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PREDICTION OF V/STOL NOISE FOR
APPLICATION TO COMMUNITY NOISE EXPOSURE

Charles L. Munch



MAY 1973
FINAL REPORT

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16. Abstract A computer program to predict the Effective Perceived Noise Level (EPNL), the tone corrected Perceived Noise Level (PNLT), and the A-Weighted Sound Level (dBA) radiated by a V/STOL vehicle as it flies along a prescribed takeoff, landing, or cruise flight path is described in detail and a complete users guide for the program is presented. The procedures used to predict the noise radiated by helicopter rotors, propellers, turboshaft engines, lift and cruise fans, and jets are described in detail. Helicopter rotor noise and jet noise are theoretically predicted with some empirical modifications while propeller, fan, and turboshaft engine noise is calculated with primarily empirical procedures. The program is designed to be easy to use; thus it should be useful in V/STOL-port planning studies. There are major limitations of current technology on the use of the program; the noise of VTOL vehicles characterized by impulsive type noise signatures should not be predicted and, because there are not yet adequate methods for predicting the noise from deflected jets, augmentor wings, blown flaps, and the like, noise of augmented lift STOL aircraft cannot yet be predicted. There is, in fact, some evidence to indicate that the EPNL measure does not adequately predict the annoyance of impulsive noise signatures and it is hoped that improved measures to account for the annoyance of impulsive noise will be developed in the near future.			
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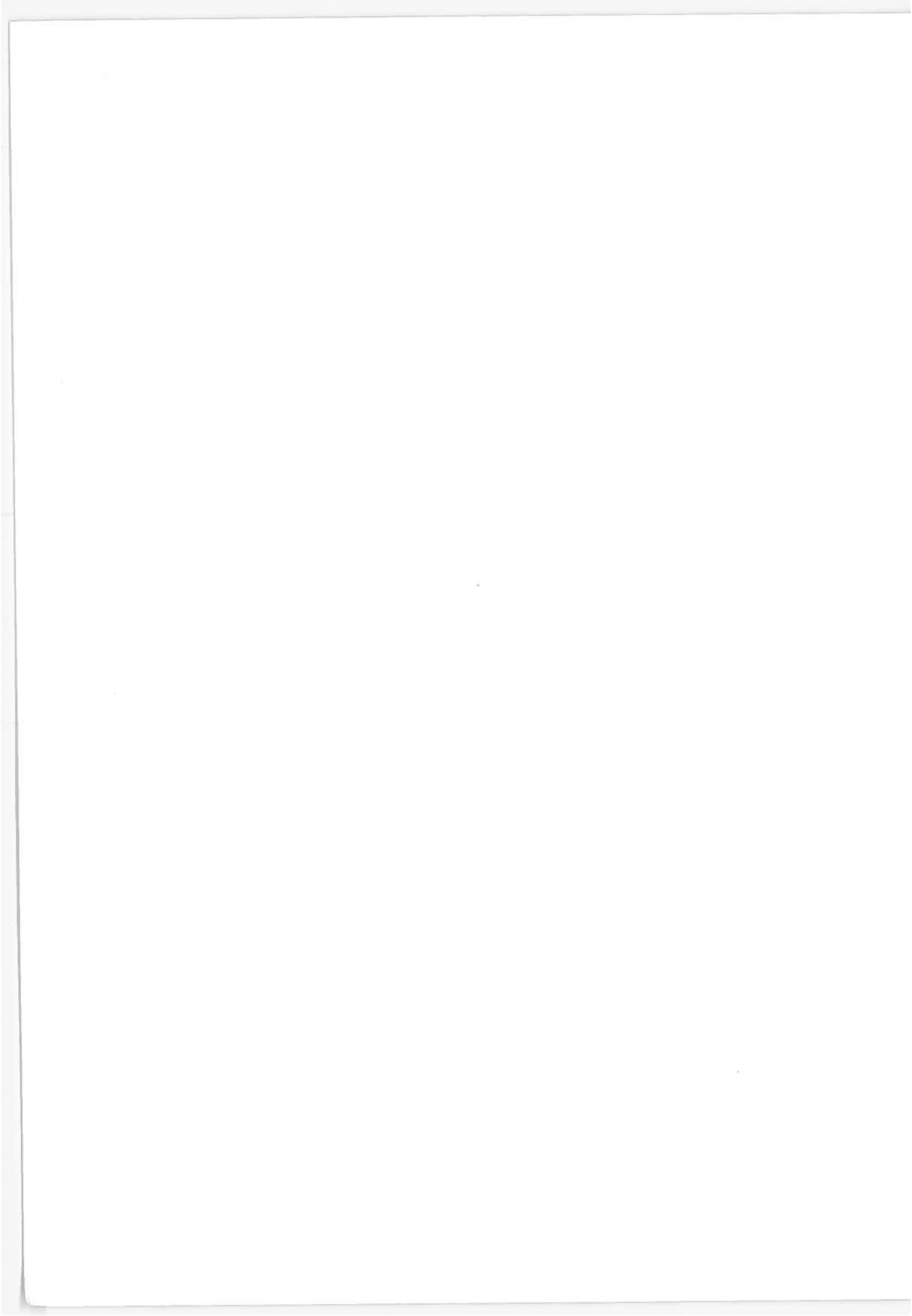


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LIST OF SYMBOLS

A_B	-	Total blade area
A_i	-	Total fan inlet area
A_m	-	Amplitude of m-th sound harmonic
B	-	Number of blades
BPR	-	Bypass ratio
C	-	Radial force on rotor blade
C_m	-	Complex magnitude of m-th sound harmonic
D	-	Drag force on rotor blade; Duration correction to calculate EPNL
D_h	-	Fan hub diameter
D_p	-	Propeller diameter
D_{t_f}	-	Fan tip diameter
DF	-	Fan diffusion factor
DI	-	Directivity index
DL	-	Duct length
EPNL	-	Effective Perceived Noise Level
G	-	Argument of Bessel Function ($= mMy/r_1$)
$J_n(k)$	-	Bessel Function of the first kind, order n, argument k
K	-	Flight segment number; Constant in Equation (46)
L	-	Number of blade airloading harmonics
M	-	Mach number
M_{ax}	-	Fan axial tip Mach number
M_f	-	Flight Mach number
M_o	-	Component of flight Mach number in direction of observer
M_{rel}	-	Fan relative tip Mach number
M_t	-	Tip Mach number
N_e	-	Number of engines

LIST OF SYMBOLS (Cont'd)

N_f	-	Number of fans
N_p	-	Number of propellers
N_{max}	-	Largest Noy value of a given 1/3-octave band spectrum
N_{oy_i}	-	Noy value of the SPL in the i-th third octave band
P_p	-	Propeller power input
PNL	-	Perceived Noise Level
PNLT	-	Perceived Noise Level, Tone corrected
PR	-	Pressure Ratio
R	-	Radius
R_K	-	Radius of turn of helical flight segment K
R_s	-	Fan blade suction surface radius of curvature
R_t	-	Tip radius
T	-	Thrust force on blade
V_{f_K}	-	Flight velocity along flight segment K
V_H	-	Propeller helical tip speed
V_t	-	Tip speed
$V_{0.7}$	-	Speed at 0.7 blade radial station
X'Y'Z'	-	Stationary coordinate system with origin at start of takeoff roll
$X'_O Y'_O Z'_O$	-	Starting point coordinates of a flight segment
$X'_{ob} Y'_{ob}$	-	Coordinates of primary observer location
1/3 OL_j	-	SPL of j-th 1/3-octave band
a_{f_j}	-	Attenuation of sound at frequency f due to filter shape of the j-th 1/3-octave band
a_m	-	Real part of complex sound pressure of m-th sound harmonic
a'_{mol}	-	Molecular atmospheric sound absorption
a_o	-	Speed of sound

LIST OF SYMBOLS (Cont'd)

$a_{\lambda C}$	-	λ -th radial loading harmonic amplitude
$a_{\lambda D}$	-	λ -th drag loading harmonic amplitude
$a_{\lambda T}$	-	λ -th thrust loading harmonic amplitude
$a_{\lambda \psi}$	-	Sine component of rotor blade airloading harmonic λ in the X,Y,Z coordinate system
$a_{\lambda \gamma}$	-	Sine component of rotor blade airloading harmonic λ in the x,y coordinate system
b_m	-	Imaginary part of sound pressure of m-th sound harmonic
$b_{\lambda \psi}$	-	Cosine component of rotor blade airloading harmonic λ in the X,Y,Z coordinate system
$b_{\lambda \gamma}$	-	Cosine component of rotor blade airloading harmonic λ in the x,y coordinate system
c	-	Blade chord
dB(A)	-	A-weighted sound pressure level
f	-	Frequency
f_{cj}	-	Center frequency of j-th 1/3-octave band
f_{lj}	-	Lower cutoff frequency of j-th 1/3-octave band
f_o	-	Fundamental rotational harmonic frequency
f_s	-	Peak rotor broadband noise frequency
f_{uj}	-	Upper cutoff frequency of the j-th 1/3-octave band
h_l	-	Apparent blade thickness due to blade angle of attack
i_d	-	Rotor disk incidence angle
l_c	-	Rotor blade airloading correlation coefficient
m	-	Sound harmonic number
p	-	Sound pressure
t	-	Time
t_c	-	Blade thickness at $\frac{1}{4}$ -chord point
t_{inc}	-	Time increment

LIST OF SYMBOLS (Cont'd)

$t_{\max K}$	-	Total travel time along flight segment K
t_0	-	Initial time
Δt	-	Time increment between successive PNLT calculations
x, y	-	Helicopter rotor coordinate system (defined in Figure 4.)
α_1	-	Rotor blade angle of attack
α_K	-	Angle of climb or descent along flight segment K
β	-	Rotor blade coning angle
β^*	-	Fan air inflow angle
γ	-	Defined by Figure 4
γ_a	-	Azimuthal location of observer relative to vehicle
η	-	Radial blade loading station ($0 \leq \eta \leq 1$)
θ_a	-	Relative camber angle at leading edge of fan blade
$\theta_{\max K}$	-	Direction of flight (in the X'Y' plane) at end of segment K
θ_1	-	Angle measured from Z axis to r_1
λ	-	Loading harmonic number
μ	-	Mach angle
ξ_c	-	Critical cutoff ratio for combination tones
ξ_K	-	Cutoff ratio of the K-th combination tone
ξ_{RF}	-	Fan rotor field cutoff ratio
σ_\emptyset	-	Standard deviation of fan blade tip metal angle
\emptyset	-	Defined by Figure 4 and Equation (30)
\emptyset_{CK}	-	Angle through which aircraft turns on helical segment K in time t_{inc}
$\emptyset_{\max K}$	-	Total angle through which aircraft turns on helical flight segment K (+ for left turn, - for right turn)
ψ	-	Defined by Figure 4
ψ_K	-	Defined by Equation (25)
Ω	-	Rotational speed

PREFACE

This report covers work sponsored by the Department of Transportation, Office of the Assistant Secretary for Systems Development and Technology, Office of Noise Abatement, TSC-50. The program was technically monitored by the Transportation Systems Center of the Department of Transportation located in Cambridge, Massachusetts.

The objective of the work was to develop a V/STOL aircraft noise prediction program and to apply the developed program to computers at the Transportation Systems Center.

INTRODUCTION

The many studies conducted in recent years into the mechanisms of noise generation by V/STOL aircraft propulsors such as propellers, fans, rotors, and engines (eg. - References 1 to 19) have resulted in reasonably accurate methods with which to predict both the spectrum shape and level of the component noise. Actual aircraft, however, are made up of several noise producing components; thus, to assess the acoustic impact of a given vehicle it becomes necessary to combine the noise from several components to produce the vehicle noise. With the advent of city-center V/STOL operations the vehicle's acoustic impact can exert considerable influence over all aspects of the system from site location to aircraft design.

Existing methods for evaluating the acoustic impact of flight operations on nearby communities (eg.- Noise Exposure Forecast (NEF), Weighted Equivalent Perceived Noise Level (WECPNL), etc.) provide for current, operational CTOL aircraft, but generally do not account for STOL or VTOL operations; hence, their use is limited to evaluation of existing or planned airports where there is little V/STOL traffic. As V/STOL operations increase at major airports and as city-center operations become a reality, a method must be available whereby the total impact of all vehicles can be evaluated. The objectives of the study presented in this report are to develop a computer program to calculate the noise generated by V/STOL vehicles flying prescribed flight paths and compute the Effective Perceived Noise Level at a ground based observer for input to existing NEF programs and to perform a limited correlation study with measured data.

The vehicles considered in the program are those that are made up of one or more of the following propulsion components: turboshaft engines, helicopter main and tail rotors, propellers, lift fans, cruise fans, fan engines, and to a limited degree, lift jets. Augmented lift devices such as externally or internally blown flaps are not yet included. The flight path followed by the aircraft is composed of both straight line and helical segments so that the path can be a realistic representation of the actual flight path. The methods used to calculate the component noise levels are discussed in detail in the next section. In following sections the structure and usage of the computer program is outlined and illustrated using sample cases. Several comparisons of measured and calculated V/STOL vehicle noise are presented to demonstrate the accuracy of the program.

COMPONENT PREDICTION METHODS

The components that are included in the prediction program are (as mentioned above) main and tail rotors, propellers, fans, turboshaft engines, and jets. No augmented lift devices such as externally or internally blown flaps or augmenting wing are included yet. Because of the modular program concept used, the addition of other sources can be easily accomplished when accurate prediction techniques are developed. By the same token existing component prediction methods can be modified or replaced if newer, more accurate methods become available.

None of the noise prediction methods in the program include the possible shielding effects of structure such as wings, fuselage, etc. Admittedly, shielding can have an effect on the propagated noise, principally changing the observed directivity, however, no comprehensive methods exist for accurately predicting shielding effects. The program thus yields levels higher than those which would be realized for components where shielding may be important (fans, propellers, engines, and jets). Also, no account is made of possible phasing effects due to source/source separation. It is felt that in the far-field where propagation distances are long compared with separation distances the source separation phase effect will be negligible.

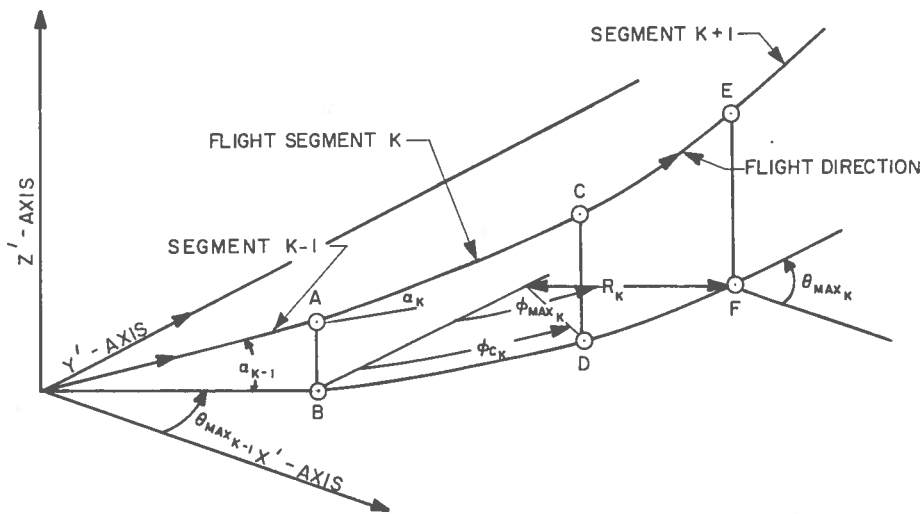
The following sections describe the methods used to predict component noise levels, how they are programmed and the nature of their relationship to the total computer program.

Flight Path Definition

All of the component noise prediction methods to be described below require knowledge of the aircraft's location with respect to an observer. Since the calculation of Effective Perceived Noise Level requires an integration of the vehicle's noise time history the noise for many aircraft locations along the flight path will be required. A subroutine which calculates these locations of the aircraft relative to the observer at successive points (or time increments) along the flight path has been developed.

The flight path is assumed to be made up of a series of straight line and helical trajectories (segments), an example of which is shown in Figure 1. In this example segment K-1 is a straight line segment directed at an angle of $\theta_{\max K-1}$ from the X' axis and the aircraft is climbing at the angle α_{K-1} . Segment K is a helical segment with a turning radius of R_K and the aircraft turns through $\theta_{\max K}$ degrees (+ for left turn, - for right turn) before flying off on segment K + 1. The aircraft is climbing at an angle of α_K degrees and flies along the K-th segment at a speed of V_{fK} .

If we now assume that the aircraft starts flying on segment K (Point A of Figure 1) at time $t = t_0$, then at a time $t = t_0 + t_{inc}$ later it has turned through an angle ϕ_{CK} (from A to C) along the flight path, a distance given by



POINT	COORDINATES
A	$X'_{O_{K-1}}, Y'_{O_{K-1}}, Z'_{O_{K-1}}$
B	$X'_{O_{K-1}}, Y'_{O_{K-1}}, 0$
C	$X'_{C_K}, Y'_{C_K}, Z_{C_K}$
D	$X'_{C_K}, Y'_{C_K}, 0$
E	$X'_{MAX_K}, Y'_{MAX_K}, Z'_{MAX_K}$
F	$X'_{MAX_K}, Y'_{MAX_K}, 0$

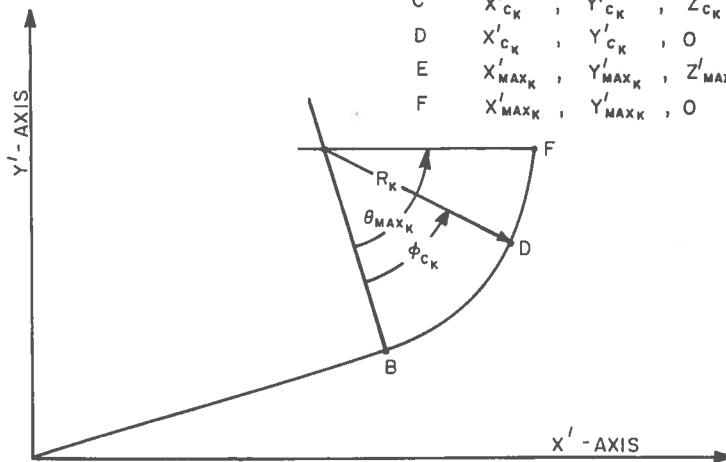


FIGURE 1. Coordinate System Arrangement for Calculating Field Point Locations Along A Flight Path - Helical Segments.

$$\overline{AC} = V_{f_K} t_{inc} \quad (1)$$

and a distance BD along the ground given by

$$\overline{BD} = R_K \phi_{c_K} \quad (2)$$

Since the aircraft is climbing at α_K degrees, \overline{BD} is also given as

$$\overline{BD} = \overline{AC} \cos(\alpha_K) \quad (3)$$

Combining Equations (1) and (3) yields:

$$\overline{BD} = V_{f_K} t_{inc} \cos \alpha_K \quad (4)$$

thus, from Equations (2) and (4):

$$R_K \phi_{c_K} = V_{f_K} t_{inc} \cos \alpha_K \quad (5)$$

the angle ϕ_{c_K} is then determined to be

$$\phi_{c_K} = \frac{1}{R_K} V_{f_K} t_{inc} \cos \alpha_K \quad (6)$$

Now the coordinates of the point C can be determined:

$$X'_{c_K} = X'_O + 2R_K \sin(\frac{1}{2}|\phi_{c_K}|) \cos(\theta_{\max_{K-1}} + \frac{1}{2}\phi_{c_K}) \quad (7)$$

$$Y'_{c_K} = Y'_O + 2R_K \sin(\frac{1}{2}|\phi_{c_K}|) \sin(\theta_{\max_{K-1}} + \frac{1}{2}\phi_{c_K}) \quad (8)$$

$$Z'_{c_K} = Z'_O + R_K |\phi_{c_K}| \tan \alpha_K \quad (9)$$

The coordinates at the end of the segment (point E), the angle ϕ_{\max_K} at which the aircraft enters segment K + 1, and the maximum travel time along segment K are given as:

$$X'_{\max_K} = X'_O + 2R_K \sin(\frac{1}{2}|\phi_{\max_K}|) \cos(\theta_{\max_{K-1}} + \frac{1}{2}\phi_{\max_K}) \quad (10)$$

$$Y'_{\max_K} = Y'_O + 2R_K \sin(\frac{1}{2}|\phi_{\max_K}|) \sin(\theta_{\max_{K-1}} + \frac{1}{2}\phi_{\max_K}) \quad (11)$$

$$Z'_{\max_K} = Z'_O + R_K |\phi_{\max_K}| \tan \alpha_K \quad (12)$$

$$\theta_{\max_K} = \theta_{\max_{K-1}} + \phi_{\max_K} \quad (13)$$

$$t_{\max_K} = R_K |\phi_{\max_K}| / (V_{f_K} \cos \alpha_K) \quad (14)$$

Figure 2 shows the similar situation when segment K is a straight line segment. Again, the aircraft starts at point A at time $t = t_0$ and travels at V_{fK} ft/sec, reaching point C, at time $t = t_0 + t_{inc}$. The coordinates of point C are then calculated:

$$X'_{cK} = X'_0 + (V_{fK} t_{inc} \cos \alpha_K) \cos \theta_{maxK} \quad (15)$$

$$Y'_{cK} = Y'_0 + (V_{fK} t_{inc} \cos \alpha_K) \sin \theta_{maxK} \quad (16)$$

$$Z'_{cK} = Z'_0 + V_{fK} t_{inc} \sin \alpha_K \quad (17)$$

The segment end point coordinates, the exit angle and maximum time of travel along the segment are given below:

$$t_{maxK} = \left| \frac{X'_{maxK} - X'_{maxK-1}}{V_{fK} \cos \theta_{maxK} \cos \alpha_K} \right| \quad (18)$$

however, when $X'_{maxK} = X'_{maxK-1}$ (ie. $\theta_{maxK} = \pm 90^\circ, \pm 270^\circ$) t_{max} is given as:

$$t_{maxK} = \left| \frac{Y'_{maxK} - Y'_{maxK-1}}{V_{fK} \cos \alpha_K \sin \theta_{maxK}} \right| \quad (19)$$

$$\theta_{maxK} = \theta_{maxK-1} \quad (20)$$

$$X'_{maxK} = X'_0 + V_{fK} t_{maxK} \cos \alpha_K \cos \theta_{maxK} \quad (21)$$

$$Y'_{maxK} = Y'_0 + V_{fK} t_{maxK} \cos \alpha_K \sin \theta_{maxK} \quad (22)$$

$$Z'_{maxK} = V_{fK} t_{maxK} \sin \alpha_K + Z'_0 \quad (23)$$

Because the component noise prediction procedures discussed below require X, Y, Z coordinates relative to the aircraft rather than relative to a fixed spacial point, the X', Y', Z' coordinates must be converted. Figure 3 shows the relationship between the two systems; the transformation is given below:

$$X_{obK} = (X'_{ob} - X'_{cK}) \cos \psi_K + (Y'_{ob} - Y'_{cK}) \sin \psi_K \quad (24)$$

$$Y_{obK} = -(Y'_{ob} - Y'_{cK}) \cos \psi_K + (X'_{ob} - X'_{cK}) \sin \psi_K$$

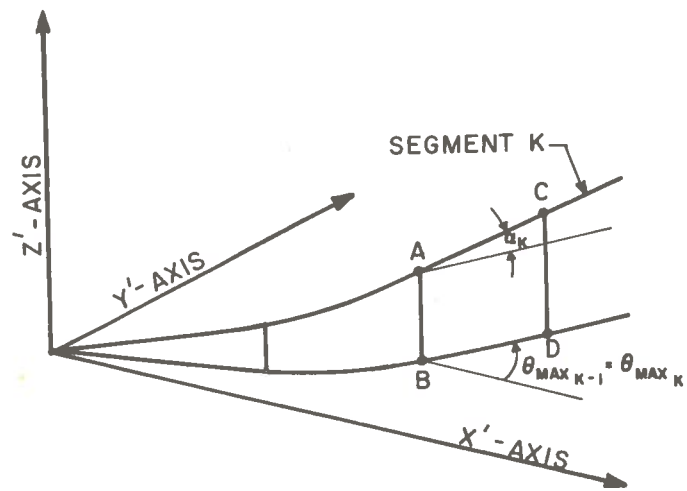
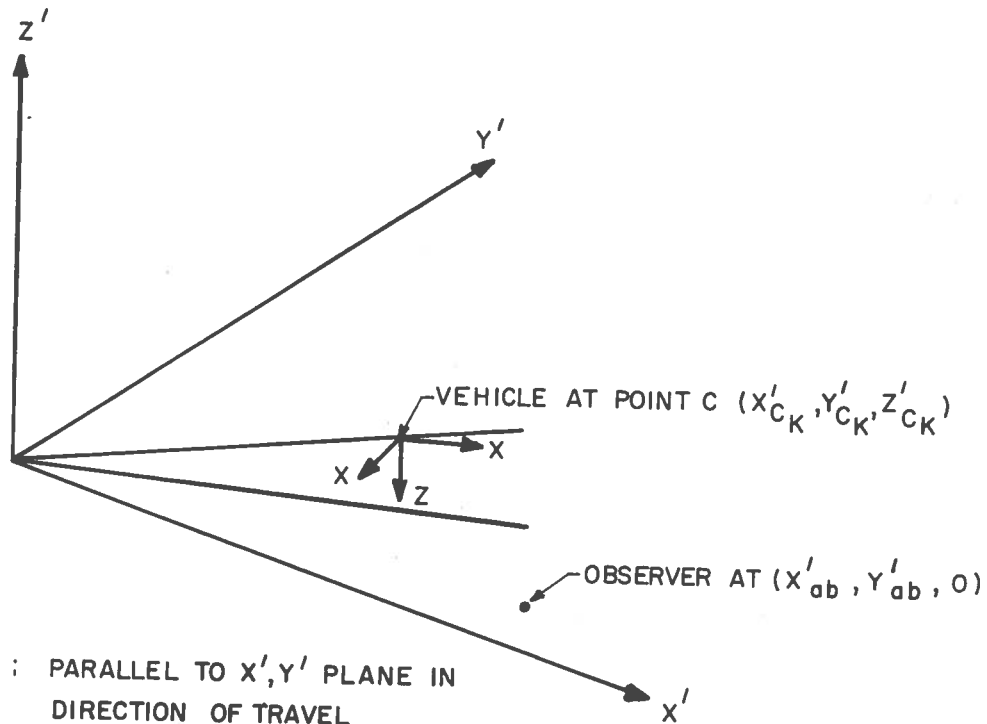


FIGURE 2. Coordinate System Arrangement For Calculating Field Point Locations Along A Flight Path - Straight Line Segments.



- X AXIS : PARALLEL TO X', Y' PLANE IN DIRECTION OF TRAVEL
- Z AXIS : PARALLEL TO Z' AXIS AND POSITIVE DOWNWARD
- Y AXIS : PARALLEL TO X', Y' PLANE AND PERPENDICULAR TO DIRECTION OF TRAVEL

FIGURE 3. Relationship Between Fixed (X', Y', Z') Coordinate System and Coordinate System Originating at the Vehicle (X, Y, Z) .

$$\begin{aligned}
 & Z_{ob_K} = Z'_{c_K} \\
 \text{where} \quad \psi_K = & \begin{cases} \theta_{\max_K} & \text{for straight line segments} \\ \theta_{\max_K} + \phi_{c_K} & \text{for helical segments} \end{cases} \quad (25)
 \end{aligned}$$

All of the equations developed so far assumed that the aircraft was conducting a takeoff operation which started at the point $X' = Y' = Z' = 0$. In the case of a landing terminating at the same point all of the equations except 24 and 25 remain the same and the calculation is carried out as if the aircraft were flying backwards up the flight path. Since at any point the aircraft is simply turned around 180° in the landing case, $(\psi_K + \pi)$ is substituted for ψ_K in Equation (25) and the coordinate transformation equations, Equations (24) then remain the same.

Helicopter Rotor Noise

The primary requirement for all of the component noise prediction procedures is that they be able to provide reasonably accurate results with a minimum of detailed helicopter performance and airloading data input in minimum computer time. In order to meet these requirements it was decided to use the closed-form solution presented by Lawson and Ollerhead in Reference 10 for rotor rotational noise. This solution, which will be described in greater detail, allows the far-field rotational noise from a rotor to be calculated from an assumed airloading spectrum quite rapidly. Other rotor noise solutions developed for example, by Schlegel, et al. in Reference 1, while accurate are not readily applicable to the present problem since they require detailed knowledge of the aircraft performance parameters and actual blade airloading. They are open-form solutions requiring radial and azimuthal iterations and, as such, are slower than the closed form solution of Reference 10.

The subprogram, as designed, is capable of calculating the total noise generated by a helicopter main and tail rotor, or any two rotors, during both hover and cruise. In the case where the two rotors are very close together, such as for a coaxial design, where the assumption of randomly phased loading is not valid the program should be used with care.

Rotational Noise

The method used to calculate the rotational noise components is the same for both the main and tail rotors, thus in the following paragraphs unless a distinction is made between the two, the term 'rotor' will be taken to mean any rotor.

The basic computer program used to predict the rotational harmonic noise levels for rotors is essentially that described in Section 5.1 of Reference 10. The program computes the closed-form solution to Equation (37) of

Reference 10 which describes the far sound field radiation of a rigid-rotor system whose only blade motion is steady coning. It was shown in Reference 10 that while these limitations may introduce some error when applied to the real helicopter case, the accuracy is sufficient for studying the general helicopter noise problem. Equation (37)10 is reproduced below as Equation (27):

$$C_m = a_m + ib_m = \sum_{\lambda=0}^{\infty} a_{m\lambda} + ib_{m\lambda} \quad (26)$$

where $a_{m\lambda}$ and $b_{m\lambda}$ are the following for $(m + \lambda)$ odd:

$$\begin{aligned} a_{m\lambda} &= \frac{m\Omega}{4\pi a_o r_1} \left\{ \frac{x a_{\lambda T}}{r_1} \left[J_{m+\lambda}(G) + (-1)^\lambda J_{m-\lambda}(G) \right] - \frac{a_{\lambda D}}{m M_t} \left[(m+\lambda) J_{m+\lambda}(G) + (-1)^\lambda (m-\lambda) J_{m-\lambda}(G) \right] \right. \\ &\quad \left. + \frac{y b_{\lambda c}}{2r_1} \left[J_{m+\lambda+1}(G) - J_{m+\lambda-1}(G) - (-1)^\lambda (J_{m-\lambda+1}(G) - J_{m-\lambda-1}(G)) \right] \right\} (-1)^{\frac{1}{2}(m+\lambda-1)} \\ b_{m\lambda} &= \frac{m\Omega}{4\pi a_o r_1} \left\{ \frac{-x b_{\lambda T}}{r_1} \left[-(-1)^\lambda J_{m-\lambda}(G) + J_{m+\lambda}(G) \right] + \frac{b_{\lambda D}}{m M_t} \left[(m+\lambda) J_{m+\lambda}(G) - (-1)^\lambda (m-\lambda) J_{m-\lambda}(G) \right] \right. \\ &\quad \left. + \frac{y a_{\lambda c}}{2r_1} \left[J_{m+\lambda+1}(G) - J_{m+\lambda-1}(G) + (-1)^\lambda (J_{m-\lambda+1}(G) - J_{m-\lambda-1}(G)) \right] \right\} (-1)^{\frac{1}{2}(m+\lambda-1)} \end{aligned} \quad (27a)$$

if $(m+\lambda)$ is even, then $a_{m\lambda}$ and $b_{m\lambda}$ are the following:

$$\begin{aligned} a_{m\lambda} &= \frac{m\Omega}{4\pi a_o r_1} \left\{ \frac{x b_{\lambda T}}{r_1} \left[J_{m+\lambda}(G) - (-1)^\lambda J_{m-\lambda}(G) \right] - \frac{b_{\lambda D}}{m M_t} \left[(m+\lambda) J_{m+\lambda}(G) - (-1)^\lambda (m-\lambda) J_{m-\lambda}(G) \right] \right. \\ &\quad \left. - \frac{y a_{\lambda c}}{r_1} \left[J_{m+\lambda+1}(G) - J_{m+\lambda-1}(G) + (-1)^\lambda (J_{m-\lambda+1}(G) - J_{m-\lambda-1}(G)) \right] \right\} (-1)^{\frac{1}{2}(m+1)} \\ b_{m\lambda} &= \frac{m\Omega}{4\pi a_o r_1} \left\{ \frac{x a_{\lambda T}}{r_1} \left[J_{m+\lambda}(G) + (-1)^\lambda J_{m-\lambda}(G) \right] - \frac{a_{\lambda D}}{m M_t} \left[(m+\lambda) J_{m+\lambda}(G) + (-1)^\lambda (m-\lambda) J_{m-\lambda}(G) \right] \right. \\ &\quad \left. + \frac{y b_{\lambda c}}{2r_1} \left[J_{m+\lambda+1}(G) - J_{m+\lambda-1}(G) - (-1)^\lambda (J_{m-\lambda+1}(G) - J_{m-\lambda-1}(G)) \right] \right\} (-1)^{\frac{1}{2}(m+1)} \end{aligned} \quad (27b)$$

Before going on to the calculation of airloading harmonic values and program modifications, it is well to describe the use of Equation (27). Equation (27) describes the real (am) and imaginary (bm) components of the sound pressure in terms of the coordinates x and y whereas the inputs to the present program are in terms of the X, Y, Z coordinate system. This requires a change of coordinates from the X, Y, Z input to the x, y system used in Equation (27). Figure 4 shows the relationship between the two systems. The x-axis is in the direction of the rotor thrust and the y-axis is in the plane of the rotor disk, directed toward the observation point. Thus the observation point always lies in the xy plane. The X-axis, on the other hand, lies in the direction of aircraft forward velocity, the Z-axis is directed perpendicularly downward and the Y-axis is mutually perpendicular to the other two. Examination of Figure 4 shows the following system transformations to permit calculation directly by Equation (27) but inputting values in the X, Y, Z coordinate system:

$$x = X \cdot \sin(i_d) - Z \cdot \cos(i_d) \quad (28)$$

$$y = -(X \cdot \cos(i_d) + Z \cdot \sin(i_d)) \cos(\phi) - Y \cdot \sin(\phi) \quad (29)$$

$$\phi = \tan^{-1} \left\{ \frac{-Y}{-X \cdot \cos(i_d) - Z \cdot \sin(i_d)} \right\} \quad (30)$$

The harmonics of airloading are specified in the X, Y, Z coordinate system and are given as Fourier sine and cosine components $b_{\lambda\psi}$ and $a_{\lambda\psi}$ where the zero reference for ψ is taken to be the -X axis and ψ is the angle, measured in the direction of rotation, from the -X axis to the blade being considered. The loading harmonics must be related to the x, y coordinate system to be of use in Equation 27 thus:

$$\begin{aligned} a_{\lambda\gamma} \cos\lambda\gamma + b_{\lambda\gamma} \sin\lambda\gamma &= a_{\lambda\psi} \cos\lambda\psi + b_{\lambda\psi} \sin\lambda\psi \\ &= a_{\lambda\psi} \cos(\lambda\gamma + \lambda\phi) + b_{\lambda\psi} \sin(\lambda\gamma + \lambda\phi) \\ &= a_{\lambda\psi} (\cos\lambda\gamma \cos\lambda\phi - \sin\lambda\gamma \sin\lambda\phi) \\ &\quad + b_{\lambda\psi} (\sin\lambda\phi \cos\lambda\gamma + \cos\lambda\phi \sin\lambda\gamma) \end{aligned} \quad (31)$$

Then:

$$\begin{aligned} a_{\lambda\gamma} &= a_{\lambda\psi} \cos\lambda\phi + b_{\lambda\psi} \sin\lambda\phi \\ b_{\lambda\gamma} &= -a_{\lambda\psi} \sin\lambda\phi + b_{\lambda\psi} \cos\lambda\phi \end{aligned} \quad (32)$$

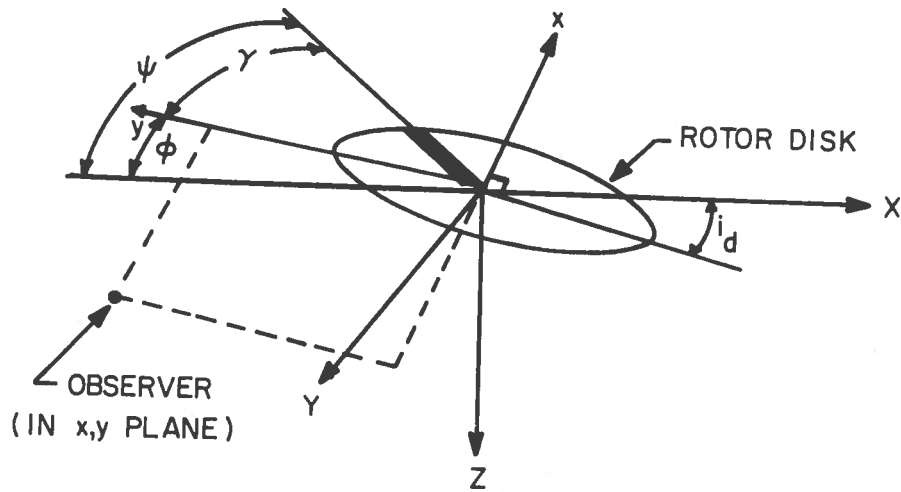


Figure 4. Definition of Rotor Coordinate Systems

However, the assumption is made that the Fourier sine components of loading are zero in the X, Y, Z coordinate system, thus:

$$b_{\lambda\psi} = 0 \quad (33)$$

and

$$\begin{aligned} a_{\lambda\gamma} &= a_{\lambda\psi} \cos\lambda\phi \\ b_{\lambda\gamma} &= -a_{\lambda\psi} \sin\lambda\phi \end{aligned} \quad (34)$$

Note that the assumption of zero sine components ($b_{\lambda\psi} = 0$) in the X, Y, Z coordinate system does not imply zero sine components in the x, y-coordinate system. A further assumption is made that the thrust, drag and outward force components are in phase and that all other phase relationships are random. This then allows Equation 34 to be written as the following:

$$\begin{aligned} a_{\lambda} &= a_{\lambda\psi} \cos\lambda\phi \\ b_{\lambda} &= a_{\lambda\psi} \sin\lambda\phi \end{aligned} \quad (35)$$

The Equations (35) provide the values for $a_{\lambda T}$, $a_{\lambda D}$, $a_{\lambda C}$, $b_{\lambda T}$, $b_{\lambda D}$, and $b_{\lambda C}$ in Equation 27.

Since the helicopter is in motion along the X-axis, it will have moved a given distance along its flight path by the time the sound it generated reaches the observer. Figure 5 illustrates this situation. If when the helicopter is at A (Figure 5) it generated sound (at time $t = 0$) and if it takes T seconds for that sound to reach the observer, then the helicopter will have moved during the propagation time, T, to a new position, B. As far as the observer is concerned, the helicopter is at B, based on the sound he hears, but in the calculation of the sound generated, it is position A, the "retarded" position of the helicopter which is important. The distance from the observer to the "retarded" position is given by:

$$r' = a_o T \quad (36)$$

and the distance the helicopter moves in this time T is $M_f a_o T$.

Then:

$$r'^2 = (X + M_f a_o T)^2 + Z^2 + Y^2 \quad (37)$$

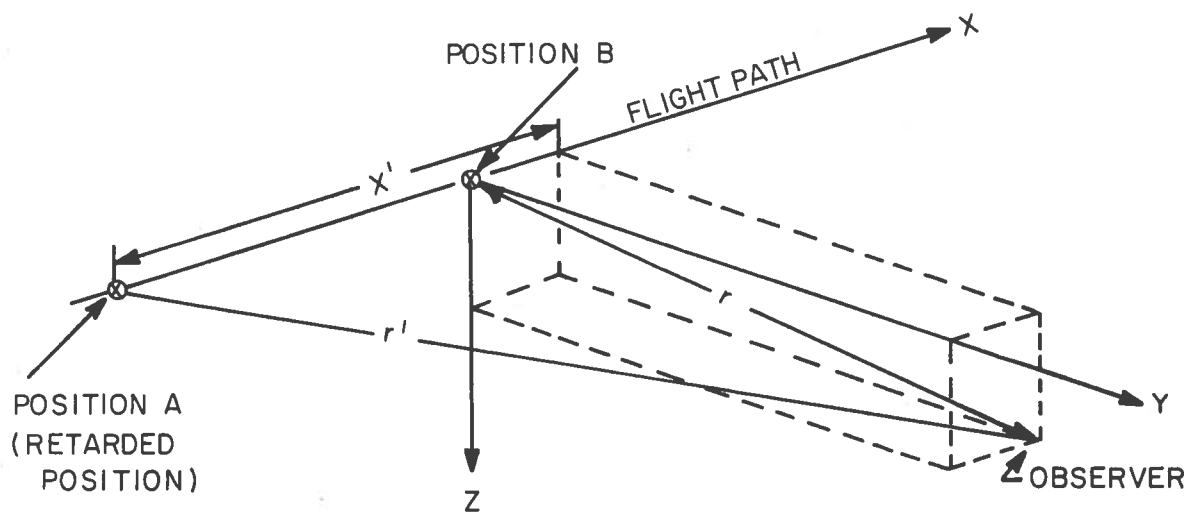


Figure 5. Definition of Helicopter 'Retarded' Position

$$T = \left[\frac{XM_f \pm \sqrt{X^2 + (1 - M_f^2)(Y^2 + Z^2)}}{a_0(1 - M_f^2)} \right] \quad (38)$$

from which:

$$X' = X + \left[\frac{XM_f^2 + M_f \sqrt{X^2 + (1 - M_f^2)(Y^2 + Z^2)}}{1 - M_f^2} \right] \quad (39)$$

The value of X' is then used in Equations 28 - 30 as the variable X .

Since the aircraft is in constant motion, the effect of this motion must be accounted for by changing the distance r' . Lowson and Ollerhead¹⁰ showed that this can be accomplished by the following substitution:

$$r_1 = r'(1 - M_0) \quad (40)$$

This is the value of r_1 used in the computation of Equation 27. As mentioned above all phase relationships are assumed to be random except those between T , D , and C . This then requires that in calculating the magnitude of m^{th} harmonic of sound, the magnitude of the contribution of each loading harmonic must be calculated before it is added to the accumulated sum indicated in Equation 27, thus:

$$|C_m| = (a_m^2 + b_m^2)^{\frac{1}{2}}$$

$$|C_m| = \sum_{\lambda=0}^{\infty} (a_{m\lambda}^2 + b_{m\lambda}^2)^{\frac{1}{2}} \quad (41)$$

In order to accurately calculate the noise radiation from the rotor, detailed knowledge of the fluctuating airloads acting on the blades must be known. Information of this type is difficult to obtain to high harmonic frequencies, consequently little or no high-frequency rotor blade loading information is available. However, Reference 10 showed, based on the limited data available, that harmonics of airloading approximately follow an inverse power law based on steady loading amplitude, for conditions of relatively smooth inflow through the rotor disk, such as in hover and forward flight out of ground effect. For rough running conditions, such as in ground effect hover and cruise, and autorotative descent, this inverse power law does not predict the harmonic levels as well.

The program also assumes that the blade load is concentrated at a single point on the blade. Reference 10 showed that results of sufficient accuracy may be obtained using this assumption. The optimum loading point for the main rotor was found to be at the 0.8 radial station (or at a distance 0.8R from the rotor hub). In the case of a tail rotor, however, it was found that the optimum loading point was at the 0.9 radial station. This can probably be explained by the lack of twist on the tail rotor blades tested which caused the loading to be concentrated nearer to the tips.

The amplitude of the λ^{th} loading harmonic due to thrust, drag, or outward components is given by the equation:

$$\begin{aligned} A_{\lambda T} &= A_{OT} l_c \lambda^{-k} \\ A_{\lambda D} &= A_{OD} l_c \lambda^{-k} \\ A_{\lambda C} &= A_{OC} l_c \lambda^{-k} \end{aligned} \quad (42)$$

The steady loading due to thrust (A_{OT}) is equal to the thrust force per blade as input to the program. The drag force acting at the loading point selected is calculated from the rotor torque by the relationship:

$$A_{OD} = D/B = Q/\eta RB \quad (43)$$

The steady loading due to drag forces is then the value of drag as calculated by Equation 43. The steady loading due to outward components is calculated from the radial force component which is determined by the relationship:

$$A_{OC} = C/B = T \sin(\beta)/B \quad (44)$$

Typical values of the airloading "k" factor are 1.8 to 2.0 for main rotors and 1.5 to 2.0 for tail rotors of standard design (ie. NACA symmetrical airfoil shapes with linear blade twist distributions). Advanced blades with non-linear twist distributions, cambered airfoils, etc tend to have k values somewhat higher (2.0 to 2.5).

The correlation coefficient in Equation (42) may vary from 0 to 1 and is a measure of the scale of phase coherence of the fluctuating airloads along the blade span (see Reference 10). For most cases $l_c = 0.7$.

The number of rotor noise harmonics that may be calculated is dependent on the number of blade loading harmonics available. As established by Reference 10, the maximum number of loading harmonics necessary to calculate m noise harmonics is given by the relationship:

$$L = mB(1+M) \quad (45)$$

When the number of sound harmonics requested makes it necessary to calculate more than about 60 loading harmonics, computer time becomes prohibitively long. Main rotor harmonics of sound up to about the 1300th would be necessary to accurately calculate third octave band levels up to the band centered at 10000 Hz. This would require calculation of loading harmonics up to the 3900th! Obviously, this is impractical and a method has been developed to calculate higher harmonics of sound that does not require calculation of loading harmonics.

Harmonics of sound up to the limiting value given by:

$$m_{lim} = 60/(B(1+M))$$

are calculated using Equation (27) while harmonics from m_{lim} up to 60 are calculated using an extrapolation method described below. It was shown in Section 6 of Reference 10 that the acoustic intensity of the higher harmonics follows a trend which is given by the asymptotic solution:

$$p^2 = K(mB)^{2-2k} \quad (46)$$

This is true because the airloads are represented by Equation (42). The sound pressure calculated for the m_{lim} -th sound harmonic is used in Equation (46) to evaluate the constant, K , after which Equation (46) is used to calculate the sound pressure of the additional harmonics from $(m_{lim}+1)$ up to the 60-th; alternatively the sound pressure level of these higher harmonics can be calculated directly by the equation:

$$SPL_m = 10((2-2k)\log(mB) + \log(K) + 7.39) \quad (47)$$

Calculation of One-Third Octave Levels

The calculation of 1/3- octave band sound pressure levels is divided into two parts, namely (a) calculation of band levels for 1/3-octaves up to one centered at f_{cc} and (b) calculation of band levels for the 1/3-octave whose center frequencies are higher than f_{cc} . The one-third octave band centered at f_{cc} is the highest band whose level can be computed by summing the calculated rotational harmonics. Assuming the -40 dB/octave filter skirt discussed below, the frequency f_{cc} is the third-octave frequency closest to the frequency given by the equation:

$$f_1 = 60f_o/1.6 \quad (48)$$

This guarantees that the level of the 60-th harmonic will be at least 30 dB down from the level of harmonics falling in the passband. The first step necessary for one third octave band level calculations is the assumption of a filter shape. This has been done and is shown in Figure 6. The shape is typical of filters in normal use and approximates the ASA Class III filter shape as given in ASA Specification S1.11-1966. The upper and lower cutoff frequencies, f_{uj} and f_{lj} , are the 3dB down points, f_{cj} is the center frequency of the j^{th} octave band, and the filter skirts drop off at 40 dB per octave. If the harmonics of rotor noise are reduced by this filter only those falling in the flat portion (passband) of the filter will be unaltered. Those falling outside this flat portion will be attenuated an amount which is determined by their frequencies in relation to the center frequency of the band. For harmonic frequencies below f_{lj} , the amount of attenuation is given by the equation:

$$a_{fj} = 133 \log(f/f_{cj}) + 3.65 \quad f \leq f_{lj} \quad (49)$$

where f is the frequency of the harmonic in question. When the harmonic frequency is above f_{uj} , the attenuation of the harmonic level by the filter is given by the relationship:

$$a_{fj} = 133 \log(f_{cj}/f) + 3.65 \quad f \geq f_{uj} \quad (50)$$

To illustrate the effect the filter has on a harmonic spectrum Figure 7 has been prepared. Figure 7a shows a typical harmonic spectrum in a frequency range from 10 Hz to 100 Hz and Figure 7b shows how this spectrum would appear after being filtered by the one-third octave band centered at 25 Hz.

The one-third octave band level as determined by a filter of the shape shown in Figure 6 is the logarithmic sum of the harmonic levels after they have been modified by the effect of the filter shape (i.e., the logarithmic sum of the harmonic levels of Figure 7b). The j^{th} one-third octave band level is then given by the equation:

$$1/3 OL_j = 10 \log \sum_{m=1}^N \text{antilog} \left(\frac{A_m}{10} + \frac{a_{fjm}}{10} \right) \quad (51)$$

where m is the harmonic number. Equation (51) is used by the computer program to calculate the sound pressure level of all third-octave bands up to the one centered at f_{cc} .

In order to expedite calculation of the sound pressure level for one-third octaves above f_{cc} an extrapolation method has been devised. This is possible because the higher harmonics follow the asymptotic trend given by Equation (46) which is reproduced below:

$$p^2 = K(mB)^{2-2k} \quad (46)$$

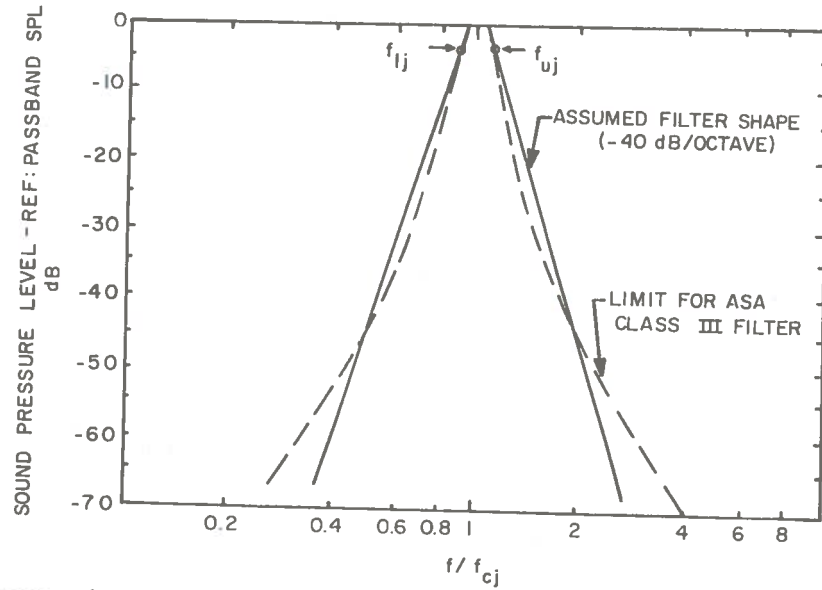


Figure 6. Assumed 1/3-Octave Band Filter Shape

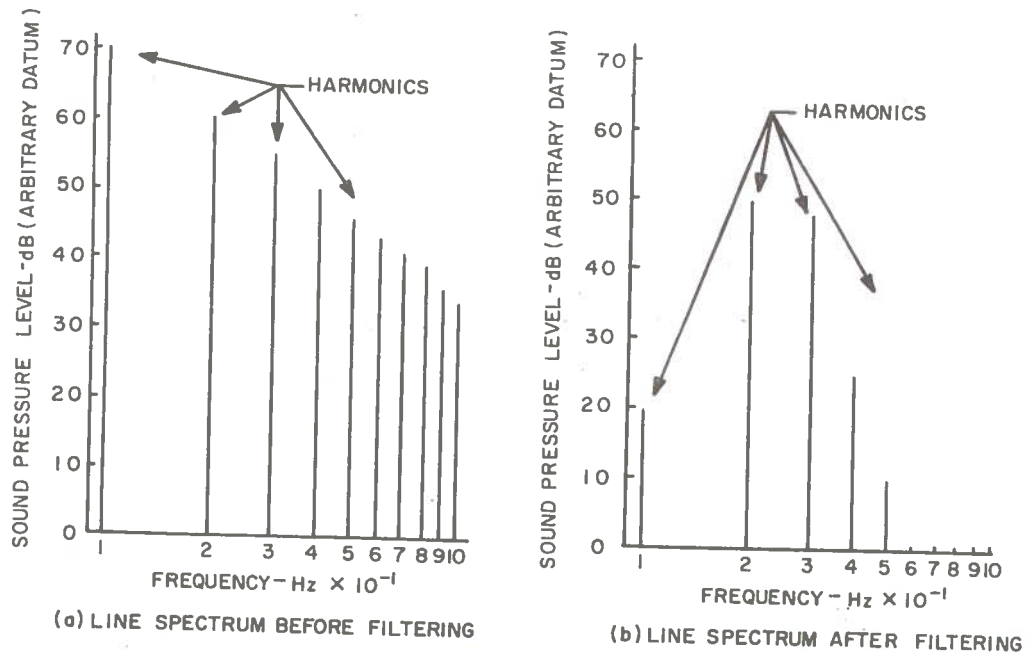


Figure 7. Effect of One-Third Octave Filter (25 Hz Center Frequency) on Sample Line Spectrum

If we let $(N + 1)$ be the number of the lowest harmonic contained in the pass-band of the j -th third octave, N is given by:

$$N = \text{mod} \left\{ \frac{f_{c,j}}{2^{1/6} f_o} \right\} \quad (52)$$

and if we assume that the level of the j -th third octave band is the sum of the harmonics contained in the passband (ie - between the upper and lower cutoff frequencies) then the level of the j -th third octave band is the sum of the harmonics from $N + 1$ to $2^{1/3}N$ since $f_{uj} = 2^{1/3}f_{lj}$:

$$1/3 \text{ OL}_j = 10 \log \sum_{n=N+1}^{2^{1/3}N} K(n)^{2-2k} \text{-SPL}_{\text{ref}} \quad (53)$$

By the same token the harmonics contained in the passband of the $(j + 1)$ -th third octave band are from $(2^{1/3}N + 1)$ to $2^{2/3}N$ and the level of $(j + 1)$ -th band is given

$$1/3 \text{ OL}_{j+1} = 10 \log \sum_{n=2^{1/3}N+1}^{2^{2/3}N} K(n)^{2-2k} \text{-SPL}_{\text{ref}} \quad (54)$$

The increment between the two band levels is given:

$$\Delta \text{dB} = 1/3 \text{ OL}_{j+1} - 1/3 \text{ OL}_j \quad (55)$$

$$\Delta \text{dB} = 10 \log \sum_{n=2^{1/3}N+1}^{2^{2/3}N} K(n)^{2-2k} - 10 \log \sum_{n=N+1}^{2^{1/3}N} K(n)^{2-2k} \quad (56)$$

$$\Delta \text{dB} = 10 \log \frac{\sum_{n=2^{1/3}N+1}^{2^{2/3}N} K(n)^{2-2k}}{\sum_{n=N+1}^{2^{1/3}N} K(n)^{2-2k}} \quad (57)$$

$$1/3 \text{ OL}_{j+1} = 1/3 \text{ OL}_j + 10 \text{ Log} \frac{(2^{1/3}N+1)^\alpha + (2^{1/3}N+2)^\alpha + \dots + (2^{2/3}N)^\alpha}{(N+1)^\alpha + (N+2)^\alpha + \dots + (2^{1/3}N)^\alpha} \quad (58)$$

where

$$\alpha = 2-2k$$

Thus the level of the one-third octave band at $2^{1/3} f_{cc}$ is given by:

$$1/3 \text{ OL}_{2^{1/3}f_{cc}} = 1/3 \text{ OL}_{f_{cc}} + 10 \text{ Log} \frac{(2^{1/3}_{N+1})^\alpha + (2^{1/3}_{N+2})^\alpha + \dots + (2^{2/3}_N)^\alpha}{(N+1)^\alpha + (N+2)^\alpha + \dots + (2^{1/3}_N)^\alpha} \quad (59)$$

Equation 58 then, is used to calculate the third octave band levels for all the bands centered above f_{cc} .

Rotor Broadband Noise

Rotor generated broad-band noise has been included in the computer program. A complete discussion of broad-band rotor noise is included in References 1 and 20 thus only a short summary will be included here.

The basic conclusion established by Lowson in Reference 20 is that the overall level of rotor generated broad band noise is most accurately calculated by means of the equation developed by Schlegel, et al (Reference 1). Lowson²⁰, however, developed a factor to modify Schlegel's equation to account for directionality effects. This factor and the spectrum shape are given as:

(a) Directionality:

$$DI = 10 \text{ Log} \left\{ \frac{\cos^2(\theta_1) + 0.1}{\cos^2(70)} \right\} \quad (60)$$

where θ_1 is the angle measured from the rotor rotational axis ($\theta_1 = 0^\circ$ below the rotor). As noted in Reference 20, the factor $(\cos^2(70^\circ))$ is included to normalize the directivity factor to the measurement location used by Schlegel, et al.¹

(b) Spectrum Shape:

The spectrum shape is that developed by Schlegel, et al and shown in Figure 8

(c) Peak frequency:

The relationship used by Schlegel in Reference 1 to determine the peak vortex frequency was given as the relation:

$$f_s = 0.28 V_{0.7}/h_1 \quad (61)$$

where:

$$h_1 = c \sin(\alpha_1) + t \cos(\alpha_1)$$

and

$V_{0.7}$ is the rotational speed at the seven-tenth radial station, c is the blade chord, t is the blade thickness, and α_1 is the angle of attack at 0.7R.

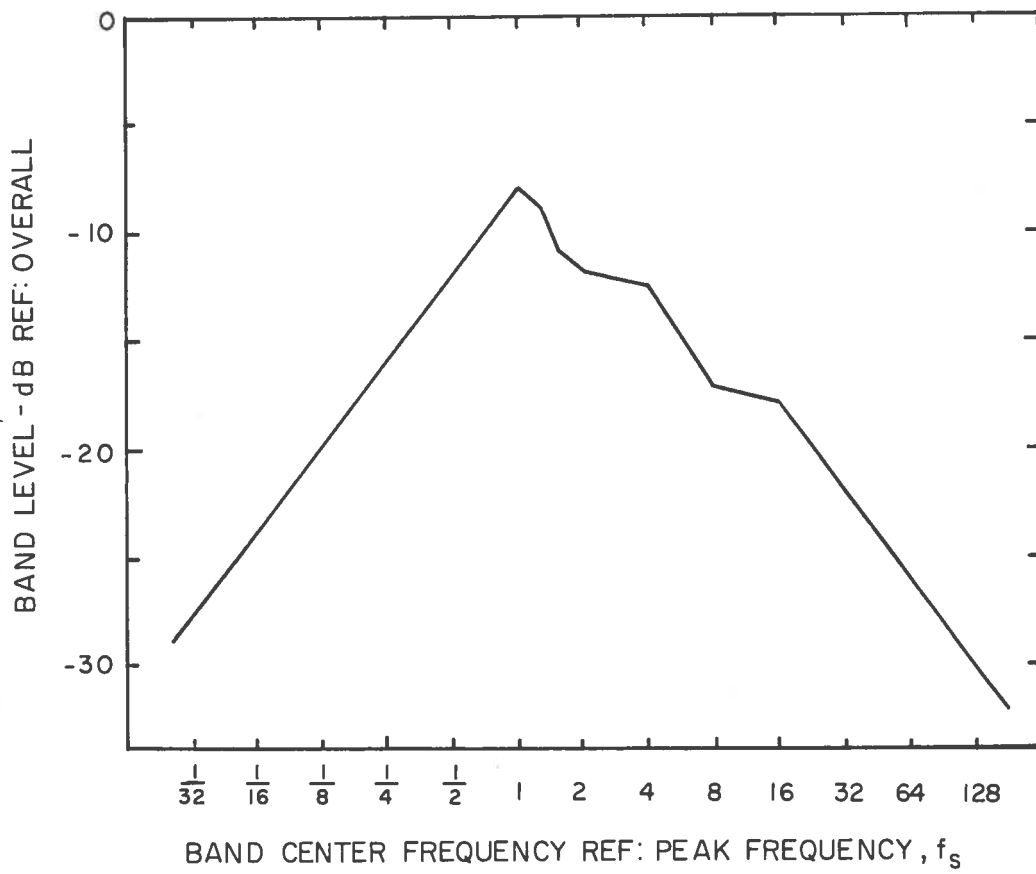


Figure 8. Rotor Broadband Noise Spectrum Shape

In order to provide a solution requiring less detailed knowledge of the blade geometry, data collapses were performed using measured rotor data. These data provided the following relation for f_s :

$$f_s = -240 \text{ Log}(T) + 0.746 V_t + 786 \quad (62)$$

which was used in the program for the peak vortex frequency.

When all these factors are combined with Schlegel's, et al¹ equation, the sound pressure level of the j -th third octave band of rotor broadband noise is given by the following:

$$\begin{aligned} \text{SPL}_{Vj} = & 20 \text{ Log}(V_t) + 20 \text{ Log}(T) - 10 \text{ Log}(B) - 10 \text{ Log}(R) \\ & - 10 \text{ Log}(c) - 20 \text{ Log}(r') + 10 \text{ Log}(\cos^2 \theta_1 + 0.1) + S_j + 19.4 \end{aligned} \quad (63)$$

where S_j is the spectrum shape correction number given in Figure 8. The complete rotor spectrum is the band by band energy sum of the rotational and broadband noise. When a tail rotor is included its' complete spectrum is added to the main rotor spectrum to produce a total rotors spectrum which is stored for later use in calculating the vehicle spectrum.

Propeller Noise

As in the case of rotor noise, calculation of propeller noise consists of two parts, rotational and broadband noise. The rotational noise calculation procedure is empirically derived from several sources (References 14, 17, 19, 27, and 33) and the broadband noise is calculated from Hubbard's (Ref. 34) interpretation of Yudin's (Reference 35) work with rotating round rods. This procedure yields acceptable correlation with measured data as will be shown in a following section.

Rotational Noise

The first step in the procedure is to calculate the overall rotational noise level, OASPL_R , at the correct distance r and azimuth γ_a . This has been determined to be

$$\begin{aligned} \text{OASPL}_R = & 15.5 \text{ Log}(P_p) - 20(\text{Log}(D_p) + \text{Log}(B_p)) + 40M_t \\ & + 10 \text{ Log}(N_p) + \text{DI}(\gamma_a) - 20 \text{ Log}(r/500) + 50.2 \end{aligned} \quad (64)$$

The value of r , the distance from observer to aircraft is calculated from the field point values X, Y, Z . The azimuth angle is defined in Figure 9 and the directivity index DI is calculated from:

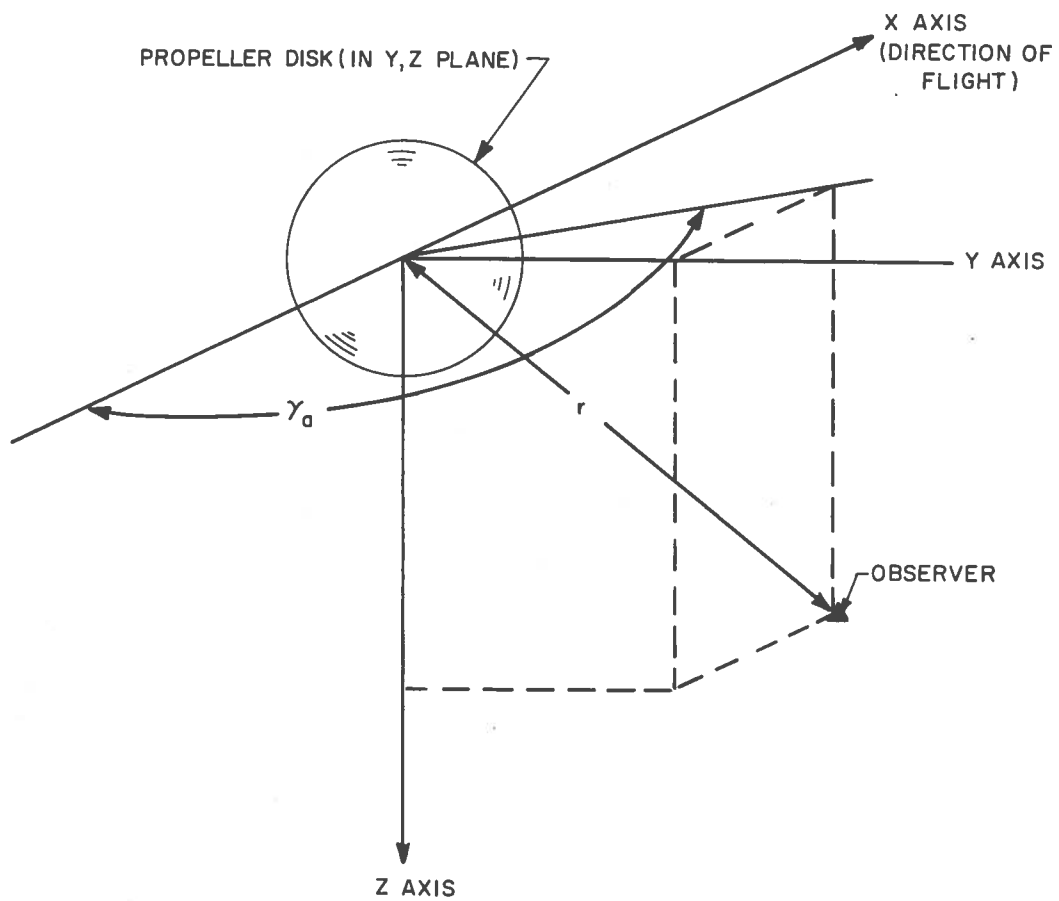


FIGURE 9. Definition of Field Point Azimuth Angle γ_a For Propeller Noise Calculation.

$$DI = \begin{cases} 0.1200\phi_1 - 7.00 & 0^\circ < \phi_1 < 50^\circ \\ 0.0286\phi_1 - 2.43 & 50^\circ < \phi_1 < 120^\circ \\ -.3080\phi_1 + 38.0 & 120^\circ < \phi_1 < 180^\circ \end{cases} \quad (65)$$

where $\phi_1 = |180^\circ - \gamma_a|$. The first ten rotational harmonics are calculated from the $OASPL_R$ value and the helical tip Mach number M_H by the use of Figure 10. The harmonic frequencies are integral multiples of the fundamental rotational frequency f_o given by:

$$f_o = V_H B / D_p \quad (66)$$

$$f_m = m V_H B / D_p \quad (67)$$

$$V_H = \sqrt{V_T^2 + V_f^2} \quad (68)$$

The harmonic spectrum is converted to a one-third octave spectrum by adding the harmonics which fall in a given one-third octave band to produce the band level. For example, the harmonic spectrum of Figure 11a results in the (ideal) third octave spectrum of Figure 11b. For the sake of simplicity the third octave filters are assumed to have an ideal shape (infinitely steep skirts).

Broadband Noise

The broadband noise component is calculated from the vortex noise equation for propellers given by Hubbard (Reference 34):

$$OASPL_v = 10 \text{ Log}(3.8 \times 10^{-11} A_B V_{0.7}) - 20 \text{ Log}(r/500) \quad (69)$$

While there are more sophisticated methods being developed (eg. Reference 17) they are somewhat more complicated to use and require the use of empirically derived constants. The Equation (69) above appears to yield reasonably accurate results and is relatively simple to use.

The one-third octave band spectrum is determined from the $OASPL_v$ of Equation (69) and the spectrum shape shown in Figure 12 adapted from Beranek's (Reference 27) vortex noise spectrum shape. The peak frequency is given by Beranek¹⁷ as:

$$f_s = 0.85 V_H / c \quad (70)$$

where c is the mean blade chord.

The complete propeller spectrum is the band by band energy summation of the rotational and broadband components:

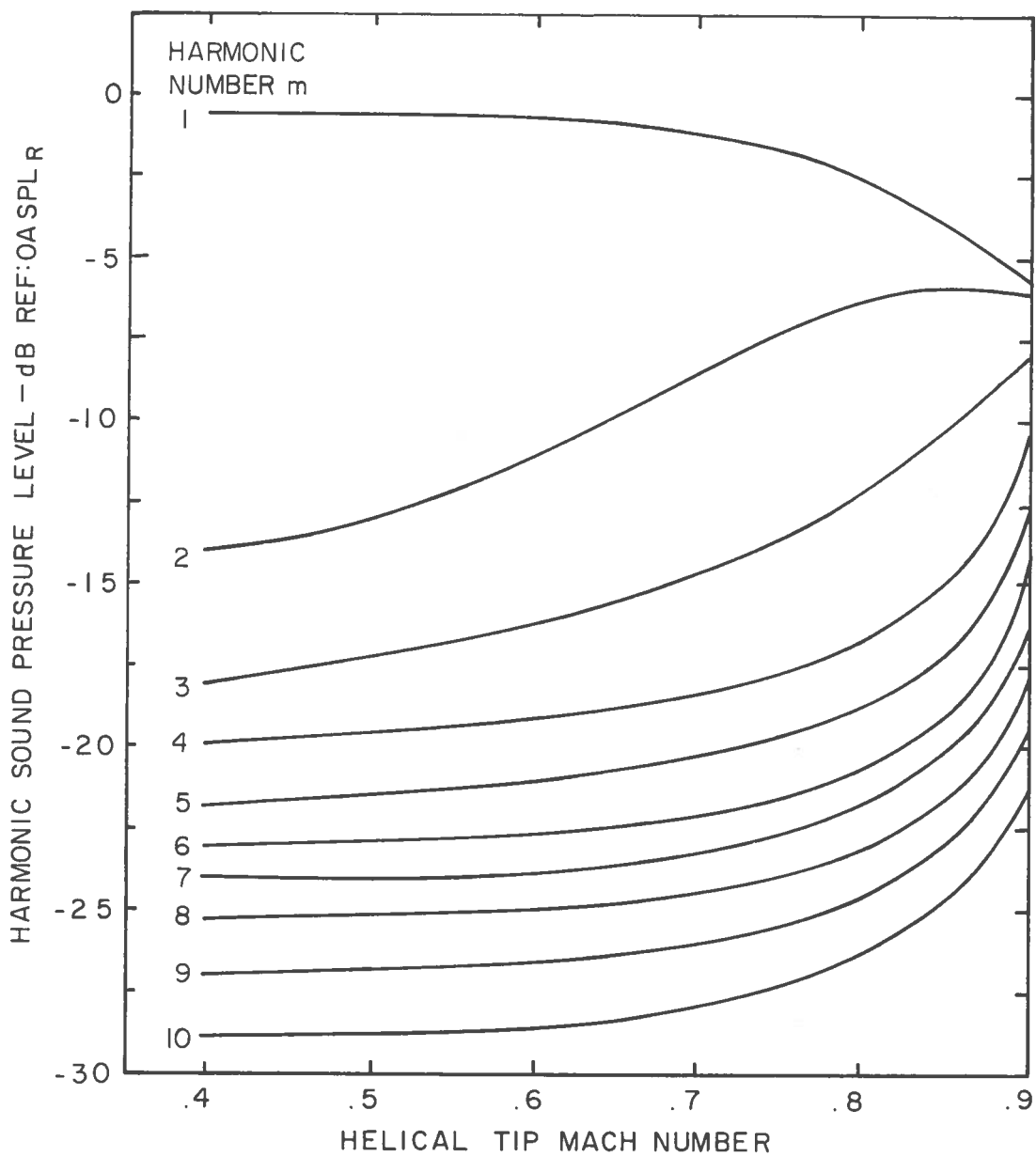
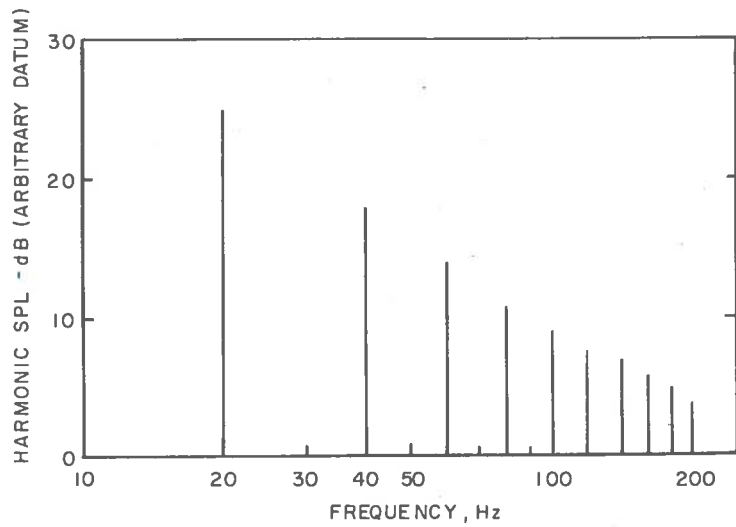
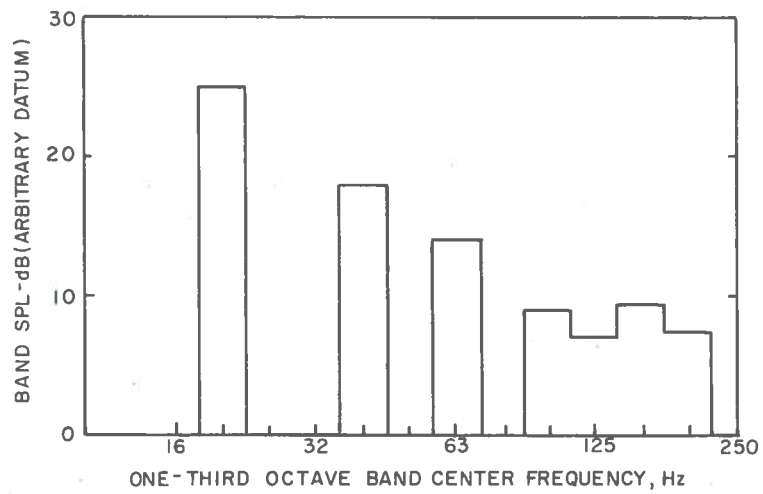


Figure 10. Relationship of Propeller Rotational Harmonic Sound Pressure Level to the Calculated OASPLR As a Function of Helical Tip Mach Number M_H



(a) SAMPLE HARMONIC (LINE) SPECTRUM



(b) CORRESPONDING ONE-THIRD OCTAVE SPECTRUM

FIGURE 11. Conversion of Harmonic Spectrum to a One-Third Octave Spectrum.

