period includes the entire 24-hour period; for NEF calculations, the daytime period includes the period from 0700 to 2200; for WECPNL calculations, the daytime period includes the period from 0700 to 1900.

NEVNOP Number of evening operations of the aircraft class. Used only for WECPNL calculations, and includes the period from 1900 to 2200.

NNGTOP Number of nighttime operations of the aircraft. Used only for NEF or WECPNL calculations, and includes the period from 2200 to 0700.

CLIMBA Angle of climb (or descent) in degrees. Used only if standard takeoff profile (see Table 3) is not desired. If used, the value indicated overrides standard profile value.

PRSEG1 Length of takeoff roll (or landing roll) in meters (or feet). Must be used if CLIMBA is used.

While aircraft class gross takeoff weight is the best characteristic for determination of the takeoff profile within each class of aircraft, it is often the case that airport operations are available only in categories of trip length rather than gross takeoff weight. Tables 1 and 2 relate these two characteristics for use in coding input information for the Noise Exposure Model MOD 4. These tables also indicate the aircraft classes included in the program and the identifying code for each. Table 3 defines the various standardized takeoff and landing profiles included in the model. The lengths of takeoff roll are useful for determining the lengths of projected Segment 2, when coding takeoff flight path extensions. programmed climb angles also are useful when coding takeoff flight path extensions, if no thrust cutback is involved. a thrust cutback is required, for noise abatement operational purposes for example, the corresponding reduction in climb angle for the aircraft class under consideration is used. As noted above, the CLIMBA and PRSEGl mnemonic instructions override the programmed standardized profiles, allowing the user the option of entering his own profiles.

Table 1. Aircraft Classification and Takeoff Profiles

Table 2. Aircraft Classifications and Takeoff Profiles

H B	Aircraft Takeoff 0- 500 1000
	Д
	В
	В
	Д
	Д
В	В

* In nautical miles for trip length

Table 3. Descriptions of Standardized Profiles

Profile	Lengt	h of	Takeof	f Ro	11	Climb	o Angle	
AA	2550	feet	(780 m	eter	s)	18°	25'	
А	4000	11	(1220	н)	11°	48 '	
В	5500	Ħ	(1675	11)	9°	35 T	
С	6800	11	(2070	11)	7°	35'	
D	9200	H	(2800	11)	6°	001	
E	10600	11	(3230	11)	5°	00'	
PA	2800	**	(850	11)	5°	11'	
Profile	Lengt	h of	Landin	g Ro	11	Descei	nt Angle	
All	5280	fee	t (1610	met	ers)	3°	00"	

PROGRAMMER'S MANUAL

The objective of this section is to provide assistance to the computer programmer in preparing the input deck and in making corrections to cases that fail to execute successfully for the Noise Exposure Model MOD 4.

Input Instruction Format

The input instructions/data are entered into the computer by punched cards in the following format:

CARD E	ORMAT	
cols	1-6	Six-character Instruction/Data mnemonic.
cols	7, 8	Blank.
cols	9-23	First data field (if any) with mandatory decimal point in column 18.
cols	24,25	Blank.
cols	26-40	Second data field (if any) with mandatory decimal point in column 35.
cols	41-72	Blank (not read by program and can be used for comments).
cols	73-80	For user's use.

Deck Setup

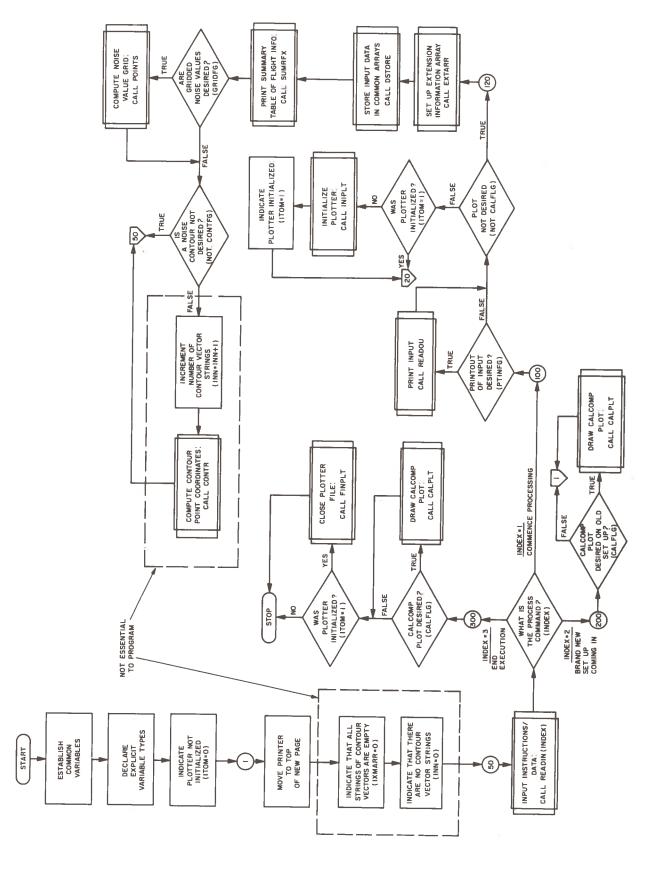
The following is the deck setup for running the Noise Exposure Model MOD 4. The computer is an IBM 7094 and the operating system is IBSYS Version 13.

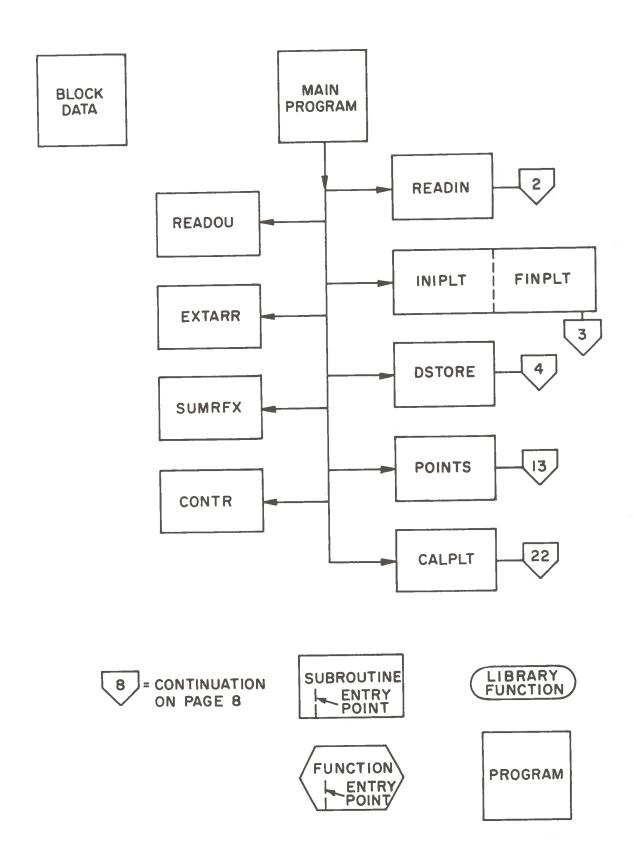
Column 1	Column 16
Job Card	
\$IBSYS	25
\$ATTACH	B5
\$AS	SYSCKl
\$EXECUTE	IBJOB
\$IBJOB	FIOCS
\$IEDIT	SYSCK1, SRCH
\$IBLDR MAIN	
\$LBLOR BLDA	
\$IBLDR KGLB	
\$IBLDR LBKG	
\$IBLDR MTF	
\$IBLDR FTM	
\$ORIGIN	ALPHA
\$IBLDR SUMRFX	
\$ORIGIN	ALPHA
\$IBLDR POIX	
\$IBLDR GENF	
\$IBLDR I	
\$IBLDR VUN	
\$IBLDR DOT	
\$IBLDR CROS	
\$IBLDR ADD	
\$IBLDR SUB	
\$IBLDR SCL	
\$IBLDR MAG	
\$IBLDR NOISE	
\$IBLDR DAT	
\$IBLDR ATTX	
\$IBLDR SLP	
\$IBLDR IBN	
\$IBLDR BN	
\$IBLDR DGT	
\$IBLDR XIN	
\$IBLDR NAC	
\$IBLDR ET2	
\$IBLDR ET3	
\$IBLDR ET4	
\$IBLDR EX	
\$IBLDR EX \$IBLDR VCT	
\$IBLDR THR	
\$IBLDR THR \$IBLDR CNTX	
\$IBLDR CNIX \$IBLDR FAIX	
·	
\$IBLDR HBEX	

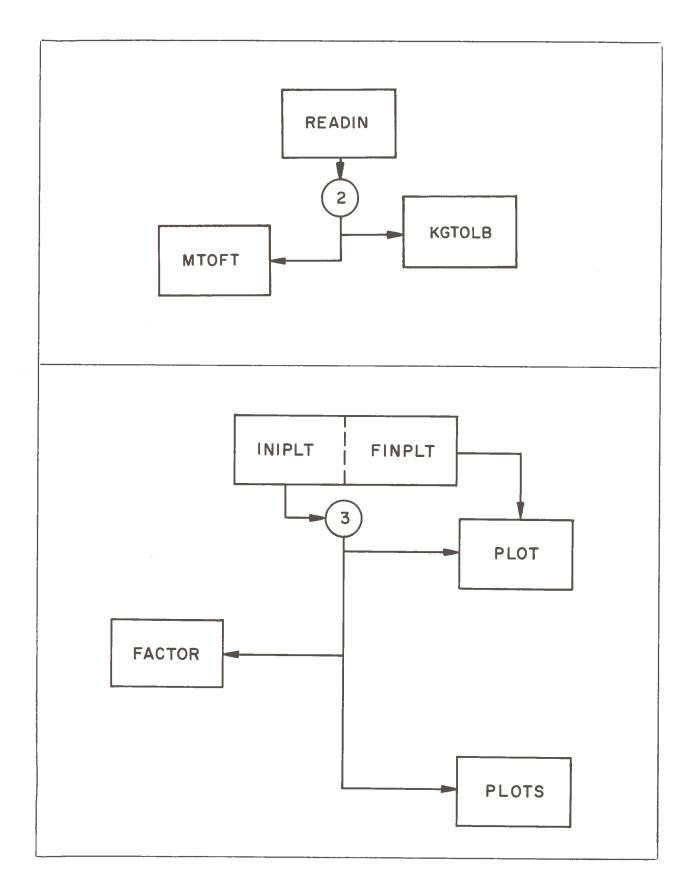
Column 1	Column	16
\$IBLDR F1X		
\$IBLDR F2X		
\$IBLDR F3X		
\$IBLDR SECX		
\$IBLDR PARX		
\$IBLDR FNHX		
\$IBLDR FUDX		
\$IBLDR ELUX		
\$IBLDR EXTX		
\$IBLDR HMNDX		
\$IBLDR HLMNX		
\$IBLDR CENHX		
\$IBLDR RDOX		
\$ORIGIN	BETA	
\$IBLDR EEXPNE		
\$IBLDR ET5N		
\$ORIGIN	BETA	
\$IBLDR EEXPWE		
\$IBLDR ET5W		
\$ORIGIN	BETA	
\$IBLDR STORE		
\$ORIGIN	ALPHA	
\$IBLDR SUB5OF		
\$ORIGIN	ALPHA	
\$IBLDR CALPWM		
\$IBLDR RWLGX		
\$IBLDR INIP		
\$IBLDR NOMX		
\$IBLDR REF		
\$IBLDR RUN		
\$IBLDR DLIN		
\$IBLDR PTA		
\$IBLDR LNE		
\$IBLDR AXE2 \$ORIGIN	GAMMA	
\$IBLDR HD	GAMMA	
\$ORIGIN	GAMMA	
\$IBLDR ACXX	GAMMA	
\$IBLDR CRECX		
\$IBLDR CUBX		
\$IBLDR ITPTX		
\$IBLDR STRKX		
\$IEDIT	SYSIN1	
\$DATA		
Instructions/Data go here		
7 - 8 card		
7 - 8 card		
· - 		

