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PARATRANS IT VEHICLE TEST AND EVALUATION Volume IV: Fuel Economy Tests

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PREFACE

This final report, Volume IV, summarizes the fuel economy testing on the Paratransit Evaluation and Testing Contract. The program was structured to provide performance data on the prototypes compared to a baseline vehicle that will be used to upgrade future redesigns.

The program was conducted by Dynamic Science, Inc. under Contract DOT-TSC-124l with the Transportation Systems Center (TSC) of Cambridge, Massachusetts for the Urban Mass Transportation Administration. The contract was technically managed by Mr. Jim Kakatsakis and Mr. Joe Picardi of TSC.

The opinions and findings expressed in this publication are those of the authors and not necessarily those of the Government.

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1.0 INTRODUCTION

The paratransit mode of transportation provides an alternative between transit in privately owned and operated vehicles and scheduled mass transit systems. Paratransit includes such systems as dial-a-ride, taxi, and jitney service. It is of vital importance to people without individual cars or ready access to regular mass transit and to people of limited mobility. The vehicles presently available for paratransit service, however, do not cover the full spectrum of required characteristics. They are slightly modified versions of vehicles designed for different purposes. As such, they are not as efficient in their operation nor as easy to enter and exit as is desirable in this type of transportation.

Therefore, the Urban Mass Transportation Administration (UMTA), working through the Transportation Systems Center (TSC), developed specifications for a vehicle specifically for use in paratransit which combines ^a number of desirable features without compromising important performance parameters. Prototype vehicles were manufactured for UMTA by two different manufacturers (ASL Engineering and Dutcher Industries) according to these specifications. The primary features of the vehicles are a low pollution, quiet, efficient propulsion system combined with ^a body designed for the comfort and convenience of both the passengers and driver. The vehicles include provisions for easy ingress and egress for the general public as well as the elderly and handicapped, including the easy ingress/egress and accomodation of a wheelchair passenger.

Dynamic Science, Inc. was selected by UMTA to conduct an *in*dependent series of tests and evaluations of the two prototype paratransit vehicles (PTV). These tests were designed to provide

additional information on the ride quality and comfort, fuel economy, performance and handling characteristics of the two vehicles. A compact passenger car (Chevrolet Nova) was utilized as a baseline test vehicle throughout the test series to furnish comparative data for the evaluations.

The paratransit vehicle testing and evaluation program consisted of six major tasks. The first task consisted of initial vehicle inspection, test preparation, and driver familiarization efforts conducted upon delivery of the vehicles to the Dynamic Science test facility. The remaining five tasks consisted of conducting and evaluating the results of five separate test series. These series were:

- Ride Comfort and Quality Test Series which measured the ride characteristics of the test vehicles to determine if and how well they satisfy accepted standards of ride quality.
- Acceleration and Interior Measurement Test Series which determined the acceleration characteristics and available interior space of the vehicles in order to evaluate their suitability for urban paratransit use.
- Handling Test Series which determined the steering and handling characteristics of the PTVs and allowed their characteristics to be compared with those of the baseline test vehicle.
- Fuel Economy Test Series which obtained fuel economy data for the PTVs under actual road conditions with various driving cycles.
- Noise Test Series which measured the acoustic noise generated by the vehicles and the noise environment inside the passenger and driver compartments.

The Paratransit Test and Evaluation Program is documented in five separate volumes as follows:

volume 1 - Ride Comfort and Quality Tests

Volume 2 - Acceleration and Interior Measurement Tests

Volume 3 - Handling Tests Volume 4 - Fuel Economy Tests Volume 5 - Noise Tests

This volume (Volume 4) presents the test procedures and results of the fuel economy tests conducted on the two PTV prototypes and the baseline test vehicle.

2.0 TEST DESCRIPTION

2.1 TEST OBJECTIVES

The fuel economy tests were conducted to obtain fuel economy data for the paratransit vehicles under actual road driving conditions.

2.2 TEST DESIGN

The tests were designed to determine on-the-road fuel economy data for the two paratransit prototypes (one from ASL engineering and the other from Dutcher Industries) and a baseline vehiole (1977 Chevrolet Nova 6). The vehicles were driven through simulated urban and suburban driving cycles (as defined in SAE JI082) as well as constant speed courses under various loading conditions. The driving test cycles are summarized in Table 1.

*Speed was determined. graphically from other constant speed tests.

2.3 SCOPE OF TEST SERIES

A summary of the test conditions is presented in Table 2. The fuel economy test series consisted of 11 test conditions on each prototype paratransit vehicle and 8 test conditions on the

baseline vehicle. There were 6 repeated runs for each test condition, leading to a total of 66 runs for each PTV and 48 runs for the baseline vehicle.