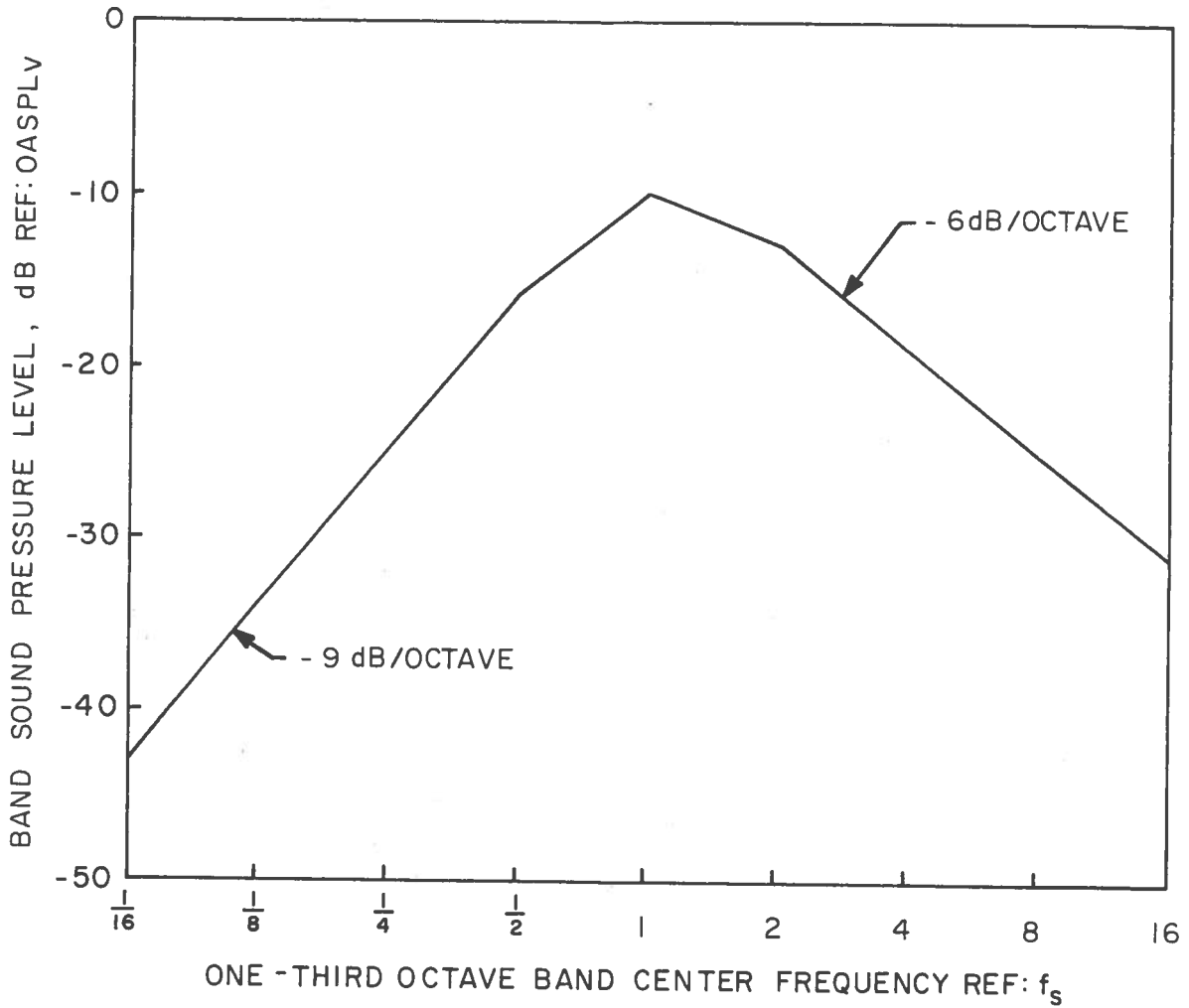


Figure 12. Assumed Propeller One-Third Octave Band Spectrum Shape (Reference 27)

$$OL_j = 10 \text{ Log} \left\{ \text{Antilog} \left[\frac{OL_{Rj}}{10} \right] + \text{Antilog} \left[\frac{OL_{Vj}}{10} \right] \right\} \quad (71)$$

Fan Noise

The method used to calculate the noise radiated from fans and fan engines is the analytical/empirical procedure described by Burdsall and Urban in Reference 15. The method is described in detail in Reference 15 hence only a limited discussion will be presented here.

Three components are calculated: discrete tone, broadband, and combination tone noise. Combination tone noise occurs at multiples of the fan rotational frequency when the fan blades operate at relative tip Mach numbers above 1. Because of the detailed design parameters required provision has been made to delete the combination tone noise calculation. For this case the calculated fan noise is an approximation. The calculated values for discrete tone noise do not include the possibility of propagating rotor/stator interaction tones. Burdsall and Urban's method for calculating discrete tone noise is developed from engine data in which there are no propagating interaction tones, hence interaction tone noise is not explicitly included in the final method. A check is performed to determine the presence of interaction tones and a warning is printed out in the event they are present. In general, when they exist they are only important for blade/vane spacings less than about four chords.

Discrete Tone Noise

The Burdsall/Urban¹⁵ method calculates the first two harmonics of blade passing noise for aft ($0^\circ < \gamma_a < 90^\circ$) and for forward ($90^\circ < \gamma_a < 180^\circ$) radiation using the following empirical equations based on rotor field cutoff ratio ξ_{RF} :

$$\xi_{RF} = \frac{M_t}{M^* \sqrt{1 - M_{ax}^2}} \quad (72)$$

where

$$M^* = 1 + 0.84B_f^{-2/3} \quad (73)$$

The forward radiated mean SPL in the first harmonic for $\xi_{RF} \leq 1.05$ is calculated to be:

$$\begin{aligned} SPL'_{1F} = & 121.84 + 38.28\xi_{RF} - 303.79\xi_{RF}^2 + 635.85\xi_{RF}^3 - 483.36\xi_{RF}^4 + 122.8\xi_{RF}^5 \\ & + 10 \text{ Log} \left\{ (PR-1) \left[\frac{D_{tf}}{24} \right]^2 \right\} - 20 \text{ Log}(r) + 5.55 \end{aligned} \quad (74)$$

When ξ_{RF} is between 1.05 and 1.5, the value for SPL_{1F} is the value calculated in Equation (74) minus $20 \log (DL)$:

$$SPL_{1F} = SPL'_{1F} - 20 \log(DL) \quad (75)$$

When ξ_{RF} is greater than 1.5 the forward radiated sound pressure level is calculated by the following equation:

$$SPL_{1F} = 127 + 10 \log \left\{ (PR-1) \left[\frac{D_{tf}}{24} \right]^2 \right\} - 20 \log(DL) - 20 \log(r) + 5.55 \quad (76)$$

The aft radiated, first harmonic sound power level for $\xi_{RF} < 1.5$ is given as:

$$SPL_{1R} = 184 - 203.18\xi_{RF} - 21.98\xi_{RF}^2 + 550.99\xi_{RF}^3 - 534.97\xi_{RF}^4 + 151.26\xi_{RF}^5 + 10 \log \left\{ (PR-1) \left[\frac{D_{tf}}{24} \right]^2 \right\} - 20 \log(r) + 5.55 \quad (77)$$

and for $\xi_{RF} < 1.5$:

$$SPL_{1R} = 129 + 10 \log \left\{ (PR-1) \left[\frac{D_{tf}}{24} \right]^2 \right\} - 20 \log(r) + 5.55 \quad (78)$$

The mean SPL of the second harmonic is calculated from the first in the following way:

$$SPL_{2F} = SPL_{1F} - C_F \quad (79)$$

$$SPL_{2R} = SPL_{1R} - C_R \quad (80)$$

where C_F and C_R are:

$$C_F = \begin{cases} 3.3 & N_c = 1 \\ 5.7 & N_c = 2 \\ 6.8 & N_c = 3 \end{cases} \quad (81)$$

$$C_R = \begin{cases} 3.2 & N_c = 1 \\ 3.5 & N_c = 2 \\ 2.5 & N_c = 3 \end{cases} \quad (82)$$

$$N_c = \text{Mod} \left(1 + \frac{\xi_{RF}}{.91} \right) \quad (83)$$

The sound pressure level at a specified azimuth angle γ_a is determined from the directivity curves of Figure 13 or the following equation:

$$\begin{aligned} \text{SPL}(\gamma_a) = \text{SPL} + K_1 + K_2(180-\gamma_a) + K_3(180-\gamma_a)^2 + K_4(180-\gamma_a)^3 \\ + K_5(180-\gamma_a)^4 + K_6(180-\gamma_a)^5 \end{aligned} \quad (84)$$

The values of K_1 through K_6 are given in Table 1.

TABLE 1
Constants K_i For Calculation of Discrete
Tone Sound Pressure Level

	ξ RK	K_1	K_2	K_3	K_4	K_5	K_6
$\text{SPL}'_{1F}(\gamma_a)$	≤ 1.05	-1.2669	5.4963 $\times 10^{-2}$	-2.9492 $\times 10^{-3}$	7.6284 $\times 10^{-5}$	3.4487 $\times 10^{-7}$	-1.2323 $\times 10^{-8}$
$\text{SPL}_{1F}(\gamma_a)$	> 1.05	-3.0339	7.2853 $\times 10^{-2}$	4.0824 $\times 10^{-4}$	2.8230 $\times 10^{-7}$	-8.8591 $\times 10^{-8}$	-6.3146 $\times 10^{-10}$
$\text{SPL}_{1R}(\gamma_a)$	ALL	-56.418	0.6450	2.0970 $\times 10^{-3}$	-6.7782 $\times 10^{-6}$	2.8956 $\times 10^{-7}$	8.5944 $\times 10^{-10}$

The frequency of the first harmonic and of the second harmonic are calculated:

$$f_{of} = \frac{B_f \Omega N f}{60} \quad (\text{first harmonic}) \quad (85)$$

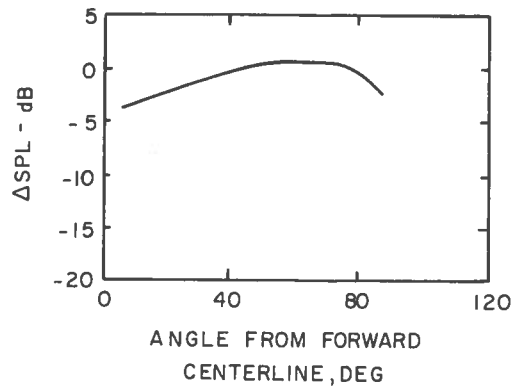
$$f_{1f} = 2f_{of} \quad (\text{second harmonic}) \quad (86)$$

The levels of the one-third octave bands containing the fundamental and the second harmonic are equal to the calculated sound pressure levels of the first and second harmonic respectively. These band levels are stored for later combination with the broadband and combination tone spectra to produce the complete spectrum.

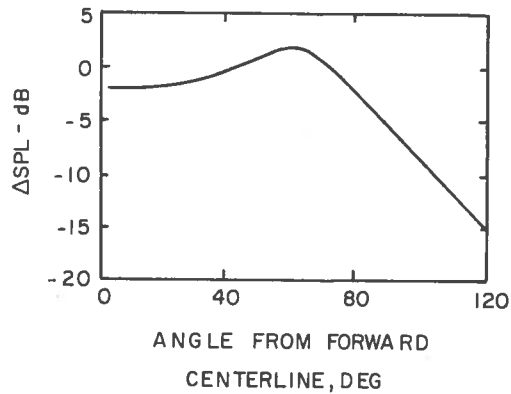
Broadband Noise

The overall broadband noise level at 60° from the inlet (150 ft away) is calculated from the relation:

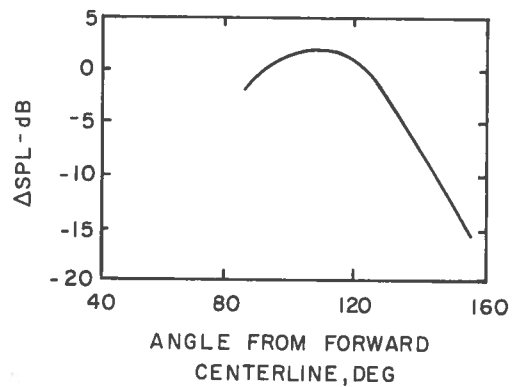
$$\begin{aligned} \text{OLSPL}_{v,60} = \text{OSPL}(DF, M_t) + 20 \text{Log} \left(\frac{D}{52} \right) - 20 \text{Log}(r/150) \\ + \alpha_o(90) \left\{ 10 \text{Log} \left\{ \frac{\text{BPR}/(\text{BPR}+1)}{0.833} \right\} \right\} \end{aligned} \quad (87)$$



(a) DISCRETE TONE DIRECTIVITY FOR $\xi_{RK} \leq 1.05$ - FORWARD RADIATION



(b) DISCRETE TONE DIRECTIVITY FOR $\xi_{RK} > 1.05$ - FORWARD RADIATION



(c) DISCRETE TONE DIRECTIVITY FOR AFT RADIATION

Figure 13. Fan Discrete Tone Noise Directivity

where: $\sigma_o(90) = 0$ if $\gamma_a \geq 90^\circ$ and $\sigma_o(90) = 1$ if $\gamma_a < 90^\circ$. OSPL (DF, M_t) is taken from the Figure 14 curve. The sound pressure level at angles other than 60° is given by:

$$OLSPL_{\gamma_a} = OLSPL_{60} + F_1(DI_{sub}) + (1-I_1)(DI_{sup}) \quad (88)$$

The directivity indicies DI_{SUB} and DI_{SUP} are taken from Figure 15 and F_1 is calculated to be:

$$F_1 = \frac{1}{2} \left\{ 1 - \tanh \left(\frac{M_{rel}^{-0.95}}{0.2} \right) \right\} \quad (89)$$

$$M_{rel} = \sqrt{M_{ax}^2 + M_t^2} \quad (90)$$

M_{ax} = axial tip Mach number

M_t = circumferential tip Mach number

The overall level is converted to a one-third octave band spectrum using the Figure 16 spectrum shapes based on the reduced frequency f^* where f^* is given as

$$f^* = \frac{fR_t}{a_o} \quad \text{for } M_{rel} \geq 1.0$$

$$f^* = \frac{fc\sqrt{1-M_{rel}^2}}{a_o M_{rel}} \quad \text{for } M_{rel} < 1.0 \quad (91)$$

and f is the one-third octave center frequency for which the sound pressure level is being calculated.

Combination Tone Noise

As Burdsall and Urban¹⁵ point out, combination tone noise is a spectral transfer of energy from the blade passage tone and harmonics to the shaft rotational frequency and all of its harmonics. Combination tones occur only when the flow over the blade tips is supersonic and results from small blade-to-blade manufacturing irregularities which are amplified by the non-linear nature of shock wave propagation. Because the calculation of combination tone noise requires rather detailed knowledge of the fan design geometry the program contains the option to delete its calculation in the event these design details are not available. In this case, the calculated fan noise represents a first approximation to the actual levels.

The overall sound power level of combination tone noise is calculated with the following empirical equation¹⁷:

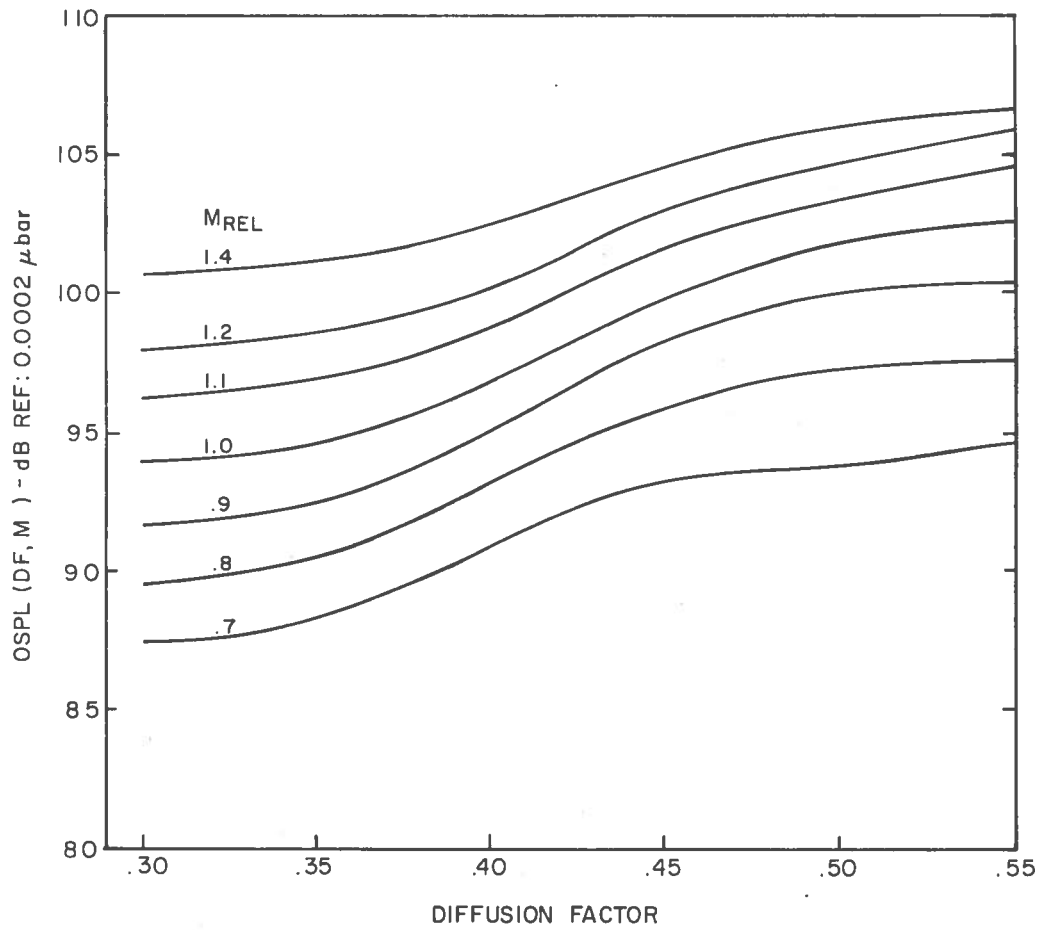


Figure 14. Fan Broadband Noise Level as a Function of Relative Tip Mach Number and Diffusion Factor

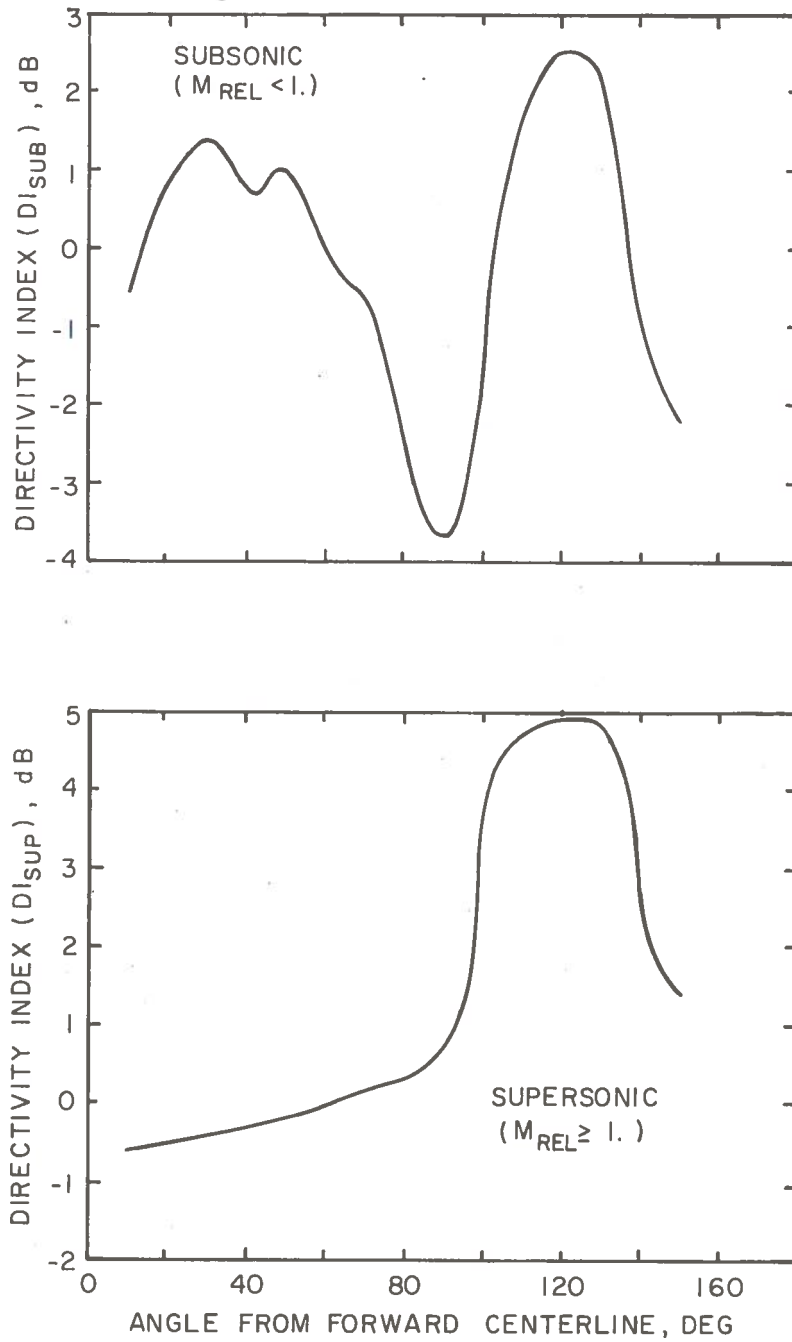


Figure 15. Fan Broadband Noise Directivity Correction

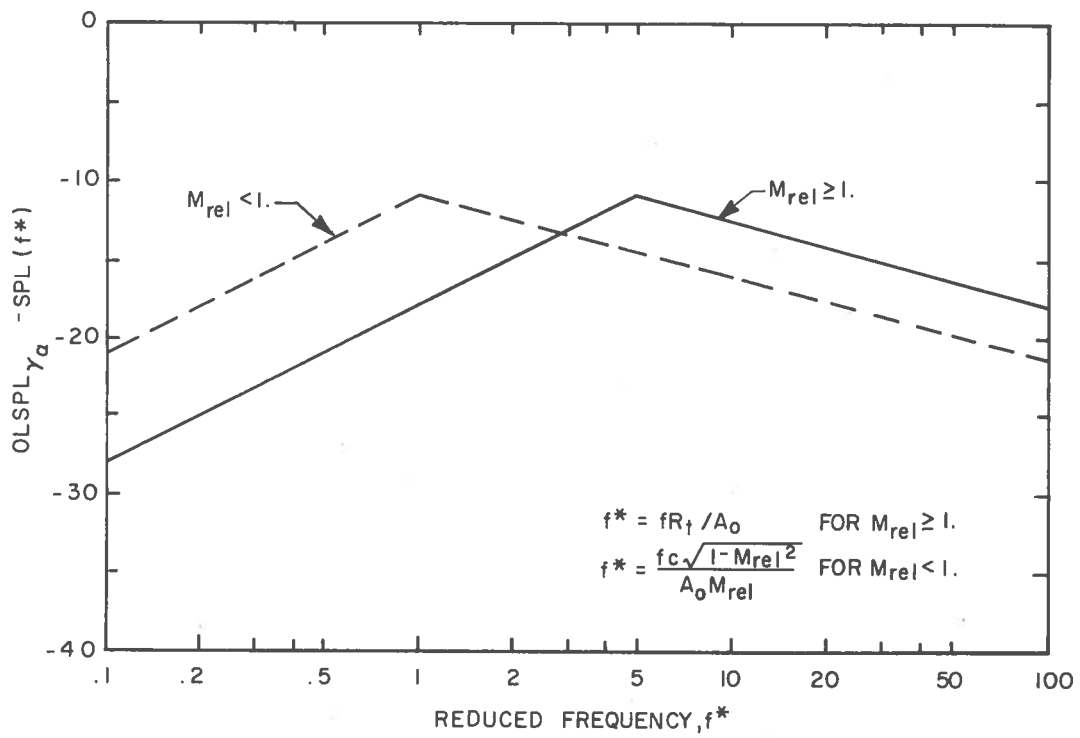


FIGURE 16. Fan Broadband Noise Spectrum Shape.

$$\begin{aligned} \text{OAWPL} = & 189.16 + 727.24M_{\text{rel}} - 488.93M_{\text{rel}}^2 + 107.69M_{\text{rel}}^3 \\ & + 10 \text{ Log } \frac{A_i}{144} - 20 \text{ Log}(\eta_f B) \end{aligned} \quad (92)$$

Where: $\eta_f = \frac{1}{2}(1 + \text{erf}(\psi_2))$ (93)

$$\text{erf}(\psi_2) = \begin{cases} 0 & \text{for } \psi_2 = 0 \\ 1 & \text{for } \psi_2 > 0 \quad \text{and } T \leq 0.43 \\ -1 & \text{for } \psi_2 < 0 \quad \text{and } T \leq 0.43 \\ +Q & \text{for } \psi_2 > 0 \quad \text{and } T > 0.43 \\ -Q & \text{for } \psi_2 < 0 \quad \text{and } T > 0.43 \end{cases} \quad (94)$$

$$T = 1 / (1 - 0.328|\psi_2|) \quad (95)$$

$$Q = 1 - Te^{-\psi_2^2} [1.061T^4 - 1.43T^3 + 1.42T^2 - 0.284T + 0.255] \quad (96)$$

$$\psi_2 = (\phi_e - \phi_a) / \sqrt{2} \cdot \sigma_\phi \quad (97)$$

$$\theta_a = 13.5 \left[\frac{R'_s \sin \mu}{\sin(\mu + \beta^*)} \right]^{0.875} \quad (98)$$

$$\mu = \tan^{-1}(1/M_{\text{rel}}) \quad (99)$$

$$\beta^* = \tan^{-1}(M_{\text{ax}}/M_t) \quad (100)$$

$$\theta_e = 2 \text{Tan}^{-1} \left[\frac{-\sin + \sqrt{\sin^2 + (T/R'_s) \sin(\mu - \beta^*) (2\cos\mu - (T/R'_s) \sin(\mu - \beta^*))}}{2\cos\mu - (T/R'_s) \sin(\mu - \beta^*)} \right] \quad (101)$$

$$R'_s = R_s R_f / (R_s - R_f) \quad \text{for } R_f \neq R_s \quad (102)$$

$$R_f = \frac{(1 - M_{\text{ax}}^2) M_{\text{rel}}^2}{2\cos\beta^* (1 + (M_{\text{ax}}^2/f)) M_{\text{ax}} M_t} \cdot \frac{D_t^2 - D_h^2}{D_t (dD_t/dx) + D_h (dD_h/dx)} \quad (103)$$

According to Burdsall and Urban's¹⁵ analytical development the distribution of power into the rotational harmonics is given by the equation

$$PWL(K) = 170.8 + 10 \text{ Log} \left\{ \left[\frac{1}{4K} \left[\frac{\eta B}{\pi K} \right]^3 \left[1 - \cos \frac{2\pi K}{\eta B} \right] + 2 \left[\frac{\pi K}{\eta B} \right]^2 \left[1 - \frac{\eta B}{\pi K} \sin \frac{2\pi K}{\eta B} \right] \right\} \right. \\ \left. \cdot \left\{ 1 + \sigma_a^2 + \exp \left[-4\sigma_e^2 \left(\frac{\pi K}{\eta B} \right)^2 \right] (B\delta_{KN} - 1) \right\} \right\} \quad (104)$$

$$\delta_{KN} = \begin{cases} 0 & K \neq B \\ 1 & K = B \end{cases} \quad (105)$$

$$\sigma_a = 0.1 \quad (106)$$

$$\sigma_e^2 = 1 - \eta + 2\eta\alpha^2 \left\{ \sigma_\phi^2 + 2\sigma_\phi^3 \cdot 2/\pi \left[\left\{ \psi_1^2 + 2^{1.5}\sigma_\phi\psi_1 + (2\sigma_\phi)^2 e^{-\psi_1^2} \right\} \right. \right. \\ \left. \left. - \left\{ \psi_2^2 + 2^{1.5}\sigma_\phi\psi_2 + (2\sigma_\phi)^2 e^{-\psi_2^2} \right\} \right] \right\} \quad (107)$$

$$\alpha = \frac{R'_s}{\tau} \cdot \frac{\sin(\mu+\theta_a)}{\sin(\mu+\beta^*)} \quad (108)$$

Since only those harmonics above cutoff will propagate the tones below cutoff are eliminated and their energy added to the remaining tones to keep the total energy constant. The cutoff ratio of each tone (ξ_k) is calculated to be:

$$\xi_k = \frac{M_t}{(1 + 0.84K^{-2/3})\sqrt{1-M_{ax}^2}} \quad (109)$$

and is compared to the critical cutoff ratio ξ_c :

$$\xi_c = 1 - 0 \frac{1}{10} \exp \left\{ 23(1-M_{rel}) \right\} \quad (110)$$

Those harmonics K whose ξ_k is less than ξ_c are eliminated.

The final step in calculating combination tone noise is to correct for directivity, convert to sound pressure level and calculate the third octave spectrum by summing those harmonics contained in each band. The sound pressure level of the Kth harmonic at the angle γ_a and distance γ is given by the empirical equation:

$$SPL_{K,\gamma_a} = PWL_K - 20 \text{ Log}(r) + \sum_{i=1}^5 D_{\gamma_i} (\xi_K)^i - 3.85 \quad (111)$$

The coefficients D_{γ_i} are given in Table 2.

TABLE 2
Coefficient D_{γ_i} Values

γ_a (deg)	D_1					
	i=0	i=1	i=2	i=3	i=4	i=5
170	-475.92	1088.41	-832.01	207.78	0	0
160	-488.88	1164.19	-929.26	244.73	0	0
150	-491.57	1202.70	-987.87	269.86	0	0
140	- 14.22	7.71	2.85	0.	0	0
130	419.53	-1046.58	867.72	-238.17	0	0
120	12.96	- 43.78	53.02	- 20.72	0	0
110	-286.74	- 635.16	-432.44	105.71	-48.71	-26.11
100	181.25	- 411.47	295.32	- 67.81	0	0
90	1618.24	-3933.70	3133.88	-821.89	0	0
80	4033.55	-9869.94	7937.61	-2104.66	0	0
70	6613.32	-16167.20	12994.70	-3443.76	0	0

Turboshaft Engine Noise

The procedure for predicting turboshaft engine noise is entirely empirical, based on noise measurements made on several engines. The first step in the procedure is to determine the PNL at 500 feet to the side of the engine using the 'average' or 'loud' engine line of Figure 17. These lines are represented by the following equations:

$$\text{Avg: } \text{PNL}_{500} = 4.4 \text{ Log}(\text{horsepower}/10) + 79.0 + 10 \text{ Log} (N_e) \quad (112)$$

$$\text{Loud: } \text{PNL}_{500} = 5.8 \text{ Log}(\text{horsepower}/10) + 80.2 + 10 \text{ Log}(N_e)$$

$$N_e = \text{Number of engines} \quad (113)$$

The directivity index of Figure 18, derived from several engines, is used to correct the sideline PNL to the azimuth location required. Since most available engine data is presented in terms of octave band levels, the calculated value of PNL is first converted to an octave band spectrum using the curves of Figure 19. These are composite curves representing an average of several different engines, thus the calculated engine spectrum represents a reasonable estimate of the engine generated noise. For most aircraft, turboshaft engine noise contributes only very little to the final EPNL value, consequently the current method is deemed adequate for the purposes of this study. When a simple, more accurate prediction method becomes available it can easily be incorporated into the program.

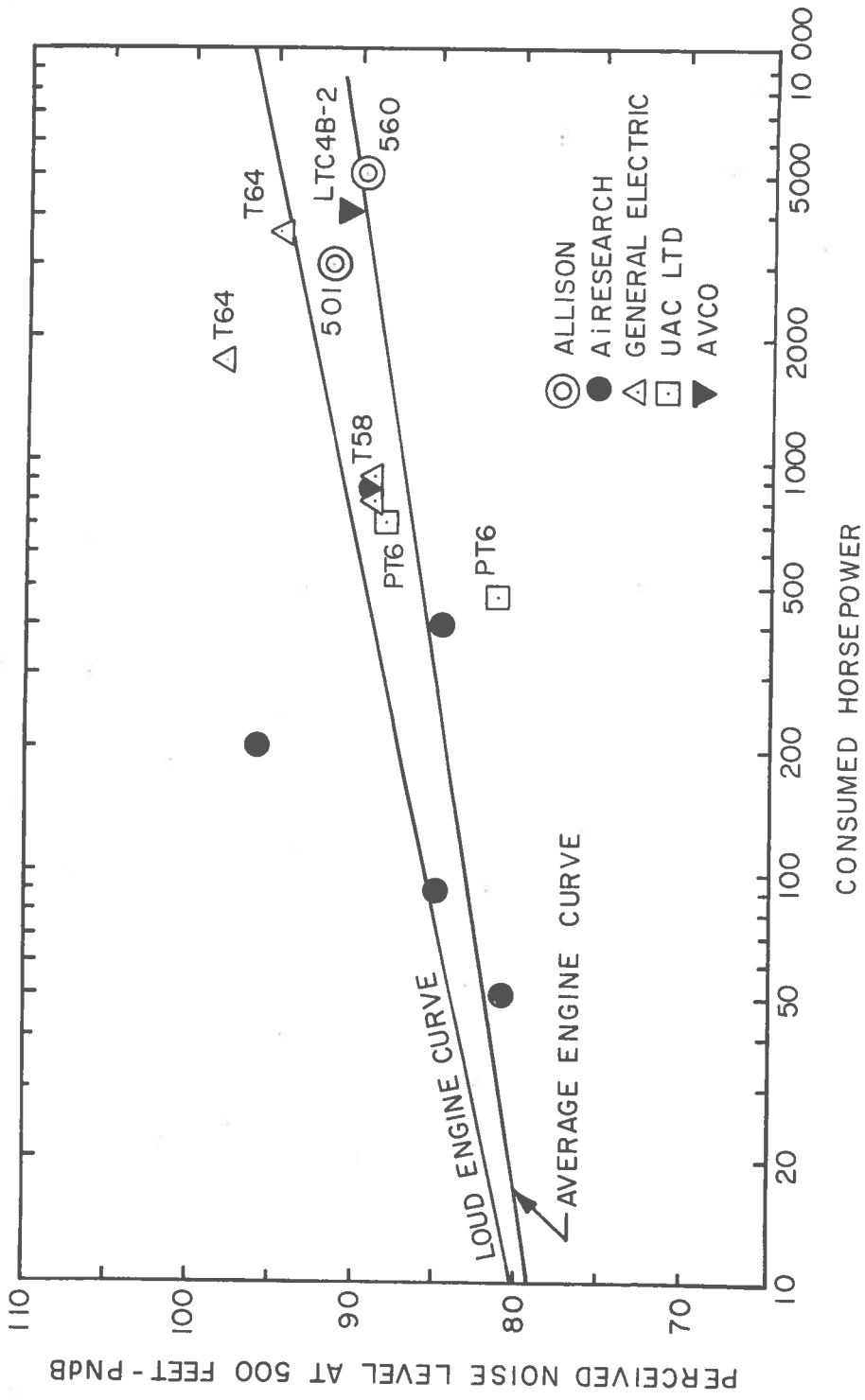


Figure 17. Derivation of Turboshaft Engine Noise Level

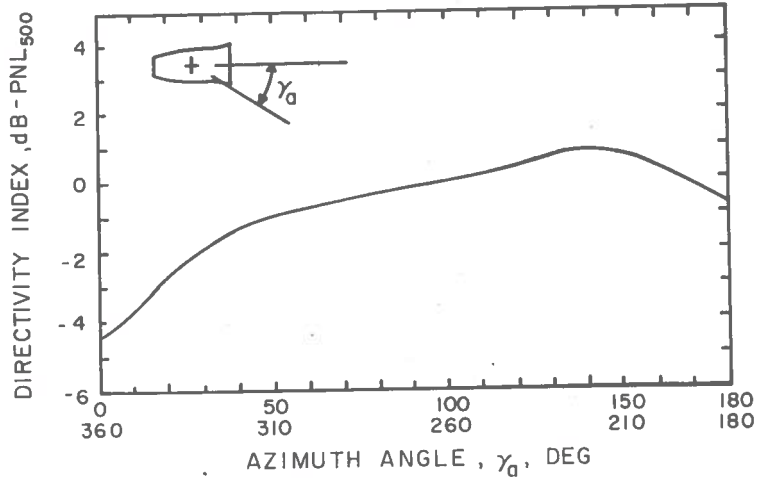


Figure 18. Turboshaft Engine Noise Directivity Index

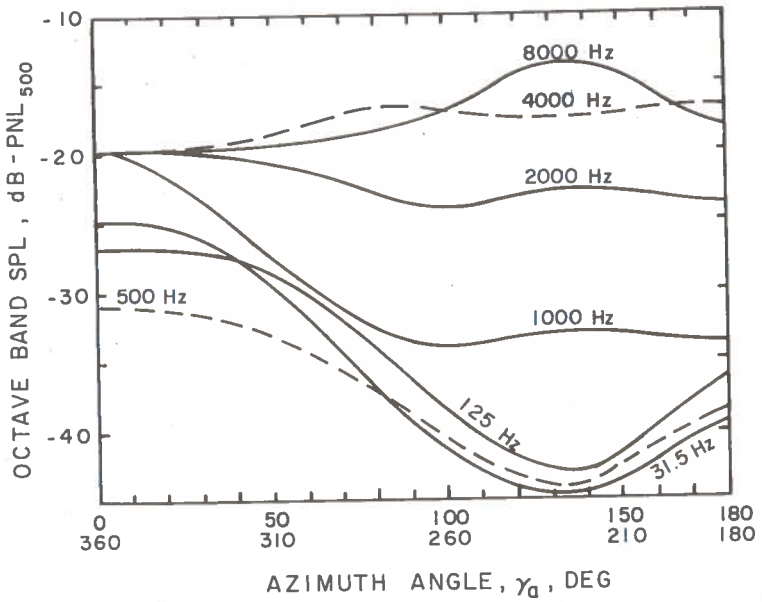


Figure 19. Turboshaft Engine Correction Factors to Determine Octave Band Spectrum

Jet Noise

Although jet noise was the subject of many studies several years ago the complexity of the subject is such that prediction of jet noise has yet to be represented accurately. The problem is further compounded in the case of direct lift jets or deflected jets where sound power levels, directivity, and spectrum can be significantly altered. However, in order to provide the V/STOL noise model with the ability to at least determine an order of magnitude estimate for those vehicles using jets the following empirically based prediction method for undeflected jets is included in the program.

According to Richards and Clarkson (Reference 32) the total acoustic power output from a subsonic jet is given as

$$PWL_j = 60 \text{ Log}(V_j) + 10 \text{ Log}(A) - 48. \quad \text{db ref: } 10^{-13} \text{ watt} \quad (114)$$

and for supersonic jet velocities as

$$PWL_j = 13.5 \text{ Log} \left\{ \frac{0.67wV_f^2}{g} \right\} + 78. \quad \text{db ref: } 10^{-13} \text{ watt} \quad (115)$$

where:

V_j = tg/w = exit velocity (ft/sec)

t = engine thrust (lb)

w = total weight flow (air + fuel) through engine (lb/sec)

g = acceleration due to gravity (ft/sec/sec)

A = nozzle area (sq. in.)

According to Beranek (Reference 27) the total acoustic power can be corrected for non-standard atmospheric conditions by

$$\Delta PWL = 10 \text{ Log} \frac{P_{a_o}}{P_{a_0}} + 40 \text{ Log} \frac{T_{j_0}}{T_{j_0}} - 35 \text{ Log} \frac{T_a}{T_{a_0}} \quad (116)$$

where: $T_{a_0} = 59.0^\circ\text{F}$

$P_{a_0} = 29.92 \text{ in Hg.}$

$T_{j_0} = \text{Jet tailpipe temperature for ambient conditions } T_{a_0}, P_{a_0}$

$P_a = \text{Ambient operating pressure (in Hg)}$

T_a = Ambient operating temperature ($^{\circ}\text{F}$)

T_j = Tailpipe temperature

Then the overall sound pressure level at a distance R feet from the jet (assuming hemispherical radiation) is given as

$$\text{SPL}_j = \text{PWL}_j - 10 \text{Log}(4\pi R^2) + 3 + \text{DI} \quad (117)$$

where DI is the azimuthal directivity index (shown in Figure 20) based on the data from Reference 31. The one-third octave band spectrum is determined from the overall level and the relative jet velocity using Figure 21 adapted from Reference 32. The relative jet velocity is the velocity of the jet relative to the surrounding air; thus if the aircraft is moving with velocity V_f the relative jet velocity, V_{rel} , is given as

$$V_{rel} = V_j - V_f \quad (118)$$

Attenuation

All sound, once generated, is attenuated by various mechanisms as it travels from source to observer. These mechanisms include spherical divergence, atmospheric absorption, ground absorption, and small-scale turbulence. Effects such as thermal and wind gradients and wind effects are not included because their existence and exact structure is never precisely known and cannot be predicted with reasonable accuracy.

Spherical Divergence

In an ideal medium the total sound power radiated by a point source far from any ground plane through an expanding spherical wave front remains constant over the surface of the sphere so that sound pressure levels are reduced by 6 dB for each doubling of a distance from the source. At sufficiently large distances from a helicopter in the air and out of ground effect, the helicopter will appear to an observer as a point source and the spherical divergence attenuation then follows the 6 dB per doubling of distance law. In the near field region where the physical dimensions of the source are not negligible so that sound radiated by the source reaches the observer from different directions and where non-propagating "hydrodynamic" pressure fluctuations cause the apparent sound level to be amplified, this attenuation law does not hold. Also, when the source or microphone is close to the ground, reflection effects

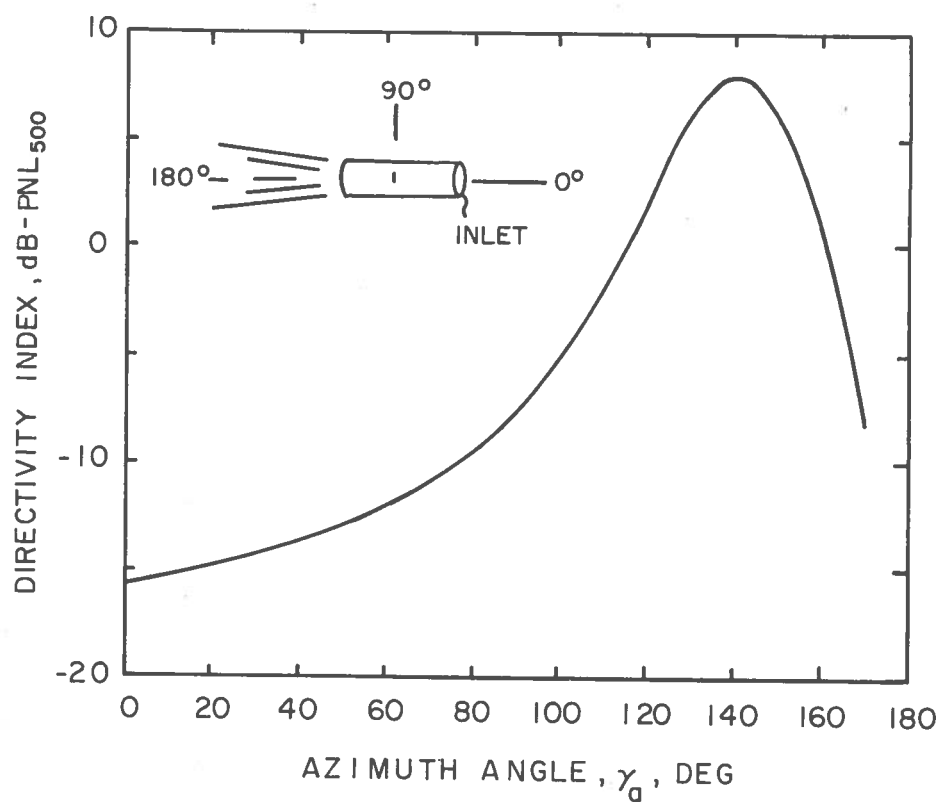


Figure 20. Directivity Index for Jet Noise

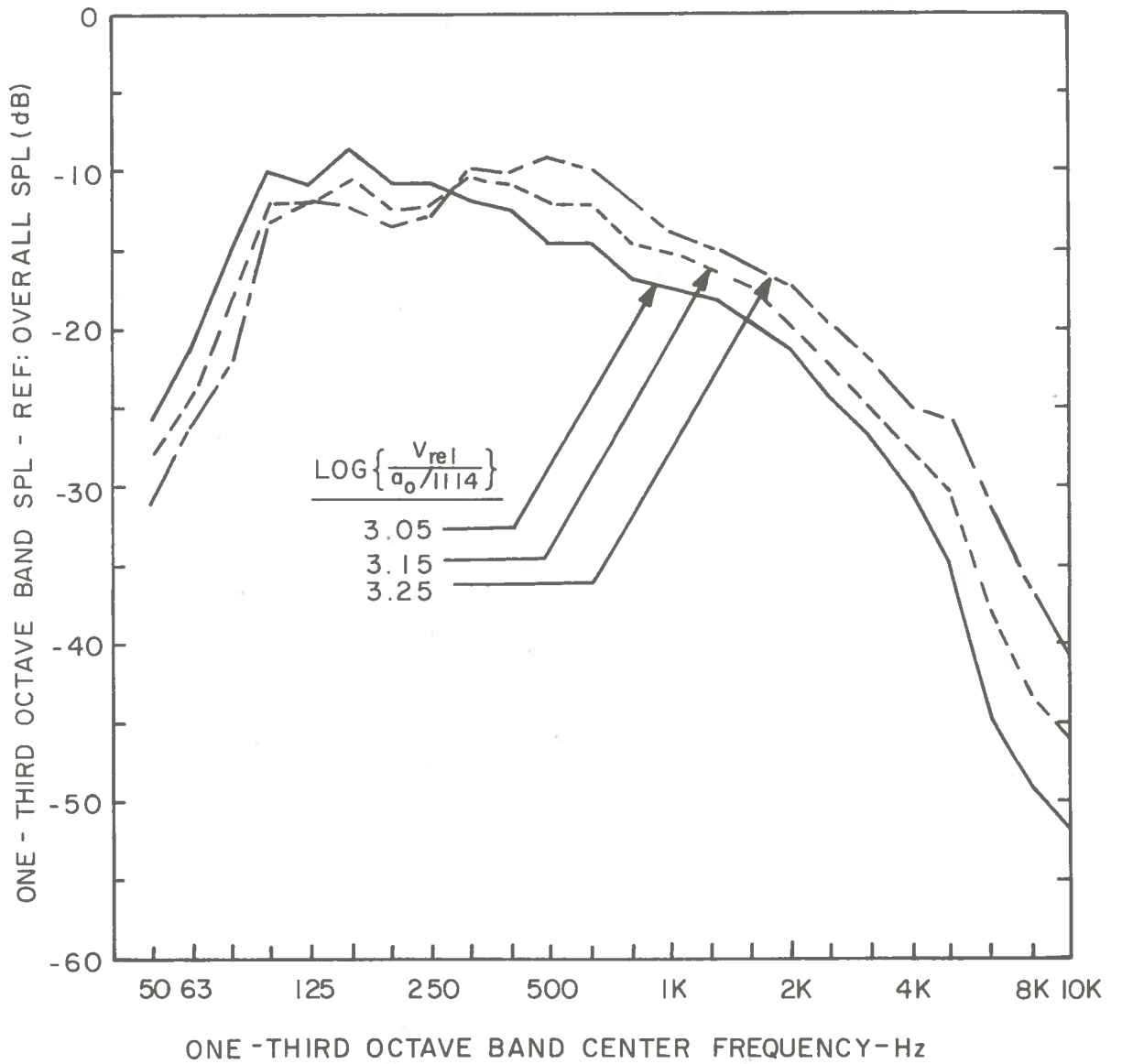


Figure 21. Jet Noise One-Third Octave Band Spectrum Shapes

cause interference between the direct and reflected waves producing large variations in the apparent sound pressure level. The computer program does not account for these near-field and reflection effects, thus it is restricted to the calculation of far-field sound levels for the vehicle out of ground effect. The program does, however, account for the far-field spherical divergence attenuation of 6 dB per doubling of distance based on the input information regarding the observer location.

Atmospheric Absorption

Attenuation of sound waves due to absorption by the air is composed of two parts, classical absorption due to viscous and heat conduction effects and molecular absorption. Of these two, only molecular absorption is important in the audible frequency range, classical absorption being about an order of magnitude less than molecular absorption at 10,000 Hz with increasing divergence for lower frequencies. Figure 22 shows both of these losses as functions of frequency.

The curves for molecular absorption a' of Figure 22 were derived from a new analytical/empirical formula adapted from Reference 21, which gives excellent agreement with experimental data and is based on the theory as discussed by Kenser (Reference 22). Figures 23 and 24 taken from Reference 21 show the agreement between the expression for a'_{mol} given as Equation (119) below and both laboratory and field experimental data taken from References 23 to 27. The molecular absorption calculated by the computer program is then given by the following expression as adapted from Reference 21:

$$a'_{mol} = a_{max} \left\{ \left[\frac{0.18f}{f_m} \right]^{-2} + \left[\frac{2(f/f_m)^2}{1+(f/f_m)^2} \right]^2 \right\}^{1/2} \quad (119)$$

where

$$a_{max} = 0.0078 f_m (T^*)^{-2.5} \exp(7.77(1-1/T^*)) \quad (119a)$$

$$f_m = (10 + 6600h + 44,400h^2)P^*/(T^*)^{0.8} \text{ Hz} \quad (119b)$$

$$h = \frac{h'}{7.57} \cdot \frac{T^*}{P^*} \text{ Percent mole ratio} \quad (119c)$$

h' = humidity in gm/m^3

P^* = pressure normalized to 14.7 psi

T^* = temperature normalized to 519°R (59°F)

f = frequency for which molecular absorption is being computed

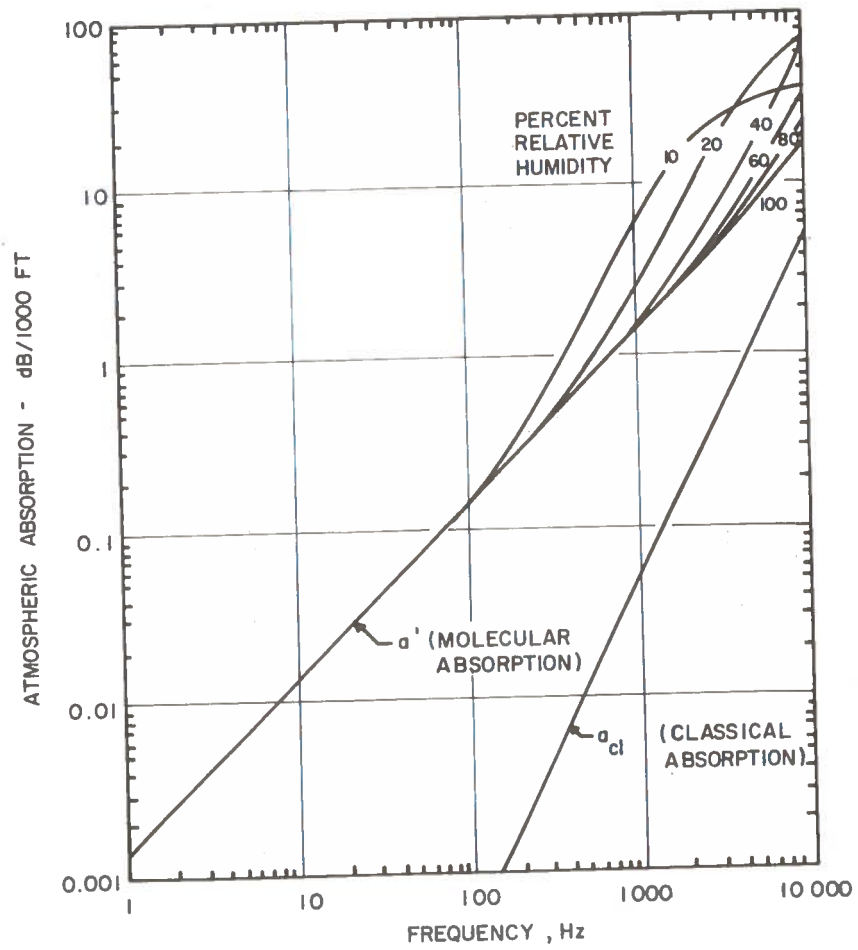


Figure 22. Atmospheric Absorption Losses for SLS Conditions at Several Relative Humidities (from Ref. 21).

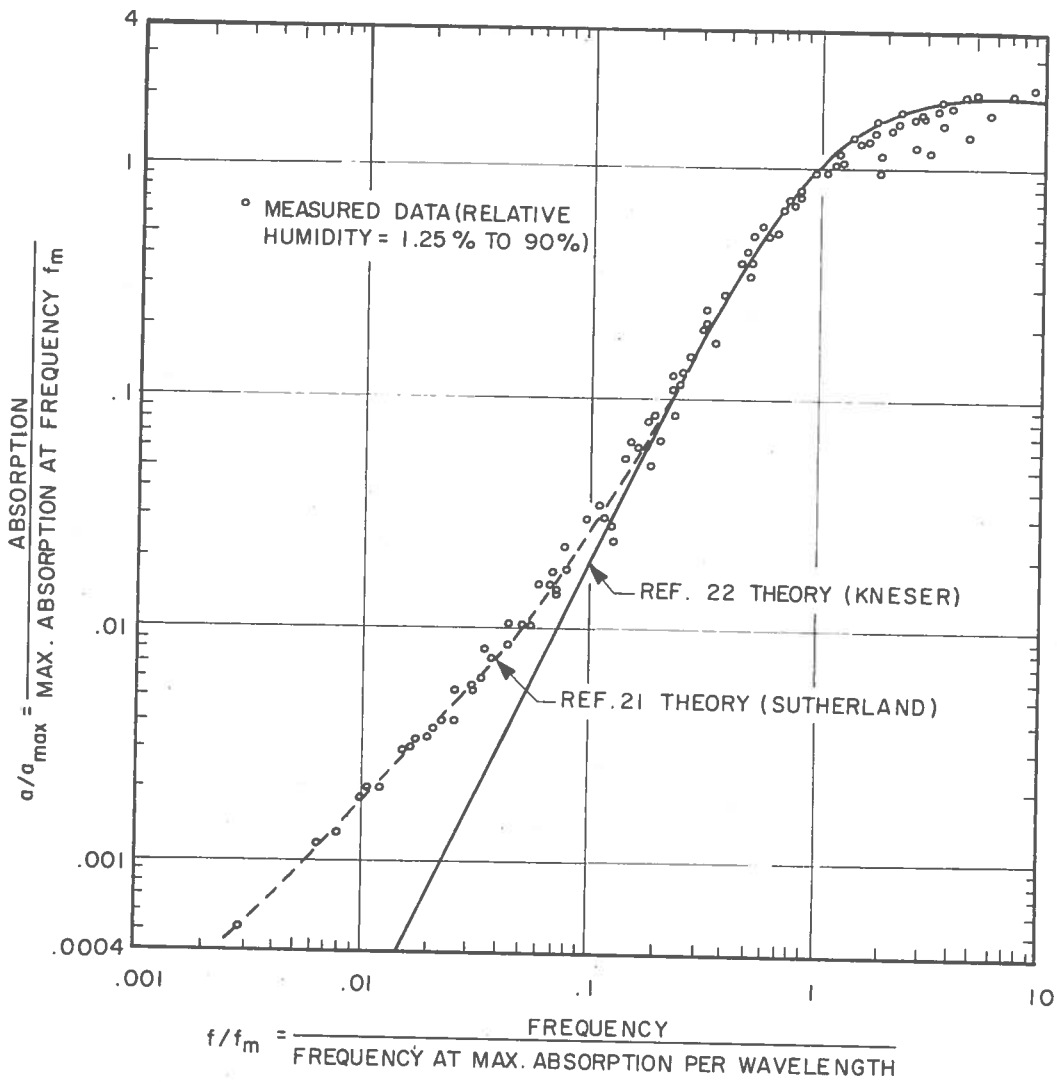


Figure 23. Comparison of Laboratory Measurements of Molecular Absorption Loss With Reference 21 and 22 Theories (Measured Data From Reference 23 and 24 Corrected for Classical Absorption Loss).

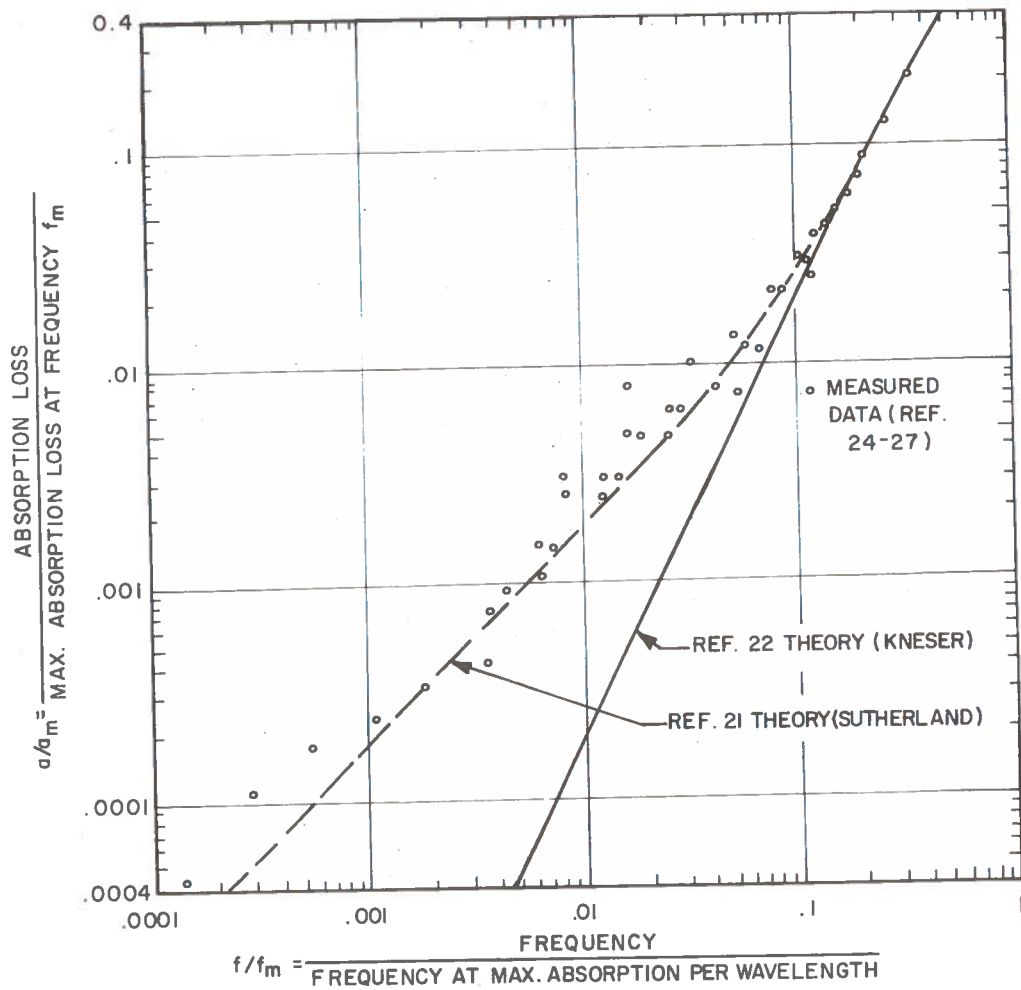


Figure 24. Comparison of Observed Air to Ground Absorption Loss With Reference 21 and 22 Theories. Adapted from Reference 21).

For the standard conditions of 14.7 psi and 59°F the Equations (119a-c) reduce as follows:

$$h' = 6.41 \text{ gm/m}^3 \text{ at 50\% relative humidity}$$

$$h = 0.847$$

$$f_m = 37,400$$

$$a_{\text{max}} = 292.0$$

and the equation used in the computer program to calculate molecular absorption becomes:

$$a'_{\text{mol}} = 292.0 \left\{ (4.81 \times 10^{-6} f)^2 + \left[\frac{1.43 \times 10^{-9} f^2}{1 + 7.14 \times 10^{-8} f^2} \right]^2 \right\}^{\frac{1}{2}} \quad (120)$$

dB/1000 ft

or

$$a'_{\text{mol}} = 292.0 \left(\frac{r'}{1000} \right) \left\{ (4.81 \times 10^{-6} f)^2 + \left[\frac{1.43 \times 10^{-9} f^2}{1 + 7.14 \times 10^{-8} f^2} \right]^2 \right\}^{\frac{1}{2}} \quad (121)$$

The program, then, computes the atmospheric attenuation (molecular absorption) for sea-level-standard conditions of temperature and pressure and for 50% relative humidity.

Ground Absorption

Of all attenuation losses, that due to ground cover is the least understood. Very little experimental data are available for either laboratory or field conditions. Those laboratory experiments which have been performed have produced insufficient results to verify the theory or to point out any theoretical inaccuracies. Field experiments have been performed, but they suffer from lack of accurate knowledge of atmospheric conditions and their fluctuations along the propagation path. Difficulty in separating the effects of unpredictable small scale turbulence and local wind and temperature gradients along the path from ground attenuation effects has further hampered the gathering of accurate field data. Pao (Ref. 28) has recently developed an analytical method to predict ground attenuation but it requires detailed knowledge of the ground cover not generally available. For these reasons and because the elevation angle between observer and aircraft for V/STOL-part operation is usually greater than about 7°, it was decided not to include ground absorption in the program.

Small Scale Turbulence

The propagation of sound waves is influenced by "small scale turbulence" in the atmosphere through a process of refraction. The overall effect may be one of attenuation or of augmentation depending upon the initial directivity pattern of the sound source. Basically, the scattering of an irregular

sound field will tend to cause an equalization of the acoustic intensity propagating in all directions at large distances from the source. It is the direct result of multiple refraction of the sound through patches of non-uniform sound velocity in the atmosphere which may be due to air velocity or temperature fluctuations. The effect will only be important when the acoustic wavelength is of the order of the atmospheric disturbance scale. In the case of rotor or propeller noise, turbulence scattering may be expected to cause results similar to that illustrated as an example in Figure 25 where the most important feature is the "filling-in" of the depressions in the directivity curves where theoretically, acoustic cancellation effects cause no sound to be radiated. Thus, from a practical standpoint turbulence scattering will only be of concern in considerations of the sound radiated at small angles above the rotor disc. The reason for this is that due to the analytical summations over very many blade airload harmonics together with the adoption of randomized phasing, the computed directivity contours are always "well rounded" with the single exception of a severe trough for the low frequency harmonics at about 5° above the plane of rotation. In this region scattering effects could be simulated by averaging the intensity over a finite area enclosing the minimum. This is exactly equivalent to the physical effects of scattering.

In a recent extensive study of rocket noise propagation (Reference 21) it was determined that the effects of scattering caused an average attenuation of the sound in the direction of maximum radiation of 0.5 dB per 1000 feet at frequencies above 60 Hz. This value decreased at lower frequencies reaching a minimum of 0.06 dB per 1000 feet below seven Hz. Now rocket noise is highly directional and these results reflect a scattering of sound away from the highly directional lobes. Elsewhere a reduction in absorption would be found. Helicopter noise is significantly less directional in character and lesser effects are to be expected. Consequently it is considered valid to ignore scattering effects, everywhere except for small angles of propagation above the rotor plane.

Calculation of PNL, PNLT, EPNL, and dBA Levels

After the vehicle one-third octave band noise spectrum has been calculated for each point along the flight path (ie. - each increment of time) and corrected for the attenuations described above the time history of Perceived Noise Level, Tone corrected (PNLT) is calculated by converting the noise spectrum at each time increment to its' corresponding PNLT value with the methods described below. The Effective Perceived Noise Level (EPNL) is calculated for the observer location in question from the PNLT time history. For comparison purposes, the A-weighted sound level (dBA) is also calculated at each time increment.

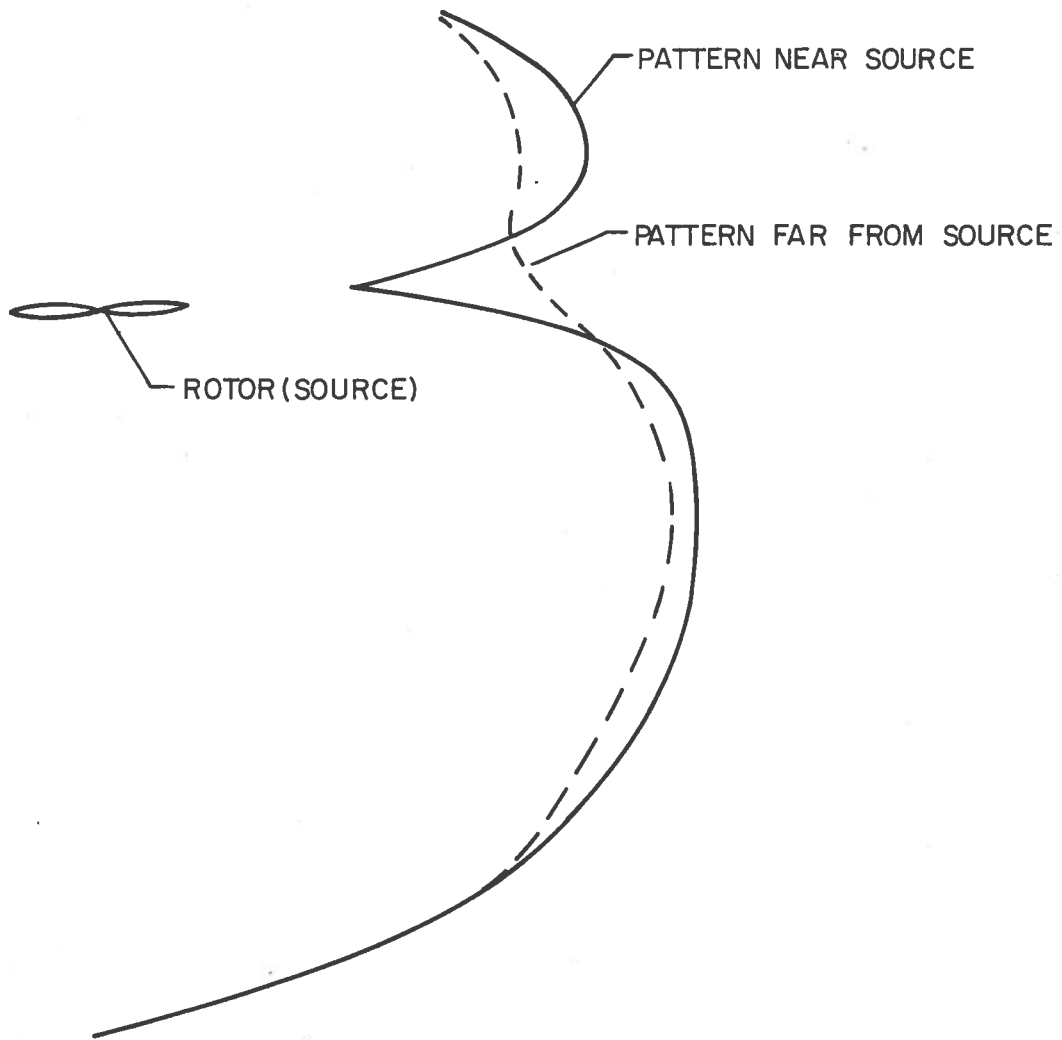


Figure 25. Effect of Small-Scale Turbulence Scattering on Source Radiation Pattern

Perceived Noise Level

The Perceived Noise Level is calculated at each time increment from the calculated one-third octave band spectrum by the SAE method of Reference 29. The Reference 29 noy tables, however, are replaced by the mathematical formulation presented by Pinker (Ref. 30) and referenced by Sperry (Ref. 31). This formulation allows direct calculation of the noy value for each band of noise rather than requiring the use of noy tables, hence significantly less computer storage is required.

After each one-third octave band from 50 Hz to 10,000 Hz has been converted to its' corresponding noy value, the value of N_T is computed:

$$N_T = 0.15 \sum_{i=1}^{24} \text{Noy}_i + 0.85 N_{\max} \quad (122)$$

where N_{\max} is the maximum of all the 24 noy values. The PNL is then calculated:

$$\text{PNL} = 40 + 33.3 \text{Log}(N_T) \quad (123)$$

Tone Corrected Perceived Noise Level

Because the calculation of EPNL requires the time history of tone corrected Perceived Noise Level, a tone correction that is applied to the PNL is computed at each time increment. The tone correction is an attempt to account for any additional annoyance resulting from the presence of pure tone components in the spectrum. The calculation method, contained in Appendix A, is not exact since it uses adjacent one-third octave band levels to establish the presence of a tone rather than using a narrow band analysis of the spectrum. Nonetheless it is the only method available and is the one recommended by the FAA (Reference 31), hence it is the one incorporated in the program.

Effective Perceived Noise Level

The Effective Perceived Noise Level is computed by adding a duration correction to the maximum PNL value. The duration correction is calculated by integrating the PNL time history between the two points that are 10 dB down from the maximum PNL. In practice the integration becomes a summation because there generally is no convenient mathematical representation for the PNL time history. This summation is given by Sperry (Ref. 31) as:

$$D = 10 \text{Log} \left\{ (1/T) \sum_{k=0}^{d/\Delta t} \Delta t \text{antilog} \left[\frac{\text{PNLT}(k)}{10} \right] \right\} \text{PNLT}_{\max} \quad (124)$$

where D = duration correction in dB
 T = normalizing time constant (sec.)
 t = time increment (sec.)
 d = duration time defined by the 10 dB-down points (sec.)

For the value of T = 10 sec given by Sperry ³¹:

$$D = 10 \text{ Log} \left\{ \left(\frac{\Delta t}{10} \right) \sum_{k=0}^{d/\Delta t} \text{antilog} \left[\frac{\text{PNLT}(k)}{10} \right] \right\} - \text{PNLT}_{\text{max}} \quad (125)$$

The generally recommended value for Δt is 0.5 seconds, however the program allows other values of Δt to be input in order to conserve computer time. Since the computed PNL T time history usually varies smoothly with time, little accuracy is sacrificed if values of t larger than 0.5 seconds are used. The EPNL value can now be defined:

$$\text{EPNL} = \text{PNLT}_{\text{max}} + D \quad (126)$$

or combining Equations (125) and (126):

$$\text{EPNL} = 10 \text{ Log} \left\{ \left(\frac{\Delta t}{10} \right) \sum_{k=0}^{d/\Delta t} \text{antilog} \left[\frac{\text{PNLT}(k)}{10} \right] \right\} \quad (127)$$

A-Weighted Sound Level

The A-Weighted Sound Level is a single number rating of a sound spectrum which attempts to simulate the way the human ear hears the sound. It is a measure of the total energy of the spectrum after the spectrum has been passed through a "filter" whose shape is that of Figure 26. In the program the calculated one-third octave spectrum is corrected to the A-Weighting shape by applying the correction numbers of Table 3 (taken from Figure 26) to each band. The A-weighted sound level is then the energy sum of all of the corrected band levels:

$$\text{dBA} = 10 \text{ Log} \sum_{j=1}^{24} \text{antilog} \frac{1/3 \text{ OL}_j + \text{CORR}_A}{10} \quad (128)$$

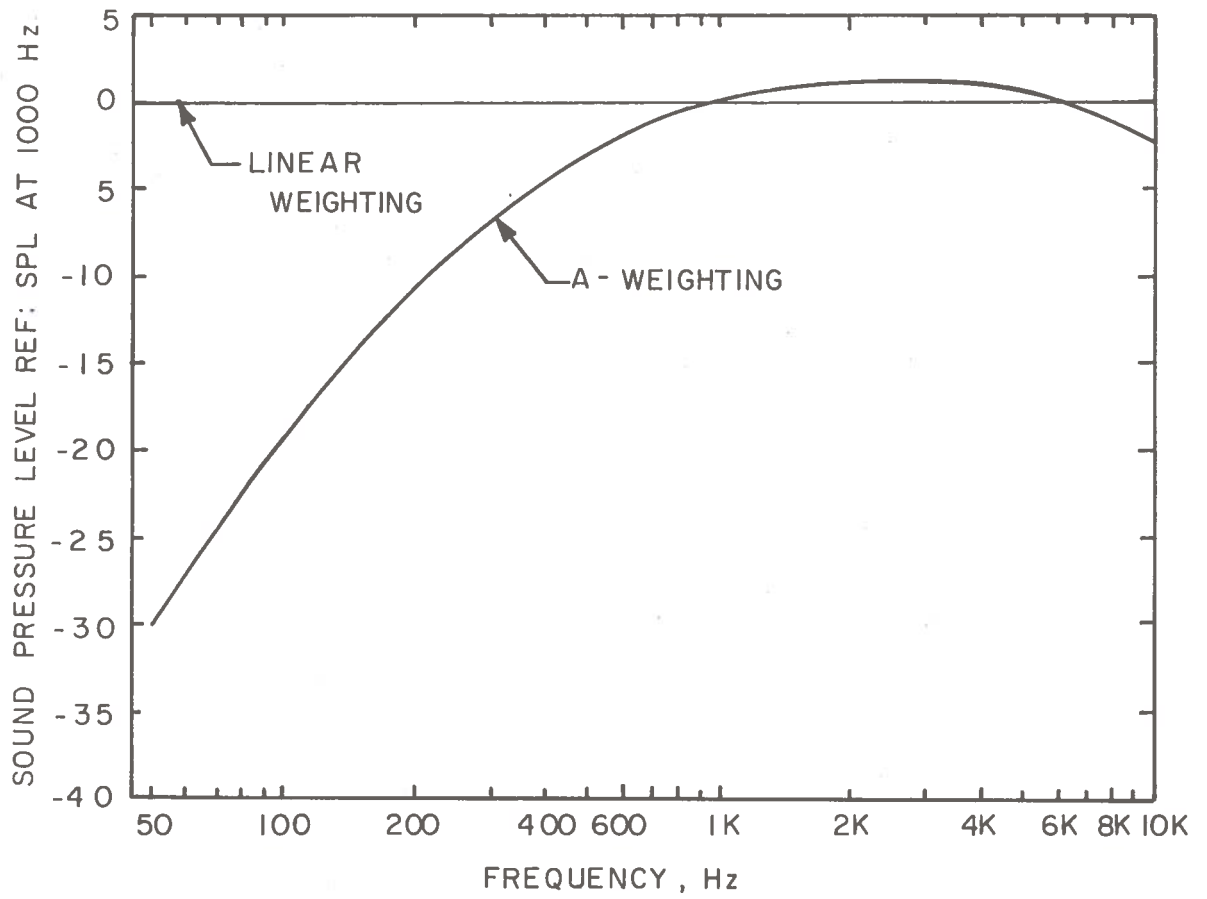


Figure 26. A-Weighting Frequency Spectrum

TABLE 3
A-Weighting Correction Numbers For 1/3-Octave Bands

ONE-THIRD OCTAVE BAND Hz	CORR _A dB	ONE-THIRD OCTAVE BAND Hz	CORR _A dB
50	-30.2	800	-0.8
63	-26.1	1000	0.0
80	-22.3	1250	0.5
100	-19.1	1600	1.0
125	-16.2	2000	1.2
160	-13.2	2500	1.2
200	-10.8	3150	1.2
250	-8.6	4000	1.0
315	-6.5	5000	0.5
400	-4.8	6300	-0.2
500	-3.3	8000	-1.1
630	-1.9	10000	-2.3

COMPUTER PROGRAM

The computer program developed from the component noise calculation procedures is described in detail in Appendices B, C, and D. A simplified flow diagram of the main program and Subroutine ACPNLT is shown in Figures 27 and 28. Briefly the main program (Figure 27) loads the necessary input data for each flight path segment, calculates the PNL, PNLT, and dBA time history at the observer locations, and calculates the EPNL value. Subroutine ACPNLT calls the required noise component subroutines, accumulates a complete one-third octave spectrum, adjusts the spectrum for atmospheric attenuation, and calculates the associated PNL, PNLT, and dBA values. A more detailed description follows.