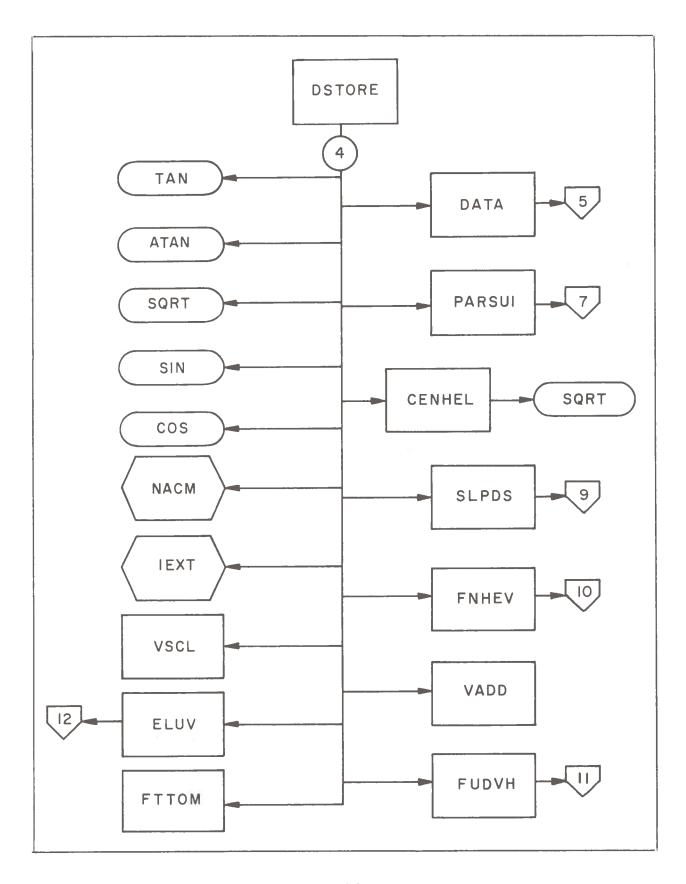
Flow Charts

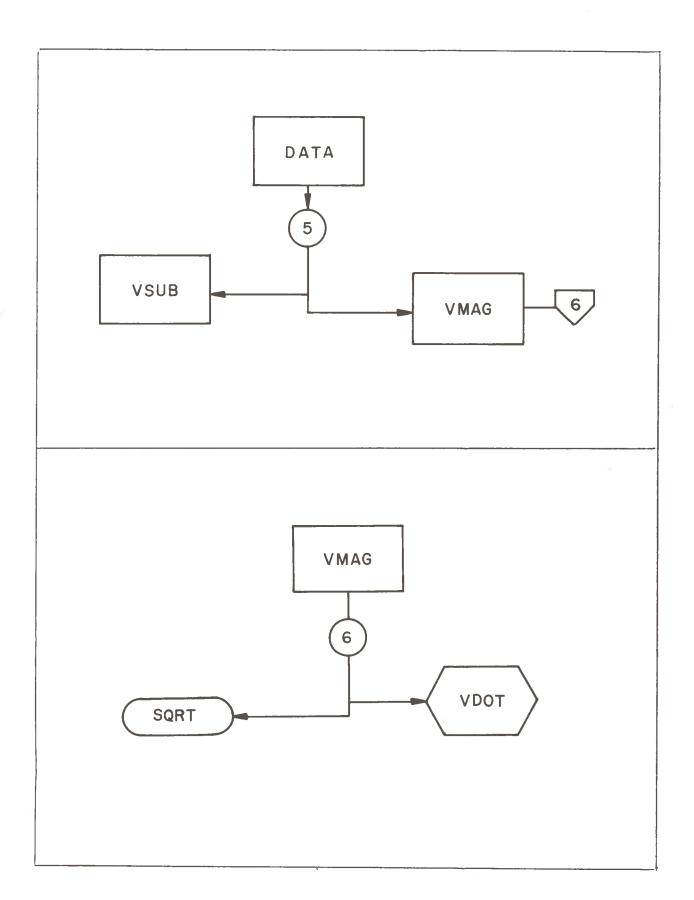
This section contains the overall program flow chart and a flow chart for each of the subroutines.