3.0 TEST VEHICLES

The test vehicles consisted of two prototype paratransit vehicles (one manufactured by ASL Engineering and the other by Dutcher Industries) and one baseline vehicle (Chevrolet Nova). These vehicles are shown in Figure 1.

3.1 ASL PARATRANSIT VEHICLE

The ASL PTV (Figure 2) is a front engine, front drive vehicle which can accommodate a maximum of five seated passengers or three seated passengers plus a wheelchair. Ingress/egress is accomplished through remotely operated sliding doors on each side of the vehicle. An electrically powered loading ramp may be extended on the right side of the vehicle to permit unassisted ingress and egress for wheelchair passengers.

The driver's compartment is separated from the passenger compartment by a bullet-resistant partition. An intercom system *is* provided for communication between the two compartments. All seating positions are equipped with belt restraints and a restraint system *is* also provided to fasten the wheelchair securely to the vehicle.

3.2 DUTCHER PARATRANSIT VEHICLE

The Dutcher PTV (Figure 3) is a rear engine, rear drive vehicle which also accommodates five seated passengers or four seated passengers plus a wheelchair. Hydraulically actuated bitold doors on each side of the vehicle permit passenger ingress and egress. An electrically powered loading ramp extending on the right side of the vehicle allows wheelchair ingress and egress.

Test Vehicles Left-to-Right: Dutcher PTV, ASL PTV, Chevrolet Nova. Figure 1.

Figure 2. ASL Paratransit Vehicle.

Dutcher Paratransit Vehicle. Figure 3.

As in the ASL PTV, the Dutcher PTV contains a driver compartment which *is* completely separated from the passenger compartment by a transparent partition. Communication between passengers and driver is accomplished through an intercom system. Restraints are provided for all seating positions and for the wheelchair.

3.3 BASELINE TEST VEHICLE

The baseline test vehicle which was used for comparative evaluation of the PTV test results was a 1977 Chevrolet Nova 6. The criteria for the selection of the baseline vehicle were:

- Compact Size
- 4-Door Passenger Car
- 6-Cylinder Engine
- Automatic Transmission
- Air Conditioning System
- Radial Tires
- Weight, Width, and Length Comparable to the Paratransit Vehicle
- Mileage Less Than 5,000 miles.

The Nova was selected because it fulfills all of the above requirements and, in addition, is more prevalent and more commonlyknown than any of the other vehicles which met the criteria.

3.4 COMPARISON OF BASIC VEHICLE CHARACTERISTICS

The basic test vehicle characteristics are listed in Table 3. The characteristics of the two PTV vehicles are similar in most instances. The major differences between the two vehicles *lie* in the engine location/drive configuration and in the frontto-rear weight ratio (1.59 for the ASL and 0.60 for the Dutcher).

TABLE 3. BASIC TEST VEHICLE CHARACTERISTICS

4.0 TEST FACILITIES

The fuel economy testing was performed at the Dynamic Science Deer Valley Facility, shown in Figure 4. All of the tests were conducted on the two-mile oval which is a minimum two lanes wide (fourteen feet each) throughout. The inside lane was utilized since it has no appreciable cross slope. Its surface is of asphaltic concrete with no perceptible bumps or dips due to overlapping paving strips. The pavement grade of the straightaways is less than 1 percent.

The course layout for the fuel economy tests is illustrated in Figure 5. The courses were marked using ground supported posts. They extended at least 4 feet above the ground and had the mileage marked on them so that they could be easily read from the test vehicle while it was traversing the course. The posts appeared at the 0.0, 0.2, 0.3, 0.5, 0.7, 0.8, 1.0, 1.2, 1.3, 1.5, 1.7, 1.8, 2.0, 2.6, 3.3, 4.0, and 5.2 mileage positions. Each post position was within 5 feet of the desired position going both ways around the track.

5.0 TEST PROCEDURE

5.1 TEST INSTRUMENTATION

5.1.1 Required Measurements

The primary variables measured during the fuel economy testing were:

1. Vehicle velocity

2. Fuel consumption

3. Fuel temperature

4. Elapsed time.

5.1.2 Instrumentation Specifications

The instrumentation specifications and requirements for the testing are presented in Table 4.

A Labeco fifth wheel was used to measure vehicle velocity. The output of the fifth wheel was inputted into a Labeco DD1.1 speedometer for visual display of velocity.

Fuel consumption was determined from a Fluidyne flowmeter system and fuel temperature was measured with a thermocouple. These instruments were read out on visual displays. Elapsed time was determined by means of a stopwatch.