Main Program Operation

The Program begins (box M.1 of Figure 27) by loading data for flight segment 1 via the LOADER Subroutine. At this point all of the component operating parameters for flight segment 1 (Figure 29), whether a landing or takeoff, are entered along with the complete flight path description and observer location. Table 4 lists all of the possible input. The loader subroutine stores the input data in pre-designated COMMON locations indicated by the column of Table 4 titled Input Sequence Location, thus the first COMMON location is occupied by the variable SAZ while the 25-th location is occupied by the variable DIA. On input the data are assigned to their respective locations, not sequentially stored; thus only necessary data need be entered.

After data for the first flight segment has been entered, 100 values of X, Y, Z (the observer coordinates relative to the aircraft for each time increment) are calculated (box M.2) along with the slant range (minimum distance from observer to aircraft), and the increment number of the end point of each flight segment. In the box M.3 the field point (K), flight segment (N), observer location (L), and segment end position (IK) indices are initialized and all the input variables in COMMON are printed out in box M4.

At this point SUBROUTINE ACPNLT is called (box M.5) and it returns the PNL, PNLT, and dBA values at the L-th observer location when the aircraft is at a location (X_k, Y_k, Z_k) on the flight path. These noise values are stored (in box M.6) and (in box M.7) they are compared with previously calculated noise values to determine the maximum value, which is stored for future use. The test in box M.8 cycles the program back to box M.5 to calculate PNL, PNLT and dBA values for additional observer locations up to a value IFPT (maximum of 10). When the observer location loop is satisfied, control passes to box M.9 where L (the observer location index) is reset to 1, K (the field point index) is increased by one, and a PNLT value that is 10 dB less than the maximum PNLT value at the IFPT-th observer location is computed (DUM).

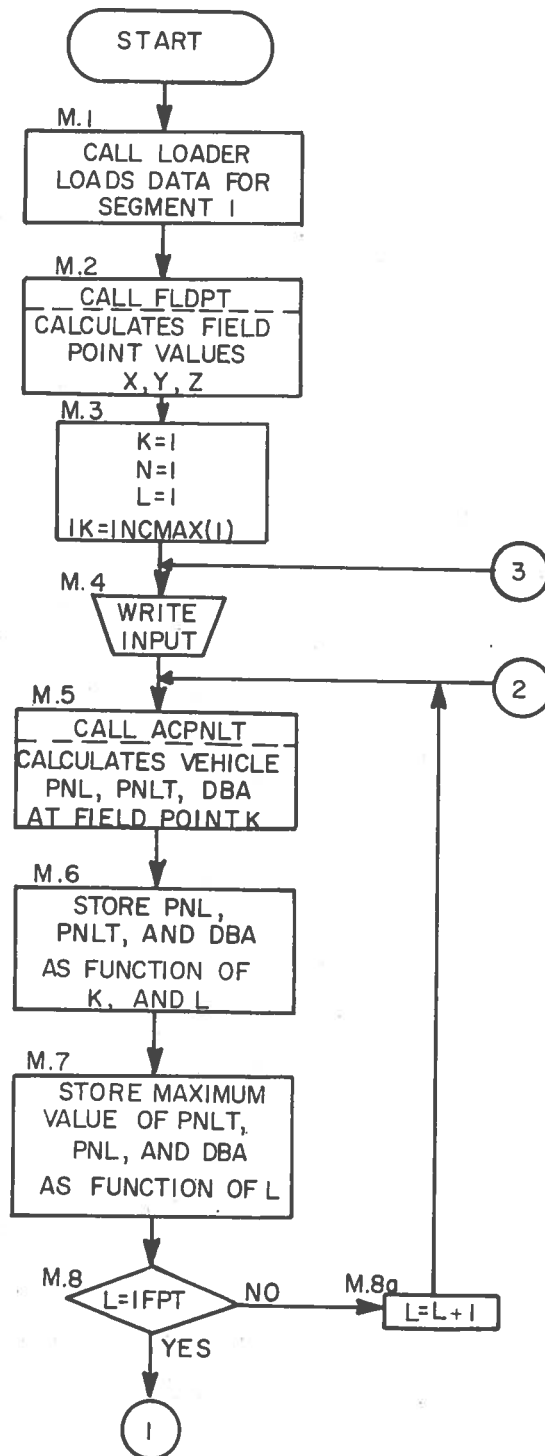


FIGURE 27. Main Program Flow Chart.

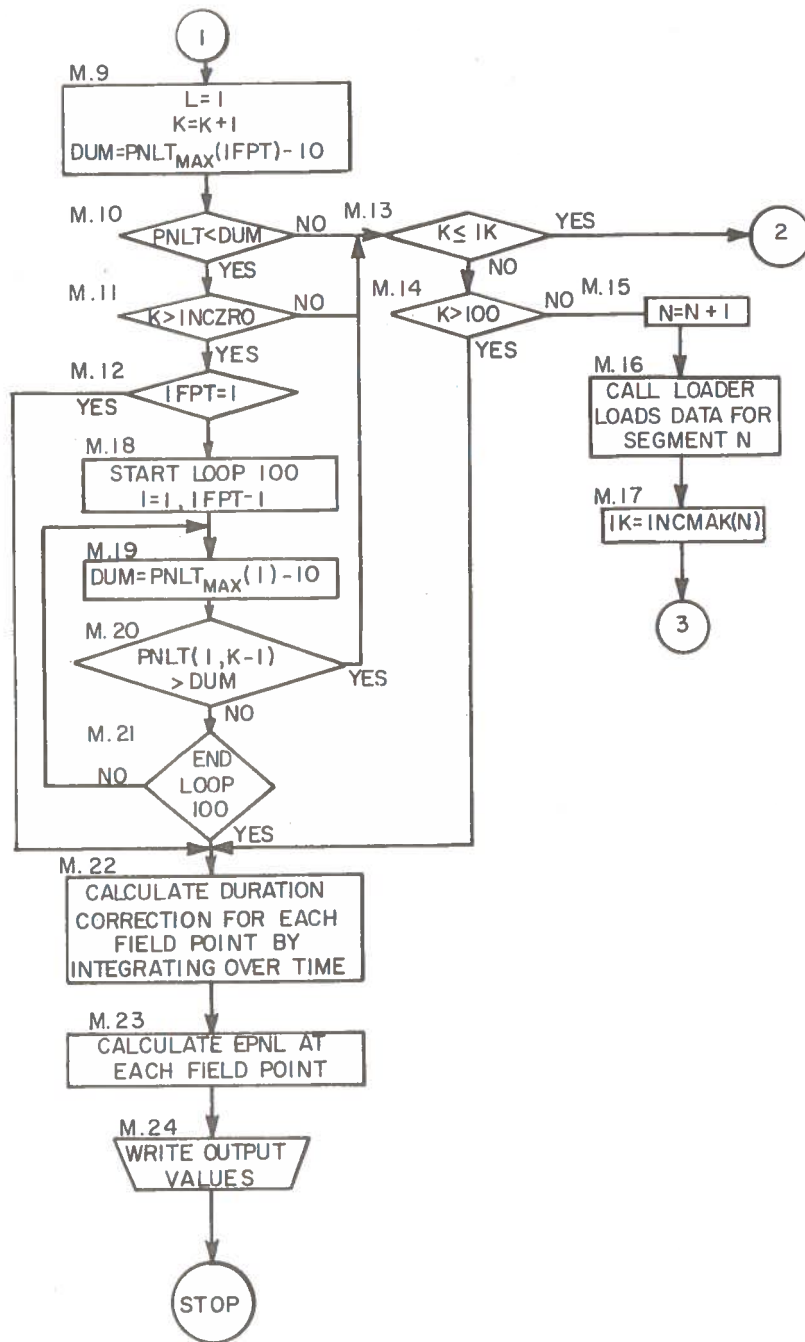


FIGURE 27. Continued

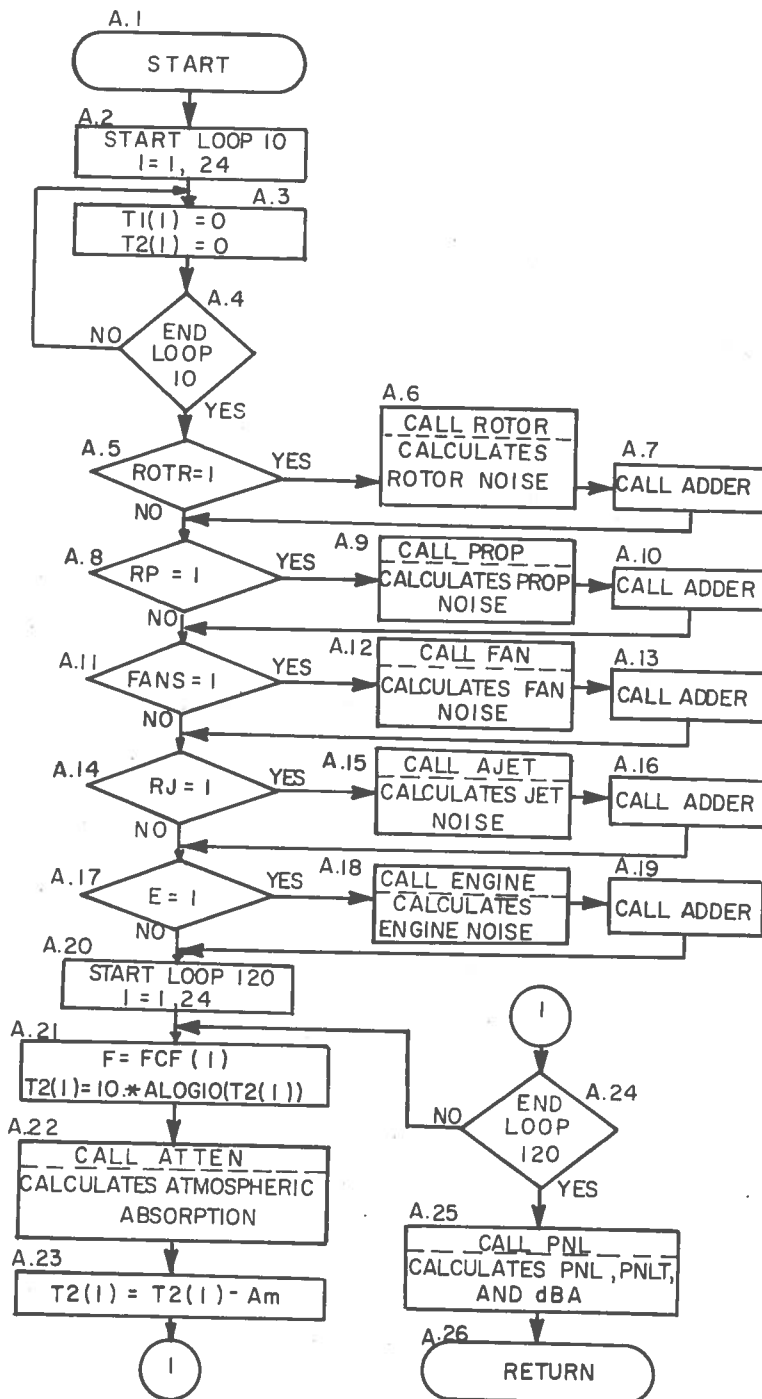


FIGURE 28. Subroutine ACPNLT Flow Chart.

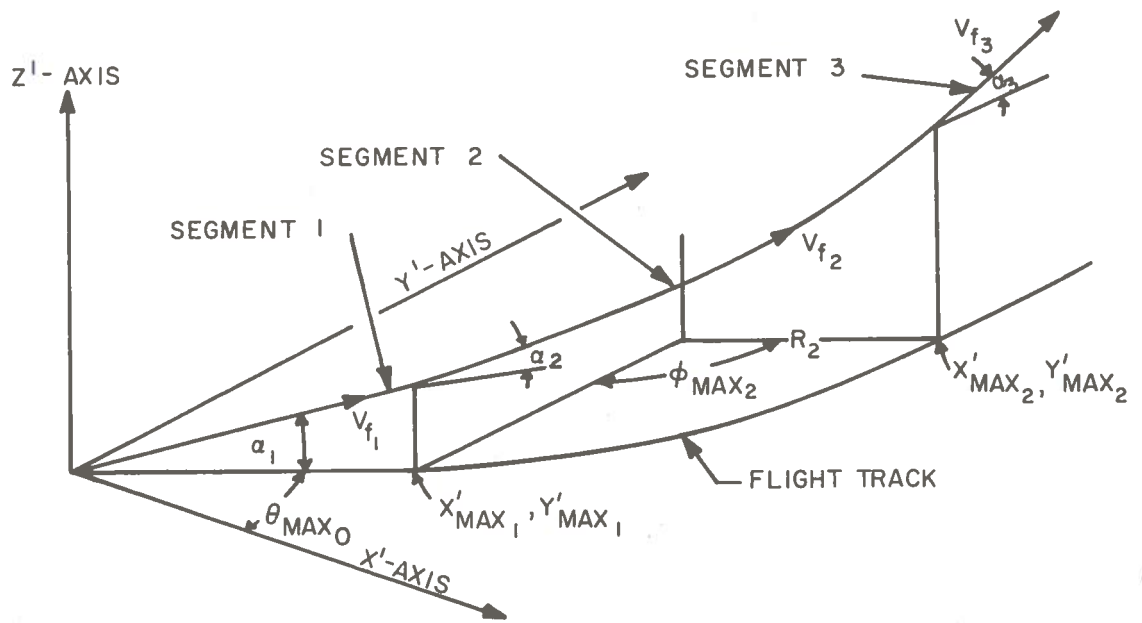


Figure 29. Definition of Flight Path Segments

The most recently calculated value of PNLTL is compared with DUM in box M.10 and if it is less than DUM and if K is greater than INCZRO (i.e. the aircraft has passed the last observer) control is passed on box M.12. If either criteria is false control passes to box M.13 where the current value of K is compared to the increment number corresponding to the end point of the N-th flight segment, IK. If $K \leq IK$ the program is cycled back to box M.5. If K is greater than IK (i.e. - the vehicle has passed on to flight segment N + 1) and if K is not greater than 100 (box M.14) the flight path segment index N is increased by one (box M.15) and any new noise component parameter values for the new flight path segment are loaded (box M.16). Only those parameters that change or those that are new need be entered since all old values are retained. In the event that no parameters change from segment N to segment N + 1 one dummy variable must be loaded since the LOADER subroutine is called each time the segment changes. In box M.17 IK is now set equal to the increment number of the end point of the new segment and control is cycled back to box M.4 where all the input variables in COMMON are printed out again.

Control is received at box M.12 when the calculated value of PNLTL is more than 10 PNdB down from the peak and the aircraft has passed the last observer. If the calculation is only for one observer location (IFPT=1) control is passed to box M.22. If there is more than one observer control passes to a loop (boxes M.18 - M.21) that assures there is a point which is at least 10 PNdB down from the maximum PNLTL at each observer location. If not, control is passed back through box M.13 for further calculation. If all the 10 PNdB down points exist, control passes to box M.22 where the integrated duration correction is calculated at each observer location and then to box M.23 to calculate the EPNL value at each observer. In box M.24 all of the calculated values are printed out.

Subroutine ACPNLTL Operation

Subroutine ACPNLTL is the primary subroutine because it controls the calculation of the vehicle spectrum and associated PNL, PNLTL, and dBA values. Control is received from MAIN in box A.1 (Figure 28) and passes to the loop (boxes A.2 - A.4) which initializes the two dummy spectrum arrays T1 and T2. If the calculation is to include rotors (ROTR=1) box A.5 transfers control to box A.6 which returns in array T1 a one-third octave band spectrum for the rotors. In box A.7 the calculated spectrum (array T1) is added to the spectrum in array T2 (which is used to accumulate the total vehicle spectrum). In box A.7 array T1 simply is transferred to array T2 because this is the first call to the subroutine and T2 has been initialized. Control passes to box A.8 (either directly from A.5 or through boxes A.6 and A.7) where a similar test and sum accumulation takes place for propeller noise (boxes A.8 - .10), assuming propellers are included. Similar cycles take place for fans (boxes A.11 - A.13), jets (boxes A.14 - A.16) and engines (boxes A.17 - .19).

The T2 array now contains the one-third octave spectrum of the complete vehicle and control passes to box A.20. This begins a loop to convert each one-third octave band sound pressure to sound pressure level (box A.21), to calculate the atmospheric attenuation at the band center frequency F (box A.22), and to correct each bands' SPL for this attenuation (box A.23). When these corrections have been made the PNL, PNLT, and dBA values of the spectrum are calculated in box A.25 and returned to MAIN in box A.26.

Users Manual

1. Determine the aircraft configuration and operating parameters. Use Forms 3 through 7 at the end of this section to tabulate the necessary values.
2. Prepare on X', Y', coordinate paper the flight track on the ground of the flight path. The flight path can consist of up to 50 straight line and helical segments. When two adjacent segments are straight lines the only restriction is that they be colinear because all turns must be accomplished by helical segments. Figures 30 and 31 demonstrate an example case (additional sample cases are presented in Appendix B). The origin of the X', Y' coordinate system is at the start of takeoff roll or at the end of ground roll; the X' axis need not be in the direction of the runway. Note that segments are numbered in increasing order starting with the segment closest to the origin, regardless of whether the flight is a takeoff or landing and that the last segment (highest segment number) must be straight line.
3. Using the flight track diagram (Figure 31) enter the required flight path information on Form 1 (Figure 32 at end of this section), and on Form 1A (Figure 33) if there are more than 25 flight path segments. Figure 32 shows the Form 1 filled out for the example of Figure 31. When the segment is straight line no values are entered for ϕ_{max} and RADIUS; for helical segments no values are entered for X'_{max} and Y'_{max} . Note that α_n is the angle of climb or descent, measured from the ground plane. The value of ϕ_{max} is entered as positive for counterclockwise turns and as negative for clockwise turns. The values of X'_{max} and Y'_{max} are estimates of the end point coordinates of straight line segments; they will be changed by the program if they disagree with the end points calculated by the program.

4. Prepare a Form 2 (Figure 34) for the first flight path segment. Include on this form all of the information from Form 1 (and 1A) and Forms 3-7 as applicable. Also include the primary observer coordinates (X'_{ob} and Y'_{ob}), the angle that the first flight track makes with the X' axis (θ_{max_0}) if the first segment is straight, the altitude (A_0) at the origin of the X' , Y' coordinate system (e.g. - hover altitude before takeoff for a helicopter), the time increment (t_{inc}) to be used between successive aircraft locations on the flight path, and the number of total observer locations (ANMFPT). Figure 31 shows how the additional observer locations will be determined. List on Form 2 only those propulsion components and their operating parameters actually used on segment 1. Figure 34 shows Form 2 filled out for segment 1 of our sample case (assumed to be a compound helicopter with propellers for auxiliary propulsion).

5. Prepare a Form 2 for each additional flight segment. Note that only those parameters that change from segment to segment or that are new are entered; however, if no parameters change a dummy input will be required for the segment since the program will attempt to read in data for every segment. This can be done by repeating a variable from the previous segment (as is done in the example case - see Figure 35), or by assigning a value to a variable not used in the particular case. Figures 35 through 38 show Form 2 filled out for our example case. In this example the aircraft is in the helicopter mode (rotors only) for segments 1 and 2 and no parameters change from segment 1 to segment 2. On segment 3 the propellers are operating and parameters change from segment 3 to 4 to 5.

6. Prepare the input data cards using the information from the FORM 2's and the coding format sheet shown in Figure 39. The Figure 39 format is that used by the LOADER subroutine to load data into the specified COMMON locations. Referring to Figure 39, column 1 is reserved for a minus sign which tells the loader to stop reading data, thus the last data card for each flight segment must contain a - in column 1. Column 2 tells how many data points (up to 5) are contained on the card and columns 3-6 indicate into which COMMON location the first data field is placed (additional data fields on the card are sequentially placed after the first)

Figure 40 shows the coding form filled out for the entire example case. The data for segment 1 is contained on cards 1 through 15, segment 2 on card 16, segment 3 on cards 17 through 21, segment 4 on cards 22 and 23, and segment 5 on cards 24 and 25. Card 7, for example, puts the value 2000. in location 80, 0. in location 81, and 5000. in location 82. Card 15 is the last card of segment 1 (- in column 1) and it puts the value 1. in location 417, puts zeros in locations 418, 419, and 420, and puts 1. in location 421.

7. Program Operation.

The program is set up such that e^+ times data for all segments may not be read and used. When the noise (PNLT) at the primary observer (X'_{ob} , Y'_{ob}) is 10 PNdB_t down from the maximum level and the aircraft has passed the observer, the calculation of further PNL_T values is halted and the EPNL values are calculated. Since the 10 dB down point may be reached before the aircraft reaches the last flight segments the data cards for these segments will be ignored.

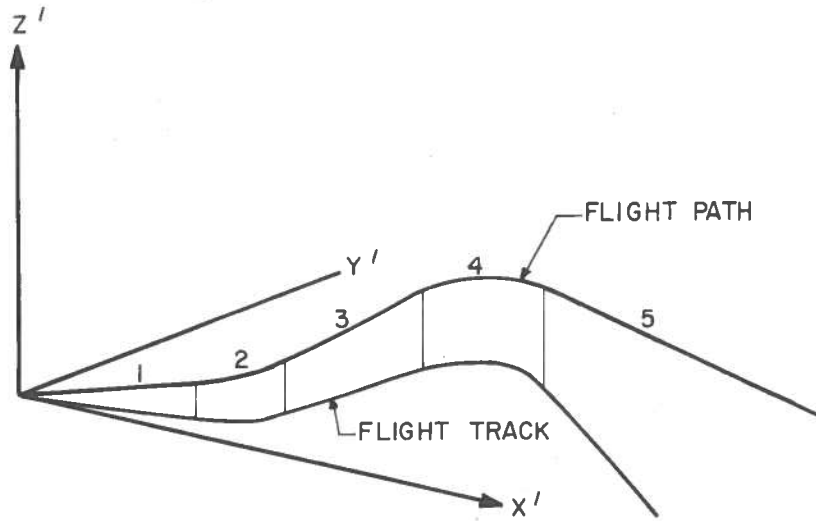


Figure 30. Example Take-off Flight For V/STOL Noise Model

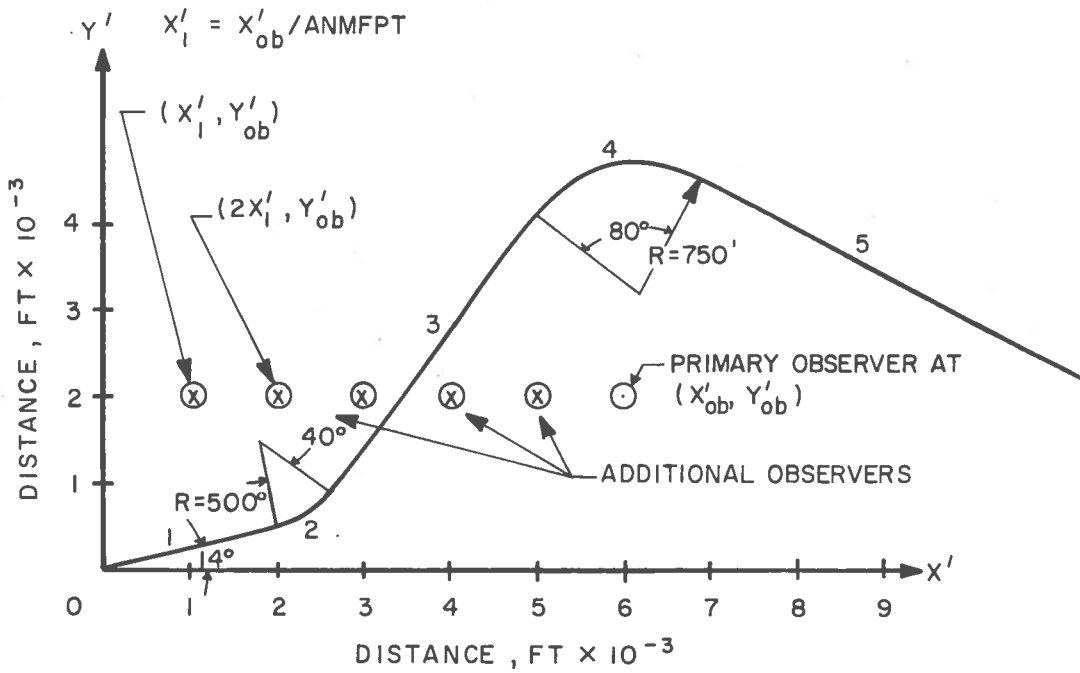


Figure 31. Example Take-off Flight - Flight Track

TABLE 4

V/STOL VEHICLE NOISE PREDICTION PROGRAM INPUT PARAMETERS			
Veri- able	Program Name	Description	Input Sequence Location
a_o	SAZ	Speed of sound (ft/sec)	1
-	SEG	Number of flight path segments (up to 50)	2
	FLYTYPE	Takeoff = 1. Landing = 2.	3
<u>HELICOPTER ROTOR PARAMETERS</u>			
k_r	RCASE	Main rotor harmonic loading factor	4
η_r	RETA	Main rotor blade radial loading station (%R)	5
B_r	RBIGB	Number of main rotor blades	6
R_r	RBIGR	Main rotor radius (ft)	7
Ω_{N_r}	ROMEGR	Main rotor rotational speed (rpm)	8
i_{d_r}	RSID	Main rotor disk incidence angle (degrees)	9
C_r	RCHORD	Main rotor blade chord (inches)	10
T_r	RTHRUS	Main rotor thrust (lb)	11
Q_r	RTORQ	Main Rotor torque (lb-ft)	12
β_r	RBETA	Main rotor coning (degrees)	13
k_t	TCASE	Tail rotor harmonic loading factor	14
η_t	TETA	Tail rotor blade radial loading station (%R)	15
B_t	TBIGB	Number of tail rotor blades	16
R_t	TBIGR	Tail rotor radius (ft)	17
Ω_{N_t}	TOMEGR	Tail rotor rotational speed (rpm)	18
i_{d_t}	TSID	Tail rotor disk incidence (degrees)	19
C_t	TCHORD	Tail rotor blade chord (inches)	20
T_t	TTHRUS	Tail rotor thrust (lb)	21
Q_t	TTORQ	Tail rotor torque (lb-ft)	22
β_t	TBETA	Tail rotor coning (degrees)	23

TABLE 4 (Cont'd)

Variable	Program Name	Description	Input Sequence Location
<u>PROPELLER PARAMETERS</u>			
P_p	PPWR	Propeller Shaft Power (hp)	24
D_p	DIA	Propeller diameter (ft)	25
B_p	BIGB	Number of propeller blades	26
Ω_p	RPMP	Propeller rotational speed (rpm)	27
-	ANMPRP	Number of propellers	28
c_p	CHORDP	Propeller mean blade chord (ft)	29
<u>TURBOSHAFT ENGINE PARAMETERS</u>			
P_e	HPENG	Engine power output (hp)	386
-	SLEVEL	Engine noise level (1 = Average, 2 = Loud)	387
-	ANENG	Number of engines	388
<u>FAN AND FAN ENGINE PARAMETERS</u>			
D_t	DIAT	Fan tip diameter (inches)	389
D_H	DIAH	Fan hub diameter (inches)	390
B_f	B	Number of fan blades	391
-	BPR	Bypass ratio	392
C_t	CHORD	Fan blade tip chord (inches)	393
D_{E_t}	DDDXT	Tip diameter gradient (in/in)	394
D_{E_h}	DDXH	Hub diameter gradient (in/in)	395
R_s	RS	Blade suction surface radius of curvature (in)	396
σ_ϕ	SIGPHI	Standard deviation of blade tip metal angle (rad)	397
L	DL	Inlet duct length (ft)	398
Ω_f	RPM	Fan rotational speed (rpm)	399
m	SPAF	Specific airflow rate (lb/sec/ft ²)	400

TABLE 4 (Cont'd)

Vari- able	Program Name	Description	Input Sequence Location
M _t	XMXTIP	Tip axial Mach number	401
P _r	PR	Fan pressure ratio	402
-	DF	Fan blade diffusion factor	403
T ₂	TT2	Ambient inlet temperature (°F)	404
P ₂	PT2	Ambient inlet pressure (in. Hg)	405
α _f	ALFA	Inclination of fan to horizontal (+90°=vertical)	406
-	FN	Number of fans	407
	COMB	Control factor to permit skipping of combination tone calculation (0 = No Calc.)	408
<u>JET ENGINE PARAMETERS</u>			
t	THRUST	Static thrust (lb)	409
W	WTFL	Gas weight flow through engine (lb/sec)	410
a _j	AREAJ	Nozzle area (sq. in)	411
P _a	PSUBA	Ambient inlet pressure (in Hg)	412
T _a	TSUBA	Ambient inlet temperature (°F)	413
T _j	TSUBJ	Tailpipe temperature (°F)	414
T _{j_o}	TSUBJO	Tailpipe temperature at standard conditions (°F)	415
α _j	ALFAJ	Inclination of jet thrust axis to horizontal (deg) (+90° = vertical)	416
-	ROTR	Control factor to include calculation of rotors*	417
-	RP	Control factor to include calculation of propellers*	418
-	FANS	Control factor to include calculation of fans*	419
-	RJ	Control factor to include calculation of jets*	420
-	E	Control factor to include calculation of turbo- shaft engine*	421

* for control factors 1 = Yes 0 = No

TABLE 4 (Cont'd)

Variable	Program Name	Description	Input Sequence Location
<u>FLIGHT PATH PARAMETERS</u>			
-	PATH(N)	Flight Segment type (1 = Helical, 2 = Straight)	30 thru 79
X'_{max_n}	XMAX(N)	X', Y' coordinate system location of end point of segment N (straight line segments only)	80 thru 129
Y'_{max_n}	YMAX(N)		
ϕ_{max_n}	PHMAX(N)	Maximum angle through which aircraft turns on helical flight segments N (+ for left turns, - for right turns)	180 thru 229
R_n	RADIUS(N)	Turning radius of helical segment N	230 thru 279
$V_f(n)$	VF1(N)	Flight velocity segment N	280 thru 329
α_n	ALF(N)	Flight path angle to horizontal for segment N	330 thru 379
X'_{ob}	XPRZRO	Observer coordinate location on ground	381
Y'_{ob}	ZPRZRO		
θ_{max_o}	THMAXO	Angle first flight segment makes with the positive x'-axis	382
A_o	AZWEO	Altitude at the X'=0, Y'=o location	383
t_{inc}	TINC	Time increment between successive PNL calculations	384
-	ANMFPT	Number of observer locations	385

FORM 1
V/STOL NOISE MODEL

CASE: _____ DESCRIPTION: _____

SEG	(a) PATH	X' max (ft)	Y' max (ft)	(b) ϕ max (deg)	RADIUS (ft)	V _f (ft/sec)	α_n (deg)
1	2.	2000.	500.	-	-	85.	20.
2	1.	-	-	40.	500.	100.	10.
3	2.	5000.	4100.	-	-	130.	10.
4	1.	-	-	-80.	750.	150.	15.
5	2.	-	-	-	-	190.	15.
6							
7							
8							
9							
10							
11							
12							
13							
14							
15							
16							
17							
18							
19							
20							
21							
22							
23							
24							
25							

(a) Flight path type: 1 = helical, 2 = straight
 (b) Positive for counterclockwise, negative for clockwise turns

Note: Values in this table are for an example case.

Figure 32. V/STOL Noise Model Form 1

FORM 1A
V/STOL NOISE MODEL

CASE: _____ DESCRIPTION: _____

SEG	(a) PATH	X' _{max} (ft)	Y' _{max} (ft)	(b) ϕ_{max} (deg)	RADIUS (ft)	V _f (ft/sec)	α_n (deg)
26							
27							
28							
29							
30							
31							
32							
33							
34							
35							
36							
37							
38							
39							
40							
41							
42							
43							
44							
45							
46							
47							
48							
49							
50							

- (a) Flight path type: 1 = helical, 2 = straight
 (b) Positive for counterclockwise, negative for clockwise turns

Figure 33. V/STOL Noise Model Form 1A

V/STOL NOISE MODEL

FORM 2

CASE: Example 1
 FLIGHT SEGMENT NUMBER: 1

DESCRIPTION: Compound helicopter, Rotors only on segments 1 and 2. Propellers and rotors on segment 3, 4, and 5.

LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE
1	SAZ	1117.	80	XMAX(1)	2000.	235	RADIUS(6)		390	DIAH	
2	SEG	5.	81	XMAX(2)		236	RADIUS(7)		391	B	
3	FLTYPE	1.	82	XMAX(3)	5000.	237	RADIUS(8)		392	BPR	
4	RCASE	2.	83	XMAX(4)		238	RADIUS(9)		393	CHORD	
5	RETA	0.8	84	XMAX(5)		239	RADIUS(10)		394	DDDXT	
6	RBIGB	6.	85	XMAX(6)		+	+		395	DDDXH	
7	RBIGR	29.4	86	XMAX(7)		279	RADIUS(50)		396	RS	
8	ROMEGR	228.	87	XMAX(8)		280	VF1(1)	85.	397	SIGPHI	
9	RSID	0.	88	XMAX(9)		281	VF1(2)	100.	398	DL	
10	RCHORD	15.	89	XMAX(10)		282	VF1(3)	130.	399	RPM	
11	RTHRUS	28200.	+	+		283	VF1(4)	150.	400	SPAF	
12	RTORQ	117000.	129	XMAX(50)		284	VF1(5)	190.	401	XMXTIP	
13	RBETA	2.	130	YMAX(1)	500.	285	VF1(6)		402	PR	
14	TCASE	2.5	131	YMAX(2)		286	VF1(7)		403	DF	
15	TETA	0.8	132	YMAX(3)	4100.	287	VF1(8)		404	TT2	
16	TBIGB	6.	133	YMAX(4)		288	VF1(9)		405	PT2	
17	TBIGR	6.5	134	YMAX(5)		289	VF1(10)		406	ALFA	
18	TOMEGR	1030.	135	YMAX(6)		+	+		407	FN	
19	TSID	0.	136	YMAX(7)		329	VF1(50)		408	COMB	
20	TCHORD	9.2	137	YMAX(8)		330	ALF(1)	20.	409	THRUST	
21	TTHRUS	2150.	138	YMAX(9)		331	ALF(2)	10.	410	WIFL	
22	TTORQ	795.	139	YMAX(10)		332	ALF(3)	10.	411	AREAJ	
23	TBETA	0.	+	+		333	ALF(4)	15.	412	PSUBA	
24	PPWR		179	YMAX(50)		334	ALF(5)	15.	413	TSUBA	
25	DIA		180	PHMAX(1)		335	ALF(6)		414	TSUBJ	
26	BIGB		181	PHMAX(2)	40.	336	ALF(7)		415	TSUBJO	
27	RPMP		182	PHMAX(3)		337	ALF(8)		416	ALFAJ	
28	ANMPRP		183	PHMAX(4)	-80	338	ALF(9)		417	ROTR	1
29	CHORDP		184	PHMAX(5)		339	ALF(10)		418	RP	0
30	PATH(1)	2.	185	PHMAX(6)		+	+		419	FANS	0
31	PATH(2)	1.	186	PHMAX(7)		379	ALF(50)		420	RJ	0
32	PATH(3)	2.	187	PHMAX(8)		380	XPRZRO	6000.	421	E	1
33	PATH(4)	1.	188	PHMAX(9)		381	YPRZRO	2000.			
34	PATH(5)	2.	189	PHMAX(10)		382	PHMAXO	14			
35	PATH(6)		+	+		383	AZERO	0			
36	PATH(7)		229	PHMAX(50)		384	TINC	1			
37	PATH(8)		230	RADIUS(1)		385	ANMFPT	6			
38	PATH(9)		231	RADIUS(2)	500.	386	HPENG	3780.			
39	PATH(10)		232	RADIUS(3)		387	SLEVEL	2.			
+	+		233	RADIUS(4)	750.	388	ANENG				
79	PATH(50)		234	RADIUS(5)		389	DIAT				

Figure 34. V/STOL Noise Model Form 2

V/STOL NOISE MODEL

FORM 2

CASE: Example 1
 FLIGHT SEGMENT NUMBER: 2

DESCRIPTION: Parameters do not change from segment
1 to segment 2, thus a dummy input is
provided

LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE
1	SAZ	1117	80	XMAX(1)		235	RADIUS(6)		390	DIAH	
2	SEG		81	XMAX(2)		236	RADIUS(7)		391	B	
3	FLTYPE		82	XMAX(3)		237	RADIUS(8)		392	BPR	
4	RCASE		83	XMAX(4)		238	RADIUS(9)		393	CHORD	
5	RETA		84	XMAX(5)		239	RADIUS(10)		394	DDDXT	
6	RBIGB		85	XMAX(6)		↓	↓		395	DDDXH	
7	RBIGR		86	XMAX(7)		279	RADIUS(50)		396	RS	
8	ROMEGN		87	XMAX(8)		280	VF1(1)		397	SIGPHI	
9	RSID		88	XMAX(9)		281	VF1(2)		398	DL	
10	RCHORD		89	XMAX(10)		282	VF1(3)		399	RPM	
11	RTHRUS		↓	↓		283	VF1(4)		400	SPAF	
12	RTORQ		129	XMAX(50)		284	VF1(5)		401	XMXTIP	
13	RBETA		130	YMAX(1)		285	VF1(6)		402	PR	
14	TCASE		131	YMAX(2)		286	VF1(7)		403	DF	
15	TETA		132	YMAX(3)		287	VF1(8)		404	TT2	
16	TBIGB		133	YMAX(4)		288	VF1(9)		405	PT2	
17	TBIGR		134	YMAX(5)		289	VF1(10)		406	ALFA	
18	TOMEGN		135	YMAX(6)		↓	↓		407	FN	
19	TSID		136	YMAX(7)		329	VF1(50)		408	COMB	
20	TCHORD		137	YMAX(8)		330	ALF(1)		409	THRUST	
21	TTHRUS		138	YMAX(9)		331	ALF(2)		410	WTFL	
22	TTORQ		139	YMAX(10)		332	ALF(3)		411	AREAJ	
23	TBETA		↓	↓		333	ALF(4)		412	PSUBA	
24	PPWR		179	YMAX(50)		334	ALF(5)		413	TSUBA	
25	DIA		180	PHMAX(1)		335	ALF(6)		414	TSUBJ	
26	BIGB		181	PHMAX(2)		336	ALF(7)		415	TSUBJO	
27	RPMP		182	PHMAX(3)		337	ALF(8)		416	ALFAJ	
28	ANMPRP		183	PHMAX(4)		338	ALF(9)		417	ROTR	
29	CHORDP		184	PHMAX(5)		339	ALF(10)		418	RP	
30	PATH(1)		185	PHMAX(6)		↓	↓		419	FANS	
31	PATH(2)		186	PHMAX(7)		379	ALF(50)		420	RJ	
32	PATH(3)		187	PHMAX(8)		380	XPRZRO		421	E	
33	PATH(4)		188	PHMAX(9)		381	YPRZRO				
34	PATH(5)		189	PHMAX(10)		382	THMAXO				
35	PATH(6)		↓	↓		383	AZERO				
36	PATH(7)		229	PHMAX(50)		384	TINC				
37	PATH(8)		230	RADIUS(1)		385	ANMFPT				
38	PATH(9)		231	RADIUS(2)		386	HPENG				
39	PATH(10)		232	RADIUS(3)		387	SLEVEL				
↓	↓		233	RADIUS(4)		388	ANENG				
79	PATH(50)		234	RADIUS(5)		389	DIAT				

Figure 35. Form 2 for Example, Segment 2

V/STOL NOISE MODEL

FORM 2

CASE: Example 1

DESCRIPTION: Propellers are now turned on

FLIGHT SEGMENT NUMBER: 3

LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE
1	SAZ		80	XMAX(1)		235	RADIUS(6)		390	DIAH	
2	SEG		81	XMAX(2)		236	RADIUS(7)		391	B	
3	FLTYPE		82	XMAX(3)		237	RADIUS(8)		392	BPR	
4	RCASE		83	XMAX(4)		238	RADIUS(9)		393	CHORD	
5	RETA		84	XMAX(5)		239	RADIUS(10)		394	DDXT	
6	RBIGB		85	XMAX(6)		+	+		395	DDXH	
7	RBIGR		86	XMAX(7)		279	RADIUS(50)		396	RS	
8	ROMEGN		87	XMAX(8)		280	VF1(1)		397	SIGPHI	
9	RSID		88	XMAX(9)		281	VF1(2)		398	DL	
10	RCHORD		89	XMAX(10)		282	VF1(3)		399	RPM	
11	RTHRUS	15000.	+	+		283	VF1(4)		400	SPAF	
12	RTORQ	32300.	129	XMAX(50)		284	VF1(5)		401	XMXTIP	
13	RBETA	1.	130	YMAX(1)		285	VF1(6)		402	PR	
14	TCASE		131	YMAX(2)		286	VF1(7)		403	DF	
15	TETA		132	YMAX(3)		287	VF1(8)		404	TT2	
16	TBIGB		133	YMAX(4)		288	VF1(9)		405	PT2	
17	TBIGR		134	YMAX(5)		289	VF1(10)		406	ALFA	
18	TOMEGN		135	YMAX(6)		+	+		407	FN	
19	TSID		136	YMAX(7)		329	VF1(50)		408	COMB	
20	TCHORD		137	YMAX(8)		330	ALF(1)		409	THRUST	
21	TTHRUS	730.	138	YMAX(9)		331	ALF(2)		410	WTFI	
22	TTORQ	378.	139	YMAX(10)		332	ALF(3)		411	AREAJ	
23	TBETA		+	+		333	ALF(4)		412	PSUBA	
24	PPWR	1236.	179	YMAX(50)		334	ALF(5)		413	TSUBA	
25	DIA	14.76	180	PHMAX(1)		335	ALF(6)		414	TSUBJ	
26	BIGB	3.	181	PHMAX(2)		336	ALF(7)		415	TSUBJO	
27	RPMP	1180.	182	PHMAX(3)		337	ALF(8)		416	ALFAJ	
28	ANMPRP	2.	183	PHMAX(4)		338	ALF(9)		417	ROTR	
29	CHORDP	1.	184	PHMAX(5)		339	ALF(10)		418	RP	1.
30	PATH(1)		185	PHMAX(6)		+	+		419	FANS	
31	PATH(2)		186	PHMAX(7)		379	ALF(50)		420	RJ	
32	PATH(3)		187	PHMAX(8)		380	XPRZRO		421	E	
33	PATH(4)		188	PHMAX(9)		381	YPRZRO				
34	PATH(5)		189	PHMAX(10)		382	THMAXO				
35	PATH(6)		+	+		383	AZERO				
36	PATH(7)		229	PHMAX(50)		384	TINC				
37	PATH(8)		230	RADIUS(1)		385	ANMFPT				
38	PATH(9)		231	RADIUS(2)		386	HPENG				
39	PATH(10)		232	RADIUS(3)		387	SLEVEL				
+	+		233	RADIUS(4)		388	ANENG				
79	PATH(50)		234	RADIUS(5)		389	DIAT				

Figure 36. Form 2 for Example 1, Segment 3

V/STOL NOISE MODEL

FORM 2

CASE: Example 1

DESCRIPTION: _____

FLIGHT SEGMENT NUMBER: 4

LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE
1	SAZ		80	XMAX(1)		235	RADIUS(6)		390	DAH	
2	SEG		81	XMAX(2)		236	RADIUS(7)		391	B	
3	FLTYPE		82	XMAX(3)		237	RADIUS(8)		392	BPR	
4	RCASE		83	XMAX(4)		238	RADIUS(9)		393	CHORD	
5	RETA		84	XMAX(5)		239	RADIUS(10)		394	DDDXT	
6	RBIGB		85	XMAX(6)		+	+		395	DDDXH	
7	RBIGR		86	XMAX(7)		279	RADIUS(50)		396	RS	
8	ROMEGR		87	XMAX(8)		280	VF1(1)		397	SIGPHI	
9	RSID		88	XMAX(9)		281	VF1(2)		398	DL	
10	RCHORD		89	XMAX(10)		282	VF1(3)		399	RPM	
11	RTHRUS		+	+		283	VF1(4)		400	SPAF	
12	RTORQ		129	XMAX(50)		284	VF1(5)		401	XMXTIP	
13	RBETA		130	YMAX(1)		285	VF1(6)		402	PR	
14	TCASE		131	YMAX(2)		286	VF1(7)		403	DF	
15	TETA		132	YMAX(3)		287	VF1(8)		404	TT2	
16	TBIGB		133	YMAX(4)		288	VF1(9)		405	PT2	
17	TBIGR		134	YMAX(5)		289	VF1(10)		406	ALFA	
18	TOMEGR		135	YMAX(6)		+	+		407	FN	
19	TSID		136	YMAX(7)		329	VF1(50)		408	COMB	
20	TCHORD		137	YMAX(8)		330	ALF(1)		409	THRUST	
21	TTHRUS		138	YMAX(9)		331	ALF(2)		410	WTFL	
22	TTORQ		139	YMAX(10)		332	ALF(3)		411	AREAJ	
23	TBETA		+	+		333	ALF(4)		412	PSUBA	
24	PPWR	1358.	179	YMAX(50)		334	ALF(5)		413	TSUBA	
25	DIA		180	PHMAX(1)		335	ALF(6)		414	TSUBJ	
26	BIGB		181	PHMAX(2)		336	ALF(7)		415	TSUBJO	
27	RPMP	1210.	182	PHMAX(3)		337	ALF(8)		416	ALFAJ	
28	ANMPRP		183	PHMAX(4)		338	ALF(9)		417	ROTR	
29	CHORDP		184	PHMAX(5)		339	ALF(10)		418	RP	
30	PATH(1)		185	PHMAX(6)		+	+		419	FANS	
31	PATH(2)		186	PHMAX(7)		379	ALF(50)		420	RJ	
32	PATH(3)		187	PHMAX(8)		380	XPRZRO		421	E	
33	PATH(4)		188	PHMAX(9)		381	YPRZRO				
34	PATH(5)		189	PHMAX(10)		382	THMAXO				
35	PATH(6)		+	+		383	AZERO				
36	PATH(7)		229	PHMAX(50)		384	TINC				
37	PATH(8)		230	RADIUS(1)		385	ANMFPT				
38	PATH(9)		231	RADIUS(2)		386	HPENG				
39	PATH(10)		232	RADIUS(3)		387	SLEVEL				
+	+		233	RADIUS(4)		388	ANENG				
79	PATH(50)		234	RADIUS(5)		389	DIAT				

Figure 37. Form 2 for Example 1, Segment 4

V/STOL NOISE MODEL

FORM 2

CASE: Example 1

DESCRIPTION: _____

FLIGHT SEGMENT NUMBER: 5

LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE
1	SAZ		80	XMAX(1)		235	RADIUS(6)		390	DIAH	
2	SEG		81	XMAX(2)		236	RADIUS(7)		391	B	
3	FLTYPE		82	XMAX(3)		237	RADIUS(8)		392	BPR	
4	RCASE		83	XMAX(4)		238	RADIUS(9)		393	CHORD	
5	RETA		84	XMAX(5)		239	RADIUS(10)		394	DDDXT	
6	RBIGB		85	XMAX(6)		+	+		395	DDDXH	
7	RBIGR		86	XMAX(7)		279	RADIUS(50)		396	RS	
8	ROMEGR		87	XMAX(8)		280	VF1(1)		397	SIGPHI	
9	RSID		88	XMAX(9)		281	VF1(2)		398	DL	
10	RCHORD		89	XMAX(10)		282	VF1(3)		399	RPM	
11	RTHRUS		+	+		283	VF1(4)		400	SPAF	
12	RTORQ		129	XMAX(50)		284	VF1(5)		401	XMXTIP	
13	RBETA		130	YMAX(1)		285	VF1(6)		402	PR	
14	TCASE		131	YMAX(2)		286	VF1(7)		403	DF	
15	TETA		132	YMAX(3)		287	VF1(8)		404	TT2	
16	TBIGB		133	YMAX(4)		288	VF1(9)		405	PT2	
17	TBIGR		134	YMAX(5)		289	VF1(10)		406	ALFA	
18	TOMEGR		135	YMAX(6)		+	+		407	FN	
19	TSID		136	YMAX(7)		329	VF1(50)		408	COMB	
20	TCHORD		137	YMAX(8)		330	ALF(1)		409	THRUST	
21	TTHRUS		138	YMAX(9)		331	ALF(2)		410	WIFL	
22	TTORQ		139	YMAX(10)		332	ALF(3)		411	AREAJ	
23	TBETA		+	+		333	ALF(4)		412	PSUBA	
24	PPWR	1480.	179	YMAX(50)		334	ALF(5)		413	TSUBA	
25	DIA		180	PHMAX(1)		335	ALF(6)		414	TSUBJ	
26	BIGB		181	PHMAX(2)		336	ALF(7)		415	TSUBJO	
27	RPMP	1240.	182	PHMAX(3)		337	ALF(8)		416	ALFAJ	
28	ANMPRP		183	PHMAX(4)		338	ALF(9)		417	ROTR	
29	CHORDP		184	PHMAX(5)		339	ALF(10)		418	RP	
30	PATH(1)		185	PHMAX(6)		+	+		419	FANS	
31	PATH(2)		186	PHMAX(7)		379	ALF(50)		420	RJ	
32	PATH(3)		187	PHMAX(8)		380	XPRZRO		421	E	
33	PATH(4)		188	PHMAX(9)		381	YPRZRO				
34	PATH(5)		189	PHMAX(10)		382	THMAXO				
35	PATH(6)		+	+		383	AZERO				
36	PATH(7)		229	PHMAX(50)		384	TINC				
37	PATH(8)		230	RADIUS(1)		385	ANMFPT				
38	PATH(9)		231	RADIUS(2)		386	HPENG				
39	PATH(10)		232	RADIUS(3)		387	SLEVEL				
+	+		233	RADIUS(4)		388	ANENG				
79	PATH(50)		234	RADIUS(5)		389	DIAT				

Figure 38. Form 2 for Example 1, Segment 5

CODING INSTRUCTIONS

- 1. LOCATION FIELD MUST BE AN INTEGER NUMBER RIGHT ADJUSTED.
- 2. DATA FIELDS 1 THRU 5 MUST CONTAIN A DECIMAL POINT, THEREFORE AN "E" OR "F" FORMAT MUST BE USED.
- 3. LAST DATA CARD OF CASE MUST CONTAIN A MINUS SIGN (-) IN CC 1.

WORD COUNT FIELD		DATA FIELD 1																DATA FIELD 2																DATA FIELD 3																DATA FIELD 4																DATA FIELD 5																	
LOCATION FIELD																		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66																		
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66																		
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66																		
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66																		
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66																		
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66																		
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66																		
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66																		
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Figure 39. V/STOL Noise Model Input Coding Form

FORM 3
V/STOL NOISE MODEL
Helicopter Rotor Parameters

VARIABLE	PROG NAME	FLIGHT PATH SEGMENT NUMBER																		
		1	2	3	4	5	6	7	8	9	10									
<u>MAIN ROTOR</u>																				
Loading harmonic K factor (a)	RCASE																			
Radial loading station %r (b)	RETA																			
Number of blades	RBIGB																			
Radius	RBIGR																			
Rotational speed	ROMEGR																			
Disk incidence angle	RSID																			
Blade chord	RCHORD																			
Thrust	RTHRUS																			
Torque	RTORQ																			
Coning angle	RBETA																			
<u>TAIL ROTOR</u>																				
Loading harmonic factor (c)	TCASE																			
Radial loading station %R (b)	TETA																			
Number of blades	TBIGB																			
Radius	TBIGR																			
Rotational speed	TOMEGR																			
Disk incidence	TSID																			
Blade chord	TCHORD																			
Thrust	TTHRUS																			
Torque	TTORQ																			
Coning angle	TBETA																			

(a) Typical value is 1.8 to 2.0 for most multi-blade rotor systems
 (b) Use a value of 0.8 for normal rotor systems
 (c) Typical value is 1.9 to 2.2 for most motors

CASE NUMBER: _____ DESCRIPTION: _____

FORM 4
 V/STOL NOISE MODEL
Propeller Parameters

VARIABLE	PROG NAME	FLIGHT PATH SEGMENT NUMBER																		
		1	2	3	4	5	6	7	8	9	10									
Shaft Power	hp	PFWR																		
Diameter	ft	DIA																		
Number of blades		BIGB																		
Rotational speed	rpm	RPMP																		
Number of propellers		ANMPRP																		
Mean blade chord	ft	CHORDP																		

CASE NUMBER: _____ DESCRIPTION: _____

FORM 5
V/STOL NOISE MODEL
Turboshaft Engine Noise

VARIABLE	PROG NAME	FLIGHT PATH SEGMENT NUMBER				
		1	2	3	4	5
Power output hp	HPENG					
Noise level curve (a)	SLEVEL					
Number of engines	ANENG					

VARIABLE	PROG NAME	FLIGHT PATH SEGMENT NUMBER				
		6	7	8	9	10
Power output hp	HPENG					
Noise level curve (a)	SLEVEL					
Number of engines	ANENG					

(a) 1 = average 2 = loud

CASE NUMBER: _____ DESCRIPTION: _____

FORM 6
V/STOL NOISE MODEL
Jet Engine Parameters

VARIABLE	PROG NAME	FLIGHT PATH SEGMENT NUMBER																		
		1	2	3	4	5	6	7	8	9	10									
Static thrust	lb	THRUST																		
Gas weight flow	lb/sec	WTFL																		
Nozzle area	sq in	AREAJ																		
Ambient inlet pressure	in Hg	PSUBA																		
Ambient inlet temperature	F	TSUBA																		
Tailpipe temperature	F	TSUBJ																		
Tailpipe temperature at SLS conditions	F	TSUBJO																		
Inclination of thrust axis to horizontal(+90=inlet up)deg		ALFAJ																		

CASE NUMBER: _____ DESCRIPTION: _____

CORRELATION WITH MEASURED DATA

The program was run to determine its accuracy when applied to existing V/STOL aircraft. Data for two aircraft configurations, a helicopter and a turbo-prop STOL, were used to determine the degree of correlation with predicted levels.

Helicopter

The helicopter for which measured data was available is the CH-53D transport helicopter at a gross weight of 36,000 pounds. Noise measurements were made at several slant range positions for typical commercial type take-offs and aircraft operating parameters were monitored during the flight. Figure 41 presents comparisons of the measured and calculated values of maximum tone corrected Perceived Noise Level ($PNLT_{max}$) and of Effective Perceived Noise Level (EPNL). The value of primary concern here, the EPNL, as well as the $PNLT_{max}$ shows good agreement between measured and calculated levels. Figure 42 shows the very good agreement achieved between the measured and calculated time histories of PNLT for two of the Figure 41 data points.

Figure 43 shows measured and predicted noise spectra at two azimuth positions around the aircraft and Figure 44 shows predicted main rotor and tail rotor rotational harmonics compared with a time averaged 2.5 Hz analysis of measured data. In all cases it can be seen that there is good correlation between measured and predicted levels.

Turboprop STOL

The data presented in Reference 36 for the McDonnell-Douglas 188 turboprop STOL aircraft was used to further demonstrate program accuracy. The test described in Reference 36 was conducted at the National Aviation Facility Experimental Center (NAFEC) near Atlantic City, New Jersey with the aircraft at a gross weight of 43,000 to 45,000 pounds. Figure 45 presents the measured data along with the predicted EPNL and $PNLT_{max}$ levels of takeoff. The EPNL values show quite good correlation, however the calculated PNLT values are a bit high although they are within one standard deviation of the mean measured values. Part of the problem may be due to the fact that aircraft operating parameters were not closely monitored during the flight and they had to be estimated from material supplied by McDonnell-Douglas. This is especially true for the landing case (Figure 46) where the agreement between measured and calculated levels is not as good as for the takeoff case. The agreement between measured and calculated levels in both takeoff and landing cases is however, felt to be acceptable.

Since reliable turbofan STOL aircraft noise data with sufficiently detailed operating parameters were not available correlation was not checked for the fan portion of the program. Because the fan noise program was developed by an engine manufacturer (Pratt and Whitney Aircraft) from measured full-scale engine data it is felt that reasonable accuracy will be achieved with this program.

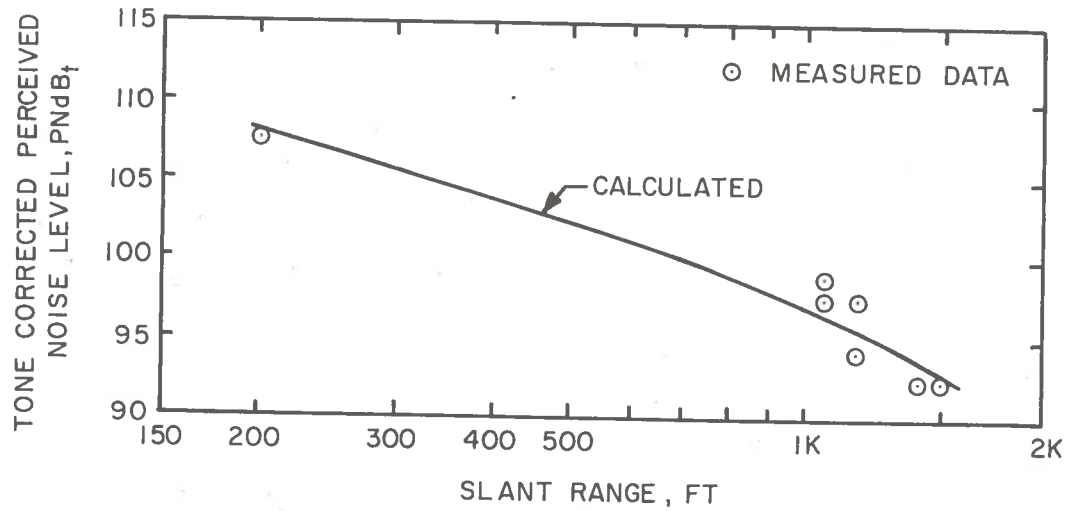
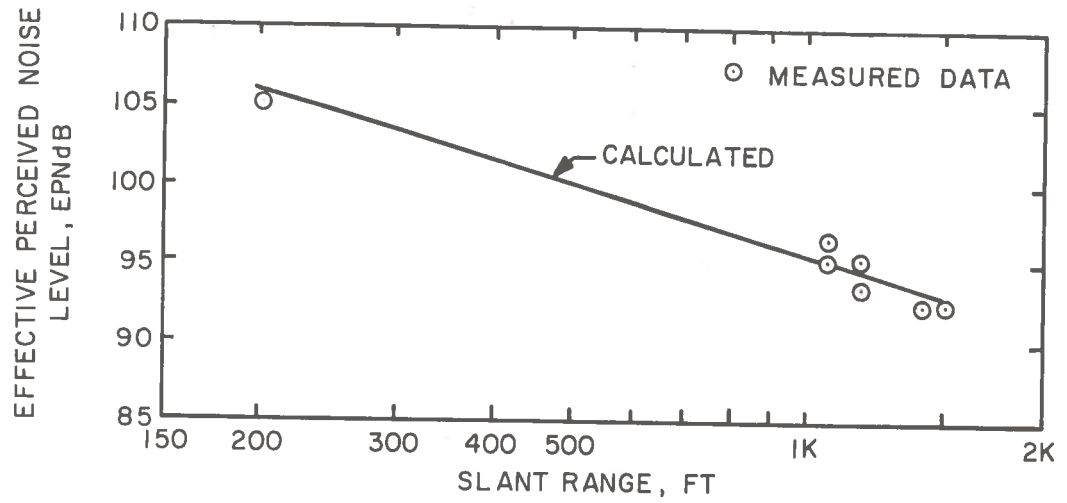
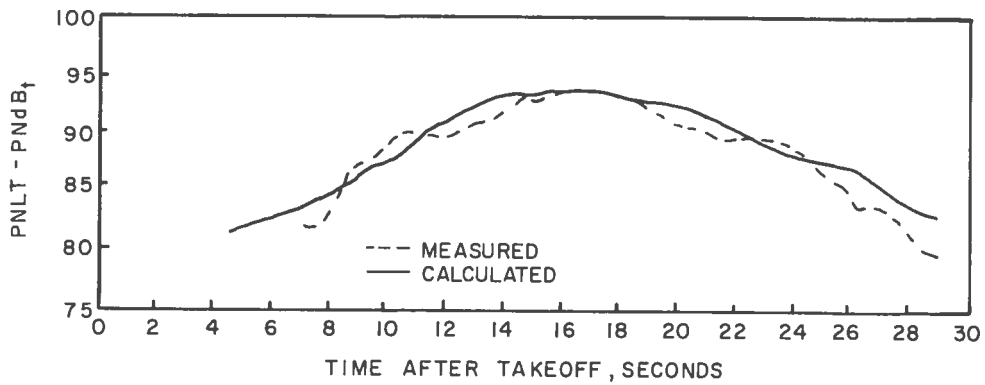
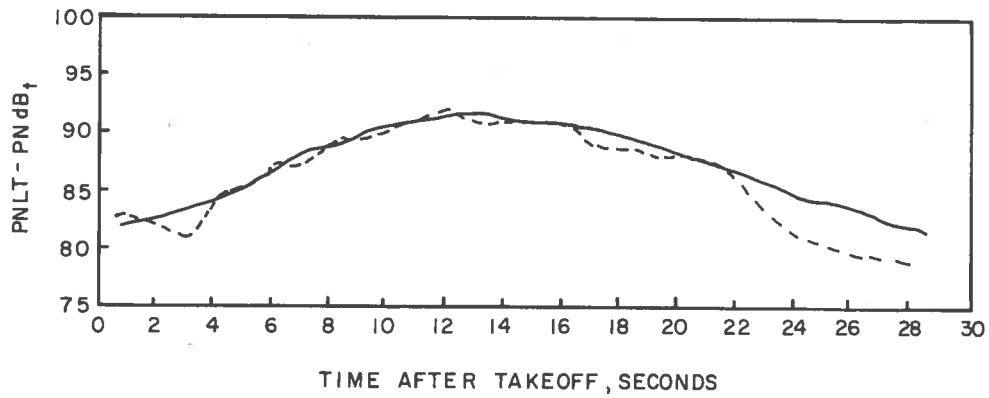


Figure 41. Comparison of Measured and Calculated EPNL and Maximum PNL_t Values for a Helicopter Takeoff



(a) TAKEOFF ONE



(b) TAKEOFF TWO

Figure 42. Comparison of Measured and Calculated PNL Time History for a Helicopter Takeoff

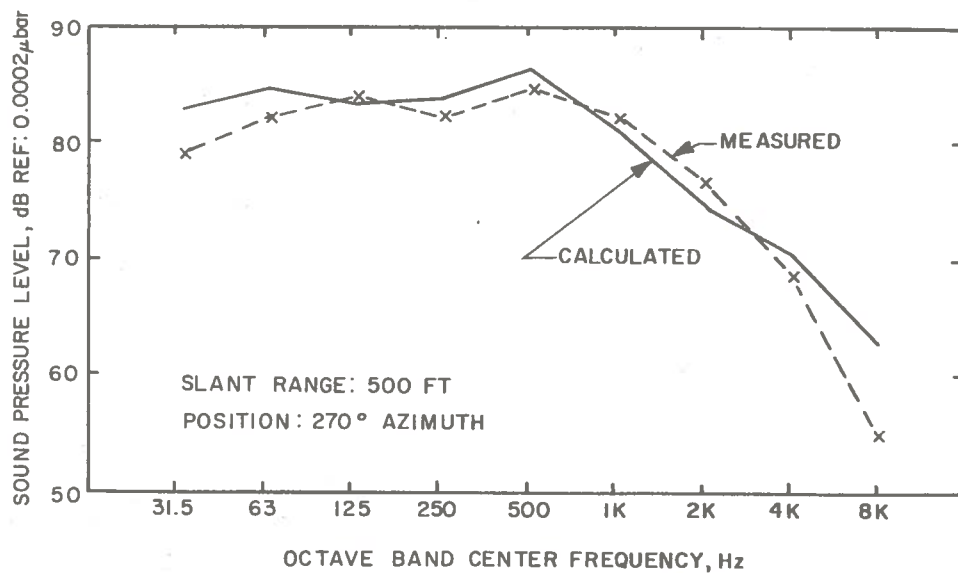
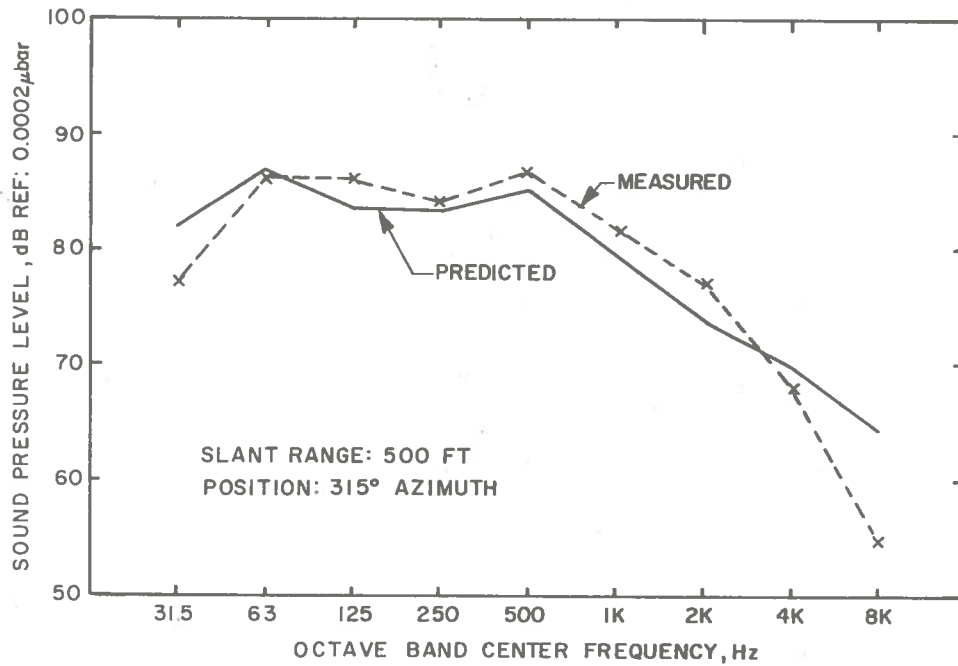


FIGURE 43. Comparison of Measured and Predicted Helicopter Noise Spectra.

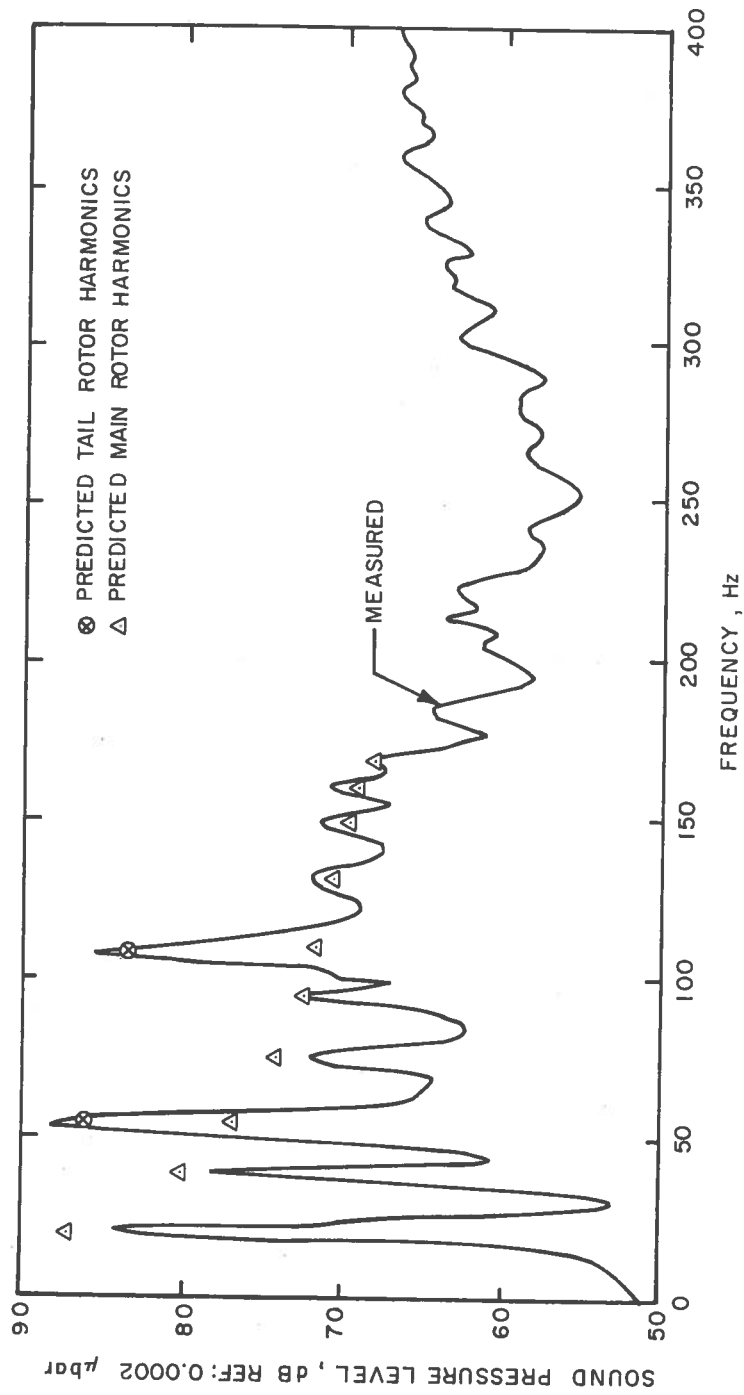


FIGURE 44. Comparison of Measured and Predicted Rotor Rotational Sound Levels.