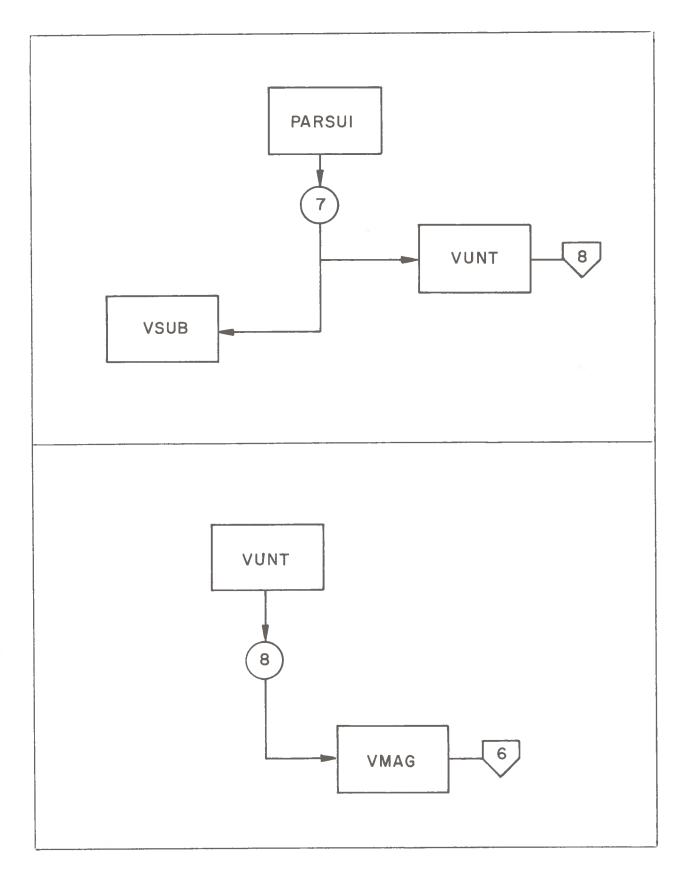


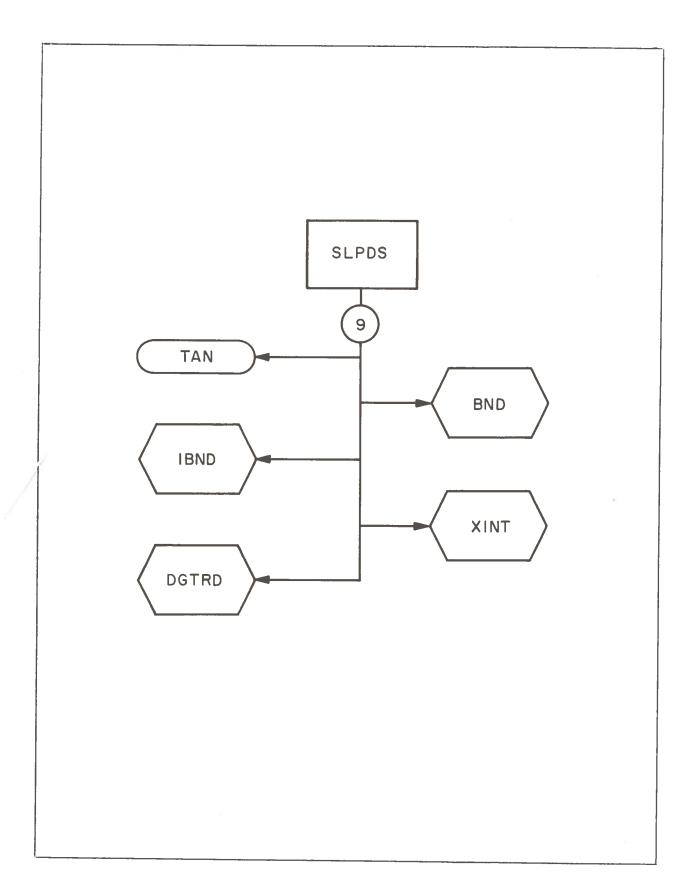


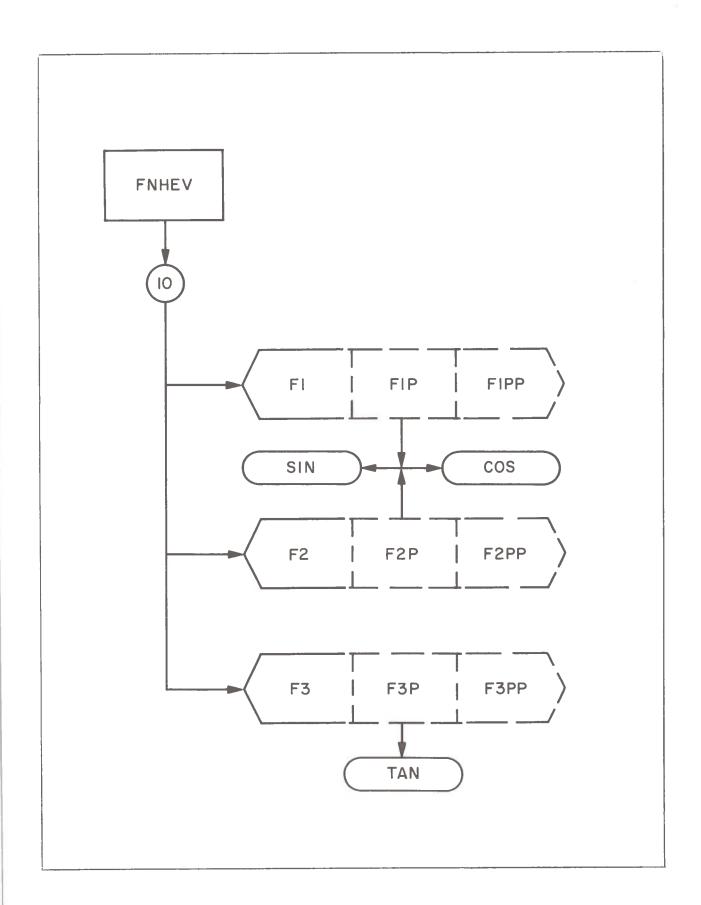


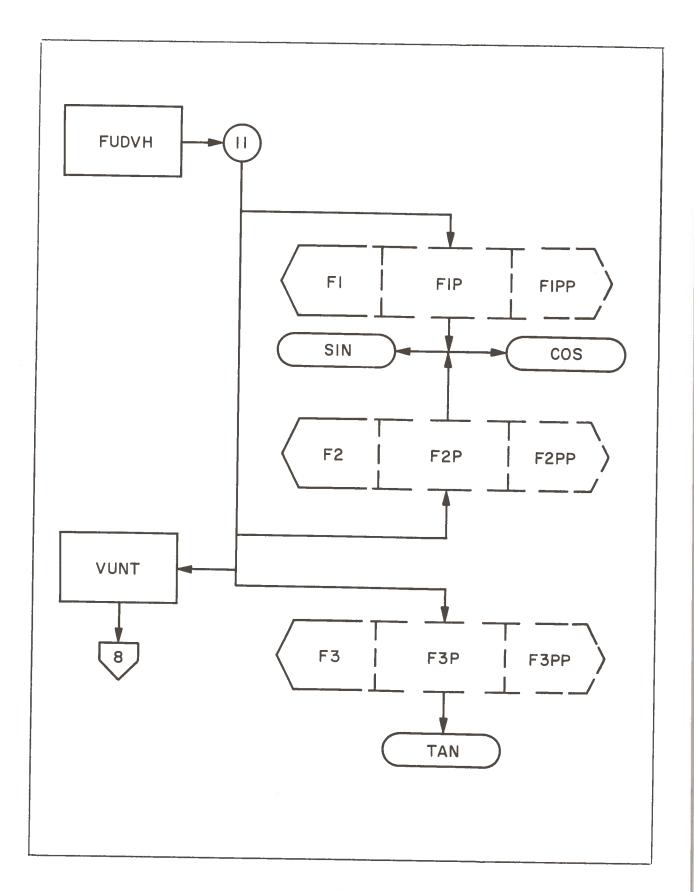


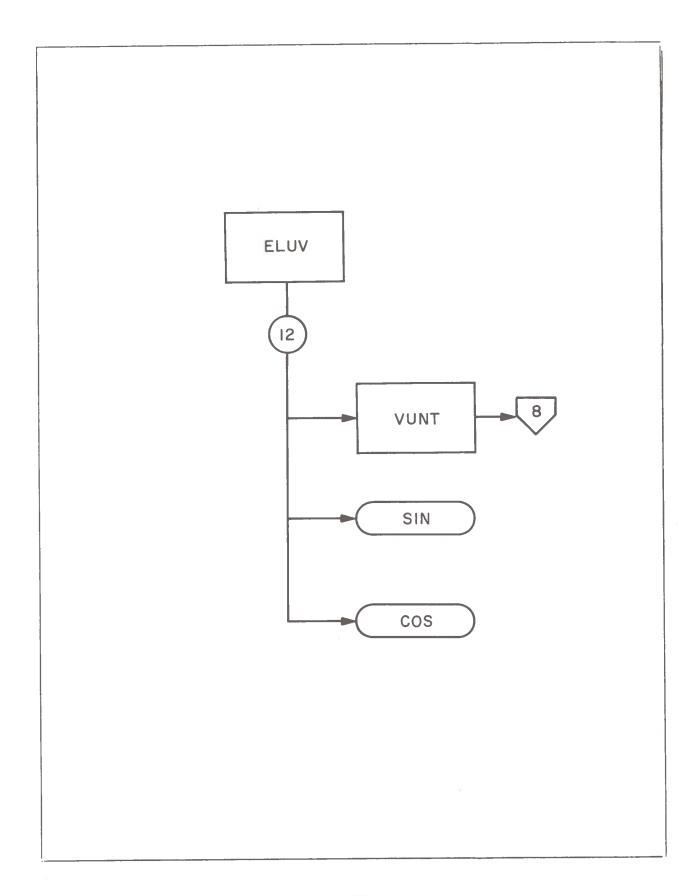


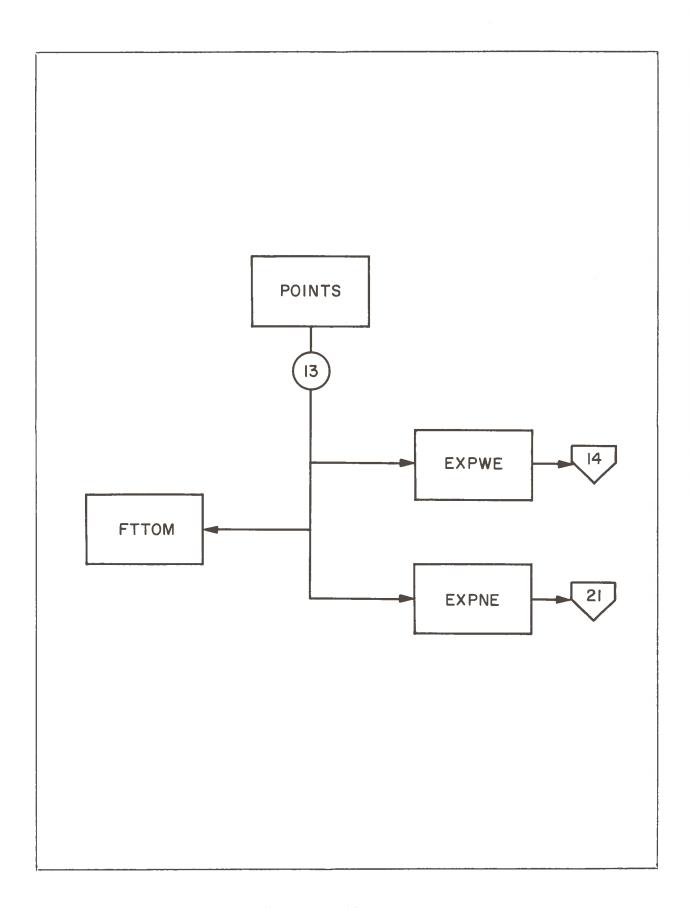


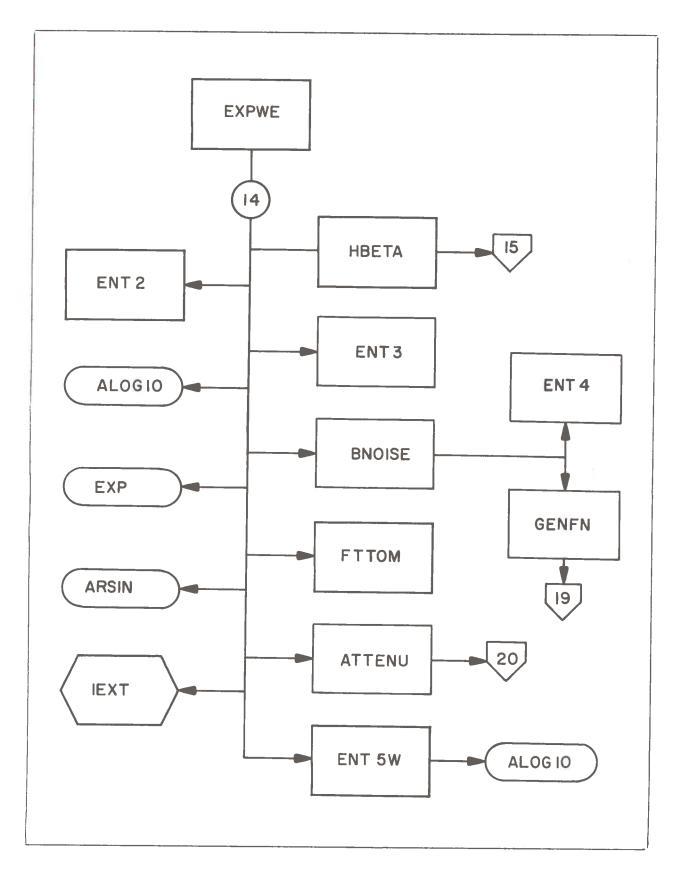


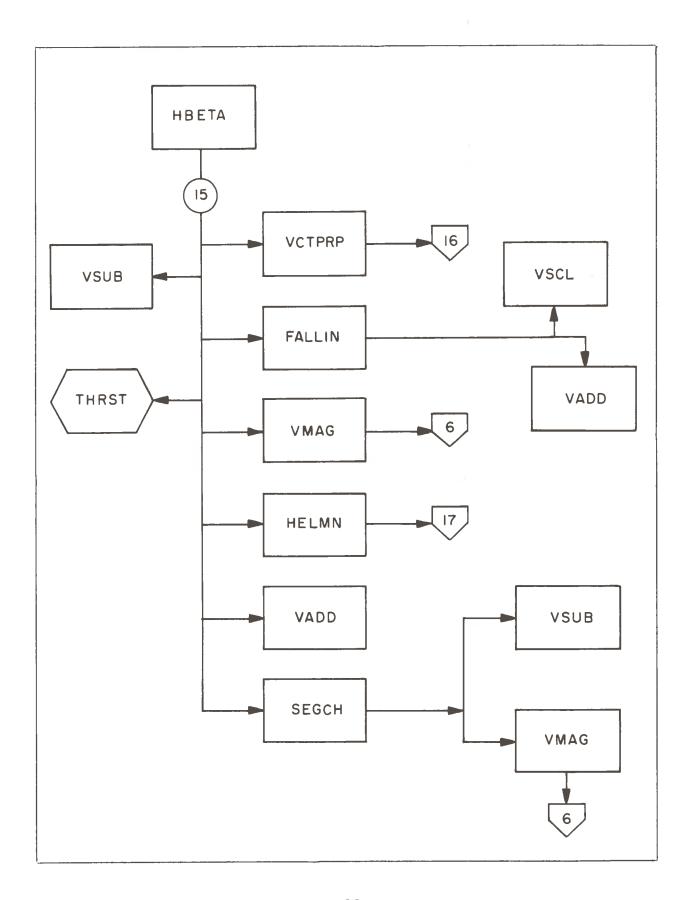


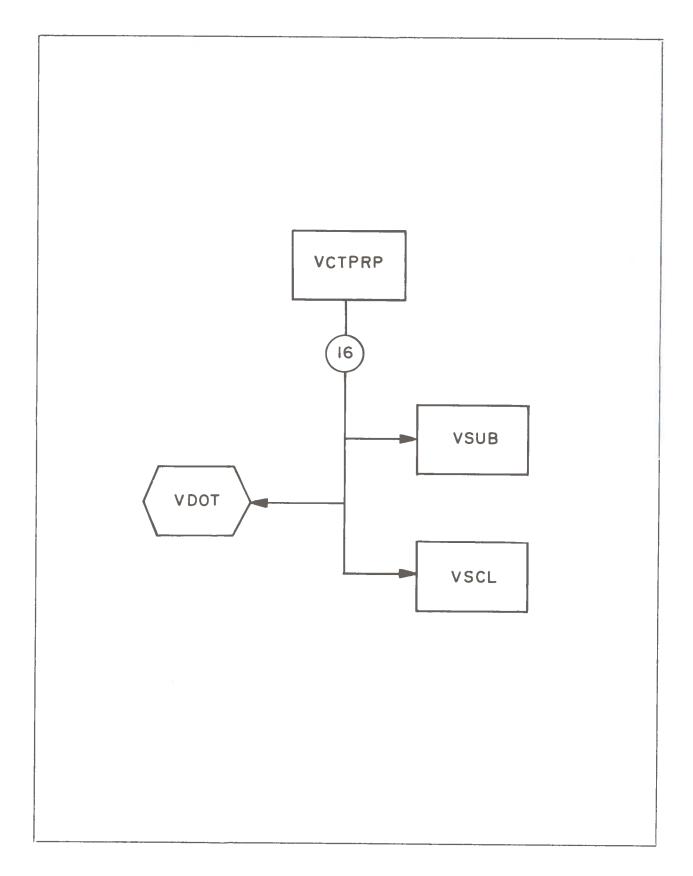


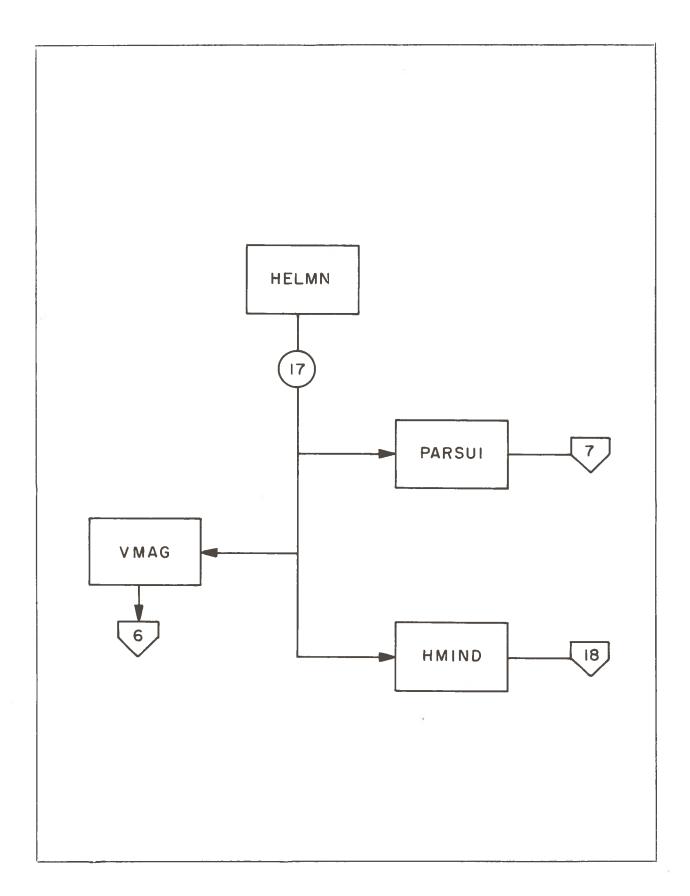


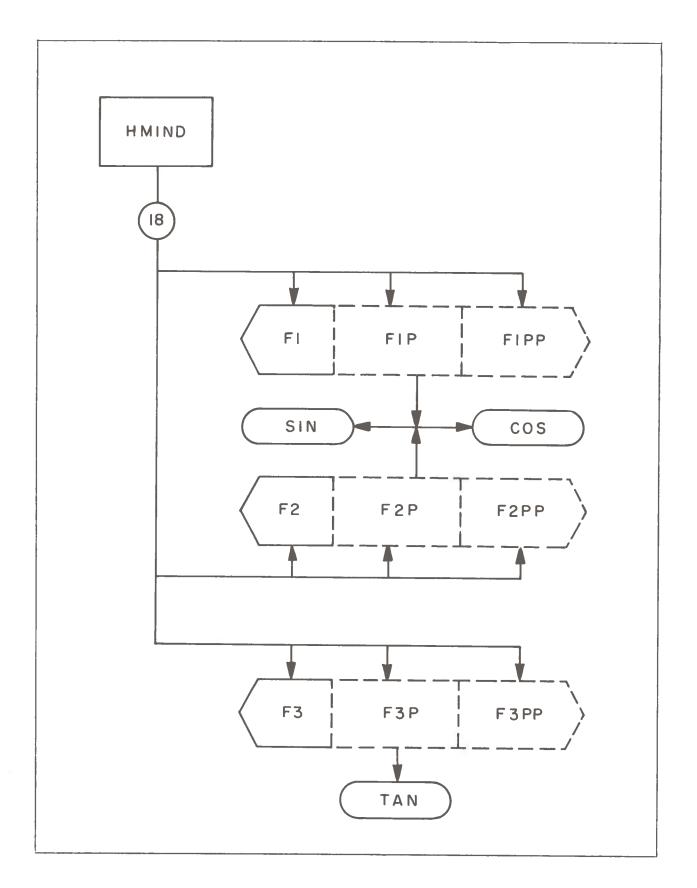


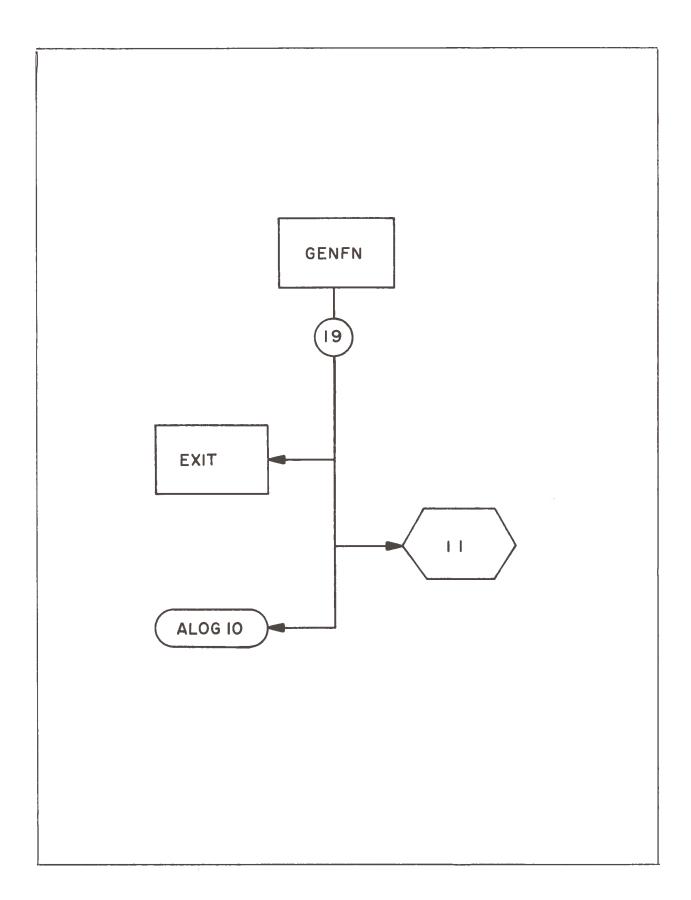


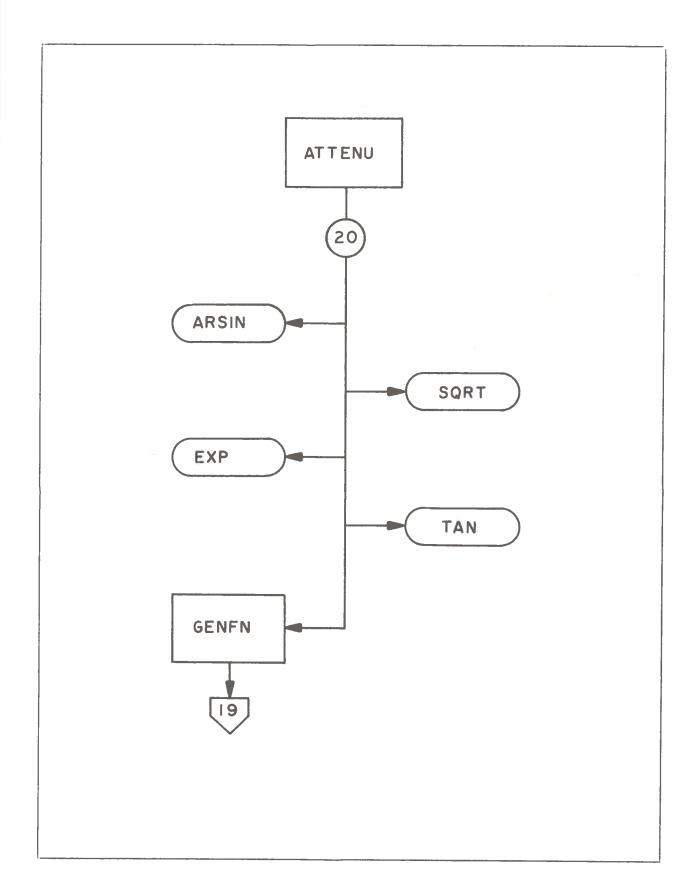


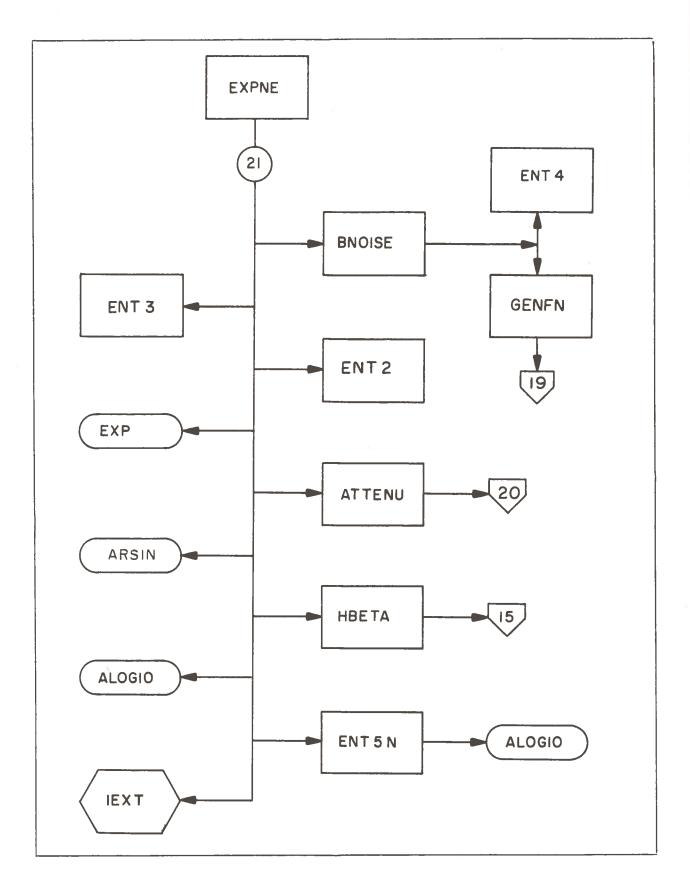


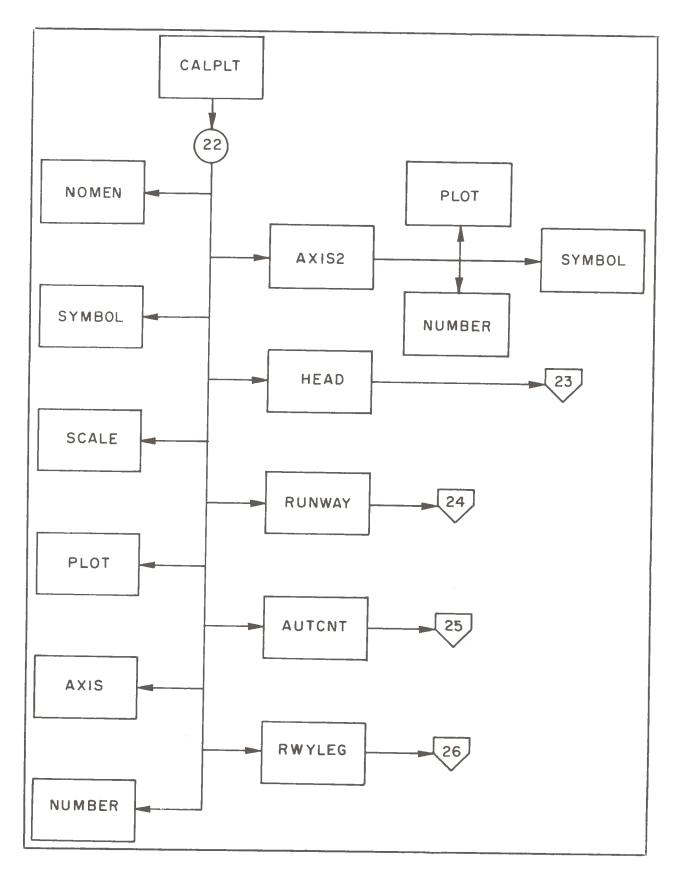


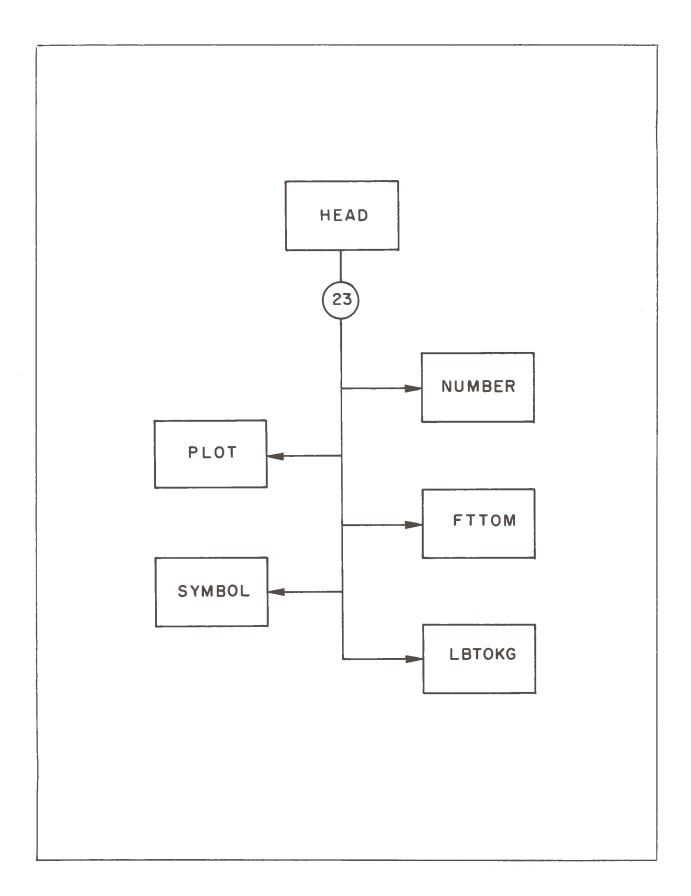


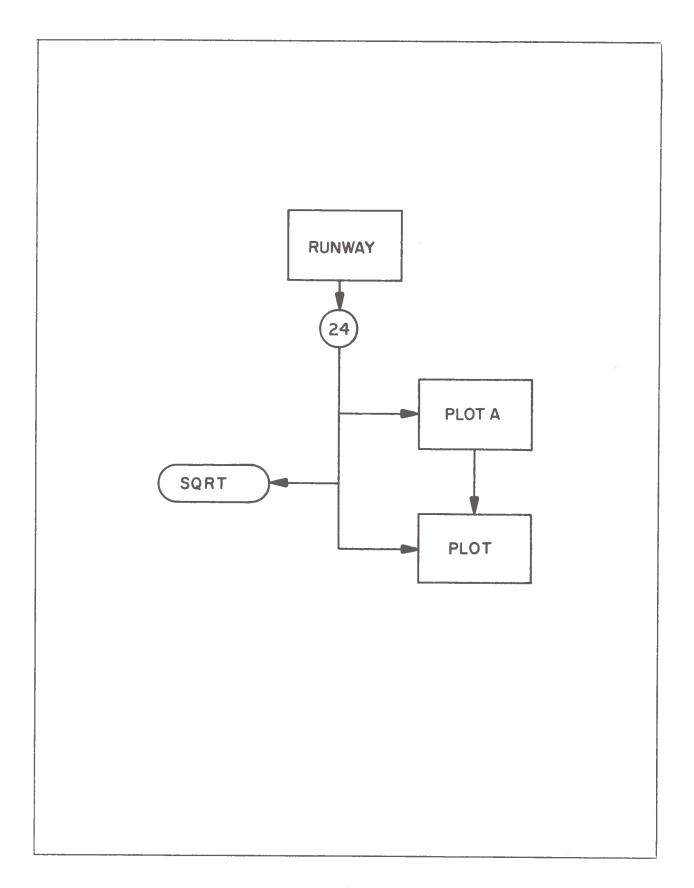


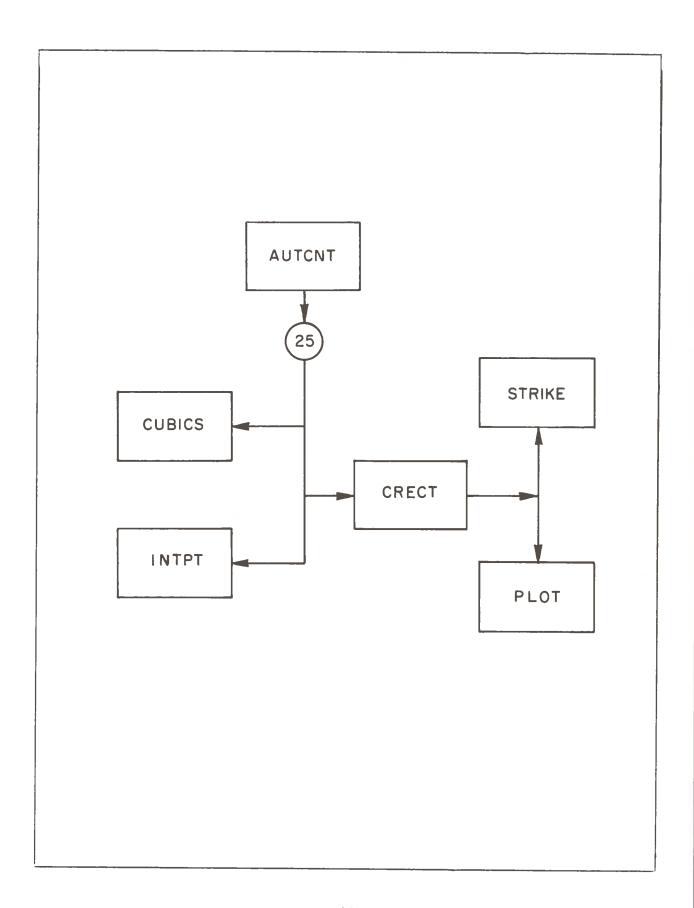


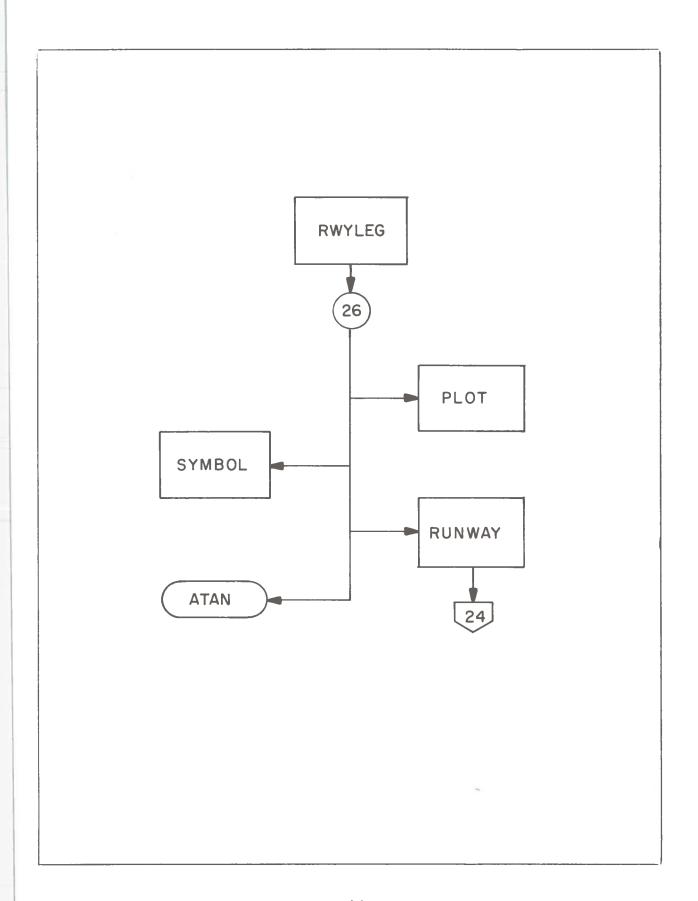












Description of Each Routine

This section describes the main program and all the subroutines.

MAIN PROGRAM

The MAIN program is the overall control program. It calls the READIN subroutine to read the input instructions/data and, on return, branches to either the initialization-and-processing section, the NEWSET section, or the ENDRUN section. For the last two returns, the MAIN program determines if CALCOMP plotting is to be done, in which case the subroutine CALPLT is called.

SUBROUTINE GENFN (M,X,MVAR,XXX)

GENFN performs a linear or log-linear interpolation or extrapolation on tables stored in its DATA statements. It does this by isolating the correct interval of a finite set that represents the curve, and then it proceeds to interpolate. Only the X-axis may be a log scale.