An Ammco manometer mounted on the vehicle *in* the driver's field of view was used to monitor the vehicle acceleration during the driving of the urban and suburban cycles.

Ambient conditions of temperature, barometric pressure, and wind speed were measured at the Central Data Acquisition and Control Station (see Figure 5).

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5.1.3 Calibration Procedures

The fifth wheel was calibrated daily using a calibration motor to spin the wheel. The tire pressure was adjusted to obtain the proper calibration values.

The flowmeter system and fuel temperature thermocouple were calibrated at the factory and physically checked in the Dynamic Science Instrumentation Laboratory before their installation in the vehicle.

The manometer installation *in* the vehicle was checked daily before testing to ascertain that the at-rest position reading was zero.

5.1.4 Data Acquisition

All test data and other pertinent test information was recorded on Test Data Log forms by the test driver. This information included:

- Time and course
- Driver's comments
- Testing decisions (repeating the tests or suspending testing and why)
- Direction traveled around course
- Fuel temperature taken several times during each test run (at vehicle idle periods) and at start and end of each test run.
- Ambient conditions (temperature, barometric pressure, wind velocity) at the start and end of each test run.
- Accumulated time and fuel consumption for each test run.

All data except that pertaining to ambient conditions were read from the visual displays in the test vehicle. Ambient conditions were relayed to the driver upon request from the Central Data Acquisition and Control Station via a two-way radio communications system.

5.2 VEHICLE PREPARATION

The vehicles were prepared for testing by installing the required instrumentation listed in Table 4 and by loading the vehicles to the prescribed loading conditions.

5.2.1 Instrumentation Installation

The fuel flowmeter and fuel temperature thermocouple were installed in the vehicles in such a manner that they did not alter the vehicle operating characteristics. These installations are described in the following paragraphs.

The fuel flow transducer and fuel temperature sensor were installed in the Nova baseline vehicle as illustrated in Figure 6. The regular fuel line between the fuel pump and the carburetor was disconnected. Flexible tubing was used to connect one end of a tee fitting to the fuel pump and the other end of the fitting to the inlet of the flow transducer. The outlet of the flow transducer was connected with tubing to the carburetor. A copperconstantan thermocouple was installed in the tee fitting to measure the gas temperature. Figures 7 and 8 show the flow transducer and thermocouple installations, respectively.

The installation of the fuel monitoring instrumentation in the Dutcher prototype is illustrated in Figure 9. The regular line between the gas tank and fuel pump was disconnected. The thermocouple and flow transducer were installed between the tank and pump using flexible tubing. The Dutcher PTV has a continuous injection system in which the fuel flows constantly and any excess

Figure 6. Installation Schematic of Fuel Monitoring Instrumentation in Nova Baseline Vehicle.

fuel is bypassed to the gas tank. To avoid counting the bypassed fuel again, the bypass to the gas tank was diverted to a position downstream of the flow transducer. The actual installation of the instrumentation is shown in Figure 10.

The ASL prototype was first prepared in the same manner as the Dutcher, with the flow transducer installed between the gas tank and the pump and with the bypass diverted downstream of the flowmeter. However, this configuration flooded the engine and made the installation shown in Figure 11 necessary. An auxiliary pump was used to pump the gasoline from the gas tank through the flow transducer into an auxiliary tank. A float valve assembly in the auxiliary tank kept the fuel level in the tank constant so that only thqt flow used to replenish the auxiliary tank was counted by the flowmeter. The gas going to the continuous injection system was pumped from the auxiliary tank. The bypassed fuel was cooled by a finned, air cooled heat exchanger and routed back into the auxiliary tank. The system as installed in the vehicle is shown in Figures 12 and 13.

Flow Transducer Installation in Nova. Figure 7.

Figure 8. Thermocouple Installation in Nova.

Figure 9. Installation Schematic of Fuel Monitoring System in Dutcher Prototype.

The fifth wheel was attached to the rear bumpers of the vehicles. A typical installation is shown in Figure 14. The visual display for the fifth wheel, as well as the displays of fuel temperature and fuel consumption, were installed for easy viewing by the test driver as shown in Figure 15.

5.2.2 Vehicle Loading

The fuel economy tests were run with the loading conditions listed in Table 5. The total load included driver and instrumentation. The passenger loading was simulated by placing sand bags in the passenger section.

Figure 10. Flow Transducer and Thermocouple Installation in Dutcher Prototype.

Figure 12. Fuel Monitoring System Installed in ASL Prototype.