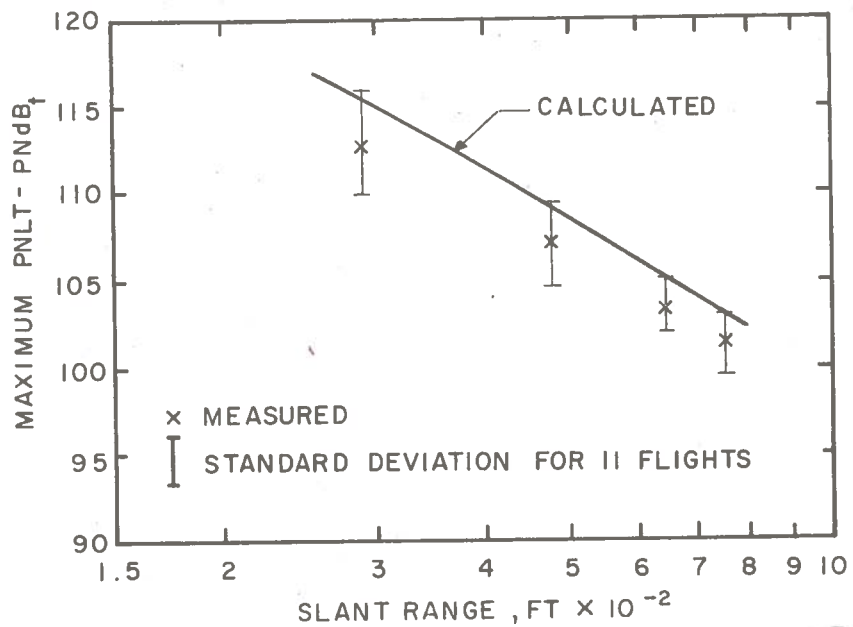
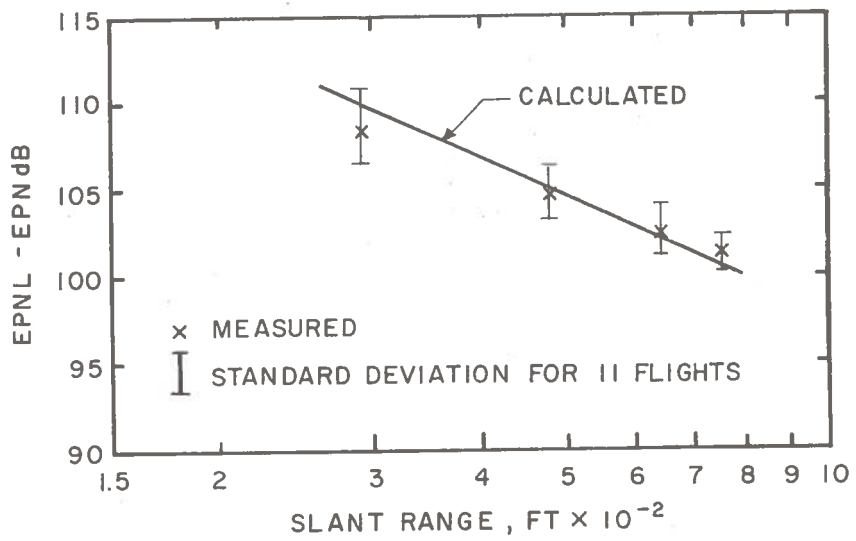


Figure 45. Comparison of Measured and Calculated Take-off $PNLT_{max}$ and EPNL Values for a McDonnell-Douglas 188 (Breguet 941) Turboprop STOL Airplane

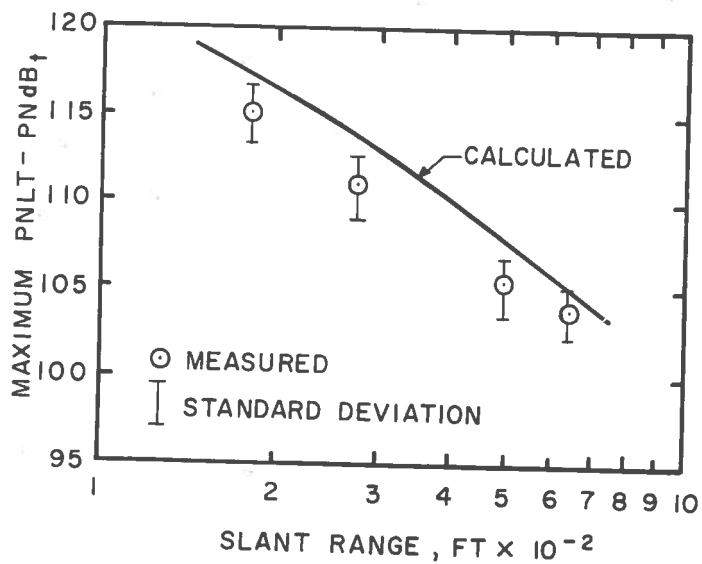
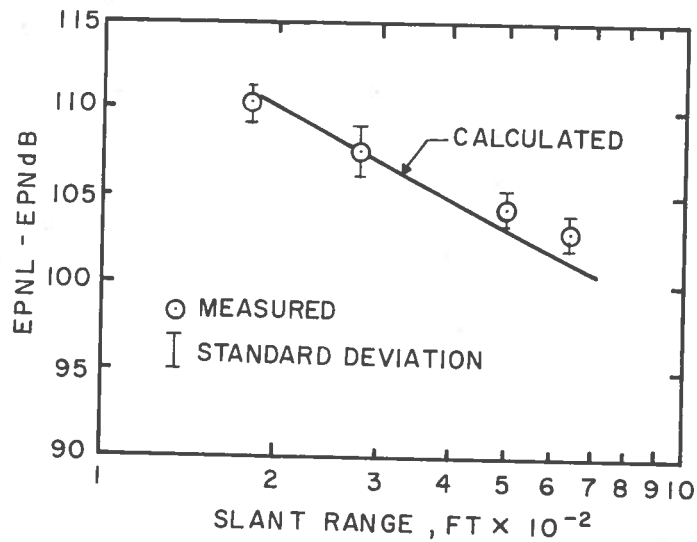


Figure 46. Comparison of Measured and Calculated Landing $PNLT_{max}$ and EPNL Values for a McDonnell-Douglas 188 (Breguet 941) Turboprop STOL Airplane

CONCLUSIONS AND RECOMMENDATIONS

Conclusions

1. The procedure described herein will predict the noise radiated by non-augmented lift V/STOL vehicles; in particular, it will predict the Effective Perceived Noise Level of these vehicles for typical take-off, landing, and cruise operations with an estimated accuracy of ± 2.5 EPNDB.
2. Comparisons of measured and predicted noise for a heavy transport helicopter and for a four engine turboprop STOL showed agreement within 2 dB for EPNL comparisons and within 3 dB for the maximum PNLT values.
3. The program cannot yet be used to calculate the noise from augmented lift STOLs because no generally accepted methods to predict the noise from these vehicles are currently available. An undeflected jet noise prediction procedure is, however, included to provide a baseline (minimum) estimate for those aircraft using deflected jets for lift.
4. The program should not be used to predict the noise of those VTOL vehicle types characterized by impulsive noise signatures. This includes both blade/vortex interaction and high speed compressibility (drag) impulsive noise. In fact, it is highly questionable as to whether the PNL (PNLT) measure adequately describes the annoyance of impulsive noise signatures. An independent study conducted in 1970 (Ref. 37) showed that the PNL method of predicting annoyance underpredicted the annoyance of impulsive noise by more than 4 dB.
5. It should also be noted that, apparently, the adequacy of the PNL (PNLT) measure of evaluating the annoyance of propeller or fan noise whose spectral content is rich in harmonics of the blade passage frequency has also not been demonstrated. Indeed, Adcock and Ollerhead concluded from a study of CTOL and STOL annoyance measures that:

"All methods (of rating annoyance) were significantly less consistent in estimating the noisiness of the STOL aircraft than they were for the CTOL aircraft. However, the difference could not be identified with any STOL performance characteristic. It seems more likely that the difference is associated with the fact that the STOL aircraft were all propeller or rotor driven."

Caution should, therefore, be exercised when evaluating the annoyance of vehicles with such acoustic characteristics.

6. The rotor noise prediction method used was developed for current state-of-the-art (NACA 0012 type) symmetrical airfoils and linearly twisted blades. The method should not be used for advanced blade designs having new airfoils with nonlinear chord and twist distributions. As methods become available to predict the noise characteristics of these newly developed rotors, such methods should be incorporated into this prediction procedure.

Recommendations

1. Methods to predict helicopter rotor impulsive noise should be developed and incorporated into the V/STOL Noise Model. Recent unpublished studies to develop a prediction method for high-speed (compressibility) drag impulsive noise has shown encouraging results in this direction.
2. Further research studies should be conducted to develop an annoyance measure similar to EPNL which accounts for the added annoyance of impulsive type noise signatures as well as harmonic trains in the mid- to high frequency range typical of some propeller configurations.
3. Procedures to predict the noise from augmented lift STOLs and deflected jets should be developed and incorporated into the V/STOL Noise Model.
4. Component noise prediction procedures should be updated or replaced as newer, more accurate, or more efficient procedures are developed.
5. The model should be modified at some future time to automatically produce a series of EPNL- slant range curves in punched computer card form for use in a V/STOL noise subroutine incorporated in the NEM Mod-5 and Mod-6 programs at the Transportation Systems Center.
6. A prediction method should be developed to predict the acoustic characteristics of the more advanced single and coaxial rotor configurations now under development.

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APPENDIX A

TONE CORRECTION CALCULATION PROCEDURE

The method for calculating the tone correction applied to the PNL to determine the PNL_T is taken from Reference 31 and is presented below. An example of the method is given in Table A-2.

Step 1.

Starting with the measured sound pressure level in the 80 Hz one-third octave band (band number 3), calculate the changes in level, S, (or "slopes") in the remainder of the 24 bands as follows:

$$s(3) = \text{no value} \quad (\text{A-1})$$

$$s(4) = \text{SPL}(4) - \text{SPL}(3) \quad (\text{A-2})$$

.

.

.

$$s(i) = \text{SPL}(i) - \text{SPL}(i-1) \quad (\text{A-3})$$

.

.

.

$$s(24) = \text{SPL}(24) - \text{SPL}(23) \quad (\text{A-4})$$

Step 2.

Encircle the value of the slope $s(i)$ where the absolute value of the change in slope is greater than five; that is, where

$$|\Delta s(i)| = |s(i) - s(i-1)| > 5 \quad (\text{A-5})$$

Step 3.

- (a) If the encircled value of the slope $s(i)$ is positive and algebraically greater than the slope $s(i-1)$, encircle the level $\text{SPL}(i)$.

- (b) If the encircled value of the slope $s(i)$ is zero or negative and the slope $s(i-1)$ is positive, encircle the level $SPL(i-1)$.
- (c) For all other cases, no level is to be encircled.

Step 4.

Omit all $SPL(i)$ encircled in Step 3 and compute new levels as follows:

- (a) For non-encircled levels, let the new levels equal the original levels,

$$SPL'(i) = SPL(i) \quad (A-6)$$

- (b) For encircled levels, let the new level equal the arithmetic average of the preceding and following levels,

$$SPL'(i) = 1/2 [SPL(i-1) + SPL(i+1)] \quad (A-7)$$

- (c) If the level in the highest frequency band is encircled, let the new level equal

$$SPL'(24) = SPL(23) + s(24) \quad (A-8)$$

Step 5.

Recompute new slopes including one for an imaginary 25-th band as follows:

$$s'(3) = s'(4) \quad (A-9)$$

$$s'(4) = SPL'(4) - SPL'(3) \quad (A-10)$$

.

.

.

$$s'(i) = SPL'(i) - SPL'(i-1) \quad (A-11)$$

.

.

$$s'(24) = SPL'(24) - SPL'(23) \quad (A-12)$$

$$s'(25) = s'(24) \quad (A-13)$$

Step 6.

Compute the arithmetic average of the three adjacent slopes as follows:

$$\bar{s}(i) = 1/3 \cdot [s'(i) + s'(i+1) + s'(i+2)] \quad (A-14)$$

Step 7.

Compute final adjusted levels by beginning with band number 3 and proceeding to band number 24 as follows:

$$SPL''(3) = SPL(3) \quad (A-15)$$

$$SPL''(4) = SPL''(3) + \bar{s}(3) \quad (A-16)$$

.

.

.

$$SPL''(i) = SPL''(i-1) + \bar{s}(i-1) \quad (A-17)$$

.

.

.

$$SPL''(24) = SPL''(23) + \bar{s}(23) \quad (A-18)$$

Step 8.

Calculate the difference between the original and adjusted levels as follows:

$$F(i) = SPL(i) - SPL''(i) \quad (A-19)$$

and note only values greater than zero.

Step 9.

Tone correction levels C are determined for any one-third octave band in accordance with Table A.1 or Figure A-1. However, only the maximum one is used.

Step 10.

The value of PNLT is given by:

$$PNLT = PNL + C_{\max} \quad (A-20)$$

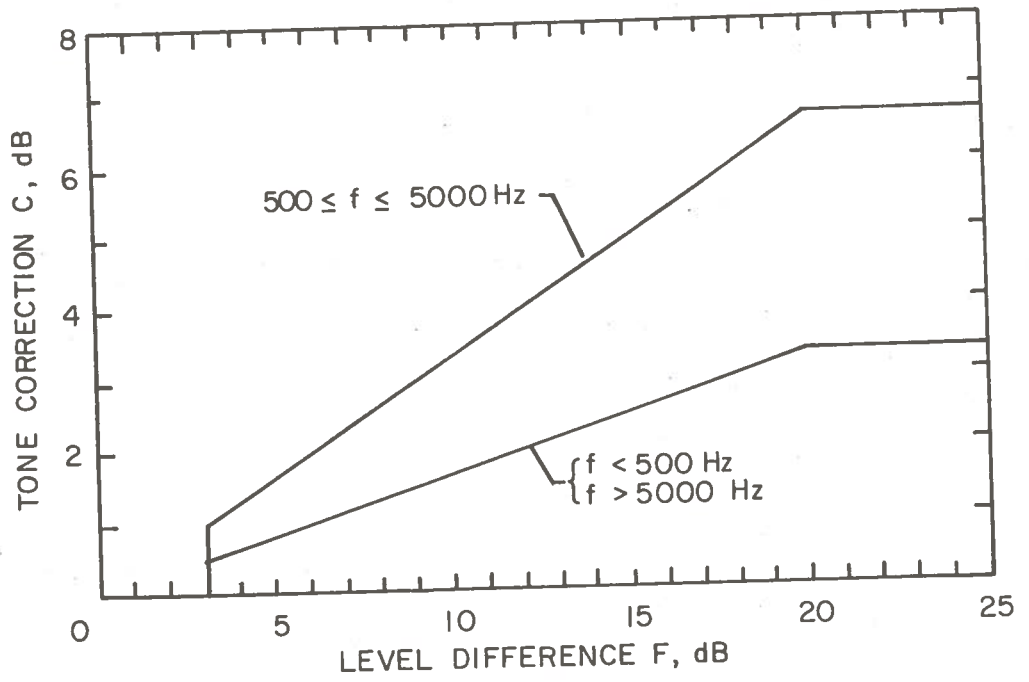


Figure A-1. Tone Correction Factors

TABLE A.1
TONE CORRECTION FACTORS

FREQUENCY f , Hz	LEVEL DIFFERENCE F , dB	TONE CORRECTION C , dB
$50 \leq f < 500$	$F < 3$ $3 \leq F < 20$ $20 \leq F$	0 $F/6$ $3^{1/3}$
$500 \leq f \leq 5000$	$F < 3$ $3 \leq F < 20$ $20 \leq F$	0 $F/3$ $6^{2/3}$
$5000 < f \leq 10000$	$F < 3$ $3 \leq F < 20$ $20 \leq F$	0 $F/6$ $3^{2/3}$

TABLE A.2

EXAMPLE OF TONE CORRECTION CALCULATION

①	②	③	④	⑤	⑥	⑦	⑧	⑨	⑩	⑪
BAND (i)	F Hz	SPL dB	S dB	S dB	SPL' dB	S' dB	\bar{S} dB	SPL'' dB	F dB	C dB
			Step 1	Step 2	Step 4	Step 5	Step 6	Step 7	Step 8	Step 9
1	50	-	-	-	-	-	-	-	-	-
2	63	-	-	-	-	-	-	-	-	-
3	80	70	-	-	70	-8	-2 ¹ / ₃	70	-	-
4	100	62	-8	-	62	-8	+3 ¹ / ₃	67 ² / ₃	-	-
5	125	70	+8	16	71	+9	+6 ² / ₃	71	-	-
6	160	80	+10	2	80	+9	+2 ² / ₃	77 ² / ₃	2 ¹ / ₃	-
7	200	82	+2	8	82	+2	-1 ¹ / ₃	80 ¹ / ₃	1 ² / ₃	-
8	250	83	+1	1	79	-3	-1 ¹ / ₃	79	4	2/3
9	315	76	-7	8	76	-3	+1 ¹ / ₃	77 ¹ / ₃	-	-
10	400	80	+4	11	78	+2	+1	78	2	-
11	500	80	0	4	80	+2	0	79	1	-
12	630	79	-1	1	79	-1	0	79	-	-
13	800	78	-1	0	78	-1	-1 ¹ / ₃	79	-	-
14	1000	80	+2	3	80	+2	-2 ² / ₃	78 ² / ₃	1 ¹ / ₃	-
15	1250	78	-2	4	78	-2	-1 ¹ / ₃	78	-	-
16	1600	76	-2	0	76	-2	+1 ¹ / ₃	77 ² / ₃	-	-
17	2000	79	+3	5	79	+3	+1	78	1	-
18	2500	85	+6	3	79	0	-1 ¹ / ₃	79	6	2
19	3150	79	-6	12	79	0	-2 ² / ₃	78 ² / ₃	1/3	-
20	4000	78	-1	5	78	-1	-6 ¹ / ₃	76	2	-
21	5000	71	-7	6	71	-7	-8	69 ² / ₃	1 ¹ / ₃	-
22	6300	60	-11	4	60	-11	-8 ² / ₃	61 ² / ₃	-	-
23	8000	54	-6	5	54	-6	-8	53	1	0
24	10000	45	-9	3	45	-9	-	45	-	-
						-9				

Step 1	③(i) - ③(i-1)
Step 2	④(i) - ④(i-1)
Step 3	see instructions
Step 4	see instructions
Step 5	⑥(i) - ⑥(i-1)

Step 6	⑦(i) + ⑦(i+1) + ⑦(i+2) / 3
Step 7	⑨(i-1) + ⑧(i-1)
Step 8	③(i) - ⑨(i)
Step 9	see Table A.1

APPENDIX B

SAMPLE PROGRAM CASES - INPUT/OUTPUT

Five sample cases are presented to demonstrate the operation of the program. Complete sets of the input along with the corresponding program output are shown. For the sake of simplicity the flight path is the same for all of the cases.

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FORM 1
V/STOL NOISE MODEL

CASE: Sample #1

DESCRIPTION: Checkout for Subroutine ROTOR

SEG	(a) PATH	X' _{max} (ft)	Y' _{max} (ft)	(b) ϕ_{max} (deg)	RADIUS (ft)	V _f (ft/sec)	α_n (deg)
1	2.	1000.	0.	-	-	75.	15.
2	1.	-	-	60.	500.	100.	5.
3	2.	2000.	1240.	-	-	150.	10.
4	1.	-	-	30.	500.	175.	10.
5	2.	-	-	-	-	175.	20.
6							
7							
8							
9							
10							
11							
12							
13							
14							
15							
16							
17							
18							
19							
20							
21							
22							
23							
24							
25							

(a) Flight path type: 1 = helical, 2 = straight
 (b) Positive for counterclockwise, negative for clockwise turns

V/STOL NOISE MODEL

FORM 2

CASE: Sample 1

DESCRIPTION: Checkout for Subroutine ROTOR

FLIGHT SEGMENT NUMBER: 1

LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE
1	SAZ	1117.	80	XMAX(1)	1000.	235	RADIUS(6)		390	DLAH	
2	SEG	5.	81	XMAX(2)		236	RADIUS(7)		391	B	
3	FLTYPE	1.	82	XMAX(3)	2000.	237	RADIUS(8)		392	BPR	
4	RCASE	2.	83	XMAX(4)		238	RADIUS(9)		393	CHORD	
5	RETA	.8	84	XMAX(5)		239	RADIUS(10)		394	DDDXT	
6	RBIGB	6.	85	XMAX(6)		+	+		395	DDDXT	
7	RBIGR	29.4	86	XMAX(7)		279	RADIUS(50)		396	RS	
8	ROMEGR	228	87	XMAX(8)		280	VF1(1)		397	SIGPHI	
9	RSID	0	88	XMAX(9)		281	VF1(2)	75.	398	DL	
10	RCHORD	15	89	XMAX(10)		282	VF1(3)	100.	399	RPM	
11	RTHRUS	28200.	+	+		283	VF1(4)	150.	400	SPAF	
12	RTORQ	117000.	129	XMAX(50)		284	VF1(5)	175.	401	XMXTIP	
13	RBETA	2.	130	YMAX(1)	0.	285	VF1(6)	175.	402	PR	
14	TCASE	2.5	131	YMAX(2)		286	VF1(7)		403	DF	
15	TETA	0.8	132	YMAX(3)	1240.	287	VF1(8)		404	TT2	
16	TBIGB	6.	133	YMAX(4)		288	VF1(9)		405	PT2	
17	TBIGR	6.5	134	YMAX(5)		289	VF1(10)		406	ALFA	
18	TOMEGR	1030.	135	YMAX(6)		+	+		407	FN	
19	TSID	0.	136	YMAX(7)		329	VF1(50)		408	COMB	
20	TCHORD	9.2	137	YMAX(8)		330	ALF(1)	15.	409	THRUST	
21	TTHRUS	2150.	138	YMAX(9)		331	ALF(2)	5.	410	WTFI	
22	TTORQ	795.	139	YMAX(10)		332	ALF(3)	10.	411	AREAJ	
23	TBETA	0.	+	+		333	ALF(4)	10.	412	PSUBA	
24	PPWR		179	YMAX(50)		334	ALF(5)	20.	413	TSUBA	
25	DIA		180	PHMAX(1)		335	ALF(6)		414	TSUBJ	
26	BIGB		181	PHMAX(2)	60.	336	ALF(7)		415	TSUBJO	
27	RPMP		182	PHMAX(3)		337	ALF(8)		416	ALFAJ	
28	ANMPRP		183	PHMAX(4)	30.	338	ALF(9)		417	ROTR	1.
29	CHORDP		184	PHMAX(5)		339	ALF(10)		418	RP	0.
30	PATH(1)	2.	185	PHMAX(6)		+	+		419	FANS	0.
31	PATH(2)	1.	186	PHMAX(7)		379	ALF(50)		420	RJ	0.
32	PATH(3)	2.	187	PHMAX(8)		380	XPRZRO	2500.	421	E	0.
33	PATH(4)	1.	188	PHMAX(9)		381	YPRZRO	500.			
34	PATH(5)	2.	189	PHMAX(10)		382	TBMAXO	0.			
35	PATH(6)		+	+		383	AZERO	0.			
36	PATH(7)		229	PHMAX(50)		384	TINC	1.			
37	PATH(8)		230	RADIUS(1)		385	ANMFPT	1.			
38	PATH(9)		231	RADIUS(2)	500.	386	HPENG				
39	PATH(10)		232	RADIUS(3)		387	SLEVEL				
+	+		233	RADIUS(4)	500.	388	ANENG				
79	PATH(50)		234	RADIUS(5)		389	DIAT				

V/STOL NOISE MODEL

FORM 2

CASE: Sample #1
 FLIGHT SEGMENT NUMBER: 2

DESCRIPTION: _____

LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE
1	SAZ		80	XMAX(1)		235	RADIUS(6)		390	DIAH	
2	SEG		81	XMAX(2)		236	RADIUS(7)		391	B	
3	FLTYPE		82	XMAX(3)		237	RADIUS(8)		392	BPR	
4	RCASE		83	XMAX(4)		238	RADIUS(9)		393	CHORD	
5	RETA		84	XMAX(5)		239	RADIUS(10)		394	DDDXT	
6	RBIGB		85	XMAX(6)		+	+		395	DDDXH	
7	RBIGR		86	XMAX(7)		279	RADIUS(50)		396	RS	
8	ROMEGR		87	XMAX(8)		280	VF1(1)		397	SIGPHI	
9	RSID	2.	88	XMAX(9)		281	VF1(2)		398	DL	
10	RCHORD		89	XMAX(10)		282	VF1(3)		399	RPM	
11	RTHRUS		+	+		283	VF1(4)		400	SPAF	
12	RTORQ		129	XMAX(50)		284	VF1(5)		401	XMXTIP	
13	RBETA		130	YMAX(1)		285	VF1(6)		402	PR	
14	TCASE		131	YMAX(2)		286	VF1(7)		403	DF	
15	TETA		132	YMAX(3)		287	VF1(8)		404	TT2	
16	TBIGB		133	YMAX(4)		288	VF1(9)		405	PT2	
17	TBIGR		134	YMAX(5)		289	VF1(10)		406	ALFA	
18	TOMEGR		135	YMAX(6)		+	+		407	FN	
19	TSID		136	YMAX(7)		329	VF1(50)		408	COMB	
20	TCHORD		137	YMAX(8)		330	ALF(1)		409	THRUST	
21	TTHRUS		138	YMAX(9)		331	ALF(2)		410	WTFI	
22	TTORQ		139	YMAX(10)		332	ALF(3)		411	AREAJ	
23	TBETA		+	+		333	ALF(4)		412	PSUBA	
24	PPWR		179	YMAX(50)		334	ALF(5)		413	TSUBA	
25	DIA		180	PHMAX(1)		335	ALF(6)		414	TSUBJ	
26	BIGB		181	PHMAX(2)		336	ALF(7)		415	TSUBJO	
27	RPMP		182	PHMAX(3)		337	ALF(8)		416	ALFAJ	
28	ANMPRP		183	PHMAX(4)		338	ALF(9)		417	ROTR	
29	CHORDP		184	PHMAX(5)		339	ALF(10)		418	RP	
30	PATH(1)		185	PHMAX(6)		+	+		419	FANS	
31	PATH(2)		186	PHMAX(7)		379	ALF(50)		420	RJ	
32	PATH(3)		187	PHMAX(8)		380	XPRZRO		421	E	
33	PATH(4)		188	PHMAX(9)		381	YPRZRO				
34	PATH(5)		189	PHMAX(10)		382	THMAXO				
35	PATH(6)		+	+		383	AZERO				
36	PATH(7)		229	PHMAX(50)		384	TINC				
37	PATH(8)		230	RADIUS(1)		385	ANMFPT				
38	PATH(9)		231	RADIUS(2)		386	HPENG				
39	PATH(10)		232	RADIUS(3)		387	SLEVEL				
+	+		233	RADIUS(4)		388	ANENG				
79	PATH(50)		234	RADIUS(5)		389	DIAT				

V/STOL NOISE MODEL

FORM 2

CASE: Sample #1
 FLIGHT SEGMENT NUMBER: 3

DESCRIPTION: _____

LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE
1	SAZ		80	XMAX(1)		235	RADIUS(6)		390	DIAH	
2	SEG		81	XMAX(2)		236	RADIUS(7)		391	B	
3	FLTYPE		82	XMAX(3)		237	RADIUS(8)		392	BPR	
4	RCASE		83	XMAX(4)		238	RADIUS(9)		393	CHORD	
5	RETA		84	XMAX(5)		239	RADIUS(10)		394	DDDXT	
6	RBIGB		85	XMAX(6)		+	+		395	DDDXT	
7	RBIGR		86	XMAX(7)		279	RADIUS(50)		396	RS	
8	ROMEGR		87	XMAX(8)		280	VF1(1)		397	SIGPHI	
9	RSID	5.	88	XMAX(9)		281	VF1(2)		398	DL	
10	RCHORD		89	XMAX(10)		282	VF1(3)		399	RPM	
11	RTHRUS		+	+		283	VF1(4)		400	SPAF	
12	RTORQ		129	XMAX(50)		284	VF1(5)		401	XMXTIP	
13	RBETA		130	YMAX(1)		285	VF1(6)		402	PR	
14	TCASE		131	YMAX(2)		286	VF1(7)		403	DF	
15	TETA		132	YMAX(3)		287	VF1(8)		404	TT2	
16	TBIGB		133	YMAX(4)		288	VF1(9)		405	PT2	
17	TBIGR		134	YMAX(5)		289	VF1(10)		406	ALFA	
18	TOMEGN		135	YMAX(6)		+	+		407	FN	
19	TSID		136	YMAX(7)		329	VF1(50)		408	COMB	
20	TCHORD		137	YMAX(8)		330	ALF(1)		409	THRUST	
21	TTHRUS		138	YMAX(9)		331	ALF(2)		410	WTFL	
22	TTORQ		139	YMAX(10)		332	ALF(3)		411	AREAJ	
23	TBETA		+	+		333	ALF(4)		412	PSUBA	
24	PPWR		179	YMAX(50)		334	ALF(5)		413	TSUBA	
25	DIA		180	PHMAX(1)		335	ALF(6)		414	TSUBJ	
26	BIGB		181	PHMAX(2)		336	ALF(7)		415	TSUBJO	
27	RPMP		182	PHMAX(3)		337	ALF(8)		416	ALFAJ	
28	ANMPRP		183	PHMAX(4)		338	ALF(9)		417	ROTR	
29	CHORDP		184	PHMAX(5)		339	ALF(10)		418	RP	
30	PATH(1)		185	PHMAX(6)		+	+		419	FANS	
31	PATH(2)		186	PHMAX(7)		379	ALF(50)		420	RJ	
32	PATH(3)		187	PHMAX(8)		380	XPRZRO		421	E	
33	PATH(4)		188	PHMAX(9)		381	YPRZRO				
34	PATH(5)		189	PHMAX(10)		382	THMAXO				
35	PATH(6)		+	+		383	AZERO				
36	PATH(7)		229	PHMAX(50)		384	TINC				
37	PATH(8)		230	RADIUS(1)		385	ANMFPT				
38	PATH(9)		231	RADIUS(2)		386	HPENG				
39	PATH(10)		232	RADIUS(3)		387	SLEVEL				
+	+		233	RADIUS(4)		388	ANENG				
79	PATH(50)		234	RADIUS(5)		389	DIAT				

V/STOL NOISE MODEL

FORM 2

CASE: Sample #1
 FLIGHT SEGMENT NUMBER: 4

DESCRIPTION: _____

LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE
1	SAZ		80	XMAX(1)		235	RADIUS(6)		390	DAH	
2	SEG		81	XMAX(2)		236	RADIUS(7)		391	B	
3	FLTYPE		82	XMAX(3)		237	RADIUS(8)		392	BPR	
4	RCASE		83	XMAX(4)		238	RADIUS(9)		393	CHORD	
5	RETA		84	XMAX(5)		239	RADIUS(10)		394	DDDXT	
6	RBIGB		85	XMAX(6)		+	+		395	DDDXH	
7	RBIGR		86	XMAX(7)		279	RADIUS(50)		396	RS	
8	ROMEGR		87	XMAX(8)		280	VF1(1)		397	SIGPHI	
9	RSID	5.	88	XMAX(9)		281	VF1(2)		398	DL	
10	RCHORD		89	XMAX(10)		282	VF1(3)		399	RPM	
11	RTHRUS		+	+		283	VF1(4)		400	SPAF	
12	RTORQ		129	XMAX(50)		284	VF1(5)		401	KMXTIP	
13	RBETA		130	YMAX(1)		285	VF1(6)		402	PR	
14	TCASE		131	YMAX(2)		286	VF1(7)		403	DF	
15	TETA		132	YMAX(3)		287	VF1(8)		404	TT2	
16	TBIGB		133	YMAX(4)		288	VF1(9)		405	PT2	
17	TBIGR		134	YMAX(5)		289	VF1(10)		406	ALFA	
18	TOMEGR		135	YMAX(6)		+	+		407	FN	
19	TSID		136	YMAX(7)		329	VF1(50)		408	COMB	
20	TCHORD		137	YMAX(8)		330	ALF(1)		409	THRUST	
21	TTHRUS		138	YMAX(9)		331	ALF(2)		410	WTFI	
22	TTORQ		139	YMAX(10)		332	ALF(3)		411	AREAJ	
23	TBETA		+	+		333	ALF(4)		412	PSUBA	
24	PPWR		179	YMAX(50)		334	ALF(5)		413	TSUBA	
25	DIA		180	PHMAX(1)		335	ALF(6)		414	TSUBJ	
26	BIGB		181	PHMAX(2)		336	ALF(7)		415	TSUBJO	
27	RPMP		182	PHMAX(3)		337	ALF(8)		416	ALFAJ	
28	ANMPRP		183	PHMAX(4)		338	ALF(9)		417	ROTR	
29	CHORDP		184	PHMAX(5)		339	ALF(10)		418	RP	
30	PATH(1)		185	PHMAX(6)		+	+		419	FANS	
31	PATH(2)		186	PHMAX(7)		379	ALF(50)		420	RJ	
32	PATH(3)		187	PHMAX(8)		380	XPRZRO		421	E	
33	PATH(4)		188	PHMAX(9)		381	YPRZRO				
34	PATH(5)		189	PHMAX(10)		382	THMAXO				
35	PATH(6)		+	+		383	AZERO				
36	PATH(7)		229	PHMAX(50)		384	TINC				
37	PATH(8)		230	RADIUS(1)		385	ANMFPT				
38	PATH(9)		231	RADIUS(2)		386	HPENG				
39	PATH(10)		232	RADIUS(3)		387	SLEVEL				
+	+		233	RADIUS(4)		388	ANENG				
79	PATH(50)		234	RADIUS(5)		389	DIAT				

V/STOL NOISE MODEL

FORM 2

CASE: Sample #1
 FLIGHT SEGMENT NUMBER: 5

DESCRIPTION: _____

LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE
1	SAZ		80	XMAX(1)		235	RADIUS(6)		390	DIAH	
2	SEG		81	XMAX(2)		236	RADIUS(7)		391	B	
3	FLTYPE		82	XMAX(3)		237	RADIUS(8)		392	BPR	
4	RCASE		83	XMAX(4)		238	RADIUS(9)		393	CHORD	
5	RETA		84	XMAX(5)		239	RADIUS(10)		394	DDDXT	
6	RBIGB		85	XMAX(6)		+	+		395	DDDXH	
7	RBIGR		86	XMAX(7)		279	RADIUS(50)		396	RS	
8	ROMEGR		87	XMAX(8)		280	VF1(1)		397	SIGPHI	
9	RSID	5.	88	XMAX(9)		281	VF1(2)		398	DL	
10	RCHORD		89	XMAX(10)		282	VF1(3)		399	RPM	
11	RTHRUS		+	+		283	VF1(4)		400	SPAF	
12	RTORQ		129	XMAX(50)		284	VF1(5)		401	XMXTIP	
13	RBETA		130	YMAX(1)		285	VF1(6)		402	PR	
14	TCASE		131	YMAX(2)		286	VF1(7)		403	DF	
15	TETA		132	YMAX(3)		287	VF1(8)		404	TT2	
16	TBIGB		133	YMAX(4)		288	VF1(9)		405	PT2	
17	TBIGR		134	YMAX(5)		289	VF1(10)		406	ALFA	
18	TOMEGN		135	YMAX(6)		+	+		407	FN	
19	TSID		136	YMAX(7)		329	VF1(50)		408	COMB	
20	TCHORD		137	YMAX(8)		330	ALF(1)		409	THRUST	
21	TTHRUS		138	YMAX(9)		331	ALF(2)		410	WTFL	
22	TTORQ		139	YMAX(10)		332	ALF(3)		411	AREAJ	
23	TBETA		+	+		333	ALF(4)		412	PSUBA	
24	PPWR	1358.	179	YMAX(50)		334	ALF(5)		413	TSUBA	
25	DIA		180	PHMAX(1)		335	ALF(6)		414	TSUBJ	
26	BIGB		181	PHMAX(2)		336	ALF(7)		415	TSUBJO	
27	RPMP	1210.	182	PHMAX(3)		337	ALF(8)		416	ALFAJ	
28	ANMPRP		183	PHMAX(4)		338	ALF(9)		417	ROTR	
29	CHORDP		184	PHMAX(5)		339	ALF(10)		418	RP	
30	PATH(1)		185	PHMAX(6)		+	+		419	FANS	
31	PATH(2)		186	PHMAX(7)		379	ALF(50)		420	RJ	
32	PATH(3)		187	PHMAX(8)		380	XPRZRO		421	E	
33	PATH(4)		188	PHMAX(9)		381	YPRZRO				
34	PATH(5)		189	PHMAX(10)		382	THMAXO				
35	PATH(6)		+	+		383	AZERO				
36	PATH(7)		229	PHMAX(50)		384	TINC				
37	PATH(8)		230	RADIUS(1)		385	ANMFPT				
38	PATH(9)		231	RADIUS(2)		386	HPENG				
39	PATH(10)		232	RADIUS(3)		387	SLEVEL				
+	+		233	RADIUS(4)		388	ANENG				
79	PATH(50)		234	RADIUS(5)		389	DIAT				

FORM 3
V/STOL NOISE MODEL
Helicopter Rotor Parameters

VARIABLE	PROG NAME	FLIGHT PATH SEGMENT NUMBER																		
		1	2	3	4	5	6	7	8	9	10									
<u>MAIN ROTOR</u>																				
Loading harmonic K factor (a)	RCASE	2.0	2.0	2.0	2.0	2.0	2.0	2.0	2.0	2.0	2.0	2.0	2.0	2.0	2.0	2.0	2.0	2.0	2.0	2.0
Radial loading station %R (b)	RETA	0.8	0.8	0.8	0.8	0.8	0.8	0.8	0.8	0.8	0.8	0.8	0.8	0.8	0.8	0.8	0.8	0.8	0.8	0.8
Number of blades	RBIGB	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6
Radius	REIGR	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4
Rotational speed	ROMEGR	185	185	185	185	185	185	185	185	185	185	185	185	185	185	185	185	185	185	185
Disk incidence angle	RSID	0	2	5	5	5	5	5	5	5	5	5	5	5	5	5	5	5	5	5
Blade chord	RCHORD	15	15	15	15	15	15	15	15	15	15	15	15	15	15	15	15	15	15	15
Thrust	RTHRUS	28200	28200	28200	28200	28200	28200	28200	28200	28200	28200	28200	28200	28200	28200	28200	28200	28200	28200	28200
Torque	RTORQ	117000	117000	117000	117000	117000	117000	117000	117000	117000	117000	117000	117000	117000	117000	117000	117000	117000	117000	117000
Coning angle	REETA	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2
<u>TAIL ROTOR</u>																				
Loading harmonic factor (c)	TCASE	2.5	2.5	2.5	2.5	2.5	2.5	2.5	2.5	2.5	2.5	2.5	2.5	2.5	2.5	2.5	2.5	2.5	2.5	2.5
Radial loading station %R (b)	TEETA	0.8	0.8	0.8	0.8	0.8	0.8	0.8	0.8	0.8	0.8	0.8	0.8	0.8	0.8	0.8	0.8	0.8	0.8	0.8
Number of blades	TBIBG	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6
Radius	TEIGR	6.5	6.5	6.5	6.5	6.5	6.5	6.5	6.5	6.5	6.5	6.5	6.5	6.5	6.5	6.5	6.5	6.5	6.5	6.5
Rotational speed	TOMEGR	1030	1030	1030	1030	1030	1030	1030	1030	1030	1030	1030	1030	1030	1030	1030	1030	1030	1030	1030
Disk incidence	TSID	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
Blade chord	TCHORD	9.2	9.2	9.2	9.2	9.2	9.2	9.2	9.2	9.2	9.2	9.2	9.2	9.2	9.2	9.2	9.2	9.2	9.2	9.2
Thrust	TTHRUS	2150	2150	2150	2150	2150	2150	2150	2150	2150	2150	2150	2150	2150	2150	2150	2150	2150	2150	2150
Torque	TTORQ	795	795	795	795	795	795	795	795	795	795	795	795	795	795	795	795	795	795	795
Coning angle	TEETA	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

- (a) Typical value is 1.8 to 2.0 for most multi-blade rotor systems
- (b) Use a value of 0.8 for normal rotor systems
- (c) Typical value is 1.9 to 2.2 for most rotors

CASE NUMBER: Sample #1 DESCRIPTION: Checkout case for subroutine ROTOR

Sample Case 1 (Rotor)

LOADER CARD INPUT

COLUMN	2	4	6	19	31	43	55	67
*	*	*	*	*	*	*	*	*
5	1	1117.	5.	1.	2.	0.8		
5	6	29.4	228.	0.	15.			
5	11	28200.	117000.	2.	2.5	0.8		
5	16	6.	6.5	1030.	0.	9.2		
3	21	2150.	795.	0.				
3	30	2.	1.	2.	1.	2.		
3	80	1000.	0.	2000.				
3	130	0.	0.	1240.				
4	180	0.	60.	0.	30.			
4	230	0.	500.	0.	500.			
5	280	75.	100.	150.	175.	175.		
5	330	15.	5.	10.	10.	20.		
5	380	2500.	500.	0.	0.	1.		
1	385	1.						
-5	417	1.	0.	0.	0.	0.		

*****INPUT VARIABLES*****
 *****FLIGHT SEGMENT 1*****

COMMON VARIABLES :

SAZ = 1117.00 SEG = 5.00 ROTR = 1.0 RP = .0 FANS = .0 RJ = .0 E = .0 ANMFT = 1.0

MAIN ROTOR VARIABLES :

SM-K = 2.00 BIGB = 6.00 BGR = 29.40 OMEGN = 228.00 THRUS = 28200.0
 ETA = .80 BETA = 2.00 CHORD = 15.00 SID = .00 TORQ = 117000.0

TAIL ROTOR VARIABLES :

SM-K = 2.50 BIGB = 6.00 BGR = 6.50 OMEGN = 1030.00 THRUS = 2150.0
 ETA = .80 BETA = .00 CHORD = 9.20 SID = .00 TORQ = 795.0

PROPELLER VARIABLES :

POWER = .0 DIA = .00 BIGB = .0 RPM = .00 NUMPRP = .0 CHORD = .00

ENGINE VARIABLES :

POWER = .0 SLEVEL = .0 NUMENG = .0

FAN VARIABLES :

DIAT = .00 B = .00 DDDXT = .00 RS = .00 TT2 = .00 DF = .00 SIGPHI = .00 RPM = .00
DIAH = .00 BPR = .00 DDDXH = .00 DL = .00 PT2 = .00 PR = .00 XMTIP = .00 SPAF = .00
CHORD = .00 COMB = .00 ALFA = .00 FN = .00

JET VARIABLES :

THRUST = .0 WTFL = .00 AREAJ = .00 PSUBA = .00 TSUBA = .00 TSUBJ = .0 TSUBJO = .0 ALFA = .0

FIELD POINT VARIABLES :

AZERO = .00 XPRZRO = 2500.0 YPRZRO = 500.0 TINC = 1.00 THMAXO = .00 ANMFPT = 1.00

SEG THETA SPEED XBREAK YBREAK INCMAX

1	15.00	75.00	1000.00	.00	13
2	5.00	100.00	1433.02	250.02	19
3	10.00	150.00	2000.00	1232.14	26
4	10.00	175.00	2066.98	1482.15	28
5	20.00	175.00	.00	.00	0

LOADER CARD INPUT

COLUMN 2 4 6	19	31	43	55	67
* * *	*	*	*	*	*
* * *	*	*	*	*	*
* * *	*	*	*	*	*
-1 9	2.				

*****INPUT VARIABLES*****
*****FLIGHT SEGMENT 2*****

COMMON VARIABLES :

SAZ = 1117.00 SEG = 5.00 ROTR = 1.0 RP = .0 FANS = .0 RJ = .0 E = 1.0 ANMFPT = 1.0

MAIN ROTOR VARIABLES :

SM-K = 2.00 BIGB = 6.00 BGR = 29.40 OMEGN = 228.00 THRUS = 28200.0
ETA = .80 BETA = 2.00 CHORD = 15.00 SID = 2.00 TORQ = 117000.0

TAIL ROTOR VARIABLES :

SM-K = 2.50 BIGB = 6.00 BGR = 6.50 OMEGN = 1030.00 THRUS = 2150.0
ETA = .80 BETA = .00 CHORD = 9.20 SID = .00 TORQ = 795.0

PROPELLER VARIABLES :

POWER = .0 DIA = .00 BIGB = .0 RPM = .00 NUMPRP = .0 CHORD = .00

ENGINE VARIABLES :

POWER = .0 SLEVEL = .0 NUMENG = .0

FAN VARIABLES :

DIAT = .00 B = .00 DDDXT = .00 RS = .00 TT2 = .00 DF = .00 SIGPHI = .00 RPM = .00
DIAH = .00 BPR = .00 DDDXH = .00 DL = .00 PT2 = .00 PR = .00 XMATIP = .00 SPAF = .00
CHORD = .00 COMB = .00 ALFA = .00 FN = .00

JET VARIABLES :

THRUST = .0 WTFL = .00 AREAJ = .00 PSUBA = .00 TSUBA = .00 TSUBJ = .0 TSUBJO = .0 ALFA = .0

FIELD POINT VARIABLES :

AZERO = .00 XPRZO = 2500.0 YPRZO = 500.0 TINC = 1.00 THMAXO = .00 ANMFPT = 1.00

SEG	THETA	SPEED	XBREAK	YBREAK	INC MAX
1	15.00	75.00	1000.00	.00	13
2	5.00	100.00	1433.02	250.02	19
3	10.00	150.00	2000.00	1232.14	26
4	10.00	175.00	2066.98	1482.15	28
5	20.00	175.00	.00	.00	0

LOADER CARD INPUT

COLUMN	2	4	6	19	31	43	55	67
	*	*	*	*	*	*	*	*
	*	*	*	*	*	*	*	*
	-1	9		5.				

*****INPUT VARIABLES*****
*****FLIGHT SEGMENT 3*****

COMMON VARIABLES :

SAZ = 1117.00 SEG = 5.00 ROTR = 1.0 RP = .0 FANS = .0 RJ = .0 E = 1.0 ANMFPT = 1.0

MAIN ROTOR VARIABLES :

SM-K = 2.00 BIGB = 6.00 BIGR = 29.40 OMEGN = 228.00 THRUS = 28200.0
ETA = .80 BETA = 2.00 CHORD = 15.00 SID = 5.00 TORQ = 117000.0

TAIL ROTOR VARIABLES :

SM-K = 2.50 BIGB = 6.00 BIGR = 6.50 OMEGN = 1030.00 THRUS = 2150.0
ETA = .80 BETA = .00 CHORD = 9.20 SID = .00 TORQ = 795.0

PROPELLER VARIABLES :

POWER = .0 DIA = .00 BIGB = .0 RPM = .00 NUMPRP = .0 CHORD = .00

ENGINE VARIABLES :

POWER = .0 SLEVEL = .0 NUMENG = .0

FAN VARIABLES :

DIAT = .00 B = .00 DDDXT = .00 RS = .00 TT2 = .00 DF = .00 SIGPHI = .00 RPM = .00
 DIAH = .00 BPR = .00 DDDXH = .00 DL = .00 PT2 = .00 PR = .00 XMXTIP = .00 SPAF = .00
 CHORD = .00 COMB = .00 ALFA = .00 FN = .00

JET VARIABLES :

THRUST = .0 WTFL = .00 AREAJ = .00 PSUBA = .00 TSUBA = .00 TSUBJ = .00 TSUBJO = .00 ALFA = .00

FIELD POINT VARIABLES :

AZERO = .00 XPRZRO = 2500.0 YPRZRO = 500.0 TINC = 1.00 THMAXO = .00 ANMFPT = 1.00

SEG	THETA	SPEED	XBREAK	YBREAK	INCMAX
1	15.00	75.00	1000.00	.00	13
2	5.00	100.00	1433.02	250.02	19
3	10.00	150.00	2000.00	1232.14	26
4	10.00	175.00	2066.98	1482.15	28
5	20.00	175.00	.00	.00	0

LOADER CARD INPUT

COLUMN 2 4 6 19 31 43 55 67
 * * * * *
 * * * * *
 * * * * *
 * * * * *

*****INPUT VARIABLES*****
 *****FLIGHT SEGMENT 4*****

COMMON VARIABLES :

SAZ = 1117.00 SEG = 5.00 ROTR = 1.0 RP = .0 FANS = .0 RJ = .0 E = 1.0 ANMFPT = 1.0

MAIN ROTOR VARIABLES :

SM-K = 2.00 BIG8 = 6.00 BIGN = 29.40 OMEGN = 228.00 THRU8 = 28200.0
ETA = .80 BETA = 2.00 CHORD = 15.00 SID = 5.00 TOR8 = 117000.0

TAIL ROTOR VARIABLES :

SM-K = 2.50 BIG8 = 6.00 BIGN = 6.50 OMEGN = 1030.00 THRU8 = 2150.0
ETA = .80 BETA = .00 CHORD = 9.20 SID = .00 TOR8 = 795.0

PROPELLER VARIABLES :

POWER = .0 DIA = .00 BIG8 = .0 RPM = .00 NUMPRP = .0 CHORD = .00

ENGINE VARIABLES :

POWER = .0 SLEVEL = .0 NUMENG = .0

FAN VARIABLES :

DIAT = .00 B = .00 DDDXT = .00 RS = .00 TT2 = .00 DF = .00 SIGPHI = .00 RPM = .00
DIAH = .00 BPR = .00 DDDXH = .00 DL = .00 PT2 = .00 PR = .00 XMTIP = .00 SPAF = .00
CHORD = .00 COMB = .00 ALFA = .00 FN = .00

JET VARIABLES :

THRUST = .0 WTFL = .00 AREAJ = .00 PSUBA = .00 TSUBA = .00 TSUBJ = .0 TSUBJO = .0 ALFA = .0

FIELD POINT VARIABLES :

AZERO = .00 XPRZRO = 2500.0 YPRZRO = 500.0 TINC = .00 THMAXO = .00 ANMFPT = 1.00

SEG	THETA	SPEED	XBREAK	YBREAK	INCMAX
1	15.00	75.00	1000.00	.00	13
2	5.00	100.00	1433.02	250.02	19
3	10.00	150.00	2000.00	1232.14	26
4	10.00	175.00	2066.98	1462.15	28
5	20.00	175.00	.00	.00	0

LOADER CARD INPUT

COLUMN 2 4 6	19	31	43	55	67
* * *	*	*	*	*	*
* * *	*	*	*	*	*
-1 9	5.				

*****INPUT VARIABLES*****
*****FLIGHT SEGMENT 5*****

COMMON VARIABLES :

SAZ = 1117.00 SEG = 5.00 ROTR = 1.0 RP = .0 FANS = .0 RJ = .0 E = 1.0 ANMFT = 1.0

MAIN ROTOR VARIABLES :

SM-K = 2.00 BIGR = 6.00 BIGR = 29.40 OMEGN = 228.00 THRUS = 20200.0
 ETA = .80 BETA = 2.00 CHORD = 15.00 SID = 5.00 TORQ = 117000.0

TAIL ROTOR VARIABLES :

SM-K = 2.50 BIGR = 6.00 BIGR = 6.50 OMEGN = 1030.00 THRUS = 2150.0
 ETA = .80 BETA = .00 CHORD = 9.20 SID = .00 TORQ = 795.0

PROPELLER VARIABLES :

POWER = .0 DIA = .00 BIGB = .0 RPM = .00 NUMPRP = .0 CHORD = .00

ENGINE VARIABLES :

POWER = .0 SLEVEL = .0 NUMENG = .0

FAN VARIABLES :

DIAT = .00 B = .00 DDDXT = .00 RS = .00 TT2 = .00 DF = .00 SIGPHI = .00 RPM = .00
 DIAH = .00 BPR = .00 DDDXH = .00 DL = .00 PT2 = .00 PR = .00 XNXTIP = .00 SPAF = .00
 CHORD = .00 COMB = .00 ALFA = .00 FN = .00

JET VARIABLES :

THRUST = .0 WTFL = .00 AREAJ = .00 PSUBA = .00 TSUBA = .00 TSUBJ = .0 TSUBJO = .0 ALFA = .0

FIELD POINT VARIABLES :

AZERO = .00 XPRZRO = 2500.0 YPRZRO = 500.0 TINC = 1.00 THMAXO = .00 ANMFPT = 1.00

SEG	THETA	SPEED	XBREAK	YBREAK	INCMAX
1	15.00	75.00	1000.00	.00	13
2	5.00	100.00	1433.02	250.02	19
3	10.00	150.00	2000.00	1232.14	26
4	10.00	175.00	2066.98	1482.15	28
5	20.00	175.00	.00	.00	0

CHECKOUT CASE FOR V/STOL VEHICLE NOISE PREDICTION PROGRAM

TINC = 1.00 XPRZRO = 2500.00 YPRZRO = 500.00 AZERO = .00 THMAXO = .00

SEG	PATH	ALFN	VF1	XMAX	YMAX	RADIUS	PHIMAX
1	2.0	15.0	75.0	1000.0	.0	.0	.0
2	1.0	5.0	100.0	1433.0	250.0	500.0	60.0
3	2.0	10.0	150.0	2000.0	1232.1	.0	.0
4	1.0	10.0	175.0	2067.0	1482.1	500.0	30.0
5	2.0	20.0	175.0	.0	.0	.0	.0

RANGE	EPNL	PNLTM	PNL	DBA	XPR
913.6	83.77	84.17	84.17	72.38	2500.0

PNLT TIME HISTORY IN 1.0 SECOND INCREMENTS FOR 1 FIELD POINTS

66.07	66.50	66.95	67.75	67.71	68.23	68.77	69.64	70.54	71.18
71.84	72.53	73.47	73.77	74.85	75.76	76.81	78.25	79.54	80.80
82.05	83.15	83.85	84.17	84.12	83.64	83.00	81.49	79.52	78.07
76.78	75.34	74.23	73.19	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00

PNLT TIME HISTORY IN 1.0 SECOND INCREMENTS FOR 1 FIELD POINTS

65.52	65.97	66.43	67.25	67.71	68.23	68.77	69.64	70.54	71.18
71.84	72.53	73.47	73.77	74.85	75.76	76.81	78.25	79.54	80.80
82.05	83.15	83.85	84.17	84.12	83.64	83.00	81.49	79.52	78.07
76.78	75.34	74.23	73.19	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00

DBA TIME HISTORY IN 1.0 SECOND INCREMENTS FOR 1 FIELD POINTS

56.05	56.47	56.90	57.36	57.80	58.29	58.81	59.35	59.92	60.51
61.13	61.77	62.44	62.62	63.48	64.39	65.34	66.67	67.85	68.90
70.09	71.24	71.94	72.33	72.38	71.96	71.45	70.12	68.55	67.21
66.03	64.84	63.79	62.82	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00

FORM 1
V/STOL NOISE MODEL

CASE: Sample #2

DESCRIPTION: Checkout case for subroutine PROP

SEG	(a) PATH	X' max (ft)	Y' max (ft)	(b) ϕ max (deg)	RADIUS (ft)	V _f (ft/sec)	α_n (deg)
1	2.	1000.	0.	-	-	75.	15.
2	1.	-	-	60.	500.	100.	5.
3	2.	2000.	1240.	-	-	150.	10.
4	1.	-	-	30.	500.	175.	10.
5	2.	-	-	-	-	175.	20.
6							
7							
8							
9							
10							
11							
12							
13							
14							
15							
16							
17							
18							
19							
20							
21							
22							
23							
24							
25							

(a) Flight path type: 1=helical, 2=straight

(b) Positive for counterclockwise, negative for clockwise turns

V/STOL NOISE MODEL

FORM 2

CASE: Sample #2
 FLIGHT SEGMENT NUMBER: 1

DESCRIPTION: Checkout for Subroutine PROP
 Since parameters do not change from segment to segment only dummy inputs will be provided for segments 2- 5 (see coding sheet)

LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE
1	SAZ	1146.	80	XMAX(1)	1000.	235	RADIUS(6)		390	DIAM	
2	SEG	5.	81	XMAX(2)		236	RADIUS(7)		391	B	
3	FLTYPE	1.	82	XMAX(3)	2000.	237	RADIUS(8)		392	BPR	
4	RCASE		83	XMAX(4)		238	RADIUS(9)		393	CHORD	
5	RETA		84	XMAX(5)		239	RADIUS(10)		394	DDXT	
6	RBIGB		85	XMAX(6)		+	+		395	DDXH	
7	RBIGR		86	XMAX(7)		279	RADIUS(50)		396	RS	
8	ROMEGN		87	XMAX(8)		280	VF1(1)	75.	397	SIGPHI	
9	RSID		88	XMAX(9)		281	VF1(2)	100.	398	DL	
10	RCHORD		89	XMAX(10)		282	VF1(3)	150.	399	RPM	
11	RTHRUS		+	+		283	VF1(4)	175.	400	SPAF	
12	RTORQ		129	XMAX(50)		284	VF1(5)	175.	401	XMXTIP	
13	RBETA		130	YMAX(1)	0.	285	VF1(6)		402	PR	
14	TCASE		131	YMAX(2)		286	VF1(7)		403	DF	
15	TETA		132	YMAX(3)	1240.	287	VF1(8)		404	TT2	
16	TBIGB		133	YMAX(4)		288	VF1(9)		405	PT2	
17	TBIGR		134	YMAX(5)		289	VF1(10)		406	ALFA	
18	TOMEGN		135	YMAX(6)		+	+		407	FN	
19	TSID		136	YMAX(7)		329	VF1(50)		408	COMB	
20	TCHORD		137	YMAX(8)		330	ALF(1)	15.	409	THRUST	
21	TTHRUS		138	YMAX(9)		331	ALF(2)	5.	410	WTFI	
22	TTORQ		139	YMAX(10)		332	ALF(3)	10.	411	AREAJ	
23	TBETA		+	+		333	ALF(4)	10.	412	PSUBA	
24	PPWR	3260.	179	YMAX(50)		334	ALF(5)	20.	413	TSUBA	
25	DIA	13.5	180	PHMAX(1)		335	ALF(6)		414	TSUBJ	
26	BIGB	4.	181	PHMAX(2)	60.	336	ALF(7)		415	TSUBJO	
27	RPMP	1020.	182	PHMAX(3)		337	ALF(8)		416	ALFAJ	
28	ANMPRP	4.	183	PHMAX(4)	30.	338	ALF(9)		417	ROTR	0.
29	CHORDP	.75	184	PHMAX(5)		339	ALF(10)		418	RP	1.
30	PATH(1)	2.	185	PHMAX(6)		+	+		419	FANS	0.
31	PATH(2)	1.	186	PHMAX(7)		379	ALF(50)		420	RJ	0.
32	PATH(3)	2.	187	PHMAX(8)		380	XPRZRO	2500.	421	E	0.
33	PATH(4)	1.	188	PHMAX(9)		381	YPRZRO	500.			
34	PATH(5)	2.	189	PHMAX(10)		382	THMAXO	0.			
35	PATH(6)		+	+		383	AZERO	0.			
36	PATH(7)		229	PHMAX(50)		384	TINC	1.			
37	PATH(8)		230	RADIUS(1)		385	ANMFPT	1.			
38	PATH(9)		231	RADIUS(2)	500.	386	HPENG				
39	PATH(10)		232	RADIUS(3)		387	SLEVEL				
+	+		233	RADIUS(4)	500.	388	ANENG				
79	PATH(50)		234	RADIUS(5)		389	DIAT				

FORM 4
V/STOL NOISE MODEL
Propeller Parameters

VARIABLE	PROG NAME	FLIGHT PATH SEGMENT NUMBERS -																		
		1	2	3	4	5	6	7	8	9	10									
Shaft power	hp	3260	3260	3260	3260	3260	3260	3260	3260	3260										
Diameter	ft	13.5	13.5	13.5	13.5	13.5	13.5	13.5	13.5	13.5										
Number of blades		4	4	4	4	4	4	4	4	4										
Rotational speed	rpm	1020	1020	1020	1020	1020	1020	1020	1020	1020										
Number of propellers		4	4	4	4	4	4	4	4	4										
Mean blade chord	ft	0.75	0.75	0.75	0.75	0.75	0.75	0.75	0.75	0.75										

CASE NUMBER: Sample #2

DESCRIPTION: Checkout case for Subroutine_PROP

Sample Case 2 (Prop)

 LOADER CARD INPUT

COLUMN	2	4	6	19	31	43	55	67
*	*	*	*	*	*	*	*	*
3	1	1146.	5.	1.				
5	24	3260.	13.5	4.	1020.	4.		
1	34	.75	2.	1.	2.	1.		
3	80	1000.	0.	2000.				
3	130	0.	0.	1240.				
4	180	0.	60.	0.	30.			
4	230	0.	500.	0.	500.			
5	280	75.	100.	150.	175.	175.		
5	330	15.	5.	10.	10.	20.		
5	380	2500.	500.	0.	0.	1.		
1	385	1.						
-5	417	0.	1.	0.	0.	0.		

 INPUT VARIABLES

 FLIGHT SEGMENT 1

COMMON VARIABLES :

SAZ = 1146.00 SEG = 5.00 ROTR = .0 RP = 1.0 FANS = .0 RJ = .0 E = .0 ANMFT = 1.0

MAIN ROTOR VARIABLES :

SM-K = .00 BIGR = .00 BGR = .00 OMEGN = .00 THRS = .0
 ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .0

TAIL ROTOR VARIABLES :

SM-K = .00 BIGR = .00 BGR = .00 OMEGN = .00 THRS = .0
 ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .0

PROPELLER VARIABLES :

POWER = 3260.0 DIA = 13.50 BIGB = 4.0 RPM = 1020.00 NUMPRP = 4.0 CHORD = .75

ENGINE VARIABLES :

POWER = .0 SLEVEL = .0 NUMENG = .0

FAN VARIABLES :

DIAT = .00 B = .00 DDDXT = .00 RS = .00 TT2 = .00 DF = .00 SIGPHI = .00 RPM = .00
DIAH = .00 BPR = .00 DDDXH = .00 DL = .00 PT2 = .00 PR = .00 XMXTIP = .00 SPAF = .00
CHORD = .00 COMB = .00 ALFA = .00 FN = .00

JET VARIABLES :

THRUST = .0 WFL = .00 AREAJ = .00 PSUBA = .00 TSUBA = .00 TSUBJ = .00 TSUBJO = .00 ALFA = .0

FIELD POINT VARIABLES :

AZERO = .00 XPRZRO = 2500.0 YPRZRO = 500.0 TINC = 1.00 THMAXO = .00 ANMFPT = 1.00

SEG	THETA	SPEED	XBREAK	YBREAK	INCMAX
1	15.00	75.00	1000.00	.00	13
2	5.00	100.00	1433.02	250.02	19
3	10.00	150.00	2000.00	1232.14	26
4	10.00	175.00	2066.98	1482.15	28
5	20.00	175.00	.00	.00	0

LOADER CARD INPUT

COLUMN	2	4	6	19	31	43	55	67
*	*	*	*	*	*	*	*	*
	-1	3	1,					

*****INPUT VARIABLES*****
*****FLIGHT SEGMENT 2*****

COMMON VARIABLES :

SAZ = 1146.00 SEG = 5.00 ROTR = .0 RP = 1.0 FANS = .0 RJ = .0 E = .0 ANMFPT = 1.0

MAIN ROTOR VARIABLES :

SM-K = .00 BIGB = .00 BIGH = .00 OMEGN = .00 THRUS = .0
ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .0

TAIL ROTOR VARIABLES :

SM-K = .00 BIGB = .00 BIGH = .00 OMEGN = .00 THRUS = .0
ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .0

PROPELLER VARIABLES :

POWER = 3260.0 DIA = 13.50 BIGB = 4.0 RPM = 1020.00 NUMPRP = 4.0 CHORD = .75

ENGINE VARIABLES :

POWER = .0 SLEVEL = .0 NUMENG = .0

FAN VARIABLES :

DIAT = .00 B = .00 DDDXT = .00 RS = .00 TT2 = .00 DF = .00 SIGPHI = .00 RPM = .00
DIAH = .00 BPR = .00 DDDXH = .00 DL = .00 PT2 = .00 PR = .00 XMXTIP = .00 SPAF = .00
CHORD = .00 COMB = .00 ALFA = .00 FN = .00

JET VARIABLES :

THRUST = .0 WTFL = .00 AREAJ = .00 PSUBA = .00 TSUBA = .00 TSUBJ = .0 TSUBJO = .0 ALFA = .0

FIELD POINT VARIABLES :

AZERO = .00 XPRZRO = 2500.0 YPRZRO = 500.0 TINC = 1.00 THMAXO = .00 ANMFPT = 1.00

SEG	THETA	SPEED	XBREAK	YBREAK	INCMAX
1	15.00	75.00	1000.00	.00	13
2	5.00	100.00	1433.02	250.02	19
3	10.00	150.00	2000.00	1232.14	26
4	10.00	175.00	2066.98	1482.15	28
5	20.00	175.00	.00	.00	0

 LOADER CARD INPUT

COLUMN	2	4	6	19	31	43	55	67
	*	*	*	*	*	*	*	*
	-1	3	1.					

*****INPUT VARIABLES*****
 *****FLIGHT SEGMENT 3*****

COMMON VARIABLES :

SAZ = 1146.00 SEG = 5.00 ROTR = .0 RP = 1.0 FANS = .0 RJ = .0 E = .0 ANMFPT = 1.0

---MAIN ROTOR VARIABLES :

SM-K = .00 BIGB = .00 BGR = .00 OMEGN = .00 THRUS = .0
 ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .0

---TAIL ROTOR VARIABLES :

SM-K = .00 BIGB = .00 BGR = .00 OMEGN = .00 THRUS = .0
 ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .0

---PROPELLER VARIABLES :

POWER = 3260.0 DIA = 13.50 BIGB = 4.0 RPM = 1020.00 NUMPRP = 4.0 CHORD = .75

ENGINE VARIABLES :

POWER = .0 SLEVEL = .0 NUMENG = .0

FAN VARIABLES :

DIAT = .00 B = .00 DDDXT = .00 RS = .00 TT2 = .00 DF = .00 SIGPHI = .00 RPM = .00
DIAH = .00 BPR = .00 DDDXH = .00 DL = .00 PT2 = .00 PR = .00 XMXTIP = .00 SPAF = .00
CHORD = .00 COMBE .00 ALFA = .00 FN = .00

JET VARIABLES :

THRUST = .0 WFTL = .00 AREAJ = .00 PSUBA = .00 TSUBA = .00 TSUBJ = .0 TSUBJO = .0 ALFA = .0

FIELD POINT VARIABLES :

AZERO = .00 XPRZRO = 2500.0 YPRZRO = 500.0 TINC = 1.00 THMAXO = .00 ANMFPT = 1.00

SEG	THETA	SPEED	XBREAK	YBREAK	INCMAX
1	15.00	75.00	1000.00	.00	13
2	5.00	100.00	1433.02	250.02	19
3	10.00	150.00	2000.00	1232.14	26
4	10.00	175.00	2066.98	1482.15	28
5	20.00	175.00	.00	.00	0

LOADER CARD INPUT

COLUMN	2	4	6	19	31	43	55	67
	*	*	*	*	*	*	*	*
	*	*	*	*	*	*	*	*
	-1	3	1.					

*****INPUT VARIABLES*****
*****FLIGHT SEGMENT *****

COMMON VARIABLES :

SAZ = 1146.00 SEG = 5.00 ROTR = .0 RP = 1.0 FANS = .0 RJ = .0 E = .0 ANNFPT = 1.0

MAIN ROTOR VARIABLES :

SM-K = .00 BIGB = .00 BGR = .00 OMEGN = .00 THRUS = .0
ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .0

TAIL ROTOR VARIABLES :

SM-K = .00 BIGB = .00 BGR = .00 OMEGN = .00 THRUS = .0
ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .0

PROPELLER VARIABLES :

POWER = 3260.0 DIA = 13.50 BIGB = 4.0 RPM = 1020.00 NUMPRP = 4.0 CHORD = .75

ENGINE VARIABLES :

POWER = .0 SLEVEL = .0 NUMENG = .0

FAN VARIABLES :

DIA1 = .00 B = .00 DDDXT = .00 RS = .00 TT2 = .00 DF = .00 SIGPHI = .00 RPM = .00
DIAH = .00 BPR = .00 DDDXH = .00 DL = .00 PT2 = .00 PR = .00 XMXTIP = .00 SPAF = .00
CHORD = .00 COMB = .00 ALFA = .00 FN = .00

JET VARIABLES :

THRUST = .0 WTFL = .00 AREAJ = .00 PSUBA = .00 TSUBA = .00 TSUBJ = .0 TSUBJO = .0 ALFA = .0

FIELD POINT VARIABLES :

AZERO = .00 XPRZRO = 2500.0 YPRZRO = 500.0 TIMC = 1.00 THMAXO = .00 ANNFPT = 1.00

SEG	THETA	SPEED	XBREAK	YBREAK	INCMAX
1	15.00	75.00	1000.00	.00	13
2	5.00	100.00	1433.02	250.02	19
3	10.00	150.00	2000.00	1232.14	26
4	10.00	175.00	2066.98	1482.15	28
5	20.00	175.00	.00	.00	0

CHECKOUT CASE FOR V/STOL VEHICLE NOISE PREDICTION PROGRAM

TINC= 1.00 XPRZRO= 2500.00 YPRZRO= 500.00 AZERO= .00 THMAXO= .00
 SEG PATH ALFN VF1 XMAX YMAX RADIUS PHIMAX
 1 2.0 15.0 75.0 1000.0 .0 .0
 2 1.0 5.0 100.0 1433.0 250.0 500.0 60.0
 3 2.0 10.0 150.0 2000.0 1232.1 .0
 4 1.0 10.0 175.0 2067.0 1482.1 500.0 30.0
 5 2.0 20.0 175.0 .0 .0 .0

RANGE EPNL PNL PNLTM PNL DBA XPR
 913.6 95.36 96.46 93.13 78.61 2500.0

PNLT TIME HISTORY IN 1.0 SECOND INCREMENTS FOR 1 FIELD POINTS

79.65	80.20	80.60	81.00	81.42	82.01	82.45	82.91	83.38	84.01
84.65	85.17	85.72	86.04	85.31	86.17	88.38	90.52	92.72	93.98
94.86	95.56	96.09	96.40	96.46	96.29	94.97	86.15	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00

PNL TIME HISTORY IN 1.0 SECOND INCREMENTS FOR 1 FIELD POINTS

76.31	76.87	77.26	77.67	78.09	78.67	79.12	79.58	80.05	80.68
81.31	81.84	82.39	82.71	81.97	82.84	85.05	87.19	89.39	90.64
91.52	92.23	92.76	93.06	93.13	92.96	91.64	82.82	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00

DBA TIME HISTORY IN 1.0 SECOND INCREMENTS FOR 1 FIELD POINTS

63.57	63.89	64.22	64.57	64.92	65.28	65.66	66.04	66.44	66.85
67.28	67.72	68.17	68.43	67.79	68.42	70.46	72.64	74.90	76.15
76.96	77.67	78.21	78.53	78.61	78.47	77.17	68.35	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00

FORM 1
V/STOL NOISE MODEL

CASE: Sample #3

DESCRIPTION: Checkout Case for Subroutine FAN

SEG	(a) PATH	X' _{max} (ft)	Y' _{max} (ft)	(b) ϕ max (deg)	RADIUS (ft)	V _f (ft/sec)	α_n (deg)
1	2.	1000.	0.	-	-	75.	15.
2	1.	-	-	60.	500.	100.	5.
3	2.	2000.	1240.	-	-	150.	10.
4	1.	-	-	30.	500.	175.	10.
5	2.	-	-	-	-	175.	20.
6							
7							
8							
9							
10							
11							
12							
13							
14							
15							
16							
17							
18							
19							
20							
21							
22							
23							
24							
25							

- (a) Flight path type: 1 = helical, 2 = straight
 (b) Positive for counterclockwise, negative for clockwise turns

V/STOL NOISE MODEL

FORM 2

CASE: Sample #3
 FLIGHT SEGMENT NUMBER: 1

DESCRIPTION: Checkout case for subroutine FAN
 Since parameters do not change from segment to segment only dummy inputs will be provided for segments 2 - 5 (see coding sheet).

LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE
1	SAZ	1080.	80	XMAX(1)	1000.	235	RADIUS(6)		390	DIAH	20.2
2	SEG	2.	81	XMAX(2)		236	RADIUS(7)		391	B	46.
3	FLTYPE	1.	82	XMAX(3)	2000.	237	RADIUS(8)		392	BPR	5
4	RCASE		83	XMAX(4)		238	RADIUS(9)		393	CHORD	4.38
5	RETA		84	XMAX(5)		239	RADIUS(10)		394	DDDXT	5
6	RBIGB		85	XMAX(6)			+	+	395	DDDXH	.44
7	RBIGR		86	XMAX(7)		279	RADIUS(50)		396	RS	-12.78
8	ROMEGR		87	XMAX(8)		280	VF1(1)	75.	397	SIGPHI	.02
9	RSID		88	XMAX(9)		281	VF1(2)	100.	398	DL	3.
10	RCHORD		89	XMAX(10)		282	VF1(3)	150.	399	RPM	4690
11	RTHRUS			+		283	VF1(4)	175.	400	SPAF	30.6
12	RTORQ		129	XMAX(50)		284	VF1(5)	175.	401	XMXTIP	.331
13	RBETA		130	YMAX(1)	0.	285	VF1(6)		402	PR	1.317
14	TCASE		131	YMAX(2)		286	VF1(7)		403	DF	.454
15	TETA		132	YMAX(3)	1240.	287	VF1(8)		404	TT2	21.
16	TBIGB		133	YMAX(4)		288	VF1(9)		405	PT2	29.90
17	TBIGR		134	YMAX(5)		289	VF1(10)		406	ALFA	0.
18	TOMEGN		135	YMAX(6)			+	+	407	FN	1.
19	TSID		136	YMAX(7)		329	VF1(50)		408	COMB	1.
20	TCHORD		137	YMAX(8)		330	ALF(1)	15.	409	THRUST	
21	TTHRUS		138	YMAX(9)		331	ALF(2)	5.	410	WTFI	
22	TTORQ		139	YMAX(10)		332	ALF(3)	10.	411	AREAJ	
23	TBETA			+		333	ALF(4)	10.	412	PSUBA	
24	PPWR		179	YMAX(50)		334	ALF(5)	20.	413	TSUBA	
25	DIA		180	PHMAX(1)		335	ALF(6)		414	TSUBJ	
26	BIGB		181	PHMAX(2)	60.	336	ALF(7)		415	TSUBJO	
27	RPMP		182	PHMAX(3)		337	ALF(8)		416	ALFAJ	
28	ANMPRP		183	PHMAX(4)	30.	338	ALF(9)		417	ROTR	0.
29	CHORDP		184	PHMAX(5)		339	ALF(10)		418	RP	0.
30	PATH(1)	2.	185	PHMAX(6)			+	+	419	FANS	1.
31	PATH(2)	1.	186	PHMAX(7)		379	ALF(50)		420	RJ	0.
32	PATH(3)	2.	187	PHMAX(8)		380	XPRZRO	2500.	421	E	0.
33	PATH(4)	1.	188	PHMAX(9)		381	YPRZRO	500.			
34	PATH(5)	2.	189	PHMAX(10)		382	THMAXO	0.			
35	PATH(6)			+		383	AZERO	0.			
36	PATH(7)		229	PHMAX(50)		384	TINC	2.			
37	PATH(8)		230	RADIUS(1)		385	ANMFPT	1.			
38	PATH(9)		231	RADIUS(2)	500.	386	HPENG				
39	PATH(10)		232	RADIUS(3)		387	SLEVEL				
				+		388	ANENG				
79	PATH(50)		234	RADIUS(5)	500.	389	DIAT	52.3			

FORM 7
V/STOL NOISE MODEL
FAN Engine Parameters

VARIABLE	PROG NAME	FLIGHT PATH SEGMENT NUMBER																		
		1	2	3	4	5	6	7	8	9	10									
Tip diameter	DIAT	52.3	52.3	52.3	52.3	52.3	52.3	52.3	52.3	52.3										
Hub diameter	DIAB	20.2	20.2	20.2	20.2	20.2	20.2	20.2	20.2	20.2										
Number of blades	B	46	46	46	46	46	46	46	46	46										
Bypass ratio	BPR	5	5	5	5	5	5	5	5	5										
Blade tip chord	CHORD	4.38	4.38	4.38	4.38	4.38	4.38	4.38	4.38	4.38										
Tip diameter gradient(a)	in/in	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5										
Hub diameter gradient(a)	in/in	0.44	0.44	0.44	0.44	0.44	0.44	0.44	0.44	0.44										
Blade suction surface radius	RS	-12.78	-12.78	-12.78	-12.78	-12.78	-12.78	-12.78	-12.78	-12.78										
Standard deviation of blade	SIGPHI	.02	.02	.02	.02	.02	.02	.02	.02	.02										
tip metal angle(a)	DL	3	3	3	3	3	3	3	3	3										
Inlet duct length	RPM	4690	4690	4690	4690	4690	4690	4690	4690	4690										
Rotational speed	SPAF	30.6	30.6	30.6	30.6	30.6	30.6	30.6	30.6	30.6										
Specific airflow	lb/sec/ft ²	.331	.331	.331	.331	.331	.331	.331	.331	.331										
Tip axial Mach number	MXMTIP	1.317	1.317	1.317	1.317	1.317	1.317	1.317	1.317	1.317										
Pressure ratio	PR	.454	.454	.454	.454	.454	.454	.454	.454	.454										
Blade diffusion factor	DF	21.	21.	21.	21.	21.	21.	21.	21.	21.										
Ambient inlet temperature	F	29.9	29.9	29.9	29.9	29.9	29.9	29.9	29.9	29.9										
Ambient inlet pressure	in Hg	PT2	PT2	PT2	PT2	PT2	PT2	PT2	PT2	PT2										
Inclination to horizontal	deg	ALFA	ALFA	ALFA	ALFA	ALFA	ALFA	ALFA	ALFA	ALFA										
(+90° = vertical)		FN	FN	FN	FN	FN	FN	FN	FN	FN										
Number of fans	COMB	1	1	1	1	1	1	1	1	1										
Control factor to skip calculation of combination tones (0 = no)																				

(a) Need not be entered if COMB = 0

CASE NUMBER: Sample #3 DESCRIPTION: Checkout Case for Subroutine FAN

Sample Case 3 (Fan)

LOADER CARD INPUT

COLUMN	2	4	6	19	31	43	55	67
*	*	*	*	*	*	*	*	*
3	1	1080.	5.	1.	1.	2.		
5	30	2.	1.	2.	1.	2.		
3	80	1000.	0.	2000.				
3	130	0.	0.	1240.				
4	180	0.	60.	0.	30.			
4	230	0.	500.	0.	500.			
5	280	75.	100.	150.	175.	175.		
5	330	15.	5.	10.	10.	20.		
5	380	2500.	500.	0.	0.	2.		
1	385	1.						
5	389	52.3	20.2	46.	5.	4.3R		
5	394	0.5	.44	-12.779	.02	3.		
5	399	4690.	30.6	.331	1.317	.45R		
5	404	21.	29.9	0.	1.0	1.0		
-5	417	0.	0.	1.	0.	0.		