M T's number of the curve of interest.

X X-value for which corresponding Y-value is desired.

MVAR Indicator of type of quantity X-axis represents.

XXX Interpolated Y-value.

FUNCTION II (N1, N2)

II is a function subroutine which calculates the number of the middle interval between the intervals Nl and N2. It is used for isolating the interval of the X-value for interpolation purposes.

N1 Number of left-most interval under consideration.
N2 Number of right-most interval under consideration.

SUBROUTINE VUNT (C,A)

VUNT calculates the unit vector in the direction of any general vector.

C Resulting unit vector.

A Input vector.

FUNCTION VDOT (A,B)

VDOT is a function subroutine which calculates the dot product of any two general vectors A and B.

A Input vector.

B Input vector.

SUBROUTINE VCROS (C,A,B)

VCROS calculates the vector cross product of any two general vectors (i.e., $C=A\times B$).

C Vector cross product.

A First vector.

B Second vector.

SUBROUTINE VADD (C,A,B)

VADD calculates the sum of two vectors (i.e., C=A+B)

C Vector sum.

A Vector addend.

B Vector addend.

SUBROUTINE VSUB (C,A,B)

VSUB calculates the difference of two vectors (i.e., C=A-B).

C Vector difference

A Vector minuend.

B Vector subtrahend.

SUBROUTINE VSCL (C,F,A)

VSCL calculates the vector scalar product (i.e., C=FA).

C Vector scalar product.

F Scalar.

A Vector.

SUBROUTINE VMAG (A,XXX)

VMAG calculates the magnitude of a vector.

A Input vector.

XXX Scalar magnitude.

SUBROUTINE BNOISE (TAC, HX)

BNOISE calculates the EPNdB value associated with the aircraft type and distance from observer to flight path.

TAC Aircraft type number.

HX Perpendicular distance from observer to flight path.

SUBROUTINE DATA (J)

DATA calculates the unit vector of the flight path segment on the runway and the distances of the touchdown and take-off roll points from the start of the runway.

J Runway number.

SUBROUTINE ATTENU (SB, HX, FTT, XXX)

ATTENU calculates the ground attenuation as a function of the distance to the observer and the observer's elevation angle.

SB Sine of the elevation angle from observer to flight path.

HX Perpendicular distance from observer to flight path.

FTT $\neq 0$ landing. = 0 takeoff.

XXX Ground attenuation value.

SUBROUTINE SLPDS (NZ, ACWT, DIST, IE, XXX)

SLPDS calculates the tangent of the climbout or descent angle for takeoff and landing flights respectively. In the case of takeoffs, it also calculates the distance along the runway from start of takeoff ground roll to takeoff.

NZ Aircraft type number (+ if takeoff, - if landing).

ACWT Aircraft weight.

O. returned if landing; otherwise distance from start of takeoff ground roll to takeoff point.

IE Error indicator set by subroutine.

Tangent of climbout or descent angle. XXX

LOGICAL FUNCTION IBND (IV, IS, IH)

IBND is a function subroutine of LOGICAL type that assumes the value FALSE unless the first argument lies between the second and third arguments (i.e., IS<IV<IH). All arguments are of type INTEGER.

Test value. ΤV Lower bound. IS Upper bound. IH

LOGICAL FUNCTION BND (V, S, H)

BND is a function subroutine of LOGICAL type which assumes the value FALSE unless the first argument lies between the second and third arguments (i.e., S<U<H). All arguments are of type REAL.

Test value. V Lower bound. Upper bound. H

FUNCTION DGTRD (DG)

DGTRD is a function subroutine which converts a quantity in degrees to radians.

Quantity in degrees. DG

FUNCTION XINT (PT, Y)

XINT is a function subroutine which calculates the X-coordinate of the point lying on the straight-line segment between two given points.

> The array of length 4 containing the PT coordinates of the two given points stored thus: X_1, Y_1, X_2, Y_2 .

Y-coordinate of point of interest.

FUNCTION NACM (FL, ACT)

NACM is a function subroutine which assigns a positive sign to the aircraft type number for takeoffs and a negative sign for landings.

> (0. takeoff. FL11. landing.

ACT Aircraft type number.

SUBROUTINE ENT2 (CAT, TW, PNF, IXX, FLT)

ENT2 is a diagnostic subroutine used to print intermediate values.

CAT Aircraft type number.

TW Aircraft weight.

PNF Aircraft thrust in percent.

IXX Aircraft profile number.

FLT | 0. takeoff. | 1. landing.

SUBROUTINE ENT3 (XO, NO, DQ)

ENT3 is a diagnostic subroutine used to print intermediate values.

XO Elevation angle from observer to flight path

in degrees.

NQ Number of operations (classified as day operations for NE calculations, as day-evening-night operations for WECPNL calculations, and as day-night operations for

NEF calculations).

DQ Distance from observer to flight path.

SUBROUTINE ENT4 (IFN, XCOR, XTH, XEPN)

ENT4 is a diagnostic subroutine used to print intermediate values.

IFN Number of particular EPNdB vs distance curve. XCOR Correction to curve (of an additive nature).

XTH Thrust correction to curve (because of

varying thrust).

XEPN Raw EPNdB value from curve.

SUBROUTINE ENT5N (XI, YI,ZI, XNEI,AXEI); SUBROUTINE ENT5W (XI, YI, ZI, XNEI, AXEI)

Subroutines ENT5N and ENT5W are diagnostic subroutines used for printout of intermediate values.

XI Attenuation value.

YI Shielding value.

Noise contribution from identical operations (day operations in ENT5N and day-evening-night operations in ENT5W).

XNEI Net EPNdB value. AXEI EPNdB subtotal.

INTEGER FUNCTION IEXT (IS, JS)

IEXT is a function subroutine of the INTEGER type which gives the location in a set of arrays where information about the extension of a flight can be obtained. The total of all extensions is designated by NEXT. If the value KS, where I<KS<NEXT, corresponds to the first extension of some flight and some runway, then KS+I designates the second extension if there is one of the same flight and runway. KS denotes the location in the set of arrays at which information pertaining to the extension is available. If the given flight and runway have no extensions, then the value of 0 is returned by the function.

IS Flight number.
JS Runway number.

SUBROUTINE VCTPRP (POS, UNIT, PR, PRP)

 $\ensuremath{\text{VCTPRP}}$ calculates the vector $\ensuremath{\text{V}}$ from a given point P to a given line L.

POS Some point through which line L passes.
UNIT A unit vector in direction of line L.
PT The given point P.
PRP Vector from point to line V.

FUNCTION THRST (TH1, TH2, X)

THRST is a function subroutine which adjusts the thrust between two segments of a flight path so that the transition of thrusts between the segments will be continuous.

TH1 Percent thrust on first segment.
TH2 Percent thrust on second segment.
X Distance along second segment.

SUBROUTINE HBETA (HX, BETAS, PEN, MAXSET, OBR, ISEG, NFL)

HBETA calculates the distance from observer to each segment of the flight path, the elevation angle, and the percent thrust for a given runway, flight, and observer position. HBETA calls either subroutine VCTPRP to compute minimum distances to linear segments or subroutine HELMN to compute minimum distances to helical segments.

HX Distance from observer to flight path.

BETAS Sine of elevation angle of observer to flight

path distance above plane of runway.

PEN Percent thrust.

MAXSEG Segment number which yields maximum noise.

OBR Observer position.

ISEG Number of segments for this flight.

NFL Number of flight (cumulative over all flights).

SUBROUTINE DSTORE

DSTORE calculates from the input data the values of the arrays in the labeled COMMON block XNEW. These include the position vectors of the end points of the segments of each flight and the unit vectors in the direction of the segments of each flight. For helical segments, DSTORE calls CENHEL to find the position vector of the center of the helix. If requested, DSTORE also prints a table of each flight's segments with the above information.

BLOCK DATA

The BLOCK DATA subprogram assigns via DATA statements values to such quantities as number of aircraft types, take-off profile data, elevation angles for various aircraft weights, scaling constants, common mathematical constants, and noise exposure constants.

SUBROUTINE POINTS

POINTS calculates either the Noise Exposure values (NE), the Noise Exposure Forecast values (NEF), or the Weighted Equivalent Continuous Perceived Noise Levels (WECPNL) throughout the points of a grid. The grid is defined via input in subroutine READIN.

SUBROUTINE KGTOLB (A, IDIM)

KGTOLB converts kilograms to pounds.

A Array of kilogram quantities converted to

pounds.

IDIM Dimension of array.

SUBROUTINE LBTOKG (A, IDIM)

KBTOKG converts pounds to kilograms.

A Array of pounds quantities converted to

kilograms.

IDIM Dimension of array.

SUBROUTINE ELUV (NSEGM, NFL)

ELUV calculates the unit vector at the initial point of a flight segment, given the unit vector at the terminal point of the preceding flight segment and the elevation angle above the XY plane of the current segment.

Number of segment. NSEGM

Number of flight (cumulative). NFL

SUBROUTINE EXTARR

EXTARR sets up the extension information for flights with extensions in certain arrays, each of which describes some property of the extension.

SUBROUTINE HMIND (THET1, THET2, THET, VEC)

HMIND finds that value of the angle THET which yields the minimum distance from a point (the observer) to the helix. The components of the helix are defined in the function subprograms F1, F2, and F3 called HMIND. A Newton-Raphson iterative technique is used to solve the minimum distance equation for THET. Failure to converge is indicated by assigning the value -99999. to THET.

Angle in radians representing the lower bound of THET1 interval of interest (usually 0).

Angle in radians representing the upper bound of THET 2

interval of interest.

Angle in radians at which minimum distance THET

Minimum distance vector from observer position VEC

to helix.

SUBROUTINE HELMN (OBR, I, NFL, VEC, TH)

HELMN is the control subroutine which finds the minimum distance vector from an observer position to the helix and the angle at which this minimum occurs. The actual computations are done by HMIND, which is called by HELMN.

I NFL	The observer position vector. Segment number of helical segment. Number of flight (cumulative). Minimum distance vector from observer to helix. Angle in radians at which minimum distance occurs.
----------	--

SUBROUTINE CENHEL (NSEGM, NFL)

CENHEL finds the position vector of the center of a helical segment and stores the vector in the array HELCN.

NSEGM Segment number of helical segment.
NFL Number of flight (cumulative).

FUNCTION F1(X); FUNCTION F2(X); FUNCTION F3(X)

F1, F2, and F3 are function subroutines which compute the three components respectively of the vector from the observer position to the point on the helix which subtends the central angle X (where X=0. corresponds to the start of the helix). Entry points also exist to calculate the first two derivatives of these components.

X Central angle in radians subtended by point on helix.

SUBROUTINE SEGCH (NSEGM, NFL, OBR)

SEGCH chooses the flight path segment onto which the projected distance from an observer position falls and which yields the minimum distance. It does this by examining the array IDTOSI set up by subroutine FALLIN. If the projected distance does not fall within any of the flight segments, it chooses the appropriate segment according to an algorithm.

NSEGM Returned segment number.

NFL Number of flight (cumulative).

OBR Observer position.

SUBROUTINE READIN (INDEX)

READIN is the master input subroutine that reads all the instructions/data cards following the \$DATA control card. Whenever a PROCES card is read, it returns control to the MAIN program with INDEX set to 1 to signal that processing should commence; finally when an ENDRUN is read, INDEX is set to 3 and return indicates that execution is to end.

SUBROUTINE PARSUI (OBR, NSEGM, NFL)

PARSUI calculates the appropriate values for the parameters in the labeled COMMON block CHELX used by the function subprograms F1, F2, and F3.

OBR Observer position. NSEGM Segment number.

NFL Number of flight (cumulative).

SUBROUTINE FNHEV (TH, VEC)

FNHEV finds the vector from the center of the helix to the helix for any given angle TH (TH=0. is the start of the helix).

TH Angle in radians.

VEC Vector from center of helix to helix.

SUBROUTINE FUDVH (TH, VECI)

FUDVH finds the unit vector which is tangent to the helix and in the direction of flight at the angle TH (TH=0. is the start of the helix).

TH Angle in radians. VECI Tangential unit vector.

SUBROUTINE MTOFT (A, IDIM)

MTOFT converts meters to feet.

A Array of meter quantities converted to feet.

IDIM Dimension of array.

SUBROUTINE FTTOM (A, IDIM)

FTTOM converts feet to meters.

A Array of feet quantities converted to meters.

IDIM Dimension of array.

SUBROUTINE EXPNE (DUMY, XXX); SUBROUTINE EXPWE (DUMY, XXX)

EXPNE and EXPWE are the overall control programs for calculating the NE, NEF, and WECPNL values respectively. Although the algorithms are slightly different, each subroutine essentially first calculates the distance and elevation angle of the observer position to the proper flight path segment and the runway under consideration; from that, the EPNdB value is computed and then modified for ground attenuation, shielding, and identical operations to get a noise value for that particular flight and runway. Finally, a weighted addition is performed for all flights and all runways to get the NE, NEF, or WECPNL values respectively.

DUMY Dummy argument.
XXX NE, NEF, or WECPNL value.

SUBROUTINE CONTR

CONTR computes the contour associated with a specific NE, NEF, or WECPNL value, using the Newton-Raphson iterative technique for the Y value associated with a given X value and given NE or WECPNL value. Failure to converge after 6 iterations terminates the processing for that contour.

SUBROUTINE FALLIN (INSEGM, NFL, X)

FALLIN determines whether a projected observer point lies within or outside a given segment of a flight path. If outside the segment, it determines whether it lies before or after (in a chronological sense) the segment. It also indicates whether it is unable to determine where the projected point lies in relation to the segment or if there is no projected point.