Typical Fifth Wheel Installation. Figure 14.

Typical Installation of Visual Displays. Figure 15.

The test weights of the vehicles were determined with the fuel tanks at least ⁹⁰ percent full. The prescribed test weights of the vehicles are listed in Table 6. Actual test weights were all within one percent of the prescribed weights.

TABLE 5. FUEL ECONOMY TEST LOADING CONDITIONS

5.3.1 General Test Conditions

Before each day's testing, the vehicle was warmed up and the electronics stabilized by driving two laps on the test track at 30-40 mph. All test driving was done in the drive range of the transmission. All vehicle accessories were turned off and the windows closed.

Acceleration/deceleration was maintained within ± 1 ft/sec² of the prescribed value. Velocity was maintained within ±l mph. The six test runs for each condition were run alternately clockwise and counterclockwise through the course. Testing was suspended if the steady wind speed exceeded ¹⁰ mph or gusts exceeded 15 mph.

standard no-lead gasoline was used in the Nova and ASL prototypes. The Dutcher Prototype used premium fuel. The properties of the gasoline used during the fuel economy tests are listed in Table 7.

5.3.2 Urban Tests

All urban test runs were conducted according to Table 8.

5.3.3 Suburban Tests

All suburban test runs were conducted according to Table 9.

5.3.4 Constant Speed Tests

The constant speed tests were conducted over a 4-mile continuous course (two laps around the test track). The vehicle was brought up to the desired speed by the time it reached the test initiation point (0 mile). The fuel consumption counter and timing device were started as the vehicle passed the test initiation point. The fuel and time measuring devices were stopped while driving at the test speed at the 4.0-mile marker. The prescribed test speeds and average test times are listed in Table 10.

An additional constant speed test for each vehicle was run at the maximum fuel economy test speed for that vehicle. This speed was determined by curve-fitting the average fuel economy (mpg) of the other constant speed tests and designed test velocities and obtaining the prediction of test velocity which should yield the largest fuel economy.

TABLE 8. URBAN TEST SCHEDULE

6.0 TEST RESULTS

The average observed fuel economy, along with the standard deviation, was calculated for each test condition. The fuel economy was then corrected according to the following formula:

Corrected mpg = (observed mpg) $(T_gCF) (P_hCF) (T_fCF) (API gr_eCF)$

where $T_SCF = 1 + 0.0014(60 - T_S)$

 $P_bCF = 1.0$ for urban cycle and constant speed course = 1.0 + 0.0072(P_b -29.000) for suburban cycle $T_fCF = 1/multiples[*]$ for volume reduction to 60°F API $gr_fCF = 1 + 0.0032$ (API $gr_f - 60.5$)

- $T_{\rm g}$ = average ambient temperature during test cycle, \circ F
- T_f = average fuel temperature at measuring instrument during test cycle, ^oF
- P_b = average barometric pressure during test cycle, in. Hg

API gr_f = API gravity of test fuel at 60°F

The observed and corrected fuel economies for the Nova, ASL, and Dutcher vehicles are given in Tables 11, 12, and 13, respectively.

The corrected fuel economy of all three vehicles is presented in Table 14 for comparison. This table shows that the Dutcher prototype had the lowest fuel economy of the three vehicles under all but one of the test conditions. It did have ^a higher fuel economy than the ASL prototype during the urban cycle, although it still ranked below the baseline vehicle.

*Multiplier obtained using T_f and API gr_f from Table 2 in SAE Jl082.

TABLE 11. SUMMARY OF FUEL ECONOMY PERFORMANCE FOR THE NOVA (BASELINE)

The fuel economy of the ASL prototype was below that of the baseline vehicle during the urban cycle and at constant speeds of ³⁰ mph or less. However, its fuel economy exceeded that of the baseline vehicle during the suburban cycle and at higher constant speeds, although its maximum fuel economy was still below that of the baseline vehicle.

The corrected fuel economies versus constant velocity for the three vehicles are presented graphically in Figures 16 through 18. These values are compared in Figure 19. This figure shows that the maximum fuel economy of the baseline vehicle, although higher than that of both prototypes, occurs at ^a considerably lower speed than do those of the paratransit vehicles. The curves also show that the rate of decrease in fuel economy at higher speeds *is* less for the ASL prototype than for the other two vehicles.

TABLE 12. SUMMARY OF FUEL ECONOMY PERFORMANCE FOR THE ASL PROTOTYPE

TABLE 13. SUMMARY OF FUEL ECONOMY PERFORMANCE FOR THE DUTCHER PROTOTYPE

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Comparison of Constant Speed Fuel Economy. Figure 19.