*****INPUT VARIABLES*****
*****FLIGHT SEGMENT 1*****

COMMON VARIABLES :

SAZ = 1080.00 SEG = 5.00 ROTR = .0 RP = .0 FANS = 1.0 RJ = .0 E = .0 ANMPT = 1.0

MAIN ROTOR VARIABLES :

SM-K = .00 BIGB = .00 BGR = .00 OMEGN = .00 THRUS = .0
ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .0

TAIL ROTOR VARIABLES :

SM-K = .00 BIGB = .00 BGR = .00 OMEGN = .00 THRUS = .0
ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .0

PROPELLER VARIABLES :

POWER = .0 DIA = .00 BIGB = .0 RPM = .00 NUMPRP = .0 CHORD = .00

ENGINE VARIABLES :

POWER = .0 SLEVEL = .0 NUMENG = .0

FAN VARIABLES :

DIAT = 52.30 B = 46.00 ODDXT = .50 RS = -12.78 TT2 = 21.00 DF = .45 SIGPMI = .02 RPM = 4690.00
DIAM = 20.20 BPR = 5.00 ODDXH = .44 DL = 3.00 PT2 = 29.90 PR = 1.32 XMTIP = .33 SPAF = 30.60
CHORDE = 4.38 COMB = 1.00 ALFA = .00 FN = 1.00

JET VARIABLES :

THRUST = .0 WTFL = .00 AREAJ = .00 PSUBA = .00 TSUBA = .00 TSUBJ = .0 TSUBJO = .0 ALFA = .0

FIELD POINT VARIABLES :

AZERO = .00 XPRZO = 2500.0 YPRZO = 500.0 TINC = 2.00 THMAXO = .00 ANMFPT = 1.00

SEG	THETA	SPEED	XBREAK	YBREAK	INCMAX
1	15.00	75.00	1000.00	.00	6
2	5.00	100.00	1433.02	250.02	9
3	10.00	150.00	2000.00	1232.14	13
4	10.00	175.00	2066.98	1482.15	14
5	20.00	175.00	.00	.00	0

LOADER CARD INPUT

COLUMN	2	4	6	19	31	43	55	67
	*	*	*	*	*	*	*	*
	*	*	*	*	*	*	*	*
	-1	3	1.					

*****INPUT VARIABLES*****
 *****FLIGHT SEGMENT 2*****

COMMON VARIABLES :

SAZ = 1080.00 SEG = 5.00 ROTR = .0 RP = .0 FANS = 1.0 RJ = .0 E = .0 ANMFPT = 1.0

MAIN ROTOR VARIABLES :

SM-K = .00 BIGB = .00 B1GR = .00 OMEGN = .00 THRUS = .0
 ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .0

TAIL ROTOR VARIABLES :

SM-K = .00 BIGB = .00 B1GR = .00 OMEGN = .00 THRUS = .0
 ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .0

PROPELLER VARIABLES :

POWER = .0 DIA = .00 BIGB = .0 RPM = .00 NUMPRP = .0 CHORD = .00

ENGINE VARIABLES :

POWER = .0 SLEVEL = .0 NUMENG = .0

FAN VARIABLES :

DIA1 = 52.30 B = 46.00 DDDXT = .50 RS = -12.78 IT2 = .21.00 DF = .45 SIGPHI = .02 RPM = 4690.00
 DIAH = 20.20 BPR = 5.00 DDDXH = .44 DL = 3.00 PT2 = 29.90 PR = 1.32 XMXTIP = .33 SPAF = 30.60
 CHORD = 4.38 COMB = 1.00 ALFA = .00 FN = 1.00

JET VARIABLES :

THRUST = .0 WTFL = .00 AREAJ = .00 PSUBA = .00 TSUBA = .00 TSUBJ = .0 TSUBJO = .0 ALFA = .0

FIELD POINT VARIABLES :

AZERO = .00 XPRZRO = 2500.0 YPRZRO = 500.0 TINC = 2.00 IHMAXO = .00 ANMFPT = 1.00

ENGINE VARIABLES :

POWER = .0 SLEVEL = .0 NUMENG = .0

FAN VARIABLES :

DIAT = 52.30 B = 46.00 DDDXT = .50 RS = -12.78 TT2 = 21.00 DF = .45 SIGPHI = .02 RPM = 4690.00
DIAH = 20.20 BPR = 5.00 DDDXH = .44 DL = 3.00 PT2 = 29.90 PR = 1.32 XMXTIP = .33 SPAF = 30.60
CHORDE = 4.38 COMB = 1.00 ALFA = .00 FN = 1.00

JET VARIABLES :

THRUST = .0 WTFL = .00 AREAJ = .00 PSUBA = .00 TSUBA = .00 TSUBJ = .0 TSUBJO = .0 ALFA = .0

FIELD POINT VARIABLES :

AZERO = .00 XPRZRO = 2500.0 YPRZRO = 500.0 TINC = 2.00 THMAXO = .00 ANMFPT = 1.00

SEG	THETA	SPEED	XBREAK	YBREAK	INCMAX
1	15.00	75.00	1000.00	.00	6
2	5.00	100.00	1433.02	250.02	9
3	10.00	150.00	2000.00	1232.14	13
4	10.00	175.00	2066.98	1482.15	14
5	20.00	175.00	.00	.00	0

LOADER CARD INPUT

COLUMN	2	4	6	19	31	43	55	67
*	*	*	*	*	*	*	*	*
*	*	*	*	*	*	*	*	*
-1	3		1.					

*****INPUT VARIABLES*****
*****FLIGHT SEGMENT 4*****

COMMON VARIABLES :

SAZ = 1080.00 SEG = 5.00 ROTR = .0 RP = .0 FANS = 1.0 RJ = .0 E = .0 ANMFPT = 1.0

MAIN ROTOR VARIABLES :

SM-K = .00 BIGB = .00 BGR = .00 OMEGN = .00 THRS = .0
ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .0

TAIL ROTOR VARIABLES :

SM-K = .00 BIGB = .00 BGR = .00 OMEGN = .00 THRS = .0
ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .0

PROPELLER VARIABLES :

POWER = .0 DIA = .00 BIGB = .0 RPM = .00 NUMPRP = .0 CHORD = .00

ENGINE VARIABLES :

POWER = .0 SLEVEL = .0 NUMENG = .0

FAN VARIABLES :

DIAT = 52.30 B = 46.00 DDDXT = .50 RS = -12.78 TT2 = 21.00 DF = .45 SIGPHI = .02 RPM = 4690.00
DIAH = 20.20 BPR = 5.00 DDDXH = .44 DL = 3.00 PT2 = 29.90 PR = 1.32 XMXTIP = .33 SPAF = 30.60
CHORD = 4.38 COMB = 1.00 ALFA = .00 FN = 1.00

JET VARIABLES :

THRUST = .0 WTFL = .00 AREAJ = .00 PSUBA = .00 TSUBA = .00 TSUBJ = .0 TSUBJO = .0 ALFA = .0

FIELD POINT VARIABLES :

AZERO = .00 XPRZRO = 2500.0 YPRZRO = 500.0 TINC = 2.00 THMAXO = .00 ANMFPT = 1.00

SEG	THETA	SPEED	XBREAK	YBREAK	INCMAX
1	15.00	75.00	1000.00	.00	6
2	5.00	100.00	1433.02	250.02	9
3	10.00	150.00	2000.00	1232.14	13
4	10.00	175.00	2066.98	1482.15	14
5	20.00	175.00	.00	.00	0

 DIAT = 52.30 B = 46.00 DDDXT = .50 RS = -12.78 TT2 = 21.00 DF = .45 SIGPHI = .02 RPM = 4690.00
 DIAH = 20.20 BPR = 5.00 DDDXH = .44 DL = 3.00 PT2 = 29.90 PR = 1.32 XMXTIP = .33 SPAF = 30.60
 CHORDE = 4.38 COMBE = 1.00 ALFA = .00 FN = 1.00

JET VARIABLES :

 THRUST = .0 WFL = .00 AREAJ = .00 PSUBA = .00 TSUBA = .00 TSUBJ = .00 TSUBJO = .0 ALFA = .0

FIELD POINT VARIABLES :

 AZERO = .00 XPRZRO = 2500.0 YPRZRO = 500.0 TINC = 2.00 THMAXO = .00 ANMFPT = 1.00

SEG	THETA	SPEED	XBREAK	YBREAK	INCMAX
1	15.00	75.00	1000.00	.00	6
2	5.00	100.00	1433.02	250.02	9
3	10.00	150.00	2000.00	1232.14	13
4	10.00	175.00	2066.98	1482.15	14
5	20.00	175.00	.00	.00	0

CHECKOUT CASE FOR V/STOL VEHICLE NOISE PREDICTION PROGRAM

 TINC = 2.00 XPRZRO = 2500.00 YPRZRO = 500.00 AZERO = .00 THMAXO = .00

SEG	PATH	ALFN	VF1	XMAX	YMAX	RADIUS	PHIMAX
1	2.0	15.0	75.0	1000.0	.0	.0	.0
2	1.0	5.0	100.0	1433.0	250.0	500.0	60.0
3	2.0	10.0	150.0	2000.0	1232.1	.0	.0
4	1.0	10.0	175.0	2067.0	1482.1	500.0	30.0
5	2.0	20.0	175.0	.0	.0	.0	.0

RANGE	EPNL	PNLTM	PNL	DBA	XPR
913.6	99.63	101.48	99.49	88.96	2500.0

PNLT TIME HISTORY IN 2.0 SECOND INCREMENTS FOR 1 FIELD POINTS

80.94	81.89	83.05	84.11	86.02	87.17	88.41	90.33	92.06	101.48
100.05	98.42	98.92	95.73	92.26	89.38	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00

PNLT TIME HISTORY IN 2.0 SECOND INCREMENTS FOR 1 FIELD POINTS

79.44	80.41	81.59	82.67	84.76	85.95	87.20	88.28	92.06	99.49
98.57	97.26	98.92	94.61	91.13	88.23	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00

DBA TIME HISTORY IN 2.0 SECOND INCREMENTS FOR 1 FIELD POINTS

69.04	69.91	70.82	71.76	73.79	74.81	75.93	76.59	80.49	88.96
87.46	85.81	86.98	83.44	80.34	77.63	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00

FORM 1
V/STOL NOISE MODEL

CASE: Sample #4

DESCRIPTION: Checkout for Subroutine AJET

SEG	(a) PATH	X' _{max} (ft)	Y' _{max} (ft)	(b) ϕ max (deg)	RADIUS (ft)	V _f (ft/sec)	α_n (deg)
1	2.	1000.	0.	-	-	75.	15.
2	1.	-	-	60.	500.	100.	5.
3	2.	2000.	1240.	-	-	150.	10.
4	1.	-	-	30.	500.	175.	10.
5	2.	-	-	-	-	175.	20.
6							
7							
8							
9							
10							
11							
12							
13							
14							
15							
16							
17							
18							
19							
20							
21							
22							
23							
24							
25							

- (a) Flight path type: 1 = helical, 2 = straight
 (b) Positive for counterclockwise, negative for clockwise turns

V/STOL NOISE MODEL

FORM 2

CASE: Sample #4
 FLIGHT SEGMENT NUMBER: 1

DESCRIPTION: Checkout for subroutine AJET
 Since parameters do not change from segment to segment only dummy inputs will be provided for segments 2 - 5 (see coding sheet)

LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE
1	SAZ	1117.	80	XMAX(1)	1000.	235	RADIUS(6)		390	DIAH	
2	SEG	5.	81	XMAX(2)		236	RADIUS(7)		391	B	
3	FLTYPE	1.	82	XMAX(3)	2000.	237	RADIUS(8)		392	BPR	
4	RCASE		83	XMAX(4)		238	RADIUS(9)		393	CHORD	
5	RETA		84	XMAX(5)		239	RADIUS(10)		394	DDDXT	
6	RBIGB		85	XMAX(6)		+	+		395	DDDXH	
7	RBIGR		86	XMAX(7)		279	RADIUS(50)		396	RS	
8	ROMEGR		87	XMAX(8)		280	VF1(1)	75.	397	SIGPHI	
9	RSID		88	XMAX(9)		281	VF1(2)	100.	398	DL	
10	RCHORD		89	XMAX(10)		282	VF1(3)	150.	399	RPM	
11	RTHRUS		+	+		283	VF1(4)	175.	400	SPAF	
12	RTORQ		129	XMAX(50)		284	VF1(5)	175.	401	XMXTIP	
13	RBETA		130	YMAX(1)	0.	285	VF1(6)		402	PR	
14	TCASE		131	YMAX(2)		286	VF1(7)		403	DF	
15	TETA		132	YMAX(3)	1240.	287	VF1(8)		404	TT2	
16	TBIGB		133	YMAX(4)		288	VF1(9)		405	PT2	
17	TBIGR		134	YMAX(5)		289	VF1(10)		406	ALFA	
18	TOMEGR		135	YMAX(6)		+	+		407	FN	
19	TSID		136	YMAX(7)		329	VF1(50)		408	COMB	
20	TCHORD		137	YMAX(8)		330	ALF(1)	15.	409	THRUST	10000
21	TTHRUS		138	YMAX(9)		331	ALF(2)	5.	410	WTFL	170
22	TTORQ		139	YMAX(10)		332	ALF(3)	10.	411	AREAJ	2.18
23	TBETA		+	+		333	ALF(4)	10.	412	PSUBA	29.92
24	PPWR		179	YMAX(50)		334	ALF(5)	20.	413	TSUBA	59.
25	DIA		180	PHMAX(1)		335	ALF(6)		414	TSUBJ	1000.
26	BIGB		181	PHMAX(2)	60.	336	ALF(7)		415	TSUBJO	1000.
27	RPMP		182	PHMAX(3)		337	ALF(8)		416	ALFAJ	0.
28	ANMPRP		183	PHMAX(4)	30.	338	ALF(9)		417	ROTR	0.
29	CHORDP		184	PHMAX(5)		339	ALF(10)		418	RP	0.
30	PATH(1)	2.	185	PHMAX(6)		+	+		419	FANS	0.
31	PATH(2)	1.	186	PHMAX(7)		379	ALF(50)		420	RJ	1.
32	PATH(3)	2.	187	PHMAX(8)		380	XPRZRO	2500.	421	E	0.
33	PATH(4)	1.	188	PHMAX(9)		381	YPRZRO	500.			
34	PATH(5)	2.	189	PHMAX(10)		382	THMAXO	0.			
35	PATH(6)		+	+		383	AZERO	0.			
36	PATH(7)		229	PHMAX(50)		384	TINC	1.			
37	PATH(8)		230	RADIUS(1)		385	ANMFPT	1.			
38	PATH(9)		231	RADIUS(2)	500.	386	HPENG				
39	PATH(10)		232	RADIUS(3)		387	SLEVEL				
+	+		233	RADIUS(4)	500.	388	ANENG				
79	PATH(50)		234	RADIUS(5)		389	DIAT				

FORM 6
V/STOL NOISE MODEL
Jet Engine Parameters

VARIABLE	PROG NAME	FLIGHT PATH SEGMENT NUMBER													
		1	2	3	4	5	6	7	8	9	10				
Static thrust	THRUST	10000	10000	10000	10000	10000	10000	10000	10000	10000	10000	10000	10000	10000	10000
Gas weight flow	WTFL	170	170	170	170	170	170	170	170	170	170	170	170	170	170
Nozzle area	AREAJ	2.18	2.18	2.18	2.18	2.18	2.18	2.18	2.18	2.18	2.18	2.18	2.18	2.18	2.18
Ambient inlet pressure	PSUBA	29.92	29.92	29.92	29.92	29.92	29.92	29.92	29.92	29.92	29.92	29.92	29.92	29.92	29.92
Ambient inlet temperature	TSUBA	59	59	59	59	59	59	59	59	59	59	59	59	59	59
Tailpipe temperature	TSUBJ	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000
Tailpipe temperature at SIS conditions	TSUBJO	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000
Inclination of thrust axis to horizontal (+90=inlet up)deg	ALFAJ	0	0	0	0	0	0	0	0	0	0	0	0	0	0

CASE NUMBER: Sample #4 DESCRIPTION: Checkout Case for Subroutine AJET

Sample Case 4 (Ajet)

LOADER CARD INPUT

COLUMN	2	4	6	19	31	43	55	67
*	*	*	*	*	*	*	*	*
3	1	1117.	5.	1.	1.	1.	1.	2.
5	30	2.	1.	2.	2.	2.	2.	2.
3	80	1000.	0.	2000.	0.	0.	0.	0.
3	130	0.	0.	1240.	0.	0.	0.	0.
4	180	0.	60.	0.	0.	30.	0.	0.
4	230	0.	500.	150.	0.	500.	0.	175.
5	280	75.	100.	10.	10.	175.	20.	1.
5	330	15.	5.	0.	0.	10.	0.	0.
5	380	2500.	500.	0.	0.	0.	0.	0.
1	385	1.	170.	2.18	29.92	59.	0.	0.
5	409	10000.	1000.	0.	0.	0.	0.	0.
5	414	1000.	1.	0.	0.	0.	0.	0.
-2	420	1.	0.	0.	0.	0.	0.	0.

*****INPUT VARIABLES*****
*****FLIGHT SEGMENT 1*****

COMMON VARIABLES :

SAZ = 1117.00 SEG = 5.00 ROTR = .0 RP = .0 FANS = .0 RJ = 1.0 E = .0 ANMFT = 1.0

MAIN ROTOR VARIABLES :

SM-K = .00 BIGB = .00 BIGR = .00 OMEGN = .00 THRUS = .00
ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORG = .00

TAIL ROTOR VARIABLES :

SM-K = .00 BIGB = .00 BIGR = .00 OMEGN = .00 THRUS = .00
ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORG = .00

PROPELLER VARIABLES :

POWER = .0 DIA = .00 BIGB = .0 RPM = .00 NUMPRP = .0 CHORD = .00

ENGINE VARIABLES :

POWER = .0 SLEVEL = .0 NUMENG = .0

FAN VARIABLES :

DIAT = .00 B = .00 DDDXT = .00 RS = .00 TT2 = .00 DF = .00 SIGPHI = .00 RPM = .00
DIAH = .00 BPR = .00 DDDXH = .00 DL = .00 PT2 = .00 PR = .00 XMTIP = .00 SPAF = .00
CHORDE = .00 COMB = .00 ALFA = .00 FN = .00

JET VARIABLES :

THRUST = 10000.0 WTFL = 170.00 AREAJ = 2.18 PSUBA = 29.92 TSUBA = 59.00 TSUBJ = 1000.0 TSUBJO = 1000.0 ALFA = .0

FIELD POINT VARIABLES :

AZERO = .00 XPRZRO = 2500.0 YPRZRO = 500.0 TINC = 1.00 THMAXO = .00 ANMFPT = 1.00

SEG	THETA	SPEED	XBREAK	YBREAK	INC	MAX
1	15.00	75.00	1000.00	.00	13	
2	5.00	100.00	1433.02	250.02	19	
3	10.00	150.00	2000.00	1232.14	26	
4	10.00	175.00	2066.98	1482.15	28	
5	20.00	175.00	.00	.00	0	

LOADER CARD INPUT

COLUMN 2 4 6 19 31 43 55 67

* * * * *
 * * * * *
 * * * * *
 * * * * *

-1 3 1.

*****INPUT VARIABLES*****
 *****FLIGHT SEGMENT 2*****

COMMON VARIABLES :

SAZ = 1117.00 SEG = 5.00 ROTR = .0 RP = .0 FANS = .0 RJ = 1.0 E = .0 ANMFPT = 1.0

MAIN ROTOR VARIABLES :

SM-K = .00 BIGB = .00 BGR = .00 OMEGN = .00 THRUS = .0
 ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .0

TAIL ROTOR VARIABLES :

SM-K = .00 BIGB = .00 BGR = .00 OMEGN = .00 THRUS = .0
 ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .0

PROPELLER VARIABLES :

POWER = .0 DIA = .00 BIGB = .0 RPM = .00 NUMPRP = .0 CHORD = .00

ENGINE VARIABLES :

POWER = .0 SLEVEL = .0 NUMENG = .0

FAN VARIABLES :

DIAT = .00 B = .00 DDDXT = .00 RS = .00 TT2 = .00 DF = .00 SIGPHI = .00 RPM = .00
 DIAH = .00 BPR = .00 DDDXH = .00 DL = .00 PT2 = .00 PR = .00 XMTIP = .00 SPAF = .00
 CHORD = .00 COMB = .00 ALFA = .00 FN = .00

JET VARIABLES :

THRUST = 10000.0 WTFL = 170.00 AREAJ = 2.18 PSUBA = 29.92 TSUBA = 59.00 TSUBJ = 1000.0 TSUBJO = 1000.0 ALFA = .0

FIELD POINT VARIABLES :

AZERO = .00 XPRZRO = 2500.0 YPRZRO = 500.0 TINC = 1.00 THMAXO = .00 ANMFPT = 1.00

SEG	THETA	SPEED	XBREAK	YBREAK	INC	MAX
1	15.00	75.00	1000.00	.00	13	
2	5.00	100.00	1433.02	250.02	19	
3	10.00	150.00	2000.00	1232.14	26	
4	10.00	175.00	2066.98	1482.15	28	
5	20.00	175.00	.00	.00	0	

 LOADER CARD INPUT

COLUMN 2 4 6 19 31 43 55 67
 * * * * *
 * * * * *
 * * * * *
 * * * * *

 INPUT VARIABLES

 FLIGHT SEGMENT 3

COMMON VARIABLES :

SAZ = 1117.00 SEG = 5.00 ROTR = .0 RP = .0 FANS = .0 RJ = 1.0 E = .0 ANMFT = 1.0

MAIN ROTOR VARIABLES :

SM-K = .00 BIGB = .00 BIGR = .00 OMEGN = .00 THRUS = .0
 ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .0

TAIL ROTOR VARIABLES :

SM-K = .00 BIGB = .00 BIGR = .00 OMEGN = .00 THRUS = .0
 ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .0

PROPELLER VARIABLES :

POWER = .0 DIA = .00 BIGB = .0 RPM = .00 NUMPRP = .0 CHORD = .00

ENGINE VARIABLES :

POWER = .0 SLEVEL = .0 NUMENG = .0

FAN VARIABLES :

DIAT = .00 B = .00 ODDXT = .00 RS = .00 TT2 = .00 DF = .00 SIGPHI = .00 RPM = .00
DIAH = .00 BPR = .00 DDDXH = .00 DL = .00 PT2 = .00 PR = .00 XMXTIP = .00 SPAF = .00
CHORD = .00 COMB = .00 ALFA = .00 FN = .00

JET VARIABLES :

THRUST = 10000.0 WTFL = 170.00 AREAJ = 2.18 PSUBA = 29.92 TSUBA = 59.00 TSUBJ = 1000.0 TSUBJO = 1000.0 ALFA = .0

FIELD POINT VARIABLES :

AZERO = .00 XPRZRO = 2500.0 YPRZRO = 500.0 TINC = 1.00 THMAXO = .00 ANMFPT = 1.00

SEG	THETA	SPEED	XBREAK	YBREAK	INCMAX
1	15.00	75.00	1000.00	.00	13
2	5.00	100.00	1433.02	250.02	19
3	10.00	150.00	2000.00	1232.14	26
4	10.00	175.00	2066.98	1482.15	28
5	20.00	175.00	.00	.00	0

LOADER CARD INPUT

COLUMN	2	4	6	19	31	43	55	67
	*	*	*	*	*	*	*	*
	*	*	*	*	*	*	*	*
	-1	3						1.

*****INPUT VARIABLES*****
*****FLIGHT SEGMENT 4*****

COMMON VARIABLES :

SAZ = 1117.00 SEG = 5.00 ROTR = .0 RP = .0 FANS = .0 RJ = 1.0 E = .0 ANMFPT = 1.0

MAIN ROTOR VARIABLES :

SM-K = .00 BIGB = .00 BGR = .00 OMEGN = .00 THRUS = .0
ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .0

TAIL ROTOR VARIABLES :

SM-K = .00 BIGB = .00 BGR = .00 OMEGN = .00 THRUS = .0
ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .0

PROPELLER VARIABLES :

POWER = .0 DIA = .00 BIGB = .00 RPM = .00 NUMPRP = .0 CHORD = .00

ENGINE VARIABLES :

POWER = .0 SLEVEL = .0 NUMENG = .0

FAN VARIABLES :

DIAT = .00 B = .00 DDDXT = .00 RS = .00 TT2 = .00 DF = .00 SIGPHI = .00 RPM = .00
DIAH = .00 BPR = .00 DDDXH = .00 DL = .00 PT2 = .00 PR = .00 XMTIP = .00 SPAF = .00
CHORD = .00 COMB = .00 ALFA = .00 FN = .00

JET VARIABLES :

THRUST = 10000.0 WTFL = 170.00 AREAJ = 2.18 PSUBA = 29.92 TSUBA = 59.00 TSUBJ = 1000.0 TSUBJO = 1000.0 ALFA = .0

FIELD POINT VARIABLES :

AZERO = .00 XPRZRO = 2500.0 YPRZRO = 500.0 TINC = 1.00 THMAXO = .00 ANMFPT = 1.00

SEG	THETA	SPEED	XBREAK	YBREAK	INCMAX
1	15.00	75.00	1000.00	.00	13
2	5.00	100.00	1433.02	250.02	19
3	10.00	150.00	2000.00	1232.14	26
4	10.00	175.00	2066.98	1482.15	28
5	20.00	175.00	.00	.00	0

DIAT = .00 B = .00 DDDXT = .00 RS = .00 TT2 = .00 DF = .00 SIGPHI = .00 RPM = .00
 DIAH = .00 BPR = .00 DDDXH = .00 DL = .00 PT2 = .00 PR = .00 XMXTIP = .00 SPAF = .00
 CHORD = .00 COMB = .00 ALFA = .00 FN = .00

JET VARIABLES :
 THRUST = 10000.0 WTFI = 170.00 AREAJ = 2.18 PSUBA = 29.92 TSUBA = 59.00 TSUBJ = 1000.0 TSUBJO = 1000.0 ALFA = .0

FIELD POINT VARIABLES :
 AZERO = .00 XPRZRO = 2500.0 YPRZRO = 500.0 TINC = 1.00 THMAXO = .00 ANMFT = 1.00

SEG	THETA	SPEED	XBREAK	YBREAK	INCMAX
1	15.00	75.00	1000.00	.00	13
2	5.00	100.00	1433.02	250.02	19
3	10.00	150.00	2000.00	1232.14	26
4	10.00	175.00	2066.98	1482.15	28
5	20.00	175.00	.00	.00	0

 CHECKOUT CASE FOR V/STOL VEHICLE NOISE PREDICTION PROGRAM

TINC = 1.00 XPRZRO = 2500.00 YPRZRO = 500.00 AZERO = .00 THMAXO = .00

SEG	PATH	ALFN	VF1	XMAX	YMAX	RADIUS	PHIMAX
1	2.0	15.0	75.0	1000.0	.0	.0	.0
2	1.0	5.0	100.0	1433.0	250.0	500.0	60.0
3	2.0	10.0	150.0	2000.0	1232.1	.0	.0
4	1.0	10.0	175.0	2067.0	1482.1	500.0	30.0
5	2.0	20.0	175.0	.0	.0	.0	.0

RANGE EPNL PNLTH PNL DBA XPR
 913.6 110.37 116.36 115.67 105.02 2500.0

PNLT TIME HISTORY IN 1.0 SECOND INCREMENTS FOR 1 FIELD POINTS

86.82	87.14	87.47	87.81	88.25	88.61	88.98	89.05	90.48	90.89
91.38	91.81	92.25	92.73	92.39	93.12	94.95	96.20	97.88	98.68
99.88	101.45	103.77	105.34	107.63	110.18	113.51	116.36	109.92	108.65
107.48	106.40	96.23	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00

PNLT TIME HISTORY IN 1.0 SECOND INCREMENTS FOR 1 FIELD POINTS

85.71	86.05	86.40	86.76	87.21	87.59	87.97	88.37	89.80	90.21
90.69	91.12	91.56	92.05	91.70	92.44	94.27	95.52	97.20	97.99
99.19	100.77	103.09	104.66	106.95	109.50	112.82	115.67	109.24	107.97
106.80	105.71	95.54	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00

DBA TIME HISTORY IN 1.0 SECOND INCREMENTS FOR 1 FIELD POINTS

76.10	76.42	76.75	77.09	77.43	77.78	78.14	78.51	79.88	80.26
80.66	81.06	81.47	81.92	81.56	82.25	83.95	85.15	86.77	87.52
88.68	90.18	92.47	94.00	96.27	98.81	102.14	105.02	98.73	97.52
96.42	95.40	85.45	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00

FORM 1
V/STOL NOISE MODEL

CASE: Sample #5

DESCRIPTION: Checkout for Subroutine ENGINE

SEG	(a) PATH	X' max (ft)	Y' max (ft)	(b) ϕ max (deg)	RADIUS (ft)	V _f (ft/sec)	α_n (deg)
1	2.	1000.	0.	-	-	75.	15.
2	1.	-	-	60.	500.	100.	5.
3	2.	2000.	1240.	-	-	150.	10.
4	1.	-	-	30.	500.	175.	10.
5	2.	-	-	-	-	175.	20.
6							
7							
8							
9							
10							
11							
12							
13							
14							
15							
16							
17							
18							
19							
20							
21							
22							
23							
24							
25							

- (a) Flight path type: 1 = helical, 2 = straight
 (b) Positive for counterclockwise, negative for clockwise turns

V/STOL NOISE MODEL

FORM 2

CASE: Sample #5
 FLIGHT SEGMENT NUMBER: 1

DESCRIPTION: Checkout for subroutine ENGINE
 Since parameters to not change from segment to segment only dummy inputs will be provided for segments 2 - 5 (see coding sheet).

LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE	LOC	VARIABLE	VALUE
1	SAZ	1117.	80	XMAX(1)	1000.	235	RADIUS(6)		390	DIAH	
2	SEG	5.	81	XMAX(2)		236	RADIUS(7)		391	B	
3	FLTYPE	1.	82	XMAX(3)	2000.	237	RADIUS(8)		392	BPR	
4	RCASE		83	XMAX(4)		238	RADIUS(9)		393	CHORD	
5	RETA		84	XMAX(5)		239	RADIUS(10)		394	DDDXT	
6	RBIGB		85	XMAX(6)		+	+		395	DDDXH	
7	RBIGR		86	XMAX(7)		279	RADIUS(50)		396	RS	
8	ROMEGR		87	XMAX(8)		280	VF1(1)	75.	397	SIGPHI	
9	RSID		88	XMAX(9)		281	VF1(2)	100.	398	DL	
10	RCHORD		89	XMAX(10)		282	VF1(3)	150.	399	RPM	
11	RTHRUS		+	+		283	VF1(4)	175.	400	SPAF	
12	RTORQ		129	XMAX(50)		284	VF1(5)	175.	401	XMXTIP	
13	RBETA		130	YMAX(1)	0.	285	VF1(6)		402	PR	
14	TCASE		131	YMAX(2)		286	VF1(7)		403	DF	
15	TETA		132	YMAX(3)	1240.	287	VF1(8)		404	TT2	
16	TBIGB		133	YMAX(4)		288	VF1(9)		405	PT2	
17	TBIGR		134	YMAX(5)		289	VF1(10)		406	ALFA	
18	TOMEGR		135	YMAX(6)		+	+		407	FN	
19	TSID		136	YMAX(7)		329	VF1(50)		408	COMB	
20	TCHORD		137	YMAX(8)		330	ALF(1)	15.	409	THRUST	
21	TTHRUS		138	YMAX(9)		331	ALF(2)	5.	410	WTFI	
22	TTORQ		139	YMAX(10)		332	ALF(3)	10.	411	AREAJ	
23	TBETA		+	+		333	ALF(4)	10.	412	PSUBA	
24	PPWR		179	YMAX(50)		334	ALF(5)	20.	413	TSUBA	
25	DIA		180	PHMAX(1)		335	ALF(6)		414	TSUBJ	
26	BIGB		181	PHMAX(2)	60.	336	ALF(7)		415	TSUBJO	
27	RPMP		182	PHMAX(3)		337	ALF(8)		416	ALFAJ	
28	ANMPRP		183	PHMAX(4)	30.	338	ALF(9)		417	ROTR	0.
29	CHORDP		184	PHMAX(5)		339	ALF(10)		418	RP	0.
30	PATH(1)	2.	185	PHMAX(6)		+	+		419	FANS	0.
31	PATH(2)	1.	186	PHMAX(7)		379	ALF(50)		420	RJ	0.
32	PATH(3)	2.	187	PHMAX(8)		380	XPRZRO	2500.	421	E	1.
33	PATH(4)	1.	188	PHMAX(9)		381	YPRZRO	500.			
34	PATH(5)	2.	189	PHMAX(10)		382	THMAXO	0.			
35	PATH(6)		+	+		383	AZERO	0.			
36	PATH(7)		229	PHMAX(50)		384	TINC	1.			
37	PATH(8)		230	RADIUS(1)		385	ANMFPT	1.			
38	PATH(9)		231	RADIUS(2)	500.	386	HPENG	1500.			
39	PATH(10)		232	RADIUS(3)		387	SLEVEL	1.			
+	+		233	RADIUS(4)	500.	388	ANENG	2.			
79	PATH(50)		234	RADIUS(5)		389	DIAT				

FORM 5
V/STOL NOISE MODEL
Turboshaft Engine Noise

VARIABLE	PROG NAME	FLIGHT PATH SEGMENT NUMBER				
		1	2	3	4	5
Power output	hp HPENG	1500	1500	1500	1500	1500
Noise level curve (a)	SLEVEL	1	1	1	1	1
Number of engines	ANENG	2	2	2	2	2

VARIABLE	PROG NAME	FLIGHT PATH SEGMENT NUMBER				
		6	7	8	9	10
Power output	hp HPENG					
Noise level curve (a)	SLEVEL					
Number of engines	ANENG					

(a) 1 = average, 2 = loud

CASE NUMBER: Sample #5

DESCRIPTION: Checkout Case for Subroutine ENGINE

CODING INSTRUCTIONS

1. LOCATION FIELD MUST BE AN INTEGER NUMBER RIGHT ADJUSTED. Sample Case #5
2. DATA FIELDS 1 THRU 5 MUST CONTAIN A DECIMAL POINT, Checkout for subroutine
THEREFORE AN "E" OR "F" FORMAT MUST BE USED.
3. LAST DATA CARD OF CASE MUST CONTAIN A MINUS SIGN (-) IN CC 1. ENGINE

WORD COUNT FIELD		LOCATION FIELD																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80	81	82	83	84	85	86	87	88	89	90	91	92	93	94	95	96	97	98	99	100	101	102	103	104	105	106	107	108	109	110	111	112	113	114	115	116	117	118	119	120	121	122	123	124	125	126	127	128	129	130	131	132	133	134	135	136	137	138	139	140	141	142	143	144	145	146	147	148	149	150	151	152	153	154	155	156	157	158	159	160	161	162	163	164	165	166	167	168	169	170	171	172	173	174	175	176	177	178	179	180	181	182	183	184	185	186	187	188	189	190	191	192	193	194	195	196	197	198	199	200	201	202	203	204	205	206	207	208	209	210	211	212	213	214	215	216	217	218	219	220	221	222	223	224	225	226	227	228	229	230	231	232	233	234	235	236	237	238	239	240	241	242	243	244	245	246	247	248	249	250	251	252	253	254	255	256	257	258	259	260	261	262	263	264	265	266	267	268	269	270	271	272	273	274	275	276	277	278	279	280	281	282	283	284	285	286	287	288	289	290	291	292	293	294	295	296	297	298	299	300	301	302	303	304	305	306	307	308	309	310	311	312	313	314	315	316	317	318	319	320	321	322	323	324	325	326	327	328	329	330	331	332	333	334	335	336	337	338	339	340	341	342	343	344	345	346	347	348	349	350	351	352	353	354	355	356	357	358	359	360	361	362	363	364	365	366	367	368	369	370	371	372	373	374	375	376	377	378	379	380	381	382	383	384	385	386	387	388	389	390	391	392	393	394	395	396	397	398	399	400	401	402	403	404	405	406	407	408	409	410	411	412	413	414	415	416	417	418	419	420	421	422	423	424	425	426	427	428	429	430	431	432	433	434	435	436	437	438	439	440	441	442	443	444	445	446	447	448	449	450	451	452	453	454	455	456	457	458	459	460	461	462	463	464	465	466	467	468	469	470	471	472	473	474	475	476	477	478	479	480	481	482	483	484	485	486	487	488	489	490	491	492	493	494	495	496	497	498	499	500	501	502	503	504	505	506	507	508	509	510	511	512	513	514	515	516	517	518	519	520	521	522	523	524	525	526	527	528	529	530	531	532	533	534	535	536	537	538	539	540	541	542	543	544	545	546	547	548	549	550	551	552	553	554	555	556	557	558	559	560	561	562	563	564	565	566	567	568	569	570	571	572	573	574	575	576	577	578	579	580	581	582	583	584	585	586	587	588	589	590	591	592	593	594	595	596	597	598	599	600	601	602	603	604	605	606	607	608	609	610	611	612	613	614	615	616	617	618	619	620	621	622	623	624	625	626	627	628	629	630	631	632	633	634	635	636	637	638	639	640	641	642	643	644	645	646	647	648	649	650	651	652	653	654	655	656	657	658	659	660	661	662	663	664	665	666	667	668	669	670	671	672	673	674	675

PROPELLER VARIABLES :

POWER = .0 DIA = .00 BIGB = .0 RPM = .00 NUMPRP = .0 CHORD = .00

ENGINE VARIABLES :

POWER = 1500.0 SLEVEL = 1.0 NUMENG = 2.0

FAN VARIABLES :

DIAT = .00 B = .00 DDDXT = .00 RS = .00 TT2 = .00 DF = .00 SIGPHI = .00 RPM = .00
DJAH = .00 BPR = .00 DDDXH = .00 DL = .00 PT2 = .00 PR = .00 XMX TIP = .00 SPAF = .00
CHORD = .00 COMB = .00 ALFA = .00 FN = .00

JET VARIABLES :

THRUST = .0 WTFL = .00 AREAJ = .00 PSUBA = .00 TSUBA = .00 TSUBJ = .0 TSUBJO = .0 ALFA = .0

FIELD POINT VARIABLES :

AZERO = .00 XPRZRO = 2500.0 YPRZRO = 500.0 TINC = 1.00 THMAXO = .00 ANMFPT = 1.00

SEG	THETA	SPEED	XBREAK	YBREAK	INCMAX
1	15.00	75.00	1000.00	.00	13
2	5.00	100.00	1433.02	250.02	19
3	10.00	150.00	2000.00	1232.14	26
4	10.00	175.00	2066.98	1482.15	28
5	20.00	175.00	.00	.00	0

LOADER CARD INPUT

COLUMN	2	4	6	19	31	43	55	67
	*	*	*	*	*	*	*	*
	*	*	*	*	*	*	*	*
	-1	3						
				1.				

*****INPUT VARIABLES*****
 *****FLIGHT SEGMENT 2*****

COMMON VARIABLES :

SAZ = 1117.00 SEG = 5.00 ROTR = .0 RP = .0 FANS = .0 RJ = .0 E = 1.0 ANMFT = 1.0

MAIN ROTOR VARIABLES :

SM-K = .00 BIGB = .00 BGR = .00 OMEGN = .00 THRUS = .00
 ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .00

TAIL ROTOR VARIABLES :

SM-K = .00 BIGB = .00 BGR = .00 OMEGN = .00 THRUS = .00
 ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .00

PROPELLER VARIABLES :

POWER = .0 DIA = .00 BIGB = .00 RPM = .00 NUMPRP = .00 CHORD = .00

ENGINE VARIABLES :

POWER = 1500.0 SLEVEL = 1.0 NUMENG = 2.0

FAN VARIABLES :

DIAT = .00 B = .00 DDDXT = .00 RS = .00 TT2 = .00 DF = .00 SIGPHI = .00 RPM = .00
 DIAH = .00 BPR = .00 DDDXH = .00 DL = .00 PT2 = .00 PR = .00 XMXTIP = .00 SPAF = .00
 CHORD = .00 COMB = .00 ALFA = .00 FN = .00

JET VARIABLES :

THRUST = .0 WTLF = .00 AREAJ = .00 PSUBA = .00 TSUBA = .00 TSUBJ = .00 TSUBJO = .00 ALFA = .00

FIELD POINT VARIABLES :

AZERO = .00 XPRZRO = 2500.0 YPRZRO = 500.0 TINC = 1.00 THMAXO = .00 ANMFT = 1.00

SEG	THETA	SPEED	XBREAK	YBREAK	INCMAX
1	15.00	75.00	1000.00	.00	13
2	5.00	100.00	1433.02	250.02	19
3	10.00	150.00	2000.00	1232.14	26
4	10.00	175.00	2066.98	1482.15	28
5	20.00	175.00	.00	.00	0

 LOADER CARD INPUT

COLUMN	2	4	6	19	31	43	55	67
	*	*	*	*	*	*	*	*
	*	*	*	*	*	*	*	*
	-1	3		1.				

 INPUT VARIABLES

 FLIGHT SEGMENT 3

COMMON VARIABLES :

SAZ = 1117.00 SEG = 5.00 ROTR = .0 RP = .0 FANS = .0 RJ = .0 E = 1.0 ANMFPT = 1.0

MAIN ROTOR VARIABLES :

SM-K = .00 BIGB = .00 BGR = .00 OMEGN = .00 THRS = .0
 ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .0

TAIL ROTOR VARIABLES :

SM-K = .00 BIGB = .00 BGR = .00 OMEGN = .00 THRS = .0
 ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .0

PROPELLER VARIABLES :

POWER = .0 DIA = .00 BIGB = .0 RPM = .00 NUMPRP = .0 CHORD = .00

ENGINE VARIABLES :

POWER = 1500.0 SLEVEL = 1.0 NUMENG = 2.0

FAN VARIABLES :

DIAT = .00 B = .00 DDDXT = .00 RS = .00 TT2 = .00 DF = .00 SIGPHI = .00 RPM = .00
DIAH = .00 BPR = .00 DDDXH = .00 DL = .00 PT2 = .00 PR = .00 XMTIP = .00 SPAF = .00
CHORDE = .00 COMB = .00 ALFA = .00 FN = .00

JET VARIABLES :

THRUST = .0 WTFL = .00 AREAJ = .00 PSUBA = .00 TSUBA = .00 TSUBJ = .0 TSUBJO = .0 ALFA = .0

FIELD POINT VARIABLES :

AZERO = .00 XPRZRO = 2500.0 YPRZRO = 500.0 TINC = 1.00 THMAXO = .00 ANMFPT = 1.00

SEG	THETA	SPEED	XBREAK	YBREAK	INCMAX
1	15.00	75.00	1000.00	.00	13
2	5.00	100.00	1433.02	250.02	19
3	10.00	150.00	2000.00	1232.14	26
4	10.00	175.00	2066.98	1482.15	28
5	20.00	175.00	.00	.00	0

LOADER CARD INPUT

COLUMN	2	4	6	19	31	43	55	67
	*	*	*	*	*	*	*	*
	*	*	*	*	*	*	*	*
	-1	3		1.				

*****INPUT VARIABLES*****
*****FLIGHT SEGMENT 4*****

COMMON VARIABLES :

SAZ = 1117.00 SEG = 5.00 ROTR = .0 RP = .0 FANS = .0 RJ = .0 E = 1.0 ANMFPT = 1.0

MAIN ROTOR VARIABLES :

SM-K = .00 BIGB = .00 BGR = .00 OMEGN = .00 THRUS = .00
ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .00

TAIL ROTOR VARIABLES :

SM-K = .00 BIGB = .00 BGR = .00 OMEGN = .00 THRUS = .00
ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .00

PROPELLER VARIABLES :

POWER = .0 DIA = .00 BIGB = .0 RPM = .00 NUMPRP = .00 CHORD = .00

ENGINE VARIABLES :

POWER = 1500.0 SLEVEL = 1.0 NUMENG = 2.0

FAN VARIABLES :

DIA1 = .00 B = .00 DDDXT = .00 RS = .00 TT2 = .00 DF = .00 SIGPHI = .00 RPM = .00
DIAH = .00 BPR = .00 DDDXH = .00 DL = .00 PT2 = .00 PR = .00 XMXTIP = .00 SPAF = .00
CHORD = .00 COMB = .00 ALFA = .00 FN = .00

JET VARIABLES :

THRUST = .0 WTFL = .00 AREAJ = .00 PSUBA = .00 TSUBA = .00 TSUBJ = .0 TSUBJO = .0 ALFA = .0

FIELD POINT VARIABLES :

AZERO = .00 XPRZRO = 2500.0 YPRZRO = 500.0 TINC = 1.00 THMAXO = .00 ANMFPT = 1.00

SEG	THETA	SPEED	XBREAK	YBREAK	INCMAX
1	15.00	75.00	1000.00	.00	13
2	5.00	100.00	1433.02	250.02	19
3	10.00	150.00	2000.00	1232.14	26
4	10.00	175.00	2066.98	1482.15	28
5	20.00	175.00	.00	.00	0

LOADER CARD INPUT

COLUMN	2	4	6	19	31	43	55	67
*	*	*	*	*	*	*	*	*
-1	3	1.						

*****INPUT VARIABLES*****
 *****FLIGHT SEGMENT 5*****

COMMON VARIABLES :

SAZ = 1117.00 SEG = 5.00 ROTR = .0 RP = .0 FANS = .0 RJ = .0 E = 1.0 ANMPT = 1.0

MAIN ROTOR VARIABLES :

SM-K = .00 BIGB = .00 BGR = .00 OMEGN = .00 THRUS = .0
 ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .0

TAIL ROTOR VARIABLES :

SM-K = .00 BIGB = .00 BGR = .00 OMEGN = .00 THRUS = .0
 ETA = .00 BETA = .00 CHORD = .00 SID = .00 TORQ = .0

PROPELLER VARIABLES :

POWER = .0 DIA = .00 BIGB = .00 RPM = .00 NUMPRP = .0 CHORD = .00

ENGINE VARIABLES :

POWER = 1500.0 SLEVEL = 1.0 NUMENG = 2.0

FAN VARIABLES :

 DIAT = .00 B = .00 DDDXT = .00 RS = .00 TT2 = .00 DF = .00 SIGPHI = .00 RPM = .00
 DIAH = .00 BPR = .00 DDDXH = .00 DL = .00 PT2 = .00 PR = .00 XMXTIP = .00 SPAF = .00
 CHORD = .00 COMBE = .00 ALFA = .00 FN = .00

JET VARIABLES :

 THRUST = .0 WTFL = .00 AREAJ = .00 PSUBA = .06 TSUBA = .00 TSUBJ = .0 TSUBJO = .0 ALFA = .0

FIELD POINT VARIABES :

 AZERO = .00 XPRZRO = 2500.0 YPRZRO = 500.0 TINC = 1.00 THMAXO = .00 ANMFT = 1.00

SEG	THETA	SPEED	XBREAK	YBREAK	INCHMAX
1	15.00	75.00	1000.00	.00	13
2	5.00	100.00	1433.02	250.02	19
3	10.00	150.00	2000.00	1232.14	26
4	10.00	175.00	2066.98	1482.15	28
5	20.00	175.00	.00	.00	0

 CHECKOUT CASE FOR V/STOL VEHICLE NOISE PREDICTION PROGRAM

TINC = 1.00 XPRZRO = 2500.00 YPRZRO = 500.00 AZERO = .06 THMAXO = .00

SEG	PATH	ALFN	VF1	XMAX	YMAX	RADIUS	PHIMAX
1	2.0	15.0	75.0	1000.0	.0	.0	.0
2	1.0	5.0	100.0	1433.0	250.0	500.0	60.0
3	2.0	10.0	150.0	2000.0	1232.1	.0	.0
4	1.0	10.0	175.0	2067.0	1482.1	500.0	30.0
5	2.0	20.0	175.0	.0	.0	.0	.0

 RANGE EPNL PNLTM PNL DBA XPR
 913.6 77.05 77.38 77.38 65.07 2500.0

PNLT TIME HISTORY IN 1.0 SECOND INCREMENTS FOR 1 FIELD POINTS

57.13	58.35	59.91	59.48	59.57	60.73	61.36	62.04	63.29	63.99
65.10	65.80	66.52	67.65	68.50	69.66	71.40	73.26	73.83	75.21
76.52	76.47	77.38	77.19	77.06	77.17	75.92	74.11	71.63	69.43
67.55	65.68	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00

PNLT TIME HISTORY IN 1.0 SECOND INCREMENTS FOR 1 FIELD POINTS

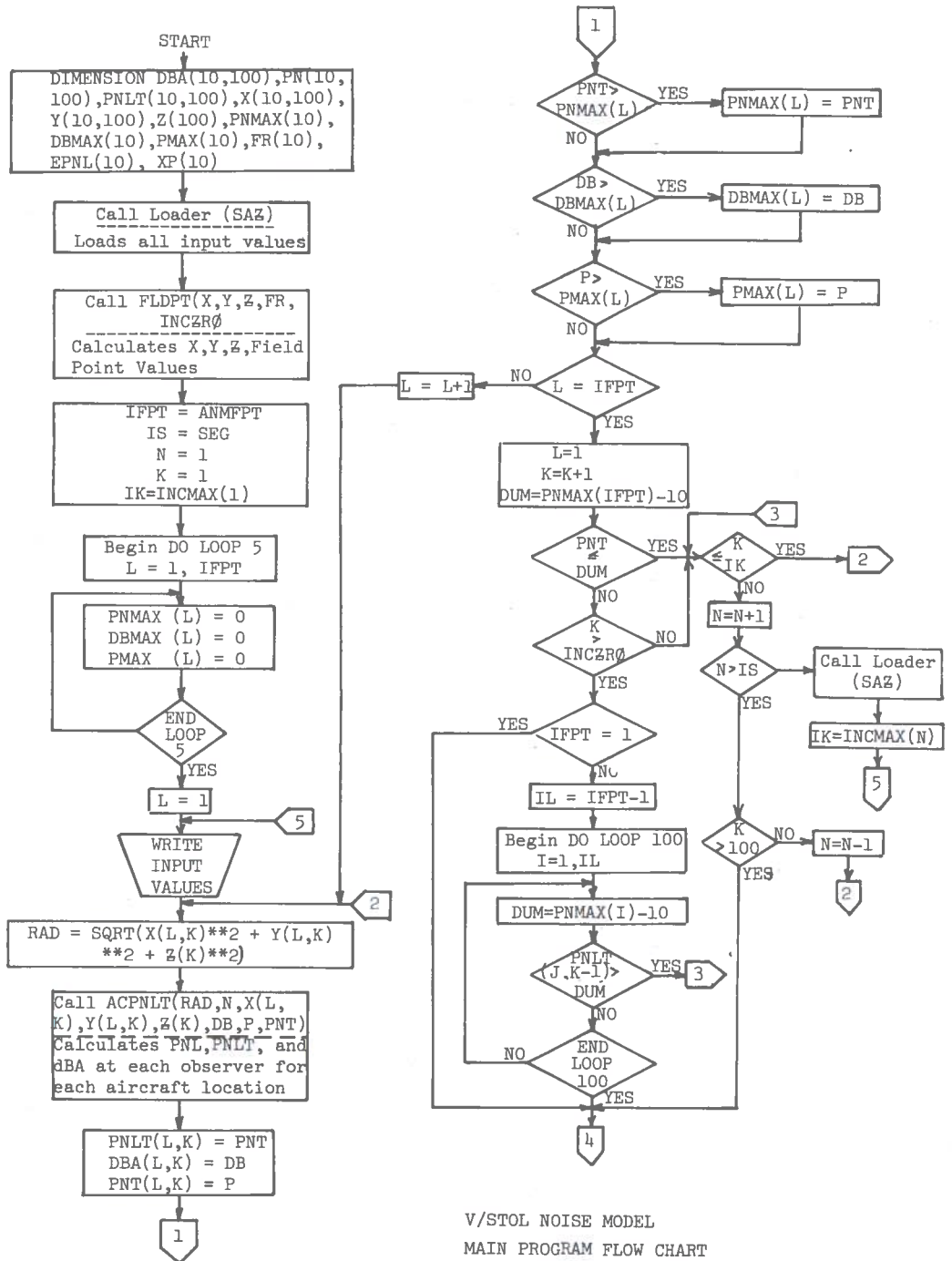
56.58	57.82	58.40	58.98	59.57	60.73	61.36	62.04	63.29	63.99
65.10	65.80	66.52	67.65	68.50	69.66	71.40	73.26	73.83	75.21
76.52	76.47	77.38	77.19	77.06	77.17	75.92	74.11	71.63	69.43
67.55	65.68	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00

DBA TIME HISTORY IN 1.0 SECOND INCREMENTS FOR 1 FIELD POINTS

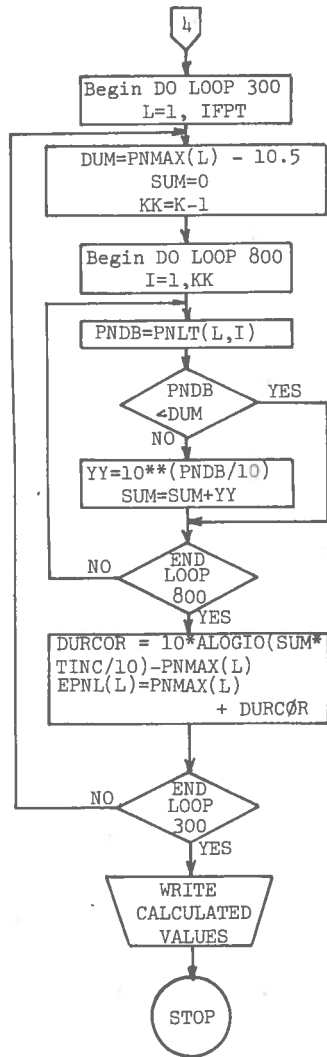
48.79	49.30	49.83	50.37	50.91	51.47	52.04	52.62	53.81	54.42
55.03	55.66	56.30	57.00	57.41	58.46	60.13	61.99	62.50	63.62
64.63	64.53	65.07	64.87	64.75	64.65	63.42	62.44	60.74	59.25
57.87	56.58	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00
.00	.00	.00	.00	.00	.00	.00	.00	.00	.00

APPENDIX C

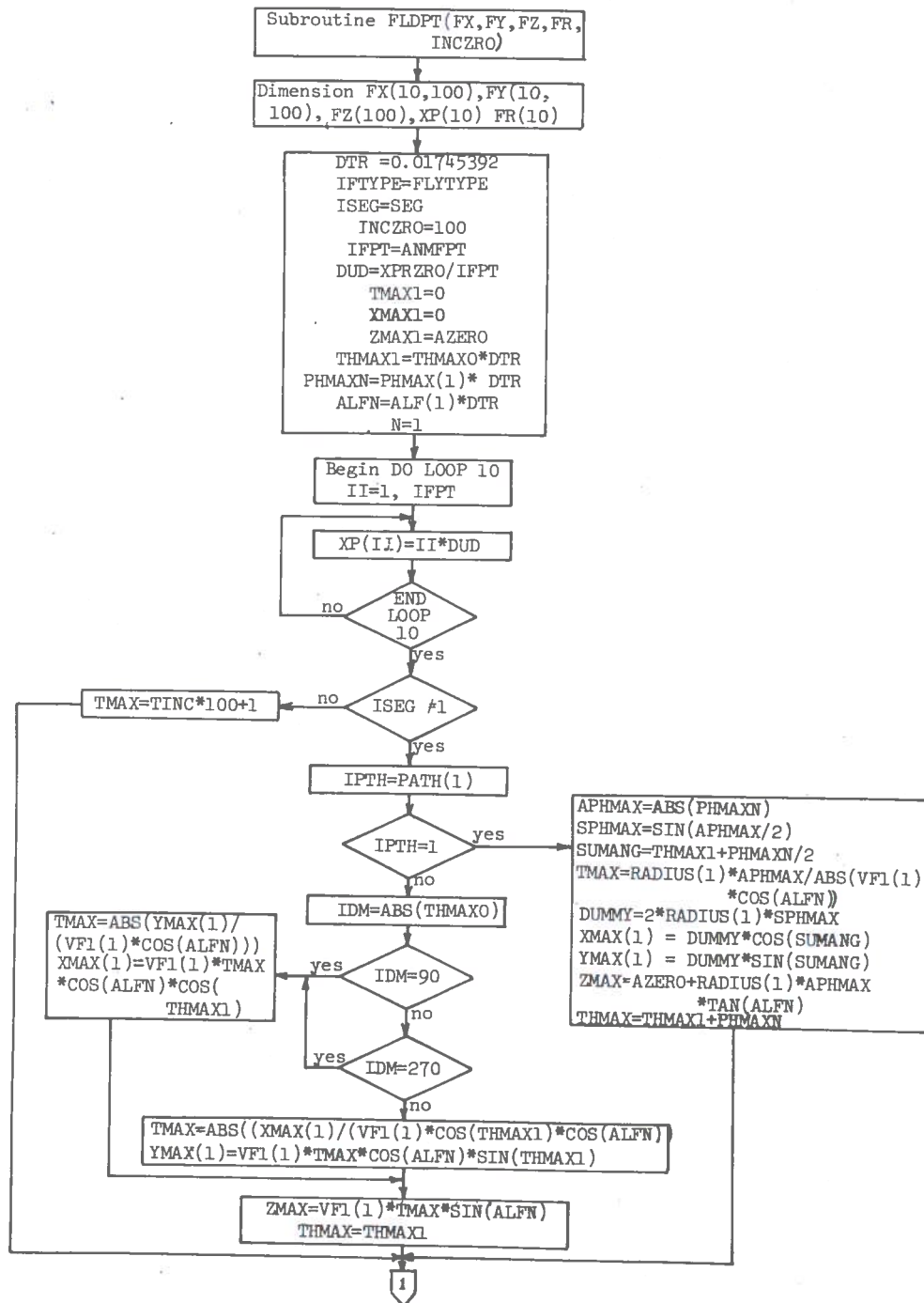
V/STOL Noise Model - Flow Charts



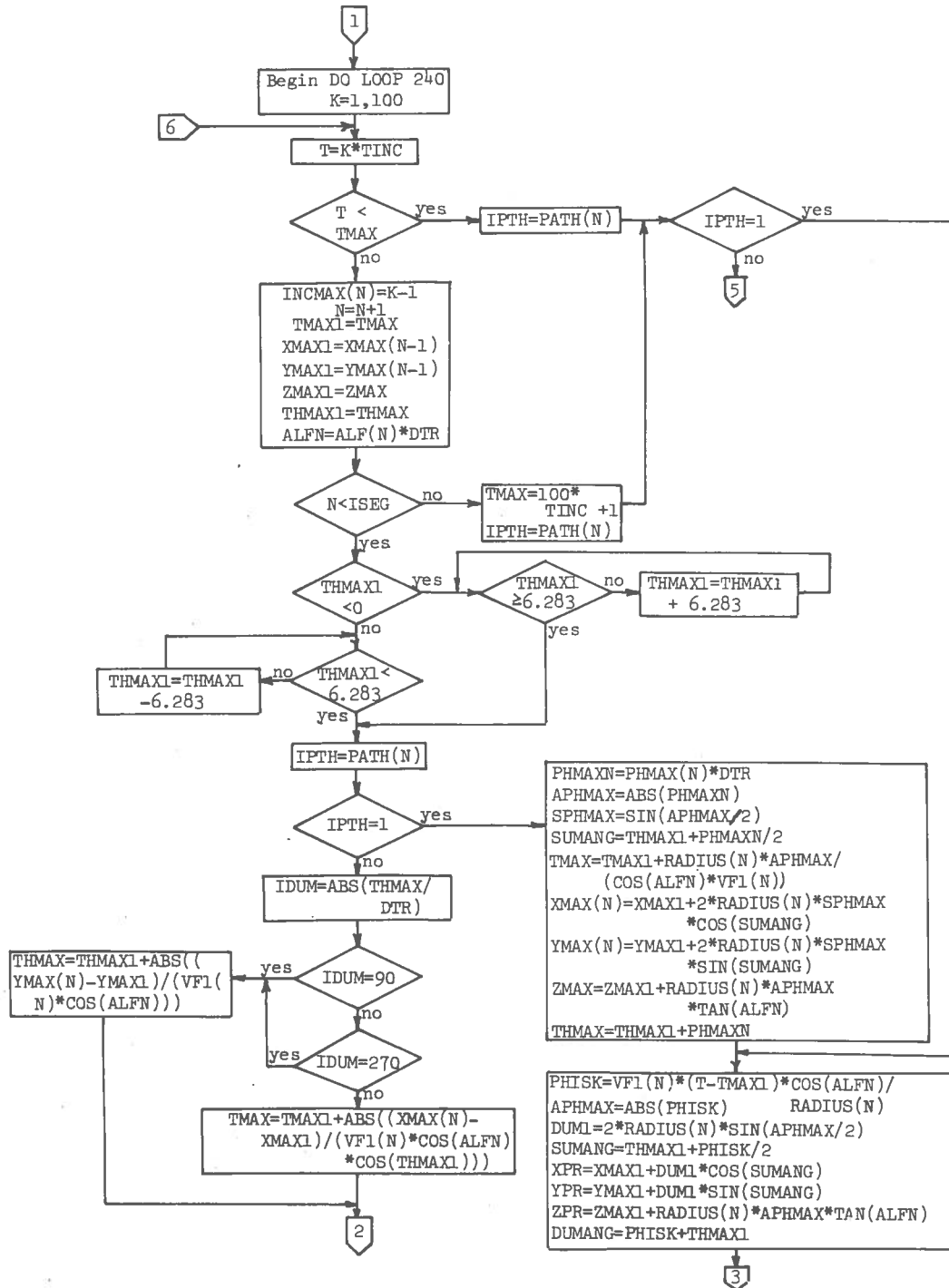
V/STOL NOISE MODEL
MAIN PROGRAM FLOW CHART



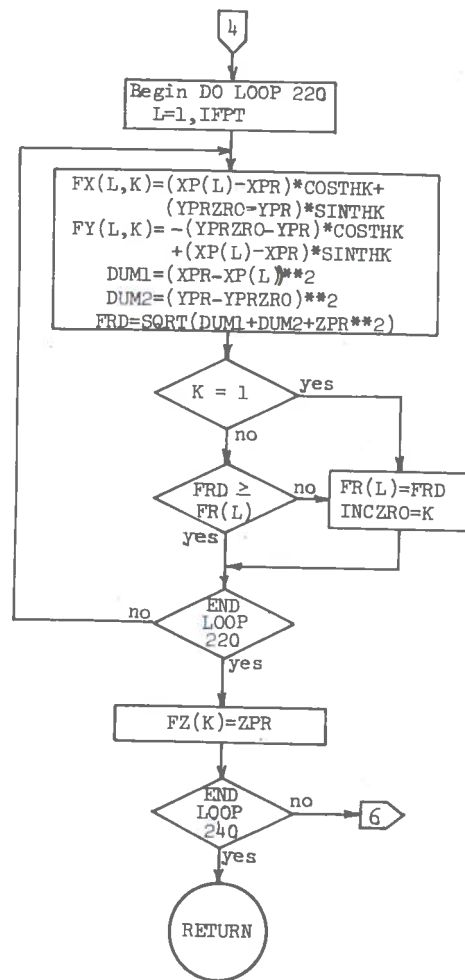
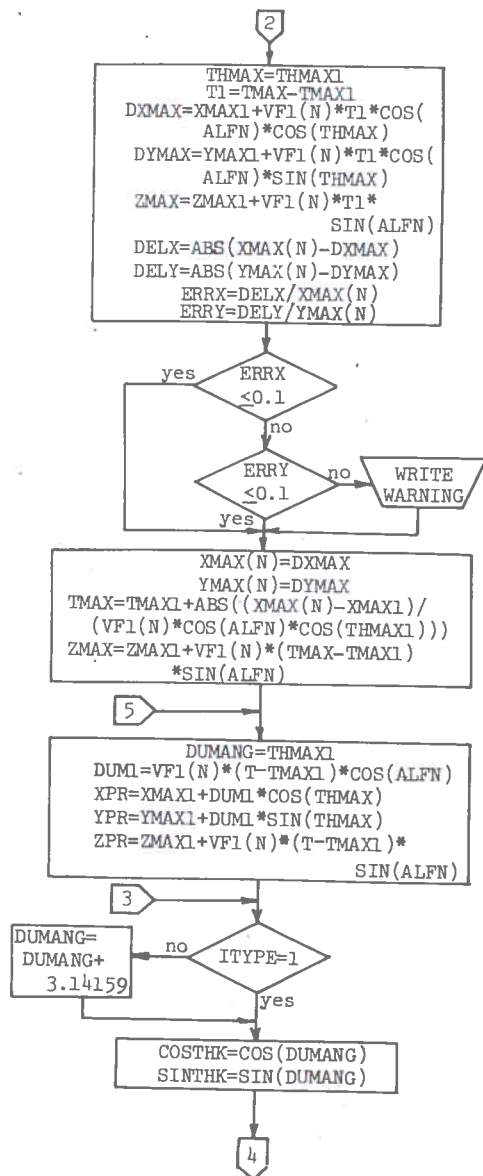
V/STOL NOISE MODEL - MAIN PROGRAM
FLOW CHART (CONT)



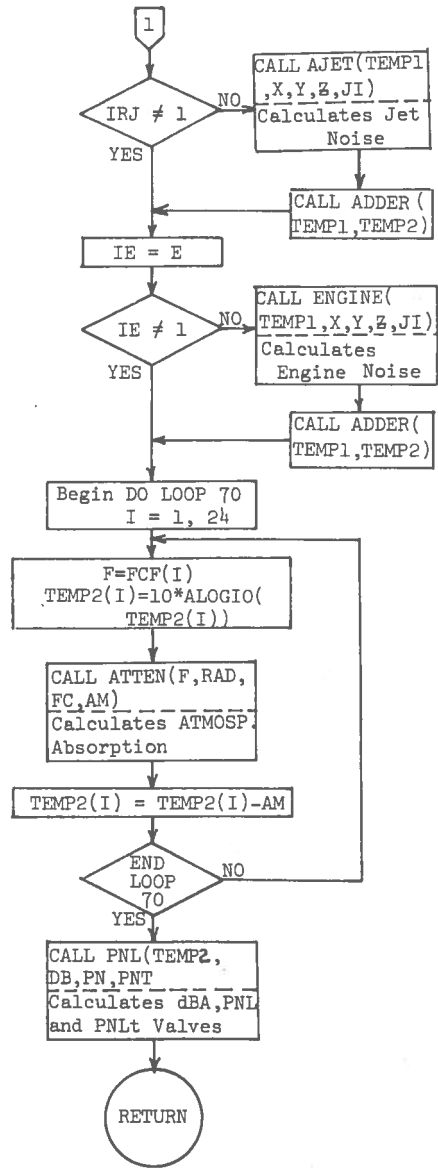
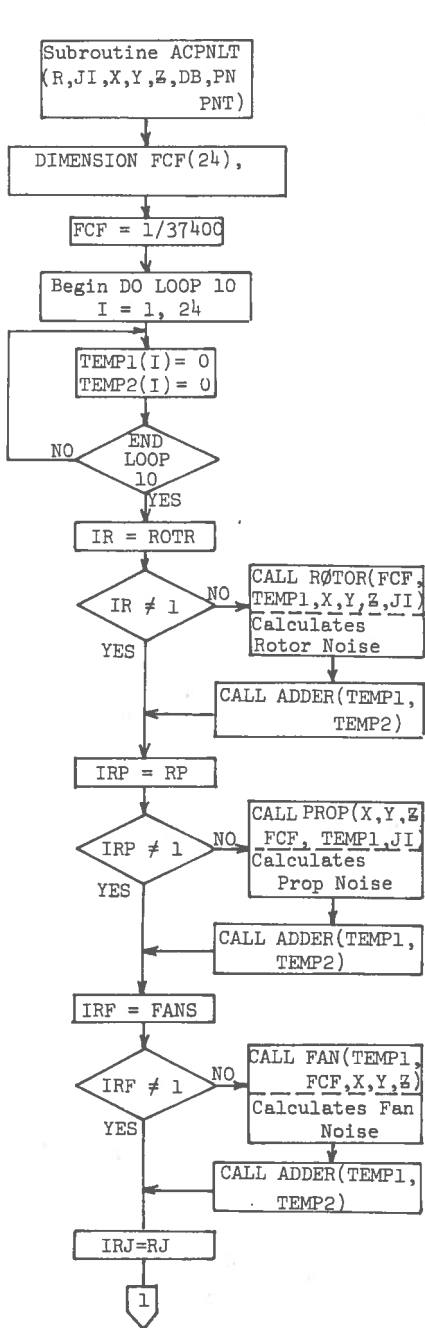
Subroutine FLDPT Flow Chart