NSEGM Segment number of flight.

NFL Flight number (cumulative).

X -100. linear segment.

-99999. previously unable to determine projected point to helical segment; otherwise, angle in radians associated with projected point onto helical segment.

SUBROUTINE HEAD (NUM)

HEAD is the subroutine which plots detailed text descriptions of the flights constituting the run. Since it is detailed, it is not called when the number of distinct flights exceeds 10.

NUM Total number of flights.

SUBROUTINE PLOTA (X, Y, I)

PLOTA is a subroutine which performs the same function as the CALCOMP subroutine PLOT except that the point X, Y is rotated before plotting a specified angle about a specified point. The specified angle and specified point are contained in the labeled COMMON block IANG. PLOTA is used, for example, to draw runways at various angles.

- X, Y Coordinates of point under consideration before rotation.
- I Same argument as in PLOT subroutine.

SUBROUTINE AXIS2 (X0, Y0, AMAX, AMIN, DELX, AINCH, BCD, NCH, NDEC, DELN)

AXIS2 is a subroutine used in place of the CALCOMP

subroutine AXIS when data are to be scaled to an axis rather than the axis being fitted to the data.

X0, Y0 AMAX, AMIN	Coordinates of starting point of axis. Maximum and minimum values on axis.
DELX	The increment along the axis at which tic marks and labeling will occur.
AINCH	The length of the axis in inches; if negative, horizontal axis is drawn, and
	if positive, a vertical axis is drawn.
BCD	The title for the axis.
NCH	Number of characters in the title.
NDEC	The number of decimal places on the numerical labels at tic marks; if -1,
	no decimal places and no decimal point are drawn.
DELN	Scale value to be used in scaling data to this axis; this value is returned
	by AXIS2.

SUBROUTINE ALINE (X, Y, N, XM, DELX, YM, DELY)

ALINE is a subroutine which draws a line connecting a set of points to user-specified scaling.

X	Array of X-coordinates of set of points.
Y	Array of corresponding Y-coordinates of
	set of points.
N	Number of points in each array.
XM	Minimum value on X-axis.
YM	Minimum value on Y-axis.
DELX	Increment along X-axis.
DELY	Increment along Y-axis.

SUBROUTINE CALPLT

CALPLT is the main subroutine which controls CALCOMP plotting. It performs appropriate conversions, sets up the FLIGHT array for plotting detailed text flight descriptions (provided the number of flights is not greater than 10), draws the axes with proper labeling, calls the RUNWAY subroutine to plot the runways, calls the NOMEN subroutine for optional additional labeling, and calls the AUTCNT subroutine up to three times to generate contour plots for a specified noise value. It also notifies the CALCOMP operator when to change pen colors.

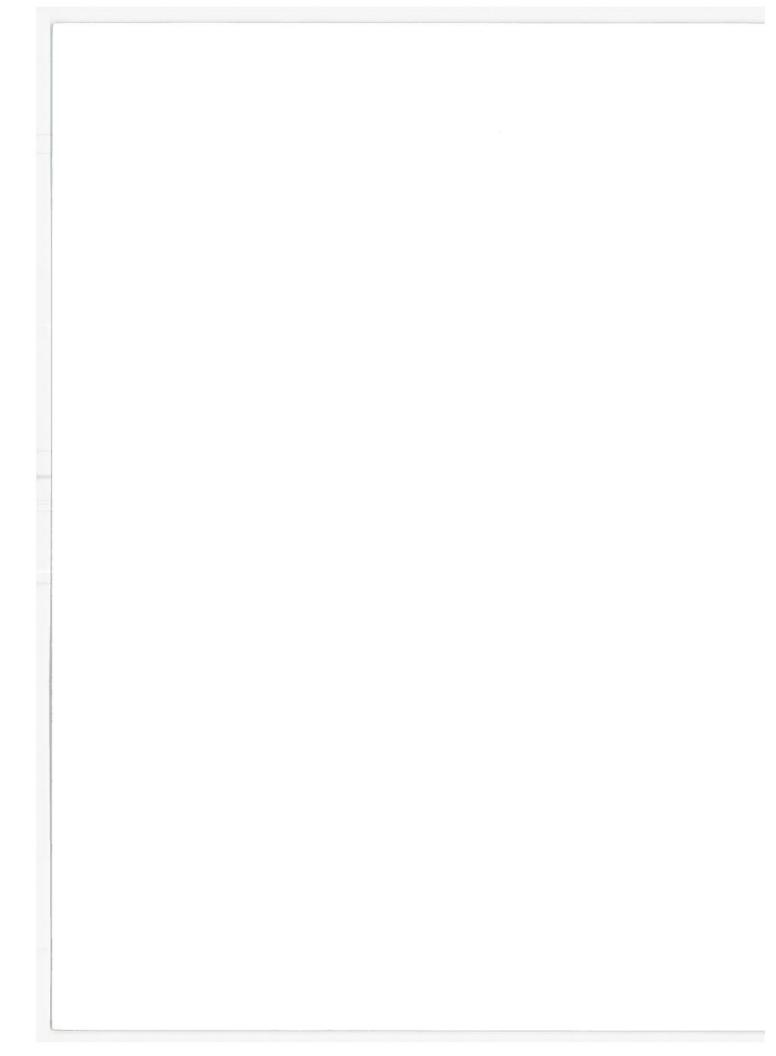
SUBROUTINE INIPLT

INIPLT initializes and finalizes the CALCOMP plotter

capability. It also calls the subroutine FACTOR to scale the entire plotting data to either the small-size or large-size plot paper. The entry for finalization is FINPLT.

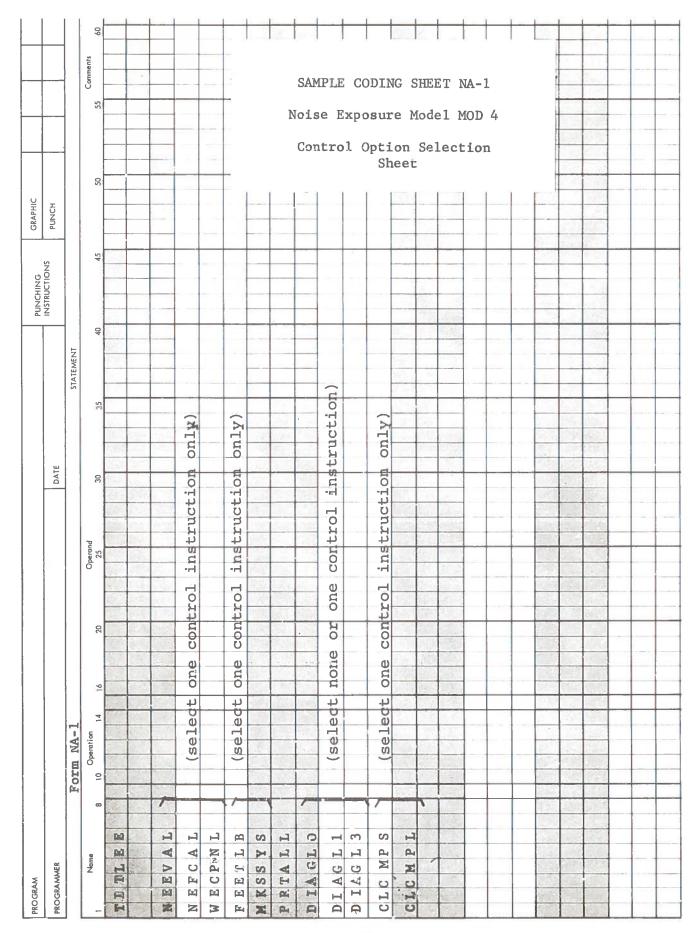
SUBROUTINE RUNWAY (X1, Y1, X2, Y2)

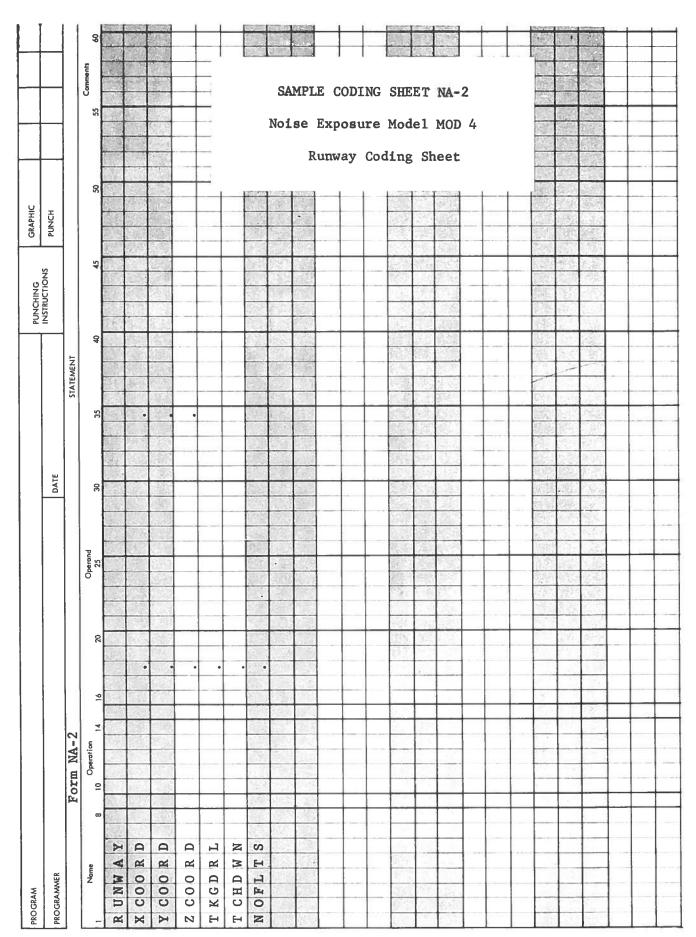
RUNWAY draws the runway with specified coordinates on the CALCOMP plotter.



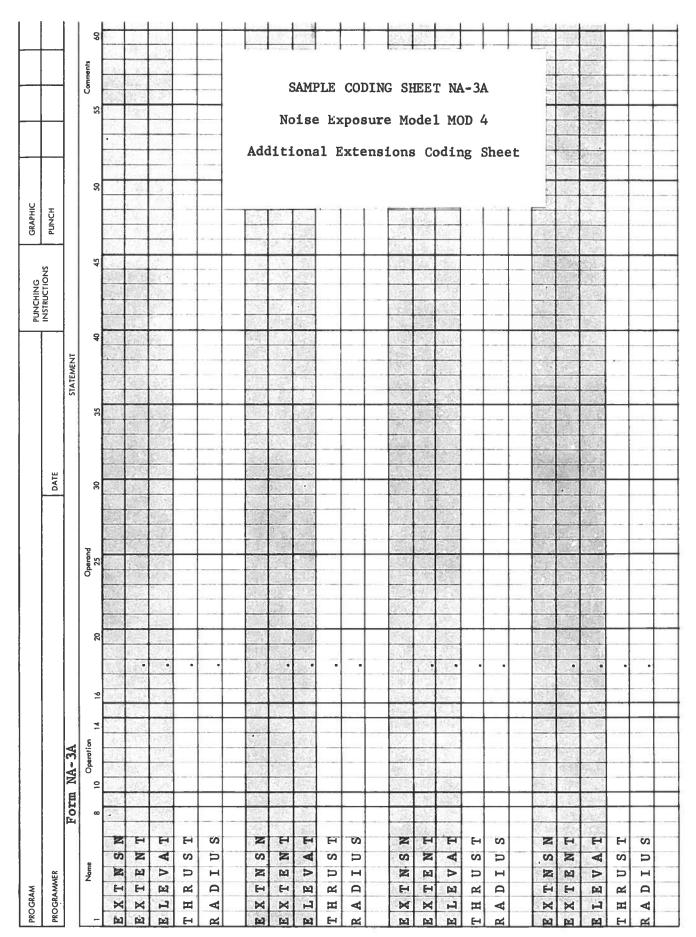
APPENDIX A

Suggested coding work sheets for Noise Exposure Model MOD 4





PROGRAM						PUNCHING	GRAFIEL		
PROGRAMMER			DATE			INSTRUCTIONS	PUNCH		
	Form NA-3			S	STATEMENT				
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Delica Admini									
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			Operation 14 16 20

APPENDIX B

Sample problem to illustrate use of Noise Exposure Model MOD 4

Sample Problem

To assist in explaining the actual use of the Noise Exposure Model MOD 4 and to illustrate the type of results the model produces, this sample problem is included, along with copies of the associated coding sheets and the printed computer results. This sample problem includes only two runways and 14 flights. Note that 20 flights are actually listed in the description of daily operations given below, but that several types of aircraft fall into the same classification (for example, both the DC-9 and BAC-111 aircraft are two-engine LBPR turbofan types). Thus, only 14 flights are needed for the model computation. The typical airport for which noise exposure calculations are required will be considerably more elaborate.

Sample Airport requires Noise Exposure Forecast (NEF) contours for 1975. Sample Airport consists of two runways: the 4000-meter-long Runway 3-21, and the 3000-meter-long Runway 8-26 (see Figure B-1). The aircraft using this airport follow reasonably well-defined paths for both takeoffs and landings. Because of a residential area east of the airport, aircraft taking off on Runway 8 and continuing eastward are required to throttle back at a 4% climb at a distance 12,000 meters from the end of the runway. The latest prediction for numbers, types, and distribution of daily operations at Sample Airport for 1975 were provided as follows (again see Figure B-1) for clarity):

Runway 8 - Flight	t Path A (landings)	:			
Flight A-1	727-type aircraft	43	daytime	14	nighttime
A-2	DC-9-type aircraft	32		7	
A-3	BAC-111-type aircra	ft 6		2	
Runway 8 - Flight	t Path B (takeoffs):				
Flight B-1	727-type aircraft	29	daytime	2	nighttime
	(57,000 kg)				
B-2	727-type aircraft	8		3	
	(72,000 kg)				
B-3	DC-9-type aircraft	24		2	
	(40,000 kg)				
B-4	BAC-111-type	4		0	
	(42,000 kg)				
Runway 8 - Flight	t Path C (takeoffs):				
Flight C-l	727-type aircraft	8	daytime	2	nighttime
-	(57,000 kg)				
C-2	727-type aircraft	5		0	
	(72,000 kg)				
C-3	DC-9-type aircraft	10		3	
	(40,000 kg)				
C-4	BAC-111-type				
	(42,000 kg)	3		1	

		nt Path D (landings): 747-type aircraft		davtime	2	nighttime
riigne		707-320B/C types	23	adycime		migneeime
		DC-8-50/60 types	15		9	
Runway 21 -	Fligh	nt Path E (takeoffs)	:			
Flight		747-type aircraft	6	daytime	1	nighttime
		(200,000 kg)				
	E-2	707-320B/C types	15		7	
		(95,000 kg)				
	E-3	DC-8-50/60 types	9		4	
		(95,000 kg)		*		
Runway 21 -	Fligh	nt Path F (takeoffs):	:			
Flight	F-1	747-type aircraft	2	daytime	0	nighttime
		(200,000 kg)				
	F-2	707-320B/C types	10		3	
		(95,000 kg)				
	F-3	DC-8-50/60 types				
		(95,000 kg)	9		2	
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Sample coding sheets and the computer printout follow, for purposes of illustrating the use of the Noise Exposure Model, MOD 4. Not all of the coding sheets are included, to reduce the size of the report, but all of the input data is shown in the computer printout. Recall that columns 41 and beyond are not used for computational purposes, but can be used for comments. In the sample which follows, this feature has been used to label each runway and each flight for bookkeeping purposes.

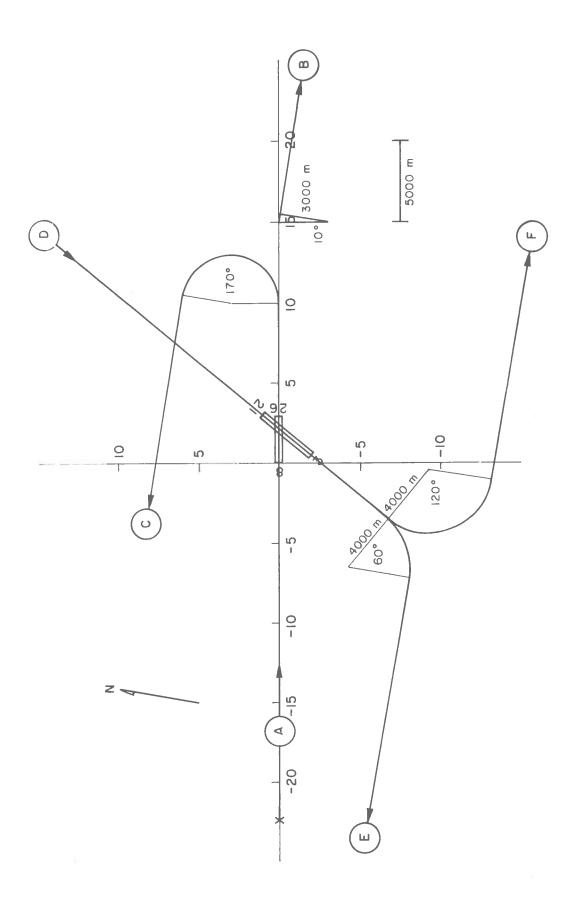
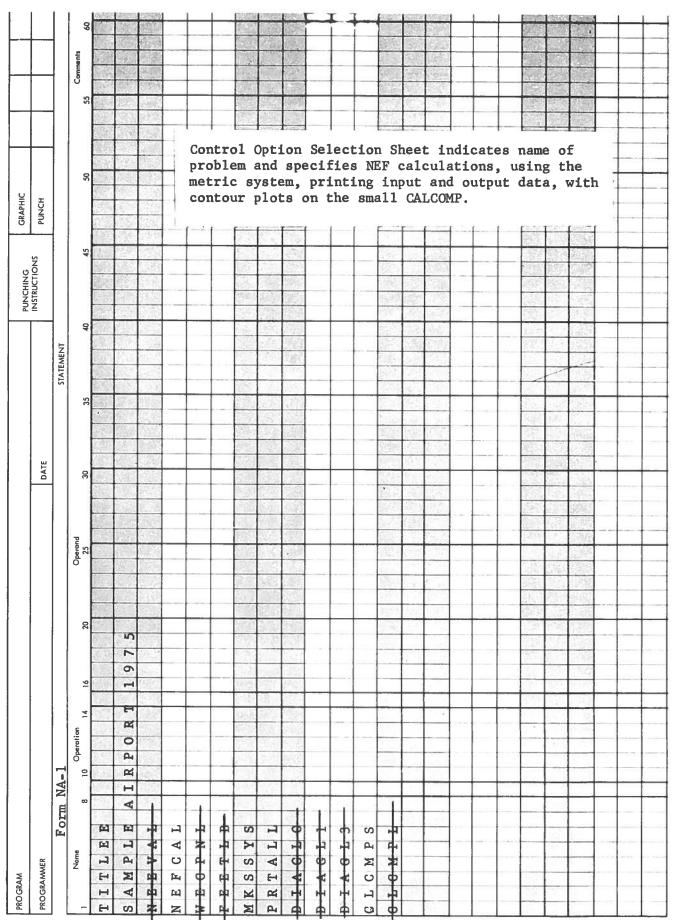
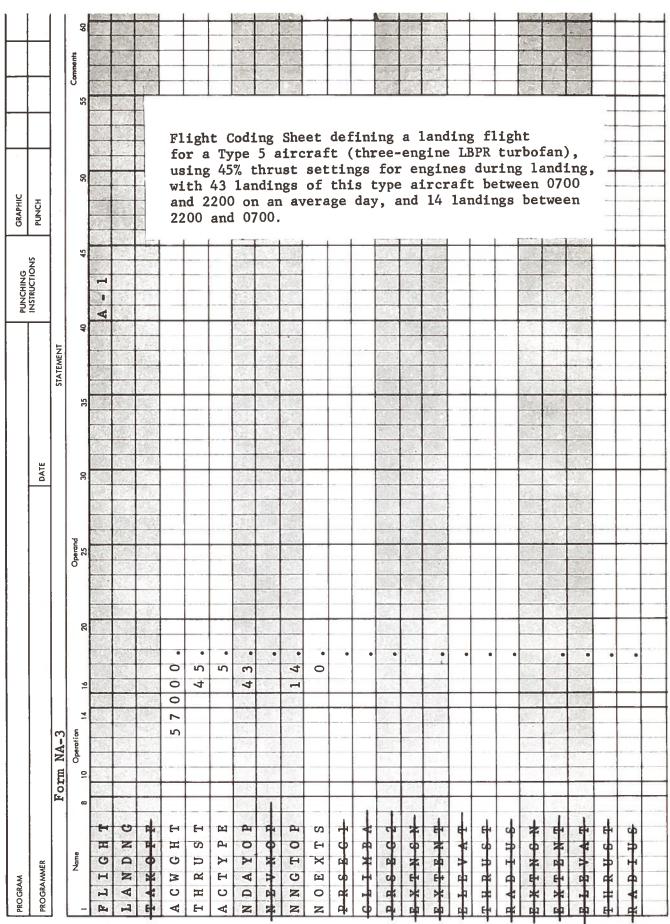