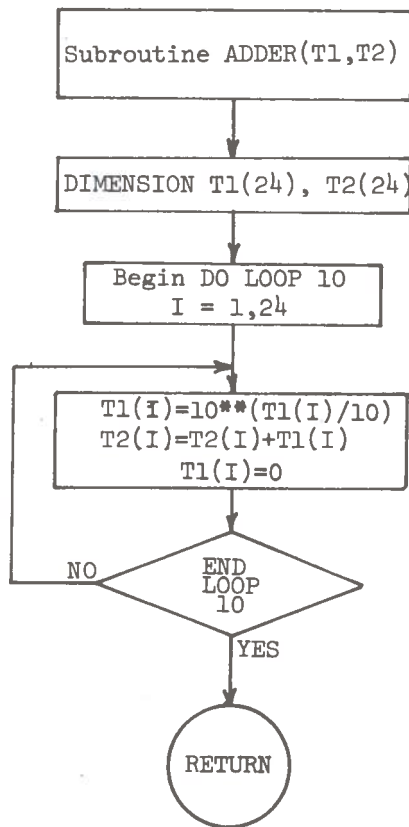
Subroutine FLDPT



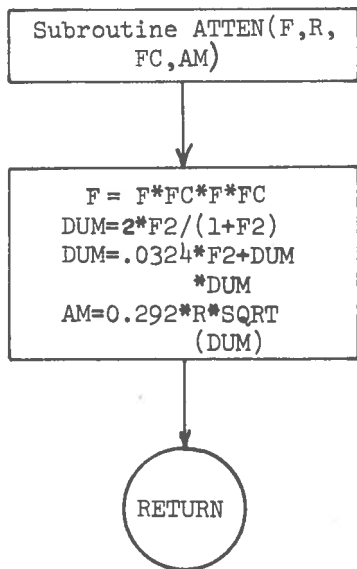
Subroutine FLDPT



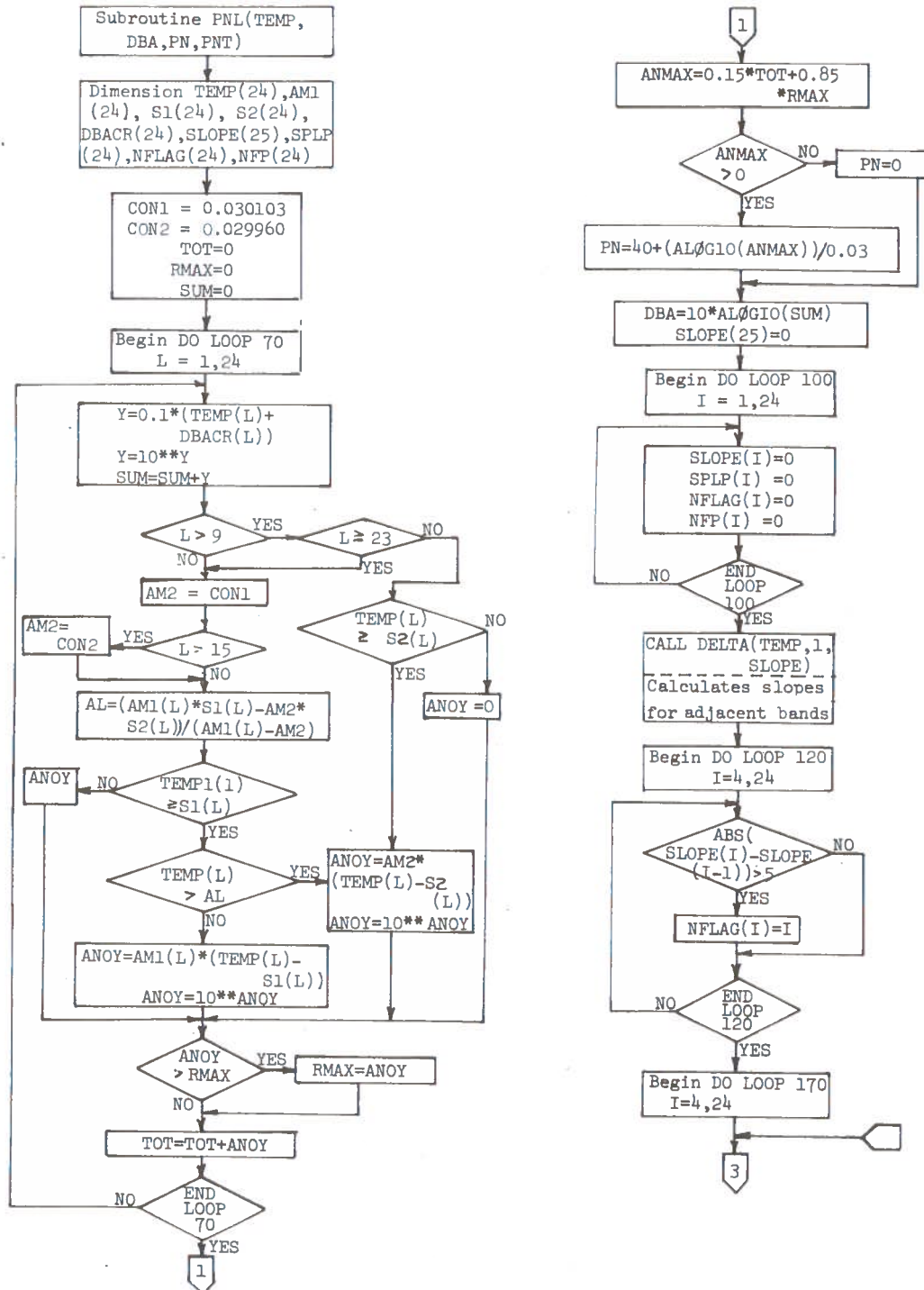
Subroutine ACPNLT
Flow Chart



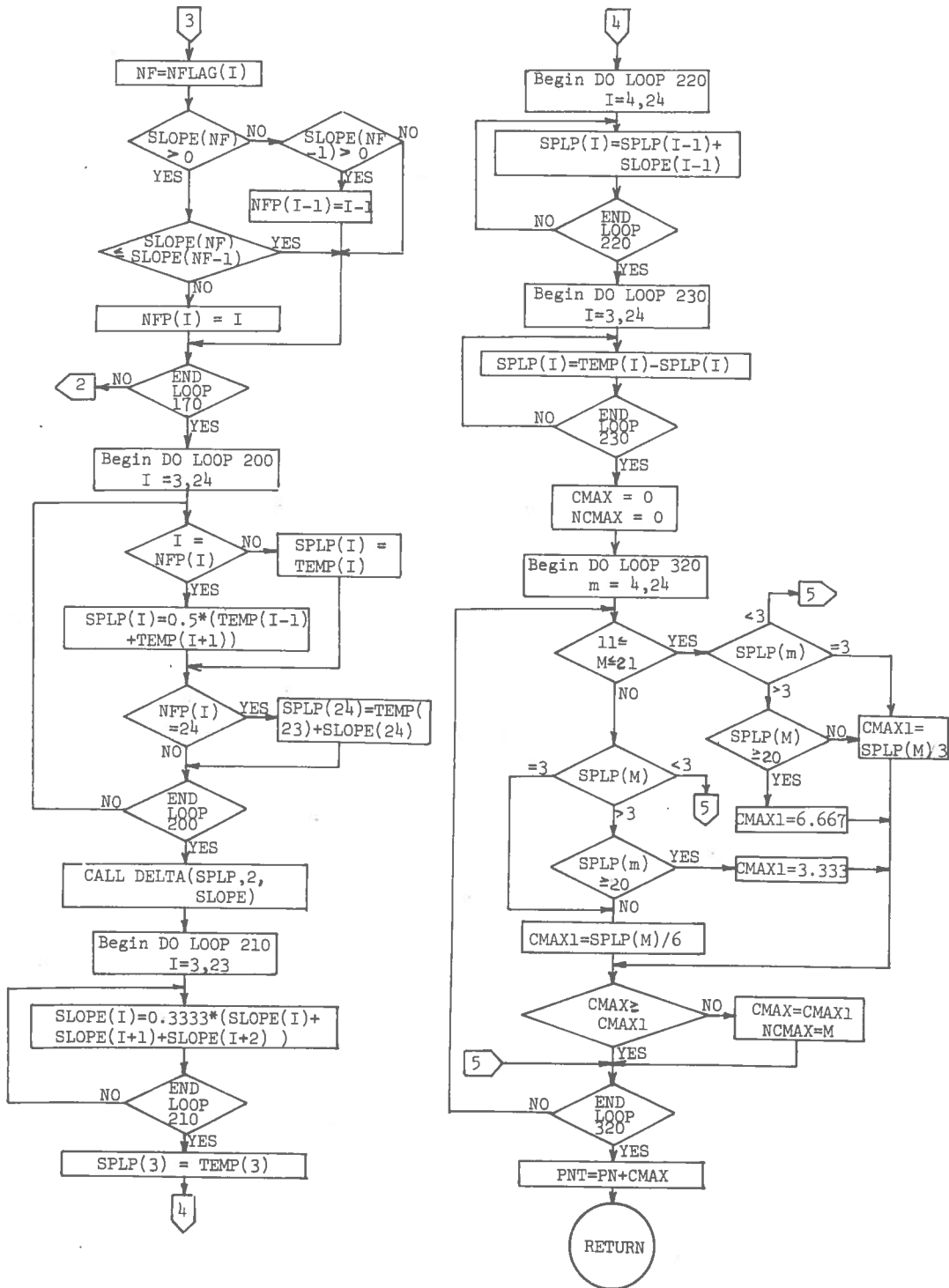
SUBROUTINE ADDER - FLOW CHART



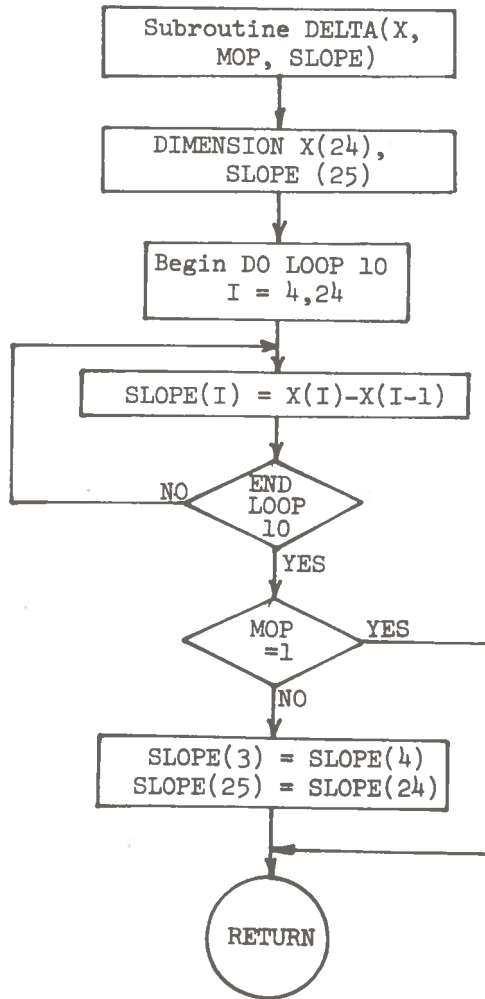
SUBROUTINE ATTEN FLOW CHART



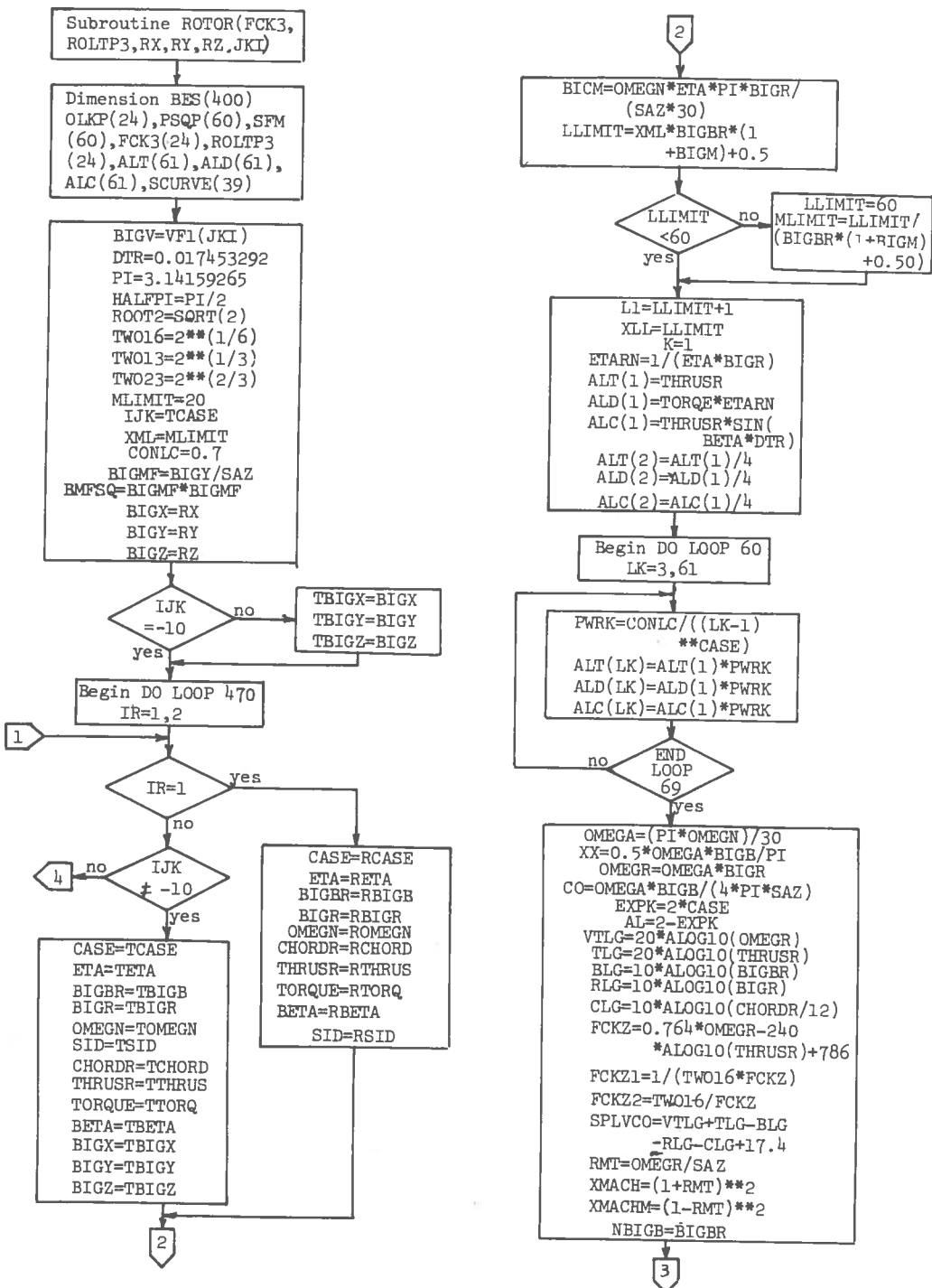
Subroutine PNL Flow Chart



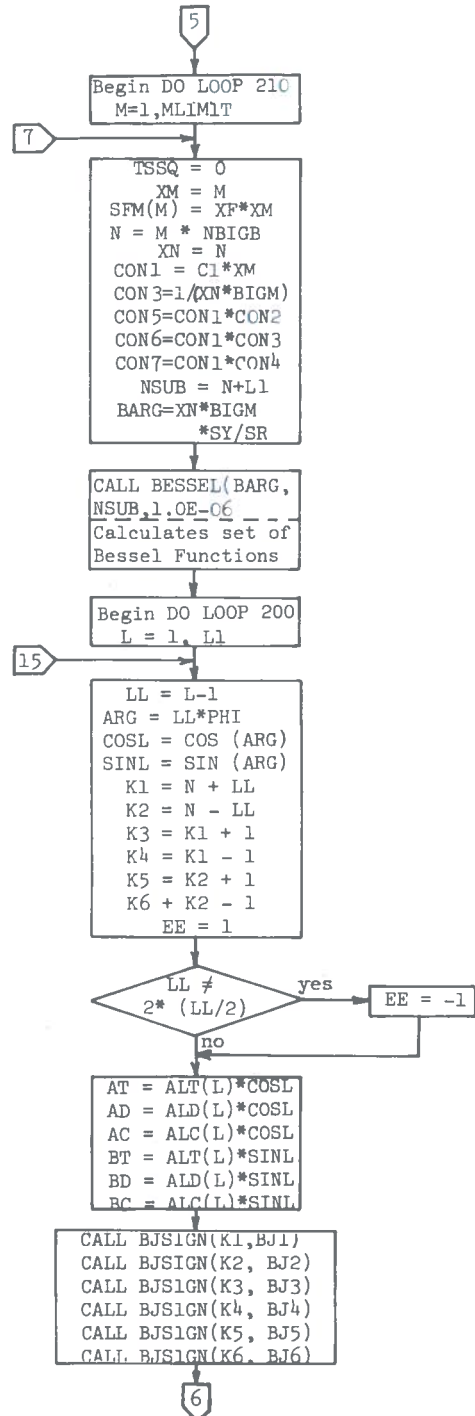
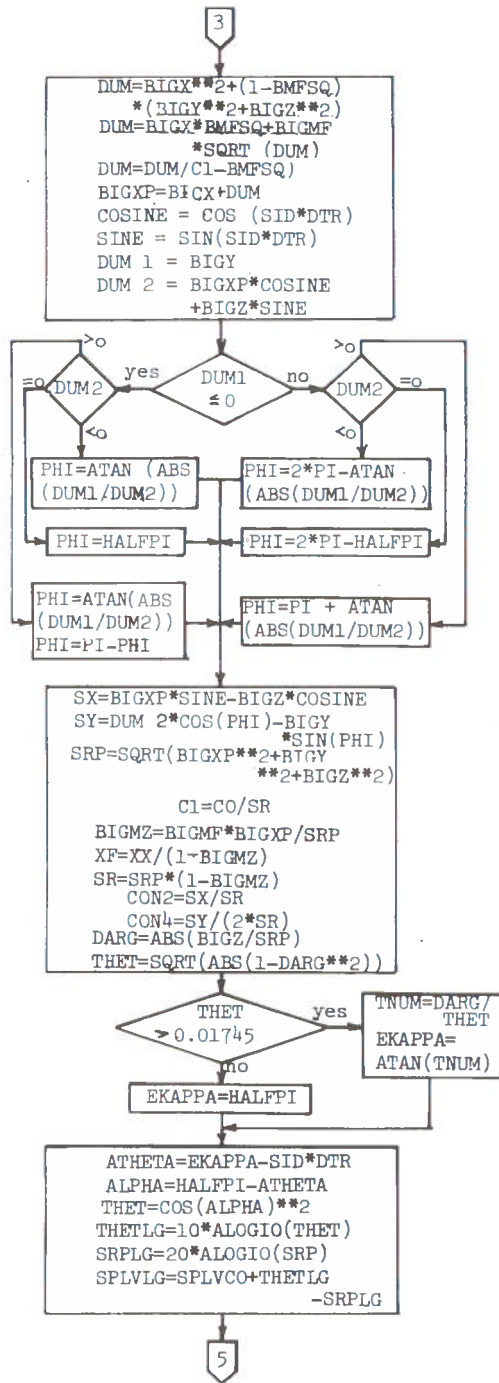
Subroutine PNL



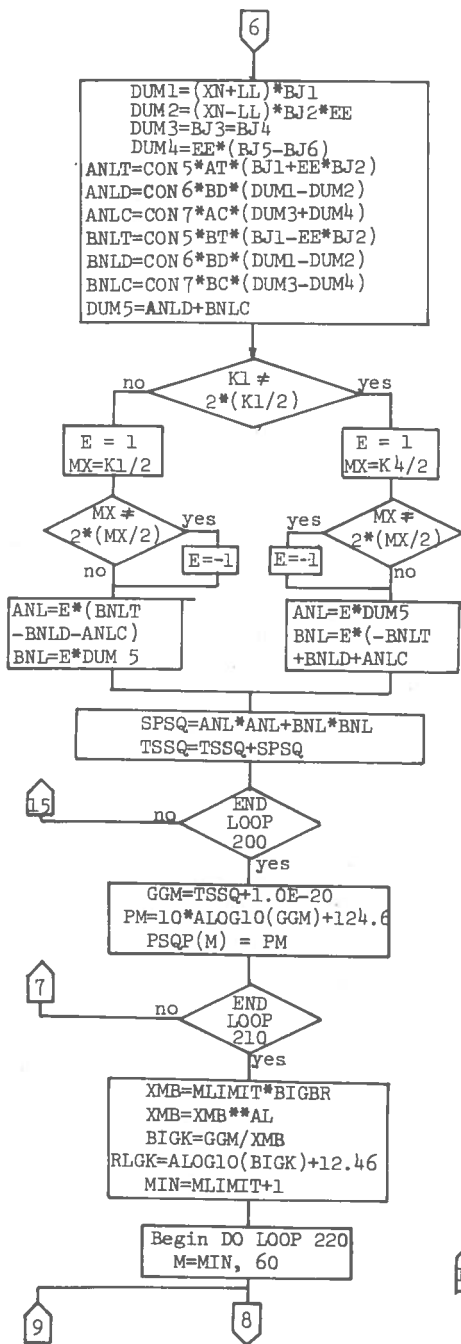
Subroutine DELTA Flow Chart



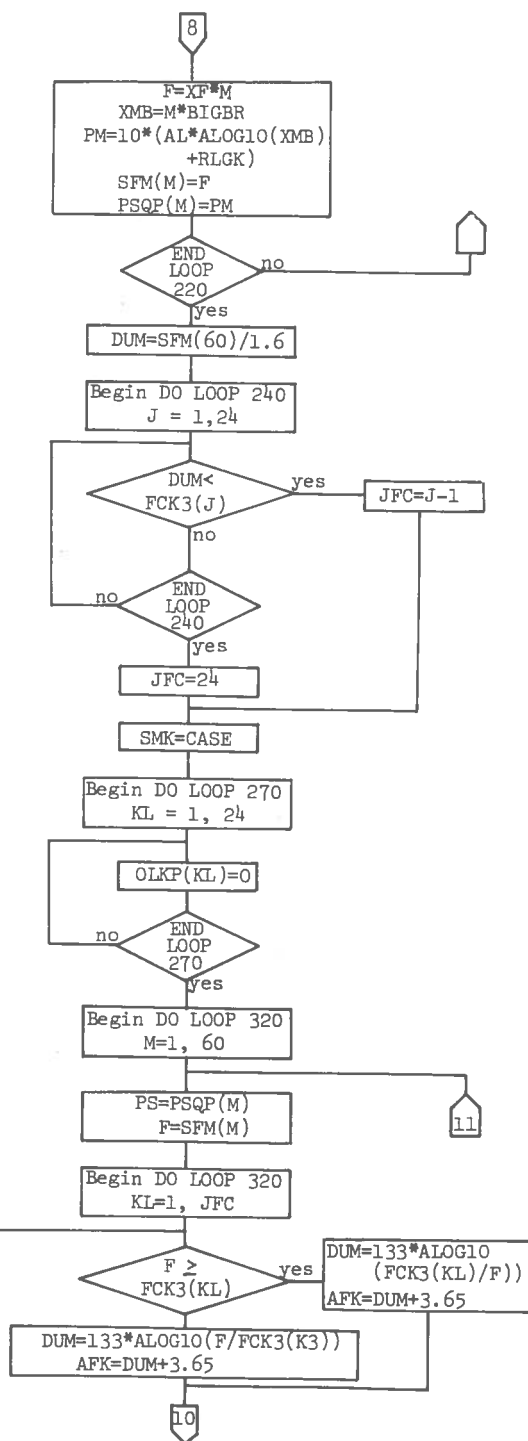
Subroutine Rotor Flow Chart

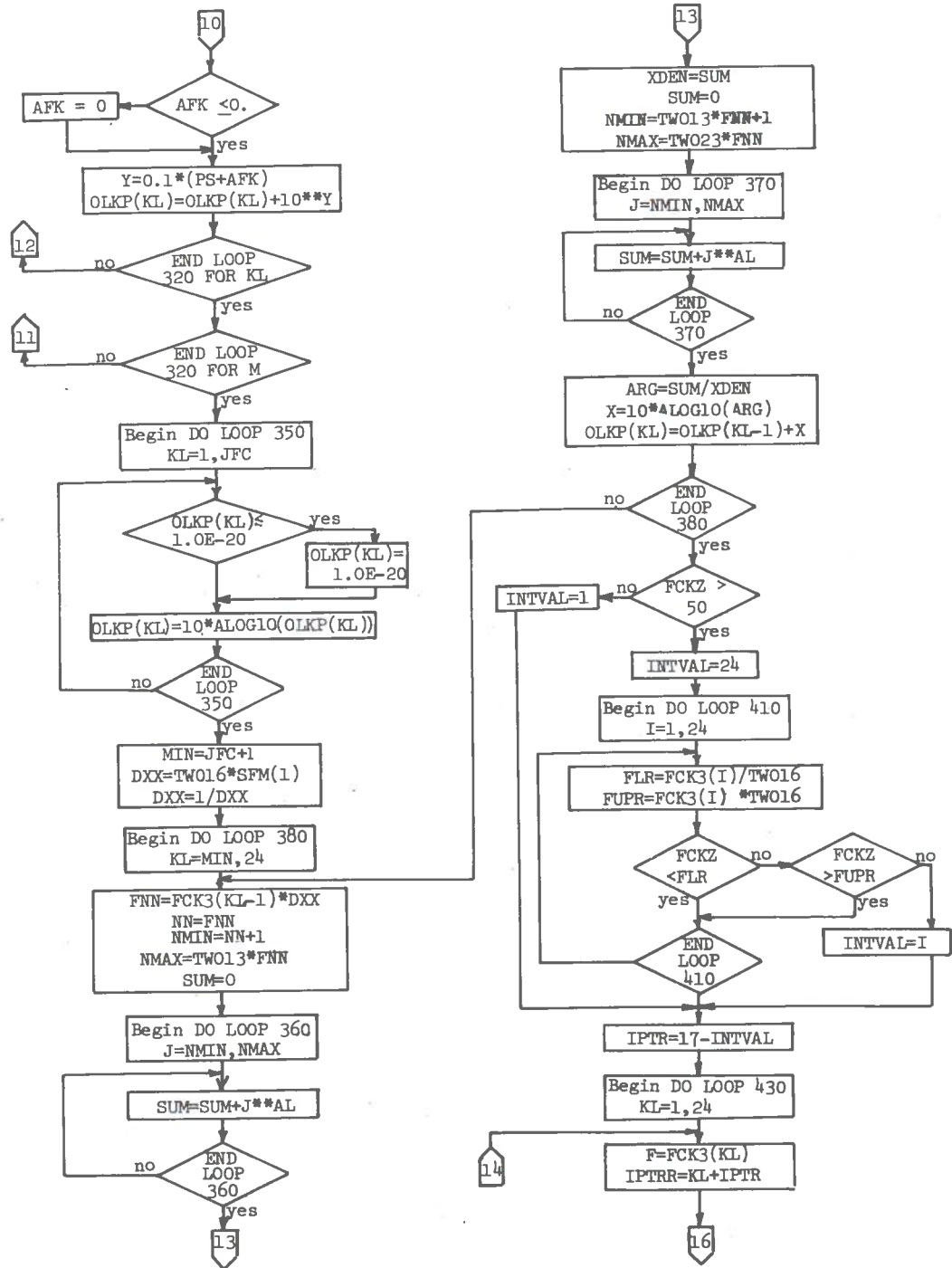


Subroutine Rotor

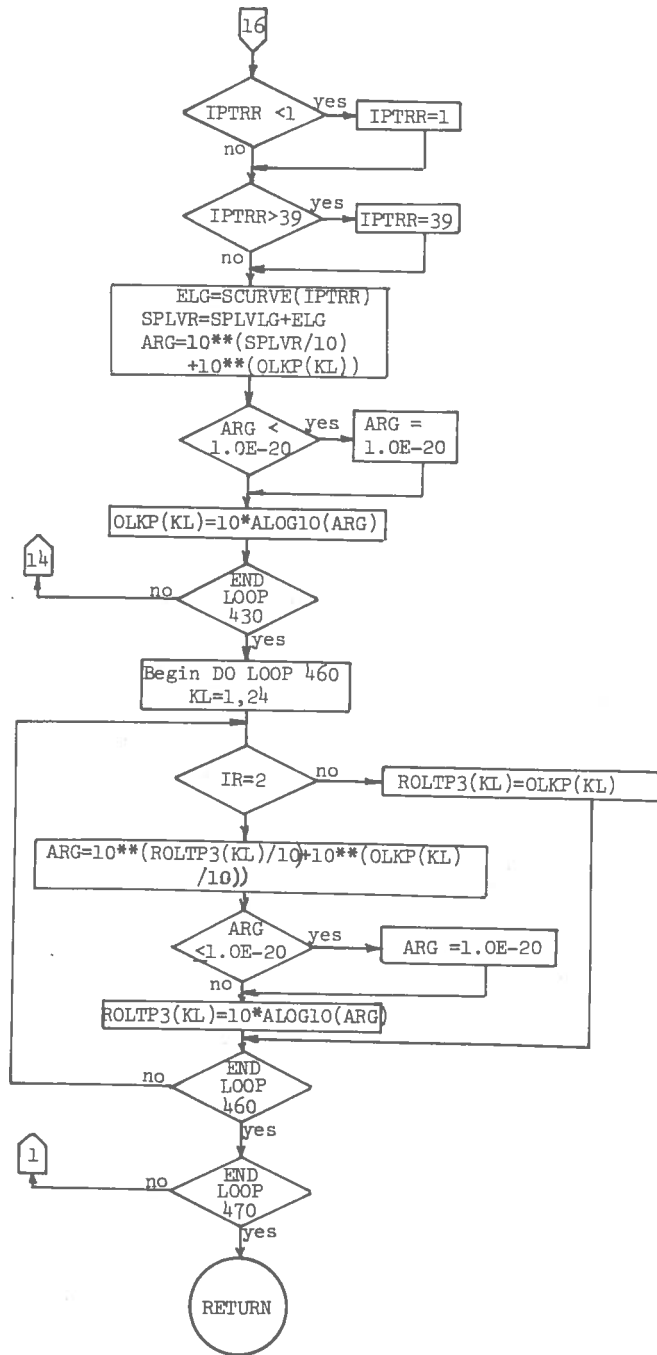


Subroutine Rotor

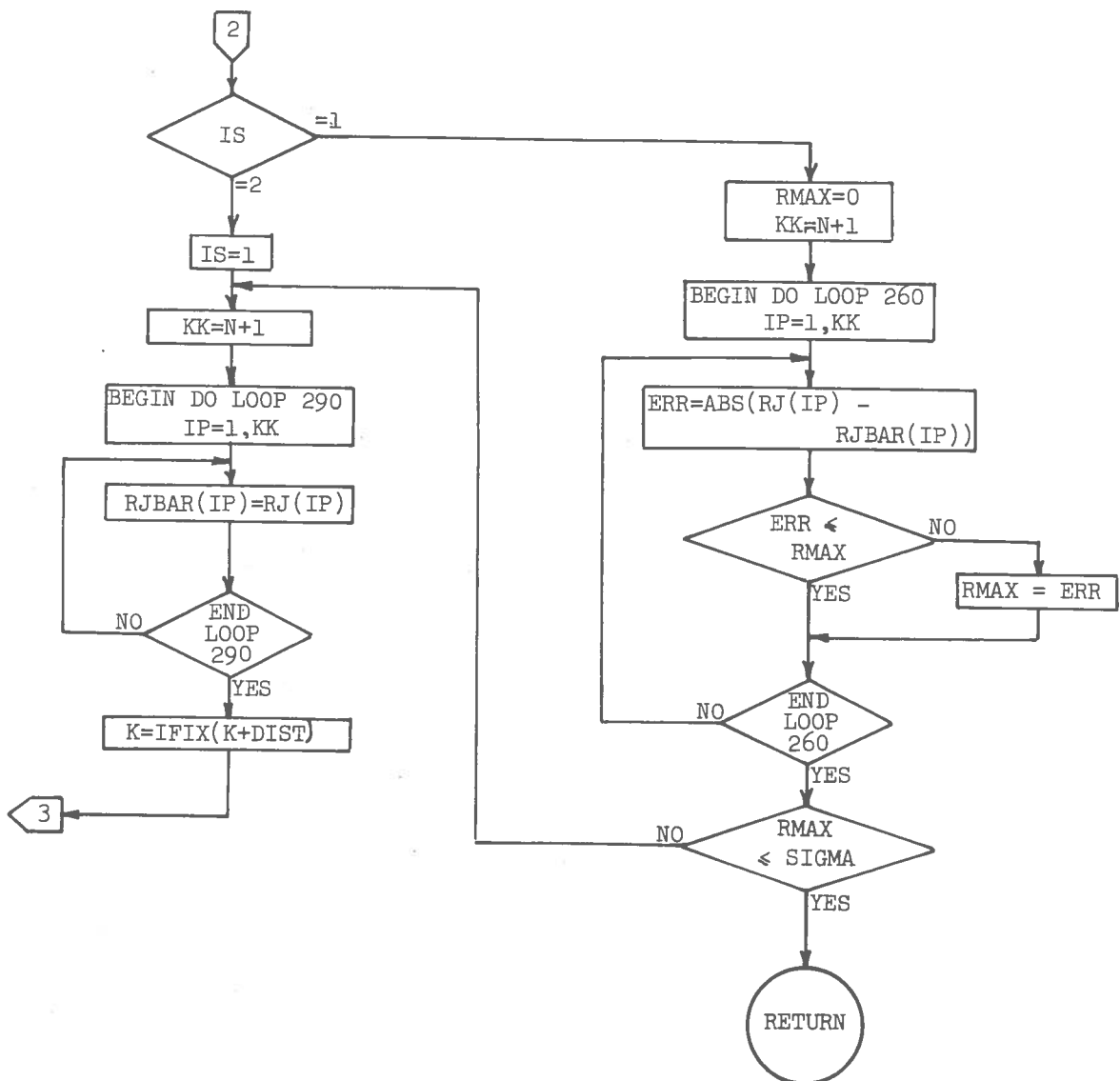




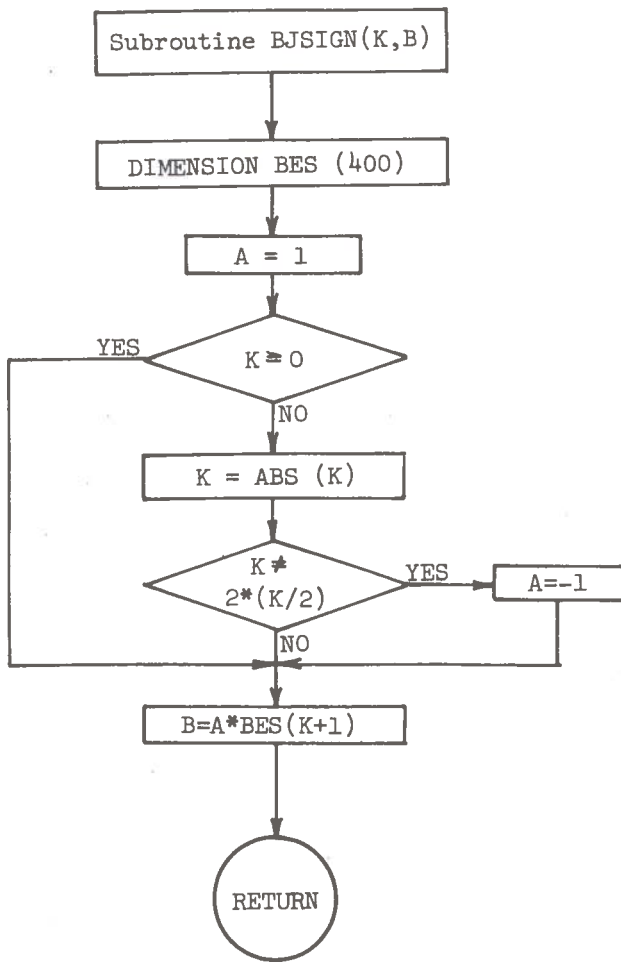
Subroutine Rotor



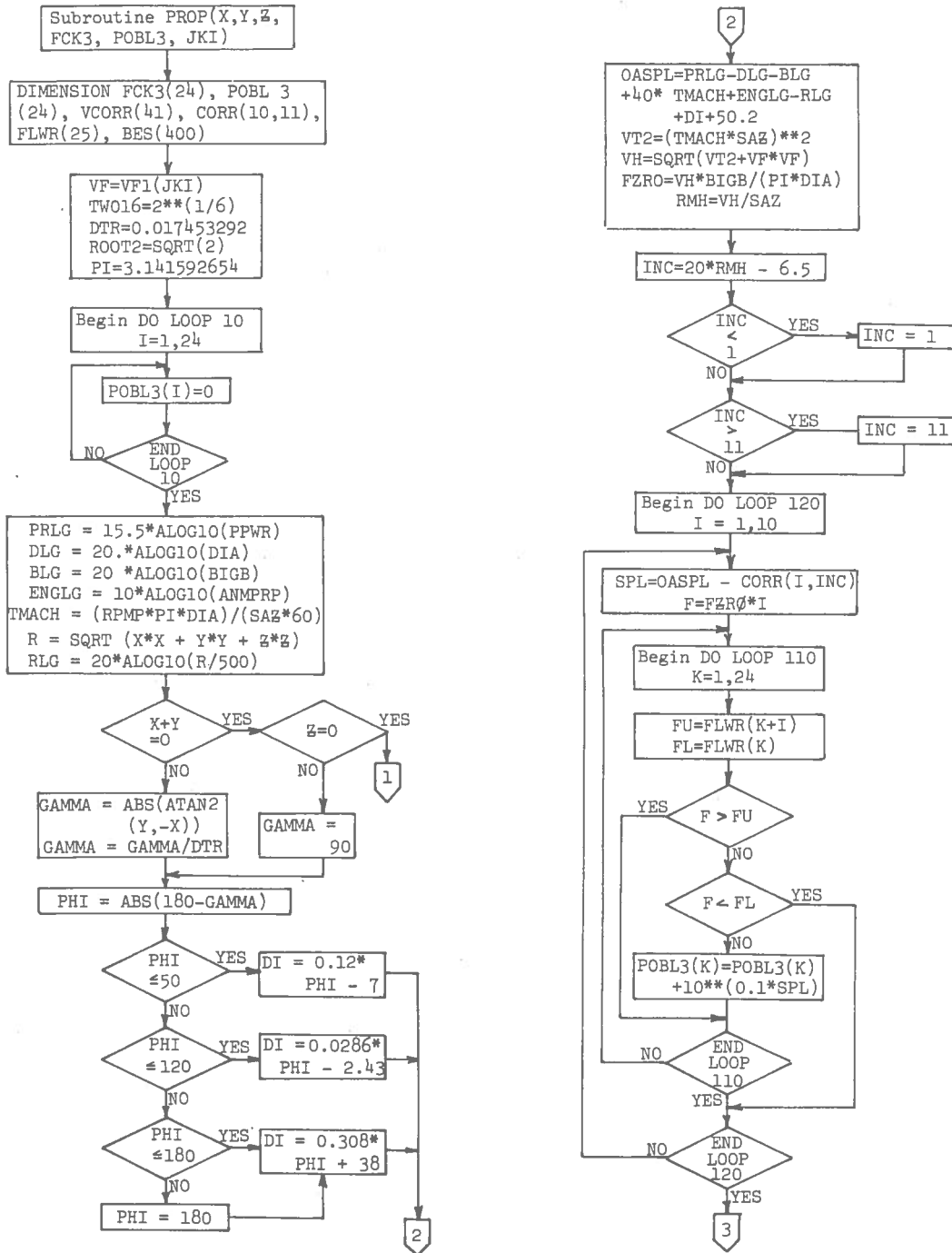
Subroutine Rotor



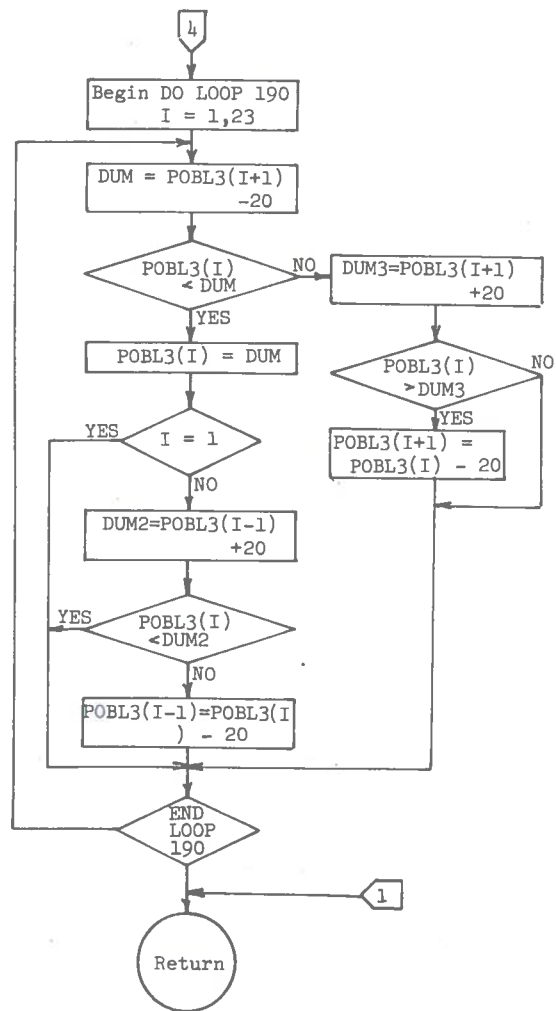
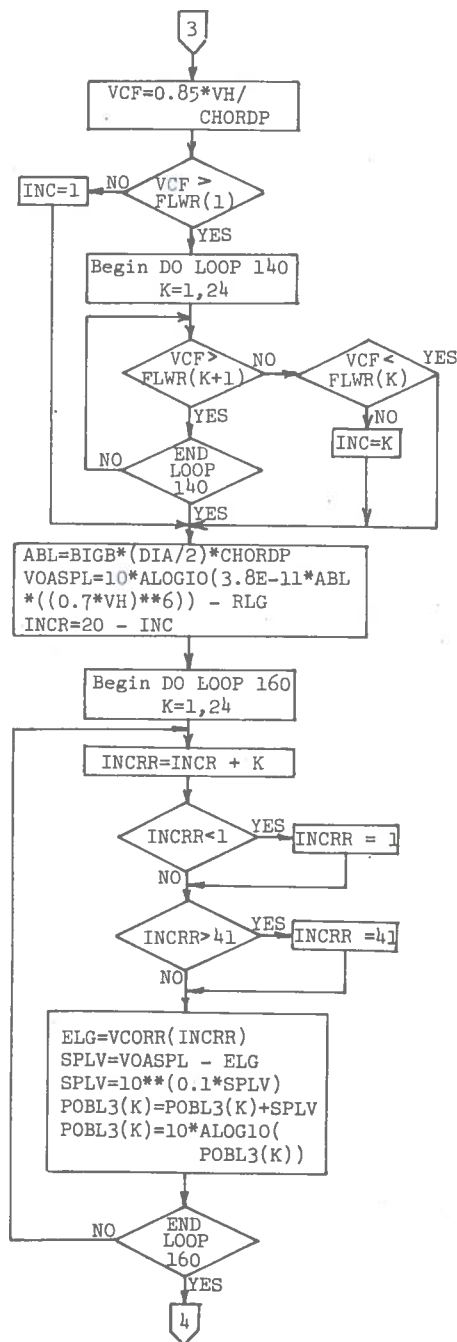
Subroutine Bessel



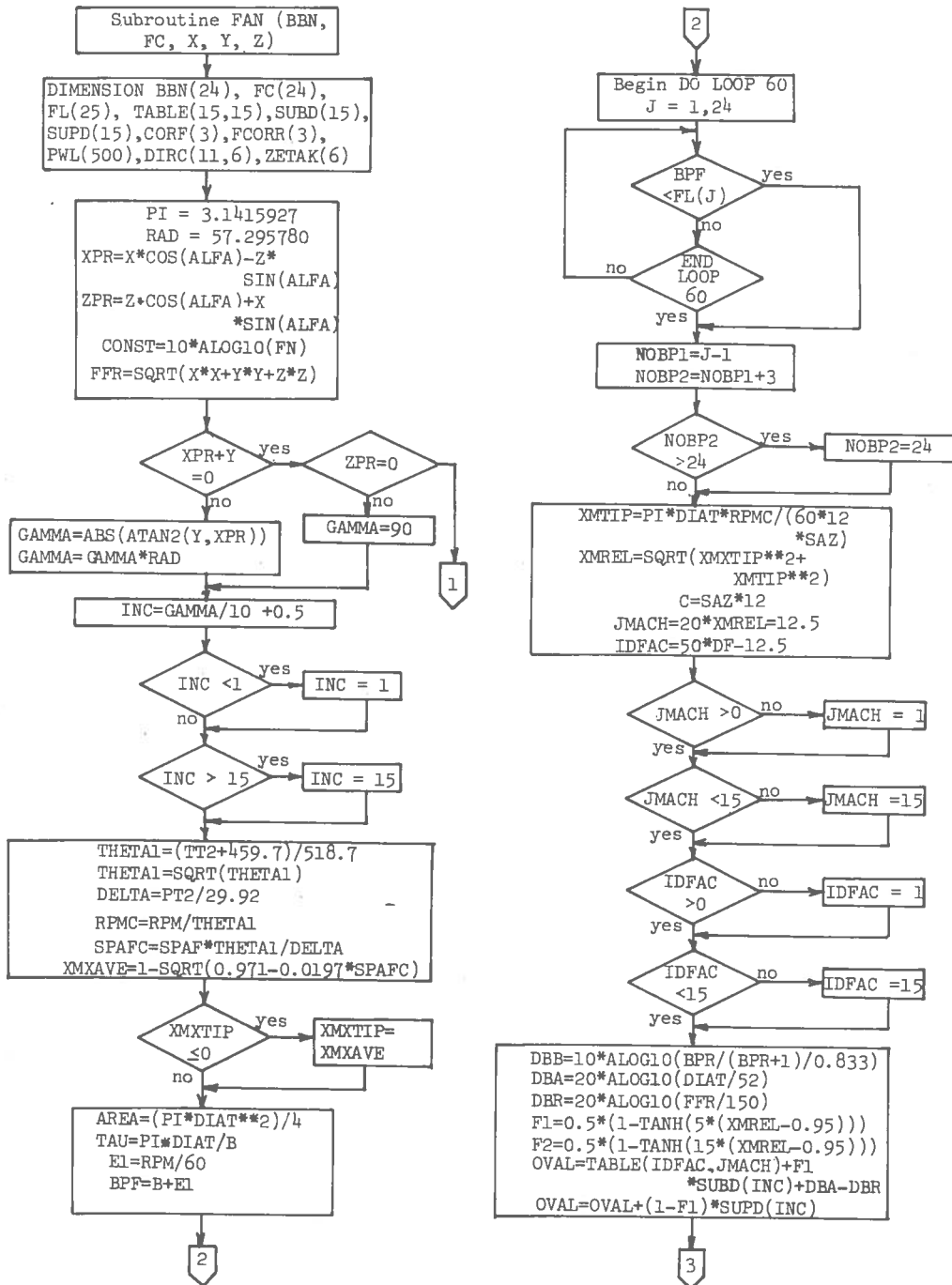
Subroutine BJSIGN Flow Chart



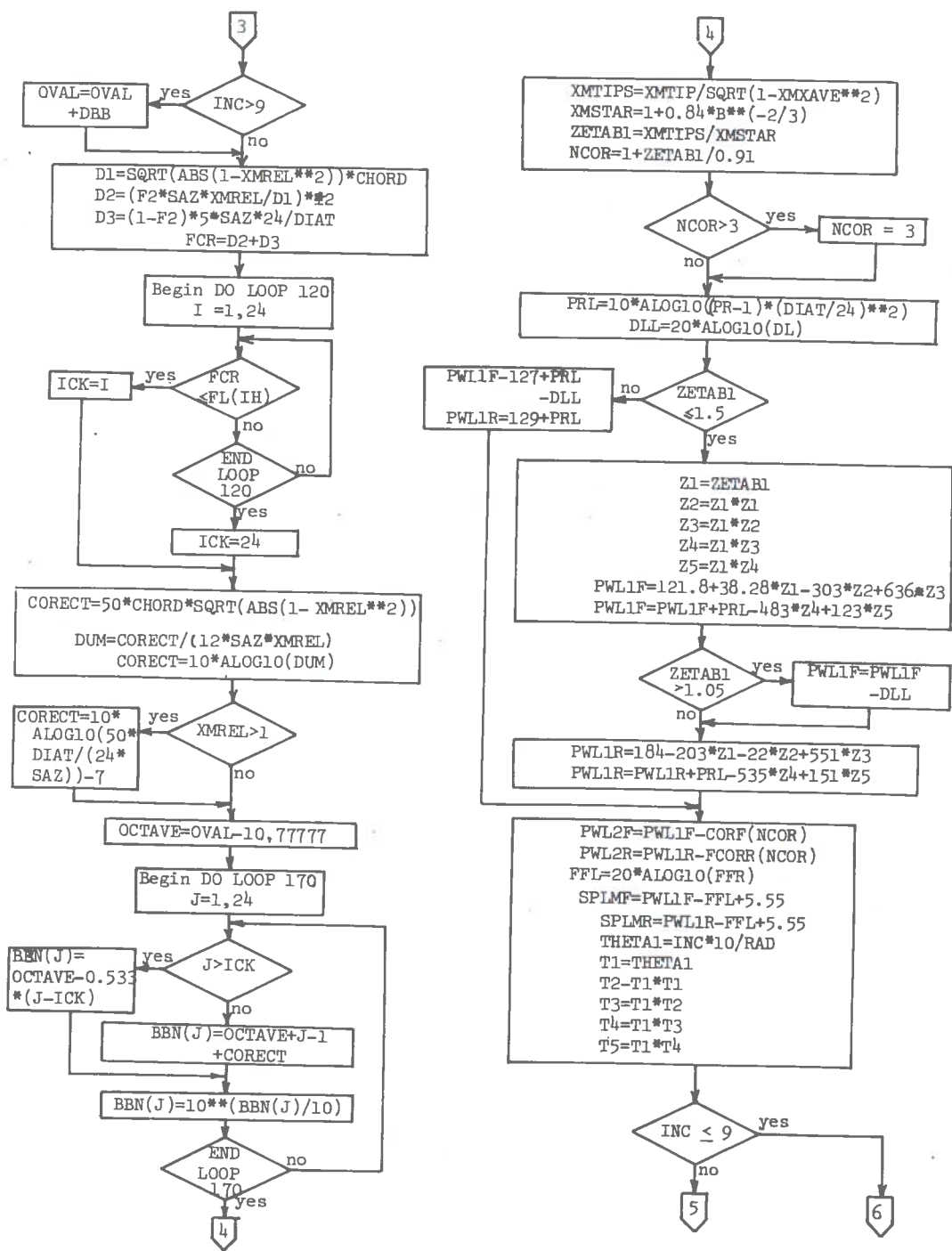
Subroutine PROP Flow Chart



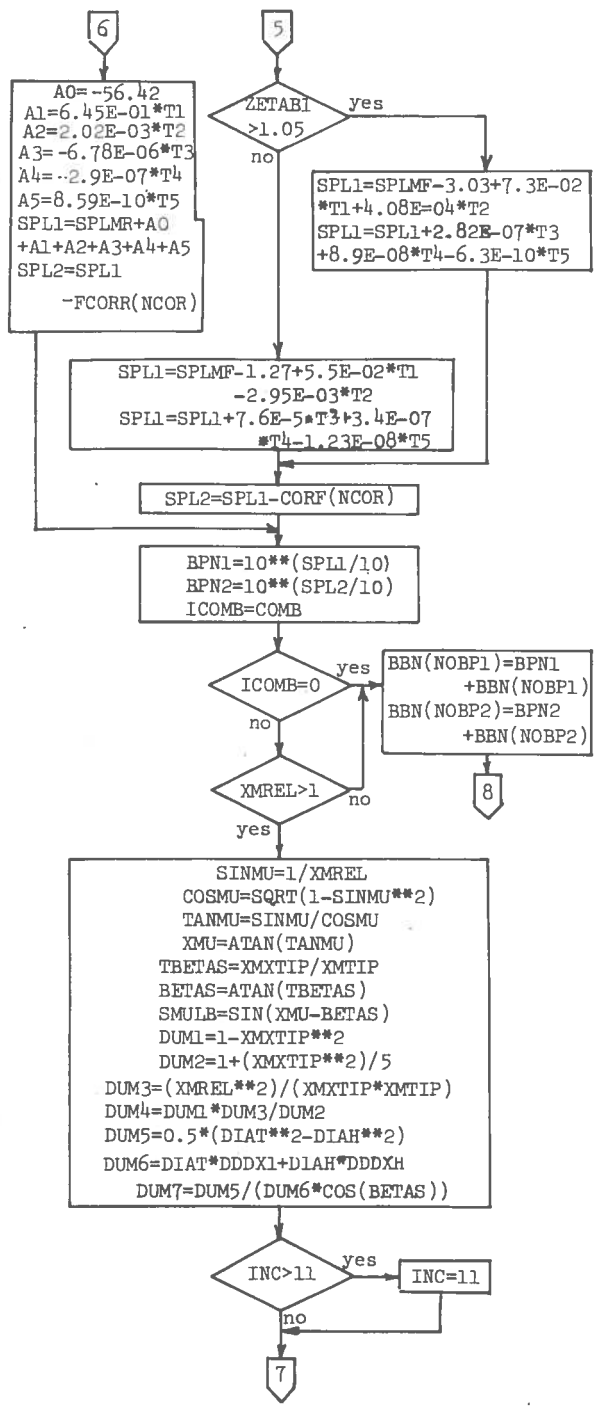
Subroutine PROP



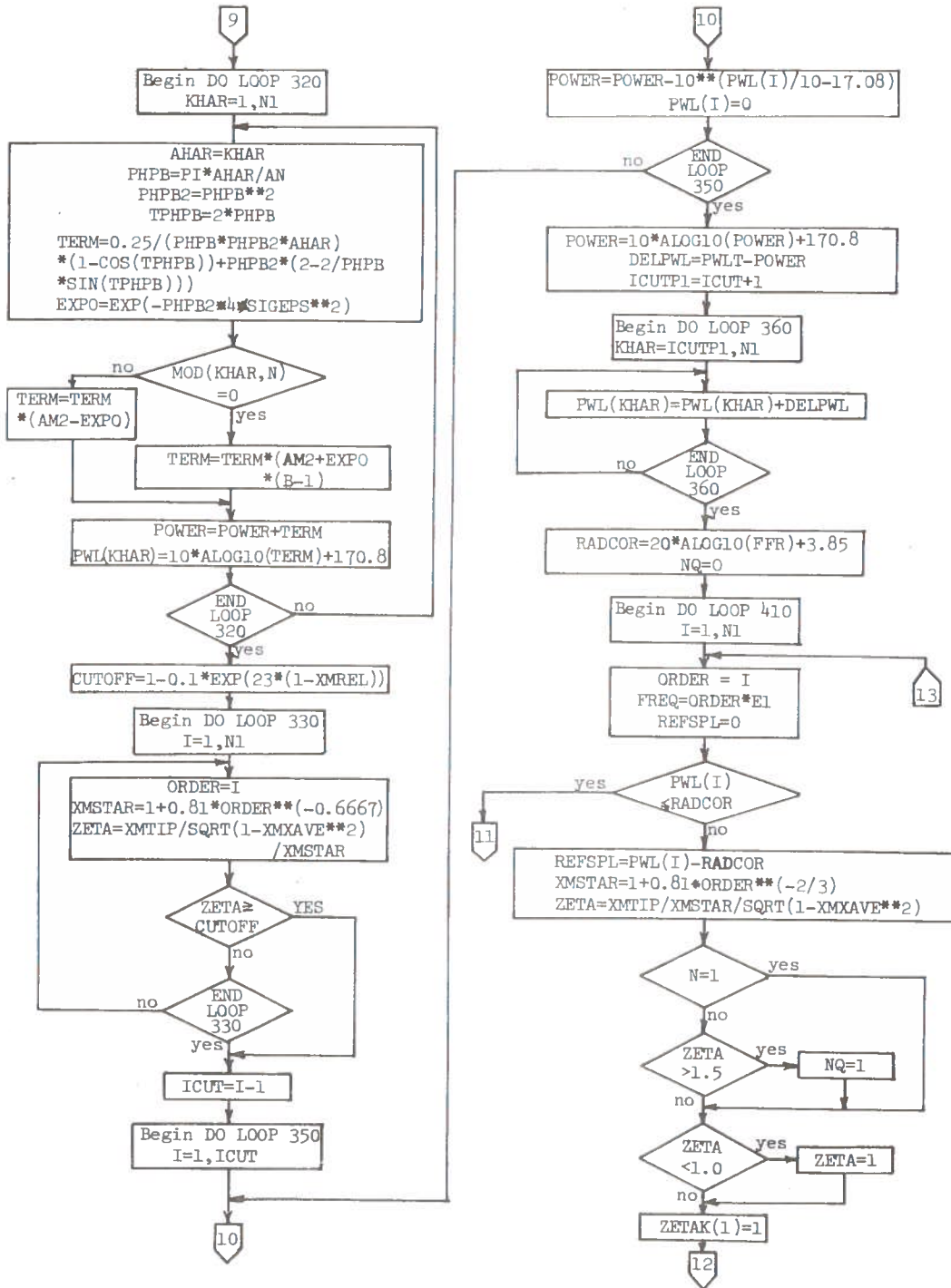
Subroutine FAN Flow Chart



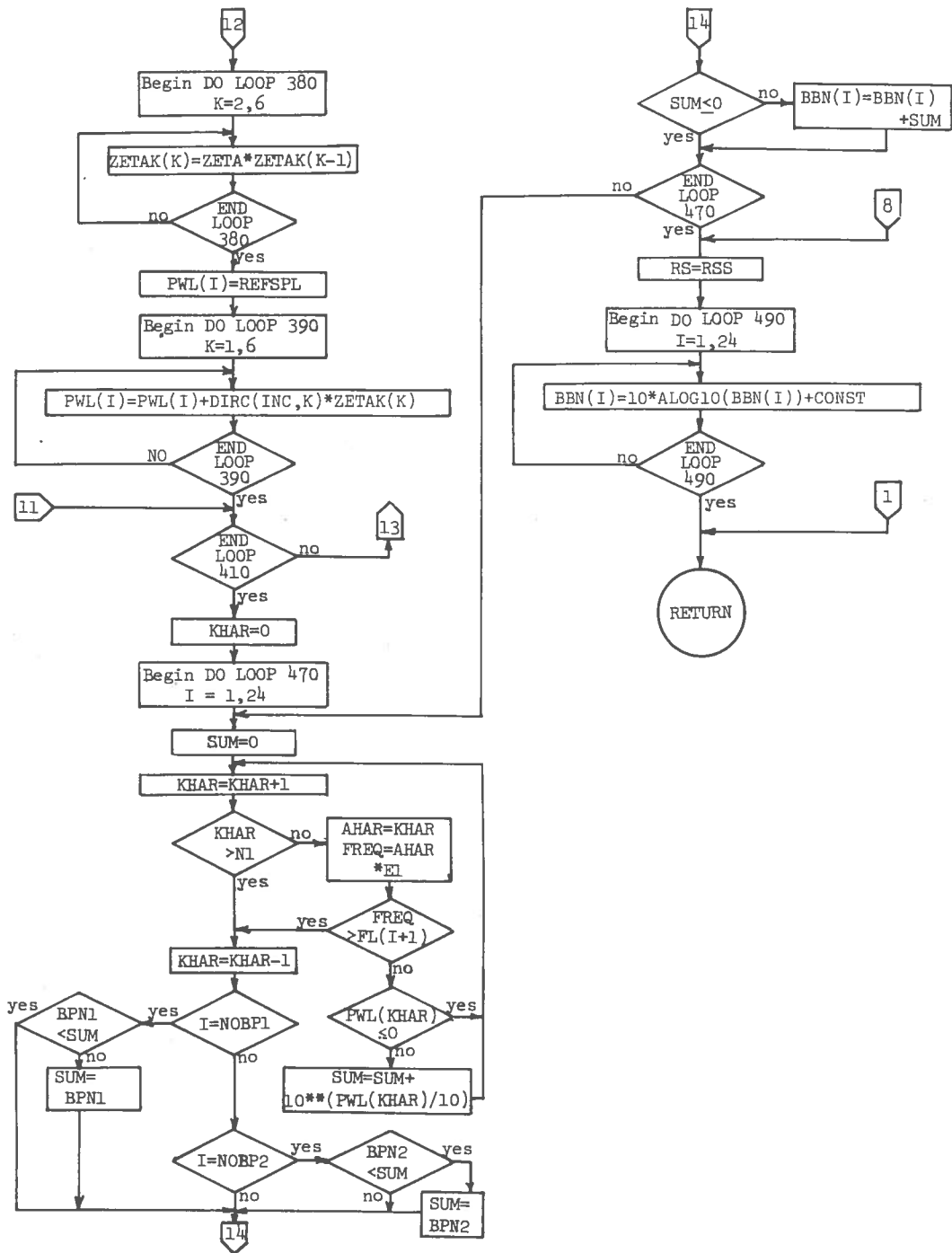
Subroutine FAN



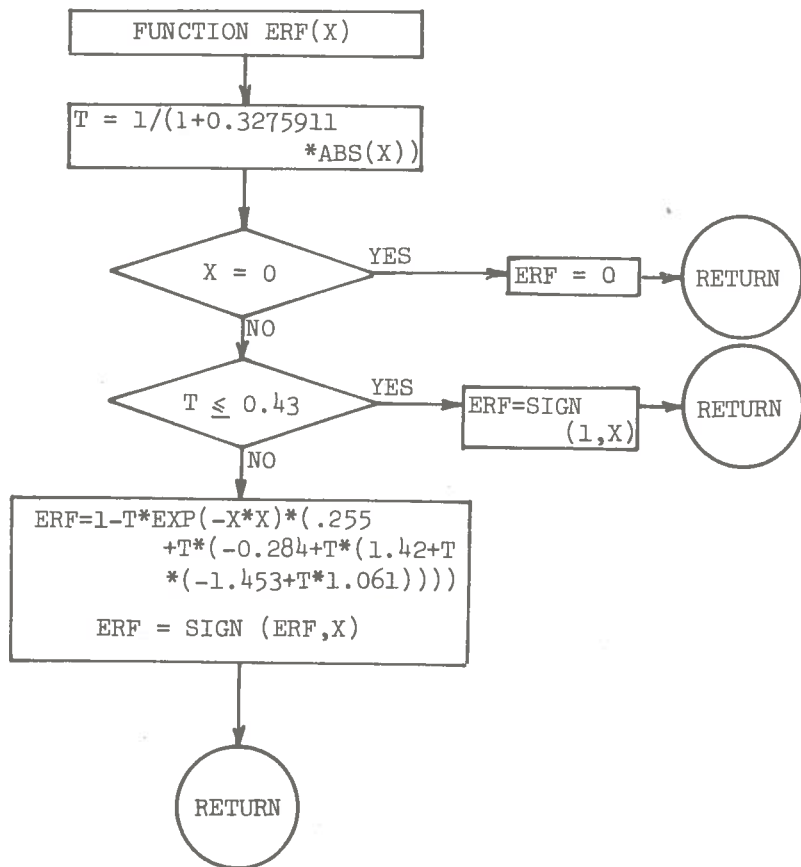
Subroutine FAN



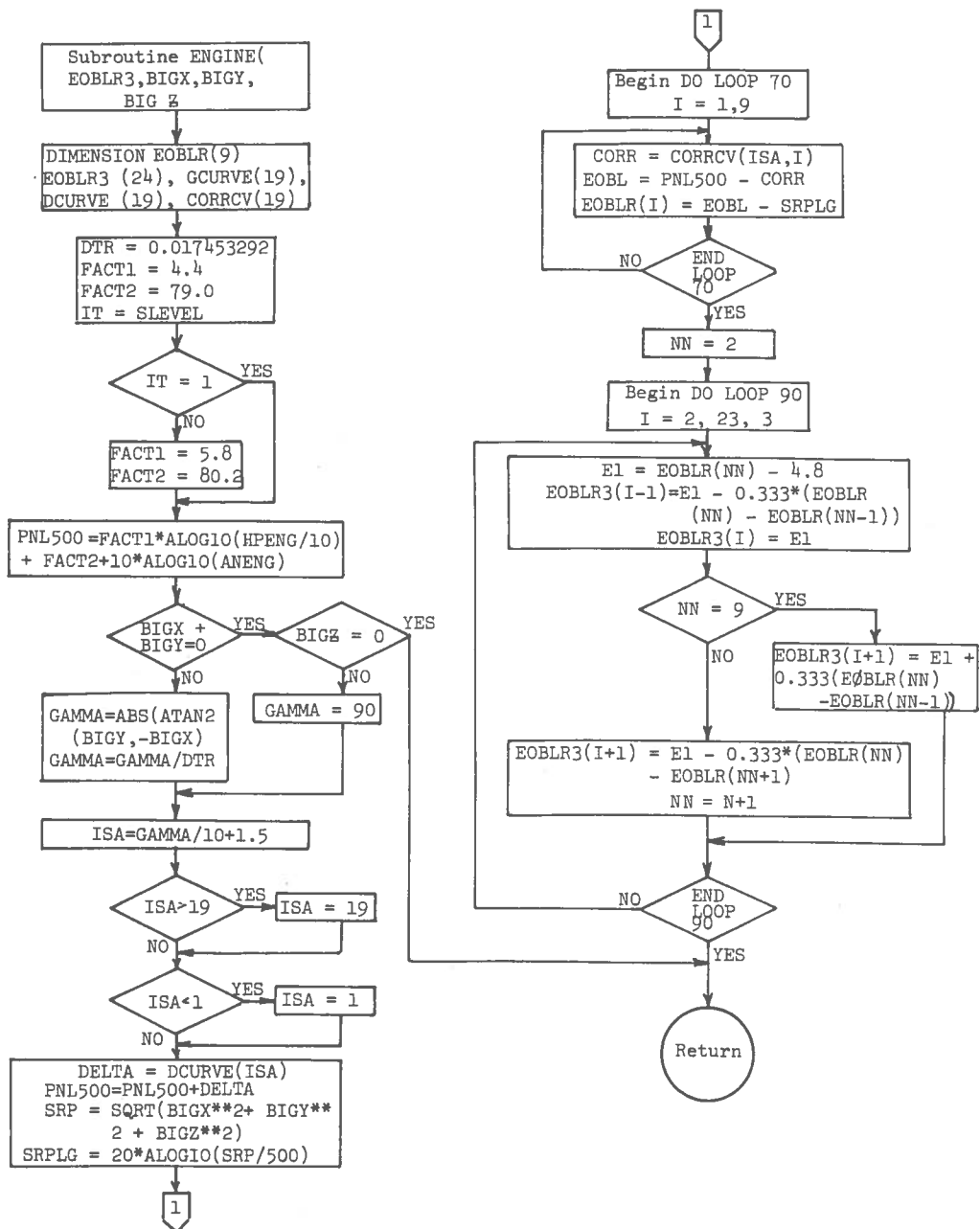
Subroutine FAN



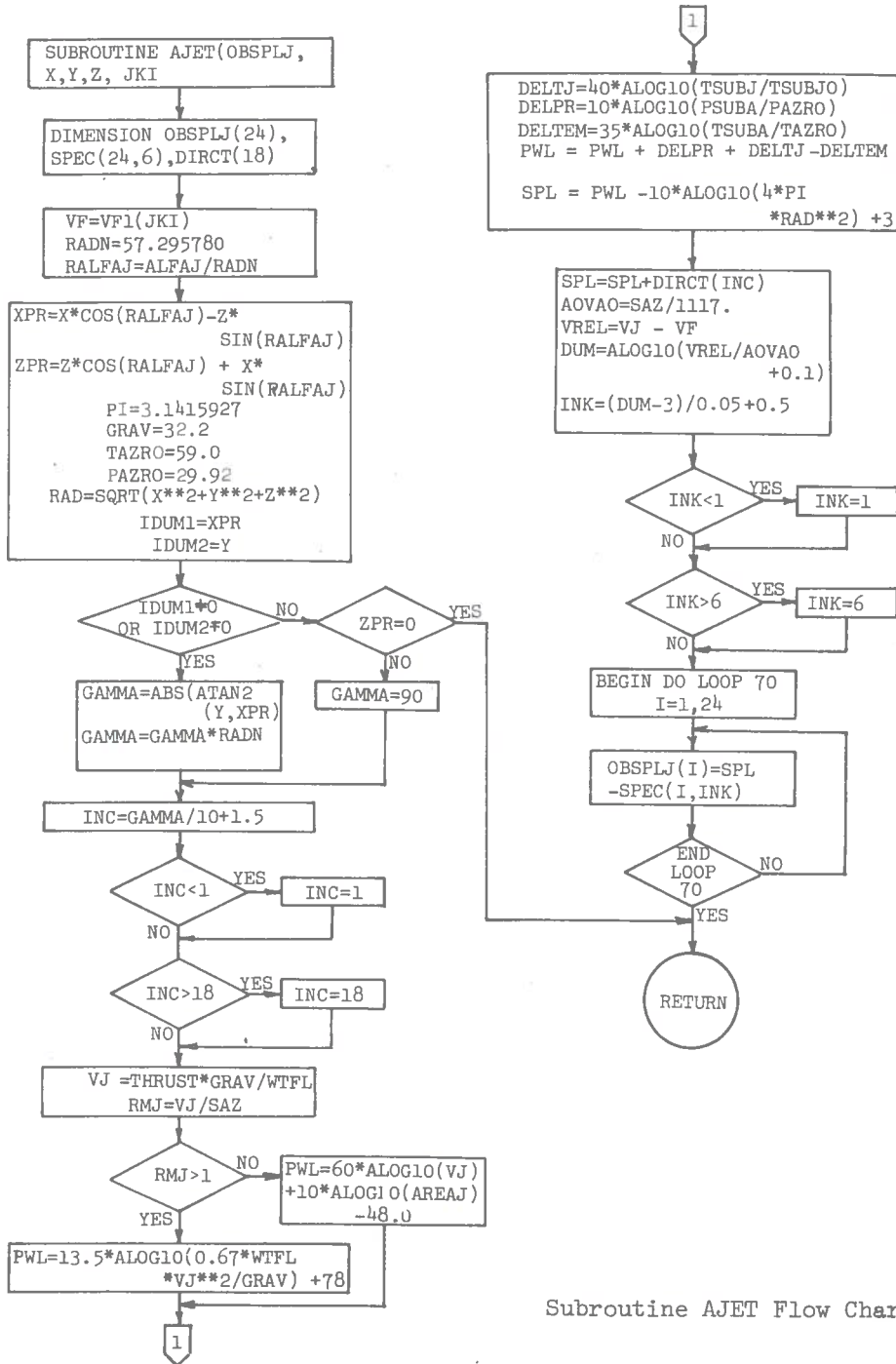
Subroutine FAN



Function ERF Flow Chart



Subroutine ENGINE Flow Chart



Subroutine AJET Flow Chart

APPENDIX D

V/STOL NOISE MODEL PROGRAM LISTING

The following pages contain the compilation listing and cross reference maps for the V/STOL Noise Model on an IBM 360/50 computer.

```

00865
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/*
//LKED.SYSLMOD DD DSN>A.AXX.Y080B2.LOAD.MODULE.Y080B2J,
//DISP>NEW,KEEP,DELETEJ,UNIT>2314,VOL>SER>PACK07,
//SPACE>[TRK,15,1,1],RLSEJ,
//DCB>[RECFM>U,BLKSIZE>7294]
/*
//Y080B2 EXEC PGM>Y080B2
//STEPLIB DD DSN>A.AXX.Y080B2.LOAD.MODULE.UNIT>2314,VOL>SER>PACK07,
//DISP>SHR
//FT05F001 DD DDNAME>SYSIN
//FT06F001 DD SYSOUT>A
//FT33F001 DD UNIT>SCRATCH,SPACE>[TRK,1,1,DCB>[RECFM>F,BLKSIZE>80]
//SYSIN DD *
C V/STOL VEHICLE NOISE PREDICTION PROGRAM --- DECK Y080B
C PROGRAMMED IN FORTRAN IV BY C.L. MUNCH --- DECEMBER 1, 1972
C THIS PROGRAM WAS WRITTEN FOR THE TRANSPORTATION SYSTEMS CENTER OF THE
C DEPARTMENT OF TRANSPORTATION, 55 BROADWAY, CAMBRIDGE, MASSACHUSETTS.
C IT COMPUTES THE EPNL AND THE TIME HISTORIES OF PNL, PNLT, AND DBA AT
C UP TO 10 FIELD POINTS FOR A V/STOL VEHICLE DURING TAKEOFF, LANDING,
C OR CRUISE ALONG A SPECIFIED FLIGHT PATH. THE FLIGHT PATH CONSISTS OF
C UP TO 50 STRAIGHT LINE OR HELICAL SEGMENTS. AIRCRAFT OPERATING PARA-
C METERS ARE CONSTANT ALONG A FLIGHT SEGMENT, HOWEVER SOME OR ALL MAY
C CHANGE FROM SEGMENT TO SEGMENT. NOISE SOURCES WHICH MAY BE INCLUDED
C ARE MAIN ROTORS, TAIL ROTORS, TURBOSHAFT ENGINES, PROPELLERS, LIFT AND
C CRUISE FANS, AND LIFT JETS. SUBROUTINES INCLUDED ARE THE FOLLOWING:
C ACPLNT FLOPT ADDER ATTEN PNL DELTA AJET
C PROP FAN ENGINE ROTOR BJSIGN BESSEL
C ALL INPUT IS ENTERED USING THE LOADER SUBROUTINE AND LABELED COMMON
C DIMENSION DBAL(10,100J),PNC(10,100J),PNLIC(10,100J),XC(10,100J),YC(10,100J),Y0800110
C 1Z(100J),PNMAXC(10J),DBMAXC(10J),PMAXC(10J),FRC(10J),EPNL(10J),XPC(10J)
C 2,BES(400J)
Y0800120
Y0800130

```



```

WRITE [6,240]N,SAZ,SEG,ROTR,RP,FANS,RJ,E,ANMFPT      Y0800450 00951
WRITE [6,250]RCASE,RBIGB,RBIGR,ROMEGN,RTHRUS,RETA, RBETA,RCHORD,RSI Y0800460 00952
1D,RTORO Y0800470 00953
WRITE [6,260]J Y0800480 00954
WRITE [6,250]TCASE,TBIGB,TBIGR,TOMEGN,TTHRUS,TETA,TBETA, TCHORD,TSI Y0800490 00955
1D,TTORO Y0800500 00956
WRITE [6,270]JPWR,DIA,BIGB,RPMP,ANMPRP,CHORDP Y0800510 00957
WRITE [6,280]HPENG,SLEVEL,ANENG Y0800520 00958
WRITE [6,290]DIAT,B,DDXT,RS,TT2,DF,SIGPHI,RPM Y0800530 00959
WRITE [6,300]DIAH,BPR,DDXH,DL,PT2,PR,XXTIP,SPAF, CHORD,COMB,ALFA, Y0800540 00960
1FN Y0800550 00961
WRITE [6,310]THRUST,WFL,AREAJ,PSUBA,TSUBA,TSUBJ,TSUBJO,ALFA Y0800560 00962
WRITE [6,320]AZERO,XPRZRO,YPRZRO,TTINC Y0800570 00963
DO 30 I>1,IS Y0800580 00964
WRITE [6,330]I,ALFLI,J,VFI,I,J,XMAX[I],YMAX[I],INCMAX[I] Y0800590 00965
40 RAD > SORT[XL,K]**2 < YL,K]**2 < ZL,K]**2 Y0800600 00966
C USE SUBROUTINE ACPNLT TO RETURN VALUES OF PNL, PNLT, AND DBA FOR EACH Y0800610 00967
C VALUE OF K Y0800620 00968
C Y0800630 00969
C Y0800640 00970
CALL ACPNLITERAD,N,X[L,K],Y[L,K],Z[K],DB,P,PNLT] Y0800650 00971
PNLT[L,K] > PNT Y0800660 00972
DBA[L,K] > DB Y0800670 00973
PNL[K] > P Y0800680 00974
IF[PNT .GT. PNMALX[L]] PNMALX[L] > PNT Y0800690 00975
IF[DB .GT. DBMAX[L]] DBMAX[L] > DB Y0800700 00976
IF[ P .GT. PMAX[L]] PMAX[L] > P Y0800710 00977
IF [L,EG,IFPT] GO TO 50 Y0800720 00978
L>L<1 Y0800730 00979
GO TO 40 Y0800740 00980
50 L > 1 Y0800750 00981
K > K < 1 Y0800760 00982
DUM > PNMALX[IFPT] - 10.0 Y0800770 00983
IF [PNT,GE,DUM] GO TO 60 Y0800780 00984
IF [K,GT,INCR] GO TO 80 Y0800790 00985
60 IF [K,LE,IK] GO TO 40 Y0800800 00986
N > N < 1 Y0800810 00987
IF [N,GT,IS] GO TO 70 Y0800820 00988
CALL LOADER[SAZ] Y0800830 00989
IK > INCMALX[N] Y0800840 00990
GO TO 20 Y0800850 00991
70 IF [K,GT,100] GO TO 100 Y0800860 00992
N > N - 1 Y0800870 00993
GO TO 40 Y0800880 00994
80 CONTINUE Y0800890 00995
IF [IFPT,EG,1] GO TO 100 Y0800900 00996
IL > IFPT - 1 Y0800910 00997
DO 90 I>1,IL Y0800920 00998
DUM > PNMALX[I] - 10.0 Y0800930 00999
IF [PNLT[I,K-I],GT,DUM] GO TO 60 Y0800940 01000

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90 CONTINUE
100 CONTINUE
DO 120 L>1,IFPT
DUM > PNMAX[L] - 10.50001
SUM > 0.
KK > K - 1
DO 110 I>1,KK
PNDB > PNL[L,I]
IF [PNDB.LT.DUM] GO TO 110
YY > 10.0 * [PNDB/10.0]
SUM > SUM < YY
110 CONTINUE
DURCOR > 10.0 * ALOG10(SUM * TINC/10.0 < 0.1] - PNMAX[L]
EPNL[L] > PNMAX[L] < DURCOR
120 CONTINUE
C END CALCULATION OF VEHICLE EPNL. AT THIS POINT AVAILABLE QUANTITIES
C ARE THE FOLLOWING :
C * VEHICLE EPNL
C * SLANT RANGE
C * UBA TIME HISTORY AND MAXIMUM DBA
C * PNL TIME HISTORY AND MAXIMUM PNL
C * PNL TIME HISTORY AND MAXIMUM PNL
C * DURATION CORRECTION
C * INPUT VARIABLES
C THE FOLLOWING WRITE STATEMENTS ARE USED IN DEBUG STAGE ONLY
C
WRITE [6,130]
130 FORMAT(1H1,25X,39H CHECKOUT CASE FOR V/STOL VEHICLE NOISE,
119H PREDICTION PROGRAM,/,26X,57[1H-J]
WRITE [6,140]TINC,XPRZRO,YPRZRO,AZERO,THMAXO
140 FORMAT(//, TINC>:,F5.2,X:XPRZRO>:,F10.2,2X:,YPRZRO>:,F7.2,2X,
1:AZERO>:,F7.2,2X:,THMAXO>:,F7.2,/,3X:,SEG:,4X:,PATH:,3X:,ALFN:,3X
2:,VF1:,4X:,XMAX:,3X:,YMAX:,2X:,RADIUS:,2X:,PHIMAX:/,57[1H-J]
DO 150 L>1,IS
150 WRITE [6,160]L,PATH[L],ALF[L],VF[L],XMAX[L],YMAX[L],RADIUS[L],PHM
1AX[L]
160 FORMAT(1X,15,2X,7F7.1]
WRITE [6,180]
DO 170 L>1,IFPT
170 WRITE [6,190]FR[L],EPNL[L],PNMAX[L],PMAX[L],DBMAX[L],XP[L]
WRITE [6,210]TINC,IFPT
WRITE [6,200]I[PNL[L,K],K>1,100],L>1,IFPT]
WRITE [6,220]TINC,IFPT
WRITE [6,200]I[PNL[L,K],K>1,100],L>1,IFPT]
WRITE [6,230]TINC,IFPT
WRITE [6,200]I[DBALL[K],K>1,100],L>1,IFPT]
180 FORMAT(//,3X:,RANGE:,3X:,EPNL:,4X:,PNLTM:,4X:,PNL:,5X:,DBA:,7X,

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Y0800950
Y0800960
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Y0800990
Y0801000
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Y0801100
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Y0801210
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Y0801270
Y0801280
Y0801290
Y0801300
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Y0801340
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Y0801380
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Y0801400
Y0801410
Y0801420
Y0801430
Y0801480

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1: XPR:,,1X,49[1H-J]
190 FORMAT(1X,F7.2,4F8.2,F10.1)
200 FORMAT(10F10.2)
210 FORMAT(//,1X,PULT TIME HISTORY IN:,F4.1, SECOND INCREMENTS FOR:,
1,13, FIELD POINTS:]
220 FORMAT(//,1X,PULT TIME HISTORY IN:,F4.1, SECOND INCREMENTS FOR:,
113, FIELD POINTS:]
230 FORMAT(//,1X,DBA TIME HISTORY IN:,F4.1, SECOND INCREMENTS FOR:,
113, FIELD POINTS:]
240 FORMAT(//,25[1H*],INPUT VARIABLES:,25[1H*],/24[1H*],
1:FLIGHT SEGMENT:,13,24[1H*],//, COMMON:,
2: VARIABLES &:/,16[1H-J],//, SAZ >:,F9.2, SEG >:,F6.2,
3: ROTR >:,F4.1, RP >:,F4.1, FANS >:,F4.1, RJ >:,F4.1, E >:,
4F4.1, ANMFT >:,F5.1,//, MAIN ROTOR VARIABLES &:/,21[1H-J]
250 FORMAT: SM-K >:,F5.2,3X,BIGB >:,F6.2,3X,BIGR >:,F7.2,3X,
1:OMEGN >:,F8.2,3X,THRUS >:,F9.1,//, ETA >:,F5.2,3X,BETA >:,
2F6.2,3X,CHORD >:,F7.2,3X,SID >:,F8.2,3X,TORG >:,F9.1]
260 FORMAT: TAIL ROTOR VARIABLES &:/,21[1H-J]
270 FORMAT: PROPELLER VARIABLES &:/,20[1H-J],//, POWER >:,F7.1,
1: DIA >:,F7.2, BIGB >:,F5.1, RPM >:,F8.2, NUMPRP >:,F5.1,
2: CHORD >:,F7.2]
280 FORMAT: ENGINE VARIABLES &:/,17[1H-J],//, POWER >:,F7.1,
1: SLEVEL >:,F4.1, NUMENG >:,F4.1]
290 FORMAT: FAN VARIABLES &:/,14[1H-J],//, DIAT >:,F6.2, B >:,
1F6.2, DDDXT >:,F7.2, RS >:,F8.2, TT2 >:,F6.2, DF >:,F6.2,
2: SIGPHI >:,F5.2, RPM >:,F7.2]
300 FORMAT: DIAH >:,F6.2, BPR >:,F6.2, DDDXH >:,F7.2, DL >:,
1F8.2, PT2 >:,F6.2, PR >:,F6.2, XMXTP >:,F5.2, SPAF >:,
2F7.2,//, CHORD >:,F6.2, COMR >:,F6.2, ALFA >:,F7.2,
3: FI >:,F8.2]
310 FORMAT: JET VARIABLES &:/,14[1H-J],//, THRUST >:,F8.1,
1: WTFL >:,F7.2, AREAJ >:,F7.2, PSUBA >:,F6.2, TSUBA >:,
2F6.2, TSUBJ >:,F6.1, TSUBJO >:,F6.1, ALFA >:,F5.1]
320 FORMAT: FIELD POINT VARIABLES &:/,22[1H-J],//, AZERO >:,F8.2,
1: XPRZRO >:,F8.1, ZPRZRO >:,F8.1, TINC >:,F5.2,//, SEG:,
23X, THETA:,3X,SPEED:,3X,XBREAK:,3X,YBREAK:,3X,INCMAX,/,2X,
33[1H-J],2X,6[1H-J],2X,6[1H-J],2X,8[1H-J],2X,8[1H-J],2X,6[1H-J]
330 FORMAT(15,2F8.2,2F10.2,16]
END
SUBROUTINE FLDPTCFX,FY,FZ,FR,INCRZO]
C TITLE: FIELD POINT
C PURPOSE: TO CALCULATE THE X,Y,Z COORDINATES OF THE AIRCRAFT RELATIVE
C TO THE OBSERVER ON THE GROUND.
C ABSTRACT: THE POSITION OF THE AIRCRAFT AT GIVEN INSTANTS OF TIME IS
C CALCULATED IN COORDINATES X',Y',Z', WHICH ARE STATIONARY
C WITH THE ORIGIN LOCATED AT THE TAKEOFF POINT. THESE POINTS
C ARE THEN TRANSFORMED INTO THE X,Y,Z SYSTEM WHOSE ORIGIN IS

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Y0801530
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Y0801570
Y0801580
Y0801590
Y0801600
Y0801610
Y0801620
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Y0801890
FLDP0010
FLDP0020

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6TT2,PT2,ALFA, FN, COMB, THRUST, WTL, AREA, J, PSUBA, TSUBA, TSUBJ, TSUBJO,
7ALFAJ, ROTR, RP, FANS, RJ, E
COMMON /B2/ XP
C
DTR > 0.017453925
IFTYPE > FLTYPE < 0.00001
N > 1
ISEG > SEG < 0.0001
INCZRO > 100
IFPT > ANMFPT < 0.0001
DUD > XPRZRO / IFPT
TMAX1 > 0.
XMAX1 > 0.
YMAX1 > 0.
ZMAX1 > AZERO
ALFN > ALF11 * DTR
PHMAXN > PHMAX11 * DTR
THMAX1 > THMAXO * DTR
C
C CALCULATE COORDINATES FOR IFPT OBSERVERS
C
DO 10 II, I, IFPT
10 XPC111 > II * DUD
IF [ISEG.NE.1] GO TO 20
TMAX > 100.0 * TINC < 1.0
GO TO 60
20 IPH > PATHC11 < 0.0001
IPH > PATH11 < 0.0001
IF [IPTH.EQ.1] GO TO 50
C
C CALCULATE END POINTS AND TMAX FOR SEGMENT 1 IF STRAIGHT LINE
C
IDM > ABS[THMAXO] < 0.0001
IF [IDM.EQ.90] GO TO 30
IF [IDM.EQ.270] GO TO 30
TMAX > ABS[XMAX11] / ABS[VFI11] * COS[THMAX11] * COS[ALFN11]
YMAX11 > VFI11 * TMAX * COS[ALFN11] * SIN[THMAX11]
GO TO 40
30 TMAX > ABS[YMAX11] / ABS[VFI11] * COS[ALFN11]
XMAX11 > VFI11 * TMAX * COS[ALFN11] * COS[THMAX11]
40 ZMAX > VFI11 * TMAX * SIN[ALFN11]
THMAX > THMAX1
GO TO 60
C
C CALCULATE END POINTS AND TMAX FOR SEGMENT 1 IF HELICAL
C
50 APHMAX > ABS[PHMAXN]
SPHMAX > SIN[APHMAX/2]
SUMANG > THMAX1 < 0.5 * PHMAXN
TMAX > RADIUS11 * APHMAX / ABS[VFI11] * COS[ALFN11]

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FLDP0120 01151
FLDP0130 01152
FLDP0140 01153
FLDP0150 01154
FLDP0180 01155
FLDP0190 01156
FLDP0200 01157
FLDP0210 01158
FLDP0220 01159
FLDP0230 01160
FLDP0240 01161
FLDP0250 01162
FLDP0260 01163
FLDP0270 01164
FLDP0280 01165
FLDP0290 01166
FLDP0300 01167
FLDP0310 01168
Y0800070 01169
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FLDP0400
FLDP0410
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FLDP0430
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FLDP0500

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FLDP0510
FLDP0520
FLDP0530
FLDP0540

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DUMMY > 2.0 * RADIUS[1] * SPHMAX
XMAX[1] > DUMMY * COS[SUMANG]
YMAX[1] > DUMMY * SIN[SUMANG]
ZMAX > AZERO < RADIUS[1] * APHMAX * TAN[ALFN]
THMAX > THMAX1 < PHMAXN
60 CONTINUE
C
C BEGIN LOOP TO CALCULATE POINTS ALONG FLIGHT PATH
C
DO 240 K>1,100
T > K * TINC
IF [T.LI.TMAX] GO TO 160
INCMAX[N] > K-1
N > N < 1
THMAX1 > TMAX
XMAX1 > XMAX[N-1]
YMAX1 > YMAX[N-1]
ZMAX1 > ZMAX
THMAX1 > THMAX
ALFN > ALFN[N] * DTR
IF [N.LI.ISEG] GO TO 70
TMAX > 100. * TINC < 1.0
IPATH > PATH[N] < 0.0001
IF [IPATH.EQ.1] GO TO 180
GO TO 150

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C
C CALCULATION FOR STRAIGHT LINE SEGMENTS
C
70 IF [THMAX1.LT.0.] GO TO 90
80 IF [THMAX1.LI.6.28319] GO TO 100
THMAX1 > THMAX1 - 6.28319
GO TO 80
90 IF [THMAX.GT.-6.28319] GO TO 100
THMAX1 > THMAX1 < 6.28319
GO TO 90
100 CONTINUE
IPATH > PATH[N] < 0.00001
IF [IPATH.EQ.1] GO TO 170
IDUM > ABS[THMAX1 / DTR]
IF [IDUM.EQ.90] GO TO 110
IF [IDUM.EQ.270] GO TO 110
TMAX > TMAX1 < ABS[[XMAX[N] - XMAX1] / [VF1[N]*COS[ALFN]
1 * COS[THMAX1]]]]
GO TO 120
110 TMAX > TMAX1 < ABS[[YMAX[N] - YMAX1] / [VF1[N]*COS[ALFN]]]]
120 THMAX > THMAX1
T1 > TMAX - TMAX1
DXMAX > XMAX1 < VF1[N] * T1 * COS[ALFN] * COS[THMAX]
DYMAY > YMAX1 < VF1[N] * T1 * COS[ALFN] * SIN[THMAX]
ZMAX > ZMAX1 < VF1[N] * T1 * SINE[ALFN]

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FLDP0550 01201
FLDP0560 01202
FLDP0570 01203
FLDP0580 01204
FLDP0590 01205
FLDP0600 01206
FLDP0610 01207
FLDP0620 01208
FLDP0630 01209
FLDP0640 01210
FLDP0650 01211
FLDP0660 01212
FLDP0670 01213
FLDP0680 01214
FLDP0690 01215
FLDP0700 01216
FLDP0710 01217
FLDP0720 01218
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FLDP0750 01221
FLDP0760 01222
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FLDP0780 01224
FLDP0790 01225
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FLDP0800
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FLDP0990
FLDP1000
FLDP1010

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DELX > ABSX XMAX[N] - DXMAX J
DELY > ABSY YMAX[N] - DYMAX J
ERRX > DELX / XMAX[N]
ERRY > DELY / YMAX[N]
IF [ERRX.LE.0.1] GO TO 140
IF [ERRY.LE.0.1] GO TO 140

C WRITE WARNING MESSAGE IF CALCULATED END POINTS OF STRAIGHT LINE
C SEGMENT DISAGREE WITH INPUT VALUES BY MORE THAN 10 PER-CENT
C
WRITE [6,130]N,DXMAX,DYMAX,XMAX[N],YMAX[N],K
130 FORMAT[//]: CALCULATED END POINTS FOR SEGMENT:,I3,: DO NOT AGREE:,FLDP1090
1: WITH INPUT. CALCULATION PROCEEDING WITH NEW END POINTS.,//, FLDP1100
2: X CALCULATED>:F8.1,: Y CALCULATED>:F8.1,: X INPUT>:F8.1,
3: Y INPUT>:F8.1,/: OCCURED AT INCREMENT NUMBER:,I3]
140 XMAX[N] > DXMAX
YMAX[N] > DYMAX
TMAX > TMAX1 < ABS[[(XMAX[N]-YMAX1]/[VF1[N]]*COS[ALFN]]*COS[THMAX1]]]
ZMAX > ZMAX1 < VF1[N]*[TMAX-TMAX1]*SIN[ALFN]
150 DUM1 > VF1[N] * [T - TMAX1] * COS[ALFN]
DUM1 > XMAX1 < DUM1 * COS[THMAX]
DUM1 > YMAX1 < DUM1 * SIN[THMAX]
DUM1 > ZMAX1 < VF1[N] * [T - TMAX1] * SIN[ALFN]
DUMANG > THMAX1
GO TO 190
160 IPATH > PATH[N] < 0.00001
IF [IPATH.EQ.1] GO TO 180
GO TO 150

C CALCULATION FOR HELICAL SEGMENTS
C
170 PHMAXH > PHMAX[N] * DTR
APHMAX > ABS[PHMAXH]
SPHMAX > SIN[APHMAX/2]
SUMANG > THMAX1 < PHMAXH/2
TMAX > TMAX1 < RADIUS[N] * APHMAX / [COS[ALFN] * VF1[N]]
XMAX[N] > XMAX1 < 2. * RADIUS[N] * SPHMAX * COS[SUMANG]
YMAX[N] > YMAX1 < 2. * RADIUS[N] * SPHMAX * SIN[SUMANG]
ZMAX > ZMAX1 < RADIUS[N] * APHMAX * TAN[ALFN]
THMAX > THMAX1 < PHMAXH
180 CONTINUE
PHISK > VF1[N] * [T - TMAX1] * COS[ALFN] / RADIUS[N]
APHMAX > ABS[PHISK]
DUM1 > 2.0 * RADIUS[N] * SIN[APHMAX/2]
SUMANG > THMAX1 < PHISK/2.
XPR > XMAX1 < DUM1 * COS[SUMANG]
YPR > YMAX1 < DUM1 * SIN[SUMANG]
ZPR > ZMAX1 < RADIUS[N] * APHMAX * TAN[ALFN]
DUMANG > PHISK < THMAX1
190 CONTINUE

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FLDP1490
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FLDP1580
FLDP1590
FLDP1600
FLDP1610
FLDP1620
FLDP1630
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ACPN0020

IF [IFTYPE.EQ.1] GO TO 200
DUMANG > DUMANG < 1.5707963
200 COSTHK > COS[DUMANG]
    SINTHK > SIN[DUMANG]
C
C CALCULATE X,Y,Z FIELD POINTS FOR EACH OF IFPT OBSERVERS
C
DO 220 L>1,IFPT
FX[L,K] > [XPLJ]-XPRJ*COSTHK < [YPRZRO-YPRJ]*SINTHK
FY[L,K] > -[YPRZRO-YPRJ]*COSTHK < [XPLJ]-XPRJ*SINTHK
DUM1 > [XPR - XPLJ]**2
DUM2 > [YPR - YPRZRO]**2
FRD > SORT[DUM1 < DUM2 < ZPR**2]
IF [K.EQ.1] GO TO 210
IF [FRD.GE.FRCLJJ] GO TO 220
210 FRCLJ > FRD
    INCZRO > K
220 CONTINUE
230 FZCKJ > ZPR
240 CONTINUE
RETURN
END
SUBROUTINE ACPNLTRAD,JI,X,Y,Z,DB,PN,PNTJ
C
C TITLE: SUBROUTINE ACPNLT
C
C PURPOSE: TO CALCULATE THE TOTAL VEHICLE ONE-THIRD OCTAVE BAND NOISE
SPECTRUM AT A SPECIFIED OBSERVER FOR A GIVEN AIRCRAFT
POSITION ON THE FLIGHT PATH, TO APPLY THE NECESSARY
ATMOSPHERIC ABSORPTION TO THE SPECTRUM, AND CALCULATE THE
RESULTING PNL, PNLT, AND DBA OF THE SPECTRUM.
C
C ABSTRACT: THE SUBROUTINE IS CALLED BY THE MAIN PROGRAM. IT CALLS THE
NECESSARY COMPONENT NOISE PREDICTION ROUTINES AND FORMS A
VEHICLE SPECTRUM BY ENERGY SUMMING THE COMPONENT SPECTRA.
THE VEHICLE SPECTRUM IS CORRECTED FOR ATMOSPHERIC ABSORPTION
AND THE PERCEIVED NOISE LEVEL, TONE CORRECTED PERCEIVED
NOISE LEVEL, AND A-WEIGHTED SOUND LEVEL.
C
C USAGE:
.....(RAD,JI,X,Y,Z,DB,PH,PNT)
RAD.....DISTANCE FROM OBSERVER TO AIRCRAFT
JI.....FLIGHT PATH SEGMENT NUMBER
X
Y.....COORDINATES OF OBSERVER RELATIVE TO AIRCRAFT
Z
DB.....DBA VALUE RETURNED TO MAIN
PN.....PNL VALUE RETURNED TO MAIN
PNT.....PNLT VALUE RETURNED TO MAIN
C
C LABELED
COMMON: /B1/, /INPUT/, /B2/

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C C /B1/ SEE SUBROUTINE FLDPT
C C /INPUT/ CONTAINS INPUT DATA FROM LOADER
C C
C C SUBROUTINES CALLED: ROTOR, ADDER, PROP, FAN, AJET, ENGINE, ATTEM,
C C PNL
C C
C C DIMENSION FCF[24],TEMP1[24],TEMP2[24]
C C 1,BE[400]
C C COMMON /B1/ BES,INCMAX[50]
C C COMMON /INPUT/ SAZ,SEG,FLTYPE,RCASE,RETA,RBIGB,RBIRGR,ROMEGR,RSID,
C C 1RCHORD,RTHRUS,RTORG,RBETA,TCASE,TEA,TBIBG,TBIGR,TOMEGN,TSID,
C C 2TCHORD,TTHRUS,TTORG,TBETA,PPWR,DIA,BIGB,RPMP,ANMPRP,CHORDP,
C C 3PATE[50],XMAX[50],YMAX[50],PHMAX[50],RADIUS[50],VFI[50],ALFL[50],
C C 4XPRZRO,YPRZRO,THMAXO,AZERO,TINC,ANMFT,HPENG,SLEVEL,ANENG,DIAT,
C C 5DIAH,B,IBPR,CHORD,DDXT,DDXH,RS,SIGPHI,DL,RPMP,SPAF,XXTIP,PR,DF,
C C 6TT2,PT2,ALFA,FN,COMB,THRUST,WFL,AREAJ,PSUBA,TSUBA,TSUBJ,TSUBJO,
C C 7ALFAJ,ROTR,RP,FANS,RJ,E
C C
C C THE ARRAY FCF CONTAINS THE ONE-THIRD OCTAVE CENTER FREQUENCIES
C C
C C DATA FCF / 50.,63., 80., 100., 125., 160., 200., 250.,
C C 1315., 400., 500., 630., 800., 1000., 1250., 1600., 2000., 2500.,
C C 23150., 4000., 5000., 6300., 8000., 10000. /
C C
C C FC > 1.0 / 37400.0
C C
C C INITIALIZE DUMMY ARRAYS TEMP1 AND TEMP2. TEMP2 WILL
C C CONTAIN THE VEHICLE SPECTRUM.
C C
C C DO 10 I>1,24
C C TEMP1[I] > 0.
C C 10 TEMP2[I] > 0.
C C
C C IR > ROTR
C C IF [IR.NE.1] GO TO 30
C C CALL ROTOR[FCF,TEMP1,X,Y,Z,JI]
C C 20 FORMAT(//,'2L12E10.4//')
C C CALL ADDER[TEMP1,TEMP2]
C C 30 IRP > RP
C C IF [IRP.NE.1] GO TO 40
C C CALL PROP[X,Y,Z,FCF,TEMP1,JI]
C C CALL ADDER[TEMP1,TEMP2]
C C 40 IRF > FANS
C C IF [IRF.NE.1] GO TO 50
C C CALL FAN[TEMP1,FCF,X,Y,ZJ]
C C CALL ADDER[TEMP1,TEMP2]
C C 50 IRJ > RJ
C C IF [IRJ.NE.1] GO TO 60
C C CALL AJET[TEMP1,X,Y,Z,JI]

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ACPN0070
ACPN0080
ACPN0090
ACPN0100
ACPN0110
ACPN0120
ACPN0130
ACPN0140
ACPN0150
ACPN0160
ACPN0170
ACPN0180
ACPN0190
ACPN0200
ACPN0210
ACPN0220
ACPN0230
ACPN0240
ACPN0250
ACPN0260
ACPN0270
ACPN0280
ACPN0290
ACPN0300
ACPN0310
ACPN0320
ACPN0330
ACPN0340
ACPN0350
ACPN0360
ACPN0370
ACPN0380
ACPN0390
ACPN0400
ACPN0410
ACPN0420

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60 IE > E
CALL ADDER[TEMP1,TEMP2]
IF [IE.NE.1] GO TO 70
CALL ENGINE[TEMP1,X,Y,Z]
CALL ADDER[TEMP1,TEMP2]
70 CONTINUE

C VEHICLE SPECTRUM COMPLETE. BEGIN CONVERSION FROM SOUND PRESSURE TO
C SOUND PRESSURE LEVEL AND APPLY ATMOSPHERIC ABSORPTION CORRECTION
C
DO 80 I>1,24
F > FC[F[I]
TEMP2[I] > 10.0 * ALOG10[ TEMP2[I] < 0.1 ]
CALL ATTEN[F,RAD,FC,AM]
TEMP2[I] > TEMP2[I] - AM
80 CONTINUE

C CALCULATE DBA, PNL, AND PNLT
C
CALL PNL[TEMP2,DB,PN,PNT]
RETURN
END
SUBROUTINE ATTEN[F,R,FC,AM]
TITLE: SUBROUTINE ATTEN
C PURPOSE: TO CALCULATE ATMOSPHERIC ATTENUATION OF SOUND IN DB
C
C ABSTRACT: ATMOSPHERIC ABSORPTION IS CALCULATED FOR A GIVEN
C PROPAGATION DISTANCE FOR STANDARD CONDITIONS OF 14.7
C PSI BAROMETRIC PRESSURE, 59 DEGREES FARENHEIT, AND 50 PER-
C CENT RELATIVE HUMIDITY. THIS IS ADEQUATE FOR ALL BUT
C EXTREME CONDITIONS. THE EQUATIONS ARE FROM WORK DONE BY
C L.C. SUTHERLAND AT WYLE LABORATORIES (REFERENCE 1).
C
C USAGE:
C .....(F,R,FC,AM)
C F.....FREQUENCY FOR WHICH ATTENUATION IS CALCULATED (HZ)
C R.....PROPAGATION DISTANCE (FT)
C FC.....A CONSTANT BASED ON ATMOSPHERIC CONDITIONS (FOR
C STANDARD CONDITIONS FC = 1.0 / 37,400.
C AM.....ATMOSPHERIC ABSORPTION VALUE (DB) RETURNED
C
C LABELED
C COMMON: NONE
C
C SUBROUTINES CALLED: NONE
C
C REFERENCES: 1. SUTHERLAND,L.C., SONIC AND VIBRATION ENVIRONMENTS
C FOR GROUND FACILITIES - A DESIGN MANUAL, WYLE
C LABS RESEARCH STAFF REPORT WR68-2, MARCH 1968,
C FINAL REPORT FOR CONTRACT NAS8-11217
C

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ACPN0430
ACPN0440
ACPN0450
ACPN0460
ACPN0470
ACPN0480
ACPN0490
ACPN0500
ACPN0510
ACPN0520
ACPN0530
ACPN0540
ACPN0550
ACPN0560
ACPN0570
ACPN0580

ACPN0590
ACPN0600
ACPN0610
ATTE0010

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C SOUND LEVEL IS COMPUTED BY APPLYING THE A-WEIGHTING
C CORRECTION NUMBERS TO THE SPECTRUM AND THEN PERFORMING A
C BAND BY BAND ENERGY SUMMATION.
C
C USAGE:
C   ... (TEMP, DBA, PN, PNT)
C   TEMP...24 ELEMENT ARRAY CONTAINING THE NOISE SPECTRUM
C   DBA...A-WEIGHTED SOUND LEVEL RETURNED
C   PN...PERCEIVED NOISE LEVEL RETURNED
C   PNT...TONE CORRECTED PNL RETURNED
C
C LABELED
C COMMON: NONE
C
C SUBROUTINES CALLED: DELTA(X,MOP,SLOPE)
C
C REFERENCES: 1. R.A.PINKER, 'MATHEMATICAL FORMULATION OF THE
C   NOY TABLES', JL. SOUND VIB., VOL 8, NO 3, 1968,
C   PP. 488-493
C   2. W.C.SPERRY, 'AIRCRAFT NOISE EVALUATION', REPORT
C   FAA-NO-68-34, SEPTEMBER 1968
C
C DIMENSION TEMPL[24], AM1[24], S1[24], S2[24], DBACR[24]
C 1, SLOPE[25], SPLP[24], NFLAG[24], NFP[24]
C
C THE ARRAY DBACR CONTAINS CORRECTIONS TO BE APPLIED TO THE SPL IN
C BANDS 50 HZ TO 10000 HZ TO PROVIDE THE A-WEIGHTED SPECTRUM FROM
C WHICH THE A-WEIGHTED SOUND LEVEL IS CALCULATED. CORRECTION NUMBERS
C ARE FROM USA STANDARD S1.4-1961, ::SPECIFICATION FOR GENERAL PURPOSE
C SOUND LEVEL METERS::, DATED JAN 1, 1961
C
C   DATA DBACR/ -30.2, -26.1, -22.3, -19.1, -16.2, -13.2, -10.8,
C 1-8.6, -6.5, -4.8, -3.3, -1.9, -0.8, 0.0, 0.5, 1.0, 1.2, 1.2,
C 2 1.2, 1.0, 0.5, -0.2, -1.1, -2.3/
C
C ARRAYS AM1, S1, AND S2 ARE THE CONSTANTS REQUIRED IN THE
C MATHEMATICAL FORMULATION OF THE NOY TABLES.
C
C   DATA AM1/0.043478,0.04057,0.036831,0.036831,0.035336,0.033333,
C 1 0.033333,0.032051,0.030675,0.030675,0.030675,0.030675,0.030675,
C 2 0.030675,0.030675,0.042285,0.042285/
C   DATA S1/64.60,56.53,51.48,46.44,42.42,40.40,40.40,40.40,
C 1 0.0,0.0,0.0,0.0,0.0,0.0,0.0,0.0,0.0,0.0,0.0,0.0,0.0,0.0,0.0,
C   DATA S2/52.51,49.47,46.45,43.42,41.41,40.40,40.40,40.40,
C 1 38.34,32.30,29.29,29.30,31.34,35.35,
C   CON1>0.030103
C   CON2>0.029960
C
C BEGIN CALCULATION OF PNDB AND DBA
C THE TERM SUM WILL CONTAIN THE A-WEIGHTED SOUND LEVEL.
C
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PNL 0080
PNL 0090
PNL 0100
PNL 0110
PNL 0120
PNL 0130
PNL 0140
PNL 0150
PNL 0160
PNL 0170
PNL 0180
PNL 0190

PNL 0280
PNL 0290
PNL 0300
PNL 0310
PNL 0320
PNL 0330
PNL 0340
PNL 0350
PNL 0360
PNL 0370
PNL 0380
PNL 0390
PNL 0400

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TOT>0.
RMAX>0.
SUM>0.
DO 70 L>1,24
Y > 0.1 * [TEMP[L] < DBACRE[L]]
Y > 10.0 ** Y
SUM>SUM*Y
IF [L.GT.9] GO TO 50
10 AM2>CON1
IF [L.GT. 15] AM2 > CON2
AL > [AM1[L]*S1[L] - AM2*S2[L]]/[AM1[L]-AM2]
IF [TEMP[L].GE.S1[L]] GO TO 20
ANOY>0.0
GO TO 40
20 IF [TEMP[L].GT.AL] GO TO 30
ANOY > AM1[L] * [TEMP[L] - S1[L]]
ANOY>10.0**ANOY
GO TO 40
30 ANOY > AM2 * [TEMP[L] - S2[L]]
ANOY>10.0**ANOY
40 IF [ANOY .GT. RMAX] RMAX>ANOY
TOT>TOT<ANOY
GO TO 70
50 IF [L.GE.23] GO TO 10
IF [TEMP[L].GE.S2[L]] GO TO 60
ANOY>0.
GO TO 40
60 ANOY > AM2 * [TEMP[L] - S2[L]]
ANOY>10.0**ANOY
GO TO 40
70 CONTINUE
ANMAX>0.15*TOT<0.85*RMAX
IF [ANMAX.GT.0.] GO TO 80
PN>0.0
GO TO 90
80 PN>40.0<<[ALOG10[ANMAX]]/0.03
90 DBA > 10.0 * ALOG10[SUM]
C
C END CALCULATION OF PERCEIVED NOISE LEVEL AND DBA.
C
C BEGIN CALCULATION OF TONE CORRECTION
C
SLOPE[25] > 0.0
DO 100 I>1,24
SLOPE[I] > 0.0
SPLP[I] > 0.0
NFLAG[I] > 0
100 NFPC[I] > 0
C
C FAA-NO-68-34.....STEP 1
C

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PNL 0410 01551
PNL 0420 01552
PNL 0430 01553
PNL 0440 01554
PNL 0450 01555
PNL 0460 01556
PNL 0470 01557
PNL 0480 01558
PNL 0490 01559
PNL 0500 01560
PNL 0510 01561
PNL 0520 01562
PNL 0530 01563
PNL 0540 01564
PNL 0550 01565
PNL 0560 01566
PNL 0570 01567
PNL 0580 01568
PNL 0590 01569
PNL 0600 01570
PNL 0610 01571
PNL 0620 01572
PNL 0630 01573
PNL 0640 01574
PNL 0650 01575
PNL 0660 01576
PNL 0670 01577
PNL 0680 01578
PNL 0690 01579
PNL 0700 01580
PNL 0710 01581
PNL 0720 01582
PNL 0730 01583
PNL 0740 01584
PNL 0750 01585
PNL 0760 01586
PNL 0770 01587
PNL 0780 01588
PNL 0790 01589
PNL 0800 01590
PNL 0810 01591
PNL 0820 01592
PNL 0830 01593
PNL 0840 01594
PNL 0850 01595
PNL 0860 01596
PNL 0870 01597
PNL 0880 01598
PNL 0890 01599
PNL 0900 01600

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C          CALL DELTAE TEMP, 1, SLOPEJ
C          C FAA-NO-68-34.....STEP 2
C          DO 120 I>4,24
C          IF [ABS[SLOPE[IJ]-SLOPE[I-1JJ]-5.0]120,120,110
C          110 NFLAG[IJ] > I
C          120 CONTINUE
C          C FLAG BANDS
C          C FAA-NO-68-34.....STEP 3
C          DO 170 I>4,24
C          NF > NFLAG[IJ]
C          IF [SLOPE[NF]]140,140,130
C          130 IF [SLOPE[NF]-SLOPE[NF-1JJ]170,170,160
C          140 IF [SLOPE[NF-1JJ]170,170,150
C          150 NFPL[I-1J] > I-1
C          GO TO 170
C          160 NFPL[IJ] > I
C          170 CONTINUE
C          C ADJUST SPECTRUM USING SPERRY:S FAA METHOD
C          C FAA-NO-68-34.....STEP 4
C          DO 200 I>3,24
C          IF [I.EQ.NFPL[IJ]] GO TO 180
C          SPLP[IJ] > TEMP[IJ]
C          GO TO 190
C          180 SPLP[IJ] > 0.5 * [TEMP[I-1J] < TEMP[I<1JJ]
C          190 IFI NFPL[IJ].EQ. 24 J SPLP[24J] > TEMP[23J] < SLOPE[24J]
C          200 CONTINUE
C          C FAA-NO-68-34.....STEP 5
C          CALL DELTAE SPLP, 2, SLOPE J
C          C CALC AVG SLOPE
C          C FAA-NO-68-34.....STEP 6
C          DO 210 I>3,23
C          210 SLOPE[IJ] > 0.33333 * [SLOPE[IJ] < SLOPE[I<1J] < SLOPE[I<2J] J
C          C FAA-NO-68-34.....STEP 7
C          SPLP[3J] > TEMP[3J]

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PNL 0910
PNL 0920
PNL 0930
PNL 0940
PNL 0950
PNL 0960
PNL 0970
PNL 0980
PNL 0990
PNL 1000
PNL 1010
PNL 1020
PNL 1030
PNL 1040
PNL 1050
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PNL 1070
PNL 1080
PNL 1090
PNL 1100
PNL 1110
PNL 1120
PNL 1130
PNL 1140
PNL 1150
PNL 1160
PNL 1170
PNL 1180
PNL 1190
PNL 1200
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PNL 1370
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PNL 1400

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DO 220 I>4,24
220 SPLP[I] > SPLP[I-1] < SLOPE[I-1]
C CALC FINAL DIFFERENCES
C
C FAA-NO-68-34.....STEP 8
DO 230 I>3,24
230 SPLP[I] > TEMP[I] - SPLP[I]
C
C FAA-NO-68-34.....STEP 9 AND 10
C
C MAX > 0.0
NCMAX > 0
DO 320 M>4,24
IF [M.GE.11.AND.M.LE.21] GO TO 270
IF [SPLP[M]-3.0]320,250,240
240 IF [SPLP[M]-20.0]250,260,260
250 CMAX1 > SPLP[M]/6.0
IF [CMAX-CMAX1]310,320,320
260 CMAX1 > 3.3333
IF [CMAX-CMAX1]310,320,320
270 IF [SPLP[M]-3.0]320,290,280
280 IF [SPLP[M]-20.0]290,300,300
290 CMAX1 > SPLP[M]/3.0
IF [CMAX-CMAX1]310,320,320
300 CMAX1 > 6.66667
IF [CMAX-CMAX1]310,320,320
310 CMAX > CMAX1
NCMAX > M
320 CONTINUE
C CALCULATE PNL
C
PNT > PN < CMAX
RETURN
END
SUBROUTINE DELTACX, MOP, SLOPE]
C TITLE: DELTA
C
C PURPOSE: TO CALCULATE THE SLOPES REQUIRED IN THE CALCULATION
C OF THE TONE CORRECTION IN SUBROUTINE PNL
C
C ABSTRACT: THE SLOPE, OR CHANGE IN LEVEL FROM THIRD OCTAVE BAND 'I'
C TO BAND 'I+1' IS CALCULATED FOR THE ENTIRE 24 BAND
C SPECTRUM. IF THE VALUE OF 'MOP' IS NOT 1 THE SLOPE FOR
C BAND 3 AND FOR IMAGINARY BAND 25 IS CALCULATED.
C
C USAGE: .....(X,MOP,SLOPE)

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PNL 1410 01651
PNL 1420 01652
PNL 1430 01653
PNL 1440 01654
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PNL 1500 01660
PNL 1510 01661
PNL 1520 01662
PNL 1530 01663
PNL 1540 01664
PNL 1550 01665
PNL 1560 01666
PNL 1570 01667
PNL 1580 01668
PNL 1590 01669
PNL 1600 01670
PNL 1610 01671
PNL 1620 01672
PNL 1630 01673
PNL 1640 01674
PNL 1650 01675
PNL 1660 01676
PNL 1670 01677
PNL 1680 01678
PNL 1690 01679
PNL 1700 01680
PNL 1710 01681
PNL 1720 01682
PNL 1730 01683
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PNL 1760 01686
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C C C X.....A 24 ELEMENT ARRAY CONTAINING THE THIRD OCTAVE
C C C SPECTRUM
C C C MOP.....CONTROL VARIABLE TO PREVENT CALCULATION OF EXTENDED
C C C SLOPES (BANDS 3 AND 25). NO = 1
C C C SLOPE..A 25 ELEMENT ARRAY CONTAINING THE CALCULATED SLOPES
C C C
C C C LABELED
C C C COMMON..NONE
C C C SUBROUTINES CALLED: NONE
C C C
C C C DIMENSION XC(24), SLOPEC(25)
C C C DO 10 I>4,24
C C C 10 SLOPEC[I] > XC[I] - XC[I-1]
C C C IF1 MOP .EG. 1)RETURN
C C C SLOPEC[3] > SLOPEC[4]
C C C SLOPEC[25] > SLOPEC[24]
C C C RETURN
C C C END
C C C SUBROUTINE PROP(X,Y,Z,FCK3,POBL3,JKI)
C C C
C C C TITLE: PROP
C C C PURPOSE: TO CALCULATE THE 1/3-OCTAVE BAND NOISE SPECTRUM OF A
C C C PROPELLER(S) AT A SPECIFIED POINT.
C C C
C C C ABSTRACT: USING EMPIRICAL MEANS THE FIRST 10 HARMONICS OF ROTATIONAL
C C C NOISE ARE CALCULATED AND CONVERTED TO A THIRD OCTAVE
C C C SPECTRUM. VORTEX NOISE IS CALCULATED FROM HUBBARD'S (REF
C C C 2) THEORETICAL EQUATION, CONVERTED TO A THIRD OCTAVE
C C C SPECTRUM USING THE REFERENCE 3 SPECTRUM SHAPE, AND ADDED
C C C TO THE ROTATIONAL SPECTRUM TO PRODUCE A COMPLETE SPECTRUM.
C C C REQUIRED PARAMETERS (INPUT VIA COMMON):
C C C PPWR...POWER INPUT TO PROPELLER (HP)
C C C DIA ....DIAMETER (FT)
C C C BIGB...NUMBER OF BLADES
C C C RPM...ROTATIONAL SPEED (RPM)
C C C ANMPRP...NUMBER OF PROPELLERS
C C C CHORDP...MEAN BLADE CHORD (FT)
C C C VF(1)...FLIGHT SPEED ON FLIGHT SEGMENT I (FPS)
C C C USAGE:
C C C X .....(X,Y,Z,FCK3,POBL3,JKI)
C C C Y.....FIELD POINT COORDINATES (INPUT)
C C C Z
C C C FCK3...A 24 ELEMENT ARRAY CONTAINING THE 1/3-OCTAVE
C C C BAND CENTER FREQUENCIES (INPUT)
C C C JKI...FLIGHT PATH SEGMENT NUMBER
C C C POBL3..A 24 ELEMENT ARRAY IN WHICH THE CALCULATED SPECTRUM
C C C IS RETURNED

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DELT0020
DELT0030
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PROP0010
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C L A B E L E D
C C O M M O N : / B 1 /   / I N P U T /
C C
C S U B R O U T I N E S C A L L E D : N O N E
C C
C R E F E R E N C E : 1. H A M I L T O N S T A N D A R D , ' ' A S T U D Y O F P R O P E L L E R N O I S E
C C R E S E A R C H ' ' , H A M I L T O N S T A N D A R D S P - 6 7 1 4 8 R E V A , 1 9 6 7
C C
C 2. H . H . H U B B A R D , ' ' P R O P E L L E R - N O I S E C H A R T S F O R T R A N S P O R T
C C A I R P L A N E S ' ' , N A C A T N - 2 9 6 8 , J U N E 1 9 5 3
C C
C 3. L . L . B E R A N E K ( E D ) ,   N O I S E R E D U C T I O N , M C G R A W - H I L L B O O K
C C C O . , N E W Y O R K , N Y , C H A P T E R 2 5
C C -----
C C
C D I M E N S I O N F C K 3 C 2 4 J , P O B L 3 C 2 4 J , V C O R R I 4 1 J , C O R R C 1 0 , 1 1 J , F L W R C 2 5 J
C 1 , B E S I 4 0 0 J
C C O M M O N / B 1 / B E S , I N C M A X I 5 0 J
C C O M M O N / I N P U T / S A Z , S E G , F L T Y P E , R C A S E , R E T A , R B I G B , R B I G R , P R O M E G N , R S I D ,
C 1 R C H O R D , R T H R U S , R T O R G , R B E T A , T C A S E , T E T A , T B I G B , T B I G R , T O M E G N , T S I D ,
C 2 T C H O R D , T T H R U S , T T O R G , T B E T A , P P W R , D I A , B I G B , R P M P , A N M P R P , C H O R D P ,
C 3 P A T H 5 0 J , Y M A X I 5 0 J , Y M A X C 5 0 J , P H M A X I 5 0 J , R A D I U S I 5 0 J , V F I 5 0 J , A L F C 5 0 J ,
C 4 X P R Z R O , Y P R Z R O , T H M A X O , A Z E R O , T I N C , A N M F P T , H P E N G , S L E V E L , A N E N G , D I A T ,
C 5 D I A H , B , B P R , C H O R D , D O D X T , D D D X H , R S , S I G P H I , D L , R P M , S P A F , X M X T I P , P R , D F ,
C 6 T T 2 , P T 2 , A L F A , F N , C O M B , T H R U S T , W T F L , A R E A J , P S U B A , T S U B A , T S U B J , T S U B J O ,
C 7 A L F A J , R O T R , R P , F A N S , R J , E
C C
C A R R A Y C O R R ( I , J ) C O N T A I N S C O R R E C T I O N N U M B E R S T O C A L C U L A T E 1 0 ( J = 1 , 1 0 )
C C R O T A T I O N A L H A R M O N I C S F O R 1 1 ( I = 1 , 1 1 ) T I P M A C H N U M B E R S F R O M T H E
C C C A L C U L A T E D O V E R A L L L E V E L .   I R E P R E S E N T S M A C H N U M B E R S F R O M 0 . 4 0 T O
C C 0 . 9 0 I N S T E P S O F 0 . 0 5
C C
C D A T A C O R R /
C 1 0 . 6 , 1 4 . 0 , 1 8 . 0 , 1 9 . 8 , 2 1 . 8 , 2 3 . 1 , 2 4 . 0 , 2 5 . 2 , 2 6 . 9 , 2 8 . 8 ,
C 1 0 . 6 , 1 3 . 7 , 1 7 . 6 , 1 9 . 7 , 2 1 . 7 , 2 3 . 0 , 2 3 . 9 , 2 5 . 1 , 2 6 . 8 , 2 8 . 7 ,
C 1 0 . 6 , 1 3 . 0 , 1 7 . 2 , 1 9 . 5 , 2 1 . 5 , 2 3 . 0 , 2 3 . 9 , 2 5 . 0 , 2 6 . 8 , 2 8 . 7 ,
C 1 0 . 6 , 1 2 . 0 , 1 6 . 7 , 1 9 . 3 , 2 1 . 3 , 2 2 . 8 , 2 3 . 7 , 2 5 . 0 , 2 6 . 6 , 2 8 . 6 ,
C 1 0 . 7 , 1 1 . 0 , 1 6 . 2 , 1 9 . 0 , 2 1 . 0 , 2 2 . 6 , 2 3 . 5 , 2 4 . 8 , 2 6 . 5 , 2 8 . 5 ,
C 1 0 . 9 , 9 . 7 , 1 5 . 5 , 1 8 . 6 , 2 0 . 6 , 2 2 . 4 , 2 3 . 4 , 2 4 . 6 , 2 6 . 2 , 2 8 . 2 ,
C 1 1 . 1 , 8 . 4 , 1 4 . 6 , 1 8 . 2 , 2 0 . 1 , 2 2 . 0 , 2 3 . 0 , 2 4 . 2 , 2 5 . 8 , 2 7 . 8 ,
C 1 1 . 6 , 7 . 1 , 1 3 . 7 , 1 7 . 6 , 1 9 . 5 , 2 1 . 4 , 2 2 . 4 , 2 3 . 7 , 2 5 . 3 , 2 7 . 2 ,
C C

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PROP0060
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PROP0080
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PROP0100
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PROP0180
PROP0190
PROP0210
PROP0220
PROP0240
PROP0250
PROP0270
PROP0280
PROP0300
PROP0310
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PROP0370
PROP0390
PROP0400

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C      1 2.6, 6.2, 12.4, 16.6, 18.6, 20.3, 21.5, 23.0, 24.4, 26.2 ,
C      1 3.9, 5.8, 10.5, 15.0, 17.0, 18.5, 20.0, 21.5, 24.4, 26.2 ,
C      1 5.5, 5.9, 8.0, 10.5, 12.5, 14.5,16.5, 18.0, 19.5, 21.4 /
C
C ARRAY VCORR(I) CONTAINS CORRECTIONS TO CALCULATE THE 1/3-OCTAVE
C SPECTRUM FROM THE COMPUTED OVERALL VORTEX NOISE LEVEL
C
DATA VCORR
134.,31.,28.,25.,22.,19.,16.,14.,12.,10.,11.,12.,13.,15.,17.,19.,
221.,23.,25.,27.,29.,31.,33.,35.,37.,39.,41.,43.,45.,47.,49. /
/64.,61.,58.,55.,52.,49.,46.,43.,40.,37.,
C
C ARRAY FLWR(I) CONTAINS LOWER CUTOFF FREQUENCIES FOR THE 1/3-OCTAVE
C BANDS FROM 50 HZ TO 12,500 HZ
C
DATA FLWR
1280.,354.,445.,561.,707.,891.,1122.,1414.,1782.,2242.,2828.,3565.,
24488.,5656.,7127.,8980.,11312. /
VF > VF1(JK1)
C
C SET CONSTANTS
C
TWO16 > 2.0 ** [1.0/6.0]
DTR > 0.0174532925
ROOT2 > SQRT(2.0)
PI > 3.1415926536
C
C INITIALIZE PUBL3 ARRAY AND CALCULATE TERMS FOR OASPL EQUATION
C
DO 10 I>1,24
10 PUBL3(I) > 0.
PRLG > 15.5 * ALOG10[PPWR]
DLG > 20.0 * ALOG10[DLA]
BLG > 20.0 * ALOG10[BLGB]
ENGLG > 10.0 * ALOG10[ANNPRP]
TMACH > [RPM] * PI * DIAJ / [ SAZ * 60.0 ]
R > SORTC X*X < Y*Y < Z*Z ]
RLG > 20.0 * ALOG10[R/500.]
C
C CALCULATE AZIMUTH ANGLE GAMMA
C
IF [X<Y]40,20,40
20 IF [Z<Y]200,30
30 GAMMA > 90.
GO TO 50
40 GAMMA > ABS(ATAN2(Y,-X))

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PROP0420
PROP0430
PROP0450
PROP0460
PROP0480
PROP0490
PROP0500
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PROP0570
PROP0600
PROP0610
PROP0620
PROP0625
PROP0630
PROP0640
PROP0650
PROP0660
PROP0670
PROP0680
PROP0690
PROP0700
PROP0710
PROP0720
PROP0730
PROP0740
PROP0750
PROP0760
PROP0770
PROP0780
PROP0790
PROP0800
PROP0810
PROP0820
PROP0830
PROP0840
PROP0850
PROP0860
PROP0870

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GAMMA > GAMMA / DTR
50 CONTINUE
C
C CALCULATE DIRECTIVITY ANGLE PHI AND DIRECTIVITY INDEX
C
  PHI > ABS[180.0 - GAMMA]
  IF [PHI.LE.50.0] GO TO 60
  IF [PHI.LE.120.0] GO TO 70
  IF [PHI.LE.180.0] GO TO 80
  PHI > 180.
  GO TO 80
60 DI > 0.120 * PHI - 7.0
  GO TO 90
70 DI > 0.0286 * PHI - 2.43
  GO TO 90
80 DI > -0.308 * PHI + 38.0
90 CONTINUE
C
C CALCULATE OASPL AT R AND GAMMA
C
  OASPL > PRLG - DLG - BLG < [40. * TMACH] < ENGLG - RLG < DI < 50.2
  GO TO 100
C
C CALCULATE FUNDAMENTAL ROTATIONAL FREQUENCY
C
  VT2 > [TMACH * SAZ]**2
  VH > SORT[VT2 < VF*VF]
  FZRO > VH * BIGB / [PI * DIA]
  RMH > VH / SAZ
C
C DETERMINE WHICH SET OF CORRECTION NUMBERS TO USE
C BASED ON HELICAL TIP MACH NUMBER
C
  INC > 20.0 * RMH - 6.500001
  IF[INC .LT. 1] INC > 1
  IF[INC .GT. 11] INC > 11
C
C BEGIN CALCULATION OF 1/3-OCTAVE BAND LEVELS FOR ROTATIONAL NOISE
C
C DETERMINE WHICH 1/3-OCTAVE VCF FALLS IN
C
  DO 120 I>1,10
  SPL > OASPL - CORR[I,INC]
  F > FZRO * I
  DO 110 K>1,24
  FL > FLWRK[K]
  FL > FLWRK[J]
  100 IF [F.GT.FU] GO TO 110
  IF [F.LI.FL] GO TO 120
  POBL3[K] > POBL3[K] < 10.0 ** [0.1 * SPL]
  110 CONTINUE

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PROP0880 01851
PROP0890 01852
PROP0900 01853
PROP0910 01854
PROP0920 01855
PROP0930 01856
PROP0940 01857
PROP0950 01858
PROP0960 01859
PROP0970 01860
PROP0980 01861
PROP0990 01862
PROP1000 01863
PROP1010 01864
PROP1020 01865
PROP1030 01866
PROP1040 01867
PROP1050 01868
PROP1060 01869
PROP1070 01870
PROP1080 01871
PROP1090 01872
PROP1100 01873
PROP1110 01874
PROP1120 01875
PROP1130 01876
PROP1140 01877
PROP1150 01878
PROP1160 01879
PROP1170 01880
PROP1180 01881
PROP1190 01882
PROP1200 01883
PROP1210 01884
PROP1220 01885
PROP1230 01886
PROP1240 01887
PROP1250 01888
PROP1260 01889
PROP1270 01890
PROP1280 01891
PROP1290 01892
PROP1300 01893
PROP1310 01894
PROP1320 01895
PROP1330 01896
PROP1340 01897
PROP1350 01898
PROP1360 01899
PROP1370 01900

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120 CONTINUE
C
C CALCULATE VORTEX AND TOTAL NOISE
C
VCF > 0.85 * VH / CHORDP
IF [VCF.GT.FLWRK1] GO TO 130
INC > 1
GO TO 150
130 CONTINUE
DO 140 K>1,24
IF [VCF.GT.FLWRK<1] GO TO 140
IF [VCF.LT.FLWRK<1] GO TO 150
INC > K
GO TO 150
140 CONTINUE
150 CONTINUE
ABL > BIGB * [DIA / 2. J * CHORDP
VOASPL > 10. * ALOG10[3.8E-11 * ABL *[[0.7 * VH]**6]] - RLG
INCR > 20 - INC
DO 160 K>1,24
INCR > INCR < K
IF[INCR .LT. 1] INCR > 1
IF[INCR .GT. 41] INCR>41
ELG > VCORR< INCR J
SPLV > VOASPL - ELG
SPLV > 10.0 ** [ 0.1 * SPLV J
POBL3[K] > POBL3[K] < SPLV
POBL3[K] > 10.0 * ALOG10< POBL3[K] J
160 CONTINUE
C
C CORRECT SPECTRUM TO ASSURE NO MORE THAN 20 DB DIFFERENCE BETWEEN
C ADJACENT BANDS
C
DO 190 I>1,23
DUM > POBL3[I<1] - 20.
IF [POBL3[I].LT.DUM] GO TO 170
DUM3 > POBL3[I<1] < 20.
IF [POBL3[I].GT.DUM3] GO TO 180
GO TO 190
170 POBL3[I] > DUM
IF [I.EQ.1] GO TO 190
DUM2 > POBL3[I-1] < 20
IF [POBL3[I].LT.DUM2] GO TO 190
POBL3[I-1] > POBL3[I] - 20.
GO TO 190
180 POBL3[I<1] > POBL3[I] - 20.
190 CONTINUE
200 CONTINUE
RETURN
END

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PROP1380
PROP1390
PROP1400
PROP1410
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PROP1440
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PROP1470
PROP1480
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PROP1590
PROP1600
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PROP1670
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PROP1820
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SUBROUTINE FAN(BBN,FC,X,Y,Z) FAN 0010
 TITLE: FAN FAN 0020
 PURPOSE: TO CALCULATE THE NOISE RADIATED BY LIFT AND CRUISE FANS
 ABSTRACT: THE DISCRETE FREQUENCY (BLADE PASSAGE) NOISE, BROADBAND NOISE, AND COMBINATION TONE NOISE ARE CALCULATED AND CONVERTED TO A 1/3-OCTAVE BAND SPECTRUM USING THE METHODS OF REFERENCE 1. THE METHOD CANNOT CALCULATE INTERACTION TONE NOISE BECAUSE IT WAS DERIVED FROM NOISE DATA OF ENGINES THAT HAVE NO PROPAGATING INTERACTION TONES. REQUIRED PARAMETERS (INPUT VIA COMMON):
 DIAT...TIP DIAMETER (INCHES)
 DIAH...HUB DIAMETER (INCHES)
 B...NUMBER OF BLADES
 BPR...BY-PASS RATIO
 CHORD...BLADE TIP CHORD (INCHES)
 * DDDXT...TIP DIAMETER GRADIENT (IN/IN)
 * DDDXH...HUB DIAMETER GRADIENT (IN/IN)
 * RS...BLADE SUCTION SURFACE RADIUS OF CURVATURE (IN)
 * SIGPHI...STANDARD DEVIATION OF BLADE TIP METAL ANGLE (RAD)
 DL...INLET DUCT LENGTH (FT)
 RPM...ROTATIONAL SPEED (RPM)
 SPAF...SPECIFIC AIRFLOW RATE (LB/SEC/50 FT)
 XMX TIP...TIP AXIAL MACH NUMBER
 PR...PRESSURE RATIO
 DF...DIFFUSION FACTOR
 TT2...AMBIENT INLET TEMPERATURE (DEGREES F)
 PT2...AMBIENT INLET PRESSURE (INCHES HG)
 ALFA...INCLINATION OF INLET TO HORIZONTAL (+90 DEG IS VERTICAL).
 FN...NUMBER OF FANS
 COMB...CONTROL FACTOR TO EXCLUDE CALCULATION OF COMBINATION TONE NOISE (0=NO)

* - THESE VALUES REQUIRED ONLY IN THE CALCULATION OF COMBINATION TONE NOISE.

USAGE: ... (BBN,FC,X,Y,Z)
 BBN...A 24 ELEMENT ARRAY IN WHICH THE CALCULATED FAN 1/3-OCTAVE BAND SPECTRUM IS RETURNED
 FC...A 24 ELEMENT ARRAY CONTAINING THE 1/3 OCTAVE BAND CENTER FREQUENCIES FROM 50 TO 10,000 HZ.
 X
 Y.....COORDINATES OF THE OBSERVER RELATIVE TO THE VEHICLE
 Z

LABELED COMMON: /B1/ /INPUT/

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 01995
 01996
 01997
 01998
 01999
 02000

C SUBROUTINE CALLED: NONE
 C
 C REFERENCE 1: E.A.BURDSALL AND R.H.URBAN, 'FAN-COMPRESSOR NOISE:
 PREDICTION, RESEARCH, AND REDUCTION STUDIES', FAA
 REPORT FAA-RD-71-73, FEBRUARY 1971
 C
 C
 C DIMENSION BBMC[24],FCL[24],FLL[25],TABLE[15,15],SUBDC[15],SUPDC[15],
 1CORFL[3],FCORR[3],PWL[500],DIRC[11,6],ZETAK[6]
 2,BESL[400]
 EQUIVALENCE (TABLE[15],XTAB)
 DIMENSION XTAB[75]
 C
 COMMON /BI/ BES,INCMAX[50]
 COMMON /INPUT/ SAZ,SEG,FLTYPE,RCASE,RETA,RBIGB,RBIGR,ROMEGN,RSID,
 1RCHORD,RTHRUS,RTORG,RBETA,TCASE,TETA,TBIGB,TBGR,TOMEGN,TSID,
 2TCHORD,TTHRUS,TTORG,TBETA,PPWR,DIA,BIGB,RPMP,ANMPRP,CHORDP,
 3PATH[50],XMAX[50],YMAX[50],PHMAX[50],RADIUS[50],VF[50],ALF[50],
 4XPRZRO,YPRZRO,THMAXO,AZERO,TINC,ANMFFT,MPENG,SLEVEL,ANENG,DIAT,
 5DIAH,B,BPR,CHORD,DDDXI,DDDXH,RS,SIGPHI,DL,RPM,SPAF,AMXTIP,PR,DF,
 6TT2,PT2,ALFA,FN,COMB,THRUST,WTFL,AREAJ,PSUBA,TSUBA,TSUBJ,TSUBJO,
 7ALFAJ,ROTR,RP,FANS,RJ,E
 C
 C ARRAY FL CONTAINS LOWER AND UPPER CUTOFF FREQUENCIES FOR THE THIRD
 C OCTAVES FROM 50 TO 10,000 HZ.
 C
 C DATA FL / 44.4, 55.8, 70.5, 88.9, 111.5, 140.0, 177.0,
 1221.0, 280., 354., 445., 561., 707., 891., 1122., 1414., 1782.,
 22242., 2828., 3565., 4488., 5656., 7127., 8980., 11312. /
 C
 C ARRAY SUBD CONTAINS THE SUBSONIC DIRECTIVITY INDICIES
 C
 C DATA SUBD / -0.5, 0.9, 1.4, 0.7, 1.0, 0.0, -0.6, -2.5,
 1-3.7, -0.9, 1.7, 2.5, 2.2, -1.0, -2.2 /
 C
 C ARRAY SUPD CONTAINS THE SUPERSONIC DIRECTIVITY INDICIES
 C
 C DATA SUPD / -0.6, -0.5, -0.4, -0.3, -0.2, 0.0, 0.2,
 10.3, 0.7, 4.0, 4.7, 4.9, 4.8, 2.5, 1.4 /
 C
 C ARRAY TABLE CONTAINS THE BROADBAND OVERALL SPL AT AN AZIMUTH ANGLE
 C OF 60 DEGREES FROM THE INLET AS A FUNCTION OF TIP MACH NUMBER AND
 C DIFFUSION FACTOR. TABLE(I,J) J=1,15 REPRESENTING DIFFUSION FACTORS
 FROM 0.28 TO 0.56 IN STEPS OF 0.02
 I=1,15 REPRESENTING MACH NUMBERS FROM
 0.7 TO 1.40 IN STEPS OF 0.05
 C
 C DATA TABLE / 87.2, 87.4, 87.6, 88.1, 88.9, 89.7,
 190.9, 92.0, 92.8, 93.4, 93.6, 93.7, 94.1, 94.4, 94.7,

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FAN 0070
 FAN 0080
 FAN 0090

 FAN 0100
 FAN 0110
 FAN 0120
 FAN 0130
 FAN 0140
 FAN 0150
 FAN 0160
 FAN 0170
 FAN 0180
 FAN 0190

 FAN 0200
 FAN 0210
 FAN 0220
 FAN 0230

 FAN 0240
 FAN 0250
 FAN 0260

 FAN 0270
 FAN 0280
 FAN 0290

 FAN 0300
 FAN 0310

C	*	193.1, 94.0, 94.6, 95.1, 95.4, 95.8, 96.0, 96.2 ,	2*88.4, 88.7, 89.2, 89.9, 90.8, 92.0,	FAN 0320	02051
C	*	193.8, 94.8, 95.8, 96.5, 97.0, 97.3, 97.4, 97.5, 97.6 ,	89.5, 89.6, 89.9, 90.5, 91.4, 92.7,	FAN 0330	02052
C	*	195.3, 96.4, 97.2, 98.2, 98.4, 98.7, 2*98.9 ,	2*90.6, 90.8, 91.3, 92.0, 92.9, 94.1,	FAN 0340	02053
C	*	195.0, 96.4, 97.7, 98.7, 99.4, 99.9, 100.1, 100.3, 100.4 ,	91.6, 91.7, 91.8, 92.2, 92.8, 93.8,	FAN 0350	02054
C	*	195.9, 97.2, 98.4, 99.4, 100.2, 100.8, 101.1, 101.4, 101.5 ,	92.6, 92.8, 93.0, 93.3, 93.9, 94.8,	FAN 0360	02055
C	*	198., 99.2, 100.2, 101., 101.7, 102.1, 102.4, 102.6 ,	93.7, 93.9, 94.1, 94.5, 95., 95.7, 96.8,	FAN 0370	02056
C	*	197.8, 98.9, 100.1, 101., 101.8, 102.4, 102.8, 103.3, 103.7 ,	94.8, 95.1, 95.3, 95.6, 96.1, 96.8,	FAN 0380	02057
C	*	199.9, 101., 101.9, 102.7, 103.3, 103.8, 104.4, 104.7 ,	96., 96.2, 96.4, 96.8, 97.2, 97.8, 98.7,	FAN 0390	02058
C	*	1100.5, 101.7, 102.7, 103.4, 104., 104.5, 105., 105.3 /	96.9, 97., 97.3, 97.7, 98.1, 98.7, 99.5,	FAN 0400	02059
C		DATA XTAB /		FAN 0410	02060
C	*	1100.2, 101.3, 102.4, 103.4, 104.1, 104.7, 105.2, 105.6, 106. ,	97.9, 98.1, 98.3, 98.6, 98.9, 99.5,	FAN 0420	02061
C	*	1101.9, 103., 103.9, 104.5, 105.1, 105.6, 105.9, 106.2 ,	2*98.7, 99., 99.2, 99.6, 100., 100.8,	FAN 0430	02062
C	*	1102.5, 103.5, 104.4, 105., 105.5, 105.9, 106.2, 106.4 ,	2*99.5, 99.6, 99.7, 100., 100.5, 101.4,	FAN 0440	02063
C	*	1103., 103.8, 104.7, 105.3, 105.7, 106.1, 106.4, 106.6 ,	2*100.1, 100.2, 100.3, 100.6, 101.2, 102.,	FAN 0450	02064
C	*	1102.5, 103.3, 104.2, 105., 105.2, 105.9, 106.3, 106.5, 106.7 /	2*100.7, 100.8, 100.9, 101.3, 101.8,	FAN 0460	02065
C		ARRAY CORF CONTAINS CORRECTION FACTORS TO CALCULATE THE SECOND		FAN 0470	02066
C		HARMONIC OF FORWARD RADIATED DISCRETE FREQUENCY NOISE FROM THE FIRST		FAN 0480	02067
C		HARMONIC.		FAN 0490	02068
C		DATA CORF / 3.3, 7.5, 6.8 /		FAN 0500	02069
				FAN 0510	02070
				FAN 0520	02071
				FAN 0530	02072
				FAN 0540	02073
				FAN 0550	02074
				FAN 0560	02075
				FAN 0570	02076
				FAN 0580	02077
				FAN 0590	02078
				FAN 0600	02079
				FAN 0610	02080
				FAN 0620	02081
				FAN 0630	02082
				FAN 0640	02083
				FAN 0650	02084
				FAN 0660	02085
				FAN 0670	02086
				FAN 0680	02087
				FAN 0690	02088
				FAN 0700	02089
				FAN 0710	02090
				FAN 0720	02091
				FAN 0730	02092
				FAN 0740	02093
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					02100
				FAN 0750	
				FAN 0760	

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C ARRAY FCORR CONTAINS CORRECTION FACTORS TO CALCULATE THE SECOND
C HARMONIC OF AFT RADIATED DISCRETE FREQUENCY NOISE FROM THE FIRST
C HARMONIC
C
C DATA FCORR / 3.2, 3.5, 2.5 /
C
C THE ARRAY DIRC CONTAINS THE CORRECTION NUMBERS USED IN COMPUTING THE
C SPL OF THE COMBINATION TONES FROM THE PWL
C
DATA DIRC /
1 -475.92 , -488.88 , -491.57 , -14.22 , 419.53 , 12.96
2 181.25 , 1618.24 , 4033.55 , 6613.32
3 1088.41 , 1164.19 , 1202.70 , 7.71 , -1046.58 , -43.78
4 635.16 , -411.47 , -3933.70 , -9869.94 , -16167.2
5 -832.01 , -929.26 , -987.87 , 2.85 , 867.72 , 53.02
6 -432.44 , 295.32 , 3133.88 , 7937.61 , 12994.70
7 207.78 , 244.73 , 269.86 , 0. , -238.17 , -20.72
8 105.71 , -67.81 , -821.89 , -2104.66 , -3443.76
9 16*0.
10 -48.7 , 4*0.
11 6*0.
12 26.11 , 4*0.
13
C
C PI > 3.1415927
C RAD > 57.295780
C XPR > X * COS( ALFA J - Z * SIN( ALFA J
C ZPR > Z * COS( ALFA J < X * SIN( ALFA J
C CONST > 10.0 * ALOG10( FN J
C FFR > SORT(X < Y * Y < Z * Z)
C
C CALCULATE GAMMA - DIRECTIVITY ANGLE - AND INTERVAL IN WHICH IT FALLS
C
IF [XPR<Y]30,10,30
10 IF [ZPR]20,500,20
20 GAMMA > 90.
GO TO 40
30 GAMMA > ABS( ATAN2( Y,XPR JJ
40 CONTINUE
INC > GAMMA / 10.0 < 0.50001
IFE INC .LT. 1 J INC > 1
IFE INC .GT. 15 J INC > 15
50 CONTINUE
C
C CALCULATE PROGRAM PARAMETERS
C
THETA1 > [TT2 < 459.688] / 518.688
THETA1 > SQRT(THETA1]
DELTA > PT2/29.92

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FAN 0770
FAN 0780

FAN 0930
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FAN 0980
FAN 0990
FAN 1000
FAN 1010
FAN 1020
FAN 1030
FAN 1040
FAN 1050
FAN 1060
FAN 1070
FAN 1080
FAN 1090
FAN 1100
FAN 1110
FAN 1120
FAN 1130
FAN 1140
FAN 1150

FAN 1170
FAN 1180
FAN 1190

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RPMC > RPM / THETA1
SPAFC > SPAF * THETA1 / DELTA
XMXAVE > 1.0 - SORTC 0.9708126 - 0.0196508 * SPAFC J
IFIXMTIP .LE. 0. JXMTIP > XMXAVE
AREA > PI * DIAT ** 2 / 4.
TAU > PI * DIAT / B
E1 > RPM / 60.0
BPF > B * E1

C DETERMINE THE 1/3-OCTAVE BANDS IN WHICH THE BLADE PASSAGE TONE AND
C ITS FIRST HARMONIC FALL
C
DO 60 J>1.24
IF [BPF.LT.FL[J]] 60 TO 70
60 CONTINUE
70 NOBP1 > J-1
NOBP2 > NOBP1 < 3
IF[NOBP2 .GT.24] NOBP2 > 24
XMTIP > PI * DIAT * RPMC / [ 60. * 12. * SAZ]
XMREL > SORT[XMTIP**2 < XMTIP**2]
C > SAZ * 12.

C * * * BEGIN CALCULATION OF BROADBAND NOISE * * *
C
JMACH > 20.0 * XMREL - 12.50001
IDFAC > 50.0 * DF - 12.50001
IF [JMACH.GT.0] 60 TO 80
JMACH > 1
80 IF [JMACH.LE.15] 60 TO 90
JMACH > 15
90 IF [IDFAC.GT.0] 60 TO 100
IDFAC > 1
100 IF [IDFAC.LE.15] 60 TO 110
IDFAC > 15
110 CONTINUE

C CALCULATE CONSTANT TERMS AND OVERALL LEVEL
C
DBB > 10.0 * ALOG10[ BPR/[BPR < 1.0]/0.833 J
DBA > 20.0 * ALOG10[ DIAT/52.0]
DBR > 20.0 * ALOG10[ FFR / 150.0 J
F1 > 0.5 * [ 1.0 - TANHC 5.0 * [XMREL - 0.95]]]
F2 > 0.5 * [ 1.0 - TANHC 15.0 * [XMREL - 0.95]]]

C
OVAL > TABLE[IDFAC, JMACH] < F1 * SUBD[INC] < DBA - DBR
OVAL > OVAL < [ 1.0 - F1 ] * SUPD[INC]
IFC INC .GT. 9 J OVAL > OVAL < DBB

C SPECTRAL DISTRIBUTION
C

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FAN 1500
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D1 > SORT[ABS[1.00 - XMREL**2]] * CHORD
D2 > [F2 * SAZ * XMREL / D1]** 12.0
D3 > [1.00-F2]** 5.00 * SAZ * 24.00 / DIAT
FCR > D2 < D3
DO 120 J>1,24
IF [FCR.LE.FL[<I]] GO TO 130
120 CONTINUE
ICK > 24
GO TO 140
130 ICK > I
140 CORECT > 50.0 * CHORD * SORT[ABS[1.00 - XMREL ** 2]]
DUM > CORECT / [12.0/* SAZ * XMREL]
CORECT > 10.0 *ALOG10[DUM]
IF[XMREL .GT. 1.0]CORECT>10.0*ALOG10[50.0*DIAT/[24.0*SAZ]] - 7.00
OCTAVE > OVAL - 10.7777
DO 170 J>1,24
IF [J.GT.ICK] GO TO 150
BBN[J] > OCTAVE < CORECT < J - 1.0
GO TO 160
150 BBN[J] > OCTAVE - 0.5333*J - ICKJ
160 BBN[J] > 10.0*[BBN[J]/10.0]
170 CONTINUE
C
C *** END BROADBAND NOISE ***
C
C * * * BEGIN CALCULATION OF DISCRETE TONE NOISE * * *
XMTIPS > XMTIP / SORT[ 1.0 - XMHAVE**2]
XMSTAR > 1.0 < 0.84*B**L-0.6666667]
ZETAB1 > XMTIPS / XMSTAR
NCOR > 1.0 < ZETAB1 / 0.91
IF[ NCOR .GT. 3 ] NCOR > 3
C
C CALCULATE POWER LEVELS
PRL > 10.0 * ALOG10[[PR-1.0] * [DIAT/24.0]**2]
DLL > 20.0 * ALOG10[DL]
IF [ZETAB1.LE.1.5] GO TO 180
PWLIF > 127.0 < PRL - DLL
PWLIR > 129.0 < PRL
GO TO 190
180 Z1 > ZETAB1
Z2 > Z1 * Z1
Z3 > Z1 * Z2
Z4 > Z1 * Z3
Z5 > Z1 * Z4
PWLIF > 121.84 < 38.28*Z1 - 303.79*Z2 < 635.85*Z3
PWLIF > PRL < PWLIF - 483.36*Z4 < 122.80* Z5
IF ZETAB1 .GT. 1.05] PWLIF > PWLIF - DLL
PWLIR > 184. - 203.18*Z1 - 21.98*Z2 < 550.99*Z3
FAN 1650
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PWL1R > PWL1R < PRL - 534.97*Z4 < 151.26*Z5
190 PWL2F > PWL1F - CORFNCORJ
    PWL2R > PWL1R - FCORRNCORJ
C DIRECTIVITY AND SPL
C
    FFL > 20.0 * ALOG10[FFR]
    SPLMF > PWL1F - FFL < 5.55
    SPLMR > PWL1R - FFL < 5.55
    THETA1 > INC * 10. / RAD
    T1 > THETA1
    T2 > T1 * T1
    T3 > T1 * T2
    T4 > T1 * T3
    T5 > T1 * T4
    IF [INC.GE.9J] GO TO 220
    IF [ZETAB1.GT.1.05J] GO TO 200
    SPL1 > SPLMF -1.26688 < 5.49633E-02*T1 - 2.949127E-03*T2
    SPL1 > SPL1 < 7.628378E-05*T3 < 3.44868E-07*T4 - 1.232265E-08*T5
    GO TO 210
200 SPL1 > SPLMF - 3.03392 < 7.285306E-02*T1 < 4.082438E-04*T2
    SPL1 > SPL1 < 2.823003E-07*T3 < 8.859138E-08*T4 - 6.314598E-10*T5
210 SPL2 > SPL1 - CORFNCORJ
    GO TO 230
220 A0 > -56.418
    A1 > 6.450250E-01 * T1
    A2 > 2.096982E-03 * T2
    A3 > -6.778207E-06 * T3
    A4 > -2.895571E-07 * T4
    A5 > 8.594444E-10 * T5
C
    SPL1 > SPLMR < A0 < A1 < A2 < A3 < A4 < A5
    SPL2 > SPL1 - FCORRNCORJ
230 CONTINUE
C
    BPN1 > 10.0 ** [SPL1/10.]
    BPN2 > 10.0 ** [SPL2/10.]
    ICOMB > COMB < 0.00001
    IF [ICOMB.EQ.0J] GO TO 240
C
C IF CALCULATION IS DESIRED FOR COMBINATION TONES AND IF RELATIVE TIP
C MACH NUMBER IS OVER 1 NEXT THREE STATEMENTS ARE SKIPPED AND
C CALCULATION FOR COMBINATION TONES BEGINS
C
    IF [XMRLE.GT.1.0J] GO TO 250
240 BBN[NOBP1] > BPN1 < BBN[NOBP1]
    BBN[NOBP2] > BPN2 < BBN[NOBP2]
    GO TO 480
C
C BEGIN CALCULATION OF COMBINATION TONE NOISE

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FAN 2150
FAN 2160
FAN 2170
FAN 2180
FAN 2200
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FAN 2990
FAN 3000
FAN 3010
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FAN 3090
FAN 3100
FAN 3110

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C 250 SINMU > 1.0 / XMREL
COSMU > SORTI1.0 - SINMU**2 J
TANMU > SINMU / COSMU
XMU > ATAN(TANMU)
TBETAS > XMXTIP / XMXTIP
BETAS > ATAN(TBETAS) J
SMULB > SINC XMU - BETAS J
DUM1 > 1.0 - XMXTIP ** 2
DUM2 > 1.0 < XMXTIP ** 2 / 5.0
DUM3 > XMREL ** 2 / [XMXTIP * XMXTIP]
DUM4 > DUM1 * DUM3 / DUM2
DUM5 > 0.5 * [DIAT ** 2 - DIAH ** 2]
DUM6 > DIAT*DDDXT < DIAH * DDDXH
DUM7 > DUM5 / [DUM6 * COS(BETAS)]

C IF AZIMUTH ANGLE .GT. 110 DEG., SET TO MAXIMUM
C
IF [INC .GT. 11] J INC > 11
RF > DUM4 * DUM7
IF [RS.LT.0.0] GO TO 260
IF [RF-RS]260,260,270
260 RS > 1.0E<25
GO TO 280
270 RS > RS * RF / [RF - RS] J
280 CONTINUE
ALPHA > RS/TAU * SINMU/SMULB
THETA > 13.5 * ALPHA**[-0.875] / RAD
ALPHA > RS/TAU * SINC XMU < THETA] / SMULB
DUM1 > 2.0 * COS(XMU) - [TAU/RS] * SMULB
DUM2 > SINC XMU]**2 < [TAU/RS] * SMULB * DUM1
THETA > 2.0 * ATAN([SINC XMU] < SORTI[DUM2]] / DUM1 J
PSI1 > THETA / [SORTI[2.0] * SIGPHI] J
PSI2 > [THETA - THETA] / [SORTI[2.0] * SIGPHI]
ETA > 0.5 * [1.0 < ERFC[PSI2] ]
A1 > 2.0 ** 1.5 * SIGPHI
DUM1 > [2.0 * SIGPHI]**2
DUM2 > PSI1**2 < A1*PSI1 < DUM1*EXP[-PSI1**2]
DUM3 > PSI2 < A1*PSI2 < DUM1**EXP[-PSI2**2]
DUM3 > DUM2 - DUM3
DUM4 > SIGPHI**2 < 2.0*SIGPHI**3*SORTI[2.0 / PI] J
DUM4 > DUM4 * DUM3
SIGESQ > 1.0 - ETA < 2.0*ETA*ALPHA**2 * DUM4
SIGEPS > SORTI[SIGESQ]
IF [SIGEPS .GT. 0.3] SIGEPS > 0.3
SIGAMP > 0.1
N1 > 11312.0 / E1

C CALCULATE SOUND POWER
C

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PWL1 > -189.16 < 727.24 * XMREL - 488.93 * XMREL**2
PWL2 > PWL1 < 107.69 * XMREL**3 < 10.0*ALOG10[AREA / 144.0]
PWL3 > PWL2 - 20.0 * ALOG10[ETA * B ]
C
C SPECTRAL DISTRIBUTION
C
N > ETA * B
AN > N
AM2 > 1.0 < SIGAMP**2
POWER > 0.0
DO 320 KHAR>1,N1
AHAR > KHAR
PHPB > PI * AHAR / AN
PHPB2 > PHPB ** 2
TPHPB > 2.0 * PHPB
TERM > 0.25 / [PHPB * PHPB2 * AHAR ] * [1.0 - COS[TPHPB]
1 < PHPB2 * [2.0 - 2.0 / PHPB * SINC[TPHPB] ] ]
EXPO > EXP[-PHPB2 * 4.0 * SIGEPS ** 2]
IF [MOD[KHAR,N]]300,290,300
290 TERM > TERM * [ AM2 < EXPO * [ B - 1.0 ] ]
GO TO 310
300 TERM > TERM * [AM2 - EXPO]
310 POWER > POWER < TERM
320 PWL[KHAR] > 10.0 * ALOG10[TERM] < 170.8
C
C DUCT PROPAGATION
C
CUTOFF > 1.0 - 0.1 * EXP[23.0259 * [1.0 - XMREL] ]
DO 330 I>1,N1
ORDER > I
XMSTAR > 1.0 < 0.81 * ORDER ** [-0.66666667]
ZETA > XMTIP / SORT[1.0 - XMSTAR ** 2] / XMSTAR
IF [ZETA*GE.CUTOFF] GO TO 340
330 CONTINUE
340 ICUT > I - 1
C
C CALCULATE TOTAL PWL CONTAINED IN HARMONICS BELOW CUTOFF AND SET PWL
C OF ALL THESE HARMONICS TO ZERO
C
DO 350 I>1,ICUT
POWER > POWER - 10.0*[ PWL[I]/10.0 - 17.08]
PWL[I] > 0.
350 POWER > 10.0 * ALOG10[POWER] < 170.8
DELPWL > PWL - POWER
ICUTP1 > ICUT < 1
C
C INCREASE THE PWL OF HARMONICS ABOVE CUTOFF TO ACCOUNT FOR PWL
C SUBTRACTED BECAUSE OF HARMONICS BELOW CUTOFF.
C
DO 360 KHAR>ICUTP1,N1

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FAN 3120
FAN 3130
FAN 3140
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02400

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360 PWLCKHARJ > PWLCKHARJ < DELPWL
 C DIRECTIVITY
 C
 RADCOR > 20.0 * ALOG10[FFRJ] - 3.85
 NG > 0
 DO 410 I>1,N1
 ORDER > I
 FREQ > ORDER * E1
 REFSPL > 0.
 IF [PWLCKHARJ-LE:RADCOR] GO TO 400
 REFSPL > PWLCKHARJ - RADCOR
 XNSTAR > 1.0 < 0.81 * ORDER ** [-2/3]
 ZETA > XMTIP / XNSTAR / SQRT[1.0 - XMXAVE ** 2]
 IF [NG.EQ.1] GO TO 370
 IF [ZETA .GT. 1.5] NG > 1
 IF [ZETA .LT. 1.0] ZETA > 1.0
 ZETA[CK] > 1.0
 DO 380 K>2,6
 380 ZETA[CK] > ZETA * ZETA[CK-1]
 PWLCKHARJ > REFSPL
 DO 390 K>1,6
 390 PWLCKHARJ > PWLCKHARJ < DIR[CK]*K] * ZETA[CK]
 400 CONTINUE
 410 CONTINUE
 C
 C THIRD OCTAVE SYNTHESIS
 C
 KHAR > 0
 DO 470 I>1,24
 SUM > 0.
 IF [KHAR.GT.N1] GO TO 430
 AHAR > KHAR
 FREQ > AHAR * E1
 IF [FREQ.GT.FL[CK]] GO TO 430
 IF [PWLCKHARJ-LE.0.0] GO TO 420
 SUM > SUM < 10.0 * [PWLCKHARJ/10.0]
 GO TO 420
 430 KHAR > KHAR - 1
 IF [I.EQ.NOBP1] GO TO 450
 IF [I.EG.NOBP2] GO TO 460
 IF [SUM.LE.0.0] GO TO 470
 440 BBN[CK] > BBN[CK] < SUM
 GO TO 470
 C FOR THIRD OCTAVES CONTAINING THE DISCRETE FREQUENCY (BLADE PASSAGE)
 C NOISE THE SPL IS EQUAL TO THE LARGER OF BLADE PASSAGE NOISE OR
 C COMBINATION TONE NOISE
 C

FAN 3540
 FAN 3550
 FAN 3560
 FAN 3570
 FAN 3580
 FAN 3590
 FAN 3600
 FAN 3610
 FAN 3620
 FAN 3630
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 FAN 3690
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450 IF [BPN1.LT.SUM] GO TO 440
    SUM > BPN1
    GO TO 440
460 IF [BPN2.LT.SUM] GO TO 440
    SUM > BPN2
    GO TO 440
470 CONTINUE
C
C END OF COMBINATION TONE NOISE CALCULATION
C
C ARRAY BBN NOW CONTAINS THE SOUND PRESSURE OF THE TOTAL OF BROADBAND,
C DISCRETE FREQUENCY TONE, AND COMBINATION TONE NOISE
C
480 CONTINUE
C
C CONVERT SOUND PRESSURE TO SPL
C
DO 490 I>1,24
490 BBN[I] > 10.0 * ALOG10[BBN[I]] < CONST
500 CONTINUE
RETURN
END
FUNCTION ERF[X]
C
C TITLE: FUNCTION ERF
C
C PURPOSE: TO CALCULATE THE VALUE OF ERF(PHI(2)) REQUIRED BY
C SUBROUTINE FAN IN THE CALCULATION OF COMBINATION TONES
C
C ABSTRACT: ERF CAN TAKE ON 5 DIFFERENT VALUES DEPENDING ON THE VALUES
C OF THE ARGUMENT PHI(2) AND A VARIABLE T GIVEN BY:
C  $T = 1/(1 - 0.328*ABS(PHI(2)))$ 
C ERF = 0 FOR PHI(2) EQ 0
C ERF = 1 FOR PHI(2) GT 0 AND T LE 0.43
C ERF = -1 FOR PHI(2) LT 0 AND T LE 0.43
C ERF = +Q FOR PHI(2) GT 0 AND T GT 0.43
C ERF = -Q FOR PHI(2) LT 0 AND T GT 0.43
C WHERE Q IS GIVEN BY:
C  $Q = 1 - T*EXP(-PHI(2)**2)/(1.061*T**4 - 1.43*T**3$ 
C  $+ 1.42*T**2 - 0.248*T + 0.255)$ 
C
C USAGE: ... (X)
C X.....INPUT VALUE OF PHI(2)
C
C LABELED
C COMMON: NONE
C
C SUBROUTINES CALLED: FUNCTION SIGN(X,Y)
C
T > 1.0 / [1.0 < 0.3275911 * ABS[X]]

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FAN 3990
FAN 4000
FAN 4010
FAN 4020
FAN 4030
FAN 4040
FAN 4050
FAN 4060
FAN 4070
FAN 4080

FAN 4090

FAN 4100
FAN 4110
FAN 4120
FAN 4130
FAN 4140
ERF 0010
ERF 0020

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ERF 0030
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 02550

ERF 0040
 ERF 0050
 ERF 0060
 ERF 0070
 ERF 0080
 ERF 0090
 ERF 0100
 ERF 0110
 ERF 0120
 ERF 0130
 ERF 0140
 ENGI0010
 ENGI0020

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IF [X]20,10,20
10 ERF > 0.
RETURN
20 IF [T-0.43]30,30,40
30 ERF > SIGN[1.0,X]
RETURN
40 ERF > 1.0 - T * EXPL-X*X]*[0.254829592 < T * [-0.284496736 <
1 T * [1.42141374 < T * [-1.45315203 < T * 1.06140543]JJJ]
ERF > SIGN[ERF,X]
RETURN
END
SUBROUTINE ENGINE[E0BLR3,BIGX,BIGY,BIGZ]
  