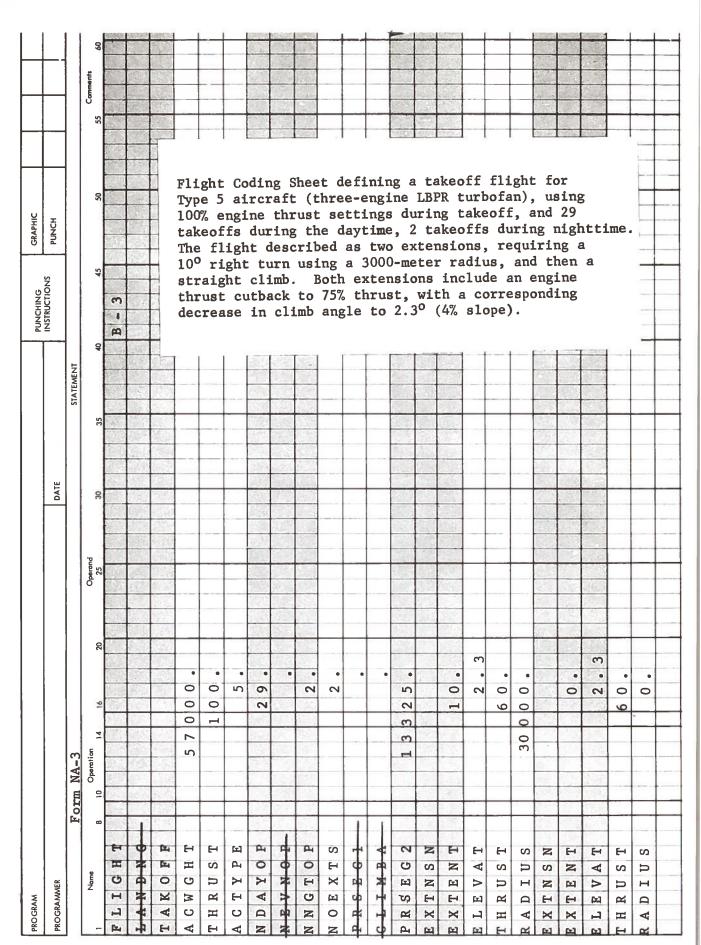
Figure B-1. Sample Airport

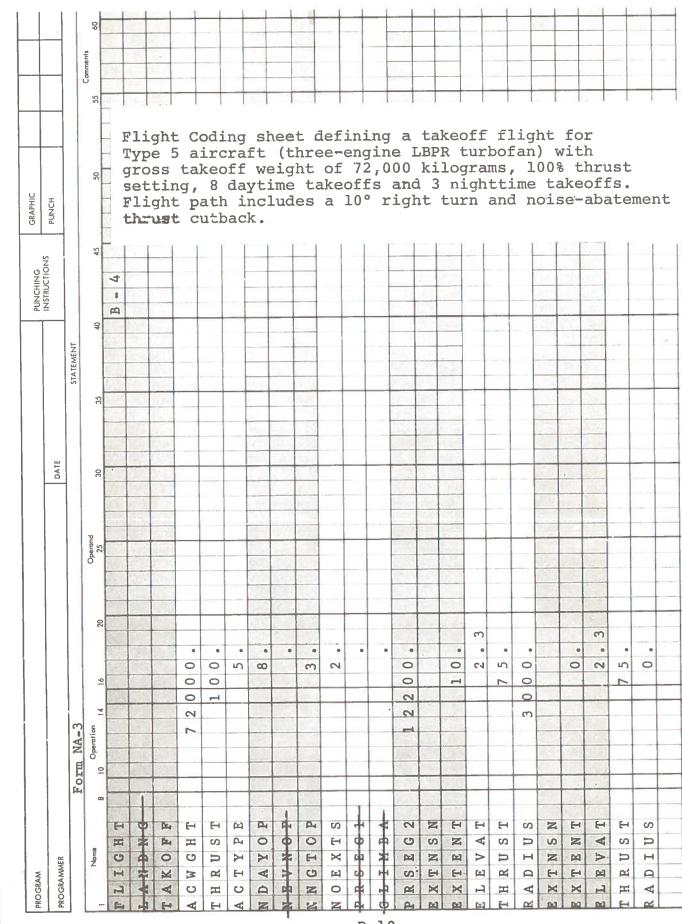


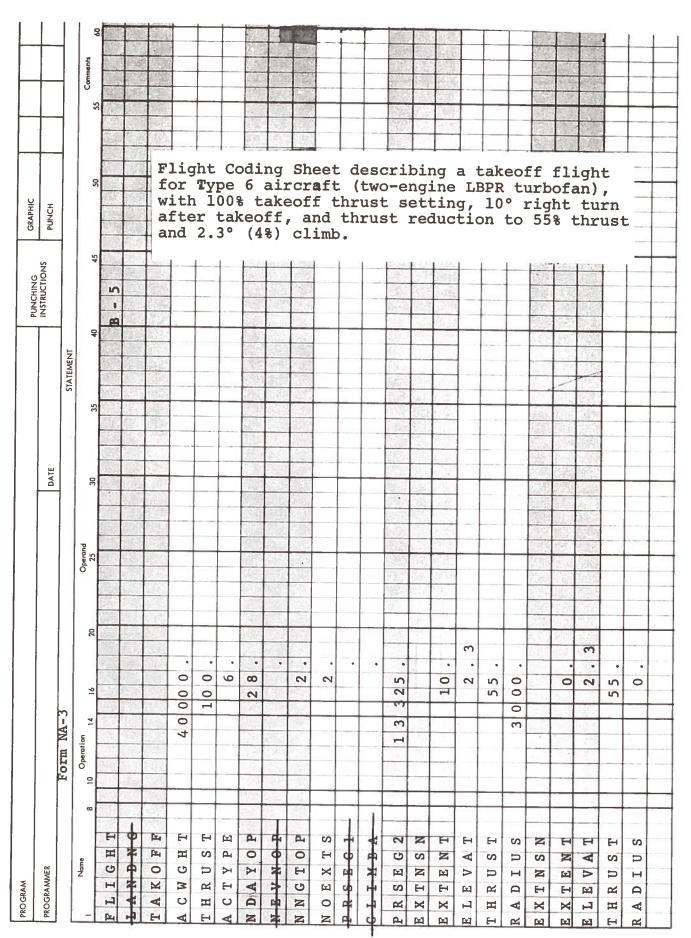
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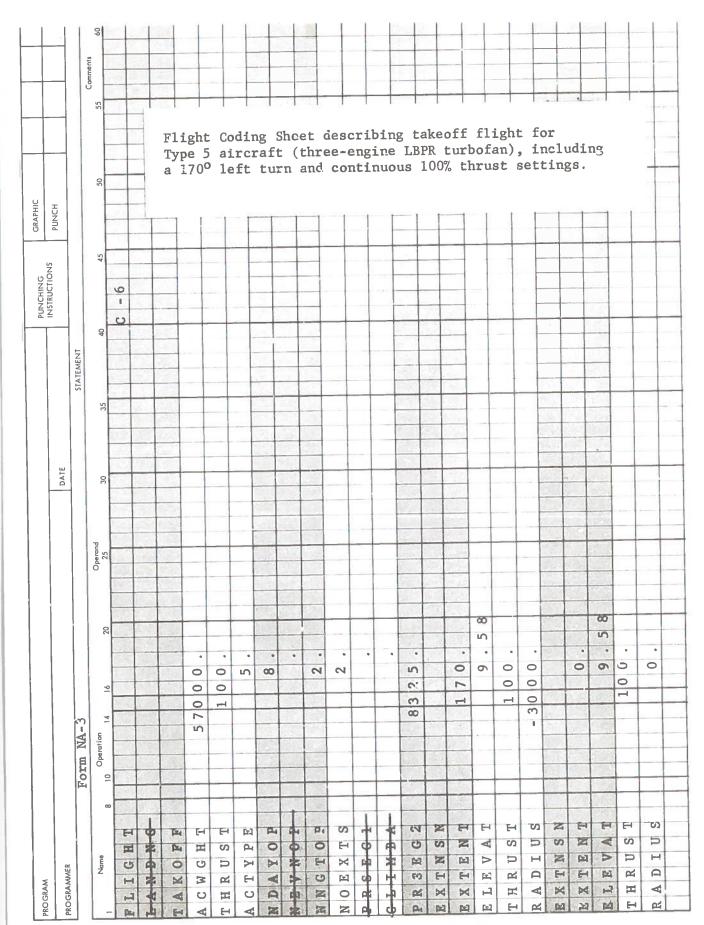


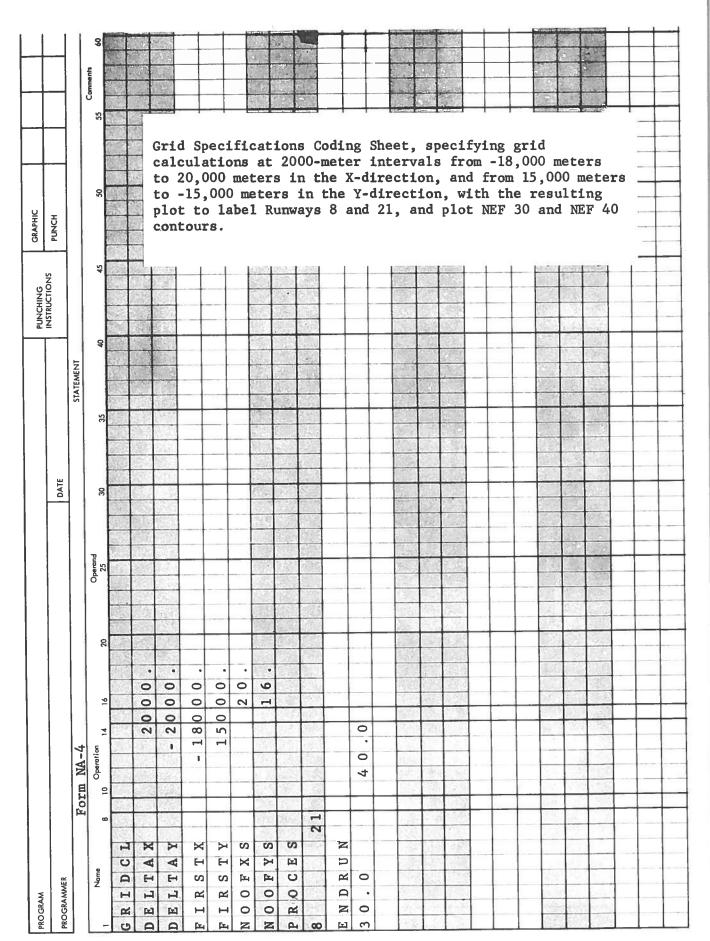
Flight Coding Sheet defining a landing flight for Type 6 aircraft (two-engine LBPR turbofan), with 45% engine thrust settings, including 38 daytime landings (between 0700 and 2200) and 9 nighttime landings (between 2200 and 0700). Note that landings for the specified DC-9 and BAC-111 aircraft types have been considered together, since both are Type 6 (two-engine LBPR turbofan) aircraft.	PROGRAM					PUNCHING	GRAPHIC	_
Flight Coding Sheet defining a landing flight for Type 6 aircraft (two-engine LBPR turbofan), with 45% engine thrust settings, including 38 daytime landings (between 0700 and 2200) and 9 nighttime landings (between 2200 and 0700). Note that landings for the specified DC-9 and BAC-111 aircraft types have been considered together, since both are Type 6 (two-engine LBPR turbofan) aircraft.	PROGRAMMER			DATE		INSTRUCTIONS	PUNCH	-
Flight Coding Sheet defining a landing flight for Type 6 aircraft (two-engine LBPR turbofan), with 45% engine thrust settings, including 38 daytime landings (between 0700 and 2200) and 9 nighttime landings (between 2200 and 0700). Note that landings for the specified DC-9 and BAC-111 aircraft types have been considered together, since both are Type 6 (two-engine LBPR turbofan) aircraft.	Form	NA-3			STATEMENT			
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Listing of control cards necessary to run Noise Exposure Model MOD 4 from tape.

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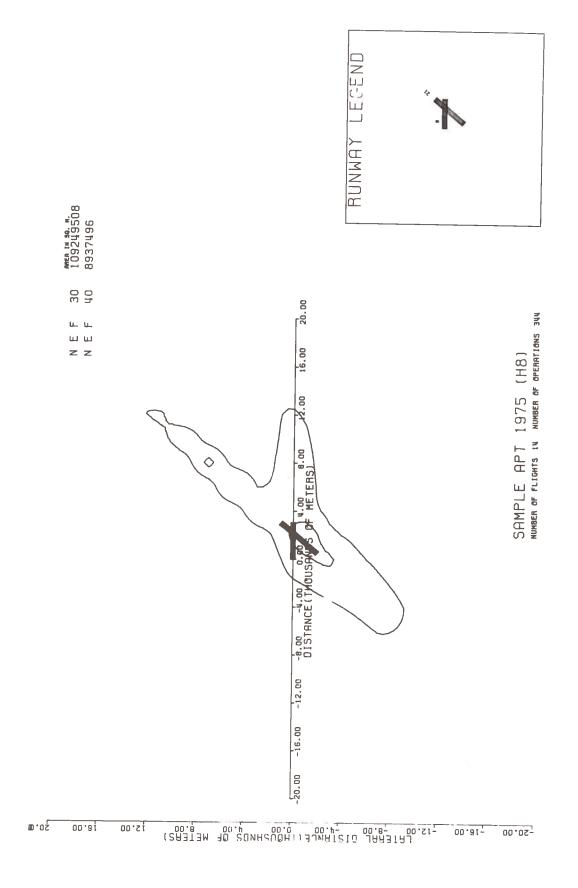
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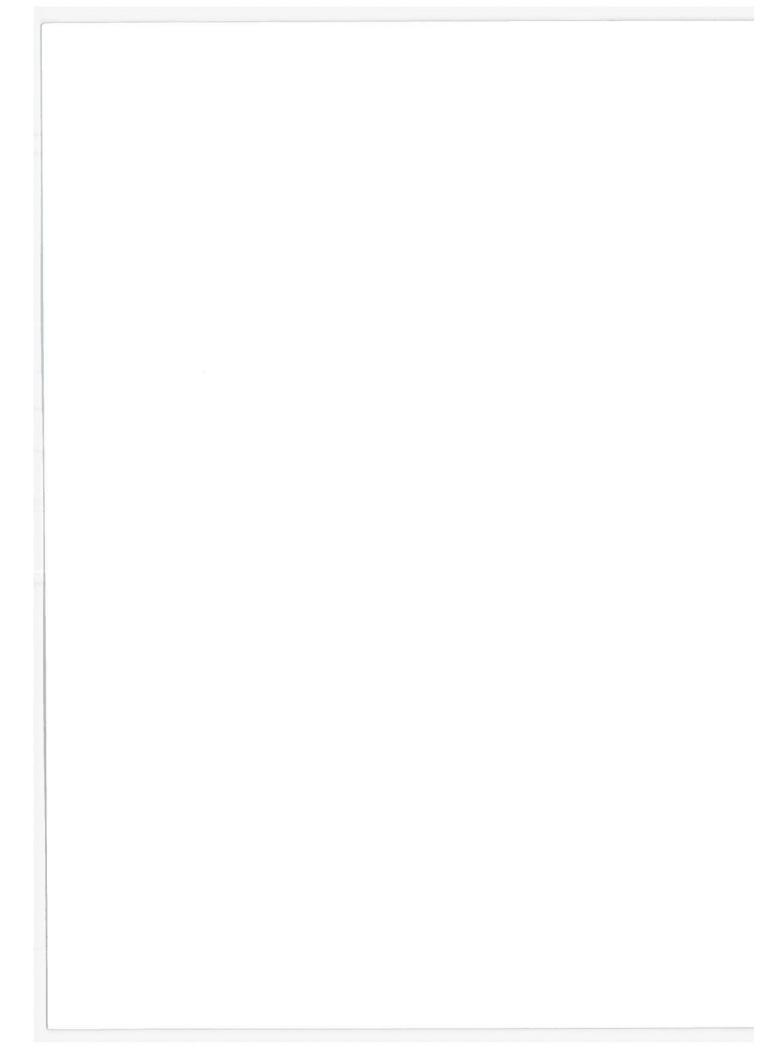
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Computer listing of runways and flights included in calculations, for verification purposes.
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	10000		14.5	17.7	26.1	37.0	24.3	21.2	24.1	30.9	30.8	24.0	19.8	19.1	10.0	19.6	20.2	20.3
	8000.		13.4	15.4	18.3	24.8	45.4	26.2	24.8	32.2	32.2	24.4	20.4	19.7	19.7	20°5	21.0	21.1
	•0009		12.5	14.5	16.9	19.6	23.9	43.9	50.9	33.5	33.5	24.3	21.8	20.0	20.8	21.6	22.0	21.7
	4000		12.2	14°C	16.1	18.4	25.1	22.8	30.6	36.6	34.7	27.3	25.4	23.3	22.2	22.5	22.9	22.2
	2002		12.0	13.8	15.8	17.8	19.0	19.6	23.2	35.3	45.8	33.1	29.0	25.3	23.4	23.5	23.7	22.6
	C)		11.9	13.7	15.6	17.3	18.0	16.1	10.1	30.0	39.1	41.3	32.9	28.0	25.3	24.7	24.6	23.0
	2002		11.9	13.6	15.4	16.8	17.2	14.5	19.5	27.5	30.4	34.2	36.0	31.8	28°C	26.5	25.3	23.2
	-4600+-		11.9	13.5	15.1	16.2	16.3	16.8	18.9	25.8	27.2	28.2	31.3	32.7	30.3	27.6	25.1	22.8
	.0505		11.9	13.3	14.7	15.6	15.5	16.8	18.2	24.4	25.3	25.1	27.2	30.1	29.4	26.6	24.2	72.1
	3500.		11.7	13.1	14.4	15°C	15.7	16.4	18.4	23.3	24.1	23 9	26.2	28.6	27.7	25.2	23.1	21.2
	100001		11.6	12.9	14.0	15°C	15.3	17.7	19.0	22.9	23.7	23.6	25.9	27.4	26.3	24.2	22°C	20.4
	2330		11.4	12.7	15.9	16.6	17.0	17.7	19.0	22.6 20.2	23.4	23.4	25.4	26.4	25.1	23.0	21.2 17.0	19,7
* *	4050°-12		14.0	15.0	15.9	16.4	16.9	17.6	18.9	22.3	23.2	23.2	25.0	25.5	24.1	22.2 16.8	20.5	19.0 18.0
A GRID***	01633314 5. 16380. 18		14.0	15.0	15.7	16.3 16.7	16.8	17.5	19.8	21.9	23.5	23.1	24.5	24.6	23.3	21.5	19.9	18.5
VALUES IN	9000		14.0	14.9	15.6	16.1	16.7	17.5	18.7	21.6	22.7	23.0	24°0 19°8	23.9	22.5	20.9	19.3	13.2
***NEF VA	x VALS -1	Y VALS	15000.	13000.	11000.	* 00 0e	7007.	5000.	3000	1000.	-1001-	-3005-	-5000-	-7000-	-0006-	-11000.	-13000.	-15000.





APPENDIX C

(Bound separately)

Computer listing for Noise Exposure Model MOD 4.

Appendix C to the basic report entitled "The Noise Exposure Model MOD 4" contains the computer program listing for the Noise Exposure Model MOD 4. This listing is bound separately from the basic report for convenience. It is available as report number DOT-TSC-OST-71-16.