```

C C TITLE: ENGINE
 C C PURPOSE: TO CALCULATE THE 1/3-OCTAVE BAND SPL SPECTRUM FOR TURBO-
 C C SHAFT ENGINES

C C ABSTRACT: AN EMPIRICAL TECHNIQUE BASED ON NOISE DATA MEASURED FOR
 C C SEVERAL ENGINE IS USED. THE SIDELINE PNL IS CALCULATED,
 C C CORRECTED TO THE OBSERVER'S AZIMUTH LOCATION, CONVERTED
 C C TO AN OCTAVE SPECTRUM, AND, FINALLY, CONVERTED TO A 1/3-
 C C OCTAVE SPECTRUM. REQUIRED INPUT (VIA COMMON):
 C C HPENG...ENGINE POWER OUTPUT
 C C SLEVEL...ESTIMATED ENGINE SOUND LEVEL, EITHER AVERAGE
 C C OR LOUD (SEE REPORT FOR DETAILS)
 C C ANENG...NUMBER OF ENGINES

C C USAGE:(E0BLR3,BIGX,BIGY,BIGZ)
 C C E0BLR3...A 24 ELEMENT ARRAY CONTAINING THE CALCULATED
 C C 1/3-OCTAVE NOISE SPECTRUM
 C C BIGX
 C C BIGY...COORDINATES OF OBSERVER RELATIVE TO VEHICLE
 C C BIGZ (INPUT)

C C LABELED
 C C COMMON: /B1/ /INPUT/

C C SUBROUTINES CALLED: NONE

C C DIMENSION E0BLR[9],E0BLR3[24],G CURVE[19],DCURVE[19],CORRCV[19,9]
 C C 1,BES[400]
 C C COMMON /B1/ BES,INCMAX[50]
 C C 1RCHORD /INPUT/ SAZ,SEG,FLTYPE,RCASE,RETA,RBIG,RBIGR,ROMEGN,RSID,
 C C 1RCHORD,RTHRUS,RTORG,FBETA,TCASE,TETA,TBIG,TBIGR,TOMEGN,TSID,
 C C 2TCHORD,TTHRUS,TTORG,TBETA,PPWR,DIA,BIGB,RPMP,ANMPRP,CHORDP,
 C C 3PATH[50],XMAX[50],YMAX[50],PHMAX[50],RADIUS[50],VF1[50],ALF[50],
 C C 4XPRZRO,YPRZRO,THMAXO,AZERO,TINC,ANMFT,HPENG,SLEVEL,ANENG,DIAT,
 C C SDIAH,B,BPR,CHORD,DDXT,DDXH,RS,SIGPHI,DL,RPM,SPAF,XMXTIP,PR,DF,
 C C 6TT2,PT2,ALFA,FN,COMB,THRUST,WTLF,AREAJ,PSUBA,TSUBA,TSUBJ,TSUBJO,
 C C ENGI0170
 C C ENGI0180
 C C ENGI0190
 C C ENGI0200
 C C ENGI0210
 C C ENGI0220
 C C ENGI0230
 C C ENGI0240
 C C ENGI0250
 C C ENGI0260


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10 CONTINUE
   PNL500 > FACT1 * ALOG10[HPENG/10.JK FACT2<
   110.0*ALOG10[ANENG]
C
C COMPUTE GAMMA, IF X AND Y ARE BOTH ZERO SET GAMMA TO 90 DEG.
C IF GAMMA IS NEGATIVE, SET POSITIVE
C GAMMA IS THE OBSERVER AZIMUTHAL LOCATION. 180 DEGREES IS IN FRONT.
C
   IF [BIGY<BIGX]40,20,40
   20 IF [BIGZ]50,100,30
   30 GAMMA > 90.
   GO TO 50
   40 GAMMA > ABS[ ATAN2[ BIGY, -BIGX ] ]
   GAMMA > GAMMA / DTR
   50 CONTINUE
C
C CORRECT SIDELINE PNL TO AZIMUTH GAMMA USING ARRAY DCURVE
C
C FIND INTERVAL IN WHICH GAMMA LIES AND APPLY CORRECTION
C
   ISA > GAMMA / 10.0 < 1.5
   IFF ISA .GT. 19 J ISA > 19
   IFF ISA .LT. 1 J ISA > 1
   DELTA > DCURVE[ISA]
   60 PNL500 > PNL500 < DELTA
   SRP > SORT[BIGX**2 < BIGY**2 < BIGZ**2]
C
C CORRECTION FOR SPHERICAL EXPANSION TO DISTANCES OTHER THAN 500 FEET.
C
   SRPLG > 20.0 * ALOG10[SRP/500.]

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ENG10930
ENG10940
ENG10950
ENG10960
ENG10970
ENG10980
ENG10990
ENG11000
ENG11010
ENG11020
ENG11030
ENG11040
ENG11050
ENG11060
ENG11070
ENG11080
ENG11090
ENG11100
ENG11110
ENG11120
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ENG11150
ENG11160
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ENG11190
ENG11200
ENG11210
ENG11220

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C CALCULATE ENGINE OCTAVE BAND SPECTRUM
C
  DO 70 I>1,9
    CORR > CORRCV[ISA,I]
    EOBL > PNL500 - CORR
    EOBLR[I] > EOBL - SRPLG
  70 CONTINUE
  NN > 2
C CALCULATE ENGINE 1/3-OCTAVE BAND SPECTRUM
C
  DO 90 I>2,23,3
    E1 > EOBLR[NN] - 4.8
    EOBLR3[I-1] > E1 - 0.333 * [ EOBLR[NN] - EOBLR[NN-1] ]
    EOBLR3[I] > E1
    IF [NN.EQ.9] GO TO 80
    EOBLR3[I<1] > E1 - 0.333 * [ EOBLR[NN] - EOBLR[NN<1] ]
    NN > NN - 1
    GO TO 90
  80 EOBLR3[I<1] > E1 < 0.333 * [ EOBLR[NN] - EOBLR[NN-1] ]
  90 CONTINUE
C END OF ENGINE 1/3-OCTAVE NOISE SPECTRUM
C
  100 CONTINUE
  RETURN
  END
C

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ENGI1230
ENGI1240
ENGI1250
ENGI1260
ENGI1270
ENGI1280
ENGI1290
ENGI1300
ENGI1310
ENGI1320
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ENGI1380
ENGI1390
ENGI1400
ENGI1410
ENGI1420
ENGI1430
ENGI1440
ENGI1450
ENGI1460
ENGI1470
ENGI1480
ENGI1490
ENGI1500

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ROTO0010

SUBROUTINE ROTORLFCCK3,ROLTP3,RX,RY,RZ,JKI

C

C TITLE: ROTOR

C PURPOSE: TO CALCULATE THE ONE-THIRD OCTAVE NOISE SPECTRUM GENERATED

C BY A HELICOPTER MAIN AND TAIL ROTOR

C

C ABSTRACT: ROTOR ROTATIONAL NOISE IS CALCULATED USING THE CLOSED-FORM

C SOLUTION MENTIONED BY LOWSON AND OLLERHEAD IN REFERENCE 1.

C THIS IS COMBINED WITH A BROADBAND NOISE SPECTRUM THAT IS

C CALCULATED FROM THE EMPIRICAL EQUATION PRESENTED IN REF. 2

C BUT CORRECTED TO ACCOUNT FOR DIRECTIVITY. SPECTRA ARE

C CALCULATED FOR THE MAIN ROTOR AND TAIL ROTOR THEN COMBINED

C TO PRODUCE THE TOTAL SPECTRUM.

C REQUIRED INPUT (VIA COMMON):

C RCASE (ICASE).....MAIN (TAIL) ROTOR AIRLOADING K FACTOR

C RETA (TETA).....MAIN (TAIL) ROTOR RADIAL LOADING STATION

C RBIGB (TBIGB).....NUMBER OF MAIN (TAIL) ROTOR BLADES

C RBIGR (TBIGR).....MAIN (TAIL) ROTOR RADIUS

C ROMEGN (TOMEGN).....MAIN (TAIL) ROTOR ROTATIONAL SPEED

C RSID (TSID).....MAIN (TAIL) ROTOR DISK INCIDENCE ANGLE

C RCHORD (TCHORD).....MAIN (TAIL) ROTOR BLADE CHORD

C RTHRUS (TTHRUS).....MAIN (TAIL) ROTOR THRUST

C RTORQ (TTORQ).....MAIN (TAIL) ROTOR TORQUE

C RBETA (TBETA).....MAIN (TAIL) ROTOR CONING ANGLE

C VF1.....FLIGHT SPEED

C(FCK3,ROLTP3,RX,RY,RZ,JKI)

C USAGE:

C ROLTP3...THE 24 ELEMENT ARRAY CONTAINING THE CALCULATED

C ONE-THIRD OCTAVE NOISE SPECTRUM

C FCK3.....A 24 ELEMENT ARRAY CONTAINING THE 1/3-OCTAVE

C CENTER FREQUENCIES FROM 50 TO 10*000 HZ (INPUT)

C JK1.....FLIGHT SEGMENT NUMBER (INPUT)

C RX.....

C RY.....COORDINATES OF OBSERVER RELATIVE TO VEHICLE

C RZ (INPUT)

C

C LABELED

C COMMON: /B1/ /INPUT/

C

C SUBROUTINES CALLED: BJSIGN BESSEL

C

C DIMENSION BESS[400],OLKPL[24],PSGPI[60],SFM[60],FCK3[24],

C 1ROLTP3[24],ALTI[61],ALDI[61],ALCI[61],SCURVE[39]

C

C COMMON /B1/ BES,INCMAXL50]

C

C COMMON /INPUT/ SAZ,SEG,FLTYPE,RCASE,RETA,RBIGB,RBIGR,ROMEGN,RSID, ROTO0090

C 1RCHORD,RTHRUS,RTORQ,RBETA,TCASE,TETA,TBIGB,TBIGR,TOMEGN,TSID, ROTO0100

C 2TCHORD,TTHRUS,TTORQ,TBETA,PPWR,DIA,BIGB,RPMP,ANMPRP,CHORDP, ROTO0110

C 3PATHE 50 J,XMAXL 50 J,YMAXL 50 J,RADIUS 50 J,VFL 50 J,ALFL 50 J, ROTO0120

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4XPRZRO,YPRZRO,THMAXO,AZERO,TINC,ANMFT,HPENG,SLEVEL,ANENG,DIAT,
5UIAH,B,8PR,CHORD,DDXT,DDXH,RS,SIGPHI,DL,RPM,SPAF,XMXTIP,PR,DF,
6T2,PT2,ALFA,FN,COMB,THRUST,WFL,AREAJ,PSUBA,TSUBA,TSUBJ,TSUBJO,
7ALFAJ,ROTR,RP,FANS,RJ,E
C THE ARRAY NOISE CONTAINS THE CORRECTION NUMBERS TO CALCULATE THE
C BROADBAND NOISE SPECTRUM FROM THE CALCULATED OVERALL LEVEL
C
DATASURVE/
1-29.1, -28.0, -26.5, -25.1, -24.0, -22.5, -21.1, ROT00130
2-20.0, -18.4, -17.1, -15.9, -14.5, -13.1, -12.0, ROT00140
3-10.8, -9.1, -8.0, -9.1, -10.9, -12.0, -12.1, ROT00200
4-12.3, -12.5, -14.0, -15.4, -17.0, -17.3, -17.7, ROT00220
5-18.0, -19.3, -20.7, -22.0, -23.3, -24.7, -26.0, ROT00230
6-27.3, -28.7, -30.0, -31.3, / ROT00240
C BIGV > VF[IJKIJ] ROT00250
C
C SET PROGRAM CONSTANTS ROT00260
C
DTR>0.0174532925 ROT00270
PI>3.1415926536 ROT00280
HALFPI>PI/2.0 ROT00290
ROOT2>SQRT[2.0] ROT00300
NPP>1 ROT00310
TWO16>2.0*[1.0/6.0] ROT00320
TWO13>2.0*[1.0/3.0] ROT00330
TWO23>2.0*[2.0/3.0] ROT00340
MLIMIT > 20 ROT00350
IJK>ICASE ROT00360
XML>FLOAT[MLIMIT] ROT00370
BIGMF>BIGV/SAZ ROT00380
BMFSG>BIGMF*BIGMF ROT00390
BIGX > RY ROT00400
BIGZ > RZ ROT00410
IF [IJK.EQ.-10] GO TO 10 ROT00420
TBIGX > BIGX ROT00430
TBIGY > BIGZ ROT00440
TBIGZ > -BIGY ROT00450
10 CONTINUE ROT00460
CONLC > 0.7 ROT00470
C
C BEGIN LOOP FOR TWO ROTORS ROT00480
C
DO 470 IR>1,2 ROT00490
IF [IR.EQ.1] GO TO 30 ROT00500
C
C IF IJK IS -10 CALCULATION FOR TAIL ROTOR IS SUPPRESSED ROT00510
C
ROT00130 00051
ROT00140 00052
ROT00150 00053
ROT00160 00054
ROT00170 00055
ROT00180 00056
ROT00190 00057
ROT00200 00058
ROT00210 00059
ROT00220 00060
ROT00230 00061
ROT00240 00062
ROT00250 00063
ROT00260 00064
ROT00270 00065
ROT00280 00066
ROT00290 00067
ROT00300 00068
ROT00310 00069
ROT00320 00070
ROT00330 00071
ROT00340 00072
ROT00350 00073
ROT00360 00074
ROT00370 00075
ROT00380 00076
ROT00390 00077
ROT00400 00078
ROT00410 00079
ROT00420 00080
ROT00430 00081
ROT00440 00082
ROT00450 00083
ROT00460 00084
ROT00470 00085
ROT00480 00086
ROT00490 00087
ROT00500 00088
ROT00510 00089
ROT00520 00090
ROT00530 00091
ROT00540 00092
ROT00550 00093
ROT00560 00094
ROT00570 00095
ROT00580 00096
ROT00590 00097
ROT00600 00098
ROT00610 00099
ROT00620 00100

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IF [IJK.NE.-10] GO TO 20
III>2
GO TO 470
20 CASE>TCASE
ETA>ETA
BIGR > TBIGB
BIGR>TBIGR
OMEGN>TOMEGN
SID>TSID
CHORDR > TCHORD
THRUSR > TTHRUS
TORQUE>TTORG
BETA>TBETA
BIGY>TBIGY
BIGX>TBIGX
BIGZ>TBIGZ
GO TO 40
30 CASE>RCASE
ETA>RETA
BIGR > RBIGB
BIGR>RBIGR
OMEGN>ROMEGN
SID>RSID
CHORDR > RCHORD
THRUSR > RTHRUS
TORQUE>RTORG
BETA>RBETA
40 BIGM>OMEGN*ETA*PI*BIGR/[SAZ*30.]
C
C CALCULATE THE MAXIMUM NUMBER OF SOUND HARMONICS THAT CAN BE CALCULATED
C FROM 60 LOADING HARMONICS
C
LLIMIT > XML * BIGR * [1.0 < BIGM] < 0.5
IF [LLIMIT.LT.60] GO TO 50
LLIMIT>60
MLIMIT > LLIMIT / [ BIGR * [1.0 < BIGM] < 0.5]
50 LI>LLIMIT<1
XLL>LLIMIT
K>1
ETARN>1.0/[ETA*BIGR]
C
C CALCULATE STEADY AND FIRST HARMONIC LOADING
C
ALTC1J > THRUSR
ALDC1J>TORQUE*ETARN
ALCC1J > THRUSR * SINEBETA * DTRJ
ALTC2J > ALTC1J/4.0
ALDC2J > ALDC1J/4.0
ALCC2J > ALCC1J / 4.0
DO 60 LK>3*61

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ROT00570
ROT00580
ROT00590
ROT00600
ROT00610
ROT00620
ROT00630
ROT00640
ROT00650
ROT00660
ROT00670
ROT00680
ROT00690
ROT00700
ROT00710
ROT00720
ROT00730
ROT00740
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ROT00770
ROT00780
ROT00790
ROT00800
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ROT00970
ROT00980
ROT00990
ROT01000
ROT01010
ROT01020

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00101
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PWRK>CONLC/[LK-1]*CASEJ
ALTLKJ>ALTL1J*PWRK
ALDELKJ>ALDL1J*PWRK
60 ALCLKJ>ALCL1J*PWRK
OMEGA>[PI*OMEGN]/30.
XX > 0.5 * OMEGA * BIGBR / PI
OMEGR>OMEGA*BIGR
CO > OMEGA * BIGBR / [4. * PI * SAZJ
EXPK>2.0*CASE
AL>2.0-EXPK

C
C CALCULATE VORTEX NOISE CONSTANT TERMS
C
VTLG>20.0*ALOG10[OMEGR]
TLG > 20. * ALOG10[THRUSRJ]
BLG > 10. * ALOG10[BIGBR]
RLG>10.0*ALOG10[BIGR]
CLG > 10. * ALOG10[CHORDR/12.]
FCKZ > 0.764 * OMEGR - 240. * ALOG10[THRUSRJ] < 786.0
FCKZ1 > 1.0/[TW016 * FCKZ]
FCKZ2 > TW016 / FCKZ
RMT>OMEGR/SAZ
XMACH>[1.0*CRMT]**2
XMACHM>[1.0-RMT]**2
SPLVCO>VTLG<TLG-BLG-RLG-CLG<17.4
NBIGB > BIGBR < 0.0001

C
C CALCULATE SMALL-X, SMALL-Y, PHI, X-PRIME, R-PRIME, AND SAML-R1
C
DUM>BIGX**2<[1.0-BMFSQJ]*[BIGY**2<BIGZ**2]
DUM>BIGX*BMFSQ<BIGMF*SORT[DUM]
DUM>DUM/[1.0-BMFSQ]
BIGXP>BIGX<DUM
COSINE>COS[SID*DTR]
SINE>SINE[SID*DTR]
DUM1>BIGY
DUM2>BIGXP<COSINE<BIGZ<SINE
IF [DUM1]70,70,110
70 IF [DUM2]80,90,100
80 PHI>ATAN[ABS[DUM1/DUM2]]
GO TO 150
90 PHI>HALFPI
GO TO 150
100 PHI>ATAN[ABS[DUM1/DUM2]]
GO TO 150
110 IF [DUM2]120,130,140
120 PHI>2.0*PI-ATAN[ABS[DUM1/DUM2]]
GO TO 150
130 PHI>2.0*PI-HALFPI

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ROTO1030
ROTO1040
ROTO1050
ROTO1060
ROTO1070
ROTO1080
ROTO1090
ROTO1100
ROTO1110
ROTO1120
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ROTO1180
ROTO1190
ROTO1200
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ROTO1390
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ROTO1450
ROTO1460
ROTO1470
ROTO1480
ROTO1490
ROTO1500
ROTO1510
ROTO1520

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00200

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GO TO 150
140 PHI>PI<ATAN1 ABS[DUM1/DUM2]]
150 CONTINUE
SX>BIGXP*SINE-BIGZ*COSINE
SY>-DUM2*COS[PHI]-BIGY*SIN[PHI]
SRP>SORT[BIGXP**2<BIGY**2<BIGZ**2]
BIGMZ>BIGMF*BIGXP/[SRP]
XF>XX/[1.0-BIGMZ]
SR>SRP/[1.0-BIGMZ]
C1>CO/SR
CON2>SX/SR
CON4>SY/[2.0*SR]
DARG>ABS[BIGZ/SRP]

C
C CALCULATE VORTEX DIRECTIVITY ANGLE AND CONSTANT TERMS
C
THET > ABS[1.0 - DARG**2]
THET > SORT[THET]
IF [THET.GT.0.01745] GO TO 160
EKAPPA>HALFPI
GO TO 170
160 TNUM > DARG / THET
EKAPPA>ATAN(TNUM)
170 ATHETA>EKAPPA-SID*DTR
ALPHA>HALFPI-ATHETA
THET > COS[ALPHA]**2 < 0.1
THETLG > 10.0 * ALOG10[THET]
SRPLG>20.0*ALOG10[SRP]
SPLVLG>SPLVCO<THETLG-SRPLG

C
C START SOUND HARMONIC LOOP
C
DO 210 M>1,MLIMIT
TSSQ>0.
XM>FLOAT[M]
SFMCMJ>XF*XM
NM>NBIGB
XN>FLOAT[N]
L11 = XN * (1.0 + BIGM) + 0.5
CON1>C1*XM
CON3>1.0/[XN*BIGM]
CON5>CON1*CON2
CON6>CON1*CON3
CON7>CON1*CON4
NSUB=N+L11+1
BARG>XN*BIGM*SY/SR
CALL BESSELBARG,NSUB,1.0E-06]

C
C BEGIN LOADING HARMONIC LOOP
C

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ROT01530
ROT01540
ROT01550
ROT01560
ROT01570
ROT01580
ROT01590
ROT01600
ROT01610
ROT01620
ROT01630
ROT01640
ROT01650
ROT01660
ROT01670
ROT01680
ROT01690
ROT01700
ROT01710
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ROT01800
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ROT01900
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ROT01940
ROT01950
ROT01970
ROT01980
ROT01990
ROT02000
ROT02010

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DO 200 L>1,L11
LL>L-1
ARG>LL*PHI
COSL>COS[ARG]
SINL>SIN[ARG]
K1>NKLL
K2>N-LL
K3>K1<1
K4>K1-1
K5>K2<1
K6>K2-1
EE>1.0
IFELL .NE. 2*[LL/2]JEE>-1.0
C TRANSFORM LOADINGS FROM X,Y,Z SYSTEM TO SX,SY SYSTEM
C
AT>ALTL[*COSL
AD>ALDCL[*COSL
AC>ALCCL[*COSL
BT>ALTL[*SINL
BD>ALDCL[*SINL
BC>ALCCL[*SINL
C CALCULATE REQUIRED BESSEL FUNCTION VALUES
C
CALL BJSIGN[K1,BJ1]
CALL BJSIGN[K2,BJ2]
CALL BJSIGN[K3,BJ3]
CALL BJSIGN[K4,BJ4]
CALL BJSIGN[K5,BJ5]
CALL BJSIGN[K6,BJ6]
C CALCULATE TERM VALUES
C
DUM1>[XNKL]*BJ1
DUM2>[XN-LL]*BJ2*EE
DUM3>BJ3-BJ4
DUM4>EE*[BJ5-BJ6]
ANLT>CON5*AT*[BJ1<EE*BJ2]
ANLD>CON6*AD*[DUM1<DUM2]
ANLC>CON7*AC*[DUM3<DUM4]
BNLT>CON5*BT*[BJ1-EE*BJ2]
BNLD>CON6*BD*[DUM1-DUM2]
BNLC>CON7*BC*[DUM3-DUM4]
DUM5>ANLT-ANLDBNLC
C DETERMINE IF NKLL IS ODD OR EVEN
C
IF [K1.NE.2*[K1/2]] GO TO 180
C

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ROT02020 00251
ROT02030 00252
ROT02040 00253
ROT02050 00254
ROT02060 00255
ROT02070 00256
ROT02080 00257
ROT02090 00258
ROT02100 00259
ROT02110 00260
ROT02120 00261
ROT02130 00262
ROT02140 00263
ROT02150 00264
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00299
00300

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C N K L L I S E V E N
C
E1>1.0
MX>K1/2
IFEMX .NE. 2*[MX/2]J E1>-1.0
ANL>E1*[BNLT-BNLD-ANLCJ
BNL>E1*DUM5
GO TO 190
180 CONTINUE
C
C N K L L I S O D D
C
E1 > 1.0
MK>K4/2
IFEMK .NE. 2*[MK/2]J E1>-1.0
ANL>E1*DUM5
BNL>E1*[BNLT<BNLD<ANLCJ
190 SPSQ>ANL*ANL<BNL*BNL
TSSQ>TSSQ<SPSQ
200 CONTINUE
C
C E N D L O A D I N G H A R M O N I C L O O P
C
GGM>TSSQ<1.0E-20
PM > 10.0 * ALOG10[GGM] < 124.58
PSQ[PM] > PM
210 CONTINUE
C
C E N D O F S O U N D H A R M O N I C L O O P
C
C C A L C U L A T E B I G K F O R H I G H E R H A R M O N I C S
C
XMB > M L I M I T * B I G B R
XMB>XMB**AL
BIGK > GGM/XMB
C
C C A L C U L A T E S O U N D H A R M O N I C S F R O M M L I M I T T O 60
C
RLGK>ALOG10[BIGK]<12.458
MIN>MLIMIT<1
DO 220 M>MIN*60
F>XF*M
XMB > M * B I G B R
PM>10.0*[AL*ALOG10[XMB]<RLGK]
SFM[M]>F
PSQ[PM] > PM
220 CONTINUE
230 CONTINUE
C
C E N D O F S O U N D H A R M O N I C C A L C U L A T I O N

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ROT02520
ROT02530
ROT0254
ROT02550
ROT02590
ROT02600
ROT02610
ROT02620
ROT02630
ROT02650
ROT02690
ROT02700
ROT02710
ROT02720
ROT02730
ROT02740
ROT02750
ROT02760
ROT02770
ROT02780
ROT02790
ROT02800
ROT02810
ROT02820
ROT02830
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ROT02880
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ROT02900
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ROT02940
ROT02950

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C C BEGIN CALCULATION OF ONE-THIRD OCTAVES OF ROTATIONAL NOISE BY
C COMPARING FREQUENCY OF THE 60-TH HARMONIC TO THE 1/3-OCTAVE CENTER
C FREQUENCIES TO DETERMINE THE BAND THAT CAN BE CALCULATED BY
C SUMMING HARMONIC LEVELS. THE CENTER FREQUENCY OF THIS BAND IS
C CALLED FCC AND THE BAND NUMBER IS JFC.
C
DUM > SFM[60] / 1.6
DO 240 J>1,24
IF [DUM.LT.FCK3[K]J] 60 TO 250
240 CONTINUE
JFC > 24
GO TO 260
250 JFC > J - 1
260 CONTINUE
SMK>CASE
DO 270 KL>1,24
270 OLKPE[KL]J>0.0

C C CALCULATE 1/3-OCTAVE LEVELS UP TO BAND JFC BY SUMMING HARMONICS.
C AFK VALUES ARE ATTENUATIONS DUE TO FILTER SHAPE ASSUMED
C
DO 320 M>1,60
PS>PSQP[M]
F>SFM[M]
DO 320 KL>1,JFC
IF [F.GE.FCK3[KL]J] 60 TO 280
DUM>133.0*ALOG10[F/FCK3[KL]J]
AFK>DUM<3.65
GO TO 290
280 DUM>133.0*ALOG10[FCK3[KL]J/F]
AFK>DUM<3.65
290 IF [AFK.LE.0] 60 TO 310
300 AFK>0.
310 CONTINUE
Y>0.1*[PS<AFK]
OLKPE[KL]J>OLKPE[KL]J<10.0**Y
GO TO 320
320 CONTINUE
330 CONTINUE

C C CALCULATE SPL'S FOR BANDS UP TO FCC
C
DO 350 KL>1,JFC
IF [OLKPE[KL]J.LE. 1.0E-20] OLKPE[KL]J>1.0E-20
340 OLKPE[KL]J>10.0*ALOG10[OLKPE[KL]J]
350 CONTINUE
MIN>JFC<1
DXX>TW016*SFM[1]
DXX>1.0/DXX

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00399
00400

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ROT03000
ROT03010
ROT03020
ROT03030
ROT03040
ROT03050
ROT03060
ROT03070
ROT03080
ROT03090
ROT03100

ROT03110
ROT03120
ROT03130
ROT03140
ROT03150
ROT03160
ROT03170
ROT03180
ROT03190
ROT03200
ROT03210
ROT03220
ROT03230
ROT03240
ROT03250
ROT03260
ROT03270
ROT03280

ROT03290

ROT03300
ROT03310
ROT03320
ROT03330
ROT03340
ROT03350
ROT03360

```

C C CALCULATE 1/3-OCTAVE BANDS ABOVE ONE AT FCC
C

```

DO 380 KL>MIN*24
FNN > FCK3[KL-1] * DX
NN > FNN
NMIN>NJK1
NMAX > TW013 * FNN
SUM>0.0
DO 360 J>NMIN,NMAX
360 SUM>SUMJ**AL
XDEN > SUM
SUM>0.0

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```

NMIN > TW013 * FNN < 1.0001
NMAX > TW023 * FNN
DO 370 J>NMIN,NMAX
370 SUM>SUMKJ**AL
ARG > SUM/XDEN
X>10.0*ALOG10[ARG]
OLKPKLJ > OLKPKL - 1J < X
380 CONTINUE
390 CONTINUE

```

C C END CALCULATION OF 1/3-OCTAVE BANDS OF ROTATIONAL NOISE
C
C BEGIN CALCULATION OF VORTEX NOISE
C

```

IF [FCKZ.GT.50] GO TO 400
INTVAL > 1
GO TO 420
400 CONTINUE
INTVAL > 24
DO 410 I>1,24
FLR > FCK3[I] / TW016
FUPR > FCK3[I] * TW016
IF [FCKZ.LT.FLR] GO TO 410
IF [FCKZ.GT.FUPR] GO TO 410
INTVAL > 1
GO TO 420
410 CONTINUE
420 CONTINUE

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```

IPTR > 17 - INTVAL
DO 430 KL>1,24
F>FCK3[KL]
IPTR > KL < IPTR
IF [IPTR.LT.1] IPTR>1
IFC IPTRR .GT. 39 J IPTRR > 39
ELG > SCURVE[IPTRR]
SPLVR>SPLV[ELG]
ARG > 10.0 **[0.1 * SPLVR] < 10.0 ** [0.1 * OLKPKLJ]

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00401 ROT03370
00402 ROT03380
00403 ROT03390
00404 ROT03400
00405 ROT03410
00406 ROT03420
00407 ROT03430
00408 ROT03440
00409 ROT03450
00410 ROT03460
00411 ROT03470
00412 ROT03480
00413 ROT03490
00414 ROT03500
00415 ROT03510
00416 ROT03520
00417 ROT03530
00418 ROT03540
00419 ROT03550
00420 ROT03560
00421 ROT03570
00422 ROT03580
00423 ROT03590
00424 ROT03600
00425 ROT03610
00426 ROT03620
00427 ROT03630
00428 ROT03640
00429 ROT03650
00430 ROT03660
00431 ROT03670
00432 ROT03680
00433 ROT03690
00434 ROT03700
00435 ROT03710
00436 ROT03720
00437 ROT03730
00438 ROT03740
00439 ROT03750
00440 ROT03760
00441 ROT03770
00442 ROT03780
00443 ROT03790
00444 ROT03800
00445 ROT03810
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00449
00450

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IF(ARG .LE. 1.0E-20) ARG > 1.0E-20
OLKPKLJ > 10.0 * ALOG10(ARG)
*30 CONTINUE
C
C END VORTEX NOISE CALCULATION
C
C CALCULATE SPECTRUM FOR BOTH ROTORS
C
DO 460 KL>1,24
IF (IR.EQ.2) GO TO 440
ROLTPJ(KL) > OLKPKLJ
GO TO 460
440 ARG > 10.0 ** [0.1 * ROLTPJ(KL)] < 10.0 ** [0.1 * OLKPKLJ]
450 ROLTPJ(KL) > 10.0 * ALOG10(ARG)
460 CONTINUE
470 CONTINUE
C
C END OF ROTOR LOOP
C
RETURN
END
SUBROUTINE BJSIGM(K,B)
C
C TITLE: BJSIGM
C
C PURPOSE: TO DETERMINE THE VALUE OF A BESSEL FUNCTION OF THE FIRST
C KIND
C
C ABSTRACT: THE VALUE OF THE K-TH ORDER BESSEL FUNCTION IS DETERMINED
C FROM A PREVIOUSLY CALCULATED SET OF VALUES FOR A SPECIFIED
C ARGUMENT. THE ARITHMETIC SIGN OF THE FUNCTION IS
C CALCULATED FROM THE SIGN OF THE ORDER VALUE.
C
C USAGE: .....(K,B)
C K...INPUT VALUE OF THE BESSEL FUNCTION ORDER
C B...BESSEL FUNCTION VALUE RETURNED
C
C LABELED
C COMMON /B1/...CONTAINS (IN ARRAY BES) THE PREVIOUSLY CALCULATED
C SET OF BESSEL FUNCTIONS
C
C SUBROUTINES CALLED: NONE
C
C DIMENSION BES(400)
C
C COMMON /B1/ BES,INCMAX(50)
C A>1.0
C IF [K.6E.0] GO TO 10
C K=IABS(K)

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ROT03820
ROT03830
ROT03840
ROT03860
ROT03870
ROT03880
ROT03890
ROT03900
ROT03910
ROT03920
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ROT03940
ROT03950
ROT03960
ROT03970
ROT03980
ROT03990
ROT04000
ROT04010
ROT04020
ROT04030
ROT04040
BJSI0010

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BJSI0020
BJSI0030
BJSI0050
BJSI0060

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C IF THE ORDER (K) IS NEGATIVE AND ODD THEN THE FUNCTION VALUE IS
C MULTIPLIED BY -1.
C
C
      IFIX,NE,2*(K/2) A>-1.0
      10 B>A*BESIK<1J
      RETURN
      END
      SUBROUTINE BESSELX,N,SIGMAJ
C
C      TITLE:      BESSEL
C
C      PURPOSE:   TO CALCULATE A SET OF BESSEL FUNCTION FOR A GIVEN ARGUMENT
C
C      ABSTRACT:  THE RECURSION METHOD (REF. 1) OF CALCULATING BESSEL
C                  FUNCTIONS OF THE FIRST KIND IS USED TO CALCULATE FUNCTION
C                  VALUES FOR ORDERS FROM 0 TO N FOR ARGUMENT X.
C
C      USAGE:     .....(X,N,SIGMA)
C                  X.....ARGUMENT VALUE
C                  N.....MAXIMUM ORDER FOR WHICH FUNCTION VALUES ARE
C                      REQUIRED
C                  SIGMA....ACCURACY TO WHICH FUNCTION VALUES ARE CALCULATED
C
C      LABELED
C      COMMON:   /B1/
C
C      SUBROUTINES CALLED: NONE
C
C      REFERENCE 1.  'HANDBOOK OF MATHEMATICAL FUNCTIONS WITH FORMULAS,
C                    GRAPHS, AND MATHEMATICAL TABLES', NAT. BUREAU OF
C                    STANDARDS, APPLIED MATHEMATICS SERIES NO. 55, JUNE
C                    1964, CHAPTER 9, PG 385
C
C      ARRAY BES WILL CONTAIN THE CALCULATED BESSEL FUNCTION VALUES
C
      DIMENSION BES(400)
      DIMENSION RJI(400), RJBAR(450)
C
      COMMON /B1/ BES,INCMAX(50)
C
      EQUIVALENCE(BES,RJ)
      RMAXOV>0.1E<30
      IX>X
      IF [IX,NE,0] GO TO 30
      KK>N<1
      DO 10 IP>1, KK
      10 RJI(IP)>0.0
      RJI(1)>1.0
C
      BESS0020
      BESS0040
      BESS0050
      BESS0060
      BESS0070
      BESS0080
      BESS0090
      BESS0100
      BESS0110
      BESS0120
C
      BJSI0080
      BJSI0090
      BJSI0100
      BJSI0110
      BESS0010
C
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BESS0140
BESS0150
BESS0160
BESS0170
BESS0180
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BESS0200
BESS0210
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BESS0240
BESS0250
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BESS0270
BESS0280
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BESS0350
BESS0360
BESS0370
BESS0380
BESS0390
BESS0400

BESS0410
BESS0420
BESS0430
BESS0440
BESS0450
BESS0460
BESS0470
BESS0480
BESS0490

```

20 RETURN
C
C DETERMINE STARTING VALUE OF ORDER FOR RECURSION
C
30 IF [ABS[X].LT.8.0] GO TO 40
   DIST>5.0*ABS[X]**[1.0/3.0]
   GO TO 50
40 DIST>10.0
50 IF [ABS[X].LT.FLOAT[N]] GO TO 60
   K>FIX[ABS[X]<DIST]K1
   GO TO 70
60 K>FIX[ $\text{FLOAT}[N]<DIST]K1$ 
70 IS>2
80 RECO>0.
   SUM>0.
   REC1>1.
   Z>RMAXOV*ABS[X]/ $\text{FLOAT}[K]J$ 
   IP>K
90 IF [IP.LE.NK] GO TO 110
100 RJ[NK<1]J>2.0* $\text{FLOAT}[IP]/X*REC1-RECO$ 
   REC2>RJ[NK<1]
   GO TO 120
110 RJ[IP]J>2.0* $\text{FLOAT}[IP]/X*REC1-RECO$ 
   REC2>RJ[IP]
120 IF [ABS[REC2].LE.Z] GO TO 160
C
C IF RECURSIVE VALUES BECOME TOO LARGE THEY ARE NORMALIZED BY THE
C NUMBER Z
C
130 REC1>REC1/Z
   REC2>REC2/Z
   SUM>SUM/Z
   M>N
   IF [M.LE.IP-1] GO TO 160
140 RJ[M<1]J>RJ[M<1]J/Z
C
C RJ HAS THE POTENTIAL OF UNDERFLOWING AT STATEMENT NUMBER 230
C TEST RJ AGAINST A LOWER LIMIT (SAY 1.E-50) AND SET RJ TO 0. WHEN
C RJ IS LESS THAN THE LOWER LIMIT
C
   IF ( RJ*(M+1) .LT. 1.0E-50 ) RJ*(M+1) = 0.
   IF [M.EQ.IP-1] GO TO 160
150 M>M-1
   GO TO 140
160 IF [IP-1.NE.0] GO TO 180
170 SUM>SUM<REC2
   GO TO 200
180 IF [IP.EQ.2*IP/2] GO TO 200
190 SUM>SUM<2.0*REC2
200 RECO>REC1

```

```

REC1>REC2
IF [IP.EG.1] GO TO 220
210 IP>IP-1
GO TO 90
220 KK>NK1
DO 230 IP>1.KK
C CALCULATE FUNCTION VALUES BY DIVIDING BY 'SUM'
C 230 RJC[IP]RJC[IP]/SUM
C
C IF THIS IS THE FIRST TIME THROUGH CALCULATE ANOTHER SET OF FUNCTION
C VALUES STARTING WITH A HIGHER ORDER
C
GO TO [240,270],15
240 RMAX>0.
KK>NK1
DO 260 IP>1.KK
C COMPARE OLD AND NEW VALUES TO DETERMINE IF THEY ARE WITHIN LIMITS
C ESTABLISHED BY SIGMA
C
ERR>ABS[RJC[IP]-RJBAR[IP]]
IF [ERR.LE.RMAX] GO TO 260
250 RMAX>ERR
260 CONTINUE
IF [RMAX-SIGMA]20,20,280
270 IS>1
280 KK>NK1
DO 290 IP>1.KK
290 RJBAR[IP]RJC[IP]
K>FIX[FLOAT[K]K<DIST]
GO TO 80
END
SUBROUTINE AJET[OBSPLJ,X,Y,Z,JKI]
C TITLE: AJET
C
C PURPOSE: TO CALCULATE THE 1/3-OCTAVE NOISE SPECTRUM OF UNDEFLECTED
C JET NOISE
C
C ABSTRACT: THE NOISE FROM AN UNDEFLECTED JET AND ITS SPECTRUM SHAPE
C IS CALCULATED BY METHOD GIVEN IN REFERENCE 1. DIRECTIVITY
C CORRECTIONS AND CORRECTION FOR NON-STANDARD ATMOSPHERIC
C CONDITIONS ARE FROM REFERENCE 2. REQUIRED INPUT (VIA
C COMMON):
C THRUST.....DEVELOPED THRUST (LB)
C WTFL.....TOTAL WEIGHT FLOW (LB/SEC)
C AREAJ.....JET NOZZLE AREA (SQ FT)
C PSUBA.....AMBIENT INLET PRESSURE (IN HG)
C

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BESS0500
BESS0510
BESS0520
BESS0530
BESS0540
BESS0550

BESS0560

BESS0570
BESS0580
BESS0590
BESS0600

BESS0610
BESS0620
BESS0630
BESS0640
BESS0650
BESS0660
BESS0670
BESS0680
BESS0690
BESS0700
BESS0710
BESS0720
AJET0010

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C TSUBA.....AMBIENT INLET TEMPERATURE (DEG F) 00651
C TSUBJ.....TAILPIPE TEMPERATURE (DEG F) 00652
C TSUBJO.....TAILPIPE TEMPERATURE AT STD CONDITIONS (DEG F) 00653
C ALFA.....INCLINATION OF THRUST AXIS TO HORIZONTAL 00654
C (POSITIVE FOR INLET UP (DEG)) 00655
C 00656
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C 00658
C 00659
C 00660
C 00661
C 00662
C 00663
C 00664
C 00665
C 00666
C 00667
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C 00696
C 00697
C 00698
C 00699
C 00700

C TSUBA.....AMBIENT INLET TEMPERATURE (DEG F)
C TSUBJ.....TAILPIPE TEMPERATURE (DEG F)
C TSUBJO.....TAILPIPE TEMPERATURE AT STD CONDITIONS (DEG F)
C ALFA.....INCLINATION OF THRUST AXIS TO HORIZONTAL
C (POSITIVE FOR INLET UP (DEG))
C
C USAGE:(OBSPLJ,X,Y,Z,U,KI)
C OBSPLJ...A 24 ELEMENT ARRAY CONTAINING THE CALCULATED 1/3-
C OCTAVE NOISE SPECTRUM
C
C LABELED
C COMMON: /BI/ /INPUT/
C
C SUBROUTINES CALLED: NONE
C
C REFERENCE 1: E.J.RICHARDS AND D.J.MEAD,'NOISE AND ACOUSTIC FATIGUE
C IN AERONAUTICS', JOHN WILEY AND SONS LTD, NEW YORK,
C N.Y., 1968, CHAPTER 7.
C
C 2 L.L.BERANEK,'NOISE REDUCTION', MCGRAW-HILL BOOK CO.,
C INC., NEW YORK,N.Y.,1960, CHAPTER 24
C
C DIMENSION OBSPLJ(24),SPECI(24,6),DIRCT(18)
C 1,BES(400)
C
C COMMON /BI/ BES,INCMAX(50)
C
C COMMON /INPUT/ SAZ,SEG,FLTYPR,RCASE,RETA,RBIG,RBIGR,ROMEGN,RSID,
C 1RCHORD,RTHRUS,RTORG,RBETA,ICASE,ETA,TBIGB,TBIGR,TOMEGN,TSID,
C 2TCHORD,TTHRUS,TTORG,TBETA,PPWR,DIA,BIGB,RPMP,ANMPRP,CHORDP,
C 3PATH(50),XMAX(50),YMAX(50),PHMAX(50),RADIUS(50),VF(50),ALF(50),
C 4XPRZRO,YPRZRO,THMAXO,AZERO,INCC,ANMFPT,HPENG,SLEVEL,ANENG,DIAT,
C 5DIAH,B,BPR,CHORD,DDXT,DDXHS,RS,SIGPHI,DL,RPM,SPAF,XMXTIP,PR,DF,
C 6TT2,PT2,ALFA,FN,COMB,THRUST,WTFL,AREAJ,PSUBA,TSUBA,TSUBJ,TSUBJO,
C 7ALFAJ,ROTR,RP,FANS,RJ,E
C
C ARRAY SPECI,KJ CONTAINS CORRECTIONS TO OBTAIN SPECTRUM FROM OVERALL
C LEVEL BASED ON RELATIVE JET VELOCITY.
C
C DATA SPEC / 26.,21.5,15.,10.,11.,8.5,11.,11.,12.,
C 112.5,14.5,14.5,17.,17.5,18.,19.5,21.5,24.5,27.,30.5,35.,44.5,
C 249.,52. ,
C
C \$ 25.5,22.5,16.5,11.,11.,5,9.5,11.5,11.5,
C 111.5,12.,13.,13.,15.5,16.5,17.,18.,20.5,24.,25.5,29.5,32.5,
C 240.5,46.5,48.5 ,
C
C \$ 28.,24.,18.,12.,11.8,10.5,12.5,11.75,10.5,11.75,10.5,
C 111.,12.,12.,14.5,15.5,16.5,17.5,20.,22.5,25.,28.,30.5,38.,43.5,
C 246. ,

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C
S      110.5,10.5,11.,13.,15.,16.,17.,19.,22.,23.,26.5,28.,35.,40.,43.5 ,
      29.5,25.5,20.,12.5,12.,11.5,13.,12.5,10.,
AJET0470
AJET0480
AJET0490
AJET0500
AJET0510
AJET0520
AJET0530
AJET0540
AJET0550
AJET0560
AJET0570
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AJET0680
AJET0690
AJET0700
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C ARRAY DIRCT[I] CONTAINS DIRECTIVITY CORRECTIONS FOR ANGLES 0 [IN
C FRONT] TO 170 DEGREES [BEHIND].
DATA DIRCT
1-12., -11., -9., -7.5, -5., -2., 2., 6., 8., 6., 1., -8. /
-15.5, -15.0, -14.0, -13.5, -13., -12.5,
DEBUG[ALL]
TRACE ON
VF > VF1[JKIJ]
RADN > 57.295780
RALFAJ > ALFAJ / RADN

C CONVERT X,Z TO X-PRIME, Z-PRIME
C
XPR > X * COS(RALFAJ) - Z * SIN(RALFAJ)
ZPR > Z * COS(RALFAJ) < X * SIN(RALFAJ)
PI > 3.1415927
GRAV > 32.2
TAZRO > 59.0
PAZRO > 29.92
RAD > SORTI X**2 < Y**2 < Z**2 J

C CALCULATE GAMMA - DIRECTIVITY ANGLE
C
IDUM1 > XPR < 0.00001
IDUM2 > Y < 0.00001
IF [IDUM1.NE.0.OR.IDUM2.NE.0] GO TO 30
10 IF [ZPR]20,80,20
20 GAMMA > 90.
GO TO 40
30 GAMMA > ABS(ATAN2[Y,XPR] J
GAMMA > GAMMA * RADN
40 INC > GAMMA/10.0 < 1.50001
IFC INC .LT. 1 J INC > 1
IFC INC .GT. 18 J INC > 18

C CALCULATE POWER LEVEL
C
VJ > THRUST * GRAV / WTFL
RMJ > VJ / SAZ
IF [RMJ.GT.1.0] GO TO 50

```

```

PWL > 60.0 * ALOG10[VJ] < 10.0 * ALOG10[AREA] - 48.0
GO TO 60
50 PWL > 13.5 * ALOG10[ 0.67 * WFL * VJ**2 / GRAV J < 78.0
60 CONTINUE
C
C CORRECT FOR NON-STANDARD ATMOSPHERE - TEMPERATURE AND PRESSURE -
C AND CONVERT TO SPL FOR HEMISPHERICAL RADIATION
C
DELPR > 10.0*ALOG10[PSUBA / PAZRO J
DEL TJ > 40.0*ALOG10[TSUBJ / TSUBJO]
DELTEM > 35.0*ALOG10[TSUBA / TAZRO J
PWL > PWL < DELPR < DEL TJ - DELTEM
SPL > PWL - 10.0 * ALOG10[ 4.0 * PI * RAD**2 J < 3.0
C
C DIRECTIVITY
C
SPL > SPL < DIRCT[INC]
C
C SPECTRUM
C
AOVAO > SAZ / 1117.0
VREL > VJ - VF
DUM > ALOG10[VREL/AOVAO < 0.1]
INK > [DUM - 3.0]/0.05 < 0.50001
IF[INK .LT. 1] INK > 1
IF[INK .GT. 6] INK > 6
DO 70 I=1,24
OBSPL[J] > SPL - SPEC[I,INK]
70 CONTINUE
80 CONTINUE
RETURN
END
SUBROUTINE LOADER [X]
WRITE[6,70]
WRITE[6,71]
70 FORMAT[//,132H *****]
X*****
X*****]
71 FORMAT[50X,17HLOADER CARD INPUT//19X,6HCOLUMN,
X1X,6H2 4 6 ,11X,2H19,10X,2H31,10X,2H43,10X,2H55,10X,2H67 ,
X/26X,1H*, 3X,1H*,12X,1H*,11X,1H*,11X,1H*,11X,1H*,11X,1H*,11X,1H*,
X/26X,1H*, 3X,1H*,12X,1H*,11X,1H*,11X,1H*,11X,1H*,11X,1H*,11X,1H*,]
SUBROUTINE LOADER(DATA)
DESCRIPTION OF PARAMETERS
DATA-- VECTOR OF ANY LENGTH
USAGE
CALL LOADER(DATA)
SUBROUTINES REQUIRED
NONE
PURPOSE

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AJET0970 00751
AJET0980 00752
AJET0990 00753
AJET1000 00754
AJET1010 00755
AJET1020 00756
AJET1030 00757
AJET1040 00758
AJET1050 00759
AJET1060 00760
AJET1070 00761
AJET1080 00762
AJET1090 00763
AJET1100 00764
AJET1110 00765
AJET1120 00766
AJET1130 00767
AJET1140 00768
AJET1150 00769
AJET1160 00770
AJET1170 00771
AJET1180 00772
AJET1190 00773
AJET1200 00774
AJET1210 00775
AJET1220 00776
AJET1230 00777
AJET1240 00778
AJET1250 00779
AJET1260 00780
AJET1270 00781
AJET1280 00782
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C C SUBROUTINE LOADER(DATA) LOADS DATA INTO THE VECTOR DATA(I).
C C DATA CARDS ARE READ SUCCESSIVELY.
C C INSTRUCTIONS FOR USING LOADER
C C 1) PLACE THE NUMBER OF VALUES (-LE. 5) TO BE READ INTO DATA(I).
C C IN COLUMN 2 OR 72. COLUMN 2 OVERRIDES 72. AN ERROR IS
C C INDICATED IF BOTH COLUMNS 2 AND 72 ARE BLANK, OR IF THE
C C VALUE IS GREATER THAN 5. THIS NUMBER USES I FORMAT.
C C 2) PLACE THE LOCATION OF THE FIRST STORAGE SPACE ASSIGNED TO
C C DATA IN COLUMNS 3 TO 6. THIS NUMBER MUST BE AN INTEGER
C C AND MUST BE RIGHT ADJUSTED. THIS NUMBER MAY BE LEFT BLANK
C C ON SUCCESSIVE CARDS IF THE DATA IS CONTINUOUS. IF THIS
C C NUMBER IS LEFT BLANK ON THE FIRST DATA CARD TO BE LOADED,
C C THE FIRST FIELD OF THE CARD IS LOADED INTO STORAGE
C C LOCATION 1.
C C 3) PLACE THE VALUES TO BE LOADED (UP TO 5 PER CARD) IN COLUMNS
C C 7-66, FORMAT SE12.4.
C C 4) FOR RETURN TO THE PROGRAM, PLACE A MINUS SIGN IN COLUMN 1 OR
C C 71 OF THE LAST CARD TO BE LOADED. THIS LAST CARD IS LOADED
C C BEFORE THE RETURN.
C C THE PROGRAM USING SUBROUTINE LOADER(DATA) MUST INCLUDE
C C A) THE SYMBOL DATA WITH PROPER SUBSCRIPT IN A DIMENSION
C C STATEMENT.
C C B) AN EQUIVALENCE STATEMENT SETTING THE VARIABLE NAME OF THE
C C FIRST ITEM OF DATA LOADED EQUAL TO DATA.
C C
C C DIMENSION A(15), X(1)
C C 3 FORMAT(A2,A4,15A4,A4)
C C 4 FORMAT(25X,A2,A4,15A4,A4)
C C 4 FORMAT(1X,A2,A4,15A4,A4)
C C 5 FORMAT(1X,A2,A4,11A4)
C C 5 FORMAT(12,14,5E12.4,16)
C C
C C BEGIN LOADING DATA
C C I=1
C C 10 READ(5,3)NA,NB,(A(J),J=1,15),NC
C C REWIND 33
C C WRITE(33,3) NA,NB,[A(J),J>1,15],NC
C C WRITE(6,4) NA,NB,[A(J),J>1,15],NC
C C REWIND 33
C C READ(33,5) NA,NB,[A(J),J>1,5],NC
C C WRITE(6,4)NA,NB,(A(J),J=1,10),NC
C C READ(0,5)NA,NB,(A(J),J=1,5),NC
C C IF(NA)6,30,6
C C 6 IF(IABS(NA) - 5) 412,412,41
C C 412 IF(NB) 999,11,8
C C 8 I=NB
C C 11 K=IABS(NA)
C C DO 20 J=1,K
C C X(I)=A(J)

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20 I=I+1
   IF(RA)999,57,57
57 IF(NC)999,10,10
30 NA=NC
   IF(NC)6,40,6
40 IF(NB)45,41,41
41 WRITE(6,50)
50 FORMAT(10X,43HERROR IN DATA SETUP. SEE SUBROUTINE LOADER
   STOP
45 WRITE(6,51)
51 FORMAT(/10X,47HDO NOT USE A NEGATIVE VALUE OF NB FOR RETURN ---,
   *23H SEE SUBROUTINE LOADER
999 RETURN
   END

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APPENDIX E

V/STOL Noise Subroutine For Use With NEM Mod-5 and Mod-6 Programs

During the development of the V/STOL Noise Model it became apparent that, while the program would be of great value in evaluating V/STOL systems, it was too cumbersome to be used efficiently in the Noise Exposure Model (NEM) computer program. For this reason a subroutine designed specifically for use in the NEM program was written. The subroutine accepts a slant range distance and a thrust value from the main program and returns the corresponding EPNL value for a helicopter by a table look-up procedure. The table of EPNL values for the various slant ranges and thrust values was established by using the output of the V/STOL Noise Model. The subroutine, as provided, is only for a single main rotor helicopter, however the method is completely general and can be applied to any vehicle by providing a different set of EPNL-slant range/thrust values.

SUBROUTINE VSTOLN (SR,TR,EPNL)

```

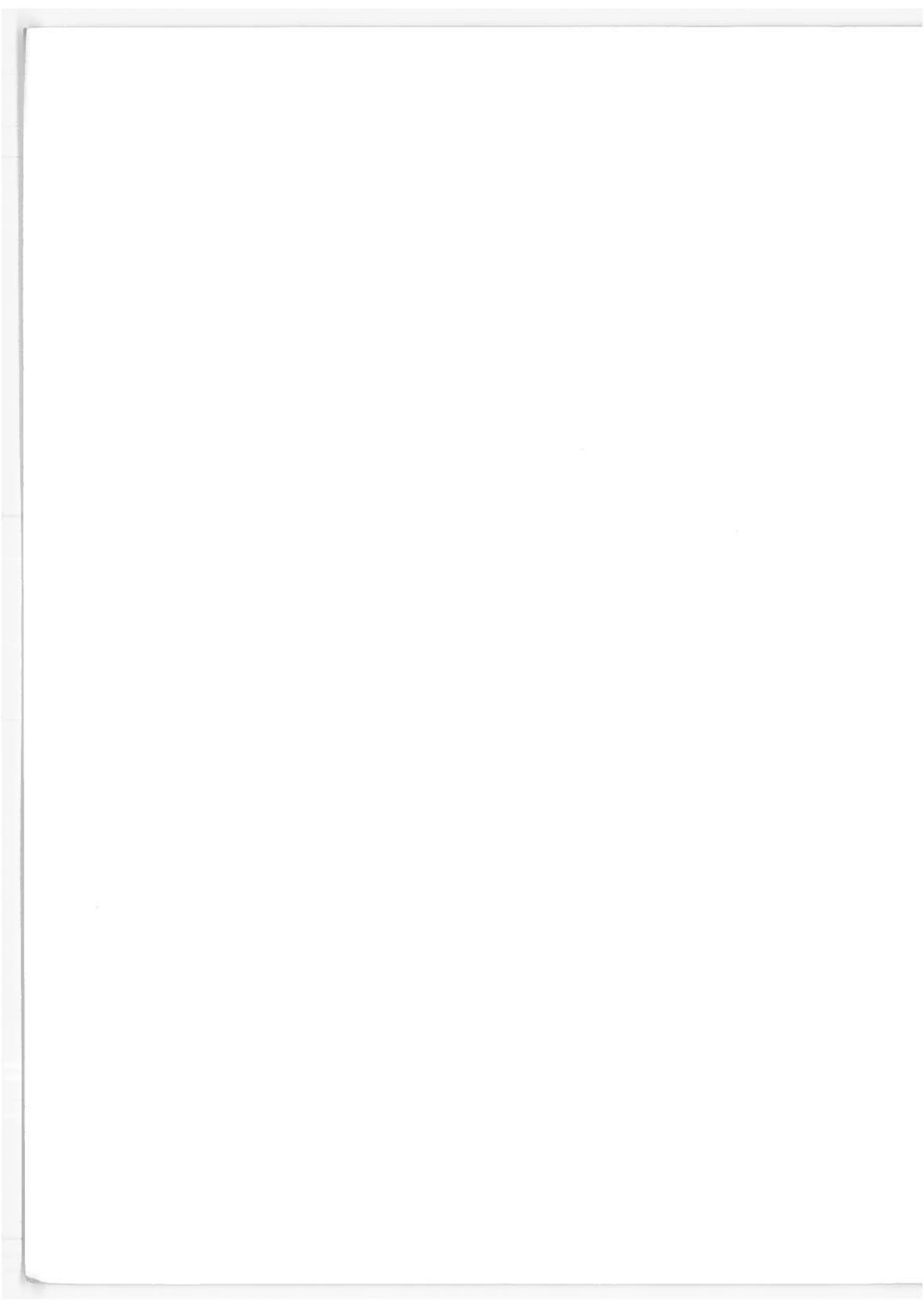
C
C TITLE: VSTOLN
C
C PURPOSE: TO CALCULATE THE EFFECTIVE PERCEIVED NOISE LEVEL FOR
C A HELICOPTER TAKEOFF, LANDING, OR FLYBY AT A GIVEN SLANT
C RANGE AND THRUST LEVEL.
C
C ABSTRACT: THE EPNL VALUE IS COMPUTED FROM THE EPNL-SLANT RANGE
C CURVES REPRESENTED BY THE ARRAY ANOISE(J,K). J=1,10
C REPRESENTS SLANT RANGE DISTANCES FROM 1000 TO 10,000 FT
C IN 1000 FT INCREMENTS AND K=1,9 REPRESENTS THRUST LEVELS
C FROM 15,000 TO 55,000 LB IN 5000 LB INCREMENTS. THE ONLY
C INPUTS REQUIRED ARE SLANT RANGE (SR) IN FEET AND THE MAIN
C ROTOR THRUST IN POUNDS. THE PROGRAM INTERPOLATES OR
C EXTRAPOLATES AS NECESSARY.
C
C *
C A * . . . TABLE OF EPNL VALUES
C N * . . . IN ARRAY ANOISE(J,K)
C O * . . .
C I * . . .
C S * . . .
C E * . . . K=2
C . * . . . K=1
C *
C *****
C SLANT RANGE (J)
C
C USAGE: VSTOLN(SR,TR,EPNL)
C SR.....SLANT RANGE IN FEET INPUT
C TR.....THRUST LEVEL IN POUNDS INPUT
C EPNL.....EPNL VALUE AT SR AND TR RETURNED.
C
C-LABELED
C COMMON: NONE
C
C SUBROUTINES
C CALLED: NONE
C
C REAL LINEAR
C LINEAR(DELX,X1,Y1,Y2,X0)= Y1+(Y2-Y1)/DELX *(X0-X1)
C
C DIMENSION ANOISE(10,9)
C
C DATA (ANOISE(I,1),I=1,10) /
C $ 83.6, 75.1, 69.2, 64.1, 59.0, 55.2, 52.0, 48.0, 45.0, 43.0 /
C
C DATA (ANOISE(I,2),I=1,10) /
C $ 86.8, 78.7, 73.0, 68.0, 63.5, 60.0, 56.8, 53.3, 50.8, 48.8 /
C
C DATA (ANOISE(I,3),I=1,10) /
C $ 89.0, 81.0, 75.5, 71.0, 67.0, 63.5, 60.4, 57.4, 55.0, 53.0 /
C
C DATA (ANOISE(I,4),I=1,10) /
C $ 90.8, 83.1, 77.9, 73.3, 69.7, 66.2, 63.1, 60.5, 58.4, 55.2 /
C
C DATA (ANOISE(I,5),I=1,10) /
C $ 92.0, 84.8, 79.5, 75.2, 71.7, 68.5, 65.5, 63.0, 61.0, 59.0 /

```

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C
DATA (ANOISE(I,6),I=1,10) /
$ 93.0, 86.0, 80.8, 76.7, 73.2, 70.1, 67.5, 65.1, 63.0, 61.1 /
C
DATA (ANOISE(I,7),I=1,10) /
$ 93.8, 86.9, 81.8, 77.8, 74.7, 71.6, 69.0, 66.8, 65.0, 63.0 /
C
DATA (ANOISE(I,8),I=1,10) /
$ 94.4, 87.5, 82.5, 79.5, 75.4, 72.7, 70.1, 68.0, 66.0, 64.1 /
C
DATA (ANOISE(I,9),I=1,10) /
$ 95.0, 88.2, 83.3, 79.5, 76.5, 73.8, 70.5, 69.1, 67.5, 65.8 /
C
DATA SRMIN/1000., SRMAX/10000., SRDEL/1000./
DATA TRMIN/15000., TRMAX/55000., TRDEL/5000./
J=0
K=0
IF (SR .LT. SRMAX ) GO TO 5
J=10
GO TO 10
5 IF (SR .GT. SRMIN ) GO TO 10
J=2
10 IF (TR .LT. TRMAX ) GO TO 15
K=9
GO TO 20
15 IF (TR .GT. TRMIN ) GO TO 20
K=2
20 IF (J .EQ. 0) J= SR/SRDEL + 1.0001
25 IF (K .EQ. 0) K= TR/TRDEL - .9999
SR1= (J-1)*SRDEL
TR1= (K-1)*TRDEL + 10000.
Z1 = LINEAR(SRDEL,SR1,ANOISE(J-1,K-1),ANOISE(J,K-1),SR)
Z2 = LINEAR(SRDEL,SR1,ANOISE(J-1,K ),ANOISE(J,K),SR)
EPNL = LINEAR(TRDEL,TR1,Z1,Z2, TR )
RETURN
END

```



APPENDIX F

REPORT OF INVENTIONS APPENDIX

In regard to the patent rights (license) clause of the contract, a review of the work performed has been made and as far as can be determined there were no subject inventions conceived or first actually reduced to practice in the course of or under the contract. There were no sub-contracts awarded for the conduct of experimental, developmental or research work.

